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# Technical Reference

**First Edition (March 1984)**

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# **FEDERAL COMMUNICATIONS COMMISSION RADIO FREQUENCY INTERFERENCE STATEMENT**

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## **CAUTION**

The product described herein is equipped with a grounded plug for the user's safety. It is to be used in conjunction with a properly grounded receptacle to avoid electrical shock.

# **Notes:**

# Preface

This manual describes the various units of the IBM Personal Computer AT and how they interact. It also has information about the basic input/output system (BIOS) and about programming support.

The information in this publication is for reference, and is intended for hardware and program designers, programmers, engineers, and anyone else who needs to understand the design and operation of the IBM Personal Computer AT.

This manual consists of nine sections, four of which describe the hardware aspects of the IBM Personal Computer AT including signal charts and register information. Section 5 contains information about the usage of BIOS and a system BIOS listing. Section 6 contains instruction sets for the 80286 microprocessor and the 80287 math coprocessor. Section 7 provides information about characters, keystrokes, and colors. Section 8 has general communications information. Section 9 contains information about the compatibility of the IBM Personal Computer AT and the rest of the IBM Personal Computer family.

A glossary of terms and a bibliography of related publications are included.

## **Prerequisite Publications**

*Guide to Operations* for the IBM Personal Computer AT

### **Suggested Reading**

- *BASIC* for the IBM Personal Computer
- *Disk Operating System (DOS)*
- *Hardware Maintenance and Service* for the IBM Personal Computer AT
- *MACRO Assembler* for the IBM Personal Computer

# Contents

<b>SECTION 1. SYSTEM BOARD</b>	<b>1-1</b>
Description	1-3
Memory	1-4
Microprocessor	1-4
System Performance	1-7
System Timers	1-8
System Interrupts	1-10
ROM Subsystem	1-11
RAM Subsystem	1-12
Direct Memory Access (DMA)	1-12
I/O Channel	1-15
Other Circuits	1-30
Speaker	1-30
Jumper	1-30
Type of Display Adapter Switch	1-31
Variable Capacitor	1-31
Keyboard Controller	1-31
Real-time Clock/Complementary Metal Oxide Semiconductor (RT/CMOS) RAM Information	1-45
Specifications	1-55
System Unit	1-55
Connectors	1-57
Logic Diagrams	1-61
<b>SECTION 2. COPROCESSOR</b>	<b>2-1</b>
Description	2-3
Programming Interface	2-3
Hardware Interface	2-4
<b>SECTION 3. POWER SUPPLY</b>	<b>3-1</b>
Inputs	3-3
Outputs	3-3
Output Protection	3-4
Dummy Load	3-4
Output Voltage Sequencing	3-4
No-Load Operation	3-5
Power-Good Signal	3-5

Fan-Out .....	3-6
Connectors .....	3-6
<b>SECTION 4. KEYBOARD .....</b>	<b>4-1</b>
Description .....	4-3
Interface .....	4-3
Sequencing Key Code Scanning .....	4-3
Keyboard Buffer .....	4-3
Keys .....	4-3
Functions Performed at Power-On Time .....	4-4
Power-On Reset .....	4-4
Basic Assurance Test .....	4-4
Commands from the System .....	4-5
Keyboard Outputs .....	4-10
Key Scan Codes .....	4-10
Command Codes to the System .....	4-12
Clock and Data Signals .....	4-14
Keyboard Data Output .....	4-15
Keyboard Data Input .....	4-15
Keyboard Layout .....	4-16
Specifications .....	4-23
Keyboard Connector .....	4-23
<b>SECTION 5. SYSTEM BIOS .....</b>	<b>5-1</b>
System BIOS .....	5-3
System BIOS Usage .....	5-3
Keyboard Encoding and Usage .....	5-12
Extended Codes .....	5-17
<b>SECTION 6. INSTRUCTION SET .....</b>	<b>6-1</b>
Instruction Sets .....	6-3
80286 Microprocessor Instruction Set .....	6-3
Data Transfer .....	6-3
Arithmetic .....	6-6
Logic .....	6-10
String Manipulation .....	6-12
Control Transfer .....	6-13
Processor Control .....	6-19
Protection Control .....	6-21
80287 Coprocessor Instruction Set .....	6-24
Data Transfer .....	6-24
Comparison .....	6-25
Constants .....	6-26

Arithmetic .....	6-27
Transcendental .....	6-29
Processor Control .....	6-29
SECTION 7. CHARACTERS, KEYSTROKES, AND COLORS ..... 7-1	
Characters, Keystrokes, and Color .....	7-3
SECTION 8. COMMUNICATIONS ..... 8-1	
Communications .....	8-3
Establishing a Data Link .....	8-5
SECTION 9. IBM PERSONAL COMPUTER COMPATIBILITY ..... 9-1	
Hardware Considerations .....	9-3
System Board .....	9-3
20Mb Fixed Disk Drive .....	9-4
High Capacity Diskette Drive .....	9-4
Adapters .....	9-4
Keyboard .....	9-4
The IBM Personal Computer AT Does Not Support .....	9-5
Application Guidelines .....	9-5
High-Level Language Considerations .....	9-5
Assembler Language Programming Considerations .....	9-6
Multi-tasking Provisions .....	9-11
SYS REQ Key .....	9-15
Copy Protection .....	9-22
Machine-Sensitive Code .....	9-23
Glossary .....	Glossary-1
Bibliography .....	Bibliography-1
Index .....	Index-1

## **Notes:**

# INDEX TAB LISTING

Section 1: System Board .....

Section 2: Coprocessor .....

Section 3: Power Supply .....

Section 4: Keyboard .....

Section 5: System BIOS .....

Section 6: Instruction Set .....

## **Notes:**

Section 7: Characters, Keystrokes, and Colors . . . . .

Section 8: Communications . . . . .

Section 9: Compatibility . . . . .

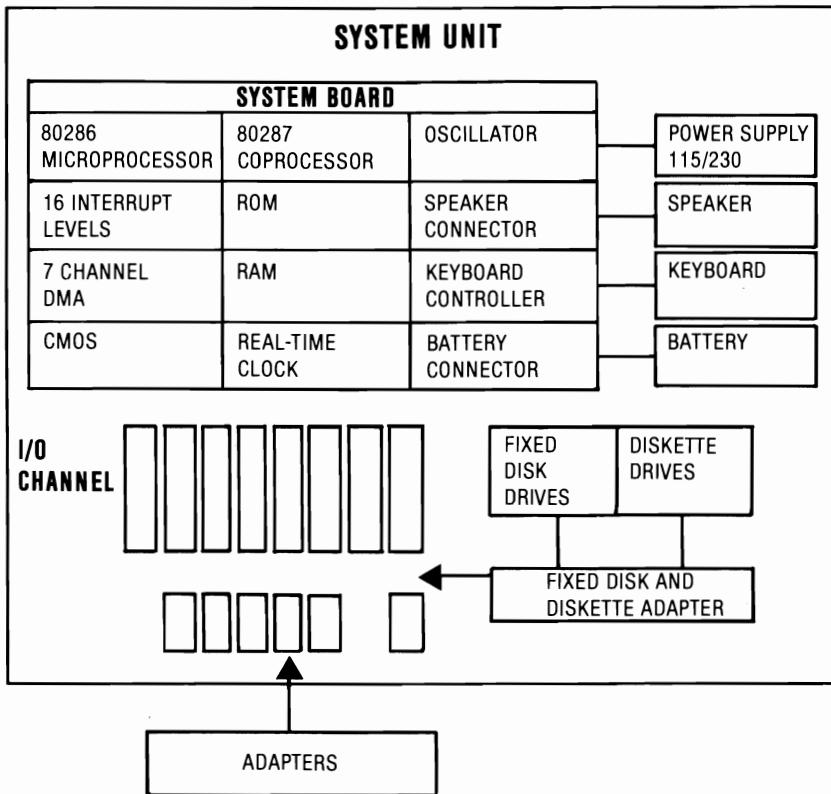
Glossary . . . . .

Bibliography . . . . .

Index . . . . .

## **Notes:**

# System Block Diagram



## **Notes:**

# SECTION 1. SYSTEM BOARD

## Contents

<b>Description</b> .....	<b>1-3</b>
Memory .....	1-4
<b>Microprocessor</b> .....	<b>1-4</b>
Real-Address Mode .....	1-4
Protected Mode .....	1-5
<b>System Performance</b> .....	<b>1-7</b>
<b>System Timers</b> .....	<b>1-8</b>
<b>System Interrupts</b> .....	<b>1-10</b>
<b>ROM Subsystem</b> .....	<b>1-11</b>
<b>RAM Subsystem</b> .....	<b>1-12</b>
<b>Direct Memory Access (DMA)</b> .....	<b>1-12</b>
Programming the 16-Bit DMA Channels .....	1-14
<b>I/O Channel</b> .....	<b>1-15</b>
I/O Channel Signal Description .....	1-22
<b>Other Circuits</b> .....	<b>1-30</b>
Speaker .....	1-30
Jumper .....	1-30
Type of Display Adapter Switch .....	1-31
Variable Capacitor .....	1-31
Keyboard Controller .....	1-31
Receiving Data from the Keyboard .....	1-32
Scan Code Translation .....	1-32
Sending Data to the Keyboard .....	1-37
Inhibit .....	1-37
Keyboard Controller System Interface .....	1-37

Status Register .....	1-38
Status-Register Bit Definition .....	1-38
Output Buffer .....	1-39
Input Buffer .....	1-40
Commands (I/O Address hex 64) .....	1-40
I/O Ports .....	1-43
Real-time Clock/Complementary Metal Oxide Semiconductor (RT/CMOS) RAM Information .....	1-45
Real-time Clock Information .....	1-45
CMOS RAM Configuration Information .....	1-48
I/O Operations .....	1-54
<b>Specifications .....</b>	<b>1-55</b>
System Unit .....	1-55
Size .....	1-55
Weight .....	1-55
Power Cables .....	1-55
Environment .....	1-55
Heat Output .....	1-56
Noise Level .....	1-56
Electrical .....	1-56
Connectors .....	1-57
Logic Diagrams .....	1-61

# Description

The system board is approximately 30.5 by 33 centimeters (12 by 13 inches) and uses very large scale integration (VLSI) technology. It has the following components:

- Intel 80286 Microprocessor
- System support function:
  - 7-Channel Direct Memory Access (DMA)
  - 16-level interrupt
  - System clock
  - Three programmable timers
- 64Kb read-only memory (ROM) subsystem, expandable to 128Kb
- Either a 256Kb or a 512Kb random-access memory (RAM) Subsystem
- Speaker attachment
- Complementary metal oxide semiconductor (CMOS) memory RAM to maintain system configuration
- Real-Time clock
- Battery backup for CMOS configuration table and Real-Time Clock
- Keyboard attachment
- 8 input/output (I/O) slots:
  - 6 with a 36- and a 62-pin card-edge socket.
  - 2 with only the 62-pin card-edge socket.

# **Memory**

The system board has two banks of memory sockets, each supporting 18 128K by 1 modules for a total maximum memory size of 512Kb, with parity checking.

# **Microprocessor**

The Intel 80286 Microprocessor has a 24-bit address, 16-bit memory interface<sup>1</sup>, an extensive instruction set, DMA and interrupt support capabilities, a hardware fixed-point multiply and divide, integrated memory management, four-level memory protection, 1-gigabyte (1,073,741,824 bytes) of virtual address space for each task, and two operating modes: the 8086-compatible real-address mode and the protected virtual-address mode. More detailed descriptions of the microprocessor may be found in the publications listed in the Bibliography of this manual.

## **Real-Address Mode**

In the real-address mode, the microprocessor's physical memory is a contiguous array of up to one megabyte. The microprocessor addresses memory by generating 20-bit physical addresses.

The selector portion of the pointer is interpreted as the upper 16 bits of a 20-bit segment address. The lower 4 bits of the 20-bit segment address are always zero. Therefore, segment addresses begin on multiples of 16 bytes.

All segments in the real-address mode are 64Kb in size and may be read, written, or executed. An exception or interrupt can occur if data operands or instructions attempt to wrap around the end of a segment; for example, a word with its low-order byte at offset FFFF and its high-order byte at 0000. If, in the real-address mode, the information contained in the segment does

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In this manual, the term interface refers to a device that carries signals between functional units.

not use the full 64Kb, the unused end of the segment may be overlayed by another segment to reduce physical memory requirements.

## Protected Mode

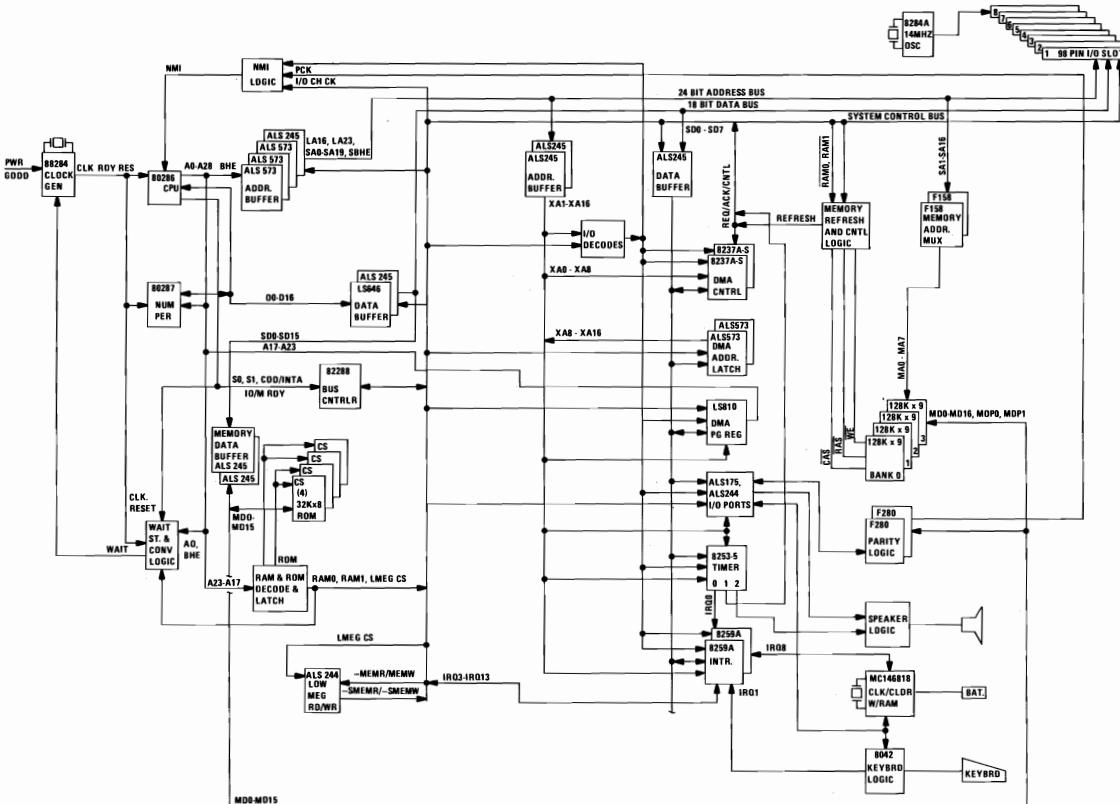
The protected mode offers extended physical and virtual memory address space, memory protection mechanisms, and new operations to support operating systems and virtual memory.

The protected mode provides a 1-gigabyte virtual address space per task mapped into a 16-megabyte physical address space. The virtual address space may be larger than the physical address space, because any use of an address that does not map to a physical memory location will cause a restartable exception.

As in the real-address mode, the protected mode uses 32-bit pointers, consisting of 16-bit selector and offset components. The selector, however, specifies an index into a memory resident table rather than the upper 16 bits of a real memory address. The 24-bit base address of the desired segment is obtained from the tables in memory. The 16-bit offset is added to the segment base address to form the physical address. The tables are automatically referenced by the microprocessor whenever a segment register is loaded with a selector. All instructions that load a segment register will refer to the memory based-tables without additional program support. The memory-based tables contain 8-byte values called *descriptors*.

Following is a block diagram of the system board.

## 1-6 System Board



System Board Block Diagram

# System Performance

The 80286 Microprocessor operates at 6 MHz, which results in a clock cycle time of 167 nanoseconds.

A bus cycle requires three clock cycles (which includes 1 wait state) so that a 500-nanosecond, 16-bit, microprocessor cycle time is achieved. 8-bit bus operations to 8-bit devices take 6 clock cycles (which include 4 wait states), resulting in a 1000-nanosecond microprocessor cycle. 16-bit bus operations to 8-bit devices take 12 clock cycles (which include 10 I/O wait states) resulting in a 2000 nanosecond microprocessor cycle.

The refresh controller operates at 6 MHz. Each refresh cycle requires 5 clock cycles to refresh all of the system's dynamic memory; 256 refresh cycles are required every 4 milliseconds. The following formula determines the percent of bandwidth used for refresh.

$$\% \text{ Bandwidth used} = \frac{5 \text{ cycles} \times 256}{4 \text{ ms}/167 \text{ ns}} = \frac{1280}{24000} = 5.3\%$$

The DMA controller operates at 3 MHz, which results in a clock cycle time of 333 nanoseconds. All DMA data-transfer bus cycles are five clock cycles or 1.66 microseconds. Cycles spent in the transfer of bus control are not included.

DMA channels 0, 1, 2, and 3 are used for 8-bit data transfers, and channels 5, 6, and 7 process 16-bit transfers. Channel 4 is used to cascade channels 0 through 3 to the microprocessor.

The following figure is a system memory map.

<b>Address</b>	<b>Name</b>	<b>Function</b>
000000 to 07FFFF	512Kb system board	System board memory
080000 to 09FFFF	128Kb	I/O channel memory - IBM Personal Computer AT 128KB Memory Expansion Option
0A0000 to 0BFFFF	128Kb video RAM	Reserved for graphics display buffer
0C0000 to 0DFFFF	128Kb I/O expansion ROM	Reserved for ROM on I/O adapters
OE0000 to OEFFFF	64Kb Reserved on system board	Duplicated code assignment at address FE0000
OF0000 to OFFFFF	64Kb ROM on the system board	Duplicated code assignment at address FF0000
100000 to FDFFFF	Maximum memory 15Mb	I/O channel memory - IBM Personal Computer AT 512KB Memory Expansion Option
FE0000 to FEFFFF	64Kb Reserved on system board	Duplicated code assignment at address OE0000
FF0000 to FFFFFFF	64Kb ROM on the system board	Duplicated code assignment at address OF0000

### **System Memory Map**

## **System Timers**

The system has three programmable timer/counters controlled by an Intel 8254-2 timer/counter chip and defined as Channels 0 through 2 as follows:

**Channel 0              System Timer**

**GATE 0**              Tied on

**CLK IN 0**              1.190 MHz OSC

**CLK OUT 0**              8259A IRQ 0

**Channel 1              Refresh Request Generator**

**GATE 1** Tied on

**CLK IN 1** 1.190 MHz OSC

**CLK OUT 1** Request Refresh Cycle

**Note:** Channel 1 is programmed as a rate generator to produce a 15-microsecond period signal.

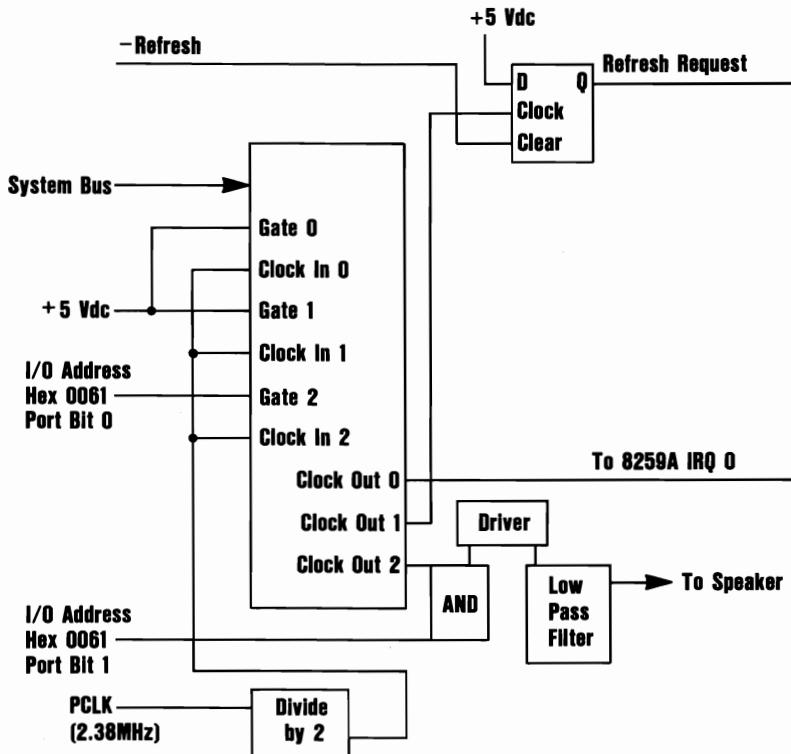
**Channel 2** Tone Generation for Speaker

**GATE 2** Controlled by bit 0 of port hex 61 PPI bit

**CLK IN 2** 1.190 MHz OSC

**CLK OUT 2** Used to drive the speaker

The 8254-2 Timer/Counter is a programmable interval timer/counter that system programs treat as an arrangement of four external I/O ports. Three ports are treated as counters; the fourth is a control register for mode programming. Following is a system-timer block diagram.



## System Interrupts

The 80286 Microprocessor NMI and two 8259A Interrupt Controller chips provide 16 levels of system interrupts. The following shows the interrupt-level assignments in decreasing priority.

**Note:** Any or all interrupts may be masked (including the microprocessor's NMI).

Level	Function
MicroProcessor NMI	Parity or I/O Channel Check
Interrupt Controllers CTLR 1      CTLR 2	
IRQ 0	Timer Output 0
IRQ 1	Keyboard (Output Buffer Full)
IRQ 2	Interrupt from CTLR 2
IRQ 3	Realtime Clock Interrupt
IRQ 4	Software Redirected to INT 0AH (IRQ 2)
IRQ 5	Reserved
IRQ 6	Reserved
IRQ 7	Reserved
IRQ 8	Reserved
IRQ 9	Coprocessor
IRQ 10	Fixed Disk Controller
IRQ 11	Reserved
IRQ 12	Serial Port 2
IRQ 13	Serial Port 1
IRQ 14	Parallel Port 2
IRQ 15	Diskette Controller
	Parallel Port 1

## ROM Subsystem

The system board's ROM subsystem consists of two 32K by 8-bit ROM/EPROM modules or four 16K by 8-bit ROM/EPROM modules in a 32K by 16-bit arrangement. The code for odd and even addresses resides in separate modules. ROM is assigned at the top of the first and last 1M address space (hex 0F0000 and hex FF0000). ROM is not parity-checked. Its access time is 150 nanoseconds and its cycle time is 230 nanoseconds.

## **RAM Subsystem**

The system board's RAM subsystem starts at address hex 000000 of the 16M address space. It consists of either 256Kb or 512Kb of 128K by 1-bit RAM modules. Memory access time is 150 nanoseconds and the cycle time is 275 nanoseconds.

Memory-refresh requests one memory cycle every 15 microseconds through the timer/counter (channel 1). The RAM initialization program performs the following functions:

- Initializes channel 1 of the timer/counter to the rate generation mode, with a period of 15 microseconds.
- Performs a memory write operation to any memory location

**Note:** The memory must be accessed or refreshed eight times before it can be used.

## **Direct Memory Access (DMA)**

The system supports seven DMA channels. Two Intel 8237A-5 DMA Controller Chips are used, with four channels for each chip. The DMA channels are assigned as follows:

Ctlr 1	Ctlr 2
Ch 0 - Spare	Ch 4 - Cascade for Ctlr 1
Ch 1 - SDLC	Ch 5 - Spare
Ch 2 - Diskette (IBM Personal Computer)	Ch 6 - Spare
Ch 3 - Spare	Ch 7 - Spare

### **DMA Channels**

DMA controller 1 contains channels 0 through 3. These channels support 8-bit data transfers between 8-bit I/O adapters and 8- or

16-bit system memory. Each channel can transfer data throughout the 16-megabyte system-address space in 64Kb blocks.

DMA controller 2 contains channels 4 through 7. Channel 4 is used to cascade channels 0 through 3 to the microprocessor. Channels 5, 6, and 7 support 16-bit data transfers between 16-bit I/O adapters and 16-bit system memory. These DMA channels can transfer data throughout the 16-megabyte system-address space in 128Kb blocks. Channels 5, 6, and 7 cannot transfer data on odd byte boundaries.

The following figure shows the addresses for the page register.

<b>Page Register</b>	<b>I/O Hex Address</b>
DMA Channel 0	0087
DMA Channel 1	0083
DMA Channel 2	0081
DMA Channel 3	0082
DMA Channel 5	008B
DMA Channel 6	0089
DMA Channel 7	008A
Refresh	008F

### **Page Register Addresses**

The following figures show address generation for the DMA channels.

<b>Source</b>	<b>DMA Page Registers</b>	<b>8237A-5</b>
Address	A23<----->A16	A15<----->A0

### **Address Generation for DMA Channels 3 through 0**

**Note:** The addressing signal, 'byte high enable' (BHE), is generated by inverting address line A0.

<b>Source</b>	<b>DMA Page Registers</b>	<b>8237A-5</b>
Address	A23<----->A17	A16<----->A1

### **Address Generation for DMA Channels 7 through 5**

**Note:** The addressing signals, 'BHE' and 'A0', are forced to a logic 0.

Addresses for all DMA channels do not increase or decrease through page boundaries (64Kb for channels 0 through 3 and 128Kb for channels 5 through 7).

## Programming the 16-Bit DMA Channels

DMA channels 5 through 7 perform 16-bit data transfers. Access can be gained only to 16 bit devices (I/O or memory) during the DMA cycles of channels 5 through 7. Access to the DMA controller (8237A-5), which controls these channels, is through I/O addresses 0C0 through 0DF. The command codes for the DMA controller are as follows:

Hex Address	Command Codes
0C0	CH0 base and current address
0C2	CH0 base and current word count
0C4	CH1 base and current address
0C6	CH1 base and current word count
0C8	CH2 base and current address
0CA	CH2 base and current word count
0CC	CH3 base and current address
0CE	CH3 base and current word count
0D0	Read Status Register/Write Command Register
0D2	Write Request Register
0D4	Write Single Mask Register Bit
0D6	Write Mode Register
0D8	Clear Byte Pointer Flip-Flop
0DA	Read Temporary Register/Write Master Clear
0DC	Clear Mask Register
0DE	Write All Mask Register Bits

## DMA Controller Registers

All DMA memory transfers made with channels 5 through 7 must occur on even-byte boundaries. When the base address for these channels is programmed, the real address divided by 2 is the data that is written to the base address register. Also, when the base word count for channels 5 through 7 is programmed, the count is the number of 16-bit words to be transferred. Therefore, DMA channels 5 through 7 can transfer 65,536 words or 128Kb maximum for any selected page of memory. These DMA channels divide the 16Mb memory space into 128Kb pages. When the DMA page registers for channels 5 through 7 are

programmed, data bits D7 through D1 should contain the high-order seven address bits (A23 through A17) of the desired memory space. Data bit D0 of the page registers for channels 5 through 7 is not used in the generation of the DMA memory address.

After power-up time, all internal locations, especially the mode registers, should be loaded with some valid value. This should be done even if some channels are unused.

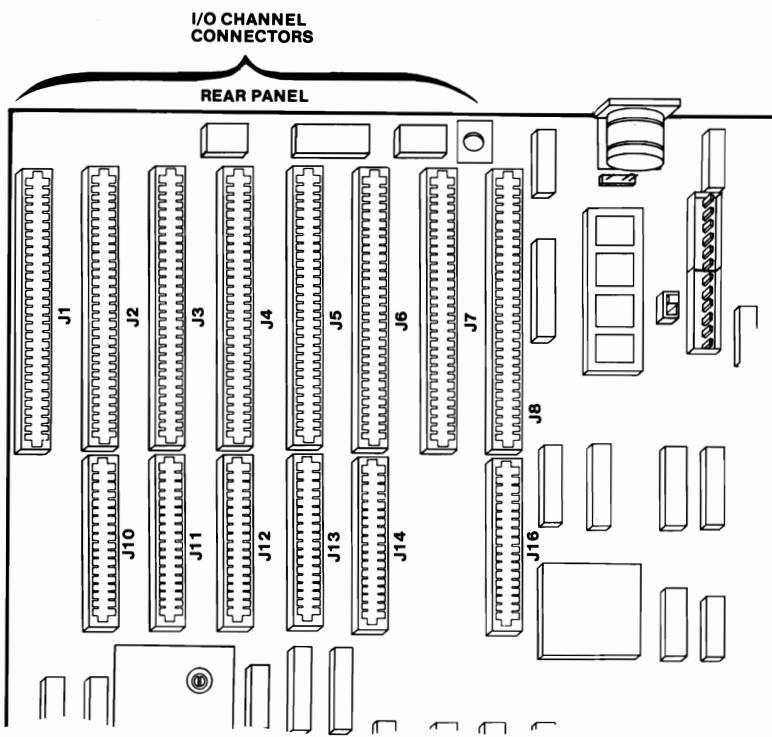
## I/O Channel

The I/O channel supports:

- I/O address space hex 100 to hex 3FF
- 24-bit memory addresses (16Mb)
- Selection of data accesses (either 8- or 16-bit)
- Interrupts
- DMA channels
- I/O wait-state generation
- Open-bus structure (allowing multiple microprocessors to share the system's resources, including memory)
- Refresh of system memory from channel microprocessors.

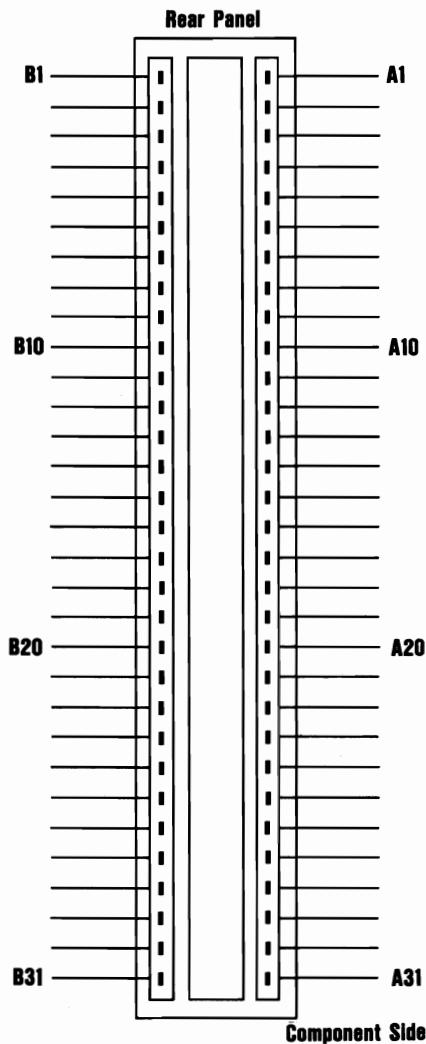
The following figure shows the location and the numbering of the I/O channel connectors. These connectors consist of eight 62-pin and six 36-pin edge connector sockets.

**Note:** In two positions on the I/O channel, the 36-pin connector is not present. These positions can support only 62-pin I/O bus adapters.



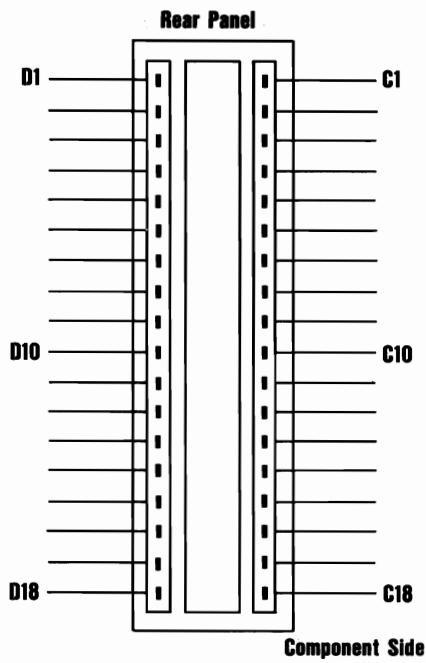
1-16 System Board

The following figure shows the pin numbering for I/O channel connectors J1 through J8.



**I/O Channel Pin Numbering  
(J1-J8)**

The following figure shows the pin numbering for I/O channel connectors J12 through J16 and J18.



**I/O Channel Pin Numbering  
(J10-J14 and J16)**

The following figures summarize pin assignments for the I/O channel connectors.

I/O Pin	Signal Name	I/O
A 1	-I/O CH CK	I
A 2	SD7	I/O
A 3	SD6	I/O
A 4	SD5	I/O
A 5	SD4	I/O
A 6	SD3	I/O
A 7	SD2	I/O
A 8	SD1	I/O
A 9	SD0	I/O
A 10	-I/O CH RDY	I
A 11	AEN	O
A 12	SA19	I/O
A 13	SA18	I/O
A 14	SA17	I/O
A 15	SA16	I/O
A 16	SA15	I/O
A 17	SA14	I/O
A 18	SA13	I/O
A 19	SA12	I/O
A 20	SA11	I/O
A 21	SA10	I/O
A 22	SA9	I/O
A 23	SA8	I/O
A 24	SA7	I/O
A 25	SA6	I/O
A 26	SA5	I/O
A 27	SA4	I/O
A 28	SA3	I/O
A 29	SA2	I/O
A 30	SA1	I/O
A 31	SA0	I/O

#### I/O Channel (A-Side, J1 through J8)

I/O Pin	Signal Name	I/O
B 1	GND	Ground
B 2	RESET DRV	0
B 3	+5 Vdc	Power
B 4	IRQ 9	I
B 5	-5 Vdc	Power
B 6	DRQ2	I
B 7	-12 Vdc	Power
B 8	OWS	I
B 9	+12 Vdc	Power
B 10	GND	Ground
B 11	-SMEMW	0
B 12	-SMEMR	0
B 13	-IOW	I/O
B 14	-IOR	I/O
B 15	-DACK3	0
B 16	DRQ3	I
B 17	-DACK1	0
B 18	DRQ1	I
B 19	-Refresh	I/O
B 20	CLK	0
B 21	IRQ7	I
B 22	IRQ6	I
B 23	IRQ5	I
B 24	IRQ4	I
B 25	IRQ3	I
B 26	-DACK2	0
B 27	T/C	0
B 28	BALE	0
B 29	+5 Vdc	Power
B 30	OSC	0
B 31	GND	Ground

### I/O Channel (B-Side J1, through J8)

I/O Pin	Signal Name	I/O
C 1	SBHE	I/O
C 2	LA23	I/O
C 3	LA22	I/O
C 4	LA21	I/O
C 5	LA20	I/O
C 6	LA19	I/O
C 7	LA18	I/O
C 8	LA17	I/O
C 9	-MEMR	I/O
C 10	-MEMW	I/O
C 11	SD08	I/O
C 12	SD09	I/O
C 13	SD10	I/O
C 14	SD11	I/O
C 15	SD12	I/O
C 16	SD13	I/O
C 17	SD14	I/O
C 18	SD15	I/O

### I/O Channel (C-Side J10 through J14 and J16)

I/O Pin	Signal Name	I/O
D 1	-MEM CS16	-
D 2	-I/O CS16	-
D 3	IRQ10	-
D 4	IRQ11	-
D 5	IRQ12	-
D 6	IRQ15	-
D 7	IRQ14	-
D 8	-DACK0	0
D 9	DRQ0	-
D 10	-DACK5	0
D 11	DRQ5	-
D 12	-DACK6	0
D 13	DRQ6	-
D 14	-DACK7	0
D 15	DRQ7	-
D 16	+5 Vdc	Power
D 17	-MASTER	-
D 18	GND	Ground

### I/O Channel (D-Side, J10 through J14 and J16)

## I/O Channel Signal Description

The following is a description of the system board's I/O channel signals. All signal lines are TTL-compatible. I/O adapters should be designed with a maximum of two low-power Shottky (LS) loads per line.

### SA0 through SA19 (I/O)

Address bits 0 through 19 are used to address memory and I/O devices within the system. These 20 address lines, in addition to LA17 through LA23, allow access of up to 16Mb of memory. SA0 through SA19 are gated on the system bus when 'BALE' is high and are latched on the falling edge of 'BALE.' These signals are generated by the microprocessor or DMA Controller. They also may be driven by other microprocessors or DMA controllers that reside on the I/O channel.

### LA17 through LA23 (I/O)

These signals (unlatched) are used to address memory and I/O devices within the system. They give the system up to 16Mb of addressability. These signals are valid when 'BALE' is high. LA17 through LA23 are not latched during microprocessor cycles and therefore do not stay valid for the whole cycle. Their purpose is to generate memory decodes for 1 wait-state memory cycles. These decodes should be latched by I/O adapters on the falling edge of 'BALE.' These signals also may be driven by other microprocessors or DMA controllers that reside on the I/O channel.

### CLK (0)

This is the 6-MHz system clock. It is a synchronous microprocessor cycle clock with a cycle time of 167 nanoseconds. The clock has a 50% duty cycle. This signal should only be used for synchronization. It is not intended for uses requiring a fixed frequency.

## RESET DRV (0)

'Reset drive' is used to reset or initialize system logic at power-up time or during a low line-voltage outage. This signal is active high.

## SD0 through SD15 (I/O)

These signals provide bus bits 0 through 15 for the microprocessor, memory, and I/O devices. D0 is the least-significant bit and D15 is the most-significant bit. All 8-bit devices on the I/O channel should use D0 through D7 for communications to the microprocessor. The 16-bit devices will use D0 through D15. To support 8-bit devices, the data on D8 through D15 will be gated to D0 through D7 during 8-bit transfers to these devices; 16-bit microprocessor transfers to 8-bit devices will be converted to two 8-bit transfers.

## BALE (0) (buffered)

'Address latch enable' is provided by the 82288 Bus Controller and is used on the system board to latch valid addresses and memory decodes from the microprocessor. It is available to the I/O channel as an indicator of a valid microprocessor or DMA address (when used with 'AEN'). Microprocessor addresses SA0 through SA19 are latched with the falling edge of 'BALE.' 'BALE' is forced high during DMA cycles.

## -I/O CH CK (I)

'-I/O channel check' provides the system board with parity (error) information about memory or devices on the I/O channel. When this signal is active, it indicates an uncorrectable system error.

## **I/O CH RDY (I)**

'I/O channel ready' is pulled low (not ready) by a memory or I/O device to lengthen I/O or memory cycles. Any slow device using this line should drive it low immediately upon detecting its valid address and a Read or Write command. Machine cycles are extended by an integral number of clock cycles (167 nanoseconds). This signal should be held low for no more than 2.5 microseconds.

## **IRQ3-IRQ7, IRQ9-IRQ12 and IRQ 14 through 15 (I)**

Interrupt Requests 3 through 7, 9 through 12, and 14 through 15 are used to signal the microprocessor that an I/O device needs attention. The interrupt requests are prioritized, with IRQ9 through IRQ12 and IRQ14 through IRQ15 having the highest priority (IRQ9 is the highest) and IRQ3 through IRQ7 having the lowest priority (IRQ7 is the lowest). An interrupt request is generated when an IRQ line is raised from low to high. The line must be held high until the microprocessor acknowledges the interrupt request (Interrupt Service routine). Interrupt 13 is used on the system board and is not available on the I/O channel. Interrupt 8 is used for the real-time clock.

### **-IOR (I/O)**

'-I/O Read' instructs an I/O device to drive its data onto the data bus. It may be driven by the system microprocessor or DMA controller, or by a microprocessor or DMA controller resident on the I/O channel. This signal is active low.

### **-IOW (I/O)**

'-I/O Write' instructs an I/O device to read the data on the data bus. It may be driven by any microprocessor or DMA controller in the system. This signal is active low.

## **-SMEMR (O) -MEMR (I/O)**

These signals instruct the memory devices to drive data onto the data bus. '-SMEMR' is active only when the memory decode is within the low 1Mb of memory space. '-MEMR' is active on all memory read cycles. '-MEMR' may be driven by any microprocessor or DMA controller in the system. '-SMEMR' is derived from '-MEMR' and the decode of the low 1Mb of memory. When a microprocessor on the I/O channel wishes to drive '-MEMR', it must have the address lines valid on the bus for one system clock period before driving '-MEMR' active. Both signals are active LOW.

## **-SMEMW (O) -MEMW (I/O)**

These signals instruct the memory devices to store the data present on the data bus. '-SMEMW' is active only when the memory decode is within the low 1Mb of the memory space. '-MEMW' is active on all memory read cycles. '-MEMW' may be driven by any microprocessor or DMA controller in the system. '-SMEMW' is derived from '-MEMW' and the decode of the low 1Mb of memory. When a microprocessor on the I/O channel wishes to drive '-MEMW', it must have the address lines valid on the bus for one system clock period before driving '-MEMW' active. Both signals are active low.

## **DRQ0-DRQ3 and DRQ5-DRQ7 (I)**

DMA Requests 0 through 3 and 5 through 7 are asynchronous channel requests used by peripheral devices and the I/O channel microprocessors to gain DMA service (or control of the system). They are prioritized, with 'DRQ0' having the highest priority and 'DRQ7' having the lowest. A request is generated by bringing a DRQ line to an active level. A DRQ line must be held high until the corresponding 'DMA Request Acknowledge' (DACK) line goes active. 'DRQ0' through 'DRQ3' will perform 8-bit DMA transfers; 'DRQ5' through 'DRQ7' will perform 16-bit transfers. 'DRQ4' is used on the system board and is not available on the I/O channel.

### **-DACK0 to -DACK3 and -DACK5 to -DACK7 (O)**

-DMA Acknowledge 0 to 3 and 5 to 7 are used to acknowledge DMA requests (DRQ0 through DRQ7). They are active low.

### **AEN (O)**

'Address Enable' is used to degate the microprocessor and other devices from the I/O channel to allow DMA transfers to take place. When this line is active, the DMA controller has control of the address bus, the data-bus Read command lines (memory and I/O), and the Write command lines (memory and I/O).

### **-REFRESH (I/O)**

This signal is used to indicate a refresh cycle and can be driven by a microprocessor on the I/O channel.

### **T/C (O)**

'Terminal Count' provides a pulse when the terminal count for any DMA channel is reached.

### **SBHE (I/O)**

'Bus High Enable' (system) indicates a transfer of data on the upper byte of the data bus, SD8 through SD15. Sixteen-bit devices use 'SBHE' to condition data bus buffers tied to SD8 through SD15.

### **-MASTER (I)**

This signal is used with a DRQ line to gain control of the system. A processor or DMA controller on the I/O channel may issue a DRQ to a DMA channel in cascade mode and receive a '-DACK'. Upon receiving the '-DACK', an I/O microprocessor may pull '-MASTER' low, which will allow it to

# **UPDATE NUMBER 4**

## **IBM TECHNICAL REFERENCE UPDATE**

**Note:** All previous Technical Reference updates must be installed before installing this update.

This package contains updates to the IBM Personal Computer AT *Technical Reference* manual.

# **IBM PERSONAL COMPUTER AT TECHNICAL REFERENCE UPDATE**

The following pages update the *Technical Reference* for the IBM Personal Computer AT.

Replace or add the update pages as instructed below.

1-27 and 1-28      Replace

1-28.1 and 1-28.2    Replace

Discard this instruction sheet.

control the system address, data, and control lines (a condition known as *tri-state*). After '-MASTER' is low, the I/O microprocessor must wait one system clock period before driving the address and data lines, and two clock periods before issuing a Read and Write command. If this signal is held low for more than 15 microseconds, system memory may be lost because of a lack of refresh.

### **-MEM CS16 (I)**

'-MEM 16 Chip Select' signals the system board if the present data transfer is a 1 wait-state, 16-bit, memory cycle. It must be derived from the decode of LA17 through LA23. '-MEM CS16' should be driven with an open collector or tri-state driver capable of sinking 20 mA.

### **-I/O CS16 (I)**

'-I/O 16 bit Chip Select' signals the system board that the present data transfer is a 16-bit, 1 wait-state, I/O cycle. It is derived from an address decode. '-I/O CS16' is active low and should be driven with an open collector or tri-state driver capable of sinking 20 mA.

### **OSC (O)**

'Oscillator' (OSC) is a high-speed clock with a 70-nanosecond period (14.31818 MHz). This signal is not synchronous with the system clock. It has a 50% duty cycle.

### **0WS (I)**

The 'Zero Wait State' (0WS) signal tells the microprocessor that it can complete the present bus cycle without inserting any additional wait cycles. In order to run a memory cycle to a 16-bit device without wait cycles, '0WS' is derived from an address decode gated with a Read or Write command. In order to run a memory cycle to an 8-bit device with a minimum of two wait states, '0WS' should be driven active one system clock after the

Read or Write command is active gated with the address decode for the device. Memory Read and Write commands to an 8-bit device are active on the falling edge of the system clock. '0WS' is active low and should be driven with an open collector or tri-state driver capable of sinking 20 mA.

The following figure is an I/O address map.

Hex Range*	Usage
000-01F	DMA controller 1, 8237A-5
020-03F	Interrupt controller 1, 8259A, Master
02E1	GPIB (Adapter 0)
02E2 & 02E3	Data Acquisition (Adapter 0)
040-05F	Timer 8254.2
060-06F	8042 (Keyboard)
06E2 & 06E3	Data Acquisition (Adapter 1)
070-07F	Real-time clock, NMI (non-maskable interrupt) mask
080-09F	DMA page registers, 74LS612
0A0-0BF	Interrupt controller 2, 8259A
0AE2 & 0AE3	Data Acquisition (Adapter 2)
0CO-ODF	DMA controller 2,8237A-5
0EE2 & 0EE3	Data Acquisition (Adapter 3)
OF0	Clear Math Coprocessor Busy
OF1	Reset Math Coprocessor
OF8-OFF	Math Coprocessor
1F0-1F8	Fixed Disk
200-207	Game I/O
22E1	GPIB (Adapter 1)
278-27F	Parallel printer port 2
2B0-2DF	Alternate Enhanced Graphics Adapter
2F8-2FF	Serial port 2

**Note:** I/O addresses, hex 000 to OFF, are reserved for the system board I/O. Hex 100 to 3FF are available on the I/O channel. The base addresses for GPIB and Data Acquisition are shown.

#### I/O Address Map (Part 1 of 2)

<b>Hex Range*</b>	<b>Usage</b>
300-31F	Prototype card
360-36F	P C Network
378-37F	Parallel printer port 1
380-38F	SDLC, bisynchronous 2
390-393	Cluster
3A0-3AF	Bisynchronous 1
3B0-3BF	Monochrome Display and Printer Adapter
3C0-3CF	Enhanced Graphics Adapter
3D0-3DF	Color / Graphics Monitor Adapter
3F0-3F7	Diskette controller
3F8-3FF	Serial port 1
42E1	GPIB (Adapter 2)
62E1	GPIB (Adapter 3)
790-793	Cluster (Adapter 1)
82E1	GPIB (Adapter 4)
A2E1	GPIB (Adapter 5)
B90-B93	Cluster (Adapter 2)
C2E1	GPIB (Adapter 6)
E2E1	GPIB (Adapter 7)
1390-1393	Cluster (Adapter 3)
2390-2393	Cluster (Adapter 4)

**Note:** I/O addresses, hex 000 to OFF, are reserved for the system board I/O. Hex 100 to 3FF are available on the I/O channel. The base addresses for GPIB and Data Acquisition are shown.

#### I/O Address Map (Part 2 of 2)

At power on time, the non-maskable interrupt (NMI) into the 80286 is masked off. The mask bit can be set and reset with system programs as follows:

**Mask On**   Write to I/O address hex 070, with data bit 7 equal to a logic 0

**Mask Off** Write to I/O address hex 070, with data bit 7 equal to a logic 1

**Note:** At the end of POST, the system sets the NMI mask on (NMI enabled).

The following is a description of the Math Coprocessor controls.

- 0F0** An 8-bit Out command to port F0 will clear the latched Math Coprocessor busy signal. 'Busy' will be latched if the coprocessor asserts its error signal while it is busy. The data output should be zero.
- 0F1** An 8-bit Out command to port F1 will reset the Math Coprocessor. The data output should be zero.

I/O address hex 080 is used as a diagnostic-checkpoint port or register. This port corresponds to a read/write register in the DMA page register (74LS612).

The '-I/O channel check signal' (-I/O CH CK) is used to report uncorrectable errors on RAM adapters on the I/O channel. This check will create a non-maskable interrupt (NMI) if enabled (see the figure, "I/O Address Map," for enable control). At power-on time, the NMI is masked off and check is disabled. Before check or NMI is enabled, the following steps should be taken.

1. Write data in all I/O RAM-adapter memory locations; this will establish good parity at all locations.
2. Enable I/O channel check.
3. Enable NMI.

**Note:** All three of these functions are performed by POST.

When a check occurs, an interrupt (NMI) will result. Check the status bits to determine the source of the NMI (see the figure, "I/O Address Map"). To determine the location of the failing adapter, write to any memory location within a given adapter. If the parity check was from that adapter, '-I/O CH CK' will be inactive.

# Other Circuits

## Speaker

The system unit has a 2-1/4 inch permanent-magnet speaker, which can be driven from:

- The I/O-port output bit
- The timer/counter's clock out
- Both

## Jumper

The system board has a 3-pin, Berg-strip connector. The placement of a jumper across the pins of the connector determines whether the system board's 2nd 256Kb of RAM is enabled or disabled. Following are the pin assignments for the connector.

Pin	Assignments
1	No connection
2	Ground
3	A8 (28S42)

### RAM Jumper Connector(J18)

The following shows how the jumper affects RAM.

Jumper Positions	Function
1 and 2	Enable 2nd 256Kb of system board ram
2 and 3	Disable 2nd 256Kb of system board ram

### RAM Jumper

**Note:** The normal mode is the enable mode. The disable mode permits the 2nd 256Kb of RAM to reside on adapters plugged into the I/O bus.

## Type of Display Adapter Switch

The system board has a slide switch, the purpose of which is to tell the system into which display adapter the primary display is attached. Its positions are assigned as follows:

**On (toward the rear of the system unit):** The primary display is attached to Color/Graphics Monitor Adapter.

**Off (toward the front of the system unit):** The primary display is attached to the Monochrome Display and Printer Adapter.

**Note:** The primary display is activated when the system is turned on.

## Variable Capacitor

The system board has a variable capacitor. Its purpose is to adjust the 14.31818 MHz oscillator (OSC) signal that is used to obtain the color burst signal required for color televisions.

## Keyboard Controller

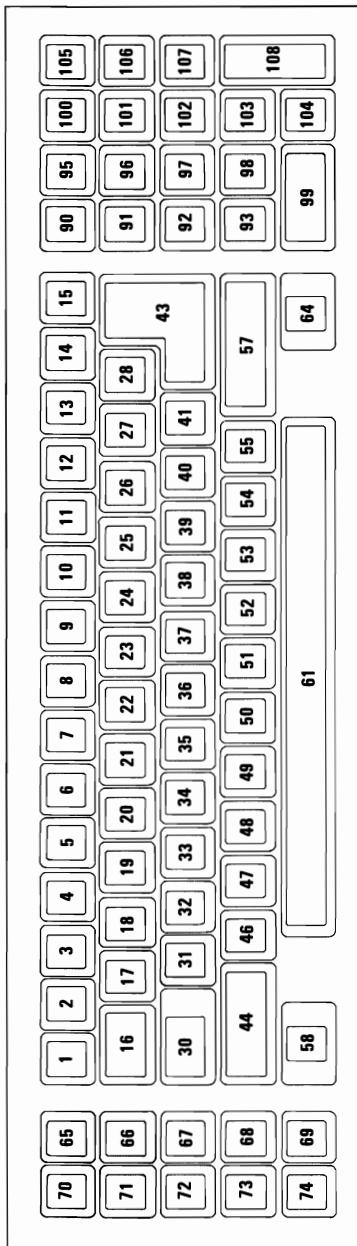
The keyboard controller is a single-chip microcomputer (Intel 8042) that is programmed to support the IBM Personal Computer AT Keyboard serial interface. The keyboard controller receives serial data from the keyboard, checks the parity of the data, translates scan codes, and presents the data to the system as a byte of data in its output buffer. The controller will interrupt the system when data is placed in its output buffer. The status register contains bits that indicate if an error was detected while receiving the data. Data may be sent to the keyboard by writing to the keyboard controller's input buffer. The byte of data will be sent to the keyboard serially with an odd parity bit automatically inserted. The keyboard is required to acknowledge all data transmissions. No transmission should be sent to the keyboard until acknowledgment is received for the previous byte sent.

## **Receiving Data from the Keyboard**

The keyboard sends data in a serial format using an 11-bit frame. The first bit is a start bit, and is followed by eight data bits, an odd parity bit, and a stop bit. Data sent is synchronized by a clock supplied by the keyboard. At the end of a transmission, the keyboard controller disables the interface until the system accepts the byte. If the byte of data is received with a parity error, a Resend command is automatically sent to the keyboard. If the keyboard controller is unable to receive the data correctly, a hex FF is placed in its output buffer, and the parity bit in the status register is set to 1, indicating a receive parity error. The keyboard controller will also time a byte of data from the keyboard. If a keyboard transmission does not end within two milliseconds, a hex FF is placed in the keyboard controller's output buffer, and the receive time-out bit in the status register is set. No retries will be attempted on a receive time-out error.

## **Scan Code Translation**

Scan codes, which are received from the keyboard, are converted by the keyboard controller before they are put into the controller's output buffer. The following figure shows the keyboard layout with key numbers.



The following figure is the scan-code translation table.

Keyboard Scan Code	Key	System Scan Code
00		FF
76	90	01
16	2	02
1E	3	03
26	4	04
25	5	05
2E	6	06
36	7	07
3D	8	08
3E	9	09
46	10	0A
45	11	0B
4E	12	0C
55	13	0D
66	15	0E
0D	16	0F
15	17	10
1D	18	11
24	19	12
2D	20	13
2C	21	14
35	22	15
3C	23	16
43	24	17
44	25	18
4D	26	19
54	27	1A
5B	28	1B
5A	43	1C
14	30	1D
1C	31	1E
1B	32	1F
23	33	20
2B	34	21
34	35	22
33	36	23
3B	37	24
42	38	25
4B	39	26
4C	40	27
52	41	28
0E	1	29
12	44	2A
5D	14	2B
1A	46	2C
22	47	2D
21	48	2E
2A	49	2F

(Part 1 of 2).

Scan-Code Translation Table

<b>Keyboard Scan Code</b>	<b>Key</b>	<b>System Scan Code</b>
32	50	30
31	51	31
3A	52	32
41	53	33
49	54	34
4A	55	35
59	57	36
7C	106	37
11	58	38
29	61	39
58	64	3A
05	70	3B
06	65	3C
04	71	3D
0C	66	3E
03	72	3F
0B	67	40
02 or 83	73	41
0A	68	42
01	74	43
09	69	44
77	95	45
7E	100	46
6C	91	47
75	96	48
7D	101	49
7B	107	4A
6B	92	4B
73	97	4C
74	102	4D
79	108	4E
69	93	4F
72	98	50
7A	103	51
70	99	52
71	104	53
7F or 84	105	54

(Part 2 of 2)

**Scan-Code Translation Table**

The following scan codes are reserved.

Keyboard Scan Code	Key	System Scan Code
60	R	55
61	R	56
78	R	57
07	R	58
0F	R	59
17	R	5A
1F	R	5B
27	R	5C
2F	R	5D
37	R	5E
3F	R	5F
47	R	60
4F	R	61
56	R	62
5E	R	63
08	R	64
10	R	65
18	R	66
20	R	67
28	R	68
30	R	69
38	R	6A
40	R	6B
48	R	6C
50	R	6D
57	R	6E
6F	R	6F
13	R	70
19	R	71
39	R	72
51	R	73
53	R	74
5C	R	75
5F	R	76
62	R	77
63	R	78
64	R	79
65	R	7A
67	R	7B
68	R	7C
6A	R	7D
6D	R	7E
6E	R	7F

### Scan-Code Translation Table

## Sending Data to the Keyboard

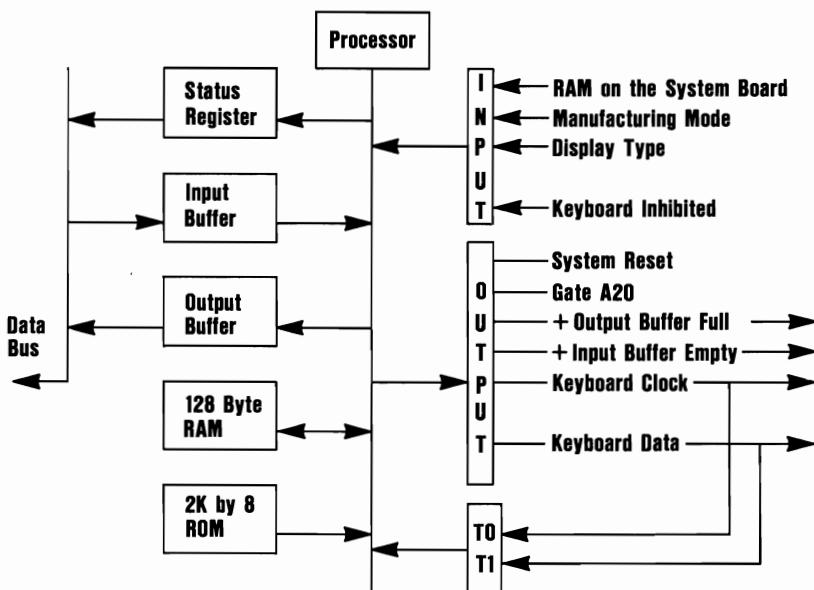
Data is sent to the keyboard in the same serial format used to receive data from the keyboard. A parity bit is automatically inserted by the keyboard controller. If the keyboard does not start clocking the data out of the keyboard controller within 15 milliseconds or complete that clocking within 2 milliseconds, a hex FE is placed in the keyboard controller's output buffer, and the transmit time-out error bit is set in the status register. The keyboard is required to respond to all transmissions. If the response contains a parity error, a hex FE is placed in the keyboard controller's output buffer, and the transmit time-out and parity error bits are set in the status register. The keyboard controller is programmed to set a time limit for the keyboard to respond. If 25 milliseconds are exceeded, the keyboard controller places a hex FE in its output buffer and sets the transmit and receive time-out error bits in the status register. No retries will be made by the keyboard controller for any transmission error.

## Inhibit

The keyboard interface may be inhibited by a key-controlled hardware switch, although all transmissions to the keyboard will be allowed, regardless of the state of the switch. The keyboard controller tests data received from the keyboard to determine if the byte received is a command response or a scan code. If the byte is a command response, it is placed in the keyboard controller's output buffer. If the byte is a scan code, it is ignored.

## Keyboard Controller System Interface

The keyboard controller communicates with the system through a status register, an output buffer, and an input buffer. The following figure is a block diagram of the keyboard interface.



## Status Register

The status register is an 8-bit read-only register at I/O address hex 64. It has information about the state of the keyboard controller (8042) and interface. It may be read at any time.

## Status-Register Bit Definition

- Bit 0**    Output Buffer Full—A 0 indicates that the keyboard controller's output buffer has no data. A 1 indicates that the controller has placed data into its output buffer but the system has not yet read the data. When the system reads the output buffer (I/O address hex 60), this bit will return to a 0.
- Bit 1**    Input Buffer Full—A 0 indicates that the keyboard controller's input buffer (I/O address hex 60 or 64) is

empty. A 1 indicates that data has been written into the buffer but the controller has not read the data. When the controller reads the input buffer, this bit will return to 0.

- Bit 2** System Flag—This bit may be set to 0 or 1 by writing to the system's flag bit in the keyboard controller's command byte. It is set to 0 after a power on reset.
- Bit 3** Command/Data—The keyboard controller's input buffer may be addressed as either I/O address hex 60 or 64. Address hex 60 is defined as the data port, and address hex 64 is defined as the command port. Writing to address hex 64 sets this bit to 1; writing to address hex 60 sets this bit to 0. The controller uses this bit to determine if the byte in its input buffer should be interpreted as a command byte or a data byte.
- Bit 4** Inhibit Switch—This bit is updated whenever data is placed in the keyboard controller's output buffer. It reflects the state of the keyboard-inhibit switch. A 0 indicates the keyboard is inhibited.
- Bit 5** Transmit Time-Out—A 1 indicates that a transmission started by the keyboard controller was not properly completed. If the transmit byte was not clocked out within the specified time limit, this will be the only error. If the transmit byte was clocked out but a response was not received within the programmed time limit, the transmit time-out and receive time-out error bits are set On. If the transmit byte was clocked out but the response was received with a parity error, the transmit time-out and parity error bits are set On.
- Bit 6** Receive Time-Out—A 1 indicates that a transmission was started by the keyboard but did not finish within the programmed receive time-out delay.
- Bit 7** Parity Error—A 0 indicates the last byte of data received from the keyboard had odd parity. A 1 indicates the last byte had even parity. The keyboard should send with odd parity.

## **Output Buffer**

The output buffer is an 8-bit read-only register at I/O address hex 60. The keyboard controller uses the output buffer to send scan codes received from the keyboard, and data bytes requested by command to the system. The output buffer should be read only when the output buffer's full bit in the status register is 1.

## **Input Buffer**

The input buffer is an 8-bit write-only register at I/O address hex 60 or 64. Writing to address hex 60 sets a flag, that indicates a data write; writing to address hex 64 sets a flag, indicating a command write. Data written to I/O address hex 60 is sent to the keyboard, unless the keyboard controller is expecting a data byte following a controller command. Data should be written to the controller's input buffer only if the input buffer's full bit in the status register is equal to 0. The following are valid keyboard controller commands.

## **Commands (I/O Address hex 64)**

- 20**      Read Keyboard Controller's Command Byte—The controller sends its current command byte to its output buffer.
- 60**      Write Keyboard Controller's Command Byte—The next byte of data written to I/O address hex 60 is placed in the controller's command byte. Bit definitions of the command byte are as follows:

**Bit 7**   Reserved—Should be written to a 0.

**Bit 6**   IBM Personal Computer Compatibility Mode—Writing a 1 to this bit causes the controller to convert the scan codes received from the keyboard to those used by the IBM

Personal Computer. This includes converting a two-byte break sequence to the one-byte IBM Personal Computer format.

- Bit 5** IBM Personal Computer Mode—Writing a 1 to this bit programs the keyboard to support the IBM Personal Computer keyboard interface. In this mode the controller does not check parity or convert scan codes.
  - Bit 4** Disable Keyboard—Writing a 1 to this bit disables the keyboard interface by driving the 'clock' line low. Data is not sent or received.
  - Bit 3** Inhibit Override—Writing a 1 to this bit disables the keyboard inhibit function.
  - Bit 2** System Flag—The value written to this bit is placed in the system flag bit of the controller's status register.
  - Bit 1** Reserved—Should be written to a 0.
  - Bit 0** Enable Output-Buffer-Full Interrupt—Writing a 1 to this bit causes the controller to generate an interrupt when it places data into its output buffer.
- AA** Self-Test—This commands the controller to perform internal diagnostic tests. A hex 55 is placed in the output buffer if no errors are detected.
  - AB** Interface Test—This commands the controller to test the keyboard clock and data lines. The test result is placed in the output buffer as follows:
    - 00** No error detected.
    - 01** The 'keyboard clock' line is stuck low.
    - 02** The 'keyboard clock' line is stuck high.
    - 03** The 'keyboard data' line is stuck low.

- 04** The 'keyboard data' line is stuck high.
- AC** Diagnostic Dump—Sends 16 bytes of the controller's RAM, the current state of the input port, the current state of the output port, and the controller's program status word to the system. All items are sent in scan-code format.
- AD** Disable Keyboard Feature—This command sets bit 4 of the controller's command byte. This disables the keyboard interface by driving the clock line low. Data will not be sent or received.
- AE** Enable Keyboard Interface—This command clears bit 4 of the command byte, which releases the keyboard interface.
- C0** Read Input Port—This commands the controller to read its input port and place the data in its output buffer. This command should be used only if the output buffer is empty.
- D0** Read Output Port—This command causes the controller to read its output port and place the data in its output buffer. This command should be issued only if the output buffer is empty.
- D1** Write Output Port—The next byte of data written to I/O address hex 60 is placed in the controller's output port.
- Note:** Bit 0 of the controller's output port is connected to System Reset. This bit should not be written low.
- E0** Read Test Inputs—This command causes the controller to read its T0 and T1 inputs. This data is placed in the output buffer. Data bit 0 represents T0, and data bit 1 represents T1.
- F0–FF** Pulse Output Port—Bits 0 through 3 of the controller's output port may be pulsed low for approximately 6 microseconds. Bits 0 through 3 of this command indicate

which bits are to be pulsed. A 0 indicates that the bit should be pulsed, and a 1 indicates the bit should not be modified.

**Note:** Bit 0 of the controller's output port is connected to System Reset. Pulsing this bit resets the microprocessor.

## I/O Ports

The keyboard controller has two 8-bit I/O ports and two test inputs. One of the ports is assigned for input and the other for output. The controller uses the test inputs to read the state of the keyboard's 'clock' line and the keyboard's 'data' line.

The following figures show bit definitions for the input, output, and test-input ports.

Bit 0	Undefined
Bit 1	Undefined
Bit 2	Undefined
Bit 3	Undefined
Bit 4	RAM on the system board 0 = Disable 2nd 256Kb of system board RAM 1 = Enable 2nd 256Kb of system board RAM
Bit 5	Manufacturing jumper 0 = Manufacturing jumper installed 1 = Jumper not installed
Bit 6	Display type switch 0 = Primary display attached to Color/Graphics adapter 1 = Primary display attached to Monochrome adapter
Bit 7	Keyboard inhibit switch 0 = Keyboard inhibited 1 = Keyboard not inhibited

### **Input-Port Definitions**

Bit 0	System reset
Bit 1	Gate A20
Bit 2	Undefined
Bit 3	Undefined
Bit 4	Output buffer full
Bit 5	Input buffer empty
Bit 6	Keyboard clock (output)
Bit 7	Keyboard data (output)

### **Output-Port Bit Definitions**

T0	Keyboard clock (input)
T1	Keyboard data (input)

### **Test-Input Port Bit Definitions**

# Real-time Clock/Complementary Metal Oxide Semiconductor (RT/CMOS) RAM Information

The RT/CMOS RAM chip (Motorola MC146818) contains the real-time clock and 64 bytes of CMOS RAM. The internal clock circuitry uses 14 bytes of this RAM, and the rest is allocated to configuration information. The following figure shows the CMOS RAM addresses.

Addresses	Description
00-0D	* Real-time clock information
0E	* Diagnostic status byte
0F	* Shutdown status byte
10	Diskette drive type byte - drives A and B
11	Reserved
12	Fixed disk type byte - drives C and D
13	Reserved
14	Equipment byte
15	Low base memory byte
16	High base memory byte
17	Low expansion memory byte
18	High expansion memory byte
19-2D	Reserved
2E-2F	2-byte CMOS checksum
30	* Low expansion memory byte
31	* High expansion memory byte
32	* Date century byte
33	* Information flags (set during power on)
34-3F	Reserved

## CMOS RAM Address Map

\* These bytes are not included in the checksum calculation and are not part of the configuration record.

## Real-time Clock Information

The following figure describes real-time clock bytes and specifies their addresses.

Byte	Function	Address
0	Seconds	00
1	Second alarm	01
2	Minutes	02
3	Minute alarm	03
4	Hours	04
5	Hour alarm	05
6	Day of week	06
7	Date of month	07
8	Month	08
9	Year	09
10	Status Register A	0A
11	Status Register B	0B
12	Status Register C	0C
13	Status Register D	0D

### Real-Time Clock Information (addresses 00–0D)

**Note:** The setup program initializes registers A, B, C, and D when the time and date are set. Also Interrupt 1A is the BIOS' interface to read/set the time and date. It initializes the status bytes the same as the Setup program.

### Status Register A

- Bit 7** Update in Progress (UIP)—A 1 indicates the time update cycle is in progress. A 0 indicates the current date and time is available to read.
- Bit 6–Bit 4** 22-Stage Divider (DV2 through DV0)—These three divider-selection bits identify which time-base frequency is being used. The system initializes the stage divider to 010, which selects a 32.768kHz time base.
- Bit 3–Bit 0** Rate Selection Bits (RS3 through RS0)—These bits allow the selection of a divider output frequency. The system initializes the rate selection bits to 0110, which selects a 1.024kHz square wave output frequency and a 976.562 microsecond periodic interrupt rate.

## Status Register B

- Bit 7** Set—A 0 updates the cycle normally by advancing the counts at one-per-second. A 1 aborts any update cycle in progress and the program can initialize the 14 time-bytes without any further updates occurring until a 0 is written to this bit.
- Bit 6** Periodic Interrupt Enable (PIE)—This bit is a read/write bit that allows an interrupt to occur at a rate specified by the rate and divider bits in register A. A 1 enables an interrupt, and a 0 disables it. The system initializes this bit to 0.
- Bit 5** Alarm Interrupt Enable (AIE)—A 1 enables the alarm interrupt, and a 0 disables it. The system initializes this bit to 0.
- Bit 4** Update-Ended Interrupt Enabled (UIE)—A 1 enables the update-ended interrupt, and a 0 disables it. The system initializes this bit to 0.
- Bit 3** Square Wave Enabled (SQWE)—A 1 enables the square-wave frequency as set by the rate selection bits in register A, and a 0 disables the square wave. The system initializes this bit to 0.
- Bit 2** Date Mode (DM)—This bit indicates whether the time and date calendar updates are to use binary or binary coded decimal (BCD) formats. A 1 indicates binary, and a 0 indicates BCD. The system initializes this bit to 0.
- Bit 1** 24/12—This bit establishes whether the hours byte is in the 24-hour or 12-hour mode. A 1 indicates the 24-hour mode and a 0 indicates the 12-hour mode. The system initializes this bit to 1.

**Bit 0** Daylight Savings Enabled (DSE)—A 1 enables daylight savings and a 0 disables daylight savings (standard time). The system initializes this bit to 0.

## Register C

**Bit 7–Bit 4** IRQF, PF, AF, UF—These flag bits are read only and are affected when the 'AIE', 'PIE', and 'UIE' interrupts are enabled in register B.

**Bit 3–Bit 0** Reserved

## Register D

**Bit 7** Valid RAM Bit (VRB)—This bit is read only and indicates the condition of the contents of the CMOS RAM through the power sense pin. A low state of the power sense pin indicates that the real-time clock has lost its power (battery dead). A 1 on the VRB indicates power on the real-time clock and a 0 indicates that the real-time clock has lost power.

**Bits 6–Bit 0** Reserved

## CMOS RAM Configuration Information

The following lists show bit definitions for the CMOS configuration bytes (addresses hex 0E– 3F).

### Diagnostic Status Byte (Hex 0E)

**Bit 7** Real-time clock chip has lost power. A 0 indicates that the chip has not lost power, and a 1 indicates that the chip lost power.

<b>Bit 6</b>	Configuration Record—Checksum Status Indicator—A 0 indicates that checksum is good, and a 1 indicates it is bad.
<b>Bit 5</b>	Incorrect Configuration Information—This is a check, at power on time, of the equipment byte of the configuration record. A 0 indicates that the configuration information is valid, and a 1 indicates it is invalid. Power-on checks require:
	<ul style="list-style-type: none"><li>• At least one diskette drive to be installed (bit 0 of the equipment byte set to 1).</li><li>• The primary display adapter setting in configuration matches the system board's display switch setting and the actual display hardware in the system.</li></ul>
<b>Bit 4</b>	Memory Size Miscompare—A 0 indicates that the power-on check determined the same memory size as in the configuration record and a 1 indicates the memory size is different.
<b>Bit 3</b>	Fixed Disk Adapter/Drive C Initialization Status—A 0 indicates that the adapter and drive are functioning properly and the system can attempt "boot up." A 1 indicates that the adapter and/or drive C failed initialization, which prevents the system from attempting to "boot up."
<b>Bit 2</b>	Time Status Indicator—(POST validity check) A 0 indicates that the time is valid and a 1 indicates that the time is invalid.
<b>Bit 1–Bit 0</b>	Reserved

### Shutdown Status Byte (Hex 0F)

The bits in this byte are defined by the power on diagnostics. For more information about this byte, see "BIOS Listing."

## Diskette Drive Type Byte (Hex 10)

- Bit 7–Bit 4** Type of first diskette drive installed:
- 0000** No drive is present.
  - 0001** Double Sided Diskette Drive (48 TPI)
  - 0010** High Capacity Diskette Drive (96 TPI)
- Note:** 0011 through 1111 are reserved.
- Bit 3–Bit 0** Type of second diskette drive installed:
- 0000** No drive is present.
  - 0001** Double Sided Diskette Drive (48 TPI)
  - 0010** High Capacity Diskette Drive (96 TPI)
- Note:** 0011 through 1111 are reserved.

Hex address 11 contains a reserved byte.

## Fixed Disk Type Byte (Hex 12)

- Bit 7–Bit 4** Defines the type of first fixed disk drive installed (drive C):
- 0000** No fixed disk drive is present.
  - 0001 through 1111 define type 1 through type 15 (see BIOS listing at label FD\_TBL).
- Bit 3–Bit 0** Defines the type of second fixed disk drive installed (drive D):
- 0000** No fixed disk drive is present.

0001 through 1111 define type 1 through type 15  
 (see BIOS listing at label FD\_TBL).

The following figure shows the BIOS fixed disk parameters.

Type	Cylinders	Heads	Write Pre-comp	Landing Zone
1	306	4	128	305
2	615	4	300	615
3	615	6	300	615
4	940	8	512	940
5	940	6	512	940
6	615	4	no	615
7	462	8	256	511
8	733	5	no	733
9	900	15	no8	901
10	820	3	no	820
11	855	5	no	855
12	855	7	no	855
13	306	8	128	319
14	733	7	no	733
15	Reserved--set to zeros			

### BIOS Fixed Disk Parameters

Hex address 13 contains a reserved byte.

### Equipment Byte (Hex 14)

**Bit 7–Bit 6**      Indicates the number of diskette drives installed:

**00**    1 drive

**01**    2 drives

**10**    Reserved

**11**    Reserved

**Bit 5–Bit 4**      Primary display

**00**    Reserved

- 01** Primary display is attached to the Color/Graphics Monitor Adapter in the 40-column mode.
  - 10** Primary display is attached to the Color/Graphics Monitor Adapter in the 80-column mode.
  - 11** Primary display is attached to the Monochrome Display and Printer Adapter.
- Bit 3–Bit 2** Not used.
- Bit 1** Math Coprocessor presence bit:
  - 0** Math Coprocessor not installed.
  - 1** Math Coprocessor installed.
- Bit 0** The set condition of this bit indicates that diskette drives are installed.

**Note:** The equipment byte defines basic equipment in the system for power-on diagnostics.

### Low and High Base Memory Bytes (Hex 15 and 16)

**Bit 7–Bit 0** Address hex 15—Low-byte base size

**Bit 7–Bit 0** Address hex 16—High-byte base size

Valid Sizes:

**0100H** 256Kb system-board RAM

**0200H** 512Kb system-board RAM

**0280H** 640Kb 512Kb system board RAM  
and the IBM Personal Computer AT  
128KB Memory Expansion Option

## Low and High Memory Expansion Bytes (Hex 17 and 18)

**Bit 7–Bit 0** Address hex 17—Low-byte expansion size

**Bit 7–Bit 0** Address hex 18—High-byte expansion size

Valid Sizes:

**0200H** 512Kb I/O adapter

**0400H** 1024Kb I/O adapter (2 adapters)

**600H** 1536Kb I/O adapter (3 adapters)

to

**3C00H** 15360Kb I/O adapter (15Mb maximum)

Hex addresses 19 through 2D are reserved.

## Checksum (Hex 2E and 2F)

**Address hex 2E** High byte of checksum

**Address hex 2F** Low byte of checksum

**Note:** Checksum is on addresses hex 10-20.

## Low and High Expansion Memory Bytes (Hex 30 and 31)

**Bit 7–Bit 0** Address hex 30—Low-byte expansion size

**Bit 7–Bit 0** Address hex 31—High-byte expansion size

Valid Sizes:

**0200H** 512Kb I/O adapter

**0400H** 1024Kb I/O adapter

**0600H** 1536Kb I/O adapter

to

**3C00H** 15360Kb I/O adapter (15Mb maximum)

**Note:** This word reflects the total expansion memory above the 1Mb address space as determined at power-on time. This expansion memory size can be determined through system interrupt 15 (see the BIOS listing). The base memory at power-on time is determined through the system memory-size-determine interrupt.

### Date Century Byte (Hex 32)

**Bit 7–Bit 0**      BCD value for the century (BIOS interface to read and set).

### Information Flag (Hex 33)

**Bit 7**      Set if the IBM Personal Computer AT 128KB Memory Expansion Option is installed.

**Bit 6**      This bit is used by the Setup utility to put out a first user message after initial setup.

**Bit 5–Bit 0**      Reserved

**Note:** Hex addresses 34 through 3F are reserved.

## I/O Operations

Writing to CMOS RAM involves two steps:

1. OUT to port hex 70 with the CMOS address that will be written to.
2. OUT to port hex 71 with the data to be written.

Reading CMOS RAM also requires two steps:

1. OUT to port hex 70 with the CMOS address that is to be read from.
2. IN from port hex 71, and the data read is returned in the AL register.

## Specifications

### System Unit

#### Size

- Length: 540 millimeters (21.3 inches)
- Depth: 439 millimeters (17.3 inches)
- Height: 162 millimeters (6.8 inches)

#### Weight

- 19.05 kilograms (42 pounds)

### Power Cables

- Length: 1.8 meters (6 feet)

## **Environment**

- Air Temperature
  - System On: 15.6 to 32.2 degrees C (60 to 90 degrees F)
  - System Off: 10 to 43 degrees C (50 to 110 degrees F)
- Humidity
  - System On: 8% to 80%
  - System Off: 20% to 80%
- Altitude
  - Maximum altitude: 2133.6 meters (7000 feet)

## **Heat Output**

- 1229 British Thermal Units per hour

## **Noise Level**

- Meets Class 3; 42 decibels average-noise rating

## **Electrical**

- VA — 450
- Range 1
  - Nominal - 115 Vac
  - Minimum - 100 Vac

- Maximum - 125 Vac
- Range 2
  - Nominal - 230 Vac
  - Minimum - 200 Vac
  - Maximum - 240 Vac

## Connectors

The system board has the following connectors:

- Speaker connector (J19)
- Two power-supply connectors (PS8 and PS9)
- Keyboard connector (J9)
- Power LED and keylock connector (J20)
- Battery connector (J21)

The speaker connector is a 4-pin, keyed, Berg strip. The pin assignments follow.

Pin	Function
1	Data out
2	Key
3	Ground
4	+5 Vdc

### Speaker Connector (J19)

The pin assignments for power-supply connectors, P8 and P9, are as follows:

<b>Pin</b>	<b>Assignments</b>	<b>Connector</b>
1	Power good	
2	+5 Vdc	
3	+12 Vdc	
4	-12 Vdc	
5	Ground	
6	Ground	
1	Ground	PS8
2	Ground	
3	-5 Vdc	
4	+5 Vdc	
5	+5 Vdc	
6	+5 Vdc	

## **Power Supply Connectors**

The keyboard connector is a 5-pin, 90-degree Printed Circuit Board (PCB) mounting, DIN connector. The pin assignments are as follows:

<b>Pin</b>	<b>Assignments</b>
1	Keyboard clock
2	Keyboard data
3	Spare
4	Ground
5	+5 Vdc

## **Keyboard Connector (J22)**

The power LED and keylock connector is a 5-pin Berg strip. Its pin assignments follow:

<b>Pin</b>	<b>Assignments</b>
1	LED Power
2	Key
3	Ground
4	Keyboard inhibit
5	Ground

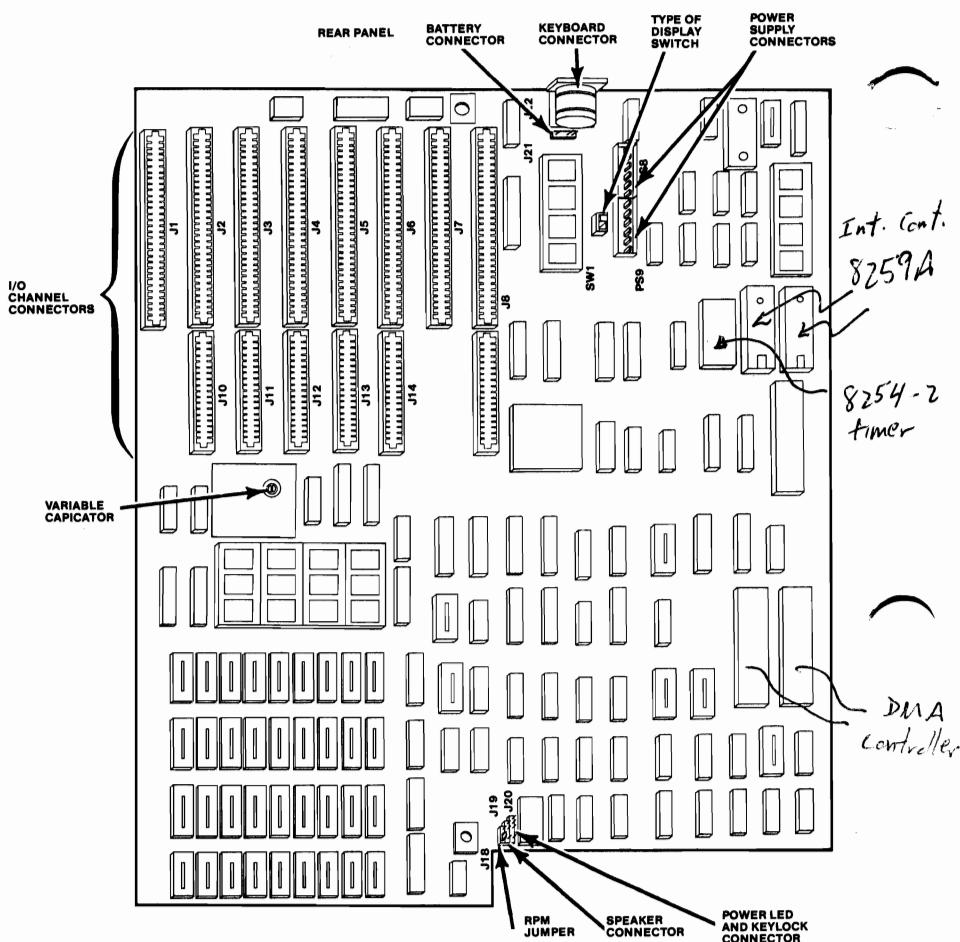
## **Power LED and Keylock Connector (J20)**

The battery connector is a 4-pin, keyed, Berg strip. The pin assignments follow:

Pin	Assignments
1	Ground
2	Not Used
3	Not Used
4	6 Vdc.

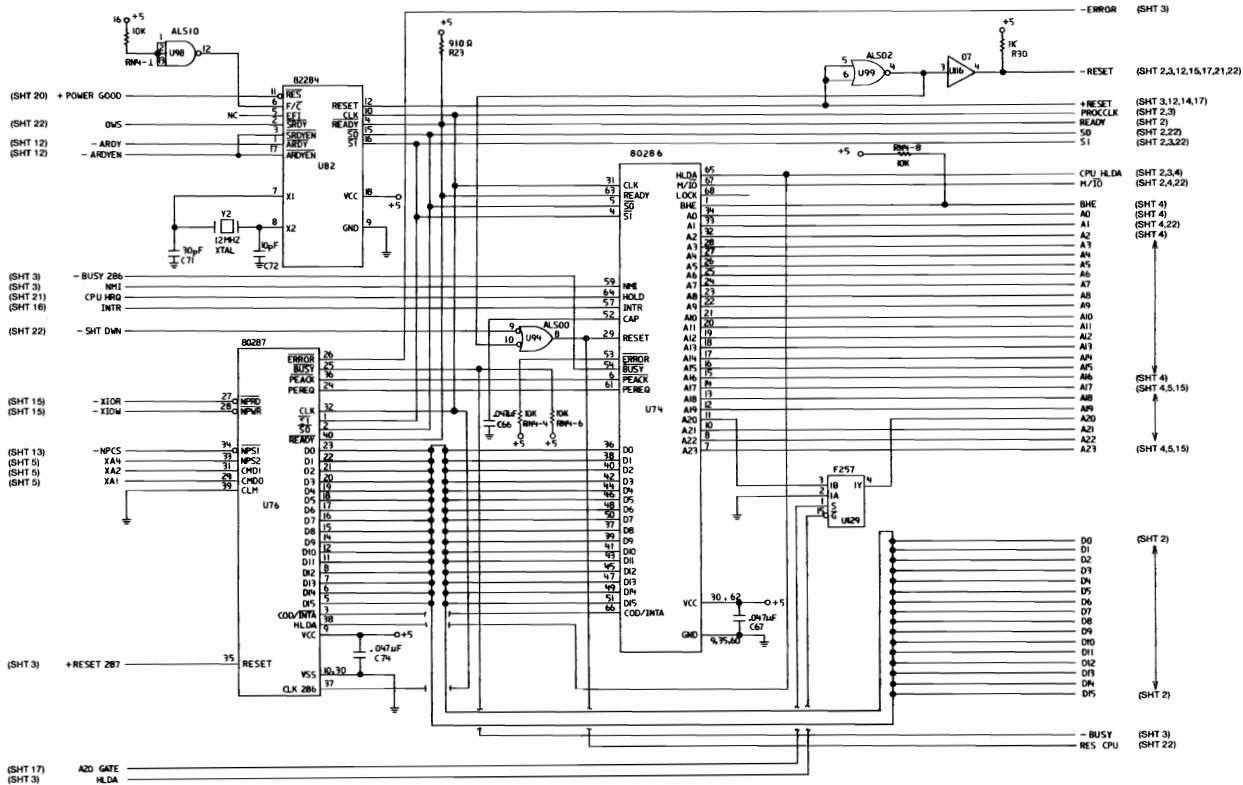
### Battery Connector (J21)

The following figure shows the layout of the system board.



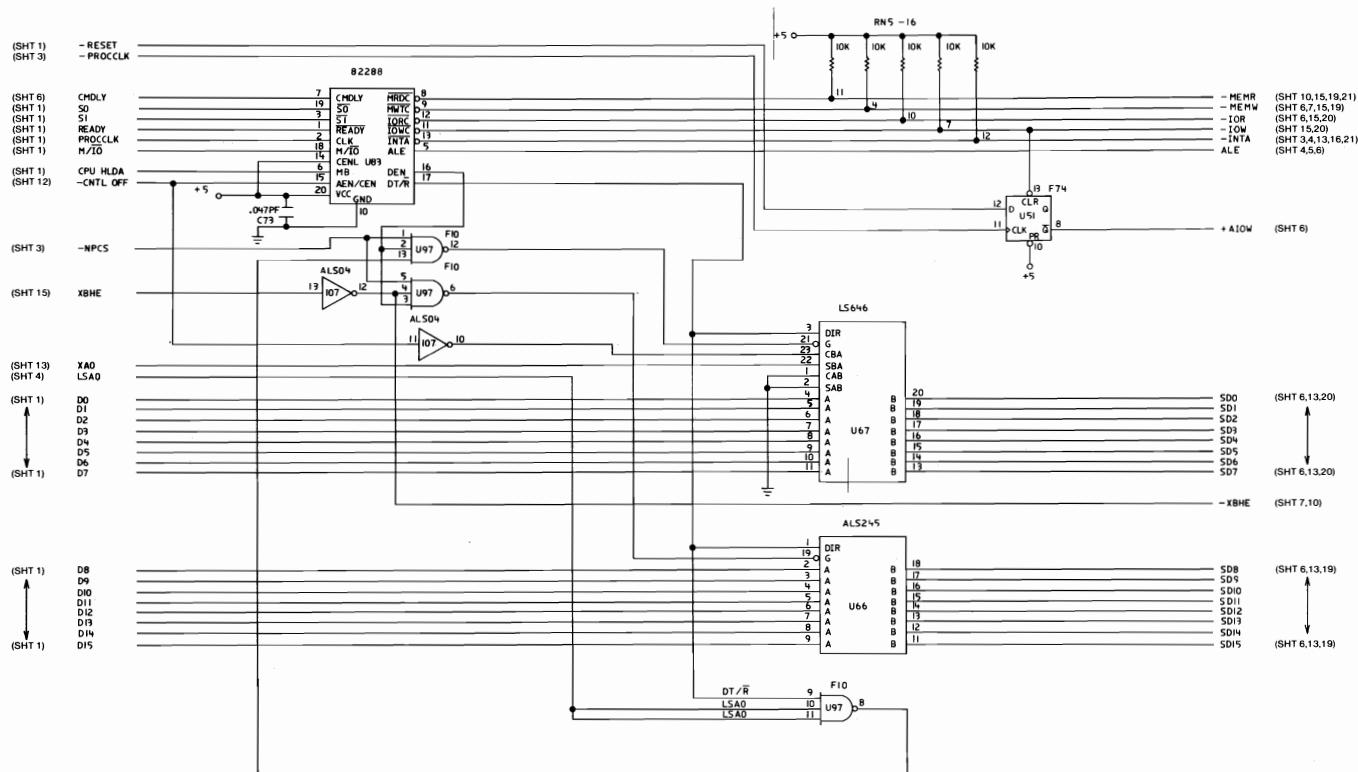
**System Board Layout**

Logic Diagrams

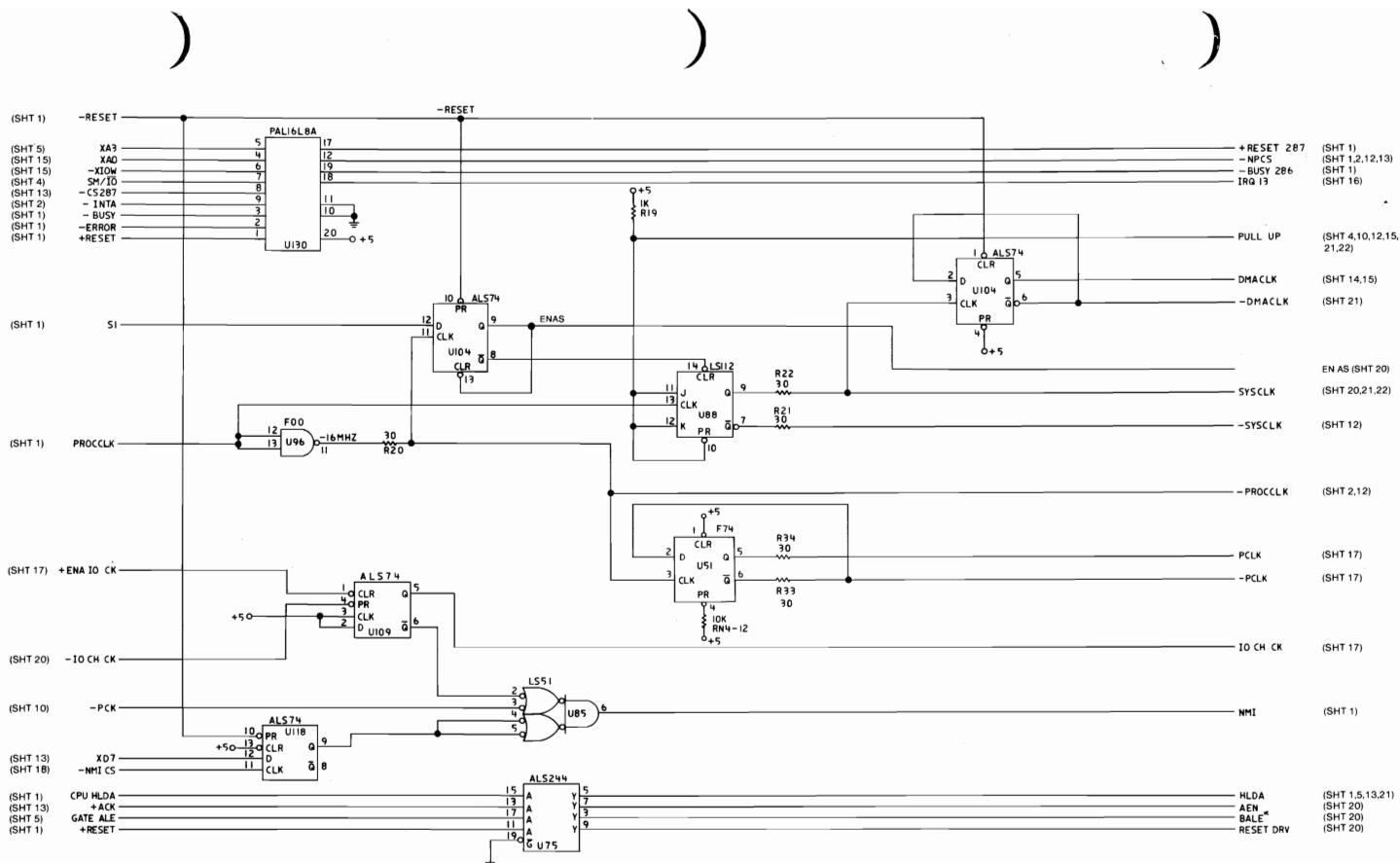


## **System Board (Sheet 1 of 22)**

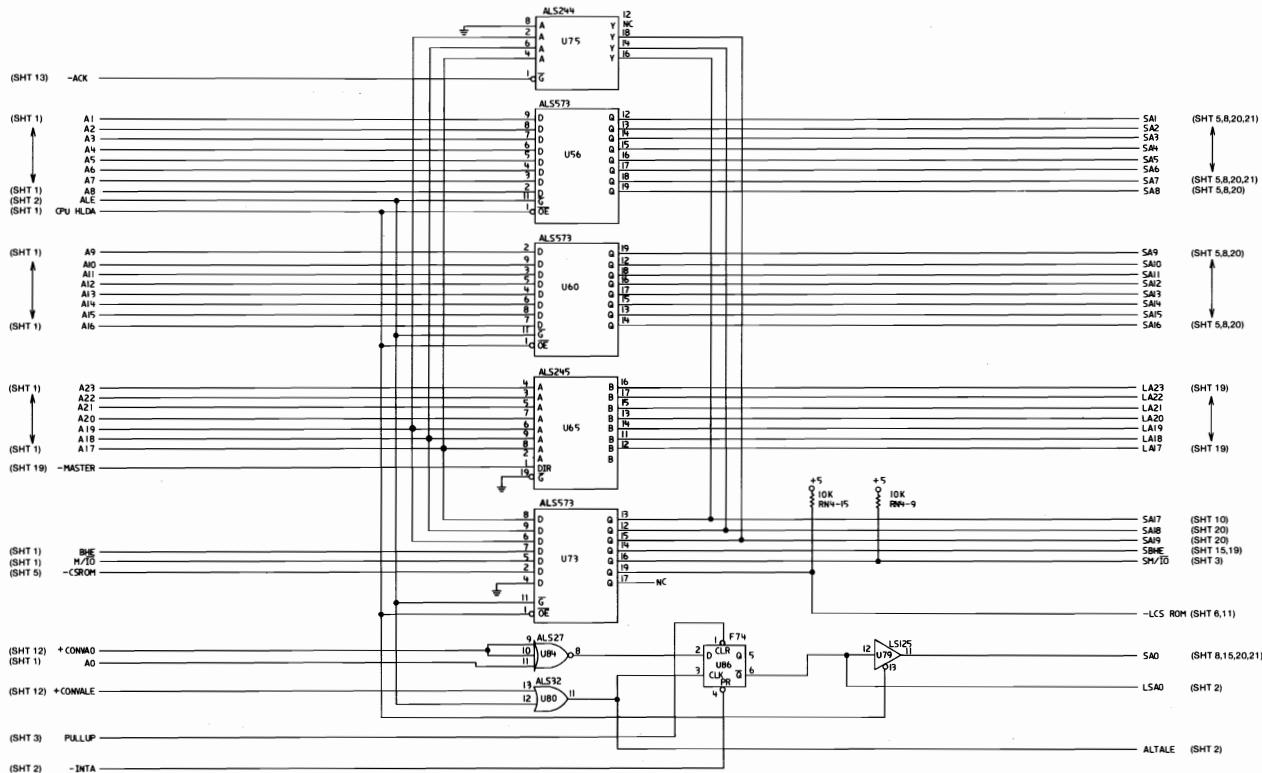
# 1-62 System Board



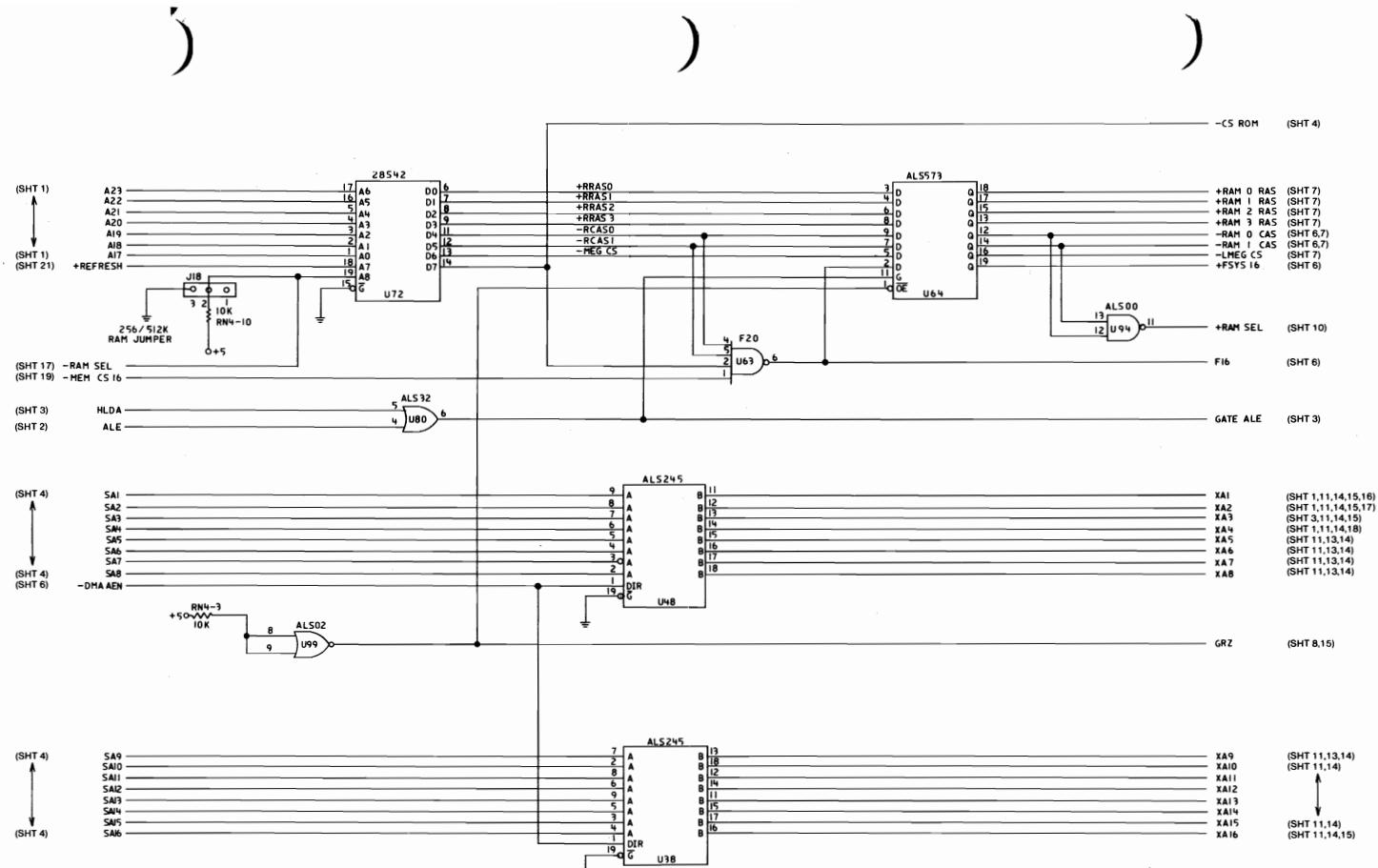
System Board (Sheet 2 of 22)



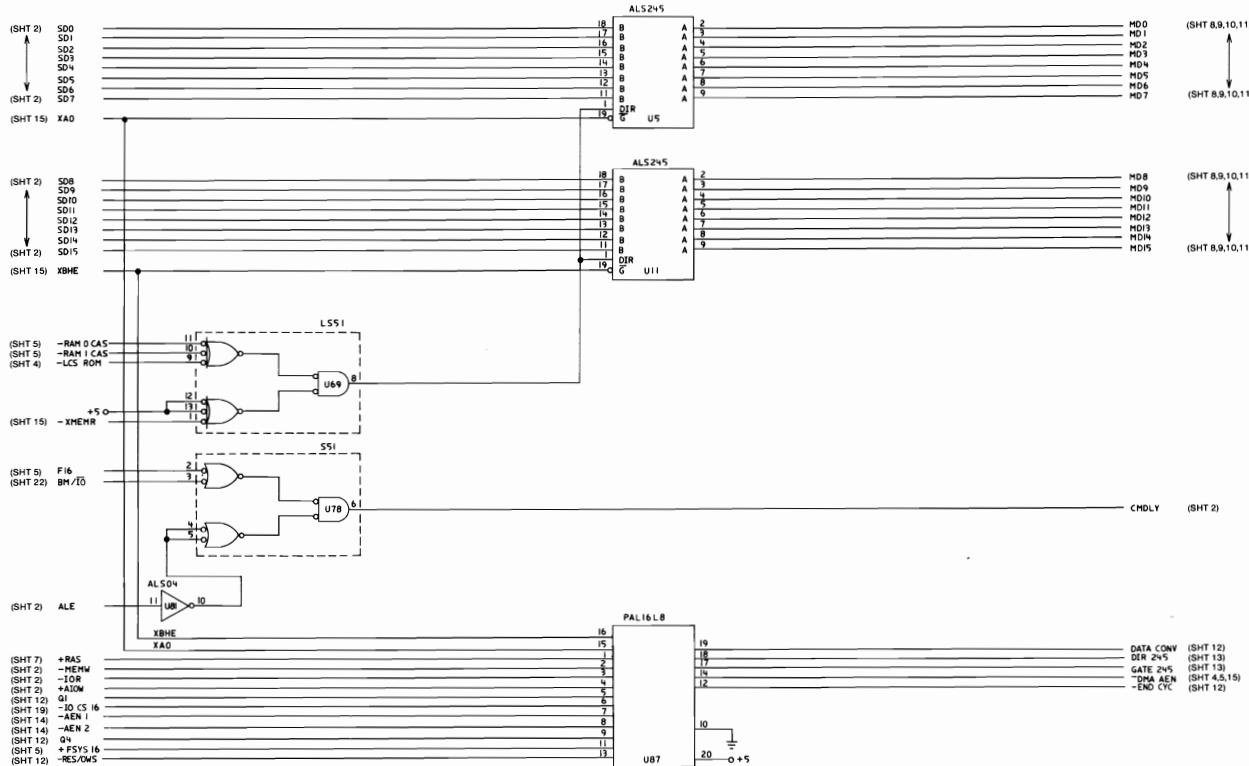
**System Board (Sheet 3 of 22)**



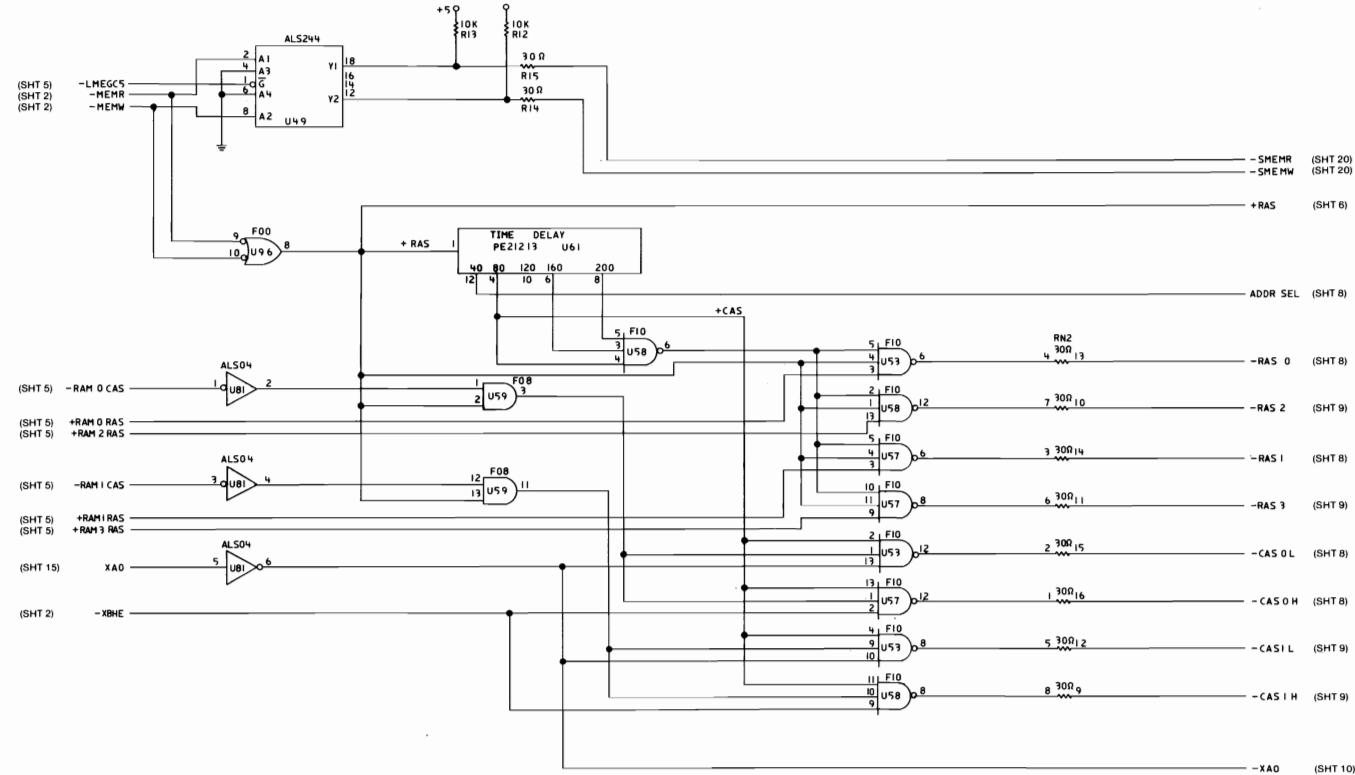
**System Board (Sheet 4 of 22)**



**System Board (Sheet 5 of 22)**

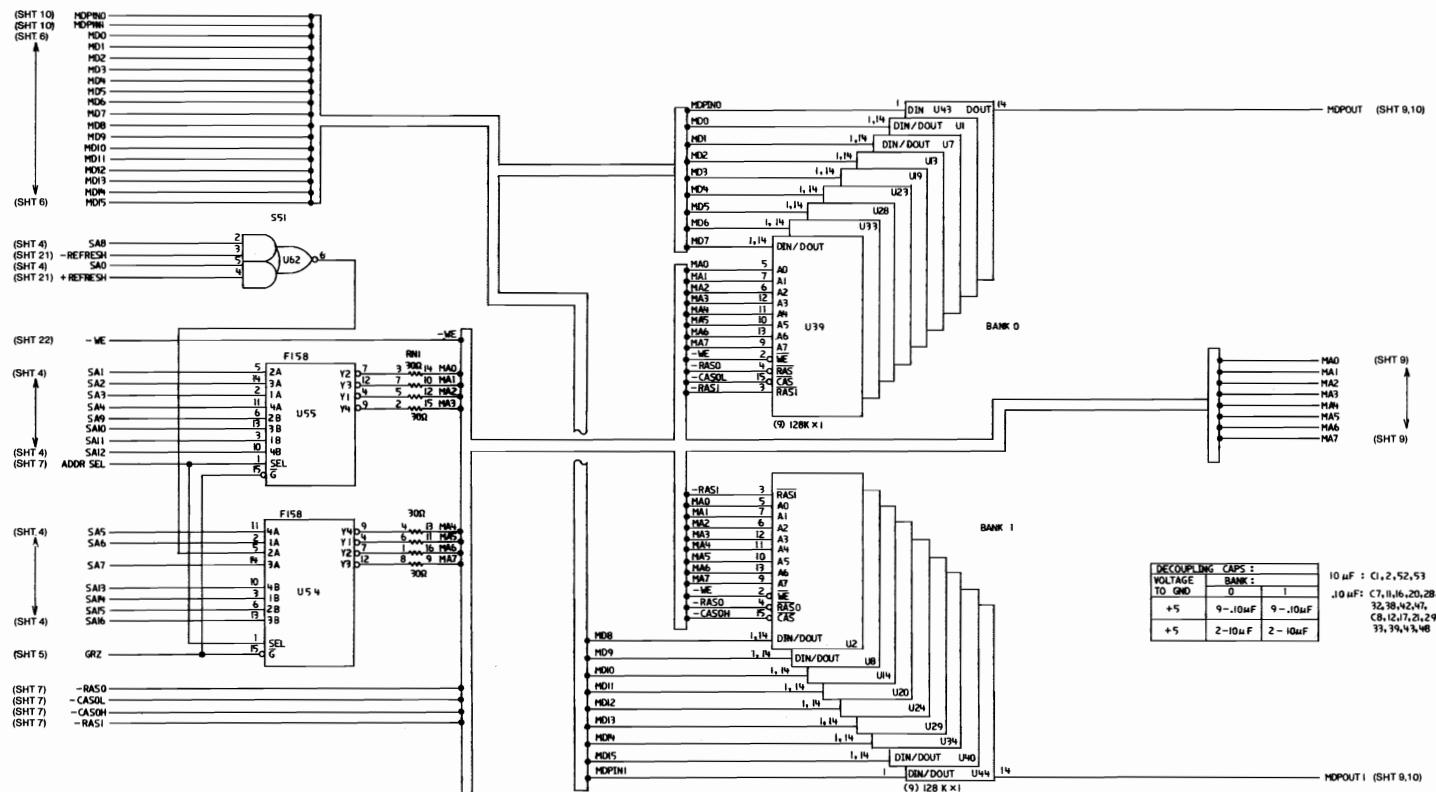


System Board (Sheet 6 of 22)

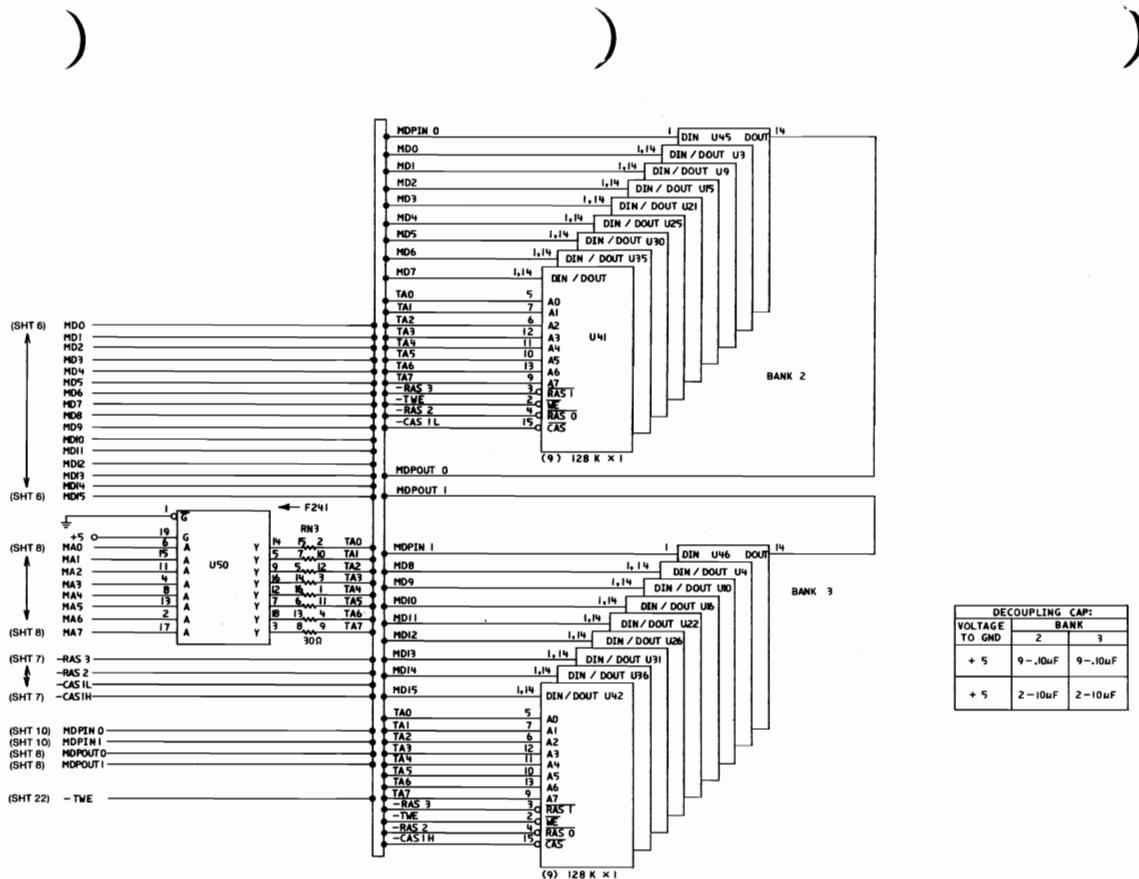


**System Board (Sheet 7 of 22)**

# 1-68 System Board



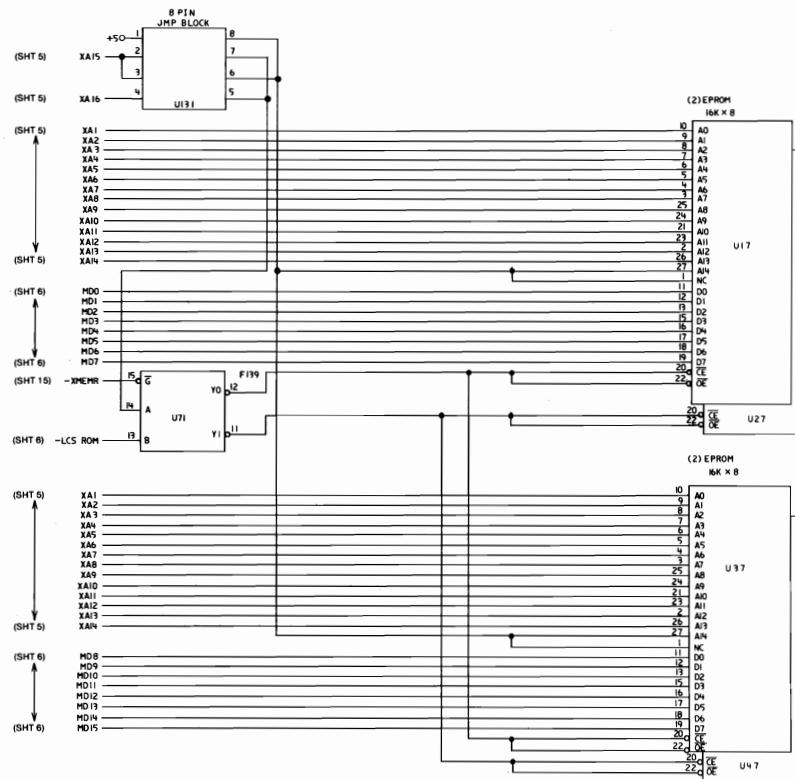
System Board (Sheet 8 of 22)



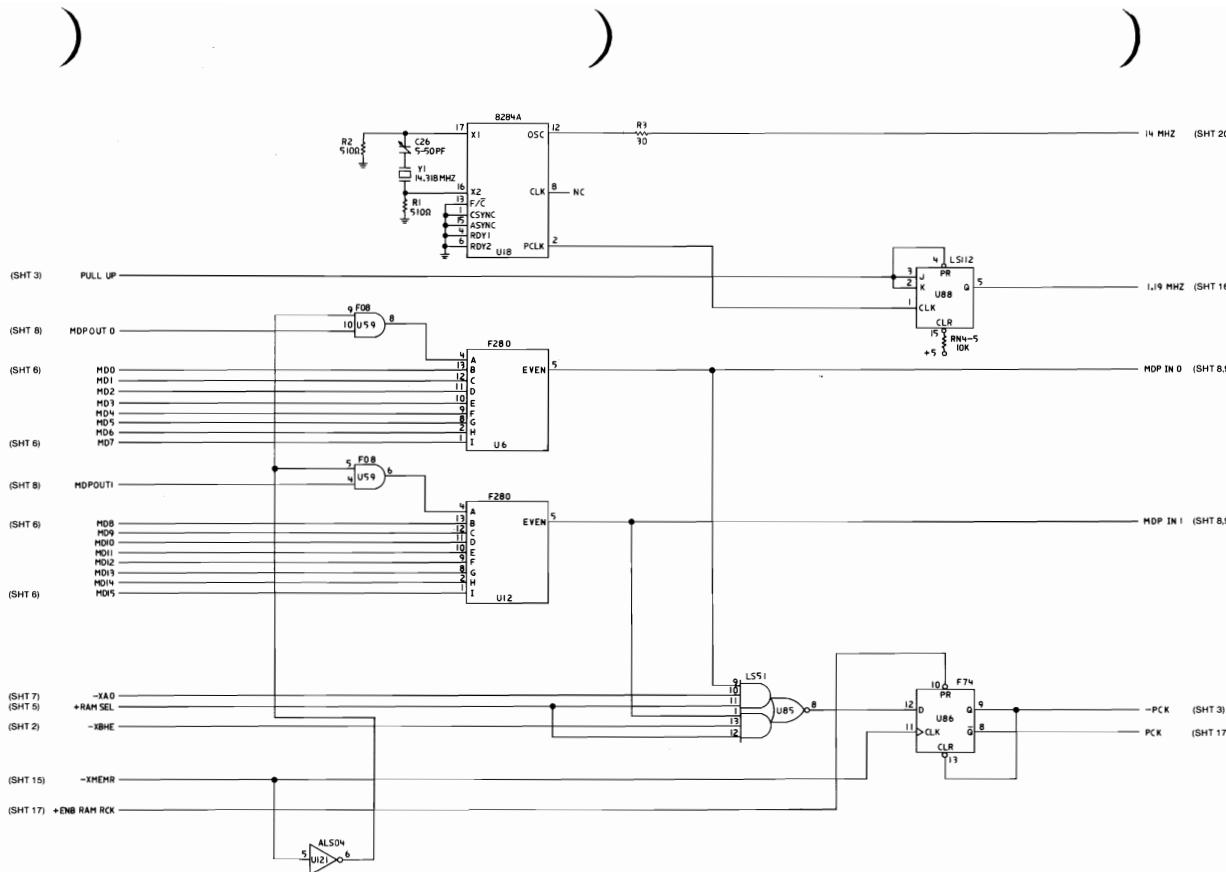
DECOUPLING CAP:	
VOLTAGE	BANK
TO GND	2      3
+ 5	9-10 $\mu$ F      9-10 $\mu$ F
+ 5	2-10 $\mu$ F      2-10 $\mu$ F

10 $\mu$ F : C3,4,5,45  
 .10 $\mu$ F: C9,13,18,22,30  
 3V4,40,44,49  
 C10,14,19,23,31  
 35,41,45,50

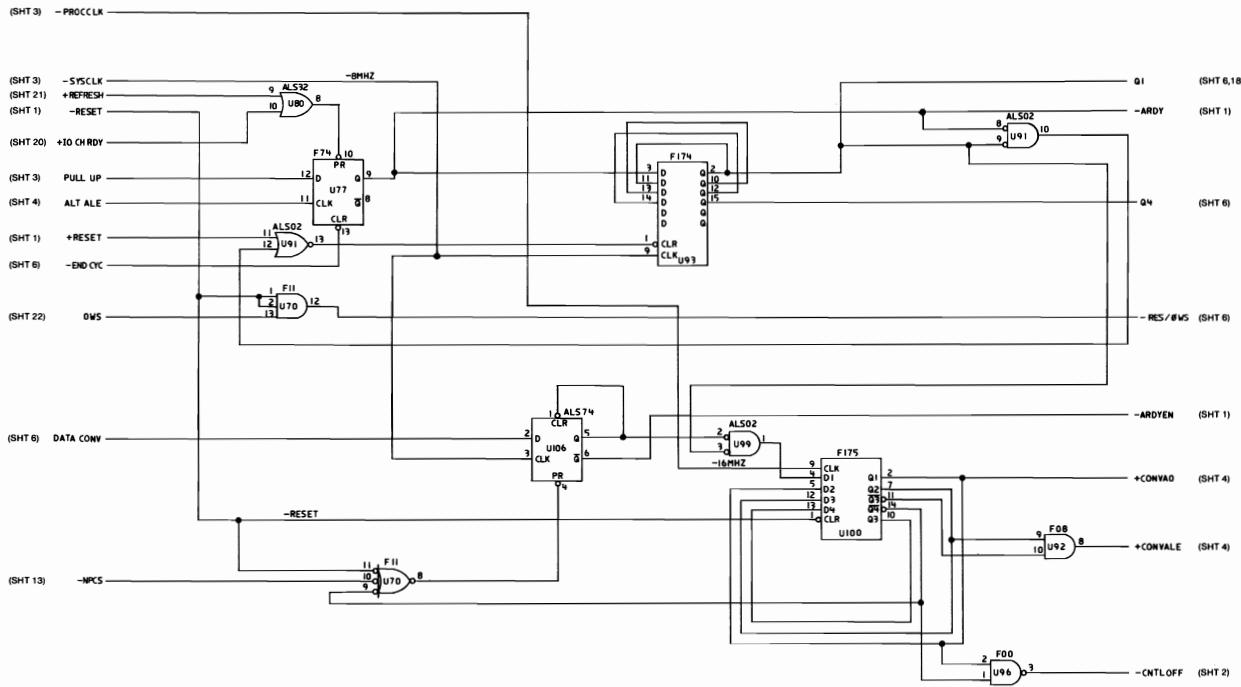
System Board (Sheet 9 of 22)



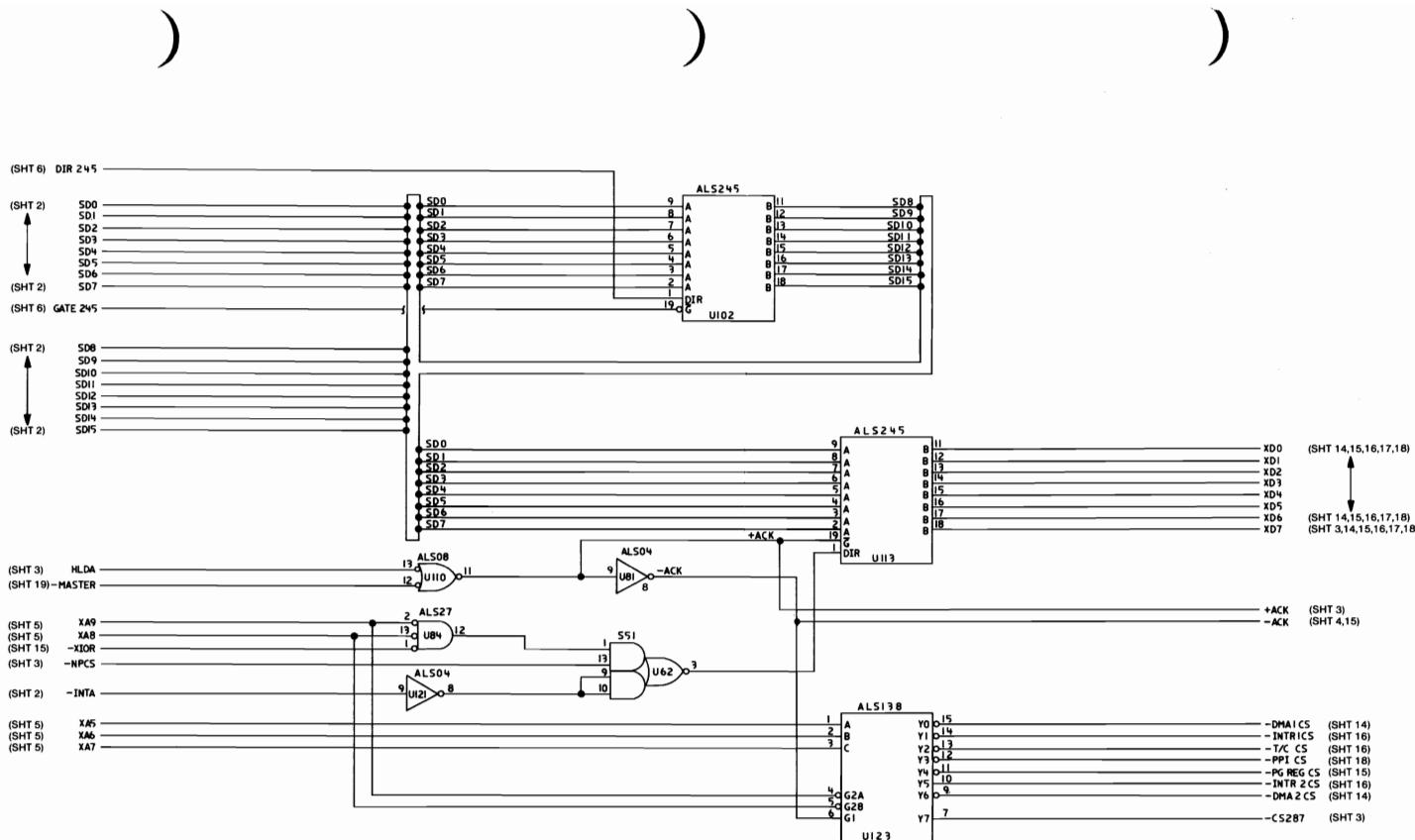
System Board (Sheet 10 of 22)



**System Board (Sheet 11 of 22)**

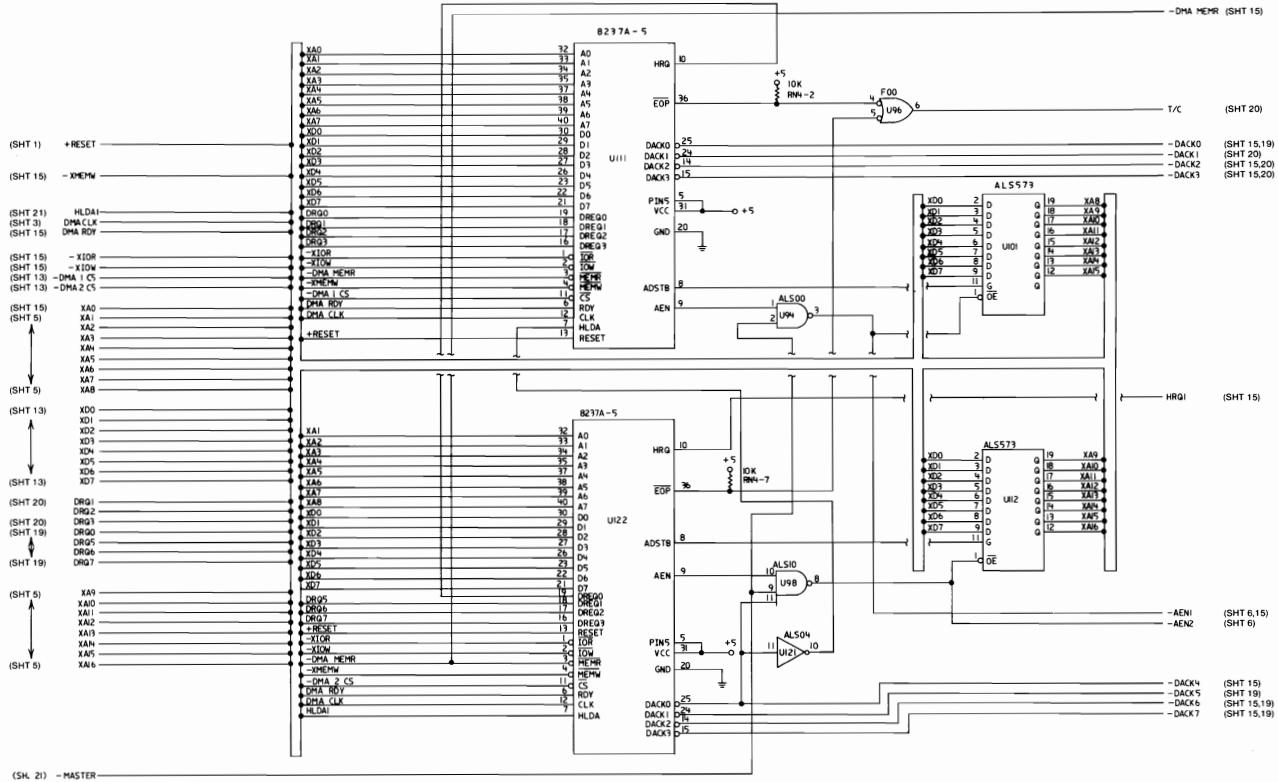


**System Board (Sheet 12 of 22)**

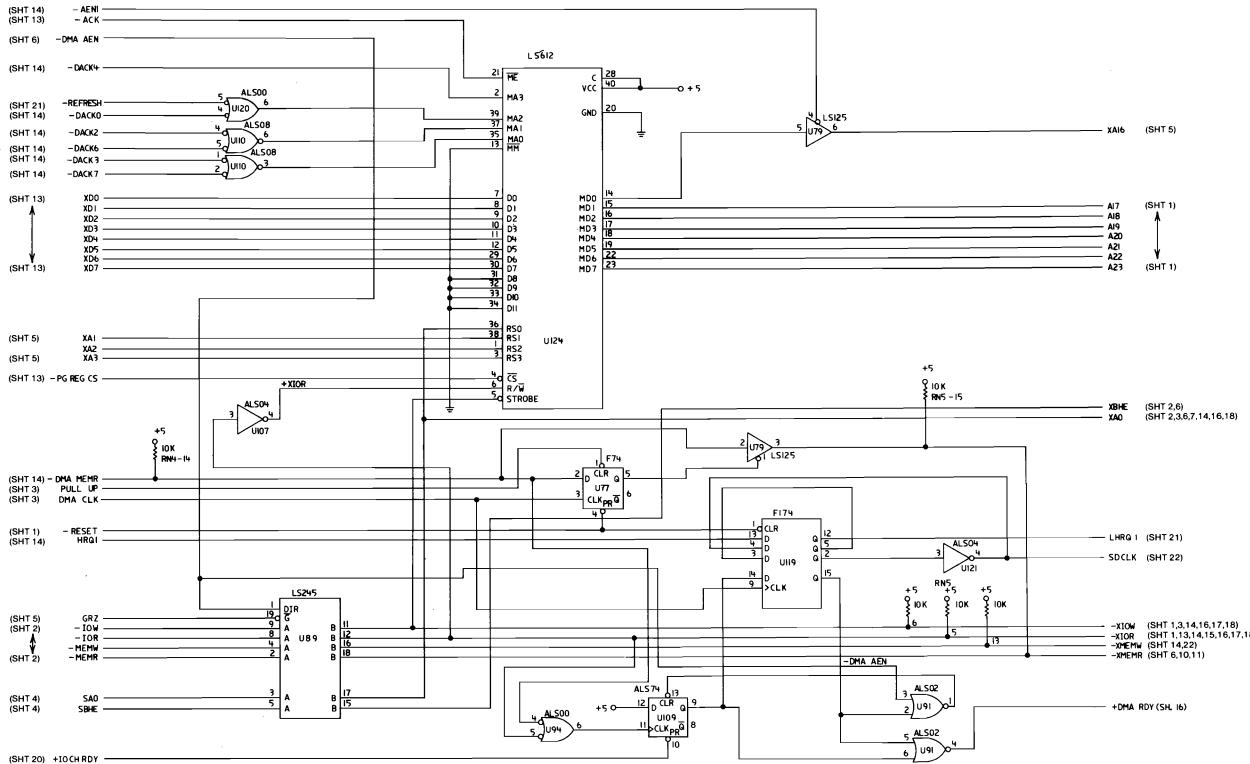


System Board (Sheet 13 of 22)

# 1-74 System Board



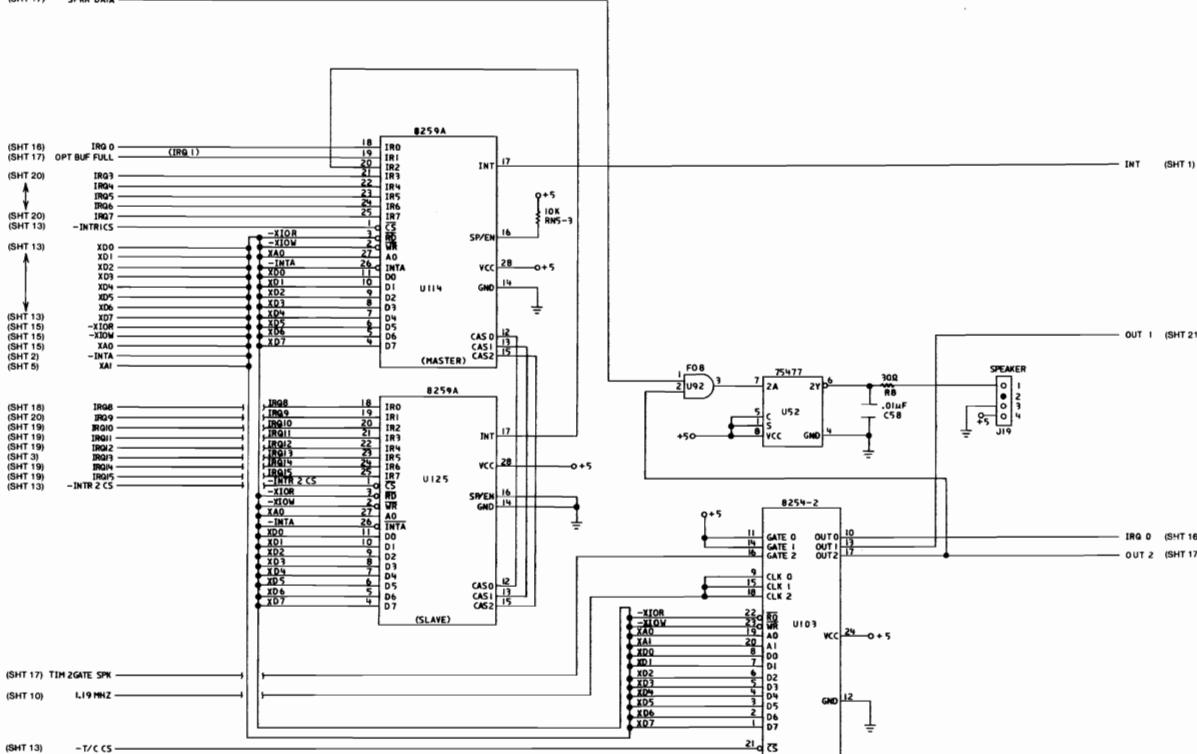
System Board (Sheet 14 of 22)



System Board (Sheet 15 of 22)

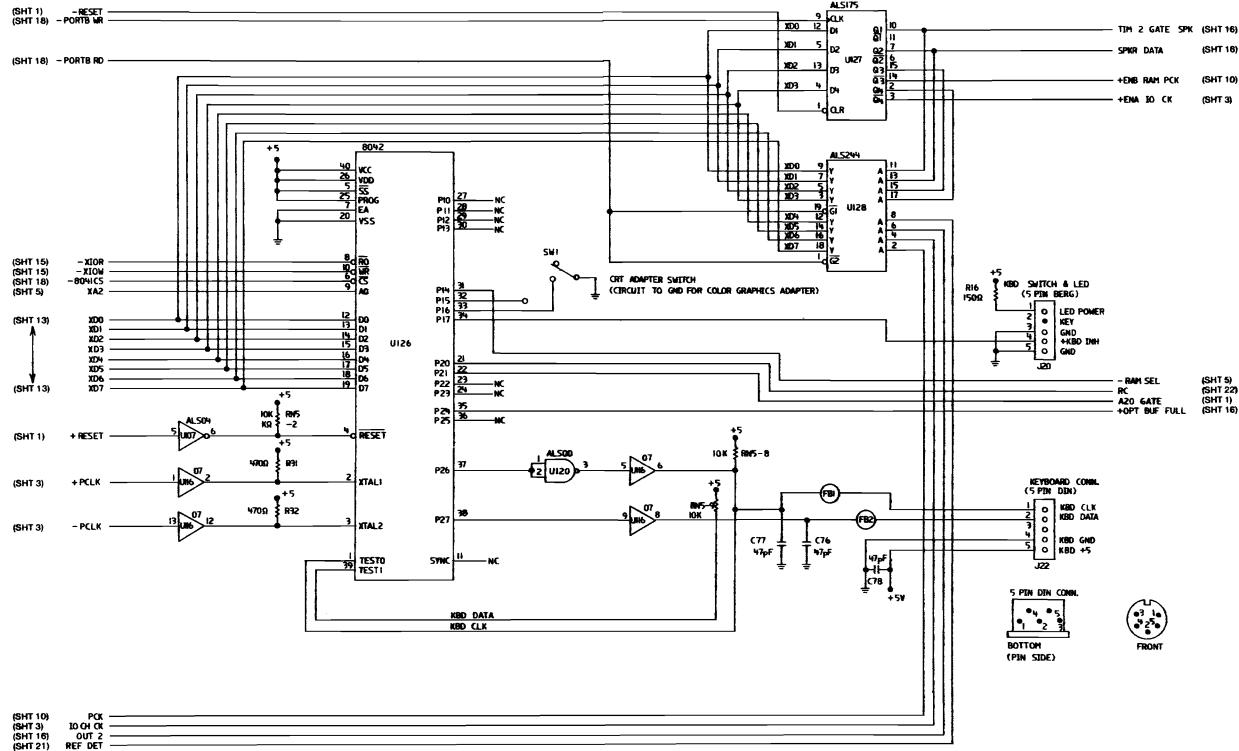
System Board (Sheet 16 of 22)

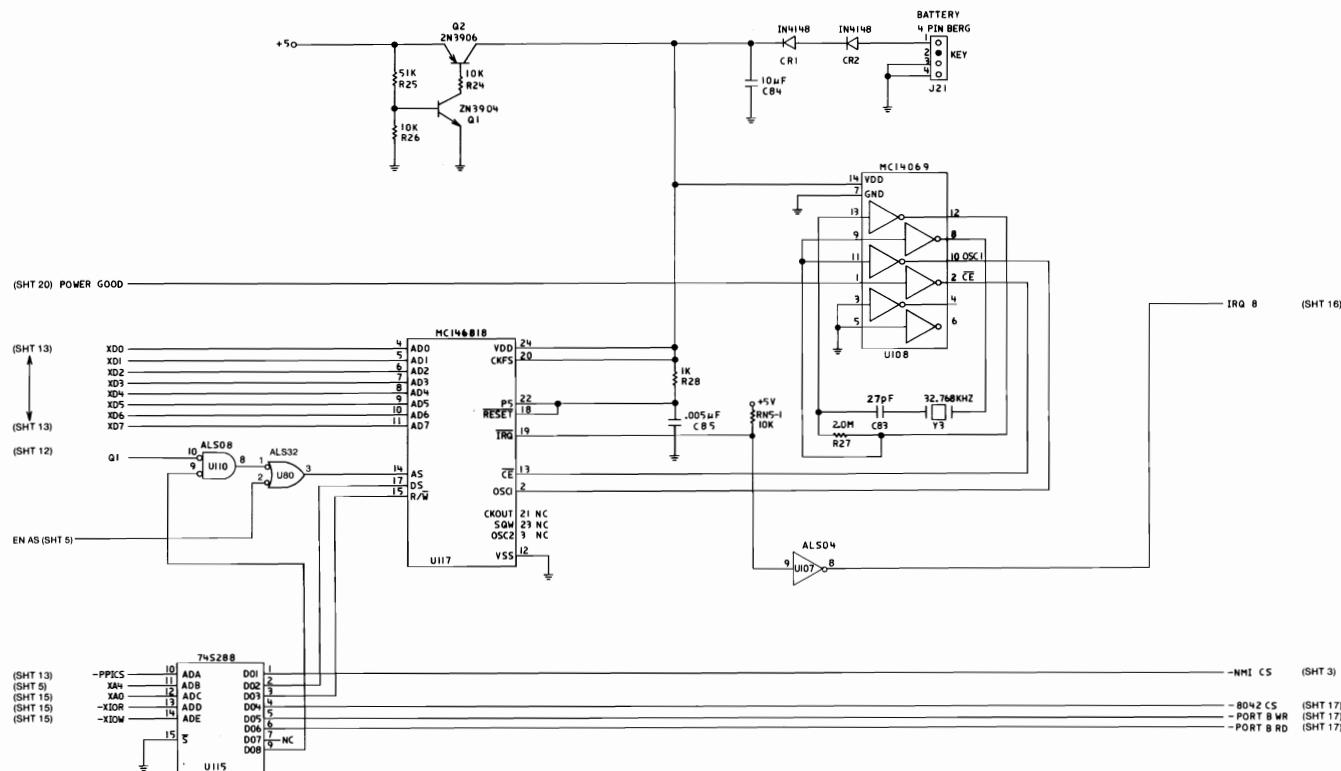
(SHT 17) SPKR DATA —



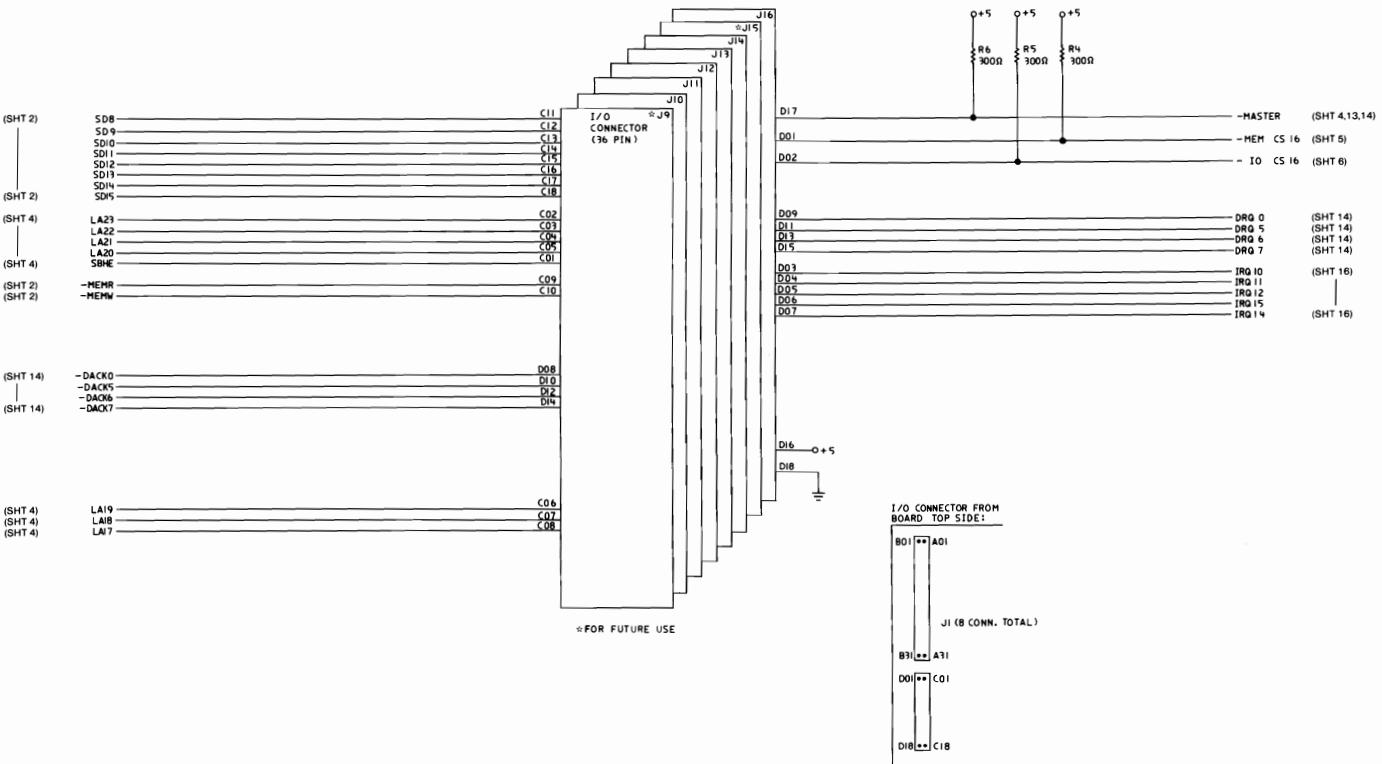
# SECTION 1

## System Board (Sheet 17 of 22)



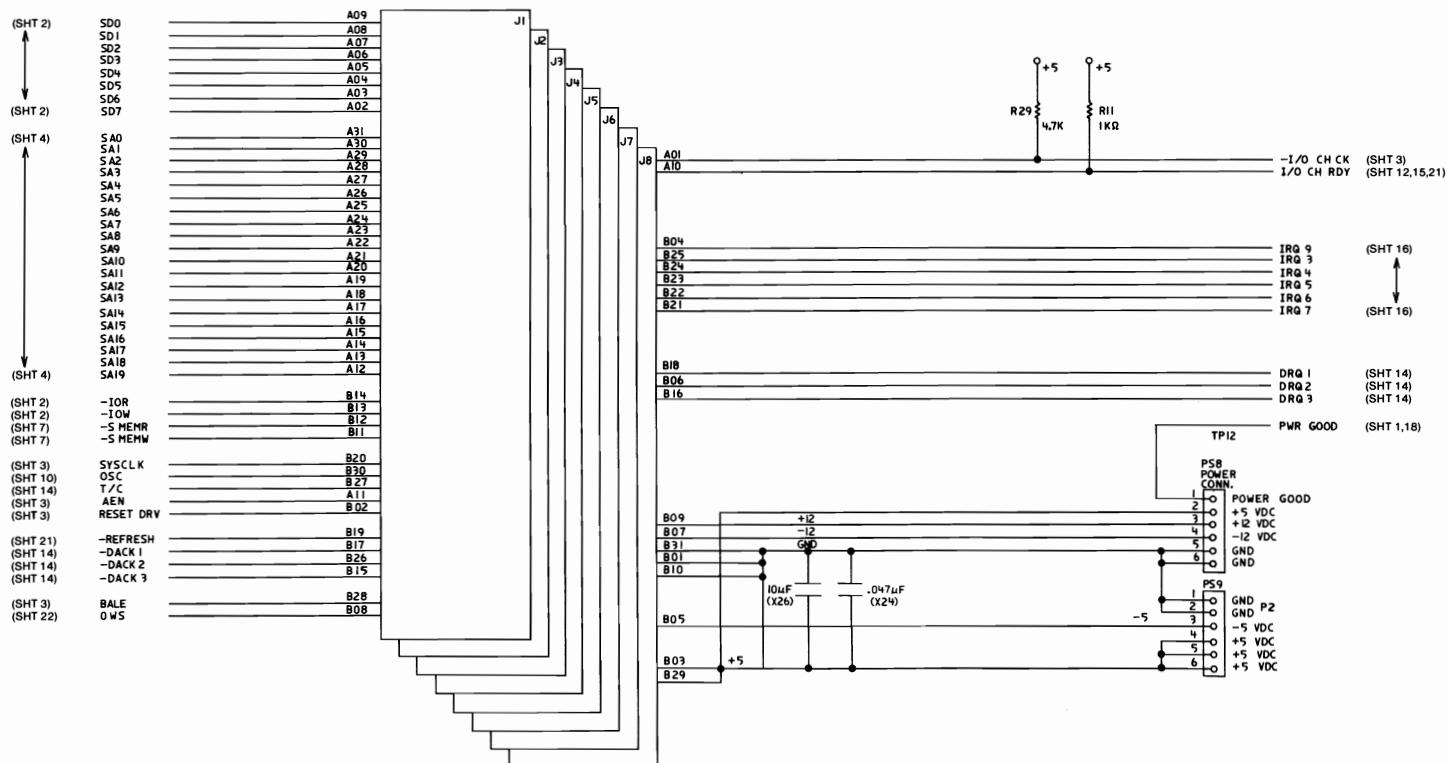


**System Board (Sheet 18 of 22)**

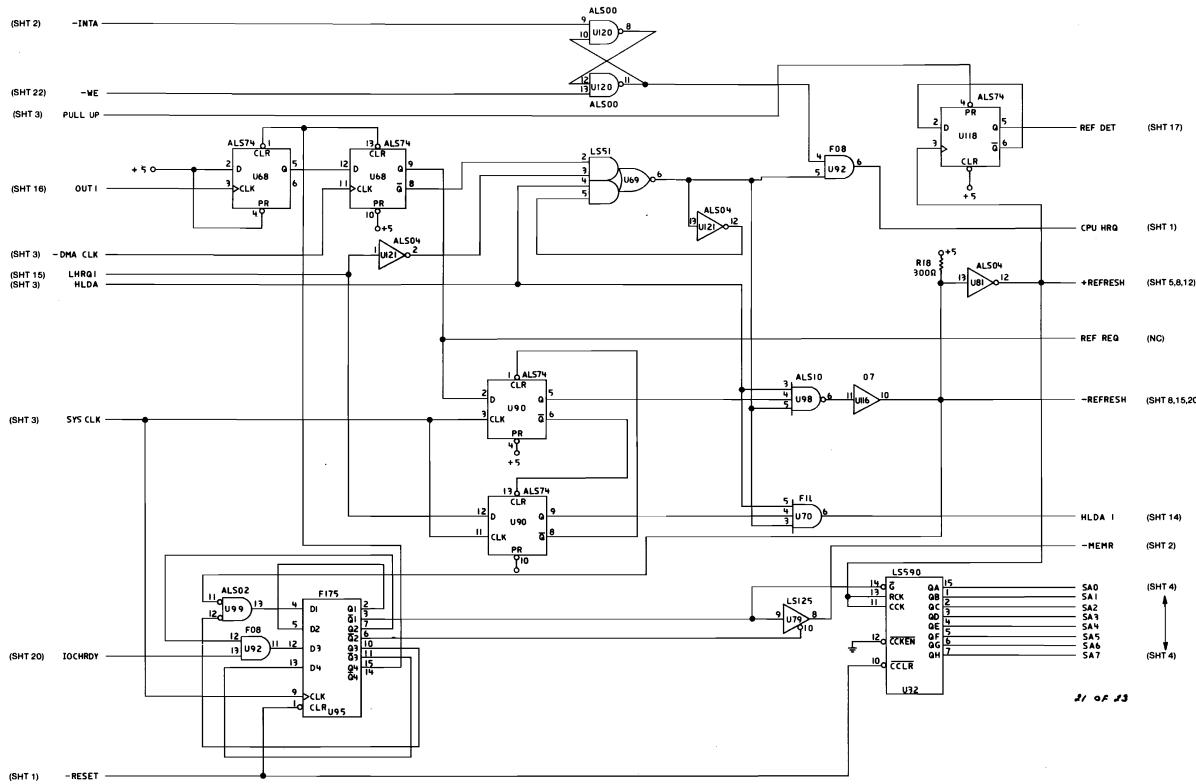


System Board (Sheet 19 of 22)

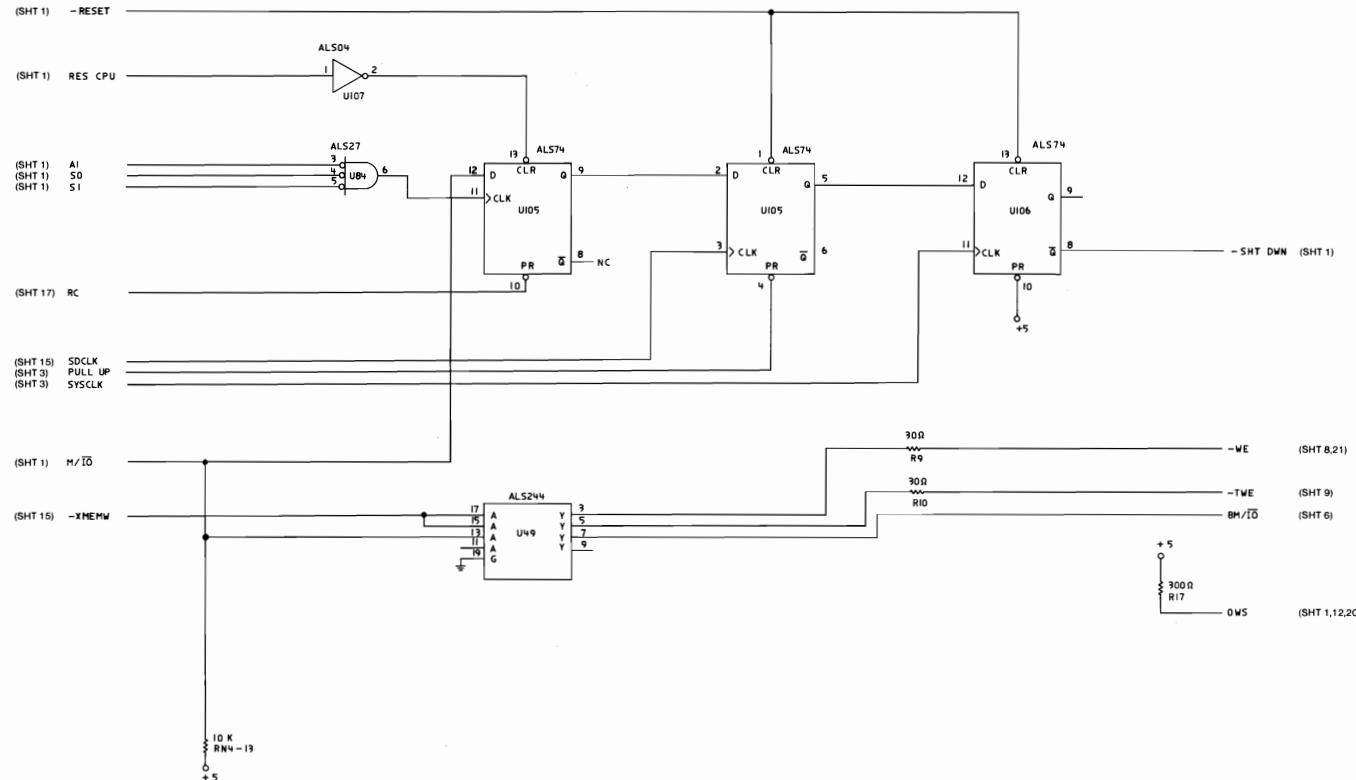
# 1-80 System Board



System Board (Sheet 20 of 22)



## **System Board (Sheet 21 of 22)**



System Board (Sheet 22 of 22)

# SECTION 2. COPROCESSOR

## Contents

Description .....	2-3
Programming Interface .....	2-3
Hardware Interface .....	2-4

## **Notes:**

# Description

The IBM Personal Computer AT Math Coprocessor enables the IBM Personal Computer AT to perform high-speed arithmetic, logarithmic functions, and trigonometric operations with extreme accuracy.

The coprocessor works in parallel with the microprocessor. The parallel operation decreases operating time by allowing the coprocessor to do mathematical calculations while the microprocessor continues to do other functions.

The coprocessor works with seven numeric data types, which are divided into the following three classes:

- Binary integers (3 types)
- Decimal integers (1 type)
- Real numbers (3 types)

# Programming Interface

The coprocessor offers extended data types, registers, and instructions to the microprocessor.

The coprocessor has eight 80-bit registers, which provide the equivalent capacity of the 40 16-bit registers in the microprocessor. This register space allows constants and temporary results to be held in registers during calculations, thus reducing memory access and improving speed as well as bus availability. The register space can be used as a stack or as a fixed register set. When used as a stack, only the top two stack elements are operated on. The following figure shows representations of large and small numbers in each data type.

Data Type	Bits	Significant Digits (Decimal)	Approximate Range (Decimal)
Word Integer	16	4	$-32,768 \leq x \leq +32,767$
Short Integer	32	9	$-2 \times 10^9 \leq x \leq +2 \times 10^9$
Long Integer	64	19	$-9 \times 10^{18} \leq x \leq +9 \times 10^{18}$
Packed Decimal	80	18	$-99...99 \leq x \leq +99...99$ (18 digits)
Short Real *	32	6-7	$8.43 \times 10^{-37} \leq x \leq 3.37 \times 10^{38}$
Long Real *	64	15-16	$4.19 \times 10^{-307} \leq x \leq 1.67 \times 10^{308}$
Temporary Real	80	19	$3.4 \times 10^{-4932} \leq x \leq 1.2 \times 10^{4932}$

## Data Types

\* The Short and Long data types correspond to the single and double precision data types.

## Hardware Interface

The math coprocessor uses the same clock generator as the microprocessor. It works at one-third the frequency of the system microprocessor clock. The coprocessor is wired so that it functions as an I/O device through I/O port addresses hex 00F8, 00FA, and 00FC. The microprocessor sends OP codes and operands through these I/O ports. The microprocessor also receives and stores results through the same I/O ports. The coprocessor's busy signal informs the microprocessor that it is executing; the microprocessor's Wait instruction forces the microprocessor to wait until the coprocessor is finished executing.

The coprocessor detects six different exception conditions that can occur during instruction execution. If the appropriate exception mask within the coprocessor is not set, the coprocessor sets its error signal. This error signal generates a hardware interrupt (interrupt 13) and causes the 'BUSY' signal to the coprocessor to be held in the busy state. The 'BUSY' signal may be cleared by an 8-bit I/O Write command to address hex F0 with D0 through D7 equal to 0.

The power-on-self test code in the system ROM enables hardware interrupt 13 and sets up its vector to point to a routine in ROM. The ROM routine clears the 'BUSY' signal's latch and

then transfers control to the address pointed to by the NMI interrupt vector. This allows code written for any IBM Personal Computer to work on an IBM Personal Computer AT. The NMI interrupt handler should read the coprocessor's status to determine if the NMI was caused by the coprocessor. If the interrupt was not generated by the coprocessor, control should be passed to the original NMI interrupt handler.

The coprocessor has two operating modes similar to the two modes of the microprocessor. When reset by a power-on reset or an I/O write operation to port hex 00F1, the coprocessor is in the real address mode. This mode is compatible with the 8087 Math Coprocessor used in other IBM Personal Computers. The coprocessor can be placed in the protected mode by executing the SETPM ESC instruction. It can be placed back in the real mode by an I/O write operation to port hex 00F1, with D7 through D0 equal to 0.

The coprocessor instruction extensions to the microprocessor can be found in Section 6 of this manual.

Detailed information for the internal functions of the Intel 80287 coprocessor can be found in books listed in the Bibliography.

## Notes:

# SECTION 3. POWER SUPPLY

## Contents

<b>Inputs</b> .....	<b>3-3</b>
<b>Outputs</b> .....	<b>3-3</b>
<b>Output Protection</b> .....	<b>3-4</b>
<b>Dummy Load</b> .....	<b>3-4</b>
<b>Output Voltage Sequencing</b> .....	<b>3-4</b>
<b>No-Load Operation</b> .....	<b>3-5</b>
<b>Power-Good Signal</b> .....	<b>3-5</b>
Fan-Out .....	3-6
<b>Connectors</b> .....	<b>3-6</b>

## **Notes:**

The system's power supply is contained *inside* of the system unit and provides power for the system board, the adapters, the diskette drives, the fixed disk drives, the keyboard, and the IBM Monochrome Display.

## Inputs

The power supply can operate at a frequency of either  $60 \pm 3$  Hz or  $50 \pm 3$  Hz and it can operate at 110 Vac, 5 A or 220/240 Vac, 2.5 A. The voltage is selected with the switch above the power-cord plug at the rear of the power supply. The following figure shows the input requirements.

Range	Voltage (Vac)	Current (Amperes)
115 Vac	Minimum 100	Maximum 5
	Maximum 125	
230 Vac	Minimum 200	Maximum 3.0
	Maximum 240	

### Input Requirements

**Note:** The maximum in-rush current is 100 A.

## Outputs

The power supply provides +5, -5, +12, and -12 Vdc. The following figure shows the load current and regulation tolerance for the voltages.

**Note:** The power supply also supplies either 115 Vac or 230 Vac for the IBM Monochrome Display.

Nominal Output	Load Current (A)		Regulation Tolerance
	Min	Max	
+5 Vdc	7.0	19.8	+5% to -4%
-5 Vdc	0.0	0.3	+10% to -8%
+12 Vdc	2.5	7.3	+5% to -4%
-12 Vdc	0.0	0.3	+10% to -9%

### DC Load Requirements

## Output Protection

If any output becomes overloaded, the power supply will switch off within 20 milliseconds. An overcurrent condition will not damage the power supply.

## Dummy Load

If no fixed disk drive is connected to the power supply, the Dummy Load must be connected to P10. The Dummy Load is a 5 ohm, 50 watt resistor.

## Output Voltage Sequencing

Under normal conditions, the output voltage levels track within 300 milliseconds of each other when power is applied to, or removed from the power supply, provided at least minimum loading is present.

# No-Load Operation

No damage or hazardous conditions occur when primary power is applied with no load on any output level. In such cases, the power supply may switch off, and a power/on cycle will be required. The power supply requires a minimum load for proper operation.

## Power-Good Signal

The power supply provides a 'power-good' signal to indicate proper operation of the power supply.

When the supply is switched off for a minimum of 1 second and then switched on, the 'power-good' signal is generated, assuming there are no problems. This signal is a logical AND of the dc output-voltage sense signal and the ac input-voltage sense signal. The power-good signal is also a TTL-compatible high level for normal operation, or a low level for fault conditions. The ac fail signal causes power-good to go to a low level at least 1 millisecond before any output voltage falls below the regulation limits. The operating point used as a reference for measuring the 1 millisecond is normal operation at minimum line voltage and maximum load.

The dc output-voltage sense signal holds the 'power-good signal' at a low level when power is switched on until all output voltages have reached their minimum sense levels. The 'power-good signal' has a turn-on delay of at least 100 milliseconds but not longer than 500 milliseconds. The following figure shows the minimum sense levels for the output voltages.

Level (Vdc)	Minimum (Vdc)
+5	+4.5
-5	-3.75
+12	+10.8
-12	-10.4

## Sense Levels

## Fan-Out

Fan-out is the number of inputs that one output can drive. The 'power-good' signal can drive six standard TTL loads.

## Connectors

The following figure shows the pin assignments for the power-supply output connectors.

Load Point	Voltage (Vdc)	Max. Current (A)
PS8-1	Power Good	See note
PS8-2	+5	3.8
PS8-3	+12	0.7
PS8-4	-12	0.3
PS8-5	Ground	0.0
PS8-6	Ground	0.0
PS9-1	Ground	0.0
PS9-2	Ground	0.0
PS9-3	-5	0.3
PS9-4	+5	3.8
PS9-5	+5	3.8
PS9-6	+5	3.8
P10-1	+12	2.8
P10-2	Ground	0.0
P10-3	Ground	0.0
P10-4	+5	1.8
P11-1	+12	2.8
P11-2	Ground	0.0
P11-3	Ground	0.0
P11-4	+5	1.8
P12-1	+12	1.0
P12-2	Ground	0.0
P12-3	Ground	0.0
P12-4	+5	0.6

### DC Load Distribution

**Note:** For more details, see 'Power-Good Signal'.

## **Notes:**

# SECTION 4. KEYBOARD

## Contents

<b>Description</b> .....	<b>4-3</b>
Interface .....	4-3
Sequencing Key Code Scanning .....	4-3
Keyboard Buffer .....	4-3
Keys .....	4-3
<b>Functions Performed at Power-On Time</b> .....	<b>4-4</b>
Power-On Reset .....	4-4
Basic Assurance Test .....	4-4
<b>Commands from the System</b> .....	<b>4-5</b>
Reset (Hex FF) .....	4-5
Resend (Hex FE) .....	4-6
No-Operation (NOP) (Hex FD through F7) .....	4-6
Set Default (Hex F6) .....	4-6
Default Disable (Hex F5) .....	4-6
Enable (Hex F4) .....	4-6
Set Typematic Rate/Delay (Hex F3) .....	4-7
No-Operation (NOP) (Hex F2 through EF) .....	4-8
Echo (Hex EE) .....	4-8
Set/Reset Mode Indicators (Hex ED) .....	4-8
<b>Keyboard Outputs</b> .....	<b>4-10</b>
Key Scan Codes .....	4-10
<b>Command Codes to the System</b> .....	<b>4-12</b>
Resend (Hex FE) .....	4-12
ACK (Hex FA) .....	4-12
Overrun (Hex 00) .....	4-13
Diagnostic Failure (Hex FD) .....	4-13
Break Code Prefix (Hex F0) .....	4-13
BAT Completion Code (Hex AA) .....	4-13
ECHO Response (Hex EE) .....	4-13

<b>Clock and Data Signals</b>	<b>4-14</b>
Keyboard Data Output	4-15
Keyboard Data Input	4-15
 <b>Keyboard Layout</b>	 <b>4-16</b>
U.S. English Keyboard	4-17
U.K. English Keyboard	4-18
French Keyboard	4-19
German Keyboard	4-20
Italian Keyboard	4-21
Spanish Keyboard	4-22
 <b>Specifications</b>	 <b>4-23</b>
Size	4-23
Weight	4-23
Keyboard Connector	4-23

# Description

The keyboard is a low-profile, 84 key, detachable unit.

## Interface

The keyboard uses a bidirectional serial interface to carry signals between the keyboard and system unit.

## Sequencing Key Code Scanning

The keyboard is able to detect all keys that are pressed, and their scan codes will be sent to the interface in correct sequence, regardless of the number of keys held down. Keystrokes entered while the interface is inhibited (when the keylock is on) will be lost. Keystrokes are stored only when the keyboard is not serviced by the system.

## Keyboard Buffer

The keyboard has a 16-character first-in-first-out (FIFO) buffer where data is stored until the interface is ready to receive it.

A buffer-overrun condition will occur if more than sixteen codes are placed in the buffer before the first keyed data is sent. The seventeenth code will be replaced with the overrun code, hex 00. (The 17th position is reserved for overrun codes). If more keys are pressed before the system allows a keyboard output, the data will be lost. When the keyboard is allowed to send data, the characters in the buffer will be sent as in normal operation, and new data entered will be detected and sent.

## Keys

All keys are classified as *make/break*, which means when a key is pressed, the keyboard sends a make code for that key to the

keyboard controller. When the key is released, its break code is sent (the break code for a key is its make code preceded by hex FO).

All keys are typematic. When a key is pressed and held down, the keyboard continues to send the make code for that key until the key is released. The rate at which the make code is sent is known as the typematic rate (The typematic rate is described under "Set Typematic Rate/Delay"). When two or more keys are held down, only the last key pressed repeats at the typematic rate. Typematic operation stops when the last key pressed is released, even if other keys are still held down. When a key is pressed and held down while the interface is inhibited, only the first make code is stored in the buffer. This prevents buffer overflow as a result of typematic action.

## Functions Performed at Power-On Time

### Power-On Reset

The keyboard logic generates a POR when power is applied to the keyboard. The POR lasts a minimum of 300 milliseconds and a maximum of 9 seconds.

**Note:** The keyboard may issue a false return during the first 200 milliseconds after the +5 Vdc is established at the 90% level. Therefore, the keyboard interface is disabled for this period.

### Basic Assurance Test

Immediately following the POR, the keyboard executes a basic assurance test (BAT). This test consists of a checksum of all read-only memory (ROM), and a stuck-bit and addressing test of all random-access memory (RAM) in the keyboard's microprocessor. The mode indicators—three light emitting diodes

(LEDs) on the upper right-hand corner of the keyboard—are turned on then off, and must be observed to ensure they are operational.

Execution of the BAT will take from 600 to 900 milliseconds. (This is in addition to the time required for the POR.)

The BAT can also be started by a Reset command.

After the BAT, and when the interface is enabled ('clock' and 'data' lines are set high), the keyboard sends a completion code to the interface—either hex AA for satisfactory completion or hex FC (or any other code) for a failure. If the system issues a Resend command, the keyboard sends the BAT completion code again. Otherwise, the keyboard sets the keys to typematic and make/break.

## Commands from the System

The commands described below may be sent to the keyboard at any time. The keyboard will respond within 20 milliseconds.

**Note:** The following commands are those sent by the system. They have a different meaning when issued by the keyboard.

### Reset (Hex FF)

The system issues a Reset command to start a program reset and a keyboard internal self-test. The keyboard acknowledges the command with an 'acknowledge' signal (ACK) and ensures the system accepts the 'ACK' before executing the command. The system signals acceptance of the 'ACK' by raising the clock and data for a minimum of 500 microseconds. The keyboard is disabled from the time it receives the Reset command until the 'ACK' is accepted or until another command overrides the previous one. Following acceptance of the 'ACK', the keyboard

begins the reset operation, which is similar to a power-on reset. The keyboard clears the output buffer and sets up default values for typematic and delay rates.

## **Resend (Hex FE)**

The system can send this command when it detects an error in any transmission from the keyboard. It can be sent only after a keyboard transmission and before the system enables the interface to allow the next keyboard output. Upon receipt of Resend, the keyboard sends the previous output again unless the previous output was Resend. In this case, the keyboard will resend the last byte before the Resend command.

## **No-Operation (NOP) (Hex FD through F7)**

These commands are reserved and are effectively no-operation or NOP. The system does not use these codes. If sent, the keyboard will acknowledge the command and continue in its prior scanning state. No other operation will occur.

## **Set Default (Hex F6)**

The Set Default command resets all conditions to the power-on default state. The keyboard responds with 'ACK', clears its output buffer, sets default conditions, and continues scanning (only if the keyboard was previously enabled).

## **Default Disable (Hex F5)**

This command is similar to Set Default, except the keyboard stops scanning and awaits further instructions.

## **Enable (Hex F4)**

Upon receipt of this command, the keyboard responds with 'ACK', clears its output buffer, and starts scanning.

## Set Typematic Rate/Delay (Hex F3)

The system issues this command, followed by a parameter, to change the typematic rate and delay. The typematic rate and delay parameters are determined by the value of the byte following the command. Bits 6 and 5 serve as the delay parameter and bits 4, 3, 2, 1, and 0 (the least-significant bit) are the rate parameter. Bit 7, the most-significant bit, is always 0. The delay is equal to 1 plus the binary value of bits 6 and 5 multiplied by 250 milliseconds  $\pm 20\%$ . The period (interval from one typematic output to the next) is determined by the following equation:

$$\text{Period} = (8 + A) \times (2^B) \times 0.00417 \text{ seconds, where } A = \text{binary value of bits 2, 1, and 0 and } B = \text{binary value of bits 4 and 3.}$$

The typematic rate (make code per second) is 1/period. The period is determined by the first equation above. The following table results.

Bit Rate	Bit Rate
00000 30.0	10000 7.5
00001 26.7	10001 6.7
00010 24.0	10010 6.0
00011 21.8	10011 5.5
00100 20.0	10100 5.0
00101 18.5	10101 4.6
00110 17.1	10110 4.3
00111 16.0	10111 4.0
01000 15.0	11000 3.7
01001 13.3	11001 3.3
01010 12.0	11010 3.0
01011 10.9	11011 2.7
01100 10.0	11100 2.5
01101 9.2	11101 2.3
01110 8.6	11110 2.1
01111 8.0	11111 2.0

### Typematic Rate

The keyboard responds to the Set Typematic Rate Delay command with an 'ACK', stops scanning, and waits for the rate parameter. The keyboard responds to the rate parameter with another 'ACK', sets the rate and delay, and continues scanning (if the keyboard was previously enabled). If a command is received instead of the rate parameter, the set-typematic-rate

function ends with no change to the existing rate, and the new command is processed. However, the keyboard will not resume scanning unless instructed to do so by an Enable command.

The default rate for the system keyboard is as follows:

The typematic rate = 10 characters per second  $\pm 20\%$  and the delay = 500 ms  $\pm 20\%$ .

## No-Operation (NOP) (Hex F2 through EF)

These commands are reserved and are effectively no-operation (NOP). The system does not use these codes. If sent, the keyboard acknowledges the command and continues in its prior scanning state. No other operation will occur.

## Echo (Hex EE)

Echo is a diagnostic aide. When the keyboard receives this command, it issues a hex EE response and continues scanning if the keyboard was previously enabled.

## Set/Reset Mode Indicators (Hex ED)

Three mode indicators on the keyboard are accessible to the system. The keyboard activates or deactivates these indicators when it receives a valid command from the system. They can be activated or deactivated in any combination.

It is up to the using system to remember the previous state of an indicator. This is in case its setting does not change when a command sequence is issued to change the state of another indicator.

The system remembers the previous state of an indicator so that its setting does not change when a command sequence is issued to change the state of another indicator.

The command has the following format:

## Set/Reset Command

A Set/Reset Mode Indicators command consists of two bytes. The first is the command byte and has the following bit setup:

11101101 – hex ED

The second byte is an option byte. It has a list of the indicators to be acted upon. The format of the option byte is as follows:

- |              |                        |
|--------------|------------------------|
| <b>Bit 7</b> | Reserved               |
| <b>Bit 6</b> | Reserved               |
| <b>Bit 5</b> | Reserved               |
| <b>Bit 4</b> | Reserved               |
| <b>Bit 3</b> | Reserved               |
| <b>Bit 2</b> | Caps Lock indicator    |
| <b>Bit 1</b> | Numeric Lock indicator |
| <b>Bit 0</b> | Scroll Lock indicator  |

**Note:** Bit 7 is the most-significant bit; bit 0 is the least-significant.

The keyboard will respond to the Set/Reset Mode Indicators command with an 'ACK', discontinue scanning, and wait for the option byte. The keyboard will respond to the option byte with an Ack, set the indicators, and continue scanning if the keyboard was previously enabled. If another command is received in place of the option byte, execution of the function of the Set/Reset Mode Indicators command is stopped with no change to the indicator states, and the new command is processed. Then scanning is resumed.

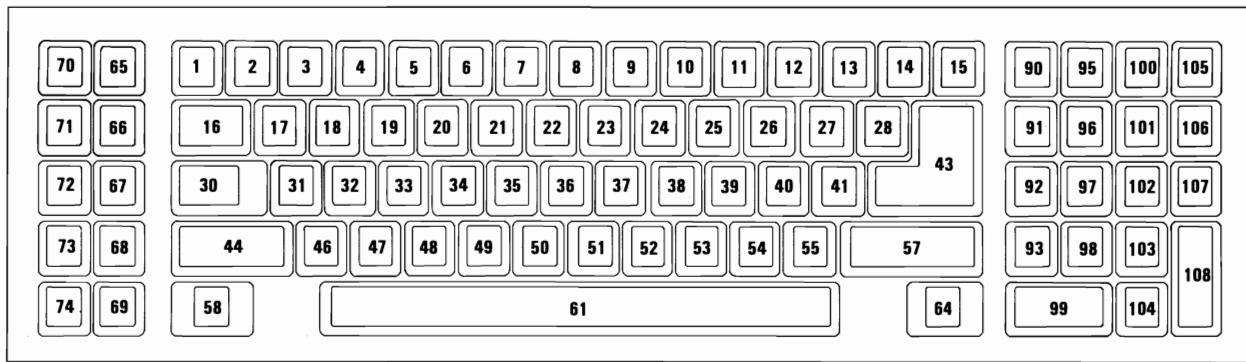
# Keyboard Outputs

## Key Scan Codes

Each key is assigned a unique 8-bit, make, scan code, which is sent when the key is pressed. Each key also sends a break code when the key is released. The break code consists of two bytes, the first of which is the break code prefix, hex F0; the second byte is the same as the make scan code for that key.

The typematic scan code for a key is the same as the key's make code. The following figure is a keyboard layout.

) ) )



The following figure lists the positions of the keys and their make scan codes.

<b>Key Positions and Their Make Codes</b>				
1--DE	18--1D	36--33	55--4A	90--76
2--16	19--24	37--3B	56--51	91--6C
3--1E	20--2D	38--42	57--59	92--6B
4--26	21--2C	39--4B	58--11	93--69
5--25	22--35	40--4C	60--19	94--77
6--2E	23--3C	41--52	61--29	96--75
7--36	24--43	43--5A	64--58	97--73
8--3D	25--44	44--12	65--D6	98--72
9--3E	26--4D	46--1A	66--DC	99--70
10--46	27--54	47--22	67--0B	100--7E
11--45	28--5B	48--21	68--0A	101--7D
12--4E	30--14	49--2A	69--09	102--74
13--55	31--1C	50--32	70--05	103--7A
14--5D	32--1B	51--31	71--04	104--71
15--66	33--23	52--3A	72--D3	105--84
16--0D	34--2B	53--41	73--83	106--7C
17--15	35--34	54--49	74--01	107--7B

### **Make Scan Codes**

## **Command Codes to the System**

The command codes described here are those sent by the keyboard. The codes have a different meaning when issued by the system.

### **Resend (Hex FE)**

The keyboard issues a Resend command following receipt of an invalid input, or any input with incorrect parity. If the system sends nothing to the keyboard, no response is required.

### **ACK (Hex FA)**

The keyboard issues an 'ACK' response to any valid input other than an Echo or Resend command. If the keyboard is interrupted

while sending 'ACK', it will discard 'ACK' and accept and respond to the new command.

## Overrun (Hex 00)

An overrun character is placed in position 17 of the keyboard buffer, overlaying the last code if the buffer becomes full. The code is sent to the system as an overrun when it reaches the top of the buffer.

## Diagnostic Failure (Hex FD)

The keyboard periodically tests the sense amplifier and sends a diagnostic failure code if it detects any problems. If a failure occurs during BAT, the keyboard stops scanning and waits for a system command or power-down to restart. If a failure is reported after scanning is enabled, scanning continues.

## Break Code Prefix (Hex F0)

This code is sent as the first byte of a 2-byte sequence to indicate the release of a key.

## BAT Completion Code (Hex AA)

Following satisfactory completion of the BAT, the keyboard sends hex AA. Hex FC (or any other code) means the keyboard microprocessor check failed.

## ECHO Response (Hex EE)

This is sent in response to an Echo command from the system.

# Clock and Data Signals

The keyboard and system communicate over the 'clock' and 'data' lines. The source of each of these lines is an open-collector device on the keyboard that allows either the keyboard or the system to force a line to a negative level. When no communication is occurring, both the 'clock' and 'data' lines are at a positive level.

Data transmissions to and from the keyboard consist of 11-bit data streams that are sent serially over the serial data line. The following figure shows the structure of the data stream.

Bit	Function
1st bit	0 start bit
2nd bit	Data bit 0 (least-significant)
3rd bit	Data bit 1
4th bit	Data bit 2
5th bit	Data bit 3
6th bit	Data bit 4
7th bit	Data bit 5
8th bit	Data bit 6
9th bit	Data bit 7 (most-significant)
10th bit	Parity bit (odd parity)
11th bit	Stop bit

## Transmission Data Stream

The parity bit is either 1 or 0, and the eight data bits, plus the parity bit, always have an odd number.

When the system sends data to the keyboard, it forces the 'data' line to a negative level and allows the 'clock' line to go to a positive level.

When the keyboard sends data to, or receives data from the system, it generates the 'clock' signal to time the data. The system can prevent the keyboard from sending data by forcing the 'clock' line to a negative level; the 'data' line may go high or low during this time.

During the BAT, the keyboard allows the 'clock' and 'data' lines to go to a positive level.

## Keyboard Data Output

When the keyboard is ready to send data, it first checks for a keyboard-inhibit or system request-to-send status on the 'clock' and 'data' lines. If the 'clock' line is low (inhibit status), data is stored in the keyboard buffer. If the 'clock' line is high and 'data' is low (request-to-send), data is stored in the keyboard buffer, and the keyboard receives system data.

If 'clock' and 'data' are both high, the keyboard sends the 0 start bit, 8 data bits, the parity bit and the stop bit. Data will be valid before the falling edge and beyond the rising edge of 'clock'. During transmission, the keyboard checks the 'clock' line for a positive level at least every 60 milliseconds. If the system lowers the 'clock' line from a positive level after the keyboard starts sending data, a condition known as *line contention* occurs, and the keyboard stops sending data. If line contention occurs before the rising edge of the tenth clock (parity bit), the keyboard buffer returns the 'data' and 'clock' lines to a positive level. If contention does not occur by the tenth clock, the keyboard completes the transmission.

Following a transmission, the system can inhibit the keyboard until the system processes the input or until it requests that a response be sent.

## Keyboard Data Input

When the system is ready to send data to the keyboard, it first checks if the keyboard is sending data. If the keyboard is sending but has not reached the tenth clock, the system can override the keyboard output by forcing the 'clock' line to a negative level. If the keyboard transmission is beyond the tenth clock, the system must receive the transmission.

If the keyboard is not sending, or if the system elects to override the keyboard's output, the system forces the 'clock' line to a negative level for more than 60 microseconds while preparing to send. When the system is ready to send the start bit ('data' line will be low), it allows the 'clock' line to go to a positive level.

The keyboard checks the state of the 'clock' line at intervals of no less than 60 milliseconds. If a request-to-send is detected, the keyboard counts 11 bits. After the tenth bit, the keyboard forces the 'data' line low and counts one more (the stop bit). This action signals the system that the keyboard has received its data. Upon receipt of this signal, the system returns to a ready state, in which it can accept keyboard output, or goes to the inhibited state until it is ready.

Each system command or data transmission to the keyboard requires a response from the keyboard before the system can send its next output. The keyboard will respond within 20 milliseconds unless the system prevents keyboard output. If the keyboard response is invalid or has a parity error, the system sends the command or data again. A Resend command should not be sent in this case.

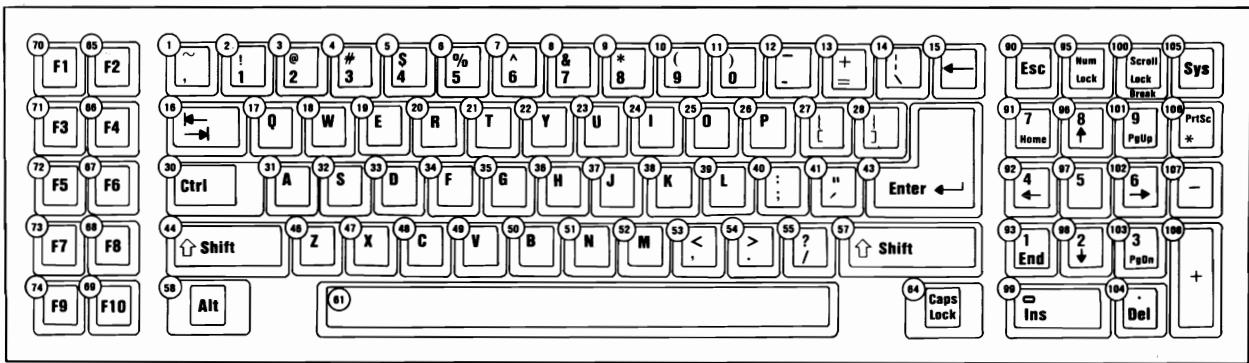
## Keyboard Layout

The IBM Personal Computer AT Keyboard is available in six different layouts:

- U.S. English
- U.K. English
- French
- German
- Italian
- Spanish

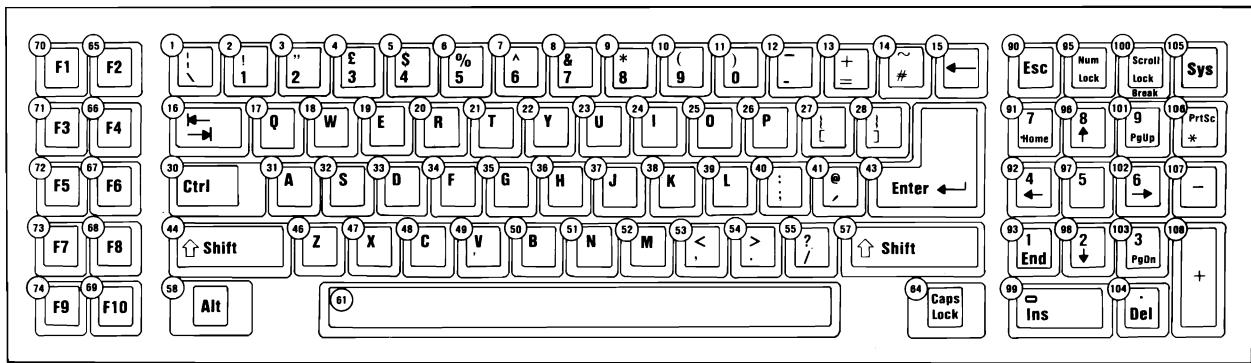
The following pages show all six possible keyboard layouts.

# U.S. English Keyboard

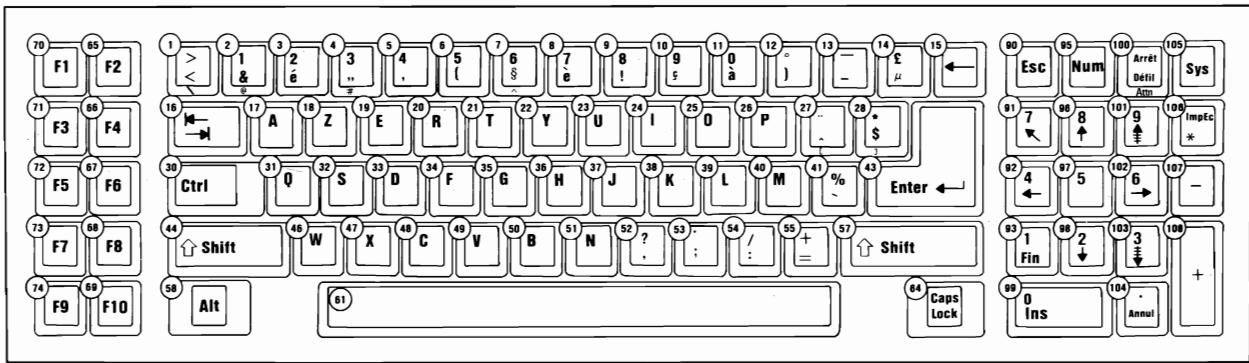


## U.K. English Keyboard

### 4-18 Keyboard

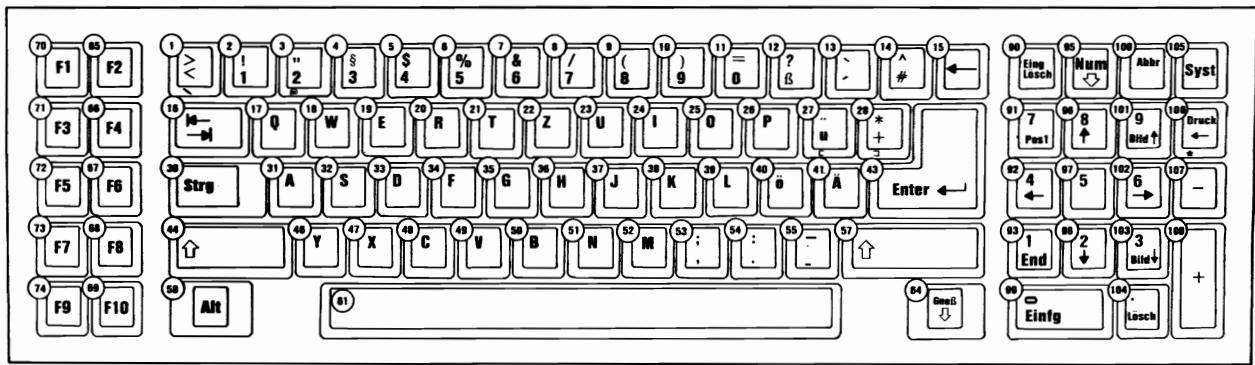


# French Keyboard



# German Keyboard

## 4-20 Keyboard

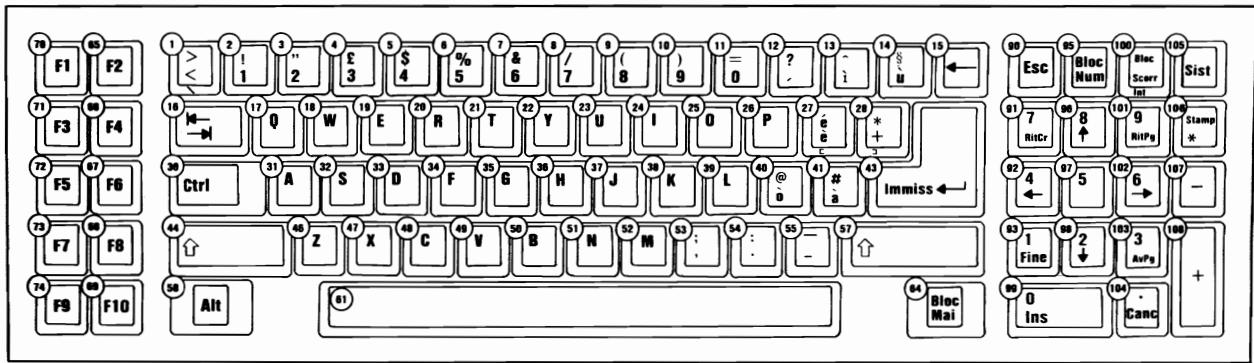


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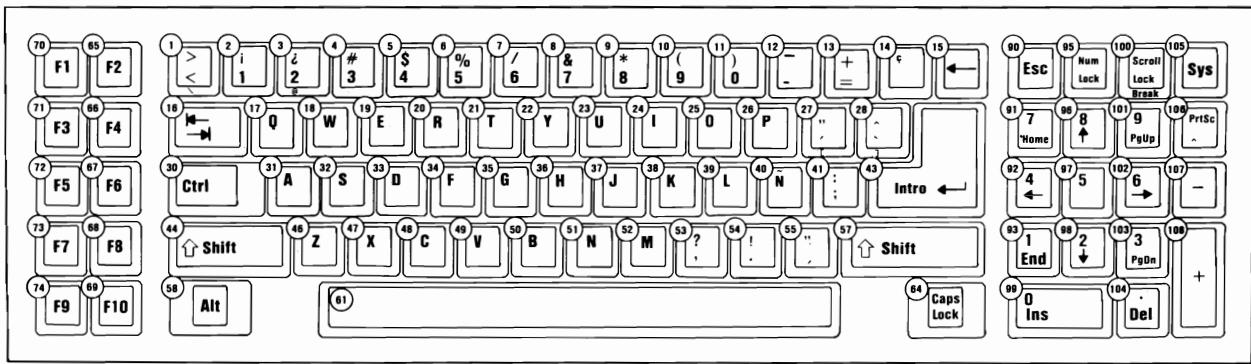
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# Italian Keyboard



Spanish Keyboard

4-22 Keyboard



# Specifications

## Size

- Length: 540 millimeters (21.6 inches)
- Depth: 100 millimeters (4 inches)
- Height: 225 millimeters (9 inches)

## Weight

- 2.8 kilograms (6.2 pounds)

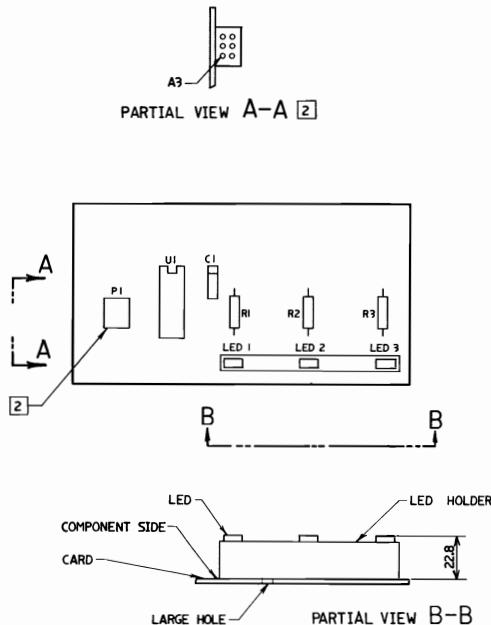
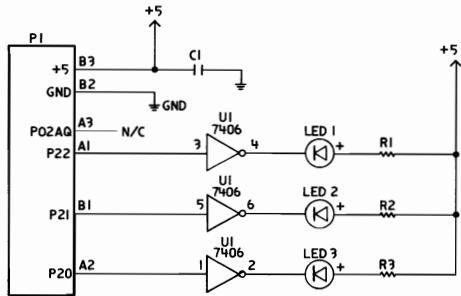
## Keyboard Connector

The keyboard cable connects to the system board through a 5-pin DIN connector. The following figure lists the connector pins and their signals.

Connector Pin	Signal Name
1	Clock
2	Data
3	Spare
4	Ground
5	+5 Vdc

**Keyboard Connector**

## 4-24 Keyboard



### NOTES:

I SOLDERING: THIS MANUFACTURING PROCESS  
MAY INCLUDE HAZARDOUS OPERATIONS AND  
REQUIRE SPECIAL HEALTH AND/OR  
SAFETY PRECAUTIONS.

[2] POLARIZE PI AT POSITION A3

## Enhancement Logic Card Assembly

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# SECTION 5. SYSTEM BIOS

## Contents

<b>System BIOS .....</b>	<b>5-3</b>
System BIOS Usage .....	5-3
Parameter Passing .....	5-4
Vectors with Special Meanings .....	5-6
Other Read/Write Memory Usage .....	5-8
BIOS Programming Hints .....	5-10
Adapters with System-Accessible ROM Modules ..	5-11
System Board Additional ROM Modules .....	5-12
Keyboard Encoding and Usage .....	5-12
Encoding .....	5-12
Character Codes .....	5-13
Extended Codes .....	5-17
Extended Functions .....	5-17
Special Handling .....	5-21

## **Notes:**

# System BIOS

The basic input/output system (BIOS) resides in ROM on the system board and provides level control for the major I/O devices in the system. Additional ROM modules may be placed on option adapters to provide device level control for that option adapter. BIOS routines enable the assembler language programmer to perform block (disk or diskette) or character-level I/O operations without concern for device address and characteristics. System services, such as time-of-day and memory size determination, are provided by the BIOS.

If the sockets labeled U17 and U37 on the system board are empty, additional ROM modules may be placed in these sockets. During POST a test is made for valid code at this location, starting at address hex E0000 and ending at hex EFFFF. More information about these sockets may be found under "System Board Additional ROM Modules" later in this section.

The goal of the ROM BIOS is to provide an operational interface to the system and relieve the programmer of concern about the characteristics of hardware devices. The BIOS interface protects the user from the hardware, allowing new devices to be added to the system, yet retaining the BIOS level interface to the device. In this manner, hardware modifications and enhancements become transparent to user programs.

The *IBM Personal Computer MACRO Assembler* manual and the *IBM Personal Computer Disk Operating System (DOS)* manual provide useful programming information related to this section. A complete listing of the BIOS is given later in this section.

## System BIOS Usage

Access to BIOS is through program interrupts of the 80286 in the real mode. Each BIOS entry point is available through its own interrupt. For example, to determine the amount of base RAM available in the system with the 80286 in the real mode, INT 12H will invoke the BIOS routine for determining the memory size and return the value to the caller.

## Parameter Passing

All parameters passed to and from the BIOS routines go through the 80286 registers. The prolog of each BIOS function indicates the registers used on the call and return. For the memory size example, no parameters are passed. The memory size, in 1Kb increments, is returned in the AX register.

If a BIOS function has several possible operations, the AH register is used at input to indicate the desired operation. For example, to set the time of day, the following code is required:

```
MOV AH,1           ;function is to set time-of-day  
MOV CX,HIGH COUNT ;establish the current time  
MOV DX,LOW COUNT  
INT 1AH           ;set the time
```

To read the time of day:

```
MOV AH,0           ;function is to read time-of-day  
INT 1AH           ;read the timer
```

The BIOS routines save all registers except for AX and the flags. Other registers are modified on return only if they are returning a value to the caller. The exact register usage can be seen in the prolog of each BIOS function.

The following figure shows the interrupts with their addresses and functions.

<b>Address</b>	<b>Int</b>	<b>Name</b>	<b>BIOS Entry</b>
0-3	0	Divide by Zero	D11
4-7	1	Single Step	D11
8-B	2	Nonmaskable	NMI INT
C-F	3	Breakpoint	D11
10-13	4	Overflow	D11
14-17	5	Print Screen	PRINT SCREEN
18-1B	6	Reserved	D11
1D-1F	7	Reserved	D11
20-23	8	Time of Day	TIMER INT
24-27	9	Keyboard	KB INT
28-2B	A	Reserved	D11
2C-2F	B	Communications	D11
30-33	C	Communications	D11
34-37	D	Alternate Printer	D11
38-3B	E	Diskette	DISK INT
3C-3F	F	Printer	D11
40-43	10	Video	VIDEO IO
44-47	11	Equipment Check	EQUIPMENT
48-4B	12	Memory	MEMORY SIZE DETERMINE
4C-4F	13	Diskette/Disk	DISKETTE IO
50-53	14	Communications	RS232 IO
54-57	15	Cassette	CASSETTE IO/System Extensions
58-5B	16	Keyboard	KEYBOARD IO
5C-5F	17	Printer	PRINTER IO
60-63	18	Resident BASIC	F600:0000
64-67	19	Bootstrap	BOOT STRAP
68-6B	1A	Time of Day	TIME OF DAY
6C-6F	1B	Keyboard Break	DUMMY RETURN
70-73	1C	Timer Tick	DUMMY RETURN
74-77	1D	Video Initialization	VIDEO PARMS
78-7B	1E	Diskette Parameters	DISK BASE
7C-7F	1F	Video Graphics Chars	0

### 80286 Program Interrupt Listing (Real Mode Only)

The following figure shows hardware, BASIC, and DOS reserved interrupts.

Address	Interrupt	Function
80-83	20	DOS program terminate
84-87	21	DOS function call
88-8B	22	DOS terminate address
8C-8F	23	DOS Ctrl Break exit address
90-93	24	DOS fatal error vector
94-97	25	DOS absolute disk read
98-9B	26	DOS absolute disk write
9C-9F	27	DOS terminate, fix in storage
A0-FF	28-3F	Reserved for DOS
100-17F	40-5F	Reserved
180-19F	60-67	Reserved for user program interrupts
1A0-1BF	68-6F	Not used
1C0-1C3	70	IRQ 8 Realtime clock INT (BIOS entry RTC_INT)
1C4-1C7	71	IRQ 9 (BIOS entry RE_DIRECT)
1C8-1CB	72	IRQ 10 (BIOS entry D11)
1CC-1CF	73	IRQ 11 (BIOS entry D11)
1D0-1D3	74	IRQ 12 (BIOS entry D11)
1D4-1D7	75	IRQ 13 BIOS Redirect to NMI interrupt (BIOS entry INT_287)
1D8-1DB	76	IRQ 14 (BIOS entry D11)
1DC-1DF	77	IRQ 15 (BIOS entry D11)
1E0-1FF	78-7F	Not used
200-217	80-85	Reserved by BASIC
218-3C3	86-FO	Used by BASIC interpreter while BASIC is running
3C4-3FF	F1-FF	Not used

## Hardware, BASIC, and DOS Interrupts

### Vectors with Special Meanings

**Interrupt 15--Cassette I/O:** This vector points to the following functions:

- Device open
- Device closed
- Program termination
- Event wait

- Joystick support
- System Request key pressed
- Wait
- Move block
- Extended memory size determination
- Processor to protected mode

Additional information about these functions may be found in the BIOS listing.

**Interrupt 1B--Keyboard Break Address:** This vector points to the code that will be executed when the Ctrl and Break keys are pressed on the keyboard. The vector is invoked while responding to keyboard interrupt, and control should be returned through an IRET instruction. The power-on routines initialize this vector to point to an IRET instruction so that nothing will occur when the Ctrl and Break keys are pressed unless the application program sets a different value.

Control may be retained by this routine with the following problems:

- The Break may have occurred during interrupt processing, so that one or more End of Interrupt commands must be sent to the 8259 controller.
- All I/O devices should be reset in case an operation was underway at the same time.

**Interrupt 1C--Timer Tick:** This vector points to the code that will be executed at every system-clock tick. This vector is invoked while responding to the timer interrupt, and control should be returned through an IRET instruction. The power-on routines initialize this vector to point to an IRET instruction, so that nothing will occur unless the application modifies the pointer. The application must save and restore all registers that will be modified.

**Interrupt 1D--Video Parameters:** This vector points to a data region containing the parameters required for the initialization of the 6845 on the video adapter. Notice that there are four separate tables, and all four must be reproduced if all modes of operation are to be supported. The power-on routines initialize this vector to point to the parameters contained in the ROM video routines.

**Interrupt 1E--Diskette Parameters:** This vector points to a data region containing the parameters required for the diskette drive. The power-on routines initialize this vector to point to the parameters contained in the ROM diskette routine. These default parameters represent the specified values for any IBM drives attached to the system. Changing this parameter block may be necessary to reflect the specifications of other drives attached.

**Interrupt 1F--Graphics Character Extensions:** When operating in graphics modes 320 x 200 or 640 x 200, the read/write character interface will form a character from the ASCII code point, using a set of dot patterns. ROM contains the dot patterns for the first 128 code points. For access to the second 128 code points, this vector must be established to point at a table of up to 1Kb, where each code point is represented by 8 bytes of graphic information. At power-on time, this vector is initialized to 000:0, and the user must change this vector if the additional code points are required.

**Interrupt 40--Reserved:** When an IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter is installed, the BIOS routines use interrupt 40 to revector the diskette pointer.

**Interrupt 41 and 46:** These vectors point to the parameters for the fixed disk drives, 41 for the first drive and 46 for the second. The power on routines initialize the vectors to point to the appropriate parameters in the ROM disk routine if CMOS is valid. The drive type codes in CMOS are used to select which parameter set the vector points to. Changing this parameter hook may be necessary to reflect the specifications of other fixed drives attached.

## Other Read/Write Memory Usage

The IBM BIOS routines use 256 bytes of memory from absolute hex 400 to hex 4FF. Locations hex 400 to 407 contain the base addresses of any RS-232C adapters attached to the system. Locations hex 408 to 40F contain the base addresses of the printer adapter.

Memory locations hex 300 to hex 3FF are used as a stack area during the power-on initialization and bootstrap, when control is passed to it from power-on. If the user desires the stack to be in a different area, that area must be set by the application.

The following figure shows the reserved memory locations.

Address	Mode	Function
400-4A1	ROM BIOS	See BIOS listing
4A2-4EF		Reserved
4F0-4FF		Reserved as intra-application communication area for any application
500-5FF	DOS	Reserved for DOS and BASIC
500		Print screen status flag store 0=Print screen not active or successful print screen operation 1=Print screen in progress 255=Error encountered during print screen operation
504	DOS	Single drive mode status byte
510-511	BASIC	BASIC's segment address store
512-515	BASIC	Clock interrupt vector segment: offset store
516-519	BASIC	Break key interrupt vector segment: offset store
51A-51D	BASIC	Disk error interrupt vector segment: offset store

### Reserved Memory Locations

If you do a DEF SEG (default workspace segment):

Offset	Length	
2E	2	Line number of current line being executed
347	2	Line number of last error
30	2	Offset into segment of start of program text
358	2	Offset into segment of start of variables (end of program text 1-1)
6A	1	Keyboard buffer contents 0=No characters in buffer 1=Characters in buffer
4E	1	Character color in graphics mode*

## BASIC Workspace Variables

\*Set to 1,2, or 3 to get text in colors 1-3. Do not set to 0. The default is 3.

### Example

100 PRINT PEEK (&H2E) + 256 x PEEK (&H2F)

L	H
Hex 64	Hex 00

The following is a BIOS memory map.

Starting Address	
00000	BIOS interrupt vectors
001E0	Available interrupt vectors
00400	BIOS data area
00500	User read/write memory
E0000	Read only memory
F0000	BIOS program area

## BIOS Memory Map

## BIOS Programming Hints

The BIOS code is invoked through program interrupts. The programmer should not "hard code" BIOS addresses into applications. The internal workings and absolute addresses within BIOS are subject to change without notice.

If an error is reported by the disk or diskette code, you should reset the drive adapter and retry the operation. A specified number of retries should be required for diskette reads to ensure that the problem is not due to motor startup.

When altering I/O-port bit values, the programmer should change only those bits necessary to the current task. Upon completion, the programmer should restore the original environment. Failure to adhere to this practice may cause incompatibility with present and future applications.

Additional information for BIOS programming can be found in Section 9 of this manual.

## Adapters with System-Accessible ROM Modules

The ROM BIOS provides a way to integrate adapters with on-board ROM code into the system. During POST, interrupt vectors are established for the BIOS calls. After the default vectors are in place, a scan for additional ROM modules occurs. At this point, a ROM routine on an adapter may gain control and establish or intercept interrupt vectors to hook themselves into the system.

The absolute addresses hex C8000 through E0000 are scanned in 2K blocks in search of a valid adapter ROM. A valid ROM is defined as follows:

**Byte 0** Hex 55

**Byte 1** Hex AA

**Byte 2** A length indicator representing the number of 512-byte blocks in the ROM.

**Byte 3** Entry via a CALL FAR

A checksum is also done to test the integrity of the ROM module. Each byte in the defined ROM module is summed modulo hex 100. This sum must be 0 for the module to be valid.

When the POST identifies a valid ROM, it does a far call to byte 3 of the ROM, which should be executable code. The adapter may now perform its power-on initialization tasks. The adapter's ROM should now return control to the BIOS routines by executing a far return.

## System Board Additional ROM Modules

The POST provides a way to integrate additional ROM modules' code into the system. These modules are placed in the sockets marked U17 and U37 if they are empty. A test for additional ROM modules on the system board occurs. At this point, the additional ROM, if valid, will gain control.

The absolute addresses hex E0000 through EFFFF are scanned in a 64K block in search of a valid checksum. Valid ROM is defined as follows:

**Byte 0**    Hex 55

**Byte 1**    Hex AA

**Byte 2**    Not used

**Byte 3**    Entry via a CALL FAR

A checksum is done to test the integrity of the ROM modules. Each byte in the ROM modules is summed modulo hex 100. This sum must be 0 for the modules to be valid. This checksum is located at address hex EFFF.

When the POST identifies a valid ROM at this segment, it does a far call to byte 3 of the ROM, which should be executable code.

## Keyboard Encoding and Usage

### Encoding

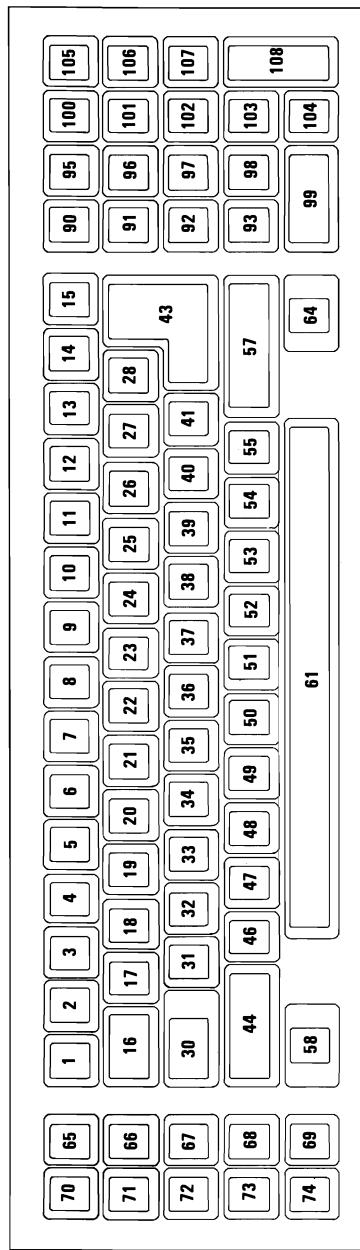
The keyboard routine provided by IBM in the ROM scan codes into what will be termed *Extended ASCII*

Extended ASCII encompasses one-byte character codes with possible values of 0 to 255, an extended code for certain extended keyboard functions, and functions handled within the keyboard routine or through interrupts.

## Character Codes

The following character codes are passed through the BIOS keyboard routine to the system or application program. A -1 means the combination is suppressed in the keyboard routine. The codes are returned in the AL register. See Section 7 for the exact codes.

The following figure is a keyboard layout showing the key positions.



<b>Key</b>	<b>Base Case</b>	<b>Upper Case</b>	<b>Ctrl</b>	<b>Alt</b>
90	Esc	Esc	Esc	-1
2	1	!	-1	Note 1
3	2	@	NUL(000) Note 1	Note 1
4	3	#	-1	Note 1
5	4	\$	-1	Note 1
6	5	%	-1	Note 1
7	6	_	RS(030)	Note 1
8	7	&	-1	Note 1
9	8	*	-1	Note 1
10	9	(	-1	Note 1
11	0	)	-1	Note 1
12	-		US(031)	Note 1
13	=	—	-1	Note 1
15	Backspace(008)	Backspace(008)	Del(127)	-1
16	→(009)	←(Note 1)	-1	-1
17	q	Q	DC1(017)	Note 1
18	w	W	ETB(023)	Note 1
19	e	E	ENQ(005)	Note 1
20	r	R	DC2(018)	Note 1
21	t	T	DC4(020)	Note 1
22	y	Y	EM(025)	Note 1
23	u	U	NAK(021)	Note 1
24	i	I	HT(009)	Note 1
25	o	O	SI(015)	Note 1
26	p	P	DLE(016)	Note 1
27	[	{	Esc(027)	Note 1
28	]	}	GS(029)	-1
43	CR	CR	LF(010)	-1
30 Ctrl	-1	-1	-1	-1
31	a	A	SOH(001)	Note 1
32	s	S	DC3(019)	Note 1
33	d	D	EOT(004)	Note 1
34	f	F	ACK(006)	Note 1
35	g	G	BEL(007)	Note 1
36	h	H	BS(008)	Note 1
37	j	J	LF(010)	Note 1
38	k	K	VT(011)	Note 1
39	l	L	FF(012)	Note 1
40	:	:	-1	-1
41	;	■	-1	-1
1	Ω	◦	-1	-1
44 Shift	-1	-1	-1	-1
14	\	—	FS(028)	-1
46	z	Z	SUB(026)	Note 1
47	x	X	CAN(024)	Note 1
48	c	C	ETX(003)	Note 1
49	v	V	SYN(022)	Note 1
50	b	B	STX(022)	Note 1

(Part 1 of 1).

**Character Codes**

Key	Base Case	Upper Case	Ctrl	Alt
51	n	N	SO(014)	Note 1
52	m	M	CR(013)	Note 1
53	,	<	-1	-1
54	.	>	-1	-1
55	/	?	-1	-1
57 Shift	-1	-1	-1	-1
106	*	Note 2	Note 1	-1
56 Alt	-1	-1	-1	-1
61	SP	SP	SP	SP
64 Caps Lock	-1	-1	-1	-1
70	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
65	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
71	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
66	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
72	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
67	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
73	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
68	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
74	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
69	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)	Nul(Note 1)
95 Num Lock	-1	-1	Pause(Note 2)	-1
100 Scroll Lock	-1	-1	Break(Note 2)	-1

**Notes:**

1. Refer to Extended Codes in this section.
2. Refer to Special Handling in this section.

(Part 2 of 2)

Character Codes

The following figure lists keys that have meaning only in Num Lock, Shift, or Ctrl states. Notice that the Shift key temporarily reverses the current Num Lock state.

Key	Num Lock	Base Case	Alt	Ctrl
91	7	Home(Note 1)	-1	Clear Screen
96	8	↑(Note 1)	-1	-1
101	9	Page Up(Note 1)	-1	Top of Text and Home
107	-	-	-1	-1
92	4	←(Note 1)	-1	Reverse Word(Note 1)
97	5	-1	-1	-1
102	6	→(Note 1)	-1	Advance Word(Note 1)
108	+	+Note 1)	-1	-1
94	1	End(Note 1)	-1	Erase to EOL(Note 1)
98	2	↓(Note 1)	-1	-1
102	3	Page Down(Note 1)	-1	Erase to EOS(Note 1)
99	0	Ins	-1	-1
104	.	Del(Notes 1,2)	Note 2	Note 2

**Notes:**  
 Refer to Extended Codes in this section.  
 Refer to Special Handling in this section

## Special Character Codes

## Extended Codes

### Extended Functions

For certain functions that cannot be represented by the standard ASCII code, an extended code is used. A character code of 000 (null) is returned in AL. This indicates that the system or application program should examine a second code, which will indicate the actual function. Usually, but not always, this second code is the scan code of the primary key that was pressed. This code is returned in AH.

Second Code	Function
3	Nul Character
15	→
16-25	Alt Q, W, E, R, T, Y, U, I, O, P
30-38	Alt A, S, D, F, G, H, J, K, L
44-50	Alt Z, X, C, V, B, N, M
59-68	F1 to F10 Function keys base case
71	Home
72	↑
73	Page Up and Home Cursor
75	←
77	→
79	End
80	↓
81	Page Down and Home Cursor
82	Ins(insert)
83	Del(delete)
84-93	F11 to F20(uppercase F1 to F10)
94-103	F21 to F30(Ctrl F1 to F10)
104-113	F31 to F40(Alt F1 to F10)
114	Ctrl PrtSc(start/stop echo to printer)
115	Ctrl ←(reverse word)
116	Ctrl →(advance word)
117	Ctrl End(erase to end of line-EOL)
118	Ctrl PgDn(erase to end of screen-EOS)
119	Ctrl Home(clear screen and home)
120-131	Alt 1, 2, 3, 4, 5, 6, 7, 8, 9, 0, -, = keys 2-13
132	Ctrl PgUp(top 25 lines of text and home cursor)

## Keyboard Extended Functions

### Shift States

Most shift states are handled within the keyboard routine, and are not apparent to the system or application program. In any case, the current status of active shift states is available by calling an entry point in the ROM keyboard routine. The following keys result in altered shift states:

**Shift:** This key temporarily shifts keys 1-14, 16-28, 31-41, 46-55, 106, and 65-74 to uppercase (base case if in Caps lock state). Also, the Shift temporarily reverses the Num Lock or non-Num Lock state of keys 91-93, 96, 98, and 101-103.

**Ctrl:** This key temporarily shifts keys 3, 7, 13, 15, 17-28, 31-39, 46-52, 106, 65-74, 42, 101, 92, 102, 91, 93, 95, 100, and 103 to the Ctrl state. The Ctrl key is also used with the Alt and Del keys to cause the system-reset function; with the Scroll Lock key to cause the break function; and with the Num Lock key to cause the pause function. The system-reset, break, and pause functions are described under "Special Handling" later in this section.

**Alt:** This key temporarily shifts keys 1-13, 17-26, 31-39, 46-52, and 65-74 to the Alt state. The Alt key is also used with the Ctrl and Del keys to cause the system reset function.

The Alt key also allows the user to enter any character code from 0-255 into the system from the keyboard. The user holds down the Alt key and types the decimal value of the characters desired on the numeric keypad (keys 91-93, 96-98, and 101-103). The Alt key is then released. If more than three digits are typed, a modulo-256 result is created. These three digits are interpreted as a character code and are sent through the keyboard routine to the system or application program. Alt is handled internal to the keyboard routine.

**Break:** The combination of the Ctrl and Break keys results in the keyboard routine signaling interrupt hex 1A. The extended characters AL=hex 00, AH=hex 00 are also returned.

**Pause:** The combination of the Ctrl and Num Lock keys causes the keyboard interrupt routine to loop, waiting for any key except Num Lock to be pressed. This provides a system- or application-transparent method of temporarily suspending list, print, etc. and then resuming the operation. The key used to resume operation is thrown away. Pause is handled internal to the keyboard routine.

**Print Screen:** The combination of the Shift and PrtSc keys results in an interrupt invoking the print screen routine. This routine works in the alphanumeric or graphics mode, with unrecognizable characters printing as blanks.

**Caps Lock:** This key shifts keys 17-26, 31-39, and 46-52 to uppercase. When Caps Lock is pressed again, it reverses the action. Caps Lock is handled internal to the keyboard routine.

When Caps Lock is pressed, it toggles the Caps Lock Mode indicator. If the indicator was on, it will go off; and if it was off, it will go on.

**Scroll Lock:** This key is interpreted by appropriate application programs as indicating that the use of cursor control keys should cause windowing over the text rather than cursor movement. When the Scroll Lock key is pressed again, it reverses the action. The keyboard routine simply records the current shift state of the Scroll Lock key. It is the responsibility of the application program to perform the function. When Scroll Lock is pressed, it toggles the Scroll Lock Mode indicator. If the indicator was on, it will go off; and if it was off, it will go on.

**Num Lock:** This key shifts keys 90-93 and 95-104 to upper case. When Num Lock is pressed again, it reverses the action. Num Lock is handled internal to the keyboard routine. When Num Lock is pressed, it toggles the Num Lock Mode indicator. If the indicator was on, it will go off; if it was off, it will go on.

**Shift Key Priorities and Combinations:** If combinations of the Alt, Ctrl, and Shift keys are pressed and only one is valid, the priority is as follows: the Alt key is first, the Ctrl key is second, and the Shift key is third. The only valid combination is Alt and Ctrl, which is used in the system-reset function.

## Sys Req

When the Sys key is pressed, a hex 8500 is placed in AX, and an interrupt 15 is executed. When the Sys key is released, a hex 8501 is placed in AX, and another interrupt 15 is executed. If an application is to use the Sys key, the following rules must be observed:

Save the previous address

Overlay interrupt vector hex 15

Check AH for a value of hex 85

If yes, process may begin

If no, go to previous address

It is the responsibility of the application to preserve the value in all registers, except AX, upon return. Sys is handled internal to the keyboard routine.

## Other Characteristics

The keyboard routine does its own buffering, and the keyboard buffer is large enough to support entries by a fast typist.

However, if a key is pressed when the buffer is full, the key will be ignored and the "alarm" will sound.

The keyboard routine also suppresses the typematic action of the following keys: Ctrl, Shift, Alt, Num Lock, Scroll Lock, Caps Lock, and Ins.

## Special Handling

### System Reset

The combination of the Alt, Ctrl, and Del keys results in the keyboard routine that starts a system reset or reboot. System reset is handled by BIOS.

## Notes:

Warning: No STACK segment

Start	Stop	Length	Name		
00000H	0FFFH	FFFFH	CODE	0000:18F7	EXC_20
				0000:18FC	EXC_21
				0000:1901	EXC_22
				0000:1906	EXC_23
				0000:190B	EXC_24
				0000:1910	EXC_25
				0000:1915	EXC_26
				0000:191A	EXC_27
				0000:191F	EXC_28
				0000:1924	EXC_29
				0000:1929	EXC_30
				0000:192E	EXC_31
				0000:1753	E_MSG
				F1	
				0000:E1C2	F1780
				0000:E393	F1782
				0000:E3A8	F1790
				0000:E3DB	F1791
				0000:E3EE	F1_A
				0000:E1FB	F1_B
				0000:E34E	F3
				0000:E21F	F3A
				0000:E152	F3B
				0000:E15D	F3D
				0000:E18B	F3D1
				0000:E1A1	F4
				0000:E2AC	F4E
				0000:E2B2	FD_TBL
				0000:E401	FILL
				0000:4752	GATE_A20
				0000:4392	GDT_BLD
				0000:1FF0	CM1
				0000:1BC6	CM2
				0000:2FA4	CM3
				0000:1852	CM4
				0000:E8E1	CM4_A
				0000:E91B	CM4_B
				0000:E955	CM4_C
				0000:E95F	CM4_D
				0000:E969	CRT_CHAR_GEN
				0000:E976	D1
				0000:30A9	D11
				0000:E87E	D2
				0000:0008	D2A
				Abs K6L	DDS
				0000:E886	DISKETTE_IO
				0000:E88E	DISKETTE_IO_1
				0000:E8C8	DISK_BASE
				0000:17D2	DISK_INT
				0000:E987	DISK_INT_1
				0000:3054	DISK_IO
				0000:E82E	DISK_SETUP
				0000:2FC8	DSKETTE_SETUP
				0000:0010	DUMMY_RETURN
				Abs M4	DUMMY_RETURN_1
				0000:FOE4	E0
				0000:FOEC	E0_A
				0000:FOF4	E0_B
				0000:F841	E1
				0000:3E62	E1_A
				0000:E2C3	E1_B
				0000:3E76	E1_C
				0000:0411	E30B
				0000:E064	E30C
				0000:06A	EQUIPMENT
				0000:002C	EQUIPMENT_1
				0000:0C3F	ERR_BEEP
				0000:16AD	EXC_00
				0000:1753	EXC_01
				0000:187F	EXC_02
				0000:199C	EXC_03
				0000:1C2D	EXC_04
				0000:EFD2	EXC_05
				0000:346F	EXC_06
				0000:FF54	EXC_07
				0000:46CC	EXC_08
				0000:174C	EXC_09
				0000:1720	EXC_10
				0000:1719	EXC_11
				0000:186A	EXC_12
				0000:176C	EXC_13
				0000:FFF0	EXC_14
				0000:38F5	EXC_15
				0000:377B	EXC_16
				0000:3A3B	EXC_17
				0000:3DBC	EXC_18
				0000:1861	EXC_19

0000:16D0	ROM_CHECK	0000:174C	PROC_SHUTDOWN
0000:1AF9	ROM_ERR	0000:1753	POST4
0000:16AD	ROS_CHECKSUM	0000:1753	E_MSG
0000:E739	RS232_IO	0000:176C	P_MSG
0000:34F5	RS232_IO_1	0000:177A	ERR_BEEP
0000:462A	RTC_INT	0000:17AA	BEEP
0000:38A3	SCROLL_DOWN	0000:17D2	KBD_RESET
0000:37FF	SCROLL_UP	0000:17FD	DDS
0000:24C1	SEEK	0000:1805	D11
0000:37B6	SET_COLOR	0000:1851	DUMMY_RETURN_1
0000:3751	SET_CPOS	0000:1852	INT_287
0000:372A	SET_CTYPE	0000:1861	RE_DIRECT
0000:364E	SET_MODE	0000:186A	PRT_SEG
0000:3F2F	SET_TOD	0000:187F	EXC_00
0000:1197	SHUT2	0000:187F	POST5
0000:114A	SHUT3	0000:1884	EXC_01
0000:169B	SHUT4	0000:1889	EXC_02
0000:11BC	SHUT6	0000:188E	EXC_03
0000:119A	SHUT7	0000:1893	EXC_04
0000:4252	SHUT9	0000:1898	EXC_05
0000:1FF9	SIDT_BLD	0000:18B1	EXC_06
0000:FF23	SLAVE_VECTOR_TABLE	0000:18B6	EXC_07
0000:EO5B	START	0000:18BB	EXC_08
0000:00A6	START_1	0000:18C0	EXC_09
0000:199C	STGTST_CNT	0000:18C5	EXC_10
0000:1F1A	SYSINIT1	0000:18CA	EXC_11
0000:1933	SYS_32	0000:18CF	EXC_12
0000:1938	SYS_33	0000:18D4	EXC_13
0000:193D	SYS_34	0000:18D9	EXC_14
0000:1942	SYS_35	0000:18DE	EXC_15
0000:1947	SYS_36	0000:18E3	EXC_16
0000:194C	SYS_37	0000:18E8	EXC_17
0000:1951	SYS_38	0000:18ED	EXC_18
0000:FEA5	TIMER_INT	0000:18F2	EXC_19
0000:4684	TIMER_INT_1	0000:18F7	EXC_20
0000:FE6E	TIME_OF_DAY	0000:18FC	EXC_21
0000:445C	TIME_OF_DAY_1	0000:1901	EXC_22
0000:03C7	TST4_B	0000:1906	EXC_23
0000:03D3	TST4_C	0000:190B	EXC_24
0000:03F7	TST4_D	0000:1910	EXC_25
0000:FEF3	VECTOR_TABLE	0000:1915	EXC_26
0000:F065	VIDEO_IO	0000:191A	EXC_27
0000:3605	VIDEO_IO_1	0000:191F	EXC_28
0000:FOA4	VIDEO_PARMS	0000:1924	EXC_29
0000:37DC	VIDEO_STATE	0000:1929	EXC_30
0000:EOB7	VIR_ERR	0000:192E	EXC_31
0000:393B	WRITE_AC_CURRENT	0000:1933	SYS_32
0000:396E	WRITE_C_CURRENT	0000:1938	SYS_33
0000:3A4C	WRITE_DOT	0000:193D	SYS_34
0000:3D38	WRITE_TTY	0000:1942	SYS_35
0000:1713	XLAT_PR	0000:1947	SYS_36
0000:1825	XNIT_8042	0000:194C	SYS_37
0000:1708	XPC_BYTE	0000:1951	SYS_38
		0000:199C	POST6
Address	Publics by Value	0000:199C	STGTST_CNT
		0000:1AF9	ROM_ERR
0000:0000	BEGIN	0000:1B25	XNIT_8042
0000:0008 Abs	K6L	0000:1B66	BOOT_STRAP_1
0000:0010 Abs	M4	0000:1BC6	H5
0000:002C	POST1	0000:1C2D	POST7
0000:00A6	START_1	0000:1F1A	SYSINIT1
0000:0222	C11	0000:1FF0	GDT_BLD
0000:03C7	TST4_B	0000:1FF9	SIDT_BLD
0000:03D3	TST4_C	0000:20A5	DISKETTE_IO_1
0000:03E5	E30B	0000:24C1	SEEK
0000:03EB	E30C	0000:260E	DISK_INT_1
0000:03F7	TST4_D	0000:2816	DSKETTE_SETUP
0000:0405	C8042	0000:28DA	DISK_SETUP
0000:0411	OBF_42	0000:2A71	DISK_IO
0000:0454	C30	0000:2FA4	HD_INT
0000:09FB	CHK_VIDEO	0000:2FC8	KEYBOARD_IO_1
0000:0C3F	POST2	0000:3054	KB_INT_1
0000:0C3F	C21	0000:30A9	K16
0000:114A	SHUT3	0000:346F	PRINTER_IO_1
0000:1197	SHUT2	0000:34F5	RS232_IO_1
0000:119A	SHUT7	0000:3605	VIDEO_IO_1
0000:11BC	SHUT6	0000:364E	SET_MODE
0000:169B	SHUT4	0000:372A	SET_CTYPE
0000:16AD	ROS_CHECKSUM	0000:3751	SET_CPOS
0000:16AD	POST3	0000:377B	READ_CURSOR
0000:16B9	BLINK_INT	0000:3792	ACT_DISP_PAGE
0000:16D0	ROM_CHECK	0000:37B6	SET_COLOR
0000:1708	XPC_BYTE	0000:37DC	VIDEO_STATE
0000:1713	XLAT_PR	0000:37FF	SCROLL_UP
0000:1719	FRT_HEX	0000:38A3	SCROLL_DOWN
0000:1720	PROT_PRT_HEX	0000:38F5	READ_AC_CURRENT
		0000:393B	WRITE_AC_CURRENT

0000:396E	WRITE_C_CURRENT	0000:F0E4	M5
0000:3A3B	READ_DOT	0000:FOEC	M6
0000:3A4C	WRITE_DOT	0000:FOF4	M7
0000:3D38	WRITE_TTY	0000:F841	MEMORY_SIZE_DETERMINE
0000:3DBC	READ_LPEN	0000:F84D	EQUIPMENT
0000:3E62	MEMORY_SIZE_DETERMINE_1	0000:F859	CASSETTE_IO
0000:3E6C	EQUIPMENT_1	0000:FA6E	CRT_CHAR_GEN
0000:3E76	NMI_INT_1	0000:FE6E	TIME_OF_DAY
0000:3F2F	SET_TOD	0000:FEA5	TIMER_INT
0000:3FE2	CASSETTE_IO_1	0000:FEF3	VECTOR_TABLE
0000:4252	SHUT9	0000:FF23	SLAVE_VECTOR_TABLE
0000:4392	GATE_A20	0000:FF53	DUMMY_RETURN
0000:445C	TIME_OF_DAY_1	0000:FF54	PRINT_SCREEN
0000:462A	RTC_INT	0000:FFF0	P_O_R
0000:4684	TIMER_INT_1		
0000:46CC	PRINT_SCREEN_1		
0000:4752	FILL		
0000:E05B	START		
0000:E05E	C1		
0000:E060	C2		
0000:E062	C8042A		
0000:E064	OBF_42A		
0000:E066	C8042B		
0000:E068	C8042C		
0000:E06A	OBF_42B		
0000:E06C	E0		
0000:E085	E0_A		
0000:E09E	E0_B		
0000:E0B7	VIR_ERR		
0000:E0D0	CM4		
0000:EOE9	E1		
0000:EOF0	E1_B		
0000:E10C	E1_C		
0000:E11C	ADERR1		
0000:E137	ADERR		
0000:E152	F3A		
0000:E15D	F3B		
0000:E164	D1		
0000:E174	D2		
0000:E184	D2A		
0000:E18B	F3D		
0000:E1A1	F3D1		
0000:E1C2	F1		
0000:E1D7	LOCK		
0000:E1FB	F1_A		
0000:E21F	F3		
0000:E234	CM1		
0000:E25D	CM2		
0000:E286	CM3		
0000:E2AC	F4		
0000:E2B2	F4E		
0000:E2C3	NMI_INT		
0000:E2C6	CM4_A		
0000:E2DF	CM4_B		
0000:E2F8	CM4_C		
0000:E311	CM4_D		
0000:E32A	E1_A		
0000:E34E	F1_B		
0000:E372	BOOT_INVA		
0000:E393	F1780		
0000:E3A8	F1781		
0000:E3BD	F1782		
0000:E3DB	F1790		
0000:E3EE	F1791		
0000:E401	FD_TBL		
0000:E6F2	BOOT_STRAP		
0000:E729	A1		
0000:E739	RS232_IO		
0000:E82E	KEYBOARD_IO		
0000:E87E	K6		
0000:E886	K7		
0000:E88E	K8		
0000:E8C8	K9		
0000:E8E1	K10		
0000:E91B	K11		
0000:E955	K12		
0000:E95F	K13		
0000:E969	K14		
0000:E976	K15		
0000:E987	KB_INT		
0000:EC59	DISKETTE_IO		
0000:EF57	DISK_INT		
0000:EFC7	DISK_BASE		
0000:EFD2	PRINTER_IO		
0000:F065	VIDEO_IO		
0000:FOA4	VIDEO_PARMS		



**BIOS I/O INTERFACE**

THESES INTERFACE LISTINGS PROVIDE ACCESS TO BIOS ROUTINES  
THESE BIOS ROUTINES ARE MEANT TO BE ACCESSED THROUGH  
SOFTWARE INTERRUPTS ONLY. ANY ADDRESSES PRESENT IN  
THE LISTINGS ARE INCLUDED ONLY FOR COMPLETENESS,  
NOT FOR REFERENCE. APPLICATIONS WHICH REFERENCE  
ABSOLUTE ADDRESSES WITHIN THE CODE SEGMENT  
VIOLATE THE STRUCTURE AND DESIGN OF BIOS.

**PAGE**

**MODULES REQUIRED**

DATA.D0	-->	DATA AREA
TEST1.SRC	-->	TEST_01 THRU TEST_16
TEST2.SRC	-->	TEST_17 THRU TEST_22
TEST3.SRC	-->	PROCEDURES
		ROS_CHECKSUM
		BLN_CHKSUM
		ROM_CHECK
		XPC_BYTE
		PRT_HEX
		PROT_PRT_HEX
		PROG_SHUTDOWN
		E_MSG
		P_MSG
		BEEP
		ERR_BEEP
		KBD_RESET
		D11_DUMMY INT HANDLER
		INT13_X287 HANDLER
		PRT_SEG
		DDS
		HARDWARE INT 9 HANDLER (TYPE 71)
TEST5.SRC	-->	EXCEPTION_INTERRUPTS
TEST6.SRC	-->	SYS_TMR_CNT
		ROM_ERR
		XMIT_8042
		BOOT_STRAP
TEST7.SRC	-->	PROTECTED_MODE_TEST
SYSINIT1.SRC	-->	BUILD_PROTECTED_MODE_DESCRIPTOR
SIDT_BLD.SRC		
CDT_BLD.SRC		
DSKETTE_SRC	-->	DISKETTE BIOS
DISK_SRC	-->	HARD FILE BIOS
KYBD_SRC	-->	KEYBOARD BIOS
PRTY_BD	-->	PRINTER BIOS
RS232_SRC	-->	RS232 BIOS
VIDEO1.SRC	-->	VIDEO BIOS
BIOS.SRC	-->	MEM_SIZE
		EQUIP_DET
		NMI
		SET_TOD
BIOS1.SRC	-->	DUMMY_CASSETTE (INT 15)
		DEVICE_OPEN
		DEVICE_CLOSE
		PROGRAM_TERMINATION
		EVENT_WAIT
		JOYSTICK_SUPPORT
		SYSTEM_REQUEST_KEY
		WAIT
		MOVE_BLOCK
		EXTENDED_MEMORY_SIZE_DETERMINE
		PROGRAM_TO_VIRTUAL_MODE
BIOS2.SRC	-->	TIME_OF_DAY
		TIMER1_INT
		PRINT_SCREEN
ORGs.SRC	-->	PC_COMPATIBILITY_AND_TABLES
		POST_ERROR_MESSAGES

**INCLUDE POSTEQU.SRC**

**EQUATES**

= 0000	EQU	0	: CONDITIONAL ASM (TEST2.SRC)
= 0000	EQU	0	: CONDITIONAL ASM (TEST2.SRC)
= 0000	EQU	0	: CONDITIONAL ASM (KYBD.SRC)
= 00F0	EQU	0FOH	: MATH PROCESSOR
= 0020	EQU	020H	: MFG LOOP POST JUMPER
= 0010	EQU	010H	: REFRESH TEST BIT
= 0000	EQU	0H	: POST STACK SEGMENT
= 8000	EQU	8000H	: POST STACK POINTER
= FFFF	EQU	0FFFFH	: SET_PROTECTED_MODE TEMP_SS
= 0000	EQU	0	: 0:FFFFH
= 0060	EQU	60H	: 8042 KEYBOARD SCAN/DIAG OUTPUTS
= 0061	EQU	61H	: 8042 READ WRITE REGISTER
= 00C0	EQU	0COH	: RAM/10 CHANNEL PARITY ERROR
= 00F3	EQU	11110011B	: AND THIS VALUE
= 000C	EQU	00000100B	: OR THIS VALUE
= 0040	EQU	01000000B	: IO CHECK?
= 0080	EQU	10000000B	: PARITY CHECK?
= 0064	EQU	64H	: 8042 STATUS PORT
= 0001	EQU	01H	: 0 = +OUTPUT BUFFER FULL
= 0002	EQU	02H	: 1 = +INPUT BUFFER FULL
= 0004	EQU	04H	: 2 = -SERIAL LINE PORT/-SELF TEST
= 0008	EQU	08H	: 3 = COMMAND/INHIBIT
= 0010	EQU	10H	: 4 = +KEYBOARD INHIBITED
= 0020	EQU	20H	: 5 = +TRANSMIT TIMEOUT
= 0040	EQU	40H	: 6 = +RECEIVE TIME OUT
= 0080	EQU	80H	: 7 = +KEYBOARD EVEN
= 00F0	EQU	0FEH	: CAUSE A SHUTDOWN COMMAND
= 00A8	EQU	0ABH	: CHECK 8042 INTERFACE CMD
= 00E0	EQU	0E0H	: GET KYBD CLOCK AND DATA CMD
= 0001	EQU	001H	: KEYBOARD CLOCK BIT 0
= 0080	EQU	80H	: MANUFACTURING CHECKPOINT PORT
<b>-----MANUFACTURING PORT-----</b>			
= 0001	EQU	0000001B	: MANUFACTURING PORT DEFINITION FOR MFG_ERR_FLAG1
= 0002	EQU	0000010B	: STORAGE TEST FAILED (ERROR 20X)
= 0004	EQU	0000010B	: VIRTUAL MODE TEST FAILED (ERROR 104)
= 0008	EQU	0000100B	: LOW MEG CHIP SELECT FAILED (ERROR 109)
= 0010	EQU	0001000B	: KEYBOARD CLOCK TEST FAILED (ERROR 304)
= 0020	EQU	0010000B	: KEYBOARD OR SYSTEM FAILED (ERROR 303)
= 0040	EQU	0100000B	: KEYBOARD FAILED (ERROR 301)
	EQU	0100000B	: DISKETTE TEST FAILED (ERROR 601)

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= 0080
C KEY_FAIL EQU 10000000B ; KEYBOARD LOCKED (ERROR 302)
C -----8042 INPUT PORT BIT DEFINITION-----
C BASE_RAM EQU 10H ; BASE R/H MEMORY
C MFG_JMP EQU 20H ; LOOP POST JUMPER
C DSP_JMP EQU 40H ; DISPLAY TYPE JUMPER
C KEY_BD_INHIB EQU 80H ; KEYBOARD INHIBIT SWITCH
= 0010
C -----8042 INPUT PORT DEFINITION-----
C KEYBOARD EQU 00H ; BYTE 0 BIT 4 OF 8042 RAM
C -----COMMANDS-----
C READ_8042_RAM EQU 20H ; BITS 0-4 = ADDRESS (20-3F)
C WRITE_8042_RAM EQU 60H ; 8042 SELF TEST
C SELF_8042_TEST EQU 0AAH ; READ 8042 INPUT PORT
C READ_8042_INPUT EQU 0C0H ; ENABLD KEYBOARD COMMAND
C KB_KBD EQU 0AEH ; DISABLE KEYBOARD COMMAND
C DIS_KBD EQU 0ADH ; ENABLE ADDR LINE BIT 20
C ENABLE_BIT20 EQU 0DFH ; DISABLE ADDR LINE BIT 20
C DISABLE_BIT20 EQU 0DDH
C -----KEYBOARD/LED COMMANDS-----
C KB_MENU EQU 00H ; SELECT MENU COMMAND
C KB_ENABLE EQU 0F4H ; KEYBOARD ENABLE
C KB_MAKE_BREAK EQU 0F7H ; TYPOMATIC
C KB_ECHO EQU 0FEH ; ECHO COMMAND
C KB_RESET EQU 0FFH ; SELF DIAGNOSTIC COMMAND
C LED_CMD EQU 0E0H ; LED WRITE COMMAND
C -----KEYBOARD RESPONSE-----
C KBx_OK EQU 0AAH ; RESPONSE FROM SELF DIAG
C KB_ACK EQU 0FAH ; ACKNOWLEDGE FROM TRANSMISSION
C KB_OVER_RUN EQU 0FFH ; OVER RUN
C KB_RESEND EQU 0FEH ; RESEND REQUEST
C KB_BREAK EQU 010H ; KEYBOARD BREAK CODE
C KB_FA EQU 010H ; ACK RECEIVED
C KB_FE EQU 020H ; RESEND RECEIVED FLAG
C KB_PR_LED EQU 040H ; MODE INDICATOR UPDATE
C -----CMOS EQUATES-----
C CMOS_PORT EQU 070H ; IO ADDRESS OF CMOS PORT
C CLK_UP EQU 08AH ; CLOCK UPDATE STATUS
C CMOS_ALARM EQU 08BH
C CMOS_BEGIN EQU 090H
C CMOS_END EQU 0A0H ; SHUTDOWN OFFSET
C SHUT_DOWN EQU 08FH ; BATTERY STATUS
C -----BAD_TEN_SECOND_STATUS-----
C M_SIZE_HI EQU 081H ; 10 MEMORY SIZE HIGH BYTE (POST)
C M_SIZE_LO EQU 080H ; 10 MEMORY SIZE LO BYTE (POST)
C MT_SIZE_HI EQU 096H ; 0->640K CONFIG MEMORY SIZE (SETUP)
C M1_SIZE_HI EQU 095H ; LOW BYTE (SETUP)
C M2_SIZE_HI EQU 098H ; 640K->1M CONFIG MEMORY SIZE (SETUP)
C M3_SIZE_HI EQU 097H ; LOW BYTE (SETUP)
C EQUIP EQU 094H ; CMOS EQUIPMENT FLAG
C HD_FILE_TYPE EQU 092H ; HARD FILE TYPE BYTE
C PAGE
C -----CMOS_DIAG_STATUS_ERROR_FLAGS-----
C DIAG_STATUS EQU 08EH ; CMOS ADDRESS OF DIAG_STATUS
C BAD_BAT EQU 080H ; DEAD BATTERY
C BAD_CKSUM EQU 040H ; CHECKSUM ERROR
C BAD_CONFIG EQU 020H ; MINIMUM CONFIG USED INSTEAD OF CMOS
C W_MEM_SIZE EQU 010H ; MEMORY SIZE NOT EQUAL TO CONFIG
C HLT_FAIL EQU 004H ; HARD FAILURE ON INIT
C CMOS_CLK_FAIL EQU 004H ; CLK NOT UPDATING OR NOT VALID
C -----CMOS_INFORMATION_FLAGS-----
C INFO_STATUS EQU 083H ; CMOS ADDRESS OF INFO BYTE
C M640K EQU 080H ; 512K -> 640K CARD INSTALLED
C NEW_INST EQU 040H ; FLAG USED BY CMOS SETUP UTILITY
C HLT_BOOT EQU 020H ; BOOT HARD FILE FLAG
C -----INTERRUPT_EQUATES-----
C INTAA0 EQU 20H ; 8259 PORT
C INTAA1 EQU 21H ; 8259 PORT
C EO1 EQU 20H
C INTB00 EQU 0A0H ; 2ND 8259
C INTB01 EQU 0A1H
C INT_VIDEO EQU 070H ; START OF 8259 INTERRUPT TABLE LOCATION
C INT_VIDEO EQU 010H ; VIDEO VECTOR
C -----TIMER_EQUATES-----
C TIMER EQU 40H ; 8253 TIMER CONTROL PORT ADDR
C TIM_CTL EQU 43H ; 8253 TIMER/ENTER D PORT ADDR
C TMR0 EQU 40H ; 8253 TIMER D INTR RECOV MASK
C TMINT EQU 01
C -----DMA_EQUATES-----
C DMA08 EQU 08 ; DMA STATUS REG PORT ADDR
C DMA EQU 00 ; DMA CH.0 ADDR. REG PORT ADDR
C -----DMA_STATUS_PORT_EQUATES-----
C DMA18 EQU 0D0H ; 2ND DMA STATUS PORT ADDR
C DMA19 EQU 0C0H ; 2ND DMA CH.0 ADDR. REG PORT ADDR
C -----DMA_PAGE_EQUATES-----
C DMA_PAGE EQU 81H ; START OF DMA PAGE REGISTERS
C LAST_DMA_PAGE EQU 8FH ; LAST DMA PAGE REGISTER
C -----KEYBOARD_EQUATES-----
C MAX_PERIOD EQU 500H
C MIN_PERIOD EQU 410H
C KBD_IN EQU 60H ; KEYBOARD DATA IN ADDR PORT
C KBINT EQU 02 ; KEYBOARD INTR MASK
C KB_DATA EQU 60H ; KEYBOARD SCAN CODE PORT
C KB_CTRL EQU 61H ; CONTROL BITS FOR KEYBOARD SENSE DATA
C KB_ERR EQU 80H ; KEYBOARD TRANSMIT ERROR FLAG
C -----SHIFT_FLAG_EQUATES_WITHIN_kb_flag-----
C INS_STATE EQU 80H ; INSERT STATE IS ACTIVE
C CAPS_STATE EQU 40H ; CAPS LOCK STATE HAS BEEN TOGGLED
C NUM_STATE EQU 20H ; NUM LOCK STATE HAS BEEN TOGGLED
C SCROLL_STATE EQU 10H ; SCROLL LOCK STATE HAS BEEN TOGGLED
C ALT_SHIFT EQU 08H ; ALTERNATE SHIFT KEY DEPRESSED
C CTL_SHIFT EQU 04H ; CONTROL SHIFT KEY DEPRESSED
C LEFT_SHIFT EQU 02H ; LEFT SHIFT KEY DEPRESSED
C RIGHT_SHIFT EQU 01H ; RIGHT SHIFT KEY DEPRESSED
C INS_SHIFT EQU 80H ; INSERT KEY IS DEPRESSED
C CAPS_SHIFT EQU 40H ; CAPS LOCK KEY IS DEPRESSED
C NUM_SHIFT EQU 20H ; NUM LOCK KEY IS DEPRESSED
C SCROLL_SHIFT EQU 10H ; SCROLL LOCK KEY IS DEPRESSED
C HOLD_STATE EQU 08H ; SUSPEND KEY HAS BEEN TOGGLED
C SYS_SHIFT EQU 04H ; SYSTEM KEY DEPRESSED AND HELD
C NUM_LOCK EQU 69 ; SCROLL LOCK FOR NUMBER LOCK
C SCROLL_KEY EQU 70 ; SCROLL LOCK KEY
C ALT_KEY EQU 56 ; ALTERNATE SHIFT KEY SCAN CODE
C CTL_KEY EQU 29 ; SCAN CODE FOR CONTROL KEY
C CPS_KEY EQU 58 ; SCAN CODE FOR CAPS LOCK
C LEFT_SHIFT EQU 42 ; SCAN CODE FOR LEFT SHIFT
C RIGHT_KEY EQU 54 ; SCAN CODE FOR RIGHT SHIFT
C INS_KEY EQU 82 ; SCAN CODE FOR INSERT KEY
C DEL_KEY EQU 83 ; SCAN CODE FOR DELETE KEY
C SYS_KEY EQU 94H ; SCAN CODE FOR SYSTEM KEY
C -----DISKETTE_EQUATES-----
C INT_FLAG EQU 080H ; INTERRUPT OCCURRENCE FLAG
C MOTOR_WAIT EQU 37 ; 2 SECS. OF COUNTS FOR MOTOR TURN OFF
C TIME_OUT EQU 80H ; ATTACHMENT FAILED TO RESPOND
C BAD_SEEK EQU 40H ; SEEK OPERATION FAILED
C BAD_CRC EQU 20H ; NEC CONTROLLER CRC FAILED
C BAD_CRC EQU 10H ; BAD CRC ON DISKETTE READ
C DMA_BOUNDARY EQU 09H ; ATTEMPT TO DMA ACROSS 64K BOUNDARY

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= 0008          C BAD_DMA      EQU 0BH          ; DMA OVERRUN ON OPERATION
= 0006          C MEDIA_CHANGE EQU 0FH          ; MEDIA REMOVED ON DUAL-ATTACH CARD
= 0004          C RECORD_NOT_FND EQU 04H          ; REQUESTED SECTOR NOT FOUND
= 0003          C WRITE_PROTECT EQU 03H          ; WRITE ATTEMPTED ON WRITE PROT DISK
= 0002          C BAD_ADDR_MARK EQU 02H          ; ADDRESS MARK NOT FOUND
= 0001          C BAD_CMD      EQU 01H          ; BAD COMMAND PASSED TO DISKETTE I/O

= 0002          C XRATE      EQU 02H          ; 250KBS DATA TRANSFER RATE
= 0001          C DUAL       EQU 01H          ; DUAL ATTACH CARD PRESENT FLAG

= 0080          C DSK_CHG      EQU 0B0H          ; DISKETTE CHANGE FLAG MASK BIT
= 0007          C STATE_MSK    EQU 007H          ; USED TO STRIP OFF STATE OF MEDIA
= 0076          C STATE_STTLE   EQU 0FBH          ; AS PART OF STATE BITS
= 0010          C DETERMINED   EQU 0D0H          ; SET STATE DETERMINED IN STATE BITS
= 0003          C TRAN_MSK    EQU 03H          ; ISOLATE SHIFTED TRANSFER RATE BITS
= 0020          C DOUBLE_STEP  EQU 020H          ; MASK TO TURN ON DOUBLE STEPPING
= 00F0          C MOTOR_MSK    EQU 0FOH          ; MASK TO CLEAR MOTOR ON BITS
= 0002          C MAX_DRV     EQU 020H          ; MAX NUMBER OF DRIVES
= 0010          C HOME        EQU 010H          ; SENSE DRIVE STATUS COMMAND
= 0004          C SENSE_DRV_ST EQU 004H          ; SEEK ONE TRACK
= 0001          C ONE         EQU 001H          ; CRASH STOP (48 TPI DRIVES)
= 0030          C TRK_SLAP     EQU 030H          ; SEEK TO TRACK 10
= 000A          C QUIET_SEEK  EQU 00AH          ; SEEK HEAD SETTLE TIME
= 000F          C HD320_SETTLE EQU 0009          ; 320 K HEAD SETTLE TIME
= 0014          C HD320_SETTLE EQU 0200          ; WRITE OPERATION FLAG
= 0080          C PAGE         EQU 0B0H          ; PAGE

;----- DISK CHANGE LINE EQUATES
= 0001          C DCHGLN      EQU 001H          ; NO DISK CHANGE LINE AVAILABLE
= 0002          C CHNL        EQU 002H          ; DISK CHANGE LINE AVAILABLE

;----- MEDIA/DRIVE STATUS INDICATORS
= 0093          C M326D326   EQU 093H          ; STATE MACHINE - 320/360 MEDIA/DRIVE
= 0074          C M326D12    EQU 074H          ; STATE MACHINE - 320/360 MEDIA,1.2DRIVE
= 0015          C M12012      EQU 015H          ; STATE MACHINE - 1.2 MEDIA/DRIVE
= 0061          C ROM_ISLAL   EQU 061H          ; 300K DATA TRANSFER RATE & STATE 1
= 0080          C PMA_START   EQU 0D0H          ; 250K DATA TRANSFER RATE & STATE 0

;----- CMOS NON-VOLATILE RAM EQUATES
= 000E          C CMOSDBS_ADDR EQU 00EH          ; DISKETTE STATUS BYTE ADDRESS
= 0070          C CADR_PRT    EQU 070H          ; CMOS ADDRESS PORT ADDRESS
= 0017          C CGDT_PRT    EQU 017H          ; CMOS DATA PORT ADDRESS
= 00C0          C CMOS_GND    EQU 000H          ; POWER AND GND CS/RS232 INDICATOR
= 0010          C CMOSDSK_BYT EQU 010H          ; DISKETTE BYTE ADDRESS
= 000F          C LOWN1B      EQU 00FH          ; ISOLATE LOW NIBBLE IN REGISTER MASK
= 0002          C INVALID_DRV EQU 002H          ; FIRST INVALID DISKETTE TYPE

;----- TIMER DATA AREA
;----- 0266 INTERRUPT LOCATIONS (READ):
0000          ABSO SEGMENT AT 0
0000          STG_LOCO      LABEL  BYTE
0008          NM1_PTR      ORG 2*4          LABEL WORD
0008          NM1_PTR      ORG 5*4          LABEL WORD
0014          INT5_PTR     ORG 8*4          LABEL WORD
0020          INT_ADDR     ORG 10H*4        LABEL WORD
0020          INT_PTR      ORG 10H*4        LABEL DWORD
0040          VIDEO_IN     ORG 13H*4        LABEL WORD
0040          ORG_VECTOR   ORG 13H*4        LABEL DWORD ; NEW FDISK
004C          ORG_VECTOR   ORG 18H*4        LABEL DWORD
0060          BASIC_PTR   ORG 19H*4        LABEL WORD
0064          BOOT_VEC    ORG 41H*4        LABEL DWORD
0064          BOOT_VECTOR ORG 1DH*4        LABEL DWORD
0074          PARM_PTR    ORG 1EH*4        LABEL DWORD ; POINTER TO VIDEO PARMS
0078          DISK_POINTER ORG 01FH*4        LABEL DWORD
007C          EXT_PTR     ORG 40H*4        LABEL DWORD
0100          DISK_VECTOR ORG 41H*4        LABEL DWORD ; DISKETTE POINTER
0104          HF_TBL_VEC  ORG 46H*4        LABEL DWORD
0118          HF1_TBL_VEC ORG 46H*4        LABEL DWORD
0118          HF1_TBL_VEC ORG 70H*4        LABEL DWORD
01CO          SLAVE_INT_PTR ORG 76H*4        LABEL DWORD ; REAL TIME CLOCK INT
01CO          RTC_INT_VEC  ORG 76H*4        LABEL DWORD ; FIXED DISK INTERRUPT VECTOR
0108          HDISK_IN     ORG 400H          LABEL DWORD
0400          DATA_AREA    LABEL BYTE          ; ABSOLUTE LOCATION OF DATA SEGMENT
0400          DATA_WORD    LABEL WORD          ; ABSOLUTE LOCATION OF DATA SEGMENT
0500          MFG_TEST_BTN ORG 0500H          LABEL FAR
0500          MFG_TEST_BTN ORG 7C00H          LABEL FAR
0700          BOOT_LOCK    ABSO ENDS          PAGE
0700          ABSO ENDS          PAGE

;----- STACK -- USED DURING INITIALIZATION ONLY
0000          STACK SEGMENT AT 30H
0000          DW 128 DUP(?)

0100          TOS LABEL WORD
0100          STACK ENDS
0000          DATA SEGMENT AT 40H
0000          DATA_BASE LABEL BYTE
0000          RS232_BASE DW 4 DUP(?) ; ADDRESSES OF RS232 ADAPTERS
0008          PRINTER_BASE DW 4 DUP(?) ; ADDRESSES OF PRINTERS
0010          EQUIP_FLAG DW 1 DUP(?) ; INSTALLED HARDWARE

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0012 01 [ ?? ] C MFG_TST DB 1 DUP(?) ; INITIALIZATION FLAG
0013 01 [ ??? ] C MEMORY_SIZE DW 1 DUP(?) ; MEMORY SIZE IN K BYTES
0015 01 [ ?? ] C MFG_ERR_FLAG DB 1 DUP(?) ; SCRATCHPAD FOR MANUFACTURING
0016 01 [ ?? ] C DB 1 DUP(?) ; ERROR CODES
0017 01 [ ?? ] C PAGE
0018 01 [ ?? ] C ;----- KEYBOARD DATA AREAS -----
0019 01 [ ?? ] C KB_FLAG DB 1 DUP(?) ;----- :
001A 01 [ ??? ] C KB_FLAG_1 DB 1 DUP(?) ; SECOND BYTE OF KEYBOARD STATUS
001C 01 [ ??? ] C ALT_INPUT DB 1 DUP(?) ; STORAGE FOR ALTERNATE KEYPAD ENTRY
001E 10 [ ??? ] C BUFFER_HEAD DW 1 DUP(?) ; POINTER TO HEAD OF KEYBOARD BUFFER
001E 01 [ ??? ] C BUFFER_TAIL DW 1 DUP(?) ; POINTER TO TAIL OF KEYBOARD BUFFER
001E 10 [ ??? ] C KB_BUFFER DW 16 DUP(?) ; ROOM FOR 15 ENTRIES
003E KB_BUFFER_END LABEL WORD
003E ;----- HEAD = TAIL INDICATES THAT THE BUFFER IS EMPTY
003E 01 [ ?? ] C ;----- DISKETTE DATA AREAS -----
003F 01 [ ?? ] C SEEK_STATUS DB 1 DUP(?) ; DRIVE RECALIBRATION STATUS
003F ;----- : ; BIT 3-0 = DRIVE 3-0 NEEDS RECAL
003F ;----- : ; BEFORE NEXT SEEK IF BIT IS = 0
003F ;----- : ; MOTOR STATUS
0040 01 [ ?? ] C MOTOR_STATUS DB 1 DUP(?) ;----- :
0041 01 [ ?? ] C ;----- : ; BIT 3-0 = DRIVE 3-0 IS CURRENTLY
0041 01 [ ?? ] C ;----- : ; RUNNING
0041 01 [ ?? ] C ;----- : ; BIT 3-0 = CURRENT OPERATION IS A WRITE,
0041 01 [ ?? ] C ;----- : ; REQUIRES DELAY
0041 01 [ ?? ] C ;----- : ; TIME OUT COUNTER FOR DRIVE TURN OFF
0042 01 [ ?? ] C DISKETTE_STATUS DB 1 DUP(?) ; RETURN CODE STATUS BYTE
0042 07 [ ' ?? ] C CMD_BLOCK LABEL BYTE
0042 HD_ERROR LABEL BYTE
0042 NEC_STATUS DB 7 DUP(?) ; STATUS BYTES FROM NEC
0049 01 [ ?? ] C PAGE
0049 ;----- : ;----- VIDEO DISPLAY DATA AREA -----
0049 ;----- : ;----- :
004A 01 [ ??? ] C CRT_MODE DB 1 DUP(?) ; CURRENT CRT MODE
004C 01 [ ??? ] C CRT_COLS DW 1 DUP(?) ; NUMBER OF COLUMNS ON SCREEN
004C ;----- :
004E 01 [ ??? ] C CRT_LEN DW 1 DUP(?) ; LENGTH OF REGEN IN BYTES
004E ;----- :
0050 08 [ ??? ] C CRT_START DW 1 DUP(?) ; STARTING ADDRESS IN REGEN BUFFER
0050 ;----- :
0060 01 [ ??? ] C CURSOR_POSN DW 8 DUP(?) ; CURSOR FOR EACH OF UP TO 8 PAGES
0060 ;----- :
0062 01 [ ?? ] C CURSOR_MODE DW 1 DUP(?) ; CURRENT CURSOR MODE SETTING
0062 ;----- :
0063 01 [ ??? ] C ACTIVE_PAGE DB 1 DUP(?) ; CURRENT PAGE BEING DISPLAYED
0063 ;----- :
0065 01 [ ?? ] C ADDR_6845 DW 1 DUP(?) ; BASE ADDRESS FOR ACTIVE DISPLAY CARD
0065 ;----- :
0066 01 [ ?? ] C CRT_MODE_SET DB 1 DUP(?) ; CURRENT SETTING OF THE 3XB REGISTER
0066 ;----- :
0066 CRT_PALLETTE DB 1 DUP(?) ; CURRENT PALLETTE SETTING COLOR CARD
0066 ;----- :
0066 PAGE

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C ;----- POST DATA AREA -----;
C IO_ROM_INIT DW 1 DUP(?) ; PTRN TO OPTIONAL I/O ROM INIT ROUTINE
C
C ;----- IO_ROM SEG -----;
C IO_ROM_SEG DW 1 DUP(?) ; POINTER TO IO ROM SEGMENT
C
C ;----- INTR_FLAG -----;
C INTR_FLAG DB 1 DUP(?) ; FLAG TO INDICATE AN INTERRUPT HAPPEND
C
C ;----- TIMER DATA AREA -----;
C TIMER_LOW DW 1 DUP(?) ; LOW WORD OF TIMER COUNT
C
C TIMER_HIGH DW 1 DUP(?) ; HIGH WORD OF TIMER COUNT
C
C ;----- TIMER_OFL -----;
C TIMER_OFL DB 1 DUP(?) ; TIMER HAS ROLLED OVER SINCE LAST READ
C
C ;----- SYSTEM DATA AREA -----;
C BIOS_BREAK DB 1 DUP(?) ; BIT 7=1 IF BREAK KEY HAS BEEN HIT
C
C ;----- RESET_FLAG -----;
C RESET_FLAG DW 1 DUP(?) ; WORD=1234H IF KEYBOARD RESET UNDERWAY
C
C PAGE
C ;----- HARD FILE DATA AREAS -----;
C ;----- DISK_STATUS1 -----;
C DISK_STATUS1 DB 1 DUP(?)
C
C HF_NUM DB 1 DUP(?)
C
C CONTROL_BYTE DB 1 DUP(?)
C
C PORT_OFF DB 1 DUP(?)
C
C ;----- PRINTER AND RS232 TIME-OUT VARIABLES -----;
C ;----- PRINT_TIM_OUT -----;
C PRINT_TIM_OUT DB 4 DUP(?)
C
C ;----- RS232_TIM_OUT -----;
C RS232_TIM_OUT DB 4 DUP(?)
C
C ;----- ADDITIONAL KEYBOARD DATA AREA -----;
C ;----- BUFFER_START -----;
C BUFFER_START DW 1 DUP(?)
C
C ;----- BUFFER_END -----;
C BUFFER_END DW 1 DUP(?)
C
C ;----- ADDITIONAL FLOPPY DATA -----;
C ;----- LASTRATE -----;
C LASTRATE ORG 8BH DB 1 DUP(?) ; LAST DATA RATE SELECTED
C
C PAGE
C ;----- ADDITIONAL HARD FILE DATA -----;
C ;----- HF_STATUS -----;
C HF_STATUS ORG 8CH DB 1 DUP(?) ; STATUS REGISTER
C
C HF_ERROR DB 1 DUP(?) ; ERROR REGISTER
C
C HF_INT_FLAG DB 1 DUP(?) ; HARD FILE INTERRUPT FLAG
C
C HF_CNSTRL DB 1 DUP(?) ; COMBO HARD FILE/FLOPPY CARD BIT 0=1
C
C ;----- ADDITIONAL DISKETTE AREA -----;
C ;----- DSK_STATE -----;
C DSK_STATE ORG 90H LABEL BYTE DB 1 DUP(?) ; DRIVE 0 MEDIA STATE
C
C ;----- DRIVE 1 MEDIA STATE -----;
C DB 1 DUP(?) ; DRIVE 1 MEDIA STATE
C
C ;----- DRIVE 0 OPERATION START STATE -----;
C DB 1 DUP(?) ; DRIVE 0 OPERATION START STATE

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?? ]
0093 01 [ ?? ]           C
                           DB    1 DUP(?) ; DRIVE 1 OPERATION START STATE
                           C
0094 01 [ ?? ]           C DSK_TRK   DB    1 DUP(?) ; DRIVE 0 PRESENT CYLINDER
                           C
0095 01 [ ?? ]           C           DB    1 DUP(?) ; DRIVE 1 PRESENT CYLINDER
                           C
0096 01 [ ?? ]           C           DB    1 DUP(?) ; RESERVED
                           C
                           C----- ADDITIONAL KEYBOARD LED FLAG -----
                           C----- ORG 97H
0097 01 [ ?? ]           C KB_FLAG_2  DB    1 DUP(?) C
                           C
                           C PAGE
                           C----- REAL TIME CLOCK DATA AREA -----
                           C----- ORG 98H
0098 01 [ ???? ]          C USER_FLAG  DW    1 DUP(?) ; OFFSET ADDR OF USERS WAIT FLAG
                           C
                           C USER_FLAG_SEG DW    1 DUP(?) ; SEG ADDR OF USER WAIT FLAG
                           C
009A 01 [ ???? ]          C RTC_LOW    DW    1 DUP(?) ; LOW WORD OF USER WAIT FLAG
                           C
009C 01 [ ???? ]          C RTC_HIGH   DW    1 DUP(?) ; HIGH WORD OF USER WAIT FLAG
                           C
009E 01 [ ???? ]          C RTC_WAIT_FLAG DB    1 DUP(?) ; WAIT ACTIVE FLAG
                           C
00A0 01 [ ?? ]            C
                           C DATA ENDS
                           C----- EXTRA DATA AREA -----
                           C----- XXDATA SEGMENT AT 50H
0000 0000 01 [ ?? ]        C STATUS_BYTE DB    1 DUP(?) C
                           C
                           C XXDATA ENDS
                           C----- VIDEO DISPLAY BUFFER -----
                           C----- VIDEO_RAM SEGMENT AT 0B800H
0000 0000 0000 4000 [ ?? ] C REGEN_LABEL BYTE
                           C REGNEW_LABEL WORD
                           C           DB 16384 DUP(?) C
                           C
                           C VIDEO_RAM ENDS
                           C
                           .LIST
                           C INCLUDE SEGMENT.SRC
                           C CODE SEGMENT BYTE PUBLIC
                           C
                           EXTRN VIDEO_PARMS:BYTE
                           EXTRN POST2:NEAR
                           EXTRN DDS:NEAR
                           EXTRN DIB:NEAR
                           EXTRN VECTOR_TABLE:NEAR
                           EXTRN KBD_RESET:NEAR
                           EXTRN DUMMY_RETURN:NEAR
                           EXTRN STGTST_CNT:NEAR
                           EXTRN ERR_CODE:NEAR
                           EXTRN ROM_CHECK:NEAR
                           EXTRN ROS_CHECKSUM:NEAR
                           EXTRN SYSINIT1:NEAR
                           EXTRN SHUT2:NEAR
                           EXTRN SHUT3:NEAR
                           EXTRN SHUT4:NEAR
                           EXTRN SHUT6:NEAR
                           EXTRN SHUT7:NEAR
                           EXTRN SHUT9:NEAR
                           EXTRN PROC_SHUTDOWN:NEAR
                           EXTRN C1:NEAR
                           EXTRN C2:NEAR
                           EXTRN C8042A:NEAR
                           EXTRN OBF_42A:NEAR
                           EXTRN C8042B:NEAR
                           EXTRN C8042C:NEAR
                           EXTRN OBF_42F:NEAR
                           EXTRN F3B:NEAR
                           EXTRN SLAVE_VECTOR_TABLE:NEAR
                           EXTRN NM1_INT:NEAR
                           EXTRN PRINT_SCREEN:NEAR
                           EXTRN GATE_A20:NEAR
                           C
                           ASSUME CS:CODE,SS:CODE,ES:ABSO,DS:DATA
                           C
                           PUBLIC POST1
                           PUBLIC BEM_N
                           PUBLIC CHK_VIDEO
                           PUBLIC START_1
                           PUBLIC C8042_
                           PUBLIC OBF_42
                           PUBLIC C1_
                           PUBLIC C2_
                           PUBLIC TST4_B
                           PUBLIC TST4_C
                           PUBLIC TST4_D
                           PUBLIC E30B
                           PUBLIC E30C

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```

= 0000          BEGIN EQU   $                                ; 6 1 8 1 0 2 8, C O P R ., I B M, 1 9 8 4 ; EVEN
               ; 6 1 8 1 0 2 9, C O P R ., I B M, 1 9 8 4 ; ODD
               DB '66118811002289 CCOOPPR.. IIBMM 11998844' ; COPYRIGHT NOTICE

0000 36 36 31 31 36 38
               31 31 30 30 32 32
               38 39 20 20 43 43
               4F 4F 50 50 52 52
               2E 2E 20 20 49 49
               42 42 4D 4D 20 20
               31 31 39 39 38 38
               34 34

;----- INITIAL RELIABILITY TESTS -- PHASE 1 -----
002C          POST1 PROC NEAR
               ;----- LOAD A BLOCK OF TEST CODE THROUGH THE KEYBOARD PORT
               ;----- FOR MANUFACTURING TEST.
               ;----- THIS ROUTINE WILL LOAD A TEST (MAX LENGTH=FAFFH) THROUGH
               ;----- THE KEYBOARD PORT. CODE WILL BE LOADED AT LOCATION
               ;----- 00000000H. AFTER LOADING, THE CODE WILL BE TRANSFERRED
               ;----- TO LOCATION 0000:0500H. STACK WILL BE LOCATED AT 30:100
               ;----- THIS ROUTINE ASSUMES THAT THE FIRST 2
               ;----- BYTES TRANSFERRED CONTAIN THE COUNT OF BYTES TO BE LOADED
               ;----- (BYTE 1=COUNT LOW, BYTE 2=COUNT HI.)
```

---

002C MFG\_BOOT:  
002C FA

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               CLI ; NO INTERRUPTS

;----- DEGATE ADDRESS LINE 20
002D B4 DD
002F E8 0000 E
               MOV AH,DISABLE_BIT20 ; DEGATE COMMAND
               CALL GATE_A20 ; ISSUE THE COMMAND

;----- SETUP HARDWARE INT VECTOR TABLE LVL 0-7
0032 2B C0
0034 8E C0
0036 B9 0008
0039 0E
003A 1F
003B 00 0000 E
003C BF 0020 R
               SUB AX,AX ; GET VECTOR CNT
               MOV ES,AX
               MOV CX,08 ; SETUP DS SEG REG
               PUSH CS
               POP DS
               MOV SI,OFFSET VECTOR_TABLE
               MOV DI,OFFSET INT_PTR
               MFG_B: MOVSW
               INC DI ; SKIP OVER SEGMENT
               INC DI
               LOOP MFG_B

;----- SETUP HARDWARE INT VECTOR TABLE LVL 8-15 (VECTORS START AT INT 70H)
0046 2B C0
0048 8E C0
004A B9 0008
004D 00 0000 E
004E 1F
004F BF 0000 E
0052 BF 01C0 R
               SUB AX,AX ; GET VECTOR CNT
               MOV ES,AX
               MOV CX,08 ; SETUP DS SEG REG
               PUSH CS
               POP DS
               MOV SI,OFFSET SLAVE_VECTOR_TABLE
               MOV DI,OFFSET SLAVE_INT_PTR
               MFG_C: MOVSW
               INC DI ; SKIP OVER SEGMENT
               INC DI
               LOOP MFG_C

;----- SET UP OTHER INTERRUPTS AS NECESSARY
005A 2B C0
005C 8E D8
005E 8E C0
0060 C7 06 R 0000 E
0066 C7 06 0014 R 0000 E
006C C7 06 0062 R F600
               ASSUME DS:ABSO
               ASSUME ES:ABSO
               SUB AX,AX ; DS=0
               MOV DS,AX
               MOV ES,AX ; ES=0
               MOV NM1_PTR,OFFSET NM1_INT ; NM1_INTERRUPT
               MOV INT5_PTR,OFFSET PRINT_SCREEN ; PRINT SCREEN
               MOV BASIC_PTR+2,OF600H ; SEGMENT FOR CASSETTE BASIC

;----- ENABLE KEYBOARD PORT
0072 B0 60
0077 E8 0005 R
0079 E0 09
0079 E6 60
               MOV AL,60H ; WRITE 80H RAM 0
               CALL C8042 ; ISSUE THE COMMAND
               MOV AL,0000001001B ; SET INHIBIT OVERRIDE/ENABLE OBF INT
               OUT PORT_A,AL ; AND NOT PC COMP

007B E8 009D R
0080 80 F8
0080 80 009D R
0083 BA E8
0085 8A CF
0087 FC
0088 BF 0500
               CALL MFG_2 ; GET COUNT LOW
               BTR AL,1 ; SAVE IT
               CALL MFG_2 ; GET COUNT HI
               MOV CH,AL
               MOV CL,BH ; CX NOW HAS COUNT
               CLD ; SET DIR. FLAG TO INCRIMENT
               MOV DI,0500H ; SET TARGET OFFSET (DS=0000)

0088 E4 64
008D A8 01
008F 7F FA
0091 E4 60
0093 AA
               MFG_1: IN AL,STATUS_PORT ; GET 8042 STATUS PORT
               TEST AL,OUT_BUFL_FULL ; KB REQUEST PENDING?
               JZ MFG_1 ; LOOP TILL DATA PRESENT
               IN AL,PORT_A ; GET DATA
               STOSB ; STORE IT

0094 E6 80
               OUT MFG_PORT,AL ; DISPLAY CHAR AT MFG PORT
0096 E2 F3
               LOOP MFG_1 ; LOOP TILL ALL BYTES READ
0098 EA 0500 ---- R
               JMP MFG_TEST_RTN ; FAR JUMP TO CODE THAT WAS JUST
               ; LOADED
               ; CHECK FOR OUTPUT BUFF FULL
               ; HANG HERE IF NO DATA AVAILABLE

009D E4 64
009F A8 01
00A1 E1 FA
               MFG_2: IN AL,STATUS_PORT ; GET THE COUNT
               TEST AL,OUT_BUFL_FULL ; IF NOT SET
               MFG_2: ; GO TO ERROUTINE IF NOT SET
               ; LOAD FLAG IMAGE TO AH

00A3 E4 60
00A5 C3
               IN RET AL,PORT_A ; GET THE COUNT

;----- TEST.01 -----
;----- X86 PROCESSOR TEST (REAL MODE) -----
;----- DESCRIPTION -----
;----- VERIFY FLAGS, REGISTERS
;----- AND CONDITIONAL JUMPS -----
;----- ASSUME CS:CODE,DS:DATA,ES:NOSTHING,SS:NOSTHING
START_1: CLD ; DISABLE INTERRUPTS
               MOV AH,0D5H ; SET SF, CF, ZF, AND AF FLAGS ON
               SAHF
               JNC ERR02 ; GO TO ERROUTINE IF CF NOT SET
               JNZ ERR02 ; GO TO ERROUTINE IF ZF NOT SET
               JNP ERR02 ; GO TO ERROUTINE IF AF NOT SET
               JNS ERR02 ; GO TO ERROUTINE IF SF NOT SET
               LAHF ; LOAD FLAG IMAGE TO AH

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0083 B1 05      MOV CL, 5          ; LOAD CNT REG WITH SHIFT CNT
0085 D2 EC      SHR AH, CL       ; SHIFT AF INTO CARRY BIT POS
0087 73 1D      JNC ERR02        ; GO TO ERR ROUTINE IF AF NOT SET
0088 40 00      NOV             ; SET OF FLAG ON
0088 DD E0      SHL AL, 1         ; SETUP FOR TESTING
008D 71 17      JNO ERR02        ; GO TO ERR ROUTINE IF OF NOT SET
008F 32 E4      XOR AH, AH       ; SET AH = 0
00C1 9E         SAHF            ; CLEAR SF, CF, ZF AND PF
00C2 76 12      JBE ERR02        ; GO TO ERR ROUTINE IF CF ON
00C4 78 10      JS  ERR02        ; GO TO ERR ROUTINE IF ZF ON
00C6 7A 0E      JP  ERR02        ; GO TO ERR ROUTINE IF SF ON
00C8 9F         LAHF            ; LOAD FLAG IMAGE TO AH
00C9 B1 05      MOV CL, 5          ; LOAD CNT REG WITH SHIFT CNT
00CB D0 EC      SHR AH, CL       ; SHIFT AF INTO CARRY BIT POS
00CC 72 77      JC  ERR02        ; GO TO ERR ROUTINE IF ON
00CF D0 E4      SHL AH, 1         ; CHECK THAT 'OF' IS CLEAR
00D1 70 03      JO  ERR02        ; GO TO ERR ROUTINE IF ON
00D3 EB 04 90    JMP CTA          ; CONTINUE
00D6 E9 0181 R   ERR02: JMP ERRO1 ; ERROR EXIT

00D9 B8 ---- R   C7A:           ;----- CHECK FOR PROCESSOR SHUTDOWN
00DC 8E D8      MOV AX, DATA     ; SET DATA SEGMENT
                                ;----- CHECK FOR PROCESSOR SHUTDOWN
00DE E4 64      IN  AL, STATUS_PORT ; CHECK FOR SHUTDOWN
00E0 A8 04      TEST AL, SYS_FLAG
00E2 75 03      JNZ C7B          ; GO IF YES
00E4 E9 0181 R   JMP C7          ;----- CHECK FOR SHUTDOWN 9
00E7 B0 8F      C7B:           ;----- CHECK FOR SHUTDOWN 9
00E9 E6 70      MOV AL, SHUT_DOWN ; CMOS ADDR FOR SHUTDOWN BYTE
00E9 00          OUT INT87+1, AL
00E9 E6 00      JMP AL, INT87+1, AL
00E9 E6 00      IN  AL, CMOS_PORT+1 ; GET WHO
00E9 E6 71      XCHG AL, AH       ; SAVE THE SHUTDOWN REQUEST
00E9 E6 00      CMP AH, 09H       ; WAS IT SHUTDOWN REQUEST ?
00F1 80 FC 09    JZ  CTC          ; BYPASS INIT OF INT CHIPS
00F4 74 3C      CTC              ;----- RE-INITIALIZE THE 8259 INTERRUPT #1 CONTROLLER CHIP :
00F6 2A C0      SUB AL, AL       ; INSURE MATH PROCESSOR RESET
00F8 E6 F1      OUT INT87+1, AL
00F9 00          MOV AL, 11H       ; ICW1 - EDGE, MASTER, ICW4
00F9 E6 11      OUT INT87+1, AL
00F9 E6 00      JMP AL, INT87+1, AL
00F9 E6 00      IN  AL, INTTYPE  ; WAIT STATE FOR IO
0100 B0 08      MOV AL, 8          ; SETUP ICW2 - INT TYPE 8 (8-F)
0102 E6 21      OUT INTA01, AL   ; WAIT STATE FOR IO
0104 E6 00      JMP AL, INT87+1, AL
0104 E6 21      OUT INTA01, AL   ; WAIT STATE FOR IO
0106 B0 04      MOV AL, 04H       ; SETUP ICW3 - MASTER LV 2
0108 E6 21      OUT INTA01, AL
010A EB 00      JMP SHORT $+2   ; IO WAIT STATE
010C B0 01      MOV AL, 01H       ; SETUP ICW4 - MASTER, 8086 MODE
010E E6 21      OUT INTA01, AL
0110 EB 00      JMP SHORT $+2   ; WAIT STATE FOR IO
0112 B0 FF      MOV AL, OFFH      ; MASK ALL INTS. OFF
0114 E6 21      OUT INTA01, AL   ; (VIDEO ROUTINE ENABLES INTS.)
                                ;----- RE-INITIALIZE THE 8259 INTERRUPT #2 CONTROLLER CHIP :
0116 B0 11      MOV AL, 11H       ; ICW1 - EDGE, SLAVE ICW4
0118 E6 A0      OUT INTB00, AL   ; WAIT STATE FOR IO
011A EB 00      JMP SHORT $+2   ; SETUP ICW2 - INT TYPE 50 (50-F)
011A 00          MOV AL, INTTYPE  ; SETUP ICW3 - SLAVE LV 2
011E E6 A1      OUT INTB01, AL
0120 B0 02      MOV AL, 02H       ; SETUP ICW4 - SLAVE
0122 E8 00      JMP SHORT $+2   ; IO WAIT STATE
0124 E6 A1      OUT INTB01, AL
0126 EB 00      JMP SHORT $+2   ; SETUP ICW5 - 8086 MODE, SLAVE
0128 B0 11      MOV AL, 01H       ; WAIT STATE FOR IO
012A E6 A1      OUT INTB01, AL
012C EB 00      JMP SHORT $+2   ; MASK ALL INTS. OFF
0130 E6 A1      OUT INTB01, AL
                                ;----- SHUTDOWN
                                ;----- RETURN CONTROL AFTER A SHUTDOWN COMMAND IS ISSUED
                                ;----- DESCRIPTION
                                ;----- A TEST IS MADE FOR THE SYSTEM FLAG BEING SET. IF
                                ;----- THE SYSTEM FLAG IS SET, THE SHUTDOWN BYTE IN CMOS
                                ;----- IS USED TO DETERMINE WHERE CONTROL IS RETURNED.
                                ;----- CMOS = 0 SOFT RESET OR UNEXPECTED SHUTDOWN
                                ;----- CMOS = 1 SHUT DOWN AFTER MEMORY SIZE
                                ;----- CMOS = 2 SHUT DOWN AFTER MEMORY TEST
                                ;----- CMOS = 3 SHUT DOWN AFTER POWER UP
                                ;----- CMOS = 4 SHUT DOWN WITH BOOT LOADER REQUEST
                                ;----- CMOS = 5 JMP DWORD REQUEST (WITH INT INIT)
                                ;----- CMOS = 6 PROTECTED MODE TEST PASSED
                                ;----- CMOS = 7 PROTECTED MODE TEST FAILED
                                ;----- CMOS = 8 PROTECTED MODE TEST UNPASSED
                                ;----- CMOS = 9 BLOCK DEVICE SHUTDOWN REQUEST
                                ;----- CMOS = A JMP DWORD REQUEST (W/O INT INIT)
                                ;----- CHECK FROM WHERE
0132 B0 8F      C7C:           ;----- CHECK FROM WHERE
0134 E6 70      MOV AL, SHUT_DOWN ; CLEAR CMOS BYTE
0136 EB 00      OUT CMOS_PORT, AL
0138 2A C0      JMP SHORT $+2   ; IO DELAY
0138 E6 71      SUB AL, AL       ; SET BYTE TO 0
013A 86 E0      OUT CMOS_PORT+1, AL
013A E6 AA      XCHG AH, AL       ; MAX TABLE ENTRYS
0140 77 2C      CMP AH, 0AH      ; GO IF GREATER THAN MAX
0142 BE 0158 R   JA  SHUTO        ; GET THE START OF BRANCH TABLE
0145 03 F0      MOV SI, OFFSET BRANCH
0145 03 F0      ADD SI, AX       ; POINT TO BRANCH ADDRESS
0149 20: 8B 1C    ADD SI, AX       ; GET BRANCH TO BX
014C FA          MOV BX, CS:[SI]
014D B8 ---- R   CLI              ;----- BRANCHES
0150 B8 DO        MOV AX, STACK    ; SET STACK
0152 BC 0100 R   MOV SS, AX       ;----- BRANCHES
0155 FB          MOV SP, OFFSET TOS
0156 FF E3      STT BX            ;----- BRANCHES
                                ;----- BRANCHES
0158 016E R      BRANCH: DW SHUTO ; NORMAL POWER UP/UNEXPECTED SHUTDOWN
015A 09B0 R      DW SHUT1        ; SHUT DOWN AFTER MEMORY SIZE
015C 0000 E      DW SHUT2        ; SHUT DOWN AFTER MEMORY TEST

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015E 0000 E          DW    SHUT3      ; SHUT DOWN WITH MEMORY ERROR
0160 0000 E          DW    SHUT4      ; SHUT DOWN WITH BOOT LOADER REQUEST
0162 0171 R          DW    SHUT5      ; JMP DWORD REQUEST (WITH INTERRUPT INIT)
0164 0000 E          DW    SHUT6      ; PROTECTED MODE TEST7 PASSED
0165 0000 E          DW    SHUT7      ; PROTECTED MODE TEST1 FAILED
0168 0F7F R          DW    SHUT8      ; BLOCK MOVE SHUTDOWN REQUEST
016A 0000 E          DW    SHUT9      ; JMP DWORD REQUEST (W/O INTERRUPT INIT)
016C 017D R          DW    SHUTA      ; SHUT DOWN
016E EB 11 90        SHUTO: JMP   C7

;----- IO_ROM_INIT MUST BE INITIALIZED BY THE USER
0171 E4 64           SHUT5: IN     AL, STATUS_PORT ; FLUSH THE KEYBOARD BUFFER
0173 A8 01           TEST   AL, OUT_BUF_FULL ; CHECK IF OUTPUT BUFFER FULL
0175 74 02           JZ    SHUT5B    ; GO IF NOT
0176 E4 60           IN     AL, PORT_A ; FLUSH
0179 B0 20           SHUT5B: MOV   AL, EOF    ; FLUSH LAST TIMER TICK
017B E6 20           OUT    INTAA0, AL ; TO ALLOW TIMER INTERRUPTS

017D FF 2E 0067 R   SHUTA: JMP   DWORD PTR DS:IO_ROM_INIT;
;----- CHECKPOINT 1
0181 B0 01           C7:   MOV   AL, 01H    ; <><><><><><><><><><><><>
0183 E6 80           OUT    MFG_PORT, AL ; <><><>CHECKPOINT 1<><>

;----- READ/WRITE THE X286 GENERAL AND SEGMENTATION REGISTERS
;----- WITH ALL ONE'S AND ZEROES'S.
0185 B8 FFFF          MOV   AX, OFFFFF ; SETUP ONE'S PATTERN IN AX
0186 F9               STC
0187 07 21           JNC   ERR01    ; SET CARRY FLAG
0188 80 D8           DS    DS, AX    ; GO IF NO CARRY
0189 80 D8           C8:   MOV   BX, DS    ; WRITE PATTERN TO ALL REGS
018D 80 DB           MOV   ES, BX
018F 8E C3           MOV   CX, ES
0191 8C C1           MOV   SS, CX
0193 8E D1           MOV   DX, SS
0195 80 02           MOV   SI, DX
0197 88 E2           MOV   BP, SP
0199 88 EC           MOV   SI, BP
019B 88 F5           MOV   DI, SI
019D 88 FE           MOV   AX, 01H    ; PATTERN MAKE IT THRU ALL REGS
019F 73 07           XCHG AX, DI ; NO - GO TO ERR ROUTINE
01A3 75 07           JNZ   ERR01    ; CLEAR CARRY FLAG
01A5 F8               CLC
01A6 EB E3           JMP   C8
01A8 00 C7           C9:   OR    AX, DI    ; TST1A
01A9 00 01           JZ    C10A    ; PATTERN MAKE IT THRU?
01AC F4               ERRO1: HALT SYSTEM ; YES - GO TO NEXT TEST
;----- INSURE THAT CMOS CLOCK INTERRUPTS ARE DISABLED
01AD B0 8B           C10A: MOV   AL, CMOS_ALARM ; GET THE CURRENT CONTROL REG
01AF E6 70           OUT   CMOS_PORT, AL ; SAVE IT
01B1 EB 00           JMP   SHORT $+2 ; CLEAR SET, PIE, AIE, AND SQWE BITS
01B3 E4 71           IN    AL, CMOS_PORT+1
01B5 86 C4           XCHG AL, AH
01B7 00 07           ANI   AL, AH7H
01B8 B0 8B           MOV   AL, CMOS_ALARM
01B9 E6 70           OUT   CMOS_PORT, AL
01BCE 86 C4           XCHG AL, AH
01C0 EB 00           JMP   SHORT $+2 ; IO DELAY
01C2 E6 71           OUT   CMOS_PORT+1, AL ; IO DELAY

01C4 EB 00           JMP   SHORT $+2 ; IO DELAY
01C6 B0 8C           MOV   AL, CMOS_ALARM+1 ; CLEAR PENDING INTERRUPT
01C8 E6 70           OUT   CMOS_PORT, AL ; IO DELAY
01CA EB 00           JMP   SHORT $+2 ; IO DELAY
01CC E4 71           IN    AL, CMOS_PORT+1 ; IO DELAY

;----- RESET VIDEO
01CE B8 ---- R       ASSUME DS:DATA
01D0 B1 00             MOV   AX, DATA
01D3 B1 3E 0072 R 1234  MOV   DS, AX    ; SET DATA SEGMENT
01D9 74 0B           CMP   RESET_FLAG, 1234H ; SOFT RESET?
01DB 2A C0           JZ    SFT_RST ; GO IF YES

01DD BA 03D8          SUB   AL, AL
01DE E4 00             MOV   DX, 3D8H
01E1 FE C0             OUT   DX, AL    ; DISABLE COLOR VIDEO
01E3 B2 B8             INC   AL
01E5 EE               MOV   DL, DB8H
01E6 B0 FC             OUT   DX, AL    ; DISABLE B/W VIDEO, EN HIGH RES
01E8 E6 61             SFT_RST: MOV  AL, 11111100B ; DISABLE PARITY CHECKERS
01E9 00 00             OUT   PORT_B, AL ; IO DELAY

;----- TEST.02
;----- VERIFY CMOS SHUTDOWN BYTE
;----- DESCRIPTION
;----- ROLLING BIT WRITTEN AND VERIFIED
;----- AT SHUTDOWN ADDRESS
;----- VERIFY AND CLEAR SHUTDOWN FLAG
01EA B0 02             MOV   AL, 2    ; <><><><><><><><>
01EC E6 80             OUT   MFG_PORT, AL ; <><><>CHECKPOINT 2<><>
01EE B9 0009          MOV   CX, 09H ; LOOP COUNT
01F1 B4 01             MOV   AH, 1    ; START WITH BIT 0
01F2 E4 00             OUT   AL, SHUT_DOWN ; OUTPUT ROLLING BIT
01F5 E6 90             OUT   CMOS_PORT, AL
01F7 8A C4             MOV   AL, AH
01F9 EB 00             JMP   SHORT $+2 ; IO DELAY
01FB E6 71             OUT   CMOS_PORT+1, AL ; READ CMOS
01FD 80 8F             MOV   AL, SHUT_DOWN ; IO DELAY
01FF EB 00             JMP   SHORT $+2 ; IO DELAY
0201 E6 70             OUT   CMOS_PORT, AL ; IO DELAY
0203 EB 00             JMP   SHORT $+2 ; IO DELAY
0205 E4 71             IN    AL, CMOS_PORT+1 ; MUST BE THE SAME
0209 3A C4             CMP   AL, AH ; ERROR IF NOT
020A 74 A1             JNZ   ERRO1    ; ROLL A BIT THRU SHUT DOWN
020B D0 04             RCL   AH, 1    ; LOOP TILL DONE
020D E2 E4             LOOP  C10B

;----- TEST.03
;----- ROS CHECKSUM TEST 1
;----- DESCRIPTION
;----- A CHECKSUM IS DONE FOR THE 32K
;----- ROS MODULES CONTAINING POD AND

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; BIOS.

020F          ;----- C10: -----
0211 80 03    MOV    AL,03H           ;><><><><><><><><>
0211 E6 80    OUT    MFG_PORT,AL   ;><><>CHECKPOINT 3<><>

0213 8C C8    MOV    AX,CS           ; SETUP SS SEG REG
0215 8E D0    MOV    SS,AX           ;
0217 8E D8    MOV    DS,AX           ; SET UP DATA SEG TO POINT TO ======
0219 BB 0000 R ASSUME SS,CODE      ; ROM ADDRESS
021C BC 0000 E MOV    SP,OFFSET BEGIN ; SETUP STARTING ROS ADDR
021F E9 0000 E JMP    ROS_CHECKSUM ; SETUP RETURN ADDRESS
0222          C11: JZ    C11A           ; HALT SYSTEM IF ERROR
0224 F4          HLT

;----- TEST.04 -----
0225 B8 ---- R ASSUME DS:DATA      ; TEST.04
0228 8E D8    C11A: MOV   AX,DATA      ; SET DATA SEGMENT
022A B0 04    MOV   DS,AX           ;
022C E6 80    MOV   AL,0AH          ;><><><><><><><><><><>
022E E6 08    OUT   MFG_PORT,AL   ;><><>CHECKPOINT 4<><>
0230 E6 D0

;----- DISABLE DMA CONTROLLER -----
0232 BB 16 0072 R MOV   DX_RESET_FLAG ; SAVE RESET FLAG WHILE REFRESH IS OFF
0236 80 54    MOV   AL,5AH          ; SEL TIMER 1,L8B,MODE 2
0238 E6 43    OUT   TIMER+3,AL   ;
023A EB 00    JMP   SHORT $+2      ; WAIT STATE FOR IO
023C 8A C1    MOV   AL,CL          ; SET INITIAL TIMER CNT TO 0
023D E6 41    OUT   TIMER+1,AL   ;
0240 B7 05    MOV   BH,09H          ; LOOP COUNT
0242          C12: MOV   AL,40H          ; TIMER1_BITS_ON
0244 EB 00    JMP   SHORT $+2      ; LATCH TIMER 1 COUNT
0246 E6 43    OUT   TIMER+3,AL   ; IO DELAY
0248 80 FF    CMP   DX,OFFH        ; YES - SEE IF ALL BITS GO OFF
024B 74 0B    JE    C13           ; TIMER1_BITS_OFF
024D E4 41    IN    AL,TIMER+1   ; READ TIMER 1 COUNT
024F 0A D8    OR    BL,AL          ; ALL BITS ON IN TIMER
0251 E2 EF    LOOP  C12           ; TIMER1_BITS_ON
0255 FE CF    DEC   BH             ;
0257 55 EB    JNZ   C12           ; TRY AGAIN
0257 F4          HLT              ; TIMER 1 FAILURE, HALT SYS
0257          ;----- TIMER1_BITS_OFF -----
0258 B0 05    ;----- C13: -----
025A E6 80    MOV   AL,05H          ;><><><><><><><><>
025C 8A C3    OUT   MFG_PORT,AL   ;><><>CHECKPOINT 5<><>
025D 2B C9    MOV   AL,C9H          ; SET TIMER 1 CNT
0260 E6 41    SUB   CX,CX           ;
0262 B7 05    OUT   TIMER+1,AL   ;
0264          C14: MOV   BH,05H          ; SET TRY AGAIN COUNT
0264 EB 00    JMP   SHORT $+2      ; TIMER_LOOP
0266 B0 40    MOV   AL,40H          ; IO DELAY
0268 80 54    OUT   TIMER+3,AL   ; LATCH TIMER 1 COUNT
026A EB 00    JMP   SHORT $+2      ; DELAY FOR TIMER
026C EB 00    JMP   SHORT $+2      ; ADDED DELAY FOR TIMER
026E E4 41    IN    AL,TIMER+1   ; READ TIMER 1 COUNT
0270 22 D8    AND   BL,AL          ;
0271 70 07    JZ    C15           ; WRAP_DMA_REG
0274 52 EE    LOOP  C14           ; TIMER_LOOP
0276 FE CF    DEC   BH             ;
0278 75 EA    JNZ   C14           ; HALT SYSTEM
0278 F4          HLT

;----- TEST.05 -----
0278          ;----- C15: -----
0278 B8 ---- R MOV   AX,DATA      ; SET DATA SEGMENT
027E 8E D8    MOV   DS,AX           ;
0280 B0 06    MOV   AL,06H          ;><><><><><><><><><>
0282 E6 80    OUT   MFG_PORT,AL   ;><><>CHECKPOINT 6<><>
0284 89 16 0072 R MOV   RES1_FLAG,DX ; RESTORE SOFT RESET FLAG
0286 E6 D0    OUT   DX,DX           ;><><>ODH,AL ;><><>MASTER CLEAR TO DMA
0286          ;----- WRAP DMA 0 CHANNEL ADDRESS AND COUNT REGISTERS -----
028A B0 FF    C16: MOV   AL,OFFH        ; WRITE PATTERN FF TO ALL REGS
028C 8A D8    MOV   BL,BL           ; SAVE PATTERN FOR COMPARE
028E 8A F8    MOV   BH,BH           ;
0290 B9 0008    MOV   DX,8             ; SETUP LOOP CNT
0293 BA 0000    C17: OUT  DX,AL          ; SETUP I/O PORT ADDR OF REG
0296 EE          MOV   DX,DMA          ; WRITE PATTERN TO REG, LSB
0297 EB 00    JMP   SHORT $+2      ; WAIT STATE FOR IO
0298 E6 01    OUT  DX,AL          ; MSB = 16-BIT REG
029A B0 01    MOV   DX,1FH          ; A TO ANOTHER 16-BIT BEFORE RD
029C EB 00    JMP   SHORT $+2      ; WAIT STATE FOR IO
029E EC          IN    AL,DX          ; READ 16-BIT DMA CH REG, LSB 2ST DMA
029F EB 00    JMP   SHORT $+2      ; WAIT STATE FOR IO
02A1 8A E0    MOV   AH,AL          ; SAVE LSB OF 16-BIT REG
02A3 EC          IN    AL,DX          ; READ MSB OF DMA CH REG

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02A4 3B D8      CMP    BX, AX          ; PATTERN READ AS WRITTEN?
02A6 74 01      JE     C18           ; YES - CHECK NEXT REG
02A8 F4          HLT              ; NO - HALT THE SYSTEM
02A9
02A9 42          C18:             ; NXT_DMA CH
02AA E2 EA      INC    DX           ; PATTERN POINT TO NEXT CH REG
02AC FE CO      LLOOP  C17           ; WRITE PATTERN TO NEXT REG
02AE 74 DC      INC    AL           ; SET PATTERN TO 0
02B0 80 FB 55    JZ    C16           ; YES CONTINUE
;----- WRITE DMA WITH 55 PATTERN
02B0 80 FB 55    CMP    BL, 55H          ; CHECK IF 55 PATTERN DONE
02B3 74 09      JZ    C19           ; GO IF YES
02B5 80 FB AA    CMP    BL, 0AAH          ; CHECK IF AA PATTERN DONE
02B8 74 08      JZ    C20           ; GO IF YES
02B8 80 55      MOV    AL, 55H           ;
02BC EB CE      JMP    C16           ;

;----- WRITE DMA WITH AA PATTERN
02BE 80 AA      C19:             ; TEST.07
02C0 EB CA      MOV    AL, 0AAH          ;><><><><><><><><>
02C0 EB CA      JMP    C16           ;><><><><><><><><>
;----- 8237 DMA 1 INITIALIZATION CHANNEL REGISTER TEST
;----- DESCRIPTION
;----- INITIALIZE THE 8237 DMA CONTROLLER 1.
;----- WRITE/READ THE CURRENT DMA 1
;----- ADDRESS AND WORD COUNT REGISTERS FOR ALL
;----- CHANNELS.
;----- CHECKPOINT 7 DMA 1
02C2 80 07      C20:             ;><><><><><><><><>
02C4 E6 80      MOV    AL, 07H           ;><><><><><><><><>
02C6 E6 DA      OUT   MFG_PORT, AL      ;><><><><><><><><>
02C6 E6 DA      OUT   DMAT+0DH2, AL     ;><><><><><><><><>
;----- WRAP DMA 1 CHANNEL ADDRESS AND COUNT REGISTERS
02C8 80 FF      C16A:            ;><><><><><><><><>
02CA 8A D8      MOV    BL, OFFH          ; WRITE PATTERN FF TO ALL REGS
02CC 8A F6      MOV    BL, AL           ; SAVE PATTERN FOR COMPARE
02CD 80 0008    MOV    BL, AH           ;
02D1 BA 0000    MOV    DX, 0000          ;
02D4 EE          MOV    DX, DMA1           ;
02D5 EB 00      C17A:             ;><><><><><><><><>
02D7 EE          OUT   DX, AL           ; SETUP I/O PORT ADDR OF REG
02D8 80 01      MOV    AL, 01H           ; WRITE PATTERN TO REG, LSB
02DA EB 00      JMP    SHORT $+2        ; WAIT STATE FOR IO
02DC EC          MOV    AL, 10H           ; MSB OF 16-BIT REG
02D8 EB 00      JMP    SHORT $+2        ; WAIT TO OTHER PAR BEFORE RD
02D9 EE 00      IN    AL, DX           ; READ 16-BIT DMA CH REG, LSB
02D9 EC          JMP    SHORT $+2        ; 2ST DMA
02D9 EC          MOV    AH, AL           ; WAIT STATE FOR IO
02E0 EC          IN    AL, DX           ; SAVE LSB OF 16-BIT REG
02E2 80 D8      CMP    BX, AX           ; READ MSB OF DMA CH REG
02E3 80 01      JZ    C18A           ; PATTERN READS AS IT IS?
02E4 74 01      JE    C18A           ; YES - CHECK NEXT REG
02E5 F4          HLT              ; NO - HALT THE SYSTEM
02E7
02E7 83 C2 02    C18A:             ;><><><><><><><><>
02E8 E2 E8      ADD    DX, 2           ; SET IO PORT TO NEXT CH REG
02E9 FE 00      LLOOP  C17A           ; WRITE PATTERN TO NEXT REG
02EE 74 DA      INC    AL           ; SET PATTERN TO 0
02EE 74 DA      JMP    C16A           ; YES CONTINUE
;----- WRITE DMA WITH 55 PATTERN
02F0 80 FB 55    CMP    BL, 55H          ;><><><><><><><><>
02F3 74 09      JZ    C20A           ;><><><><><><><><>
02F5 80 FB AA    CMP    BL, 0AAH          ;><><><><><><><><>
02F8 74 08      JZ    C21A           ;><><><><><><><><>
02FA 80 55      MOV    AL, 55H           ;><><><><><><><><>
02FC EB CC      JMP    C16A           ;><><><><><><><><>
;----- WRITE DMA WITH AA PATTERN
02FE 80 AA      C20A:             ;><><><><><><><><>
0300 EB C8      MOV    AL, 0AAH          ;><><><><><><><><>
;----- INITIALIZE AND START MEMORY REFRESH.
0302 8B 1E 0072 R C21:             ;><><><><><><><><>
0306 A3 0010 R  MOV    BX, RESET_FLAG    ; GET THE RESET FLAG
0309 80 12      MOV    EQUIP_FLAG, AX    ; DO A DUMMY WRITE RAM BEFORE REFRESH
030B E6 41      MOV    AL, 18           ; START TIMER
030D 2A C0      C21Z:            ;><><><><><><><><>
030F E6 08      SUB    AL, AL           ; DACK SENSE LOW, DREQ SENSE HIGH
0310 2A C0      OUT    DMA+B, AL         ; LATE WRITE, FIXED PRIORITY, NORMAL TIMING
0310 E6 08      MOV    AL, 00H           ; CONTROLLER ENABLE, CHO ADDR HOLD DISABLE
0311 E6 00      OUT    TIMER+, AL        ; MEMORY TO MEM DISABLE
0311 E6 00      OUT    DMA18, AL         ; SAME TO SECOND CONTROLLER
;----- MODE SET ALL DMA CHANNELS
0313 80 40      C21Z:            ;><><><><><><><><>
0315 E6 08      MOV    AL, 40H           ; SET MODE FOR CHANNEL 0
0317 B0 C0      OUT    DMA+B0H, AL       ; SET CASCADE MODE ON CHANNEL 4
0319 E6 06      MOV    AL, 00H           ; SET MODE FOR CHANNEL 1
031B EB 00      OUT    DMA18+06H, AL      ; WAIT STATE FOR IO
031B EB 00      MOV    AL, 40H           ; SET MODE FOR CHANNEL 1
031F E6 08      OUT    DMA+B0H, AL       ; SET MODE FOR CHANNEL 5
0321 E6 06      OUT    DMA18+06H, AL      ; WAIT STATE FOR IO
0323 E6 00      MOV    AL, 42H           ; SET MODE FOR CHANNEL 2
0325 B0 42      OUT    DMA+B0H, AL       ; SET MODE FOR CHANNEL 2
0327 E6 06      OUT    DMA18+06H, AL      ; SET MODE FOR CHANNEL 6
0329 E6 06      OUT    DMA+B0H, AL       ; WAIT STATE FOR IO
032B EB 00      JMP    SHORT $+2        ; SET MODE FOR CHANNEL 3
032D B0 43      MOV    AL, 43H           ; SET MODE FOR CHANNEL 3
032F E6 08      OUT    DMA+B0H, AL       ; SET MODE FOR CHANNEL 7
0331 E6 06      OUT    DMA18+06H, AL      ; SET MODE FOR CHANNEL 7
;----- RESTORE RESET FLAG
0333 89 1E 0072 R MOV    RESET_FLAG, BX    ;><><><><><><><><>
;----- TEST.08
;----- DMA PAGE REGISTER TEST
;----- DESCRIPTION
;----- WRITE/READ ALL PAGE REGISTERS
;----- CHECK POINT 8
0337 B0 08      MOV    AL, 0BH           ;><><><><><><><><>

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0339 E6 80          OUT    MFC_PORT,AL      ;><><>CHECKPOINT 8<><><>
033B 2A C0          SUB    AL,AL
033D BA 0081        MOV    DX, DMA_PAGE
0340 B9 00FF        MOV    CX,OFFH      DO ALL DATA PATTERNS
0343 EE              C22A: OUT   DX,AL
0344 4C              INC    DX
0345 FE C0          CMP    DX,BFH      TEST DMA PAGES 81 THUR BEH
0347 81 FA 008F      JNZ    C22A
034B 75 F6          XCHG   AH,AL      SAVE CURRENT DATA PATTERN
034D 86 E0          DEC    AH
034F FE CC          DEC    DX
0351 A1              DEC    DX
0352 2A C0          C22B: SUB   AL,AL      CHANGE DATA BEFORE READ
0354 EC              IN    AL,DX
0355 3A C4          CMP    AL,AH      DATA AS WRITTEN?
0357 75 30          JNZ    C26      GO ERROR HALT IF NOT
0359 FE CC          DEC    AH
035A 4C              DEC    DX
035C 81 FA 0080      CMP    DX,MFG_PORT
0360 75 F0          JNZ    C22B      CONTINUE TILL PORT 80
0362 FE C4          INC    AH
0364 8A C4          MOV    AL,AH      NEXT PATTERN TO RIPPLE
0366 E2 D8          LOOP   C22A      ;
;----- TEST LAST DMA PAGE REGISTER (USED FOR ADDRESS LINES DURING REFRESH)
0368 B0 CC          MOV    AL,OCHH      ; WRITE AN CC TO PAGE REGISTERS
036A BA 008F        C22: MOV    DX,LAST_DMA_PAGE
036D 8A E0          MOV    AH,DX      ; SAVE THE DATA PATTERN
036F EE              OUT   DX,AL      ; OUTPUT PAGE REQ
;----- VERIFY PAGE REGISTER 8F
0370 2A C0          C24: SUH   AL,AL      ; CHANGE DATA PATTERN BEFORE READ
0371 4C              IN    AL,DX      GET THE DATA FROM PAGE REG
0373 3A C4          CMP    AL,AH      ; GO IF ERROR
0375 75 12          JNZ    C26
0377 80 FC CC      CMP    AH,OCHH
037A 75 04          JNZ    C25      ; GO IF ERROR
037C B0 33          MOV    AL,033H      SET THE DATA PATTERN OF 33
037E 80 EA          JMP    C22      DO DATA 33
0380 80 FC 00      CMP    AH,0
0383 74 05          JZ    C27      CHECK DONE
0385 2A C0          SUB   AL,AL      ; GO IF YES
0387 EB E1          JMP    C22      SET UP FOR DATA PATTERN 00
;----- ERROR HALT
0389 F4              C26: HLT      ; HALT SYSTEM
;----- TEST.09
;----- STORAGE REFRESH TEST
;----- DESCRIPTION
;----- VERIFY STORAGE REFRESH IS OCCURRING
;----- CHECKPOINT 9 TEST MEMORY REFRESH
038A B0 09          C27: MOV    AL,09H      ;><><><><><><><><>
038C E6 80          OUT   MFG_PORT,AL      ;><><>CHECKPOINT 9<><>
038E 2B C9          SUB   CX,CX      ;----- INSURE REFRESH BIT IS Toggling
0390 EB 61          IN    AL,PORT_B
0392 A8 10          TEST  AL,REFRESH_BIT
0394 E1 FA          LOOPZ C28      ;----- INSURE REFRESH IS OFF
0396 74 F1          JZ    C26      ;----- GO IF NOT
0398 2B C9          SUB   CX,CX
039A E4 61          C29: IN    AL,PORT_B      ;----- INSURE REFRESH IS ON
039E A8 10          TEST  AL,REFRESH_BIT
039F E0 FA          LOOPNZ C29      ;----- GO IF NO REFRESH
03A0 75 E7          JNZ    C26
;----- TEST.10
;----- 55H TEST AND CONFIGURATION JUMPERS
;----- DESCRIPTION
;----- ISSUE A SELF TEST TO THE 8042
;----- INSURE A 55H IS RECEIVED
;----- GET MANUFACTURING/DISPLAY TYPE JUMPER
;----- INPUT PORT INFO SAVED IN MFG_TEST
;----- CHECKPOINT 0A
03A2 B0 0A          MOV    AL,0AH      ;><><><><><><><>
03A4 E6 80          OUT   MFG_PORT,AL      ;><>CHECKPOINT 0A<><>
;----- SOFT RESET (HANDLE ALL POSSIBLE CONDITIONS)
03A6 2B C9          SUB   CX,CX      ;----- 100 MSEC FOR THIS LOOP
03A8 E4 64          TST1: IN    AL,STATUS_PORT      ;----- CHECK FOR INPUT BUFFER FULL
03AA 80 10          MOV    AH,DX
03AC F6 C0 01          TEST  AH,OUT_BUF_FULL
03AF 74 02          JZ    TST2      ;----- GO IF NOT
03B1 E4 60          IN    AL,PORT_A      ;----- FLUSH
03B3 F6 C4 02          TST2: TEST  AH,INPT_BUF_FULL      ;----- IS THE OUTPUT BUFFER ALSO FULL?
03B6 E0 F0          LOOPNZ TST1      ;----- TRY AGAIN
03B8 74 01          JZ    TST4      ;----- CONTINUE IF OK
03BA F4              ERRO: HLT      ;----- HALT SYSTEM IF BUFFER FULL
;----- ISSUE A RESET TO THE 8042
03BB B0 0B          TST4: MOV    AL,0BH      ;----- ISSUE A RESET TO THE 8042
03BD E6 80          OUT   MFG_PORT,AL      ;><><><><><><>
03BF B0 AA          MOV    AL,0AAH      ;----- SELF TEST COMMAND
03C1 B0 0000 E        MOV    SP,OFFSET C8042A      ;----- SET RETURN ADDR
03C4 EB 3F 90          JMP    C0042
03C7 A8 01          TST4_B: TEST  AL,OUT_BUF_FULL      ;----- IS THE OUTPUT BUFFER FULL?
03C9 74 02          JZ    TST4_A      ;----- GO IF NOT
03CB E4 60          IN    AL,PORT_A      ;----- FLUSH
03CD B0 0000 E        TST4_A: MOV    SP,OFFSET OBF_42A      ;----- SET RETURN ADDR
03D0 EB 3F 90          JMP    C0042      ;----- GO WAIT FOR BUFFER
03D3 E4 60          TST4_C: IN    AL,PORT_A      ;----- GET THE ENDING RESPONSE
03D5 3C 55          CMP    AL,55H      ;
03D7 B0 0C          MOV    AL,OCHH      ;><><><><><><><><>
03D9 E6 80          OUT   MFG_PORT,AL      ;><><>CHECKPOINT 0C <><>
03DB 75 DD          JNZ    ERRO      ;----- GO IF NOT OK
;----- GET THE SWITCH SETTINGS
03DD B0 C0          MOV    AL,OCHH      ;----- READ INPUT COMMAND
03DF BC 0000 E        MOV    SP,OFFSET C8042C      ;----- SET RETURN ADDRESS
03E2 EB 21 90          JMP    C0042      ;----- ISSUE COMMAND
03E5 BC 0000 E        E30B: MOV    SP,OFFSET OBF_42B      ;----- SET RETURN ADDRESS

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03E8 EB 27 90           JMP    OBF_42          ; GO WAIT FOR RESPONSE
03EB E4 60             IN     AL,PORT_A       ; GET THE SWITCH
03ED E6 82             OUT    DMA_PAGE+1,AL   ; SAVE TEMP

;----- WRITE BYTE 0 OF 8042 RAM

03EF B0 60             MOV    AL,0EH          ; WRITE BYTE COMMAND
03F1 BC 0000 E          MOV    SP,OFFSET C8042B ; SET RETURN ADDR
03F4 EB OF 90          JMP    C8042           ; ISSUE THE COMMAND
03F7 74 05             TST4_D: JZ    TST4_D1        ; CONTINUE IF COMMAND ACCEPTED

03F9 B0 0D             MOV    AL,0DH          ; <><><><><><><><><><><>
03F6 E6 80             OUT    MFG_PORT,AL      ; <><><><><><><><><><><>
03FD F4               HLT
03FE B0 5D             TST4_D1:MOV  AL,5DH          ; ENABLE OUTPUT BUFF FULL INT - DISABLE KEYBOARD
0400 E6 60             OUT    PORT_A,AL      ; SET SYS FLAG - PC 1 COMP - INH OVERRIDE
0402 EB 1E 90           JMP    E30A           ; CONTINUE

;----- ISSUE THE COMMAND TO THE 8042

0405 FA               CLI
0406 E6 64             OUT    STATUS_PORT,AL  ; NO INTERRUPTS ALLOWED
0408 B8 09             SUB    CX,CX          ; SEND COMMAND IN AL REG
040A E4 64             IN     AL,STATUS_PORT ; LOOP COUNT
040C A8 02             TEST   AL,INPT_BUF_FULL ; WAIT FOR THE COMMAND ACCEPTED
040E E0 FA             LOOPNZ C42_1         ; CONTINUE
0410 C3               RET

;----- WAIT FOR 8042 RESPONSE

0411 B2 C9             MOV    CX,CX          ; 200MS/PER LOOP * 6 =1200 MS +
0413 B3 06             MOV    BL,6           ; CHECK FOR RESPONSE
0415 E4 64             IN     AL,STATUS_PORT ; AL,STATUS_PORT
0417 A0 01             TEST   AL,AL           ; TEST AL,AL,BUF_FULL
0419 75 06             JNZ    C42_2         ; GO IF RESPONSE
041B E2 F8             LOOPC C42_2         ; TRY AGAIN
041D FE CB             DEC    BL              ; DECREMENT LOOP COUNT
041F 75 F4             JNZ    C42_2         ; JNZ C42_2
0421 C3               RET              ; RETURN TO CALLER

;----- TEST.11
;----- BASE 64K READ/WRITE STORAGE TEST
;----- DESCRIPTION
;----- WRITE/READ/VERIFY DATA PATTERNS
;----- AA,55,FF,01, AND 00 TO 151 64K OF
;----- STORAGE. VERIFY STORAGE ADDRESSABILITY.

;----- FILL MEMORY WITH DATA

0422 B0 0E             MOV    AL,0EH          ; SET CHECKPOINT (E)
0424 E6 80             OUT    MFG_PORT,AL      ; <><><><><><><><><><><>
0426 B8 ---- R          MOV    AX,DATA        ; GET THE SYSTEM SEGMENT
0429 BE D8             MOV    DS,AX          ; OF DATA
042B 80 01 1E 0072 R      MOV    BX,RESET_FLAG ; MOVE RESET_FLAG IN BX
042F FC               CLD
0430 B9 8000           MOV    CX,2000H#4 ; SET DIR FLAG TO INC.
0433 2B FF             SUB    D1,D1          ; SET FOR 32K WORDS
0435 2B F6             SUB    SI,SI          ; FIRST 16K
0437 2B C0             SUB    AX,AX          ;
0439 03 00             MOV    DS,DX          ;
043B BE C0             MOV    ES,AX          ; WARM START?
043D B1 FB 1234         CMP    BX,1234H ; JNZ E30A_0
0441 75 03             JNZ    E30A_0         ; GO IF NOT
0443 E9 05E6 R           JMP    CLR_STG        ; CLR_STG

;----- GET THE INPUT BUFFER (SWITCH SETTINGS)

0446 B0 0F             E30A_0: MOV    AL,0FH          ; <><><><><><><><><><><>
0448 E6 80             OUT    MFG_PORT,AL      ; <><><><><><><><><><><>
044A B0 80             MOV    AL,PRTY_CHK ; SET BASE RAM PARITY
044C E6 87             OUT    DMA_PAGE+6,AL ; USE AS TEMP SAVE
044E BC 0000 E          MOV    SP,OFFSET C2 ; SET RETURN ADDRESS
0451 E9 0000 E          JMP    STGTST_CNT ; SETGTST_CNT
0454 BB D8             C30:  MOV    BX,AX          ; SAVE FAILING BIT PATTERN
0456 75 03             JNZ    C31           ; C31
0458 E9 05F1 R           JNZ    C33           ; C33
045B B8 C000           ; STORAGE OK, CONTINUE

;----- BASE 64K STORAGE FAILURE
;----- DISPLAY THE CHECKPOINT (MFG_CHECKPOINT)
;----- AND XOR EXPECTED WITH READ IN MFG_PORT
;----- DISPLAY CHECKPOINT IN MFG_PORT+3
;----- DISPLAY XOR'D DATA HIGH BYTE MFG_PORT+1
;----- LOW BYTE IN MFG_PORT+2
;----- A READ/WRITE SCOPE LOOP OF THE FIRST
;----- WORD FOR POSSIBLE ADDRESS LINE FAILURES

;----- C31: MOVE AL,BH          ; SAVE HIGH BYTE
045B B8 C000           MOV    MFG_PORT+1,AL ; SAVE LOW BYTE
045D E6 81             MOV    AL,BL          ;
045F B8 C3             OUT    MFG_PORT+2,AL ;
0461 E6 82             ;----- CHECK FOR VIDEO ROM

0463 B9 C000           M1:   MOV    CX,0C000H ; START OF IO ROM
0466 BE D9             SUB    DS,CX          ; GET THE FIRST 2 LOCATIONS
0468 03 00             SHLD  BX,DX          ;
046A BB 07             MOV    AX,[BX]        ; BUS SETTLE
046C EB 00             SHORT $+2      ; IS THE VIDEO ROM PRESENT?
046E 3D A455           CMP    AX,0AA55H ; GO IF YES
0471 74 0C             JZ    Z5           ; PRINT TO NEXT 2K BLOCK
0473 B1 C1 0080         ADD    CX,080H ; TOP OF VIDEO ROM AREA YET?
0477 B1 19 C800         CMP    CX,0C800H ; TRY AGAIN
047B 7C E9             JL    M1           ; SET NON ZERO FLAG
047D 23 C9             AND    CX,CX          ;
047F T5 03             Z5:   JNZ    C32           ; GO IF NOT
0481 E9 0573 R           JMP    C31_0         ; BYPASS ERROR DISPLAY IF VIDEO ROM

;----- SET VIDEO MODE TO DISPLAY MEMORY ERROR
;----- THIS ROUTINE INITIALIZES THE ATTACHMENT TO
;----- TO DISPLAY FIRST 64K STORAGE ERRORS.
;----- BOTH COLOR AND MONO ATTACHMENTS ARE INITIALIZED.

= 0010 M4:   EQU    10H
;----- INIT COLOR/MONO
0484 B8 03D8           C32:  MOV    DX,3D8H ; CONTROL REG ADDRESS OF COLOR CARD
0487 2A C0             SUB    AL,AL          ; MODE SET
0489 EE               OUT    DX,AL          ;

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048A BA 03B8      MOV    DX,03B8H      ; CONTROL REG ADDRESS OF BW CARD
048D B0 01      MOV    AL,1          ; MODE SET FOR CARD
048F EE          OUT   DX,AL        ; RESET VIDEO
0490 03 EA 04      SUB   DX,4         ; BACK TO BASE REGISTER

0493 BB 0030 E    MOV    BX,[OFFSET_VIDEO_PARMS+M4*3] ; POINT TO VIDEO PARMS
0496 B9 0010      ASSUME DS:[CODE]
Z_2: MOV    CX,M4        ; COUNT OF MONO VIDEO PARMS
;----- BX POINTS TO CORRECT ROW OF INITIALIZATION TABLE
0499 32 E4      XOR   AH,AH        ; AH WILL SERVE AS REGISTER NUMBER DURING LOOP
;----- LOOP THROUGH TABLE, OUTPUTTING REG ADDRESS, THEN VALUE FROM TABLE
049B 8A C4      M10: MOV   AL,AH        ; GET 6845 REGISTER NUMBER
049D EE          OUT   DX,AL        ; POINT TO DATA PORT
049E 42          INC   DX          ; NEXT REGISTER VALUE
049F FE C4      INC   AH          ; GET TABLE VALUE
04A0 25 07       MOV   AX,[CS:[BX]] ; OUT TO CHIP
04A4 EE          OUT   DX,AL        ; NEXT IN TABLE
04A5 43          INC   BX          ; BACK TO POINTER REGISTER
04A6 4A          DEC   DX          ; DO THE WHOLE TABLE
04A7 E2 F2      LOOP  M10        ; CHECK IF COLOR CARD DONE
04A8 B0 E4 F0      AND   AH,0F0H     ; STRIP UNWANTED BITS?
04AE 80 FC D0      CMP   AH,0D0H     ; IS IT THE COLOR CARD?
04B1 74 08       JZ   Z_3         ; CONTINUE IF COLOR
04B3 BB 0000 E    MOV   BX,[OFFSET_VIDEO_PARMS] ; POINT TO VIDEO PARMS
04B6 BA 03D4      MOV   DX,3D4H     ; COLOR BASE
04B9 EB DB      JMP   Z_2         ; CONTINUE
;----- FILL REGEN AREA WITH BLANK
04BB 33 FF      Z_3: XOR  DI,DI        ; SET UP POINTER FOR REGEN
04BD B8 B000      MOV   AX,0B000H    ; SET UP ES TO VIDEO REGEN
04C0 8E CO      MOV   ES,AX        ;
04C2 B9 0800      MOV   CX,2048      ; NUMBER OF WORDS IN MONO CARD
04C5 B8 0720      MOV   AX,'1'+7*256 ; FILL CHAR FOR ALPHA
04C8 F3/ AB      REP  STOSW        ; FILL THE REGEN BUFFER WITH BLANKS
04CA 33 FF      XOR  DI,DI        ; CLEAR COLOR VIDEO RAM
04CC BB B800      MOV   BX,0B800H    ; SET UP ES TO COLOR VIDEO RAM
04CF BE C3      MOV   ES,BX        ;
04D1 B9 2000      MOV   CX,8192      ;
04D4 F3/ AB      REP  STOSW        ; FILL WITH BLANKS
;----- ENABLE VIDEO AND CORRECT PORT SETTING
04D6 BA 03B8      MOV   DX,3B8H      ; SET VIDEO ENABLE PORT
04D9 B9 29      MOV   AL,29H        ;
04DB EE          OUT   DX,AL        ; SET VIDEO ENABLE PORT
;----- SET UP OVERSCAN REGISTER
04DC 42          INC   DX          ; SET OVERSCAN PORT TO A DEFAULT
04DD B0 30      MOV   AL,30H        ; VALUE OF 30H FOR ALL MODES EXCEPT 640X200
04DF EE          OUT   DX,AL        ; OUTPUT THE CORRECT VALUE TO 3D9 PORT
;----- ENABLE COLOR VIDEO AND CORRECT PORT SETTING
04E0 BA 03D8      MOV   DX,3D8H      ; SET VIDEO ENABLE PORT
04E3 B0 28      MOV   AL,28H        ;
04E5 EE          OUT   DX,AL        ; SET VIDEO ENABLE PORT
;----- SET UP OVERSCAN REGISTER
04E6 42          INC   DX          ; SET OVERSCAN PORT TO A DEFAULT
04E7 B0 30      MOV   AL,30H        ; VALUE OF 30H FOR ALL MODES EXCEPT 640X200
04E9 EE          OUT   DX,AL        ; OUTPUT THE CORRECT VALUE TO 3D9 PORT
;----- DISPLAY FAILING CHECKPOINT AND
04EA 8C C8      MOV   AX,CS        ; SET STACK SEGMENT TO CODE SEGMENT
04EC 8E D0      MOV   SS,AX        ;
04EE BB B000      MOV   BX,0B000H    ; SET DS TO BW CRT BUFFER
04F1 8E DB      MOV   DS,BX        ;
04F3 B0 30      Z_0: MOV  AL,'0'      ; DISPLAY BANK 000000
04F4 B9 0006      MOV  AL,'0'<6>    ; START AT 0
04F8 2B F7      SUB  DI,DI        ; WRITE TO CRT BUFFER
04FA 88 05      Z:  MOV  DS:[DI],AL    ; POINT TO NEXT POSTITION
04FC 47          INC  DI          ;
04FD 47          INC  DI          ;
04FE E2 FA      LOOP Z          ;
0500 80 FF B8      CMP  BH,0B8H      ; CHECK THAT COLOR BUFFER WRITTEN
0503 74 0C      JZ   Z_1         ; POINT TO START OF BUFFER
0505 2B FF      SUB  DI,DI        ;
0507 B7 B0      MOV  BH,0B0H      ; ES = MONO
0509 8E C3      MOV  ES,BX        ; SET SEGMENT TO COLOR
050B B7 B8      MOV  BH,0B8H      ; DS = COLOR
050D 8E DB      MOV  DS,BX        ;
050F EB E2      JMP  Z_0         ;
;----- PRINT FAILING BIT PATTERN
0511 B0 20      Z_1: MOV  AL,' '      ; DISPLAY A BLANK
0513 88 05      MOV  DS:[DI],AL    ; WRITE TO COLOR BUFFER
0515 26 88 05      MOV  ES:[DI],AL    ; WRITE TO MONO BUFFER
0517 88 05      INC  DI          ; POINT TO NEXT POSTITION
0519 47          INC  DI          ;
051A E4 81      IN   AL,MFG_PORT+1  ; GET THE HIGH BYTE OF FAILING PATTERN
051C B1 04      MOV  CL,4         ; SHIFT COUNT
051E D2 E8      SHR  AL,CL        ; NIBBLE SWAP
0520 BC 05E2 R    MOV  SP,OFFSET Z1_0
0523 EB 1E 90      JMP  PR          ;
0526 E4 81      Z1: IN   AL,MFG_PORT+1  ;
0528 24 0F      AND  AL,0FH        ; ISOLATE TO LOW NIBBLE
052B BC 05E0 R    MOV  SP,OFFSET Z2_0
052D B0 1E 90      JMP  PR          ;
0530 E4 82      Z2: IN   AL,MFG_PORT+2  ; GET THE HIGH BYTE OF FAILING PATTERN
0532 B1 04      MOV  CL,4         ; SHIFT COUNT
0534 D2 E8      SHR  AL,CL        ; NIBBLE SWAP
0536 BC 05E2 R    MOV  SP,OFFSET Z3_0
0539 EB 1E 90      JMP  PR          ;
053C E4 82      Z3: IN   AL,MFG_PORT+2  ; ISOLATE TO LOW NIBBLE
053E 24 0F      AND  AL,0FH        ; RETURN TO Z4_
0540 BC 05E4 R    MOV  SP,OFFSET Z4_0
;----- CONVERT AND PRINT

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0543 0H 90 PR: ADD AL,090H ; CONVERT 00-0F TO ASCII CHARACTER
0545 27 DAA ; ADD FIRST CONVERSION FACTOR
0546 1H 40 ADC AL,040H ; ADJUST FOR NUMERIC AND ALPHA RANGE
0548 27 DAA ; ADD CONVERSION AND ADJUST HIGH NIBBLE
0549 88 05 MOV DS:[DI],AL ; ADJUST HIGH NIBBLE TO ASCII RANGE
054B 26: 88 05 MOV ES:[DI],AL
054C 47 INC DI
054F 47 INC DI
0550 C3 RET

;----- DISPLAY 201 ERROR
0551 80 20 Z4: MOV AL,' '
0553 88 05 MOV DS:[DI],AL ; WRITE TO COLOR BUFFER
0555 26: 88 05 MOV ES:[DI],AL ; WRITE TO MONO BUFFER
0556 47 INC DI ; POINT TO NEXT POSTITON
0559 47 INC DI
055A 80 32 MOV AL,'2'
055C 88 05 MOV DS:[DI],AL ; DISPLAY 201 ERROR
055E 26: 88 05 MOV ES:[DI],AL ; WRITE TO CRT BUFFER
0560 47 INC DI ; WRITE TO MONO BUFFER
0561 47 INC DI ; POINT TO NEXT POSTITON
0562 47 INC DI
0563 B8 30 MOV AL,'0'
0565 88 05 MOV DS:[DI],AL ; WRITE TO CRT BUFFER
0567 26: 88 05 MOV ES:[DI],AL ; WRITE TO MONO BUFFER
0568 47 INC DI ; POINT TO NEXT POSTITON
0569 B8 31 MOV AL,'1'
056E 88 05 MOV DS:[DI],AL ; WRITE TO CRT BUFFER
0570 26: 88 05 MOV ES:[DI],AL ; WRITE TO MONO BUFFER

;----- ROLL ERROR CODE IN MFG_PORT --> FIRST THE CHECKPOINT
0573 B8 DD C31_0: MOV AL,0DDH ; <><><><><><><><><>
0575 E6 80 OUT MFG_PORT,AL ; <><>CHECKPOINT DD <><>
0577 E6 83 OUT MFG_PORT+3,AL ; ALSO DISPLAY CHECK POINT IN PORT 83
0579 2B C9 SUB CX,CX ;
057B C31_A: SUB AX,AX ; SETUP SEGMENT
057D 8E DB MOV DS:AX ;
057F 88 AA55 MOV AX,0AA55H ; WRITE AN AA55
0582 2B FF SUB DI,DI
0584 89 05 MOV DS:[DI],AX ; READ THE FIRST WORD
0586 B8 05 MOV AX,DS:[DI] ; DISPLAY CHKPT LONGER
0587 E2 F1 LODP C31_A
058A 89 05 C31_B: MOV DS:[DI],AX ;
058C 8B 05 MOV AX,DS:[DI] ;
058E E2 FA LOOP C31_B
0590 89 05 C31_C: MOV DS:[DI],AX ;
0592 8B 05 MOV AX,DS:[DI] ;
0594 E2 FA LOOP C31_C
0596 C31_D: MOV DS:[DI],AX ;
0598 89 05 MOV AX,DS:[DI] ;
059A E2 FA LODP C31_D
059C 89 05 C31_E: MOV DS:[DI],AX ;
059E 8B 05 MOV AX,DS:[DI] ;
05A0 E2 FA LOOP C31_E

;----- ROLL ERROR CODE IN MFG_PORT --> NEXT THE HIGH BYTE
05A2 E4 81 C31_G: IN AL,MFG_PORT+1 ; XOR OF FAILING BIT PATTERN
05A4 E6 80 OUT MFG_PORT,AL ; HIGH BYTE
05A6 B8 AA55 MOV AX,0AA55H ; WRITE AN AA55
05A9 89 05 MOV DS:[DI],AX ; READ THE FIRST WORD
05B1 8B 05 MOV AX,DS:[DI] ;
05B3 E2 FA LODP C31_G
05B5 C31_H: MOV DS:[DI],AX ;
05B7 89 05 MOV AX,DS:[DI] ;
05B9 E2 FA LOOP C31_H
05B8 89 05 C31_I: MOV DS:[DI],AX ;
05B9 8B 05 MOV AX,DS:[DI] ;
05B9 E2 FA LOOP C31_I

;----- ROLL ERROR CODE IN MFG_PORT --> THEN THE LOW BYTE
05BB E4 82 C31_K: IN AL,MFG_PORT+2 ; LOW BYTE
05BD E6 80 OUT MFG_PORT,AL ;
05BF 88 AA55 MOV AX,0AA55H ; WRITE AN AA55
05C0 2B FF SUB DI,DI
05C1 89 05 MOV DS:[DI],AX ; READ THE FIRST WORD
05C3 8B 05 MOV AX,DS:[DI] ;
05C5 E2 FA LODP C31_K
05CA 89 05 C31_L: MOV DS:[DI],AX ;
05CC 8B 05 MOV AX,DS:[DI] ;
05CE E2 FA LOOP C31_L
05D0 C31_M: MOV DS:[DI],AX ;
05D2 8B 05 MOV AX,DS:[DI] ;
05D4 E2 FA LODP C31_M
05D6 89 05 C31_N: MOV DS:[DI],AX ;
05D8 8B 05 MOV AX,DS:[DI] ;
05DA E2 FA LODP C31_N
05DC EB 95 JMP C31_O ; DO AGAIN
05DE 0526 R Z1_0: DW Z1 ; TEMP STACK
05EO 0530 R Z2_0: DW Z2 ; TEMP STACK
05E2 053C R Z3_0: DW Z3 ; TEMP STACK
05E4 0551 R Z4_0: DW Z4 ; TEMP STACK

;----- CLEAR STORAGE ENTRY
05E6 CLR_STG: ASSUME DS:DATA ; STORE 32K WORDS OF 0000
05E8 88 ---- R RD 32000 MOV AL,DATA ; RESTORE DATA SEGMENT
05EB 8E D8 MOV DS,AX ; RESTORE RESET FLAG
05ED 89 1E 0072 R MOV RESET_FLAG,BX ; RESTORE RESET FLAG

;----- SETUP STACK SEG AND SP
05F1 B8 ---- R C33: MOV AX,DATA ; SET DATA SEGMENT
05F4 8E D8 MOV DS,AX ; GET STACK VALUE UP
05F6 BC 0000 MOV SP,POST_SS ; SET THE STACK UP
05F9 8E D4 MOV SS,SP

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05FB BC 8000          MOV     SP_POST_SP      ; STACK IS READY TO GO
                      ;----- GET THE INPUT BUFFER (SWITCH SETTINGS)
05FE B0 11          C37:  MOV     AL,11H      ; <><><><><><><><>
0600 E6 80          OUT    MFG_PORT,AL   ; <><><>CHECKPOINT 11 <><>
0602 E4 82          IN     AL,DMA_PAGE+1  ; GET THE SWITCH SETTINGS
0604 24 F0          AND    AL,0FOH      ; STRIP UNUSED BITS
0606 A2 0012 R      MOV    MFG_TST,AL   ; SAVE SETTINGS
0609 2A C0          SUB    AL,AL       ; RESET DMA_PAGE
060B E6 82          OUT    DMA_PAGE+1,AL ; <><><><><><><><>
                      ;----- TEST 11A
0602 E4 82          VERIFY 286 LGDT/SGDT LIDT/SIDT
0604 24 F0          INSTRUCITONS
0606 A2 0012 R      DESCRIPTION
0609 2A C0          LOAD_GDT AND IDT REGISTERS WITH
060B E6 82          AA,55,00 AND VERIFY CORRECT
                      ;----- VERIFY STATUS INDICATE COMPABILITY (REAL) MODE
060D 0F             SWSW   AX         ; GET THE CURRENT STATUS WORD
060E D1 E0          + DB    0OFH
060E ??0000          + LABEL BYTE
0610                   + SHL   AX,1
0610 ??0001          + LABEL BYTE
0610                   + ORG   OFFSET CS:??0000
0610                   + DB    0FH
0610                   + ORG   OFFSET CS:??0001
0610                   TEST  AX,0FH
0613 75 37          JNZ    ERR_PROT  ; PE/MP/EM/TS BITS SHOULD BE ZERO
0613                   ; GO IF STATUS NOT REAL MODE
                      ;----- TEST PROTECTED MODE REGISTERS
0615 B0 12          MOV    AL,12H      ; SET CHECK POINT 12
0617 E6 80          OUT    MFG_PORT,AL ; <><><><><><><><>
0619 1E             PUSH   DS         ; SET ES TO SAME SEGMENT AS DS
061A 07             POP    ES
061B BF DOAO          MOV    DI_SYS_IDT_LOC ; USE THIS AREA TO BUILD TEST PATTERN
061C B9 0003          MOV    CX,3
0621 B8 AAAAH        MOV    AX,0AAAHH ; FIRST PATTERN
0622 E8 064F R      CALL   WRT_PAT
0623 A9 0000          MOV    AX,0555H
0624 E8 064F R      CALL   WRT_PAT
0625 2B CO           SUB    AX,AX   ; WRITE NEXT PATTERN
0626 E8 064F R      CALL   WRT_PAT
0627 2B ED           SUB    BP,BP   ; WRITE 0
0632 2B ED           CALL   WRT_PAT
0632                   ; RESTORE BP REG
                      ;----- TEST 286 CONTROL FLAGS
0634 FD             STD
0635 9C             PUSHF
0636 58             POP    AX
0637 A9 0200          TEST   AX,0200H ; SET DIRECTION FLAG FOR DECREMENT
0638 A5 10             JNZ    ERR_PROT ; GET THE FLAGS
0639 A9 0400          TEST   AX,0400H ; INTERRUPT FLAG SHOULD BE OFF
063F 74 0B             JZ    ERR_PROT ; GO IF NOT
0641 FC             CLD
0642 0F             PUSHF
0643 58             POP    AX
0644 A9 0400          TEST   AX,0400H ; CHECK DIRECTION FLAG
0647 75 03             JNZ    ERR_PROT ; GO IF NOT SET
0649 EB 3E 90          JMP    C37A    ; CLEAR DIRECTION FLAG
064C F4             ERR_PROT
064D EB FD           JMP    SHORT_ERR_PROT ; INSURE DIRECTION FLAG IS RESET
064D                   ; TEST OR CONTINUE
064E F4             PROTECT_MODE_REGISTER_FAILURE
064F EB FD           JMP    SHORT_ERR_PROT ; INSURE NO BREAKOUT OF HALT
                      ;----- WRITE TO 286 REGISTERS
06HF B9 0003          WRT_PAT:MOV  CX,3
0652 F3/ AB          REP    STOSW
0654 BD DOAO          MOV    BP,SYN_IDT_LOC ; STORE 6 BYTES OF PATTERN
0657 26             SEGOV ES
0658 OF             L_IDT [BP] ; LOAD THE IDT
0659 ??0003          + LABEL BYTE
0659 8B 5E 00          MOV    BX,WORD PTR [BP] ; REGISTER FROM THIS AREA
065C ??0004          + LABEL BYTE
0659                   + ORG   OFFSET CS:??0003
0659 01             + DB    0FH
065C                   + ORG   OFFSET CS:??0004
065C BD DOAO          MOV    BP,SYN_IDT_LOC ; LOAD THE GDT
065F 26             SEGOV ES
065F                   DB    026H ; LOAD THE GDT
0660 0F             LIDT [BP] ; FROM THE SAME AREA
0661 8B 56 00          MOV    DX,WORD PTR [BP]
0664 ??0006          + LABEL BYTE
0661                   + ORG   OFFSET CS:??0006
0661 01             + DB    001H
0664                   + ORG   OFFSET CS:??0007 ;----- READ AND VERIFY 286 REGISTERS
0664 BD DBAO          MOV    BP,GDT_LOC ; STORE THE REGISTERS HERE
0667 26             SEGOV ES
0668 OF             SIDT [BP] ; GET THE IDT REGS
0669 ??0009          + LABEL BYTE
0669 8B 4E 00          MOV    CX,[BP]
0669 ??000A          + LABEL BYTE
0669                   + ORG   OFFSET CS:??0009
0669 01             + DB    001H
066C BD DB8A5          MOV    BP,GDT_LOC+5 ;----- READ AND VERIFY 286 REGISTERS
066F 26             SEGOV ES
066F                   DB    026H ; GET THE GDT REGS
0670 0F             SGDT [BP]
0671 ??000C          + DB    0OFH
0671 03 46 00          + LABEL BYTE
0671 ??000D          + ADD    AX,[BP]
0671                   + ORG   OFFSET CS:??000C
0671 01             + DB    001H
0674 BF DOAO          MOV    DI_SYS_IDT_LOC ; GET THE PATTERN WRITTEN
0675 BB 0F             MOV    AX,DS:[DI] ; CHECK ALL_REGISTERS
0679 B9 0005          MOV    AX,ES:[SI] ; POINT TO THE BEGINNING
067C BE DBAO          MOV    SI,GDT_LOC
067F 26: 3B 04          C37B: CMP    AX,ES:[SI]

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0682 75 C8 JNZ ERR_PROT ; HALT IF ERROR
0684 46 INC SI ; POINT TO NEXT WORD
0685 46 INC SI
0686 E2 F7 LOOP C37B ; CONTINUE TILL DONE
0688 C3

;----- INITIALIZE THE 8259 INTERRUPT #1 CONTROLLER CHIP : -----
C37A: SUB AL,AL ; RESET MATH PROCESSOR
      OUT X2077+1,AL ; ICW1 - EDGE, MASTER, ICW4
      INC SI
      OUT INTA00,AL ; WAIT STATE FOR IO
      JMP SHORT $+2 ; SETUP ICW2 - INT TYPE 8 (8-F)
      OUT INTA01,AL ; WAIT STATE FOR IO
      JMP SHORT $+2 ; WAIT STATE FOR IO
      MOV AL,0AH ; SETUP ICW3 - MASTER LV 2
      OUT INTA01,AL ; IO WAIT STATE
      JMP SHORT $+2 ; SETUP ICW4 - MASTER, 8086 MODE
      MOV AL,0FH ; WAIT STATE FOR IO
      OUT INTA01,AL ; MASK ALL INTS. OFF
      MOV AL,0FFH ; (VIDEO ROUTINE ENABLES INTS.)
      OUT INTA01,AL

;----- INITIALIZE THE 8259 INTERRUPT #2 CONTROLLER CHIP : -----
0689 2A C0 MOV AL,13H ; <><><><><><><><><><>
068B E6 F1 OUT MFQ_PORT,AL ; <><><>CHECKPOINT 13 <>>
068D B0 11 MOV AL,11H ; ICW1 - EDGE, SLAVE ICW4
06AF E6 A0 OUT INTB00,AL ; WAIT STATE FOR IO
06B1 EB 00 JMP SHORT $+2 ; SETUP ICW2 - INT TYPE 50 (50-F5)
06B3 EB 00 MOV AL,0FH ; SETUP ICW3 - SLAVE LV 2
06B5 E6 A1 OUT INTB01,AL ; IO WAIT STATE
06B7 B0 02 MOV AL,02H ; SETUP ICW4 - 8086 MODE, SLAVE
06B9 EB 00 JMP SHORT $+2 ; WAIT STATE FOR IO
06B8 E6 A1 OUT INTB01,AL ; MASK ALL INTS. OFF
06B9 EB 00 MOV AL,0FH ; (VIDEO ROUTINE ENABLES INTS.)
06B8 E6 A1 OUT INTB01,AL ; SET UP THE INTERRUPT VECTORS TO TEMP INTERRUPT
06C0 80 13 MOV AL,14H ; <><><><><><><><><><>
06C1 E6 80 OUT MFQ_PORT,AL ; <><><>CHECKPOINT 14 <>>
06AD B0 11 MOV CX,78H ; FILL ALL INTERRUPT LOCATIONS
06AF E6 A0 SUB DI,DI ; FIRST INTERRUPT LOCATION
06B1 EB 00 MOV ES,DI ; SET ES ALSO
06B3 EB 00 D3: MOV AX,OFFSET D11 ; MOVE ADDRESS OF INT OFFSET
06B4 BB 0000 E STOSW ; GET THE SEGMENT
06D7 AB MOV AX,CS ; ESTABLISH BIOS SUBROUTINE CALL INTERRUPT VECTORS
06D8 8C C8 STOSW ; SET UP ADDRESS OF VECTOR TABLE
06DA AB LOOP D3 ; SET AX=SEGMENT
06DB E2 F7

06C9 B0 14 MOV AL,15H ; <><><><><><><><><>
06CB E6 80 OUT MFQ_PORT,AL ; <><><>CHECKPOINT 15 <>>

06CD B9 0078 MOV DI,OFFSET VIDEO_INT ; SET VIDEO INT AREA
06D0 2B FF PUSH CS
06D2 8E C7 POP DS ; SET UP ADDRESS OF VECTOR TABLE
06D4 BB 0000 E MOV AX,DS ; SET AX=SEGMENT
06D7 AB D3: MOV SI,OFFSET VECTOR_TABLE+16 ; START WITH VIDEO ENTRY
06D8 8C C8 STOSW ; MOVE VECTOR TABLE TO RAM
06DA AB LOOP D3A ; SKIP SEGMENT POINTER
06DB E2 F7

06E1 BF 0040 R MOV CX,16 ; VERIFY CMOS CHECKSUM/BATTERY GOOD
06E4 0E ASSUME DS:DATA ; DESCRIPTION
06E5 1F D3: TEST AL,CMOS_PORT+1 ; DETERMINE IF CONFIG RECORD SHOULD BE
06E6 8C D8 IN AL,BAD_BAT ; USED FOR INITIALIZATION
06E8 BE 0010 E MOV DS,CMOS_PORT ; IS THE BATTERY LOW?
06E9 B9 0010 MOV DS,CMOS_PORT ; GO IF YES
06E9 B9 0010 MOV DS,CMOS_PORT ; GET THE OLD STATUS
06E9 B9 0010

06EE A5 D3A: MOVSW DS,DATA ; HAS CUSTOMER SETUP BEEN EXECUTED?
06EF 47 INC DI ; GO CHECK CHECKSUM IF YES
06F0 47 INC DI ; SKIP SEGMENT POINTER
06F1 E2 FB LOOP D3A ; CONTINUE WITHOUT CONFIG

;----- TEST.12 -----
;----- VERIFY CMOS CHECKSUM/BATTERY GOOD -----
;----- DESCRIPTION -----
;----- DETERMINE IF CONFIG RECORD SHOULD BE -----
;----- USED FOR INITIALIZATION -----
;----- IS THE BATTERY LOW THIS POWER UP? -----
06F3 E8 0000 E CMOS: ASSUME DS:DATA ; SET THE DATA SEGMENT
06F5 B0 16 MOV AL,16H ; <><><><><><><><><>
06F6 E6 80 OUT MFQ_PORT,AL ; <><><>CHECKPOINT 16 <>>

;----- IS THE BATTERY LOW THIS POWER UP? -----
06FA B0 8D MOV AL,BATTERY_COND_STATUS ; CHECK BATTERY CONDITION
06FB E6 70 OUT CMOS_PORT,AL ; POINT TO BATTERY STATUS
06FE EB 00 JMP SHORT $+2 ; WAIT STATE FOR IO
0700 E4 71 IN AL,CMOS_PORT+1 ; IS THE BATTERY LOW?
0702 A8 80 TEST AL,80H ; GO IF YES
0704 74 0F JZ CMOSTA ; GET THE OLD STATUS
0705 B0 8D MOV AL,BATTERY_STATUS ; HAS CUSTOMER SETUP BEEN EXECUTED?
0706 E6 70 OUT CMOS_PORT,AL ; GO CHECK CHECKSUM IF YES
0707 EB 00 JMP SHORT $+2
0708 E6 70 IN AL,CMOS_PORT+1 ; SET THE DEAD BATTERY FLAG
0709 E4 71 TEST AL,BAD_BAT ; JZ CMOST1
070E A8 80 JZ CMOST1 ; CONTINUE WITHOUT CONFIG
0710 74 21

0712 E9 07A1 R JMP CMOS4 ; SET DEFECTIVE BATTERY FLAG
0715 B0 17 CMOS1A: MOV AL,17H ; <><><><><><><><><>
0717 E6 80 OUT MFQ_PORT,AL ; <><><>CHECKPOINT 17 <>>

0719 B0 8E MOV AL,DIAG_STATUS ; CMOS DIAGNOSTIC STATUS BYTE
071B E6 70 OUT CMOS_PORT,AL ; JMP SHORT $+2
071D EB 00 IN AL,CMOS_PORT+1 ; GET THE CURRENT STATUS
071F E4 71 XCHG AL,AH ; SAVE
0721 B0 8C XCHG OR AH,BAD_BAT ; SET THE DEAD BATTERY FLAG
0723 B0 CC 80 MOV AL,DIAG_STATUS ; OUT CMOS_PORT,AL
0725 B0 8E OUT AI,AH ; OUTPUT THE STATUS
0726 E6 70 XCHG JMP SHORT $+2 ; SET FLAG IN CMOS
0727 E0 8C OUT CMOS_PORT+1,AL
072A E6 C4
072C EB 00
072E E6 71

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07E5          +     ORG    OFFSET CS:??000F
07E5          A9 0001   TEST   AX,VIRTUAL_ENABLE
07E8          75 10     JNZ    VIR_OK
; ARE WE IN PROTECTED MODE

07EA          B0 8F     SHUT_8: MOV    AL,SHUT_DOWN
07EC          E6 70     OUT    CHOS_PORT,AL
07EE          EB 00     JMP    SHORT $+2
07F0          B0 00     K0V    AL,0BH
07F2          E6 71     OUT    CHOS_PORT+1,AL
07F4          E9 0000 E  JMP    PROC_SHUTDOWN
; SET THE RETURN ADDR
; IO DELAY
; SET SHUTDOWN 8
; CAUSE A SHUTDOWN

;----- VIRTUAL MODE ERROR HALT
07F7          F4        SHUT8: HLT
07F8          EB FL    JMP    SHUTB
; ERROR HALT

;----- 64K SEGMENT LIMIT
07FA          C7 06 0048 FFFF  VIR_OK: MOV    DS:ES_TEMP.SEG_LIMIT,MAX_SEG_LEN
;----- CPLO, DATA ACCESS RIGHTS
0800          C6 06 004D 93  MOV    BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),CPLO_DATA_ACCESS
;----- START WITH SEGMENT ADDR 01-0000 (SECOND 64K)
0805          C6 06 004C 01  MOV    BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),01H
080A          C7 06 004A 0000  MOV    DS:ES_TEMP.BASE_LO_WORD,0H
0810          B0 1B     MOV    AL,1BH
0812          E6 80     OUT    MFQ_PORT,AL
; <><><><><><><><><><>
0814          BB 0040   MOV    BX,16*4
; SET THE FIRST 64K DONE

;----- START STORAGE SIZE/CLEAR
0817          B8 0048   NOT_DONE:
081A          8E C0     MOV    AX,ES_TEMP
081C          E8 0838 R  MOV    ES_AX
081D          74 03     CALL   HOW_BIG
0821          E9 08B7 R  JZ    NOT_FIN
0824          83 C3 40   JMP    DONE
; POINT ES TO DATA
; POINT TO SEGMENT TO TEST
; DO THE FIRST 64K
; CHECK IF TOP OF RAM
NOT_FIN:
ADD   BX,16*4
; BUMP MEMORY COUNT BY 64K

;----- DO NEXT 64K (0X0000) BLOCK
0827          FE 06 004C   INC    BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE)

;----- CHECK FOR END OF FIRST 640K (END OF BASE RAM)
0828          B0 3E 004C 0A  CMP    BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),0AH
0830          75 E5     JNZ    NOT_DONE
0832          E8 08B8 R  CALL   HOW_BIG_END
0835          E9 08B7 R  JMP    DONE
; GO IF NOT
; GO SET MEMORY SIZE.

;----- FILL/CHECK LOOP
0838          2B FF     HOW_BIG:
083A          B8 AA55   SUB    DI,DI
083D          BB C8     MOV    AX,0AA55H
083E          26: 89 05   MOV    CX,AX
0840          48 0F     CALL   ES:[DI],AX
0842          26: 8B 05   MOV    AL,0FH
0844          26: 8B 05   MOV    AX,ES:[DI]
0847          26: 89 05   MOV    ES:[DI],AX
084A          33 C1     XOR    AX,CX
084C          75 3D     JNZ    HOW_BIG_END
; TEST PATTERN
; SAVE PATTERN
; SET PATTERN TO MEM.
; PUT SOMETHING IN AL
; GET PATTERN
; INSURE NO PARITY TO CHECK
; COMPARE PATTERNS
; GO END IF NO COMPARE

084E          1E        084E: 1E
084F          B8 0018   PUSH   DS
0852          8E D8     MOV    AX,RSDA_PTR
0854          81 3E 0072 R 1234  MOV    DS,AX
085A          1F        CMP    RESET_FLAG,1234H
085B          75 26     POP    DS
JNZ    HOW_BIG_2
; POINT TO SYSTEM DATA AREA
; SOFT RESET
; RESTORE DS
; GO IF NOT SOFT RESET

0850          26: C7 05 0101  MOV    WORD PTR ES:[DI],0101H
; TURN OFF BOTH PARITY BITS

0862          E4 61     0862: E4 61
0864          EB 00     IN     AL,PORT_B
0866          0C 0C     OR     AL,RAM_PAR_OFF
0868          E6 61     OUT    PORT_B,AL
086A          E6 00     JMP    SHORT $+2
086C          29 F3     AND    AL,RAM_PAR_ON
086E          E6 61     OUT    PORT_B,AL
; IO DELAY
; TOGGLE PARITY CHECK ENABLES

0870          B8 FFFF   0870: B8 FFFF
0873          50        MOV    AX,OFFFH
0874          58        PUSH   AX
0875          26: 8B 05   POP    AX
0876          E5 61     MOV    AX,ES:[DI]
; DELAY
; CHECK PARITY

0878          E4 61     0878: E4 61
087A          24 C0     AND    AL,PARITY_ERR
; CHECK FOR PARITY/IO CHECK

087C          26: C7 05 0000 087C: 26: C7 05 0000
087D          75 08     JNZ    HOW_BIG_END
; INSURE NO PARITY TO CHECK
; GO IF PARITY/IO CHECK

0883          2B C0     HOW_BIG_2:
SUB   AX,AX
; WRITE ZEROS

0885          B9 8000   0885: B9 8000
0888          F3/ AB   REP    STOSW
088A          C3        RET
; SET COUNT FOR 32K WORDS
; FILL 32K WORDS

088B          9C        088B: 9C
088C          B0 1C     PUSHF  AL,1CH
088E          E6 80     OUT    MFQ_PORT,AL
; SAVE THE CURRENT FLAGS
; <><><><><><><><><>
; <><><><><><><><><>
; CHECKPOINT 1C <><>

;----- SET OR RESET 512 TO 640 INSTALLED FLAG
0890          B0 B3     0890: B0 B3
0892          E6 70     MOV    AL,INFO_STATUS
0894          E6 70     OUT    CHOS_PORT,AL
0896          E6 71     JMP    SHORT $+2
0898          OC 80     IN     AL,CHOS_PORT+1
089A          8C C4     OR     AL,M640K
089C          B0 B3     XCHG   AL,AH
089E          E6 70     MOV    AL,INFO_STATUS
08A0          86 C6     OUT    CHOS_PORT,AL
08A2          81 FB 0200  XCHG   AL,AH
08A4          77 02     CMP    BX,512
08A6          24 7F     JA    K640
08A8          E6 71     AND    AL,NOT M640K
08AA          E6 71     K640: OUT    CHOS_PORT+1,AL
; SET/RESET 640K STATUS FLAG
; IO DELAY
; GET THE DIAGNOSTIC STATUS
; SAVE THE STATUS
; RESTORE THE STATUS
; CHECK MEMORY SIZE
; SET FLAG FOR 512 -> 640 INSTALLED
;
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08AC B8 0018          MOV    AX,RSDA_PTR      ; RESTORE THE DATA SEGMENT
08AF 8E D8          MOV    DS,AX           ; SAVE MEMORY SIZE
08B1 B9 0E 0013 R     MOV    MEMORY_SIZE,BX ; RESTORE THE FLAG REG
08B5 9D              POPF   RET
08B6 C3

;----- TEST_13A :  

;----- MEMORY SIZE DETERMINE (RAM ABOVE 1024K) :  

;----- DESCRIPTION :  

;----- THIS LINE RUNS IN PROTECTED MODE :  

;----- MEMORY SIZE ABOVE 1MEG ADDRESSING IS :  

;----- SAVED IN CMOS :  

;-----
```

08B7 DONE:

08B7 B8 0008 MOV AX,GDT\_PTR ; POINT DS TO THE DESCRIPTER TABLE
08BA 8E D8 MOV DS,AX ;

;----- START WITH SEGMENT ADDR 10-0000 (ONE MEG AND ABOVE)

08BC C6 06 004C 10 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),10H
08C1 C7 06 004A 0000 MOV DS:ES\_TEMP.BASE\_LO\_WORD,0H

08C7 B0 1D MOV AL,1DH ; <><><><><><><><><>
08C9 E6 80 OUT MFG\_PORT,AL ; <><><>CHECKPOINT 1D <><>
08CB 2B DB SUB BX,BX ; START WITH COUNT 0

;----- START STORAGE SIZE/CLEAR

08CD NOT\_DONE1:  
08CD B8 0048 MOV AX,ES\_TEMP ; POINT ES TO DATA
08D0 8E C0 MOV ES\_AX ; POINT TO SEGMENT TO TEST
08D2 E8 08EE R CALL HOW\_BIG1 ; DO THE FIRST 64K

08D5 74 03 JZ DONEA ; CHECK IF TOP
08D7 EB 75 90 JMP DONE1 ; GO IF TOP

08DA 83 C3 40 DONEA: ADD BX,16\*# ; BUMP MEMORY COUNT BY 64K

;----- DO NEXT 64K (XX0000) BLOCK

08DD FE 06 004C INC BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE)

;----- CHECK FOR TOP OF RAM (FE0000)

08E1 NOT\_END\_BASE:  
08E1 80 3E 004C FE CMP BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),0FEH ; LAST OF POSSIBLE RAM?
08E6 75 E5 JNZ NOT\_DONE1 ; GO IF NOT
08E8 E8 0933 R CALL HOW\_BIG\_END1 ; GO SET MEMORY SIZE
08EB EB 61 90 JMP DONE1 ;

;----- FILL/CHECK LOOP

08EE HOW\_BIG1:  
08EE 2B FF SUB DI,DI ; TEST PATTERN
08F0 B8 AA55 MOV AX,0AA55H ; SAVE PATTERN
08F3 88 C8 MOV CX,AX ; SET PATTERN TO MEM.
08F6 26: 89 05 MOV ES:[DI],AX ; PUT SOMETHING IN AL
08F8 88 C8 MOV CX,CH ; GET PATTERN
08F9 26: 8B 05 MOV AX,ES:[DI] ; INSURE NO PARITY IO CHECK
08FD 88 C8 MOV ES:[DI],AX ; COMPARE PATTERNS
0900 33 C1 XOR AX,CX ; GO END IF NO COMPARE
0902 75 2F JNZ HOW\_BIG\_END1 ;

0904 1E PUSH DS ; POINT TO SYSTEM DATA AREA
0905 B8 0018 MOV AX,RSDA\_PTR
0908 8E D8 MOV DS,AX ;

090A 81 3E 0072 R 1234 CMP RESET\_FLAG,1234H ; SOFT RESET
0910 1F POP DS ; RESTORE DS
0911 75 18 JNZ HOW\_BIG\_2A ; GO IF NOT SOFT RESET

0913 26: C7 05 0101 MOV WORD PTR ES:[DI],0101H ; TURN OFF BOTH PARITY BITS
0918 B8 FFFF MOV AX,0FFFFH
0919 50 PUSH AX
091C 58 POP AX ; DELAY
091D 26: 8B 05 MOV AX,ES:[DI] ; CHECK PARITY
0920 E8 61 IH AL,PORT\_B ; CHECK FOR IO CHECK
0922 E8 A0 TEST AL,IO\_CHK ;

0924 26: C7 05 0000 MOV WORD PTR ES:[DI],0 ; INSURE NO PARITY IO CHECK
0928 75 08 JNZ HOW\_BIG\_END1 ; GO IF IO CHECK

0928 HOW\_BIG\_2A:  
0928 2B CO SUB AX,AX ; WRITE ZEROS
0929 B9 8000 MOV CX,2000H\*# ; SET COUNT FOR 32K WORDS
0930 F3/ AB REP STOSW ; FILL 32K WORDS
0932 C3

0933 HOW\_BIG\_END1:  
0933 B0 1E MOV AL,1EH ; <><><><><><><><><>
0935 E6 80 OUT MFG\_PORT,AL ; <><>CHECKPOINT 1E <><>

;----- SET IO RAM SIZE IN CMOS

0937 B0 B0 MOV AL,M\_SIZE\_LO ; ADDRESS LO BYTE
0939 E6 70 OUT CMOS\_PORT,AL ; IO DELAY
093B EB 00 JMP SHORT \$+2 ; SET THE MEMORY SIZE
093D B8 C3 MOV AL,BL ; IN CMOS
093E E6 71 OUT CMOS\_PORT+1,AL ; IO DELAY
0941 EB 00 JMP SHORT \$+2 ; SET THE HIGH MEMORY SIZE
0943 B0 B1 MOV AL,M\_SIZE\_HI ; ADDRESS HI BYTE
0945 E6 70 OUT CMOS\_PORT,AL ; IN CMOS
0947 EB 00 JMP SHORT \$+2
0949 8A C7 MOV AL,BH ; SET THE HIGH MEMORY SIZE
094B E6 71 OUT CMOS\_PORT+1,AL ; IN CMOS

094D C3 RET

;----- TEST ADDRESS LINES 19 ~ 23

094E B0 1F DONE1: MOV AL,1FH ; <><><><><><><><><>
0950 E6 80 OUT MFG\_PORT,AL ; <><><>CHECKPOINT 1F <><>
0952 C6 06 004C 00 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),00H
0957 BA FFFF MOV DX,0FFFFH ; WRITE FFFF AT ADDRESS 0
095A E8 098A R CALL SDO ; WRITE 0
095D 2B D2 SUB DX,DX ;

095F C6 06 004C 08 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),08H
0964 E8 098A R CALL SDO ;

0967 C6 06 004C 10 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),10H
0969 8A 00 CALL SDO ;

096F C6 06 004C 20 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),20H
0974 E8 098A R CALL SDO ;

0977 C6 06 004C 40 MOV BYTE PTR DS:(ES\_TEMP.BASE\_HI\_BYTE),40H
097C E8 098A R CALL SDO ;

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097F C6 06 004C 80           MOV    BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),80H
0984 E8 098A R              CALL   SD0
0987 EB 20 90               JMP    SD0 ; TEST PASSED CONTINUE
098A 2B FF
098C BB 0048
098F 8E C0
0991 26: 89 15
0994 C6 06 004C 00           MOV    BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),00H
0999 BB 0048
099C 8E C0
099D 05: 01 31 FFFF          MOV    AX,ES_TEMP
099E 8E C0                   CMP    ES,AX
09A3 75 03                   WWD PTR ES:[DI],0FFFFH ; POINT TO SEGMENT TO TEST
09A5 E9 07EA R              JZ    SD1 ; LOCATION 0 CHANGE?
09A8 C3                     JMP    SHUT_8 ; CONTINUE IF NOT
09A9 B0 20
09AB E6 80
09AD E9 0000 E              SD1: RET
;----- CAUSE A SHUTDOWN
09B0 B0 21
09B2 E6 80
09B4 B0 ---- R
09B7 BE D4
09B9 BC 0100 R
09BC BB ---- R
09BF BE 08
SHUT1: MOV   AL,21H          ; <><><><><><><><><>
OUT   MFG_PORT_AL           ; <><><>CHECKPOINT 21 <><>
SP,STACK
MOV   SS,SP
MOV   SP,OFFSET TOS          ; SET REAL MODE STACK
;----- GET THE CONFIGURATION FROM CMOS
09C1 B0 BE
09C3 E6 70
09C5 00 00
09C7 EH 71
09C9 AB C0
09CB 74 03
09CD EB 77 90
09DE 8A E0
09D2 8E 70
09D4 E6 70
09D6 86 C4
09D8 24 DF
09DA E6 71
09DB 80 00
09DE 80 00
09E0 E6 70
09E2 EB 00
09E4 E4 71
MOV   AL,DIAG_STATUS         ; CHECK CMOS GOOD
OUT   CMOS_PORT_AL
JMP   SHORT $+2
IN    AL,CMOS_PORT+1
TEST  AL,O0H
JZ    M_OK
MOV   MOK,BAD_MOS
MOV   AH,AL
MOV   AL,DIAG_STATUS
OUT   CMOS_PORT_AL
XCHG  AL,AH
AND   AL,ODFH
TEST  AL,ODFH
MOV   AL,EQNP
JMP   SHORT $+2
OUT   CMOS_PORT_AL
JMP   SHORT $+2
IN    AL,CMOS_PORT+1
;----- INSURE CONFIGURATION HAS CORRECT VIDEO TYPE
09E6 8A E0
09E8 A8 30
09EA 75 2E
09EC E8 09FB R
09EF 74 4A
MOV   AH,AL
TEST  AL,030H
JNZ   MOS_OK_1
CALL  CHK_VIDEO
JZ    MOS_OK
;----- ROUTINE CHECK FOR VIDEO ROM PRESENT
09F1 F6 06 0012 R 20
09F6 74 7A
TEST  MFG_TST,MFG_JMP
JZ    NORMAL_CONFIG
;----- CMOS VIDEO BITS NON ZERO (CHECK FOR PRIMARY DISPLAY AND NO VIDEO ROM)
09FB EB 4C 90
JMP   BAD_MOS
;----- ROUTINE CHECK FOR VIDEO ROM PRESENT
09FB 89 C000
CHK_VIDEO01:
MOV   CX,0C00H
;----- ROUTINE CHECK FOR VIDEO ROM PRESENT
09FF 50
09FF 1E
0A00 8E D9
0A02 2B DB
0A04 88 07
0A06 1F
0A07 3D AA55
0A08 58
0A0B 74 0C
0A0D 81 C1 0080
0A11 81 F9 C800
0A17 7C E7
0A17 23 C9
0A19 C3
MOV   AX,0AA55H
POP   DS
CMP   AX,CX
JZ    CHK_VIDEO02
MOV   DS,CX
ADD   CX,D80H
CMP   CX,0C800H
JL    CHK_VIDEO01
AND   CX,CX
CHK_VIDEO02:
RET
;----- CMOS VIDEO BITS NON ZERO (CHECK FOR PRIMARY DISPLAY AND NO VIDEO ROM)
0A1A E8 09FB R
0A1D 74 27
MOS_OK_1:
CALL  CHK_VIDEO
JZ    BAD_MOS
;----- ROUTINE CHECK FOR VIDEO ROM PRESENT
0A1F 8A C4
0A21 F6 06 0012 R 40
0A26 74 0B
MOV   AL,AH
TEST  MFG_TST,DSP_JMP
JZ    MOS_OK_2
;----- MONO CARD IS PRIMARY DISPLAY (NO JUMPER INSTALLED)
0A28 24 30
0A2A 3C 30
0A2C 75 18
0A2E 8A C4
0A30 EB 09 90
AND   AL,30H
CMP   AL,30H
JNZ   BAD_MOS
MOV   AL,AH
JMP   MOS_OK
;----- COLOR CARD
0A33 24 30
0A35 3C 30
0A37 8A C4
0A39 74 0B
AND   AL,30H
CMP   AL,30H
JNZ   BAD_MOS
MOV   AL,AH
JZ    BAD_MOS
;----- CONFIGURATION MUST HAVE AT LEAST ONE DISKETTE
0A3B A8 01
0A3D 75 33
0A3F F6 06 0012 R 20
0A44 74 2C
MOS_OK: TEST  AL,01H
JNZ   NORMAL_CONFIG
TEST  MFG_TST,MFG_JMP
JZ    NORMAL_CONFIG
;----- MUST HAVE AT LEAST ONE DISKETTE
;----- GO SET CONFIGURATION IF OK
;----- EXCEPT IF MFG JUMPER IS INSTALLED
;----- GO IF INSTALLED

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OB04 B9 0B00 MOV CX,2048 ; RAM WORD CNT FOR B/W CD
OB07 B0 01 MOV AL,1 ; SET MODE FOR BW CARD
OB09 B0 FC 30 CMP AH,30H ; B/W VIDEO CARD ATTACHED?
OB0C 74 09 JE E9 ; YES - GO TEST VIDEO STG
OB0E B7 B8 MOV BH,0BBH ; BEST VIDEO RAM COLOR CD
OB11 B0 0D8H MOV DX,3D8H ; MODE REG FOR COLOR CD
OB13 B5 20H MOV CH,20H ; RAM WORD CNT FOR COLOR CD
OB15 FE C8 DEC AL ; SET MODE TO 0 FOR COLOR CD
OB17 E9 : TEST_VIDEO_STG;
OUT DX,AL ; DISABLE VIDEO FOR COLOR CD
MOV ES,BX ; POINT ES TO COLOR RAM
MOV DS,BX ; POINT DS TO VIDEO RAM
ROR CX,1 ; DIVIDE BY 2 FOR WORD COUNT
CALL STGTST_CNT ; GO TEST VIDEO R/W STG
JNE E17 ; R/W STG FAILURE - BEEP SPK

OB18 EE : TEST.15 ;
OUT DX,AL ; DISABLE VIDEO FOR COLOR CD
MOV ES,BX ; POINT ES TO COLOR RAM
MOV DS,BX ; POINT DS TO VIDEO RAM
ROR CX,1 ; DIVIDE BY 2 FOR WORD COUNT
CALL STGTST_CNT ; GO TEST VIDEO R/W STG
JNE E17 ; R/W STG FAILURE - BEEP SPK

OB19 B8 C3 : TEST.15 ;
SETUP VIDEO DATA ON SCREEN FOR VIDEO
LINE TEST.
DESCRIPTION
ENABLE VIDEO SIGNAL AND SET MODE.
DISPLAY A HORIZONTAL BAR ON SCREEN.

OB20 B9 0B00 E10: MOV AL,22H ; <><><><><><><><><><><>
OUT MFG_PORT,AL ; <><>CHECKPOINT 22 <>
POP AX ; GET VIDEO SENSE SWS (AH)
PUSH AX ; SAVE IT
MOV AH,0 ; ENABLE VIDEO AND SET MODE
INT INT_VIDEO ; VIDEO
MOV AX,7020H ; WRT BLANKS IN REVERSE VIDEO
SUB DI,DI ; SETUP STARTING LOC
MOV CX,40 ; NO. OF BLANKS TO DISPLAY
REP STOSH ; WRITE VIDEO STORAGE

OB21 75 6F : TEST.16 ;
CRT INTERFACE LINES TEST
DESCRIPTION
VIDEO ON/OFF TRANSITION OF THE
VIDEO ENABLE AND HORIZONTAL
SYNC LINES.

OB22 B0 22 POP AX ; GET VIDEO SENSE SW INFO
OB25 E6 80 PUSH AX ; SAVE IT
OB27 58 CMP AH,30H ; B/W/CARD ATTACHED?
OB29 B4 00 MOV DX,03BAH ; SETUP ADDR OF BW STATUS PORT
OB2B CD 10 JE E11 ; YES - GO TEST LINES
OB2D B8 7020 MOV DX,03DAH ; COLOR CARD IS ATTACHED
OB30 2B FF SUB DI,DI ; LINE_TST:
OB32 B9 0028 MOV CX,40 ; OFLLOOP_CNT:
OB35 F3/ AB REP STOSH ; GET VIDEO SENSE SW INFO

OB37 5B : TEST.16 ;
OB38 50 CRT INTERFACE LINES TEST
OB39 B0 FC 30 DESCRIPTION
OB3C BA 03BA VIDEO ON/OFF TRANSITION OF THE
OB3F 74 03 VIDEO ENABLE AND HORIZONTAL
OB41 BA 03DA SYNC LINES.
OB44 B4 08 E11: MOV AH,8 ; READ CRT STATUS PORT
OB46 2B C9 SUB CX,CX ; CHECK VIDEO/HORZ LINE
OB48 EC E12: IN AL,DX ; IT ON OR OFF IF IT GOES OFF
OB49 22 C4 AND AL,AH ; LOOP TILL ON OR TIMEOUT
OB50 B4 00 JZ E13 ; GO PRINT ERROR MSG
OB52 B4 F9 LOOP E13 ; READ CRT STATUS PORT
OB54 B4 F1 JMP SHORT E17 ; CHECK VIDEO/HORZ LINE
OB55 B4 08 E14: SUB CX,CX ; IT ON OR OFF IF IT GOES OFF
OB53 EC E15: IN AL,DX ; LOOP TILL ON OR TIMEOUT
OB54 22 C4 AND AL,AH ; GO ERROR BEEP
OB56 74 05 E16: INT INT_VIDEO ; READ CRT STATUS PORT
OB58 B4 F9 E17 ; CHECK VIDEO/HORZ LINE
OB59 EA B6 36 GO ERROR BEEP ; IT ON OR OFF IF IT GOES OFF
OB60 90 : ----- CHECK HORIZONTAL LINE
OB61 B1 03 E16: MOV CL,3 ; GET NEXT BIT TO CHECK
OB65 D2 EC SHR AL,CL ; CONTINUE
OB67 75 E3 JNZ E12 ; DISPLAY_CURSOR:
OB63 :----- DISPLAY_CURSOR:
OB64 B4 00 POP AX ; GET VIDEO SENSE SWS (AH)
OB66 CD 10 MOV AH,0 ; SET MODE AND DISPLAY CURSOR
INT INT_VIDEO ; CALL VIDEO I/O PROCEDURE

OB67 BA C000 :----- CHECK FOR THE ADVANCED VIDEO CARD
OB68 B0 0000 E18A:1 MOV DX,0C000H ; SET THE LOW SEGMENT VALUE
OB69 B0 0000 OUT AL,23H ; <><><><><><><><><><><>
OB70 E6 80 MFG_PORT,AL ; <><>CHECKPOINT 23 <>
OB71 B8 DA MOV DS,BX ; GET FIRST 2 LOCATIONS
OB73 BB 0B SUB BX,BX ; LET BUS SETTLE
OB75 53 PUSH BX ; PRESENT?
OB77 5B CMP AX,0AA55H ; NO? GO LOOK FOR OTHER MODULES
OB78 7D A555 JNZ E18B ; GO SCAN MODULE
OB7C E8 0000 E CALL ROM_CHECK ; READ ADDRESS
OB7F EB 04 ADD DX,0D80H ; POINT TO NEXT 2K BLOCK
OB80 80 0080 E18B: CMP DX,0C800H ; TOP OF VIDEO ROM AREA YET?
OB85 91 FA C800 JL E18C: GO SCAN FOR ANOTHER MODULE
OB89 7C E0 MOV AL,24H ; <><><><><><><><><><><>
OB8B B0 24 OUT MFG_PORT,AL ; <><>CHECKPOINT 24 <><>
OB8D E6 80 JMP POST2 ; GO TO NEXT TEST
OB8F E9 0000 E :----- CRT ERROR SET MFG CKPT AND ERR BEEP

OB92 E8 0000 E E17: CALL DDS ; POINT TO DATA

OB93 :----- CHECKPOINT OC = MONO FAILED
OB94 C6 06 0015 R 0C MOV MFG_ERR_FLAG,0CH ; <><><><><><>
OB95 80 3E 0072 R 64 CMP BYTE PTR RESET_FLAG,064H ; IS THIS A MFG REQUEST?
OB97 74 0D JE E19 ; BY PASS ERROR BEEP IF YES
OB9A B1 06 0012 R 20 TEST MFG_TST,MFG_JMP ; IS THE MFG LOOP JUMPER INSTALLED
OB9B 74 0D E19: JZ E19 ; BY PASS ERROR BEEP IF YES
OB98 BA 0102 MOV DX,102H ; CALL ERR_BEEP ; GO BEEPER SPEAKER
OB9E BA 0000 E CALL ERR_BEEP ; GET THE CURRENT VIDEO
OB9F A1 0010 R MOV AX,EQUIP_FLAG ; STRIP OTHER BITS
OB82 24 30 AND AL,30H ; IS IT MONO?
OB84 3C 30 CMP AL,30H ; GO IF YES
OB86 74 31 JZ TRY_COLOR ; TRY COLOR

OB96 :----- COLOR FAILED TRY MONO
OB97 :----- CHECKPOINT OD = COLOR FAILED

OB88 C6 06 0015 R 0D MOV MFG_ERR_FLAG,0DH ; <><><><><><>
OBBD BA 03BB MOV DX,3B8H ; DISABLE B/W
OBCC B0 01 OUT AL,DX ; OUTPUT THE DISABLE
OB92 B7 00 OUT DS,AL ; CHECK FOR MONO VIDEO RAM
OB93 BB B000 MOV BX,0B000H ; WRITE AN A55
OB96 BE 8B MOV DS,BX ; COLOR
OB98 BB A555 MOV AX,0AA55H ; WRITE AN A55

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OBCB 2B DB           SUB    BX, BX          ; TO THE FIRST LOCATION
OBCD 89 07           MOV    [BX], AX        ; ALLOW BUS TO SETTLE
OBCF EB 00           JMP    SHORT S+2      ; READ THE FIRST LOCATION
OBD1 8B 07           MOV    AX, [BX]        ; IS THE MONO VIDEO CARD THERE?
OBD3 3D AA55         CMP    AX, 0AA55H     ; RESTORE THE DATA SEGMENT
OBD5 4C 00           POP   DS              ; GO IF NOT
OBD7 75 56           JNZ    E17_3          ; TURN ON MONO BITS IN EQUIP FLAG
OBD9 81 0E 0010 R 0030 OR     EQUIP_FLAG, 30H ; ENABLE VIDEO
OBDF A1 0010 R       MOV    AX, EQUIP_FLAG
OBE2 2A E4           SUB   AH, AH
OBE4 CD 10           INT    INT_VIDEO
OBE6 EB 35 90         JMP    E17_1          ; CONTINUE

;----- MONO FAILED TRY COLOR

TRY_COLOR:
OBE9 80 01           MOV    AL, 01H        ; SET MODE COLOR 40X25
OBEA 2A E4           SUB   AH, AH
OBED CD 10           INT    INT_VIDEO
OBEF BA 03D8         MOV    DX, 3D8H
OBF2 B0 00           MOV    AL, 0
OBF4 EE 00           OUT   DX, AL          ; DISABLE COLOR
OBF5 BB B800         MOV    BX, DB800H
OBF8 8E DB           MOV    DX, DB800H
OBF9 B8 AA55         MOV    AX, 0AA55H
OBFD 29 DB           SUB   BX, BX          ; OUTPUT THE DISABLE
OBF9 89 07           MOV    [BX], AX        ; CHECK FOR COLOR VIDEO RAM
OC01 E9 00           JMP    SHORT S+2      ; WRITE AN AA55
OC03 8B 07           MOV    AX, [BX]        ; TO THE FIRST LOCATION
OC05 DD AA55         CMP    AX, 0AA55H
OC08 1F               POP   DS              ; ALLOW BUS TO SETTLE
OC09 75 24           JNZ    E17_3          ; READ THE FIRST LOCATION
OC0B 81 26 0010 R FFCF AND   EQUIP_FLAG, OFFCFH ; IS THE COLOR VIDEO CARD THERE?
OC10 80 00 0010 R 0010 OR     EQUIP_FLAG, 10H ; RESTORE THE DATA SEGMENT
OC17 80 01           MOV    AL, 01H        ; GO IF NOT
OC19 2A E4           SUB   AH, AH
OC1B CD 10           INT    INT_VIDEO      ; TURN OFF VIDEO BITS
OC1D                           E17_1:          ; SET COLOR 40X24
OC1D 58               POP   AX              ; SET NEW VIDEO TYPE ON STACK
OC1E 81 0010 R        MOV    AX, EQUIP_FLAG
OC21 24 30           AND   AL, 30H        ; IS IT THE B/W?
OC23 3C 30           CMP    AL, 30H
OC25 2A C0           SUB   AL, AL
OC27 74 02           JZ    E17_2          ; GO IF YES
OC29 FE C0           INC    AX              ; INIT FOR 40X25
OC2A 50               INC    AX
OC2C E9 0B63 R        E17_2:          PUSH  AX
                                         E17_4:          JMP    E18

;----- BOTH VIDEO CARDS FAILED SET DUMMY RETURN IF RETRACE FAILURE

E17_3:
POST1 ENDP
CODE ENDS
ENDN

E17_3:
PUSH  DS              ; SET DS SEGMENT TO 0
SUB   AX, AX
MOV   DS, AX
MOV   DI, OFFSET VIDEO_INT ; SET INT 10H TO DUMMY
MOV   WORD PTR [DI], OFFSET DUMMY_RETURN ; RETURN IF NO VIDEO CARD
POP   DS
JMP   E18_1            ; BYPASS REST OF VIDEO TEST

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00DE 75 0D ; DID TIMER 0 INTERRUPT OCCUR?
00EO E2 F7 ; YES - CHECK TIMER OP FOR SLOW TIME
00E2 C6 06 0015 R 02 MOV MFG_ERR_FLAG,02H ; WAIT FOR INTR FOR SPECIFIED TIME
; <><><><><><><><><><><><>
; <><><>TIMER CHECKPOINT (2)<>

00E7 BE 0000 E ; DISPLAY 102 ERROR
00EA E9 004F R ; TIMER 0 INTR DIDN'T OCCUR - ERR
00ED B0 2B ; SET PGW LOOP CNT
00EF E6 80 OUT MFG_PORT,AL ; WRITE TIMER 0 CNT REG
00F1 FA CLT ; RESET INTR RECEIVED FLAG
00F4 B0 0C MOV AL,0FFH ; REENABLE TIMER 0 INTERRUPTS
00F6 E6 40 OUT TIMER0_AL
00F8 B6 06 006B R 00 MOV INTR_FLAG,0
00FD B0 FE MOV AL,0FEH
00E0 E0 21 OUT INTA01_AL
0101 FB STI ; DID TIMER 0 INTERRUPT OCCUR?
0102 F6 06 006B R 01 D10: TEST INTR_FLAG,01H ; YES - TIMER COUNTING TOO FAST, ERR
0107 75 DE JNZ D10 ; WAIT FOR INTR FOR SPECIFIED TIME
0109 E2 F7 LOOP D10

;----- WAIT FOR INTERRUPT
010B B2 C9 SUB CX,CX ;
010D B0 2C MOV AL,2CH ; <><><><><><><><><><><>
010F E6 80 OUT MFG_PORT,AL ; <><><>CHECKPOINT 2C <><><>

0111 F6 06 006B R 01 D11: TEST INTR_FLAG,01H ; DID TIMER 0 INTERRUPT OCCUR?
0116 75 08 JNZ D12 ; GO IF YES
0118 E2 F7 LOOP D11 ; TRY AGAIN
011A BE 0000 E MOV SI,OFFSET EO_B ; DISPLAY 103 ERROR
011D E9 004F R JMP D6A ; ERROR IF NOT

;----- SETUP TIMER 0 TO MODE 3
0120 FA CLI ; DISABLE ALL DEVICE INTERRUPTS
0121 B0 FF MOV AL,0FFH
0123 E6 21 OUT INTA01_AL ; SEL TIM 0,LSB,MSB,MODE 3
0125 B0 36 MOV AL,36H ; WRITE TIMER MODE REG
0127 E6 43 OUT TIMER+3_AL
0129 EB 00 JMP SHORT $+2 ; IO DELAY
012B B0 00 MOV AL,00H
012D E6 40 OUT TIMER_AL ; WRITE LSB TO TIMER 0 REG
012F EB 00 JMP SHORT $+2 ; IO DELAY
0131 E6 40 OUT TIMER_AL ; WRITE MSB TO TIMER 0 REG
;===== CHECK 8042 FOR LAST COMMAND ACCEPTED
0133 B2 C9 SUB CX,CX ; SET WAIT TIME
0135 B0 2D MOV AL,2DH ; <><><><><><><><><><><>
0137 E6 80 OUT MFG_PORT,AL ; <><><>CHECKPOINT 2D <><><>
0139 E4 64 D13: IN AL,STATUS_PORT ; GET THE 8042 STATUS
013B A8 02 TEST AL,INPT_BUF_FULL ; HAS THE LAST COMMAND BEEN ACCEPTED?
013D 74 08 JZ E19 ; GO IF YES
013F E2 F8 LOOP D13 ; TRY AGAIN
;----- ERROR EXIT (MSG 105)
0141 BE 0000 E MOV SI,OFFSET CM4 ; PRINT 105 ERROR
0144 E9 004F R JMP D6A ; GO ERROR HALT

;----- TEST. 19
; ADDITIONAL READ/WRITE STORAGE TEST
; ++++ MUST RUN IN PROTECTED MODE +++
; DESCRIPTION
; READ/WRITE DATA PATTERNS TO ANY READ/WRITE
; STORAGE AFTER THE FIRST 64K. STORAGE
; ADDRESSABILITY IS CHECKED.
;----- ASSUME DS:DATA
E19: ASSUME DS:DATA
CALL DDS ; SET DATA SEGMENT
MOV AL,2FH ; <><><><><><><><><><><>
OUT MFG_PORT,AL ; <><><>CHECKPOINT 2F <><><>
;----- WARM START?
CMP RESET_FLAG,1234H ; WARM START?
JNE E19A ; GO IF NOT
JMP SHUT2 ; GO TO NEXT TEST IF WARM START
;----- SET SHUTDOWN RETURN 2
0147 E8 0000 E
014A B0 2F
014C E6 80
014E 81 3E 0072 R 1234
0154 75 03
0156 E9 0558 R
E19A: MOV AL,30H ; ADDR FOR SHUTDOWN BYTE
OUT MFG_PORT,AL ; SECOND ENTRY INTO TABLE
;----- SHUTDOWN
MOV AL,SHUT_DOWN ; IO DELAY
OUT CMOS_PORT,AL
MOV AL,00H
JMP SHORT $+2 ; CMOS_PORT+1,AL
;----- ENABLE PROTECTED MODE
0167 BC 0000
016A B8 DU
016C BC 8000
016F E8 0000 E
0172 B0 31
0174 E6 80
CALL SYSINIT1 ; GO ENABLE PROTECTED MODE
MOV AL,31H
OUT MFG_PORT,AL ; <><><><><><><><><><><>
;----- SET TEMPORY STACK
0176 B8 0008
0179 8E C0
017B 26: C7 06 005A 0000
0182 26: C6 06 005C 00
0184 B8 0058
0186 8E DC
018D BC FFFF
MOV AX,GDT_PTR ; SET STACK FOR SYSINIT1
MOV ES,AX
MOV SS,SP
MOV SP,POST_SP ;
CALL SYSINIT1 ; GO ENABLE PROTECTED MODE
MOV AL,31H
OUT MFG_PORT,AL ; <><><><><><><><><><><>
;----- DATA SEGMENT TO SYSTEM DATA AREA
0190 B8 0018
0193 8E DB
0195 B0 80
MOV AX,RSDA_PTR ; POINT TO DATA AREA
MOV DS,AX
MOV AL,PRTY_CHK ; SET CHECK PARITY

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0197 E6 87 OUT DMA\_PAGE+6, AL ; SAVE WHICH CHECK TO USE

;----- PRINT 64 K BYTES OK

0199 B8 0040 E20A: MOV AX, 16\*I ; STARTING AMT. OF MEMORY OK  
019C 50 PUSH AX ; SAVE MEMORY OK SIZE  
019D E9 0347 R JMP PRT\_SIZ ; POST MESSAGE

;----- IS CMOS GOOD?

01A0 B0 BE E20B: MOV AL, DIAG\_STATUS ; DETERMINE THE CONDITION OF CMOS  
01A2 E6 70 OUT CMOS\_PORT, AL  
01A4 E6 00 JMP SHORT S+2 ; IO DELAY  
01A6 E8 71 IN AL, CMOS\_PORT+1 ; GET THE CMOS STATUS  
01A8 50 PUSH AX ; SAVE CMOS STATUS

;----- GET THE MEMORY SIZE DETERMINED (PREPARE BX FOR BAD CMOS)

01A9 B0 B1 MOV AL, M\_SIZE\_HI ; GET THE HIGH BYTE  
01AD E6 70 OUT CMOS\_PORT, AL  
01AE E6 00 JMP SHORT S+2 ; IO DELAY  
01AF E4 71 IN AL, CMOS\_PORT+1 ; HIGH BYTE  
01B1 86 C4 XCHG AH, AL ; SAVE HIGH BYTE  
01B3 80 B0 MOV AL, M\_SIZE\_LO ; GET LOW BYTE  
01B5 E6 70 OUT CMOS\_PORT, AL  
01B7 E8 00 JMP SHORT S+2 ; IO DELAY  
01B9 E4 71 IN AL, CMOS\_PORT+1 ; LOW BYTE  
01BB 88 1E 00013 R MOV BX, MEMORY\_SIZE ; PRE LOAD THE MEMORY SIZE  
01BF 03 D8 ADD BX, AX ; SET TOTAL MEMORY SIZE  
01C1 89 1E 00017 R ADD WORD PTR KB\_FLAG, BX ; SAVE THE TOTAL SIZE  
01C5 58 POP AX ; RESTORE CMOS STATUS

01C6 A8 C0 TEST AL, 0COH ; CMOS OK?  
01C8 74 03 JZ E20B0 ; GO IF YES  
01CA E9 026E R JMP E20C ; DEFAULT IF NOT

E20B0: ;----- GET THE BASE 0->640K MEMORY SIZE FROM CONFIG IN CMOS

01CD B0 96 MOV AL, M\_SIZE\_HI ; GET THE HIGH BYTE  
01D1 E6 70 OUT CMOS\_PORT, AL  
01D3 E4 71 JMP SHORT S+2 ; IO DELAY  
01D5 86 E0 IN AL, CMOS\_PORT+1 ; HIGH BYTE  
01D7 B0 95 MOV AL, M\_SIZE\_LO ; SAVE HIGH BYTE  
01D9 E6 70 OUT CMOS\_PORT, AL ; GET LOW BYTE  
01DB E8 00 JMP SHORT S+2 ; IO DELAY  
01DD E4 71 IN AL, CMOS\_PORT+1 ; LOW BYTE  
01DF 39 06 00013 R CMP MEMORY\_SIZE, AX ; IS MEMORY SIZE GREATER THAN CONFIG?  
01E3 74 1C JZ E20B1 ; GO IF EQUAL

;----- SET MEMORY SIZE DETERMINE NOT EQUAL TO CONFIG

01E5 50 PUSH AX ; SAVE AX  
01E6 B0 BE MOV AL, DIAG\_STATUS ; ADDRESS THE STATUS BYTE  
01E8 E6 70 OUT CMOS\_PORT, AL  
01EA E8 00 JMP SHORT S+2 ; GET THE STATUS  
01EC E4 71 IN AL, CMOS\_PORT+1 ; SET CMOS FLAG  
01F0 86 C4 XCHG AH, AL ; SAVE AL

01F2 B0 BE MOV DIAG\_STATUS ; RESTORE AL  
01F4 E6 70 OUT CMOS\_PORT, AL ; IO DELAY  
01F6 86 C4 XCHG AH, AL ; RESTORE AX  
01F8 E8 00 JMP SHORT S+2 ; IS MEMORY SIZE GREATER THAN CONFIG?  
01FA E6 71 POP AX ; DEFAULT TO MEM SIZE DET IF YES  
01FD 39 06 00013 R CMP MEMORY\_SIZE, AX ; SET 640K MEMORY SIZE  
0201 77 6B E20B1: JA E20B0 ; CHECK IF BASE RAM LESS 512K  
0203 88 00 MOV BX, AX ; GO IF YES  
0205 4D 0201 CMP AX, 513 ; SET 640K BASE RAM BIT  
0208 72 16 JB NO\_640 ; TURN ON 640K BIT IF NOT ALREADY ON  
020A B0 B3 MOV AL, INFO\_STATUS ; SAVE THE CURRENT DIAG STATUS  
020C E6 70 OUT CMOS\_PORT, AL ; ADDR THE STATUS BYTE  
020E E8 00 JMP SHORT S+2 ; RESTORE THE STATUS  
0210 50 IN AL, CMOS\_PORT+1 ; IO DELAY  
0212 0C 80 OR AL, M640K ; GET THE CURRENT STATUS  
0214 86 C4 XCHG AL, AH ; TURN ON 640K BIT IF NOT ALREADY ON  
0216 B0 B3 MOV AL, INFO\_STATUS ; SAVE THE CURRENT DIAG STATUS  
0218 E6 70 OUT CMOS\_PORT, AL ; ADDR THE STATUS BYTE  
021A 86 C4 XCHG AL, AH ; RESTORE THE STATUS  
021C E8 00 JMP SHORT S+2 ; IO DELAY  
021E E6 71 OUT CMOS\_PORT+1, AL ; RESTORE AX

;----- CHECK MEMORY SIZE ABOVE 640K FROM CONFIG

0220 NO\_640: MOV AL, M2\_SIZE\_HI ; GET THE HIGH BYTE  
0222 E6 70 OUT CMOS\_PORT, AL  
0224 E8 00 JMP SHORT S+2 ; IO DELAY  
0226 E4 71 IN AL, CMOS\_PORT+1 ; HIGH BYTE  
0228 86 00 XCHG AH, AL ; SAVE HIGH BYTE  
022A E8 00 MOV AL, M\_SIZE\_LO ; GET LOW BYTE  
022C E6 70 OUT CMOS\_PORT, AL  
022E E8 00 JMP SHORT S+2 ; IO DELAY  
0230 E4 71 IN AL, CMOS\_PORT+1 ; LOW BYTE  
0232 88 C8 MOV CX, AX ; SAVE THE ABOVE 640K RAM SIZE

;----- ABOVE 640K RAM SIZE FROM MEMORY SIZE DETERMINE

0234 B0 B1 MOV AL, M\_SIZE\_HI ; GET THE HIGH BYTE  
0236 E6 70 OUT CMOS\_PORT, AL  
0238 E8 00 JMP SHORT S+2 ; IO DELAY  
023A E4 71 IN AL, CMOS\_PORT+1 ; HIGH BYTE  
023C E8 00 XCHG AH, AL ; SAVE HIGH BYTE  
023E B0 B0 MOV AL, M\_SIZE\_LO ; GET LOW BYTE  
0240 E6 70 OUT CMOS\_PORT, AL  
0242 E8 00 JMP SHORT S+2 ; IO DELAY  
0244 E4 71 IN AL, CMOS\_PORT+1 ; LOW BYTE

;----- CX=CONFIG CX-MEMORY SIZE DETERMINE

0246 3B C8 CMP CX, AX ; IS CONFIG EQUAL TO DETERMINED?  
0248 74 18 JZ SET\_MEM1 ; GO IF EQUAL

;----- SET MEMORY SIZE DETERMINE NOT EQUAL TO CONFIG

024A 50 PUSH AX ; SAVE AX  
024B B0 BE MOV AL, DIAG\_STATUS ; ADDRESS THE STATUS BYTE  
024D E6 70 OUT CMOS\_PORT, AL  
024F E8 00 JMP SHORT S+2 ; IO DELAY  
0251 E4 71 IN AL, CMOS\_PORT+1 ; GET THE STATUS  
0253 0C 10 DR AL, M\_SIZE\_HI ; SET CMOS FLAG  
0255 86 C4 XCHG AH, AL ; SAVE AL

0257 B0 BE MOV DIAG\_STATUS ; RESTORE AL  
0258 86 C4 XCHG AH, AL ; IO DELAY  
025D E8 00 JMP SHORT S+2 ; RESTORE AX  
025F E6 71 OUT CMOS\_PORT+1, AL ; RESTORE AX

0261 58 POP AX ; RESTORE AX

SET\_MEM1:

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0262 3B C8          CMP    CX, AX           ; IS CONFIG GREATER THAN DETERMINED?
0264 77 02          JA     SET_MEM         ; GO IF YES
0266 BB C8          MOV    CX, AX           ; USE MEMORY SIZE DETERMINE IF NOT
0267 00 00
0268 03 D9          SET_MEM
026A 89 1E 0017 R   MOV    WORD PTR KB_FLAG,BX ; SET TOTAL MEMORY SIZE
026E 83 EB 40        E20C: SUB   BX,16*4      ; SAVE TOTAL SIZE FOR LATER TESTING
0271 B1 06          MOV    CL,06H
0273 03 EB          SHR    BX,CL           ; 1ST 64K ALREADY DONE
0275 53             PUSH   BX             ; DIVIDE BY 54
0276 B8 0008          ; SAVE COUNT OF 64K BLOCKS
0279 8E C0          ;===== MODIFY DESCRIPTOR TABLES =====
027A 00 00
027B 26: C7 06 0048 FFFF  MOV    AX,GDT_PTR      ; MODIFY THE DESCRIPTER TABLE
027D 00 00
027E 26: C6 06 004D 93  MOV    ES,AX           ; SET TEMP ES DESCRIPTOR 64K SEGMENT LIMIT
027F 00 00
0280 26: C6 06 004C 00  MOV    ES:ES_TEMP.SEG_LIMIT,MAX_SEG_LEN
0281 26: C7 06 004A 0000 ;===== CPLO, DATA ACCESS RIGHTS
0282 00 00
0283 26: C6 06 004D 93  MOV    BYTE PTR ES:(ES_TEMP.DATA_ACC_RIGHTS),CPLO_DATA_ACCESS
0284 00 00
0285 26: C6 06 0004 00  ;===== START WITH SEGMENT 010000 (SECOND 64K)
0286 26: C7 06 0004A 0000 MOV    BYTE PTR ES:(ES_TEMP.BASE_HI_BYTE),0
0287 00 00
0288 26: C6 06 004C 00  MOV    ES:ES_TEMP.BASE_LO_WORD,0
0289 00 00
028A 26: C7 06 0060 FFFF  ;===== SET TEMP DS DESCRIPTOR 64K SEGMENT LIMIT
028B 00 00
028C 26: C6 06 0065 93  MOV    ES:DS_TEMP.SEG_LIMIT,MAX_SEG_LEN
028D 00 00
028E 26: C6 06 0064 00  ;===== CPLO, DATA ACCESS RIGHTS
028F 26: C7 06 0062 0000 MOV    BYTE PTR ES:(DS_TEMP.^_ACC_RIGHTS),CPLO_DATA_ACCESS
0290 00 00
0291 26: C7 06 0060 FFFF  ;===== START WITH SEGMENT 010000
0292 00 00
0293 26: C6 06 0064 00  MOV    BYTE PTR ES:(DS_TEMP.BASE_HI_BYTE),0
0294 26: C7 06 0062 0000 MOV    ES:DS_TEMP.BASE_LO_WORD,0
0295 00 00
0296 26: C7 06 0060 FFFF  ;===== TEMPORARY SEGMENT SAVE IN DMA PAGE REGISTER
0297 00 00
0298 26: C6 06 0064 00  MOV    SUB   AL,AL           ; HIGH BYTE OF LOW WORD OF SEGMENT
0299 26: C7 06 0062 0000 OUT   DMA_PAGE+4,AL       ; LOW BYTE OF LOW WORD OF SEGMENT
0300 00 00
0301 26: C6 06 0064 00  OUT   DMA_PAGE+5,AL       ; SET HIGH BYTE OF SEGMENT WORD
0302 26: C7 06 0062 0000 OUT   DMA_PAGE+3,AL       ; HIGH BYTE OF SEGMENT
0303 00 00
0304 26: C7 06 0060 FFFF  ;===== POINT TO NEXT BLOCK OF 32K WORDS
0305 00 00
0306 26: C6 06 0064 00  E21: MOV   AX,GDT_PTR      ; POINT TO START OF DESCRIPTOR TABLE
0307 26: C7 06 0062 0000 MOV   DS,AX           ; DS:AX
0308 00 00
0309 26: C6 06 0064 00  INC   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE)
0310 26: C7 06 0062 0000 INC   BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE)
0311 00 00
0312 26: C7 06 0060 FFFF  ;===== CHECK FOR END OF 256K PLANAR RAM
0313 00 00
0314 26: C6 06 0064 00  E21_0: CMP   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE),04H
0315 26: C7 06 0062 0000 JB    E21_0          ; GO IF STILL BASE RAM
0316 00 00
0317 26: C6 06 0064 00  PUSH  DS             ; SAVE THE CURRENT DATA SEGMENT
0318 26: C7 06 0062 0000 MOV   AX,RSDA_PTR    ; POINT TO POST DATA SEGMENT
0319 00 00
0320 26: C6 06 0064 00  MOV   DS,AX           ; GET THE JUMPER INFO
0321 26: C7 06 0062 0000 POP   DS             ; RESTORE_DS
0322 00 00
0323 26: C6 06 0064 00  TEST  AL,BASE_RAM     ; CHECK IF SECOND 256K ON BASE PLANAR
0324 26: C7 06 0062 0000 JB    E21_0          ; GO IF YES
0325 00 00
0326 26: C6 06 0064 00  MOV   AL,TOCHK        ; SET TO CHANNEL CHECK TEST
0327 26: C7 06 0062 0000 OUT   DMA_PAGE+6,AL
0328 00 00
0329 26: C7 06 0060 FFFF  ;===== CHECK END OF FIRST 516K OR 640K (END OF BASE RAM)
0330 00 00
0331 26: C6 06 0064 00  E21_0: MOV   AL,INFO_STATUS  ; SET 640K BASE RAM BIT
0332 26: C7 06 0062 0000 OUT   CMOS_PORT,AL      ; OUT
0333 00 00
0334 26: C6 06 0064 00  JMP   SHORT $+2        ; IO DELAY
0335 26: C7 06 0062 0000 IN    AL,CMOS_PORT+1    ; GET THE CURRENT STATUS
0336 00 00
0337 26: C7 06 0060 FFFF  ;===== CHECK FOR END OF 512K PLANAR RAM
0338 00 00
0339 26: C6 06 0064 00  E21_C: CMP   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE),08H
0340 26: C7 06 0062 0000 JB    E21_A          ; GO IF STILL BASE RAM
0341 00 00
0342 26: C6 06 0064 00  ;===== SET USE TEST IO CHECK
0343 00 00
0344 26: C6 06 0064 00  XCHG  AL,AH           ; SAVE AL
0345 26: C7 06 0062 0000 MOV   AL,IO_CHK        ; AL,IO_CHK
0346 00 00
0347 26: C6 06 0064 00  OUT   DMA_PAGE+6,AL       ; RESTORE AL
0348 26: C7 06 0062 0000 XCHG  AL,AH
0349 00 00
0350 26: C7 06 0060 FFFF  ;===== CHECK FOR 640K BASE RAM (128K IO CARD)
0351 00 00
0352 26: C6 06 0064 00  E12_A: TEST  AL,M640K        ; IS 640K BASE INSTALLED?
0353 26: C7 06 0062 0000 JZ    E12_B          ; GO IF NO
0354 00 00
0355 26: C6 06 0064 00  CMP   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE),0AH
0356 26: C7 06 0062 0000 JNZ   NEXT1         ; CONTINUE
0357 26: C7 06 0062 0000 JMP   E12_C
0358 00 00
0359 26: C6 06 0064 00  E12_B: CMP   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE),08H
0360 26: C7 06 0062 0000 JNZ   NEXT1
0361 00 00
0362 26: C7 06 0060 FFFF  ;===== DO ADDITIONAL STORAGE ABOVE 1 MEG
0363 00 00
0364 26: C6 06 0064 00  E12_C: MOV   BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE),10H
0365 26: C7 06 0062 0000 MOV   BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),10H
0366 00 00
0367 26: C7 06 0060 FFFF  ;===== SAVE BASE_HI_BYTE IN DMA PAGE REGISTERS 3
0368 00 00
0369 26: C6 06 0064 00  NEXT1: MOV   AL,BYTE PTR DS:(DS_TEMP.BASE_HI_BYTE)
0370 26: C7 06 0062 0000 OUT   DMA_PAGE+3,AL       ; SAVE THE HIGH BYTE OF SEGMENT
0371 00 00
0372 26: C7 06 0060 FFFF  ;===== FOR POSSIBLE ERROR
0373 00 00
0374 26: C6 06 0064 00  CMP   BYTE PTR DS:(ES_TEMP.BASE_HI_BYTE),0FEH ; TOP OF RAM?
0375 26: C7 06 0062 0000 JNZ   NEXT2         ; GO IF NOT
0376 26: C7 06 0062 0000 JMP   KB_LOOP3      ; GO NEXT TEST
0377 00 00
0378 26: C7 06 0060 FFFF  ;===== SET ES AND DS REGISTERS
0379 00 00
0380 26: C6 06 0064 00  031A: 80 3E 004C FE
0381 26: C7 06 0062 0000 031F: 75 03
0382 26: C6 06 0064 00  0321: EB 66 90

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0324 B8 0060      NEXT: MOV    AX,DS_TEMP
0327 8E D8        MOV    DS_AX
0329 B8 0048      MOV    AX,ES_TEMP
032C 8E C0        MOV    ES_AX

032E B0 31        MOV    AL,31H
0330 E6 80        OUT   MFG_PORT_AL ;>>><<<>><<<>><<<>>
; SET COUNT FOR 32K WORDS
0332 B9 8000      MOV    CX,2000H*4
0335 E8 0000 E     CALL   STGTST_CNT
0336 F0 03        JZ    N1
033A E9 047D R    JMP    E21A
033D 59          POP   CX
033E 58          POP   AX
N1:              POP   CX
                POP   AX
                ; RECOVER TESTED MEMORY

;----- WRITE THE CURRENT SIZE FOR (ADDRESS LINE 23-17 TEST) USED LATER
033F 2B FF        SUB   DI,DI
0341 AB          STOSW
; POINT TO BEGINNING OF A BLOCK
; WRITE THE CURRENT SIZE
; AT THE STARTING ADDRESS
0342 05 0040      ADD   AX,16*4
0344 20          PUSH  AX
0346 51          PUSH  CX
; SAVE TESTED MEMORY
; SAVE LOOP COUNT

0347 PRT_SIZE:    PUSH  AX
0347 50          MOV    BX,10
; SET DECIMAL CONVERT
0348 BB 000A      ;----- CONVERT AND SAVE
034E 2B FF        MOV    CX,5
; OF 5 NIBBLES XX,XXX KB
0350 33 D2        SUB   DI,DI
; CRT BUFFER POSITION
0352 54 F3        XOR   DX,DX
; DIVIDE BY 10
0354 80 CA 30      DIV   DX
; MAKE INTO ASCII
0357 52 F6        OR    DL,30H
; SAVE
0358 E2 F6        PUSH  DX
; DECIMAL_LOOP
0359 B9 0005      LOOP  CX
;----- DISPLAY LAST OK MEMORY
035A 58          MOV    CX,5
035B 0000 E       PRT_DEC_LOOP:
035E E8 0000 E     POP   AX
; RECOVER A NUMBER
0361 47          CALL   PROT_PRT_HEX
0362 E2 F9        INC   DI
; POINT TO CRT BUFF
0364 B9 0006 E     LOOP  PRT_DEC_LOOP
0367 BE 0000 E     MOV    CX,6
036A 2E 8A 04      MOVS SI,OFFSET F3B
; PRINT ' KB OK'
036B 46          POP   AX
036C E8 0000 E     CALL   PROT_PRT_HEX
0371 47          INC   DI
; INCREMENT BUFF PTR
0372 E2 F6        LOOP  KB_LOOP
0374 58          POP   AX
; RECOVER WORK REGS
0375 3D 0040      CMP   AX,16*4
; FIRST PASS?
0378 75 03        JNZ   KB_LOOP1
; GO IF NOT
037A E9 01A0 R    JMP   E20B
037D 59          POP   CX
; RECOVER 64K BLOCK COUNT
037E 58          POP   AX
;----- KB_LOOP1:
037F E2 03        LOOP  KB_LOOP2
0381 EB 06 90      JMP   KB_LOOP3
; CONTINUE
0384 KB_LOOP2:    PUSH  AX
0385 50          PUSH  CX
;----- KB_LOOP3:
0386 E9 02B9 R    JMP   E21
;----- CALCULATE NUMBER OF 64K BLOCKS
0389 B8 0040      MOV    AX,64
;----- ADDRESS LINE 16-23 TEST
038C 50          PUSH  AX
;----- CALCULATE NUMBER OF 64K BLOCKS
0389 B8 0018      MOV    AX,RSDA_PTR
; GET THE MEMORY SIZE
0390 8E D8        MOV    DS_AX
;----- INITIALIZATION
0392 B8 1E 0017 R MOV    BX,WORD PTR KB_FLAG
; GET THE TOTAL MEMORY SIZE
0396 83 EB 40      SUB   BX,64
; KB_FLAG USED AS TEMP STORAGE
0397 B1 06          MOVS CL,06H
; START AT SECOND 64K BOUNDARY
0398 B3 E8         SHR   BX,CL
; DIVIDE BY 64K
0390 53          PUSH  BX
;----- INITIALIZATION DS DESCRIPTOR
039E B8 0008      MOV    AX,GDT_PTR
03A1 8E C0        MOV    ES_AX
03A3 25: C6 06 0064 00 MOV    BYTE PTR ES:(DS_TEMP,BASE_HI_BYTE),0
03A9 26: C7 06 0062 0000 MOV    ES:DS_TEMP,BASE_LO_WORD,0
;----- TEMPORARY SEGMENT SAVE IN DMA PAGE REGISTER
03B0 2A C0        SUB   AL,AL
03B2 E6 85        OUT   DMA_PAGE+4,AL
; HIGH BYTE OF LOW WORD OF SEGMENT
03B4 E6 B6        OUT   DMA_PAGE+5,AL
; LOW BYTE OF LOW WORD OF SEGMENT
03B6 B0 01        MOV    AL,01H
; SET HIGH BYTE OF SEGMENT WORD
03B8 E6 84        OUT   DMA_PAGE+3,AL
; HIGH BYTE OF SEGMENT

;----- POINT TO NEXT BLOCK OF 64K
03BA E21_A:       MOV    AL,33H
;----- CHECK END OF FIRST 516K OR 640K (END OF BASE RAM)
03BC B0 33        OUT   MFG_PORT_AL
;----- CHECKPOINT 33 <<<>><<<>>
03BD E6 80        ADD   BYTE PTR ES:(DS_TEMP,BASE_HI_BYTE),01
;----- CHECK FOR END OF 512K PLANAR RAM
03CE B0 B3        MOV    AL,INFO_STATUS
; SET 640K BASE RAM BIT
03C6 E6 70        OUT   CMOS_PORT_AL
;----- CHECKPOINT 33 <<<>><<<>>
03C8 EB 00        JMP    SHORT_S2
; IO DELAY
03CA E8 71        IN    AL,CMOS_PORT+1
; GET THE CURRENT STATUS
03CC A8 00        TEST  AL,A640K
; CHECK FOR 640K BASE RAM
03CE 74 0B        JZ    NEXT_A1
; GO IF ONLY 512K

;----- CHECK FOR END OF 512K PLANAR RAM
03D0 26: 80 3E 0064 0A CMP   BYTE PTR ES:(DS_TEMP,BASE_HI_BYTE),0AH
03D6 75 15        JNZ   NEXT_A1
; GO IF STILL BASE RAM
03D8 EB 09 90      JMP   NEXT_A2
;----- CHECKPOINT 33 <<<>><<<>>
03DB 26: 80 3E 0064 0B NEXT_A1: CMP   BYTE PTR ES:(DS_TEMP,BASE_HI_BYTE),0BH
03E1 75 0A        JNZ   NEXT_A
;----- CHECKPOINT 33 <<<>><<<>>

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;----- DO ADDITIONAL STORAGE ABOVE 1 MEG
03E3 26: C6 06 0064 10      NEXT_A2:MOV     BYTE PTR ES:(DS_TEMP.BASE_HI_BYTE),10H
;----- SET USE TEST IO CHECK
03E9 80 40      MOV     AL,10_CHK
03EB E6 87      OUT    DMA_PAGE+6,AL      ;
03ED 26: A0 0064      NEXT_A: MOV     AL,BYTE PTR ES:(DS_TEMP.BASE_HI_BYTE)
;----- DMA PAGE REGISTERS 3
03F1 E6 84      OUT    DMA_PAGE+3,AL      ; SAVE THE HIGH BYTE OF SEGMENT
;----- FOR POSSIBLE ERROR
;----- CHECK FOR TOP OF RAM (FE0000) 16MEG
03F3 26: 80 3E 0064 FE      CMP    BYTE PTR ES:(DS_TEMP.BASE_HI_BYTE),0FEH ; TOP OF RAM?
03F9 75 03      JNZ    KB_LOOP_3        ; GO IF NOT
03FB EB 79 90      JMP    KB_LOOP_3        ; GO NEXT TEST
;----- SET DS REGISTER
03FE B8 0060      NEXT_B: MOV     AX,DS TEMP
0401 BE 08      MOV     DS,AX
0403 2B FF      SUB    DI,DI
0405 BB 05      MOV     AX,DS:[DI]      ; POINT TO START OF BLOCK
0407 BB D0      MOV     DX,AX      ; GET THE VALUE OF THIS BLOCK
0409 BB F7      MOV     SV,DI      ; SAVE
040B BB C0      SUB    AX,AX      ; SET SI FOR POSSIBLE ERROR
040D BB 05      MOV     DS:[DI],AX      ; CLEAR RAM LOCATION
;----- ALLOW CRT TIME TO DISPLAY MSG
040F 2B C9      SUB    CX,CX
0411 E2 FE      Z2:   LOOP   Z2          ; GET THE LOOP COUNT
0413 55          PUSH   AX          ; RECOVER TESTED MEMORY
0414 58          POP    AX          ; SAVE TESTED MEMORY
0415 50          PUSH   CX          ; SAVE LOOP COUNT
0416 51          PUSH   CX          ; DOES THE BLOCK ID MATCH
0417 3B C2      CMP    AX,DX      ; OR THE BLOCK ID FOR POSSIBLE ERROR
0418 80 C2      MOV    AX,DX
0419 75 60      JNZ    E21A        ; GO PRINT ERROR
041D 59          POP    CX          ; POP CX TO GET AX
041E 58          POP    AX          ; RECOVER TESTED MEMORY
041F 05 0040      ADD    AX,64      ; 64K INCREMENTS
0422 50          PUSH   AX          ; SAVE TESTED MEMORY
0423 51          PUSH   CX          ; SAVE LOOP COUNT
0424 50          PUSH   AX          ; SET DECIMAL CONVERT
0425 BB 000A      MOV    BX,10
;----- CONVERT AND SAVE
0428 B9 0005      MOV    CX,5      ; OF 5 NIBBLES XX,XXX KB
042B 2B FF      SUB    DI,DI      ; CRT BUFFER POSITION
042D 33 D2      DEC_LOOP: XOR   DX,DX
042F F7 F3      DIV    BX,10      ; DIVIDE BY 10
0431 80 CA 30      OR    DL,30H      ; MAKE INTO ASCII
0434 52          PUSH   DX          ; SAVE
0435 E2 F6      LOOP   DEC_LOOP
;----- DISPLAY LAST OK MEMORY
0437 B9 0005      MOV    CX,5      ; PRINT ' KB OK'
043A 58          PRT_DEC: POP   AX          ; RECOVER A NUMBER
043B E8 0000 E      CALL   PROT_PRT_HEX
043E 47          INC    DI          ; POINT TO CRT BUFF
043F E2 F9      LOOP   PROT_DEC
0441 B9 0006      MOV    CX,6
0444 BE 0000 E      MOV    SI,[OFFSET F3B] ; PRINT ' KB OK'
0447 KB_LOOP_1:  MOV    AL,CS:[SI]
044A 46          INC    SI          ; INCREMENT BUFF PTR
044B E8 0000 E      CALL   PROT_PRT_HEX
044C 47          IN     D1          ; RECOVER WORK REGS
044F E2 F6      LOOP   KB_LOOP_1
0451 58          POP    AX          ; RECOVER 64K BLOCK COUNT
0452 59          POP    CX
0453 58          POP    AX
0454 E2 1B      LOOP   KB_LOOP_2
;----- CHECK PARITY
0456 E6 89      OUT    DMA_PAGE+8,AL      ; SAVE AX
0458 B6 C4      XCHG   AL,AL
045A 86 8A      OUT    DMA_PAGE+9,AL
045C E4 11      IN     AL,PORT_B      ; CHECK FOR IO OR PAR CHECK
045E 24 C0      AND    AL,PARITY_ERR
0460 B6 C4      XCHG   AL,AH      ; STRIP UNWANTED BITS
0462 E4 87      IN     AL,DMA_PAGE+6      ; SAVE ERROR
0464 22 E0      AND    AH,AL      ; CHECK FOR R/W OR IO ERR
0466 B6 C4      XCHG   AL,AL
0468 B6 C4      IN     AL,DMA_PAGE+9
046A E4 89      XCHG   AL,AH
046C 75 0F      JNZ    E21A        ; RESTORE AX
;----- GO IF PARITY ERROR
046E EB 06 90      KB_LOOP_2:  JMP    KB_LOOP_3      ; CONTINUE
0471 50          PUSH   AX          ; SAVE LOOP COUNT
0472 51          PUSH   CX
0473 E9 03BA R      JMP    E21_A        ; CONTINUE TILL DONE
;----- BACK TO REAL MODE
0476 KB_LOOP_3:  MOV    AL,34H      ;<><><><><><><><><>
0478 E6 80      OUT    MFG_PORT,AL      ;<><><>CHECKPOINT 34 <><>
047A E9 0000 E      JMP    PROC_SHUTDOWN ; BACK TO REAL MODE
;----- NEXT TEST VIA JUMP TABLE (SHUT2)
;----- PRINT FAILING ADDRESS AND XOR'ED PATTERN IF DATA COMPARE ERROR
;----- USE DMA PAGE REGISTERS AS TEMPORARY SAVE AREA FOR ERROR
;----- SET SHUTDOWN 3
E21A:  OUT    DMA_PAGE+1,AL      ; SAVE FAILING BIT PATTERN (LOW BYTE)
047D E6 82      MOV    AL,AH      ; SAVE HIGH BYTE
047F 6A C4      JMP    SHORT $+2      ; IO DELAY
0481 EB 00      OUT    DMA_PAGE+2,AL
0483 E6 83      MOV    AX,SI      ; GET THE FAILING OFFSET
0485 BB C6      OUT    DMA_PAGE+5,AL
0487 E6 86      XCHG   AH,AL
0489 B6 E0      JMP    SHORT $+2      ; IO DELAY
048B EB 00      OUT    DMA_PAGE+4,AL

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;----- CLEAR IO CH CHK OR R/W PAR CHK
048F 2B F6          SUB    SI,SI          ; WRITE TO FAILING BLOCK
0491 AB            STOSW             ; 
0492 E4 61          IN     AL,PORT_B      ; 
0494 0C 0C          OR     AL,RAM_PAR_OFF   ; TOGGLE IO/PAR CHECK ENABLE
0496 EB 00          JMP    SIORT_S+2      ; IO DELAY
0498 E6 61          OUT    PORT_B,AL      ; 
049A EB F3          AND    AL,RAM_PAR_ON   ; 
049C EB 00          JMP    SIORT_S+2      ; IO DELAY
049E E6 61          OUT    PORT_B,AL      ; 

;===== SET MEMORY SIZE =====
04A0 B8 0018          MOV    AX,RSDA_PTR  ; SET THE DATA SEGMENT
04A3 8E D8            MOV    DS,AX          ; IN PROTECTED MODE

;----- GET THE DIAG_STATUS FROM CMOS
04A5 B0 8E          MOV    AL,DIAG_STATUS  ; 
04A7 E6 70          OUT   CMOS_PORT,AL    ; 
04A9 EB 00          JMP    SIORT_S+2      ; IO DELAY
04AB E4 71          IN    AL,CMOS_PORT+1  ; 
04AD 8A D8          MOV    BL,AL          ; SAVE THE STATUS BYTE

04AF B0 B3          MOV    AL,INFO_STATUS  ; 
04B1 E6 70          OUT   CMOS_PORT,AL    ; 
04B3 EB 00          JMP    SIORT_S+2      ; IO DELAY
04B5 E4 71          IN    AL,CMOS_PORT+1  ; 
04B7 8A F8          MOV    BH,AL          ; SAVE THE STATUS BYTE

;----- GET THE LAST OF GOOD MEMORY
04B9 59            POP   CX              ; 
04BA 58            POP   AX              ; GET THE LAST OF GOOD MEMORY
04BB B8 C8          MOV    CX,AX          ; SAVE IT

;----- BELOW 512K?
04BD 3D 0200          CMP   AX,512        ; LAST GOOD MEMORY BELOW 512K?
04C0 72 39          JB    M3            ; GO IF YES

;----- BELOW 640K?
04C2 3D 0280          CMP   AX,640        ; LAST GOOD MEMORY BELOW 640K?
04C5 72 11          JB    M1            ; GO IF YES

;----- 640K UP ERROR
04C7 F6 C7 80          TEST  BH,M640K      ; IS BASE RAM 640K
04CA 75 06          JNZ   MO            ; 
04CC 2D 0200          SUB   AX,512        ; 512K BASE RAM
04CD 75 90          JNZ   M2            ; 
04D2 2D 0280          MO    SUB AX,640      ; 640K BASE RAM
04D5 EB 09 90          JMP   M2            ; 

;----- 512K TO 640K ERROR
04D8 F6 C7 80          M1:   TEST  BH,M640K      ; IS BASE RAM 640K?
04DB 75 1E          JNZ   M3            ; GO IF YES
04DD 2D 0200          SUB   AX,512        ; STRIP BASE RAM FROM 10 RAM

;----- WRITE SIZE TO CMOS
04E0 B8 C8          M2:   MOV   CX,AX          ; SAVE ADJUSTED MEMORY SIZE
04E2 B8 01          MOV   AL,SIZE_HI      ; 
04E4 E6 70          OUT   CMOS_PORT,AL    ; 
04E6 8A C5          MOV   AL,CH          ; GET THE HIGH BYTE MEMORY SIZE
04E8 EB 00          JMP   SIORT_S+2      ; IO DELAY
04EA E6 71          OUT   CMOS_PORT+1,AL  ; WRITE IT
04EC B0 B0          MOV   AL,SIZE_LO      ; DO THE LOW BYTE
04EF E6 00          JMP   SIORT_S+2      ; 
04F0 E6 70          OUT   CMOS_PORT,AL    ; 
04F2 8A C1          MOV   AL,CL          ; GET THE LOW BYTE
04F4 EB 00          JMP   SIORT_S+2      ; IO DELAY
04F6 E6 71          OUT   CMOS_PORT+1,AL  ; WRITE IT
04F8 EB 04 90          JMP   M4            ; CONTINUE

;----- SET BASE MEMORY SIZE
04FB A3 0013 R         M3:  MOV   MEMORY_SIZE,AX  ; TO INDICATE HOW MUCH MEM WORKING

;----- SET SHUTDOWN 3
04FE B0 8F          M4:   MOV   AL,SHUT_DOWN  ; ADDR FOR SHUTDOWN RETURN
0500 E6 70          OUT   CMOS_PORT,AL    ; 
0502 B0 03          MOV   AL,3            ; SET RETURN 3
0504 EB 00          JMP   SHORT_S+2      ; IO DELAY
0506 E6 71          OUT   CMOS_PORT+1,AL  ; 

;----- SHUTDOWN
0508 E9 0000 E         PAGE  PROC_SHUTDOWN  ; 
;----- ENTRY 3 FROM PROCESSOR SHUTDOWN

;----- MEMORY REPORTING
;----- DESCRIPTION FOR ERRORS 201(CMP ERROR or PARITY)
;----- or 202(ADDRESS LINE 0-15 ERROR)
;----- R/W MEMORY ERRORS WILL BE REPORTED AS FOLLOWS
;----- AA=HIGH BYTE OF 24 BIT ADDRESS
;----- BB=MIDDLE BYTE OF 24 BIT ADDRESS
;----- CC=LOW BYTE OF 24 BIT ADDRESS
;----- DD=HIGH BYTE OF XOR FAILING BIT PATTERN
;----- EE=LOW BYTE OF XOR FAILING BIT PATTERN

;----- DESCRIPTION FOR ERROR 202 (ADDRESS LINE 00-15)
;----- A WORD OF FFFF IS WRITTEN AT THE FIRST WORD AND LAST WORD
;----- OF EACH 64K BLOCK WITH ZEROS AT ALL OTHER LOCATIONS OF THE
;----- BLOCK. A SCAN OF THE BLOCK IS MADE TO INSURE ADDRESS LINE
;----- 0-15 ARE FUNCTIONING.

;----- DESCRIPTION FOR ERROR 203 (ADDRESS LINE 16-23)
;----- AT THE LAST PASS OF THE STORAGE TEST, FOR EACH BLOCK OF
;----- 64K, THE CURRENT STORAGE SIZE (ID) IS WRITTEN AT THE FIRST
;----- WORD OF EACH BLOCK. IT IS USED TO DETERMINE ADDRESSING
;----- FAILURES.

;----- AABBCC DDEE 203
;----- SAME AS ABOVE EXCEPT FOR DDEE

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;<>> VIRTUAL MODE FAILED<><>
056F E8 0000 E          CALL    E_MSG           ; PRINT MSG
0572 EB 09 90            JMP     SHUT6          ; PRINT MSG
0575 E8 0000 E          SHUT7B: CALL E_MSG
0578 80 0E 0016 R 04      OR     MFG_ERR_FLAG+1, LMCS_FAIL; <><><><><><><><><>
                                                ;<><> LOW MEG CHIP SELECT <><>

;----- PROTECTED MODE TEST PASSED ENTRY FROM A SHUTDOWN
057D E8 0000 E          SHUT6: CALL DDS          ; PROTECTED MODE STATE PASSED
0580 28 C0              SUB    AX,AX          ; CLEAR KEYBOARD STATE FLAGS
0582 A3 0017 R          MOV    WORD PTR KB_FLAG,AX
0585 B9 000E             MOV    CX, OEH        ; CLEAR PAGE REGS
0588 BA 0082            MOV    DX, DMA_PAGE+1
058B F7 00               CLR_LOOP: SUB AL, AL
058C 2A C0              DUT    DX, AL
058D EE                INC    DX
058E 42                LOOP   CLR_LOOP
058F E2 FA

;----- TEST_21
;----- KEYBOARD TEST
;----- DESCRIPTION
;----- RESET THE KEYBOARD AND CHECK THAT SCAN CODE AA' IS RETURNED TO THE CPU.
;----- CHECK FOR STUCK KEYS.

0591 B0 35              MOV    AL, 35H          ;<><><><><><><><><>
0593 E6 80              OUT   MFG_PORT, AL; <><><>CHECKPOINT 35 <><>
0595 F6 06 0012 R 20      TEST   MFG_TST, LOOP_POST ; MANUFACTURING BURN IN TEST MODE?
059A 75 03              JNZ   F7_A
059C E9 0651 R          JMP   F7_A
059F 80 3E 0072 R 64      F7_A: CMP  BYTE PTR RESET_FLAG, 064H ; YES - SKIP KEYBOARD TEST
05A0 75 01              JNZ   F7_B
05A2 E9 0651 R          JMP   F7_B
05A9 B0 36              MOV    AL, 36H          ; YES - SKIP KEYBOARD TEST
05AB E6 80              OUT   MFG_PORT, AL; <><><>CHECKPOINT 36 <><>
05AD FA
05AE B1 3E 0072 R 1234
05B0 74 01              CMP   RESET_FLAG, 1234H ; SOFT RESET?
05B2 00 3E 0072 R AA      JZ    G10
05B8 74 10              CMP   G10, OAAH        ; CHECK FOR AA ALREADY RECEIVED
05BD B0 AE              MOV    AL, ENA_KBD
05BF E8 0000 E          CALL  C8042          ; ENABLE KEYBOARD
05C2 B7 00              MOV    BH, 4           TRY 4 TIMES
05C4 E8 0000 E          CALL  C8042          ; CHECK FOR OUTPUT BUFFER FULL
05C7 75 04              JNZ   G10
05C9 FE CF              DEC    BH
05CB 75 F7              JNZ   LOOP1
05CD B0 AD              G10: MOV   AL, 35H_S_KBD ; DISABLE KEYBOARD
05DE F4 0000 E          CALL  C8042
05D2 E6 60              IN    AL, PORT_A       FLUSH
05D4 B0 E0              MOV   AL, KYBD_CLK_DATA
05D6 E8 0000 E          CALL  C8042          ; GET THE CLOCK AND DATA LINES
05D9 E8 0000 E          CALL  C8042          ; WAIT FOR OUTPUT BUFFER FULL
05DC E6 60              IN    AL, PORT_A       ; GET THE RESULTS
05E1 40 01              TEST  KYBD_CLK ; KEYBOARD CLOCK MUST BE LOW
05E0 74 0B              JZ    G11
05E2 80 0E 0016 R 08      OR    MFG_ERR_FLAG+1, KYCLK_FAIL; <><><><><><><><>
05E7 BE 0000 E          MOV   S1, OFFSET F1_B ;<><> KEYBOARD CLOCK HIGH<><>
05EA E8 62 90            JMP   FGD
05FB E8 0000 E          G11: CALL  C8042_RESET ; ISSUE RESET TO KEYBRD
05FD E3 28              JCXZ  FC
05F2 B0 37              MOV   AL, 37H          ; ISSUE RESET TO KEYBRD
05F4 E6 80              OUT   MFG_PORT, AL; <><><>CHECKPOINT 37 <><>
05F6 80 FB AA            CMP   BL, OAAH        ; SCAN CODE AS EXPECTED?
05F9 75 1F              JNE   F6
                                                ; NO - DISPLAY ERROR MSG

;----- CHECK FOR STUCK KEYS
05FB B0 38              MOV   AL, 38H          ;<><><><><><><><>
05FD E6 80              OUT   MFG_PORT, AL; <><><>CHECKPOINT 38 <><>
05FF B0 AE              MOV   AL, ENA_KBD
0601 E8 0000 E          CALL  C8042          ; ASSURE KEYBOARD ENABLED
0604 28 C9              SUB   CX, CX          ; ISSUE THE COMMAND
0606 E2 FE              LOOP  F5
0608 E4 64              IN    AL, STATUS_PORT ; DELAY FOR A WHILE
060A A6 01              TEST  AL, OUT_BUF_FULL ; CHECK FOR STUCK KEYS
060C 74 43              JE    F7
                                                ; OUT BUFFER FULL?
                                                ; YES - CONTINUE TESTING

060E B0 39              MOV   AL, 39H          ;<><><><><><><><>
0610 E6 80              OUT   MFG_PORT, AL; <><><>CHECKPOINT 39 <><>
0612 E4 60              IN    AL, PORT_A       ; GET THE SCAN CODE
0614 E8 0000 E          CALL  XPC_BYTEx ; CONVERT AND PRINT
0617 EB 2D 90            JMP   F6C
                                                ; CONTINUE

;----- KEYBOARD ERROR TRY TO DETERMINE IF 8042 INTERFACE IS WORKING
F6: CLI
0618 B0 AB              MOV   AL, INTR_FACE_CK ; COMMAND TO 8042
061D E6 64              OUT   STATUS_PORT, AL
061F 2B C9              SUB   CX, CX
0620 01 05              MOV   S1, 0105
0623 E8 64              F6A: IN    AL, STATUS_PORT ; WAIT FOR OUTPUT BUFFER FULL
0625 A8 01              TEST  AL, OUT_BUF_FULL ; 8042 FINISHED TEST?
0627 E1 FA              LOOPZ F6A
0629 75 0A              JNZ   F6A
0630 FE CF              DEC   BH
0632 40 F4              JNZ   F6A
062F BE 0000 E          MOV   S1, OFFSET F1_A ; TRY AGAIN
0632 EB 1A 90            JMP   F6D
0635 E4 60              F6B: IN    AL, PORT_A ; INDICATE PLANAR FAILURE
0637 3C 00              CMP   AL, 0           ; (REMOVE KEYBOARD TRY AGAIN)
0639 74 0B              JZ    F6C
063B 80 0E 0016 R 10      OR    MFG_ERR_FLAG+1, KY_SYS_FAIL; <><><><><><><><>
0640 BE 0000 E          MOV   S1, OFFSET F1_A ;<><> KEYBOARD/SYSTEM<><>
0643 EB 09 90            JMP   F6D
0646 BE 0000 E          F6C: MOV   S1, OFFSET F1 ; GO IF YES
                                                ; GET MSG ADDR

0649 80 0E 0016 R 20      OR    MFG_ERR_FLAG+1, KYBD_FAIL; <><><><><><><><>
064E E8 0000 E          F6D: CALL  E_MSG           ; PRINT MSG ON SCREEN

;----- INITIALIZE 8042 TO HONOR KEY LOCK

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0651 B0 3A
0653 E6 80
0655 B0 FF
0656 F0 21
0659 FA
065A B0 60
065C E8 0000 E
065F B0 45
0661 E6 60
F7: MOV AL,3AH ;<><><><><><><><><>
OUT MFG_PORT,AL ;<><>CHECKPOINT 3A <><><>
MOV AL,0FFH ; DISABLE INTERRUPTS
INTA01,AL ;
CLI
MOV AL,60H ; WRITE 8042 RAM COMMAND
CALL CS0H2 ; ISSUE THE COMMAND
MOV AL,45H ; SET SYSTEM FLAG - OUTBUF INT -
OUT PORT_A,AL ; SYSTEM FLAG - PC 1 COMPATABILITY
; RESET INHIBIT OVER RIDE

;----- DEGATE ADDRESS LINE 20
0663 B4 DD
0665 E8 0000 E
MOV AH,DISABLE_BIT20 ; SET COMMAND IN AH
CALL GATE_A20 ; ISSUE THE COMMAND

;----- SETUP HARDWARE INT VECTOR TABLE LVL 0-7
0668 2B C0
066A B8 C0
066C B9 0008
066D 0E
0670 1F
0671 BF 0000 E
0674 BF 0020 R
0677 A5
0678 47
0679 47
067A E2 FB
SUB AX,AX ; ; GET VECTOR CNT
MOV ES,AX ; ; SETUP DS SEG REG
PUSH CS
POP DS
MOV SI,OFFSET VECTOR_TABLE
MOV DI,OFFSET INT_PTR
F7A: MOVSW INC DI ; SKIP OVER SEGMENT
INC DI
LOOP F7A

;----- SETUP HARDWARE INT VECTOR TABLE LVL 8-15 (VECTORS START AT INT 50H)
067C 2B C0
067E B8 C0
0680 B9 0008
0683 0E
0684 1F
0685 BE 0000 E
0687 00 01C0 R
0688 A5
068C 47
068D 47
068E E2 FB
SUB AX,AX ; ; GET VECTOR CNT
MOV ES,AX ; ; SETUP DS SEG REG
PUSH CS
POP DS
MOV SI,OFFSET SLAVE_VECTOR_TABLE
MOV DI,OFFSET SLAVE_INT_PTR
F7A1: MOVSW INC DI ; SKIP OVER SEGMENT
INC DI
LOOP F7A1

;----- SET UP OTHER INTERRUPTS AS NECESSARY
0690 2B C0
0692 0E
0693 C7 06 0008 R 0000 E
0694 C7 06 0014 R 0000 E
069A C7 06 0062 R F600
ASSUME DS:ABSO
SUB AX,AX ; DS=0
MOV DS,AX ; DS=0
MOV NMI_PTR,OFFSET NMI_INT ; NMI_INTERRUPT
MOV INT_PTR,OFFSET PRINT_SCREEN ; PRINT SCREEN
MOV BASIC_PTR+2,0F600H ; SEGMENT FOR CASSETTE BASIC

;----- ZERO RESERVED VECTORS
06A6 BF 0180
06A9 B9 000E
06AC C7 05 0000
06B0 83 C7 02
06B3 E2 F7
MOV DI,60H*4 ; INT 60 THRU 67 FILL WITH ZERO
MOV CX,14 ; CLEAR 14 WORDS
F7A2: MOV WORD PTR DS:[DI],0 ; POINT TO NEXT LOCATION
ADD DI,2
LOOP F7A2

;----- SETUP TIMER 0 TO BLINK LED IF MANUFACTURING TEST MODE
06B5 F6 06 0412 R 20
06B8 75 0A
06BC C7 06 0020 R 0000 E
06C2 B0 FE
06C4 E6 21
06C6 FB
TEST DATA_AREA[MFG_TST-DATA_base],LOOP_POST ; MFG. TEST MODE?
JNZ F9 ; SETUP TIMER INTR TO BLINK LED
MOV INT_ADDR,OFFSET BLINK_INT ; ENABLE TIMER INTERRUPT
MOV AL,0FEH
OUT INT01,AL
F9: STI ; ALLOW INTERRUPTS

06C7 E8 0000 E
ASSUME DS:DATA
CALL DDS ; ESTABLISH DATA SEGMENT
; THE OPERATING SYSTEM

;----- ISSUE A RESET TO THE HARD FILE IF SOFT RESET
06CA 81 3E 0072 R 1234
06D0 75 0E
06D2 B9 00FF
06D3 B0 03F6
06D8 B0 04
06DA EE
06DB E2 FE
06DD 2A C0
06DF EE
CMP RESET_FLAG,1234H ; SOFT RESET?
JNZ F9A ; CONTINUE IF NOT
MOV CX,0FFH
MOV DX,03F6H
MOV AL,0H
OUT AL,0H ; RESET
OUT DX,AL
F9_A: LOOP F9_A ; HOLD RESET
SUB AL,AL
OUT DX,AL ; REMOVE RESET

;----- TEST.23
;----- DISKETTE ATTACHMENT TEST
;----- DESCRIPTION
;----- CHECK IF IPL DISKETTE DRIVE IS ATTACHED TO SYSTEM. IF
;----- ATTACHED, VERIFY STATUS OF NEC FDC AFTER A RESET. ISSUE
;----- A RECAL AND SEFK CMD TO FDC AND CHECK STATUS. COMPLETE
;----- SYSTEM INITIALIZATION THEN PASS CONTROL TO THE BOOT
;----- LOADER PROGRAM.
F9A: MOV AL,3CH ;<><><><><><><><><>
OUT MFG_PORT,AL ;<><>CHECKPOINT 3C <><><>
MOV AL,02H ; SET DATA RATE TO 250 K BITS / SEC
MOV DX,3F7H
OUT DX,3F7H
TEST BYTE PTR EQUIP_FLAG,01H ; DISKETTE PRESENT?
JZ F15 ; MFG JUMPER INSTALLED?
TEST MFG_TST,LOOP_POST ; GO IF YES
JZ F15 ; DISK_TEST?
IN AL,INTA01
JMP SHORT $42 ; IO DELAY
AND AL,0BFH ; ENABLE DISKETTE INTERRUPTS
OUT INTA01,AL
MOV AH,0
MOV DL,0H ; SET FOR DRIVE 0
INT 13H ; VERIFY STATUS AFTER RESET
TEST AH,0FFH ; STATUS OK?
JNZ F13 ; NO - FDC FAILED

;----- TURN DRIVE 0 MOTOR ON
070B BA 03F2
070E B0 1C
0710 EE
0711 2B C9
0713 B2 0C
0715 75 24
MOV DX,03F2H ; GET ADDR OF FDC CARD
MOV AL,1CH ; TURN MOTOR ON, EN DMA/INT
OUT DX,AL ; WRITE FDC CONTROL REG
SUB CX,CX ; WAIT 1 SECOND
MOV BL,12 ; MOTOR_WAIT:
F11:

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0715 F2 E2
0717 FE CA
0719 75 FA

LOOP DEC JNZ F11 ; WAIT FOR 1 SECOND
      DL ; DECREMENT OUTTER LOOP
      F11

0718 33 D2 XOR DX,DX ; SELECT DRIVE 0
071D B5 01 HLD CH_1 ; SELECT TRACK 1
071F 08 16 003E R MOV SEEK_STATUS_DL
0723 E8 0000 E CALL SEEK ; RECALIBRATE DISKETTE
0726 72 07 JC F13 ; GO TO ERR SUBROUTINE IF ERR
0728 B5 22 MOV CH_34 ; SELECT TRACK 34
072A EB 0000 E CALL SEEK ; SEEK TO TRACK 34
072D 73 0B JNC F14 ; OK, TURN MOTOR OFF
072F F13: ; DSK_ERR:

072F 80 0E 0016 R 40 OR MFG_ERR_FLAG+1,DSK_FAIL ;<><><><><><><><><><>
0734 BE 0000 E MOV SI,_OFFSET F3 ;><> DISKETTE FAILED<><><>
0737 EB 0000 E CALL E_MSG ; GET ADDR OF MSG
073F F14: ; GO PRINT ERROR MSG

;----- TURN DRIVE 0 MOTOR OFF
073A B0 0C MOV AL,OCH ; DRO_OFF:
073B BA 03F2 MOV DX,03F2H ; TURN DRIVE 0 MOTOR OFF
073F EE OUT DX,AL ; FDC CTL ADDRESS

;----- SETUP KEYBOARD PARAMETERS
0740 G6 06 005B R 00 F15: MOV INTR_FLAG,00H ; SET STRAY INTERRUPT FLAG = 00
0745 BE 001E R MOV SI,_OFFSET KB_BUFFER ; SETUP KEYBOARD PARAMETERS
0748 89 36 001A R MOV BUFFER_HEAD,SI
074C 89 36 001C R MOV BUFFER_TAIL,SI
0750 89 36 0080 R MOV BUFFER_START,SI
0754 83 C9 20 ADD SI,32 ;DEFAULT BUFFER OF 32 BYTES
0757 89 36 0082 R MOV BUFFER_END,SI

;----- SET PRINTER TIMEOUT DEFAULT
0758 BF 0078 R MOV DI,_OFFSET PRINT_TIM_OUT ;SET DEFAULT PRINTER TIMEOUT
0759 FE 1E R PUSH DI
075F 07 D0 00 POP ES
0760 BB 1414 MOV AX,1414H ; DEFAULT=20
0763 AB STOSW
0764 AB STOSW

;----- SET 4S232 DEFAULT
0765 BB 0101 MOV AX,0101H ;RS232 DEFAULT=01
0768 AB STOSW
0769 AB STOSW

;----- ENABLE TIMER INTERRUPTS
076A E4 21 IN AL,INTA01
076C 24 FE AND AL,OFEH ; ENABLE TIMER AND KB INTS
076E EB 00 JMP SHORT S+2 ; IO DELAY
0770 E6 21 OUT INTA01,AL

;----- CHECK CMOS BATTERY/CHECKSUM
0772 F6 06 0012 R 20 TEST MFG_JUMPER? ; MFG JUMPER?
0773 F5 03 JNZ B1 ; GO IF NOT
0779 E9 0B58 R JMP F15C ; BYPASS IF YES

077C B0 8E B1_OK: MOV AL,DIAG_STATUS ; IO DELAY
077E E6 70 OUT CMOS_PORT,AL
0780 EB 00 JMP SHORT S+2 ; BAD BATTERY, CHK SUM, OR MIN CONFIG
0782 E4 71 IN AL,CMOS_PORT+1
0784 24 E0 AND AL,OE0H ; GO IF YES
0786 00 00 JZ C_09 ; BATTERY BAD?
0788 A8 80 TEST AL,80H ; PRELOAD BATTERY MSG
078A BE 0000 E MOV SI,_OFFSET CM1 ; GO IF BATTERY OK
078D 74 06 JZ B2_OK ; PRINT BATTERY MSG
078F EB 0000 E CALL E_MSG ; CONTINUE(BYPASS CLOCK ETC)
0792 EB 62 90 JMP H_OKIA

0795 BE 0000 E B2_OK: MOV SI,_OFFSET CM2 ; PRE LOAD CKSUM BAD
0798 EB 0000 E CALL E_MSG ; PRINT MSG
079B EB 59 90 JMP H_OKIA ; BYPASS CLOCK TEST-MEM SIZE

;----- TEST CLOCK UPDATING
079E B3 03 C_OK: MOV BL,03H ; OUTER LOOP COUNT
07A0 2B C9 D_OK: SUB CX,CX ; INNER LOOP COUNT
07A2 B0 8A E_OK: MOV AL,CLK_UP ; GET THE CLOCK UPDATE BYTE
07A4 E7 00 JMP OUT CMOS_PORT,AL
07A6 00 00 IN AL,CMOS_PORT+1 ; IO DELAY
07A8 E4 71 TEST AL,80H ; CHECK FOR UPDATE IN PROGRESS
07AC 75 25 JNZ G_OK ; GO IF YES
07E4 E2 CB LOOP E_OK ; TRY AGAIN
07B0 FE CB DEC AL ; DEC OUTTER LOOP
07C4 E4 04 JMP D_OK ; TRY AGAIN
0784 BE 0000 E F_OK: MOV SI,_OFFSET CM3 ; PRINT MSG
07B7 EB 0000 E CALL E_MSG ; CONTINUE

;----- SET CMOS_DIAG_STATUS 04 (CLOCK ERROR)
078A B0 8E MOV AL,DIAG_STATUS ; SET CLOCK ERROR
078C E6 70 OUT CMOS_PORT,AL ; SAVE STATUS ADDRESS
078E 86 C6 XCHG AL,AH ; IO DELAY
07C0 EB 00 JMP SHORT S+2 ; GET THE CURRENT STATUS
07C2 E7 01 IN AL,CMOS_PORT+1 ; SET NEW STATUS
07C4 E4 04 OR AL,CMOS_CLK_FAIL ; GET STATUS ADDR AND SAVE NEW STATUS
07C6 86 C4 XCHG AL,AH
07C8 EB 70 OUT CMOS_PORT,AL ; IO DELAY
07CA 86 C4 XCHG AL,AH ; SET CLOCK ERROR
07CC EB 00 JMP SHORT S+2 ; CONTINUE
07D0 EB 12 90 OUT H_OK ; TRY AGAIN

;----- CHECK CLOCK UPDATE
07D3 B9 0258 G_OK: MOV CX,600 ; LOOP COUNT
07D6 BB 84 I_OK: MOV AL,CLK_UP ; CHECK FOR OPPOSITE STATE
07D8 EB 70 OUT CMOS_PORT,AL ; IO DELAY
07DA EB 00 JMP SHORT S+2 ; TRY AGAIN
07DC E4 71 IN AL,CMOS_PORT+1 ; PRINT ERROR IF TIMEOUT
07DE EB 00 LOOPNZ I_OK ; GET THE STATUS BYTE
07E0 EB F4 F_OK: DEC AL ; CONTINUE
07E2 E3 D0 JCXZ F_OK

;----- CHECK MEMORY SIZE DETERMINED = CONFIG
07E4 B0 8E H_OK: MOV AL,DIAG_STATUS ; GET THE STATUS BYTE
07E6 F6 70 OUT CMOS_PORT,AL

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07EB EB 00           JMP   SHORT $+2          ; IO DELAY
07EA E4 71           IN    AL,CMOS_PORT+1   ; WAS THE CONFIG=MEM_SIZE_DETERMINED?
07EC A8 10           TEST  AL,V_MEM_SIZE
07EE 74 06           JZ    H_0KTA
;----- MEMORY SIZE ERROR
07F0 BE 0000 E        MOV   SI,OFFSET_E1_A    ; PRINT SIZE ERROR
07F3 E8 0000 E        CALL  E_MSG             ; DISPLAY ERROR
;----- CHECK FOR CRT ERROR
07F6 80 3E 0015 R 0C H_0K1A: CMP   MFG_ERR_FLAG_OCH ; CHECK FOR MONO CRT ERROR
07FB BE 0000 E        MOV   SI,OFFSET_E1_B    ; PRELOAD MONO CRT ERROR
07FE 74 0A           JZ    H_0K1B
0800 80 3E 0015 R 0D CMP   MFG_ERR_FLAG_ODH ; CHECK FOR COLOR CRT ERROR
0809 75 06           JNZ   J_0K
0807 BE 0000 E        MOV   SI,OFFSET_E1_C    ; CONTINUE IF NOT
080A E8 0000 E        H_0K1B: CALL  E_MSG     ; CRT ERROR MSG
;----- CHECK FOR COMBO HARD FILE/DISKETTE CARD
080D B3 0F           J_0K: MOV   BL,0FH          ; OUTTER LOOP COUNT WAIT FOR BUSY OFF
080F 2B C9           SUB   CX,CX
0811 80 01F7          NOV   DA,00F7H
0814 EC              IN    AL,DX
0815 A8 80           TEST  AL,080H
0817 74 0D           JZ    J_0K2
0819 E2 F9           LOOP  J_0K1
081B FE CB           DEC   BL
081C 75 07           JNZ   J_0K1
081F 24 0C           AND   AL,OCH
0821 74 1A           JZ    J_0K3
0823 EB 33 90           JMP   F15C
0826 BA 01F4          J_0K2: MOV   DX,1FH          ; VERIFY COMBO CARD
0829 B0 55           OUT   AL,055H
082B EE              OUT   DX,AL
082C EB 00           JMP   SHORT $+2
082E EC              IN    AL,DX
0830 3C 55           CMP   AL,055H
0831 75 25           JNZ   F15C
0833 B0 AA           MOV   AL,0AAH
0835 EE              OUT   DX,AL
0836 EB 00           JMP   SHORT $+2
0838 EC              IN    AL,DX
0839 3C 5A           CMP   AL,0AAH
083B 75 1B           JNZ   F15C
083D C6 06 008F R 01 J_0K3: MOV   HF_CNTRL,DUAL ; SET THE HF/FLOPPY SWITCH ON
;----- INITIALIZE FLOPPY FOR DRIVE TYPE
0842 B0 3D           MOV   AL,3DH          ;<><><><><><><><><><>
0844 E6 80           OUT   MFG_PORT_AL ;<><>CHECKPOINT 3D <><><>
0846 EB 0000 E        CALL  DSKETTE_SETUP ;<><>INITIALIZE FLOPPY
;----- CHECK FOR 2ND DISKETTE DRIVE
0849 EB 0000 E        CALL  DDS             ; INSURE DATA SEGMENT
084C B0 3E 0091 R 00 CMP   DSK_STATE+1,0 ; IS THERE A DRIVE 2 ATTACHED?
0851 74 05           JZ    F15C
0853 B0 0E 0010 R 40 OR    BYTE PTR EQUIP_FLAG,40H ; GO IF NOT
; SET SECOND DRIVE INSTALLED
;----- INITIALIZE HARD FILE
0858 B0 3E           F15C: MOV   AL,3EH          ;<><><><><><><><><><>
085A E6 80           OUT   MFG_PORT_AL ;<><>CHECKPOINT 3E <><><>
085C B0 8E           MOV   AL,DIA_STATUS ; GET THE CMOS STATUS
085F E6 70           OUT   CMOS_PORT,AL
0860 EB 00           JMP   SHORT $+2
0862 E4 71           IN    AL,CMOS_PORT+1
0864 A8 C0           TEST  AL,0C0H
0866 75 0F           JNZ   ROM_SCAN1
0868 B0 92           MOV   AL,HD_FILE_TYPE ; BATTERY/CHECKSUM OK
086A E6 70           OUT   CMOS_PORT,AL ; BYPASS DISK SETUP IF NOT
086C EB 00           JMP   SHORT $+2
086E E4 71           IN    AL,CMOS_PORT+1
0870 3C 00           CMP   AL,0H
0872 74 03           JZ    ROM_SCAN1
0874 E8 0000 E        CALL  DISK_SETUP ; INSURE CMOS DEFINES THE TYPE OF HARD FILE
;----- TEST_22
; CHECK FOR OPTIONAL ROM FROM C800->E000 IN 2K BLOCKS
; (A VALID MODULE HAS '55AA' IN THE FIRST_2 LOCATIONS
; LENGTH INDICATOR (LENGTH/512) IN THE 3RD LOCATION
; AND TEST/INIT. CODE STARTING IN THE 4TH LOCATION)
;----- ROM_SCAN1
0877 FB              ROM_SCAN1: STI   ; ALLOW INTERRUPTS
0878 B0 3B           MOV   AL,3BH
087A E6 80           OUT   MFG_PORT_AL ;<><><><><><><><><><>
087C E8 0000 E        CALL  DDS             ;<><>CHECKPOINT 3B <><>
087D 00 0A           MOV   AL,10             ; SET REAL MODE DATA SEGMENT
0881 E8 0000 E        CALL  PRI1_HEX ; LINE FEED ON CRT
;----- ROM_SCAN2
0884 2A C0           ROM_SCAN2: SUB   AL,AL
0886 E6 D2           OUT   DMA18+2,AL ; SEND ZERO TO MASK REG
0888 EB 00           JMP   SHORT $+2
088A E6 D4           OUT   DMA18+4,AL ; SEND ZERO TO REQ REG
088C BA C800          MOV   DX,0C800H ; SET BEGINNING ADDRESS
088E 00 0F           MOV   DS,DX
088F B6 DA           SUB   BX,BX
0891 2B DB           MOV   AX,[BX]
0893 BB 07           PUSH  BX
0895 53              POP   BX
0896 00 00           CMP   AX,0AA55H ; BUS SETTLING
0897 3D AA55          JNZ   NEXT_ROM ; = TO ID WORD?
089A 75 06           CALL  ROM_CHECK ; PROCEED TO NEXT ROM IF NOT
089C E8 0000 E        ARE_WE_DONE: CALL  ARE_WE_DONE ; GO CHECK OUT MODULE
089F EB 05 90          JMP   ARE_WE_DONE ; CHECK FOR END OF ROM SPACE
;----- NEXT_ROM
0900 00 00           NEXT_ROM: ADD   DX,0080H ; POINT TO NEXT 2K ADDRESS
0902 B1 C2 0080         ARE_WE_DONE: CMP   DX,0E000H ; AT E0000 YET?
0904 B1 FA E000

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08AA 7C E3 JL ROM_SCAN2 ; GO CHECK ANOTHER ADD. IF NOT
ENDIF ;----- TEST FOR KEYBOARD LOCKED
08AC E8 0000 E CALL DDS ; SET DATA SEGMENT
08AF E4 64 IN AL,STATUS_PORT ; IS KEYBOARD UNLOCKED?
08B1 24 10 AND AL,KYBD_INH ;
08B3 74 03 JZ KEY1 ; GO IF OFF
08B5 EB 0C 90 JMP KEY10 ; GO IF OFF
08B8 80 0E 0016 R 80 KEY1: OR MFG_ERR_FLAG+1,KEY_FAIL ;<><><><><><><><><><>
08B9 ;<><> KEYBOARD IS LOCKED <><>
ELSE
08BD KEY9: ASSUME DS:DATA
08BD BE 0000 E MOV SI,OFFSET LOCK ; PRINT LOCKED MESSAGE (302)
08C0 E8 0000 E CALL E_MSG ;
ENDIF
08C3 KEY10: ;=====
;----- SETUP PRINTER_BASE
;=====

08C3 BF 0000 E MOV DI,OFFSET F4 ; PRT_SRC_TBL
08C6 BE 0000 E MOV SI,0 ;
08C9 2E: BB 15 F16: MOV DX,CS:[DI] ; PRT_BASE:
08C8 BB AA MOV AL,OAAH ; GET PRINTER BASE ADDR
08C9 EC 00 OUT DX,AL ; WRITE DATA TO PORT A
08CF EB 00 JMP SHORT $2+ ; IO DELAY
08D1 1E PUSH DS ; BUS SETTLING
08D2 EC IN AL,DX ; READ PORT A
08D3 1F POP DS ;
08D4 3C AA CMP AL,0AAH ; DATA PATTERN SAME
08D6 00 06 JNE F17 ; NO NEED NEW PRT_CD
08D8 89 94 0008 R MOV PRINTER_BASE[SI],DX ; TCS - STORE PRT BASE ADDR
08DC 46 INC SI ; INCREMENT TO NEXT WORD
08D0 46 INC SI ;
08D4 46 F17: INC DI ; POINT TO NEXT BASE ADDR
08DF 47 INC DI ; ALL POSSIBLE ADDRS CHECKED?
08E0 81 FF 0000 E CMP DI,OFFSET F4E ; PRT_BASE
08E4 75 E3 F16: JNE F16 ;
;----- SETUP RS232
;=====

08E6 BB 0000 F18: MOV BX,0 ; POINTER TO RS232 TABLE
08E9 BA 03FA MOV DX,3FAH ; CHECK IF RS232 CD 1 ATTCH?
08EC EC IN AL,DX ; READ INTR ID REG
08ED A8 F8 TEST AL,OF8H ;
08F0 75 08 JNZ F18 ; RS232_BASE[BX],3F8H ; SETUP RS232 CD #1 ADDR
08F1 87 0000 R 03F8 INC BX ;
08F7 43 INC BX ; RS232_BASE[BX],3F8H ; SETUP RS232 CD #1 ADDR
08F8 43 F19: INC BX ; CHECK IF RS232 CD 2 ATTCH
08F9 BA 02FA MOV DX,2FAH ; READ INTERRUPT ID REG
08FC EC IN AL,DX ;
08FD A8 F8 TEST AL,OF8H ;
08FF 75 08 JNZ F19 ; BASE_END
0901 C7 87 0000 R 02F8 MOV RS232_BASE[BX],2F8H ; SETUP RS232 CD #2
0907 43 INC BX ;
0908 43 INC BX ;
;----- SET UP EQUIP_FLAG TO INDICATE NUMBER OF PRINTERS AND RS232 CARDS
;=====

0909 F19: ;----- BASE-END:
0909 8B C6 MOV AX,SI ; SI HAS 2nd NUMBER OF RS232
0908 B1 03 MOV CL,3 ; SHIFT COUNT
090D D2 C8 ROR AL,CL ; ROTATE RIGHT 3 POSITIONS
090F 0A C3 OR AL,CL ; OR IN THE PRINTER COUNT
0911 A2 0011 R MOV BYTE PTR EQUIP_FLAG+1,AL ; STORE AS SECOND BYTE
;----- TEST FOR ANY ERRORS (BP NOT ZERO)
;=====

0914 K_OK: ;----- CLEAR KEYBOARD STATE FLAGS
0914 2B C0 SUB AX,AX ; RESET ALL KEYBOARD STATE FLAGS
0916 A3 0017 R MOV WORD PTR KB_FLAG,AX ;
;----- ENABLE KEYBOARD INTERRUPTS
0919 E4 21 IN AL,INTA01 ;----- MFG RUN IN MODE -> SET ERROR FLAG
0918 24 FD AND AL,OFDH ;----- MFG RUN IN MODE -> SET ERROR FLAG
0919 EB 00 JMP INTA01,AL ;----- MFG RUN IN MODE -> SET ERROR FLAG
091F E6 21 OUT INTA01,AL ;----- MFG RUN IN MODE -> SET ERROR FLAG
0921 C6 06 0015 R 00 MOV BYTE PTR MFG_ERR_FLAG,0 ;----- MFG RUN IN MODE -> SET ERROR FLAG
0926 83 FD 00 CMP BP,0000H ;----- MFG RUN IN MODE -> SET ERROR FLAG
;----- MFG RUN IN MODE -> SET ERROR FLAG
0929 74 3D JE F15A_0 ;----- MFG RUN IN MODE -> SET ERROR FLAG
0928 80 3E 0072 R 64 CMP BYTE PTR RESET_FLAG,64H ;----- MFG RUN IN MODE -> SET ERROR FLAG
0930 75 08 JNZ ERR_WAIT ;----- MFG RUN IN MODE -> SET ERROR FLAG
;----- MFG RUN IN MODE -> SET ERROR FLAG
0932 C6 06 0015 R AA MOV BYTE PTR MFG_ERR_FLAG,0AAH ;----- MFG RUN IN MODE -> SET ERROR FLAG
0937 EB 2F 90 JMP F15A_0 ;----- MFG RUN IN MODE -> SET ERROR FLAG
093A ;----- MFG RUN IN MODE -> SET ERROR FLAG
093A BA 0002 MOV DX,2 ;----- MFG RUN IN MODE -> SET ERROR FLAG
0930 EE 0000 E CALL ERR_BEEP ;----- MFG RUN IN MODE -> SET ERROR FLAG
0940 E4 64 IN AL,STATUS_PORT ;----- MFG RUN IN MODE -> SET ERROR FLAG
0942 24 10 AND AL,KYBD_INH ;----- MFG RUN IN MODE -> SET ERROR FLAG
0944 BE 0000 E MOV SI,OFFSET F3D ;----- MFG RUN IN MODE -> SET ERROR FLAG
0947 72 09 JNZ ERR_WAIT2 ;----- MFG RUN IN MODE -> SET ERROR FLAG
0948 80 0000 E MOV SI,OFFSET F3D1 ;----- MFG RUN IN MODE -> SET ERROR FLAG
094C E8 0000 E CALL P_MSG ;----- MFG RUN IN MODE -> SET ERROR FLAG
094F BE 0000 E MOV SI,OFFSET F3D ;----- MFG RUN IN MODE -> SET ERROR FLAG
0952 E8 0000 E CALL P_MSG ;----- INIT PRINTER (ALT DISPLAY DEVICE)
0955 B8 01 MOV AH,1 ;----- FIRST PRINTER
0957 2B D2 SUB DX,DX ;
0959 CD 17 INT 17H ;
ERR_WAIT1: ;----- INIT PRINTER (ALT DISPLAY DEVICE)
0958 B0 3F MOV AL,3FH ;----- CHECKPOINT 3F
095D F6 80 OUT MFG_PORT_AL ;----- CHECKPOINT 3F
;----- INIT PRINTER (ALT DISPLAY DEVICE)

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095F B4 00          MOV AH,00           ; WAIT FOR 'F1' KEY
0961 CD 16          INT 16H
0963 80 FC 3B       CMP AH,3BH
0966 75 F3          JNE ERR_WAIT1
0968 F6 06 0012 R 20 F15A_0: TEST MFG_TST_LOOP_POST ; MFG BURN IN MODE
096D 75 03          JNZ F15A
096F E9 0000 E       JMP START_1
0972 80 3E 0072 R 64 F15A: CMP BYTE PTR RESET_FLAG,64H ; MFG RUN IN?
0977 74 06          JZ F15B
0979 BA 0001         MOV DX,1            ; 1 SHORT BEEP (NO ERRORS)
097C E8 0000 E       CALL ERR_BEEP
097F 2A E4          F15B: SUB AH,AH        ; CLEAR FLAGS
0981 A0 0049 R       MOV AL,CRT_MODE
0984 CD 10          INT 10H             ; CLEAR SCREEN
;----- CLEAR DESCRIPTOR TABLES
0986 B9 01F4         F20: MOV CX,0500      ; CLEAR 1K
0989 BF D0A0         MOV DI,SYS_IDT_LOC ; POINT ES TO START OF DESCRIPTORS
098C 2B C0          SUB AX,AX
098E 8E C0          MOV ES,AX
0990 26: 89 05       F20_A: MOV ES:[DI],AX ; CLEAR
0993 83 C7 02       ADD DI,2           ; POINT TO NEXT LOCATION
0996 E2 F8          LOOP F20_A        ; CONTINUE TILL DONE
;=====SET TIME OF DAY=====
;=====SET SYSTEM STACK
0998 E8 0000 E       CALL SET_TOD
;-----SET SYSTEM STACK
099B B8 ---- R     MOV AX,STACK        ; GET THE STACK SEGMENT
099E 8E D0          MOV SS,AX
09A0 BC 0100 R       MOV SP,OFFSET TOS
;-----ENABLE HARDWARE INTERRUPT IF MATH PROCESSOR (X287)
09A3 B0 40          MOV AL,40H          ;<><><><><><><><><><><>
09A5 E6 80          OUT MFG_PORT,AL   ;<><>CHECKPOINT 40 <><><>
09A7 A1 0067 R       MOV AX,IO_ROM_INIT ; TEMP STORAGE
09A9 50             PUSH AX
09AA 2B C0          SUB AX,AX
09AD 33 0067 R       MOV AX,IO_ROM_INIT ; CLEAR IO_ROM_INIT
09BD DB E3          ESC 28,BX        ;<>
09B2 33 C0          XOR AX,AX
09B4 D0 3E 0067 R    ESC 15,IO_ROM_INIT ;<>
09B8 60             PUSHA 060H        ; TIME FOR 287 TO RESPOND
09B9 61             POPA              ;<>
09BA 81 26 0067 R  1F3F AND 061H          ; CLEAR UNUSED 287 BITS
09C0 81 3E 0067 R  033F CMP IO_ROM_INIT,01F3FH ; IS THE 287 INSTALLED?
09C6 75 24          JNZ NO_287        ; GO IF MATH PROCESSOR IS NOT INSTALLED
09C8 9B             WAIT              ; STORE THE STATUS WORD
09C9 DD 3E 0067 R    ESC 02FH,IO_ROM_INIT ; TIME FOR 287 TO RESPOND
09CD 60             PUSHA 060H        ;<>
09CE 61             POPA              ;<>
09CF F7 06 0067 R  B8BF TEST IO_ROM_INIT,0B8BFH ; ALL BITS SHOULD BE OFF
09D5 75 15          JNZ NO_287        ; GO IF NOT INSTALLED
09D7 E4 A1          IN AL,INTB01     ; GET THE SLAVE INT MASK
09D9 24 DF          AND AL,0DFH      ; ENABLE 287 INTERRUPTS
09DB E0 A0          JMP INTB01,AL    ; IO DELAY
09DD E6 A1          OUT INTB01,AL    ;<>
;-----ENSURE THAT MASTER LEVEL 2 ENABLED
09DF E4 21          IN AL,INTA01     ; GET THE CURRENT MASK
09E1 24 FB          AND AL,0FBH      ;<>
09E3 EB 00          JMP SHORT $+2   ; IO DELAY
09E5 E6 21          OUT INTA01,AL    ;<>
09E7 80 0E 0010 R  02 OR BYTE PTR EQUIP_FLAG,02H ; SET 287 BIT ON
09EC NO_287:          NO_287:          ;<>
09E6 58             POP AX           ; RESTORE IO_ROM_INIT
09ED A3 0067 R       MOV IO_ROM_INIT,AX ;<>
;-----TEST FOR MFG RUN-IN TEST
09F0 80 3E 0072 R  64 CMP BYTE PTR RESET_FLAG,64H ; IS THE THE MFG RUN-IN TEST?
09F5 75 03          JNZ END_287
09F7 EB 63 90        JMP SHUT4        ; BOOT LOAD IF YES
;-----UNMASK SLAVE HARDWARE INT 9 (LEVEL 71)
END_287:           END_287:          ;<>
09FA E4 A1          IN AL,INTB01     ; GET THE CURRENT MASK
09FC 24 FD          AND AL,0FDH      ;<>
09FE EB 00          JMP SHORT $+2   ; IO DELAY
0A00 E6 A1          OUT INTB01,AL    ; SET NEW MASK
;-----TEST FOR SYSTEM CODE AT SEGMENT E000:0
; FIRST WORD = AA55H
; LAST BYTE = CHECKSUM
; ENTRY POINT = FIRST BYTE + 3
; IF TEST IS SUCCESSFUL A CALL FAR TO THE ENTRY POINT IS EXECUTED
0A02 B0 41          MOV AL,41H          ;<><><><><><><><><><><>
0A04 E6 80          OUT MFG_PORT,AL   ;<><>CHECKPOINT 41 <><>
0A06 B0 AD          MOV AL,CMOS_END ; INSURE NMI OFF
0A08 E6 70          OUT CMOS_PORT,AL ;<>
ENDIF
0A0A C6 06 0072 R  00 MOV BYT PTR RESET_FLAG,0 ; CLEAR FLAG
0A0F BB E000         MOV AX,0E000H      ; SEGMENT OF SYSTEM CODE
0A12 8E C0          MOV ES,AX
0A14 2B FF          SUB DI,DI
0A16 26: 8B 05       MOV AX,ES:[DI]    ; CHECK FOR AA55
0A19 53             PUSH BX
0A21 58             POP BX
0A22 2D AA55         CMP AX,0AA55H    ;<>
0A24 9C              PUSHF             ; SAVE FLAGS
0A1F 26: 89 05       MOV ES:[DI],AX  ; CLEAR POSSIBLE PARITY CHECK
0A22 E4 61          IN AL,PORT_B    ;<>
0A24 OC 0C          OR AL,RAM_PAR_OFF ; TOGGLE IO/PAR CHECK ENABLE

```

```

0A26 EB 00      JMP    SHORT $+2          ; IO DELAY
0A28 E6 61      OUT    PORT_B,AL
0A2A 24 F3      AND    AL, RAM_PAR_ON
0A2C EB 00      JMP    SHORT $+2          ; IO DELAY
0A2E E6 61      OUT    PORT_B,AL
0A30 9D         POPF   DS
0A31 75 29      JNZ    SHUT4             ; RESTORE FLAGS
                                            ; CONTINUE

;----- CHECKSUM SYSTEM CODE

0A33 1E         PUSH   DS
0A34 06         PUSH   ES
0A35 1F         POP    DS
0A36 2B DB      SUB    BX,BX
0A38 E8 0000 E   CALL   ROS_CHECKSUM     ; STARTING OFFSET
0A3B 1F         POP    DS
0A3C 75 1E      JNZ    SHUT4             ; RESTORE DATA SEGMENT
                                            ; GO IF CHECKSUM NOT OK

;----- ENABLE NMI AND IO/PAR CHECKS

0A3E B0 2D      MOV    AL,2DH           ; ENABLE NMI
0A40 E6 70      OUT   CMOS_PORT,AL
0A42 E4 61      IN    AL,PORT_B        ; ENABLE PARITY
0A44 EB 00      JMP    SHORT $+2        ; IO DELAY
0A46 24 F3      AND    AL, RAM_PAR_ON
0A48 E6 61      OUT   PORT_B,AL       ; ENABLE RAM PCK AND IO CH

0A4A C7 06 0067 R 0003      MOV    DS:IO_ROM_INIT,0003H ; SET THE OFFSET
0A50 8C 06 0069 R           MOV    DS:IO_ROM_SEG,ES      ; SET THE SEGMENT

0A54 B0 42      I V   AL,42H           ;<><><><><><><><><>
0A56 E6 80      OUT   MFG_PORT,AL     ;<><><>CHECKPOINT 4<><><>

;----- EXIT TO SYSTEM CODE

0A58 FF 1E 0067 R           CALL   DWORD PTR DS:IO_ROM_INIT ; GO TO SYSTEM CODE
                                            ; VIA CALL

;----- ENABLE NMI INTERRUPTS + ENTRY FROM SHUTDOWN WITH BOOT REQUEST

SHUT4: MOV    AL,2DH           ; ENABLE NMI
       OUT   CMOS_PORT,AL
0A5C B0 2D      IN    AL,PORT_B        ; ENABLE PARITY
0A5E E6 70      JMP    SHORT $+2        ; IO DELAY
0A60 E4 61      AND    AL, RAM_PAR_ON
0A62 EB 00      OUT   PORT_B,AL       ; ENABLE RAM PCK AND IO CH
0A64 24 F3
0A66 E6 61

0A68 B0 43      MOV    AL,43H           ;<><><><><><><><><>
0A6A E6 80      OUT   MFG_PORT,AL     ;<><><>CHECKPOINT 4<><><>

ENDIF

0A6C CD 19      INT    19H             ; GO TO BOOT LOADER

0A6E ENDIF
0A6E POST2        ENDP
0A6E CODE         ENDS
0A6E ENDS
0A6E END

```

```

TITLE 09-26-83 TEST3      POST UTILITIES

_LIST_
PUBLIC POST3
PUBLIC ROS_CHECKSUM
PUBLIC BLINK_INT
PUBLIC ROM_CHECK
PUBLIC XPC_BYTETE
PUBLIC PRT_HEX
PUBLIC XLAT_PR
PUBLIC PROT_PRT_HEX
PUBLIC PROC_SHUTDOWN

C INCLUDE SEGMENT.SRC
C CODE SEGMENT BYTE PUBLIC
C

EXTRN ROM_ERR:NEAR
;-----[-----ROS_CHECKSUM SUBROUTINE-----]
;-----[-----]

ASSUME CS:CODE, DS:ABSO

POST3:    ASSUME CS:CODE, DS:ABSO
ROS_CHECKSUM PROC NEAR
SUB CX,CX ; NEXT_ROS_MODULE
MOV AL,00H ; NUMBER OF BYTES TO ADD IS 64K
ROS_CHECKSUM_CNT:    XOR AL,AL ; ENTRY FOR OPTIONAL ROS TEST
C26:      ADD AL,DS:[BX] ; POINT TO NEXT BYTE
INC BX ; ADD ALL BYTES IN ROS MODULE
LOOP C26 ; SUM = 0?
OR AL,AL ; RET
RET

ROS_CHECKSUM ENDP

;-----[-----BLINK LED PROCEDURE FOR MFG RUN-IN TESTS-----]
;-----[-----IF LED IS ON, TURN IT OFF. IF OFF, TURN ON.-----]
;-----[-----]

ASSUME DS:DATA
BLINK_INIT PROC NEAR
ST1:      PUSH AX ; SAVE AX REG CONTENTS
IN AL,MFG_PORT ; READ CURRENT VAL OF MFG_PORT
MOV AH,AL
NOT AH
AND AL,01000000B ; FLIP ALL BITS
AND AH,1011111B ; ISOLATE CONTROL BIT
OR AL,AH ; MASK OUT OF ORIGINAL VAL
OUT MFG_PORT,AL ; OR NEW CONTROL BIT IN
MOV AL,E0I
OUT AL,E0I
POP AX ; RESTORE AX REG
IRET

BLINK_INIT ENDP

;-----[-----THIS ROUTINE CHECKSUMS OPTIONAL ROM MODULES AND-----]
;-----[-----IF CHECKSUM IS OK, CALLS INIT/TEST CODE IN MODULE-----]
;-----[-----]

ROM_CHECK PROC NEAR
MOV AX,DATA ; POINT ES TO DATA AREA
MOV ES,AX
MOV AL,AH ; ZERO OUT AH
SUB AL,00H ; GET LENGTH INDICATOR
MOV AL,[BX+2]
MOV CL,09H ; MULTIPLY BY 512
SHL AX,CL
MOV CX,AX ; SET COUNT
PUSH CX ; SAVE COUNT
MOV CX,4 ; ADJUST
SHR AX,CL
ADD DX,AX ; SET POINTER TO NEXT MODULE
POP CX ; RETRIEVE COUNT
CALL ROS_CHECKSUM_CNT ; DO CHECKSUM
JZ ROM_CHECK_1 ; POST CHECKSUM ERROR
CALL ROM_ERR ; AND EXIT
JMP ROM_CHECK_END

ROM_CHECK_1:
PUSH DX ; SAVE POINTER
MOV ES:10_ROM_INIT,0003H ; LOAD OFFSET
MOV ES:10_ROM_SEG,DS ; LOAD SEGMENT
CALL DDWORD PTR ES:10_ROM_INIT ; CALL INIT./TEST ROUTINE
POP DX

ROM_CHECK_END:
RET ; RETURN TO CALLER

ROM_CHECK ENDP

;-----[-----CONVERT AND PRINT ASCII CODE-----]
;-----[-----AL MUST CONTAIN NUMBER TO BE CONVERTED.-----]
;-----[-----AX AND BX DESTROYED.-----]
;-----[-----]

XPC_BYTETE PROC NEAR
PUSH AX ; SAVE FOR LOW NIBBLE DISPLAY
MOV CL,4 ; SHIFT COUNT
SHR AX,CL ; NIBBLE SWAP
CALL XLAT_PR ; RECOVER THE NIBBLE
POP AX ; ISOLATE TO LOW NIBBLE
AND AL,0FH ; FALL INTO LOW NIBBLE CONVERSION
XLAT_PR PROC NEAR ; CONVERT 00-0F TO ASCII CHARACTER
ADD AL,090H ; ADD FIRST CONVERSION FACTOR
DAA ; ADJUST FOR NUMERIC AND ALTA RANGE
ADC AL,040H ; ADD CONVERS ON AND ADJUST LOW NIBBLE
DAA ; ADJUST HIGH NIBBLE TO ASCII RANGE

PRT_HEX PROC NEAR
MOV AH,14 ; DISPLAY CHARACTER IN AL
MOV BH,0
INT 10H ; CALL VIDEO_IO

PRT_HEX ENDP
XLAT_PR ENDP
XPC_BYTETE ENDP

;-----[-----PUT CHARACTER TO THE CRT FOR TEST.11 IN-----]
;-----[-----PROTECTED MODE-----]
;-----[-----AL=ASCII CHARACTER DI=CRT BUFFER POSITION-----]
;-----[-----]

PROT_PRT_HEX PROC NEAR
PUSH DS ; SAVE CURRENT SEGMENT REGS
PUSH BX ; ; GO PRINT CHARACTER
CALL PROT_PRT ; SET DS TO B/W CRT BUFFER
;-----[-----B/W VIDEO CARD-----]
MOV BX,C_BWCRT_PTR ; SET DS TO B/W CRT BUFFER
MOV DS,BX ; GO PRINT CHARACTER
CALL PROT_PRT ; SET DS TO B/W CRT BUFFER
;-----[-----]

0000 BB 0020
0075 BB 0020
0078 BE DB
007A EA 0098 R
0073 1E
0074 53

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;----- COMPATIBLE COLOR
007D BB 0028      MOV    BX,C_CCRT_PTR      ; SET DS TO COMPATIBLE COLOR RAM
0080 BE DB          MOV    DS,BX
0082 E8 0098 R      CALL   PROT_PTR
;----- ENHANCED COLOR
0085 BB 0030      MOV    BX,E_CCRT_PTR      ; ENHANCED COLOR
0088 BE DB          MOV    DS,BX
008A E8 0098 R      CALL   PROT_PRT
008D BB 0038      MOV    BX,E_CCRT_PTR2     ENHANCED COLOR PTR HI 64K
0090 BE DB          MOV    DS,BX
0092 E8 0098 R      CALL   PROT_PRT
0095 5B             POP    BX
0096 1F             POP    DS
0097 C3             RET
0098 PROT_PRT:      PROT_PRT
0098 57             PUSH   DI,1              ; SAVE DISPLACEMENT
0099 D1 C7          ROL    DI,1
009A 00 05          MOV    DS:[DI],AL        ; MULT 16^2
009D 5F             POP    DI,1              WRITE TO CRT BUFFER
009E C3             RET
009F PROT_PRT_HEX:  PROT_PRT_HEX
009F ENDP
PROC_SHUTDOWN:      PROC
00A1 BO FE          MOV    AL,SHUT_CMD      ; SHUTDOWN COMMAND
00A2 OUT   STATUS_PORT,AL
PROC_S:   HLTT        JMP    PROC_S
00A3 F4             PROC_S
00A4 EB FD          ENDP
PROC_SHUTDOWN:      PROC_SHUTDOWN
00A6 CODE  EDOS        END
00A6 END

```

```

TITLE 10/05/83 TEST4    POST UTILITIES
.LIST
PUBLIC POST4
PUBLIC E_MSG
PUBLIC BEEP_RESET
PUBLIC BEEP
PUBLIC ERR_BEEP
PUBLIC E_MSG
PUBLIC DDS
PUBLIC P_MSG
PUBLIC SEG
PUBLIC DUMMY_RETURN_1
PUBLIC D11
PUBLIC INT_287
PUBLIC RE_DIRECT

0000      C INCLUDE SEGMENT.SRC
C CODE SEGMENT BYTE PUBLIC

0000      EXTRN PRT_HEX_NEAR
EXTRN XPC_BYTENEAR
EXTRN XM1T_8042_NEAR
EXTRN OBF_R2_NEAR
ASSUME CS:CODE,DS:ABSO
POST4:

0000      THIS SUBROUTINE WILL PRINT A MESSAGE ON THE DISPLAY
ENTRY REQUIREMENTS:
SI = OFFSET(ADDRESS) OF MESSAGE BUFFER
CX = MESSAGE BYTE COUNT
MAXIMUM MESSAGE LENGTH IS 36 CHARACTERS

0000      E_MSG PROC NEAR
MOV BP,SI ; SET BP NON-ZERO TO FLAG ERR
CALL P_MSG ; PRINT MESSAGE
PUSH DS

ASSUME DS:DATA
0000      CALL DDS
MOV AL, BYTE PTR EQUIP_FLAG ; LOOP/HALT ON ERROR
AND AL,01H ; SWITCH ON?
JNZ NOT_ON ; NO - RETURN

MFG_HALT:
CLI ; YES - HALT SYSTEM
MOV AL,MFG_ERR_FLAG ; RECOVER ERROR INDICATOR
OUT MFG_PORT,AL ; SET INTO MFG PORT
HLT ; HALT SYS

NOT_ON:
POP DS ; WRITE_MSG:
RET

E_MSG ENDP

0000      P_MSG PROC NEAR
G12A: MOV AL,CX:[SI] ; PUT CHAR IN AL
INC SI ; POINT TO NEXT CHAR
PUSH AX ; SAVE PRINT CHAR
CALL PRT_HEX ; CALL VIDEO IO
POP AX ; RECOVER PRINT CHAR
CMP AL,10 ; WAS IT LINE FEED?
JNE G12A ; NO, KEEP PRINTING STRING
RET

P_MSG ENDP

; INITIAL RELIABILITY TEST -- SUBROUTINES
ASSUME CS:CODE,DS:DATA

SUBROUTINES FOR POWER ON DIAGNOSTICS

THIS PROCEDURE WILL ISSUE ONE LONG TONE (3 SECs) AND ONE OR
MORE SHORT TONES (1 SEC) TO INDICATE A FAILURE ON THE PLANAR
BOARD, BAD RAM MODULE, OR A PROBLEM WITH THE CRT.
; ENTRY PARAMETERS:
; DH = NUMBER OF LONG TONES TO BEEP
; DL = NUMBER OF SHORT TONES TO BEEP.

0027      ERR_BEEP PROC NEAR
PUSHF ; SAVE FLAGS
CLI ; DISABLE SYSTEM INTERRUPTS
PUSH DS ; SAVE DS REG CONTENTS
CALL DDS
OR DH,DH ; ANY LONG ONES TO BEEP?
JZ G1 ; NO, DO THE SHORT ONES
LONG_BEEP:
G1: MOV BL,6 ; COUNTER FOR BEEPS
CALL DEEP ; DO THE BEEP
G2: LOOP G2 ; DELAY BETWEEN BEEPS
DEC DH ; ANY MORE TO DO?
JNE G1 ; DO IT
CMP MFG_TST,1 ; MFG TEST MODE?
JNE G3 ; YES - CONTINUE BEEPING SPEAKER
MFG_HALT ; STOP BLINKING LED
G3: MOV BL,1 ; SHORT BEEPS
CALL BEEP ; DO THE SOUND
G4: LOOP G4 ; DELAY BETWEEN BEEPS
DEC DL ; DONE WITH SHORTS
JNE G5 ; DO SOME MORE
G5: LOOP G5 ; LONG DELAY BEFORE RETURN
G6: POP DS ; RESTORE ORIG CONTENTS OF DS
POPF DS ; RESTORE FLAGS TO ORIG SETTINGS
RET ; RETURN TO CALLER
ERR_BEEP ENDP

; ROUTINE TO SOUND BEEPER
BEEP PROC NEAR
MOV AL,10110110B ; SEL TIM 2,LSB,MSB,BINARY
OUT TIMER+,AL ; WRITE THE TIMER MODE REG
JMP SHOR_S2 ; IO DELAY
MOV AX,533H ; DIVISOR FOR 896 HZ
OUT TIMER+2,AL ; WRITE TIMER 2 CNT - LSB
JMP SHORT_S2 ; IO DELAY
MOV AL,03 ; TURN SPEAKER ON
OUT PORT_B,AL ; WRITE TIMER 2 CNT - MSB
SUB CX,CX ; GET CURRENT SETTING OF PORT
MOV AH,AL ; SAVE THAT SETTING
JMP SHORT_S2 ; IO DELAY
OUT PORT_B,AL ; TURN SPEAKER ON
G7: LOOP G7 ; SET CNT TO WAIT 500 MS
DEC BL ; DELAY BEFORE TURNING OFF
JNZ G7 ; DELAY CNT EXPIRED?
                                ; NO - CONTINUE BEEPING SPK
0057      BEEP
0057      B0 B6
0058      E9 00
0059      E9 00
005D      B8 0533
0060      E6 42
0062      EB 00
0064      BA C0
0065      E5 62
0068      E8 61
006A      8A E0
006C      EB 00
006E      DC 03
0070      E7 61
0072      2B C9
0074      E2 FE
0076      FE CB
0078      75 FA

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007A 8A C4          MOV    AL,AH      ; RECOVER VALUE OF PORT
007C EG 61          OUT   PORT_B,AL
007E C3             RET
007F BEEP           ENDP

;----- THIS PROCEDURE WILL SEND A SOFTWARE RESET TO THE KEYBOARD.
;----- SCAN CODE 'AA' SHOULD BE RETURNED TO THE CPU,
;----- SCAN CODE '65' IS DEFINED FOR MANUFACTURING TEST
;----- -----
;----- KBD_RESET  PROC NEAR
007F B0 FF          MOV    AL,0FFH    ; SET KEYBOARD RESET COMMAND
0081 E8 0000 E        CALL  AH1_80N2
0084 E3 23          JCZ   G13       ; GO IF ERROR
0086 3C FA          CMP    AL,KB_ACK
0088 75 1F          JNZ   G13       ;
008A B0 FD          MOV    AL,OFDH    ; ENABLE KEYBOARD INTERRUPTS
008C E6 21          OUT   INTA01,AL
008E C6 06 006B R 00  MOV    INTR_FLAG,O
0093 FB              STI
0094 B3 0A          MOV    BL,10     ; TRY FOR 400 MSEC
0096 28 C9          SUB   CX,CX     ; SETUP INTERRUPT TIMEOUT CNT
0098 F6 06 006B R 02 G11: TEST  INTR_FLAG,02H
0099 75 06          JNZ   G12       ; DID A KEYBOARD INTR OCCUR?
009F E2 F7          LOOP  G11       ; YES - READ SCAN CODE RETURNED
00A1 FE CB          DEC   BL
00A3 75 F3          JNZ   G11       ; NO - LOOP TILL TIMEOUT
00A5 E4 60          G12: IN    AL,PORT_A
00A7 8A D8          MOV    BL,AL     ; READ KEYBOARD SCAN CODE
00A9 C3             G13: RET      ; SAVE SCAN CODE JUST READ
00AA KBD_RESET      ENDP

00AA DDS             PROC NEAR
00AA 50              PUSH  AX
00AB BB ----- R      MOV   AX,DATA
00AE 8E D8          MOV   DS,AX
00B0 58              POP   AX
00B1 C3             RET
00B2 DDS             ENDP

;----- TEMPORARY INTERRUPT SERVICE ROUTINE
;----- 1. THIS ROUTINE IS ALSO LEFT IN PLACE AFTER THE
;----- POWER ON DIAGNOSTICS TO SERVICE UNUSED
;----- INTERRUPT VECTORS. LOCATION 'INTR_FLAG' WILL
;----- CONTAIN ONE OF THE FOLLOWING:
;----- 1. '00' FOR ALL OF HARDWARE INT. THAT
;----- CAUSED CODE TO BE EXECUTED.
;----- 2. 'FF' FOR NON-HARDWARE INTERRUPTS THAT WAS
;----- EXECUTED ACCIDENTALLY.
;----- -----
;----- D11  PROC NEAR
00B2 1E              ASSUME DS:DATA
00B3 52              PUSH  DS
00B4 50              PUSH  DX
00B5 53              PUSH  AX
00B6 E8 00AA R        PUSH  BX
00B7 00              CALL  DS
00B8 00              MOV   AL,0BH    ; SAVE REG AX CONTENTS
00B9 EB 00          MOV   AL,INTB00
00B8 E6 20          OUT  INTA00,AL
00B0 EB 00          JMP   SHORT $+2
00BF 90              NOP
00C0 E4 20          IN   AL,INTA00
00C2 8A E0          MOV   AL,INTB00
00C3 04 04          OR   AL,AH    ; READ IN-SERVICE REG
00C5 75 04          JNZ   HW_INT
00C6 B4 FF          MOV   AH,0FFH
00CA EB 2A          JMP   SHORT SET_INTR_FLAG
00CC 00              ; SET FLAG TO FF IF NON-HARDWARE
00C0 B0 08          MOV   AL,0BH    ; READ IN-SERVICE REG INT CHIP 2
00C1 E6 A0          OUT  INTB00,AL
00D0 EB 00          JMP   SHORT $+2
00D2 E4 A0          IN   AL,INTB00
00D4 8A F8          MOV   BH,AL    ; IO DELAY
00D6 04 FF          OR   BH,BH    ; CHECK THE SECOND INT CHIP
00D7 74 E6          JZ   NOT_SEC
00DA E4 A1          IN   AL,INTB01
00DC 0A C7          OR   AL,BH    ; SAVE IT
00DE EB 00          JMP   SHORT $+2
00E0 E6 A1          IN   AL,INTB01
00E2 00 00          OUT  AL,00
00E4 EB 00          JMP   SHORT $+2
00E6 E6 A0          OUT  INTB00,AL
00E8 E4 21          NOT_SEC: IN  AL,INTA01
00EA EB 00          JMP   SHORT $+2
00EC DA C4          OR   AL,AH    ; SEND EOI TO SECOND CHIP
00E7 74 E6          JZ   NOT_SEC
00F0 EB 00          OUT  INTA01,AL
00F2 B0 20          JMP   SHORT $+2
00F4 E6 20          MOV   AL,EO1    ; IO DELAY
00F6 B0 26 006B R      OUT  INTA00,AL
00FA 5B              SET_INTR_FLAG: INTR_FLAG,AH
00FB 58              POP   BX
00FC 5A              POP   AX
00FD 1F              POP   DX
00FE CF              DUMMY_RETURN_1: RET
00FF D11             ENDP

;----- HARDWARE INT 13 (LEVEL 75H) -----
;----- SERVICE X287 INTERRUPTS
;----- THIS ROUTINE FIELDS X287 INTERRUPTS AND CONTROL
;----- IS PASSED TO THE NMI INTERRUPT HANDLER FOR
;----- COMPATABILITY.
;----- -----
;----- INT_287  PROC NEAR
00FF 50              PUSH  AX
0100 32 C0          XOR   AL,AL
0102 E6 F0          OUT  X287,AL
0104 B0 20          MOV   AL,EO1    ; REMOVE THE INT REQUEST
0106 E6 A0          OUT  INTB00,AL
0108 E6 20          OUT  INTA00,AL
010A 58              POP   AX
010B CD 02          INT  2       ; ENABLE THE INTERRUPT
                                         ; THE SLAVE
                                         ; THE MASTER
                                         ; RESTORE AX
                                         ; GIVE CONTROL TO NMI

```

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010D  CF          IRET          ; RETURN
010E ENDP

;-----HARDWARE INT 9 (LEVEL 71H)-----
;-----REDIRECT SLAVE INTERRUPT 9 TO INTERRUPT LEVEL 2-----
;-----THIS ROUTINE FIELDS LEVEL 9 INTERRUPTS AND-----
;-----CONTROL IS PASSED TO MASTER INTERRUPT LEVEL 2-----
;-----



010E
010E 50          RE_DIRECT PROC NEAR
010F B0 20        PUSH AX           ; SAVE AX
0111 E6 A0        MOV AL,EOI
0113 58          OUT INTB00,AL    ; EOI TO SLAVE INT CONTROLLER
0114 CD 0A        POP AX           ; RESTORE AX
0116 CF          INT OAH         ; GIVE CONTROL TO HARDWARE LEVEL 2
0117 ENDP

IRET          ; RETURN

RE_DIRECT ENDP

;-----PRINT A SEGMENT VALUE TO LOOK LIKE A 21 BIT ADDRESS-----
;-----DX MUST CONTAIN SEGMENT VALUE TO BE PRINTED-----
;-----



0117
0119 8A C6        PRT_SEG PROC NEAR
011C 8A C2        MOV AL,DX         ; GET MSB
011E E8 0000 E    CALL XPC_BYT
0121 B8 30        MOV AL,DI         ; LSB
0123 E8 0000 E    CALL XPC_BYT
0126 B8 20        MOV AL,DL         ; PRINT A '0'
0128 E8 0000 E    CALL PRT_HEX
012B B8 20        MOV AL,DL         ; SPACE
012C C3          CALL PRT_HEX
012C RET          ; ;
PRT_SEG ENDP
CODE ENDS
END

```



TITLE 12/16/83 TEST5 EXCEPTION INTERRUPT HANDLER  
LIST

```

PUBLIC POST5
PUBLIC EXC_00
PUBLIC EXC_01
PUBLIC EXC_02
PUBLIC EXC_03
PUBLIC EXC_04
PUBLIC EXC_05
PUBLIC EXC_06
PUBLIC EXC_07
PUBLIC EXC_08
PUBLIC EXC_09
PUBLIC EXC_10
PUBLIC EXC_11
PUBLIC EXC_12
PUBLIC EXC_13
PUBLIC EXC_14
PUBLIC EXC_15
PUBLIC EXC_16
PUBLIC EXC_17
PUBLIC EXC_18
PUBLIC EXC_19
PUBLIC EXC_20
PUBLIC EXC_21
PUBLIC EXC_22
PUBLIC EXC_23
PUBLIC EXC_24
PUBLIC EXC_25
PUBLIC EXC_26
PUBLIC EXC_27
PUBLIC EXC_28
PUBLIC EXC_29
PUBLIC EXC_30
PUBLIC EXC_31

PUBLIC SYS_32
PUBLIC SYS_33
PUBLIC SYS_34
PUBLIC SYS_35
PUBLIC SYS_36
PUBLIC SYS_37
PUBLIC SYS_38

```

0000 C INCLUDE SEGMENT.SRC  
0000 C CODE SEGMENT BYTE PUBLIC  
C

```

;----- EXCEPTION INTERRUPT ROUTINE -----
ASSUME CS:CODE, DS:ABS0
POST5:
EXC_00:
MOV AL,90H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_01:
MOV AL,91H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_02:
MOV AL,92H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_03:
MOV AL,93H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_04:
MOV AL,94H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_05:
MOV AL,95H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

0019 06
PUSH ES
MOV AX,ES_TEMP ; LOAD ES REGISTER
MOV ES,AX

;----- FIX BOUND PARAMETERS
001F 2B FF
0021 26: C7 05 0000
0026 26: C7 45 02 7FFF ; SET SECOND TO 07FFF
002C 07

002D 80 95 ;<><>SET CHECKPOINT<><>
002E E9 00D7 R ; GO TEST IF EXCEPTION WAS EXPECTED
EXC_06:
MOV AL,96H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_07:
MOV AL,97H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_08:
MOV AL,98H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_09:
MOV AL,99H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_10:
MOV AL,9AH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_11:
MOV AL,9BH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_12:
MOV AL,9CH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_13:
MOV AL,9DH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_14:
MOV AL,9EH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_15:
MOV AL,9FH ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_16:
MOV AL,0A0H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_17:
MOV AL,0A1H ;<><>SET CHECKPOINT<><>
JMP TEST_EXC ; GO TEST IF EXCEPTION WAS EXPECTED

EXC_18:
MOV AL,0A2H ;<><>SET CHECKPOINT<><>

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```

0070 EB 65 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0073 B0 A2             MOV     AL,0A2H          ;<><>SET CHECKPOINT<><><>
0075 EB 60 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0078 B0 A3             MOV     AL,0A3H          ;<><>SET CHECKPOINT<><><>
007A EB 5B 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
007D B0 A4             MOV     AL,0A4H          ;<><>SET CHECKPOINT<><><>
007F EB 56 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0082 B0 A5             MOV     AL,0A5H          ;<><>SET CHECKPOINT<><><>
0084 EB 51 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0087 B0 A6             MOV     AL,0A6H          ;<><>SET CHECKPOINT<><><>
0089 EB 4C 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
008C B0 A7             MOV     AL,0A7H          ;<><>SET CHECKPOINT<><><>
008E EB 47 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0091 B0 A8             MOV     AL,0A8H          ;<><>SET CHECKPOINT<><><>
0093 EB 42 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
0096 B0 A9             MOV     AL,0A9H          ;<><>SET CHECKPOINT<><><>
0098 EB 3D 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
009B B0 AA             MOV     AL,0AAH          ;<><>SET CHECKPOINT<><><>
009D EB 38 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
00A0 B0 AB             MOV     AL,0ABH          ;<><>SET CHECKPOINT<><><>
00A2 EB 33 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
00A5 B0 AC             MOV     AL,0ACH          ;<><>SET CHECKPOINT<><><>
00A7 EB 2E 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
00AA B0 AD             MOV     AL,0ADH          ;<><>SET CHECKPOINT<><><>
00AC EB 29 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED
00AF B0 AE             MOV     AL,0AEH          ;<><>SET CHECKPOINT<><><>
00B1 EB 24 90           JMP     TEST_EXC          ; GO TEST IF EXCEPTION WAS EXPECTED

00B4 SYS_32             MOV     AL,0AFH          ;<><>SET CHECKPOINT<><><>
00B6 EB 1F 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00B9 B0 B0             MOV     AL,0B0H          ;<><>SET CHECKPOINT<><><>
00BDE EB 1A 90          JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00BE B0 B1             MOV     AL,0B1H          ;<><>SET CHECKPOINT<><><>
00C0 EB 15 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00C3 B0 B2             MOV     AL,0B2H          ;<><>SET CHECKPOINT<><><>
00C5 EB 10 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00C8 B0 B3             MOV     AL,0B3H          ;<><>SET CHECKPOINT<><><>
00CA EB 0B 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00CD B0 B4             MOV     AL,0B4H          ;<><>SET CHECKPOINT<><><>
00CF EB 06 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00D2 B0 B5             MOV     AL,0B5H          ;<><>SET CHECKPOINT<><><>
00D4 EB 01 90           JMP     TEST_EXC          ; GO TEST IF INTERRUPT WAS EXPECTED
00D7 TEST_EXC            OUT    MFG_PORT,AL      ; OUTPUT THE CHECKPOINT
00D9 E6 80             CMP    AL,0AEH          ; CHECK FOR EXCEPTION
00DB 77 22             JA    TEST_EXCO         ; GO IF A SYSTEM INT

00DD 1E               PUSH   DS              ; SAVE THE CURRENT DATA SEGMENT
00DF 50               PUSH   AX              ; RESTORE REGS
00E0 0B 0008           MOV    AX,GDT_PTR
00E2 8E 08             MOV    DS,AX
00E4 C7 06 0048 FFFF  MOV    DS:ES_TEMP,SEG LIMIT,MAX SEG LEN
00EA C6 06 004D 93    MOV    BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),CPLO_DATA_ACCESS
00EF 0048              MOV    AX,ES_TEMP
00F1 8C C0              MOV    ES,AX
00F4 1B               POP    AX
00F5 1F               POP    DS
00F6 5A               POP    DX
00F7 59               POP    CX
00F8 51               PUSH   CX
00F9 53 F9 40          CHG    CX,SYST_ROM_CS
00FC 75 01             JNZ    TEST_EXCO        ; CONTINUE IF ERROR CODE
00FE 52               PUSH   DX
                                         ; PUT SEGMENT BACK ON STACK

00FF TEST_EXCO          XCHG   AH,AL          ; SAVE THE CHECKPOINT
0101 E4 88             IN    AL,DMA_PAGE+0AH
0103 3A C4             CMP    AL,AH          ; WAS THE EXCEPTION EXPECTED?
0105 74 0E             JZ    TEST_EXC3        ; GO IF YES
0107 TEST_EXC1          TEST   MFG_PORT,AL      ; CHECK THE CURRENT CKPT
0109 E4 80             CMP    AL,03BH          ; HALT IF CKPT BELOW 3BH
010B 3C 3B             JB    TEST_EXC2        ;
0108 72 01             IRET
010D CF               TEST   EXC2
010E 86 E0             XCHG   AH,AL          ; OUTPUT THE CURRENT CHECKPOINT
0110 E6 80             OUT    MFG_PORT,AL      ; <><> CKPT 90 THRU B5 <><>
                                         ; INSURE SYSTEM HALT
0112 F4               HLT
0113 EB F9             JMP    TEST_EXC2
0115 2A C0             TEST   EXC3
0117 E5 BB             OUT    AL,AL          ; CLEAR DMA PAGE
0119 BB 0100           MOV    DMA_PAGE+0AH,AL
011C CF               IRET
011D CODE              ENDS
                                         ; USED FOR BOUND INSTR EXPECTED INT5
                                         ; RETURN

```

TITLE 01/03/84 TEST6 POWER ON SELF TEST  
 LIST  
 PUBLIC STCTST\_CNT  
 PUBLIC ROM\_FRR  
 PUBLIC BOOT\_STRAP\_1  
 PUBLIC XMIT\_8042  
 PUBLIC POST6  
 PUBLIC H5

0000 C INCLUDE SEGMENT.SRC  
 C CODE SEGMENT BYTE PUBLIC  
 C  
 .  
 EXTRN E0:NEAR  
 EXTRN E\_MSG:NEAR  
 EXTRN KBD\_RESET:NEAR  
 EXTRN XPC\_BYTEx:NEAR  
 EXTRN F1:NEAR  
 EXTRN NW\_VTOR\_TABLE:NEAR  
 EXTRN NM\_INT:NEAR  
 EXTRN PRINT\_SCREEN\_1:NEAR  
 EXTRN BLINK\_INT:NEAR  
 EXTRN PRT\_HEX:NEAR  
 EXTRN F3B:NEAR  
 EXTRN NM\_INT:NEAR  
 EXTRN XPC\_BYTEx:NEAR  
 EXTRN E1:NEAR  
 EXTRN ROM\_CHECK:NEAR  
 EXTRN ROS\_CHECKSUM:NEAR  
 EXTRN ERR\_K:NEAR  
 EXTRN F3:NEAR  
 EXTRN ERR\_BEEP:NEAR  
 EXTRN P\_MSG:NEAR  
 EXTRN START\_1:NEAR  
 EXTRN F4:NEAR  
 EXTRN NM\_INT:NEAR  
 EXTRN DDS:NEAR  
 EXTRN F3A:NEAR  
 EXTRN DISK\_BASE:NEAR  
 EXTRN F3D:NEAR  
 EXTRN PROT\_PRT\_DTDOWN:NEAR  
 EXTRN SYSINI1:NEAR  
 EXTRN PROT\_PRT\_HEX:NEAR  
 EXTRN DISK\_IO:NEAR  
 EXTRN HD\_INT:NEAR  
 EXTRN C8042:NEAR  
 EXTRN BOOT\_INVA:NEAR  
 PAGE ASSUME CS:CODE  
 ASSUME DS:DATA

0000 POST6 PROC NEAR  
 ;-----  
 ; THIS SUBROUTINE PERFORMS A READ/WRITE STORAGE TEST ON A BLOCK :  
 ; OF STORAGE.  
 ; ENTRY REQUIREMENTS:  
 ; DS = ADDRESS OF STORAGE SEGMENT BEING TESTED  
 ; DS = ADDRESS OF STORAGE SEGMENT BEING TESTED  
 ; CX = WORD COUNT OF STORAGE BLOCK TO BE TESTED  
 ; EXIT PARAMETERS:  
 ; ZERO FLAG = 0 IF STORAGE ERROR (DATA COMPARE OR PARITY  
 ; CHECK). AL=0 DENOTES A PARITY CHECK, ELSE AL=XOR'ED  
 ; BIT PATTERN OF THE EXPECTED DATA PATTERN VS THE ACTUAL  
 ; DATA READ.  
 ; AX,BX,CX,D1, AND SI ARE ALL DESTROYED.  
 ;-----  
 STGTEST\_CNT PROC NEAR  
 MOV BX,CX ; SAVE WORD COUNT OF BLOCK TO TEST  
 IN AL,PORT\_B  
 JMP SHORT \$+2 ; IO DELAY  
 OR AL,RAM\_PAR\_OFF ; TOGGLE PARITY CHECK LATCHES  
 OUT PORT\_B\_AL  
 JMP SHORT \$+2 ; IO DELAY  
 AND AL,RAM\_PAR\_ON ;  
 OUT PORT\_B\_AL  
 ;----- ROLL A BIT THROUGH THE FIRST WORD  
 C1: MOV DX,0001H ; WRITE THE INIT DATA PATTERN  
 MOV CX,16 ; ROLL 16 BIT POSITIONS  
 SUB DI,DI ; START AT BEGINNING OF BLOCK  
 SUB SI,SI ; INITIALIZE DESTINATION POINTER  
 MOV AX,DX ; GET THE PATTERN  
 STOSW ; STORE DATA PATTERN  
 XOR AX,DX ; START AT SECONDING  
 LODSW ; GET THE FIRST WRITTEN  
 JZ C1\_A ; INSURE DATA AS EXPECTED  
 C1\_A: XOR AX,DX ; EXIT IF NOT  
 SHL DX,1 ; SHIFT BIT TO NEXT BIT POSITION  
 LOOP C1 ; SHIFT LOOP TILL DONE  
 ;----- CHECK CAS LINES FOR HIGH BYTE LOW BYTE  
 C1\_B: SUB DI,DI ; START AT BEGINNING OF BLOCK  
 SUB SI,SI ; INITIALIZE DESTINATION POINTER  
 SUB AX,AX ; WRITE 0  
 MOV DX,0FF00H ;  
 STOSW ; STORE DATA PATTERN  
 MOV DI,1 ; AT THE FIRST ODD LOCATION  
 MOV BYTE PTR [DI],OFFH ; WRITE A BYTE OF FF  
 SUB DI,DI ;  
 MOV AX,WORD PTR [DI] ; GET THE DATA  
 XOR AX,DX ; CHECK THE FIRST WRITTEN  
 JZ C1\_B ;  
 JMP C1\_B ; EXIT IF NOT  
 C1\_B: SUB DI,DI ; START AT BEGINNING OF BLOCK  
 SUB AX,AX ; WRITE 0  
 MOV DX,000FFH ;  
 STOSW ; STORE DATA PATTERN  
 MOV DI,DI ; AT THE FIRST EVEN LOCATION  
 MOV BYTE PTR [DI],OFFH ; WRITE A BYTE OF FF  
 SUB DI,DI ; BUS SETTLE  
 MOV AX,WORD PTR [DI] ; GET THE DATA  
 XOR AX,DX ; CHECK THE FIRST WRITTEN  
 JNZ C1\_B ; EXIT IF NOT  
 ;----- TEMP SAVE FOR AX (PUSH NOT ALLOWED)  
 005B E6 B9 OUT DMA\_PAGE+8,AL ; SAVE AX  
 005C 86 C4 XCHG AL,AF ;  
 005F EB 00 JMP SHORT \$+2 ;  
 0061 E6 BA OUT DMA\_PAGE+9,AL ;

```

;----- CHECK IO OR BASE RAM
0063 E4 61           IN    AL,PORT_B          ; CHECK FOR IO/PAR CHECK
0064 20 D0           AND   AL,PARITY_ERR      ; STRIP UNWANTED BITS
0067 86 C4           XCHG  AL,AH          ; SAVE ERROR
0069 E4 87           IN    AL,DMA_PAGE+6     ; CHECK FOR R/W OR IO ERR
006B 22 E0           AND   AH,AL          ; 

;----- RESTORE AX
006D E4 8A           IN    AL,DMA_PAGE+9     ; GET AH
006F 86 C4           XCHG  AL,AH          ; GET AL
0071 E4 89           IN    AL,DMA_PAGE+8     ; 

;----- PARITY ERROR EXIT
0073 75 50           JNZ   C13             ; GO IF YES
0075 BA AA55          MOV   DX,0AA55H        ; WRITE THE INIT DATA PATTERN
0078 2B FF           MOV   DI,DI          ; START AT BEGINNING OF BLOCK
007A 2B F6           SUB   DI,DI          ; INITIALIZE DESTINATION POINTER
007C 80 CB           MOV   SI,SI          ; SETUP BYTE COUNT FOR LOOP
007E 80 CB           MOV   CX,CX          ; GET THE FIRST WORD
0080 F3 / AB         REP   STOSW         ; STORE 64K BYTES (32K WORDS)
0082 8B CB           MOV   CX,BX          ; SET COUNT
0084 2B F6           SUB   SI,SI          ; START AT BEGINNING
0086 AD              LODSW            ; GET THE FIRST WRITTEN
0088 31 C2           XOR   AX,DX          ; INSURE DATA AS EXPECTED
0089 75 3A           JNZ   C13             ; EXIT IF NOT
008B E2 F9           LOOP  C6             ; LOOP TILL DONE

;----- TEMP SAVE FOR AX (PUSH NOT ALLOWED)
008D E6 80           OUT   DMA_PAGE+8,AL     ; SAVE AX
008F 86 C4           XCHG  AL,AH          ; 
0091 EB 00           JMP   SHORT $+2        ; 
0093 E6 8A           OUT   DMA_PAGE+9,AL     ; 

;----- CHECK IO OR BASE RAM
0095 E4 61           IN    AL,PORT_B          ; CHECK FOR IO/PAR CHECK
0097 24 C0           AND   AL,PARITY_ERR      ; STRIP UNWANTED BITS
0099 86 C4           XCHG  AL,AH          ; SAVE ERROR
009B E4 87           IN    AL,DMA_PAGE+6     ; CHECK FOR R/W OR IO ERR
009D 22 E0           AND   AH,AL          ; 

;----- RESTORE AX
009F E4 8A           IN    AL,DMA_PAGE+9     ; GET AH
00A1 86 C4           XCHG  AL,AH          ; GET AL
00A3 E4 89           IN    AL,DMA_PAGE+8     ; 

;----- PARITY ERROR EXIT
00A5 75 1E           JNZ   C13             ; GO IF YES

;----- CHECK FOR END OF 64K BLOCK
00A7 23 D2           AND   DX,DX          ; ENDING ZERO PATTERN WRITTEN TO STG ?
00A9 74 1A           JZ    C14             ; YES - RETURN TO CALLER WITH AL=0

;----- SETUP NEXT PATTERN
00AB 81 FA 55AA        CMP   DX,055AAH        ; CHECK IF LAST PATTERN =55AA
00AF 74 0F           JZ    C9             ; GO IF NOT
00B1 81 FA 0101        CMP   DX,0101H         ; LAST PATTERN 0101?
00B5 74 0F           JZ    C10             ; GO IF YES
00B7 BA 55AA          MOV   DX,055AAH        ; WRITE 55AA TO STORAGE
00BA EB BC           JMP   C3             ; 

;----- LAST PATTERN = 0000
00BC 2B D2           C8:  SUB   DX,DX          ; WRITE 0000 TO STORAGE
00BE EB BB           JMP   C3             ; 

;----- INSURE PARITY BITS ARE NOT STUCK ON
00C0 BA 0101          C9:  MOV   DX,0101H         ; WRITE 0101 TO STORAGE
00C3 EB B3           JMP   C3             ; 

;----- EXIT
00C5 C3               C13: RET             ; 

;----- CHECKER BOARD TEST
00C6 2B FF           C10: SUB   DI,DI          ; POINT TO START OF BLOCK
00C8 8B CB           MOV   CX,BX          ; GET THE BLOCK COUNT
00CA D1 E9           SHR   CX,1           ; DIVIDE BY 2
00CB 00 5555          MOV   AX,0101010101010101B ; FIRST CHECKER PATTERN
00CC AB              STOSW            ; WRITE IT
00DD B8 AAAA          MOV   AX,1010101010101010B ; SECOND CHECKER PATTERN
00D3 AB              STOSW            ; WRITE IT
00D4 E2 F6           C11: LOOP  C11             ; DO IT FOR CX COUNT
00D5 2B F6           SUB   SI,SI          ; POINT TO START OF BLOCK
00D6 00 68             MOV   CX,BX          ; GET THE BLOCK COUNT
00DA D1 E9           SHR   CX,1           ; DIVIDE BY 2
00DC AD              LODSW             ; GET THE DATA
00DD 35 5555          XOR   AX,101010101010101B ; CHECK CORRECT
00E0 75 E3           LODSW             ; EXIT IF NOT
00E2 A9              XOR   AX,1010101010101010B ; GET NEXT DATA
00E3 75 AAAA          JNZ   C13             ; GO IF NOT CORRECT
00E5 75 DD           LODSW             ; CONTINUE TILL DONE
00E8 E2 F2           LOOP  C12             ; 

;----- TEMP SAVE FOR AX (PUSH NOT ALLOWED)
00EA E6 89           OUT   DMA_PAGE+8,AL     ; SAVE AX
00EC 86 C4           XCHG  AL,AH          ; 

```

TITLE 12/28/83 TEST2 EXCERPTION INTERRUPT TEST

**TEST.20 ADDITIONAL PROTECTED (VIRTUAL MODE) TEST DESCRIPTION**

THE PROCESSOR IS PUT IN PROTECTED MODE AND THE FOLLOWING FUNCTIONS ARE VERIFIED

1. VERIFY PROTECTED MODE  
THE MACHINE STATUS IS CHECK FOR VIRTUAL MODE
2. PROGRAMMED INTERRUPT TEST  
AN PROGRAMMED INTERRUPT 32 IS ISSUED AND VERIFIED
3. EXCEPTION INT 13 TEST  
A DESCRIPTOR SEGMENT LIMIT IS SET TO ZERO  
AND A WRITE TO THAT SEGMENT IS ATTEMPTED  
AN EXCEPTION 13 IS EXPECTED AND VERIFIED
4. LDT/SDT/LTR/STR TEST  
LOAD LDT, SDT, LTR AND VERIFY CORRECT  
LOAD TASK REGISTER AND VERIFY CORRECT  
THEY ARE VERIFIED VIA THE STORE INSTRUCTION
5. THE CONTROL FLAGS OF THE 286 FOR DIRECTION  
ARE VERIFIED VIA THE STD AND CLD COMMANDS  
IN PROTECTED MODE
6. BOUND INSTRUCTION TEST (EXC INT 5)  
CREATE A SIGNED ARRAY INDEX WITHIN AND  
OUTSIDE THE LIMITS. CHECK THAT NO EXC INT 5  
IF WITHIN LIMIT AND THAT AN EXC INT 5  
OCCURS IF OUTSIDE THE LIMITS.
7. PUSH ALL POP ALL TEST  
SET ALL GENERAL PURPOSE REGS TO DIFFERENT  
VALUES ISSUE A PUSH ALL, CLEAR THE REGS  
ISSUE A POP ALL AND VERIFY CORRECT.
8. CHECK FOR READ/WRITE/VERIFY INSTRUCTIONS  
THE ACCESS BYTE IS SET TO READ ONLY THEN TO  
A WRITE ONLY AND THE VERR/VERM INST ARE  
VERIFIED.
9. CAUSE AN INTERRUPT 13 VIA A WRITE TO A  
REALLY FAR SEGMENT
10. VERIFY THE ARPL INSTRUCTION FUNCTIONS  
SET THE RPL FIELD OF A SELECTOR AND  
VERIFY THAT CURRENT SELECTOR RPL IS SET  
CORRECTLY.
11. VERIFY THE LAR INSTRUCTION FUNCTIONS
12. VERIFY THE LSL INSTRUCTION FUNCTIONS
13. LOW MEG CHIP SELECT TEST

.LIST PUBLIC POST7

80000

```
C INCLUDE SEGMENT.SRC  
C CODE SEGMENT BYTE PUBLIC
```

```

0035 BC FFFF          MOV    SP,MAX_SEG_LEN-2
;-----VERIFY PROTECTED MODE
;-----  

0036 0F               SMSW   AX
0037 + ??0000 LABEL   BYTE
0038 D1 E0             SH     AX,1
0039 + ??0001 LABEL   BYTE
0039 ORG   OFFSET CS:??0000
0039 + DB    001H
0038 ORG   OFFSET CS:??0001
0038 A9 0001 TEST   AX,VIRTUAL_ENABLE ; ARE WE IN PROTECTED MODE
0038 75 03 JNZ    T1
0040 E9 02EA R           JMP    ERROR_EXIT ; ERROR IF NOT  

0043 B0 F1             T7_1:  MOV    AL,OF1H ;<><><><><><><><><><><>
0045 E6 80             OUT   MFG_PORT,AL ;<><><>CHECKPOINT F1<><><>  

;-----  

0047 B0 AF             MOV    AL,0AFH ; SET EXCEPTION FLAG
0049 E6 BB             OUT   DMA_PAGE+0AH,AL ; FOR INT 10
004A 75 00 INT    32
004D 2B C9             SUB    CX,CX ; INTERRUPT
004E E4 BB             LOOPI  IN    AL,DMA_PAGE+0AH ; WAIT FOR INT
0051 22 C0             AND    AL,AL ; DID THE INTERRUPT OCCUR?
0053 E0 FA             LOOPNZ LOOP1 ;  

0055 74 03 JZ    T7_2 ; MISSING INTERRUPT
0057 E9 02EA R           JMP    ERROR_EXIT ;  

;----- CAUSE AN EXCEPTION INTERRUPT (GENERAL PROTECTION INT 13D)
005A B0 F2             T7_2:  MOV    AL,0F2H ;<><><><><><><><><>
005C E6 80             OUT   MFG_PORT,AL ;<><><>CHECKPOINT F2<><><>  

005E B0 9D             MOV    AL,9DH ; SET INT 13 FLAG
0060 E6 8B             OUT   DMA_PAGE+0AH,AL ; FOR THE INT HANDLER  

;----- MODIFY DESCRIPTOR TABLES
;-----  

0062 C7 06 0048 0000   MOV    DS:ES_TEMP.SEG_LIMIT,0 ; SET SEGMENT TO 0  

;----- CPLO, DATA ACCESS RIGHTS
0068 C6 06 004D 93   MOV    BYTE PTR DS:[ES_TEMP.DATA_ACC_RIGHTS],CPLO_DATA_ACCESS
0069 C6 06 004C 00   MOV    WORD PTR DS:[ES_TEMP.BASE_HI_BYTET],01 ; DO ALL TESTS ON 2ND 64K
0072 C7 06 004A 0000   MOV    WORD PTR DS:[ES_TEMP.BASE_LO_WORD],0  

;----- SET ES REGISTER
0078 B8 0048             MOV    AX,ES_TEMP ; LOAD ES
007B 8E C0             MOV    ES,AX ;  

;----- CAUSE AN EXCEPTION 13 INTERRUPT
007D 2B FF             SUB    DI,DI ; THIS SHOULD CAUSE AN EXCEPTION
007F 26: 8B 05           MOV    AX,ES:[DI]  

0082 2B C9             SUB    CX,CX ; WAIT FOR INT
0084 E4 BB             LOOP2: IN    AL,DMA_PAGE+0AH ; DID THE INTERRUPT OCCUR?
0086 22 C0             AND    AL,AL ;  

0088 E0 FA             LOOPNZ LOOP2 ; CONTINUE IF INTERRUPT
008A 74 03 JZ    T7_3 ; MISSING INTERRUPT
008C E9 02EA R           JMP    ERROR_EXIT ;  

008F  

;-----  

;----- VERIFY 286 LDT/SDT LTR/STR INSTRUCTIONS
;----- DESCRIPTION
;----- LOAD_LDT REGISTERS WITH A DESCRIPTOR
;----- VERIFY CORRECT
;-----  

;----- WRITE TO 286 LDT REGISTER
008F B0 F3             MOV    AL,0F3H ;<><><><><><><><><><>
0091 E6 80             OUT   MFG_PORT,AL ;<><><>CHECKPOINT F3<><><>
0093 BF 0078             MOV    DI,POST_LDTR ; REGISTER FROM THIS AREA  

0096 0F               + DB    00FH ; CLEAR AX
0097 + ??0002 LABEL   BYTE ; GET THE LDT SELECTOR
0097 8B D7             MOV    DX,DI
0097 + ??0003 LABEL   BYTE
0097 00               MOV    BX,DX
0097 + DB    000H
0097 ORG   OFFSET CS:??0002
0099 + DB    000H
0099 ORG   OFFSET CS:??0003  

;----- READ AND VERIFY 286 LDT SELECTOR
0099 2B C0             SUB    AX,AX ; CLEAR AX
0098 0F               SLDT   AX ; GET THE LDT SELECTOR
0099 + DB    00FH
0099 + ??0004 LABEL   BYTE
0099 03 C0             AND    AX,AX
0099 + ??0005 LABEL   BYTE
0099 ORG   OFFSET CS:??0004
0099 00               DB    000H
0099 ORG   OFFSET CS:??0005
0099 25 00F8             AND    AX,0FBH ; STRIP T1/RPL
0099 3D 0078             CMP    AX,POST_LDTR ; CORRECT SELECTOR?
0099 75 1B             JNZ    ERROR ; GO IF NOT  

;----- WRITE TO 286 TR
00A6 BF 0068             MOV    DI,POST_TR ; REGISTER FROM THIS AREA
00A9 0F               LTR    DI
00A9 + DB    00FH
00AA 8B DF             MOV    BX,DI
00AA + ??0006 LABEL   BYTE
00AA 00               + ??0007 LABEL   BYTE
00AA + DB    000H
00AA ORG   OFFSET CS:??0006
00AC 00               + DB    000H
00AC ORG   OFFSET CS:??0007  

;----- VERIFY 286 TR REGISTERS

```



```

;----- SET REGISTERS TO A KNOWN VALUE AND
;----- PUSH ALL, RESET THE REGISTERS POPALL
;----- AND VERIFY
;----- T7_9:
;----- MOV AL,0F5H ;<><><><><><><><><><>
;----- OUT MFG_PORT,AL ;><><>CHECKPOINT F5 <><><>
;----- MOV AX,01 ; SET AX=1
;----- MOV BX,AX ; SET BX=2
;----- INC BX
;----- MOV CX,BX ; SET CX=3
;----- INC CX
;----- MOV DX,CX ; SET DX=4
;----- INC DX
;----- MOV D1,DX ; SET D1=5
;----- INC SI,DI ; SET SI=6
;----- PUSH BP ; SAVE THE BP REGISTER
;----- MOV BP,SI ; SET BP=7
;----- INC BP
;----- PUSHA ; ISSUE THE PUSH ALL COMMAND
;----- DB 060H ; CLEAR ALL REGS
;----- SUB AX,AX
;----- MOV BX,AX
;----- MOV CX,AX
;----- MOV DX,AX
;----- MOV DI,AX
;----- MOV SI,AX
;----- MOV BP,AX
;----- POPA ; GET THE REGISTERS BACK
;----- DB 061H ; BP SHOULD BE 7
;----- CMP BP,07 ; RESTORE BP
;----- POP BP
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP AX,01 ; AX SHOULD BE 1
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP BX,02 ; BX SHOULD BE 2
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP CX,03 ; CX SHOULD BE 3
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP DX,04 ; DX SHOULD BE 4
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP DI,05 ; DI SHOULD BE 5
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- CMP SI,06 ; SI SHOULD BE 6
;----- JNZ ERROR_EXIT1 ; GO IF NOT
;----- JMP T7_10

;----- ERROR EXIT1:
;----- E9 02EA R
;----- JMP ERROR_EXIT

;----- VERIFY ACCESS RIGHTS FUNCTION CORRECTLY
;----- DESCRIPTION: SET ACCESS RIGHTS OF DESCRIPTER TO READ ONLY, VERIFY THE VERW/VERR INSTR, ACCESS A READ ONLY WITH A WRITE AND VERIFY AN EXCEPTION INT 13
;----- T7_10: MOV AL,0F6H ;<><><><><><><><><><>
;----- OUT MFG_PORT,AL ;><><>CHECKPOINT F6 <><><>
;----- MOV DS:ES_TEMP,SEG_LIMIT,MAX SEG_LEN ; SET SEGMENT TO OFFFFH
;----- MOV BYTE PTR DS:(ES_TEMP.BASE_HI_BYT),0 ;SET THE ADDRESS
;----- MOV DS:ES_TEMP,BASE_LO_WORD,0FOO0H

;----- MOV AX,ES_TEMP ; LOAD ES REGISTER
;----- MOV ES,AX ; THIS SEGMENT SHOULD BE WRITEABLE
;----- INSURE ACCESS RIGHTS MAY BE WRITTEN
;----- 3E
;----- SEGOV DS ; SET SEGMENT OVERRIDE TO START OF TABLE
;----- DB 03EH ; CHECK THE ACCESS RIGHTS OF ES_TEMP
;----- 0F
;----- VERW AX
;----- DB 00FH
;----- ??0014 LABEL BYTE
;----- ??0014 DB 00AH
;----- ??0015 LABEL BYTE
;----- ??0015 DB 000H
;----- ORG OFFSET CS:??0014
;----- ??0015 DB 000H
;----- ORG OFFSET CS:??0015
;----- JNZ ERROR_EXIT1 ; ERROR IF SEGMENT CAN NOT WRITE
;----- SET ACCESS RIGHTS TO READ ONLY
;----- C048
;----- MOV BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),91H
;----- MOV AX,ES_TEMP ; LOAD ES REGISTER
;----- MOV ES,AX
;----- 3E
;----- SEGOV DS ; SET SEGMENT OVERRIDE TO START OF TABLE
;----- DB 03EH ; CHECK THE ACCESS RIGHTS OF ES_TEMP
;----- 0F
;----- VERW AX
;----- DB 00FH
;----- ??0017 LABEL BYTE
;----- ??0017 DB 00AH
;----- ??0018 LABEL BYTE
;----- ??0018 DB 000H
;----- ORG OFFSET CS:??0017
;----- ??0018 DB 000H
;----- ORG OFFSET CS:??0018
;----- JZ ERROR_EXIT1 ; ERROR IF SEGMENT IS WRITEABLE
;----- B8 0048
;----- MOV AX,ES_TEMP ; INSURE THAT SEGMENT IS READABLE
;----- SEGOV DS
;----- DB 03EH
;----- 0F
;----- VERR AX
;----- DB 00FH
;----- ??001A LABEL BYTE
;----- ??001A DB 00AH
;----- ??001B LABEL BYTE
;----- ??001B DB 000H
;----- ORG OFFSET CS:??001A
;----- ??001B DB 000H
;----- ORG OFFSET CS:??001B
;----- JNZ ERROR_EXIT1 ; GO IF SEGMENT NOT READABLE
;----- CAUSE AN EXCEPTION 13 INTERRUPT
;----- B8 9D
;----- MOV AL,00DH ; SET EXCEPTION FLAG
;----- E6 8B
;----- OUT DMA_PAGE+0AH,AL ; FOR INT 13
;----- 2B F6
;----- SUB SI,SI

```

```

01D5 26: C6 04 00    MOV    BYTE PTR ES:[SI],00      : WRITE A BYTE THAT SHOULD
01D9 2B C9    SUB    CX,CX      : CAUSE AN EXCEPTION
01DB E4 8B    LOOPD: IN AL, DMA_PAGE+0AH   : WAIT FOR INT
01DD 22 C0    AND    AL,AL      : DID THE INTERRUPT OCCUR?
01DF EO FA    LOOPNZ LOOP    JNZ ERROR_EXIT1   : MISSING INTERRUPT

;----- RESTORE THE ACCESS RIGHTS BYTE

01E3 C6 06 004D 93  MOV    BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),CPL0_DATA_ACCESS

;----- VERIFY ADJUST RPL FIELD OF SELECTOR
;----- INSTRUCTION (ARPL) FUNCTIONS
;----- DESCRIPTION
;----- SET THE RPL FIELD OF A SELECTOR
;----- AND VERIFY THAT THE ZERO FLAG IS SET
;----- CORRECTLY AND THAT THE SELECTOR RPL
;----- FIELD IS SET CORRECTLY

01E8 B0 F7    MOV    AL,0F7H      ;<><><><><><><><><><><>
01EA E6 80    OUT   MFG_PORT,AL  ;<><>CHECKPOINT F7 <><><>
01EC BB 0048  MOV    AX,ES TEMP   ; PUT A SELECTOR IN AX
01EF BB 0060  MOV    BX,DS TEMP   ; PUT A SELECTOR IN BX
01F2 0D 0003  OR     AX,03H      ; MAKE ACCESS OF AX < BX

;----- NOTE BX = FIRST OPERAND AX = SECOND OPERAND

01F5 BB C3    ARPL AX,BX      ; ISSUE THE RPL COMMAND
+ ??001C LABEL BYTE      ; NOTE: SOURCE / TARGET REGS ARE REVERSED
+ ??001D LABEL BYTEx     ; DUE TO OPCODE BIT 1
01F5 63        MOV    AX,BX      ;
+ ORG   OFFSET CS:??001C   ;
+ DB    063H      ;
+ ORG   OFFSET CS:??001D   ;
01F7 75 9A    UNZ  ERROR_EXIT1  ; GO IF RPL HAS NOT CHANGED
01F9 80 E3 03  AND   BL,03H      ; STRIP UNWANTED BITS
01FC 80 FB 03  CMP   BL,03H      ; AS EXPECTED?
01FF 75 92    JNZ  ERROR_EXIT1  ; GO IF NOT

;----- CHECK THAT ACCESS RIGHTS DO NOT CHANGE

0201 BB 0060  MOV    BX,DS TEMP   ; PUT A SELECTOR IN BX
0204 BB 0048  MOV    AX,ES TEMP   ; PUT A SELECTOR IN AX
0207 BB CB 03  OR     BL,03H      ; MAKE ACCESS OF BX < AX

;----- NOTE BX = FIRST OPERAND AX = SECOND OPERAND

020A BB C3    ARPL AX,BX      ; ISSUE THE RPL COMMAND
+ ??001E LABEL BYTE      ; NOTE: SOURCE / TARGET REGS ARE REVERSED
+ ??001F LABEL BYTEx     ; DUE TO OPCODE BIT 1
020A 63        MOV    AX,BX      ;
+ ORG   OFFSET CS:??001E   ;
+ DB    063H      ;
+ ORG   OFFSET CS:??001F   ;
020C 74 85    JNZ  ERROR_EXIT1  ; GO IF RPL WAS NOT CHANGED
020E 80 53 03  AND   BL,03H      ; STRIP UNWANTED BITS
0211 80 FB 03  CMP   BL,03H      ; AS EXPECTED?
0214 75 2F    JNZ  ERROR_EXIT2  ; GO IF NOT

;----- VERIFY LOAD SEGMENT LIMIT (LSL)
;----- AND LOAD ACCESS RIGHTS (LAR) INSTR
;----- =====
;----- CHECK THE LAR INSTRUCTION
;----- =====

0216 B0 F8    MOV    AL,0FBH      ;<><><><><><><><><><><>
0218 E6 80    OUT   MFG_PORT,AL  ;<><>CHECKPOINT F8 <><><>

;----- SET THE DESCRIPTOR TO LEVEL 3

021A C6 06 004D F3  MOV    BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),CPL3_DATA_ACCESS
021F BB 0048  MOV    BX,ES TEMP   ;
0222 2B C0    SUB    AX,AX      ; CLEAR AX

;----- GET THE CURRENT DESCRIPTOR'S ACCESS RIGHTS

0224 0F        LAR    AX,BX      ; ISSUE THE LAR COMMAND
0225 BB C3    + ??0020 LABEL BYTE
0225 02        + ??0021 LABEL BYTEx
0225 02        + ORG   OFFSET CS:??0020
0227          + DB    002H      ;
+ ORG   OFFSET CS:??0021
;----- INSURE THE DESCRIPTOR WAS VISIBLE
0227 75 1C    JNZ  ERROR_EXIT2  ; GO IF LAR WAS NOT CHANGED

;----- THE DESCRIPTOR'S ACCESS RIGHTS MUST BE 3

0229 B0 FC F3  CMP    AH,CPL3_DATA_ACCESS  ; AS EXPECTED?
022C 75 17    JNZ  ERROR_EXIT2  ; GO IF NOT
;----- =====
;----- CHECK THE LSL (LOAD SEGMENT LIMITS)
;----- =====

022E B0 F9    MOV    AL,0FH       ;<><><><><><><><><><><>
0230 E6 80    OUT   MFG_PORT,AL  ;<><>CHECKPOINT F9 <><><>
0232 C7 06 0048 AAAA  MOV    DS:ES_TEMP.SEG_LIMIT,0AAAAH  ; SET SEGMENT LIMIT TO 0AAAAH

0238 C6 06 004D 93  MOV    BYTE PTR DS:(ES_TEMP.DATA_ACC_RIGHTS),CPL0_DATA_ACCESS
023D BB 0048  MOV    AX,ES TEMP   ; LOAD ES REGISTER

;----- GET THE DESCRIPTOR SEGMENT LIMIT
0240 0F        LSL    BX,AX      ;
0241 BB D8    + ??0022 LABEL BYTE
0241 03        + ??0023 LABEL BYTEx
0241 03        + ORG   OFFSET CS:??0022
0243          + DB    003H      ;
+ ORG   OFFSET CS:??0023
JZ    R07        ; GO IF OK

0245 F9 02EA R  ERROR_EXIT12: JMP   ERROR_EXIT  ; GO IF NOT SUCCESSFUL

```







TITLE GDT\_BLD - 09/26/83 BUILD THE GDT  
LIST

```

0000          C INCLUDE SEGMENT.SRC
0000          C CODE SEGMENT BYTE PUBLIC
0000          ASSUME CS:CODE
0000          ASSUME SS:NOTHING
0000          ASSUME DS:CODE
0000          ASSUME ES:NOTHING
0000          PUBLIC GDT_BLD
PAGE
;
;
; THE FOLLOWING DATA DEFINES THE PRE-INITIALIZED GDT.
; THESE MUST BE INITIALIZED IN THE ORDER IN WHICH THEY APPEAR
; IN THE GDT_DEF STRUCTURE DEFINITION AS IT IS IN SYSDATA.INC.
;

0000          GDT_DATA_START LABEL WORD
;
; FIRST ENTRY UNUSABLE
;
0000 0000      + DESCR_DEF    SEG, 0, 0, 0
0002 0000      + DW 0           ; Segment limit
0004 0000      + DW 0           ; Segment base address - low word
0005 00        + DW 0           ; Segment base address - high byte
0006 0000      + DB 0           ; Access rights byte
0006 0000      + DW 0           ; Reserved
;
; THE GDT ITSELF
;
0008 0088      + DESCR_DEF    SEG, GDT_LEN, GDT_LOC, 0, CPL0_DATA_ACCESS
000A D8A0      + DW GDT_LEN     ; Segment limit
000C 00        + DW GDT_LOC     ; Segment base address - low word
000D 93        + DB 0           ; Segment base address - high byte
000E 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
000E 0000      + DW 0           ; Reserved
PAGE
;
; THE SYSTEM IDT DESCRIPTOR
;
0010 0800      + DESCR_DEF    SEC, SYS_IDT_LEN, SYS_IDT_LOC, 0, CPL0_DATA_ACCESS
0012 D0A0      + DW SYS_IDT_LEN   ; Segment limit
0014 00        + DW SYS_IDT_LOC   ; Segment base address - low word
0015 93        + DB 0           ; Segment base address - high byte
0016 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
0016 0000      + DW 0           ; Reserved
;
; THE SYSTEM DATA AREA DESCRIPTOR
;
0018 0300      + DESCR_DEF    SEG, SDA_LEN, SDA_LOC, 0, CPL0_DATA_ACCESS
001A 0000      + DW SDA_LEN     ; Segment limit
001C 00        + DW SDA_LOC     ; Segment base address - low word
001D 93        + DB 0           ; Segment base address - high byte
001E 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
001E 0000      + DW 0           ; Reserved
PAGE
;
; COMPATIBLE MONOCHROME CRT
;
0020 1000      + DESCR_DEF    SEG, MCRT_SIZE, MCRT@_LO, MCRT@_HI, CPL0_DATA_ACCESS
0022 0000      + DW MCRT_SIZE    ; Segment limit
0024 0B        + DW MCRT@_LO     ; Segment base address - low word
0025 93        + DB MCRT@_HI     ; Segment base address - high byte
0026 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
0026 0000      + DW 0           ; Reserved
;
; COMPATIBLE COLOR CRT
;
0028 4000      + DESCR_DEF    SEG, CCRT_SIZE, CCRT@_LO, CCRT@_HI, CPL0_DATA_ACCESS
002A 8000      + DW CCRT_SIZE    ; Segment limit
002C 0B        + DW CCRT@_LO     ; Segment base address - low word
002D 93        + DB CCRT@_HI     ; Segment base address - high byte
002E 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
002E 0000      + DW 0           ; Reserved
;
; ENHANCED COLOR CRT - ONE ENTRY FOR EACH 64K
;
0030 FFFF      + DESCR_DEF    SEG, ECCRT_SIZE, ECCRT@_LO_LO, ECCRT@_LO_HI, CPL0_DATA_ACCESS
0032 0000      + DW ECCRT_SIZE   ; Segment limit
0034 04        + DW ECCRT@_LO_LO   ; Segment base address - low word
0035 93        + DB ECCRT@_LO_HI   ; Segment base address - high byte
0036 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
0036 0000      + DW 0           ; Reserved
;
; SECOND PART OF CRT
;
0038 FFFF      + DESCR_DEF    SEG, ECCRT_SIZE, ECCRT@_HI_LO, ECCRT@_HI_HI, CPL0_DATA_ACCESS
003A 0000      + DW ECCRT_SIZE   ; Segment limit
003C 0C        + DW ECCRT@_HI_LO   ; Segment base address - low word
003D 93        + DB ECCRT@_HI_HI   ; Segment base address - high byte
003E 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
003E 0000      + DW 0           ; Reserved
PAGE
;
; CODE SEGMENT FOR POST CODE, SYSTEM IDT
;
0040 FFFF      + DESCR_DEF    SEG, MAX_SEG_LEN, CSEG@_LO, CSEG@_HI, CPL0_CODE_ACCESS
0042 0000      + DW MAX_SEG_LEN  ; Segment limit
0044 0F        + DW CSEG@_LO     ; Segment base address - low word
0045 98        + DB CSEG@_HI     ; Segment base address - high byte
0046 0000      + DB CPL0_CODE_ACCESS ; Access rights byte
0046 0000      + DW 0           ; Reserved
;
; TEMPORARY DESCRIPTORS FOR ES, CS, SS, AND DS
;
0048 FFFF      + DESCR_DEF    SEG, MAX_SEG_LEN, NSEG@_LO, NSEG@_HI, CPL0_DATA_ACCESS
004A 0000      + DW MAX_SEG_LEN  ; Segment limit
004C 00        + DW NSEG@_LO     ; Segment base address - low word
004D 93        + DB NSEG@_HI     ; Segment base address - high byte
004E 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
004E 0000      + DW 0           ; Reserved
;
0050 FFFF      + DESCR_DEF    SEG, MAX_SEG_LEN, NSEG@_LO, NSEG@_HI, CPL0_DATA_ACCESS
0052 0000      + DW MAX_SEG_LEN  ; Segment limit
0054 00        + DW NSEG@_LO     ; Segment base address - low word
0055 93        + DB NSEG@_HI     ; Segment base address - high byte
0056 0000      + DB CPL0_DATA_ACCESS ; Access rights byte
0056 0000      + DW 0           ; Reserved
;
```

```

0058 FFFF DESCRIPTOR_DEF SEC, MAX_SEG_LEN, NSEG@_LO, NSEG@_HI, CPL0_DATA_ACCESS
005A 0000 + DW MAX_SEG_LEN ; Segment limit
005C 00 + DW NSEG@_LO ; Segment base address - low word
005D 93 + DB NSEG@_HI ; Segment base address - high byte
005E 0000 + DW 0 ; Reserved

; DESCRIPTOR_DEF SEC, MAX_SEG_LEN, NSEG@_LO, NSEG@_HI, CPL0_DATA_ACCESS
0060 FFFF +
0062 0000 + DW MAX_SEG_LEN ; Segment limit
0064 00 + DW NSEG@_LO ; Segment base address - low word
0065 93 + DB NSEG@_HI ; Segment base address - high byte
0066 0000 + DW CPL0_DATA_ACCESS ; Access rights byte
0068 0000 + DW 0 ; Reserved

; POST_TR
0068 TR_LOC: DESCRIPTOR_DEF SEG, 800H_0C000H_0, FREE_TSS
0069 0800 + DW 800H ; Segment limit
006A C000 + DW 0C000H ; Segment base address - low word
006C 00 + DB 0 ; Segment base address - high byte
006D 81 + DB FREE_TSS ; Access rights byte
006E 0000 + DW 0 ; Reserved

; POST_TSS_PTR
006F DESCRIPTOR_DEF SEG, 800H_0C000H_0, CPL0_DATA_ACCESS
0070 0800 +
0072 0068 R + DW 800H ; Segment limit
0074 00 + DW TR_LOC ; Segment base address - low word
0075 93 + DB 0 ; Segment base address - high byte
0076 0000 + DB CPL0_DATA_ACCESS ; Access rights byte
0078 0000 + DW 0 ; Reserved

LDT_LOC:
; POST_LDTR
0078 DESCRIPTOR_DEF SEG, GDT_LEN, 0D000H_0, LDT_DESC
0079 0088 + DW GDT_LEN ; Segment limit
007A D000 + DW 0D000H ; Segment base address - low word
007B 00 + DB 0 ; Segment base address - high byte
007C E2 + DB LDT_DESC ; Access rights byte
007E 0000 + DW 0 ; Reserved

; POST_LDT_PTR
007F DESCRIPTOR_DEF SEG, GDT_LEN, LDT_LOC_0, CPL0_DATA_ACCESS
0080 0088 +
0082 0078 R + DW GDT_LEN ; Segment limit
0084 00 + DW LDT_LOC ; Segment base address - low word
0085 93 + DB CPL0_DATA_ACCESS ; Access rights byte
0086 0000 + DW 0 ; Reserved

PAGE
; GDT_DATA_END LABEL WORD
; END OF PRE-ALLOCATED GDT
0088 GDT_BLD PROC NEAR
0088 BE 0000 R MOV SI,OFFSET GDT_DATA_START ; DS:SI --> GDT
0088 B9 0044 MOV CX,(GDT_DATA_END-GDT_DATA_START)/2 ; NUMBER OF WORDS TO COPY
008E F3/ A5 REP MOVSW ; COPY GDT INTO RAM
0090 C3 RET 0

0091 GDT_BLD ENDP
0091 CODE ENDS ; MPC
ENDS

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```

TITLE SIDT_BLD 6/10/83 PROTECTED MODE INTERRUPT TABLE
; SIDT_BLD Include files
INCLUDE SYSDATA.INC
INCLUDE ACCESS.INC
INCLUDE SYSDATA.MAC
INCLUDE IAPX286.MAC

.LIST
0000
C INCLUDE SEGMENT.SRC
C CODE SEGMENT BYTE PUBLIC
C
ASSUME CS:CODE
ASSUME SS:NOTHING
ASSUME DS:NOTHING
ASSUME ES:NOTHING

0000          PUBLIC SIDT_BLD
SIDT_BLD      PROC NEAR
; BUILD THE IDT. THE IDT WILL CONTAIN VECTORS FOR
; EXCEPTION HANDLERS
MOV    SI,OFFSET SYS_IDT_OFFSETS ; MAKE DS:SI POINT TO
0003  BC C0                   ; INTERRUPT ENTRY POINTS
0005  8E D8
0007  BF D0A0
000A  2B C0
000C  8E C0
MOV    DS,AX
MOV    DI,SYST_IDT_LOC ; POINT TO SYS_IDT_LOC
SUB   AX,AX
MOV    ES,AX
; WHERE THE IDT WILL BE.

000E  BB 0066 R
0003  BC C0
0005  8E D8
0007  BF D0A0
000A  2B C0
000C  8E C0
MOV    BX,SYS_ROM_CS ; CS IS THE SAME FOR ALL INTERRUPTS
0011  B6 87
0013  B2 00
MOV    DH,TRAP_GATE ; ACCESS RIGHTS BYTE FOR THE GATE
MOV    DL,0           ; THE WORD COUNT FIELD IS UNUSED
0015  B9 0020
MOV    CX,32          ; THERE ARE 32 RESERVED INTERRUPTS
0018
LOW_IDT:
0018  A5
MOVSW
0019  BB C3
001B  AB
001C  BB C2
001E  AB
001F  BB 0000
0022  AB
0023  E2 F3
STOSW AX,BX
MOV    AX,DX
STOSW AX,O
STOSW LOW_IDT ; THE RESERVED POSITIONS
LOOP
0025  B9 00E0
0028  BD 00A6 R
MOV    CX,256-32 ; 256 TOTAL - 32 DONE = WHATEVER IS LEFT
MOV    BP,OFFSET FREE_INTS ; THERE IS A COPY OF AN UNINITIALIZED
                           ; INTERRUPT DESCRIPTOR AT FREE_INTS

PAGE
002B
HIGH_IDT:
002B  8B F5
MOV    SI,BP
; DS:SI --> FREE DESCRIPTOR
; LES:D, [LEFT_OF_TABLE INT 32]
; MOVE THE OFFSET OF THE IRET INSTRUCTION
; MOVE THE CS SELECTOR
; MOVE THE ACCESS RIGHTS BYTE
; ZERO OUT THE RESERVED WORD
; FILL THE REMAINDER OF THE TABLE
002D  A5
002E  A5
002F  A5
0030  AB
0031  E2 F8
MOVSH
MOVSH
MOVSW
STOSW
LOOP HIGH_IDT

; INITIALIZE THE ENTRY POINTS FOR POST TEST
0033  26: C7 06 D1A0 0000 E
003A  26: C7 06 D1A8 0000 E
0041  26: C7 06 D1B0 0000 E
0048  26: C7 06 D1B8 0000 E
004F  26: C7 06 D1C0 0000 E
0056  26: C7 06 D1C8 0000 E
005D  26: C7 06 D1D0 0000 E
MOV    WORD PTR ES:(SYS_IDT_LOC+(032*DESC_LEN).ENTRY_POINT),OFFSET SYS_32
MOV    WORD PTR ES:(SYS_IDT_LOC+(033*DESC_LEN).ENTRY_POINT),OFFSET SYS_33
MOV    WORD PTR ES:(SYS_IDT_LOC+(034*DESC_LEN).ENTRY_POINT),OFFSET SYS_34
MOV    WORD PTR ES:(SYS_IDT_LOC+(035*DESC_LEN).ENTRY_POINT),OFFSET SYS_35
MOV    WORD PTR ES:(SYS_IDT_LOC+(036*DESC_LEN).ENTRY_POINT),OFFSET SYS_36
MOV    WORD PTR ES:(SYS_IDT_LOC+(037*DESC_LEN).ENTRY_POINT),OFFSET SYS_37
MOV    WORD PTR ES:(SYS_IDT_LOC+(038*DESC_LEN).ENTRY_POINT),OFFSET SYS_38

0064  C3
RET    0

PAGE
0065
IRET_ADDR LABEL WORD ; FOR UNINITIALIZED INTERRUPTS
0065  CF
IRET

; EXTRNS FOR THE FIRST 32 SYSTEM INTERRUPTS
EXTRN EXC_00:NEAR
EXTRN EXC_01:NEAR
EXTRN EXC_02:NEAR
EXTRN EXC_03:NEAR
EXTRN EXC_04:NEAR
EXTRN EXC_05:NEAR
EXTRN EXC_06:NEAR
EXTRN EXC_07:NEAR
EXTRN EXC_08:NEAR
EXTRN EXC_09:NEAR
EXTRN EXC_10:NEAR
EXTRN EXC_11:NEAR
EXTRN EXC_12:NEAR
EXTRN EXC_13:NEAR
EXTRN EXC_14:NEAR
EXTRN EXC_15:NEAR
EXTRN EXC_16:NEAR
EXTRN EXC_17:NEAR
EXTRN EXC_18:NEAR
EXTRN EXC_19:NEAR
EXTRN EXC_20:NEAR
EXTRN EXC_21:NEAR
EXTRN EXC_22:NEAR
EXTRN EXC_23:NEAR
EXTRN EXC_24:NEAR
EXTRN EXC_25:NEAR
EXTRN EXC_26:NEAR
EXTRN EXC_27:NEAR

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        EXTRN  EXC_28:NEAR
        EXTRN  EXC_29:NEAR
        EXTRN  EXC_30:NEAR
        EXTRN  EXC_31:NEAR
        EXTRN  SYS_32:NEAR
        EXTRN  SYS_33:NEAR
        EXTRN  SYS_34:NEAR
        EXTRN  SYS_35:NEAR
        EXTRN  SYS_36:NEAR
        EXTRN  SYS_37:NEAR
        EXTRN  SYS_38:NEAR
PAGE
; Entry points for the first 32 system interrupts
SYS_IDT_OFFSETS      LABEL   WORD
; INTERRUPTS AS DEFINED
0066 0000 E           DW      OFFSET EXC_00    ; EXCPT 00 - DIVIDE ERROR
0068 0000 E           DW      OFFSET EXC_01    ; EXCPT 01 - SINGLE STEP
006A 0000 E           DW      OFFSET EXC_02    ; EXCPT 02 - NMI, SYS REQ FOR D1
006C 0000 E           DW      OFFSET EXC_03    ; EXCPT 03 - BREAKPOINT
006E 0000 E           DW      OFFSET EXC_04    ; EXCPT 04 - INTO DETECT
0070 0000 E           DW      OFFSET EXC_05    ; EXCPT 05 - FLOPPIE
0072 0000 E           DW      OFFSET EXC_06    ; EXCPT 06 - INVALID OPCODE
0074 0000 E           DW      OFFSET EXC_07    ; EXCPT 07 - PROCESSOR EXT NOT AVAIL
0076 0000 E           DW      OFFSET EXC_08    ; EXCPT 08 - DOUBLE EXCEPTION
0078 0000 E           DW      OFFSET EXC_09    ; EXCPT 09 - PROCESSOR EXT SEGMENT ERR
007A 0000 E           DW      OFFSET EXC_10    ; EXCPT 10 - STACK SEGMENT TRANSFER
007C 0000 E           DW      OFFSET EXC_11    ; EXCPT 11 - SEGMENT NOT PRESENT
007E 0000 E           DW      OFFSET EXC_12    ; EXCPT 12 - STACK SEGMENT NOT PRESENT
0080 0000 E           DW      OFFSET EXC_13    ; EXCPT 13 - GENERAL PROTECTION
0082 0000 E           DW      OFFSET EXC_14    ; EXCPT 14 - FPU
0084 0000 E           DW      OFFSET EXC_15    ; EXCPT 15 - FPU
0086 0000 E           DW      OFFSET EXC_16    ; EXCPT 16 - PROCESSOR EXTENSION ERROR
0088 0000 E           DW      OFFSET EXC_17    ; EXCPT 17 - FPU
008A 0000 E           DW      OFFSET EXC_18    ; EXCPT 18 - FPU
008C 0000 E           DW      OFFSET EXC_19    ; EXCPT 19 - FPU
008E 0000 E           DW      OFFSET EXC_20    ; EXCPT 20 - FPU
0090 0000 E           DW      OFFSET EXC_21    ; EXCPT 21 - FPU
0092 0000 E           DW      OFFSET EXC_22    ; EXCPT 22 - FPU
0094 0000 E           DW      OFFSET EXC_23    ; EXCPT 23 - FPU
0096 0000 E           DW      OFFSET EXC_24    ; EXCPT 24 - FPU
0098 0000 E           DW      OFFSET EXC_25    ; EXCPT 25 - FPU
009A 0000 E           DW      OFFSET EXC_26    ; EXCPT 26 - FPU
009C 0000 E           DW      OFFSET EXC_27    ; EXCPT 27 - FPU
009E 0000 E           DW      OFFSET EXC_28    ; EXCPT 28 - FPU
00A0 0000 E           DW      OFFSET EXC_29    ; EXCPT 29 - FPU
00A2 0000 E           DW      OFFSET EXC_30    ; EXCPT 30 - FPU
00A4 0000 E           DW      OFFSET EXC_31    ; EXCPT 31 - FPU
PAGE
; FORMAT INTERRUPT DESCRIPTORS (GATES) 32 - 255
FREE_INTS            DW      OFFSET IRET_ADDR ; DESTINATION OFFSET
                      DH      SYS_ROM_CS   ; DESTINATION SEGMENT
                      DB      0,INT_GATE ; UNUSED BYTE, ACCESS RIGHTS BYTE
SIDT_BLD             CODE   ENDP
CODE                ENDS
END

```

TITLE DSKETTE DATE 01-12-84 DISKETTE BIOS  
 .LIST  
 C INCLUDE SEGMENT.SRC  
 C CODE SEGMENT BYTE PUBLIC  
 PUBLIC DISK\_INT\_1  
 PUBLIC SEEK  
 PUBLIC DISKETTE\_SETUP  
 EXTRN DDS:NEAR

---

INT 13 --/  
 DISKETTE I/O  
 THIS INTERFACE PROVIDES ACCESS TO THE 5 1/4" DISKETTE DRIVES  
 320/360K DISKETTE DRIVES AND 1.2M DISKETTE DRIVES SUPPORTED  
 INPUT

(AH)=0 RESET DISKETTE SYSTEM  
 (AH)=1 READ THE STATUS OF THE SYSTEM INTO (AH)  
 DISKETTE STATUS FROM LAST OP'N IS USED  
 REGISTERS FOR READ/WRITE/VERIFY/FORMAT  
 (DL) - DRIVE NUMBER (0=1 ALLOWED, VALUE CHECKED)  
 (DH) - HEAD NUMBER (0=1 ALLOWED, NOT VALUE CHECKED)  
 (CH) - TRACK NUMBER (NOT VALUE CHECKED)  
 MEDIA DRIVE TRACK NUMBER  
 320/360 320/360 0-39  
 320/360 1.2M 0-39  
 1.2M 1.2M 0-79  
 (CL) - SECTOR NUMBER (NOT VALUE CHECKED, NOT USED FOR FORMAT)  
 MEDIA DRIVE SECTOR NUMBER  
 320/360 320/360 1-8/9  
 320/360 1.2M 1-8/9  
 1.2M 1.2M 1-15  
 (AL) - NUMBER OF SECTORS (NOT VALUE CHECKED)  
 MEDIA DRIVE MAX NUMBER OF SECTORS  
 320/360 320/360 8/9  
 320/360 1.2M 8/9  
 1.2M 1.2M 15

(ES:BX) - ADDRESS OF BUFFER ( REQUIRED FOR VERIFY)

(AH)=2 READ THE DESIRED SECTORS INTO MEMORY  
 (AH)=3 WRITE THE DESIRED SECTORS FROM MEMORY  
 (AH)=4 VERIFY THE DESIRED SECTORS  
 (AH)=5 FORMATTING DISKETTE  
 FOR THE FORMAT OPERATION, THE BUFFER POINTER (ES,BX) MUST  
 POINT TO THE COLLECTION OF DESIRED ADDRESS FIELDS FOR THE  
 TRACK. EACH FIELD IS COMPOSED OF 4 BYTES, (C,H,R,N), WHERE  
 C = TRACK NUMBER, H=HEAD NUMBER, R = SECTOR NUMBER, N = NUMBER  
 OF BYTES PER SECTOR (00=128, 01=256, 02=512, 03=1024.)  
 THERE MUST BE ONE ENTRY FOR EVERY SECTOR ON THE TRACK.  
 THIS INFORMATION IS USED TO FIND THE REQUESTED SECTOR DURING  
 READ/WRITE ACCESS.  
 PRIOR TO FORMATTING A DISKETTE, FUNCTION CALL 17 OF THIS  
 ROUTINE MUST BE INVOKED TO SET THE DISKETTE TYPE THAT IS TO  
 BE FORMATTED.  
 IN ORDER TO FORMAT 320/360K MEDIA IN EITHER A 320/360K OR  
 1.2M DISKETTE DRIVE THE GAP LENGTH FOR FORMAT PARAMETER  
 OF DISK BASE MUST BE CHANGE TO 050H. ALSO THE EOT  
 PARAMETER (LAST SECTOR ON TRACK) MUST BE SET TO THE  
 DESIRED NUMBER OF SECTORS/TRACK - 8 FOR 320K, 9 FOR 360K.  
 DISK BASE IS POINTED TO BY DISK POINTER LOCATED AT  
 ABSOLUTE ADDRESS 0:78.  
 WHEN 320/360K FORMAT OPERATIONS ARE COMPLETE, THE PARAMETERS  
 SHOULD BE RESTORED TO THEIR RESPECTIVE INITIAL VALUES.

(AH)=19 READ DASD TYPE  
 REGISTERS  
 (AH) - ON RETURN IF CARRY FLAG NOT SET, OTHERWISE ERROR  
 00 - DRIVE NOT PRESENT  
 01 - DISKETTE, NO CHANGE LINE AVAILABLE  
 02 - DISKETTE, CHANGE LINE AVAILABLE  
 03 - FIXED DISK

(DL) - DRIVE NUMBER (0=1 ALLOWED, VALUE CHECKED)

(AH)=16 DISK CHANGE LINE STATUS  
 REGISTERS  
 (AH)=00 - DISK CHANGE LINE NOT ACTIVE  
 06 - DISK CHANGE LINE ACTIVE & CARRY BIT ON  
 (DL) - DRIVE NUMBER (0=1 ALLOWED, VALUE CHECKED)

(AH)=17 SET DASD TYPE FOR FORMAT  
 REGISTERS  
 (AL) - 00 - NOT USED  
 01 - DISKETTE 320/360K IN 320/360K DRIVE  
 02 - DISKETTE 320/360K IN 1.2M DRIVE  
 03 - DISKETTE 1.2M IN 1.2M DRIVE

(DL) - DRIVE NUMBER (0=1 ALLOWED, VALUE CHECKED);  
 DO NOT USE WHEN DISKETTE ATTACH CARD USED;  
 DISK CHANGE LINE IS ASSOCIATED WITH A 1.2M BYTE DISKETTE  
 DRIVE IS SPECIFIED. IF THE DISK CHANGE LINE IS FOUND TO BE  
 ACTIVE THE FOLLOWING ACTIONS TAKE PLACE:  
 ATTEMPT TO RESET DISK CHANGE LINE TO INACTIVE STATE,  
 IF ATTEMPT SUCCEEDS SET DASD TYPE FOR FORMAT AND RETURN DISK  
 CHANGE LINE CODE;  
 IF ATTEMPT FAILS RETURN TIMEOUT ERROR CODE AND SET DASD TYPE  
 TO A PREDETERMINED STATE INDICATING MEDIA TYPE UNKNOWN.  
 IF THE DISK CHANGE LINE IN INACTIVE PERFORM SET DASD TYPE FOR FORMAT.

DATA VARIABLE -- DISK\_POINTER  
 DOUBLE WORD POINTER TO THE CURRENT SET OF DISKETTE PARAMETERS  
 OUTPUT  
 AH = STATUS OF OPERATION  
 STATUS BITS ARE DEFINED IN THE EQUATES FOR DISKETTE\_STATUS  
 VARIABLE IN THE DATA SEGMENT OF THIS MODULE  
 CY = 0 SUCCESSFUL OPERATION (AH=0 ON RETURN, EXCEPT FOR READ DASD  
 TYPE (AH=15))  
 CY = 1 FAILED OPERATION (AH HAS ERROR REASON)  
 FOR READ/WRITE/VERIFY  
 DS,BX,DX,CH,CL PRESERVED  
 NOTE: IF AN ERROR IS REPORTED, CHECK THE DISKETTE CODE, THE APPROPRIATE  
 ACTION IS TO RESET THE DISKETTE, THEN RETRY THE OPERATION.  
 ON READ ACCESSES, NO MOTOR START DELAY IS TAKEN, SO THAT  
 THREE RETRIES ARE REQUIRED ON READS TO ENSURE THAT THE  
 PROBLEM IS NOT DUE TO MOTOR START-UP.

---

DISKETTE STATE MACHINE - ABSOLUTE ADDRESS 40:90 & 91  
 (DRIVE 0 = 90, DRIVE 1 = 91)  
 BITS

7	6	5	4	3	2	1	0
1	1	1	1	1	1	1	1

RESERVED --PRESENT STATE

000: 360K IN 360K DRIVE UNESTABLISHED  
001: 360K IN 1.2M DRIVE UNESTABLISHED  
002: 1.2M IN 1.2M DRIVE UNESTABLISHED  
003: 360K IN 360K DRIVE ESTABLISHED  
004: 360K IN 1.2M DRIVE ESTABLISHED  
005: 1.2M IN 1.2M DRIVE ESTABLISHED

--> MEDIA/DRIVE ESTABLISHED  
--> DOUBLE STEPPING REQUIRED (360K IN 1.2M DRIVE)  
--> DATA TRANSFER RATE FOR THIS DRIVE:  
00: 500 KBS  
01: 300 KBS  
10: 250 KBS  
11: RESERVED

STATE OPERATION STARTED - ABSOLUTE ADDRESS 40:92 & 93  
(DRIVE 0 - 92, DRIVE 1 - 93)  
PRESENT CYLINDER NUMBER - ABSOLUTE ADDRESS 40:94 & 95  
(DRIVE 0 - 94, DRIVE 1 - 95)

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ASSUME CS:CODE,DS:DATA,ES:DATA

```

PUBLIC DISKETTE_10_1 PROC FAR
DISKETTE_10_1 PROC FAR ;>>> ENTRY POINT FOR ORG 00C59H
    STI             ; INTERRUPTS BACK ON
    PUSH BX          ; SAVE ADDRESS
    PUSH CX          ;
    PUSH DS          ; SAVE SEGMENT REGISTER VALUE
    PUSH SI          ; SAVE ALL REGISTERS DURING OPERATION
    PUSH DI          ;
    PUSH BP          ;
    PUSH DX          ;
    MOV  BP,SP        ; SET UP POINTER TO HEAD PARM
    MOV  SI,DATA      ;
    MOV  DS,SI        ;
    CMP  AH,1         ; CHECK FOR RESET AND STATUS OPERATIONS
    JBE  R4          ; BYPASS DRIVE CHECK IF YES
    CMP  DL,1         ; CHECK DRIVE NUMBER FOR VALIDITY
    JBE  R4          ; IF VALID CONTINUE
    MOV  DISKETTE_STATUS,BAD_CMD ; INVALID DRIVE ADDRESS, TERMINATE
    MOV  SI,0         ; INSURE THAT RETURN STATUS GETS SETUP
    JMP  SHORT_OK     ; GO TERMINATE COMMAND

R5:   MOV  AX,DISKETTE_STATUS,BAD_CMD ; INVALID DRIVE ADDRESS, TERMINATE
    MOV  SI,0         ; INSURE THAT RETURN STATUS GETS SETUP
    JMP  SHORT_OK     ; GO TERMINATE COMMAND

R4:   PUSH AX          ; SAVE ORIGINAL OPERATION FOR RETRY LATER ON
    CALL J1           ; CALL THE REST TO ENSURE DS RESTORED
    POP  SI           ; RESTORE ORIGINAL OPERATION FOR RETRY
    MOV  DX,SI         ; GET ORIGINAL OPERATION FOR TESTING
    CMP  DH,1         ; SEE IF IT IS A RESET OR STATUS OPERATION
    JBE  OK           ; BYPASS STATE UPDATE

    TEST JZ, HF_CTRNL_DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
    JZ   HF_CTRNL_DUAL ; DISKETTE ATTACH CARD

    CMP  DH,15H        ; READ DISK CHANGE STATUS OR DISK TYPE COMMAND
    JAE  OK           ; IF YES, BYPASS STATE PROCESSING

    MOV  DX,[BP]        ; RESTORE DRIVE PARAMETER
    XOR  BH,BH        ; SETUP ADDRESS TO MEDIA STATE FOR THIS DRIVE
    MOV  BH,BH        ;
    MOV  AH,DISKETTE_STATUS ; GET STATUS OF OPERATION
    OR   AH,AH         ; SEE IF ANY ERRORS
    JNZ  RETRY         ; JUMP TO CHECK FOR MEDIA CHANGE

    MOV  AH,DSK_STATE[BX] ; GET MEDIA STATE OF DRIVE
    TEST AH,DETERMINED ; SEE IF MEDIA STATE SET ALREADY
    JNZ  OK2           ; IF SET, DONT CHANGE STATE

    MOV  CL,AH          ; GET PRESENT STATE
    AND  CL,STATE_MSK  ; ISOLATE STATE NUMBER
    ADD  CL,CL          ; EXTRACT STATE TO SET ALREADY
    AND  AH,REV_STATE   ; CLEAR OUT STATE NUMBER
    OR   AH,CL          ; SET NEW STATE NUMBER
    OR   AH,DETERMINED ; MAKE MEDIA STATE SET
    MOV  DSK_STATE[BX],AH ; SAVE IN DRIVE STATE INDICATOR
    MOV  DS,DSK_STATE[BX+2] ; GET THE MOTOR WAIT PARAMETER
    OR   DS,DS           ; GET ORIGINAL OG AGAIN
    RETR  DS            ; SAVE RETURN VALUE

OK2:  MOV  BH,4          ; GET THE MOTOR WAIT PARAMETER
    MOV  DX,SI          ; GET ORIGINAL OG AGAIN
    PUSH AX            ; SAVE RETURN VALUE

    CALL GET_PARM       ; SET THE TIMER COUNT FOR THE MOTOR
    MOV  AH,MOTOR_COUNT,AH ; RESTORE RETURN VALUE
    POP  AX            ; SEE IF READ DASD OPERATION
    CMP  DH,015H        ; IF NOT BYPASS
    JNE  R20           ; GO LEAVE

    XCHG AH,AL          ; PUT RESULT IN AH
    CLC               ; SET SUCCESSFUL OPERATION
    JMP  SHORT_R19      ; GO LEAVE

R20:  MOV  AH,DISKETTE_STATUS ; GET STATUS OF OPERATION
    CMP  AH,1         ; SET THE CARRY FLAG TO INDICATE
    CHC               ; SUCCESS OR FAILURE
    R19:  POP  DX          ; RESTORE ALL REGISTERS
    POP  BP          ;
    POP  DI          ;
    POP  SI          ;
    POP  DS          ;
    POP  CX          ;
    POP  BX          ; RECOVER ADDRESS
    RETR  2           ; THROW AWAY SAVED FLAGS

    RETRY: CMP JE DISKETTE_STATUS,MEDIA_CHANGE ; CHECK FOR DISK CHANGE ERROR
    JE   OK1          ; TRUE ERROR DONT RETRY

    MOV  AH,DSK_STATE[BX] ; GET MEDIA STATE OF DRIVE
    AND  AH,STATE_MSK  ; ISOLATE STATE
    CMP  AH,3         ; SEE IF IN STATE 3
    JAE  OK2          ; IF ESTABLISHED STATE THEN TRUE ERROR

    ----- HANDLE STATES 0, 1 & 2 -----
    INC  AH          ; TRY NEXT STATE
    CMP  AH,3         ; SEE IF OVERFLOW IN NON-ESTABLISHED STATES
    JNE  R2           ; SKIP RESET TO BEGINNING IF YES

    MOV  AH,0          ; NEXT STATE TO TRY AFTER OVERFLOW
    MOV  CH,DSK_STATE[BX+2] ; GET START RETRY STATE
    AND  CH,STATE_MSK  ; ISOLATE STATE BITS
    CMP  CH,AH         ; ALL STATES TRIED

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00BB 74 47 ; JE OK3 ; IF YES, THEN TRUE ERROR
;----- SETUP STATE INDICATOR FOR RETRY ATTEMPT
00B0 8A AF 0090 R MOV CH,DSK_STATE[BX] ; GET STATE INDICATOR
00C1 D0 C9 ROR CH,* ; MOVE TRANSFER RATE TO LOW ORDER BITS
00C3 D0 D5 ROL CH,1
00C5 80 E5 03 AND CH,TRAN_MSK ; ISOLATE TRANSFER RATE BITS
00C8 FE CD DEC CH ; CONVERT TO NEXT RATE
00CA 80 FD FF CMP CH,0FFF ; SEE IF OVERFLOW OCCURRED
00CD 75 02 JNE R3 ; JUMP IF NO OVERFLOW

00CF B5 02 ; MOV CH,XRATE ; SET TO NEXT RATE
00D1 D0 CD R3: ROR CH,1 ; PUT TRANSFER BITS BACK WHERE THEY BELONG
00D3 D0 CD ROR CH,1
00D5 80 FC 01 CMP AH,1 ; SEE IF THIS STATE REQUIRES DOUBLE STEP
00D8 75 03 JNE R9 ; IF NOT, BYPASS SETTING DOUBLE STEP

00DA 80 CD 20 ; OR CH,DOUBLE_STEP ; TURN ON DOUBLE STEP REQUIRED
00DD 80 E5 R9: OR AH,CH ; COMBINE WITH STATE TO MAKE NEW INDICATOR
00DF 88 A7 0090 R MOV DSK_STATE[BX],AH ; SAVE AS NEW INDICATOR

;----- SETUP FOR ACTUAL RETRY OPERATION
00E3 88 56 00 ; MOV DX,[BP] ; RESTORE PARAMETERS FROM STACK
00E6 88 4E 0A MOV CX,[BP+10] ; *
00E9 88 5E 0C MOV BX,[BP+12] ; *
00EC 88 C6 MOV AX,SI ; GO RETRY OPERATION
00EE E9 0023 R JMP R4

00F1 88 56 00 ; OK1: MOV DX,[BP] ; RESTORE DRIVE PARAMETER
00F4 E8 0604 R CALL READ_DSKCHNG ; GO READ DISK CHANGE LINE STATUS
00F7 75 03 JNZ JK4 ; IF ACTIVE, NO DISKETTE IN DRIVE, TIMEOUT

00F9 E9 0067 R ; JMP OK2 ; IF NOT ACTIVE, DISKETTE IN DRIVE, DISK CHANGE

00FC C6 06 0041 R 00 ; OK4: MOV DISKETTE_STATUS,TIME_OUT ; INDICATE TIMEOUT IF DRIVE EMPTY
0101 E9 0067 R JMP OK2

0104 C6 87 0090 R 00 ; OK3: MOV DSK_STATE[BX],POA_START ; ERROR PUT STATE AT POWER ON ASSUMPTION
0109 E9 0067 R JMP OK2

010C DISKETTE_10_1 ENDP

;----- DETERMINE NEW MEDIA TYPE, NEED TO RESET DISK CHANGE LINE HERE
010C 80 FC 01 ; J1: PROC NEAR
010F 76 76 CMP AH,1 ; TEST FOR RESET AND STATUS OPERATION
J1E JBE ; BYPASS STATE CHECK AND UPDATE

0111 F6 06 008F R 01 ; TEST HF_CNTRL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
0116 74 11 JZ J1A ; DISKETTE ATTACH CARD

0118 80 FC 15 ; CMP AH,15H ; TEST FOR DISK CHANGE STATUS OR DISK TYPE
011B 73 6A JAE J1E ; BYPASS STATE CHECK AND UPDATE

011D 50 ; PUSH AX ; SAVE ORIGINAL PARAMETERS
011E 53 PUSH BX ; SAVE PARAMETERS
011F 51 PUSH CX ; *
0120 52 PUSH DX ; *
0121 E8 0604 R CALL READ_DSKCHNG ; GO READ DISK CHANGE LINE STATE
0124 74 0C JZ J1I ; BYPASS HANDLING DISK CHANGE LINE

0126 E9 05E2 R ; JMP J1F ; HANDLE DISK CHANGE LINE ACTIVE

0129 50 ; J1A: PUSH AX ; SAVE ORIGINAL PARAMETERS
012A 53 PUSH BX ; SAVE PARAMETERS
012B 51 PUSH CX ; *
012C 52 PUSH DX ; *
012D E8 0604 R CALL READ_DSKCHNG ; SELECT DRIVE FOR DISKETTE ATTACH CARD
0130 EB 51 JMP SHORT J1H ; IGNORE DISK CHANGE STATUS

0132 8A 87 0090 R ; J1I: MOV AL,DSK_STATE[BX] ; GET MEDIA STATE INFORMATION FOR DRIVE
0136 0A C0 OR AL,AL ; CHECK FOR NO STATE INFORMATION AT ALL
0138 75 06 JNZ J1D ; IF INFORMATION DONT DEFAULT

013A 80 80 ; MOV AL,POA_START ; GET DEFAULT TO STATE 0
013C 88 87 0090 R DSK_STATE[BX],AL ; SET UP DEFAULT TO STATE 1

0140 3C 61 ; J1D: CMP AL,POA_DUAL ; SEE IF DOUBLE STEP RATE
0142 75 1E J1G ; BYPASS TRACK CHECK

0144 88 4E 0A ; MOV CX,[BP+10] ; GET ORIGINAL TRACK PARAMETER
0147 80 FD 28 CMP CH,40 ; SEE IF TRACK IS PAST END OF DISKETTE(320)
014A 72 16 JB J1G ; GO TRY OPERATION AT THIS STATE IF NOT

014C G6 87 0090 R 02 ; MOV DSK_STATE[BX],02H ; SET NEXT STATE TO TRY IN ALGORITHM
0151 80 87 0092 R MOV AL,02H ; PUT NEW STATE IN WORKING REGISTER
0153 8A 87 0092 R MOV DSK_STATE[BX+2],00H ; SET UP OPERATION STATE
0157 0A F6 OR DH,DH ; CHECK FOR OPERATION START
0159 75 13 JNZ J1C ; IF STARTED PREVIOUSLY, BYPASS SETTING IT UP

015B G6 87 0092 R 61 ; MOV DSK_STATE[BX+2],POA_DUAL ; SETUP STARTING STATE
0160 EB 0C JMP SHORT J1C ; BYPASS NEXT STEP ALREADY DONE

0162 8A 97 0092 R ; J1G: MOV DL,DSK_STATE[BX+2] ; GET START MEDIA STATE
0166 0A D2 OR DL,DL ; SEE IF THIS IS ORIGINAL OPERATION OR A RETRY
0166 75 04 JNZ J1C ; IF RETRY IGNORE

016A 88 87 0092 R ; J1C: MOV CL,LASTRATE ; GET LAST DATA RATE SELECTED
016E 8A 0E 008B R CMP AL,CL ; COMPARE TO LAST OPERATION
0172 3A C1 JE J1H ; IF SAME DONT SELECT NEW TRANSFER RATE
0174 74 00 ; MOV LASTRATE,AL ; SAVE NEW TRANSFER RATE FOR NEXT CHECK
0176 A2 008B R ROL AL,1 ; MOVE TRANSFER RATE DATA TO LOW BITS
0178 D0 C0 ROL AL,1
017D 24 03 AND AL,TRAN_MSK ; CLEAR ALL BITS BUT DATA TRANSFER RATE BITS
017E B4 03F7 MOV DX,03F7H ; ADDRESS FLOPPY CONTROL REGISTER
017F 5E OUT DX,AL ; SET DATA TRANSFER RATE
0183 5A POP DX ; RESTORE PARAMETERS
0184 59 POP CX ; *
0185 5B POP BX ; *
0186 58 POP AX ; *

0187 80 F0 ; J1H: MOV DX,AL ; SAVE # SECTORS IN DH
0189 00 26 003F R 7F AND MOTOR_STATUS,07FH ; INDICATE A READ OPERATION
018E 0A E4 OR AH,AH ; AH=0
0190 74 38 JZ DISK_RESET ; *
0192 FE CC DEC AH ; AH=1
0193 76 76 JZ DISK_STATUS ; *
0196 56 0041 R 00 MOV DISKETTE_STATUS,0 ; RESET THE STATUS INDICATOR
0198 FE CC DEC AH ; AH=2
019D 74 6E JZ DISK_READ ; *
019F FE CC DEC AH ; AH=3
01A1 75 03 JNZ J2 ; TEST_DISK_VERF
01A3 E9 0240 R JMP DISK_WRITE

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01A6 FE CC          J2: DEC AH      ; TEST_DISK_VERF
01A8 74 6C          JZ  DISK_VERF ; AH=4
01AA FE CC          DEC AH      ; AH=5
01AC 74 6C          JZ  DISK_FORMAT
01AE 80 EC 10        SUB AH,T0H ; AH=15H
01B1 75 03          JNZ J3      ; BYPASS DISK TYPE OPERATION

01B3 E9 0698 R          ; JMP DISK_TYPE ; GO PERFORM DISK TYPE OPERATION

01B6 FE CC          J3: DEC AH      ; AH = 16H
01B8 75 03          JNZ J4      ; BYPASS DISK CHANGE STATUS

01BA E9 0646 R          ; JMP DISK_CHANGE ; GO CHECK DISK CHANGE LINE STATUS

01BD FE CC          J4: DEC AH      ; AH = 17H
01BF 75 03          JNZ J5      ; BAD COMMAND

01C1 E9 0700 R          ; JMP FORMAT_SET ; GO SET MEDIA/DRIVE TYPE FOR FORMAT

01C4 C6 06 0041 R 01        J5: MOV DISKETTE_STATUS,BAD_CMD ; ERROR CODE, NO SECTORS TRANSFERRED
01C9 C3              RET         ; UNDEFINED OPERATION
01CA ENDP

;----- RESET THE DISKETTE SYSTEM

DISK_RESET PROC NEAR
01CA B4 03F2          MOV DX,03F2H ; ADAPTER CONTROL PORT
01CB FF 00            OR AL,0FFH ; HIGH NIBBLE
01CE A0 003F R          MOV AL,MOTOR_STATUS ; WHICH MOTOR IS ON
01D1 24 3F          AND AL,03FH ; STRIP OFF UNWANTED BITS
01D3 B1 04          MOV CL,4   ; SHIFT COUNT
01D5 02 C0          ROL AL,CL ; MOVE MOTOR VALUE TO HIGH NIBBLE, DRIVE SELECT
01D7 OC 08          OR AL,8   ; TURN ON INTERRUPT ENABLE
01D9 EE              OUT DX,AL ; RESET THE ADAPTER
01DA C6 06 003E R 00        MOV SEEK_STATUS,0 ; SET RECAL REQUIRED ON ALL DRIVES
01DF C6 06 0041 R 00        MOV DISKETTE_STATUS,0 ; SET OK STATUS FOR DISKETTE
01E4 EB 00          JMP S+2   ; I/O WAIT STATE
01E6 DC 04          OR AL,4   ; TURN OFF INTERRUPT
01E8 EB 00          OUT DX,AL ; RESET
01E9 FB              STI DX,AL ; TURN OFF INTERRUPT
01EA E8 051A R          CALL CHK_STAT_2 ; REENABLE THE INTERRUPTS
01ED A0 0042 R          MOV AL,NEC_STATUS ; DO SENSE INTERRUPT STATUS FOLLOWING RESET
01F0 3C C0          CMP AL,OCH0 ; IGNORE ERROR RETURN AND DO OWN TEST
01F2 74 01          JZ J7    ; TEST FOR DRIVE READY TRANSITION
01F4 80 0E 0041 R 20        OR DISKETTE_STATUS,BAD_NEC ; EVERYTHING OK
01F9 C3              RET         ; SET ERROR CODE

;----- SEND SPECIFY COMMAND TO NEC

J7: MOV AH,03H          ; DRIVE READY
01FA B4 03          CALL NEC_OUTPUT ; SPECIFY COMMAND
01FC E8 03E2 R          MOV BX,T   ; OUTPUT THE COMMAND
01FF BB 0001          CALL GET_PARM ; FIRST BYTE PARM IN BLOCK
0202 E8 0382 R          MOV BX,3   ; TO THE NEC CONTROLLER
0203 BB 0001          CALL GET_PARM ; SECOND BYTE PARM IN BLOCK
0208 E8 0382 R          CALL GET_PARM ; TO THE NEC CONTROLLER
020B C3              RET         ; RESET REQ
020C ENDP

;----- DISKETTE STATUS ROUTINE

020C C3              DISK_RESET ENDP

DISK_STATUS PROC NEAR
020C C3              RET
020D ENDP

;----- DISKETTE READ

DISK_READ PROC NEAR
020D B0 46          MOV AL,046H ; READ COMMAND FOR DMA
020E F7              CALL DMA_SETUP ; DISKREAD_CONT
0212 EB 04CA R          MOV AH,06EH ; SET UP THE DMA
0214 BB E6          JMP SHORT RW_OPEN ; SET UP READ COMMAND FOR NEC CONTROLLER
0216 EB 36          DISK_READ ENDP ; GO DO THE OPERATION

;----- DISKETTE VERIFY

0216 B0 42          DISK_READ ENDP ; READ COMMAND FOR DMA
0218 EB F5          DISK_VERIFY ENDP ; DO AS IF DISK READ

;----- DISKETTE FORMAT

021A B0 0E 003F R 80        DISK_FORMAT PROC NEAR
021B B0 44          OR MOTOR_STATUS,WRITE_OP ; INDICATE WRITE OPERATION
021C E8 04CA R          MOV AL,04AH ; WILL WRITE TO THE DISKETTE
0221 BB 0009          CALL DMA_SETUP ; SET UP THE DMA
0224 BB 40          MOV AH,04DH ; ESTABLISH THE FORMAT COMMAND
0226 EB 24          JMP SHORT RW_OPEN ; DO THE OPERATION
0228 BB 0007          J10: MOV BX,7   ; CONTINUATION OF RW_OPEN FOR FMT
0229 E8 0382 R          CALL GET_PARM ; GET THE
0230 BB 0009          MOV BX,B   ; SECTOR/SECTOR VALUE TO NEC
0231 EB 0382 R          CALL GET_PARM ; GET THE
0234 BB 000F          MOV BX,T5  ; SECTORS/TRACK VALUE TO NEC
0237 EB 0382 R          CALL GET_PARM ; GET THE
023A BB 0011          MOV BX,T7  ; GAP LENGTH VALUE TO NEC
023D E9 032A R          JMP J16   ; GET THE FILLER BYTE
0240 ENDP             DISK_FORMAT ENDP ; TO THE CONTROLLER

;----- DISKETTE WRITE ROUTINE

0240 B0 0E 003F R 80        DISK_WRITE PROC NEAR
0245 B0 4A          OR MOTOR_STATUS,WRITE_OP ; INDICATE WRITE OPERATION
0247 EB 04CA R          MOV AL,04AH ; DMA WRITE COMMAND
024A BB C5          CALL DMA_SETUP ; NEC COMMAND TO WRITE TO DISKETTE
024C ENDP

;----- ALLOW WRITE ROUTINE TO FALL INTO RW_OPEN

RW_OPEN PROC NEAR
024C 73 08          DISK_WRITE ENDP ; ALLOW WRITE ROUTINE TO FALL INTO RW_OPEN

;----- THIS ROUTINE PERFORMS THE READ/WRITE/VERIFY OPERATION

RW_OPEN PROC NEAR
024E C6 06 0041 R 09        JNC J11   ; TEST FOR DMA ERROR
0253 B0 00          MOV DISKETTE_STATUS,DMA_BOUNDARY ; SET ERROR
0255 C3              MOV AL,0   ; NO SECTORS TRANSFERRED
0256 50              RET         ; RETURN TO MAIN ROUTINE
0256 50              DO_RW_OPEN ; DO RW_OPEN
0256 50              SAVE THE COMMAND

;----- TURN ON THE MOTOR AND SELECT THE DRIVE

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0257 51
0258 8A CA
025A 80 01
025C 80 E0
025E FA
025F 84 06 003F R
.0263 74 OC

0265 80 3E 0040 R EC
026A C6 06 0040 R FF
026F 72 42

0271 08 06 003F R
0275 B1 08
0277 80 26 003F R CF
027C D2 C2
027E 08 16 003F R
0282 D2 CA
0284 F1
0285 A0 003F R
0288 24 3F
028A D2 C0
028C 00 0C
028E 52
0292 00 0A 03F2
0292 EE
0293 5A

PUSH CX ; SAVE THE T/S PARMS
MOV CL, DL ; GET DRIVE NUMBER AS SHIFT COUNT
MOV AL, 1 ; MASK FOR DETERMINING MOTOR BIT
SAL CL ; SHIFT THE DRIVE BIT
CLI ; NO INTERRUPTS WHILE DETERMINING MOTOR STATUS
TEST AL, MOTOR_STATUS ; IS THIS MOTOR ON
JZ R13 ; IF NOT GO TEST FOR WAIT NECESSARY

0265 80 3E 0040 R EC
CMP MOTOR_COUNT, 0ECH ; SEE IF THE MOTOR HAS BEEN ON LONG ENOUGH
MOV MOTOR_STATUS, OFFH ; ENSURE MOTOR DOESNT TURN OFF DURING OPERATION
JB J14 ; IS LESS THAN EC, THEN TURN ON NOT DUE TO
; READING OF DISK CHANGE LINE, OTHERWISE
; GO TEST FOR WAIT NECESSARY

R13: OR MOTOR_STATUS, AL ; TURN ON THE CURRENT MOTOR
MOV CL, 4 ; SHIFT COUNT TO MOVE DRIVE TO HIGH NIBBLE
AND MOTOR_STATUS, 0CFH ; CLEAR ENCODED DRIVE SELECT BITS(4 & 5)
ROL DL, CL ; MOVE DRIVE ENCODED BITS TO HIGH NIBBLE
OR MOTOR_STATUS, DL ; AS SELECTED DRIVE
ROR DL, CL ; PREVIOUSLY SET
INTERRUPTS BACK ON
MOV AL, MOTOR_STATUS ; GET MOTORS ON AND DRIVE SELECTED
AND AL, 03FH ; STRIP OFF UNWANTED BITS
ROL AL, CL ; SHIFT BITS AROUND TO DESIRED POSITIONS
OR AL, OCH ; NO RESET, ENABLE DMA/INT
PUSH DX ; SAVE REG
MOV DX, 03F2H ; CONTROL PORT ADDRESS
OUT DX, AL ; RECOVER REGISTERS
POP DX

;----- WAIT FOR MOTOR

0294 F8
0295 B8 90FD ; CLEAR TIMEOUT INDICATOR
0298 CD 15 ; LOAD WAIT CODE & TYPE
029A 72 17 ; PERFORM OTHER FUNCTION
; BYPASS TIMING LOOP IF TIMEOUT OCCURRED

029C BB 0014 ; GET THE MOTOR WAIT
029F E8 0382 R ; PARAMETER
02A2 0A E4 ; TEST FOR NO WAIT
02A4 J12: INT 15H ; TEST_WAIT_TIME
02A4 74 0D ; EXIT WITH TIME EXPIRED
02A6 2B C9 ; SET UP 1/8 SECOND LOOP TIME
02A8 E2 FE ; WAIT FOR THE REQUIRED TIME

02AA B9 6D06 ;----- DO THE SEEK OPERATION
02AD E2 FE
02AF FE CC
02B1 75 F1

02B3 FB
02B4 59

J14: STI ; MOTOR_RUNNING
POP CX ; INTERRUPTS BACK ON FOR BYPASS WAIT

;----- DO THE SEEK OPERATION

02B5 E8 041C R ; CALL SEEK ; MOVE TO CORRECT TRACK
02B6 56 ; POP AX ; RECOVER COMMAND
02B9 8A FC ; MOV BH, AH ; SAVE COMMAND IN BH
02B8 B6 00 ; MOV DH, 0 ; SET NO SECTORS READ IN CASE OF ERROR
02BD 72 72 ; JC J17 ; IF ERROR, THEN EXIT AFTER MOTOR OFF
02BF BE 0331 R ; MOV S1, OFFSET J17 ; DUMMY RETURN ON STACK FOR NEC_OUTPUT
02C2 56 ; PUSH SI ; SO THAT IT WILL RETURN TO MOTOR OFF LOCATION

;----- SEND OUT THE PARAMETERS TO THE CONTROLLER

02C3 E8 03E2 R ; CALL NEC_OUTPUT ; OUTPUT THE OPERATION COMMAND
02C6 8A 66 01 ; MOV AH, [BP+1] ; GET THE CURRENT HEAD NUMBER
02C9 E4 01 ; SAL AH, 1 ; MOVE IT TO BIT 2
02C8 00 ; SAL AH, 1 ; ISOLATE THAT BIT
02CD 80 E4 04 ; AND AH, 4 ; OR IN THE DRIVE NUMBER
02D0 04 E2 04 ; CALL NEC_OUTPUT
02D2 E8 03E2 R

;----- TEST FOR FORMAT COMMAND

02D5 80 FF 4D ;----- TEST FOR FORMAT COMMAND
02D6 75 03 ; CMP BH, 04DH ; IS THIS A FORMAT OPERATION
02D4 E9 0228 R ; JNE J15 ; NO, CONTINUE WITH R/W/V
JMP J10 ; IF SO, HANDLE SPECIAL

J15: MOV AH, CH ; CYLINDER NUMBER
CALL NEC_OUTPUT ; HEAD NUMBER FROM STACK
MOV AH, [BP+1] ; SECTOR NUMBER
CALL NEC_OUTPUT ; BYTES/SECTOR PARM FROM BLOCK
MOV AH, CL ; TO THE NEC
CALL NEC_OUTPUT ; EOT PARM FROM BLOCK
MOV BX, 9 ; TO THE NEC
CALL GET_PARM ; RESTOREATIVE NUMBER FROM PARMS
MOV BX, [BP] ; READ HIGH ORDER INDEX REGISTER
XOR BH, BH ; GET DRIVE STATE VALUE
MOV AH, DSK_STATE[BX] ; TEST AH, DETERMINED ; SEE IF STATE ALREADY ESTABLISHED
JZ DO ; BYPASS STATE REDUCTION FOR GAP LENGTH

03D0 80 E4 07 ;----- LET THE OPERATION HAPPEN
03D1 80 EC 03 ; AND AH, 07H ; STRIP OFF HIGH BITS
SUB AH, 03H ; REDUCE STATES

03D0 80 E4 07 ;----- LET THE OPERATION HAPPEN
03D1 80 FC 00 ; DO: AND AH, 07H ; STRIP OFF HIGH BITS
CMP AH, 0 ; CHECK FOR DISKETTE ATTACH CARD OR 320 DRIVE
JNE R16 ; IF NOT CHECK FOR NEXT STATE

03D1 75 04 ;----- LET THE OPERATION HAPPEN
03D2 84 2A ; MOV AH, 02AH ; LOAD 320/360 DRIVE GAP LENGTH
03D1 EB 0B ; JMP SHORT R15 ; GO OUTPUT

03D1 80 FC 01 ;----- LET THE OPERATION HAPPEN
03D2 75 04 ; R16: CMP AH, 1 ; CHECK FOR 320 MEDIA IN 1.2 DRIVE
; IF NOT, THEN HANDLE 1.2 MEDIA IN 1.2 DRIVE
;----- LET THE OPERATION HAPPEN
03D1 EB 02 ; MOV AH, 023H ; LOAD 320/360 MEDIA IN 1.2 DRIVE GAP LENGTH
JMP SHORT R15 ;----- LET THE OPERATION HAPPEN
;----- LET THE OPERATION HAPPEN
03D2 BH 1B ; R17: MOV AH, 01BH ; LOAD 1.2 MEDIA IN 1.2 DRIVE GAP LENGTH
03D4 E8 03E2 R ; R15: CALL NEC_OUTPUT ; DTL PARM FROM BLOCK
03D2 BB 000D ; MOV BX, T3 ; RW_OPN FINISH
03D2 E8 0382 R ;----- LET THE OPERATION HAPPEN
03D2 5E ; CALL GET_PARM ; TO THE NEC
POP SI ; CAN NOW DISCARD THAT DUMMY RETURN ADDRESS

03D2 E8 053B R ;----- LET THE OPERATION HAPPEN
03D3 72 45 ; CALL WAIT_INT ; WAIT FOR THE INTERRUPT
J17: JC J21 ; MOTOR_OFF ; LOOK FOR ERROR

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0333 E8 0580 R          CALL JC    RESULTS      ; GET THE NEC STATUS
0336 72 3F              JC J20           ; LOOK FOR ERROR
;----- CHECK THE RESULTS RETURNED BY THE CONTROLLER
0338 FC                CLD             ; SET THE CORRECT DIRECTION
0339 DE 0042 R          MOVSI_OFFSET_NECK_STATUS ; POINT TO STATUS FIELD
033C AC                LODS NEC_STATUS   ; GET STATUS
033D 24 C0              AND AL,0C0H    ; TEST FOR NORMAL TERMINATION
033F 74 3B              JZ J22         ; OPN_OK
0341 3C 40              CMP AL,040H    ; TEST FOR ABNORMAL TERMINATION
0343 75 29              JNZ J18         ; NOT ABNORMAL, BAD NEC
;----- ABNORMAL TERMINATION, FIND OUT WHY
0345 AC                LODS NEC_STATUS   ; GET ST1
0346 D0 E0              SAL AH,T        ; TEST FOR EOT FOUND
0348 B4 04              MOV AH,RECORD_NOT_FND
0349 34                 JG J19         ; RW_FAIL
034C D0 E0              SAL AL,1        ; TEST FOR CRC ERROR
034E D0 E0              SAL AL,1        ; TEST FOR RECORD NOT FOUND
0350 B4 10              MOV AH,BAD_CRC
0352 72 1C              JC J19         ; RW_FAIL
0354 34                 SAL AL,1        ; TEST FOR DMA OVERRUN
0356 B4 08              MOV AH,BAD_DMA
0358 72 16              JC J19         ; RW_FAIL
035A D0 E0              SAL AL,1        ; TEST FOR RECORD NOT FOUND
035C D0 E0              SAL AL,1        ; TEST FOR WRITE_PROTECT
035E B4 04              MOV AH,RECORD_NOT_FN
0360 34                 JG J19         ; RW_FAIL
0362 D0 E0              SAL AL,1        ; TEST FOR MISSING ADDRESS MARK
0364 B4 03              MOV AH,WRITE_PROTECT
0366 72 08              JC J19         ; RW_FAIL
0368 D0 E0              SAL AL,1        ; TEST FOR WRITE_PROTECT
036A B4 02              MOV AH,BAD_ADDR_MARK
036C 72 02              JC J19         ; RW_FAIL
;----- NEC MUST HAVE FAILED
036E B4 20              J18: MOV AH,BAD_NEC ; RW-NEC-FAIL
0370 08 26 0041 R        J19: OR DISKETTE_STATUS,AH ; RW-FAIL
0374 E8 05CB R          CALL NUM_TRANS ; HOW MANY WERE REALLY TRANSFERRED
0377 C3                J20: RET          ; RETURN TO CALLER
0378 E8 0580 R          J21: CALL RESULTS ; RW_ERR_RES
037B C3                RET           ; FLUSH THE RESULTS BUFFER
;----- OPERATION WAS SUCCESSFUL
037C E8 05CB R          J22: CALL NUM_TRANS ; OPN_OK
037F 32 E4              XOR AH,AH    ; HOW MANY GOT MOVED
0381 C3                RET           ; NO ERRORS
0382 RV_OPEN ENDP
;----- GET_PARM
; THIS ROUTINE FETCHES THE INDEXED POINTER FROM
; THE DISK_BASE_BLOCK POINTED AT BY THE DATA
; WORD ABOVE DISK_POINTER
; A BYTE FROM THAT TABLE IS THEN MOVED INTO AH,
; THE INDEX OF THAT BYTE BEING THE PARM IN BX,
; ENTRY --
;     BX = INDEX OF BYTE TO BE FETCHED * 2
;     IF THE LOW BIT OF BX IS ON, THE BYTE IS IMMEDIATELY
;     OUTPUT TO THE NEC CONTROLLER
; EXIT --
;     AH = THAT BYTE FROM BLOCK
;----- GET_PARM PROC NEAR
0382 1E                PUSH DS          ; SAVE SEGMENT
0383 56                PUSH SI          ; SAVE
0384 2B C0              SUB AX,AX    ; ZERO TO AX
0386 8E D8              MOV DS,AX
ASSUME DS:ABSD
0388 C5 36 0078 R        LDS SI,DISK_POINTER ; POINT TO BLOCK
0389 D0 EB              SHL BX,1     ; DIVIDE BX BY 2, AND SET FLAG FOR EXIT
038F 8A 20              MOV AH,[SI+BX] ; GET THE WORD
0390 5E                POP SI          ; RESTORE
0391 1F                POP DS          ; RESTORE SEGMENT
0392 9C                PUSHF DS       ; SAVE RESULTS FOR EXIT
ASSUME DS:DATA
0393 83 FB 0A              CMP BX,10    ; LOOK FOR MOTOR STARTUP DELAY PARM
0396 75 19              JNE GPO      ; BYPASS IF NOT PARM LOOKING FOR
;----- TEST
0398 F6 06 003F R 80      TEST MOTOR_STATUS,WRITE_OP ; IS THIS A WRITE
039D 74 09              JZ GP1        ; NO, ENFORCE MINIMUM READ WAIT
;----- CMP AH,8
03A2 80 FC 08              JAE GP2        ; SEE IF AT LEAST A SECOND IS SPECIFIED
;----- JMP SHORT GP2
03A4 B4 08              MOV AH,8        ; FORCE A SECOND WAIT FOR MOTOR START
03A6 EB 36              JMP SHORT GP2 ; CONTINUE
;----- GP1: CMP AH,5
03A8 80 FC 05              JAE GP2        ; SEE IF A 625 MS WAIT ON READ
03AB 73 31              ; IF THERE GO CONTINUE
;----- MOV AH,5
03AD B4 05              JMP SHORT GP2 ; ENFORCE A 625 MS WAIT
03AF EB 20              ; CONTINUE
;----- GPO: CMP BX,9
03B1 83 FB 09              JNE GP2        ; IS THIS HEAD SETTLE PARM
03B4 75 28              ; BYPASS IF NOT HEAD SETTLE
;----- TEST
03B6 F6 06 003F R 80      TEST MOTOR_STATUS,WRITE_OP ; SEE IF A WRITE OPERATION
03B8 74 21              JZ GP2        ; IF NOT, DONT ENFORCE ANY VALUES
;----- OR AH,AH
03BD 0A E4              JNZ GP2        ; CHECK FOR ANY WAIT?
03BF 75 1D              ; IF THERE DONT ENFORCE
;----- PUSH DX
03C1 52                PUSH DX          ; SAVE REGISTER
03C2 53                PUSH BX          ; SAVE REGISTER
03C3 8B 56 00              MOV DX,[BP]    ; GET ORIGINAL DRIVE REQUESTED
03C6 32 FF              XOR BH,BH    ; SET UP ADDRESSING TO STATE INDICATOR
03C8 8A DA              MOV BL,DL    ; SPEC'ED HEAD SETTLE TIME FOR 1.2 DRIVE
03C9 8A 0F              MOV AH,HD12_SETTLE ; GET MEDIA/DRIVE STATE
03C0 5B 87 0090 R        MOV AL,DISK_STATE[BX]
03D0 5B                POP BX          ; RESTORE
03D1 5A                POP DX          ; RESTORE
03D2 24 07              AND AL,STATE_MSK ; ISOLATE STATE NUMBER
03D4 75 04              JNZ GP4        ; BRANCH IF STATES 1 THRU 5
;----- GP3: MOV AH,HD320_SETTLE
03D6 B4 14              JMP SHORT GP2 ; SPEC'ED HEAD SETTLE TIME FOR 320 DRIVE
03D8 EB 04              ; GO TO WAIT LOOP

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03DA 3C 03          ; SEE IF STATE 3(320 DRIVE/320 MEDIA)
03DC 74 F8          ; GO REESTABLISH WAIT TIME

03DE 9D             ; RESTORE EXIT RESULTS
03DF 72 01          ; IF FLAG SET, OUTPUT TO CONTROLLER
03E1 C3             ; RETURN TO CALLER
03E2               ; ENDP

;-----[NEC_OUTPUT-----]
; THIS ROUTINE SENDS A BYTE TO THE NEC CONTROLLER
; AFTER TESTING FOR CORRECT DIRECTION AND CONTROLLER READY
; THIS ROUTINE WILL TIME OUT IF THE BYTE IS NOT ACCEPTED
; WITHIN A REASONABLE AMOUNT OF TIME, SETTING THE DISKETTE STATUS
; ON COMPLETION
INPUT   (AH)    BYTE TO BE OUTPUT
OUTPUT   CY = 0  SUCCESS
         CY = 1  FAILURE -- DISKETTE STATUS UPDATED
                  IF A FAILURE HAS OCCURRED, THE RETURN IS MADE ONE LEVEL
                  HIGHER THAN THE CALLER OF NEC_OUTPUT
                  THIS REMOVES THE REQUIREMENT OF TESTING AFTER EVERY CALL
                  TO NEC_OUTPUT
         (AL)  DESTROYED
NEC_OUTPUT PROC NEAR
PUSH    DX           ; SAVE REGISTERS
PUSH    CX
PUSH    BX
MOV     DX,03F4H      ; STATUS PORT
MOV     BL,2           ; HIGH ORDER COUNTER
MOV     CX,CX          ; COUNT FOR TIME OUT
R11:   XOR    CX,CX
J23:   IN    AL,DX        ; GET STATUS
TEST   AL,080H      ; TEST DIRECTION BIT
JZ    R12           ; DIRECTION OK
LOOP   J23

03E2 52
03E2 51
03E4 53
03E5 BA 03F4
03E8 B8 02
03EA 33 C9
03EC EC
03ED A8 40
03EF 74 11
03F1 E2 F9
03F3 FE CB
03F5 75 F3
03F7 80 0E 0041 R 80
03F7 5B
03FD 59
03FE 5A
03FF 58
0400 F9
0401 C3
0402 B3 02
0404 33 C9
0406 EC
0407 A8 80
0409 75 08
040B E2 F9
040D FE CB
040F 75 F3
0411 EB E4
0413 8A C4
0415 B2 F5
0417 EE
0418 5B
0419 59
041A 5A
041B C3
041C               ; CY = 0 FROM TEST INSTRUCTION

NEC_OUTPUT ENDP

;-----[SEEK-----]
; THIS ROUTINE WILL MOVE THE HEAD ON THE NAMED DRIVE
; TO THE NAMED TRACK.  IF THE DRIVE HAS NOT BEEN ACCESSED
; SINCE THE DRIVE RESET COMMAND WAS ISSUED, THE DRIVE WILL BE
; RECALIBRATED.
INPUT   (DL) = DRIVE TO SEEK ON
        (CH) = TRACK TO SEEK TO
OUTPUT   CY = 0  SUCCESS
         CY = 1  FAILURE -- DISKETTE_STATUS SET ACCORDINGLY
         (AX)  DESTROYED
SEEK   PROC NEAR
MOV    AH,1           ; ESTABLISH MASK FOR RECAL TEST
PUSH   CX           ; SAVE INPUT VALUES
MOV    CL,DL          ; GET DRIVE VALUE INTO CL
ROL    AL,CL          ; SHIFT IT BY THE DRIVE VALUE
POP    CX           ; RECOVER TRACK VALUE
TEST   AL,SEEK_STATUS ; TEST FOR RECAL REQUIRED
JNZ   J28           ; NO_RECAL

042A 08 06 003E R
042E B0 01
041E 51
041F 8A CA
0421 D2 C0
0423 59
0424 84 06 003E R
0425 75 37
042A 08 06 003E R
042E B4 07
CALL   E8 03E2 R
0433 EA E2
0435 EA 03E2 R
0438 EB 051A R
043B 73 14
;----- ISSUE RECALIBRATE FOR 80 TRACK DISKETTES
;-----[SEEK-----]
MOV    AH,07H          ; CLEAR OUT INVALID STATUS
MOV    AH,07H          ; RECALIBRATE COMMAND
CALL   NEC_OUTPUT
CALL   NEC_OUTPUT      ; OUTPUT THE DRIVE NUMBER
CALL   CHK_STAT_2      ; GET THE INTERRUPT AND SENSE INT STATUS
JNC   J28A           ; SEEK_COMPLETE

043D C6 06 0041 R 00
0442 B4 07
CALL   E8 03E2 R
0447 EA E2
0449 EB 03E2 R
044C EB 051A R
044F 72 78
;-----[TEST-----]
TEST  HF_CNTL,DUAL   ; GO DETERMINE TYPE OF CONTROLLER CARD
JZ    J28B           ; DISKETTE ATTACH CARD

0458 32 FF
045A 8A DA
045C CG 87 0094 R 00
;-----[XOR-----]
XOR   BH,BH          ; SET UP ADDRESSING TO STATE INDICATOR
MOV    BL,DL          ; *
MOV    DSK_TRK[BX],0   ; SAVE NEW CYLINDER AS PRESENT POSITION
;----- DRIVE IS IN SYNCH WITH CONTROLLER, SEEK TO TRACK

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0461 32 FF XOR BH,BH ; SET UP ADDRESSING TO STATE INDICATOR
0463 BA DA MOV BL,DL ;*
0465 7C 06 008F R 01 TEST HF_CNTRL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
046A 74 09 JZ R7 ; DISKETTE ATTACH CARD

046C F6 87 0090 R 20 ; TEST DSK_STATE[BX],DOUBLE_STEP ; CHECK FOR DOUBLE STEP REQUIRED
0471 74 02 ; SINGLE STEP REQUIRED BYPASS DOUBLE

0473 DO E5 ; SHL CH,1 ; DOUBLE NUMBER OF STEP TO TAKE
0475 3A AF 0094 R R7: CMP CH,DSK_TRK[BX] ; SEEK IF ALREADY AT THE DESIRED TRACK
0479 74 3E JE J32 ; IF YES, DONT NEED TO SEEK

047B 88 AF 0094 R ; MOV DSX,TRK[BX],CH ; SAVE NEW CYLINDER AS PRESENT POSITION
047D 84 0F ADD AH,AL ; SEEK COMMAND TO NEC
0481 E8 03E2 R CALL NEC_OUTPUT ;*
0484 E8 E2 MOV AH,DL ; DRIVE NUMBER
0486 E8 03E2 R CALL NEC_OUTPUT ;*
0489 E8 E5 MOV AH,CH ; GET CYLINDER NUMBER
0491 E8 05E2 R CALL NEC_OUTPUT ;*
049E E8 051A R CALL CH_STAT_2 ; GET ENDING INTERRUPT AND SENSE STATUS
0491 F6 06 008F R 01 TEST HF_CNTRL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
0496 74 09 JZ RA ; DISKETTE ATTACH CARD

0498 F6 87 0090 R 20 ; TEST DSK_STATE[BX],DOUBLE_STEP ; CHECK FOR DOUBLE STEP REQUIRED
049D 74 02 ; SINGLE STEP REQUIRED BYPASS DOUBLE

049F DO ED ; SHR CH,1 ; SET BACK TO LOGICAL SECTOR
04A1 RA: ;----- WAIT FOR HEAD SETTLE

04A1 9C PUSHF ; SAVE STATUS FLAGS
04A2 BB 0012 MOV BX,18 ; GET HEAD SETTLE PARAMETER
04A5 E8 0382 R CALL GET_PARM ;*
04A8 51 PUSH CX ; SAVE REGISTER
04A9 B9 0320 MOV CX,800 ; HEAD_SETTLE
04AC 0A E4 OR AH,AH ; * MS_LOOP
04AE 74 06 JZ J31 ; TEST FOR TIME EXPIRED

04B0 F2 FE LOOP J30 ; DELAY FOR 1 MS
04B2 FE CC DEC AH ; DECREMENT THE COUNT
04B4 00 04 JMP J29 ; DO IT SOME MORE
04B6 00 04
04B8 59 POP POPF CX ; RECOVER STATE
04B7 9D RET ; RETURN TO CALLER
04B8 C3 ;----- DMA_SETUP
04B9 B9 0320 TEST HF_CNTRL,DUAL ; SEEK_ERROR
04B9 F6 06 008F R 01 JZ RB ; GO DETERMINE TYPE OF CONTROLLER CARD
04B9 74 09 ; DISKETTE ATTACH CARD

04C0 F6 87 0090 R 20 ; TEST DSK_STATE[BX],DOUBLE_STEP ; CHECK FOR DOUBLE STEP REQUIRED
04C5 74 02 ; SINGLE STEP REQUIRED BYPASS DOUBLE

04C7 DO ED ; SHR CH,1 ; SET BACK TO LOGICAL SECTOR
04C9 C3 ;----- DMA_SETUP
04CA SEEK RET ENDP ; RETURN TO CALLER
04CA ;----- DMA_SETUP
; THIS ROUTINE SETS UP THE DMA FOR READ/WRITE/VERIFY
; OPERATIONS.
; INPUT
; (AL) = MODE BYTE FOR THE DMA
; (ES:BX) - ADDRESS TO READ/WRITE THE DATA
; OUTPUT
; (AX) DESTROYED
DMA_SETUP PROC NEAR
04CA 51 PUSH CX ; SAVE THE REGISTER
04CA FA CLI ; DISABLE INTERRUPTS DURING DMA SET-UP
04CC E6 0C OUT DMA+12,AL ; SET THE FIRST/LAST F/F
04CE EB 00 JMP $+2 ; WAIT FOR IO
04D0 E6 0B OUT DMA+11,AL ; OUTPUT THE MODE BYTE
04D2 8C C0 MOV AX,ES ; GET HIGH 4 BITS OF ES VALUE
04D4 00 04 MOV CL,ES ; SHIFT COUNT
04D6 D3 C0 ROL AX,CL ; ROTATE LEFT
04D8 8A E8 MOV CH,AL ; GET HIGHEST NYBBLE OF ES TO CH
04DA 24 F0 AND AL,OF0H ; ZERO THE LOW NYBBLE FROM SEGMENT
04DC 03 C3 ADD AX,BX ; TEST FOR CARRY FROM ADDITION
04DD 73 02 JNC J33 ;*
04E0 FE C5 INC CH ; CARRY MEANS HIGH 4 BITS MUST BE INC
04E2 50 PUSH AX ; SAVE START ADDRESS
04E3 E6 04 OUT DMA+4,AL ; OUTPUT LOW ADDRESS
04E5 EB 00 JMP $+2 ; WAIT FOR IO
04E6 8A 04 MOV AL,AH ;*
04E9 E6 04 OUT DMA+4,AL ; OUTPUT HIGH ADDRESS
04EB 8A C5 MOV AL,CH ; GET HIGH 4 BITS
04ED EB 00 JMP $+2 ; I/O WAIT STATE
04EF 24 0F AND AL,OFH ;*
04F1 E6 81 OUT 081H,AL ; OUTPUT THE HIGH 4 BITS TO PAGE REGISTER
04F3 8A E6 ;----- DETERMINE COUNT
04F5 2A C0 MOV AH,DH ; NUMBER OF SECTORS
04F6 E8 SUB AL,AL ; TIMES 256 INTO AX
04F7 50 SHR AX,1 ; SECTORS * 128 INTO AX
04F8 BB 0006 PUSH AX ;*
04FD E8 0382 R CALL GET_PARM ; USE AS SHIFT COUNT (0=128, 1=256 ETC)
0500 8A CC MOV CL,AH ;*
0501 00 04 POP AX ;*
0503 D3 E0 SHL AX,CL ; MULTIPLY BY CORRECT AMOUNT
0505 48 DEC AX ; -1 FOR DMA VALUE
0506 50 PUSH AX ; SAVE COUNT VALUE
0507 E6 05 OUT DMA+5,AL ; LOW BYTE OF COUNT
0509 EB 00 JMP $+2 ; WAIT FOR IO
050A 8A 04 MOV AL,AH ;*
050D F6 05 OUT DMA+5,AL ; HIGH BYTE OF COUNT
050F FB STI ; RE-ENABLE INTERRUPTS
0510 59 POP CX ; RECOVER COUNT VALUE
0511 58 POP AX ;*
0512 00 04 ADD AX,CX ; ADD COUNT ADDRESS VALUE
0514 59 POP CX ; ADD TEST FOR COUNT OVERFLOW
0515 B0 02 MOV AL,2 ; RECOVER REGISTER
0517 E6 0A OUT DMA+10,AL ; MODE FOR 8237
0519 C3 RET ; INITIALIZE THE DISKETTE CHANNEL
051A DMA_SETUP ENDP ; RETURN TO CALLER, CFL SET BY ABOVE IF ERROR
051A ;----- CHK_STAT_2
; THIS ROUTINE HANDLES THE INTERRUPT RECEIVED AFTER
; A RECALIBRATE, SEEK, OR RESET TO THE ADAPTER.
; THE INTERRUPT IS WAITED FOR, THE INTERRUPT STATUS SENSED,
; AND THE RESULT RETURNED TO THE CALLER.

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; INPUT      NONE
; OUTPUT     CY = 0 SUCCESS
;           CY = 1 FAILURE -- ERROR IS IN DISKETTE_STATUS
;           (AX) DESTROYED
-----[CHK_STAT_2]-----[PROC] [NEAR]
051A    E8 053B R   CALL WAIT_INT          ; WAIT FOR THE INTERRUPT
051B    49           JC  J34              ; IF ERROR, RETURN IT
051C    B4 08         MOV AH,08H          ; SENSE INTERRUPT STATUS COMMAND
0521    E8 03E2 R   CALL NEC_OUTPUT      ; READ IN THE RESULTS
0524    E8 0580 R   CALL RESULTS        ; CHK2_RETURN
0527    72 0A         JC  J34              ; GET THE FIRST STATUS BYTE
0529    A0 0042 R   MOV AL,NEC_STATUS    ; ISOFN THE BITS
0530    00 60         AND AL,060H        ; TEST FOR CORRECT VALUE
0530    5C 00         OR  AL,060H         ; IF ERROR, GO MARK IT
0532    F8           JZ   J35              ; GOOD RETURN
0533
0533    C3           CLC
0534
0534    80 0E 0041 R 40  J34:    RET      ; RETURN TO CALLER
0535    F9           OR   DISKETTE_STATUS,BAD_SEEK ; CHK2_ERROR
0539    C3           STC
053B    053B          RET      ; ERROR RETURN CODE
-----[CHK_STAT_2]-----[ENDP]

-----[WAIT_INT]-----[PROC] [NEAR]
053B    FB           STI
053C    50           PUSH AX            ; TURN ON INTERRUPTS, JUST IN CASE
053D    53           PUSH BX            ; SAVE REGISTERS
053E    51           PUSH CX            ; *
053F    F8           CLC
0540    BB 9001          MOV AX,09001H      ; CLEAR TIMEOUT INDICATOR
0543    CD 15           INT 15H           ; LOAD WAIT CODE AND TYPE
0545    72 11           JC   J36A          ; PERFORM OTHER FUNCTION
;           BYPASS TIMING LOOP IF TIMEOUT OCCURRED
-----[WAIT_INT]-----[ENDP]
0547    B3 04           STI
0549    33 C9           PUSH AX            ; CLEAR THE COUNTERS
054B
054B    F6 06 003E R 80  TEST SEEK_STATUS,INT_FLAG ; FOR 2 SECOND WAIT
0550    75 0C           JNZ  J37             ; TEST FOR INTERRUPT OCCURRING
0552    EC F8           LOOP J36            ; COUNT DOWN WHILE WAITING
0554    EC F8           DEC BL             ; SECOND LEVEL COUNTER
0556    75 F3           JNZ  J36
;           OR   DISKETTE_STATUS,TIME_OUT ; NOTHING HAPPENED
0558    80 0E 0041 R 80  J36A:  OR   DISKETTE_STATUS,TIME_OUT ; ERROR RETURN
0559    F9           STC
0560
0560    9C           J37:    PUSHF AND SEEK_STATUS,NOT INT_FLAG ; SAVE CURRENT CARRY
0565    80 26 003E R 7F  POPF  POP CX            ; TURN OFF INTERRUPT FLAG
0566    9D           POPF  POP BX            ; RECOVER CARRY
0565    59           POPF  POP AX            ; RECOVER REGISTERS
0566    5B           POPF  POP AX            ; *
0567    58           POPF  POP DS            ; *
0568    C3           RET    ; GOOD RETURN CODE COMES FROM TEST INST
0569
-----[WAIT_INT]-----[ENDP]

-----[DISK_INT]-----[PROC] [NEAR]
0569    FB           STI
0569    E6           PUSH DS            ; RE_ENABLE_INTERRUPTS
0568    50           PUSH AX            ; SAVE REGISTERS
056C    E8 0000 E   CALL DDS           ; SETUP DATA ADDRESSING
056F    80 0E 003E R 80  OR   SEEK_STATUS,INT_FLAG ; TURN ON INTERRUPT OCCURRED
0574    B0 20           MOV AL,20H          END OF INTERRUPT MARKER
0576    E6 20           OUT 20H,AL        ; INTERRUPT CONTROL PORT
0578    B6 9101          MOV AX,09101H      ; INTERRUPT_POST_CODE & TYPE
0579    5D 15           INT 15H           ; PERFORM OTHER TASK
0570    58           POP AX            ; RECOVER REQ
057E    1F           POP DS            ; *
057F    CF           IRET   ; RETURN FROM INTERRUPT
0580
-----[DISK_INT_1]-----[PROC] [FAR]
0569    FB           STI
0569    E6           PUSH DS            ; >>> ENTRY POINT FOR ORG OEF57H
0568    50           PUSH AX            ; RE_ENABLE_INTERRUPTS
056C    E8 0000 E   CALL DDS           ; SAVE REGISTERS
056F    80 0E 003E R 80  OR   SEEK_STATUS,INT_FLAG ; SETUP DATA ADDRESSING
0574    B0 20           MOV AL,20H          TURN ON INTERRUPT OCCURRED
0576    E6 20           OUT 20H,AL        END OF INTERRUPT MARKER
0578    B6 9101          MOV AX,09101H      ; INTERRUPT CONTROL PORT
0579    5D 15           INT 15H           ; INTERRUPT_POST_CODE & TYPE
0570    58           POP AX            ; PERFORM OTHER TASK
057E    1F           POP DS            ; RECOVER REQ
057F    CF           IRET   ; RETURN FROM INTERRUPT
-----[DISK_INT_1]-----[ENDP]

-----[RESULTS]-----[PROC] [NEAR]
0580    FC           STI
0581    BF 0042 R   CLD
0584    51           MOV DI,[OFFSET NEC_STATUS]; POINTER TO DATA AREA
0585    52           PUSH CX            ; SAVE COUNTER
0586    B3           PUSH DX            ; *
0587    B3 07           MOV BX            ; MAX STATUS BYTES
;           MOV BL,7
-----[RESULTS]-----[ENDP]
0580
0580    FC           CLD
0581    BF 0042 R   MOV DI,[OFFSET NEC_STATUS]; POINTER TO DATA AREA
0584    51           PUSH CX            ; SAVE COUNTER
0585    52           PUSH DX            ; *
0586    B3           PUSH BX            ; MAX STATUS BYTES
0587    B3 07           MOV BL,7
-----[WAIT_MASTER]-----[PROC] [NEAR]
0580    B7 02           R10:  MOV BH,2          ; HIGH ORDER COUNTER
0588    33 C9           J38:    XOR CX,CX        ; INPUT_LOOP
0589    BA 03F4           MOV DX,03F4H       ; COUNTER
0590
0590    EC           J39:    IN  AL,DX          ; STATUS_PORT
0591    00 80           TEST AL,080H        ; WAIT FOR MASTER
0593    75 10           JNZ  J40A          ; GET_STATUS
0595    E2 F9           LOOP J39          ; TEST_DIR
;           WAIT_MASTER
0597    FE CF           DEC BH            ; DECREMENT HIGH ORDER COUNTER

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0599 75 F0 ; JNZ J38 ; REPEAT TIL DELAY DONE
059B 80 0E 0041 R 80 ; J40: OR DISKETTE_STATUS,TIME_OUT ; RESULTS_ERROR
05A0 00 ; STC ; SET ERROR RETURN
05A1 F9 ; POP BX
05A1 5B ; POP DX
05A2 5A ; POP CX
05A3 59 ; RET
05A4 C3 ;----- TEST THE DIRECTION BIT
05A5 EC ; J40A: IN AL,DX ; GET STATUS REG AGAIN
05A6 A8 40 ; TEST AL,040H ; TEST DIRECTION BIT
05A7 75 07 ; JNZ J42 ; OK, READ STATUS
05A8 00 ; POP BX ; NEC FAIL
05AA 80 0E 0041 R 20 ; OR DISKETTE_STATUS,BAD_NEC ; RESULTS_ERROR
05AF EB EF ; JMP J40 ;----- READ IN THE STATUS
05B1 42 ; J42: INC DX ; INPUT_STAT
05B2 EC ; IN AL,DX ; POINT AT DATA PORT
05B3 88 05 ; MOV [DI],AL ; GET THE DATA
05B4 47 ; INC DI ; STORE THE BYTE
05B5 B9 0014 ; MOV CX,20 ; INCREMENT THE POINTER
05B6 E9 FE ; LOOP J43 ; LOOP TO KILL TIME FOR NEC
05B7 E2 0014 ; DEC DX ;----- POINT AT STATUS PORT
05B8 4A ; IN AL,DX ; GET STATUS
05B9 EC ; TEST AL,010H ; TEST FOR NEC STILL BUSY
05B9 A6 10 ; JZ J44 ; RESULTS DONE
05B9 75 06 ; DEC BL ;----- INCREMENT THE STATUS COUNTER
05C1 FF CB ; JNZ R10 ; GO BACK FOR MORE
05C3 75 C4 ; JMP J41 ; CHIP HAS FAILED
05C5 EB E3 ;----- RESULT OPERATION IS DONE
05C7 5B ; J44: POP BX ; RECOVER REGISTERS
05C8 5A ; POP DX ; GOOD RETURN CODE FROM TEST INST
05C9 59 ; RET
05CA C3 ;----- NUM_TRANS
05CB A0 0045 R ; THIS ROUTINE CALCULATES THE NUMBER OF SECTORS THAT
05CE 3A C5 ; WERE ACTUALLY TRANSFERRED TO/FROM THE DISKETTE
05D0 A0 0047 R ;----- INPUT
05D1 74 0A ; (CH) = CYLINDER OF OPERATION
05D2 B8 0008 ; (CL) = START SECTOR OF OPERATION
05D3 E8 0382 R ;----- OUTPUT
05D4 8A C4 ; (AL) = NUMBER ACTUALLY TRANSFERRED
05D5 FE C0 ; NO OTHER REGISTERS MODIFIED
05D6 2A C1 ;----- PROC NEAR
05D7 01 ; NUM_TRANS
05D8 00 ; MOV AL,NEC_STATUS+3 ; GET CYLINDER ENDED UP ON
05D9 00 ; CMP DX,[BP] ; SAME AS WE STARTED
05D9 00 ; MOV AL,CH ; GET ENDING SECTOR
05D9 00 ; JZ J45 ; IF ON SAME CYL, THEN NO ADJUST
05D9 00 ; MOV BX,8 ;----- CALL GET_PARM
05D9 00 ; MOV AL,[AH] ; GET EOT VALUE
05D9 00 ; INC AL ;----- INTO AL
05D9 00 ; SUB AL,CL ; USE EOT+1 FOR CALCULATION
05D9 00 ; RET ;----- SUBTRACT START FROM END
05D9 00 ;----- ENDP
05D9 00 ;----- RESULTS ENDP
05D9 00 ;----- HANDLE DISK CHANGE IF FOUND TO BE
05D9 00 ;----- ACTIVE
05D9 00 ;----- J1F: MOV DSK_STATE[BX],POA_DUAL ; CLEAR STATE FOR THIS DRIVE
05D9 00 ;----- THIS SEQUENCE OF SEEKS IS USED TO RESET DISKETTE CHANGE SIGNAL
05D9 00 ;----- CALL DISK_RESET ;----- RESET NEC
05D9 00 ;----- MOV DX,[BP] ;----- RESTORE DRIVE PARAMETER
05D9 00 ;----- MOV CH,01H ;----- MOVE TO CYLINDER 1
05D9 00 ;----- CALL SEEK ;----- ISSUE SEEK
05D9 00 ;----- MOV DX,[BP] ;----- RESTORE DRIVE PARAMETER
05D9 00 ;----- MOV CH,00H ;----- MOVE TO CYLINDER 0
05D9 00 ;----- CALL SEEK ;----- ISSUE SEEK
05D9 00 ;----- MOV DSKETTE_STATUS,MEDIA_CHANGE ;----- INDICATE MEDIA REMOVED FROM DRIVE
05D9 00 ;----- RESTORE PARAMETERS
05D9 00 ;----- POP AX ;----- *
05D9 00 ;----- POP CX ;----- *
05D9 00 ;----- POP BX ;----- *
05D9 00 ;----- POP AX ;----- *
05D9 00 ;----- RET ;----- MEDIA CHANGE, GO DETERMINE NEW TYPE
05D9 00 ;---------- READ_DSKCHNG
05D9 00 ;----- THIS ROUTINE READS THE STATE OF THE
05D9 00 ;----- DISK CHANGE LINE
05D9 00 ;----- ZERO FLAG:
05D9 00 ;----- 0 - DISK CHANGE LINE INACTIVE
05D9 00 ;----- 1 - DISK CHANGE LINE ACTIVE
05D9 00 ;---------- PROC NEAR
05D9 00 ;----- XOR BH,BH ;----- CLEAR HIGH ORDER OFFSET
05D9 00 ;----- MOV BL,DL ;----- LOAD DRIVE NUMBER AS OFFSET
05D9 00 ;----- AND BH,01 ;----- MASK FOR DETERMINING MOTOR BIT
05D9 00 ;----- MOV MOTOR_STATUS,0CFH ;----- CLEAR ENDED UP DEVICE SELECT BITS(4 & 5)
05D9 00 ;----- MOV CL,4 ;----- SHIFT DRIVE NUMBER INTO HIGH NIBBLE COUNT
05D9 00 ;----- ROL BL,CL ;----- SHIFT DRIVE NUMBER INTO HIGH NIBBLE
05D9 00 ;----- OR MOTOR_STATUS,BL ;----- ADD IN DRIVE NUMBER SELECTED FOR LATER USE
05D9 00 ;----- ROR BL,CL ;----- RESTORE DRIVE NUMBER
05D9 00 ;----- ROR CL,BL ;----- RESTORE DRIVE NUMBER
05D9 00 ;----- SHL AL,CL ;----- FORM MOTOR ON BIT MASK
05D9 00 ;----- CLI ;----- NO INTERRUPTS WHILE DETERMING MOTOR STATUS
05D9 00 ;----- TEST AL,MOTOR_STATUS ;----- TEST
05D9 00 ;----- JNZ R8 ;----- DON'T NEED TO SELECT DEVICE IF MOTOR ON
05D9 00 ;---------- R8: OR MOTOR_STATUS,AL ;----- TURN ON CURRENT MOTOR
05D9 00 ;----- MOV MOTOR_COUNT,0FFH ;----- SET LARGE COUNT DURING OPERATION
05D9 00 ;----- FB STI ;----- ENABLE INTERRUPTS AGAIN
05D9 00 ;---------- R9: MOV DX,03F2H ;----- ADDRESS DIGITAL OUTPUT REGISTER
05D9 00 ;----- AND AL,003F ;----- GET DIGITAL OUTPUT REGISTER REFLECTION
05D9 00 ;----- MOV AL,03FH ;----- STRIKE AWAY UNWANTED BITS
05D9 00 ;----- ROL AL,CL ;----- PUT BITS IN DESIRED POSITIONS
05D9 00 ;----- OR AL,0CH ;----- NO RESET, ENABLE DMA/INT
05D9 00 ;----- OUT DX,AL ;----- SELECT DRIVE
05D9 00 ;----- MOV DX,03F7H ;----- ADDRESS DIGITAL INPUT REGISTER
05D9 00 ;----- JMP $+2 ;----- DELAY FOR SUPPORT CHIP

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0642 EC IN AL,DX : INPUT DIR
0643 A8 80 TEST AL,DSK_CHG : CHECK FOR DISK CHANGE LINE ACTIVE
0645 C3 RET : RETURN TO CALLER WITH ZERO FLAG SET
READ_DSKCHNG ENDP

DISK_CHANGE
THIS ROUTINE RETURNS THE STATE OF THE
DISK CHANGE LINE
DISKETTE_STATUS:
00 - DISK CHANGE LINE INACTIVE
06 - DISK CHANGE LINE ACTIVE

0646 F6 06 008F R 01
0648 74 29 TEST JZ HF_CNTL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
; ; DISKETTE ATTACH CARD, SET CHANGE LINE ACTIVE
064D 32 FF XOR BH,BH ; CLEAR HIGH ORDER OFFSET
064E 8A AA MOV BL,DL ; LOAD DRIVE NUMBER AS OFFSET
0651 B8 07 0090 R MOV AH,DSK_STATE[BX] ; GET PRESENT STATE INFORMATION FOR DRIVE
0655 24 07 AND AL,STATE_MSK ; ISOLATE STATE
0657 3C 03 CMP AL,3 ; CHECK FOR 4BTPi DRIVE & NOT ESTABLISHED STATES
0659 74 07 SETIT JE ; IF FOUND SET DISK CHANGE ACTIVE

065B 72 0B ; JB DCO ; IF NOT ESTABLISHED, GO CHECK FOR NO DRIVE
065D E8 0604 R CALL READ_DSKCHNG ; GO CHECK STATE OF DISK CHANGE LINE
0660 74 05 FINIS ; CHANGE LINE NOT ACTIVE, RETURN

0662 C6 06 0041 R 06
0667 C3 SETIT: MOV AL,DSK_STATE[BX] ; GET MEDIA STATE INFORMATION FOR DRIVE
; ; FINIS: RET OR AL,AL ; CHECK FOR NO DRIVE INSTALLED
0668 BA 87 0090 R OR JNZ SETIT ; IF DRIVE PRESENT, SET CHANGE LINE ACTIVE
066C 0A C0
066E 75 F2

0670 80 0E 0041 R 80
0675 C3 DC1: OR DISKETTE_STATUS,TIME_OUT ; SET TIMEOUT BECAUSE NO DRIVE PRESENT
; ; RET : RETURN TO CALLER

0676 B0 0E TEST JZ AL,CMOSDSK_ADDR ; GET CMOS DIAGNOSTIC STATUS BYTE ADDRESS
0677 E6 70 OUT CADR_PRT,AL ; WRITE ADDRESS TO READ OUT TO CMOS
0686 EB 00 JMP S+2 ; DELAY
0688 E4 71 IN AL,CDATA_PRT ; GET DISKETTE BYTE
068A 0A D2 OR DL,DL ; SEE WHICH DRIVE IN QUESTION
068C 75 04 JNZ DC3 ; IF DRIVE 1, DATA ALREADY IN LOW NIBBLE

068E B1 04 ; MOV CL,4 ; GET ROTATE COUNT TO SHIFT HIGH TO LOW NIBBLE
0690 D2 C8 ROR AL,CL ; EXCHANGE NIBBLES
0692 24 0F AND AL,LOWNIB ; CLEAR AWAY UNDESIRABLE DRIVE DATA
0694 74 DA DC3: JZ DC1 ; NO DRIVE THEN SET TIMEOUT ERROR

0696 EB CA ; SHORT_SETIT ; DRIVE, ON 320/360K DRIVES SET DISK CHANGE
DISK_CHANGE ENDP

DISK_TYPE
THIS ROUTINE IS USED TO EITHER ESTABLISH THE
TYPE OF MEDIA/DRIVE TO BE USED IN THE NEXT
OPERATION (FOR FORMAT ONLY) OR RETURN THE
TYPE OF MEDIA/DRIVE INSTALLED AT THE DRIVE
SPECIFIED

0698 F6 06 008F R 01
069D 74 49 TEST JZ HF_CNTL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD
; ; DISKETTE ATTACH CARD, GO DO TYPE OPERATION
069F 32 FF XOR BH,BH ; CLEAR HIGH ORDER OFFSET
06A1 8A DA MOV BL,DL ; LOAD DRIVE NUMBER AS OFFSET
06A3 8A AT 0090 R MOV AH,DSK_STATE[BX] ; GET PRESENT STATE INFORMATION

06A7 F6 C6 10 TEST JZ AH_DETERMINED ; SEE IF MEDIA/DRIVE TYPE ALREADY ESTABLISHED
06AA 74 0B ; IF NOT, GO RETURN ZERO VALUE

06AC 80 E4 07 AND AH,STATE_MSK ; STRIP OFF HIGH ORDER BITS
06AF 80 EC 03 SUB AH,03H ; CONVERT TO TYPE FOR OUTPUT
06B2 75 0C JNZ T7 ; SKIP IF NOT 320/360 DRIVE AND MEDIA

06B4 B0 01 MOV AL,NOCHGLN ; INDICATE NO CHANGE LINE AVAILABLE
06B6 C3 RET ; RETURN TO CALLER

06B7 0A E4 T5: OR AH,AH ; CHECK FOR NO DRIVE
06B9 74 2A JZ TI ; IF NONE GO INDICATE SUCH TO CALLER

06B8 80 E4 07 AND AH,STATE_MSK ; STRIP OFF HIGH ORDER BITS
06BE 74 03 JZ TA ; IF STATE 0 CHECK CMOS

06C0 B0 02 T7: MOV AL,CHGLN ; 1,2 DRIVE
06C2 C3 RET ; RETURN TO CALLER

06C3 B0 0E TA: MOV AL,CMOSDSB_ADDR ; GET CMOS DIAGNOSTIC STATUS BYTE ADDRESS
06C5 E6 70 OUT CADR_PRT,AL ; WRITE ADDRESS TO READ OUT TO CMOS
06C8 E4 71 JMP S+2 ; DELAY
06C9 E4 71 IN AL,CDATA_PRT ; GET DISKETTE BYTE
06CB 8A C0 TEST AL,CMOS_GOOD ; SEE IF BATTERY GOOD AND CHECKSUM VALID
06CD 75 16 JNZ T1 ; IF DRIVE 1, DATA ALREADY IN LOW NIBBLE

06D6 B0 10 MOV AL,CMOSDSK_BYTE ; ADDRESS OF DISKETTE BYTE IN CMOS
06D1 E6 70 OUT CADR_PRT,AL ; WRITE ADDRESS TO READ OUT TO CMOS
06D3 EB 00 JMP S+2 ; DELAY
06D5 E4 71 IN AL,CDATA_PRT ; GET DISKETTE BYTE
06D7 0D 0A OR DL,DL ; SEE WHICH DRIVE IN QUESTION
06D9 75 04 JNZ TB ; IF DRIVE 1, DATA ALREADY IN LOW NIBBLE

06DB B1 04 T1: MOV CL,4 ; GET ROTATE COUNT TO SHIFT HIGH TO LOW NIBBLE
06DD D2 C8 ROR AL,CL ; EXCHANGE NIBBLES
06DF 24 0F AND AL,LOWNIB ; CLEAR AWAY UNDESIRABLE DRIVE DATA
06E1 3C 03 CMP AL,3 ; SEE IF UNDEFINED DISKETTE TYPE
06E3 72 02 JB TC ; RETURN IT NOT, RESULTS IN AL

06E5 32 C0 T1: XOR AL,AL ; STATE NO DRIVE PRESENT OR UNKNOWN
06E7 C3 TC: RET ; RETURN TO CALLER

06E8 B0 0E T2: MOV AL,CMOSDSB_ADDR ; GET CMOS DIAGNOSTIC STATUS BYTE ADDRESS
06E9 E6 70 OUT CADR_PRT,AL ; WRITE ADDRESS TO READ OUT TO CMOS
06EC EB 00 JMP S+2 ; DELAY
06EE E4 71 IN AL,CDATA_PRT ; GET CMOS STATUS
06F0 A8 C0 TEST AL,CMOS_GOOD ; SEE IF BATTERY GOOD AND CHECKSUM VALID
06F2 75 F1 JNZ T1 ; IF DRIVE 1, DATA ALREADY IN LOW NIBBLE

06F4 B0 10 MOV AL,CMOSDSK_BYTE ; ADDRESS OF DISKETTE BYTE IN CMOS
06F6 E6 70 OUT CADR_PRT,AL ; WRITE ADDRESS TO READ OUT TO CMOS

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06F8 EB 00           JMP    $+2      ; DELAY
06FA E4 71           IN     AL,CDATA_PRT ; GET DISKETTE BYTE
06FB 04 02           OR     AL,DL      ; SEE WHICH DRIVE IN QUESTION
070E 75 04           JNZ    T3       ; IF DRIVE 1, DATA ALREADY IN LOW NIBBLE
0700 ;               MOV    CL,4      ; GET ROTATE COUNT TO SHIFT HIGH TO LOW NIBBLE
0702 D2 C8           ROR    AL,CL      ; EXCHANGE NIBBLES
0704 24 0F           T3:   AND    AL,LOWNIB ; CLEAR AWAY UNDESIRABLE DRIVE DATA
0706 3C 02           CMP    AL,INVALID_DRV ; SEE IF UNDEFINED DISKETTE TYPE
0708 72 02           JB     T6       ; RETURN IF NOT, RESULTS IN AL
070A 32 C0           ;               XOR    AL,AL      ; STATE NO DRIVE PRESENT OR UNKNOWN
070C C3             T6:   RET       ; RETURN TO CALLER
070D ;               DISK_TYPE ENDP

;-----[FORMAT_SET]-----[THIS ROUTINE IS USED TO ESTABLISH THE TYPE OF MEDIA/DRIVE TO BE USED FOR THE FOLLOWING FORMAT OPERATION]
;-----[FORMAT_SET]-----[TEST HF_CTRNL,DUAL SO PROC NEAR]
;-----[FORMAT_SET]-----[JZ HF_CTRNL,DUAL ; GO DETERMINE TYPE OF CONTROLLER CARD]
;-----[FORMAT_SET]-----[RET HF_CTRNL,DUAL ; DISKETTE ATTACH CARD, GO DO TYPE OPERATION]
;-----[FORMAT_SET]-----[MOV BH,BH      ; CLEAR HIGH ORDER OFFSET]
;-----[FORMAT_SET]-----[MOV BL,DL      ; LOAD DRIVE NUMBER AS OFFSET]
;-----[FORMAT_SET]-----[DEC AL       ; CHECK FOR 320/360K MEDIA & DRIVE]
;-----[FORMAT_SET]-----[JNZ S1       ; BYPASS IF NOT]
;-----[FORMAT_SET]-----[MOV DSK_STATE[BX],M326D326 ; SET STATE VARIABLE]
;-----[FORMAT_SET]-----[RET DSK_STATE[BX],M326D326 ; RETURN TO CALLER]
;-----[FORMAT_SET]-----[MOV AX,DX,[BX] ; SAVE TYPE VALUE]
;-----[FORMAT_SET]-----[CALL READ_DSKCHNG ; GO CHECK DISK CHANGE LINE]
;-----[FORMAT_SET]-----[JZ S3       ; NOT ACTIVE GO ON PROCESSING]
;-----[FORMAT_SET]-----[MOV DISKETTE_STATUS,MEDIA_CHANGE ; INDICATE DISK CHANGE ACTIVE]
;-----[FORMAT_SET]-----[MOV DX,[BP]  ; RESTORE DRIVE PARAMETER]
;-----[FORMAT_SET]-----[MOV CH,01H  ; MOVE TO CYLINDER 1]
;-----[FORMAT_SET]-----[CALL SEEK   ; ISSUE SEEK]
;-----[FORMAT_SET]-----[MOV DX,[BP]  ; RESTORE DRIVE PARAMETER]
;-----[FORMAT_SET]-----[MOV CH,00H  ; MOVE TO CYLINDER 0]
;-----[FORMAT_SET]-----[CALL SEEK   ; ISSUE SEEK]
;-----[FORMAT_SET]-----[MOV DX,[BP]  ; RESTORE DRIVE PARAMETER]
;-----[FORMAT_SET]-----[CALL READ_DSKCHNG ; GO CHECK DISK CHANGE LINE]
;-----[FORMAT_SET]-----[JZ S3       ; CHANGE LINE INACTIVE, GO SET TYPE]
;-----[FORMAT_SET]-----[POP AX       ; RESTORE TYPE VALUE]
;-----[FORMAT_SET]-----[MOV DISKETTE_STATUS,TIME_OUT ; INDICATE NO MEDIA IN DRIVE]
;-----[FORMAT_SET]-----[MOV BX,[BP]  ; RESTORE DRIVE PARAMETER FOR USE AS INDEX]
;-----[FORMAT_SET]-----[XOR BH,BH      ; CLEAR HIGH ORDER OFFSET]
;-----[FORMAT_SET]-----[MOV DSK_STATE[BX],POA_DUAL ; SET STATE TO POWER ON ASSUMPTION]
;-----[FORMAT_SET]-----[RET DSK_STATE[BX],POA_DUAL ; RETURN TO CALLER]
;-----[FORMAT_SET]-----[MOV AX,DX,[BP] ; RESTORE TYPE VALUE]
;-----[FORMAT_SET]-----[DEC AL       ; CHECK FOR 320/360K MEDIA IN 1.2M DRIVE]
;-----[FORMAT_SET]-----[JNZ S2       ; BYPASS IF NOT]
;-----[FORMAT_SET]-----[MOV DSK_STATE[BX],M12D12 ; SET STATE VARIABLE]
;-----[FORMAT_SET]-----[RET DSK_STATE[BX],M12D12 ; RETURN TO CALLER]
;-----[FORMAT_SET]-----[MOV AX,DX,[BP] ; RESTORE TYPE VALUE]
;-----[FORMAT_SET]-----[CALL DEC AL      ; CHECK FOR 1.2M MEDIA IN 1.2M DRIVE]
;-----[FORMAT_SET]-----[JNZ S2       ; BYPASS IF NOT, ERROR CONDITION NOW EXISTS]
;-----[FORMAT_SET]-----[MOV DSK_STATE[BX],M12D12 ; SET STATE VARIABLE]
;-----[FORMAT_SET]-----[RET DSK_STATE[BX],M12D12 ; RETURN TO CALLER]
;-----[FORMAT_SET]-----[MOV SE,MOV SO,RET ; DISKETTE_STATUS,BAD_CMD ; UNKNOWN STATE,BAD COMMAND]
;-----[FORMAT_SET]-----[FORMAT_SET ENDP]

;-----[DSKETTE_SETUP]-----[THIS ROUTINE DOES A PRELIMINARY CHECK TO SEE WHAT TYPE OF DISKETTE DRIVES ARE ATTACH TO THE SYSTEM. TEST IS ONLY PERFORMED WHEN A DUAL ATTACHMENT CARD EXISTS.]
;-----[DSKETTE_SETUP]-----[TEST HF_CTRNL,DUAL SO PROC NEAR]
;-----[DSKETTE_SETUP]-----[PUSH AX      ; SAVE REGISTERS]
;-----[DSKETTE_SETUP]-----[PUSH CX      ; *]
;-----[DSKETTE_SETUP]-----[PUSH DX      ; *]
;-----[DSKETTE_SETUP]-----[PUSH SI      ; *]
;-----[DSKETTE_SETUP]-----[PUSH DI      ; *]
;-----[DSKETTE_SETUP]-----[PUSH ES      ; *]
;-----[DSKETTE_SETUP]-----[PUSH DS      ; *]
;-----[DSKETTE_SETUP]-----[PUSH BP      ; *]
;-----[DSKETTE_SETUP]-----[CALL DDS      ; LOAD DATA SEGMENT REGISTER TO ROM BIOS AREA]
;-----[DSKETTE_SETUP]-----[MOV BX,0      ; INITIALIZE DATA POINTER]
;-----[DSKETTE_SETUP]-----[MOV WORD PTR DSK_STATE[BX],0 ; INITIALIZE START STATES]
;-----[DSKETTE_SETUP]-----[MOV WORD PTR DSK_STATE[BX+1],0 ; INITIALIZE START STATES]
;-----[DSKETTE_SETUP]-----[MOV LASTRTE,0      ; INITIALIZ LAST DATA TRANSFER RATE]
;-----[DSKETTE_SETUP]-----[MOV SEEK_STATUS,0 ; INDICATE RECALIBRATES NEEDED]
;-----[DSKETTE_SETUP]-----[MOV MOTOR_COUNT,0 ; INITAILIZE MOTOR COUNT]
;-----[DSKETTE_SETUP]-----[MOV MOTOR_STATUS,0 ; INITAILIZE DRIVES TO OFF STATE]
;-----[DSKETTE_SETUP]-----[PUSHF      ; SAVE PICTURE]
;-----[DSKETTE_SETUP]-----[MOV AL,01      ; MASK FOR DETERMINING MOTOR BIT]
;-----[DSKETTE_SETUP]-----[AND MOTOR_STATUS,OCFFH ; CLEAR ENCODED DRIVE SELECT BITS(4 & 5)]
;-----[DSKETTE_SETUP]-----[MOV CL,4      ; SHIFT DRIVE NUMBER INTO HIGH NIBBLE COUNT]
;-----[DSKETTE_SETUP]-----[ROL BL,CL      ; SHIFT DRIVE NUMBER INTO HIGH NIBBLE]
;-----[DSKETTE_SETUP]-----[MOV MOTOR_STATUS,BL ; ALIGN NUMBER WITH DRIVES SELECTED FOR LATER USE]
;-----[DSKETTE_SETUP]-----[ROR BL,CL      ; RESTORE DRIVE NUMBER]
;-----[DSKETTE_SETUP]-----[MOV CL,BL      ; RESTORE DRIVE NUMBER]
;-----[DSKETTE_SETUP]-----[SHL AL,CL      ; FORM MOTOR ON BIT MASK]
;-----[DSKETTE_SETUP]-----[CLI          ; NO INTERRUPTS WHILE DETERMING MOTOR STATUS]
;-----[DSKETTE_SETUP]-----[TEST AL,MOTOR_STATUS ; TEST]
;-----[DSKETTE_SETUP]-----[JNZ SUP2      ; DONT NEED TO SELECT DEVICE IF MOTOR ON]
;-----[DSKETTE_SETUP]-----[OR MOTOR_STATUS,AL ; TURN ON CURRENT MOTOR]
;-----[DSKETTE_SETUP]-----[MOV MOTOR_COUNT,0FFH ; SET LARGE COUNT DURING OPERATION]
;-----[DSKETTE_SETUP]-----[SUP2:  SHL AL,MOTOR_STATUS ; ENABLE INTERRUPTS AGAIN]
;-----[DSKETTE_SETUP]-----[MOV DX,03F2H ; ADDRESS DIGITAL INPUT REGISTER]
;-----[DSKETTE_SETUP]-----[AND AL,03FH ; ADDRESS DIGITAL INPUT REGISTER]
;-----[DSKETTE_SETUP]-----[GET DIGITAL OUTPUT REGISTER REFLECTION]
;-----[DSKETTE_SETUP]-----[STRIP AWAY UNWANTED BITS]
;-----[DSKETTE_SETUP]-----[SHIFT COUNT]
;-----[DSKETTE_SETUP]-----[PUT BITS IN DESIRED POSITIONS]
;-----[DSKETTE_SETUP]-----[NO RESET,ENABLE DMA/INT]
;-----[DSKETTE_SETUP]-----[SELECT DRIVE]
;-----[DSKETTE_SETUP]-----[ESTABLISH DRIVE PARM FOR SEEK ROUTINE]
;-----[DSKETTE_SETUP]-----[GET TRACK TO SEEK TO(>0)]
;-----[DSKETTE_SETUP]-----[MOV CH,TR_SLAP ; SEEK =]
;-----[DSKETTE_SETUP]-----[CALL SEEK      ; SEEK TO TRACK]
;-----[DSKETTE_SETUP]-----[POT DX      ; RESTORE POINTER]
;-----[DSKETTE_SETUP]-----[PUSH AX      ; SAVE POSITION]
;-----[DSKETTE_SETUP]-----[MOV CH,QUIET_SEEK ; SEEK SO FAR IN, BEFORE ISSUING SINGLE STEPS]
;-----[DSKETTE_SETUP]-----[CALL SEEK      ; SEEK TO TRACK 10]

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07EH B5 0A          MOV CH,_QUIET_SEEK ; GET TRACK AT PRESENTLY
07E6 33 F6          XOR SI,SI   ; CLEAR SEEK COUNTER
07E8 FE CD          SUP3: DEC CH      ; SEEK TO NEXT TRACK, TOWARDS TRACK 0
07EA 5A              POP DX      ; RESTORE POINTER
07EB 52              PUSH DX    ; SAVE POINTER
07EC 56              PUSH SI    ; SAVE COUNTER
07ED EB 041C R      CALL SEEK   ; SEEK TO TRACK

07F0 B4 04          MOV AH,_SENSE_DRV_ST ; SENSE DRIVE STATUS COMMAND BYTE
07F2 E8 082C R      CALL SUP5    ; ISSUE THE COMMAND
07F5 E8 0580 R      CALL RESULTS ; GO GET STATUS
07F8 5E              POP SI     ; RESTORE COUNTER
07F9 46              INC SI     ; COUNT NUMBER OF SEEKS TIL AT HOME(TRACK 0)

07FA F6 06 0042 R 10 ; TEST NEC_STATUS,HOME ; LOOK TO SEE IF HEAD IS AT TRACK 0
07FF 75 08          JNZ SUP4    ; GO DETERMINE DRIVE TYPE

0801 83 FE 0B          ; CMP SI,_QUIET_SEEK+1 ; SEE IF THE NUMBER OF SEEKS = NUMBER ISSUED
0804 72 E2          JB SUP3    ; IF LESS THAN, NOT DONE YET

0806 5B              POP BX      ; RESTORE POINTER
0807 EB 10          JMP SHORT NXT_DRV ; DRIVE NOT INSTALLED, BYPASS

0809 5B              ; SUP4: POP BX      ; RESTORE POINTER
080A 83 FE 0A          CMP SI,_QUIET_SEEK ; SEE IF SEEKS STEPPED EQUAL THE ORIGINAL
080D C6 87 0090 R 61 ; MOV DSK_STATE[BX],POA_DUAL; SETUP POWER ON ASSUMPTION
0812 73 05          JAE NXT_DRV ; IF YES 1.2 DRIVE

0814 C6 87 0090 R 93 ; MOV DSK_STATE[BX],M326D326 : ESTABLISH 320/360K STATE
0819 NXT_DRV:          ; INC BX      ; POINT TO NEXT DRIVE
081A 43              CMP BX,_MAX_DRV ; SEE IF DONE
081D 74 03          JE SUP1    ; IF FINISHED LEAVE TEST

081F E9 07AO R      JMP SUP0    ; REPEAT TIL DONE FOR EACH DRIVE

0822 5D              ; SUP1: POP BP      ; RESTORE ALL REGISTERS
0823 1F              POP DS      ; *
0824 07              POP ES      ; *
0825 5F              POP DI      ; *
0826 5E              POP SI      ; *
0827 5A              POP DX      ; *
0828 59              POP CX      ; *
0829 5B              POP BX      ; *
082A 58              POP AX      ; *
082B C3              RET        ; OTHERWISE RETURN

;----- KEEP STACK CORRECT FOR CALL TO NEC_OUTPUT IF ERROR

082C E8 03E2 R      SUP5: CALL NEC_OUTPUT ; OUTPUT TO NEC
082F 8A E2          MOV AH,DL   ; GET DRIVE NUMBER SELECTED
0831 E8 03E2 R      CALL NEC_OUTPUT ; OUTPUT TO NEC
0834 C3              RET        ; *

0835 DSKEETTE_SETUP ENDP

0835 CODE ENDS END

```

**5-102 Diskette**

## TITLE FIXED DISK BIOS FOR IBM DISK CONTROLLER 1-11-84

PUBLIC DISK\_IO  
PUBLIC HD\_INT  
PUBLIC DISK\_SETUP

EXTRN F1780:NEAR  
EXTRN F1781:NEAR  
EXTRN F1782:NEAR  
EXTRN F1790:NEAR  
EXTRN F1791:NEAR  
EXTRN FD\_TBL:NEAR

;-- INT 13 -----

## ; FIXED DISK I/O INTERFACE

THIS INTERFACE PROVIDES ACCESS TO 5 1/4" FIXED DISKS  
THROUGH THE IBM DISK CONTROLLER.  
THE BIOS ROUTINES ARE MEANT TO BE ACCESSED THROUGH  
SOFTWARE INTERRUPTS ONLY. ANY ADDRESSES PRESENT IN  
THE LISTINGS ARE INCLUDED ONLY FOR COMPLETENESS,  
NOT FOR REFERENCE. APPLICATIONS WHICH REFERENCE  
ABSOLUTE ADDRESSES WITHIN THE CODE SEGMENT  
VIOLATE THE STRUCTURE AND DESIGN OF BIOS.

## INPUT (AH = HEX VALUE)

(AH)=00 RESET DISK (DL = 80H,81H) / DISKETTE  
(AH)=01 READ THE STATUS OF THE LAST DISK OPERATION INTO (AL)  
NOTE: DL < 80H - DISKETTE  
DL > 80H - DISK  
(AH)=02 READ THE DESIRED SECTORS INTO MEMORY  
(AH)=03 WRITE THE DESIRED SECTORS FROM MEMORY  
(AH)=04 VERIFY THE DESIRED SECTORS  
(AH)=05 FORMAT THE DESIRED TRACK  
(AH)=06 UNUSED  
(AH)=07 UNUSED  
(AH)=08 RETURN THE CURRENT DRIVE PARAMETERS  
(AH)=09 INITIALIZE DRIVE PAIR CHARACTERISTICS  
INTERRUPT 41 POINTS TO DATA BLOCK FOR DRIVE 0  
INTERRUPT 45 POINTS TO DATA BLOCK FOR DRIVE 1  
(AH)=0A READ LONG  
(AH)=0B WRITE LONG  
NOTE: READ AND WRITE LONG ENCOMPASS 512 + 4 BYTES ECC  
(AH)=0C SEEK  
(AH)=0D ALTERNATE DISK RESET (SEE DL)  
(AH)=0E UNUSED  
(AH)=0F UNUSED  
(AH)=10 TEST DRIVE READY  
(AH)=11 RECALIBRATE  
(AH)=12 UNUSED  
(AH)=13 UNUSED  
(AH)=14 CONTROLLER INTERNAL DIAGNOSTIC  
(AH)=15 READ DASD TYPE

## PAGE

## REGISTERS USED FOR FIXED DISK OPERATIONS

(DL) - DRIVE NUMBER (80H-81H FOR DISK, VALUE CHECKED)  
(DH) - HEAD NUMBER (0-15 ALLOWED, NOT VALUE CHECKED)  
(CH) - CYLINDER NUMBER (0-1023, NOT VALUE CHECKED)(SEE CL)  
(CL) - SECTOR NUMBER (1-17, NOT VALUE CHECKED)

NOTE: HIGH 2 BITS OF CYLINDER NUMBER ARE PLACED  
IN THE HIGH 2 BITS OF THE CL REGISTER  
(10 BITS TOTAL)  
(AL) - NUMBER OF SECTORS (MAXIMUM POSSIBLE RANGE 1-80H,  
FOR READ/WRITE LONG 1-79H)  
(ES:BX) - ADDRESS OF BUFFER FOR READS AND WRITES,  
(NOT REQUIRED FOR VERIFY)

FORMAT (AH=5) ES:BX POINTS TO A 512 BYTE BUFFER. THE FIRST  
2\*(SECTORS/TRACK) BYTES CONTAIN F\_1 FOR EACH SECTOR.  
F = FIRST SECTOR  
00H FOR A BAD SECTOR  
N = SECTOR NUMBER  
FOR AN INTERLEAVE OF 2 AND 17 SECTORS/TRACK  
THE TABLE SHOULD BE:  
DB 00H,01H,00H,0AH,00H,02H,00H,0BH,00H,03H,00H,0CH  
DB 00H,04H,00H,0DH,00H,05H,00H,0EH,00H,06H,00H,0FH  
DB 00H,07H,00H,10H,00H,08H,00H,11H,00H,09H

## OUTPUT

AH = STATUS OF CURRENT OPERATION  
STATUS BITS ARE DEFINED IN THE EQUATES BELOW  
CY = 0 SUCCESSFUL OPERATION (AH=0 ON RETURN)  
CY = 1 FAILED OPERATION (AH HAS ERROR REASON)

NOTE: ERROR 11H INDICATES THAT THE DATA READ HAD A RECOVERABLE  
ERROR WHICH WAS CORRECTED BY THE ECC ALGORITHM. THE DATA  
IS PROBABLY GOOD. HOWEVER THE BIOS ROUTINE INDICATES AN  
ERROR TO ALLOW THE CONTROLLING PROGRAM A CHANCE TO DECIDE  
FOR ITSELF. THE ERROR MAY NOT RECUR IF THE DATA IS  
REWRITTEN.

IF DRIVE PARAMETERS WERE REQUESTED,

DL = NUMBER OF CONSECUTIVE ACKNOWLEDGING DRIVES ATTACHED (0-2)  
(CONTROLLER CARD ZERO TALLY ONLY)

DH = MAXIMUM USEABLE VALUE FOR HEAD NUMBER

CH = MAXIMUM USEABLE VALUE FOR CYLINDER NUMBER

CL = MAXIMUM USEABLE VALUE FOR SECTOR NUMBER  
AND CYLINDER NUMBER HIGH BITS

IF READ DASD TYPE WAS REQUESTED,

AH = 0 - NOT PRESENT

- 1 - DISKETTE - NO CHANGE LINE AVAILABLE
- 2 - DISKETTE - CHANGE LINE AVAILABLE
- 3 - FIXED DISK

CX,DX = NUMBER OF 512 BYTE BLOCKS WHEN AH = 3

REGISTERS WILL BE PRESERVED EXCEPT WHEN THEY ARE USED TO RETURN  
INFORMATION.

NOTE: IF AN ERROR IS REPORTED BY THE DISK CODE, THE APPROPRIATE  
ACTION IS TO RESET THE DISK, THEN RETRY THE OPERATION.

= 00FF	SENSE FAIL	EQU	0FFH	; NOT IMPLEMENTED
= 00E0	NO_ERR	EQU	0EH	; STATUS ERROR/ERROR REG=0
= 00C0	WRITE_FAULT	EQU	0CH	; WRITE FAULT OCCURRED
= 00B8	UNDEF_ERR	EQU	0BH	; UNDEFINED ERROR OCCURRED
= 00AA	NOT_RDY	EQU	0AH	; DRIVE NOT READY
= 0080	TIME_OUT	EQU	80H	; ATTACHMENT FAILED TO RESPOND
= 0040	BAD_SEEK	EQU	40H	; SEEK OPERATION FAILED

```

= 0020      BAD_CNTLRL    EQU     20H          ; CONTROLLER HAS FAILED
= 0011      DATA_CORRECTED EQU     11H          ; ECC CORRECTED DATA ERROR
= 0010      BAD_ECC      EQU     10H          ; BAD ECC ON DISK READ
= 000B      BAD_BLOCK     EQU     0AH          ; BAD BLOCK DETECTED
= 000A      BAD_SECTOR    EQU     0AH          ; BAD SECTOR FLAG DETECTED
= 0009      DMA_BOUNDARY  EQU     09H          ; DATA EXTENDS TOO FAR
= 0007      INIT_FAIL    EQU     07H          ; DRIVE PARAMETER ACTIVITY FAILED
= 0005      BAD_RESET    EQU     05H          ; RESET FAILED
= 0004      RECORD_NOT_FND EQU     04H          ; REQUESTED SECTOR NOT FOUND
= 0002      BAD_ADDR_MARK EQU     02H          ; ADDRESS MARK NOT FOUND
= 0001      BAD_CMD       EQU     01H          ; BAD COMMAND PASSED TO DISK I/O
PAGE

```

;-----; FIXED DISK PARAMETER TABLE

```

;-----;
;-----; - THE TABLE IS COMPOSED OF A BLOCK DEFINED AS:
;-----;
;-----+0  (1 WORD) - MAXIMUM NUMBER OF CYLINDERS
;-----+2  (1 BYTE) - MAXIMUM NUMBER OF HEADS
;-----+3  (1 WORD) - NOT USED/SET PC-XT
;-----+5  (1 WORD) - NOT USED/WRITE PRECOMPENSATION CYL
;-----+7  (1 BYTE) - MAXIMUM END DATA BURST LENGTH
;-----+8  (1 BYTE) - CONTROL BYTE
;-----    BIT 7 DISABLE RETRIES -OR-
;-----    BIT 6 DISABLE RETRIES
;-----    BIT 5 MORE THAN 8 HEADS
;-----+9  (3 BYTES) - USED/SET PC-XT
;-----+12 (1 WORD) - LANDING ZONE
;-----+14 (1 BYTE) - NUMBER OF SECTORS/TRACK
;-----+15 (1 BYTE) - RESERVED FOR FUTURE USE

```

```

;-----; - TO DYNAMICALLY DEFINE A SET OF PARAMETERS
;-----; BUILD A TABLE FOR UP TO 15 TYPES AND PLACE
;-----; THE CORRESPONDING VECTOR INTO INTERRUPT 41
;-----; FOR DRIVE 0 AND INTERRUPT 46 FOR DRIVE 1.
;-----;

```

```

LIST
PAGE
C INCLUDE SEGMENT.SRC
C CODE SEGMENT BYTE PUBLIC

```

;-----; HARDWARE SPECIFIC VALUES

```

;-----; - CONTROLLER I/O PORT
;-----> WHEN READ FROM:
;-----HF_PORT      EQU     01F0H          ; DISK PORT
;-----HF_PORT+1    EQU     0000H          ; READ DATA (FROM CONTROLLER TO CPU)
;-----HF_PORT+2    EQU     0000H          ; GET ERROR REGISTER
;-----HF_PORT+3    EQU     0000H          ; GET SECTOR COUNT
;-----HF_PORT+4    EQU     0000H          ; GET SECTOR NUMBER
;-----HF_PORT+5    EQU     0000H          ; GET CYLINDER LOW
;-----HF_PORT+6    EQU     0000H          ; GET CYLINDER HIGH (2 BITS)
;-----HF_PORT+7    EQU     0000H          ; GET SIZE/DRIVE/HEAD
;-----HF_PORT+7    EQU     0000H          ; GET STATUS REGISTER
;-----> WHEN WRITTEN TO:
;-----HF_PORT+0    EQU     0000H          ; WRITE DATA (FROM CPU TO CONTROLLER)
;-----HF_PORT+1    EQU     0000H          ; SET PRECOMPENSATION CYLINDER
;-----HF_PORT+2    EQU     0000H          ; SET SECTOR COUNT
;-----HF_PORT+3    EQU     0000H          ; SET SECTOR NUMBER
;-----HF_PORT+4    EQU     0000H          ; SET CYLINDER LOW
;-----HF_PORT+5    EQU     0000H          ; SET CYLINDER HIGH (2 BITS)
;-----HF_PORT+6    EQU     0000H          ; SET SIZE/DRIVE/HEAD
;-----HF_PORT+7    EQU     0000H          ; SET COMMAND REGISTER

```

```

= 01F0 HF_PORT      EQU     01F0H          ; DISK PORT
= 03F6 HF_REG_PORT  EQU     3F6H

```

;-----; STATUS REGISTER

```

= 0001 ST_ERROR      EQU     00000001B          ; ECC CORRECTION SUCCESSFUL
= 0002 ST_INDEX      EQU     00000010B
= 0004 ST_CORRCTD   EQU     00000100B
= 0008 ST_D_RQ       EQU     00001000B
= 0010 ST_BLOCK_COMPL EQU     00010000B          ; SEEK COMPLETE
= 0020 ST_WRT_FLT    EQU     00100000B          ; WRITE FAULT
= 0040 ST_READY      EQU     01000000B
= 0080 ST_BUSY       EQU     10000000B

```

;-----; ERROR REGISTER

```

= 0001 ERR_DAM       EQU     00000001B          ; DATA ADDRESS MARK NOT FOUND
= 0002 ERR_TRK_0     EQU     00000010B          ; TRACK 0 NOT FOUND ON RECAL
= 0004 ERR_ABORT     EQU     00000100B          ; ABORTED COMMAND
;-----;
= 0010 ERR_ID        EQU     00010000B          ; NOT USED
;-----;
= 0040 ERR_DATA_ECC  EQU     00100000B          ; ID NOT FOUND
= 0080 ERR_BAD_BLOCK EQU     10000000B          ; NOT USED

```

```

= 0010 RECAL_CMD    EQU     00010000B          ; DRIVE RECAL (10H)
= 0020 READ_CMD     EQU     00100000B          ; READ (20H)
= 0030 WRITE_CMD    EQU     00000000B          ; WRITE (40H)
= 0040 VERIFY_CMD   EQU     01000000B          ; VERIFY (40H)
= 0050 FMTTRK_CMD   EQU     01010000B          ; FORMAT TRACK (50H)
= 0060 INIT_CMD     EQU     01100000B          ; INITIALIZE (60H)
= 0070 SEEK_CMD     EQU     01110000B          ; SEEK (70H)
= 0080 DIAOG_CMD    EQU     10000000B          ; DIAGNOSTIC (80H)
= 0091 SET_PARM_CMD EQU     10010000B          ; DRIVE PARMS (91H)
= 0001 NO_RETRY     EQU     00000001B          ; CMD MODIFIER (01H)
= 0002 ECG_MODE      EQU     00000010B          ; CMD MODIFIER (02H)
= 0006 BUFFER_MODE   EQU     00000100B          ; CMD MODIFIER (08H)

```

```

= 00A0 INT_CTL_PORT EQU     0AOH          ; 8259 CONTROL PORT #2
= 0020 INT_CTL_PORT EQU     020H          ; 8259 CONTROL PORT #1
= 0020 EOI          EQU     20H          ; END OF INTERRUPT COMMAND

```

```

= 0002 MAX_FILE     EQU     2
= 0002 S_MAX_FILE   EQU     2

```

```

= 0020 DELAY_1       EQU     20H          ; DELAY FOR OP COMPLETE
= 0600 DELAY_2       EQU     0600H         ; DELAY FOR READY
= 0100 DELAY_3       EQU     0100H         ; DELAY FOR DATA REQUEST

```

```

= 0008 HF_FAIL      EQU     08H          ; CMOS FLAG IN BYTE 0EH
EXTRN P_MSG:NEAR

```

ASSUME CS:CODE

PAGE

;-----; FIXED DISK I/O SETUP

;-----;

```

; - ESTABLISH TRANSFER VECTORS FOR THE FIXED DISK
; - PERFORM POWER ON DIAGNOSTICS
; SHOULD AN ERROR OCCUR A "1701" MESSAGE IS DISPLAYED
;-----DISK_SETUP-----PROC NEAR-----ASSUME ES:ABSO-----SUB AX,AX-----MOV ES,AX-----CLI-----MOV AX,WORD PTR ORG_VECTOR-----MOV WORD PTR DISK_VECTOR,AX-----MOV AX,WORD PTR ORG_VECTOR+2-----MOV WORD PTR DISK_VECTOR+2,AX-----MOV WORD PTR ORG_VECTOR,OFFSET DISK_IO-----MOV WORD PTR ORG_VECTOR+2,CS-----MOV WORD PTR DISK_VEC+2,CS-----MOV WORD PTR HDISK_INT_AX-----MOV WORD PTR HDISK_INT+2,CS-----MOV WORD PTR HF_TBL_VEC,OFFSET FD_TBL-----MOV WORD PTR HF_TBL_VEC+2,CS-----MOV WORD PTR HF_TBL_VEC,OFFSET FD_TBL-----MOV WORD PTR HF_TBL_VEC+2,CS-----MOV WORD PTR HF_TBL_VEC+2,CS-----STI-----IN AL,INT_CTL_PORT+1 ; ** IO DELAY NOT REQUIRED **-----AND AL,0BFH-----OUT INT_CTL_PORT+1,AL-----IN AL,INT_CTL_PORT+1-----AND AL,0BFH-----OUT INT_CTL_PORT+1,AL-----ASSUME DS:DATA-----MOV AX,DATA ; ESTABLISH SEGMENT-----MOV DS,AX-----MOV DI,STATUS1,0 ; RESET THE STATUS INDICATOR-----MOV HF_NUM,0 ; ZERO NUMBER OF HARD FILES-----MOV CONTROL_BYTE,0-----MOV AL,8EH-----OUT 70H,AL ; CHECK CMOS VALIDITY-----JMP SHORT $+2-----IN AL,71H-----MOV AH,AL ; SAVE CMOS FLAG-----MOV AH,RCF_HF_FAIL-----AND AL,0-----OUT 70H,AL-----MOV AL,AH-----JMP SHORT $+2-----IN AL,71H-----MOV AH,AL ; CMOS NOT VALID -- NO HARD FILES-----AND AL,0-----OUT 70H,AL ; ALLOW HARD FILE IPL-----MOV AH,92H-----OUT 71H,AL ; WRITE IT BACK-----MOV HF_NUM,1 ; ACCESS HARD FILE BYTE IN CMOS-----JMP SHORT $+2-----IN AL,71H-----MOV PORT_OFFSET,0 ; ZERO CARD OFFSET-----BL,AL-----MOV AH,0 ; SAVE HARD FILE BYTE-----AND AL,0-----OUT 70H,AL-----MOV AL,0 ; GET FIRST DRIVE TYPE-----AND AL,0FOH-----JZ POD_DONE ; NO HARD FILES-----ADD AX,OFFSET FD_TBL-160 ; COMPUTE OFFSET-----MOV WORD PTR HF_TBL_VEC,AX-----MOV HF_NUM,1 ; AT LEAST ONE DRIVE-----MOV AL,BL-----ISHL AL,4 ; GET SECOND DRIVE TYPE-----+ ????0000 LABEL BYTE-----+ ????0001 SHL AL,1-----+ ????0002 LABL BYTE-----+ ????0003 LDH AL,1-----+ ????0004 ORG OFFSET CS:????0000-----+ ????0005 DB OC0H-----+ ????0006 ORG OFFSET CS:????0001-----+ ????0007 DB 4-----+ ????0008 SHORT L4 ; ONLY ONE DRIVE-----+ ????0009 JZ POD_DONE-----MOV AH,0-----ADD AX,OFFSET FD_TBL-160 ; COMPUTE OFFSET FOR DRIVE 1-----MOV WORD PTR HF_TBL_VEC,AX-----MOV HF_NUM,2 ; TWO DRIVES-----MOV DL,80H-----MOV AH,1AH ; CHECK THE CONTROLLER-----INT 13H-----JC CTL_ERRX-----MOV AX,TIMER_LOW ; GET START TIMER COUNTS-----MOV BX,AX-----ADD AX,TIMER_182 ; 60 SECONDS * 18.2-----MOV CX,AX-----CALL HD_RESET_1 ; SET UP DRIVE 0-----CMP HF_NUM,1 ; WERE THERE TWO DRIVES?-----JE BL,POD_DONE ; NO-ALL DONE-----MOV DL,81H-----CALL HD_RESET_1 ; SET UP DRIVE 1-----POD_DONE:-----CL I ; ** IO DELAY NOT REQUIRED **-----IN AL,021H ; BE SURE TIMER IS ENABLED-----AND AL,0FEH-----OUT 021H,AL-----RET-----;---- POD_ERROR -----CTL_ERRX:-----MOV SI,OFFSET F1782-----CALL SET_FAIL ; CONTROLLER_ERROR-----CALL P_MSG ; DONT IPL FROM DISK-----MOV BP,0FH ; DISPLAY ERROR-----JMP SHORT POD_DONE ; POD ERROR FLAG-----OOEF-----PROC NEAR-----PUSH BX-----PUSH CX-----MOV AH,09H ; SAVE TIMER LIMITS-----INT 13H-----JC RES_2 ; SET DRIVE PARMS-----RES_1:-----MOV AH,09H-----INT 13H-----JC RES_2 ; RECALIBRATE DRIVE-----RES_2:-----MOV AH,11H-----INT 13H-----JC RES_1 ; DRIVE OK-----RES_1:-----MOV AH,09H-----INT 13H-----JC RES_2 ; CHECK TIME OUT-----RES_FL:-----MOV SI,OFFSET F1781 ; INDICATE DISK 1 FAILURE-----TEST DL-----JZ RES_E1-----MOV SI,OFFSET F1780 ; INDICATE DISK 0 FAILURE-----SET FAIL-----CALL SET_FAIL ; DONT TRY TO IPL DISK 0-----JMP SHORT RES_E1-----RES_E1:-----MOV AH,08H ; GET MAX CYL,HEAD,SECTOR-----RES_CK:-----
```

```

0114 8A DA
0116 CD 13
0118 72 33
011A 74 03
011C B8 0401
011F CD 13
0121 73 3B
0123 80 FC 0A
0126 74 36
0128 80 FC 11
0129 74 31
012D 80 FC 10
0130 74 2C
0132 E8 0178 R
0135 72 00
013A A0 0044 R
013A FE C8
013C 74 D4
013E 8A 2E 0045 R
0142 8A 0E 0046 R

0146
0146 DD E1
0148 +
0146 ??0003 LABEL
0148 SHL CL,1
0148 ??0004 LABEL
0146 ORG BYTE
0146 + OFFSET CS:??0003
0146 CO DEC 0COH
0146 + ORG OFFSET CS:??0004
0148 +
0148 06 DB 6
0149 04 C8 OR CL,AL
014B EB CF JMP RES_3
014D BE 0000 E RES_ER: MOV SI,OFFSET F1791
0150 70 02 01 JNZ RES_E1
0153 75 03 UNZ RES_E1
0155 BE 0000 E MOV SI,OFFSET F1790
0158 E8 0000 E P MSG
015B BD 000F MOV BP,OFH
015E 59 RES_E1: CALL CX
015F 58 RES_OK: POP BX
0160 C3 RET BX
0161 HD_RESET_1 ENDP

0161 SET_FAIL PROC NEAR
0163 B8 8E MOV AL,8EH
0163 E6 70 OUT 70H,AL
0165 EB 00 JMP SHORT $+2
0167 E4 71 IN AL,71H
0169 OC 08 OR AL,HF FAIL
016B 8A E0 MOV AH,AH
016C 80 E5 MOV AL,8EH
016F E6 70 OUT 70H,AL
0171 8A C4 MOV AL,AH
0173 EB 00 JMP SHORT $+2
0175 E6 71 OUT 71H,AL
0177 C3 RET ; PUT IT OUT
0178 SET_FAIL ENDP

0178 POD_TCHK PROC NEAR
0179 58 POP AX
0179 59 POP CX
0179 5B POP BX
0179 53 PUSH BX
017C 51 PUSH CX
017D 50 PUSH AX
017E A1 006C R MOV AX,TIMER_LOW
0181 3B D9 CMP BX,CX
0183 72 06 JB TCHK1
0185 3B D8 CMP BX,AX
0187 72 0C JB TCHK2
0189 EB 04 JMP SHORT TCHK2
0190 30 23 TCHK1: CMP AX,CX
018D 72 04 JB TCHKNG
018F 3B C1 TCHK2: CMP AX,CX
0191 72 02 JB TCHK
0193 F9 TCHKNG: STC
0194 C3 RET
0195 F8 TCHKG: CLC
0196 C3 RET
0197 POD_TCHK ENDP

0197 DISK_SETUP PAGE
DISK BIOS ENTRY POINT
DISK_IO PROC FAR
ASSUME DS:NOTHING,ES:NOTHING
0197 80 FA 80 CMP DL,80H ; TEST FOR FIXED DISK DRIVE
019A 73 05 JAE HARD_DISK ; YES, HANDLE HERE
019C CD 40 INT 40H ; DISKETTE HANDLER
019E CA 0002 RET_2: RET 2 ; BACK TO CALLER
01A1 HARD_DISK: ASSUME DS:DATA
01A1 S1 INT 1 ; ENABLE INTERRUPTS
01A2 04 E4 OR AH,AH
01A4 75 09 JNZ A2
01A6 CD 40 INT 40H ; RESET NEC WHEN AH=0
01A8 2A E4 SUB AH,AH
01AA 80 FA 81 CMP DL,(80H + S_MAX_FILE - 1)
01AD 77 EF JA RET_2
A2: CMP AH,08H ; GET PARAMETERS IS A SPECIAL CASE
01B2 75 03 JNZ A3
01B4 E9 038B R JMP GET_PARM_N
01B7 80 FC 15 A3: CMP AH,15H ; READ DASD TYPE IS ALSO
01B9 75 03 JNZ A4
01BC E9 0349 R JMP READ_DASD_TYPE
A4: PUSH BX ; SAVE REGISTERS DURING OPERATION
01BF 53 PUSH CX
01C0 51 PUSH DX
01C1 52 PUSH DS
01C2 1E PUSH ES
01C3 06 PUSH SI
01C4 56 PUSH DI
01C5 57 PUSH D1
01C6 04 E4 OR AH,AH ; CHECK FOR RESET
01C9 75 02 JNZ A5
01CA B2 80 MOV DL,80H ; FORCE DRIVE 80 FOR RESET
01CC E8 0212 R A5: CALL DISK_IO_CONT ; PERFORM THE OPERATION
01CF 50 PUSH AX
01D0 B8 ---- R MOV AX,DATA
01D3 8E D8 MOV DS,AX ; ESTABLISH SEGMENT

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01D5 58          POP    AX      ; GET STATUS FROM OPERATION
01D6 8A 26 0074 R MOV    AH, DISK_STATUS1 ; SET THE CARRY FLAG TO INDICATE
01EA FC 01        CMP    AH, 1   ; SUCCESS OR FAILURE
01DD F5          POP    DI     ; RESTORE REGISTERS
01DE 5F          POP    SI     ; THROW AWAY SAVED FLAGS
01E0 5E          POP    ES
01E1 F           POP    DS
01E2 5A          POP    DX
01E3 59          POP    CX
01E4 5B          POP    BX
01E5 CA 0002      RET    2
01E6 DISK_IO ENDP ; THROW AWAY SAVED FLAGS

01E8 02B3 R      M1    LABEL WORD   ; FUNCTION TRANSFER TABLE
01EA 0307 R      DW    DISK_RESET ; 000H
01EC 0310 R      DW    RETURN_STATUS ; 001H
01EE 0312 R      DW    DISK_READ ; 002H
01F0 0320 R      DW    DISK_WRITE ; 003H
01F2 0333 R      DW    DISK_VERIFY ; 004H
01F4 02AB R      DW    FMT_TRK ; 005H
01F6 02AB R      DW    BAD_COMMAND ; 006H FORMAT BAD SECTORS
01F8 02AB R      DW    BAD_COMMAND ; 007H FORMAT DRIVE
01FA 02AB R      DW    BAD_COMMAND ; 008H RETURN PARMS
01FC 041F R      DW    BAD_COMMAND ; 009H
01FE 0427 R      DW    RD_LONG ; 00AH
0200 042F R      DW    WR_LONG ; 00BH
0202 02B3 R      DW    DISK_SEEK ; 00CH
0204 02AB R      DW    DISK_RESET ; 00DH
0206 02AB R      DW    BAD_COMMAND ; 00EH
0208 044E R      DW    BAD_COMMAND ; 00FH READ BUFFER
020A 0465 R      DW    TST_ROD ; 010H WRITE BUFFER
020C 02AB R      DW    HDISK_RECAL ; 011H
020E 02AB R      DW    BAD_COMMAND ; 012H RAM DIAGNOSTIC
0210 0489 R      DW    BAD_COMMAND ; 013H DRIVE DIAGNOSTIC
0212 == 002A      DW    CTLR_DIAGNOSTIC ; 014H CONTROLLER DIAGNOSTIC
0213 50          M1L   EQU    $-M1

DISK_IO_CONT PROC NEAR
0214 80 44 00    PUSH  AX
0215 00          MOV    AX, DATA ; ESTABLISH SEGMENT
0216 00 0E D8    MOV    AX, 00H
0218 58          POP    AX
0219 80 FC 01    CMP    AH, 01H ; RETURN STATUS
021C 75 03        JNZ    SU0
021E E9 0307 R   JMP    RETURN_STATUS

SU0:             SU0:             PROC NEAR
0221 C6 06 0074 R 00 MOV    DISK_STATUS1, 0 ; RESET THE STATUS INDICATOR
0226 53          PUSH  BX
0227 8A 1E 0075 R MOV    BL, HF_NUM ; SAVE DATA ADDRESS
0228 50          PUSH  AX
0229 80 E2 7F    AND    DL, 7FH ; GET NUMBER OF DRIVES
0230 00 0A DA    CMP    AH, DL
0231 76 76        JBE    BAD_COMMAND_POP ; INVALID DRIVE
0233 06          PUSH  ES
0234 E8 06B4 R   CALL   GET_VEC ; GET DISK PARMS
0237 26: 8B 47 05 MOV    AX, WORD PTR ES:[BX][5] ; GET WRITE PRE-COMP CYL

0238 D1 E8        + ??0006 LABEL BYTE
023D 00          SHR    AX, 1
023E A2 0042 R   + ??0007 LABEL BYTE
0241 26: 8A 47 08 ORG    OFFSET CS:??0006
0245 00          + ??0008 LABEL NEAR
0246 DA 03F6    ORG    OH
0249 EE          + ??0008 LABEL NEAR
024A 5A          DB    2
024B 07          MOV    CMD_BLOCK, AL ; SET EXTRA HEAD OPTION IN
024C 8A 26 0076 R AND   AH, 000H ; CONTROL BYTE
0250 00 00 E0 C0 OR    AH, AL ; CONTROL BYTE
0253 0A E0        MOV    CONTROL_BYT, AH
0255 8A 26 0076 R POP    AX
0259 58          MOV    CMD_BLOCK+1, AL ; SET EXTRA HEAD OPTION IN
025A A2 0043 R   POP    DX
025D 00          PUSH  AX
025E 8A C1        MOV    AL, CL ; SECTOR COUNT
0260 24 3F        AND   AL, 3FH ; GET SECTOR NUMBER
0262 A2 0044 R   MOV    CMD_BLOCK+2, AL
0265 8A 2E 0045 R MOV    CMD_BLOCK+3, CH
0269 8A C1        POP    DX ; GET CYLINDER NUMBER
026B 00          I SHR   AL, 0
026B D0 E8        + ??0009 LABEL BYTE
026D 00          SHR    AL, 1
026B 00          + ??000A LABEL BYTE
026B CO          ORG    OFFSET CS:??0009
026D 00          DB    0
026D 00          + ??000A LABEL BYTE
026D 06          ORG    OFFSET CS:??000A
026E A2 0046 R   DB    6
0271 8A C2        MOV    CMD_BLOCK+4, AL ; CYLINDER HIGH ORDER 2 BITS
0271 00          MOV    AL, DL ; DRIVE NUMBER
0273 D0 E0        + ??000C LABEL BYTE
0275 00          SHR    AL, 1
0273 CO          + ??000D LABEL BYTE
0275 00          ORG    OFFSET CS:??000C
0273 00          OCOH
0275 04          + ??000D LABEL BYTE
0276 80 E6 0F    ORG    OFFSET CS:??000D
0279 0A C6        DB    4
0278 0C A0        AND   DH, OFH ; HEAD NUMBER
027D A2 0047 R   OR    AL, DH
0280 00          OR    AL, 80H OR 20H ; ECC AND 512 BYTE SECTORS
0281 50          POP    AX
0282 8A C4        SAL    AX, AX ; ECC/SIZE/DRIVE/HEAD
0284 32 E4        XOR    AH, AH
0286 D1 E0        SAL    AX, AX ; TEST WITHIN RANGE
0288 00          MOV    AX, AX ; #2 FOR TABLE LOOKUP
028A 0D 002A     POP    AX ; PUT INTO SI FOR BRANCH
028D 73 5A        CMP    AX, M1L ; TEST WITHIN RANGE
028F 58          JNB    BAD_COMMAND_POP ; RESTORE AX
0290 58          POP    AX ; AND DATA ADDRESS
0291 51          PUSH  CX
0292 50          PUSH  AX ; ADJUST ES:BX
0293 8B C8        MOV    CX, BX ; GET 3 HIGH ORDER NYBBLES OF BX
0295 D1 E9        + ??000F LABEL BYTE
0297 00          SHR    CX, 4
0295 00          + ??0010 LABEL BYTE
0295 00          ORG    OFFSET CS:??000F
0295 00          + ??0011 LABEL NEAR

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0295 C1          +     DB    0C1H
0297 04          +     ORG   OFFSET CS:??0010
0297 0C C0        +     DB    A
029A 03 C1        MOV   AL,ES
029C 8E C0        ADD   AX,CX
029E 81 E3 000F   MOV   ES,AX
02A2 58          AND   BX,000FH ; ES:BX CHANGED TO ES:000X
02A4 59          POP   AX
02A4 2E FF A4 01E8 R JMP   WORD PTR CS:[SI + OFFSET M1]
02A9 58          POP   AX
02AA 5B          POP   BX
02AB             BAD_COMMAND:
02A9 66 06 0074 R 01  MOV   AL,DISK_STATUS1,BAD_CMD ; COMMAND ERROR
02B0 80 00
02B2 C3          RET
02B3             DISK_IO_CONT ENDP

;-----: RESET THE DISK SYSTEM (AH = 000H) :-----:
02B3             DISK_RESET PROC NEAR
02B3 FA          CLD
02B3 24 A1        IN    AL,INT_CTL+PORT+1 ; ** IO DELAY NOT REQUIRED **
02B6 24 BF        AND   AL,0BFH ; GET THE MASK REG
02B8 E6 A1        OUT   INT_CTL+PORT+1,AL ; ENABLE HARD FILE INT.
02B8 FB          STI
02B8 B0 04        MOV   AL,04H ; START INTERRUPTS
02B8 BA 03F6      MOV   DX,HF_REG_PORT
02C0 50          OUT   DX,AL ; RESET
02C1 B9 000A      MOV   CX,10 ; DELAY COUNT
02C4 49          DEC   CX
02C5 75 FD        JNZ   DRD ; WAIT 4.8 MICRO-SEC
02C7 A0 0076 R    IN    AL,INT_CTL+PORT+1
02C8 20 0F        AND   AL,0FH ; GET THE MASK REG
02C8 EE          OUT   INT_CTL+PORT+1,AL ; ENABLE HARD FILE INT.
02C9 E8 05DF R    CALL  NOT_BUSY ; SET HEAD OPTION
02D0 75 2F        JNZ   DRERR ; TURN RESET OFF
02D2 BA 01F1      MOV   DX,HF_PORT+1 ; TIME OUT ON RESET
02D5 EC          IN    AL,DX ; GET RESET STATUS
02D6 30 01        CMP   AL,01H
02D8 75 27        JNZ   DRERR ; BAD RESET STATUS
02DA B0 26 0047 R EF  AND   CMD_BLOCK+5,0E8H ; SET TO DRIVE 0
02DF 2A D2        SUB   DL,DL
02E1 E8 03E4 R    CALL  INIT_DRV ; SET MAX HEADS
02E1 E8 0465 R    CALL  HDISK_RECAL ; RECAL TO RESET SEEK SPEED
02E2 60 31 0075 R 01  CMP   AL,NUM_1 ; CHECK FOR DRIVE 1
02E2 76 0D        JBE   DRD ; IGNORE ANY SET UP ERRORS
02E2 80 0E 0047 R 10 OR    CMD_BLOCK+5,010H ; SET TO DRIVE 1
02F3 B2 01        MOV   DL,1
02F5 E8 03E4 R    CALL  INIT_DRV ; SET MAX HEADS
02F5 E8 0465 R    CALL  HDISK_RECAL ; RECAL TO RESET SEEK SPEED
02FB C6 06 0074 R 00  DRE:  MOV   DISK_STATUS1,0 ; IGNORE ANY SET UP ERRORS
0300 C3          RET
0301 C6 06 0074 R 05  DRERR: MOV   DISK_STATUS1,BAD_RESET ; CARD FAILED
0306 C3          RET
0307             DISK_RESET ENDP

;-----: DISK STATUS ROUTINE (AH = 001H) :-----:
0307             RETURN_STATUS PROC NEAR
0307 A0 0074 R    MOV   AL,DISK_STATUS1 ; OBTAIN PREVIOUS STATUS
030A C6 06 0074 R 00  MOV   DISK_STATUS1,0 ; RESET STATUS
0307 C3          RET
0307             RETURN_STATUS ENDP

;-----: DISK READ ROUTINE (AH = 002H) :-----:
0310             DISK_READ PROC NEAR
0310 C6 06 0048 R 20  MOV   CMD_BLOCK+6,READ_CMD
0315 E9 04BB R    JMP   COMMAND1
0318             DISK_READ ENDP

;-----: DISK WRITE ROUTINE (AH = 003H) :-----:
0318             DISK_WRITE PROC NEAR
0318 C6 06 0048 R 30  MOV   CMD_BLOCK+6,WRITE_CMD
031D E9 04FB R    JMP   COMMAND1
0320             DISK_WRITE ENDP

;-----: DISK VERIFY (AH = 004H) :-----:
0320             DISK_VERIFY PROC NEAR
0320 C6 06 0048 R 40  MOV   CMD_BLOCK+6,VERIFY_CMD
0325 05 04 R        CALL  COMMAND
0328 75 08          JNZ   VERF_EXIT ; CONTROLLER STILL BUSY
032A E8 05A5 R    CALL  WAIT
032D 75 03          JNZ   VERF_EXIT ; TIME OUT
032F E8 061E R    CALL  CHECK_STATUS
0332 C3          VERF_EXIT:
0333 C3          RET
0333             DISK_VERIFY ENDP

;-----: FORMATTING (AH = 005H) :-----:
0333             FMT_TRK PROC NEAR
0333 C6 06 0048 R 50  MOV   CMD_BLOCK+6,FMTTRK_CMD ; FORMAT TRACK (AH = 005H)
0338 06          PUSH  ES
0338 03          PUSH  DS
033A E8 06B4 R    CALL  GET_VEC ; GET DISK PARMS ADDRESS
033D 26: BA 47 0E  MOV   AL,ES:[BX][14] ; GET SECTORS/TRACK
0341 A2 0043 R    MOV   CMD_BLOCK+1,AL ; SET SECTOR COUNT IN COMMAND
0344 5B          POP   BX
0345 07          POP   ES
0346 E9 0500 R    JMP   CMD_OF ; GO EXECUTE THE COMMAND
0349             FMT_TRK ENDP PAGE

;-----: READ DASD TYPE (AH = 15H) :-----:
0349             READ_DASD_TYPE PROC NEAR
0349 READ_D_T        PUSH  DS ; GET DRIVE PARAMETERS
0349 1E          FAR ; SAVE REGISTERS

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034A 06
034B 53
034C B8 ---- R
034F 8E DB
0351 C6 06 0074 R 00
0356 8A 1E 0075 R
035A 80 E2 7F
035D 3A DA
035F 76 22
0360 E1 0074 R
0364 26: 8A 97 02
0368 26: 8A 4F 0E
036C F6 E9
036E 26: 88 0F
0371 49
0372 F7 E9
0374 88 CA
0376 88 D0
0378 28 C0
037A B4 03
037D 20
037D 07
037E 1F
037F F8
0380 CA 0002
0383 88 C0
0385 88 C8
0387 88 D0
0389 EB F1
038B 03
038B 26: 88 0F
038B 1E
038C 06
038D 53
038E 26: 80
0390 8E D8
0392 F6 C2 01
0395 74 06
0397 C4 1E 0118 R
0398 EB 04
039D C4 1E 0104 R
03A1 B8 ---- R
03A4 8E D8
03A6 80 EA 80
03A9 80 00 02
03AC 73 2C
03AE C6 06 0074 R 00
03B3 26: 8B 07
03B6 2D 0002
03B9 8A 00
03B9 26: 0300
03BE D1 E8
03C0 D1 E8
03C2 26: 0A 47 0E
03C6 8A C8
03C9 F8 00
03CE 8A 16 0075 R
03D2 28 C0
03D4
03D4 5B
03D7 07
03D6 1F
03D7 CA 0002
03DA
03DA C6 06 0074 R 07
03D9 80 00 00
03E1 2A C0
03E3 2B 02
03E5 2B C9
03E7 F9
03E8 EB EA
03EA
03EA C6 06 0048 R 91
03EF E8 0684 R
03F2 26: 8A 47 02
03F6 FE C8
03F8 8A 26 0047 R
03F9 80 00 00
03FF 04 E0
0401 88 26 0047 R
0405 26: 8A 47 0E
0409 A2 0043 R
040B 80 00 00
040E A2 0005 R
0411 EB 0544 R
0414 75 08
0416 E8 05DF R
0419 75 03
041B E8 061E R
041E C3
041F C3
041F
041F C6 06 0048 R 22
0424 E9 04BB R
0427
0427 C6 06 0048 R 32
042C E9 04FB R
042F

PUSH    ES
PUSH    BX
MOV     AX, DATA
MOV     DS, AX
ASSUME DS:DATA
MOV     DISK_STATUS1, 0
MOV     BL, HF_NUM
AND    DL, 7FH
CMP     BL, DL
JBE     RDT_NOT_PRESENT
CALL    GET_SECT
MOV     AL, ES:[BX][2]
MOV     CL, ES:[BX][14]
IMUL   CL, ES:[BX]
MOV     AX, CX
DEC    CX
INCL   CX
MOV     CX, DX
MOV     DX, AX
SUB    AX, AX
MOV     AH, 03H
POP    BX
POP    DS
RET    2
RDT2:  POP    DS
POP    ES
CLC
RET    2
RDT_NOT_PRESENT:
MOV    AX, AX
MOV    CX, AX
MOV    DX, AX
JMP   RDT2
READ_D_T PAGE
;-----[ GET PARAMETERS (AH = 8) ]-----:
;-----[-----]
GET_PARM_N LABEL NEAR
GET_PARM PROC FAR
PUSH DS
PUSH ES
PUSH BX
ASSUME DS:ABSO
SUB   AX, AX
MOV   DS, AX
TEST  DL, 1
JZ    GO
LES   BX, HF1_TBL_VEC
JMP   SH01_G1
LES   BX, HF1_TBL_VEC
ASSUME DS:DATA
MOV   AX, DATA
MOV   DS, AX
SUB   DL, B0H
CMP   DL, MAX_FILE
JAE   GH
MOV   DISK_STATUS1, 0
MOV   AX, ES:[BX]
MOV   AX, 2
SUB   DL, 1
JZ    GH
AND   AX, 0300H
SHR   AX, 1
SHR   AX, 1
OR    AL, ES:[BX][14]
MOV   CL, AL
MOV   DH, ES:[BX][2]
DEC   DH
MOV   DL, HF_NUM
SUB   AX, AX
G5:   POP    BX
POP    DS
RET    2
G1:   POP    DS
RET    2
G0:   LES   BX, HF1_TBL_VEC
ASSUME DS:DATA
MOV   AX, DATA
MOV   DS, AX
SUB   DL, B0H
CMP   DL, MAX_FILE
JAE   GH
MOV   DISK_STATUS1, 0
MOV   AX, ES:[BX]
MOV   AX, 2
SUB   DL, 1
JZ    GH
AND   AX, 0300H
SHR   AX, 1
SHR   AX, 1
OR    AL, ES:[BX][14]
MOV   CL, AL
MOV   DH, ES:[BX][2]
DEC   DH
MOV   DL, HF_NUM
SUB   AX, AX
G5:   POP    BX
POP    DS
RET    2
G4:   MOV   DISK_STATUS1, INIT_FAIL
MOV   AH, INIT_FAIL
SUB   AL, AL
SUB   DX, DX
SUB   CX, CX
STC
JMP   G5
GET_PARM PAGE
;-----[ INITIALIZE DRIVE ]-----:
INIT_DRV PROC NEAR
MOV   CMD_BLOCK+6, SET_PARM_CMD
CALL  GET_VEC
MOV   AL, ES:[BX][2]
MOV   AL, ES:[BX][14]
DEC   AL
MOV   AH, CMD_BLOCK+5
AND   AH, 0OH
OR    AH, AL
MOV   CMD_BLOCK+5, AH
MOV   AL, ES:[BX][14]
MOV   CMD_BLOCK+1, AL
SUB   AX, AX
MOV   CMD_BLOCK+3, AL
CALL  COMMAND
JNZ   INIT_EXIT
CALL  NOT_BUSY
JNZ   INIT_EXIT
CALL  CHECK_STATUS
INIT_EXIT:
RET
INIT_DRV ENDP
;-----[ READ LONG (AH = 0AH) ]-----:
RD_LONG PROC NEAR
MOV   CH0_BLOCK+6, READ_CMD OR ECC_MODE
JMP   COMMAND0
RD_LONG ENDP
;-----[ WRITE LONG (AH = 0BH) ]-----:
WR_LONG PROC NEAR
MOV   CH0_BLOCK+6, WRITE_CMD OR ECC_MODE
JMP   COMMAND0
WR_LONG ENDP
;
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;-----[SEEK (AH = 0CH)]-----:
042F  C6 06 0048 R 70
0430  E8 0544 R
0437  75 11
0439  E8 05A5 R
043C  75 0F
043E  E8 061E R
0440  B0 3E 0074 R 40
0446  C3
0448  C6 06 0074 R 00
044D  C3
044E  C3
044F  C3
0450  DS_EXIT:
0451  RET
0452  DISK_SEEK ENDP

;-----[TEST DISK READY (AH = 010H)]-----:
044E  E8 05BF R
0451  75 11
0453  A0 0047 R
0456  BA 01F6
0459  EE
045A  E8 0630 R
045B  75 05
045C  C6 06 0074 R 00
045D  C3
045E  TST_RDY ENDP

;-----[RECALIBRATE (AH = 011H)]-----:
0465  C6 06 0048 R 10
0466  E8 0544 R
046D  75 14
046F  E8 05A5 R
0472  75 0F
0474  E8 061E R
0475  B0 3E 0074 R 40
047C  75 05
047E  C6 06 0074 R 00
0483  C3
0488  C3
0489  RECAL_EXIT:
0490  CMP
0491  RET
0492  HDISK_REGAL ENDP

;-----[CONTROLLER DIAGNOSTIC (AH = 14H)]-----:
0489  E4 A1
048B  24 BF
048D  E6 A1
048F  E4 21
0491  24 B
0493  E6 21
0495  E8 05DF R
0498  75 1A
049A  BA 01F7
049D  B0 90
04A0  E8 05DF R
04A3  B4 80
04A5  75 0F
04A7  BA 01F1
04AA  E8 008D R
04AE  B4 00
04B0  3C 01
04B2  74 02
04B4  B4 20
04B6  88 26 0074 R
04B8  C3
04BB  C3
04BC  C3
04BD  E8 068F R
04BE  72 3A
04C0  BB FB
04C2  E8 0544 R
04C5  75 33
04C7  E8 05A5 R
04CA  75 2E
04CC  B9 0100
04CF  BA 01F0
04D2  FC
04D3  F3 6D
04D5  F6 06 0048 R 02
04DA  74 12
04DC  E8 0608 R
04DF  72 12
04E0  B4 01F0
04E4  B9 0004
04E7  EC
04E8  26: 88 05
04EB  E2 F9
04EC  E8 061E R
04F1  75 07
04F3  F6 06 008C R 80
04FB  75 CD
04FA  CMD_ABORT:
04FB  TM_OUT:
04FC  RET
04FD  DISK_SEEK ENDP

;-----[COMMAND]-----:
;-----[REPEATEDLY INPUTS DATA TIL NSECTOR
;      RETURNS ZERO]-----:
04BB  COMMAND:
04BC  CALL  CHECK_DMA ; CHECK 64K BOUNDARY ERROR
04BD  JC   CMD_ABORT
04C0  MOV  D1_BX
04C2  CALL  COMMAND ; OUTPUT COMMAND
04C5  JNZ  CMD_ABORT
04C7  CMD_I11:
04CA  CALL  WAIT ; WAIT FOR DATA REQUEST INT
04CB  JNZ  TM_OUT ; TIME OUT
04CC  MOV  CX_256D ; SECTOR SIZE IN WORDS
04CD  MOV  DX, HF_PORT
04CE  CLD
04CF  REP_INSW ; GET THE SECTOR
04D0  +    TEST  CMD_BLOCK+6,ECC_MODE ; CHECK FOR NORMAL INPUT
04D1  JZ   CMD_I3
04D2  CALL  WAIT_DRQ ; WAIT FOR DATA REQUEST
04D3  JC   TM_OUT
04D4  MOV  DX,HF_PORT
04D5  MOV  CX_4 ; GET ECC BYTES
04D6  AL,DX
04D7  MOV  ES:BYTE PTR [DI],AL ; GO SLOW FOR BOARD
04D8  LOOP  CMD_I2
04D9  CALL  CHECK_STATUS
04DA  JNZ  CMD_ABORT ; ERROR RETURNED
04DB  TEST  HF_STATUS, ST_BUSY ; CHECK FOR MORE
04DC  JNZ  SHORT_CMD_I1
04DD  CMD_ABORT:
04DE  TM_OUT:
04DF  RET
04E0  DISK_SEEK ENDP

;-----[COMMAND]-----:
;-----[REPEATEDLY OUTPUTS DATA TIL NSECTOR
;      RETURNS ZERO]-----:

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04FB CALL CHECK_DMA ; CHECK 64K BOUNDARY ERROR
04FE JC CMD_ABORT
0500 MOV SI,BX
0502 CALL COMMAND ; OUTPUT COMMAND
0505 JNZ CMD_ABORT
0507 JC WAIT_DRQ ; WAIT FOR DATA REQUEST
0509 JC TM_OUT ; TOO LONG
050C PUSH DS
050D PUSH ES
050E POP DS
050F MOV CX,256D
0512 MOV DX,HF_PORT ; PUT THE DATA OUT TO THE CARD
0515 CLD
0516 REP_OUTSW

+ DB 0F3H,06FH
POP DS
TEST CMD_BLOCK+6,ECC_MODE ; CHECK FOR NORMAL OUTPUT
JZ DCD_03
CALL WAIT_DRQ ; WAIT FOR DATA REQUEST
JC TM_OUT
MOV DX,HF_PORT
MOV CX,4
MOV AL,ES:BYTE PTR [SI] ; OUTPUT THE ECC BYTES
CMD_O2: OUT DX,AL
INC SI
LOOP CMD_O2

CMD_O3: CALL WAIT ; WAIT FOR SECTOR COMPLETE INT
JNZ PRTUT ; ERROR RETURNED
CALL CHECK_STATUS
JNZ CMD_ABORT ; CHECK FOR MORE
TEST HF_STATUS,ST_DRQ
JNZ SHORT CMD_O1
RET

;-----+
; COMMAND
; THIS ROUTINE OUTPUTS THE COMMAND BLOCK
; -----
; OUTPUT
; BL = STATUS
; BH = ERROR REGISTER
; -----+



COMMAND PROC NEAR
PUSH BX
MOV CX,DELAY_2 ; WAIT FOR SEEK COMPLETE AND READY
COMMAND1: ; SET INITIAL DELAY BEFORE TEST
PUSH CX
CALL TST_RDY ; SAVE LOOP COUNT
POP CX
JZ COMMAND2 ; CHECK DRIVE READY
CMP DX,0
LOOP COMMAND1 ; DRIVE IS READY
TST_RDY TIMED OUT--GIVE UP
COMMAND2: ; KEEP TRYING FOR A WHILE
JMP SHORT COMMAND4 ; ITS NOT GOING TO GET READY
COMMAND3: ; NO--GO TO GET READY
POP BX
PUSH DI
MOV HF_INT_FLAG,0 ; ** IO DELAY NOT REQUIRED ***
IN AL,INT_CTRL_PORT+1 ; RESET INTERRUPT FLAG
AND AL,0FFH ; TURN ON SECOND INTERRUPT CHIP
OUT INT_CTRL_PORT+1,AL
IN AL,INT_CTRL_PORT+1,AL ; LET INTERRUPTS PASS THRU TO
AND AL,0FBH ; SECOND CHIP
OUT INT_CTRL_PORT+1,AL
MOV DI,OFFSET CMD_BLOCK ; INDEX THE COMMAND TABLE
MOV DX,0 ; DISK ADDRESS
TEST CONTROL_BYTC,OCH ; CHECK FOR RETRY SUPPRESSION
JZ COMMAND3
MOV AL,CMD_BLOCK+6 ; YES-GET OP CODE
AND AL,0FOH ; GET RID OF MODIFIERS
CMP DX,20H ; 20H-40H IS READ, WRITE, VERIFY
JNB COMMAND3 ; JA COMMAND3
AL,40H
OR CMD_BLOCK+6,no_retries ; VALID OP FOR RETRY SUPPRESS
COMMAND4: ; NO--GO DO NEXT ONE
MOV AL,[DI] ; GET THE COMMAND STRING
OUT DX,AL ; GIVE IT TO CONTROLLER
INC DI ; NEXT BYTE
INC DX ; NEXT DISK REGISTER
CMP DX,HF_PORT+8 ; ALL DONE?
JNZ COMMAND3 ; NO--GO DO NEXT ONE
POP DI ; ZERO FLAG IS SET
RET

CMD_TIMEOUT: ; ZERO FLAG IS SET
MOV DISK_STATUS1,BAD_CNTL
COMMAND5: ; SET CONDITION CODE FOR CALLER
POP BX
DISK_STATUS1,0
COMMAND ENDP

;-----+
; WAIT FOR INTERRUPT
; -----+



WAIT PROC NEAR
STI ; MAKE SURE INTERRUPTS ARE ON
SUB CX,CX ; SET INITIAL DELAY BEFORE TEST
CLC
MOV AX,9000H ; DEVICE WAIT INTERRUPT
INT 15H
JC WTS ; DEVICE TIMED OUT
TEST HF_INT_FLAG,80H ; TEST FOR INTERRUPT ALREADY
JNZ WT2 ; NO--GO TO WT1
MOV BL,DELAY_1 ; SET DELAY COUNT
WAIT_LOOP

WT1: TEST HF_INT_FLAG,80H ; TEST FOR INTERRUPT
LOOPZ WTT ; INTERRUPT--LETS GO
JNZ WT2 ; KEEP TRYING FOR A WHILE
JNC WT1
SHORT WT3 ; NO--GO TO WT1

WT2: MOV DISK_STATUS1,0 ; SET CONDITION CODE FOR CALLER
MOV HF_INT_FLAG,0
DEC BL
JNC WT2
RET

WTX: CMP DISK_STATUS1,0 ; SET CONDITION CODE FOR CALLER
MOV HF_INT_FLAG,0
JNP WTX ; REPORT TIME OUT ERROR
WT3: MOV DISK_STATUS1,TIME_OUT ; REPORT TIME OUT ERROR
JNP WTX
WAIT ENDP

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;-----: WAIT FOR CONTROLLER NOT BUSY :-----:
050F NOT_BUSY PROC NEAR
050F FB STI BX ; MAKE SURE INTERRUPTS ARE ON
051E 53 PUSH BX
051E B3 20 MOV BL,_DELAY_1
05E3 2B C9 SUB CX,CX ; SET INITIAL DELAY BEFORE TEST
05E5 BA 01F7 MOV DX,HF_PORT+7
05E8 EC INT AL,DX ; CHECK STATUS
05E9 A8 80 TEST AL,DX
05E9 E0 FB LOOPNZ NB1 ; NOT BUSY--LETS GO
05ED 74 06 JZ NB2 ; KEEP TRYING FOR A WHILE
05EF FE CB DEC BL
05F1 75 F5 JNZ NB1 ; KEEP TRYING FOR A WHILE
05F3 EB OC JMP SHORT NB3
05F4 C0 06 0074 R 00 NB2: MOV AH,DISK_STATUS1,0
05FA 5B POP BX
05FB 80 3E 0074 R 00 NBX: CMP DX,DISK_STATUS1,0 ; SET CONDITION CODE FOR CALLER
0600 C3 RET
0601 C6 06 0074 R 80 NB3: MOV DISK_STATUS1,TIME_OUT ; REPORT TIME OUT ERROR
0606 EB F2 JMP NB2
0608 NOT_BUSY ENDP

;-----: WAIT FOR DATA REQUEST :-----:
0608 B9 0100 WAIT_DRQ PROC NEAR
0608 BA 01F7 MOV CX,_DELAY_3
060E EC MOV DX,HF_PORT+7
060F A8 08 WQ_1: IN AL,DX ; GET STATUS
0613 75 09 TEST AL,ST_DRQ ; WAIT FOR DRQ
0613 E0 CC LOOP NZCOK ; KEEP TRYING FOR A SHORT WHILE
0615 C6 06 0074 R 80 MOV AH,DISK_STATUS1,TIME_OUT ; ERROR
061A F9 STC
061B C3 RET
061C F8 CLC
061D C3 RET
061E C3 WAIT_DRQ ENDP

;-----: CHECK HARD FILE STATUS :-----:
061E E8 0630 R CHECK_STATUS PROC NEAR
0621 75 07 CALL CHECK_ST ; CHECK THE STATUS BYTE
0623 A8 01 JNZ CHECK_S1 ; AN ERROR WAS FOUND
0625 74 03 TEST AL,ST_ERROR ; WERE THERE ANY OTHER ERRORS
0626 75 04 JZ CHECK_S1 ; NO ERROR REPORTED
062A E8 0664 R CALL CHECK_ER ; ERROR REPORTED
062A CMP DISK_STATUS1,0 ; SET STATUS FOR CALLER
062A RET
062A CHECK_STATUS ENDP

;-----: CHECK HARD FILE STATUS BYTE :-----:
0630 BA 01F7 CHECK_ST PROC NEAR
0631 EC IN DX,HF_PORT+7 ; GET THE STATUS
0634 A2 008C R MOV AH,DISK_STATUS1,AL
0637 B8 00 MOV AH,0
0639 A8 80 TEST AL,ST_BUSY ; IF STILL BUSY
063B 75 1A JNZ CKST_EXIT ; REPORT OK
063D B4 CC MOV AH,WRITE_FAULT
063F A8 20 TEST AL,ST_WRITE_FLT ; CHECK FOR WRITE FAULT
0641 75 41 JNZ CKST_EXIT ; CHECK FLIT
0643 B4 AA MOV AH,NOT_RDY
0645 A8 40 TEST AL,ST_READY ; CHECK FOR NOT READY
0647 74 0E JZ CKST_EXIT ; CHECK FOR SEEK NOT COMPLETE
0649 B4 40 MOV AH,BAD_SEEK
064A 75 00 TEST AL,ST_SEEK_COMPL ; CHECK FOR SEEK NOT COMPLETE
064B 74 08 JZ CKST_EXIT ; CHECK FOR CORRECTED ECC
064F B4 11 MOV AH,DATA_CORRECTED
0651 A8 04 TEST AL,ST_CORRCTD ; CHECK FOR CORRECTED ECC
0653 75 02 JNZ CKST_EXIT ; CHECK FOR CORRECTED ECC
0655 B4 00 MOV AH,0
0657 88 26 0074 R CKST_EXIT1: MOV DISK_STATUS1,AH ; SET ERROR FLAG
0658 B0 FC 11 CMP AH,DATA_CORRECTED ; KEEP GOING WITH DATA CORRECTED
065E 74 03 JZ CKST_EXIT1 ; CKST_EXIT
0660 B0 FC 00 CMP AH,0
0663 C3 CKST_EXIT1: RET
0664 CHECK_ST ENDP

;-----: CHECK HARD FILE ERROR REGISTER :-----:
0664 BA 01F1 CHECK_ER PROC NEAR
0667 EC IN DX,HF_PORT+1 ; GET THE ERROR REG
0668 A2 008D R MOV AL,DX
066B 53 PUSH BX
0670 00 0008 CK1: MOV AH,0 ; TEST ALL 8 BITS
067F D0 E0 SHL AL,1 ; MOVE NEXT ERROR BIT TO CARRY
0671 72 02 JC CK2 ; FOUND THE ERROR
0673 E2 FA LOOP CK1 ; KEEP TRYING
0675 BB 0686 R CK2: MOV BX,OFFSET ERR_TBL ; COMPUTE ADDRESS OF
0676 00 D0 ADD AX,BX ; ERROR CODE
067A E2 F8 MOV AH,BYTE PTR CS:[BX] ; GET ERROR CODE
067D 88 26 0074 R CKEX: MOV DISK_STATUS1,AH ; SAVE ERROR CODE
0681 5B POP BX
0682 B0 FC 00 CMP AH,0
0685 C3 RET
0687 00 00
0687 02 40 01 BB ERR_TBL DB NO_ERR ; RECORD NOT FND, UNDEF_ERR, BAD_ECC, BAD_SECTOR
0688 04 BB 10 0A DB BAD_ADDR_MARK, BAD_SEEK, BAD_CMD, UNDEF_ERR
068F CHECK_ER ENDP

;-----: CHECK_DMA :-----:
;-----: -CHECK ES:BX AND # SECTORS TO MAKE SURE THAT IT WILL
;-----: FIT WITHOUT SEGMENT OVERFLOW.
;-----: -ES:BX HAS BEEN REVISED TO 16-BIT FORMAT SSSS:0000
;-----: -OK IF # SECTORS < 80H (100H) IF LONG READ OR WRITE)
;-----: -OK IF # SECTORS < 80H (7FH) AND BX <= OOH (04H)
;-----: -ERROR OTHERWISE
068F CHECK_DMA PROC NEAR
068F 50 PUSH AX ; SAVE RECS
0690 B8 8000 MOV AX,8000H ; AH = MAX # SECTORS
0693 F6 06 0048 R 02 TEST AL,MAX_OFFSET ; AL = MAX OFFSET

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0698 7B 03
069A BB 7F04
069D 3A 26 0043 R
06A1 77 06
06A3 72 07
06A5 72 C3
06A7 72 03
06A9 F8
06AA 58
06AB C3
06C0 F9
06AD 26 06 0074 R 09
06B2 58
06B3 C3
06B4

JZ      CKD1
MOV    AX,7F04H ; ECC IS 4 MORE BYTES
CMP    AH,CMD_BLOCK+1 ; NUMBER OF SECTORS
JA     CKDOK ; IT WILL FIT
CKDOK CKDERR ; TO MANY
        CKDERR ; CHECK OFFSET ON MAX SECTORS
        JB     CKDERR ; ERROR
        CLC
        POP   AX ; CLEAR CARRY
        RET
CKDERR SMC ; NORMAL RETURN
        MAC
        POP   AX ; INDICATE ERROR
        RET
CHECK_DMA ENDP

;-----SET UP ES:BX->DISK PARMS-----
;-----GET_VEC PROC NEAR-----;
06B4 28 C0
06B6 8E C0
06B8 F6 C2 01
06BB 74 07
06BD 26: C4 1E 0118 R
06C0 EB 05
06C4 26: C4 1E 0104 R
06C9 C3
06CA

GET_VEC PROC NEAR ; GET DISK PARAMETER ADDRESS
SUB   AX,AX
MOV   ES,AX
ASSUME ES:ABSO
TEST  DL,1
JZ    GV_0
LES   BX,HF1_TBL_VEC ; ES:BX -> DRIVE PARAMETERS
JMP   SHORT GV_EXIT
GV_0: LES   BX,HF_TBL_VEC ; ES:BX -> DRIVE PARAMETERS
GV_EXIT: RET
GET_VEC ENDP

;-----HARD DISK INTERRUPT ROUTINE-----
;-----HD_INT PROC NEAR-----;
06CA 50
06CB E
06CC B8 ---- R
06CF 8E D8
06D1 C6 06 008E R FF
06D6 B0 20
06D8 E6 A0
06E0 E6 00
06DC E6 20
06DE 1F
06DF FB
06E0 BB 9100
06E1 CB 15
06E5 58
06E6 CF
06E7 31 2F 31 31 2F 38
            34
06EE END_ADDRESS
          CODE ENDS
          ENDS

HD_INT PROC NEAR ; ALL DONE
PUSH  AX
PUSH  DS
MOV   AX,DATA ; NON-SPECIFIC END OF INTERRUPT
MOV   DS,AX
MOV   HF1_INT_FLAG,OFFH
MOV   AL_EOI ; FOR CONTROLLER #2
OUT   INT_CTL_PORT,AL ; WAIT
        DS
        OUT   INT1_CTL_PORT,AL ; FOR CONTROLLER #1
        POP   DS
        STI
        MOV   AX,9100H ; RE-ENABLE INTERRUPTS
        INT   15H ; DEVICE POST
        POP   AX ; INTERRUPT
IRET
HD_INT ENDP ; RETURN FROM INTERRUPT

06E7 DB '1/11/84' ; RELEASE MARKER
            34
06EE LABEL BYTE
          ENDS

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TITLE 01/04/84 KEYBOARD BIOS
.LIST

PUBLIC KEYBOARD_I0_1
PUBLIC KB_INT_1
PUBLIC K16

0000
CODE SEGMENT BYTE PUBLIC
EXTRN DOS$:_READ
EXTRN START_1:NEAR
EXTRN K6:BYTE
EXTRN K6L:ABS
EXTRN K7:BYTE
EXTRN K8:BYTE
EXTRN K9:BYTE
EXTRN K10:BYTE
EXTRN K11:BYTE
EXTRN K12:BYTE
EXTRN K13:BYTE
EXTRN K14:BYTE
EXTRN K15:BYTE

;---- INT 16 -----
; KEYBOARD I/O
; THESE ROUTINES PROVIDE KEYBOARD SUPPORT
INPUT
    (AH)=0 READ THE NEXT ASCII CHARACTER STRUCK FROM THE KEYBOARD
    RETURN THE RESULT IN (AL), SCAN CODE IN (AH)
    SET THE Z FLAG TO INDICATE IF AN ASCII CHARACTER IS AVAILABLE
    TO BE READ,
    (ZF)=0 -- NO CODE AVAILABLE
    (ZF)=1 -- CODE IS AVAILABLE
    IF ZF = 0, THE NEXT CHARACTER IN THE BUFFER TO BE READ IS
    IN AX, AND THE ENTRY REMAINS IN THE BUFFER
    (AH)=2 RETURN THE CURRENT SHIFT STATUS IN AL REGISTER
    THE BIT SETTINGS FOR THIS CODE ARE INDICATED IN THE
    THE EQUATES FOR KB_FLAG

OUTPUT
    AS NOTED ABOVE, ONLY AX AND FLAGS CHANGED
    ALL REGISTERS RETAINED
ASSUME CS:CODE,DS:DATA

0000 FB KEYBOARD_I0_1 PROC FAR ;>>> ENTRY POINT FOR ORG 0E82EH
0001 1E STI ;INTERRUPTS BACK ON
0002 C3 PUSH DS ;SAVE CURRENT DS
0003 EB 0000 E CALL DDS ;SAVE BX TEMPORARILY
0004 0A E4 OR AH,AH ;ESTABLISH POINTER TO DATA REGION
0005 74 0B JZ K1B ;ASCII_I_READ
0006 FE CC DEC AH ;AH=1
0007 74 A5 JZ K2 ;ASCII_I_STATUS
0008 4C CC DEC AH ;AH=0
0009 74 67 JZ K3 ;SHIFT_STATUS
0010 74 67 POP BX ;RECOVER REGISTER
0011 5B POP DS
0012 1F IRET ;INVALID COMMAND

;---- READ THE KEY TO FIGURE OUT WHAT TO DO
K1B: MOV BX,BUFFER_HEAD ;GET POINTER TO HEAD OF BUFFER
0015 8B 1E 001A R CMP BX,BUFFER_TAIL ;TEST END OF BUFFER
0019 3B 1E 001C R JNE K1C ;IF ANYTHING IN BUFFER DONT DO INTERRUPT
001D 75 07 ;;

001F BB 9002 ;MOVE IN WAIT CODE & TYPE
0022 CD 15 ;INT 15H
K1: STI ;PERFORM OTHER FUNCTION
0024 FB NOP ;ASCII READ
0025 3D CLI ;INTERRUPTS BACK ON DURING LOOP
0026 FA MOV BX,BUFFER_HEAD ;ALWAYS A WAIT TO OCCUR
K1C: GLI ;INTERUPTS BACK OFF
    MOV BX,BUFFER_TAIL ;GET POINTER TO HEAD OF BUFFER
    CMP BX,BUFFER_TAIL ;TEST END OF BUFFER
    PUSHF BX ;SAVE ADDRESS
    PUSHF ;SAVE FLAG
    CALL MAKE_LED ;GO GET MODE INDICATOR DATA BYTE
    MOV BL,KB_FLAG_2 ;GET PREVIOUS BITS
    XOR BL,AL ;SEE IF ANY DIFFERENT
    AND BL,07H ;ISOLATE INDICATOR BITS
    JZ K1A ;IF NO CHANGE BYPASS UPDATE
0030 9C ;;
0031 1B 008A R CALL SND_LED1 ;GO TURN ON MODE INDICATORS
0034 8A 1E 0097 R CMP K4 ;DISABLE INTERRUPTS
0038 32 D8 POP BX ;RESTORE FLAGS
003A 80 E3 07 POP K1 ;RESTORE ADDRESS
003D 74 04 ;LOOP UNTIL SOMETHING IN BUFFER

003F E8 044C R ;;
0042 FA K1A: POPF ;;
0043 9D CLI ;;
0044 5B POP BX ;;
0045 74 DD JZ K1 ;;
0047 BB 07 ;;
0049 E8 007F R MOV AX,[BX] ;GET SCAN CODE AND ASCII CODE
004C 89 1E 001A R CALL K4 ;MOVE POINTER TO NEXT POSITION
MOV BUFFER_HEAD,BX ;STORE VALUE IN VARIABLE
0050 5B ;;
0051 1F POP BX ;RECOVER REGISTER
0052 CF POP DS ;RECOVER SEGMENT
IRET ;RETURN TO CALLER

;---- ASCII STATUS
K2: GLI ;INTERUPTS OFF
0053 FA MOV BX,BUFFER_HEAD ;GET HEAD POINTER
0054 8B 1E 001A R CMP BX,BUFFER_TAIL ;IF EQUAL (Z=1) THEN NOTHING THERE
0055 3B 1E 001C R MOV AX,[BX]
0056 8B 07 ;;
0057 9C PUSHF ;SAVE FLAGS
0058 50 ;;
0060 E8 048A R PUSH AX ;SAVE CODE
0063 8A 1E 0097 R CALL MAKE_LED ;GO GET MODE INDICATOR DATA BYTE
0066 32 D8 MOV BL,KB_FLAG_2 ;GET PREVIOUS BITS
0069 80 E3 07 XOR BL,AL ;SEE IF ANY DIFFERENT
006C 74 03 AND BL,07H ;ISOLATE INDICATOR BITS
JZ SK2 ;IF NO CHANGE BYPASS UPDATE

006E E8 044C R ;;
0072 5B CALL SND_LED1 ;GO TURN ON MODE INDICATORS
0073 9D POPF ;RESTORE CODE
0073 FB STI ;RESTORE FLAGS
0074 5B POP BX ;INTERUPTS BACK ON
0075 1F POP DS ;RECOVER REGISTER
0076 CA 0002 RET 2 ;RECOVER SEGMENT
THROW AWAY FLAGS

;---- SHIFT STATUS
K3: MOV AL,KB_FLAG ;GET THE SHIFT STATUS FLAGS
0079 A0 0017 R POP BX ;RECOVER REGISTER
007C 5B POP DS ;RECOVER REGISTERS
007D 1F IRET ;RETURN TO CALLER
007E CF KEYBOARD_I0_1 ENDP
007F

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;----- INCREMENT A BUFFER POINTER
007F 43 K4 PROC NEAR
0080 43 INC BX ; MOVE TO NEXT WORD IN LIST
0081 BB 1E 0082 R INC BX
0085 75 04 CMP BX,BUFFER_END ; AT END OF BUFFER?
0087 BB 1E 0080 R JNE K4 ; NO, CONTINUE
0088 MOV BX,BUFFER_START ; YES, RESET TO BUFFER BEGINNING
008B C3 K5: RET
008C ENDP

;----- KEYBOARD INTERRUPT ROUTINE
008C 1 PROC FAR
008D STI ; ENABLE INTERRUPTS
008E FB PUSH BP
008F 55 PUSH AX
0090 53 PUSH BX
0091 51 PUSH CX
0092 52 PUSH DX
0093 56 PUSH SI
0094 57 PUSH DI
0095 06 PUSH DS
0096 FC PUSH ES
0097 EA 0000 E CLD ; FORWARD DIRECTION
0098 80 AD CALL DDS ; SET UP ADDRESSING
0099 E8 0498 R MOVS AL,DIS_KBD ; DISABLE THE KEYBOARD
009A CALL SHIP_IT ; EXECUTE DISABLE

;----- WAIT FOR COMMAND TO BE ACCEPTED
009F FA CLI ; DISABLE INTERRUPTS
00A0 2B C9 SUB CX,CX
00A2 E4 64 KB_INT_01 ; IN AL,STATUS_PORT ;
00A4 A8 02 TEST AL,INPT_BUF_FULL
00A6 E0 FA LOOPNZ KB_INT_01 ; WAIT FOR COMMAND TO BE ACCEPTED

00AB E4 60 IN AL,KB_DATA ; READ IN THE CHARACTER
00AA FB STI ; ENABLE INTERRUPTS AGAIN

;-----CHECK FOR A RESEND COMMAND TO KEYBOARD
00AB 3C FE CMP AL,KB_RESEND ; IS THE INPUT A RESEND
00AD 74 0D JE KB_INT_4 ; GO IF RESEND

;----- CHECK FOR RESPONSE TO A COMMAND TO KEYBOARD
00AF 3C FA CMP AL,KB_ACK ; IS THE INPUT AN ACKNOWLEDGE
00B1 75 12 JNZ KB_INT_2 ; GO IF NOT

;----- A COMMAND TO THE KEYBOARD WAS ISSUED
00B3 FA CLI ; DISABLE INTERRUPTS
00B4 80 0E 0097 R 10 OR KB_FLAG_2,KB_FA ; INDICATE ACK RECEIVED
00B9 E9 01E2 R JMP K26 ; RETURN IF NOT (THIS ACK RETURNED FOR DATA)

;----- RESEND THE LAST BYTE
KB_INT_4:
00B9 FA CLI ; DISABLE INTERRUPTS
00B0 80 0E 0097 R 20 OR KB_FLAG_2,KB_FE ; INDICATE RESEND RECEIVED
00C2 E9 01E2 R JMP K26 ; RETURN IF NOT (THIS ACK RETURNED FOR DATA)

00C5 KB_INT_2:
;-----UPDATE MODE INDICATORS IF CHANGE IN STATE
00C6 E8 048A R PUSH AX ; SAVE DATA IN
00C9 8A 1E 0097 R CALL MAKE_LED ; GET MODE INDICATOR DATA BYTE
00C0 32 D8 MOV BL,KB_FLAG_2 ; GET PREVIOUS BITS
00C1 80 0E 07 XOR BL,AL ; SEE IF ANY CHANGED
00C2 74 03 AND BL,07H ; ISOLATE INDICATOR BITS
00C3 JZ UP0 ; IF NO CHANGE BYPASS UPDATE

00D4 E8 0439 R CALL SND_LED ; GO TURN ON MODE INDICATORS
00D7 58 UP0: POP AX ; RESTORE DATA IN
00D8 8A E0 MOV AH,AL ; SAVE SCAN CODE IN AH ALSO

;----- TEST FOR OVERRUN SCAN CODE FROM KEYBOARD
00DA 3C FF CMP AL,0FFH ; IS THIS AN OVERRUN CHAR
00DC 75 03 JNZ K16 ; NO, TEST FOR SHIFT KEY
00DE E9 03D6 R JMP K26 ; BUFFER_FULL_BEEP

;----- TEST FOR SHIFT KEYS
K16:
00E1 24 7F AND AL,07FH ; TEST_SHIFT
00E3 0E PUSH CS ; TURN OFF THE BREAK BIT
00E4 07 POP ES ; ESTABLISH ADDRESS OF SHIFT TABLE

;----- TEST FOR SYSTEM KEY
00E5 3C 5b CMP AL,SYS_KEY ; IS IT THE SYSTEM KEY?
00E7 75 3D JNZ K16A ; CONTINUE IF NOT

00E9 F6 C4 80 TEST AH,080H ; CHECK IF THIS A BREAK CODE
00EC 75 21 JNZ K16C ; DONT TOUCH SYSTEM INDICATOR IF TRUE

00EE F6 06 0018 R 04 TEST KB_FLAG_1,SYS_SHIFT ; SEE IF IN SYSTEM KEY HELD DOWN
00F3 75 17 JNZ K16B ; IF YES, DONT PROCESS SYSTEM INDICATOR

00F5 80 0E 0018 R 04 OR KB_FLAG_1,SYS_SHIFT ; INDICATE SYSTEM KEY DEPRESSED
00FA 80 20 MOV AL,E01 ; END OF INTERRUPT COMMAND
00FC E6 20 OUT 020H,AL ; SEND COMMAND TO INTERRUPT CONTROL PORT
                           ; INTERRUPT-RETURN-NO-E01
                           ; INSURE KEYBOARD IS ENABLED
                           ; EXECUTE ENABLE

00FE B0 AE MOV AL,ENA_KBD ; FUNCTION VALUE FOR MAKE OF SYSTEM KEY
0100 E8 0498 R CALL SHIP_IT ; EXECUTE ENABLE
0103 BB 8500 MOV AX,0850H ; MAKE SURE INTERRUPTS ENABLED
                           ; USER INTERRUPT
                           ; END PROCESSING
0107 CD 15 INT 15H
0109 E9 01EC R JMP K27A
010C E9 01E2 R K16B: JMP K26 ; IGNORE SYSTEM KEY

010F B0 AE MOV KB_FLAG_1,NOT SYS_SHIFT ; TURN OFF SHIFT KEY HELD DOWN
0114 B0 20 AND AL,E01 ; END OF INTERRUPT COMMAND
0116 E6 20 OUT 020H,AL ; SEND COMMAND TO INTERRUPT CONTROL PORT
                           ; INTERRUPT-RETURN-NO-E01
                           ; INSURE KEYBOARD IS ENABLED
                           ; EXECUTE ENABLE

0118 B0 AE MOV AL,ENA_KBD ; FUNCTION VALUE FOR BREAK OF SYSTEM KEY
0119 E8 0498 R CALL SHIP_IT ; EXECUTE ENABLE
0120 BB 8501 MOV AX,08501H ; MAKE SURE INTERRUPTS ENABLED
                           ; USER INTERRUPT
0121 CD 15 INT 15H ; USER INTERRUPT

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0123 E9 01EC R ; JMP K27A ; IGNORE SYSTEM KEY
0126 BF 0000 E ; K16A: MOV DI,OFFSET K6 ; SHIFT KEY TABLE
0129 B9 0000 E ; MOV CX,OFFSET K6L ; LENGTH
012B F2? AE ; REPNE SCASB ; LOOK THROUGH THE TABLE FOR A MATCH
012E 8C C4 ; MOV AL,AH ; RECOVER SCAN CODE
0130 74 03 ; JE K17 ; JUMP IF MATCH FOUND
0132 E9 01CE R ; JMP K25 ; IF NO MATCH, THEN SHIFT NOT FOUND

;----- SHIFT KEY FOUND

0135 81 EF 0001 E ; K17: SUB DI,OFFSET K6+1 ; ADJUST PTR TO SCAN CODE MTC
0139 E8 8A A5 0000 E ; MOV AH,CS:K7[DI] ; GET MASK INTO AH
013E A8 80 ; TEST AL,80H ; TEST FOR BREAK KEY
0140 74 02 ; JZ K17C ; BREAK_SHIFT_FOUND
0142 EB 63 ; JMP SHORT K23 ; CONTINUE

;----- DETERMINE SET OR TOGGLE

0144 80 FC 10 ; K17C: CMP AH,SCROLL_SHIFT ; IF SCROLL SHIFT OR ABOVE, TOGGLE KEY
0147 73 07 ; JAE K18 ; ; IF SCROLL SHIFT OR ABOVE, TOGGLE KEY

;----- PLAIN SHIFT KEY, SET SHIFT ON

0149 08 26 0017 R ; OR KB_FLAG,AH ; TURN ON SHIFT BIT
014D E9 01E2 R ; JMP K26 ; ; INTERRUPT_RETURN

;----- TOGGLED SHIFT KEY, TEST FOR 1ST MAKE OR NOT

0150 F6 06 0017 R 04 ; K18: TEST KB_FLAG, CTL_SHIFT ; SHIFT-TOGGLE
0155 74 03 ; JZ K18A ; CHECK CTL SHIFT STATE
0157 EB 75 90 ; K18A: JMP K25 ; JUMP IF CTL STATE
015A 3C 52 ; CMP AL, INS_KEY ; CHECK FOR INSERT KEY
015C 75 25 ; JNZ K22 ; JUMP IF NOT INSERT KEY
015D 00 00 0017 R 08 ; TEST KB_FLAG, ALT_SHIFT ; CHECK FOR ALTERNATE SHIFT
015E 74 03 ; JZ K19 ; JUMP IF NOT ALTERNATE SHIFT
0165 FB 67 90 ; JMP K25 ; ALTERNATE SHIFT
0168 F6 06 0017 R 20 ; K19: TEST KB_FLAG, NUM_STATE ; CHECK FOR BASE STATE
016D 75 00 ; JNZ K21 ; JUMP IF NUM LOCK IS ON
016F F6 06 0017 R 03 ; TEST KB_FLAG, LEFT_SHIFT+ RIGHT_SHIFT ; CHECK FOR BASE STATE
0174 74 00 ; JZ K22 ; JUMP IF BASE STATE

0176 F6 06 0017 R 03 ; K20: MOV AX, 5230H ; NUMERIC ZERO, NOT INSERT KEY
0177 E9 0375 R ; JMP K57 ; PUT OUT AN ASCII ZERO
0178 74 00 ; K21: TEST KB_FLAG, LEFT_SHIFT+ RIGHT_SHIFT ; BUFFER FILL
017C F6 06 0017 R 03 ; JZ K20 ; ; LEFT SHIFT BE NUMERIC
0181 F4 F3 ; K22: TEST AH,KB_FLAG_1 ; ; JUMP NUMERIC, NOT INSERT
0183 F6 06 0018 R ; K22: TEST AH,KB_FLAG_1 ; SHIFT TOGGLE KEY HIT; PROCESS IT
0185 84 26 0018 R ; JZ K22A0 ; IS THIS KEY ALREADY DEPRESSED
0187 74 02 ; JMP K22 ; GO TO DEPRESS
0189 EB 57 ; K22A0: OR KB_FLAG_1, AH ; JUMP IF KEY ALREADY DEPRESSED
018B 88 26 0018 R ; XOR KB_FLAG_1, AH ; INDICATE THAT THE KEY IS DEPRESSED
018F 30 26 0017 R ; ; TOGGLE THE SHIFT STATE

;----- TOGGLE LED IF CAPS OR NUM KEY DEPRESSED

0193 F6 C4 70 ; K23: TEST AH,CAPS_SHIFT+NUM_SHIFT+SCROLL_SHIFT ; SHIFT TOGGLE?
0196 74 05 ; JZ K22B ; GO IF NOT
0198 50 ; PUSH AX ; SAVE SCAN CODE AND SHIFT MASK
0199 E8 0439 R ; CALL SND_LED ; GO TURN MODE INDICATORS ON
019C 58 ; POP AX ; RESTORE SCAN CODE

019D 3C 52 ; K22B: CMP AL,INS_KEY ; TEST FOR 1ST MAKE OF INSERT KEY
019F 75 41 ; JNE K26 ; JUMP IF NOT INSERT KEY
01A1 BB 5200 ; MOV AX,INS_KEY*256 ; SET SCAN CODE INTO AH, 0 INTO AL
01A4 E9 0375 R ; JMP K57 ; PUT INTO OUTPUT BUFFER

;----- BREAK SHIFT FOUND

01A7 F6 06 0019 R ; K23: CMP AH,SCROLL_SHIFT ; IS THIS A TOGGLE KEY
01B0 80 FC 10 ; JAE K24 ; YES, HANDLE BREAK TOGGLE
01B3 73 1A ; NOT AH ; INVERT MASK
01AC F6 D4 ; AND KB_FLAG,AH ; TURN OFF SHIFT BIT
01AE 20 26 0017 R ; CMP AL,ALT_KEY+80H ; IS THIS ALTERNATE SHIFT RELEASE
01B2 3C B8 ; JNE K26 ; ; JUMP IF NOT
01B4 75 2C ; ; INTERRUPT_RETURN

;----- ALTERNATE SHIFT KEY RELEASED, GET THE VALUE INTO BUFFER

01B6 A0 0019 R ; K24: NOT AH ; BREAK-TOGGLE
01B9 B8 00 ; MOV AL,ALT_INPUT ; INVERT MASK
01BF 68 06 0019 R ; MOV AH,0 ; ZERO OUT THE FIELD
01C0 3C 00 ; CMP AL,0 ; WAS THE INPUT=0
01C1 74 1F ; JE K26 ; ; INTERRUPT_RETURN
01C3 E9 037E R ; JMP K58 ; IT WASN'T, SO PUT IN BUFFER

01C6 F6 D4 ; K24: AND KB_FLAG_1,AH ; BREAK-TOGGLE
01C8 20 26 0018 R ; JMP SHORT K26 ; INVERT MASK
01CC EB 14 ; ; INDICATE NO LONGER DEPRESSED
;----- TEST FOR HOLD STATE

01CE 3C 80 ; K25: CMP AL,80H ; INTERRUPT_RETURN
01DE 73 10 ; JAE K26 ; TURN OFF INTERRUPTS
01DD F6 06 0018 R 08 ; TEST KB_FLAG_1,HOLD_STATE ; END OF INTERRUPT COMMAND
01E0 74 05 ; JZ K27 ; SEND COMMAND TO INTERRUPT CONTROL PORT
01E1 3C 45 ; CMP AL,NUM_KEY ; INTERRUPT-RETURN-NO-EOI
01DB 74 05 ; JE K26 ; BRANCH AROUND TEST IF NOT
01D8 20 26 0018 R F7 ; AND KB_FLAG_1,NOT HOLD_STATE ; CAN'T END HOLD ON NUM_LOCK
;----- TEST FOR HOLD STATE

01E2 FA ; K26: CLI ; ; INTERRUPT-RETURN
01E3 B0 20 ; MOV AL,E0I ; TURN OFF INTERRUPTS
01E5 E6 20 ; OUT 020H,AL ; END OF INTERRUPT COMMAND
01E7 F6 D4 ; K27: MOV AL,ENA_KBD ; SEND COMMAND TO INTERRUPT CONTROL PORT
01E9 B0 AE ; CALL SHIP_IT ; INTERRUPT-RETURN-NO-EOI
01E9 E8 0498 R ; ; INSURE KEYBOARD IS ENABLED
;----- EXECUTE ENABLE

01E1 FA ; K27A: CLI ; ; DISABLE INTERRUPTS
01E2 07 ; POP ES ; RESTORE REGISTERS
01E3 F ; POP DS ; ; *
01E4 F5 ; POP DI ; ; *
01F0 5E ; POP SI ; ; *
01F1 5A ; POP DX ; ; *
01F2 59 ; POP CX ; ; *
01F3 5B ; POP BX ; ; *
01F4 58 ; POP AX ; ; *
01F5 5D ; POP BP ; ; *
01F6 CF ; IRET ; RETURN, INTERRUPTS BACK ON WITH FLAG CHANGE

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;----- NOT IN HOLD STATE
01F7 F6 06 0017 R 08
01FC 75 03
01FE E9 0290 R
K28: TEST KB_FLAG,ALT_SHIFT ; NO-HOLD-STATE
      JNZ K29 ; ARE WE IN ALTERNATE SHIFT
      JMP K38 ; JUMP IF ALTERNATE
;----- TEST FOR RESET KEY SEQUENCE (CTL ALT DEL)
0201 F6 06 0017 R 04
0206 74 31
0208 3C 53
020A 75 2D
K29: TEST KB_FLAG,CTL_SHIFT ; TEST-RESET
      JZ K31 ; NO_RESET
      CMP AL,DEL_KEY ; SHIFT STATE IS THERE, TEST KEY
      JNE K31 ; NO_RESET
;----- CTL-ALT-DEL HAS BEEN FOUND, DO I/O CLEANUP
020C C7 06 0072 R 1234
0212 E9 0000 E
MOV RESET_FLAG, 1234H ; SET FLAG FOR RESET FUNCTION
JMP START_1 ; JUMP TO POWER ON DIAGNOSTICS
;----- ALT-INPUT-TABLE
0215 52 4F 50 51 4B 4C
021C 4D
021C 47 48 49
K30 LABEL BYTE
DB 82,79,80,81,75,76,77
;----- SUPER-SHIFT-TABLE
021F 10 11 12 13 14 15
0221 16 17
0221 18 19 1E 1F 20 21
022F 24 25 26 2C 2D 2E
0237 2F 30
0237 31 32
DB 71,72,73 ; 10 NUMBERS ON KEYPAD
DB 16,17,18,19,20,21,22,23 ; A-Z TYPEWRITER CHARS
DB 24,25,30,31,32,33,34,35
DB 36,37,38,44,45,46,47,48
DB 49,50
;----- IN ALTERNATE SHIFT, RESET NOT FOUND
0239 3C 39
023B 75 05
023D B0 20
023F E9 0375 R
K31: CMP AL,57 ; NO-RESET
      JNE K32 ; TEST FOR SPACE KEY
      MOV AL,' ' ; NOT THERE
      JMP K57 ; SET SPACE CHAR
;----- LOOK FOR KEY PAD ENTRY
0242 8F 0215 R
0245 B9 000A
0248 F2/ AE
024A 75 12
024C 81 EF 0216 R
0250 A0 0019 R
0251 80 00
0255 F6 E4
0257 03 C7
0259 A2 0019 R
025C EB 84
K32: MOV DI,OFFSET K30 ; ALT-KEY-PAD
      MOV CX,10 ; ALT-INPUT-TABLE
      REPNE SCASB ; LOOK FOR ENTRY USING KEYPAD
      JNE K33 ; LOOK FOR MATCH
      SUB DI,OFFSET K30+1 ; NO_ALT_KEYPAD
      MOV AL,ALT_INPUT ; DI NOW HAS ENTRY VALUE
      MOV AH,AL ; GET THE CURRENT BYTE
      MUL AX,10 ; MULTIPLY BY 10
      ADD AX,DI ; ADD IN THE LATEST ENTRY
      MOV AL,ALT_INPUT ; STORE IT AWAY
      JMP K26 ; THROW AWAY THAT KEYSTROKE
;----- LOOK FOR SUPERSHIFT ENTRY
025E C6 06 0019 R 00
0263 B9 001A
0266 F2/ AE
0268 75 05
026A B0 00
026C E9 0375 R
K33: MOV ALT_INPUT,0 ; NO-ALT-KEYPAD
      MOV CX,26 ; ZERO ANY PREVIOUS ENTRY INTO INPUT
      REPNE SCASB ; DI_ES ALREADY POINTING
      JNE K34 ; LOOK FOR MATCH ALPHABET
      MOV AL,0 ; NO FOUND FUNCTION KEY OR OTHER
      JMP K57 ; ASCII CODE OF ZERO
      ; PUT IT IN THE BUFFER
;----- LOOK FOR TOP ROW OF ALTERNATE SHIFT
026F 3C 02
0271 72 0C
0273 3C 0E
0275 73 08
0277 80 CA 76
027C B0 00
027C E9 0375 R
K34: CMP AL,2 ; ALT-TOP-ROW
      JB K35 ; KEY WITH '1' ON IT
      NOT ONE OF INTERESTING KEYS
      IS IT IN THE REGION
      JAE K35 ; ALT-TOP-ROW
      ADD AH,118 ; CONVERT PSEUDO SCAN CODE TO RANGE
      MOV AL,AH ; INDICATE AS SUCH
      JMP K57 ; BUFFER_FILL
;----- TRANSLATE ALTERNATE SHIFT PSEUDO SCAN CODES
027F 3C 3B
0281 73 03
0283 E9 01E2 R
K35: CMP AL,59 ; ALT-FUNCTION
      JAE K37 ; TEST FOR IN TABLE
      ; ALT-CONTINUE
      ; CLOSE-RETURN
      ; IGNORE THE KEY
      ; IN KEYPAD REGION
      ; ALT-CONTINUE
      ; IF SO, IGNORE
      ; ALT SHIFT PSEUDO SCAN TABLE
      ; TRANSLATE THAT
K36: JMP K26
K37: CMP AL,71 ; ALT-CONTINUE
      JAE K36 ; IGNORE THE KEY
      MOV BX,OFFSET K13 ; ALT SHIFT PSEUDO SCAN TABLE
      JMP K63 ; TRANSLATE THAT
;----- NOT IN ALTERNATE SHIFT
0290 F6 06 0017 R 04
0295 74 62
K38: TEST KB_FLAG,CTL_SHIFT ; NOT-ALT-SHIFT
      JZ K44 ; ARE WE IN CONTROL SHIFT
      ; NOT-CTL-SHIFT
;----- CONTROL SHIFT, TEST SPECIAL CHARACTERS
;----- TEST FOR BREAK AND PAUSE KEYS
0297 3C 46
0299 75 1D
029B 88 1E 0080 R
029D 80 0E 001A R
02A3 89 1E 001C R
02A7 C6 06 0071 R 80
K39: CMP AL,SCROLL_KEY ; TEST FOR BREAK
      JNE K39 ; NO-BREAK
      MOV BX,BUFFER_START ; RESET BUFFER TO EMPTY
      MOV AX,BUFFER_HEAD,BX
      MOV BX,BUFFER_TAIL,BX
      MOV BIOS_BREAK,B0H ; TURN ON BIOS_BREAK BIT
;----- ENABLE KEYBOARD
02AC B0 AE
02AE E8 0098 R
02B1 CD 1B
02B3 2B C0
02B5 E9 0375 R
K40: MOV AL,ENA_KBD ; ENABLE KEYBOARD
      CALL SH1P_IT ; EXECUTE ENABLE
      INT 1BH ; BREAK INTERRUPT VECTOR
      SUB AX,AX ; PUT OUT DUMMY CHARACTER
      JMP K57 ; BUFFER_FILL
02B8 3C 45
02BA 75 26
02BC 80 0E 0018 R 08
K39: CMP AL,NUM_KEY ; NO-BREAK
      JNE K11 ; LOOK FOR PAUSE KEY
      OR KB_FLAG_1,HOLD_STATE ; NO-PAUSE
      ; TURN ON THE HOLD FLAG
;----- ENABLE KEYBOARD
02C1 B0 AE
02C3 E8 0498 R
02C6 B0 20
02C8 E6 20
K41: MOV AL,ENA_KBD ; ENABLE KEYBOARD
      CALL SH1P_IT ; EXECUTE ENABLE
      MOV AL,E0I ; END OF INTERRUPT TO CONTROL PORT
      OUT 020H,AL ; ALLOW FURTHER KEYSTROKE INTS

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;----- DURING PAUSE INTERVAL, TURN CRT BACK ON

02CA B0 3E 0049 R 07           CMP   CRT_MODE,7      ; IS THIS BLACK AND WHITE CARD
02CF 74 07                     JE    K40_              ; YES, NOTHING TO DO
02D1 BA 03D8                   MOV   DX,03D8H        ; PORT FOR COLOR CARD
02D4 AO 0065 R                 MOV   AL,CRT_MODE_SET
02D7 EE                         OUT  DX,AL            ; GET THE VALUE OF THE CURRENT MODE
02D8 K40:                      ; SET THE CRT MODE, SO THAT CRT IS ON
                                ; PAUSE-LOOP

ENDIF

02D8 K40A:                     TEST  KB_FLAG_1,HOLD_STATE
02D9 JNZ   K40A               ; LOOP UNTIL FLAG TURNED OFF
02D0 75 F9                     JMP   K27A             ; INTERRUPT_RETURN_NO_EOI
02D2 E9 01EC R
02E2 K41:                      ; NO-PAUSE

;----- TEST SPECIAL CASE KEY 55

02E2 3C 37                     CMP   AL,55          ; NOT-KEY-55
02E4 75 06                     JNE   K42              ; START/STOP PRINTING SWITCH
02E5 BB 7200                   MOV   AX,114*256
02E9 E9 0375 R                 JMP   K57              ; BUFFER_FILL

;----- SET UP TO TRANSLATE CONTROL SHIFT

02EC K42:                      ; NOT-KEY-55
02EC BB 0000 E                 MOV   BX,OFFSET K8  ; SET BX TO TRANSLATE CTL
02EF 3C 3B                     CMP   AL,59          ; IS IT IN TABLE
02F1 72 7E                     JB    K56              ; YES, GO TRANSLATE CHAR
02F3 BB 0000 E                 MOV   BX,OFFSET K9  ; CTL_TABLE-TRANSLATE
02F6 E9 03CC R                 JMP   K63              ; CTL_TABLE SCAN
                                ; TRANSLATE_SCAN

;----- NOT IN CONTROL SHIFT

02F9 K44:                      ; NOT-CTL-SHIFT
02F9 3C 47                     CMP   AL,71          ; TEST FOR KEYPAD REGION
02FB 73 33                     JAE   K48              ; TEST FOR KEYPAD REGION
02FD F6 06 0017 R 03           TEST  KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT
0302 74 62                     JZ    K54              ; TEST FOR SHIFT STATE

;----- UPPER CASE, HANDLE SPECIAL CASES

0304 3C 0F                     CMP   AL,15          ; BACK TAB KEY
0306 75 05                     JNE   K45              ; NOT-BACK-TAB
0308 BB 0FO0                   MOV   AX,15*256
030B EB 68                     JMP   SHORT K57      ; SET PSEUDO SCAN CODE
                                ; BUFFER_FILL

030D K45:                      ; NOT-BACK-TAB
030D 3C 37                     CMP   AL,55          ; PRINT SCREEN KEY
030F 75 10                     JNE   K46              ; NOT-PRINT-SCREEN

;----- ISSUE INTERRUPT TO INDICATE PRINT SCREEN FUNCTION

0311 B0 AE                     MOV   AL,ENA_KBD      ; INSURE KEYBOARD IS ENABLED
0313 E9 0198 R                 CALL  SHIP_IT       ; EXECUTE_ENABLE
0316 B0 20                     MOV   AL,EO1          ; END OF CURRENT INTERRUPT
0318 E6 20                     OUT  020H,AL        ; SO FURTHER THINGS CAN HAPPEN
031A 55                         PUSH  BP             ; SAVE POINTER
031B CD 05                     INT   5H             ; ISSUE PRINT SCREEN INTERRUPT
031D 50                         POP   BP             ; RESTORE POINTER
031E E9 01E7 R                 JMP   K27              ; GO BACK WITHOUT EO1 OCCURRING

0321 K46:                      ; NOT-PRINT-SCREEN
0321 3C 3B                     CMP   AL,59          ; FUNCTION KEYS
0323 72 06                     JB    K47              ; NOT-UPPER-FUNCTION
0325 BB 0000 E                 MOV   BX,OFFSET K12  ; UPPER CASE PSEUDO SCAN CODES
0328 E9 03CC R                 JMP   K63              ; TRANSLATE_SCAN

0328 K47:                      ; NOT-UPPER-FUNCTION
0328 BB 0000 E                 MOV   BX,OFFSET K11  ; POINT TO UPPER CASE TABLE
032E EB 41                     JMP   SHORT K56      ; OK, TRANSLATE THE CHAR

;----- KEYPAD KEYS, MUST TEST NUM LOCK FOR DETERMINATION

0330 K48:                      ; KEYPAD-REGION
0330 F6 06 0017 R 20           TEST  KB_FLAG,NUM_STATE ; ARE WE IN NUM_LOCK
0332 75 21                     JNZ   K52              ; TEST FOR NUMLOCK
0337 F6 06 0017 R 03           TEST  KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT ; ARE WE IN SHIFT STATE
033C 75 21                     JNZ   K53              ; IF SHIFTED, REALLY NUM STATE

;----- BASE CASE FOR KEYPAD

033E K49:                      ; BASE-CASE
033E 3C 4A                     CMP   AL,74          ; SPECIAL CASE FOR A COUPLE OF KEYS
0340 74 0C                     JE    K50              ; MINUS
0342 3C 4E                     CMP   AL,78          ; PLUS
0343 74 0D                     JE    K51              ; PLUS
0346 C0 17                     SUB   AL,71          ; CONVERT ORIGIN
0348 BB 0000 E                 MOV   BX,OFFSET K15  ; BASE CASE TABLE
0349 E9 03CE R                 JMP   K64              ; CONVERT TO PSEUDO SCAN

034E B8 4A2D                   K50:  MOV   AX,74*256+'-' ; MINUS
0351 EB 22                     JMP   SHORT K57      ; BUFFER_FILL

0353 B8 4E2B                   K51:  MOV   AX,78*256+'+' ; PLUS
0356 EB 1D                     JMP   SHORT K57      ; BUFFER_FILL

;----- MIGHT BE NUM LOCK, TEST SHIFT STATUS

0358 K52:                      ; ALMOST-NUM-STATE
0358 F6 06 0017 R 03           TEST  KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT ; SHIFTED TEMP OUT OF NUM STATE
035D 75 DF                     JNZ   K49              ; SHIFTED TEMP OUT OF NUM STATE

035F K53:                      ; REALLY_NUM_STATE
035F 2C 46                     SUB   AL,70          ; CONVERT ORIGIN
0361 BB 0000 E                 MOV   BX,OFFSET K14  ; NUM STATE TABLE
0364 EB 0B                     JMP   SHORT K56      ; TRANSLATE_CHAR

;----- PLAIN OLD LOWER CASE

0366 K54:                      ; NOT-SHIFT
0366 3C 3B                     CMP   AL,59          ; TEST FOR FUNCTION KEYS
0368 72 04                     JB    K55              ; NOT-LOWER-FUNCTION
036A BB 00                     MOV   AL,0             ; SCAN CODE IN AH ALREADY
036C EB 07                     JMP   SHORT K57      ; BUFFER_FILL

036E K55:                      ; NOT-LOWER-FUNCTION
036E BB 0000 E                 MOV   BX,OFFSET K10  ; LC TABLE

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0371 FE C8 ; TRANSLATE-CHAR
0373 2E: D7 ; CONVERT ORIGIN
; CONVERT THE SCAN CODE TO ASCII

;----- PUT CHARACTER INTO BUFFER

0375 3C FF ; BUFFER-FILL
0377 74 1F ; IS THIS AN IGNORE CHAR
0379 80 FC FF ; YES, DO NOTHING WITH IT
037C 74 1A ; LOOK FOR -1 PSEUDO SCAN
; NEAR_INTERRUPT_RETURN

;----- HANDLE THE CAPS LOCK PROBLEM

037E F6 06 0017 R 40 ; BUFFER-FILL-NOTES
0383 74 20 ; ARE WE IN CAPS LOCK STATE
; SKIP IF NOT

;----- IN CAPS LOCK STATE

0385 F6 06 0017 R 03 ; TEST KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT ; TEST FOR SHIFT STATE
038A 74 0F ; JZ K60 ; IF NOT SHIFT, CONVERT LOWER TO UPPER

;----- CONVERT ANY UPPER CASE TO LOWER CASE

038C 3C 41 ; CMP AL,'A' ; FIND OUT IF ALPHABETIC
038E 15 ; JB K61 ; NOT_CAPS_STATE
0390 3C 5A ; CMP AL,'Z' ; NOT_CAPS_STATE
0392 77 11 ; JA K61 ; NOT_CAPS_STATE
0394 04 20 ; ADD AL,'a'-'A' ; CONVERT TO LOWER CASE
0396 EB 0D ; JMP SHORT K61 ; NOT_CAPS_STATE

0398 E9 01E2 R ; K59: JMP K26 ; NEAR_INTERRUPT_RETURN
; INTERRUPT_RETURN

;----- CONVERT ANY LOWER CASE TO UPPER CASE

039B 3C 61 ; K60: CMP AL,'a' ; LOWER-TO-UPPER
039D 72 06 ; JB K61 ; FIND OUT IF ALPHABETIC
039F 3C 7A ; CMP AL,'z' ; NOT_CAPS_STATE
03A1 77 02 ; JA K61 ; NOT_CAPS_STATE
03A3 2C 20 ; SUB AL,'a'-'A' ; CONVERT TO UPPER CASE

03A5 8B 1E 001C R ; K61: MOV BX,BUFFER_TAIL ; NOT-CAPS-STATE
03A9 8B F3 ; MOV SI,BX ; GET THE END POINTER TO THE BUFFER
03AB EB 007F R ; CALL K4 ; SAVE THE VALUE
03AD 50 0001A R ; CMP AL,BUFFER_HEAD ; ADVANCE THE TAIL
03B2 74 22 ; JE K62 ; MAKE SURE TAIL WRAPPED AROUND
03B4 89 04 ; MOV [SI],AX ; BUFFER_FULL_BEEP
03B6 89 1E 001C R ; MOV BUFFER_TAIL,BX ; STORE THE VALUE
03B8 FA ; CLI ; MOVE THE POINTER UP
03B9 8D 20 ; MOV AL,E01 ; TURN OFF INTERRUPTS
03BD E6 20 ; OUT 020H,AL ; END INTERRUPT COMMAND
03BF B0 AE ; MOV AL,ENA_KBD ; SEND COMMAND TO INTERRUPT CONTROL PORT
03C1 E8 0498 R ; CALL SHIP_IT ; INSURE KEYBOARD IS ENABLED
03C4 B8 9102 ; MOV AX,09102H ; EXECUTE ENABLE
03C7 CD 15 ; INT 15H ; MOVE IN POST CODE & TYPE
03C9 E9 01EC R ; JMP K27A ; PERFORM OTHER FUNCTION
; INTERRUPT_RETURN

;----- TRANSLATE SCAN FOR PSEUDO SCAN CODES

03CC 2C 3B ; K63: SUB AL,59 ; TRANSLATE-SCAN
03CE 2E: D7 ; XLAT CS:K9 ; CONVERT SCANS TO FUNCTION KEYS
03D0 8A E0 ; MOV AH,AL ; CTL TABLE SCAN
03D2 B0 00 ; MOV AL,0 ; PUT VALUE INTO AH
03D4 EB 9F ; JMP K57 ; ZERO ASCII CODE
; PUT IT INTO THE BUFFER

03D6 ;----- KB_INT_1 ENDP

03D8 80 20 ; K62: MOV AL,E01 ; ENABLE INTR. CTL. CHIP
03D9 E6 20 ; OUT INTAA0,AL ; NUMBER OF CYCLES FOR 1/8 SECOND TONE
03DA BB 0082 ; MOV BX,82H ; GET CONTROL INFORMATION
03DB E4 61 ; IN AL,KB_CTL ; SAVE
03DF 50 ; PUSH AX ; BEEP-CYCLE
03E0 24 FC ; K65: AND AL,0FCH ; TURN OFF TIMER GATE AND SPEAKER DATA
03E2 EB 00 ; JMP SHORT S+2 ; 10 DEAY
03E3 E6 61 ; OUT CTLT,AL ; OUTPUT TO CONTROL
03E5 B9 00CE ; MOV CX,OCEH ; HALF CYCLE TIME FOR TONE
03E9 E2 FE ; K66: LOOP K66 ; SPEAKER OFF
03EB OC 02 ; OR AL,2 ; TURN ON SPEAKER BIT
03ED E6 61 ; OUT KB_CTL,AL ; OUTPUT TO CONTROL
03F1 B9 00E5 ; MOV CX,0EH ; COUNT UP COUNT
03F2 E2 FE ; K67: LOOP K67 ; ANOTHER HALF CYCLE
03F4 4B ; DEC BX ; TOTAL TIME COUNT
03F5 75 E9 ; JNZ K65 ; DO ANOTHER CYCLE
03F7 58 ; POP AX ; RECOVER CONTROL
03F8 E6 61 ; OUT KB_CTL,AL ; OUTPUT THE CONTROL
03FA E9 01E7 R ; JMP K27 ; EXIT

;----- SND_DATA

THIS ROUTINES HANDLES TRANSMISSION OF COMMAND AND DATA BYTES
TO THE KEYBOARD AND RECEIPT OF ACKNOWLEDGEMENTS. IT ALSO
HANDLES ANY RETRIES IF REQUIRED

;----- SND_DATA PROC NEAR

03FD 50 ; PUSH AX ; SAVE REGISTERS
03FE 53 ; PUSH BX ; *
03FF 51 ; PUSH CX ; *
0400 F1 F8 ; MOV BH,AL ; SAVE TRANSMITTED BY FOR RETRIES
0402 B3 03 ; MOV BL,3 ; LOAD RETRY COUNT
0404 FA ; SDO: CLI ; DISABLE INTERRUPTS
0405 80 26 0097 R CF ; AND KB_FLAG_2,NOT (KB_FE+KB_FA) ; CLEAR ACK AND RESEND FLAGS

;----- WAIT FOR COMMAND TO ACCEPTED

040A 2B C9 ; SDO5: SUB CX,CX ; *
040C E4 64 ; IN AL,STATUS_PORT ; *
040E A8 02 ; TEST AL,INPT_BUF_FULL ; WAIT FOR COMMAND TO BE ACCEPTED
0410 E0 FA ; LOOPNZ SD5 ; *

0412 8A C7 ; MOV AL,BH ; REESTABLISH BYTE TO TRANSMIT
0414 E6 60 ; OUT PORT_A,AL ; SEND BYTE
0416 FB ; STI ; ENABLE INTERRUPTS
0417 B9 1A00 ; MOV CX,01A00H ; LOAD COUNT FOR 10mS+

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041A F6 06 0097 R 30
041F 75 0D
0421 E2 F7
0423 FE CB
0425 75 DD
0427 80 0E 0097 R 80
042C EB 07
042E F6 06 0097 R 10
0433 74 EE
0435 59
0436 5B
0437 58
0438 C3
0439
0439 FA
043A F6 06 0097 R 40
043F 75 47
0441 80 0E 0097 R 40
0446 80 20
0448 E6 20
044A E6 0D
044C
044C FA
044D F6 06 0097 R 40
0452 75 34
0454 80 0E 0097 R 40
0459 B0 ED
045B 00 03FD R
045C FA
045F E8 048A R
0462 80 26 0097 R F8
0467 08 06 0097 R
0468 F6 06 0097 R 80
0470 75 0B
0472 E8 03FD R
0475 FA
0476 F6 06 0097 R 80
0478 74 06
047D B0 F4
047F E8 03FD R
0482 FA
0483 80 26 0097 R 3F
0488 FB
0489 C3
048A
048A 51
048B 00 0017 R
048E 24 70
0490 B1 04
0492 D2 C0
0494 24 07
0496 59
0497 C3
0498
0498 50
0499 FA
049A 2B C9
049C
049C E8 64
049E A8 02
04A0 E0 FA
04A2 58
04A3 E6 64
04A5 FB
04A6 C3
04A7
04A7
SD1: TEST KB_FLAG_2,KB_FE+KB_FA ; SEE IF EITHER BIT SET
      SD3: JNZ SD1 ; IF SET, SOMETHING RECEIVED GO PROCESS
      ; LOOP
SD2: DEC BL ; DECREMENT RETRY COUNT
      SD3: JNZ SD0 ; RETRY TRANSMISSION
      ; OR KB_FLAG_2,KB_ERR ; TURN ON TRANSMIT ERROR FLAG
      ; SHORT SD4 ; RETRIES EXHAUSTED FORGET TRANSMISSION
SD3: TEST KB_FLAG_2,KB_FA ; SEE IF THIS IS AN ACKNOWLEDGE
      SD2: JZ SD3 ; IF NOT, GO RESEND
      ; POP CX ; RESTORE REGISTERS
      ; POP BX
      ; POP AX
      ; RET * ; RETURN, GOOD TRANSMISSION
SND_DATA ENDP

-----
;----- SND_LED -----
;----- THIS ROUTINES TURNS ON THE MODE INDICATORS. -----
;----- SND_LED PROC NEAR -----
CL1: TEST KB_FLAG_2,KB_PR_LED ; TURN OFF INTERRUPTS
      TEST KB_FLAG_2,KB_PR_LED ; CHECK FOR MODE INDICATOR UPDATE
      SL1: JNZ SL2 ; DONT UPDATE AGAIN IF UPDATE UNDERWAY
      ; OR KB_FLAG_2,KB_PR_LED ; TURN ON UPDATE IN PROCESS
      ; MOV AL,E0H ; END OF INTERRUPT COMMAND
      ; OUT 020H,AL ; SEND COMMAND TO INTERRUPT CONTROL PORT
      ; JMP SHORT SL0 ; GO SEND MODE INDICATOR COMMAND
;----- SND_LED1 -----
SL0: CLI ; TURN OFF INTERRUPTS
      TEST KB_FLAG_2,KB_PR_LED ; CHECK FOR MODE INDICATOR UPDATE
      JNZ SL1 ; DONT UPDATE AGAIN IF UPDATE UNDERWAY
      ; OR KB_FLAG_2,KB_PR_LED ; TURN ON UPDATE IN PROCESS
      ; CALL AL,LED_CMD ; LED CMD BYTE
      ; SND_DATA ; SEND DATA TO KEYBOARD
      ; CLI
      ; CALL MAKE_LED ; GO FORM INDICATOR DATA BYTE
      ; AND KB_FLAG_2,OFBH ; CLEAR MODE INDICATOR BITS
      ; OR KB_FLAG_2,AL ; SAVE PRESENT INDICATORS STATES FOR NEXT TIME
      ; TEST KB_FLAG_2,KB_ERR ; TRANSMIT ERROR DETECTED
      SL2: JNZ SL3 ; IF YES, BYPASS SECOND BYTE TRANSMISSION
      ; CALL SND_DATA ; SEND DATA TO KEYBOARD
      ; CLI ; TURN OFF INTERRUPTS
      ; TEST KB_FLAG_2,KB_ERR ; TRANSMIT ERROR DETECTED
      ; JZ SL3 ; IF NOT, DONT SEND AN ENABLE COMMAND
      ; MOV AL,KB_ENABLE ; GET KEYBOARD CSA ENABLE COMMAND
      ; CALL SND_DATA ; SEND DATA TO KEYBOARD
      ; CLI ; TURN OFF INTERRUPTS
      ; AND KB_FLAG_2,NOT(KB_PR_LED) ; TURN OFF MODE INDICATOR
      ; OR KB_FLAG_2,KB_ERR ; TURN ON MODE INDICATOR
      ; UPDATE AND TRANSMIT ERROR FLAG
      ; STI ; ENABLE INTERRUPTS
      ; RET ; RETURN TO CALLER
SND_LED ENDP

-----
;----- MAKE_LED -----
;----- THIS ROUTINES FORMS THE DATA BYTE NECESSARY TO TURN ON/OFF THE MODE INDICATORS -----
;----- MAKE_LED PROC NEAR -----
PUSH CX
      MOV AL,KB_FLAG ; SAVE CX
      AND AL,CAPS_STATE+NUM_SCROLL_STATE ; GET CAPS & NUM LOCK INDICATORS
      AND AL,SCROLL_STATE ; ISOLATE INDICATORS
      MOV CL,AL ; SHIFT COUNT
      ROL AL,CL ; SHIFT BITS OVER TO TURN ON INDICATORS
      AND AL,07H ; MAKE SURE ONLY MODE BITS ON
      POP CX
      RET ; RETURN TO CALLER
MAKE_LED ENDP

-----
;----- SHIP_IT -----
;----- THIS ROUTINES HANDLES TRANSMISSION OF COMMAND AND DATA BYTES TO THE KEYBOARD CONTROLLER. -----
;----- SHIP_IT PROC NEAR -----
PUSH AX ; SAVE DATA TO SEND
      ; WAIT FOR COMMAND TO BE ACCEPTED
      ; CLI ; DISABLE INTERRUPTS
      ; SUB CX,CX ; CLEAR COUNTER
S10: IN AL,STATUS_PORT ; GET STATUS PORT
      TEST AL,INPT_BUF_FULL ; SEND TO KEYBOARD CONTROLLER
      LOOPNZ S10 ; ENABLE INTERRUPTS AGAIN
      ; POP AX ; RETURN TO CALLER
      ; OUT STATUS_PORT,AL ; RETURN TO CALLER
      ; STI
      ; RET
SHIP_IT ENDP
CODE ENDS
END

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TITLE 09/09/83 PRINT BIOS
LIST
INCLUDE SEGMENT.SRC
CODE SEGMENT BYTE PUBLIC
C

EXTRN DDS:NEAR
PUBLIC PRINTER_10_1
--- INT 17 -----
; PRINTER_IO
; THIS ROUTINE PROVIDES COMMUNICATION WITH THE PRINTER
INPUT
    (AH)=0 PRINT THE CHARACTER IN (AL)
    ON RETURN, AH=1 IF CHARACTER COULD NOT BE PRINTED (TIME OUT)
    OTHER BITS SET AS ON NORMAL STATUS CALL
    (AH)=1 INITIALIZE THE PRINTER PORT
    RETURNS WITH (AH) SET WITH PRINTER STATUS
    (AH)=2 READ THE PRINTER STATUS INTO (AH)
    7 6 5 4 3 2-1 0 TIME OUT
    | | | | | | |
    | | | | | | 1 = UNUSED
    | | | | | | 1 = I/O ERROR
    | | | | | | 1 = SELECTED
    | | | | | | 1 = OUT OF PAPER
    | | | | | | 1 = ACKNOWLEDGE
    | | | | | | 1 = NOT BUSY

    (DX) = PRINTER TO BE USED (0,1,2) CORRESPONDING TO ACTUAL VALUES
    IN PRINTER_BASE AREA
    DATA AREA PRINTER_BASE CONTAINS THE BASE ADDRESS OF THE PRINTER CARD(S)
    AVAILABLE (LOCATED AT BEGINNING OF DATA SEGMENT, 408H ABSOLUTE, 3 WORDS)

    DATA AREA PRINT_TIM_OUT (BYTE) MAY BE CHANGE TO CAUSE DIFFERENT
    TIME OUT WAITS. DEFAULT=20 * 4

REGISTERS
    AH IS MODIFIED
    ALL OTHERS UNCHANGED

ASSUME CS:CODE, DS:DATA

0000  FB
0001  1E
0002  52
0003  56
0004  51
0005  53
0006  E8 0000 E
0009  B8 F2
000B  8A 90 0078 R
000F  D1 E6
0011  8B 90 0008 R
0015  74 3C
0017  74 0C
0019  0A E4
001B  74 0E
001D  FE CC
001F  74 54
0021  FE CC
0023  74 3C
0025  5B
0026  59
0027  5E
0028  5A
0029  1F
002A  CF

PRINTER_10_1 PROC FAR ; ENTRY POINT FOR ORG 00FD2H
    STI             ; INTERRUPTS BACK ON
    PUSH DS          ; SAVE SEGMENT
    PUSH DX
    PUSH SI
    PUSH CX
    PUSH BX
    CALL DDS
    MOV SI,DX        ; GET PRINTER PARM
    MOV BL,PRINT_TIM_OUT[SI] ; LOAD TIMEOUT VALUE
    SHL SI,1          ; WORD OFFSET INTO TABLE
    MOV DX,PRINTER_BASE[SI] ; GET BASE ADDRESS FOR PRINTER CARD
    OR DX,DX          ; TEST FOR ZERO, INDICATING NO PRINTER
    JZ B1             ; RETURN
    AH,AH            ; TEST FOR (AH)=0
    JZ B2             ; PRINT_AL
    DEC AH           ; TEST FOR (AH)=1
    JZ B3             ; INIT_PRNT
    DEC AH           ; TEST FOR (AH)=2
    JZ B5             ; PRINTER STATUS
    RET              ; RETURN

B1:   POP BX
    POP CX
    POP SI            ; RECOVER REGISTERS
    POP DX
    POP DS            ; RECOVER REGISTERS
    IRET

;----- PRINT THE CHARACTER IN (AL)

002B  50
002C  EE
002D  42

B2:   PUSH AX          ; SAVE VALUE TO PRINT
    OUT DX,AL         ; OUTPUT CHAR TO PORT
    INC DX            ; POINT TO STATUS PORT

;----- CHECK FOR PRINTER BUSY

002E  53
002F  EC
0030  A8 80
0032  75 05

B3:   PUSH BX          ; GET STATUS
    IN AL,DX          ; IS THE PRINTER CURRENTLY BUSY
    TEST AL,80H        ; OUT_STROBE
    JNZ B2_A

;----- INT 15 DEVICE BUSY

0034  B8 90FE
0037  CD 15

MOV AX,90FEH ; FUNCTION 90 PRINTER ID
INT 15H      ; 

;-----ADJUST OUTER LOOP COUNT

0039  2A FF
003B  D1 D3
003D  D1 D3

B2_A:  SUB BH,BH        ; CLEAR BH
    RCL BX,1          ; MULT BY 4
    RCL BX,1          ; 

;-----WAIT BUSY

0041  EC
0042  8A E0
0044  AB 80
0046  75 0E
0048  E2 F7
004A  4B
004B  75 F2

B3:   SUB CX,CX        ; INNER LOOP (64K)
B3_1:  IN AL,DX          ; GET STATUS
    MOV AH,AL          ; STATUS TO AH ALSO
    TEST AL,80H        ; IS THE PRINTER CURRENTLY BUSY
    JNZ B4             ; OUT_STROBE
    LOOP B3_1          ; LOOP IF NOT
    DEC BX             ; DROP OUTER LOOP COUNT -----
    JNZ B3             ; MAKE ANOTHER PASS IF NOT ZERO

004D  5B

POP BX          ; RESTORE BX -----
;-----SET ERROR FLAG
;-----TURN OFF THE UNUSED BITS
;-----RETURN WITH ERROR FLAG SET
;-----RESTORE BX -----
;-----OUT_STROBE

004E  80 CC 01
0051  B0 E4 F9
0054  EB 17
0056  5B

B4:   OR AH,1           ; SET ERROR FLAG
    AND AH,0F9H        ; TURN OFF THE UNUSED BITS
    JMP SHORT B7        ; RETURN WITH ERROR FLAG SET
    POP BX             ; RESTORE BX -----
    OUT AL,ODH          ; SET THE STROBE HIGH
    INC DX
    OUT DX,AL          ; SET THE STROBE LOW
    MOV AL,0CH          ; IO DELAY
    JMP SHORT $+2
    OUT DX,AL
    POP AX             ; RECOVER THE OUTPUT CHAR

;----- PRINTER STATUS

0061
0061  50
0062
0062  B8 94 0008 R

B5:   PUSH AX          ; SAVE AL REG
B6:   MOV DX,PRINTER_BASE[SI]

```

```

0066 42           INC    DX
0067 EC           IN     AL,DX      ; GET PRINTER STATUS
0068 8A E0           MOV    AH,AL
0069 80 E4 F8       AND    AH,0F8H   ; TURN OFF UNUSED BITS
006D          B7:    POP    DX
006D 5A           MOV    AL,DL      ; STATUS SET
006E 8A C2           MOV    AH,48H   ; RECOVER AL REG
0070 80 F4 48       XOR    AH,48H   ; GET CHARACTER INTO AL
0073 EB B0           JMP    B1       ; FLIP A COUPLE OF BITS
0073                                     ; RETURN FROM ROUTINE

;----- INITIALIZE THE PRINTER PORT

0075
0075 50           B8:    PUSH   AX      ; SAVE AL
0075 42           INC    DX      ; POINT TO OUTPUT PORT
0077 42           INC    DX
0078 B0 08           MOV    AL,8      ; SET INIT LINE LOW
007A EE           OUT    DX,AL
007B B8 0FA0       MOV    AX,1000*4 ; -----
007C          B9:    DEC    AX      ; INIT_LOOP
007E 48           JNZ    B9      ; LOOP FOR RESET TO TAKE
007F 75 FD           MOV    AL,0CH   ; INIT_LOOP
0081 B0 0C           MOV    AL,OC
0083 EE           OUT    DX,AL   ; NO INTERRUPTS, NON AUTO LF, INIT HIGH
0084 EB DC           JMP    BC      ; PRT_STATUS_1
0086          PRINTER_101    ENDP
0086          CODE    ENDS
0086          END

```

TITLE DATE 07/06/83 RS232  
 LLIST  
 C INCLUDE SEGMENT.SRC  
 C CODE SEGMENT BYTE PUBLIC  
 C  
 EXTRN DDS:NEAR  
 EXTRN AI:NEAR  
 PUBLIC RS232\_10\_1

;----- INT 14 -----  
 :RS232\_10 THIS ROUTINE PROVIDES BYTE STREAM I/O TO THE COMMUNICATIONS PORT ACCORDING TO THE PARAMETERS.  
 (AH)=0 INITIALIZE THE COMMUNICATIONS PORT  
 (AL) HAS PARMs FOR INITIALIZATION

7	6	5	4	3	2	1	0
----	BAUD RATE --		PARITY--		STOPBIT		WORD LENGTH--
000	- 110		X0 - NONE		0 - 1	10 - 7 BITS	
001	- 150		01 - ODD		1 - 2	11 - 8 BITS	
010	- 300		11 - EVEN				
011	- 600						
100	- 1200						
101	- 2400						
110	- 4800						
111	- 9600						

ON RETURN, CONDITIONS SET AS IN CALL TO COMMO STATUS (AH=3)  
 (AH)=1 SEND THE CHARACTER IN AL OVER THE COMMOM LINE  
 (AL) REGISTER IS PRESERVED  
 ON EXIT, BIT 7 OF AH IS SET IF THE ROUTINE WAS UNABLE TO  
 TO TRANSMIT THE BYTE OF DATA OVER THE LINE.  
 IF BIT 7 OF AH IS NOT SET, THE  
 REMAINDER OF AH IS SET AS IN A STATUS REQUEST,  
 RETURNING THE CURRENT STATUS OF THE LINE.  
 (AH)=2 RECEIVE A CHARACTER IN (AL) FROM COMMO LINE BEFORE  
 RETURNING TO CALLER  
 ON EXIT, AH HAS THE CURRENT LINE STATUS, AS SET BY THE  
 THE STATUS ROUTINE, EXCEPT THAT THE ONLY BITS  
 THAT ARE THE ERRORS (7,4,3,2,1)  
 IF AH HAS BIT 7 SET (TIME OUT) THE REMAINING  
 BITS ARE NOT PREDICTABLE.  
 THUS, AH IS NON ZERO ONLY WHEN AN ERROR OCCURRED.  
 (AH)=3 RETURN THE COMMO PORT STATUS IN (AX)  
 AH CONTAINS THE LINE CONTROL STATUS  
 BIT 7 = MODEM OUT  
 BIT 6 = TRAN SHIFT REGISTER EMPTY  
 BIT 5 = TRAN HOLDING REGISTER EMPTY  
 BIT 4 = BREAK DETECT  
 BIT 3 = FRAMING ERROR  
 BIT 2 = PARITY ERROR  
 BIT 1 = OVER ERROR  
 BIT 0 = DATA READY  
 AL CONTAINS THE MODEM STATUS  
 BIT 7 = RECEIVED LINE SIGNAL DETECT  
 BIT 6 = RING INDICATOR  
 BIT 5 = OVER SIGNAL  
 BIT 4 = CLEAR TO SEND  
 BIT 3 = DELTA RECEIVE LINE SIGNAL DETECT  
 BIT 2 = TRAILING EDGE RING DETECTOR  
 BIT 1 = DELTA DATA SET READY  
 BIT 0 = DELTA CLEAR TO SEND

(DX) = PARAMETER INDICATING WHICH RS232 CARD (0,1 ALLOWED)  
 DATA AREA RS232\_BASE CONTAINS THE BASE ADDRESS OF THE 8250 ON THE CARD  
 LOCATION 400H CONTAINS UP TO 4 RS232 ADDRESSES POSSIBLE  
 DATA AREA LABLE RS232\_TIM\_OUT (BYTE) CONTAINS OUTER LOOP COUNT  
 VALUE FOR TIMEOUT (DEFAULT=1)

OUTPUT AX MODIFIED ACCORDING TO PARMs OF CALL  
 ALL OTHERS UNCHANGED

ASSUME CS:CODE,DS:DATA

0000 RS232\_10\_1 PROC FAR  
 ;----- VECTOR TO APPROPRIATE ROUTINE

STI		; INTERRUPTS BACK ON
PUSH DS		; SAVE SEGMENT
PUSH DX		
PUSH SI		
PUSH DI		
PUSH CX		
PUSH BX		
MOV SI,DX		: RS232 VALUE TO SI
MOV DI,DX		; AND TO DI (FOR TIMEOUTS)
SIL S1,1		; WORD OFFSET
CALL DOS		
MOV DX,RS232_BASE[SI]		: GET BASE ADDRESS
OR DX,DX		; TEST FOR 0 BASE ADDRESS
JZ A3		; RETURN
OR AH,AH		: TEST FOR (AH)=0
JZ A4		: COMMUN INIT
DEC AH		: TEST FOR (AH)=1
JZ A5		; AND
DEC AH		: TEST FOR (AH)=2
JZ A12		: RECEIVE INTO AL
A2:	DEC AH	: TEST FOR (AH)=3
JNZ A3		
JMP A18		: COMMUNICATION STATUS
A3:	POP BX	; RETURN FROM RS232
POP CX		
POP D1		
POP SI		
POP DX		
POP DS		
IRET		; RETURN TO CALLER, NO ACTION

;----- INITIALIZE THE COMMUNICATIONS PORT

A4:  
 MOV AH,AL ; SAVE INIT PARMs IN AH  
 ADD DX,3 ; POINT TO 8250 CONTROL REGISTER  
 MOV AL,BOH  
 OUT DX,AL ; SET DLAB=1

;----- DETERMINE BAUD RATE DIVISOR

003A 8A D4	MOV DL,AH	; GET PARMs TO DL
003C B1 04	MOV CL,4	
003E D2 C2	ROL DL,CL	
0040 81 E2 000E	AND DX,OEH	; ISOLATE THEM

```

0044 BF 0000 E      MOV    DI,OFFSET A1          ; BASE OF TABLE
0047 03 FA          ADD    DI,DX              ; PUT INTO INDEX REGISTER
0049 BB 94 0000 R    MOV    DX,RS232_BASE[SI] ; POINT TO HIGH ORDER OF DIVISOR
004D 42              INC    AL                ; GET HIGH ORDER OF DIVISOR
004E 2E: 8A 45 01    MOV    AL,CS:[DI]+1       ; SET MS OF DIV TO 0
0052 EE              OUT    DX,AL              ; SET LOW OF DIVISOR
0053 4A              DEC    DX                ; IO DELAY
0054 2E: 00          JMP    SHORT $+2         ; GET LOW ORDER OF DIVISOR
0056 EE: 8A 05        MOV    AL,CS:[DI]         ; SET LOW OF DIVISOR
0059 EE              OUT    DX,AL              ; GET PARS BACK
005A 83 C2 03        ADD    DX,3               ; STRIP OFF THE BAUD BITS
005D 8A C4          MOV    AL,AH              ; LINE CONTROL TO 8 BITS
005F 24 1F          AND    AL,01FH            ; STRIP OFF THE BAUD BITS
0060 4C              OUT    DX,AL              ; LINE CONTROL TO 8 BITS
0062 4A              DEC    DX                ; IO DELAY
0064 EB 00          JMP    SHORT $+2         ; IO DELAY
0066 B0 00          MOV    AL,0               ; INTERRUPT_ENABLES ALL OFF
0068 EE              OUT    DX,AL              ; COM_STATUS
0069 EB 4B          JMP    SHORT A18           ; COM_STATUS

;----- SEND CHARACTER IN (AL) OVER COMMOM LINE

A5:   PUSH  AX          ; SAVE CHAR TO SEND
006B 50              ADD    DX,4               ; MODEM CONTROL REGISTER
006C 83 C2 04        MOV    AL,3               ; DTR AND RTS
006F B0 03          OUT    DX,AL              ; DATA TERMINAL READY, REQUEST TO SEND
0071 EE              INC    DX                ; MODEM STATUS REGISTER
0072 42              INC    DX                ; MODEM STATUS REGISTER
0074 B7 30          MOV    BH,30H             ; DATA SET READY & CLEAR TO SEND
0076 E8 0005 R        CALL   WAIT_FOR_STATUS ; ARE BOTH TRUE
0079 74 08          JE     A9                ; YES, READY TO TRANSMIT CHAR
007B 00              RET    AX                ; RETURN

A7:   POP   CX          ; RELOAD DATA BYTE
007B 59              MOV    AL,CL              ; INDICATE TIME OUT
007C 8A C1          OR    AH,80H             ; RETURN
007E 80 CC 80        JMP    A3                ; YES, READY TO TRANSMIT CHAR
0081 EB A8          ; RETURN

A9:   PUSH  AX          ; CLEAR_TO_SEND
0083 4A              DEC    DX                ; LINE STATUS REGISTER
0084 A10:             DEC    DX                ; WAIT_SEND
0085 B7 20          MOV    BH,20H             ; IS TRANSMITTER READY
0086 E8 0005 R        CALL   WAIT_FOR_STATUS ; TEST FOR TRANSMITTER READU
0087 75 F0          JNZ    A7                ; RETURN WITH TIME OUT SET
0088 B3 EA 05        SUB    DX,5               ; OUT_CHAR
0089 59              POP    CX                ; DATA PORT
008A 8A C1          MOV    AL,CL              ; MOVE CHAR TO AL FOR OUT, STATUS IN AH
008B EE              OUT    DX,AL              ; OUTPUT CHARACTER
008C EB 97          JMP    A3                ; RETURN

;----- RECEIVE CHARACTER FROM COMMOM LINE

A12:  ADD   DX,4          ; MODEM CONTROL REGISTER
0091 83 C2 04        MOV    AL,1               ; DATA TERMINAL READY
0092 B0 01          OUT    DX,AL              ; MODEM STATUS REGISTER
0093 42              INC    DX                ; MODEM STATUS REGISTER
0094 42              INC    DX                ; MODEM STATUS REGISTER
A13:  ADD   DX,4          ; WAIT_DSR
0095 B7 20          MOV    BH,20H             ; DATA_SET_READY
0096 E8 0005 R        CALL   WAIT_FOR_STATUS ; TEST FOR DSR
0097 75 DB          JNZ    A8                ; RETURN WITH ERROR
0098 A0              INC    DX                ; WAIT_DSR_END
0099 4A              DEC    DX                ; LINE STATUS REGISTER
0100 A1              DEC    DX                ; WAIT_DSR_END
0101 4A              DEC    DX                ; RECEIVE_BUFFER_FULL
0102 A4              MOV    BH,1               ; TEST FOR REC. BUFF. FULL
0103 E8 0005 R        CALL   WAIT_FOR_STATUS ; SET TIME OUT ERROR
0104 75 D3          JNZ    A8                ; GET_CHAR
0105 A0AB             AND    AH,00011110B       ; TEST FOR ERROR CONDITIONS ON RCV CHAR
0106 80 E4 1E          MOV    DX,RS232_BASE[SI] ; DATA PORT
0107 B8 94 0000 R    IN     AL,DX              ; GET LINE CONTROL STATUS
0108 EC              INC    DX                ; POINT TO MODEM STATUS REGISTER
0109 E0              IN     AL,DX              ; GET MODEM CONTROL STATUS
0110 C1              JMP    A3                ; RETURN

;----- COMMOM PORT STATUS ROUTINE

A18:  MOV    DX,RS232_BASE[SI] ; CONTROL PORT
0111 8B 94 0000 R    ADD    DX,5               ; GET LINE CONTROL STATUS
0112 B3 C2 05        IN     AL,DX              ; PUT IN AH FOR RETURN
0113 00DB             MOV    AH,AL              ; POINT TO MODEM STATUS REGISTER
0114 EC              INC    DX                ; GET MODEM CONTROL STATUS
0115 C0              IN     AL,DX              ; GET MODEM CONTROL STATUS
0116 C2              JMP    A3                ; RETURN

;----- WAIT FOR STATUS ROUTINE
; ENTRY: DS1=STATUS[SI], DS2=LOOK FOR,
;        DX=ADDR_OF_STATUS_REG
; EXIT: ZERO FLAG ON = STATUS FOUND
;        ZERO FLAG OFF = TIMEOUT.
;        AH=LAST STATUS READ
;----- WAIT_FOR_STATUS PROC NEAR
0117 00C5             MOV    BL,RS232_TIM_OUT[DI] ; LOAD OUTER LOOP COUNT

;-----ADJUST OUTER LOOP COUNT
;-----WFS0: SUB    CX,CX          ; SAVE BP -----
0118 00C9 55          PUSH  BP              ; SAVE BP -----
0119 00CA 53          PUSH  BX              ; SAVE BX -----
0120 00CB 5D          POP   BP              ; USE BP FOR OUTER LOOP COUNT
0121 00CC 81 E5 00FF   AND    BP,0FFFH        ; STRIP HIGH BITS
0122 00D0 D1 D5        RCL    BP,1             ; MULT OUTER BY 4
0123 00D2 D1 D5        RCL    BP,1             ; -----


00D4 2B C9          WFS0: SUB    CX,CX          ;GET STATUS
00D5 EC              WFS1: IN     AL,DX          ; MOVE TO AH
00D6 B8 E0          AND    AH,AL              ; ISOLATE BITS TO TEST
00D7 22 07          CMP    AL,BH              ; EXACTLY = TO MASK
00D8 3A C7          JE     WFS1END         ; RETURN WITH ZERO FLAG ON
00D9 74 07          LOOP   WFS1END         ; TRY AGAIN
00D9 F2 F5          DEC    BH                ; -----
00E0 4D              JNZ    WFS0             ; -----
00E1 F2 F0          OR     BH,BH            ; SET ZERO FLAG OFF
00E2 0A FF          ; -----
00E3 WFS1END:        POP   BP              ; RESTORE BP -----
00E4 5D              RET    ; -----
00E5 C3              WAIT_FOR_STATUS ENDP
00E6 RS232_IO_1      RS232_IO_1      ENDP

00E8 CODE  ENDS

```

TITLE 08/18/83 VIDEO1  
 LIST  
 ; includes are posteque.src, dseg.src

```

0000      INCLUDE SEGMENT.SRC
C       CODE SEGMENT BYTE PUBLIC
C
  EXTRN  DDS:NEAR
  EXTRN  M5:WORD
  EXTRN  M6:BYTE
  EXTRN  M7:BYTE
  EXTRN  CRT CHAR GEN:NEAR
  EXTRN  BEEP:NEAR

PUBLIC  VIDEO_10_1
M4      EQU    0010H
;----- INT 10 -----
VIDEO_10
;----- THESE ROUTINES PROVIDE THE CRT INTERFACE
THE FOLLOWING FUNCTIONS ARE PROVIDED:
(AH)=0 SET MODE (AL) CONTAINS MODE VALUE
  (AL)=0 40X25 BW (POWER ON DEFAULT)
  (AL)=1 40X25 COLOR
  (AL)=2 80X25 BW
  (AL)=3 80X25 COLOR
GRAPHICS MODES
  (AL)=4 320X200 COLOR
  (AL)=5 320X200 BW
  (AL)=6 640X200 COLOR
CRT MODES 40X25 &BW CARD (USED INTERNAL TO VIDEO ONLY)
*** NOTES -BW MODES OPERATE SAME AS COLOR MODES, BUT COLOR
BURST IS NOT ENABLED
-CURSOR IS NOT DISPLAYED IN GRAPHICS MODE

(AH)=1 SET CURSOR TYPE
  (CH) = BITS 4-0 = START LINE FOR CURSOR
        ** HARDWARE WILL ALWAYS CAUSE BLINK
        ** SETTING BIT 5 OR 6 WILL CAUSE ERRATIC BLINKING
        OR NO CURSOR AT ALL
  (CL) = BITS 4-0 = END LINE FOR CURSOR
  (DH,DL) = ROW, COLUMN (0,0) IS UPPER LEFT
  (BH) = PAGE NUMBER (MUST BE 0 FOR GRAPHICS MODES)

(AH)=3 READ CURSOR POSITION
  (BH) = PAGE NUMBER (MUST BE 0 FOR GRAPHICS MODES)
ON EXIT (DH,DL) = ROW, COLUMN OF CURRENT CURSOR
  (CH,CL) = CURSOR MODE CURRENTLY SET

(AH)=4 READ LIGHT PEN POSITION
ON EXIT:
  (AH) = 0 -- LIGHT PEN SWITCH NOT DOWN/NOT_TRIGGERED
  (AH) = 1 -- VALID LIGHT PEN VALUE IN REGISTERS
  (DH,DL) = ROW, COLUMN OF CHARACTER LP POSN
  (BH) = RASTER LINE (0-199)
  (BX) = PIXEL COLUMN (0-319,639)

(AH)=5 SELECT ACTIVE DISPLAY PAGE (VALID ONLY FOR ALPHA MODES)
  (AL)=NEW PAGE VALUE (0-7 FOR MODES 0&1, 0-3 FOR MODES 2&3)

(AH)=6 SCROLL ACTIVE PAGE UP
  (AL) = NUMBER LINES, INPUT LINES BLANKED AT BOTTOM OF WINDOW
        AL = 0 MEANS BLANK ENTIRE WINDOW
  (CH,CL) = ROW, COLUMN OF UPPER LEFT CORNER OF SCROLL
  (DH,DL) = ROW, COLUMN OF LOWER RIGHT CORNER OF SCROLL
  (BH) = ATTRIBUTE TO BE USED ON BLANK LINE

(AH)=7 SCROLL ACTIVE PAGE DOWN
  (AL) = NUMBER LINES, INPUT LINES BLANKED AT TOP OF WINDOW
        AL = 0 MEANS BLANK ENTIRE WINDOW
  (CH,CL) = ROW, COLUMN OF UPPER LEFT CORNER OF SCROLL
  (DH,DL) = ROW, COLUMN OF LOWER RIGHT CORNER OF SCROLL
  (BH) = ATTRIBUTE TO BE USED ON BLANK LINE

CHARACTER HANDLING ROUTINES

(AH) = 8 READ ATTRIBUTE/CHARACTER AT CURRENT CURSOR POSITION
  (BH) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
ON EXIT:
  (AL) = CHAR READ
  (AH) = ATTRIBUTE OF CHARACTER READ (ALPHA MODES ONLY)

(AH) = 9 WRITE ATTRIBUTE/CHARACTER AT CURRENT CURSOR POSITION
  (BH) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
  (CX) = COUNT OF CHARACTERS TO WRITE
  (AL) = CHAR TO WRITE
  (BL) = ATTRIBUTE OF CHARACTER (ALPHA)/COLOR OF CHAR (GRAPHICS)
        SEE NOTE ON WRITE DOT FOR BIT 7 OF BL = 1.

(AH) = 10 WRITE CHARACTER ONLY AT CURRENT CURSOR POSITION
  (BH) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
  (CX) = COUNT OF CHARACTERS TO WRITE
  (AL) = CHAR TO WRITE

FOR READ/WRITE CHARACTER INTERFACE WHILE IN GRAPHICS MODE, THE
CHARACTERS ARE FORMED FROM A CHARACTER GENERATOR IMAGE
MAINTAINED IN THE SYSTEM ROM, ONLY THE 1ST 128 CHARS
ARE CONTAINED THERE. TO READ/WRITE THE SECOND 128 CHARS,
THE FIRST 128 MUST ALREADY BE WRITTEN. THE ADDRESS (DH)
(LOCATION 0007CH) TO POINT TO THE 1K BYTE TABLE CONTAINING
THE CODE POINTS FOR THE SECOND 128 CHARS (128-255).

FOR WRITE CHARACTER INTERFACE IN GRAPHICS MODE, THE REPLICATION FACTOR
CONTAINED IN (CX) ON ENTRY WILL PRODUCE VALID RESULTS ONLY
FOR CHARACTERS CONTAINED ON THE SAME ROW. CONTINUATION TO
SUCCEEDING LINES WILL NOT PRODUCE CORRECTLY.

GRAPHICS INTERFACE
(AH) = 11 SET COLOR PALETTE
  (BH) = PALLETTE COLOR ID BEING SET (0-127)
  (BL) = COLOR VALUE TO BE USED WITH THAT COLOR ID
NOTE: FOR THE CURRENT COLOR CARD, THIS ENTRY POINT HAS
        MEANING ONLY FOR 320X200 GRAPHICS.
        COLOR ID = 0 SELLECTS THE BACKGROUND COLOR (0-15)
        COLOR ID = 1 SELLECTS THE PALLETTE TO BE USED:
          0 = GREEN(1)/RED(2)/WHITE(3)
          1 = CYAN(1)/MAGENTA(2)/WHITE(3)
        IN 40X25 OR 80X25 ALPHA MODES, THE VALUE SET FOR
        PALLETTE COLOR 0 INDICATES THE BORDER COLOR
        TO BE USED (VALUES 0-31, WHERE 16-31 SELECT THE
        HIGH INTENSITY BACKGROUND SET.

(AH) = 12 WRITE DOT
  (DX) = ROW NUMBER
  (CX) = COLUMN NUMBER
  (AL) = COLOR VALUE
        IF BIT 7 OF AL = 1, THEN THE COLOR VALUE IS EXCLUSIVE
        OR'D WITH THE CURRENT CONTENTS OF THE DOT

(AH) = 13 READ DOT
  (DX) = ROW NUMBER
  (CX) = COLUMN NUMBER
  (AL) RETURNS THE DOT READ

```

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; ASCII TELETYPE ROUTINE FOR OUTPUT
    (AH) = 1N WRITE TELETYPE TO ACTIVE PAGE
        (AL) = CHAR TO WRITE
        (BL) = FOREGROUND COLOR IN GRAPHICS MODE
        NOTE -- SCREEN WIDTH IS CONTROLLED BY PREVIOUS MODE SET

    (AH) = 15 CURRENT VIDEO STATE
        RETURNS THE CURRENT VIDEO STATE
        (AL) = MODE CURRENTLY SET ( SEE AH=0 FOR EXPLANATION)
        (AH) = NUMBER OF CHARACTER COLUMNS ON SCREEN
        (BH) = CURRENT ACTIVE DISPLAY PAGE

    (AH) = 16 RESERVED
    (AH) = 17 RESERVED
    (AH) = 18 RESERVED

    (AH) = 19 WRITE STRING
        ES:BP = - POINTER TO STRING TO BE WRITTEN
        CX = - LENGTH OF CHARACTER STRING TO WRITTEN
        DX = - CURSOR POSITION FOR STRING TO BE WRITTEN
        BH = - PAGE NUMBER

    (AL) = 0      BL = - ATTRIBUTE
                  STRING IS [CHAR,CHAR, ... ,CHAR]
                  CURSOR NOT MOVED
    (AL) = 1      BL = - ATTRIBUTE
                  STRING IS [CHAR,CHAR, ... ,CHAR]
                  CURSOR IS MOVED
    (AL) = 2      STRING IS [CHAR,ATTR,CHAR,ATTR .. ,CHAR,ATTR]
                  CURSOR IS NOT MOVED
    (AL) = 3      STRING IS [CHAR,ATTR,CHAR,ATTR .. ,CHAR,ATTR]
                  CURSOR IS MOVED

    NOTE: CARRIAGE RETURN, LINE FEED, BACKSPACE, AND BELL ARE
          TREATED AS COMMANDS RATHER THAN PRINTABLE CHARACTERS.

SS,SP,ES,DS,DX,CX,BX,SI,DI,BP PRESERVED DURING CALL
ALL OTHERS DESTROYED.

ASSUME CS:CODE,DS:DATA,ES:VIDEO_RAM
-----
```

```

PUBLIC SET_MODE
PUBLIC SET_CTYPE
PUBLIC SET_CPOS
PUBLIC SET_CURSOR
PUBLIC READ_LINER
PUBLIC ACT_DISP_PAGE
PUBLIC SCROLL_UP
PUBLIC SCROLL_DOWN
PUBLIC READ_AC_CURRENT
PUBLIC WRITE_AC_CURRENT
PUBLIC WRITE_C_CURRENT
PUBLIC SET_COLOR
PUBLIC WRITE_DOT
PUBLIC READ_DOT
PUBLIC WRITE_TTY
PUBLIC WRITE_STATE
PUBLIC VIDEO_STATE
M1   LABEL WORD ; TABLE OF ROUTINES WITHIN VIDEO I/O
0000 0071 R   DW     OFFSET SET_MODE
0002 014D R   DW     OFFSET SET_CTYPE
0004 014E R   DW     OFFSET SET_CPOS
0006 014F R   DW     OFFSET SET_CURSOR
0008 07DF R   DW     OFFSET READ_LINER
000A 01B5 R   DW     OFFSET ACT_DISP_PAGE
000C 0222 R   DW     OFFSET SCROLL_UP
000E 0265 R   DW     OFFSET SCROLL_DOWN
0010 035E R   DW     OFFSET READ_AC_CURRENT
0012 035F R   DW     OFFSET WRITE_AC_CURRENT
0014 0391 R   DW     OFFSET WRITE_C_CURRENT
0016 01D9 R   DW     OFFSET SET_COLOR
0018 046F R   DW     OFFSET WRITE_DOT
001A 045E R   DW     OFFSET READ_DOT
001C 045F R   DW     OFFSET WRITE_TTY
001E 01FF R   DW     OFFSET WRITE_STATE
0020 0144 R   DW     OFFSET VIDEO_RETURN ; Reserved
0022 0144 R   DW     OFFSET VIDEO_RETURN ; Reserved
0024 0144 R   DW     OFFSET VIDEO_RETURN ; Reserved
0026 03C3 R   DW     OFFSET WRITE_STRING ; CASE 19h, Write string
= 0028
M1L  EQU $-M1
```

```

0028                   VIDEO_IO_1    PROC NEAR ; ENTRY POINT FOR ORG 0F065H
0029                   INTI           ; INTERRUPTS BACK ON
002A 06                 CLD             ; SET DIRECTION FORWARD
002B 1E                 PUSH DS          ; SAVE SEGMENT REGISTERS
002C 52                 PUSH DX
002D 51                 PUSH CX
002E 53                 PUSH BX
002F 56                 PUSH SI
0030 57                 PUSH DI
0031 55                 PUSH BP
0032 50                 PUSH AX          ; SAVE AX VALUE
0033 84 CH               MOV AL,AH        ; GET INTO LOW BYTE
0034 82 EH               XOR AH,AH        ; ZERO HIGH BYTE
0035 D1 EO               SAL AX,1         ; #2 FOR TABLE LOOKUP
0036 81 F0               MOV S1,AX        ; PUT INTO SI FOR BRANCH
0037 3B 0028              CMP AX,M1L       ; TEST FOR WITHIN RANGE
0038 72 04               JB M2          ; BRANCH AROUND BRANCH
0039 E9 0144 R            JMP VIDEO_RETURN ; THROW AWAY THE PARAMETER
0040 58                 POP AX          ; DO NOTHING IF NOT IN RANGE
0041
0044 E8 0000 E            M2:          CALL DDS
0045 BB BB00              MOV AX,0B800H ; SEGMENT FOR COLOR CARD
0046 AA 0010 R            MOV DX,EQUIP_FLAG ; GET EQUIPMENT SETTING
0047 81 E7 0030            AND DX,1H        ; ISOLATE CRT SWITCHES
0048 83 FF 30              CMP DX,30H       ; IS SETTING FOR BW CARD?
0049 75 02               JNE M3          ; NO, GO TO M3
0050 B5 B0               MOV AH,0B0H ; SEGMENT FOR BW CARD
0051 8E CO               MOV ES,AX        ; SET UP TO POINT AT VIDEO RAM AREAS
0052 58                 POP AX          ; RECOVER VALUE
0053
0054 80 FC 13              CMP AH,13H ; TEST FOR WRITE STRING OP
0055 75 07               JNE MM3         ; NO, GO TO MM3
0056 55                 PUSH BP          ; IF IT'S WRITE STRING THEN GET THE
0057 8B EC               MOV BP,SP        ; STRINGS SEGMENT, SINCE IT GET Clobbered
0058 46 10               MOV ES,[BP].ES_POS ;
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0067 5D          POP    BP    ;
MM3:           MOV    AH,CRT_MODE ; GET CURRENT MODE INTO AH
0068 00          JMP    WORD PTR CS:[SI+OFFSET M1]
006C 2E: FF A4 0000 R
0071 VIDEO_101    ENDP

;----- SET_MODE
;----- THIS ROUTINE INITIALIZES THE ATTACHMENT TO
;----- THE SELECTED MODE. THE SCREEN IS BLANKED.
;----- INPUT   (AL) = MODE SELECTED (RANGE 0-9)
;----- OUTPUT  NONE
;----- -----
;----- SET_MODE
;----- PROC  NEAR
;----- ADDRESS OF COLOR CARD
0071 BA 03D4     MOV    DX,03D4H
0074 B3 00       MOV    BL,0
0076 83 FF 30    CMP    DI,30H
0079 75 07       JNE    M8
007B 80 07       MOV    AL,7
007D 03 E0 03B4  MOV    DX,03B4H
0080 FE 00       INC    BX
0082 EA E0       MOV    AH,AL ; SAVE MODE IN AH
0084 A2 0049 R   MOV    CRT_MODE,AL ; SAVE IN GLOBAL VARIABLE
0087 89 16 0063 R MOV    ADDR_6845,DX ; SAVE ADDRESS OF BASE
0088 1E          PUSH   DS
0089 4C 00       PUSH   AX
008A 4C 00       PUSH   DX
008B 52          ADD    DX,4
008E 83 C2 04    MOV    AL,BL ; POINT TO CONTROL REGISTER
0091 8A C3       JC    M9
0093 EE          OUT   DX,AL ; GET MODE SET FOR CARD
0094 5A          POP    DX
0095 2B C0       SUB    AX,AX ; RESET VIDEO
0097 8E D8       MOV    DS,AX ; BACK TO BASE REGISTER
0099 C5 1E 0074 R ASSUME DS:ABSO ; SET UP FOR ABSO SEGMENT
0099 58          LDS    BX,PARM_PTR ; ESTABLISH VECTOR TABLE ADDRESSING
009A          PARM_PTR
009B          AX
009E B9 0010     ASSUME DS:CODE ; GET POINTER TO VIDEO PARMS
00A1 80 FC 02    MOV    CX,M4 ; RECOVER PARMS
00A4 72 10       CMP    AH,2
00A6 03 D9       JC    M9
00A8 80 FC 04    ADD    BX,CX ; DETERMINE WHICH ONE TO USE
00A9 72 0F       CMP    AH,4
00AD 03 D9       JC    M9
00AF 80 FC 07    ADD    BX,CX ; MODE IS 0 OR 1
00B0 86 EO       CMP    AH,7 ; MODE IS 2 OR 3
00B2 72 02       JC    M9 ; MODE IS 4,5, OR 6
00B4 03 D9       ADD    BX,CX ; MOVE TO BW CARD ROW OF INIT_TABLE
;----- BX POINTS TO CORRECT ROW OF INITIALIZATION TABLE
00B6 50          PUSH   AX ; OUT_INIT
00B6          50          MOV    AH,0 ; SAVE MODE IN AH
00B7 06          PUSH   ES ; SAVE SCREEN BUFFER'S SEGMENT
00B8 33 C0       XOR    AX,AX ; ESTABLISH ADDRESSIBILITY TO ABSO
00B9 8E C0       MOV    ES,AX
00BC BB 47 0A    MOV    AX,WORD PTR [BX+10] ; GET THE CURSOR MODE FROM THE TABLE
00BF 86 EO       XCHG   AH,AL ; PUT CURSOR MODE IN CORRECT POSITION
00C1 26: A3 0460 R ASSUME ES:ABSO ; ESTABLISH ADDRESSIBILITY TO ABSO
00C5 07          MOV    ES:WORD PTR DATA_AREA[CURSOR_MODE-DATA],AX ; RESTORE THE SCREEN BUFFER'S SEGMENT
00C6 32 E4       XOR    AH,AH ; AH WILL SERVE AS REGISTER NUMBER DURING LOOP
;----- LOOP THROUGH TABLE, OUTPUTTING REG ADDRESS, THEN VALUE FROM TABLE
00C8 8A C4       XOR    DI,DI ; INIT_LOOP
00CA EE          MOV    AL,AH ; GET 6845 REGISTER NUMBER
00CC F2          OUT   DX,AL
00CD 4C 00       INC    DX ; POINT TO DATA PORT
00CE 8A 07       MOV    AH,0 ; NEXT REGISTER VALUE
00DD EE          INC    BX ; GET TABLE VALUE
00E1 43          OUT   DX,AL ; OUT TO CHIP
00E2 4A          INC    BX ; NEXT IN TABLE
00E3 E2 F3       DEC    DX ; BACK TO POINTER REGISTER
00E5 50          LOOP   M10 ; DO THE WHOLE TABLE
00E6 1F          POP    M10 ; GET MODE BACK
00E6          DS
ASSUME DS:DATA ; RECOVER SEGMENT VALUE
;----- FILL REGEN AREA WITH BLANK
0007 33 FF       XOR    DI,DI ; SET UP POINTER FOR REGEN
0009 89 3E 004E R MOV    CRT_START,DI ; START ADDRESS SAVED IN GLOBAL
000D C6 00 0062 R 00 MOV    ACTIVE_PAGE,0 ; SET PAGE VALUE
0012 80 2000     MOV    CX,8192 ; NUMBER OF BUSES IN COLOR CARD
0014 80 FC 04    MOV    AH,4 ; TEST FOR GRAPHICS
0015 72 0C       CMP    M1,0 ; NO_GRAPHICS_INIT
0016 80 FC 07    JC    M12 ; TEST FOR BW CARD
0017 74 04       CMP    AH,7 ; NO_GRAPHICS_INIT
0018 33 C0       JE    M13 ; BW_CARD_INIT
001F EB 05       XOR    AX,AX ; FILE FOR GRAPHICS MODE
0020 00          JMP    SHORT M13 ; CLEAR_BUFFER
0021          BH
0022          08H ; BUFFER SIZE ON BW CARD (2048)
0023 B5 08       M11:  MOV    CH,08H ; NO_GRAPHICS_INIT
0025 BB 0720     M12:  MOV    AX,'!+7*256 ; FIL_CHAR FOR ALPHA
0028 F3/ AB      M13:  REP    STOSW ; CLEAR_BUFFER
                           ; FILL THE REGEN BUFFER WITH BLANKS
;----- ENABLE VIDEO AND CORRECT PORT SETTING
00FA A0 0049 R   MOV    AL,CRT_MODE ; GET THE MODE
00FB 32 E4       XOR    AH,AH ; INTO AN REGISTER
00FF 80 F0       MOV    SI,AX ; TABLE POINTER, INDEXED BY MODE
0101 BB 16 0063 R MOV    DX,ADDR_6845 ; PREPARE TO OUTPUT TO VIDEO ENABLE PORT
0105 83 C2 04    ADD    DX,4
0108 2E: 8A 84 0000 E MOV    AL,CS:[SI + OFFSET BYTE PTR M7]
010D EE          OUT   DX,AL ; SET VIDEO ENABLE PORT
010E A2 0065 R   MOV    DX,CRT_MODE_SET,AL ; SAVE THAT VALUE
;----- DETERMINE NUMBER OF COLUMNS, BOTH FOR ENTIRE DISPLAY
;----- AND THE NUMBER TO BE USED FOR TTY INTERFACE
0111 2E: BA 84 0000 E MOV    AL,CS:[SI + OFFSET BYTE PTR M6]
0116 32 E4       XOR    AH,AH
0118 A3 004A R   MOV    CRT_COLS,AX ; NUMBER OF COLUMNS IN THIS SCREEN
;----- SET CURSOR POSITIONS
011B B1 F6 0000 F AND    SI,0FH ; WORD_OFFSET INTO CLEAR_LENGTH TABLE

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011F 2E 8B 8C 0000 E      MOV    CX,CS:[SI + OFFSET M5] ; LENGTH TO CLEAR
0124 B9 004C R            MOV    CRT_LEN,CX          ; SAVE LENGTH OF CRT -- NOT USED FOR BW
0128 B9 0008 R            MOV    CX,8              ; CLEAR ALL CURSOR POSITIONS
0129 B9 0050 R            PUSH   DS,OFFSET_CURSOR_POSN
012E 1E                   POP    ES              ; ESTABLISH SEGMENT
012F 07                   POP    AX              ; ADDRESSING
0130 33 C0               XOR    AX,AX          ; FILL WITH ZEROES
0132 F3/ AB              REP    STOSW         ; FILL WITH ZEROES

;----- SET UP OVERSCAN REGISTER
0134 42                   INC    DX              ; SET OVERSCAN PORT TO A DEFAULT
0135 B0 30               MOV    AL,30H          ; VALUE OF 30H FOR ALL MODES EXCEPT 640X200
0137 B0 3E 0049 R 06       CMP    CRT_MODE,6        ; SEE IF THE MODE IS 640X200 BW
013C 75 02               JNZ    M14             ; IF IT ISNT 640X200, THEN GOTO REGULAR
013E B0 03 F              MOV    AL,3FH          ; IF IT IS 640X200, THEN PUT IN 3FH
0140 EEE                 OUT   DX,AL          ; OUTPUT THE CORRECT VALUE TO 30H PORT
0141 A2 0066 R            MOV    CRT_PALLETTE,AL ; SAVE THE VALUE FOR FUTURE USE

;----- NORMAL RETURN FROM ALL VIDEO RETURNS
0144 5D                   POP    BP              ; VIDEO_RETURN:
0145 5F                   POP    DI              ; VIDEO_RETURN_C
0146 5E                   POP    SI              ; RECOVER SEGMENTS
0147 5B                   POP    BX              ; ALL DONE
0148 59                   POP    CX              ; SET_MODE
0149 5A                   POP    DX              ; SET_CTYPE
014A 1F                   POP    DS              ; THIS ROUTINE SETS THE CURSOR VALUE
014B 07                   POP    ES              ; INPUT (CX) HAS CURSOR VALUE CH-START LINE, CL-STOP LINE
014C CF                   IRET             ; OUTPUT NONE
014D 00                   SET_MODE ENDP

;----- SET_CTYPE
;----- SET_CTYPE THIS ROUTINE SETS THE CURSOR VALUE
;----- INPUT (CX) HAS CURSOR VALUE CH-START LINE, CL-STOP LINE
;----- OUTPUT NONE
014D B4 0A               MOV    AH,10          ; 6845 REGISTER FOR CURSOR SET
014E B9 0E 0060 R          MOV    CURSOR_MODE,CX ; SAVE IN DATA AREA
0153 EB 0158 R            CALL   M16             ; OUTPUT CX REG
0156 EB EC               JMP    VIDEO_RETURN

;----- THIS ROUTINE OUTPUTS THE CX REGISTER TO THE 6845 REGS NAMED IN AH
0158 BB 16 0063 R          M16:  MOV    DX,ADDR_6845 ; ADDRESS REGISTER
015C B8 C4               MOV    AL,AH          ; GET VALUE
015E EE                   OUT   DX,AL          ; REGISTER SET
015F H2                   INC    DX              ; DATA REGISTER
0160 E0 00               JMP    SHORT $+2        ; IO DELAY
0162 B8 C5               MOV    AL,CH          ; DATA
0164 EE                   OUT   DX,AL          ; POINT TO OTHER DATA REGISTER
0165 4A                   DEC    DX              ; SET FOR SECOND REGISTER
0166 EB 00               JMP    SHORT $+2        ; IO DELAY
0168 B8 C4               MOV    AL,AH          ; DATA
016A FE C0               INC    AL,AH          ; POINT TO OTHER DATA REGISTER
016C EE                   OUT   DX,AL          ; SET FOR SECOND REGISTER
016D H2                   INC    DX              ; IO DELAY
016E EB 00               JMP    SHORT $+2        ; IO DELAY
0170 B8 C1               MOV    AL,CL          ; SECOND DATA VALUE
0172 EE                   OUT   DX,AL          ; ALL DONE
0173 C3                   RET
0174 SET_CTYPE ENDP

;----- SET_CPOS
;----- SET_CPOS THIS ROUTINE SETS THE CURRENT CURSOR POSITION TO THE NEW X-Y VALUE PASSED
;----- INPUT DX - ROW,COLUMN OF NEW CURSOR
;----- INPUT BH - DISPLAY PAGE OF CURSOR
;----- OUTPUT CURSOR IS SET AT 6845 IF DISPLAY PAGE IS CURRENT DISPLAY
0174 B8 C0               SET_CPOS PROC NEAR
0176 32 ED               MOV    CL,BH          ; ESTABLISH LOOP COUNT
0177 E1                   XOR    CH,CH          ; WORD_OFFSET
0178 B9 11               SAL    CX,1           ; USE INDEX REGISTER
017C B9 94 0050 R          MOV    SI,[SI+OFFSET_CURSOR_POSN],DX ; SAVE THE POINTER
0180 38 3E 0062 R          CMP    ACTIVE_PAGE,BH
0184 75 05               JNZ    M17             ; SET_CPOS_RETURN
0186 BB C2               MOV    AX,DX          ; GET ROW/COLUMN TO AX
0188 E8 B18D R            CALL   M18             ; CURSOR_SET
0189 EB B7               JMP    VIDEO_RETURN ; SET_CPOS_RETURN
018D SET_CPOS ENDP

;----- SET_CURSOR_POSITION, AX HAS ROW/COLUMN FOR CURSOR
018D B8 0211 R            M17:  PROC  NEAR
0190 BB C8               CALL   POSITION          ; DETERMINE LOCATION IN REGEN BUFFER
0192 03 0E 004E R          MOV    CX,AX          ; ADD IN THE START ADDRESS FOR THIS PAGE
0196 D1 F0               ADD    CX,CRT_START        ; DIVIDE BY 2 FOR CHAR ONLY COUNT
0198 B9 0E 0060 R          SAR    CX,1           ; REGISTER NUMBER FOR CURSOR
019A E8 0158 R            MOV    AL,M16          ; OUTPUT THE VALUE TO THE 6845
019D C3                   RET
019E M18 ENDP

;----- READ_CURSOR
;----- READ_CURSOR THIS ROUTINE READS THE CURRENT CURSOR VALUE FROM THE 6845, FORMATS IT, AND SENDS IT BACK TO THE CALLER
;----- INPUT BH - PAGE OF CURSOR
;----- OUTPUT DX - ROW, COLUMN OF THE CURRENT CURSOR POSITION
;----- CX - CURRENT CURSOR MODE
019E B8 DF               READ_CURSOR PROC NEAR
01A0 32 FF               MOV    BL,BH          ; WORD_OFFSET
01A2 D1 E3               SAL    BX,1           ; WORD_OFFSET
01A4 BB 97 0050 R          MOV    DX,[BX+OFFSET_CURSOR_POSN]
01A8 BB 0E 0060 R          MOV    CX,CURSOR_MODE
01AC 5D                   POP    BP              ; DISCARD SAVED CX AND DX
01AD 57                   POP    SI              ; ADDRESSING
01AE 5E                   POP    BX              ; ADDRESSING
01AF 5B                   POP    AX              ; ADDRESSING

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01B1 58
01B2 1F
01B3 07
01B4 CF
01B5
READ_CURSOR PROC NEAR
    POP AX
    POP DS
    POP ES
    IRET
    ENDP

;----- ACT_DISP_PAGE -----
; THIS ROUTINE SETS THE ACTIVE DISPLAY PAGE, ALLOWING
; THE FULL USE OF THE RAM SET ASIDE FOR THE VIDEO ATTACHMENT
; INPUT
;     AL HAS THE NEW ACTIVE DISPLAY PAGE
; OUTPUT
;     THE 6845 IS RESET TO DISPLAY THAT PAGE
ACT_DISP_PAGE PROC NEAR
    MOV ACTIVE_PAGE,AL ; SAVE ACTIVE PAGE VALUE
    MOV CX,CRT_LEN ; GET SAVED LENGTH OF REGEN BUFFER
    CBW ; CONVERT AL TO WORD
    PUSH AX ; SAVE PAGE VALUE
    MUL CX ; DISPLAY PAGE TIMES REGEN LENGTH
    MOV CRT_START,AX ; SAVE START ADDRESS FOR LATER REQUIREMENTS
    MOV CX,AX ; STAR ADDRESS FOR CX
    SAR CX,1 ; DIVIDE BY 2 FOR 6845 HANDLING
    MOV AH,12 ; 6845 REGISTER FOR START ADDRESS
    CALL M16 ; SET THE 6845
    POP BX ; RECOVER PAGE VALUE
    SAL BX,1 ; *2 FOR WORD OFFSET
    MOV AX,[BX + OFFSET_CURSOR_POS] ; GET CURSOR FOR THIS PAGE
    CALL M18 ; SET THE CURSOR POSITION
    JMP VIDEO_RETURN
ACT_DISP_PAGE ENDP

;----- SET COLOR -----
; THIS ROUTINE WILL ESTABLISH THE BACKGROUND COLOR, THE OVERSCAN COLOR,
; AND THE FOREGROUND COLOR SET FOR MEDIUM RESOLUTION GRAPHICS
; INPUT
;     (BH) HAS COLOR ID
;         IF BH=0, THE BACKGROUND COLOR VALUE IS SET
;         FROM THE LOW BITS OF BL (0-31)
;         IF BH=1, THE PALETTE SELECTION IS MADE
;             BASED ON THE LOW BIT OF BL:
;                 0 = GREEN, RED, YELLOW FOR COLORS 1,2,3
;                 1 = BLUE, CYAN, MAGENTA FOR COLORS 1,2,3
;     (BL) HAS THE COLOR VALUE TO BE USED
; OUTPUT
;     THE COLOR SELECTION IS UPDATED
SET_COLOR PROC NEAR
    MOV DX,ADDR_6845 ; I/O PORT FOR PALETTE
    ADD DX,10H ; OVERSCAN PORT
    ADD AL,CRT_PALETTE ; GET THE CURRENT PALETTE VALUE
    OR BH,BH ; IS THIS COLOR 0?
    JNZ M20 ; OUTPUT COLOR 1

;----- HANDLE COLOR 0 BY SETTING THE BACKGROUND COLOR
M19:
    AND AL,0EH ; TURN OFF LOW 5 BITS OF CURRENT
    AND BL,01FH ; TURN OFF HIGH 3 BITS OF INPUT VALUE
    OR AL,BL ; PUT VALUE INTO REGISTER
    OUT DX,AL ; OUTPUT THE PALETTE
    MOV CRT_PALETTE,AL ; SAVE THE COLOR VALUE
    JMP VIDEO_RETURN

;----- HANDLE COLOR 1 BY SELECTING THE PALLETTE TO BE USED
M20:
    AND AL,0DFH ; TURN OFF PALLETTE SELECT BIT
    SHR BL,1 ; TEST THE LOW ORDER BIT OF BL
    JNC M19 ; ALREADY DONE
    OR AL,20H ; TURN ON PALLETTE SELECT BIT
    JMP M19 ; GO DO IT
SET_COLOR ENDP

;----- VIDEO STATE -----
; RETURNS THE CURRENT VIDEO STATE IN AX
; AH = NUMBER OF COLUMNS ON THE SCREEN
; AL = CURRENT VIDEO MODE
; BH = CURRENT ACTIVE PAGE
VIDEO_STATE PROC NEAR
    MOV AH,BYTE PTR CRT_COLS ; GET NUMBER OF COLUMNS
    MOV AL,CRT_MODE ; CURRENT MODE
    MOV BH,ACTIVE_PAGE ; GET CURRENT ACTIVE PAGE
    RECOVER_REGS
    POP DI
    POP SI
    POP CX
    POP BX ; DISCARD SAVED BX
    RET ; RETURN TO CALLER
VIDEO_STATE ENDP

;----- POSITION -----
; THIS SERVICE ROUTINE CALCULATES THE REGEN BUFFER ADDRESS
; OF A CHARACTER IN THE ALPHA MODE
; INPUT
;     AX = ROW, COLUMN POSITION
; OUTPUT
;     AX = OFFSET OF CHAR POSITION IN REGEN BUFFER
POSITION PROC NEAR
    PUSH BX ; SAVE REGISTER
    MOV BX,AX ; ROW, COLUMN POSITION
    MOV AL,AH ; ROWS TO AL
    MUL BYTE PTR CRT_COLS ; DETERMINE BYTES TO ROW
    XOR BH,BH ; ADD AX,BX ; ADD IN COLUMN VALUE
    ADD AX,BX ; * 2 FOR ATTRIBUTE BYTES
    POP BX
    RET
POSITION ENDP

;----- SCROLL_UP -----
; THIS ROUTINE MOVES A BLOCK OF CHARACTERS UP
; ON THE SCREEN
; INPUT
;     (AH) = CURRENT CRT MODE
;     (AL) = NUMBER OF ROWS TO SCROLL
;     (CX) = ROW/COLUMN OF UPPER LEFT CORNER
;     (DX) = ROW/COLUMN OF LOWER RIGHT CORNER
;     (BH) = ATTRIBUTE TO BE USED ON BLANKED LINE
;     (DS) = DATA SEGMENT
;     (ES) = REGEN BUFFER SEGMENT
; OUTPUT
;     NONE -- THE REGEN BUFFER IS MODIFIED
ASSUME CS:CODE,DS:DATA,ES:DATA

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0222          SCROLL_UP      PROC NEAR
0222    E8 0303 R   CALL TEST_LINE_COUNT ;
0225    80 FC 04   CMP AH,4      ; TEST FOR GRAPHICS MODE
0228    72 02       JC N1        ; HANDLE SEPARATELY
022A    80 FC 07   CMP AH,7      ; TEST FOR BW CARD
022D    74 03       JE N1
022E    E9 0405 R   JMP GRAPHICS_UP
022F
N1:           PUSH BX      ; UP_CONTINUE
0232    53          MOV AX,CX    ; SAVE FILL ATTRIBUTE IN BH
0233    BB C1       CALL SCROLL_POSITION ; UPPER LEFT POSITION
0235    E8 026F R   JZ N7        ; DO SETUP FOR SCROLL
0238    74 31       ADD SI,AX    ; BLANK FIELD
023C    03 F0       ADD DI,BP    ; FROM ADDRESS
023E    8A E6       MOV AH,DH    ; DOWN BY BLOCK
023E    2A E3       SUB AH,BL    ; # ROWS TO BE MOVED
0240
N2:           CALL N10      ; ROW_LOOP
0242    58          ADD SI,BP    ; MOVE ONE ROW
024C    80 20       ADD DI,BP
024D    00 D0       DEC AL
024E    FE CC       JNZ N2      ; CLEAR_ENTRY
024F    75 F5       POP AX      ; RECOVER ATTRIBUTE IN AH
024B
N3:           POP AL,1'    ; FILL WITH BLANKS
024E    E8 02B6 R   CALL N11      ; CLEAR THE ROW
0251    03 FD       ADD DI,BP    ; POINT TO NEXT LINE
0253    FE CB       DEC BL      ; COUNTER OF LINES TO SCROLL
0255    75 F7       JNZ N4      ; CLEAR_LOOP
0257
N4:           CALL N11      ; SCROLL_END
0259    80 0000 E   CMP CRT_MODE,7 ; IS THIS THE BLACK AND WHITE CARD
025A    80 3E 0049 R 07  JE N6        ; IF SO, SKIP THE MODE RESET
025F    74 07       MOV AL,CRT_MODE_SET ; GET THE VALUE OF THE MODE SET
0261    A0 0065 R   MOV DX,03D8H ; ALWAYS SET COLOR CARD PORT
0264    BA 03D8
0266    EE          OUT DX,AL
0268
N6:           CALL DDS      ; VIDEO_RETURN
026B    E9 0144 R   JMP VIDEO_RETURN ; BLANK_FIELD
026B    8A DE       MOV BL,DH    ; GET ROW COUNT
026D    EB DC       JMP N3        ; GO CLEAR THAT AREA
026F   SCROLL_UP    ENDP
;----- HANDLE COMMON SCROLL SET UP HERE
SCROLL_POSITION PROC NEAR
026F    80 3E 0049 R 02  CMP CRT_MODE,2 ; TEST FOR SPECIAL CASE HERE
0274    72 19       JB N1        ; HAVE TO HANDLE 80X25 SEPARATELY
0276    80 3E 0049 R 03  CMP CRT_MODE,3
027B    77 12       JA N9
N8:           PUSH DX      ; GUARANTEED TO BE COLOR CARD HERE
027E    BA 03DA
0281    50          PUSH AX
0282
0283    EC          IN AL,DX    ; WAIT DISP_ENABLE
0283    A8 08       TEST AL,8     ; GET PORT
0285    74 FB       JZ N8        ; WAIT FOR VERTICAL RETRACE
0287    B0 25       MOV AL,25H
0289    BA 03D8
028C    EE          MOV DX,03D8H ; TURN OFF VIDEO
028D    58          OUT DX,AL   ; DURING VERTICAL RETRACE
028E    FA          POP AX
028F    FE C0       POP DX
0290    32 ED       CALL POSITION ; CONVERT TO REGEN POINTER
0292    03 06 004E R ADD AX,CRT_START ; OFFSET OF ACTIVE PAGE
0296    8B F8       MOV DI,AX    ; TO ADDRESS FOR SCROLL
0298    8B F0       MOV SI,AX    ; FROM ADDRESS FOR SCROLL
0299    2B 01       SHL DX,CX    ; DX = #ROWS, #COLS IN BLOCK
029C    FE C6       INC DL
029E    FE C2       INC DL
02A0    32 ED       XOR CH,CH    ; INCREMENT FOR O ORIGIN
02A2    8B 25 004A R MOV BP,CRT_COLS ; SET HIGH BYTE OF COUNT TO ZERO
02A6    00 E0 00     ADD BP,DP    ; GET NUMBER OF COLUMNS IN DISPLAY
02A8    8A 03       MOV AP,BI    ; TIMES LINE ATTRIBUTE BYTE
02AA    F6 26 004A R MUL AP,BI    ; GET LINE COUNT
02AE    03 CO       ADD AX,AX    ; DETERMINE OFFSET TO FROM ADDRESS
02B0    06          PUSH ES      ; *2 FOR ATTRIBUTE BYTE
02B1    1F          PUSH DS      ; ESTABLISH ADDRESSING TO REGEN BUFFER
02B2    80 FB 00   CMP BL,0     ; FOR BOTH POINTERS
02B5    C3          RET         ; 0 SCROLL MEANS BLANK FIELD
02B6   SCROLL_POSITION ENDP
;----- MOVE_ROW
N10:          MOVE_ROW      NEAR
02B6    8A CA       MOV CL,DL    ; GET # OF COLS TO MOVE
02B8    56          PUSH SI
02B9    57          PUSH DI
02BA    F3/ A5      REP MOVSW ; MOVE THAT LINE ON SCREEN
02BC    5F          POP DI
02BD    5E          POP SI
02BF    C3          RET
02B6   N10          ENDP
;----- CLEAR_ROW
N11:          CLEAR_ROW      NEAR
02B6    8A CA       MOV CL,DL    ; GET # COLUMNS TO CLEAR
02C1    57          PUSH DI
02C2    F3/ AB      REP STOSW ; STORE THE FILL CHARACTER
02C4    5F          POP DI
02C5    C3          RET
02C6   N11          ENDP
;----- SCROLL_DOWN
;----- THIS ROUTINE MOVES THE CHARACTERS WITHIN A DEFINED
;----- BLOCK DOWN ON THE SCREEN, FILLING THE TOP LINES
;----- WITH A DEFINED CHARACTER
;----- INPUT
;----- (AH) = CURRENT CRT MODE
;----- (AL) = NUMBER OF LINES TO SCROLL
;----- (CX) = UPPER LEFT CORNER OF REGION
;----- (DX) = LOWER RIGHT CORNER OF REGION
;----- (BH) = FILL CHARACTER
;----- (DS) = DATA SEGMENT
;----- (ES) = REGEN SEGMENT
;----- OUTPUT
;----- NONE -- SCREEN IS SCROLLED
SCROLL_DOWN    PROC NEAR
02C6    FD          STD
02C7    E8 0303 R   CALL TEST_LINE_COUNT ; DIRECTION FOR SCROLL DOWN
02CA    80 FC 04   CMP AH,4      ; TEST FOR GRAPHICS
02CD    72 08       JC N12

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02CF 80 FC 07           CMP AH,7          ; TEST FOR BW CARD
02D2 74 03           JE N12
02D4 E9 052E R         JMP GRAPHICS_DOWN
02D7
02D8 53
02D9 88 C2
02DA E8 026F R
02D0 74 20
02D1 2B F0
02E1 8A E0
02E2 2A E3
02E5
02E5 E8 0286 R
02E8 2B F5
02EA 2B FD
02EB FE CC
02EF 75 F5
02F0
02F0 58
02F1 B0 20
02F3
02F4 E8 02BF R
02F6 2B FD
02F8 FE CB
02FA 75 F7
02FC E9 0257 R
02FF
02FF 8A DE
0301 EB ED
0303

N12: PUSH BX             ; CONTINUE DOWN
      MOV AX,DX          ; SAVE ATTRIBUTE IN BH
      CALL SCROLL_POSITION ; LOWER RIGHT CORNER
      JZ N16
      SUB SI,AH          ; GET REGEN LOCATION
      N13: PUSH BX          ; SI IS FROM ADDRESS
      SUB DI,BP          ; COUNT TO MOVE IN SCROLL
      DEC AH
      JNZ N13
      N14: POP AX           ; MOVE ONE ROW
      MOV AL,11
      CALL N11             ; RECOVER ATTRIBUTE IN AH
      SUB DI,BP
      DEC BL
      JNZ N15
      JMP N5               ; SCROLL_END
      N16: MOV AH,DH          ; CLEAR ONE ROW
      JMP N5
      N17: MOV BL,DH          ; GO TO NEXT ROW
      JMP N14
      SCROLL_DOWN ENDP

;----- TEST IF AMOUNT OF LINES TO BE SCROLLED = AMOUNT OF LINES IN WINDOW
;----- IF TRUE THEN WE ADJUST AL, IF FALSE WE RETURN...
0303 TEST_LINE_COUNT PROC NEAR
0303 8A D8
0305 0A C0
0307 74 0E
0309 50
030A 8A C6
030C 2A C5
030D 3A C3
0310 3A C3
0312 58
0313 75 02
0315 2A DB
0316
0317 C3
0318

MOV BL,AL          ; SAVE LINE COUNT IN BL
OR AL,AL          ; TEST IF AL IS ALREADY ZERO
JZ BL_SET          ; IF IT IS THEN RETURN...
PUSH AX            ; SAVE AX
MOV AH,DH          ; SUBTRACT LOWER ROW FROM UPPER ROW
SUB AL,CH          ; ADJUST DIFFERENCE BY 1
INC AH
CMP AL,BL          ; TEST IF LINE COUNT = AMOUNT OF ROWS IN WINDOW
POP AX
JNE BL_SET          ; IF NOT THEN WE'RE ALL SET
SUB BL,BL          ; OTHERWISE SET BL TO ZERO
BL_SET: RET          ; RETURN
TEST_LINE_COUNT ENDP

;----- READ_AC_CURRENT
;----- THIS ROUTINE READS THE ATTRIBUTE AND CHARACTER AT THE CURRENT
;----- CURSOR POSITION AND RETURNS THEM TO THE CALLER
;----- INPUT
;----- (AH) = CURRENT CRT MODE
;----- (BH) = DISPLAY PAGE ( ALPHA MODES ONLY )
;----- (DS) = DATA SEGMENT
;----- (ES) = REGEN SEGMENT
;----- OUTPUT
;----- (AL) = CHAR READ
;----- (AH) = ATTRIBUTE READ
;----- ASSUME CS:CODE,DS:DATA,ES:DATA
READ_AC_CURRENT PROC NEAR
0318 80 FC 04          ; IS THIS GRAPHICS
0318 72 08
031D 80 FC 07          ; IS THIS BW CARD
0320 74 03
0321 E9 0669 R
0325
0325 E8 0342 R
0328 BB F3

P1: CMP AH,7          ; READ_AC_CONTINUE
JMP GRAPHICS_READ
CALL FIND_POSITION
MOV SI,BX          ; ESTABLISH ADDRESSING IN SI

;----- WAIT FOR HORIZONTAL RETRACE
032A BB 16 0063 R
032E 83 C2 06
0331 06
0332 1F
0333
0333 EC
0334 A8 01
0336 75 FB
0338 FA
0339
0339 EC
033A A8 01
033C 74 FB
033E AD
033F E9 0144 R
0342

MOV DX,ADDR_6845          ; GET BASE ADDRESS
ADD DX,6              ; POINT AT STATUS PORT
PUSH ES
POP DS                ; GET SEGMENT FOR QUICK ACCESS
P2: IN AL,DX          ; WAIT FOR RETRACE LOW
TEST AL,1
JNZ P2
CLI
P3: IN AL,DX          ; IS HORIZ RETRACE LOW
TEST AL,1
JZ P3
IS IT HIGH
LODSW
P4: IN AL,DX          ; NO MORE INTERRUPTS
TEST AL,1
JZ P4
IS IT HIGH
WAIT UNTIL IT IS
GET THE CHAR/ATTR
JMP VIDEO_RETURN
READ_AC_CURRENT ENDP

FIND_POSITION PROC NEAR
0342 8A CF
0344 32 ED
0346 8B F1
0348 40 06
034A 8B 00 0050 R
034E 33 DB
0350 E3 06
0352
0352 03 1E 004C R
0356 E2 FA
0358
0358 E8 0211 R
0358 03 DB
0350 C3
035E

MOV CL,BH          ; DISPLAY PAGE TO CX
XOR CH,CH
MOV SI,CX
SAL SI,1            ; MOVE TO SI FOR INDEX
MOV AX,[SI+OFFSET_CURSOR_PAGE] ; + 2 FOR WORD OFFSET
XOR BX,BX          ; SET START ADDRESS TO ZERO
JCXZ P5
P4: ADD BX,CRT_LEN ; NO PAGE
LOOP P4
P5: CALL POSITION   ; PAGE_LOOP
ADD BX,AX          ; DETERMINE LOCATION IN REGEN
RET
FIND_POSITION ENDP

;----- WRITE_AC_CURRENT
;----- THIS ROUTINE WRITES THE ATTRIBUTE AND CHARACTER AT
;----- THE CURRENT CURSOR POSITION
;----- INPUT
;----- (AH) = CURRENT CRT MODE
;----- (BH) = DISPLAY PAGE
;----- (CX) = COUNT OF CHARACTERS TO WRITE
;----- (AL) = CHAR TO WRITE
;----- (BL) = ATTRIBUTE OF CHAR TO WRITE
;----- (DS) = DATA SEGMENT
;----- (ES) = REGEN SEGMENT
;----- OUTPUT
;----- NONE

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035E          WRITE_AC_CURRENT    PROC NEAR
035E 80 FC 04    CMP AH,4           ; IS THIS GRAPHICS
0361 72 08       JC P6             ; 
0363 80 FC 07       CMP AH,7           ; IS THIS BW CARD
0366 74 03       JE P6             ;
0368 E9 05B8 R     JMP GRAPHICS_WRITE
036B 8A E3       MOV AH,BL          ; WRITE_AC_CONTINUE
036D 50          PUSH AX            ; GET ATTRIBUTE TO AH
036E 51          PUSH CX            ; SAVE ON STACK
036F E8 0342 R     CALL FIND_POSITION ; SAVE WRITE COUNT
0370 80 FB       MOV DI,BX          ; ADDRESS TO DI REGISTER
0374 59          POP CX             ; WRITE COUNT
0375 5B          POP BX             ; CHARACTER IN BX REG
0376          P7:                ; WRITE_LOOP
;----- WAIT FOR HORIZONTAL RETRACE
0376 8B 16 0063 R   MOV DX,ADDR_6845 ; GET BASE ADDRESS
037A 83 C2 06       ADD DX,6            ; POINT AT STATUS PORT
037D          P8:                ; GET STATUS
037D EC          IN AL,DX          ; IS IT LOW
037E A8 01          TEST AL,1           ; WAIT UNTIL IT IS
037F 75 FB       JNZ P8             ; NO MORE INTERRUPTS
0382 FA          CLI               ;
0383          P9:                ; GET STATUS
0384 A8 01          TEST AL,1           ; IS IT HIGH
0385 74 FB       JZ P9              ; WAIT UNTIL IT IS
0388 8B C3          MOV AX,BX          ; RECOVER THE CHAR/ATTR
038A AB          STOSW             ; PUT THE CHAR/ATTR
038B FB          STI               ; INTERRUPTS BACK ON
038C E2 E8          LOOP P7            ; AS MANY TIMES AS REQUESTED
038E E9 0144 R     JMP VIDEO_RETURN
0391          WRITE_AC_CURRENT ENDP

;----- WRITE_C_CURRENT
;----- THIS ROUTINE WRITES THE CHARACTER AT
;----- THE CURRENT CURSOR POSITION, ATTRIBUTE UNCHANGED
;----- INPUT
;----- (AH) = CURRENT CRT MODE
;----- (BH) = DISPLAY PAGE
;----- (CX) = COUNT OF CHARACTERS TO WRITE
;----- (AL) = CHAR TO WRITE
;----- (DS) = DATA SEGMENT
;----- (ES) = REGEN SEGMENT
;----- OUTPUT
;----- NONE
;----- -----
0391          WRITE_C_CURRENT    PROC NEAR
0391 80 FC 04       CMP AH,4           ; IS THIS GRAPHICS
0394 72 08          JC P10            ; 
0396 80 FC 07       CMP AH,7           ; IS THIS BW CARD
0399 74 03          JE P10             ;
039B E9 05B8 R     JMP GRAPHICS_WRITE
039E          P10:               ; SAVE ON STACK
039F 50          PUSH AX            ; SAVE WRITE COUNT
03A0 E8 0342 R     CALL FIND_POSITION ; ADDRESS TO DI
03A3 8B FB       MOV DI,BX          ; WRITE COUNT
03A5 59          POP CX             ; BL HAS CHAR TO WRITE
03A6 5B          POP BX             ; WRITE_LOOP
03A7          P11:               ;----- WAIT FOR HORIZONTAL RETRACE
03A7 8B 16 0063 R   MOV DX,ADDR_6845 ; GET BASE ADDRESS
03AB 83 C2 06       ADD DX,6            ; POINT AT STATUS PORT
03AE          P12:               ; GET STATUS
03AF EC          IN AL,DX          ; IS IT LOW
03B0 A8 01          TEST AL,1           ; WAIT UNTIL IT IS
03B1 75 FB       JNZ P12             ; NO MORE INTERRUPTS
03B3 FA          CLI               ;
03B4          P13:               ; GET STATUS
03B5 A8 01          TEST AL,1           ; IS IT HIGH
03B7 74 FB       JZ P13              ; WAIT UNTIL IT IS
03B9 8A C3          MOV AL,BL          ; RECOVER CHAR
03B8 FB          STI               ; ENABLE INTS.
03BC AA          STOSB             ; PUT THE CHAR/ATTR
03BD 77          INC DI             ; BUMPS UP PAST ATTRIBUTE
03BE E2 E7          LOOP P11            ; AS MANY TIMES AS REQUESTED
03C0 E9 0144 R     JMP VIDEO_RETURN
03C3          WRITE_C_CURRENT ENDP
page
;----- -----
;----- WRITE_STRING
;----- This routine writes a string of characters to the crt.
;----- INPUT
;----- (AL) = WRITE STRING COMMAND 0 - 3
;----- (BH) = DISPLAY PAGE
;----- (CX) = COUNT OF CHARACTERS TO WRITE, IF CX == 0 THEN RETURN
;----- (BL) = ATTRIBUTE OF CHAR TO WRITE IF AL == 0 || AL == 1
;----- (ES) = STRING SEGMENT
;----- (BP) = STRING OFFSET
;----- OUTPUT
;----- N/A
;----- -----
03C3          WRITE_STRING     PROC NEAR
03C5 3C 04          CMP AL,04          ; TEST FOR INVALID WRITE STRING OPTION
03C5 72 03          JB W0             ; IF OPTION INVALID THEN RETURN
03C7 E9 045B R     JMP W0             ;
03CA 80 C9          W0:                ; TEST FOR ZERO LENGTH STRING
03CC 75 01          OR CX,CX          ; 
03CE E9 045B R     JMP W0             ;
03D1 53          W1:                ; IF ZERO LENGTH STRING THEN RETURN
03D2 8A DF          PUSH BX            ; SAVE PAGE AND POSSIBLE ATTRIBUTE
03D3 32 FF          XOR BH,BH          ; 
03D6 41 E3          SAL SI             ; GET CURRENT CURSOR POSITION
03D8 8B B7 0050 R   MOV SI,[BX+OFFSET_CURSOR_POSN]
03DC 5B          POP BX             ; RESTORE BX
03D0 56          PUSH SI             ; SAVE CURRENT CURSOR POSITION
03DE 50          PUSH AX             ; SAVE WRITE STRING OPTION
03DF BB 0200 R     MOV AX,0200H        ; SET NEW CURSOR POSITION
03E2 CD 10          INT 10H            ; 
03E4 58          POP AX             ; RESTORE WRITE STRING OPTION
03E5          P5:                ;----- WRITE_CHAR:
03E5 51          PUSH CX            ;
03E6 53          PUSH BX            ;

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03E7 50
03E8 06
03E9 86 E0
03EB 26: 8A 46 00
03EF 49

PUSH AX
PUSH ES

XCHG AH, AL ; PUT THE WRITE STRING OPTION INTO AH
MOV AL, ES:[BP] ; GET CHARACTER FROM INPUT STRING
INC BP ; BUMP POINTER TO CHARACTER

;---- TEST FOR SPECIAL CHARACTER'S

03F0 3C 08
03F2 74 0C
03F4 3C 0D
03F6 78 08
03F8 3C 0A
03FA 74 0C
03FC 3C 07
03FE 75 13
0400
0400 B4 0E
0402 CD 00
0404 8A DF
0406 D0 E7
0408 80 97 0050 R
040C 07
040D 58
040E 58
040F 59
0410 E8 32 90

PUSH AX
PUSH ES
POP AX
POP BX
POP CX
JMP ROWS_SET

CMP AL, 8 ; IS IT A BACKSPACE
JE DO_TTY ; BACK_SPACE
CMP AL, 0DH ; IS IT CARRIAGE RETURN
JE DO_TTY ; CARRET
CMP AL, 0AH ; IS IT A LINE FEED
JE DO_TTY ; LINE_FEED
CMP AL, 07H ; IS IT A BELL
JNE GET_ATTRIBUTE ; IF NOT THEN DO WRITE CHARACTER

DO_TTY:
MOV AH, 14 ; WRITE TTY CHARACTER TO THE CRT
INT 10H
MOV BH, BH ; GET CURRENT CURSOR POSITION
SAL BH, 1 INTO THE DX REGISTER
MOV DX, [BX+OFFSET_CURSOR_POSN]
POP ES ; RESTORE REGISTERS
POP BX
POP CX
JMP ROWS_SET

GET_ATTRIBUTE:
MOV AH, 09 ; SET CHARACTER WRITE AMOUNT TO ONE
INT 10H ; IS THE ATTRIBUTE IN THE STRING
JB GOT_IT ; IF NOT THEN JUMP
INC BP ; ELSE GET IT
BL, ES:[BP] ; BUMP STRING POINTER

GOT_IT:
MOV AH, 09 ; WRITE CHARACTER TO THE CRT
INT 10H
POP ES ; RESTORE REGISTERS
POP AX
POP BX
POP CX

INC DL ; INCREMENT COLUMN COUNTER
CMP DL, BYTE PTR CRT_COLS ; IF COLS ARE WITHIN RANGE FOR
; THIS MODE THEN
; COLUMNS_SET
JB COLUMNS_SET ; BUMP ROW COUNTER BY ONE
INC DH ; SET COLUMN COUNTER TO ZERO
SUB DL, DL ; IF ROWS ARE < 25 THEN
CMP DH, 25 ; GOTO ROWS_SET
JB ROWS_SET ; SAVE ROWS SETTING PARAMETER REGS
; SAVE REG'S THAT GET CLOBBERED

PUSH ES ; SAVE WRITE STRING OPTION
PUSH AX ; SET NEW CURSOR POSITION
MOV AX, 0EOAH ; DO SCROLL ONE LINE
INT 10H ; RESET ROW COUNTER TO 24
DEC DH ; RESTORE REG'S
POP AX
POP ES

ROWS_SET:
COLUMNS_SET:
PUSH AX ; SAVE WRITE STRING OPTION
MOV AX, 0200H ; SET NEW CURSOR POSITION
INT 10H ; DO IT ONCE MORE UNTIL CX = ZERO
POP AX ; RESTORE OLD CURSOR COORDINATES
LOOP WRITE_CHAR ; IF CURSOR WAS TO BE MOVED THEN
; WE'RE DONE

0420
0420 B4 09
0422 CD 10
0424 07
0425 58
0426 58
0427 59

0428 FE C2
042A 3A 16 004A R

042E 72 14
0430 FE C6
0432 2A D2
0434 2B FE 19
0437 72 0B

0439 06
043A 50
043B B8 0E0A
043E CD 10
0440 B8 FE CE
0442 58
0443 07

0444
0444 50
0445 B8 0200
0446 40 10
044A 58
044B E2 98

044D 5A
044E 4C 01
0450 79 09
0452 3C 03
0454 74 05
0456 B8 0200
0459 CD 10
045A 40 10
045B E9 0144 R

045E
045E E8 0492 R
0461 26: 8A 04
0464 22 C4
0466 D2 E0
0468 00 00
046A D2 C0
046C E9 0144 R
046F

046F 50
0470 50
0471 E8 0492 R
0474 D2 E8
0476 22 C4
0478 40 10
0479 58
047C F6 C3 80
047F 75 0D
0481 F6 D4
0483 22 CC
0485 00 C1
0487
0487 26: 88 04
048A 58
048B E9 0144 R
048E 32 C1

PUSH AX
PUSH ES
CALL R3 ; DETERMINE BYTE POSITION OF DOT
MOV AL, ES:[SI] ; GET THE BYTE
AND AL, AH ; MASK OFF THE OTHER BITS IN THE BYTE
SHL AL, CL ; LEFT JUSTIFY THE VALUE
MOV CL, AL ; GET NUMBER OF BITS IN RESULT
ROL AL, CL ; RIGHT JUSTIFY THE RESULT
JMP VIDEO_RETURN ; RETURN FROM VIDEO IO

READ_DOT:
ASSUME CS:CODE, DS:DATA, ES:DATA
PROC NEAR
CALL R3 ; DETERMINE BYTE POSITION OF DOT
MOV AL, ES:[SI] ; GET THE BYTE
AND AL, AH ; MASK OFF THE OTHER BITS IN THE BYTE
SHL AL, CL ; LEFT JUSTIFY THE VALUE
MOV CL, AL ; GET NUMBER OF BITS IN RESULT
ROL AL, CL ; RIGHT JUSTIFY THE RESULT
JMP VIDEO_RETURN ; RETURN FROM VIDEO IO

READ_DOT ENDP

WRITE_DOT:
PROC NEAR
PUSH AX ; SAVE DOT VALUE
PUSH AX ; TWICE
CALL R3 ; DETERMINE BYTE POSITION OF THE DOT
SHR AL, CL ; SHIFT TO SET UP THE BITS FOR OUTPUT
AND AL, AH ; SET UP OF THE OTHER BITS
MOV CL, ES:[SI] ; GET THE CURRENT BYTE
POP BX ; RECOVER XOR FLAG
TEST BL, 80H ; IS IT ON
JNZ R2 ; YES, XOR THE DOT
NOT AH ; SET THE MASK TO REMOVE THE INDICATED BITS
AND CL, AH ; OR IN THE NEW VALUE OF THOSE BITS
OR AL, CL ; FINISH DOT
MOV ES:[SI], AL ; RESTORE THE BYTE IN MEMORY
POP AX
JMP VIDEO_RETURN ; RETURN FROM VIDEO IO

R2:
XOR AL, CL ; XOR DOT
; EXCLUSIVE OR THE DOTS

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0490 EB F5
0492      JMP R1          ; FINISH UP THE WRITING
0492      ENDP

;----- THIS SUBROUTINE DETERMINES THE REGEN BYTE LOCATION OF THE
;----- INDICATED ROW COLUMN VALUE IN GRAPHICS MODE.
;----- ENTRY --
;----- DX = ROW VALUE (0-199)
;----- CX = COLUMN VALUE (0-639)
;----- EXIT --
;----- SI = OFFSET INTO REGEN BUFFER FOR BYTE OF INTEREST
;----- AH = MASK TO STRIP OFF THE BITS OF INTEREST
;----- DL = BITS TO LEFT & RIGHT JUSTIFY THE MASK IN AH
;----- DH = # BITS IN RESULT

0492 53
0493 50

R3      PROC NEAR
        PUSH BX          ; SAVE BX DURING OPERATION
        PUSH AX          ; WILL SAVE AL DURING OPERATION

;----- DETERMINE 1ST BYTE IN INDICATED ROW BY MULTIPLYING ROW VALUE BY 40
;----- ( LOW BIT OF ROW DETERMINES EVEN/ODD, 80 BYTES/RW)

0494 80 28
0495 52
0497 80 E2 FE
049A F6 E2
049C 5A
049D F6 C2 01
04A0 74 03
04A2 05 2000
04A5 88 F0
04A7 58
04A8 88 D1

R4:      MOV AL,40
        PUSH DX          ; SAVE ROW VALUE
        AND DL,0FEH       ; STRIP OFF ODD/EVEN BIT
        MUL DX           ; AX HAS ADDRESS OF 1ST BYTE OF INDICATED ROW
        POP DX
        TEST DL,1         ; TEST FOR EVEN/ODD
        JZ R4             ; IF EVEN ROW
        ADD AX,2000H      ; OFFSET TO LOCATION OF ODD ROWS
        MOV AX,2000H      ; EVEN ROW
        MOV SI,AX         ; MOVE POINTER TO SI
        POP AX            ; RECOVER AL VALUE
        MOV DX,CX         ; COLUMN VALUE TO DX

;----- DETERMINE GRAPHICS MODE CURRENTLY IN EFFECT

;----- SET UP THE REGISTERS ACCORDING TO THE MODE
;----- CH = MASK FOR LOW OF COLUMN ADDRESS (.7/3 FOR HIGH/MED RES)
;----- CL = # OF ADDRESS BITS IN COLUMN VALUE (.3/2 FOR H/M)
;----- BL = MASK TO SELECT BITS FROM POINTEED BYTE (.8/0 FOR H/M)
;----- BH = NUMBER OF VALID BITS IN POINTEED BYTE (.1/2 FOR H/M)

04AA BB 02C0
04AB B9 0302
04B0 80 0049 R 06
04B5 72 06
04B7 BB 0180
04BA B9 0703

R5:      MOV BX,200H      ; SET PARS FOR MED RES
        CMP CRT_MODE,6   ; HANDLE IF MED ARES
        JC R5             ; RECOVER REG
        MOV BX,180H      ; SET PARS FOR HIGH RES

;----- DETERMINE BIT OFFSET IN BYTE FROM COLUMN MASK

04BD 22 EA
R5:      AND CH,DL      ; ADDRESS OF PEL WITHIN BYTE TO CH

;----- DETERMINE BYTE OFFSET FOR THIS LOCATION IN COLUMN

04BF D3 EA
04C1 03 F2
04C3 8A F7

R6:      SHR DX,CL      ; SHIFT BY CORRECT AMOUNT
        ADD SI,DX         ; INCREMENT THE POINTER
        MOV DI,BH         ; GET THE # OF BITS IN RESULT TO DH

;----- MULTIPLY BH (VALID BITS IN BYTE) BY CL (BIT OFFSET)

04C5 2A C9
04C7 D0 C8
R6:      SUB CL,CL      ; ZERO INTO STORAGE LOCATION
        ROR AL,1          ; LEFT JUSTIFY THE VALUE IN AL (FOR WRITE)
        ADD CL,CH
        DEC BH
        LOOP CONTROL
        JNZ R6             ; ON EXIT, CL HAS SHIFT COUNT TO RESTORE BITS
        MOV AH,BL          ; MOVE THE MASK TO CORRECT LOCATION
        SHR AH,CL
        POP BX
        RET
        POP DS
        RET
        R3 ENDP

;----- SCROLL UP
;----- THIS ROUTINE SCROLLS UP THE INFORMATION ON THE CRT
;----- ENTRY --
;----- CH,CL = UPPER LEFT CORNER OF REGION TO SCROLL
;----- DH,DL = LOWER RIGHT CORNER OF REGION TO SCROLL
;----- BOTH OF THESE ABOVE ARE CHARACTER POSITIONS
;----- BL = # LINES TO BLANK (LINES)
;----- AL = # LINES TO SCROLL (AL=0 MEANS BLANK THE ENTIRE FIELD)
;----- DS = DATA SEGMENT
;----- ES = REGEN SEGMENT
;----- EXIT --
;----- NOTHING, THE SCREEN IS SCROLLED

04D5 8A D8
04D7 8B C1

GRAPHICS_UP PROC NEAR
        MOV BL,AL          ; SAVE LINE COUNT IN BL
        MOV AX,CX          ; GET UPPER LEFT POSITION INTO AX REG

;----- USE CHARACTER SUBROUTINE FOR POSITIONING
;----- ADDRESS RETURNED IS MULTIPLIED BY 2 FROM CORRECT VALUE

04D9 E8 0748 R
04DC BB F8
R5:      CALL GRAPH_POSN
        MOV DI,AX          ; SAVE RESULT AS DESTINATION ADDRESS

;----- DETERMINE SIZE OF WINDOW

04DE 2B D1
04E0 B1 C2 0101
04E1 D0 E5
04E6 D0 E6

R6:      SUB DX,CX
        ADD DX,101H      ; ADJUST VALUES
        SAL DH,1          ; MULTIPLY # ROWS BY 4 SINCE 8 VERT DOTS/CHAR
        SAL DI,1          ; AND EVEN/ODD ROWS

;----- DETERMINE CRT MODE

04E8 80 3E 0049 R 06
04E9 73 04

R6:      CMP CRT_MODE,6   ; TEST FOR MEDIUM RES
        JNC R7             ; FIND_SOURCE

;----- MEDIUM RES UP

04EF D0 E2
04F1 D1 E7

R7:      SAL DI,1          ; # COLUMNS * 2, SINCE 2 BYTES/CHAR
        SAL DI,1          ; OFFSET * 2 SINCE 2 BYTES/CHAR

;----- DETERMINE THE SOURCE ADDRESS IN THE BUFFER

04F3 06
04F4 F1
04F5 2A ED
04F7 D0 E3
04F9 D0 E3
04FB 74 2D
04FD 8A C3
04FE 80 00
0501 FG E4
0503 8B F7
0505 03 F0
0507 8A E6

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0509 2A E3          SUB    AH,BL      ; DETERMINE NUMBER TO MOVE
0508 E8 058E R      R8:   CALL    R17       ; ROW_LOOP
0505 81 EE 1FB0     SUB    S1,2000H+80  ; MOVE ONE ROW
0512 81 EF 1FB0     SUB    D1,2000H+80  ; MOVE TO NEXT ROW
0516 FE CC          DEC    AH           ; NUMBER OF ROWS TO MOVE
0518 75 F1          JNZ    R8           ; CONTINUE TILL ALL MOVED

;----- FILL IN THE VACATED LINE(S)
051A 8A C7          R9:   MOV    AL,BH      ; CLEAR_ENTRY
051C 8A C7          R10:  MOV    AL,BH      ; ATTRIBUTE TO FILL WITH
051C E8 05A7 R      CALL    R18       ; CLEAR THAT ROW
051F 81 EF 1FB0     SUB    D1,2000H+80  ; POINT TO NEXT LINE
0523 FE CB          DEC    BL           ; NUMBER OF LINES TO FILL
0525 75 F5          JNZ    R10       ; CLEAR_LOOP
0527 E9 0144 R      JMP    VIDEO_RETURN ; EVERYTHING DONE

052A 8A DE          R11:  MOV    BL,DH      ; BLANK_FIELD
052A EB EC          JMP    R9           ; SET BLANK COUNT TO EVERYTHING IN FIELD
052C 8A C7          GRAPHICS_UP    ENDP

;----- SCROLL DOWN
;----- THIS ROUTINE SCROLLS DOWN THE INFORMATION ON THE CRT
;----- ENTRY --
;----- CH, CL = UPPER LEFT CORNER OF REGION TO SCROLL
;----- DH, DL = LOWER RIGHT CORNER OF REGION TO SCROLL
;----- BOTH OF THE ABOVE ARE IN CHARACTER POSITIONS
;----- BH = FILL VALUE FOR BLANKED LINES
;----- AL = # LINES TO SCROLL (AL=0 MEANS BLANK THE ENTIRE FIELD)
;----- DS = DATA SEGMENT
;----- ES = REGEN SEGMENT
;----- EXIT --
;----- NOTHING, THE SCREEN IS SCROLLED
;----- -----
052E FD          GRAPHICS_DOWN PROC NEAR
052E 8A D8          STW    DS          ; SET DIRECTION
052F BB C2          MOV    BL,AL      ; SAVE LINE COUNT IN BL
0531 BB C2          MOV    AX,DX      ; GET LOWER RIGHT POSITION INTO AX REG

;----- USE CHARACTER SUBROUTINE FOR POSITIONING
;----- ADDRESS RETURNED IS MULTIPLIED BY 2 FROM CORRECT VALUE
0533 E8 0748 R      CALL    GRAPH_POSN ; GRAPH_POSN
0536 BB F8          MOV    DI,AX      ; SAVE RESULT AS DESTINATION ADDRESS

;----- DETERMINE SIZE OF WINDOW
0538 2B D1          SUB    DX,CX      ; ADJUST VALUES
053A 81 C2 0101     ADD    DX,101H    ; MULTIPLY # ROWS BY 4 SINCE 8 VERT DOTS/CHAR
053E D0 E6          SAL    DH,1       ; AND EVEN/ODD ROWS
0540 D0 E6          SAL    DH,1

;----- DETERMINE CRT MODE
0542 80 3E 0049 R 06  CMP    CRT_MODE,6 ; TEST FOR MEDIUM RES
0547 73 05          JNC    R12       ; FIND_SOURCE_DOWN

;----- MEDIUM RES DOWN
0549 D0 E2          SAL    DL,1       ; # COLUMNS * 2, SINCE 2 BYTES/CHAR (OFFSET OK)
054B D1 E7          SAL    DL,1       ; OFFSET * 2 SINCE 2 BYTES/CHAR
054D 47             INC    DI           ; POINT TO LAST BYTE

;----- DETERMINE THE SOURCE ADDRESS IN THE BUFFER
054E 06             R12:  PUSH   ES          ; FIND_SOURCE_DOWN
054F 1F             POP    DS          ; BOTH SEGMENTS TO REGEN
0550 2A ED          POP    DS
0552 81 C7 00FO     SUB    CH,CH      ; ZERO TO HIGH OF COUNT REG
0556 D0 E3          ADD    D1,240     ; POINT TO LAST ROW OF PIXELS
0558 D0 E3          SAL    BL,1       ; MULTIPLY NUMBER OF LINES BY 4
055A 74 2E          SAL    BL,1
055C 8A C3          JZ    R16       ; IF ZERO, THEN BLANK ENTIRE FIELD
055E B4 50          MOV    AL,BL      ; GET NUMBER OF LINES IN AL
0560 F6 E4          MOV    AH,80      ; 80 BYTES/ROW
0561 80 3E 0049 R 06  MUL    AH,4       ; DETERMINE OFFSET TO SOURCE
0564 2B F0          MOV    SI,DI      ; SET SOURCE ADDRESS
0566 8A E6          SUB    SI,AX      ; SUBTRACT THE OFFSET
0568 2A E3          MOV    AH,DH      ; NUMBER OF ROWS IN FIELD
056A AH BL          SUB    AH,BL      ; DETERMINE NUMBER TO MOVE

;----- LOOP THROUGH, MOVING ONE ROW AT A TIME, BOTH EVEN AND ODD FIELDS
056A E8 058E R      R13:  CALL    R17       ; ROW_LOOP_DOWN
056D 81 EE 2050     SUB    S1,2000H+80  ; MOVE ONE ROW
0571 81 EF 2050     SUB    D1,2000H+80  ; MOVE TO NEXT ROW
0575 FE CC          DEC    AH           ; NUMBER OF ROWS TO MOVE
0577 75 F1          JNZ    R13       ; CONTINUE TILL ALL MOVED

;----- FILL IN THE VACATED LINE(S)
0579 8A C7          R14:  MOV    AL,BH      ; CLEAR_ENTRY_DOWN
057B 8A C7          R15:  MOV    AL,BH      ; ATTRIBUTE TO FILL WITH
057B E8 05A7 R      CALL    R18       ; CLEAR_LOOP_DOWN
057E 81 EF 2050     SUB    D1,2000H+80  ; CLEAR A ROW
0582 FE CB          DEC    BL           ; NUMBER OF LINES TO FILL
0584 75 F5          JNZ    R15       ; CLEAR_LOOP_DOWN
0586 FC BB          CLD    R15       ; RESET THE DIRECTION FLAG
0587 E9 0144 R      JMP    VIDEO_RETURN ; EVERYTHING DONE

;----- ROUTINE TO MOVE ONE ROW OF INFORMATION
058E 8A CA          R16:  MOV    BL,DH      ; BLANK_FIELD_DOWN
0590 56             JMP    R14       ; SET BLANK COUNT TO EVERYTHING IN FIELD
0591 57             GRAPHICS_DOWN ENDP

0592 F3/A4          R17:  PROC   NEAR
0594 5F             MOV    CL,DL      ; NUMBER OF BYTES IN THE ROW
0595 2E             PUSH   S1          ; SAVE POINTERS
0596 80 G6 2000     ADD    D1,2000H    ; POINT TO THE ODD FIELD
0598 81 C7 2000     ADD    D1,2000H
059E 56             PUSH   S1          ; SAVE THE POINTERS
059F 57             PUSH   DI          ; COUNT BACK
05A0 8A CA          MOV    CL,DL      ; COUNT BACK
05A2 F3/A4          REP    H0VSB     ; MOVE THE ODD FIELD
05A4 5F             POP    DI          ; POINTERS BACK
05A5 5E             POP    S1          ; RETURN TO CALLER
05A6 C3             RET

```

;----- CLEAR A SINGLE ROW

```
R18 PROC NEAR
    MOV CL,DL      ; NUMBER OF BYTES IN FIELD
    PUSH DI       ; SAVE POINTER
    REP STOSB     ; STORE THE NEW VALUE
    POP DI        ; POINTER BACK
    ADD DI,2000H   ; POINT TO ODD FIELD
    PUSH DI
    MOV CL,DL
    REP STOSB     ; FILL THE ODD FILELD
    POP DI
    RET          ; RETURN TO CALLER
R18 ENDP
```

;----- GRAPHICS WRITE

```
; THIS ROUTINE WRITES THE ASCII CHARACTER TO THE CURRENT
; POSITION ON THE SCREEN BY MATCHING THE DOTS ON THE SCREEN TO THE
; CHARACTER GENERATOR CODE POINTS
ENTRY --
AL = CHARACTER TO WRITE
BL = COLOR INDEX. 0 IS USED FOR FOREGROUND COLOR
IF BIT 7 IS SET, THE CHAR IS XOR'D INTO THE REGEN BUFFER
(0 IS USED FOR THE BACKGROUND COLOR)
CX = NUMBER OF CHARS TO WRITE
DS = DATA SEGMENT
ES = REGEN SEGMENT
EXIT --
NOTHING IS RETURNED
```

;----- GRAPHICS READ

```
; THIS ROUTINE READS THE ASCII CHARACTER AT THE CURRENT CURSOR
; POSITION ON THE SCREEN BY MATCHING THE DOTS ON THE SCREEN TO THE
; CHARACTER GENERATOR CODE POINTS
ENTRY --
NONE (0 IS ASSUMED AS THE BACKGROUND COLOR)
EXIT --
AL = CHARACTER READ AT THAT POSITION (0 RETURNED IF NONE FOUND)
```

FOR BOTH ROUTINES, THE IMAGES USED TO FORM CHARS ARE CONTAINED IN ROM  
FOR THE 1ST 128 CHARS, TO ACCESS CHARS IN THE SECOND HALF, THE USER  
MUST INITIALIZE THE VECTOR AT INTERRUPT 1FH (LOCATION 0007CH) TO  
POINT TO THE USER SUPPLIED TABLE OF GRAPHIC IMAGES (8x8 BOXES).  
FAILURE TO DO SO WILL CAUSE STRANGE RESULTS

```
ASSUME CS:CODE, DS:DATA, ES:DATA
GRAPHICS_WRITE PROC NEAR
    MOV AH,0      ; ZERO TO HIGH OF CODE POINT
    PUSH AX       ; SAVE CODE POINT VALUE
```

;----- DETERMINE POSITION IN REGEN BUFFER TO PUT CODE POINTS

```
CALL S26      ; FIND LOCATION IN REGEN BUFFER
MOV DI,AX     ; REGEN POINTER IN DI
```

;----- DETERMINE REGION TO GET CODE POINTS FROM

```
POP AX        ; RECOVER CODE POINT
CMP AL,80H    ; IS IT IN SECOND HALF
JAE S1        ; YES
```

;----- IMAGE IS IN FIRST HALF, CONTAINED IN ROM

```
MOV SI,OFFSET CRT_CHAR_GEN ; OFFSET OF IMAGES
PUSH CS        ; SAVE SEGMENT ON STACK
JMP SHORT S2  ; DETERMINE_MODE
```

;----- IMAGE IS IN SECOND HALF, IN USER RAM

```
S1:           SUB AL,80H      ; EXTEND CHAR
    PUSH DS        ; ZERO ORIGIN FOR SECOND HALF
    SUB SI,SI      ; SAVE DATA POINTER
    MOV DS,SI      ; ESTABLISH VECTOR ADDRESSING
    ASSUME DS:AB50
    LDS SI,EXT_PTR ; GET THE OFFSET OF THE TABLE
    MOV DX,DS      ; GET THE SEGMENT OF THE TABLE
    ASSUME DS:DATA
    POP DS        ; RECOVER DATA SEGMENT
    PUSH DX      ; SAVE TABLE SEGMENT ON STACK
```

;----- DETERMINE GRAPHICS MODE IN OPERATION

```
S2:           SAL AX,1      ; DETERMINE MODE
    SAL AX,1      ; MULTIPLY CODE POINT
    SAL AX,1      ; VALUE BY 8
    ADD SI,AX    ; SI HAS OFFSET OF DESIRED CODES
    CMP CRT_MODE,6 ; TEST FOR MEDIUM RESOLUTION MODE
    POP DS
    JC S7        ; RECOVER TABLE POINTER SEGMENT
    DS 57        ; TEST FOR MEDIUM RESOLUTION MODE
```

;----- HIGH RESOLUTION MODE

```
S3:           PUSH DI        ; HIGH CHAR
    PUSH SI        ; SAVE REGEN POINTER
    PUSH DS        ; SAVE CODE POINTER
    MOV DH,4      ; NUMBER OF TIMES THROUGH LOOP
    S4:           LODSB         ; GET BYTE FROM CODE POINTS
    TEST BL,80H    ; SHOULD WE USE THE FUNCTION
    JNZ S6        ; TO PUT CHAR IN
    STOSB         ; STORE IN REGEN BUFFER
    LODSB
    S5:           MOV ES:[DI+2000H-1],AL ; STORE IN SECOND HALF
    ADD DI,79      ; MOVE TO NEXT ROW IN REGEN
    DEC DH        ; DONE WITH LOOP
    JNZ S4
    POP SI
    POP DI
    INC DI
    LOOP S3      ; MORE CHARS TO WRITE
    JMP VIDEO_RETURN
```

```
S6:           XOR AL,ES:[DI] ; EXCLUSIVE OR WITH CURRENT
    STOSB         ; STORE THE CODE POINT
    LODSB         ; AGAIN FOR ODD FIELD
    XOR AL,ES:[DI+2000H-1]; AGAIN
    JMP SS        ; BACK TO MAINSTREAM
```

;----- MEDIUM RESOLUTION WRITE

```
S7:           MOV DL,BL      ; MED_RES_WRITE
    SAL DI,1      ; SAVE HIGH COLOR BIT
    SAL DI,1      ; OFFSET#2 SINCE 2 BYTES/CHAR
```



06F1

```
GRAPHICS READ ENDP
; EXPAND MED COLOR
; THIS ROUTINE EXPANDS THE LOW 2 BITS IN BL TO
; FILL THE ENTIRE BX REGISTER
ENTRY --
BL = COLOR TO BE USED ( LOW 2 BITS )
EXIT --
BX = COLOR TO BE USED ( 8 REPLICATIONS OF THE 2 COLOR BITS )
```

06F1 80 E3 03  
06F4 A8 C3  
06F7 51  
06F7 B9 0003

```
S19 PROC NEAR
    AND BL,3 ; ISOLATE THE COLOR BITS
    MOV AL,BL ; COPY TO AL
    PUSH CX ; SAVE REGISTER
    MOV CX,3 ; NUMBER OF TIMES TO DO THIS
S20: SAL AL,1 ; LEFT SHIFT BY 2
    SAL AL,1 ; ANOTHER COLOR VERSION INTO BL
    OR BL,AL ; FILL UP OF BL
    LOOP S20 ; FILL UPPER PORTION
    POP BH,BL ; REGISTER BACK
    POP CX ; ALL DONE
    RET
```

0706

```
S19 ENDP
; EXPAND BYTE
; THIS ROUTINE TAKES THE BYTE IN AL AND DOUBLES ALL
; OF THE BITS, TURNING THE 8 BITS INTO 16 BITS.
; THE RESULT IS LEFT IN AX
```

0706 52  
0707 51  
0708 53  
0709 28 D2  
0709 B9 0001

```
S21 PROC NEAR
    PUSH CX ; SAVE REGISTERS
    PUSH BX
    SUB DX,DX ; RESULT REGISTER
    MOV CX,1 ; MASK REGISTER
S22: MOV BX,AX ; BASE INTO TEMP
    AND BX,CX ; USE MASK TO EXTRACT A BIT
    OR DX,BX ; PUT INTO RESULT REGISTER
    SHL AX,1 ; SHIFT BASE AND MASK BY 1
    SHL CX,1 ; BASE TO TEMP
    MOV BX,CX ; EXTRACT THE SAME BIT
    OR DX,BX ; PUT INTO RESULT
    SHL CX,1 ; SHIFT ONLY MASK NOW, MOVING TO NEXT BASE
    JNC S22 ; USE MASK BIT COMING OUT TO TERMINATE
    POP DX,DX ; RESULT TO PARM REGISTER
    POP BX
    POP CX ; RECOVER REGISTERS
    POP DX
    RET
```

0728

S21 ENDP

0728

```
; MED READ BYTE
; THIS ROUTINE WILL TAKE 2 BYTES FROM THE REGEN BUFFER,
; COMPARE AGAINST THE CURRENT FOREGROUND COLOR, AND PLACE
; THE CORRESPONDING ON/OFF BIT PATTERN INTO THE CURRENT
; POSITION IN THE SAVE AREA
ENTRY --
SI,DS = POINTER TO REGEN AREA OF INTEREST
BX = EXPANDED FOREGROUND COLOR
BP = POINTER TO SAVE AREA
; EXIT --
; BP IS INCREMENT AFTER SAVE
```

0728 8A 24  
072A 8A 44 01  
072D B9 C000  
0730 8B 00

```
S23 PROC NEAR
    MOV AH,[SI] ; GET FIRST BYTE
    MOV AL,[SI+1] ; GET SECOND BYTE
    MOV CX,0C000H ; 2 BIT MASK TO TEST THE ENTRIES
    MOV DL,0 ; RESULT REGISTER
S24: TEST AX,CX ; IS THIS SECTION BACKGROUND?
    CLC ; CLEAR CARRY IN HOPES THAT IT IS
    JZ S25 ; IF ZERO, IT IS BACKGROUND
    SHR CX,1 ; MASH'N, SO SET CARRY
    RCL DL,1 ; MOVE THAT BIT INTO THE RESULT
    SHR CX,1 ; MOVE THE MASK TO THE RIGHT BY 2 BITS
    JNC S24 ; DO IT AGAIN IF MASK DIDN'T FALL OUT
    MOV [BP],DL ; STORE RESULT IN SAVE AREA
    INC BP ; ADJUST POINTER
    RET
```

0732

```
S24: ENDP
; VI POSITION
; THIS ROUTINE TAKES THE CURSOR POSITION CONTAINED IN
; THE MEMORY LOCATION, AND CONVERTS IT INTO AN OFFSET
; INTO THE REGEN BUFFER, ASSUMING ONE BYTE/CHAR.
; FOR MEDIUM RESOLUTION GRAPHICS, THE NUMBER MUST
; BE DOUBLED.
; -- NO REGISTERS, MEMORY LOCATION CURSOR_POSN IS USED
; EXIT --
; AX CONTAINS OFFSET INTO REGEN BUFFER
```

0732 85 C1  
0734 F8  
0735 75 01  
0737 59  
0738 D0 D2  
073A D1 E9  
073C D1 E9  
073E F7 F2  
0740 8B 56 00  
0743 C6  
0744 C3

```
S25: RCL DL,1 ; MOVE THAT BIT INTO THE RESULT
    SHR CX,1 ; MOVE THE MASK TO THE RIGHT BY 2 BITS
    JNC S24 ; DO IT AGAIN IF MASK DIDN'T FALL OUT
    MOV [BP],DL ; STORE RESULT IN SAVE AREA
    INC BP ; ADJUST POINTER
    RET
```

0745

```
S23 ENDP
; VI POSITION
; THIS ROUTINE TAKES THE CURSOR POSITION CONTAINED IN
; THE MEMORY LOCATION, AND CONVERTS IT INTO AN OFFSET
; INTO THE REGEN BUFFER, ASSUMING ONE BYTE/CHAR.
; FOR MEDIUM RESOLUTION GRAPHICS, THE NUMBER MUST
; BE DOUBLED.
```

0745 A1 0050 R  
0746 53  
0749 8B D8  
074B 8A C4  
074D F6 26 004A R

```
GRAPH_POSN LABEL NEAR
    PUSH BX ; SAVE REGISTER
    MOV BX,AX ; SAVE A COPY OF CURRENT CURSOR
    MOV AL,AH ; GET ROWS TO AL
```

0751

```
    MUL BYTE PTR CRT_COLS ; MULTIPLY BY BYTES/COLUMN
    ADD AX,AL ; MULTIPLY * 4 SINCE 4 ROWS/BYTE
```

0753

```
    SHL AX,1 ; ISOLATE COLUMN VALUE
    SHL AX,1 ; DETERMINE OFFSET
```

0755

```
    SUB BH,BH ; RECOVER POINTER
    ADD AX,BX ; RECOVER POINTER
    POP BX ; ALL DONE
```

0757

```
    RET
```

0758

```
S26 ENDP
```

0758

```
; WRITE_TTY
; THIS INTERFACE PROVIDES A TELETYPE LIKE INTERFACE TO THE
; VIDEO CARD. THE INPUT CHARACTER IS WRITTEN TO THE CURRENT
; CURSOR POSITION AND THE CURSOR IS MOVED TO THE NEW POSITION.
```

0759

```
IF THE CURSOR LEAVES THE LAST COLUMN OF THE FIELD, THE COLUMN
IS SET TO ZERO, AND THE ROW VALUE IS INCREMENTED. IF THE ROW
```

0759

```
ROW VALUE LEAVES THE FIELD, THE CURSOR IS PLACED ON THE LAST ROW,
FIRST COLUMN, AND THE ENTIRE SCREEN IS SCROLLED UP ONE LINE.
```

0759

```
WHEN THE SCREEN IS SCROLLED UP, THE ATTRIBUTES FOR THE LINE
THE NEWLY BLANKED LINE IS READ FROM THE CURSOR POSITION ON THE PREVIOUS
LINE BEFORE THE SCROLL. IN CHARACTER MODE, IN GRAPHICS MODE,
THE 0 COLOR IS USED.
```

0759

```
ENTRY --
(AH) = CURRENT CRT MODE
(AL) = CHARACTER TO BE WRITTEN
```

0759

```
NOTE THAT BACK SPACE, CAR RET, BELL AND LINE FEED ARE HANDLED
```

```

;----- AS COMMANDS RATHER THAN AS DISPLAYABLE GRAPHICS
;----- (BL) = FOREGROUND COLOR FOR CHAR WRITE IF CURRENTLY IN A GRAPHICS MODE
;----- EXIT --
;----- ALL REGISTERS SAVED
;----- ASSUME CS:CODE,DS:DATA
;----- WRITE_TTY PROC NEAR
    PUSH AX ; SAVE REGISTERS
    PUSH AX ; SAVE CHAR TO WRITE
    MOV AH,3 ; GET CURRENT PAGE SETTING
    MOV BH,ACTIVE_PAGE ; GET CURRENT PAGE SETTING
    INT 10H ; READ THE CURRENT CURSOR POSITION
    POP AX ; RECOVER CHAR

;----- DX NOW HAS THE CURRENT CURSOR POSITION

0765 3C 08
0768 74 50 ; IS IT A BACKSPACE
0750 50 ; BACK SPACE
0750 B4 03 ; IS IT CARRIAGE RETURN
075F 8A 3E 0062 R ; CARRET
0763 CD 10 ; LINE FEED
0765 58 ; LINE FEED
0766 74 5A ; BELL
0766 3C 08 ; BELL
0768 74 52 ; IS IT A BACKSPACE
076A 3C 0D ; BACK SPACE
076C 74 57 ; IS IT CARRIAGE RETURN
076E 3C 0A ; CARRET
0770 74 57 ; LINE FEED
0772 3C 07 ; BELL
0774 74 5A ; BELL

;----- WRITE THE CHAR TO THE SCREEN

0776 B4 0A ; WRITE CHAR ONLY
0778 B9 0001 ; ONLY ONE CHAR
077B CD 10 ; WRITE THE CHAR

;----- POSITION THE CURSOR FOR NEXT CHAR

077D FE C2
077F 3A 16 004A R ; TEST FOR COLUMN OVERFLOW
0783 75 33 ; SET_CURSOR
0785 B2 00 ; COLUMN FOR CURSOR
0787 B0 FE 18 ; SET_CURSOR_INC
078A 75 2A ; SET_CURSOR_INC

;----- SCROLL REQUIRED

078C U1:
078C B4 02 ; SET THE CURSOR
078E CD 10

;----- DETERMINE VALUE TO FILL WITH DURING SCROLL

0790 A0 0049 R ; GET THE CURRENT MODE
0793 3C 04 ; READ-CURSOR
0795 75 06 ; READ-CURSOR
0797 3C 07 ; READ-CURSOR
0799 B7 00 ; FILL WITH BACKGROUND
079B 75 06 ; SCROLL-UP

0790 75 06
0790 B4 08 ; READ-CURSOR
079F CD 10 ; READ CHAR/ATTR AT CURRENT CURSOR
07A1 8A FC ; STORE IN BH

0743 B8 0601 ; SCROLL-UP
0746 2B C9 ; SCROLL ONE LINE
0748 B6 18 ; UPPER LEFT CORNER
074A 8A 16 004A R ; LOWER RIGHT ROW
074E FE CA ; LOWER RIGHT COLUMN
0780 CD 10 ; VIDEO-CALL-RETURN
0782 75 06 ; SCROLL UP THE SCREEN
0782 58 ; TTY-RETURN
0783 E9 0144 R ; RESTORE THE CHARACTER
                ; RETURN TO CALLER

0785 FE C6 ; SET-CURSOR-INC
0786 FE C6 ; NEXT ROW
0788 B4 02 ; SET-CURSOR
078A EB F4 ; ESTABLISH THE NEW CURSOR

;----- BACK SPACE FOUND

07BC U8:
07BC 80 FA 00 ; ALREADY AT END OF LINE
07BF 74 F7 ; SET_CURSOR
07C1 FE CA ; NO -- JUST MOVE IT BACK
07C3 EB F3 ; SET_CURSOR

;----- CARRIAGE RETURN FOUND

07C5 U9:
07C5 B2 00 ; MOVE TO FIRST COLUMN
07C7 EB EF ; SET_CURSOR

;----- LINE FEED FOUND

07C9 80 FE 18 ; BOTTOM OF SCREEN
07CC 75 F8 ; YES, SCROLL THE SCREEN
07CE EB BC ; NO, JUST SET THE CURSOR

;----- BELL FOUND

07D0 U10:
07D0 B3 02 ; SET UP COUNT FOR BEEP
07D2 E8 0000 E ; SOUND THE POD BELL
07D5 EB DB ; TTY_RETURN
07D7 WRITE_TTY ENDP

;----- LIGHT PEN
;----- THIS ROUTINE TESTS THE LIGHT PEN SWITCH AND THE LIGHT
;----- PEN TRIGGER. IF BOTH ARE SET, THE LOCATION OF THE LIGHT
;----- PEN IS DETERMINED. OTHERWISE, A RETURN WITH NO INFORMATION
;----- IS MADE.
;----- ON EXIT:
;----- (AH) = 0 IF NO LIGHT PEN INFORMATION IS AVAILABLE
;----- BX,CX,DX ARE DESTROYED
;----- (AH) = 1 IF LIGHT PEN IS AVAILABLE
;----- (DH,DL) = CURRENT LIGHT PEN POSITION
;----- (CX) = RASTER POSITION
;----- (BX) = BEST GUESS AT PIXEL HORIZONTAL POSITION

;----- ASSUME CS:CODE,DS:DATA
;----- SUBTRACT_TABLE
V1 LABEL BYTE
    DB 3,3,5,5,3,3,3,4 ; ASSUME DS:DATA
07D7 03 05 05 03 03 ; SUBTRACT_TABLE
07D7 03 04 ; V1 LABEL BYTE
07DF READ_LPEN PROC NEAR

```

```

;----- WAIT FOR LIGHT PEN TO BE DEPRESSED
07DF B4 00          MOV AH,0           ; SET NO LIGHT PEN RETURN CODE
07E1 B9 16 0063 R   MOV DX,ADDR_6845 ; SET BASE ADDRESS OF 6845
07E5 B3 C2 06          ADD DX,6        ; POINT TO STATUS REGISTER
07E8 EC              IN AL,DX       ; GET STATUS REGISTER
07E9 A8 04          TEST AL,4      ; TEST LIGHT PEN SWITCH
07EB 74 03          JZ V6_A       ; GO IF YES
07ED E9 0872 R       JMP V6         ; NOT SET, RETURN

;----- NOW TEST FOR LIGHT PEN TRIGGER
07F0 A8 02          V6_A: TEST AL,2    ; TEST LIGHT PEN TRIGGER
07F2 75 03          JNZ V7A       ; RETURN WITHOUT RESETTING TRIGGER
07F4 E9 087C R       JMP V7         ; NOT SET, RETURN

;----- TRIGGER HAS BEEN SET, READ THE VALUE IN
07F7 B4 10          V7A: MOV AH,16     ; LIGHT PEN REGISTERS ON 6845

;----- INPUT REGS POINTED TO BY AH, AND CONVERT TO ROW COLUMN IN DX
07F9 B8 16 0063 R   MOV DX,ADDR_6845 ; ADDRESS REGISTER FOR 6845
07FD B8 C4          MOV AL,AH      ; REGISTER TO READ
07FE F1              OUT DX,AL     ; SET UP
0800 EB 00          JMP SHORT $+2  ; IO DELAY
0802 42              INC DX       ; DATA REGISTER
0803 EC              IN AL,DX     ; GET THE VALUE
0804 8A E8          MOV CH,AL     ; SAVE IN CX
0806 9A               DEC DX       ; ADDRESS REGISTER
0807 FE C4          INC AH       ; SECOND DATA REGISTER
0809 B8 C4          MOV AL,AH     ; SECOND DATA REGISTER
080B EE              OUT DX,AL     ; TAKE IT AWAY
080C 42              INC DX       ; IO DELAY
080D EB 00          JMP SHORT $+2  ; GET SECOND DATA VALUE
080F EC              IN AL,DX     ; AX HAS INPUT VALUE
0810 B8 E5          MOV AH,CH     ; AX HAS INPUT VALUE

;----- AX HAS THE VALUE READ IN FROM THE 6845
0812 B8 1E 0049 R   MOV BL,CRT_MODE ; MODE VALUE TO BX
0816 B8 FF          SUB BH,BL     ; DETERMINE AMOUNT TO SUBTRACT
0818 2E: 8A 9F 07D7 R MOV BH,CS:V1[BX] ; TAKE IT AWAY
081D 2B C3          SUB AX,BX     ; ALPHA_PEN
081F B8 1E 004E R   MOV BX,CRT_START ; CONVERT TO CORRECT PAGE ORIGIN
0823 D1 EB          SHL BX,1      ; IF POSITIVE, DETERMINE MODE
0825 2B C3          SUB AX,BX     ; <0 PLAYS AS 0
0827 79 02          JNS V2        ; DETERMINE MODE
0829 2B C0          SUB AX,AX     ; DETERMINE MODE

;----- DETERMINE MODE OF OPERATION
082B V2:            MOV CL,3      ; DETERMINE_MODE
082B B1 03          CMP CRT_MODE,4 ; SET *8 SHIFT COUNT
082D 80 3E 0049 R 04 JB V4        ; DETERMINE IF GRAPHICS OR ALPHA
0832 72 2A          CMP CRT_MODE,7 ; ALPHA_PEN
0834 80 3E 0049 R 07 JE V6        ; ALPHA_PEN

;----- GRAPHICS MODE
083B B2 28          MOV DL,40      ; DIVISOR FOR GRAPHICS
083D F6 F2          DIV DL       ; DETERMINE ROW(AL) AND COLUMN(AH)
                                ; AL RANGE 0-99, AH RANGE 0-39

;----- DETERMINE GRAPHIC ROW POSITION
083F 8A E8          MOV CH,AL     ; SAVE ROW VALUE IN CH
0841 02 ED          ADD CH,CH     ; *2 FOR EVEN/ODD FIELD
0843 8A DC          MOV BI,AH     ; COLUMN VALUE TO BX
0845 2A FF          SUB BH,BH     ; MULTIPLY BY 8 FOR MEDIUM RES
0846 00 00 0049 R 06 CMP CRT_MODE,6 ; DETERMINE MEDIUM OR HIGH RES
0848 75 04          JNE V3        ; NOT_HIGH_RES
084E B1 04          MOV V3,4      ; SHIFT VALUE FOR HIGH RES
0850 D0 E4          SAL AH,1      ; COLUMN VALUE TIMES 2 FOR HIGH RES
0852 D3 E3          V3: SHL BX,CL ; NOT_HIGH_RES
                                ; MULTIPLY *16 FOR HIGH RES

;----- DETERMINE ALPHA CHAR POSITION
0854 8A D4          MOV DL,AH     ; COLUMN VALUE FOR RETURN
0856 8A F0          MOV DH,AL     ; ROW VALUE
0858 D0 EE          SHR DH,1      ; DIVIDE BY 4
085A D0 EE          SHR DH,1      ; FOR VALUE IN 0-24 RANGE
085C EB 12          JMP SHORT V5 ; LIGHT_PEN_RETURN_SET

;----- ALPHA MODE ON LIGHT PEN
085E F6 36 004A R   V4: DIV BYTE PTR CRT_COLS ; ALPHA_PEN
0862 B8 F0          MOV DH,AL     ; DETERMINE ROW,COLUMN VALUE
0864 8A D4          MOV DI,AH     ; ROWS TO DH
0866 D2 E0          SAL AL,CL     ; COLS TO DL
0868 8A E8          MOV CH,AL     ; MULTIPLY ROWS * 8
086A A4 D0          MOV BI,AH     ; GET RASTER VALUE TO RETURN REG
086C D2 FF          XOR BH,BH     ; COLUMN VALUE
086E D3 E3          SAL BX,CL     ; TO BX
0870 B4 01          V5: MOV AH,1      ; LIGHT_PEN_RETURN_SET
0871 00 00           POP BP       ; INDICATE EVERYTHING SET
0872 52              V6: PUSH DX ; LIGHT_PEN_RETURN
0873 B8 16 0063 R   MOV DX,ADDR_6845 ; SAVE RETURN VALUE (IN CASE)
0877 83 C2 07          ADD DX,7    ; GET BASE ADDRESS
087A EE              OUT DX,AL     ; POINT TO RESET PARM
087B 5A              POP DX       ; ADDRESS NOT DATA, IS IMPORTANT
087C V7:             POP DS       ; RECOVER VALUE
087D 50              POP ES       ; RETURN_NO_RESET
087D 5F              POP DI       ; DISCARD SAVED BX,CX,DX
087E 5E              POP SI       ;
087F 1F              POP DS       ;
0880 1F              POP DS       ;
0881 1F              POP DS       ;
0882 1F              POP DS       ;
0883 07              POP ES       ;
0884 CF              RET         ;
0885 READ_LPEP        ENDP        ;
0885 CODE ENDS        END         ;

```

```

TITLE 11/22/83 BIOS
LIST
C INCLUDE SEGMENT_SRC
C CODE SEGMENT BYTE PUBLIC
C
EXTRN C8042:NEAR
EXTRN OBF_42:NEAR
EXTRN DDS:NEAR
EXTRN PRG:NEAR
EXTRN D1:NEAR
EXTRN D2:NEAR
EXTRN P_MSG:NEAR
EXTRN D2A:NEAR
EXTRN PRI_SEG:NEAR
EXTRN PROG_TIMEOUT:NEAR
EXTRN CM3:NEAR
EXTRN E_MSG:NEAR

PUBLIC MEMORY_SIZE_DETERMINE_1
PUBLIC EQUIPMENT_1
PUBLIC NM1_INT_1
PUBLIC SET_TOD

--- INT 12 -----
MEMORY_SIZE_DETERMINE_1
; THIS ROUTINE RETURNS THE AMOUNT OF MEMORY IN THE
; SYSTEM AS DETERMINED BY THE POST ROUTINES.
; NOTE THAT THE SYSTEM MAY NOT BE ABLE TO USE I/O MEMORY
; UNLESS THERE IS A FULL COMPLEMENT OF 512K BYTES ON THE
; PLANAR.

INPUT
NO REGISTERS
THE MEMORY_SIZE VARIABLE IS SET DURING POWER ON
DIAGNOSTICS ACCORDING TO THE FOLLOWING ASSUMPTIONS:
1. CONFIGURATION RECORD IN NON-VOLATILE MEMORY
EQUALS THE ACTUAL MEMORY SIZE INSTALLED.
2. ALL INSTALLED MEMORY IS FUNCTIONAL. IF THE
MEMORY TEST DURING POST INDICATES LESS, THEN THIS
VALUE BECOMES THE DEFAULT. IF NON-VOLATILE MEMORY
IS NOT VALID (NOT INITIALIZED OR BATTERY FAILURE)
THEN ACTUAL MEMORY DETERMINED BECOMES THE DEFAULT.
3. ALL MEMORY FROM 0 TO 640K MUST BE CONTIGUOUS.

OUTPUT
(AX) = NUMBER OF CONTIGUOUS 1K BLOCKS OF MEMORY
ASSUME CS:CODE,DS:DATA

MEMORY_SIZE_DETERMINE_1 PROC FAR
    STI ; INTERRUPTS BACK ON
    PUSH DS ; SAVE SEGMENT REGISTER
    CALL DDS ; ESTABLISH ADDRESSING
    MOV AX,MEMORY_SIZE ; GET VALUE
    POP DS ; RECOVER SEGMENT
    IRET ; RETURN TO CALLER
MEMORY_SIZE_DETERMINE_1 ENDP

--- INT 11 -----
EQUIPMENT DETERMINATION
THIS ROUTINE ATTEMPTS TO DETERMINE WHAT OPTIONAL
DEVICES ARE ATTACHED TO THE SYSTEM.

INPUT
NO REGISTERS
THE EQUIP_FLAG VARIABLE IS SET DURING THE POWER ON
DIAGNOSTICS USING THE FOLLOWING HARDWARE ASSUMPTIONS:
PORT 3FA = INTERRUPT ID REGISTER OF 8250 (PRIMARY)
2FA = INTERRUPT ID REGISTER OF 8250 (SECONDARY)
BITS 15,14 ARE ALWAYS 0
PORT 378 = OUTPUT PORT OF PRINTER (PRIMARY)
278 = OUTPUT PORT OF PRINTER (SECONDARY)
3BC = OUTPUT PORT OF PRINTER (MONO-PRINTER)

OUTPUT
(AX) IS SET, BIT SIGNIFICANT, TO INDICATE ATTACHED I/O
BIT 15,14 = NUMBER OF PRINTERS ATTACHED
BIT 13,12 NOT USED
BIT 11,10,9 = NUMBER OF RS232 CARDS ATTACHED
BIT 8 = NOT USED
BIT 7,6 = NUMBER OF DISKETTE DRIVES
    0000 - 01-2 ONLY IF BIT 0 = 1
BIT 5,4 = INITIAL VIDEO MODE
    00 - UNUSED
    01 - 40X25 BW USING COLOR CARD
    10 - 80X25 BW USING COLOR CARD
    11 - 80X25 BW USING BW CARD
BIT 3 = NOT USED
BIT 2 = NOT USED
BIT 1 = MATH COPROCESSOR
BIT 0 = ((PLA 8248 IS INSTALLED))
NO OTHER REGISTERS AFFECTED

ASSUME CS:CODE,DS:DATA

EQUIPMENT_1 PROC FAR
    STI ; >>> ENTRY POINT FOR ORG OF 84DH
    PUSH DS ; INTERRUPTS BACK ON
    CALL DDS ; SAVE SEGMENT REGISTER
    MOV AX,EQUIP_FLAG ; ESTABLISH ADDRESSING
    POP DS ; GET THE CURRENT SETTINGS
    IRET ; RECOVER SEGMENT
    ; RETURN TO CALLER
EQUIPMENT_1 ENDP

--- INT 2 -----
NON-MASKABLE INTERRUPT ROUTINE (REAL MODE)
THIS ROUTINE WILL PRINT A "PARITY CHECK 1 OR 2" MESSAGE
AND ATTEMPT TO FIND THE ADDRESS LOCATION CONTAINING THE
BAD PARITY. IF FOUND, THE SEGMENT ADDRESS WILL BE
PRINTED. IF NO PARITY ERROR CAN BE FOUND (INTERMITTENT
READ PROBLEM) ?????<- WILL BE PRINTED WHERE THE ADDRESS
WOULD NORMALLY GO.

PARITY CHECK 1 = PLANAR BOARD MEMORY FAILURE,
PARITY CHECK 2 = OFF PLANAR BOARD MEMORY FAILURE.

NM1_INT_1 PROC NEAR
ASSUME DS:DATA
PUSH AX ; SAVE ORIG CONTENTS OF AX
IN AL,MFG_PORT ; INCREMENT NMI COUNT
INC AL
JMP SHORT $+2 ; IN DELAY
OUT MFG_PORT,AL ; SET COUNT

IN AL,PORT_B
TEST AL,PARITY_ERR ; PARITY CHECK?

```

```

0021 8A E0           MOV AH, AL          ; SAVE PARITY STATUS
0023 75 03           JNZ NM1_1         ; NO, EXIT FROM ROUTINE
0025 E9 00C1 R       JMP D14          ; YES, CONTINUE
0026

NM1_1:   ----- GET THE SWITCH SETTINGS
0028 B0 AD           MOV AL_DIS_KBD ; DISABLE THE KEYBOARD
002A E8 0000 E         CALL C8042        ; IN AL_PORT_A
002B F0 00             MOV AL_PORT_A ; FLUSH
002F E0 00             MOV AL_PORT_B ; SET THE SWITCH SETTINGS
0031 F8 0000 E         CALL C8042        ; TEST AH,40H
0034 E8 0000 E         CALL OBF_42      ; ISSUE THE COMMAND
0037 E4 60             IN AL_PORT_A ; WAIT FOR OUTPUT BUFF FULL
0039 E6 80             OUT MFG_PORT, AL ; GET THE SWITCH
0041

003B BA ---- R       MOV DX, DATA
003E BE DA             MOV DS, DX
0040 BE 0000 E         MOV SI_OFFSET_D1 ; ADDR OF ERROR MSG
0043 F6 C4 40           TEST AH,40H ; I/O PARITY CHECK
0046 75 03             JNZ NM1_2        ; DISPLAY ERROR MSG
0048 BE 0000 E         MOV SI_OFFSET_D2 ; MUST BE PLANAR
004B

NM1_2:   ----- SET IF LOCATION THAT CAUSED PARITY CHECK CAN BE FOUND
0055 B0 FF             MOV AH, 0          ; INIT AND SET MODE FOR VIDEO
0057 E6 70             MOV AL_CRT_MODE ; CALL VIDEO_IO PROCEDURE
0059 E4 61             INT 10H          ; PRINT ERROR MSG
005B EB 00             CALL P_MSG
005D 00 00             MOV AL, 0FFH ; MASK TRAP
005F E6 61             OUT CMOS_PORT, AL ; IO DELAY
0061 EB 00             IN AL_PORT_B ; AL_RAM_PAR_OFF
0063 24 F3             OR AL, AL ; TOGGLE PARITY CHECK ENABLES
0065 E6 61             OUT AL, RAM_PAR_ON ; IO DELAY
0067 B8 1E 0013 R       MOV BX, MEMORY_SIZE ; GET MEMORY SIZE WORD
006B EC 0C             ADD BX, BX ; SET DIV FLAG TO INCREMENT
006C 2B D2             CLD             ; POINT DX AT START OF MEM
006E

NMI_LOOP:           SUB DX, DX
0070 8E DA             MOV DS, DX
0072 BE C2             MOV ES, DX
0074 B9 8000            MOV CX, 4000H*2 ; SET FOR 64KB SCAN
0075 2B F6             SUB SI, SI ; SET DS TO BE REALTIVE TO
0077 F3 AD             REP LODSW ; START OF ES
0079 E4 61             IN AL_PORT_B ; READ 64KB OF MEMORY
007B B6 C4             XCHG AL, AH ; SEE IF PARITY CHECK HAPPENED
007D 81 FA 4000           CMP DX, 4000H ; SAVE PARITY CHECK
0081 72 0C             JB NM1_3        ; CHECK FOR END OF FIRST 256K
0083 81 FA 8000           CMP DX, 8000H ; CHECK ABOVE 512K
0085 73 0C             JAE NM1_4       ; CHECK FOR IO CHECK
0087 00 00             IN AL_RFC_PORT ; GET THE SWITCH SETTINGS
0088 A8 10             TEST AL, BASE_RAM ; CHECK FOR 2ND 256K ON PLANAR
008D 74 06             JZ NM1_4        ; GO IF NOT
008F F6 C4 80             NMI_3: TEST AH, PRTY_CHK ; CHECK FOR PARITY ERR
0092 EB 04 90             JMP NM1_5        ; CONTINUE
0094 76 C4 40             NMI_4: TEST AH, IO_CHK ; TEST FOR IO ERROR
0096 78 11             JP NM1_5        ; GO PRINT ADDRESS IF IT DID
0098 81 C2 1000            ADD DX, 1000H ; POINT TO NEXT 64K BLOCK
009E 83 EB 40             SUB BX, 16D*4
00A1 75 CB             JNZ NM1_LOOP ; PRINT ROW OF ????? IF PARITY
00A3 BE 0000 E             MOV SI, (OFFSET D2A) ; CHECK COULD NOT BE RE-CREATED
00A6 E8 0000 E             CALL P_MSG
00A8 EA               CLI             ; HALT SYSTEM
00AA F4               HLT             ; HALT SYSTEM
00AB PRT_NM1:           MOV DX, DS ; PRINT SEGMENT VALUE
00AD E8 0000 E             CALL PRT_SEG ; PRINT (S)
00B0 00 00             MOV AX, T1L ; PRINT AL
00B2 E8 0000 E             CALL PRT_HEX ; PRINT AL_T1
00B5 B0 53             MOV AX, T1H ; PRINT AL
00B7 E8 0000 E             CALL PRT_HEX ; PRINT AL_T1
00BA B9 29             CALL PRT_HEX ; PRINT AL
00BF EA               CLI             ; HALT SYSTEM
00CC F4               HLT             ; HALT SYSTEM
00C1

D14:    ----- RESTORE ORIG CONTENTS OF AX
00C3 E9 70             MOV AL, 8FH ; TOGGLE NMI
00C5 EB 00             OUT CMOS_PORT, AL ; IO DELAY
00C7 B0 0F             JMP SHORT $42 ; RESTORE ORIG CONTENTS OF AX
00C9 E6 70             OUT CMOS_PORT, AL
00CB 58               POP AX
00CC CF               IRET
00CD

NM1_INT_1 ENDP
PAGE
-----
```

THIS ROUTINE INITIALIZES THE TIMER DATA AREA IN THE ROM BIOS DATA AREA. IT IS CALLED BY THE POWER ON ROUTINES. IT CONVERTS HR:MIN:SEC FROM CMOS TO TIMER TICKS. IF CMOS IS INVALID, TIMER DATA IS SET TO ZERO.

```

INPUT   NONE PASSED TO ROUTINE BY CALLER
CMOS BYTES USED FOR SETUP
00  SECONDS
02  MINUTES
04  HOURS
0A  REGISTER A (UPDATE IN PROGRESS)
0E  CMOS VALID IF ZERO

OUTPUT
  TIMER_LOW
  TIMER_HIGH
  TIMER_OFH
  ALL REGISTERS UNCHANGED
-----
```

= 0012	COUNTS_SEC	EQU 18
= 0044	COUNTS_MIN	EQU 092
= 0007	COUNTS_HOUR	EQU 7
= 0070	CMOS_ADR	EQU 70H
= 00E1	CMOS_DATA	EQU 71H
= 0000	CMOS_VALID	EQU 0EH
= 0002	CMOS_SECONDS	EQU 00H
= 0004	CMOS_HOURS	EQU 04H
= 000A	CMOS_REGA	EQU 0AH
= 0080	UPDATE_TIMER	EQU 80H
= 00CD	SET_TOD PROC	NEAR
	PUSHA	

```

00CD 60          +     DB    060H
00CE 1E          PUSH   DS
ASSUME DS:DATA
00CF B8  ---- R MOV    AX,DATA
00D2 8E DB        MOV    DS,AX
00D4 2B C0        SUB    AX,AX
00D9 A2 0070 R   MOV    TIMER_OFLL_AL
00D9 A3 00C4 R   MOV    TIMER_LOW_AX
00DC A3 006E R   MOV    TIMER_HIGH_AX
00DF B0 E9        OUT   CMOS_ADR_VALID
00E1 E6 70        OUT   SHORT $+2
00E3 EB 00        IN    AL,CMOS_DATA
00E5 E4 71        AND   AL,0FFFH
00E7 74 04        JNZ   POD_DONE
00E9 75 61        SUB   CX,CX
00ED EB 0A        UIP:  MOV   AL,CMOS_REGA
00EF E8 70        OUT   CMOS_ADR_AL
00F1 F7 E3        JMP   SHORT $+2
00F3 E4 71        IN    AL,CMOS_DATA
00F5 A8 80        TEST  AL,UPDATE_TIMER
00F7 74 05        JZ    READ_SEC
00F9 E2 F2        LOOP  UIP
00FB 74 04        JMP   EB 4F
00FE          READ_SEC
00FE B0 00        MOV   AL,CMOS_SECONDS
0100 E6 70        OUT   CMOS_ADR_AL
0102 EB 00        JMP   SHORT $+2
0104 E4 71        IN    AL,CMOS_DATA
0106 3C 59        CMP   AL,50H
0108 77 4D        JA    TOD_ERROR
CALL  CVT_BINARY
MOV   BX,COUNTS_SEC
0109 B1 E2        NUL   BL
0111 88 C8        MOV   CX,AX
0113 B2 02        MOV   AL,CMOS_MINUTES
0115 E7 70        OUT   CMOS_ADR_AL
0117 EB 00        JMP   SHORT $+2
0119 E4 71        IN    AL,CMOS_DATA
011B 3C 59        CMP   AL,59H
0119 77 38        JA    TOD_ERROR
CALL  CVT_BINARY
MOV   BX,COUNTS_MIN
0122 BB 0444        MUL   BX
0125 F7 E3        ADD   AX,CX
0127 03 C1        MOV   CX,AX
0129 88 C6        MOV   AL,CMOS_HOURS
012B B0 00        OUT   CMOS_ADR_AL
012D 66 00        JMP   SHORT $+2
012F EB 00        IN    AL,CMOS_DATA
0131 E4 71        CMP   AL,23H
0133 3C 23        JA    TOD_ERROR
CALL  CVT_BINARY
MOV   BX,COUNTS_HOUR
0134 BB 00        NUL   BL
0136 C3 07        MOV   DX,AX
013E F6 E3        MUL   BL
0140 03 C1        ADD   AL,CX
0142 83 D2 00        ADC   DX,0000H
0144 89 16 006E R  MOV   TIMER_HIGH_DX
0149 A3 006C R   MOV   TIMER_LOW_AX
014C          POD_DONE:
014C FA          CLI
014D E4 21        IN    AL,021H
014E 28 FE        AND   AL,0FH
0151 66 21        OUT  021H,AL
0153 FB           STI
0154 1F           POP   DS
0155 61          +     DB    061H
0156 C3           RET
0157          TOD_ERROR:
0157 1F           POP   DS
                  ; RESTORE SEGMENT
                  ; RESTORE REGS
0158 61          +     DB    061H
0159 BE 0000 E   MOV   SI,OFFSET CM3
015C 88 0000 E   CALL  E_HSC
015F B0 89        MOV   AL,DIAIG_STATUS
0161 E7 70        OUT  CMOS_PORT,AL
0163 86 C4        XCHG AL,AH
0165 EB 00        JMP   SHORT $+2
0167 64 00        IN    AL,CMOS_PORT+1
0169 DC 04        OR    AL,CMOS_CLK_FAIL
0169 86 C4        XCHG AL,AH
016A E6 70        OUT  CMOS_PORT,AL
016F 86 C4        XCHG AL,AH
0171 E9 00        JMP   SHORT $+2
0173 66 71        OUT  CMOS_PORT+1,AL
0175 C3           RET
0176          SET_TOD ENDP
0176 8A E0        CVT_BINARY PROC  NEAR
0176 8A E0        MOV   AH,AL
0176 8A E0        ISHR  AH,4
0178 D0 EC        + ??0000 LABEL BYTE
0178 D0 EC        + ??0001 LABEL BYTE
0178 CO           + ??0001 LABEL BYTE
0178 CO           + ??0001 LABEL BYTE
017A 04           + ??0001 LABEL BYTE
017A 04           + ??0001 LABEL BYTE
017A 24 0F        AND   AH,4
017D D5 0A        ADD   AH,4
017F C3           RET
0180          CVT_BINARY ENDP
0180 CODE ENDN
                  ; UNPACK 2 BCD DIGITS IN AL
0178 D0 EC        PROC  NEAR
0178 D0 EC        MOV   CS,?0000
0178 D0 EC        ORG   000H
0178 D0 EC        OFFSET CS:??0000
0178 D0 EC        ORG   CS:??0001
0178 D0 EC        OFFSET CS:??0001
0178 D0 EC        AL,0FH
                  ; RESULT IS IN AX
                  ; CONVERT UNPACKED BCD TO BINARY

```



TITLE 11/22/83 BIOS1  
 .LIST  
 C INCLUDE SEGMENT.SRC  
 C CODE SEGMENT BYTE PUBLIC  
 C  
 EXTRN DDS:NEAR  
 EXTRN PRT\_HEX:NEAR  
 EXTRN D1:NEAR  
 EXTRN D2:NEAR  
 EXTRN P\_MSG:NEAR  
 EXTRN D2A:NEAR  
 EXTRN PRG\_SEC:NEAR  
 EXTRN PROC\_SHUTDOWN:NEAR  
  
 PUBLIC SHUT9  
 PUBLIC GATE\_A20  
 PUBLIC CASSETTE\_10\_1  
  
 ---- INT 15 ----  
 INPUT - CASSETTE I/O FUNCTIONS  
 (AH) = 00  
 (AH) = 01  
 (AH) = 02  
 (AH) = 03  
 RETURNS FOR THESE FUNCTIONS ALWAYS (AH) = 86H, CF = 1  
 IF CASSETTE PORT NOT PRESENT  
  
 INPUT - UNUSED FUNCTIONS  
 (AH) = 04 THROUGH 7F  
 RETURNS FOR THESE FUNCTIONS ALWAYS (AH) = 86H, CF = 1  
  
 Extensions  
 (AH) = 80H DEVICE OPEN  
 (BX) = DEVICE ID  
 (CX) = PROCESS ID  
  
 (AH) = 81H DEVICE CLOSE  
 (BX) = DEVICE ID  
 (CX) = PROCESS ID  
  
 (AH) = 82H PROGRAM TERMINATION  
 (BX) = DEVICE ID  
  
 (AH) = 83H EVENT\_WAIT  
 (AL) = 0 SET INTERVAL  
 (ES:BX) POINTER TO A BYTE IN CALLERS MEMORY  
 THAT WILL HAVE THE HIGH ORDER BIT SET  
 AS SOON AS POSSIBLE AFTER THE INTERVAL  
 ENDURES.  
 (CX,DX) NUMBER OF MICROSECONDS TO ELAPSE BEFORE  
 POSTING.  
 (AL) = 1 CANCEL  
  
 (AH) = 84H JOYSTICK SUPPORT  
 (DX) = 0 READ ADJUSTED SWITCH SETTINGS  
 RETURNS AL = SWITCH SETTINGS (BITS 7-4)  
 (DX) = 1 READ THE RESISTIVE INPUTS  
 RETURNS AX = A(X) VALUE  
 BX = A(Y) VALUE  
 CX = B(X) VALUE  
 DX = B(Y) VALUE  
  
 (AH) = 85H SYSTEM REQUEST KEY PRESSED  
 (AL) = 00 MAKE OF KEY  
 (AL) = 01 BREAK OF KEY  
  
 (AH) = 86H WAIT  
 (CX,DX) NUMBER OF MICROSECONDS TO ELAPSE BEFORE  
 RETURN TO CALLER  
  
 (AH) = 87H MOVE\_BLOCK  
 (CX) NUMBER OF WORDS TO MOVE  
 (ES:SI) POINTER TO DESCRIPTOR TABLE  
  
 (AH) = 88H EXTENDED MODE; SIZE DETERMINE  
 (AH) = 89H PROCESSOR TO VIRTUAL MODE  
  
 (AH) = 90H DEVICE BUSY LOOP  
 (AL) SEE TYPE CODE  
  
 (AH) = 91H INTERRUPT COMPLETE FLAG SET  
 (AL) TYPE CODE  
 00H -> 7FH  
 SERIALLY REUSABLE DEVICES;  
 OPERATING SYSTEM MUST SERIALIZE  
 ACCESS  
 80H -> BFH  
 REENTRANT DEVICES; ES:BX IS  
 USED TO DISTINGUISH DIFFERENT  
 CALLS (MULTIPLE I/O CALLS ARE  
 ALLOWED SIMULTANEOUSLY)  
 COH -> FFH  
 WAIT ONLY CALLS; THERE IS NO  
 COMPLEMENTARY 'POST' FOR THESE  
 WAITS -- THESE ARE TIMEOUT  
 ONLY. TIMES ARE FUNCTION NUMBER:  
 DEPENDENT  
  
 TYPE DESCRIPTION TIMEOUT  
 00H = DISK YES  
 01H = DISKETTE YES  
 02H = KEYBOARD NO  
 80H = NETWORK NO  
 ES:BX -> NCB  
 FDH = DISKETTE MOTOR START YES  
 FEH = PRINTER YES  
  
 ASSUME CS:CODE  
 CASSETTE\_10\_1 PROC FAR  
 STI  
 CMP AH, 80H ; CHECK FOR RANGE  
 JE C1 ; RETURN IF 00-7FH  
 SUB AH, 80H ; BASE ON 0  
 OR AH, AH  
 JZ DEV\_OPEN ; DEVICE OPEN  
 DEC AH  
 JZ DEV\_CLOSE ; DEVICE CLOSE  
 DEC AH  
 JZ PROG\_TERM ; PROGRAM TERMINATION  
 DEC AH  
 JZ EVENT\_WAIT ; EVENT WAIT  
 DEC AH  
 JZ JOY\_STICK ; JOYSTICK BIOS  
 DEC AH  
 JZ SYS\_REQ ; SYSTEM REQUEST KEY  
 DEC AH  
 JZ C1\_A ; WAIT  
 DEC AH ;

```

0027 75 06          JNZ    C1_B      ; MOVE BLOCK
0029 E9 0183 R      JMP    C1_A:    ; WAIT
002C E9 0132 R      C1_A:  JMP    WAIT
002F FE CC          C1_B:  DEC    AH
0031 75 03          JNZ    C1_C      ; GO GET THE EXTENDED MEMORY
0033 E9 03D2 R      JMP    C1_C:    EXT_MEMORY
0036 FE CC          C1_C:  DEC    AH
0038 75 03          JNZ    C1_D      ; CHECK FOR FUNTION 89
003A E9 03E6 R      JMP    C1_D:    SET_VMODE
003D 80 EC 07          C1_D:  SUB    AH,7
0040 75 03          JNZ    C1_E      ; CHECK FOR FUNCTION 90
0042 E9 0475 R      JMP    C1_E:    DEVICE_BUSY
0045 FE CC          C1_E:  DEC    AH
0047 75 03          JNZ    C1_F      ; CHECK FOR FUNCTION 8B
0049 E9 0479 R      JMP    C1_F:    INT_COMPLETE
004C B4 86          C1:   MOV    AH,66H
004E F9              STC    ; SET BAD COMMAND
004F CA 0002         C1_F:  RET    2
0052               DEVP_OPEN:
0052               DEVP_CLOSE:
0052               PROG_TERM:
0052               SYS_REQ:  JMP    C1_F      ;RETURN
0054             CASSETTE_10_1  ENDP
0054               ASSUME CS:CODE,DS:DATA
0054               EVENT_WAIT PROC NEAR
0054     .ASSUME CS:CODE,DS:DATA
0055 1E              PUSH   DS
0055 E8 0000 E          CALL   DDS
0056 F6 06 00AO R 01  TEST   RTC_WAIT_FLAG,01
0057 74 04          JZ    EVENT_WAIT_1
0058 1F              POP    DS
0059 F7              STC    ; SET ERROR
0060 EB EC          JMP    C1_F      ; RETURN
0063 FA              CLT    ; NO INTERRUPTS ALLOWED
0064 E4 A1          IN    AL,OATH
0065 1F              AND    AL,OFEH
0066 E4 A1          OUT   OAH1_AL
0067 BC 06 009A R 01  MOV    USER_FLAG_SEG,ES
0068 89 1E 0098 R      MOV    USER_FLAG,BX
0072 89 0E 009E R      MOV    RTC_HIGH,CX
0076 89 06 009C R      MOV    RTC_LOW,DW
0077 89 00 00AO R 01  MOV    RTC_WAIT_FLAG,01
007F B0 0B          MOV    AL,0BH
0081 E6 70          OUT   CMOS_PORT_AL
0083 E4 71          IN    AL,CMOS_PORT+1
0085 24 7F          AND    AL,07FH
0086 E6 71          OUT   CMOS_PORT+1,AL
0089 00 00            OR    AL,040H
008A B0 0B          PUSH   AL
008C E6 70          MOV    AL,0BH
008E 58              OUT   AL,0BH
008F E6 71          POP    AX
0090 F7              STI    DS
0092 1F              POP    DS
0093 EB BA          JMP    C1_F      ; ENABLE INTERRUPTS
0095               EVENT_WAIT ENDP
;--- JOY_STICK -----
; THIS ROUTINE WILL READ THE JOYSTICK PORT
;----- INPUT -----
; (DX)=0 READ THE CURRENT SWITCHES
; RETURNS (AL)=SWITCH SETTINGS IN BITS 7-4
;----- (DX)=1 -----
; READ THE RESISTIVE INPUTS
; RETURNS (AX)=A(x) VALUE
; (BX)=A(y) VALUE
; (CX)=B(x) VALUE
; (DX)=B(y) VALUE
;----- CY FLAG ON IF NO ADAPTER CARD OR INVALID CALL
;----- JOY_STICK -----
; ASSUME CS:CODE
JOY_STICK PROC NEAR
0095 FB              STI    ; INTERRUPTS BACK ON
0096 BB C2          MOV    AX,DX
0098 BA 0201         MOV    DX,201H ; GET SUBFUNCTION CODE
0099 0A C0          OR    AL,AL
009D 74 09          JZ    JOY_2
009F FE C8          DEC    AL
00A0 0A              JZ    JOY_3
00A3 EB A7          JMP    C1_F      ; READ RESISTIVE INPUTS
00A5 FB              STI    ; GO TO ERROR RETURN
00A6 EB A7          JMP    C1_F      ; GO TO COMMON RETURN
;----- JOY_2 -----
;----- JOY_3 -----
;----- TEST_CORD -----
TEST_CORD PROC NEAR
00AD B3 01          MOV    BL,1
00AF E8 00CB R      CALL   TEST_CORD
00B2 51              PUSH   CX
00B3 B3 02          MOV    BL,2
00B5 E8 00CB R      CALL   TEST_CORD
00B8 51              PUSH   CX
00B9 B3 04          MOV    BL,4
00BB E8 00CB R      CALL   TEST_CORD
00BE 51              PUSH   CX
00BF B3 08          MOV    BL,6
00C1 E8 00CB R      CALL   TEST_CORD
00C4 BB D1          MOV    DX,CX
00C6 59              POP    CX
00C7 5B              POP    BX
00C8 58              POP    AX
00C9 EB DA          JMP    JOY_1
;----- FINISHED - RETURN
00CB TEST_CORD      PROC NEAR
00CB 52              PUSH   DX

```

```

00CC FA
005D B0 00
005F E6 43
0061 FB 00
0063 E4 40
0065 FB 00
0067 8A E0
0069 8A E0
00DB 86 E0
00DE B9 0FFF
00E1 EE
00E2 EB 00
00E3 EB 00
00E4 EC
00E5 84 C3
00E7 EO FB
00E9 83 00 00
00E9 50
00E9 75 04
00EF 2B C9
00F1 EB 2D
00F3 EB 00
00F5 E6 43
00F7 EB 00
00F9 E4 40
00FB 8A E0
00FD EB 00
00FF EB 40
0101 86 E0

0103 3B C8
0105 73 0B
0107 52
0108 BA FFFF

010B 2B D0
010D 03 CA
010F 5A
0110 EB 02

0112 2B C8
0114 1E 1FF0
0118 D1 E9
011A D1 E9
011C D1 E9
011E D1 E9

0120 FB
0120 BA 0201
0124 51
0125 50
0126 B9 04FF
0129
0129 EC
012A A8 0F
012C EO FB

012E 58
012F 59
0130 5A

0131 C3
0132
0132 RET
0132 TEST_CORD
0132 JOY_STICK
0132 ENDP
0132
0132 WAIT
0132 PROC NEAR
0132 PUSH DS
0132 CALL DDS
0132 TEST RTC_WAIT_FLAG,01 ; TEST FOR FUNCTION ACTIVE
0132 JZ WAIT_1
0132 POP DS
0132 STC
0132 JMP C1_F ; SET ERROR
0132
0141 FA
0143 E4 A1
0145 24 FE
0147 E6 A1
0149 8C 1E 009A R
014D G0 06 00A0 R 01
0150 89 05 009C R
0152 89 16 009C R
0154 89 05 009C R
0157 89 16 009C R
015B C6 06 00A0 R 01
0160 B0 0B
0162 E6 70
0164 24 71
0166 24 7F
0168 OC 40
016A 50
016B B0 0B
016D E6 70
016F 24 71
0170 E6 71
0172 FB
0173 F6 06 00A0 R 80
0174 F6 06 00A0 R 80
017A C6 06 00A0 R 00
017F 1F
0180 E9 004F R

0183 ENDP

TEST_CORD_1:
IN AL,DX ; READ VALUES
OUT AL,00 ; HAS PULSE ENDED?
JMP SHORT,$+2
IN AL,TIMER ; READ HIGH BYTE OF TIMER 0
XCHG AH,AL ; REARRANGE TO HIGH,LOW
PUSH AX ; SAVE
MOV CX,4FFF ; SET COUNT
OUT DX,AL ; FIRE TIMER
JMP SHORT,$+2

TEST_CORD_2:
IN AL,DX ; SET UP TO LATCH TIMER 0
OUT AL,00 ; SET UP TO LATCH TIMER 0
JMP SHORT,$+2
IN AL,TIMER ; READ LOW BYTE OF TIMER 0
MOV AH,AL ; READ HIGH BYTE OF TIMER 0
JMP SHORT,$+2
IN AL,TIMER ; REARRANGE TO HIGH,LOW
XCHG AH,AL ; READ HIGH BYTE OF TIMER 0
JMP SHORT,$+2

TEST_CORD_3:
CMP CX,AX ; CHECK FOR COUNTER WRAP
JAE TEST_CORD_4 ; GO IF NO
PUSH DX
MOV DX,-1 ; COUNT

TEST_CORD_4:
SUB DX,AX ; ADJUST FOR WRAP
ADD CX,DX
POP DX
JMP SHORT TEST_CORD_5

TEST_CORD_5:
SUB CX,AX ; ADJUST
ADD CX,DX
SHR CX,1
SHR CX,1
SHR CX,1
SHR CX,1

TEST_CORD_6:
STI ; INTERRUPTS BACK ON
MOV DX,201H ; FLUSH OTHER INPUTS
PUSH CX
PUSH AX
MOV CX,4FFF ; COUNT
TEST AL,0FH
LOOPNZ TEST_CORD_6

TEST_CORD_7:
IN AL,DX ; SET COUNT
TEST AL,0FH
LOOPNZ TEST_CORD_7

TEST_CORD_8:
POP AX ; RETURN
POP CX
POP DX ; SET COUNT
RET ; RETURN

TEST_CORD
ENDP

WAIT:
PROC NEAR
PUSH DS ; SAVE
CALL DDS
TEST RTC_WAIT_FLAG,01 ; TEST FOR FUNCTION ACTIVE
JZ WAIT_1
POP DS
STC
JMP C1_F ; SET ERROR
RET ; RETURN

WAIT_1:
CLI ; NO INTERRUPTS ALLOWED
IN AL,0A1H ; ENSURE INTERRUPT UNMASKED
AND AL,0FEH
OUT AL,0A1H,AL
MOV USER_FLAG_SEG,DS ; SET UP TRANSFER TABLE
MOV USER_FLAG_OFFSET RTC_WAIT_FLAG
MOV RTC_HIGH,DX
MOV RTC_LOW,DX
MOV RTC_WAIT_FLAG,01 ; SET ON FUNCTION ACTIVE SWITCH
OUT AL,0BH ; ENABLE PIE
CMOS_PORT,AL
IN AL,07FH ; AL=07FH
AND AL,07FH
OR AL,040H
PUSH AX
MOV AL,0BH
OUT AL,0BH ; CMOS_PORT,AL
POP AX
OUT CMOS_PORT+1,AL ; CMOS_PORT+1,AL
STI ; ENABLE INTERRUPTS

WAIT_2:
TEST RTC_WAIT_FLAG,0B0H ; CHECK FOR END OF WAIT
JZ WAIT_2
MOV RTC_WAIT_FLAG,0 ; SET FUNCTION INACTIVE
POP DS
JMP C1_F

WAIT PAGE
ENDP

----- INT 15 (FUNCTION 87H - MOVE BLOCK) -----
PURPOSE:
THIS BIOS FUNCTION PROVIDES A MEANS TO TRANSFER A BLOCK OF STORAGE TO AND FROM STORAGE ABOVE THE 1 MEG ADDRESS RANGE IN VIRTUAL (PROTECTED) MODE.

ENTRY REQUIREMENTS:
ES:SI POINTS TO A DESCRIPTOR TABLE (DPT) BUILT BEFORE INTERRUPTING TO THIS FUNCTION. THESE DESCRIPTORS ARE USED BY THIS FUNCTION TO PERFORM THE BLOCK MOVE. THE SOURCE AND TARGET DESCRIPTORS BUILT BY THE USER MUST HAVE THE SEGMENT LENGTH = 2 * CX - 1 OR GREATER. THE DATA ACCESS RIGHTS BYTE WILL BE SET TO CPL0-R/W(93H). THE 24 BIT ADDRESS (BYTE HI, WORD LOW) WILL BE SET TO THE TARGET/SOURCE.

THE DESCRIPTORS ARE DEFINED AS FOLLOWS:

```

1. THE FIRST DESCRIPTOR IS THE REQUIRED DUMMY.  
(USER INITIALIZED TO 0)
2. THE SECOND DESCRIPTOR POINTS TO THE GDT TABLE AS  
A DATA SEGMENT.  
(USER INITIALIZED TO 0)
3. THE THIRD DESCRIPTOR IS THE DESCRIPTOR THAT POINTS  
TO THE SOURCE TO BE MOVED. (FROM)  
(USER INITIALIZED)
4. THE FOURTH DESCRIPTOR IS THE DESCRIPTOR THAT POINTS  
TO THE DESTINATION. (TO)  
(USER INITIALIZED)
5. THE FIFTH IS A DESCRIPTOR THAT THIS FUNCTION USES  
TO CREATE A VIRTUAL CODE SEGMENT  
(USER INITIALIZED TO 0)
6. THE SIXTH IS A DESCRIPTOR THAT THIS FUNCTION USES  
TO CREATE A VIRTUAL STACK SEGMENT. (POINTS TO USERS  
STACK)  
(USER INITIALIZED TO 0)

PAGE

----- INT 15 (FUNCTION 87H CONTINUED) -----

AH=87 (FUNCTION CALL)  
ES:SI = LOCATION OF THE GDT TABLE BUILD BY ROUTINE  
USING THIS FUNCTION.  
CX = WORD COUNT OF STORAGE BLOCK TO BE MOVE.

NOTE: MAX COUNT = 8000H 32K WORDS

EXIT PARAMETERS:

AH = 0 IF SUCCESSFUL  
AH = 1 IF RAM PARITY (PARITY ERROR IS CLEARED)  
AH = 2 IF EXCEPTION INTERRUPT ERROR  
AH = 3 IF GATE ADDRESS LINE 20 FAILED  
ALL REGISTER ARE RESTORED EXCEPT AX.  
CARRY FLAG = 1 IF ERROR  
ZERO FLAG = 1 IF SUCCESSFUL

CONSIDERATIONS:

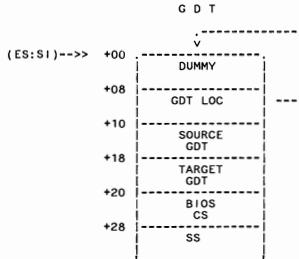
NO INTERRUPTS ARE ALLOWED.  
TIME OF DAY (ADJUSTED BY USER????)

DESCRIPTION:

1. CLI (NO INTERRUPTS ALLOWED) WHILE THIS FUNCTION IS EXECUTING.
2. ADDRESS LINE 20 IS CATED ACTIVE.
3. THE GDT (INTERRUPT DESCRIPTOR TABLE) IS ROM RESIDENT.
4. THE CURRENT USER STACK SEGMENT AND OFFSET IS SAVED.
5. THE GDTR IS LOADED WITH THE OFFSET INTO ES:SI
6. THE IDTR SELECTOR IS ROM RESIDENT AND IS LOADED.
7. THE PROCESSOR IS PUT IN VIRTUAL MODE.
8. THE CS SELECTOR IS LOADED AS THE SOURCE DESCRIPTOR EXTRA SEGMENT IS LOADED WITH THE TARGET DESCRIPTOR.
9. DS:SI (SOURCE) ES:DI (TARGET) REP MOVSW IS EXECUTED.
10. DS:SI SHUTDOWN 09 IS EXECUTED.
11. STACK SEGMENT/OFFSET IS RESTORED.
12. ADDRESS LINE 20 IS CATED.
13. INTERRUPTS ARE ALLOWED.

PAGE

THE FOLLOWING DIAGRAM DEPICTS THE ORGANIZATION OF GDT.



SAMPLE OF SOURCE OR TARGET DESCRIPTOR

SOURCE\_TARGET\_DEF STRUCT

SEG_LIMIT DW	; SEGMENT LIMIT (1-65536 BYTES)
BASE_LO_WORD DW	; 24 BIT SEGMENT PHYSICAL
BASE_HI_BYTE DB	; ADDRESS [0 TO (16M-1)]
DATA_ACC_RIGHTS DB	; ACCESS RIGHTS BYTE
DATA_RESERVED DW	; RESERVED WORD

SOURCE\_TARGET ENDS

THE GLOBAL DESCRIPTOR TABLE (ACTUAL LOCATION POINTED TO BY ES:SI)

0000 00 00 00 00 00 00	DUMMY DQ 0	; FIRST DESCRIPTOR NOT ACCESSIBLE
0008 00 00 00 00 00 00	GDT_LOC DQ 0	; LOCATION OF CALLING ROUTINE GDT
0010 00 00 00 00 00 00	SOURCE DQ 0	; SOURCE DESCRIPTOR
0018 00 00 00 00 00 00	TARGET DQ 0	; TARGET DESCRIPTOR
0020 00 00 00 00 00 00	BIOS_CS DQ 0	; BIOS CODE DESCRIPTOR
0028 00 00 00 00 00 00	TEMP_SS DQ 0	; STACK DESCRIPTOR

BLOCKMOVE\_GDT\_DEF ENDS

```

ASSUME CS:CODE
ASSUME DS:DATA

0183          BLOCKMOVE PROC NEAR
;----- INITIALIZE FOR VIRTUAL MODE
0183  FA      CLI           ; NO INTERRUPTS ALLOWED
0184  FC      CLD           ; SET DIRECTION
0185  60      PUSHA         ; SAVE GENERAL PURPOSE REGS
+    DDH       060H
0186  00      PUSH  ES
0187  1E      PUSH  DS
;----- CLEAR EXCEPTION ERROR FLAG
0188  2A  C0   SUB  AL,AL
018A  E6  80   OUT  MFG_PORT,AL ; SET TO 0
;----- GATE ADDRESS BIT 20 ON
018C  B4  DF   MOV  AH,ENABLE_BIT20
018D  00  03B0 R CALL  GATE_A20
0191  3C  00   CMP  AL,0
0193  7U  07   JZ   BL4
0195  B0  03   MOV  AL,03H
0197  E6  80   OUT  MFG_PORT,AL
0199  E9  0270 R JMP  SHUT9
;----- SET SHUTDOWN RETURN ADDR
019C  B0  8F   BL4:  MOV  AL,SHUT_DOWN
019E  E6  70   INT  CMOS_PORT,AL ; SET THE SHUTDOWN BYTE
01A0  00  00   JMP  SHORT $+2
01A2  B0  09   MOV  AL,9
01A4  E6  71   OUT  CMOS_PORT+1,AL ; TO SHUT DOWN 9
;----- SET UP THE GDT DEFINITION
;----- MAKE A 24 BIT ADDRESS OUT OF THE ES:SI
01A6  8C  C0   MOV  AX,ES
01A8  BB  DE   MOV  BX,SI
01AA  8A  F4   MOV  DH,AH
01AC  80  E6  F0 AND  DH,OF0H
+    ????0000 LABEL BYTE
+    ????0001 SHL  DH,1
+    ????0001 LABEL BYTE
+    ????0001 ORG  OFFSET CS:????0000
+    ????0001 DB   OCOH
+    ????0001 ORG  OFFSET CS:????0001
+    ????0001 DB   4
+    ????0001 AND  AH,00FH
+    ????0001 ISHL  AX,4
+    ????0001 SHL  AX,1
+    ????0001 LABEL BYTE
+    ????0001 ORG  OFFSET CS:????0003
+    ????0001 DB   00AH
+    ????0001 ORG  OFFSET CS:????0004
+    ????0001 DB   4
+    ????0001 ADD  BX,AX
+    ????0001 JNC  BL3A
+    ????0001 INC  DH
+    ????0001 INC  DH
;----- SET THE GDT_LOC
01B5  26  88  74  0C  BL3A:  MOV  ES:[SI].CGDT_LOC.BASE_HI_BYTE,DH ; SET THE HIGH BYTE
01C2  26  89  5C  0A  MOV  ES:[SI].CGDT_LOC.BASE_LO_WORD,BX ; SET THE LOW WORD
;----- LOAD THE IDT
01C6  26  C7  44  08  FFFF  MOV  ES:[SI].CGDT_LOC.SEG_LIMIT_MAX_SEG_LEN
01CC  26  C7  44  0E  0000  MOV  ES:[SI].CGDT_LOC.DATA_RESERVED,0 ; RESERVED
;----- LOAD THE IDT
01D2  BD  02A1 R MOV  BX,OFFSET ROM_IDT_LOC
01D5  2E      SEG0V CS
+    DB   02EH ; LOAD THE IDT
01DC  0F      LIDT [BP]
01D7  8B  5E  00  +    ????0007 DB   00FH ; REGISTER FROM THIS AREA
01DA  00      LABE1 BYTE
01D7  8B  5E  00  +    ????0008 MOV  BX,WORD PTR [BP]
01DA  01      LABE2 BYTE
01D7  01      +    ????0008 ORG  OFFSET CS:????0007
01DA  01      +    ????0008 DB   001H
01D7  01      +    ????0008 ORG  OFFSET CS:????0008
;----- LOAD THE GDTR
;----- LOAD THE GDT
01DA  26      SEG0V ES ; LOAD THE GLOBAL DESCRIPTOR TABLE REG
+    DB   026H
01DB  0F      CGDT [SI].CGDT_LOC
+    DB   00FH
01DC  8B  54  08  +    ????0000 LABEL BYTE
+    ????0000 MOV  DX,WORD PTR [SI].CGDT_LOC
01DF  00      +    ????0000 DB   001H
01DC  01      +    ????0000 ORG  OFFSET CS:????000A
01DF  01      +    ????0000 DB   000H
01DF  01      +    ????0000 ORG  OFFSET CS:????000B
;----- SET THE DATA SEGMENT TO BIOS RAM
01DF  E8  0000  E  CALL  DDS ; SET DS TO DATA AREA
;----- SAVE THE CALLING ROUTINE'S STACK
01E2  8C  D0   MOV  AX,SS ; GET THE STACK SEGMENT
01E3  A3  0069 R MOV  IO_ROM_SEG,AX ; SAVE STACK SEGMENT
01E7  9B  C0   MOV  AX,SP ; SAVE STACK POINTER
01E9  A3  0067 R MOV  IO_ROM_INIT,AX ; ;

PAGE
;----- MAKE A 24 BIT ADDRESS OUT OF THE SS (SP REMAINS USER SP)
01EC  8C  D0   MOV  AX,SS ; GET THE CURRENT STACK SEGMENT
01EE  8A  F4   MOV  DH,AH ; DEVELOP THE HIGH BYTE OF THE 24BIT ADDR
01FO  80  E6  F0 AND  DH,OF0H ; USE ONLY THE HIGH NIBBLE
+    ????0000 LABEL BYTE
+    ????0001 SHL  DH,1
+    ????0000 LABEL BYTE
+    ????0000 ORG  OFFSET CS:????000C
+    ????0001 DB   OCOH

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01F5      +     ORG    OFFSET CS:??0000
01F5      +     DB     4
01F6 80 E4 OF  AND    AH,00H ; STRIP HIGH NIBBLE FROM AH
01F6      +     ISHL   AX,4 ; SHIFT AX
01F9 D1 E0  ??000F LABEL  BYTE
01F9      +     SHL    AX,1
01F9      +     ??0010 LABEL  BYTE
01F9      +     ORG    OFFSET CS:??000F
01F9 C1   ??0011 LABEL  NEAR
01FB      +     DB     OC1H
01FB 04   +     ORG    OFFSET CS:??0010
01FB      +     DB     4
01FB      +     DB     H

;----- SS IS NOW IN POSITION FOR A 24 BIT ADDRESS --> SETUP THE DESCRIPTOR

01FC 26: 88 74 2C  BL3: MOV   ES:[SI].TEMP_SS.BASE_HI_BYTE,DH ; SET THE HIGH BYTE
0200 26: 89 44 2A  MOV   ES:[SI].TEMP_SS.BASE_LO_WORD,AX ; SET THE LOW WORD
0204 26: C7 44 28 FFFF MOV   ES:[SI].TEMP_SS.SEG_LIMIT,MAX_SEG_LEN ; SET THE SS SEGMENT LIMIT
020A 26: C6 44 2D 93  MOV   ES:[SI].TEMP_SS.DATA_ACC_RIGHTS,CPLD_DATA_ACCESS ; SET CPL 0

;----- STACK IS NOW SET --> SET UP THE CODE SEGMENT DESCRIPTOR

0201 26: C6 44 24 OF  MOV   ES:[SI].BIOS_CS.BASE_HI_BYTE,CSEG_H ; HIGH BYTE OF CS=0
0214 26: 80 00 0000  MOV   ES:[SI].BIOS_CS.BASE_LO_BYTE,CSEG_L0 ; LOW WORD OF CS=0
021A 26: C7 44 20 FFFF MOV   ES:[SI].BIOS_CS.SEG_LIMIT,MAX_SEG_LEN
0220 26: C6 44 29 9B  MOV   ES:[SI].BIOS_CS.DATA_ACC_RIGHTS,CPLD_CODE_ACCESS
0225 26: C7 44 26 0000  MOV   ES:[SI].BIOS_CS.DATA_RESERVED,0 ; RESERVED

;----- SWITCH TO VIRTUAL MODE

0228 B8 0001  MOV   AX,VIRTUAL_ENABLE ; MACHINE STATUS WORD NEEDED TO
022E 0F   LMSW   AX ; SWITCH TO VIRTUAL MODE
022F 00 0000  DB    00FH
022F B8 F0  ??0012 LABEL  BYTE
0231      +     MOV   SI,AX
022F ??0013 LABEL  BYTE
022F      +     ORG    OFFSET CS:??0012
022F 01   +     DB    001H
0231      +     ORG    OFFSET CS:??0013
0231 EA   JUMPFAR VIRT,BIOS_CS ; MUST PURGE PRE-FETCH QUEUE
0232 0236 R  +     DB    OEH ; Jump far direct
0234 0020  +     DW    (OFFSET VIRT) ; to this offset
0236      +     DW    BIOS_CS ; in this segment

;----- SET STACK SEGMENT (NEEDED FOR POSSIBLE EXCEPTIONS)

0236 B8 0028  MOV   AX,TEMP_SS ; USER'S SS+SP IS NOT A DESCRIPTOR
0239 8E D0  MOV   SS,AX ; 

;----- SETUP SOURCE/TARGET REGISTERS

0238 B8 0010  MOV   AX,SOURCE ; GET THE SOURCE ENTRY
023E 8E D0  MOV   DS,AX ; 
0240 B8 0018  MOV   AX,TARGET ; GET THE TARGET ENTRY
0243 8E C0  MOV   ES,AX ; 
0245 2B FF  SUB   DI,DI ; SET INDEX REGS TO ZERO
0247 2B F6  SUB   SI,SI ; 
0249 F3/ A5  REP   MOVSW ; MOVE THE BLOCK

;----- CHECK FOR RAM PARITY BEFORE SHUTDOWN

024B E4 61  IN    AL,PORT_B ; GET THE PARITY LATCHES
024D 24 C0  AND   AL,PARITY_ERR ; STRIP UNWANTED BITS
024F 74 1C  JZ    DONE1 ; GO IF NO PARITY ERROR

;----- CLEAR PORT B PARITY BEFORE SHUTDOWN

0251 26: 8B 04  MOV   AX,ES:[SI] ; FETCH CURRENT TARGET DATA
0254 26: 89 04  MOV   ES:[SI],DS:[DI] ; WRITE IT BACK
0255 80 07  MOV   DS:[DI],DS:[DI] ; FETCH CURRENT SOURCE DATA
0259 89 05  MOV   DS:[DI],AX ; WRITE IT BACK
025B 80 01  MOV   AL,01 ; SET PARITY CHECK ERROR
025D E6 80  OUT   MFG_PORT,AL ; 

025F E4 61  IN    AL,PORT_B ; IO DELAY
0261 EB 00  JMP   SHORT,$42 ; 
0263 0C 0C  OR    AL,RAM_PAR_OFF ; TOGGLE PARITY CHECK LATCHES
0265 E6 61  OUT   PORT_B,AL ; 
0267 EB 00  JMP   SHORT,$42 ; IO DELAY
0269 24 F3  AND   AL,RAM_PAR_ON ; 
026B E6 61  OUT   PORT_B,AL ; 

;----- CAUSE A SHUTDOWN

026D E9 0000 E  DONE1: JMP   PROC_SHUTDOWN ; 

;=====RETURN FROM SHUTDOWN=====

0270      +     SHUT9: ;----- ENABLE NMI INTERRUPTS

0272 2A C0  SUB   AL,AL ; 
0272 E6 70  OUT   CMOS_PORT,AL ; 

;----- GATE ADDRESS BIT 20 OFF

0274 B4 DD  MOV   AH,DISABLE_BIT20 ; 
0276 E8 03B0 R CALL   GATE_A20 ; 
0279 3C 00  CMP   AL,0 ; COMMAND ACCEPTED?
027B 74 0A  JZ    DONE3 ; GO IF YES
027D B4 00  IN    AL,MFG_PORT ; CHECK FOR ERROR
027F 3C 00  CMP   AL,0 ; WAS THERE AN ERROR?
0281 75 04  JNZ   DONE3 ; GO IF YES
0283 B0 03  MOV   AL,03H ; SET ERROR FLAG
0285 E6 80  OUT   MFG_PORT,AL ; 

;----- RESTORE USERS STACK

0287 E8 0000 E  DONE3: CALL   DDS ; SET DS TO DATA AREA
028A A1 0069 R  MOV   AX,IO_ROM_SEG ; SAVE STACK SEGMENT
028D 8E D0  MOV   SS,AX ; RESTORE THE STACK POINTER
028F A1 0067 R  MOV   AX,IO_ROM_INIT ; 
0292 8B E0  MOV   SP,AX ; 

;----- RESTORE THE USER DATA SEGMENT

0294 1F   POP   DS ; RESTORE USER DATA SEGMENT

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0295 07      POP    ES      ; RESTORE USER EXTRA SEGMENT
0296 61      POPA   ; RESTORE THE GENERAL PURPOSE REGS
0297 86 C4    XCHG  AL,AH ; SAVE AL

0299 E4 80    IN     AL,MFG_PORT ; CHECK THE ENDING STATUS
029B 3C 00    CMP    AL,0   ; SET THE ZERO FLAG
029D 00 E0    XCHG  AH,AL ; RETURN INTERRUPTS ON
029F FB      STII   ; TURN INTERRUPTS ON
02A0 CF      IRET   ; RETURN TO USER

;----- ROM IDT LOCATION
= 0100 ROM_IDT_LEN EQU 32*8 ; SIZE OF THE EXCEPTION INTERRUPTS
02A1 ROM_IDT_LOC:

02A1 0100 R + IDT_GDT_DEF ROM_IDT_LEN,ROM_IDT,CSEG@_HI
02A3 02A7 R + DW    ROM_IDT_LEN ; Segment limit
02A5 0F      DW    ROM_IDT ; Segment base address - low word
02A6 00      DB    CSEG@_HI ; Segment base address - high byte
02A6 00      DB    0       ; Reserved

;----- THE ROM EXCEPTION INTERRUPT VECTORS
02A7 ROM_IDT:
;EXCEPTION 00
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02A7 03A7 R + DW    EX_INT ; Destination offset
02A9 0020 R + DW    BIOS_CS ; Destination segment selector
02AB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02AC 87      + DB    TRAP_GATE ; Access rights byte
02AD 0000 R + DW    0       ; Reserved
;EXCEPTION 01
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02AF 03A7 R + DW    EX_INT ; Destination offset
02B1 0020 R + DW    BIOS_CS ; Destination segment selector
02B3 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02B4 87      + DB    TRAP_GATE ; Access rights byte
02B5 0000 R + DW    0       ; Reserved
;EXCEPTION 02
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02B7 03A7 R + DW    EX_INT ; Destination offset
02B9 0020 R + DW    BIOS_CS ; Destination segment selector
02BB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02BC 87      + DB    TRAP_GATE ; Access rights byte
02BD 0000 R + DW    0       ; Reserved
;EXCEPTION 03
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02BF 03A7 R + DW    EX_INT ; Destination offset
02C1 0020 R + DW    BIOS_CS ; Destination segment selector
02C3 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02C4 87      + DB    TRAP_GATE ; Access rights byte
02C5 0000 R + DW    0       ; Reserved
;EXCEPTION 04
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02C7 03A7 R + DW    EX_INT ; Destination offset
02C9 0020 R + DW    BIOS_CS ; Destination segment selector
02CB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02CC 87      + DB    TRAP_GATE ; Access rights byte
02CD 0000 R + DW    0       ; Reserved
;EXCEPTION 05
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02CF 03A7 R + DW    EX_INT ; Destination offset
02D1 0020 R + DW    BIOS_CS ; Destination segment selector
02D3 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02D4 87      + DB    TRAP_GATE ; Access rights byte
02D5 0000 R + DW    0       ; Reserved
;EXCEPTION 06
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02D7 03A7 R + DW    EX_INT ; Destination offset
02D9 0020 R + DW    BIOS_CS ; Destination segment selector
02DB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02DC 87      + DB    TRAP_GATE ; Access rights byte
02DD 0000 R + DW    0       ; Reserved
;EXCEPTION 07
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02DF 03A7 R + DW    EX_INT ; Destination offset
02E1 0020 R + DW    BIOS_CS ; Destination segment selector
02E3 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02E4 87      + DB    TRAP_GATE ; Access rights byte
02E5 0000 R + DW    0       ; Reserved
;EXCEPTION 08
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02E7 03A7 R + DW    EX_INT ; Destination offset
02E9 0020 R + DW    BIOS_CS ; Destination segment selector
02EB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02EC 87      + DB    TRAP_GATE ; Access rights byte
02ED 0000 R + DW    0       ; Reserved
;EXCEPTION 09
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02EF 03A7 R + DW    EX_INT ; Destination offset
02F1 0020 R + DW    BIOS_CS ; Destination segment selector
02F3 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02F4 87      + DB    TRAP_GATE ; Access rights byte
02F5 0000 R + DW    0       ; Reserved
;EXCEPTION 10
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02F7 03A7 R + DW    EX_INT ; Destination offset
02F9 0020 R + DW    BIOS_CS ; Destination segment selector
02FB 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
02FC 87      + DB    TRAP_GATE ; Access rights byte
02FD 0000 R + DW    0       ; Reserved
;EXCEPTION 11
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
02FF 03A7 R + DW    EX_INT ; Destination offset
0301 0020 R + DW    BIOS_CS ; Destination segment selector
0303 00      DB    0       ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
0304 87      + DB    TRAP_GATE ; Access rights byte
0305 0000 R + DW    0       ; Reserved
;EXCEPTION 12
        DESCRIPTOR_DEF GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0307 03A7 R + DW    EX_INT ; Destination offset
0309 0020 R + DW    BIOS_CS ; Destination segment selector

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030B 00 + nges) DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
030C 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
030D 0000 + + + DW 0 ; Reserved
;EXCEPTION 13
030F 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0311 0020 + + + DW EX_INT ; Destination offset
0313 00 + + + DW BIOS_CS ; Destination segment selector
0314 87 + + + DW 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0315 0000 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0317 03A7 R + + + DW 0 ; Access rights byte
0319 0020 + + + DW BIOS_CS ; Destination segment selector
031B 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
031C 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
031D 0000 + + + DW 0 ; Reserved
;EXCEPTION 15
031F 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0321 0020 + + + DW EX_INT ; Destination offset
0323 00 + + + DW BIOS_CS ; Destination segment selector
0324 87 + + + DW 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0325 0000 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0327 03A7 R + + + DW 0 ; Reserved
;EXCEPTION 17
0329 0020 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0331 00 + + + DW EX_INT ; Destination offset
0333 00 + + + DW BIOS_CS ; Destination segment selector
0334 87 + + + DW 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0335 0000 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0337 03A7 R + + + DW 0 ; Reserved
;EXCEPTION 19
0339 0020 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0341 00 + + + DW EX_INT ; Destination offset
0343 00 + + + DW BIOS_CS ; Destination segment selector
0344 87 + + + DW 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0345 0000 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0347 03A7 R + + + DW 0 ; Reserved
;EXCEPTION 20
0349 0020 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0351 00 + + + DW BIOS_CS ; Destination segment selector
0353 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0354 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0355 0000 + + + DW 0 ; Reserved
;EXCEPTION 21
0356 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0358 0020 + + + DW EX_INT ; Destination offset
0360 00 + + + DW BIOS_CS ; Destination segment selector
0362 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0363 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0365 0000 + + + DW 0 ; Reserved
;EXCEPTION 22
0367 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0369 0020 + + + DW EX_INT ; Destination offset
0371 00 + + + DW BIOS_CS ; Destination segment selector
0373 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0374 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0375 0000 + + + DW 0 ; Reserved
;EXCEPTION 24
0377 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0379 0020 + + + DW EX_INT ; Destination offset
0381 00 + + + DW BIOS_CS ; Destination segment selector
0383 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0384 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0385 0000 + + + DW 0 ; Reserved
;EXCEPTION 26
0387 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0389 0020 + + + DW EX_INT ; Destination offset
0391 00 + + + DW BIOS_CS ; Destination segment selector
0393 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0394 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0396 0000 + + + DW 0 ; Reserved
;EXCEPTION 27
0398 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0400 0020 + + + DW EX_INT ; Destination offset
0402 00 + + + DW BIOS_CS ; Destination segment selector
0404 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
0406 87 + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0408 0000 + + + DW 0 ; Reserved
;EXCEPTION 28
0410 03A7 R + + + DESCR_DEF_GATE,EX_INT,BIOS_CS,0,TRAP_GATE
0412 0020 + + + DW EX_INT ; Destination offset
0414 00 + + + DW BIOS_CS ; Destination segment selector
0416 00 + + + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha

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0387 03A7 R + DW EX_INT ; Destination offset
0389 0020 + DW BIOS_CS ; Destination segment selector
038B 00 + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
038C 87 + DW TRAP_GATE ; Access rights byte
038D 0000 ; EXCEPTION 29
038F 03A7 R + DW EX_INT ; Destination offset
0391 0020 + DW BIOS_CS ; Destination segment selector
0393 00 + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
0394 87 + DW TRAP_GATE ; Access rights byte
0395 0000 ; EXCEPTION 30
0397 03A7 R + DW EX_INT ; Destination offset
0399 0020 + DW BIOS_CS ; Destination segment selector
039B 00 + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
039C 87 + DW TRAP_GATE ; Access rights byte
039D 0000 ; EXCEPTION 31
039F 03A7 R + DW EX_INT ; Destination offset
03A1 0020 + DW BIOS_CS ; Destination segment selector
03A3 00 + DB 0 ; Word count for stack-to-stack copy (only for call gates when PL cha
nges)
03A4 87 + DW TRAP_GATE ; Access rights byte
03A5 0000 + DW 0 ; Reserved
;----- EXCEPTION INTERRUPT HANDLER
03A7
03A7 B0 02 MOV AL,02H ; SET EXCEPTION INT
03A9 E8 80 OUT MFG_PORT_AL
03AB E9 0000 E JMP PROC_SHUTDOWN ; CAUSE A EARLY SHUTDOWN
03AE EB FE EX_INTT: JMP EX_INTT ; STAY HERE TILL SHUTDOWN
03B0 BLOCKMOVE ENDP
PAGE
;----- GATE_A20
THIS ROUTINE CONTROLS A SIGNAL WHICH GATES ADDRESS BIT 20.
THE GATE A20 SIGNAL IS AN OUTPUT OF THE 8042 SLAVE PROCESSOR.
ADDRESS BIT 20 SHOULD BE GATED ON BEFORE ENTERING PROTECTED MODE.
IT SHOULD BE GATED OFF AFTER ENTERING REAL MODE FROM PROTECTED
MODE.
INPUT [(AH)=DH ADDRESS BIT 20 GATE OFF. (A20 ALWAYS ZERO)]
[(AH)=DF ADDRESS BIT 20 GATE ON. (A20 CONTROLLED BY 80286)]
OUTPUT [(AL)=0 OPERATION SUCCESSFUL 8042 HAS ACCEPTED COMMAND.
(AL)=2 FAILURE=8042 UNABLE TO ACCEPT COMMAND.
;----- GATE_A20 PROC
03B0 FA CLI ;DISABLE INTERRUPTS WHILE USING 8042
03B1 E8 03C7 R CALL EMPTY_8042 ;INSURE 8042 INPUT BUFFER EMPTY
03B2 F2 00 JZ GATE_A20_RETURN ;RETURN IF 8042 UNABLE TO ACCEPT COMMAND
03B6 D1 MOV AL,0DH ;8042 COMMAND TO WRITE OUTPUT PORT
03B8 E6 64 OUT STATUS_PORT_AL ;OUTPUT COMMAND TO 8042
03B9 E8 03C7 R CALL EMPTY_8042 ;WAIT FOR 8042 TO ACCEPT COMMAND
03BD 75 07 JNZ GATE_A20_RETURN ;RETURN IF 8042 UNABLE TO ACCEPT COMMAND
03BF 8A C4 MOV AL,AH ;8042 PORT DATA
03C1 E6 60 OUT PORT_A_AL ;OUTPUT PORT DATA TO 8042
03C3 E8 03C7 R CALL EMPTY_8042 ;WAIT FOR 8042 TO ACCEPT PORT DATA
;----- 8042 OUTPUT WILL SWITCH WITHIN 20 USEC OF ACCEPTING PORT DATA -----
03C6 C3 GATE_A20_RETURN:
RET
;----- EMPTY_8042
THIS ROUTINE WAITS FOR THE 8042 INPUT BUFFER TO EMPTY.
INPUT NONE
OUTPUT [(AL)=0 8042 INPUT BUFFER EMPTY (ZERO FLAG SET)]
[(AL)=2 TIME OUT, 8042 INPUT BUFFER FULL (NON-ZERO FLAG SET)]
EMPTY_8042:
SUB CX,CX ;SAVE CX
SUB CX,CX ;CX=0, WILL BE USED AS TIME OUT VALUE
EMPTY_LOOP:
IN AL,STATUS_PORT ;READ 8042 STATUS PORT
AND AL,INP_BUFS_FULL ;TEST INPUT BUFFER FULL FLAG (BIT 1)
LOOPNZ EMPTY_LOOP ;LOOP UNTIL INPUT BUFFER EMPTY OR TIME OUT
POP CX ;RESTORE CX
RET
;----- GATE_A20 ENDP
PAGE
INT 15 (FUNCTION 88H - 10 MEMORY SIZE DETERMINE)
EXT_MEMORY
THIS ROUTINE RETURNS THE AMOUNT OF MEMORY IN THE
SYSTEM THAT IS LOCATED STARTING AT THE 1024K ADDRESSING
RANGE AS DETERMINED BY THE POST ROUTINES.
NOTE THAT THE SYSTEM MAY NOT BE ABLE TO USE I/O MEMORY
UNLESS THERE IS A FULL COMPLEMENT OF 512K OR 640 BYTES
ON THE PLANAR. THIS SIZE IS STORED IN CMOS AT ADDRESS
30 AND 31.
INPUT AH = 88H
THE 10 MEMORY SIZE VARIABLE IS SET DURING POWER ON
DIAGNOSTICS ACCORDING TO THE FOLLOWING ASSUMPTIONS:
3. ALL INSTALLED MEMORY IS FUNCTIONAL.
4. ALL MEMORY FROM 0 TO 640K MUST BE CONTIGUOUS.
OUTPUT (AX) = NUMBER OF CONTIGUOUS 1K BLOCKS OF MEMORY A
AVAILABLE STARTING AT ADDRESS 1024K.
;----- EXT_MEMORY PROC
03D2 FB STI ; INTERRUPTS BACK ON
03D3 B0 31 MOV AL,31H ; GET THE HIGH BYTE OF 10 MEMORY
03D5 E6 70 OUT CMOS_PORT_AL
03D7 EB 00 JMP SHORT $+2 ; IO DELAY
03D9 E4 71 IN AL,CMOS_PORT+1
03DB 86 C4 XCHG AL,AH ; PUT HIGH BYTE IN POSITION (AH)
03DD B0 30 MOV AL,30H ; GET THE LOW BYTE OF 10 MEMORY
03DF E6 70 OUT CMOS_PORT_AL

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03E1 EB 00      JMP     SHORT S+2          ; IO DELAY
03E3 E4 71      IN      AL,CMOS_PORT+1   ; RETURN TO USER
03E5 CF          RET
03E6          EXT_MEMORY ENDP
PAGE
----- INT 15H (FUNCTION 80H) -----
PURPOSE:
THIS BIOS FUNCTION PROVIDES A MEANS TO THE USER TO SWITCH INTO VIRTUAL (PROTECTED) MODE. UPON COMPLETION OF THIS FUNCTION THE PROCESSOR WILL BE IN VIRTUAL (PROTECTED) MODE AND CONTROL WILL BE TRANSFERRED TO THE CODE SEGMENT THAT WAS SPECIFIED BY THE USER.

ENTRY REQUIREMENTS:
ES:SI POINTS TO A DESCRIPTOR TABLE (GDT) BUILT BEFORE INTERRUPTING TO THIS FUNCTION. THESE DESCRIPTORS ARE ARE USED BY THIS FUNCTION TO INITIALIZE THE IDTR, THE GDTR AND THE STACK SEGMENT SELECTOR. THE DATA SEGMENT (DS) SELECTOR AND THE EXTRA SEGMENT (ES) SELECTOR WILL BE INITIALIZED TO DESCRIPTORS BUILT BY THE ROUTINE USING THIS FUNCTION.

BH - OFFSET INTO THE INTERRUPT DESCRIPTOR TABLE
STATING WHERE THE FIRST EIGHT HARDWARE INTERRUPTS WILL BEGIN. (INTERRUPT LEVEL 1)
BL - OFFSET INTO THE INTERRUPT DESCRIPTOR TABLE
STATING WHERE THE SECOND EIGHT HARDWARE INTERRUPTS WILL BEGIN. (INTERRUPT LEVEL 2)

THE DESCRIPTORS ARE DEFINED AS FOLLOWS:
1. THE FIRST DESCRIPTOR IS THE REQUIRED DUMMY.
    (USER INITIALIZED TO 0)
2. THE SECOND DESCRIPTOR POINTS TO THE GDT TABLE AS A DATA SEGMENT.
    (USER INITIALIZED)
3. THE THIRD DESCRIPTOR POINTS TO THE USER DEFINED INTERRUPT DESCRIPTOR TABLE (IDT).
    (USER INITIALIZED)
4. THE FORTH DESCRIPTOR POINTS TO THE USER'S DATA SEGMENT (DS).
    (USER INITIALIZED)
5. THE FIFTH DESCRIPTOR POINTS TO THE USER'S EXTRA SEGMENT (ES).
    (USER INITIALIZED)
6. THE SIXTH DESCRIPTOR POINTS TO THE USER'S STACK SEGMENT (SS).
    (USER INITIALIZED)
7. THE SEVENTH DESCRIPTOR POINTS TO THE CODE SEGMENT THAT THIS FUNCTION WILL RETURN TO.
    (USER INITIALIZED TO THE USER'S CODE SEGMENT.)
8. THE EIGHTH DESCRIPTOR IS USED BY THIS FUNCTION TO ESTABLISH A CODE SEGMENT FOR ITSELF. THIS IS NEEDED SO THAT THIS FUNCTION CAN COMPLETE ITS EXECUTION WHILE IN PROTECTED MODE. WHEN CONTROL GETS PASSED TO THE USER'S CODE THIS DESCRIPTOR CAN BE USED BY HIM IN ANY WAY HE CHOOSES.

NOTE - EACH DESCRIPTOR MUST CONTAIN ALL THE NECESSARY DATA I.E. THE LIMIT, BASE ADDRESS AND THE ACCESS RIGHTS BYTE.

AH=80H (FUNCTION CALL)
ES:SI = LOCATION OF THE GDT TABLE BUILT BY ROUTINE
USING THIS FUNCTION.

EXIT PARAMETERS:
AH = 0 IF SUCCESSFUL
ALL SEGMENT REGISTERS ARE CHANGED, AX AND BP DESTROYED

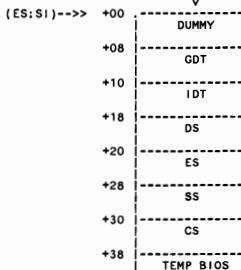
CONSIDERATIONS:
1. NO BIOS AVAILABLE TO USER. USER MUST HANDLE ALL IO COMMANDS.
2. INTERRUPT & INTERRUPT VECTOR LOCATIONS MUST BE MOVED, DUE TO THE 286 RESERVED AREAS. THE HARDWARE INTERRUPT CONTROLLERS MUST BE REINITIALIZED TO DEFINE LOCATIONS THAT DO NOT RESIDE IN THE 286 RESERVED AREAS.
3. EXCEPTION DESCRIPTOR TABLE AND HANDLER MUST BE INITIALIZED BY THE USER.
4. THE INTERRUPT DESCRIPTOR TABLE MUST NOT OVERLAP THE REAL MODE BIOS INTERRUPT DESCRIPTOR TABLE.
5. THE FOLLOWING GIVES AN IDEA OF WHAT THE USER CODE SHOULD LOOK LIKE WHEN INVOKING THIS FUNCTION.

Real mode ---> "USER CODE"
    " MOV AX,GDT SEGMENT
    " MOV ES,AX
    " MOV SI,GDT OFFSET
    " MOV BH,HARDWARE INT LEVEL 1 OFFSET
    " MOV BL,HARDWARE INT LEVEL 2 OFFSET
    " MOV AH,80H
    " INT 15H

Virtual mode ---> "USER CODE"

DESCRIPTION:
1. CLI (NO INTERRUPTS ALLOWED) WHILE THIS FUNCTION IS EXECUTING.
2. ADDRESS LINE 20 IS GATED ACTIVE.
3. THE CURRENT USER STACK SEGMENT DESCRIPTOR IS INITIALIZED.
4. THE GDTR IS LOADED WITH THE GDT BASE ADDRESS.
5. THE IDTR IS LOADED WITH THE IDT BASE ADDRESS.
6. THE B259 IS REINITIALIZED WITH THE NEW INTERRUPT OFFSET.
7. THE PROCESSOR IS PUT IN VIRTUAL MODE WITH THE CODE SEGMENT DESIGNATED FOR THIS FUNCTION.
8. DATA SEGMENT IS LOADED WITH THE USER DEFINED SELECTOR FOR THE DS REGISTER.
9. EXCEPTION DESCRIPTOR TABLE IS LOADED WITH THE USER DEFINED SELECTOR FOR THE ES REGISTER.
10. STACK SEGMENT IS LOADED WITH THE USER DEFINED SELECTOR FOR THE SS REGISTER.
11. CODE SEGMENT DESCRIPTOR SELECTOR VALUE IS SETTLED ON THE STACK FOR RETURN TO USER.
12. WE TRANSFER CONTROL TO THE USER WITH INTERRUPTS DISABLED.
-----
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G D T



THE GLOBAL DESCRIPTOR TABLE (ACTUAL LOCATION POINTED TO BY ES:SI)

VIRTUAL\_ENABLE\_GDT\_DEF STRUC

0000	00 00 00 00 00 00	DUMY DQ 0 ; FIRST DESCRIPTOR NOT ACCESSIBLE
0008	00 00 00 00 00 00	GDT PTR DQ 0 ; GDT DESCRIPTOR
0010	00 00 00 00 00 00	IDTPTR DQ 0 ; IDT DESCRIPTOR
0018	00 00 00 00 00 00	USER_DS DQ 0 ; USER DATA SEGMENT DESCRIPTOR
0020	00 00 00 00 00 00	USER_ES DQ 0 ; USER EXTRA SEGMENT DESCRIPTOR
0028	00 00 00 00 00 00	USER_SS DQ 0 ; USER STACK SEGMENT DESCRIPTOR
0030	00 00 00 00 00 00	USER_CS DQ 0 ; USER CODE SEGMENT DESCRIPTOR
0038	00 00 00 00 00 00	BIO_CS DQ 0 ; TEMPORARY BIOS DESCRIPTOR
0040		VIRTUAL_ENABLE_GDT_DEF ENDS

ASSUME CS:CODE  
ASSUME DS:DATA

03E6	X_VIRTUAL_SET_VMODE:	PROC FAR
03E6		CLI ; NO INTERRUPTS ALLOWED
----- ENABLE ADDRESS LATCH BIT 20 -----		
03E7	B4 DF	MOV AH,ENABLE_BIT20 ; ENABLE BIT 20 FOR ADDRESS GATE
03E7	00 00 B0 R	CALL GDTR_A20
03EC	00	CMP AL,0
03EE	74 00	JZ B1T20_ON
03F0	B4 FF	MOV AH,OFFH
03F2	F9	STC
03F3	CF	IRET
03F4		B1T20_ON:
03F4	26	SEGMOV ES,026H ; LOAD THE GLOBAL DESCRIPTOR TABLE REG
03F5	0F	DB 0FFH
03F6	BB 54 08	LDT [SI].GDTPTR
03F9		+ ??0015 LABEL BYTE
03F6		+ ??0016 MOV DX,WORD PTR [SI].GDTPTR
03F6		+ ??0016 LABEL BYTE
03F6	01	+ ORG OFFSET CS:??0015
03F9		+ DB 001H
03F9		+ ORG OFFSET CS:??0016
03F9	26	SEGMOV ES,026H ; LOAD THE INTERRUPT DESCRIPTOR TABLE REG
03FA	0F	DB 0FFH
03FB	BB 5C 10	LDT [SI].IDTPTR
03FE	01	+ ??0018 LABEL BYTE
03FB		+ ??0019 MOV DX,WORD PTR [SI].IDTPTR
03FB		+ ??0019 LABEL BYTE
03FB	01	+ ORG OFFSET CS:??0018
03FE		+ DB 001H
03FE		+ ORG OFFSET CS:??0019

; REINITIALIZE THE 8259 INTERRUPT CONTROLLER #1 TO THE USER SPECIFIED OFFSET |

03FE	B0 11	MOV AL,11H ; START INITIALIZATION SEQUENCE-ICW1
0400	E6 20	OUT INTA01_AL,AL EDGE, INTERVAL-8,MASTER,ICW4 NEEDED
0402	EB 00	JMP SHORT \$+2
0404	8A C7	MOV AL,BH ; HARDWARE INT'S START AT INT # (BH)
0406	E6 21	OUT INTA01_AL SEND ICW2
0408	E6 21	JMP SHORT \$+2
040A	B0 04	MOV AL,DH ; SEND ICW3 - MASTER LEVEL 2
040C	E6 21	OUT INTA01_AL
040E	EB 00	JMP SHORT \$+2
0410	B0 01	MOV AL,01H ; SEND ICW4 - MASTER,8086 MODE
0412	E6 21	OUT INTA01_AL
0414	E6 00	JMP SHORT \$+2
0416	B0 FF	MOV AL,OFFH ; MASK OFF ALL INTERRUPTS
0418	E6 21	OUT INTA01_AL

; REINITIALIZE THE 8259 INTERRUPT CONTROLLER #2 TO THE USER SPECIFIED OFFSET |

041A	B0 11	MOV AL,11H ; START INIT SEQUENCE-ICW1 FOR SLAVE
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041C E6 A0          OUT    INTB00_AL      ; EDGE, INTERVAL-8,MASTER, ICW4 NEEDED
041E EB 00          JMP    $+2
0420 8A C3          MOV    AL,BL
0422 F6 A1          OUT    INTB01_AL      ; HARDWARE INT'S START AT INT # (BL)
0424 B0 02          MOV    AL,02H
0426 EB 00          JMP    SHORT $+2
0428 E6 A1          OUT    INTB01_AL      ; SEND ICW2
042A 80 00          JMP    SHORT $+2
042C B0 01          MOV    AL,01H
042E E6 A1          OUT    INTB01_AL      ; SEND ICW3 - SLAVE LEVEL 2
0430 EB 00          JMP    SHORT $+2
0432 B0 FF          MOV    AL,OFFH
0434 E6 A1          OUT    INTB01_AL      ; SEND ICW4 - SLAVE,8086 MODE
0436 26: C7 44 38 FFFF
043C 26: C6 44 3C 0F
0441 26: C7 44 3A 0000
0447 26: C6 44 3D 9B
044C 26: C7 44 3E 0000
0452 B8 0001
0455 0F
0456 8B F0
0458 + ??001A LABEL BYTE
0459 + ??001B LABEL BYTE
045A + ??001C ORG   CS:??001A
045B + ??001D DB    001H
045C + ??001E ORG   OFFSET CS:??001B
045D EA
0459 045D R
045B 0038
045D B8 0018
0460 8E D8
0462 B8 0020
0463 8E D0
0467 B8 0028
046A 8E D0
046C 5B
046D B3 C4 04
0470 68
0471 0030
0473 53
0474 CB
0475 F8
0476 E9 004F R
0479 CF
047A
047A CODE ENDS
047A ENDP

;----- SETUP BIOS CODE SEGMENT DESCRIPTOR -----
MOV    ES:[SI].BIO_CS.SEG_LIMIT,MAX_SEG_LEN ; SET LENGTH
MOV    ES:[SI].BIO_CS.BASE_HI_BYT,ESEG0_HI ; SET HIGH BYTE OF CS=0
MOV    ES:[SI].BIO_CS.BASE_LO_WORD,CSEG0_LO ; SET LOW WORD OF CS=0
MOV    ES:[SI].BIO_CS.DATA_ACCESS,CPL0_CODE_ACCESS ; SET ACCESS RIGHTS BYTE
MOV    ES:[SI].BIO_CS.DATA_RESERVED,0 ; ZERO RESERVED AREA

;----- ENABLE PROTECTED MODE -----
MOV    AX,VIRTUAL_ENABLE ; MACHINE STATUS WORD NEEDED TO
                          ; SWITCH TO VIRTUAL MODE
LMSW  AX
DB    00FH
+ ??001A LABEL BYTE
+ ??001B LABEL BYTE
+ ??001C ORG   CS:??001A
+ ??001D DB    001H
+ ??001E ORG   OFFSET CS:??001B
JUMPFAR VMODE,BIO_CS ; MUST PURGE PRE-FETCH QUEUE
DB    0EAH ; Jump far direct
DW    (OFFSET VMODE) ; to this offset
DW    BIO_CS ; in this segment

VMODE:
;----- SETUP USER SEGMENT REGISTERS -----
MOV    AX,USER_DS ; SETUP USER'S DATA SEGMENT
MOV    DS,AX
MOV    AX,USER_ES ; SETUP USER'S EXTRA SEGMENT
MOV    ES,AX
MOV    AX,USER_SS ; SETUP USER'S STACK SEGMENT
MOV    SS,AX

;----- PUT TRANSFER ADDRESS ON THE STACK AND RETURN TO THE USER -----
POP    BX ; GET RETURN IP FROM THE STACK
ADD    SP,4 ; NORMALIZE STACK POINTER
IPUSH  USER_CS ; SET STACK FOR A RETURN FAR
+ ??001F DB    068H
+ ??0020 DW    USER_CS
PUSH   BX
RET   ; RETURN TO USER IN VIRTUAL MODE

X_VIRTUAL ENDP

;--- DEVICE BUSY AND INTERRUPT COMPLETE -----
THIS ROUTINE IS A TEMPORARY HANDLER FOR DEVICE BUSY
AND INTERRUPT COMPLETE
INPUT
SEE PROLOG

;----- DEVICE_BUSY -----
DEVICE_BUSY PROC NEAR
JC    C1_F ; TURN CARRY OFF
JMP   ENDP ; RETURN WITH CARRY FLAG
;----- INT_COMPLETE -----
INT_COMPLETE PROC NEAR
IRET
INT_COMPLETE ENDP ; RETURN
;----- -----

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TITLE 08-08-83 BIOS2 BIOS INTERRUPT
;LIST
C INCLUDE SEGMENT.SRC
C CODE SEGMENT BYTE PUBLIC
C
EXTRN DDS:NEAR
PUBLIC TIME_OF_DAY_1,TIMER_INT_1,PRINT_SCREEN_1
PUBLIC RTC_INT
;-- INT 1A -----
TIME_OF_DAY
; THIS ROUTINE ALLOWS THE CLOCK TO BE SET/READ

INPUT
(AH) = 0      READ THE CURRENT CLOCK SETTING
              RETURNS CX = HIGH PORTION OF COUNT
              DX = LOW PORTION OF COUNT
              AL = 0 IF TIMER HAS NOT PASSED 24 HOURS
              SINCE LAST READ. > 0 IF ON ANOTHER DAY
(AH) = 1      SET THE CURRENT CLOCK
              CX = HIGH PORTION OF COUNT
              DX = LOW PORTION OF COUNT

NOTE: COUNTS OCCUR AT THE RATE OF 1193180/65536 COUNTS/SEC
(OR ABOUT 18.2 PER SECOND -- SEE EQUATES)

(AH) = 2      READ THE REAL TIME CLOCK
              RETURNS CH = HOURS IN BCD
              CL = MINUTES IN BCD
              DH = SECONDS IN BCD

(AH) = 3      SET THE REAL TIME CLOCK
              CH = HOURS IN BCD
              CL = MINUTES IN BCD
              DH = SECONDS IN BCD
              DL = 1 IF DAYLIGHT SAVINGS TIME OPTION, ELSE 0

(AH) = 4      READ THE DATE FROM THE REAL TIME CLOCK
              RETURNS CH = CENTURY IN BCD (19 OR 20)
              CL = YEAR IN BCD
              DH = MONTH IN BCD
              DL = DAY IN BCD

(AH) = 5      SET THE DATE INTO THE REAL TIME CLOCK
              CH = CENTURY IN BCD (19 OR 20)
              CL = YEAR IN BCD
              DH = MONTH IN BCD
              DL = DAY IN BCD

(AH) = 6      SET THE ALARM
              THE ALARM CAN BE SET TO INTERRUPT UP TO
              23:59:59 FROM PRESENT TIME.
              ONE ALARM FUNCTION MAY BE ACTIVE AT ANY TIME
              CH = HOURS IN BCD
              CL = MINUTES IN BCD
              DH = SECONDS IN BCD

(AH) = 7      RESET THE ALARM

NOTE: FOR AH = 2, 4, 6 - CY FLAG SET IF CLOCK NOT OPERATING
FOR AH = 6 - CY FLAG SET IF ALARM ALREADY ENABLED
NOTE: FOR THE ALARM FUNCTION (AH = 6) THE USER MUST CODE A
ROUTINE AND PLACE THE CORRECT ADDRESS IN THE VECTOR
; TABLE FOR INT 4AH
;----- ASSUME CS:CODE,DS:DATA :-----;

0000
0000 FB
0001 F0
0002 E8 0000 E
0005 0A E4
0007 74 14
0009 FE CC
0008 74 23
000D 80 00 07
0010 40 03
0012 EB 2C 90
0015
0015 FB
0016 1F
0017 CF
0018
0018 F9
0019 1F
001A CA 0002
001D
001D FA
001E A0 0070 R
0021 C6 00 0070 R 00
0020 80 0E 006E R
002A 8B 16 006C R
002E EB E5
0030
0030 FA
0031 89 16 006C R
0035 89 0E 006E R
0039 C6 06 0070 R 00
003E EB D5
0040
0040 FE CC
0042 74 07
0044 FE CC
0046 74 26
0048 E9 0070 R
004B
004B E8 01B7 R
004E 73 02
0050 EB C6
0052
0052 FA
0053 B2 FE
0055 E8 0192 R
0057 E8 0192 R
005A 8A F0
005C E8 0192 R
005F E4 71
0061 8A C8
0063 E8 0192 R
0066 E4 71
0000
0000 STI
0001 PUSH DS
0002 CALL DDS
0003 OR AH,AH
0004 JZ T2
0005 DEC AH
0006 JZ T3
0007 CMP AH,7
0008 JGE T1
0009 JMP RTC_0
0010 T1:
0011 STI
0012 POP DS
0013 IRET
0014
0014 T1_A:
0015 STC
0016 POP DS
0017 RET 2
0018
0018 T1_A:
0019 STC
0020 POP DS
0021 RET 2
0022
0022 T2:
0023 CLI
0024 MOV AL,TIMER_OFL
0025 MOV TIMER_OFL,0
0026 MOV CX,TIMER_HIGH
0027 MOV DX,TIMER_LOW
0028 JMP T1
0029
0029 T3:
0030 CLI
0031 MOV TIMER_LOW,DX
0032 MOV TIMER_HIGH,CX
0033 MOV TIMER_OFL,0
0034 JMP T1
0035
0035 RTC_0:
0036 DEC AH
0037 JZ RTC_2
0038 DEC AH
0039 RTC_3
0040 JMP RTC_1
0041 RTC_GET_TIME PROC NEAR
0042
0042 RTC_2:
0043 CALL UPD_IN_PR
0044 JNC RTC_2A
0045 JMP T1_A
0046
0046 RTC_2A:
0047 CLI
0048 MOV DL,-2
0049 CALL PORT_INC_2
0050 IN AL,CMOS_PORT+1
0051 MOV DH,AL
0052 CALL PORT_INC_2
0053 IN AL,CMOS_PORT+1
0054 CL,AL
0055 CALL PORT_INC_2
0056 IN AL,CMOS_PORT+1
0057
0057 ; INTERRUPTS BACK ON
0058 ; SAME SEGMENT
0059 ; SET DATA SEGMENT
0060 ; AH=0
0061 ; READ_TIME
0062 ; AH=1
0063 ; SET_TIME
0064 ; READ_IF_VALID
0065 ; RETURN_IF_INVALID
0066 ; GO_CHECK_OTHER_FUNCTIONS
0067 ; TOD_RETURN
0068 ; INTERRUPTS_BACK_ON
0069 ; RECOVER_SEGMENT
0070 ; RETURN_TO_CALLER
0071
0071 ; SET_ERROR_RETURN
0072
0072 ; READ_TIME
0073 ; NO_INTERRUPTS WHILE READING
0074 ; GET_OVERFLOW, AND RESET THE FLAG
0075
0075 ; SET_TIMER
0076 ; NO_INTERRUPTS WHILE WRITING
0077 ; SET THE TIME
0078 ; RESET_OVERFLOW
0079 ; TOD_RETURN
0080
0080 ; SET_TIMER
0081 ; NO_INTERRUPTS WHILE WRITING
0082 ; SET THE TIME
0083 ; RESET_OVERFLOW
0084 ; TOD_RETURN
0085
0085 ; CHECK_FOR_UPDATE_IN_PROCESS
0086 ; GO_AROUND_IF_OK
0087 ; RETURN_IF_ERROR
0088
0088 ; INTERRUPTS OFF DURING READ
0089 ; SET_ADDRESS_OF_SECONDS
0090 ; IN AL,CMOS_PORT+2
0091 ; SAVE
0092 ; SET_ADDRESS_OF_MINUTES
0093 ; SAVE
0094 ; SET_ADDRESS_OF_HOURS
0095
0095 ; INTERRUPTS BACK ON
0096 ; SAME SEGMENT
0097 ; SET DATA SEGMENT
0098 ; AH=0
0099 ; READ_TIME
0100 ; AH=1
0101 ; SET_TIME
0102 ; READ_IF_VALID
0103 ; RETURN_IF_INVALID
0104 ; GO_CHECK_OTHER_FUNCTIONS
0105 ; TOD_RETURN
0106 ; INTERRUPTS_BACK_ON
0107 ; RECOVER_SEGMENT
0108 ; RETURN_TO_CALLER
0109
0109 ; SET_ERROR_RETURN
0110
0110 ; READ_TIME
0111 ; NO_INTERRUPTS WHILE READING
0112 ; GET_OVERFLOW, AND RESET THE FLAG
0113
0113 ; SET_TIMER
0114 ; NO_INTERRUPTS WHILE WRITING
0115 ; SET THE TIME
0116 ; RESET_OVERFLOW
0117 ; TOD_RETURN
0118
0118 ; SET_TIMER
0119 ; NO_INTERRUPTS WHILE WRITING
0120 ; SET THE TIME
0121 ; RESET_OVERFLOW
0122 ; TOD_RETURN
0123
0123 ; CHECK_FOR_UPDATE_IN_PROCESS
0124 ; GO_AROUND_IF_OK
0125 ; RETURN_IF_ERROR
0126
0126 ; INTERRUPTS OFF DURING READ
0127 ; SET_ADDRESS_OF_SECONDS
0128 ; IN AL,CMOS_PORT+2
0129 ; SAVE
0130 ; SET_ADDRESS_OF_MINUTES
0131 ; SAVE
0132 ; SET_ADDRESS_OF_HOURS
0133
0133 ; INTERRUPTS BACK ON
0134 ; SAME SEGMENT
0135 ; SET DATA SEGMENT
0136 ; AH=0
0137 ; READ_TIME
0138 ; AH=1
0139 ; SET_TIME
0140 ; READ_IF_VALID
0141 ; RETURN_IF_INVALID
0142 ; GO_CHECK_OTHER_FUNCTIONS
0143 ; TOD_RETURN
0144 ; INTERRUPTS_BACK_ON
0145 ; RECOVER_SEGMENT
0146 ; RETURN_TO_CALLER
0147
0147 ; SET_ERROR_RETURN
0148
0148 ; READ_TIME
0149 ; NO_INTERRUPTS WHILE READING
0150 ; GET_OVERFLOW, AND RESET THE FLAG
0151
0151 ; SET_TIMER
0152 ; NO_INTERRUPTS WHILE WRITING
0153 ; SET THE TIME
0154 ; RESET_OVERFLOW
0155 ; TOD_RETURN
0156
0156 ; SET_TIMER
0157 ; NO_INTERRUPTS WHILE WRITING
0158 ; SET THE TIME
0159 ; RESET_OVERFLOW
0160 ; TOD_RETURN
0161
0161 ; CHECK_FOR_UPDATE_IN_PROCESS
0162 ; GO_AROUND_IF_OK
0163 ; RETURN_IF_ERROR
0164
0164 ; INTERRUPTS OFF DURING READ
0165 ; SET_ADDRESS_OF_SECONDS
0166 ; IN AL,CMOS_PORT+2
0167 ; SAVE
0168 ; SET_ADDRESS_OF_MINUTES
0169 ; SAVE
0170 ; SET_ADDRESS_OF_HOURS
0171
0171 ; INTERRUPTS BACK ON
0172 ; SAME SEGMENT
0173 ; SET DATA SEGMENT
0174 ; AH=0
0175 ; READ_TIME
0176 ; AH=1
0177 ; SET_TIME
0178 ; READ_IF_VALID
0179 ; RETURN_IF_INVALID
0180 ; GO_CHECK_OTHER_FUNCTIONS
0181 ; TOD_RETURN
0182 ; INTERRUPTS_BACK_ON
0183 ; RECOVER_SEGMENT
0184 ; RETURN_TO_CALLER
0185
0185 ; SET_ERROR_RETURN
0186
0186 ; READ_TIME
0187 ; NO_INTERRUPTS WHILE READING
0188 ; GET_OVERFLOW, AND RESET THE FLAG
0189
0189 ; SET_TIMER
0190 ; NO_INTERRUPTS WHILE WRITING
0191 ; SET THE TIME
0192 ; RESET_OVERFLOW
0193 ; TOD_RETURN
0194
0194 ; SET_TIMER
0195 ; NO_INTERRUPTS WHILE WRITING
0196 ; SET THE TIME
0197 ; RESET_OVERFLOW
0198 ; TOD_RETURN
0199
0199 ; CHECK_FOR_UPDATE_IN_PROCESS
0200 ; GO_AROUND_IF_OK
0201 ; RETURN_IF_ERROR
0202
0202 ; INTERRUPTS OFF DURING READ
0203 ; SET_ADDRESS_OF_SECONDS
0204 ; IN AL,CMOS_PORT+2
0205 ; SAVE
0206 ; SET_ADDRESS_OF_MINUTES
0207 ; SAVE
0208 ; SET_ADDRESS_OF_HOURS
0209
0209 ; INTERRUPTS BACK ON
0210 ; SAME SEGMENT
0211 ; SET DATA SEGMENT
0212 ; AH=0
0213 ; READ_TIME
0214 ; AH=1
0215 ; SET_TIME
0216 ; READ_IF_VALID
0217 ; RETURN_IF_INVALID
0218 ; GO_CHECK_OTHER_FUNCTIONS
0219 ; TOD_RETURN
0220 ; INTERRUPTS_BACK_ON
0221 ; RECOVER_SEGMENT
0222 ; RETURN_TO_CALLER
0223
0223 ; SET_ERROR_RETURN
0224
0224 ; READ_TIME
0225 ; NO_INTERRUPTS WHILE READING
0226 ; GET_OVERFLOW, AND RESET THE FLAG
0227
0227 ; SET_TIMER
0228 ; NO_INTERRUPTS WHILE WRITING
0229 ; SET THE TIME
0230 ; RESET_OVERFLOW
0231 ; TOD_RETURN
0232
0232 ; SET_TIMER
0233 ; NO_INTERRUPTS WHILE WRITING
0234 ; SET THE TIME
0235 ; RESET_OVERFLOW
0236 ; TOD_RETURN
0237
0237 ; CHECK_FOR_UPDATE_IN_PROCESS
0238 ; GO_AROUND_IF_OK
0239 ; RETURN_IF_ERROR
0240
0240 ; INTERRUPTS OFF DURING READ
0241 ; SET_ADDRESS_OF_SECONDS
0242 ; IN AL,CMOS_PORT+2
0243 ; SAVE
0244 ; SET_ADDRESS_OF_MINUTES
0245 ; SAVE
0246 ; SET_ADDRESS_OF_HOURS
0247
0247 ; INTERRUPTS BACK ON
0248 ; SAME SEGMENT
0249 ; SET DATA SEGMENT
0250 ; AH=0
0251 ; READ_TIME
0252 ; AH=1
0253 ; SET_TIME
0254 ; READ_IF_VALID
0255 ; RETURN_IF_INVALID
0256 ; GO_CHECK_OTHER_FUNCTIONS
0257 ; TOD_RETURN
0258 ; INTERRUPTS_BACK_ON
0259 ; RECOVER_SEGMENT
0260 ; RETURN_TO_CALLER
0261
0261 ; SET_ERROR_RETURN
0262
0262 ; READ_TIME
0263 ; NO_INTERRUPTS WHILE READING
0264 ; GET_OVERFLOW, AND RESET THE FLAG
0265
0265 ; SET_TIMER
0266 ; NO_INTERRUPTS WHILE WRITING
0267 ; SET THE TIME
0268 ; RESET_OVERFLOW
0269 ; TOD_RETURN
0270
0270 ; SET_TIMER
0271 ; NO_INTERRUPTS WHILE WRITING
0272 ; SET THE TIME
0273 ; RESET_OVERFLOW
0274 ; TOD_RETURN
0275
0275 ; CHECK_FOR_UPDATE_IN_PROCESS
0276 ; GO_AROUND_IF_OK
0277 ; RETURN_IF_ERROR
0278
0278 ; INTERRUPTS OFF DURING READ
0279 ; SET_ADDRESS_OF_SECONDS
0280 ; IN AL,CMOS_PORT+2
0281 ; SAVE
0282 ; SET_ADDRESS_OF_MINUTES
0283 ; SAVE
0284 ; SET_ADDRESS_OF_HOURS
0285
0285 ; INTERRUPTS BACK ON
0286 ; SAME SEGMENT
0287 ; SET DATA SEGMENT
0288 ; AH=0
0289 ; READ_TIME
0290 ; AH=1
0291 ; SET_TIME
0292 ; READ_IF_VALID
0293 ; RETURN_IF_INVALID
0294 ; GO_CHECK_OTHER_FUNCTIONS
0295 ; TOD_RETURN
0296 ; INTERRUPTS_BACK_ON
0297 ; RECOVER_SEGMENT
0298 ; RETURN_TO_CALLER
0299
0299 ; SET_ERROR_RETURN
0300
0300 ; READ_TIME
0301 ; NO_INTERRUPTS WHILE READING
0302 ; GET_OVERFLOW, AND RESET THE FLAG
0303
0303 ; SET_TIMER
0304 ; NO_INTERRUPTS WHILE WRITING
0305 ; SET THE TIME
0306 ; RESET_OVERFLOW
0307 ; TOD_RETURN
0308
0308 ; SET_TIMER
0309 ; NO_INTERRUPTS WHILE WRITING
0310 ; SET THE TIME
0311 ; RESET_OVERFLOW
0312 ; TOD_RETURN
0313
0313 ; CHECK_FOR_UPDATE_IN_PROCESS
0314 ; GO_AROUND_IF_OK
0315 ; RETURN_IF_ERROR
0316
0316 ; INTERRUPTS OFF DURING READ
0317 ; SET_ADDRESS_OF_SECONDS
0318 ; IN AL,CMOS_PORT+2
0319 ; SAVE
0320 ; SET_ADDRESS_OF_MINUTES
0321 ; SAVE
0322 ; SET_ADDRESS_OF_HOURS
0323
0323 ; INTERRUPTS BACK ON
0324 ; SAME SEGMENT
0325 ; SET DATA SEGMENT
0326 ; AH=0
0327 ; READ_TIME
0328 ; AH=1
0329 ; SET_TIME
0330 ; READ_IF_VALID
0331 ; RETURN_IF_INVALID
0332 ; GO_CHECK_OTHER_FUNCTIONS
0333 ; TOD_RETURN
0334 ; INTERRUPTS_BACK_ON
0335 ; RECOVER_SEGMENT
0336 ; RETURN_TO_CALLER
0337
0337 ; SET_ERROR_RETURN
0338
0338 ; READ_TIME
0339 ; NO_INTERRUPTS WHILE READING
0340 ; GET_OVERFLOW, AND RESET THE FLAG
0341
0341 ; SET_TIMER
0342 ; NO_INTERRUPTS WHILE WRITING
0343 ; SET THE TIME
0344 ; RESET_OVERFLOW
0345 ; TOD_RETURN
0346
0346 ; SET_TIMER
0347 ; NO_INTERRUPTS WHILE WRITING
0348 ; SET THE TIME
0349 ; RESET_OVERFLOW
0350 ; TOD_RETURN
0351
0351 ; CHECK_FOR_UPDATE_IN_PROCESS
0352 ; GO_AROUND_IF_OK
0353 ; RETURN_IF_ERROR
0354
0354 ; INTERRUPTS OFF DURING READ
0355 ; SET_ADDRESS_OF_SECONDS
0356 ; IN AL,CMOS_PORT+2
0357 ; SAVE
0358 ; SET_ADDRESS_OF_MINUTES
0359 ; SAVE
0360 ; SET_ADDRESS_OF_HOURS
0361
0361 ; INTERRUPTS BACK ON
0362 ; SAME SEGMENT
0363 ; SET DATA SEGMENT
0364 ; AH=0
0365 ; READ_TIME
0366 ; AH=1
0367 ; SET_TIME
0368 ; READ_IF_VALID
0369 ; RETURN_IF_INVALID
0370 ; GO_CHECK_OTHER_FUNCTIONS
0371 ; TOD_RETURN
0372 ; INTERRUPTS_BACK_ON
0373 ; RECOVER_SEGMENT
0374 ; RETURN_TO_CALLER
0375
0375 ; SET_ERROR_RETURN
0376
0376 ; READ_TIME
0377 ; NO_INTERRUPTS WHILE READING
0378 ; GET_OVERFLOW, AND RESET THE FLAG
0379
0379 ; SET_TIMER
0380 ; NO_INTERRUPTS WHILE WRITING
0381 ; SET THE TIME
0382 ; RESET_OVERFLOW
0383 ; TOD_RETURN
0384
0384 ; SET_TIMER
0385 ; NO_INTERRUPTS WHILE WRITING
0386 ; SET THE TIME
0387 ; RESET_OVERFLOW
0388 ; TOD_RETURN
0389
0389 ; CHECK_FOR_UPDATE_IN_PROCESS
0390 ; GO_AROUND_IF_OK
0391 ; RETURN_IF_ERROR
0392
0392 ; INTERRUPTS OFF DURING READ
0393 ; SET_ADDRESS_OF_SECONDS
0394 ; IN AL,CMOS_PORT+2
0395 ; SAVE
0396 ; SET_ADDRESS_OF_MINUTES
0397 ; SAVE
0398 ; SET_ADDRESS_OF_HOURS
0399
0399 ; INTERRUPTS BACK ON
0400 ; SAME SEGMENT
0401 ; SET DATA SEGMENT
0402 ; AH=0
0403 ; READ_TIME
0404 ; AH=1
0405 ; SET_TIME
0406 ; READ_IF_VALID
0407 ; RETURN_IF_INVALID
0408 ; GO_CHECK_OTHER_FUNCTIONS
0409 ; TOD_RETURN
0410 ; INTERRUPTS_BACK_ON
0411 ; RECOVER_SEGMENT
0412 ; RETURN_TO_CALLER
0413
0413 ; SET_ERROR_RETURN
0414
0414 ; READ_TIME
0415 ; NO_INTERRUPTS WHILE READING
0416 ; GET_OVERFLOW, AND RESET THE FLAG
0417
0417 ; SET_TIMER
0418 ; NO_INTERRUPTS WHILE WRITING
0419 ; SET THE TIME
0420 ; RESET_OVERFLOW
0421 ; TOD_RETURN
0422
0422 ; SET_TIMER
0423 ; NO_INTERRUPTS WHILE WRITING
0424 ; SET THE TIME
0425 ; RESET_OVERFLOW
0426 ; TOD_RETURN
0427
0427 ; CHECK_FOR_UPDATE_IN_PROCESS
0428 ; GO_AROUND_IF_OK
0429 ; RETURN_IF_ERROR
0430
0430 ; INTERRUPTS OFF DURING READ
0431 ; SET_ADDRESS_OF_SECONDS
0432 ; IN AL,CMOS_PORT+2
0433 ; SAVE
0434 ; SET_ADDRESS_OF_MINUTES
0435 ; SAVE
0436 ; SET_ADDRESS_OF_HOURS
0437
0437 ; INTERRUPTS BACK ON
0438 ; SAME SEGMENT
0439 ; SET DATA SEGMENT
0440 ; AH=0
0441 ; READ_TIME
0442 ; AH=1
0443 ; SET_TIME
0444 ; READ_IF_VALID
0445 ; RETURN_IF_INVALID
0446 ; GO_CHECK_OTHER_FUNCTIONS
0447 ; TOD_RETURN
0448 ; INTERRUPTS_BACK_ON
0449 ; RECOVER_SEGMENT
0450 ; RETURN_TO_CALLER
0451
0451 ; SET_ERROR_RETURN
0452
0452 ; READ_TIME
0453 ; NO_INTERRUPTS WHILE READING
0454 ; GET_OVERFLOW, AND RESET THE FLAG
0455
0455 ; SET_TIMER
0456 ; NO_INTERRUPTS WHILE WRITING
0457 ; SET THE TIME
0458 ; RESET_OVERFLOW
0459 ; TOD_RETURN
0460
0460 ; SET_TIMER
0461 ; NO_INTERRUPTS WHILE WRITING
0462 ; SET THE TIME
0463 ; RESET_OVERFLOW
0464 ; TOD_RETURN
0465
0465 ; CHECK_FOR_UPDATE_IN_PROCESS
0466 ; GO_AROUND_IF_OK
0467 ; RETURN_IF_ERROR
0468
0468 ; INTERRUPTS OFF DURING READ
0469 ; SET_ADDRESS_OF_SECONDS
0470 ; IN AL,CMOS_PORT+2
0471 ; SAVE
0472 ; SET_ADDRESS_OF_MINUTES
0473 ; SAVE
0474 ; SET_ADDRESS_OF_HOURS
0475
0475 ; INTERRUPTS BACK ON
0476 ; SAME SEGMENT
0477 ; SET DATA SEGMENT
0478 ; AH=0
0479 ; READ_TIME
0480 ; AH=1
0481 ; SET_TIME
0482 ; READ_IF_VALID
0483 ; RETURN_IF_INVALID
0484 ; GO_CHECK_OTHER_FUNCTIONS
0485 ; TOD_RETURN
0486 ; INTERRUPTS_BACK_ON
0487 ; RECOVER_SEGMENT
0488 ; RETURN_TO_CALLER
0489
0489 ; SET_ERROR_RETURN
0490
0490 ; READ_TIME
0491 ; NO_INTERRUPTS WHILE READING
0492 ; GET_OVERFLOW, AND RESET THE FLAG
0493
0493 ; SET_TIMER
0494 ; NO_INTERRUPTS WHILE WRITING
0495 ; SET THE TIME
0496 ; RESET_OVERFLOW
0497 ; TOD_RETURN
0498
0498 ; SET_TIMER
0499 ; NO_INTERRUPTS WHILE WRITING
0500 ; SET THE TIME
0501 ; RESET_OVERFLOW
0502 ; TOD_RETURN
0503
0503 ; CHECK_FOR_UPDATE_IN_PROCESS
0504 ; GO_AROUND_IF_OK
0505 ; RETURN_IF_ERROR
0506
0506 ; INTERRUPTS OFF DURING READ
0507 ; SET_ADDRESS_OF_SECONDS
0508 ; IN AL,CMOS_PORT+2
0509 ; SAVE
0510 ; SET_ADDRESS_OF_MINUTES
0511 ; SAVE
0512 ; SET_ADDRESS_OF_HOURS
0513
0513 ; INTERRUPTS BACK ON
0514 ; SAME SEGMENT
0515 ; SET DATA SEGMENT
0516 ; AH=0
0517 ; READ_TIME
0518 ; AH=1
0519 ; SET_TIME
0520 ; READ_IF_VALID
0521 ; RETURN_IF_INVALID
0522 ; GO_CHECK_OTHER_FUNCTIONS
0523 ; TOD_RETURN
0524 ; INTERRUPTS_BACK_ON
0525 ; RECOVER_SEGMENT
0526 ; RETURN_TO_CALLER
0527
0527 ; SET_ERROR_RETURN
0528
0528 ; READ_TIME
0529 ; NO_INTERRUPTS WHILE READING
0530 ; GET_OVERFLOW, AND RESET THE FLAG
0531
0531 ; SET_TIMER
0532 ; NO_INTERRUPTS WHILE WRITING
0533 ; SET THE TIME
0534 ; RESET_OVERFLOW
0535 ; TOD_RETURN
0536
0536 ; SET_TIMER
0537 ; NO_INTERRUPTS WHILE WRITING
0538 ; SET THE TIME
0539 ; RESET_OVERFLOW
0540 ; TOD_RETURN
0541
0541 ; CHECK_FOR_UPDATE_IN_PROCESS
0542 ; GO_AROUND_IF_OK
0543 ; RETURN_IF_ERROR
0544
0544 ; INTERRUPTS OFF DURING READ
0545 ; SET_ADDRESS_OF_SECONDS
0546 ; IN AL,CMOS_PORT+2
0547 ; SAVE
0548 ; SET_ADDRESS_OF_MINUTES
0549 ; SAVE
0550 ; SET_ADDRESS_OF_HOURS
0551
0551 ; INTERRUPTS BACK ON
0552 ; SAME SEGMENT
0553 ; SET DATA SEGMENT
0554 ; AH=0
0555 ; READ_TIME
0556 ; AH=1
0557 ; SET_TIME
0558 ; READ_IF_VALID
0559 ; RETURN_IF_INVALID
0560 ; GO_CHECK_OTHER_FUNCTIONS
0561 ; TOD_RETURN
0562 ; INTERRUPTS_BACK_ON
0563 ; RECOVER_SEGMENT
0564 ; RETURN_TO_CALLER
0565
0565 ; SET_ERROR_RETURN
0566
0566 ; READ_TIME
0567 ; NO_INTERRUPTS WHILE READING
0568 ; GET_OVERFLOW, AND RESET THE FLAG
0569
0569 ; SET_TIMER
0570 ; NO_INTERRUPTS WHILE WRITING
0571 ; SET THE TIME
0572 ; RESET_OVERFLOW
0573 ; TOD_RETURN
0574
0574 ; SET_TIMER
0575 ; NO_INTERRUPTS WHILE WRITING
0576 ; SET THE TIME
0577 ; RESET_OVERFLOW
0578 ; TOD_RETURN
0579
0579 ; CHECK_FOR_UPDATE_IN_PROCESS
0580 ; GO_AROUND_IF_OK
0581 ; RETURN_IF_ERROR
0582
0582 ; INTERRUPTS OFF DURING READ
0583 ; SET_ADDRESS_OF_SECONDS
0584 ; IN AL,CMOS_PORT+2
0585 ; SAVE
0586 ; SET_ADDRESS_OF_MINUTES
0587 ; SAVE
0588 ; SET_ADDRESS_OF_HOURS
0589
0589 ; INTERRUPTS BACK ON
0590 ; SAME SEGMENT
0591 ; SET DATA SEGMENT
0592 ; AH=0
0593 ; READ_TIME
0594 ; AH=1
0595 ; SET_TIME
0596 ; READ_IF_VALID
0597 ; RETURN_IF_INVALID
0598 ; GO_CHECK_OTHER_FUNCTIONS
0599 ; TOD_RETURN
0600 ; INTERRUPTS_BACK_ON
0601 ; RECOVER_SEGMENT
0602 ; RETURN_TO_CALLER
0603
0603 ; SET_ERROR_RETURN
0604
0604 ; READ_TIME
0605 ; NO_INTERRUPTS WHILE READING
0606 ; GET_OVERFLOW, AND RESET THE FLAG
0607
0607 ; SET_TIMER
0608 ; NO_INTERRUPTS WHILE WRITING
0609 ; SET THE TIME
0610 ; RESET_OVERFLOW
0611 ; TOD_RETURN
0612
0612 ; SET_TIMER
0613 ; NO_INTERRUPTS WHILE WRITING
0614 ; SET THE TIME
0615 ; RESET_OVERFLOW
0616 ; TOD_RETURN
0617
0617 ; CHECK_FOR_UPDATE_IN_PROCESS
0618 ; GO_AROUND_IF_OK
0619 ; RETURN_IF_ERROR
0620
0620 ; INTERRUPTS OFF DURING READ
0621 ; SET_ADDRESS_OF_SECONDS
0622 ; IN AL,CMOS_PORT+2
0623 ; SAVE
0624 ; SET_ADDRESS_OF_MINUTES
0625 ; SAVE
0626 ; SET_ADDRESS_OF_HOURS
0627
0627 ; INTERRUPTS BACK ON
0628 ; SAME SEGMENT
0629 ; SET DATA SEGMENT
0630 ; AH=0
0631 ; READ_TIME
0632 ; AH=1
0633 ; SET_TIME
0634 ; READ_IF_VALID
0635 ; RETURN_IF_INVALID
0636 ; GO_CHECK_OTHER_FUNCTIONS
0637 ; TOD_RETURN
0638 ; INTERRUPTS_BACK_ON
0639 ; RECOVER_SEGMENT
0640 ; RETURN_TO_CALLER
0641
0641 ; SET_ERROR_RETURN
0642
0642 ; READ_TIME
0643 ; NO_INTERRUPTS WHILE READING
0644 ; GET_OVERFLOW, AND RESET THE FLAG
0645
0645 ; SET_TIMER
0646 ; NO_INTERRUPTS WHILE WRITING
0647 ; SET THE TIME
0648 ; RESET_OVERFLOW
0649 ; TOD_RETURN
0650
0650 ; SET_TIMER
0651 ; NO_INTERRUPTS WHILE WRITING
0652 ; SET THE TIME
0653 ; RESET_OVERFLOW
0654 ; TOD_RETURN
0655
0655 ; CHECK_FOR_UPDATE_IN_PROCESS
0656 ; GO_AROUND_IF_OK
0657 ; RETURN_IF_ERROR
0658
0658 ; INTERRUPTS OFF DURING READ
0659 ; SET_ADDRESS_OF_SECONDS
0660 ; IN AL,CMOS_PORT+2
0661 ; SAVE
0662 ; SET_ADDRESS_OF_MINUTES
0663 ; SAVE
0664 ; SET_ADDRESS_OF_HOURS
0665
0665 ; INTERRUPTS BACK ON
0666 ; SAME SEGMENT
0667 ; SET DATA SEGMENT
0668 ; AH=0
0669 ; READ_TIME
0670 ; AH=1
0671 ; SET_TIME
0672 ; READ_IF_VALID
0673 ; RETURN_IF_INVALID
0674 ; GO_CHECK_OTHER_FUNCTIONS
0675 ; TOD_RETURN
0676 ; INTERRUPTS_BACK_ON
0677 ; RECOVER_SEGMENT
0678 ; RETURN_TO_CALLER
0679
0679 ; SET_ERROR_RETURN
0680
0680 ; READ_TIME
0681 ; NO_INTERRUPTS WHILE READING
0682 ; GET_OVERFLOW, AND RESET THE FLAG
0683
0683 ; SET_TIMER
0684 ; NO_INTERRUPTS WHILE WRITING
0685 ; SET THE TIME
0686 ; RESET_OVERFLOW
0687 ; TOD_RETURN
0688
0688 ; SET_TIMER
0689 ; NO_INTERRUPTS WHILE WRITING
0690 ; SET THE TIME
0691 ; RESET_OVERFLOW
0692 ; TOD_RETURN
0693
0693 ; CHECK_FOR_UPDATE_IN_PROCESS
0694 ; GO_AROUND_IF_OK
0695 ; RETURN_IF_ERROR
0696
0696 ; INTERRUPTS OFF DURING READ
0697 ; SET_ADDRESS_OF_SECONDS
0698 ; IN AL,CMOS_PORT+2
0699 ; SAVE
0700 ; SET_ADDRESS_OF_MINUTES
0701 ; SAVE
0702 ; SET_ADDRESS_OF_HOURS
0703
0703 ; INTERRUPTS BACK ON
0704 ; SAME SEGMENT
0705 ; SET DATA SEGMENT
0706 ; AH=0
0707 ; READ_TIME
0708 ; AH=1
0709 ; SET_TIME
0710 ; READ_IF_VALID
0711 ; RETURN_IF_INVALID
0712 ; GO_CHECK_OTHER_FUNCTIONS
0713 ; TOD_RETURN
0714 ; INTERRUPTS_BACK_ON
0715 ; RECOVER_SEGMENT
0716 ; RETURN_TO_CALLER
0717
0717 ; SET_ERROR_RETURN
0718
0718 ; READ_TIME
0719 ; NO_INTERRUPTS WHILE READING
0720 ; GET_OVERFLOW, AND RESET THE FLAG
0721
0721 ; SET_TIMER
0722 ; NO_INTERRUPTS WHILE WRITING
0723 ; SET THE TIME
0724 ; RESET_OVERFLOW
0725 ; TOD_RETURN
0726
0726 ; SET_TIMER
0727 ; NO_INTERRUPTS WHILE WRITING
0728 ; SET THE TIME
0729 ; RESET_OVERFLOW
0730 ; TOD_RETURN
0731
0731 ; CHECK_FOR_UPDATE_IN_PROCESS
0732 ; GO_AROUND_IF_OK
0733 ; RETURN_IF_ERROR
0734
0734 ; INTERRUPTS OFF DURING READ
0735 ; SET_ADDRESS_OF_SECONDS
0736 ; IN AL,CMOS_PORT+2
0737 ; SAVE
0738 ; SET_ADDRESS_OF_MINUTES
0739 ; SAVE
0740 ; SET_ADDRESS_OF_HOURS
0741
0741 ; INTERRUPTS BACK ON
0742 ; SAME SEGMENT
0743 ; SET DATA SEGMENT
0744 ; AH=0
0745 ; READ_TIME
0746 ; AH=1
0747 ; SET_TIME
0748 ; READ_IF_VALID
0749 ; RETURN_IF_INVALID
0750 ; GO_CHECK_OTHER_FUNCTIONS
0751 ; TOD_RETURN
0752 ; INTERRUPTS_BACK_ON
0753 ; RECOVER_SEGMENT
0754 ; RETURN_TO_CALLER
0755
0755 ; SET_ERROR_RETURN
0756
0756 ; READ_TIME
0757 ; NO_INTERRUPTS WHILE READING
0758 ; GET_OVERFLOW, AND RESET THE FLAG
0759
0759 ; SET_TIMER
0760 ; NO_INTERRUPTS WHILE WRITING
0761 ; SET THE TIME
0762 ; RESET_OVERFLOW
0763 ; TOD_RETURN
0764
0764 ; SET_TIMER
0765 ; NO_INTERRUPTS WHILE WRITING
0766 ; SET THE TIME
0767 ; RESET_OVERFLOW
0768 ; TOD_RETURN
0769
0769 ; CHECK_FOR_UPDATE_IN_PROCESS
0770 ; GO_AROUND_IF_OK
0771 ; RETURN_IF_ERROR
0772
0772 ; INTERRUPTS OFF DURING READ
0773 ; SET_ADDRESS_OF_SECONDS
0774 ; IN AL,CMOS_PORT+2
0775 ; SAVE
0776 ; SET_ADDRESS_OF_MINUTES
0777 ; SAVE
0778 ; SET_ADDRESS_OF_HOURS
0779
0779 ; INTERRUPTS BACK ON
0780 ; SAME SEGMENT
0781 ; SET DATA SEGMENT
0782 ; AH=0
0783 ; READ_TIME
0784 ; AH=1
0785 ; SET_TIME
0786 ; READ_IF_VALID
0787 ; RETURN_IF_INVALID
0788 ; GO_CHECK_OTHER_FUNCTIONS
0789 ; TOD_RETURN
0790 ; INTERRUPTS_BACK_ON
0791 ; RECOVER_SEGMENT
0792 ; RETURN_TO_CALLER
0793
0793 ; SET_ERROR_RETURN
0794
0794 ; READ_TIME
0795 ; NO_INTERRUPTS WHILE READING
0796 ; GET_OVERFLOW, AND RESET THE FLAG
0797
0797 ; SET_TIMER
0798 ; NO_INTERRUPTS WHILE WRITING
0799 ; SET THE TIME
0800 ; RESET_OVERFLOW
0801 ; TOD_RETURN
0802
0802 ; SET_TIMER
0803 ; NO_INTERRUPTS WHILE WRITING
0804 ; SET THE TIME
0805 ; RESET_OVERFLOW
0806 ; TOD_RETURN
0807
0807 ; CHECK_FOR_UPDATE_IN_PROCESS
0808 ; GO_AROUND_IF_OK
0809 ; RETURN_IF_ERROR
0810
0810 ; INTERRUPTS OFF DURING READ
0811 ; SET_ADDRESS_OF_SECONDS
0812 ; IN AL,CMOS_PORT+2
0813 ; SAVE
0814 ; SET_ADDRESS_OF_MINUTES
0815 ; SAVE
0816 ; SET_ADDRESS_OF_HOURS
0817
0817 ; INTERRUPTS BACK ON
0818 ; SAME SEGMENT
0819 ; SET DATA SEGMENT
0820 ; AH=0
0821 ; READ_TIME
0822 ; AH=1
0823 ; SET_TIME
0824 ; READ_IF_VALID
0825 ; RETURN_IF_INVALID
0826 ; GO_CHECK_OTHER_FUNCTIONS
0827 ; TOD_RETURN
0828 ; INTERRUPTS_BACK_ON
0829 ; RECOVER_SEGMENT
0830 ; RETURN_TO_CALLER
0831
0831 ; SET_ERROR_RETURN
0832
0832 ; READ_TIME
0833 ; NO_INTERRUPTS WHILE READING
0834 ; GET_OVERFLOW, AND RESET THE FLAG
0835
0835 ; SET_TIMER
0836 ; NO_INTERRUPTS WHILE WRITING
0837 ; SET THE TIME
0838 ; RESET_OVERFLOW
0839 ; TOD_RETURN
0840
0840 ; SET_TIMER
0841 ; NO_INTERRUPTS WHILE WRITING
0842 ; SET THE TIME
0843 ; RESET_OVERFLOW
0844 ; TOD_RETURN
0845
0845 ; CHECK_FOR_UPDATE_IN_PROCESS
0846 ; GO_AROUND_IF_OK
0847 ; RETURN_IF_ERROR
0848
0848 ; INTERRUPTS OFF DURING READ
0849 ; SET_ADDRESS_OF_SECONDS
0850 ; IN AL,CMOS_PORT+2
0851 ; SAVE
0852 ; SET_ADDRESS_OF_MINUTES
0853 ; SAVE
0854 ; SET_ADDRESS_OF_HOURS
0855
0855 ; INTERRUPTS BACK ON
0856 ; SAME SEGMENT
0857 ; SET DATA SEGMENT
0858 ; AH=0
0859 ; READ_TIME
0860 ; AH=1
0861 ; SET_TIME
0862 ; READ_IF_VALID
0863 ; RETURN_IF_INVALID
0864 ; GO_CHECK_OTHER_FUNCTIONS
0865 ; TOD_RETURN
0866 ; INTERRUPTS_BACK_ON
0867 ; RECOVER_SEGMENT
0868 ; RETURN_TO_CALLER
0869
0869 ; SET_ERROR_RETURN
0870
0870 ; READ_TIME
0871 ; NO_INTERRUPTS WHILE READING
0872 ; GET_OVERFLOW, AND RESET THE FLAG
0873
0873 ; SET_TIMER
0874 ; NO_INTERRUPTS WHILE WRITING
0875 ; SET THE TIME
0876 ; RESET_OVERFLOW
0877 ; TOD_RETURN
0878
0878 ; SET_TIMER
0879 ; NO_INTERRUPTS WHILE WRITING
0880 ; SET THE TIME
0881 ; RESET_OVERFLOW
0882 ; TOD_RETURN
0883
0883 ; CHECK_FOR_UPDATE_IN_PROCESS
0884 ; GO_AROUND_IF_OK
0885 ; RETURN_IF_ERROR
0886
0886 ; INTERRUPTS OFF DURING READ
0887 ; SET_ADDRESS_OF_SECONDS
0888 ; IN AL,CMOS_PORT+2
0889 ; SAVE
0890 ; SET_ADDRESS_OF_MINUTES
0891 ; SAVE
0892 ; SET_ADDRESS_OF_HOURS
0893
0893 ; INTERRUPTS BACK ON
0894 ; SAME SEGMENT
0895 ; SET DATA SEGMENT
0896 ; AH=0
0897 ; READ_TIME
0898 ; AH=1
0899 ; SET_TIME
0900 ; READ_IF_VALID
0901 ; RETURN_IF_INVALID
0902 ; GO_CHECK_OTHER_FUNCTIONS
0903 ; TOD_RETURN
0904 ; INTERRUPTS_BACK_ON
0905 ; RECOVER_SEGMENT
0906 ; RETURN_TO_CALLER
0907
0907 ; SET_ERROR_RETURN
0908
0908 ; READ_TIME
0909 ; NO_INTERRUPTS WHILE READING
0910 ; GET_OVERFLOW, AND RESET THE FLAG
0911
0911 ; SET_TIMER
0912 ; NO_INTERRUPTS WHILE WRITING
0913 ; SET THE TIME
0914 ; RESET_OVERFLOW
0915 ; TOD_RETURN
0916
0916 ; SET_TIMER
0917 ; NO_INTERRUPTS WHILE WRITING
0918 ; SET THE TIME
0919 ; RESET_OVERFLOW
0920 ; TOD_RETURN
0921
0921 ; CHECK_FOR_UPDATE_IN_PROCESS
0922 ; GO_AROUND_IF_OK
0923 ; RETURN_IF_ERROR
0924
0924 ; INTERRUPTS OFF DURING READ
0925 ; SET_ADDRESS_OF_SECONDS
0926 ; IN AL,CMOS_PORT+2
0927 ; SAVE
0928 ; SET_ADDRESS_OF_MINUTES
0929 ; SAVE
0930 ; SET_ADDRESS_OF_HOURS
0931
0931 ; INTERRUPTS BACK ON
0932 ; SAME SEGMENT
0933 ; SET DATA SEGMENT
0934 ; AH=0
0935 ; READ_TIME
0936 ; AH=1
0937 ; SET_TIME
0938 ; READ_IF_VALID
0939 ; RETURN_IF_INVALID
0940 ; GO_CHECK_OTHER_FUNCTIONS
0941 ; TOD_RETURN
0942 ; INTERRUPTS_BACK_ON
0943 ; RECOVER_SEGMENT
0944 ; RETURN_TO_CALLER
0945
0945 ; SET_ERROR_RETURN
0946
0946 ; READ_TIME
0947 ; NO_INTERRUPTS WHILE READING
0948 ; GET_OVERFLOW, AND RESET THE FLAG
0949
0949 ; SET_TIMER
0950 ; NO_INTERRUPTS WHILE WRITING
0951 ; SET THE TIME
0952 ; RESET_OVERFLOW
0953 ; TOD_RETURN
0954
0954 ; SET_TIMER
0955 ; NO_INTERRUPTS WHILE WRITING
0956 ; SET THE TIME
0957 ; RESET_OVERFLOW
0958 ; TOD_RETURN
0959
0959 ; CHECK_FOR_UPDATE_IN_PROCESS
0960 ; GO_AROUND_IF_OK
0961 ; RETURN_IF_ERROR
0962
0962 ; INTERRUPTS OFF DURING READ
0963 ; SET_ADDRESS_OF_SECONDS
0964 ; IN AL,CMOS_PORT+2
0965 ; SAVE
0966 ; SET_ADDRESS_OF_MINUTES
0967 ; SAVE
0968 ; SET_ADDRESS_OF_HOURS
0969
0969 ; INTERRUPTS BACK ON
0970 ; SAME SEGMENT
0971 ; SET DATA SEGMENT
0972 ; AH=0
0973 ; READ_TIME
0974 ; AH=1
0975 ; SET_TIME
0976 ; READ_IF_VALID
0977 ; RETURN_IF_INVALID
0978 ; GO_CHECK_OTHER_FUNCTIONS
0979 ; TOD_RETURN
0980 ; INTERRUPTS_BACK_ON
0981 ; RECOVER_SEGMENT
0982 ; RETURN_TO_CALLER
0983
0983 ; SET_ERROR_RETURN
0984
0984 ; READ_TIME
0985 ; NO_INTERRUPTS WHILE READING
0986 ; GET_OVERFLOW, AND RESET THE FLAG
0987
0987 ; SET_TIMER
0988 ; NO_INTERRUPTS WHILE WRITING
0989 ; SET THE TIME
0990 ; RESET_OVERFLOW
0991 ; TOD_RETURN
0992
0992 ; SET_TIMER
0993 ; NO_INTERRUPTS WHILE WRITING
0994 ; SET THE TIME
0995 ; RESET_OVERFLOW
0996 ; TOD_RETURN
0997
0997 ; CHECK_FOR_UPDATE_IN_PROCESS
0998 ; GO_AROUND_IF_OK
0999 ; RETURN_IF_ERROR
0999 ;-----
```

```

0068 8A E8          MOV    CH,AL      ; SAVE
006A B2 00          MOV    DL,0        ; SET DL TO ZERO
006C EB A7          JMP    T1         ; RETURN
006E                                     RTC_GET_TIME ENDP

006E                                     ; RTC_SET_TIME PROC NEAR
006F                                     RTC_3: CALL  UPD_IN_PR ; CHECK FOR UPDATE IN PROCESS
0070 E8 01B7 R       JNC    RTC_3A ; GO AROUND IF CLOCK OPERATING
0071 73 03          CALL  INITIALIZE_STATUS

0076                                     RTC_3A: CLI   ; INTERRUPTS OFF DURING SET
0077 52              PUSH   DX        ; SAVE
0078 B2 FF          MOV    DL,-2     ; FIRST ADDRESS
0079 E8 0192 R       CALL  PORT_INC_2 ; UPDATE ADDRESS
007D 8A C6          MOV    AL,DH     ; GET TIME BYTE - SECONDS
007F E6 71          OUT   CMOS_PORT+1,AL ; STORE TIME BYTE
0080 E8 0192 R       CALL  PORT_INC_2 ; UPDATE ADDRESS
0081 8A C1          MOV    AL,C1     ; GET TIME BYTE - MINUTES
0082 E6 71          OUT   CMOS_PORT+1,AL ; STORE TIME BYTE
0083 8A C5          MOV    AL,CH     ; UPDATE ADDRESS
0084 E8 0192 R       CALL  PORT_INC_2 ; GET TIME BYTE - HOURS
0085 8A C0          OUT   CMOS_PORT+1,AL ; STORE TIME BYTE
0086 E6 71          MOV    DL,OAH    ; STORE TIME BYTE
0087 B2 04          CALL  PORT_INC ; RESTORE
0088 E8 01B8 R       CALL  PORT_INC ; GET CURRENT VALUE
0089 58              OR    AL,DL     ; MASK FOR VALID BIT POSITIONS
0090 00 02          OR    AL,O2H    ; GET DST BIT
0091 E8 01B8 R       PUSH   AX        ; TURN ON 24 HR MODE
0092 8A C4          CALL  PORT_INC ; ...
0093 E8 01B8 R       CALL  PORT_INC ; ...
0094 5A              POP    DX        ; ...
0095 E6 71          IN    AL,CMOS_PORT+1 ; ...
0096 24 23          AND   AL,23H    ; ...
0097 04 C2          OR    AL,DL     ; ...
0098 00 02          OR    AL,O2H    ; ...
0099 E8 01B8 R       PUSH   AX        ; ...
009D 8A F0          CALL  PORT_INC ; ...
009E B2 04          MOV    DL,OAH    ; ...
00A0 E8 01B8 R       CALL  PORT_INC ; ...
00A1 58              OUT   AL,CMOS_PORT+1,AL ; ...
00A2 E6 71          JMP    T1         ; ...
00A3 E9 0015 R       CALL  RTC_SET_TIME ; ...
00A4                                     RTC_SET_TIME ENDP ; DONE
00A5                                     ; ...

00A9                                     RTC_GET_DATE PROC NEAR
00A9                                     RTC_4: CALL  UPD_IN_PR ; ...
00AC 73 03          JNC    RTC_4A ; ...
00AE E9 0018 R       JMP    T1_A      ; RETURN ON ERROR
00B1                                     RTC_4A: CLI   ; ...
00B2 8A 06          MOV    DL,6      ; ...
00B3 E8 01B8 R       CALL  PORT_INC ; ...
00B4 E6 71          IN    AL,CMOS_PORT+1 ; ...
00B5 8A E8          MOV    CH,AL     ; ...
00B6 E8 01B8 R       CALL  PORT_INC ; ...
00B7 E6 71          IN    AL,CMOS_PORT+1 ; ...
00B8 8A F0          MOV    DL,0      ; ...
00B9 E8 01B8 R       CALL  PORT_INC ; ...
00C0 E6 71          IN    AL,CMOS_PORT+1 ; ...
00C1 8A C5          MOV    DL,CH     ; ...
00C2 E8 01B8 R       CALL  PORT_INC ; ...
00C3 E6 71          IN    AL,CMOS_PORT+1 ; ...
00C4 8A C8          MOV    CL,AL     ; ...
00C5 E6 71          MOV    DL,31H    ; ...
00C6 8A C8          CALL  PORT_INC ; ...
00C7 E6 71          IN    AL,CMOS_PORT+1 ; ...
00C8 8A C5          MOV    DL,CH     ; ...
00C9 E6 71          CALL  PORT_INC ; ...
00CA E8 01B8 R       CALL  PORT_INC ; ...
00CE E6 71          IN    AL,CMOS_PORT+1 ; ...
00DD 8A D5          MOV    DL,CH     ; ...
00DE 8A E8          MOV    CH,AL     ; ...
00DF E9 0015 R       JMP    T1         ; ...
00E0                                     RTC_GET_DATE ENDP ; FINISHED
00E1                                     RTC_5: DEC   AH=4 ; ...
00E2 74 CC          JZ    RTC_4 ; ...
00E3 FE CC          DEC   AH=5 ; ...
00E4 74 CE          JZ    RTC_5 ; ...
00E5 FE CC          DEC   AH=6 ; ...
00E6 74 07          JZ    RTC_6 ; ...
00E7 FE CC          DEC   AH=7 ; ...
00E8 E9 0175 R       JMP    RTC_7 ; ...
00E9                                     ; RESET RTC ALARM

00E6                                     RTC_SET_DATE PROC NEAR
00E6                                     RTC_5: CALL  UPD_IN_PR ; ...
00E7 73 03          JNC    RTC_5A ; ...
00E8 E8 019A R       CALL  INITIALIZE_STATUS ; ...
00E9                                     RTC_5A: CLI   ; ...
00EA 51              PUSH   CX        ; ...
00EB 04 EA          MOV    CX,DL    ; ...
00FC B2 05          MOV    DL,5      ; ...
00FD E8 01B8 R       CALL  PORT_INC ; ...
00FE B0 00          MOV    AL,00H    ; ...
00FF E6 71          OUT   CMOS_PORT+1,AL ; ...
0000 E8 01B8 R       CALL  PORT_INC ; ...
0001 E6 71          OUT   CMOS_PORT+1,AL ; ...
0002 E8 01B8 R       CALL  PORT_INC ; ...
0003 E6 71          OUT   CMOS_PORT+1,AL ; ...
0004 E8 01B8 R       CALL  PORT_INC ; ...
0005 E6 71          OUT   CMOS_PORT+1,AL ; ...
0006 E8 01B8 R       CALL  PORT_INC ; ...
0007 E6 71          OUT   CMOS_PORT+1,AL ; ...
0008 E8 01B8 R       CALL  PORT_INC ; ...
0009 E6 71          OUT   CMOS_PORT+1,AL ; ...
000A E8 01B8 R       CALL  PORT_INC ; ...
000B E6 71          OUT   CMOS_PORT+1,AL ; ...
000C E8 01B8 R       CALL  PORT_INC ; ...
000D E6 71          OUT   CMOS_PORT+1,AL ; ...
000E E8 01B8 R       CALL  PORT_INC ; ...
000F E6 71          OUT   CMOS_PORT+1,AL ; ...
0010 E8 01B8 R       CALL  PORT_INC ; ...
0011 E6 71          OUT   CMOS_PORT+1,AL ; ...
0012 E8 01B8 R       CALL  PORT_INC ; ...
0013 E6 71          IN    AL,CMOS_PORT+1 ; ...
0014 20 7F          AND   AL,07FH    ; ...
0015 E6 71          OUT   CMOS_PORT+1,AL ; ...
0016 59              POP    CX        ; ...
0017 E8 01B8 R       CALL  PORT_INC ; ...
0018 E6 71          MOV    DL,31H    ; ...
0019 E8 01B8 R       CALL  PORT_INC ; ...
001A E6 71          IN    AL,CMOS_PORT+1 ; ...
001B E8 01B8 R       CALL  PORT_INC ; ...
001C B2 31          MOV    DL,CH     ; ...
001D E8 01B8 R       CALL  PORT_INC ; ...
001E E6 71          MOV    AL,CH     ; ...
001F E8 01B8 R       CALL  PORT_INC ; ...
0020 E6 71          OUT   CMOS_PORT+1,AL ; ...
0021 E8 01B8 R       CALL  PORT_INC ; ...
0022 E6 71          OUT   CMOS_PORT+1,AL ; ...
0023 E8 01B8 R       CALL  PORT_INC ; ...
0024 E6 71          OUT   CMOS_PORT+1,AL ; ...
0025 E8 01B8 R       CALL  PORT_INC ; ...
0026 E6 71          JMP    T1         ; ...
0027                                     RTC_SET_DATE ENDP ; ...

0128                                     RTC_SET_ALARM PROC NEAR
0128                                     RTC_6: B2 0A          MOV    DL,OAH    ; ...
0129 E8 01B8 R       CALL  PORT_INC ; ...
0130 E6 71          IN    AL,CMOS_PORT+1 ; ...
0131 20 7F          TEST  AL,20H    ; ...
0132 E6 71          JZ    RTC_6A ; ...
0133 70 05          XOR   AX,AX     ; ...
0134 E9 0018 R       JMP    T1_A      ; ...
0135                                     RTC_6A: CALL  UPD_IN_PR ; ...
0136 73 03          JNC    RTC_6B ; ...
0137 E8 019A R       CALL  INITIALIZE_STATUS ; ...
0138                                     RTC_6B: CLI   ; ...
0139 5A              MOV    DL,-1     ; ...
0140 E8 01B8 R       CALL  PORT_INC_2 ; ...
0141 B2 FF          CALL  PORT_INC_2 ; ...
0142 E8 0192 R       MOV    AL,DH     ; ...
0143 E6 71          OUT   CMOS_PORT+1,AL ; ...
0144 E8 0192 R       CALL  PORT_INC_2 ; ...
0145 E6 71          OUT   CMOS_PORT+1,AL ; ...
0146 E8 0192 R       CALL  PORT_INC_2 ; ...
0147 E6 71          OUT   CMOS_PORT+1,AL ; ...
0148 E6 71          OUT   CMOS_PORT+1,AL ; ...

```

```

014A E8 0192 R          CALL    PORT_INC_2
014D 8A C1              MOV     AL,CL           ; GET MINUTES PARAMETER
014F E6 71              OUT    CMOS_PORT+1,AL ; LOAD ALARM BYTE - MINUTES
0151 E8 0192 R          CALL    PORT_INC_2
0154 E6 C5              MOV     AL,CH           ; GET HOURS PARAMETER
0156 E6 71              OUT    CMOS_PORT+1,AL ; LOAD ALARM BYTE - HOURS
0158 E6 A1              IN     AL,DA1H         ; ENSURE INTERRUPT UNMASKED
015A 24 FE              AND    AL,0FEH
015C E6 A1              OUT    OAH1,AL
015E B6 04              MOV     DL,0AH
0160 E8 018B R          CALL    PORT_INC
0162 E6 71              IN     AL,CMOS_PORT+1
0164 24 7F              AND    AL,07FH        ; ENSURE SET BIT TURNED OFF
0167 OC 20              OR     AL,20H         ; TURN ON ALARM ENABLE
0169 50
016A B2 0A              PUSH   AX
016C E8 018B R          MOV     DL,0AH
016D 24 50              CALL   PORT_INC
0170 E6 71              POP    AX
0172 E9 0015 R          OUT    CMOS_PORT+1,AL ; ENABLE ALARM
0175 JMP    T1
0175 RTC_SET_ALARM ENDP

0175 RTC_RESET_ALARM PROC NEAR
0175 RTC_7:
0175     CLI
0176 B2 0A              MOV     DL,0AH
0178 E8 018B R          CALL   PORT_INC
017B E4 71              IN     AL,CMOS_PORT+1
017D 24 57              AND    AL,57H        ; GET STATUS BYTE
017F 50
0180 B2 0A              PUSH   AX
0182 E8 018B R          MOV     DL,0AH
0185 58
0186 E6 71              CALL   PORT_INC
0188 E9 0015 R          OUT    CMOS_PORT+1,AL ; RESTORE
018B JMP    T1
018B RTC_RESET_ALARM ENDP

018B RTC_TIMEBIOS_SUBR PROC NEAR
018B PORT_INC:
018B     ADD    DL,1             ; INCREMENT ADDRESS
018D 8A C2              MOV     AL,DL
018F E6 70              OUT    CMOS_PORT,AL
0191 C3
0192 ;PORT_INC_2:
0192 80 C2 02             ADD    DL,2             ; INCREMENT ADDRESS
0195 8A C2
0197 E6 70
0199 C3
019A ;INITIALIZE_STATUS PROC NEAR
019A 52
019B B2 09              PUSH   DX             ; SAVE
019D E8 018B R          CALL   PORT_INC
01AD B6 26              MOV     AL,26H
01B2 E6 26              OUT    CMOS_PORT+1,AL ; INITIALIZE 'A' REGISTER
01A4 E8 018B R          CALL   PORT_INC
01A7 B0 82              MOV     AL,82H        ; SET 'SET BIT' FOR CLOCK INITIALIZATION
01A9 E6 71              OUT    CMOS_PORT+1,AL ; AND 24 HOUR MODE
01A8 E8 018B R          CALL   PORT_INC        ; INITIALIZE 'B' REGISTER
01B0 E8 018B R          CALL   PORT_INC
01B3 E4 71              IN     AL,CMOS_PORT+1
01B5 5A 71              POP    DX             ; READ REGISTER 'C' TO INITIALIZE
01B6 C3
01B7 ;INITIALIZE_STATUS ENDP
01B7 ;UPD_IN_PR:
01B7 51
01B8 B9 0258             PUSH   CX             ; SET LOOP COUNT
01B9 E6 70
01B8 B0 0A              MOV     CX,600
01BD E6 70              UPDATE: MOV    AL,0AH           ; ADDRESS OF `A` REGISTER
01BF EB 00              OUT    CMOS_PORT,AL
01C1 E4 71              JMP    S2             ; I/O TIME DELAY
01C3 A8 80              IN     AL,80H           ; READ IN REGISTER 'A'
01C4 57 00              TEST   AL,80H
01C7 E2 F2              JZ    UPD_IN_PREND ; IF BXH--> UIP BIT IS ON (CANNOT READ TIM
01C9 33 C0              LOOP   UPDATE
01CB F9
01CC E6 70              XOR    AX,AX
01CD 59
01CE C3
01CE ;UPD_IN_PREND:
01CE             POP    CX             ; SET CARRY FOR ERROR
01CE             RET
01CE RTC_TIMEBIOS_SUBR ENDP
01CE TIME_OF_DAY_T ENDP
01CE PAGE
;INT 50 (LEVEL 8)
;THIS ROUTINE HANDLES THE PERIODIC AND ALARM INTERRUPTS FROM
;THE NON-VOLATILE TIMER. INPUT FREQUENCY IS 1.024 KHZ
;OR APPROXIMATELY 1024 INTERRUPTS EVERY SECOND FOR THE
;PERIODIC INTERRUPT. FOR THE ALARM FUNCTION, AN INTERRUPT WILL
;OCCUR AT THE DESIGNATED TIME.
;THE INTERRUPT IS ENABLED ONLY WHEN EVENT OR ALARM FUNCTIONS
;ARE ACTIVE.
;FOR THE EVENT INTERRUPT, THE HANDLER WILL DECREMENT THE
;WAIT COUNTER, AND WHEN IT EXPIRES WILL TURN ON THE HIGH ORDER
;BIT OF THE DESIGNATED ADDRESS.
;FOR THE ALARM INTERRUPT, THE USER ROUTINE WILL BE INVOKED
;THROUGH INT 4AH. THE USER MUST CODE A ROUTINE AND PLACE THE
;CORRECT ADDRESS IN THE VECTOR TABLE.
-----+
RTC_INT PROC FAR
01CE ST1    DS             ; INTERRUPTS BACK ON
01CF 1E    PUSH  DS           ; SAVE REGISTERS
01D0 50    PUSH  AX
01D1 52    PUSH  DX
01D2 57 00  MOV   DL,0AH        ; GET ENABLES
01D3 52 0A  PUSH  DI
01D5 E8 018B R          CALL   PORT_INC
01D6 E4 71              IN     AL,CMOS_PORT+1
01D8 8A E0              MOV    AH,AL           ; SAVE
01DC E8 018B R          CALL   PORT_INC
01DD 58 71  IN     AL,CMOS_PORT+1 ; GET SOURCE
01E1 52 04  AND    AL,AH
01E3 50
01E5 A8 40  PUSH  AX           ; SAVE
01E6 74 2E  TEST   AL,040H_9      ; CHECK FOR PERIODIC INTERRUPT
01E7 00 0000 E          CALL   RTC_INT_9    ; NO - GO AROUND
01E8 B1 2E 000C R 03D0  SUB    RTC_LOW,0976 ; ESTABLISH ADDRESSABILITY
01F1 83 1E 009E R 00    SBB   RTC_HIGH,0  ; DECREMENT COUNT
01F6 77 1E  JA    RTC_INT_9

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01FB B2 0A
01FA E8 018B R
01FD E4 71
01FF 24 BF
0201 50
0202 B2 0A
0203 E8 018B R
0207 50
0208 E6 71
020A C6 06 00AO R 00
020F C5 3E 0098 R
0213 C6 05 80

0216 FB 00
0217 A8 20
0219 74 02
021B CD 4A
021D 50
021D B0 20
021F E6 A0
0221 E6 20
0223 5F
0224 5A
0225 58
0226 1F
0227 CF
0228 58

MOV DL,0AH ; TURN OFF PIE
CALL PORT_INC
IN AL,CMOS_PORT+1
AND AL,0BFH
PUSH AX
MOV DL,0AH
CALL PORT_INC
OUT AL,CMOS_PORT+1,AL
MOV RTC_WAIT_FLAG,0 ; SET FUNCTION ACTIVE FLAG OFF
DI,DWORD PTR USER_FLAG ; SET UP DS,DI TO POINT TO USER FLAG
BYTE PTR[DI],80H ; TURN ON USERS FLAG

RTC_INT_9:
POP AX ; GET INTERRUPT SOURCE BACK
TEST AL,20H ; TEST FOR ALARM INTERRUPT
JZ RTC_INT_10 ; NO - GO AROUND
INT 4AH ; TRANSFER TO USER ROUTINE
MOV AL,EOI ; END OF INTERRUPT TO 8259 - 2
OUT 0A0H,AL ; AND TO 8259 - 1
MOV 020H,AL ; RESTORE REGISTERS
POP DX
POP DS
IRET ; END OF INTERRUPT
RTC_INT_ENDP
PAGE

;----- INT 8 (LEVEL 0) -----
; THIS ROUTINE HANDLES THE TIMER INTERRUPT FROM
; CHANNEL 0 OF THE 8253 TIMER. INPUT FREQUENCY IS 1.19318 MHZ
; AND THE DIVISOR IS 65536, RESULTING IN APPROX. 18.2 INTERRUPTS
; EVERY SECOND.
;
; THE INTERRUPT HANDLER MAINTAINS A COUNT OF INTERRUPTS SINCE
; POWER ON TIME, WHICH MAY BE USED TO ESTABLISH TIME OF DAY.
; THE INTERRUPT HANDLER ALSO DECREMENTS THE MOTOR CONTROL COUNT
; OF THE DISKETTE, AND WHEN IT EXPIRES, WILL TURN OFF THE
; DISKETTE MOTOR(S), AND RESET THE MOTOR RUNNING FLAGS.
;
; THIS LOGIC WILL BE INVOKED BY THE USER ROUTINE THROUGH
; INTERRUPT 1CH AT EVERY TIME TICK. THE USER MUST CODE A
; ROUTINE AND PLACE THE CORRECT ADDRESS IN THE VECTOR TABLE.

;----- TIMER_INTERRUPT_1 PROC FAR ; 
0228 FB STI ; INTERRUPTS BACK ON
0229 1E PUSH DS
022A 50 PUSH AX
022B 52 PUSH DDS
022C E8 0000,E CALL DDS ; SAVE MACHINE STATE
022D FF 06 006C R INC TIMER_LOW ; ESTABLISH ADDRESSABILITY
0233 75 04 UNZ TH ; INCREMENT TIME
0235 FF 06 006E R INC TIMER_HIGH ; TEST_DAY
0239 83 3E 006E R 18 CMP TIMER_HIGH,018H ; TEST FOR COUNT EQUALLING 24 HOURS
023E 75 15 JNZ T5 ; DISKETTE_CTL
0240 81 3E 006C R 00B0 CMP TIMER_LOW,0B0H
0246 75 0D JNZ T5 ; DISKETTE_CTL

;----- TIMER HAS GONE 24 HOURS
0248 B8 00 SUB AX,AX
024A A3 006E R MOV TIMER_HIGH,AX
024D A3 006C R MOV TIMER_LOW,AX
0250 C6 06 0070 R 01 MOV TIMER_OFL,1

;----- TEST FOR DISKETTE TIME OUT
T5: DEC MOTOR_COUNT ; DISKETTE_CTL
0255 FF 0E 0040 R JNZ T6 ; RETURN IF COUNT NOT OUT
0259 75 0B AND MOTOR_STATUS,0FOH ; TURN OFF MOTOR RUNNING BITS
0260 B0 0C MOV AL,OCH
0261 BA 03F2 MOV DX,03F2H ; FDC CTL PORT
0265 EE OUT DX,AL ; TURN OFF THE MOTOR

T6: INT 1CH ; TIMER_RET:
0266 CD 1C MOV AL,EOI ; TRANSFER CONTROL TO A USER ROUTINE
0267 B0 20 MOV 020H,AL ; END OF INTERRUPT TO 8259
026A E6 20 POP DX
026C 5A POP AX
026D 58 POP DS ; RESET MACHINE STATE
026F 1F IRET ; RETURN FROM INTERRUPT
0270 CF TIMER_INTERRUPT_1 ENDP

;----- INT 5 -----
; THIS LOGIC WILL BE INVOKED BY INTERRUPT 0DH TO PRINT
; THE SCREEN. THE CURSOR POSITION AT THE TIME THIS ROUTINE
; IS INVOKED WILL BE SAVED AND RESTORED UPON COMPLETION. THE
; ROUTINE IS INTENDED TO RUN WITH INTERRUPTS ENABLED.
; IF A SUBSEQUENT 'PRINT SCREEN' KEY IS DERESSED DURING THE
; TIME THIS ROUTINE IS PRINTING, IT WILL BE IGNORED.
; ADDRESS 50:0 CONTAINS THE STATUS OF THE PRINT SCREEN:
;
; 50:0 =0 EITHER PRINT SCREEN HAS NOT BEEN CALLED
; OR UPON RETURN FROM A CALL THIS INDICATES
; A SUCCESSFUL OPERATION.
;
; =1 PRINT SCREEN IS IN PROGRESS
;
; =255 ERROR ENCOUNTERED DURING PRINTING
;
; ASSUME CS:CODE,DS:XXDATA

;----- PRINT_SCREEN_1 PROC FAR ; 
0270 FB STI ; MUST RUN WITH INTERRUPTS ENABLED
0271 1E PUSH DS ; MUST USE 50:0 FOR DATA AREA STORAGE
0272 50 PUSH AX
0273 53 PUSH BX
0274 51 PUSH CX ; WILL USE THIS LATER FOR CURSOR LIMITS
0275 52 PUSH DX ; WILL HOLD CURRENT CURSOR POSITION
0276 B8 ---- R MOV AX,XXDATA ; HEX 50
0277 04 D8 MOV AX,0
0278 B0 3E 0000 R 01 CMP STATUS_BYT,1 ; SEE IF PRINT ALREADY IN PROGRESS
0280 74 5F JZ EXIT ; JUMP IF PRINT ALREADY IN PROGRESS
0282 C6 06 0000 R 01 MOV STATUS_BYT,1 ; INDICATE PRINT NOW IN PROGRESS
0287 B4 0F MOV AH,15 ; WILL REQUEST THE CURRENT SCREEN MODE
0289 CD 10 INT TOH ; [AH]=MODE ; [AH]=NUMBER COLUMNS/LINE
; [BH]=VISUAL PAGE
; ****


```

AT THIS POINT WE KNOW THE COLUMNS/LINE ARE IN [AX] AND THE PAGE IF APPLICABLE IS IN [BH]. THE STACK HAS DS,AX,BX,CX,DX PUSHED. [AL] HAS VIDEO MODE

```

028B 8A CC          ; *****
028D B5 19          MOV CL,AH   ; WILL MAKE USE OF [CX] REGISTER TO
028E E8 02E7 R      MOV CH,25  ; CONTROL ROW & COLUMNS
CALL CRLF           CALL CRLF ; CARRIAGE RETURN LINE FEED ROUTINE
PUSH CX             SAVE SCREEN BOUNDS
MOV AH,3             INT 10H ; WILL NOW READ THE CURSOR.
INT 10H             INT 10H ; READ PREVIOUS POSITION
POP DX              POP DX ; RECALL SCREEN BOUNDS
PUSH DX              PUSH DX ; RECALL [BH]=VISUAL PAGE
XOR DX,DX            XOR DX,DX ; WILL SET CURSOR POSITION TO [0,0]
0299 33 D0          ; *****

029B B4 02          ; THE LOOP FROM PR10 TO THE INSTRUCTION PRIOR TO PR120
029D CD 10          ; IS THE LOOP TO READ EACH CURSOR POSITION FROM THE SCREEN
029E B4 03          ; AND PR115
02A1 CD 10          ; *****
02A7 29             ; *****
0298 32             ; *****
0299 33 D0          ; *****

```

029B B4 02 ; PRI10: MOV AH,2 ; TO INDICATE CURSOR SET REQUEST
029D CD 10 ; INT 10H ; NEW CURSOR POSITION ESTABLISHED
029E B4 03 ; MOV AH,B ; TO INDICATE RECENT CHARACTER
02A1 CD 10 ; INT 10H ; CHARACTER NOT IN [AL]
02A3 0A C0 ; OR AL,AL ; SEE IF VALID CHAR
02A5 75 02 ; JNZ PR115 ; JUMP IF VALID CHAR
02A7 B0 20 ; MOV AL,' ' ; MAKE A BLANK
02A9 52 ; \*\*\*\*\*
02AA 33 D2 ; PRI115: PUSH DX ; SAVE CURSOR POSITION
02AC 32 E4 ; XOR DX,DX ; INDICATE PRINTER 1
02AE CD 17 ; XOR AH,AH ; TO INDICATE PRINT CHAR IN [AL]
02B0 5A ; INT 17H ; PRINT THE CHARACTER
02B1 F4 C4 29 POP DX ; RECALL CURSOR POSITION
TEST AH,29H TEST AH,29H ; TEST FOR AN INTERNAL ERROR
JNZ ERR10 ; JNZ ERR10 ; JUMP IF ERROR DETECTED
INC DL ; INC DL ; ADVANCE TO NEXT COLUMN
CMP CL,DL ; CMP CL,DL ; SEE IF AT END OF LINE
JNZ PR110 ; JNZ PR110 ; IF NOT PROCEED
02B8 3A CA ; XOR DL,DL ; BACK TO COLUMN 0
02B9 75 DF ; MOV AH,DL ; LINE=1
02B8 3A CA ; PUSH DX ; SAVE NEW CURSOR POSITION
02B9 75 DF ; CALL CRLF ; LINE FEED CARRIAGE RETURN
02B8 32 D2 ; POP DX ; RECALL CURSOR POSITION
02B9 75 DF ; INC DH ; ADVANCE TO NEXT LINE
02C0 52 ; \*\*\*\*\*
02C1 E8 02E7 'R ; PRI120: POP POP ; FINISHED
02C4 5A ; MOV AH,2 ; NOT CONTINUE
02C5 FE C6 ; INT 10H ; CALL CRLF ; RECALL CURSOR POSITION
02C6 3A EE ; XOR DX,DX ; TO INDICATE CURSOR SET REQUEST
02C8 5A ; JNZ PR110 ; NEW CURSOR POSITION
02C9 5A ; MOV AH,2 ; TO INDICATE CURSOR SET REQUEST
02CC B4 02 ; INT 10H ; CURSOR POSITION RESTORED
02D0 G6 00 0000 R 00 ; MOV STATUS\_BYTE,O ; INDICATE FINISHED
02D1 0A ; JNZ SHORT\_EXIT ; EXIT IF FINISHED
02D5 5A ; SHORT\_EXIT: POP DX ; GET CURSOR POSITION
02D6 B4 02 ; MOV AH,2 ; TO REQUEST CURSOR SET
02DA CD 10 ; INT 10H ; CURSOR POSITION RESTORED
02DC G6 00 0000 R FF ; ERR20: MOV STATUS\_BYTE,OFFH ; INDICATE ERROR
02E1 5A ; EXIT: POP DX ; RESTORE ALL THE REGISTERS USED
02E2 59 ; POP CX
02E3 5B ; POP BX
02E4 58 ; POP AX
02E5 1F ; POP DS
02E6 CF ; IRET
PRINT\_SCREEN\_1 ENDP ; \*\*\*\*\*

;----- CARRIAGE RETURN, LINE FEED SUBROUTINE
CRLF PROC NEAR
02E7 33 D2 XOR DX,DX ; PRINTER 0
02E9 32 E4 XOR AH,AH ; WILL NOW SEND INITIAL LF,CR TO PRINTER
02EB B0 0A MOV AL,12Q ; LF
02ED CD 17 INT 17H ; SEND THE LINE FEED
02EF 32 E4 XOR AH,AH ; NOW FOR THE CR
02F1 B0 0D MOV AL,15Q ; CR
02F3 CD 17 INT 17H ; SEND THE CARRIAGE RETURN
02F5 C3 RET
02F6 ENDS CRLF CODE ENDS
ENDS



```

TITLE 12/08/83 ORGS
.LIST
INCLUDE SEGMENT.SRC
CODE SEGMENT BYTE PUBLIC
C
ASSUME CS:CODE, DS:DATA

EXTRN K16:NEAR
EXTRN IN_287:NEAR
EXTRN DSKETTE_SETUP:NEAR
EXTRN DISK_SETP:NEAR
EXTRN SEEK:NEAR
EXTRN RTC_INT:NEAR
EXTRN START_1:NEAR
EXTRN NMI_INT_1:NEAR
EXTRN BOOT_STRAP:NEAR
EXTRN KEYBOARD_IO:NEAR
EXTRN KB_INT_1:NEAR
EXTRN DISKETTE_IO_1:NEAR
EXTRN DISK_INT_1:NEAR
EXTRN PRINTER_IO_1:NEAR
EXTRN VIDEOPARM:NEAR
EXTRN MEMORY_SIZE_DETERMINE_1:NEAR
EXTRN EQUIPMENT_1:NEAR
EXTRN CASSETTE_TO_1:NEAR
EXTRN TIME_OF_DAY_1:NEAR
EXTRN TIMER_INT_1:NEAR
EXTRN D11:NEAR
EXTRN RS232_IO_1:NEAR
EXTRN DUMMY_RETURN_1:NEAR
EXTRN PRINT_SCREEN_1:NEAR
EXTRN C11:NEAR
EXTRN C21:NEAR
EXTRN TSTA_B:NEAR
EXTRN TSTU_C:NEAR
EXTRN TSTU_D:NEAR
EXTRN E30B:NEAR
EXTRN E30C:NEAR
EXTRN RE_DIRECT:NEAR

PUBLIC BOOT_INVA
PUBLIC TUTOR
PUBLIC START
PUBLIC C1
PUBLIC C2
PUBLIC C8042A
PUBLIC OBF_42B
PUBLIC OBF_42A
PUBLIC C9042B
PUBLIC C9042C
PUBLIC EO
PUBLIC EO_A
PUBLIC EO_B
PUBLIC TUR_ERR
PUBLIC E1
PUBLIC F3A
PUBLIC D1
PUBLIC D2
PUBLIC D2A
PUBLIC F3D
PUBLIC F2D1
PUBLIC F1D1
PUBLIC F1_A
PUBLIC F1_B
PUBLIC F3
PUBLIC CLOCK
PUBLIC CM1
PUBLIC CM2
PUBLIC CM3
PUBLIC CM4

PUBLIC CM4_A
PUBLIC CM4_B
PUBLIC CM4_C
PUBLIC CM4_D
PUBLIC F3B
PUBLIC F2
PUBLIC FUE
PUBLIC E1_A
PUBLIC E1_B
PUBLIC E1_C
PUBLIC ADEERR
PUBLIC ADERR_PARM
PUBLIC VECTOR_TABLE
PUBLIC SLAVE_VECTOR_TABLE
PUBLIC DISK_BASE
PUBLIC VIDEO_PARMS
PUBLIC M0
PUBLIC M2
PUBLIC M6
PUBLIC M7
PUBLIC CRT_CHAR_GEN
PUBLIC PRINT_SCREEN
PUBLIC A1
PUBLIC K6
PUBLIC K6L
PUBLIC K7
PUBLIC K8
PUBLIC K9
PUBLIC K10
PUBLIC K11
PUBLIC K12
PUBLIC K13
PUBLIC K14
PUBLIC K15
PUBLIC RS232_IO
PUBLIC DUMMY_RETURN
PUBLIC NMI_INT
PUBLIC BOOT_STRAP
PUBLIC KEYBOARD_IO
PUBLIC KB_INT
PUBLIC DISKETTE_IO
PUBLIC DISK_INT
PUBLIC PRINTER_IO
PUBLIC VIDEOPARM
PUBLIC MEMORY_SIZE_DETERMINE
PUBLIC EQUIPMENT
PUBLIC CASSETTE_IO
PUBLIC TIME_OF_DAY
PUBLIC TIMER_INT
PUBLIC HROM
PUBLIC FLOPPY
PUBLIC SEEKS_1
PUBLIC F1780
PUBLIC F1781
PUBLIC F1782

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PUBLIC F1790  
PUBLIC F1791  
PUBLIC ED TBI

THIS MODULE HAS BEEN ADDED TO FACILITATE THE EXPANSION OF THIS PROGRAM. IT ALLOWS FOR THE FIXED ORG STATEMENT ENTRY POINTS THAT HAVE TO REMAIN AT THE SAME ADDRESSES...ADDED ON 9/16/82.

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; ORG 0E000H

0000 36 31 38 31 30 32 DB '6181028 COPR. IBM 1984'  
38 43 4F 50 52  
2E 20 49 42 4D 20  
31 39 38 34

```

005B          ;           ORG    0E05BH
005B          ;           ORG    0005BH
005B          RESET     LABEL   FAR
005B          START:    JMP    START_1
005B E9 0000 E

```

; ++++++ ++++++ ++++++ ++++++

TEMPORARY STACK FOR POST				
		C1	DH	C11
005E	0000	E	C1	-
0060	0000	E	C2	DW
0062	0000	E	C8042A	DW
0064	0000	E	0BF_42A	DW
0066	0000	E	C8042B	DW
0068	0000	E	C8042C	DW
006A	0000	E	0BF_52C	DW

-----

006C 20 31 30 31 2D 53 E0 DB '101-System Board Error',13,10 ; INTERRUPT FAILURE  
29 33 26 C5 ED 29

0085 00 31 30 32 2D 53 EO\_A DB ' 102-System Board Error',13,10 ; TIMER FAILURE  
42 6F 61 72 64 20  
45 72 72 6F 72 0D

009E 20 31 30 33 20 53 EO\_B DB ' 103-System Board Error',13,10 ; TIMER INTERRUPT FAILURE  
79 73 74 65 60 20

42 6F 61 72 6A 20  
45 72 72 6F 7D 0D  
0A  
00B7 20 31 30 34 2D 53 VIR\_ERR DB ' 104-System Board Error',13,10 ; PROTECTED MODE FAILURE

0000 20 31 30 35 2D 53 CM4 DB '105-System Board Error' 13 10 : LAST 80H2 COMMAND NOT ACCEPTED

00E9 00 32 30 31 2D 4D E1 DB '201-Memory Error',13,  
65 6D 6F 72 79 20  
45 72 72 6F 72 0D  
0A  
00FC 20 34 30 31 2D 43 E1 B DB '401-CRT Error',13,10

52 54 20 45 72 72  
6F 72 00 0A  
20 35 30 31 2D 43  
52 54 20 45 72 72

E1\_C DB ' 501-CRT Error',13,10

011C 6F 72 00 OA  
00 32 30 32 2D 4D ADERR1 DB ' 202-Memory Address E  
65 60 6F 72 79 20  
41 64 64 72 65 73  
73 20 45 72 72 6F

0137 72 0D 0A  
20 32 30 33 2D 4D ADERR DB ' 203-Memory Address E  
65 6D 6F 72 79 20  
41 64 64 72 65 73  
73 69 65 72 72 65

72 0D 72 6F 52 0D 52 4F 20 45 72 F3A DB 'ROM Error',13,10 ; ROM CHECKSUM  
72 6F 72 0D 72 F3B DB 'KB OK!',13 ; KB FOR MEMORY SIZE

0164 00 D1 DB 'PARITY CHECK 2',13,10  
 50 41 52 49 54 59  
 20 43 58 42 43 4B  
 32 00 50 43 58 59  
 0174 00 D2 DB 'PARITY CHECK 1',13,10  
 50 43 60 00 4F 50

0174 0A 43 48 45 43 4B D2 DB PARITY CHECK 1,13,10  
20 43 48 45 43 4B  
20 31 0D 0A  
0184 3F 3F 3F 3F 0D D2A DB '?????',13,10  
0A

018B 20 28 52 45 53 55 F3D DB '(RESUME = "F1" KEY)', 13, 10  
45 20 20 22 48 45  
59 29 20 04  
01A1 20 29 20 20 20 55 F3D1 DB '-Unlock System Unit Keylock', 13, 10

```

    20 60 60 60 55      1501      00      -ONTRACK SYSTEM ON
    6E 6C 6F 63 20
    53 79 73 74 65 6D
    20 55 6E 69 74 20
    4B 65 79 6C 6F 63

```

01C2 6B 3D 3D 31 2D 4B F1 DB ' 301-Keyboard Error',13,10  
2B 3D 3D 31 2D 4B  
65 99 2D 6F 61 72  
64 20 45 72 72 6F  
72 DD 0A

01D7 20 33 30 32 2D 53      LOCK      DB      ' 302-System Unit Keylock is Locked',13,10 ; KEYBOARD LOCK ON  
79 73 74 65 6D 20  
55 6E 69 74 20 4B  
65 70 6C 6F 63 6B

01FB 20 69 73 20 40 61  
63 6B 20 40 AA  
20 69 30 33 20 4B F1\_A DB ' 303-Keyboard Or System Unit Error',13,10  
65 79 62 6F 61 72  
64 20 4E 72 20 53

79 73 74 65 60 20  
55 6E 69 74 20 45  
72 72 6F 72 0D 0A

021F 20 36 30 31 2D 44 F3 DB ' 601-Diskette Error',13,10 ; DISKETTE ERROR  
 69 73 6B 65 74 74  
 65 20 62 72 72 6F  
 72 00 0A  
 0234 20 31 36 31 2D 53 CM1 DB ' 161-System Options Not Set-(Run SETUP)',13,10 ; DEAD BATTERY  
 79 73 74 65 6D 20  
 4F 70 74 69 6F 6E  
 73 20 4E 6F 74 20  
 53 65 6D 20 53 52  
 75 6E 20 53 45 54  
 55 50 29 0D 0A  
 025D 20 31 36 32 2D 53 CM2 DB ' 162-System Options Not Set-(Run SETUP)',13,10  
 79 73 74 65 6D 20  
 4F 70 74 69 6F 6E  
 73 20 4E 6F 74 20  
 53 65 74 20 28 52  
 75 6E 20 53 45 54  
 55 50 29 0D 0A  
 0286 20 31 36 33 2D 54 CM3 DB ' 163-Time & Date Not Set-(Run SETUP)',13,10 ; CMOS CHECKSUM ERROR  
 69 6D 65 20 26 20  
 44 61 74 65 20 4E  
 67 74 20 53 55 74  
 20 28 50 75 GE 20  
 53 45 54 55 50 29  
 0D 0A ; CLOCK NOT UPDATING  
 -----  
 : PRINTER TABLE  
 F4 LABEL WORD  
 02AC 03BC DW 3BCH  
 02AE 0378 DW 37BH  
 02B0 0278 DW 27BH  
 02B2 F4E LABEL WORD  
 -----  
 :----- NMI ENTRY  
 02C3 ; ORG 0E2C3H  
 = 02C3 NM1\_INT ORG 002C3H  
 EQU S  
 02C3 E9 0000 E JMP NM1\_INT\_1  
 02C6 20 31 30 36 2D 53 CM4\_A DB ' 106-System Board Error',13,10 ; CONVERTING LOGIC TEST  
 79 73 74 65 6D 20  
 42 6F 61 72 64 20  
 45 72 72 6F 72 0D  
 0A  
 02DF 20 31 30 37 2D 53 CM4\_B DB ' 107-System Board Error',13,10 ; HOT NMI TEST  
 79 73 74 65 6D 20  
 42 6F 61 72 64 20  
 45 72 72 6F 72 0D  
 0A  
 02F8 20 31 30 38 2D 53 CM4\_C DB ' 108-System Board Error',13,10 ; TIMER BUS TEST  
 79 73 74 65 6D 20  
 42 6F 61 72 64 20  
 45 72 72 6F 72 0D  
 0A  
 0311 20 31 30 39 2D 53 CM4\_D DB ' 109-System Board Error',13,10 ; LOW MEG CHIP SELECT TEST  
 79 73 74 65 6D 20  
 42 6F 61 72 64 20  
 45 72 72 6F 72 0D  
 0A  
 -----  
 032A 20 31 36 34 2D 4D E1\_A MEMORY SIZE ERROR DB ' 164-Memory Size Error-(Run SETUP)',13,10  
 69 6D 65 20 39 20  
 53 69 7A 65 20 56  
 72 72 6F 72 2D 28  
 52 75 6E 20 53 45  
 54 55 50 29 0D 0A ; CMOS DOES NOT MATCH SYSTEM  
 -----  
 034E 20 33 30 34 2D 4B F1\_B KEYBOARD/SYSTEM ERROR DB ' 304-Keyboard Or System Unit Error',13,10  
 65 79 62 6F 61 72  
 64 20 4F 72 20 53  
 79 73 74 65 6D 20  
 55 6E 69 74 20 45  
 72 72 6F 72 0D 0A ; KEYBOARD CLOCK LINE HIGH  
 -----  
 0372 20 36 30 32 2D 44 BOOT\_INVA DB ' 602-Diskette Boot Record Error',13,10 ; DISKETTE BOOT RECORD IS NOT VALID  
 65 73 68 6D 65 74  
 65 20 42 6F 6F 74  
 20 52 65 63 6F 72  
 64 20 45 72 72 6F  
 72 0D 0A  
 -----  
 0393 31 37 38 30 2D 44 F1780 DB ' 1780-Disk 0 Failure',0DH,0AH  
 69 73 6B 60 20 30 20  
 46 61 69 6C 75 72  
 65 0D 0A  
 03A8 31 37 38 31 2D 44 F1781 DB ' 1781-Disk 1 Failure',0DH,0AH  
 69 73 6B 20 31 20  
 46 61 69 6C 75 72  
 65 0D 0A  
 03BD 31 37 38 32 2D 44 F1782 DB ' 1782-Disk Controller Failure',0DH,0AH  
 69 73 6B 60 20 30 20  
 61 74 62 6F 6C 6C  
 65 72 20 46 61 69  
 60 75 72 65 0D 0A  
 03DB 31 37 39 30 2D 44 F1790 DB ' 1790-Disk 0 Error',0DH,0AH  
 69 73 6B 20 30 20  
 61 72 6F 72 6F 72 0D  
 0A  
 03EE 31 37 39 31 2D 44 F1791 DB ' 1791-Disk 1 Error',0DH,0AH  
 69 73 6B 20 31 20  
 65 72 72 6F 72 0D 0A  
 -----  
 :-----  
 : INITIALIZE DRIVE CHARACTERISTICS  
 :-----  
 : FIXED DISK PARAMETER TABLE  
 :-----  
 : THE TABLE IS COMPOSED OF A BLOCK DEFINED AS:  
 :-----  
 :+0 (1 WORD) - MAXIMUM NUMBER OF CYLINDERS  
 :+2 (1 BYTE) - MAXIMUM NUMBER OF HEADS  
 :+3 (1 WORD) - NOT USED/SEE PC-XT  
 :+5 (1 WORD) - NOT USED/SEE PC-XT  
 :+7 (1 BYTE) - NOT USED/SEE PC-XT  
 :+8 (1 BYTE) - CONTROL BYTE  
 : BIT 7 DISABLE RETRIES -OR-  
 : BIT 6 DISABLE RETRIES

```

        ;-----+
        ;+9  (3 BYTES) - 3 MORE THAN 8 HEADS
        ;+12  (1 WORD) - LANDING ZONE
        ;+14  (1 BYTE) - NUMBER OF SECTORS/TRACK
        ;+15  (1 BYTE) - RESERVED FOR FUTURE USE
        ;-----+
        ; TO DYNAMICALLY DEFINE A SET OF PARAMETERS
        ; BUILD A TABLE FOR UP TO 15 TYPES AND PLACE
        ; THE CORRESPONDING VECTOR INTO INTERRUPT 41
        ; FOR DRIVE 0 AND INTERRUPT 46 FOR DRIVE 1.
        ;-----+
FD_TBL:
;----- DRIVE TYPE 01
0401 0132          DW    0306D          ; CYLINDERS
0403 04             DB    04D           ; HEADS
0404 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0406 0080          DW    0128D          ; LANDING ZONE
0408 00             DB    0             ; SECTORS/TRACK
0409 00             DB    0             ; CONTROL BYTE
040A 00 00 00       DB    0,0,0         ; CYLINDERS
040B 0131          DW    0305D          ; HEADS
040C 11             DB    17D           ; SECTORS/TRACK
0410 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 02
0411 0267          DW    0615D          ; CYLINDERS
0413 04             DB    04D           ; HEADS
0414 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0416 012C          DW    0300D          ; LANDING ZONE
0418 00             DB    0             ; SECTORS/TRACK
0419 00             DB    0             ; CONTROL BYTE
041A 00 00 00       DB    0,0,0         ; CYLINDERS
041B 0267          DW    0615D          ; HEADS
041C 11             DB    17D           ; SECTORS/TRACK
0420 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 03
0421 0267          DW    0615D          ; CYLINDERS
0423 06             DB    06D           ; HEADS
0424 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0426 012C          DW    0300D          ; LANDING ZONE
0428 00             DB    0             ; SECTORS/TRACK
0429 00             DB    0             ; CONTROL BYTE
042A 00 00 00       DB    0,0,0         ; CYLINDERS
042B 0267          DW    0615D          ; HEADS
042C 11             DB    17D           ; SECTORS/TRACK
0430 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 04
0431 03AC          DW    0940D          ; CYLINDERS
0433 00             DB    08D           ; HEADS
0434 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0436 0200          DW    0512D          ; LANDING ZONE
0438 00             DB    0             ; SECTORS/TRACK
0439 00             DB    0             ; CONTROL BYTE
043A 00 00 00       DB    0,0,0         ; CYLINDERS
043B 03AC          DW    0940D          ; HEADS
043C 11             DB    17D           ; SECTORS/TRACK
0440 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 05
0441 03AC          DW    0940D          ; CYLINDERS
0443 06             DB    06D           ; HEADS
0444 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0446 0200          DW    0512D          ; LANDING ZONE
0448 00             DB    0             ; SECTORS/TRACK
0449 00             DB    0             ; CONTROL BYTE
044A 00 00 00       DB    0,0,0         ; CYLINDERS
044B 03AC          DW    0940D          ; HEADS
044C 11             DB    17D           ; SECTORS/TRACK
0450 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 06
0451 0267          DW    0615D          ; CYLINDERS
0453 04             DB    04D           ; HEADS
0454 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0456 FFFF           DW    0FFFFH         ; LANDING ZONE
0458 00             DB    0             ; SECTORS/TRACK
0459 00             DB    0             ; CONTROL BYTE
045A 00 00 00       DB    0,0,0         ; CYLINDERS
045B 0267          DW    0615D          ; HEADS
045C 11             DB    17D           ; SECTORS/TRACK
0460 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 07
0461 01CE          DW    0462D          ; CYLINDERS
0463 08             DB    08D           ; HEADS
0464 0000          DW    0             ; WRITE PRE-COMPENSATION CYL
0466 0100          DW    0256D          ; LANDING ZONE
0468 00             DB    0             ; SECTORS/TRACK
0469 00             DB    0             ; CONTROL BYTE
046A 00 00 00       DB    0,0,0         ; CYLINDERS
046B 01FF          DW    0511D          ; HEADS
046C 11             DB    17D           ; SECTORS/TRACK
0470 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 08
0471 02DD          DW    0733D          ; CYLINDERS
0473 05             DB    05D           ; HEADS
0474 0000          DW    0             ; NO WRITE PRE-COMPENSATION
0476 FFFF           DW    0FFFFH         ; LANDING ZONE
0478 00             DB    0             ; SECTORS/TRACK
0479 00             DB    0             ; CONTROL BYTE
047A 00 00 00       DB    0,0,0         ; CYLINDERS
047B 02DD          DW    0733D          ; HEADS
047C 11             DB    17D           ; SECTORS/TRACK
0480 00             DB    0             ; LANDING ZONE
;----- DRIVE TYPE 09
0481 0384          DW    0900D          ; CYLINDERS
0483 0F             DB    15D           ; HEADS
0484 0000          DW    0             ; NO WRITE PRE-COMPENSATION
0486 FFFF           DW    0FFFFH         ; LANDING ZONE
0488 00             DB    0             ; SECTORS/TRACK

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0489 08 DB 008H ; CONTROL BYTE
048A 00 00 00 DB 0,0,0
048D 0385 DW 0901D ; LANDING ZONE
048F 11 DB 17D ; SECTORS/TRACK
0490 00 DB 0

;----- DRIVE TYPE 10
0491 0334 0354 DW 0820D ; CYLINDERS
0493 03 DB 03D ; HEADS
0494 0000 DW 0
0496 FFFF DW OFFFFF ; NO WRITE PRE-COMPENSATION
0498 00 DB 0
0499 00 DB 0,0,0 ; CONTROL BYTE
049A 00 00 00 DW 0820D ; LANDING ZONE
049D 0334 DW 17D ; SECTORS/TRACK
049F 11 DB 0
04A0 00 DB 0

;----- DRIVE TYPE 11
04A1 0357 039D DH 0855D ; CYLINDERS
04A3 05 DB 05D ; HEADS
04A4 0000 DW 0
04A6 FFFF DW OFFFFF ; NO WRITE PRE-COMPENSATION
04A8 00 DB 0
04A9 00 DB 0
04AA 00 00 00 DW 0,0,0 ; CONTROL BYTE
04AD 0357 DW 0855D ; LANDING ZONE
04AF 11 DB 17D ; SECTORS/TRACK
04B0 00 DB 0

;----- DRIVE TYPE 12
04B1 0357 039D DW 0855D ; CYLINDERS
04B3 07 DB 07D ; HEADS
04B4 0000 DW 0
04B6 FFFF DW OFFFFF ; NO WRITE PRE-COMPENSATION
04B8 00 DB 0
04B9 00 DB 0
04BA 00 00 00 DW 0,0,0 ; CONTROL BYTE
04BD 0357 DW 0855D ; LANDING ZONE
04BF 11 DB 17D ; SECTORS/TRACK
04C0 00 DB 0

;----- DRIVE TYPE 13
04C1 0132 0264 DW 0306D ; CYLINDERS
04C3 04 DB 08D ; HEADS
04C4 0000 DW 0
04C6 0080 DW 0128D ; WRITE PRE-COMPENSATION CYL
04C8 00 DB 0
04C9 00 DB 0
04CA 00 00 00 DW 0,0,0 ; CONTROL BYTE
04CD 013F DW 0319D ; LANDING ZONE
04CF 11 DB 17D ; SECTORS/TRACK
04D0 00 DB 0

;----- DRIVE TYPE 14
04D1 02DD 02F2 DW 0733D ; CYLINDERS
04D3 07 DB 07D ; HEADS
04D4 0000 DW 0
04D6 FFFF DW OFFFFF ; WRITE PRE-COMPENSATION CYL
04D8 00 DB 0
04D9 00 DB 0
04DA 00 00 00 DW 0,0,0 ; CONTROL BYTE
04DD 02DD DW 0733D ; LANDING ZONE
04DF 11 DB 17D ; SECTORS/TRACK
04E0 00 DB 0

;----- DRIVE TYPE 15 RESERVED **** DO NOT USE ****
04E1 0000 DW 0000D ; CYLINDERS
04E3 00 DB 000D ; HEADS
04E4 0000 DW 0
04E6 00000 DW 00000D ; WRITE PRE-COMPENSATION CYL
04E8 00 DW 0
04E9 00 DB 0
04EA 00 00 00 DW 0,0,0 ; CONTROL BYTE
04ED 0000 DW 00000D ; LANDING ZONE
04EF 00 DB 000D ; SECTORS/TRACK
04F0 00 DB 0

;----- BOOT LOADER INTERRUPT
; ORG 066F2H
; ORG 006F2H
BOOT_STRAP EQU $S
JMP BOOT_STRAP_1

;-----BAUD RATE INIT
; ORG 0E729H
; ORG 00729H
A1 LABEL WORD
0729 0017 DW 1047 ; 110 BAUD ; TABLE OF INIT VALUE
0729 0300 DW 768
0729 0180 DW 304 ; 300
072F 00C0 DW 192 ; 600
0731 0060 DW 96 ; 1200
0733 0030 DW 48 ; 2400
0735 0018 DW 24 ; 4800
0737 000C DW 12 ; 9600

;----- RS232
; ORG 0E739H
; ORG 00739H
RS232_IO EQU $S
JMP RS232_IO_1

;----- KEYBOARD
; ORG 0E82EH
; ORG 0082EH
KEYBOARD_IO EQU $S
JMP KEYBOARD_IO_1

;----- TABLE OF SHIFT KEYS AND MASK VALUES (EARLY PC)

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087E          K6      LABEL   BYTE
087F          DB      INS_KEY
087F          DB      CAPS_KEY,NUM_KEY,SCROLL_KEY,ALT_KEY,CTL_KEY
0884          DB      LEFT_KEY,RIGHT_KEY
0884          = 0008
0884          K6L     EQU    $-K6

;----- SHIFT_MASK_TABLE

0886          K7      LABEL   BYTE
0886          DB      INS_SHIFT
0887          DB      CAPS_SHIFT,NUM_SHIFT,SCROLL_SHIFT,ALT_SHIFT,CTL_SHIFT
088C          DB      LEFT_SHIFT,RIGHT_SHIFT
088C          = 01

;----- SCAN CODE TABLES

088E          K8      LABEL   BYTE
088E          DB      27,-1,0,-1,-1,-1,30,-1
0896          DB      -1,-1,-1,31,-1,127,-1,17
089E          DB      23,5,18,20,25,21,9,15
089E          FF 11
089E          09 0F
08A6          10 18 1D 0A FF 01
08AD          04 06 07 08 0A 0B
0886          OC FF FF
0886          FF F1 1C 1A 18 03
08BE          16 02
08BE          0E 0F FF FF FF FF
08C6          FF FP 20 FF
08C6          = 01

;----- CTL TABLE SCAN

08C8          K9      LABEL   BYTE
08C8          DB      94,95,96,97,98,99,100,101
08D0          DB      65 65 65 65 65 65
08D0          65 67 FF FF 77 FF
08D8          73 FF 74 FF 75 FF
08E0          FF

;----- LC TABLE

08E1          K10     LABEL  BYTE
08E1          DB      01BH,'1234567890=-',08H,09H
08E1          1B 31 32 33 34 35
08E1          36 37 38 39 30 2D
08E1          3D 08 09
08F0          70 67 65 72 74 79
08F0          75 69 68 70 58 5D
08F0          OD FF 61 73 64 66
08F0          67 68 6A 6B 6C 3B
08F0          27
0909          60 FF 5C 7A 78 63
0909          76 62 6E 6D 2C 2E
0909          2F FF 2A FF 20
091A          FF

;----- UC TABLE

091B          K11     LABEL  BYTE
091B          DB      27,'!@#$',37,05EH,'&(_)=',08H,0
091B          1B 21 40 23 24 25
091B          5E 26 24 28 29 5F
091B          2B 08 00
092A          51 57 45 52 54 59
092A          55 49 4F 50 7B 7D
092A          OD FF 41 53 44 46
092A          47 48 4A 4B 4C 3A
092A          22
0943          7E FF 7C 5A 58 43
0943          56 42 4E 4D 3C 3E
0943          3F FF 00 20 FF

;----- UC TABLE SCAN

0955          K12     LABEL  BYTE
0955          DB      84,85,86,87,88,89,90
0955          54 55 56 57 58 59
095C          5A SC 5C 5D
095C          = 095C

;----- ALT TABLE SCAN

095F          K13     LABEL  BYTE
095F          DB      91,92,93
095F          68 69 6A 6B 6C
0964          6D 6E 6F 70 71

;----- NUM STATE TABLE

0969          K14     LABEL  BYTE
0969          DB      '789-456+1230.'

;----- BASE CASE TABLE

0976          K15     LABEL  BYTE
0976          DB      71,72,73,-1,75,-1,77
097D          FF 4F 50 51 52 53
097D          = 097D

;----- KEYBOARD INTERRUPT

0987          ; ORG 0E987H
0987          KB_INT EQU $ 
0987          = 0987
0987          JMP KB_INT_1

;----- DISKETTE I/O

0C59          ; ORG 0EC59H
0C59          DISKETTE_IO EQU $ 
0C59          = 0C59
0C59          JMP DISKETTE_IO_1

;----- DISKETTE INTERRUPT

0F57          ; ORG 0EF57H
0F57          DISK_INT EQU $ 
0F57          = 0F57
0F57          JMP DISK_INT_1

;----- DISKETTE PARMs

0FC7          ; ORG 0EFC7H
0FC7          = 0FC7
0FC7          JMP DISKETTE_PARMs_1

;----- DISK BASE
; THIS IS THE SET OF PARAMETERS REQUIRED FOR
; DISKETTE OPERATION.  THEY ARE POINTED AT BY THE
; DATA VARIABLE DISK_POINTER.  TO MODIFY THE PARAMETERS,
; BUILD ANOTHER PARAMETER BLOCK AND POINT AT IT

;----- DISK_BASE

0FC7          DISK_BASE LABEL  BYTE
0FC7          DB      11011111B ; SRT=D, HD UNLOAD=OF = 1ST SPECIFY BYTE
0FC9          DB      2 ; HD LOAD=1, MODE=DMA = 2ND SPECIFY BYTE

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0FC9 25          DD   MOTOR_WAIT    ; WAIT AFTER OPEN TIL MOTOR OFF
0FC4 02          DB   2             ; 512 BYTES/SECTOR
0FCB 0F          DB   15            ; EOT ( LAST SECTOR ON TRACK )
0FC0 1B          DB   01BH           ; GAP LENGTH
0FC0 FF          DB   0FFH           ; DT
0FCF 24          DB   094H           ; GAP LENGTH FOR FORMAT
0FCF F6          DB   076H           ; FILL BYTE FOR FORMAT
0FD0 0F          DB   15             ; HEAD SETTLE TIME (MILLISECONDS)
0FD1 08          DB   8              ; MOTOR START TIME (1/8 SECONDS)

;----- PRINTER IO
;          ORG 0EFD2H
;          ORG 00FD2H
PRINTER_IO      EQU S
JMP  PRINTER_IO_1

;----- VIDEO IO
;----- ADDED FOR POSSIBLE COMPATABILITY ENTRY POINTS

1045             ;ORG 0FO45H
;ORG 01045H
ASSUME CS:CODE,DS:DATA,ES:VIDEO_RAM

EXTRN SET_MODE:NEAR
EXTRN SET_TYPE:NEAR
EXTRN SET_CURSOR:NEAR
EXTRN READ_CURSOR:NEAR
EXTRN READ_LPEN:NEAR
EXTRN ACT_DISP_PAGE:NEAR
EXTRN SCROLL_UP:NEAR
EXTRN SCROLL_DOWN:NEAR
EXTRN READ_AC_CURRENT:NEAR
EXTRN WRITE_AC_CURRENT:NEAR
EXTRN WRITE_C_CURRENT:NEAR
EXTRN SET_COLOR:NEAR
EXTRN READ_TTY:NEAR
EXTRN READ_DOT:NEAR
EXTRN WRITE_TTY:NEAR
EXTRN VIDEO_STATE:NEAR

1045      LABEL WORD ; TABLE OF ROUTINES WITHIN VIDEO I/O
1046      0000 E
1047      0000 E
1049      0000 EEE
104B      0000 E
104D      0000 EEE
104E      0000 E
1051      0000 E
1053      0000 E
1055      0000 E
1057      0000 E
1059      0000 E
105A      0000 E
105D      0000 E
105F      0000 E
1061      0000 E
1063      0000 E
= 0020     M1   LABEL WORD
           DW   OFFSET SET_MODE
           DW   OFFSET SET_CTYPE
           DW   OFFSET SET_CPOS
           DW   OFFSET READ_CURSOR
           DW   OFFSET READ_LPEN
           DW   OFFSET ACT_DISP_PAGE
           DW   OFFSET SCROLL_UP
           DW   OFFSET SCROLL_DOWN
           DW   OFFSET READ_AC_CURRENT
           DW   OFFSET WRITE_AC_CURRENT
           DW   OFFSET WRITE_C_CURRENT
           DW   OFFSET SET_COLOR
           DW   OFFSET WRITE_TTY
           DW   OFFSET READ_DOT
           DW   OFFSET VIDEO_STATE
M1L      EQU S-M1
           ;ORG 0F065H
           ;ORG 01065H
VIDEO_IO      EQU S
JMP  VIDEO_IO_1

;----- VIDEO PARMS
;          ORG 0FOA4H
;          ORG 010A4H
VIDEO_PARMS    LABEL BYTE

10A4      38 28 20 0A 1F 06 ;----- INIT_TABLE
10A5      19               DB   38H,28H,2DH,0AH,1FH,6,19H ; SET UP FOR 40X
10A8      1C 02 07 06 07   DB   1CH,2,7,6,7
10B0      00 00 00 00 00   DB   0,0,0,0
= 0010     M4   EQU S-VIDEO_PARMS
           DB   71H,50H,5AH,0AH,1FH,6,19H ; SET UP FOR 80X
10B8      19               DB   1CH,2,7,6,7
10C0      0C 02 07 06 07   DB   0,0,0,0
10C4      38 28 20 0A 7F 06 DB   38H,28H,2DH,0AH,7FH,6,64H ; SET UP FOR GRA
10CB      64               DB   70H,2,1,6,7
10D0      70 02 01 06 07   DB   0,0,0,0
10D4      61 50 52 0F 19 06 DB   61H,50H,52H,0FH,19H,6,19H ; SET UP FOR 80X
10D5      19               DB   19H,2,0DH,0BH,0CH
10E0      00 00 00 00 00   DB   0,0,0,0
10E4      LABEL WORD ; TABLE OF REGEN LENGTHS
10E4      0800             DW   2048           ; 40X25
10E6      1000             DW   4096           ; 80X25
10E8      4000             DW   16384          ; GRAPHICS
10EA      4000             DW   16384          ;
10EC      LABEL BYTE ;----- COLUMNS
10EC      28 28 50 50 28 28 DB   40,40,80,80,40,40,80,80
50 50
10F4      LABEL BYTE ;----- C_REG_TAB
10F4      2C 28 2D 29 2A 2E DB   2CH,28H,2DH,29H,2AH,2EH,1EH,29H ; TABLE OF MODE SETS
1E 29
1841      LABEL WORD ;----- MEMORY SIZE
1841      = 1841           DW   0FB841H
MEMORY_SIZE_DETERMINE EQU S
JMP  MEMORY_SIZE_DETERMINE_1

;----- EQUIPMENT DETERMINE

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; ORG 0F84DH
; ORG 0184DH
; EQU $ 
; JMP EQUIPMENT_1
;----- CASSETTE (NO BIOS SUPPORT) -----
; ORG 0F859H
; ORG 01859H
; EQU $ 
; JMP CASSETTE_IO_1
;----- CHARACTER GENERATOR GRAPHICS FOR 320X200 AND 640X200 GRAPHICS -----
;----- CRT_CHAR_GEN -----
; ORG 01A4CH
; LABEL BYTE
; DB 000H,000H,000H,000H,000H,000H,000H ; D_00
; DB 07EH,081H,0A5H,081H,0BDH,099H,081H,07EH ; D_01
; DB 07EH,0FFH,0DBH,0FFH,0C3H,0E7H,0FFH,07EH ; D_02
; DB 06CH,0FEH,0FEH,0FEH,07CH,038H,010H,000H ; D_03
; DB 010H,038H,07CH,0FEH,07CH,038H,010H,000H ; D_04
; DB 038H,07CH,038H,0FEH,0FEH,07CH,038H,07CH ; D_05
; DB 010H,010H,038H,07CH,0FEH,07CH,038H,07CH ; D_06
; DB 000H,000H,018H,03CH,03CH,018H,000H,000H ; D_07
; DB 0FFH,0FFH,0E7H,0C3H,0C3H,0E7H,0FFH,0FFH ; D_08
; DB 000H,03CH,066H,042H,042H,066H,03CH,000H ; D_09
; DB 0FFH,0C3H,099H,0BDH,0BDH,099H,0C3H,0FFH ; D_0A
; DB 00FH,007H,00FH,07DH,0CCH,0CCH,0CCH,078H ; D_0B
; DB 03CH,066H,066H,066H,03CH,018H,07EH,018H ; D_0C
; DB 03FH,033H,03FH,030H,030H,070H,0F0H,0E0H ; D_0D
; DB 07FH,063H,07FH,063H,063H,067H,0E6H,0C0H ; D_0E
; DB 099H,05AH,03CH,0E7H,0E7H,03CH,05AH,099H ; D_0F
;----- A1AE -----
; DB 080H,0E0H,0F8H,0FEH,0F8H,0E0H,0E0H,000H ; D_10
; DB 002H,00EH,03EH,0FEH,03EH,0OEH,002H,000H ; D_11
; DB 018H,03CH,07EH,018H,018H,07EH,03CH,018H ; D_12
; DB 066H,066H,066H,066H,066H,066H,000H,066H,000H ; D_13
; DB 07FH,0DBH,0DBH,07BH,018H,01BH,01BH,000H ; D_14
; DB 03EH,063H,038H,06CH,06CH,038H,0CCH,078H ; D_15
; DB 000H,000H,000H,000H,000H,000H,000H,000H ; D_16
; DB 018H,03CH,07EH,018H,018H,07EH,03CH,018H,0FFH ; D_17
; DB 018H,03CH,07EH,018H,018H,018H,018H,000H ; D_18
; DB 018H,018H,018H,018H,018H,07EH,03CH,018H,000H ; D_19
; DB 000H,018H,0C0H,0FEH,0OCH,018H,000H,000H ; D_1A
; DB 000H,030H,060H,060H,060H,060H,030H,000H,000H ; D_1B
; DB 000H,000H,0C0H,0C0H,0C0H,0C0H,000H,000H ; D_1C
; DB 000H,024H,066H,0FFH,066H,024H,000H,000H ; D_1D
; DB 000H,018H,03CH,07EH,0FFH,0FFH,000H,000H ; D_1E
; DB 000H,0FFH,0FFH,07EH,03CH,018H,000H,000H ; D_1F
;----- B1E6 -----
; DB 000H,000H,000H,000H,000H,000H,000H,000H ; SP D_20
; DB 030H,078H,078H,030H,030H,000H,030H,000H ; ! D_21
; DB 06CH,06CH,06CH,06CH,06CH,06CH,000H,000H ; " D_22
; DB 06CH,06CH,0FEH,06CH,0FEH,06CH,06CH,000H ; # D_23
; DB 030H,07CH,0C0H,078H,0OCH,0F8H,030H,000H ; $ D_24
; DB 000H,0C6H,0CCH,018H,030H,066H,0C6H,000H ; PER CENT D_25
; DB 038H,06CH,038H,076H,0OCH,0CCH,076H,000H ; & D_26
; DB 060H,060H,0C0H,000H,000H,000H,000H,000H ; ' D_27
; DB 018H,030H,060H,060H,060H,030H,018H,000H ; ( D_28
; DB 060H,030H,018H,018H,018H,030H,060H,000H,000H ; ) D_29
; DB 000H,066H,03CH,0FFH,03CH,066H,000H,000H ; * D_2A
; DB 000H,030H,030H,0FCH,030H,030H,000H,000H ; + D_2B
; DB 000H,000H,000H,000H,000H,030H,030H,060H ; , D_2C
; DB 000H,000H,000H,000H,000H,000H,030H,000H ; - D_2D
; DB 000H,000H,000H,000H,000H,030H,030H,000H ; . D_2E
; DB 006H,0OCH,018H,030H,060H,0C0H,080H,000H ; / D_2F
;----- 1BEE -----
; DB 07CH,0C6H,0CEH,0DEH,0F6H,0E6H,07CH,000H ; 0 D_30
; DB 030H,070H,030H,030H,030H,030H,0FCH,000H ; 1 D_31
; DB 078H,0CCH,00CH,038H,060H,0CCH,0FCH,000H ; 2 D_32
; DB 078H,0CCH,00CH,038H,00CH,0CCH,078H,000H ; 3 D_33

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1C0E	1C 3C 6C CC FE OC	DB	01CH,03CH,06CH,0CCH,0FEH,00CH,01EH,000H ; 4 D_34
1C16	FC 00 F8 0C OC CC	DB	0FCH,0COH,0F8H,00CH,0OCH,0CCH,078H,000H ; 5 D_35
1C1E	38 60 CO F8 CC CC	DB	038H,060H,0COH,0F8H,0CCH,0CCH,078H,000H ; 6 D_36
1C26	FC CC 0C 18 30 30	DB	0FCH,0CCH,0COH,018H,030H,030H,030H,000H ; 7 D_37
1C2E	78 CO CC 78 CC CC	DB	078H,0CCH,0CCH,078H,0CCH,0CCH,078H,000H ; 8 D_38
1C36	78 CO CC 7C OC 18	DB	078H,0CCH,0CCH,07CH,00CH,018H,070H,000H ; 9 D_39
1C3E	00 30 30 00 00 30	DB	000H,030H,030H,000H,000H,030H,030H,000H ; 1 D_3A
1C46	00 30 30 00 00 30	DB	000H,030H,030H,000H,000H,030H,030H,060H ; 2 D_3B
1C4E	18 30 60 CO 60 30	DB	018H,030H,060H,0COH,060H,030H,018H,000H ; < D_3C
1C56	00 00 FC 00 00 FC	DB	000H,000H,0FCH,000H,000H,0FCH,000H,000H ; = D_3D
1C5E	60 30 18 OC 18 30	DB	060H,030H,018H,0OCH,018H,030H,060H,000H ; > D_3E
1C66	78 CO CC 18 30 00	DB	078H,0CCH,0OCH,018H,030H,000H,030H,000H ; ? D_3F
1C6E	7C C6 DE DE DE CO	DB	07CH,0C6H,0DEH,0DEH,0DEH,0COH,078H,000H ; @ D_40
1C76	78 08 CC CC FC CC	DB	030H,078H,0CCH,0CCH,0FCH,0CCH,0CCH,000H ; A D_41
1C7E	FC 66 66 7C 66 66	DB	0FCH,066H,066H,07CH,066H,066H,0FCH,000H ; B D_42
1C86	3C 66 CO CO CO 66	DB	03CH,066H,0COH,0COH,0COH,066H,03CH,000H ; C D_43
1C8E	3C 66 66 66 66 6C	DB	0F8H,06CH,066H,066H,066H,06CH,0F8H,000H ; D D_44
1C96	FE 62 68 78 68 62	DB	0FEH,062H,068H,078H,068H,062H,0FEH,000H ; E D_45
1C9E	FE 62 68 78 68 60	DB	0FEH,062H,068H,078H,068H,060H,0FOH,000H ; F D_46
1CA6	3C 66 CO CO CE 66	DB	03CH,066H,0COH,0COH,0COH,0CEH,066H,03EH,000H ; G D_47
1CAE	CC CC CC FC CC CC	DB	0CCH,0CCH,0CCH,0FCH,0CCH,0CCH,0CCH,000H ; H D_48
1CB6	78 30 30 30 30 30	DB	078H,030H,030H,030H,030H,030H,078H,000H ; I D_49
1CBE	1E 0C 0C OC CC CC	DB	01EH,00CH,00CH,00CH,0CCH,0CCH,078H,000H ; J D_4A
1CCE	E6 60 6C 78 6C 66	DB	0E6H,066H,06CH,078H,06CH,066H,0E6H,000H ; K D_4B
1CCE	E6 60 60 62 66	DB	0FOH,060H,060H,060H,062H,066H,0FEH,000H ; L D_4C
1CD6	C6 EE FE FE D6 C6	DB	0C6H,0EEH,0FEH,0FEH,0DGH,0C6H,0C6H,000H ; M D_4D
1CDE	C6 E6 F6 DE CE C6	DB	0C6H,0E6H,0F6H,0DEH,0CEH,0C6H,0C6H,000H ; N D_4E
1CE6	38 6C 6C C6 C6 6C	DB	038H,06CH,0C6H,0C6H,0C6H,06CH,038H,000H ; O D_4F
1CEE	FC 66 66 7C 60 60	DB	0FCH,066H,066H,07CH,060H,060H,0FOH,000H ; P D_50
1CF6	FO 00 CC CC DC 78	DB	078H,0CCH,0CCH,0CCH,0DCH,078H,01CH,000H ; Q D_51
1CF6	FC 66 66 7C 6C 66	DB	0FCH,066H,066H,07CH,06CH,066H,0E6H,000H ; R D_52
1D06	78 CC EO 70 1C CC	DB	078H,0CCH,0EOH,070H,01CH,0CCH,078H,000H ; S D_53
1D0E	5F 80 30 30 30 30	DB	0FCH,0B4H,030H,030H,030H,030H,078H,000H ; T D_54
1D16	CC CC CC CC CC CC	DB	0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,000H ; U D_55
1D1E	FC 00 CC CC CC 78	DB	0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,078H,030H,000H ; V D_56
1D26	6C 66 D6 FE EE	DB	0C6H,0C6H,0C6H,0D6H,0FEH,0EEH,0C6H,000H ; W D_57
1D2E	C6 C6 6C 38 38 6C	DB	0C6H,0C6H,0C6H,038H,038H,06CH,0C6H,000H ; X D_58
1D36	CC CC CC 78 30 30	DB	0CCH,0CCH,0CCH,078H,030H,030H,078H,000H ; Y D_59
1D3E	1E 66 8C 18 32 66	DB	0FEH,0C6H,08CH,018H,032H,066H,0FEH,000H ; Z D_5A
1D46	78 60 60 60 60 60	DB	078H,060H,060H,060H,060H,060H,078H,000H ; [ D_5B
1D4E	60 60 30 18 OC 06	DB	0COH,060H,030H,018H,0OCH,000H,006H,002H,000H ; BACKSLASH D_5C
1D56	78 18 18 18 18 18	DB	078H,018H,018H,018H,018H,018H,078H,000H ; ] D_5D
1D5E	10 30 6C 00 00 00	DB	01OH,038H,06CH,0C6H,000H,000H,000H,000H,000H ; CIRCUMFLEX D_5E
1D66	00 00 00 00 00 00	DB	000H,000H,000H,000H,000H,000H,000H,0FFH ; _ D_5F
1D6E	30 30 18 00 00 00	DB	030H,030H,018H,000H,000H,000H,000H,000H,000H ; ` D_60
1D76	00 00 78 0C 7C CC	DB	000H,000H,078H,0OCH,07CH,0CCH,076H,000H ; LOWER CASE A D_61
1D7E	E0 60 60 7C 66 66	DB	0EOH,060H,060H,07CH,066H,066H,0DCH,000H ; L.C. B D_62
1D86	00 00 78 CC CO CC	DB	000H,000H,078H,0CCH,0COH,0CCH,078H,000H ; L.C. C D_63
1D8E	78 00 00 0C 7C CC CC	DB	01CH,0OCH,00CH,07CH,0CCH,0CCH,076H,000H ; L.C. D D_64
1D96	00 00 78 CC FC CO	DB	000H,000H,078H,0CCH,0FCH,0COH,078H,000H ; L.C. E D_65
1D9E	38 6C 60 F0 60 60	DB	038H,06CH,060H,0FOH,060H,060H,0FOH,000H ; L.C. F D_66
1DA6	00 00 76 CC CC 7C	DB	000H,000H,076H,0CCH,0CCH,07CH,0OCH,0F8H ; L.C. G D_67
1DAE	E0 60 6C 76 66 66	DB	0EOH,060H,06CH,076H,066H,066H,0E6H,000H ; L.C. H D_68
1DB6	30 00 70 30 30 30	DB	030H,000H,070H,030H,030H,030H,078H,000H ; L.C. I D_69
1DBE	OC 00 00 OC 0C CC	DB	0OCH,000H,0OCH,0OCH,0OCH,0CCH,0CCH,078H ; L.C. J D_6A
1DC6	CC 78 60 66 6C 78 6C	DB	0EOH,060H,066H,06CH,078H,06CH,0E6H,000H ; L.C. K D_6B
1DCE	78 00 00 30 30 30	DB	070H,030H,030H,030H,030H,030H,078H,000H ; L.C. L D_6C
1DD6	00 00 CC FE FE D6	DB	000H,000H,0CCH,0FEH,0FEH,0OFEH,066H,0C6H,000H ; L.C. M D_6D
1DDE	00 00 F8 CC CC CC	DB	000H,000H,0F8H,0CCH,0CCH,0CCH,0CCH,000H ; L.C. N D_6E
1DE6	00 00 78 CC CC CC	DB	000H,000H,078H,0CCH,0CCH,0CCH,0CCH,078H,000H ; L.C. O D_6F
1DEE	00 00 DC 66 66 7C	DB	000H,000H,0OCH,066H,066H,07CH,060H,0FOH ; L.C. P D_70

```

1DF6 00 00 76 CC CC 7C DB 000H,000H,076H,0CCH,0CCH,07CH,00CH,01EH ; L.C. Q D_71
0C 1E
1DFE 00 00 DC 76 66 60 DB 000H,000H,0DCH,076H,066H,060H,0F0H,00H ; L.C. R D_72
FO 00
1E06 00 00 7C CO 78 0C DB 000H,000H,07CH,0COH,078H,00CH,0F8H,00H ; L.C. S D_73
FO 00
1E0E 10 00 7C 30 30 34 DB 010H,030H,07CH,030H,030H,034H,018H,00H ; L.C. T D_74
18 00
1E16 00 00 CC CC CC 7C DB 000H,000H,0CCH,0CCH,0CCH,0CCH,076H,00H ; L.C. U D_75
76 00
1E1E 00 00 CC CC CC 78 DB 000H,000H,0CCH,0CCH,0CCH,0CCH,078H,030H,00H ; L.C. V D_76
30 00
1E26 00 00 C6 D6 FE FE DB 000H,000H,0C6H,0D6H,0FEH,0FEH,06CH,00H ; L.C. W D_77
6C 00
1E2E 00 00 C6 6C 38 6C DB 000H,000H,0C6H,06CH,038H,06CH,0C6H,00H ; L.C. X D_78
C6 00
1E36 00 00 CC CC CC 7C DB 000H,000H,0CCH,0CCH,0CCH,0CCH,07CH,00CH,0F8H ; L.C. Y D_79
0C 00
1E3E 00 00 FC 98 30 64 DB 000H,000H,0FCH,098H,030H,064H,0FCH,00H ; L.C. Z D_7A
FC 00
1E46 1C 30 30 E0 30 30 DB 01CH,030H,030H,0E0H,030H,030H,01CH,00H ; I D_7B
1C 00
1E4E 18 18 18 00 18 18 DB 018H,018H,018H,000H,018H,018H,018H,00H ; I D_7C
1E56 EO 30 30 1C 30 30 DB 0E0H,030H,030H,01CH,030H,030H,0E0H,00H ; I D_7D
EO 00
1E5E 76 DC 00 00 00 00 DB 076H,0DCH,000H,000H,000H,000H,000H,00H ; O D_7E
00 00
1E66 00 10 38 6C C6 C6 DB 000H,010H,038H,06CH,0C6H,0C6H,0FEH,00H ; DELTA D_7F
FE 00

.LIST
;----- TIME OF DAY
;
; ORG 0FE6EH
; ORG 01E6EH
TIME_OF_DAY EQU $ JMP TIME_OF_DAY_1

;----- TIMER INTERRUPT
;
; ORG 0F0E5H
; ORG 01E5AH
TIMER_INT EQU $ JMP TIMER_INT_1

;----- VECTOR TABLE
;
; ORG 0FFEF3H
; ORG 01EF3H
VECTOR_TABLE LABEL WORD

1EF3 1E45 R DW OFFSET TIMER_INT ; VECTOR TABLE
1EF5 0987 R DW OFFSET KB_INT ; INTERRUPT 8
1EF7 0000 E DW OFFSET D11 ; INTERRUPT 9
1EF9 0000 E DW OFFSET D11 ; INTERRUPT A (SLAVE INPUT)
1EFB 0000 E DW OFFSET D11 ; INTERRUPT B
1EFD 0000 E DW OFFSET D11 ; INTERRUPT C
1EFF 05F7 R DW OFFSET DISK_INT ; INTERRUPT D
1F01 0000 E DW OFFSET D11 ; INTERRUPT E
1F03 0000 E DW OFFSET D11 ; INTERRUPT F

;----- SOFTWARE INTERRUPTS
;
; INT 10H
1F05 1840 R DW OFFSET VIDEO_IO
1F07 1841 R DW OFFSET EQUIPMENT
1F09 0C59 R DW OFFSET MEMORY_SIZE_DETERMINE ; INT 11H
1F0B 0739 R DW OFFSET DISKETTE_IO ; INT 12H
1F0D 1859 R DW OFFSET RS232_IO ; INT 13H
1F0F 002E R DW CALLINT_10 ; INT 14H
1F11 002E R DW OFFSET KEYBOARD_IO ; INT 15H
1F13 0000 E DW OFFSET PRINTER_TO ; INT 16H
1F15 06F2 R DW 000000 ; INT 17H
1F17 1ECE R DW OFFSET BOOT_STRAP ; MUST BE INSERTED INTO TABLE LATER
1F19 1E53 R DW TIME_OF_DAY ; INT 18H
1F1B 1F53 R DW DUMMY_RETURN ; INT 19H -- TIME OF DAY
1F1D 10AH R DW DUMMY_RETURN ; INT 19H -- KEYBOARD BREAK ADDR
1F1F 0FC7 R DW VIDEO_PARMS ; INT 1CH -- TIMER BREAK ADDR
1F21 0000 E DW OFFSET DISK_BASE ; INT 1DH -- VIDEO PARAMETERS
1F23 0000 E DW 0 ; INT 1EH -- DISK PARMs
1F25 0000 E DW 0 ; INT 1FH -- POINTER TO VIDEO EXT

1F23 SLAVE_VECTOR_TABLE LABEL WORD ;( INTERRUPT 70 THRU 7F)

1F25 0000 E DW OFFSET RTC_INT ; INT 70 REAL TIME CLOCK INTERRUPT VECTOR
1F27 0000 E DW OFFSET RE_DIRECT ; INT 71 REDIRECT THIS TO INT A
1F29 0000 E DW OFFSET D11 ; INT 72
1F2B 0000 E DW OFFSET D11 ; INT 73
1F2D 0000 E DW OFFSET INT_287 ; INT 74
1F2F 0000 E DW OFFSET D11 ; INT 75 MATH PROCESSOR INTERRUPT
1F31 0000 E DW OFFSET D11 ; INT 76
1F33 0000 E DW OFFSET D11 ; INT 77

;----- DUMMY INTERRUPT HANDLER
;
; ORG 0FF53H
; ORG 01F53H
DUMMY_RETURN EQU $ IRET ; ;( INTERRUPT 78 THRU 7F)

1F53 CF IRET ; ;( INTERRUPT 78 THRU 7F)

;----- PRINT SCREEN
;
; ORG 0FF54H
; ORG 01F54H
PRINT_SCREEN EQU $ JMP PRINT_SCREEN_1

1F54 = 1F54
1F54 E9 0000 E .LIST ; TUTOR

```

```
-----  
POWER ON RESET VECTOR  
-----  
;  
1FF0           ORG      0FFFFH  
               ORG      01FFOH  
PUBLIC  P_O_R  
;----- POWER ON RESET  
P_O_R     LABEL FAR  
1FF0   EA  
1FF1   005B R  
1FF3   F000  
1FF5   30 31 2F 31 30 2F  
       38 34  
1FFE   FC  
1FFF   FC  
               DB      0EAH    ;HARD CODE JUMP  
               DW      OFFSET  RESET  ;OFFSET  
               DW      0F000H  ;SEGMENT  
               DB      '01/10/84' ;RELEASE MARKER  
               ORG      01FFEH  
               DB      0FC0H  ;THIS PC'S ID  
CODE    ENDS  
END
```

**5-176 ORGS**

# SECTION 6. INSTRUCTION SET

## Contents

<b>Instruction Sets .....</b>	<b>6-3</b>
<b>80286 Microprocessor Instruction Set .....</b>	<b>6-3</b>
Data Transfer .....	6-3
Arithmetic .....	6-6
Logic .....	6-10
String Manipulation .....	6-12
Control Transfer .....	6-13
Processor Control .....	6-19
Protection Control .....	6-21
<b>80287 Coprocessor Instruction Set .....</b>	<b>6-24</b>
Data Transfer .....	6-24
Comparison .....	6-25
Constants .....	6-26
Arithmetic .....	6-27
Transcendental .....	6-29
Processor Control .....	6-29

# **Notes:**

# Instruction Set

## 80286 Microprocessor Instruction Set

The following is an instruction set summary for the Intel 80286 microprocessor.

### Data Transfer

**MOV = move**

#### Register to Register/Memory

1000100w	mod reg r/w
----------	-------------

#### Register/Memory to Register

1000101w	mod reg r/w
----------	-------------

#### Immediate to Register/Memory

1100011w	mod 000 r/w	data	data if w = 1
----------	-------------	------	---------------

#### Immediate to Register

1011wreg	data	data if w = 1
----------	------	---------------

#### Memory to Accumulator

1010000w	addr-low	addr-high
----------	----------	-----------

#### Accumulator to Memory

1010001w	addr-low	addr-high
----------	----------	-----------

#### Register/Memory to Segment Register

10001110	mod0reg r/w
----------	-------------

**Segment Register to Register Memory**

10001100	mod0reg r/w
----------	-------------

**PUSH = Push****Memory**

11111111	mod110 r/w
----------	------------

**Register**

01010reg
----------

**Segment Register**

000reg110
-----------

**Immediate**

011010s0	data	data if s = 0
----------	------	---------------

**PUSHA = Push All****Push All**

01100000
----------

**POP = Pop****Memory**

10001111	mod000 r/m
----------	------------

**Register**

01011reg
----------

**Segment Register**

000reg111	reg ≠ 0
-----------	---------

**POPA = Pop All****Pop All**

01100001
----------

## XCHG = Exchange

Register Memory with Register

1000011w	mod reg r/m
----------	-------------

Register with Accumulator

10010reg
----------

## IN = Input From

Fixed Port

1110010w	port
----------	------

Variable Port

1110110w
----------

## OUT = Output To

Fixed Port

1110011w	port
----------	------

Variable Port

1110111w
----------

## XLAT = Translate Byte to AL

Translate Byte to AL

11010111
----------

## LEA = Load EA to Register

Load EA to Register

10001101	mod reg r/m
----------	-------------

## LDS = Load Pointer to DS

Load Pointer to DS

11000101	mod reg r/m	mod ≠ 11
----------	-------------	----------

## **LES = Load Pointer to ES**

**Load Pointer to ES**

11000100	mod reg r/m   mod ≠ 11
----------	------------------------

## **LAHF = Load AH with Flags**

**Load AH with Flags**

10011111
----------

## **SAHF = Load AH with Flags**

**Store AH with Flags**

10011110
----------

## **PUSHF = Push Flags**

**Push Flags**

10011100
----------

## **POPF = Pop Flags**

**Pop Flags**

10011101
----------

## **Arithmetic**

### **ADD = Add**

**Reg/Memory with Register to Either**

0000000w	mod reg r/m
----------	-------------

**Immediate to Register Memory**

100000sw	mod000 r/m	data	data if sw = 01
----------	------------	------	-----------------

**Immediate to Accumulator**

0000010w	data	data if w = 1
----------	------	---------------

### **ADC = Add with Carry**

**Reg/Memory with Register to Either**

000100dw	mod reg r/m
----------	-------------

**Immediate to Register Memory**

100000sw	mod000 r/m	data	data if sw = 01
----------	------------	------	-----------------

**Immediate to Accumulator**

0001010w	data	data if w = 1
----------	------	---------------

**INC = Increment****Register/Memory**

1111111w	mod000 r/m
----------	------------

**Register**

01000reg
----------

**SUB = Subtract****Reg/Memory with Register to Either**

001010dw	mod reg r/m
----------	-------------

**Immediate from Register Memory**

100000sw	mod101 r/m	data	data if sw = 01
----------	------------	------	-----------------

**Immediate from Accumulator**

0010110w	data	data if w = 1
----------	------	---------------

**SBB = Subtract with Borrow****Reg/Memory with Register to Either**

000110dw	mod reg r/m
----------	-------------

**Immediate to Register Memory**

100000sw	mod011 r/m	data	data if sw = 01
----------	------------	------	-----------------

**Immediate to Accumulator**

0001110w	data	data if w = 1
----------	------	---------------

**DEC = Decrement****Register/Memory**

1111111w	mod001 r/m
----------	------------

**Register**

01001reg
----------

**CMP = Compare****Register/Memory with Register**

0011101w	mod reg r/m
----------	-------------

**Register with Register/Memory**

0011100w	mod reg r/m
----------	-------------

**Immediate with Register/Memory**

100000sw	mod111 r/m	Data	Data if sw = 01
----------	------------	------	-----------------

**Immediate with Accumulator**

0001110w	Data	Data if w = 1
----------	------	---------------

**NEG = Change Sign****Change Sign**

1111011w	mod011 r/m
----------	------------

**AAA = ASCII Adjust for Add****ASCII Adjust for Add**

00110111
----------

**DEC = Decimal Adjust for Add****Decimal Adjust for Add**

00100111
----------

## AAS = ASCII Adjust for Subtract

ASCII Adjust for Subtract

00111111
----------

## DAS = Decimal Adjust for Subtract

Decimal Adjust for Subtract

00110111
----------

## MUL = Multiply (Unsigned)

Multiply

1111011w
----------

mod100 r/m
------------

## IMUL = Integer Multiply (Signed)

Integer Multiply

1111011w
----------

mod101 r/m
------------

## IIMUL = Integer Immediate Multiply (Signed)

Integer Immediate Multiply

011010s1
----------

mod reg r/m
-------------

Data
------

Data if s = 0
---------------

## DIV = Divide (Unsigned)

Divide

1111011w
----------

mod110 r/m
------------

## IDIV = Integer Divide (Signed)

Integer Divide

1111011w
----------

mod111 r/m
------------

## AAM = ASCII Adjust for Multiply

ASCII Adjust for Multiply

11010100
----------

00001010
----------

## AAD = ASCII Adjust for Divide

### **ASCII Adjust for Divide**

11010101	00001010
----------	----------

### **CBW = Convert Byte to Word**

#### **Convert Byte to Word**

10011000
----------

### **CWD = Convert Word to Double Word**

#### **Convert Word to Double Word**

10011001
----------

## **Logic**

### **Shift Rotate Instructions**

#### **Register Memory by 1**

1101000w	mod TTT r/m
----------	-------------

#### **Register Memory by CL**

1101001w	mod TTT r/m
----------	-------------

#### **Register Memory by Count**

1100000w	mod TTT r/m	Count
----------	-------------	-------

### **T T T Instruction**

- 000 ROL**
- 001 ROR**
- 010 RCL**
- 011 RCR**
- 100 SHL/SAL**
- 101 SHR**
- 111 SAR**

### **AND = And**

#### **Reg/Memory and Register to Either**

001000dw	mod reg r/m
----------	-------------

**Immediate to Register Memory**

1000000w	mod000 r/m	Data	Data if w = 1
----------	------------	------	---------------

**Immediate to Accumulator**

0010010w	Data	Data if w = 1
----------	------	---------------

**TEST = AND Function to Flags; No Result**

**Register Memory and Register**

1000010w	mod reg r/m
----------	-------------

**Immediate Data and Register Memory**

1111011w	mod000 r/m	Data	Data if w=1
----------	------------	------	-------------

**Immediate to Accumulator**

0000110w	Data	Data if w = 1
----------	------	---------------

**Or = Or**

**Reg/ Memory and Register to Either**

000010dw	mod reg r/m
----------	-------------

**Immediate to Register Memory**

1000000w	mod001 r/m	Data	Data if w = 1
----------	------------	------	---------------

**Immediate to Accumulator**

0000110w	Data	Data if w = 1
----------	------	---------------

**XOR = Exclusive OR**

**Reg/Memory and Register to Either**

001100dw	mod reg r/m
----------	-------------

**Immediate to Register Memory**

1000000w	mod110 r/m	Data	Data if w = 1
----------	------------	------	---------------

**Immediate to Accumulator**

0010010w	Data	Data if w = 1
----------	------	---------------

**NOT = Invert Register/Memory****Invert Register/Memory**

1111011w	mod010 r/m
----------	------------

## String Manipulation

**MOVS = Move Byte Word****Move Byte Word**

1010010w
----------

**CMPS = Compare Byte Word****Compare Byte Word**

1010011w
----------

**SCAS = Scan Byte Word****Scan Byte Word**

1010111w
----------

**LODS = Load Byte Word to AL/AX****Load Byte Word to AL/AX**

1010110w
----------

**STOS = Store Byte Word from AL/AX****Store Byte Word from AL/AX**

1010101w
----------

**INS = Input Byte from DX Port****Input Byte Word from DX Port**

0110110w
----------

**OUTS = Output Byte to DX Port**

**Output Byte Word to DX Port**

0110111w
----------

**MOVS = Move String**

**Move String**

11110010	1010010w
----------	----------

**CMPS = Compare String**

**Compare String**

1111001z	1010011w
----------	----------

**SCAS = Scan String**

**Scan String**

11110010	1010111w
----------	----------

**LODS = Load String**

**Load String**

11110010	1010110w
----------	----------

**STOS = Store String**

**Store String**

11110010	1010101w
----------	----------

**INS = Input String**

**Input String**

11110010	0110110w
----------	----------

**OUTS = Output String**

**Output String**

11110010	1010011w
----------	----------

**Control Transfer**

## **CALL = Call**

### **Direct Within Segment**

11101000	disp-low	disp-low
----------	----------	----------

### **Register/Memory Indirect Within Segment**

11111111	mod010 r/m
----------	------------

### **Direct Intersegment**

10011010	Segment Offset	Segment Selector
----------	----------------	------------------

## **Protected Mode Only (Direct Intersegment)**

- Via call gate to same privilege level
- Via call gate to different privilege level, no parameters
- Via call gate to different privilege level, x parameters
- Via TSS
- Via task gate.

### **Indirect Intersegment**

11111111	mod011 r/m (mod ≠ 11)
----------	-----------------------

## **Protected Mode Only (Indirect Intersegment)**

- Via call gate to same privilege level
- Via call gate to different privilege level, no parameters
- Via call gate to different privilege level, x parameters
- Via TSS
- Via task gate.

## **JMP = Unconditional Jump**

### **Short/Long**

11101011	disp-low
----------	----------

### **Direct within Segment**

11101001	disp=low	disp-high
----------	----------	-----------

### Register/Memory Indirect Within Segment

11111111	mod100 r/m
----------	------------

### Direct Intersegment

11101010	Segment Offset	Segment Selector
----------	----------------	------------------

### Protected Mode Only (Direct Intersegment)

- Via call gate to same privilege level
- Via TSS
- Via task gate.

### Indirect Intersegment

11111111	mod101 r/m (mod ≠ 11)
----------	-----------------------

### Protected Mode Only (Indirect Intersegment)

- Via call gate to same privilege level
- Via TSS
- Via task gate.

### RET = Return from Call

#### Within Segment

11000011
----------

#### Within Segment Adding Immediate to SP

11000010	data-low	data-high
----------	----------	-----------

#### Intersegment

11001011
----------

#### Intersegment Adding Immediate to SP

11001010	data-low	data-high
----------	----------	-----------

### Protected Mode Only (RET)

- To Different Privilege Level

**JE/JZ = Jump on Equal Zero**

Jump on Equal Zero

01110100	disp
----------	------

**JL/JNGE = Jump on Less Not Greater, or Equal**

Jump on Less Not Greater, or Equal

01111100	disp
----------	------

**JLE/JNG = Jump on Less, or Equal Not Greater**

Jump on Less, or Equal Not Greater

01111110	disp
----------	------

**JB/JNAE = Jump on Less, or Equal Not Greater**

Jump on Less, or Equal Not Greater

01110010	disp
----------	------

**JBE/JNA = Jump on Below, or Equal Not Above**

Jump on Below, or Equal Not Above

01110110	disp
----------	------

**JP/JPE = Jump on Parity Parity Even**

Jump on Parity Parity Even

01111010	disp
----------	------

**JO = Jump on Overflow**

Jump on Overflow

01110000	disp
----------	------

**JS = Jump on Sign**

Jump on Sign

01111000	disp
----------	------

**JNE/JNZ = Jump on Not Equal Not Zero**

**Jump on Not Equal Not Zero**

01110101	disp
----------	------

**JNL/JGE = Jump on Not Less Greater or Equal**

**Jump on Not Less Greater or Zero**

01111101	disp
----------	------

**JNLE/JG = Jump on Not Less or Equal Greater**

**Jump on Not Less or Equal Greater**

01111111	disp
----------	------

**JNB/JAE = Jump on Not Below Above or Equal**

**Jump on Not Below Above or Equal**

01110011	disp
----------	------

**JNBE/JA = Jump on Not Below or Equal Above**

**Jump on Not Below or Equal Above**

01110111	disp
----------	------

**JNP/JPO = Jump on Not Parity Parity Odd**

**Jump on Not Parity Parity Odd**

01111011	disp
----------	------

**JNO = Jump on Not Overflow**

**Jump on Not Overflow**

01110001	disp
----------	------

**JNS = Jump on Not Sign**

**Jump on Not Sign**

01111011	disp
----------	------

**LOOP = Loop CX Times**

**Loop CX Times**

11100010	disp
----------	------

**LOOPZ/LOOPE = Loop while Zero Equal**

**Loop while Zero Equal**

11100001	disp
----------	------

**LOOPNZ/LOOPNE = Loop while Not Equal Zero**

**Loop while Not Equal Zero**

11100000	disp
----------	------

**JCXZ = Jump on CX Zero**

**Jump on CX Zero**

11100011	disp
----------	------

**ENTER = Enter Procedure**

**Enter Procedure**

11001000	data-low	data-high	L
----------	----------	-----------	---

L=0

L=1

L>1

**LEAVE = Leave Procedure**

**Leave Procedure**

11001001
----------

**INT = Interrupt**

**Type Specified**

11001101	Type
----------	------

**Type 3**

11001100
----------

## **INTO = Interrupt on Overflow**

**Interrupt on Overflow**

11001110
----------

### **Protected Mode Only**

- Via interrupt or trap gate to same privilege level
- Via interrupt or trap gate to different privilege level
- Via task gate.

## **IRET = Interrupt Return**

**Interrupt Return**

11001111
----------

### **Protected Mode Only**

- To same privilege level
- To different task (NT = 1).

## **BOUND = Detect Value Out of Range**

**Detect Value Out of Range**

01100010
----------

mod reg r/m
-------------

## **Processor Control**

### **CLC = Clear Carry**

**Clear Carry**

1111100
---------

### **CMC = Complement Carry**

**Complement Carry**

11001111
----------

### **STC = Set Carry**

**Set Carry**

11111001
----------

**CLD = Clear Direction**

**Clear Direction**

11111100

**STD = Set Direction**

**Set Direction**

11111101

**CLI Clear Interrupt**

**Clear Interrupt**

11111010

**STI = Set Interrupt**

**Set Interrupt**

11111011

**HLT = Halt**

**Halt**

11110100

**WAIT = Wait**

**Wait**

10011011

**LOCK = Bus Lock Prefix**

**Bus Lock Prefix**

11110000

**CTS = Clear Task Switched Flag**

**Clear Task Switched Flag**

00001111

00000110

**ESC = Processor Extension Escape**

10011TTT

modLLL r/m

## Protection Control

**LGDT = Load Global Descriptor Table Register**

**Load Global Descriptor Table Register**

00001111

00000001

mod010 r/m

**SGDT = Store Global Descriptor Table Register**

**Store Global Descriptor Table Register**

00001111

00000001

mod000 r/m

**LIDT = Load Interrupt Descriptor Table Register**

**Load Interrupt Descriptor Table Register**

00001111

00000001

mod011 r/m

**SIDT = Store Interrupt Descriptor Table Register**

**Store Interrupt Descriptor Table Register**

00001111

00000001

mod001 r/m

**LLDT = Load Local Descriptor Table Register from Register Memory**

**Load Local Descriptor Table Register from Register Memory**

00001111

00000000

mod010 r/m

**SLDT = Store Local Descriptor Table Register from Register Memory**

**Store Local Descriptor Table Register from Register Memory**

00001111

00000000

mod000 r/m

**LTR = Load Task Register from Register Memory**

**Load Task Register from Register Memory**

00001111

00000000

mod011 r/m

**STR = Store Task Register to Register Memory****Store Task Register to Register Memory**

00001111	00000000	mod001 r/m
----------	----------	------------

**LMSW = Load Machine Status Word from Register Memory****Load Machine Status Word from Register Memory**

00001111	00000001	mod110 r/m
----------	----------	------------

**SMSW = Store Machine Status Word****Store Machine Status Word**

00001111	00000001	mod100 r/m
----------	----------	------------

**LAR = Load Access Rights from Register Memory****Load Access Rights from Register Memory**

00001111	00000010	mod reg r/m
----------	----------	-------------

**LSL = Load Segment Limit from Register Memory****Load Segment Limit from Register Memory**

00001111	00000011	mod reg r/m
----------	----------	-------------

**ARPL = Adjust Requested Privilege Level from Register Memory****Adjust Requested Privilege Level from Register Memory**

	01100011	mod reg r/m
--	----------	-------------

**VERR = Verify Read Access; Register Memory****Verify Read Access; Register Memory**

00001111	00000000	mod100 r/m
----------	----------	------------

**VERR = Verify Write Access****Verify Write Access**

00001111	00000000	mod101 r/m
----------	----------	------------

**Note:** The effective address (EA) of the memory operand is computed according to the mod and r/m fields:

If mod = 11, then r/m is treated as a reg field.

If mod = 00, then disp = 0, disp-low and disp-high are absent.

If mod = 01, then disp = disp-low sign-extended to 16 bits,  
disp-high is absent.

If mod = 10, then disp = disp-high:disp-low.

If r/m = 000, then EA = (BX) + (SI) + disp

If r/m = 001, then EA = (BX) + (SI) + disp

If r/m = 010, then EA = (BP) + (SI) + disp

If r/m = 011, then EA = (BP) + (DI) + disp

If r/m = 100, then EA = (SI) + disp

If r/m = 101, then EA = (DI) + disp

If r/m = 110, then EA = (BP) + disp

If r/m = 111, then EA = (BX) + disp

disp follows the second byte of the instruction (before data if required).

### Segment Override Prefix

#### Segment Override Prefix

001reg001

reg is assigned as follows:

#### reg Segment Register

00 ES

01 CS

10 SS

11 DS

16-bit (w = 1)	8-bit (w = 0)
000 AX	000 AL
001 CX	001 CL
010 DX	010 DL
011 BX	011 BL
100 SP	100 AH
101 BP	101 CH
110 SI	110 DH
111 DI	111 BH

The physical addresses of all operands addressed by the BP register are computed using the SS segment register. The physical addresses of the destination operands of the string primitive operations (those addressed by the DI register) are computed using the ES segment, which may not be overridden.

## 80287 Coprocessor Instruction Set

The following is an instruction set summary for the 80287 coprocessor.

### Data Transfer

#### FLD = Load

##### **Integer/Real Memory to ST(0)**

escape MF 1	mod 000 r/m
-------------	-------------

##### **Long Integer Memory to ST(0)**

escape 111	mod 101 r/m
------------	-------------

##### **Temporary Real Memory to ST(0)**

escape 011	mod 101 r/m
------------	-------------

##### **BCD Memory to ST(0)**

escape 111	mod 100 r/m
------------	-------------

##### **ST(i) to ST(0)**

escape 001	11000ST(i)
------------	------------

#### FST = Store

##### **ST(0) to Integer/Real Memory**

escape MF 1	mod 010 r/m
-------------	-------------

##### **ST(0) to ST(i)**

escape 101	11010 ST(i)
------------	-------------

## FSTP = Store and Pop

**ST(0) to Integer/Real Memory**

escape MF 1	mod 011 r/m
-------------	-------------

**ST(0) to Long Integer Memory**

escape 111	mod 111 r/m
------------	-------------

**ST(0) to Temporary Real Memory**

escape 011	mod 111 r/m
------------	-------------

**ST(0) to BCD Memory**

escape 111	mod 110 r/m
------------	-------------

**ST(0) to ST(i)**

escape 101	11011 ST(i)
------------	-------------

## FXCH = Exchange ST(i) and ST(0)

**Exchange ST(i) and ST(0)**

escape 001	11001 ST(i)
------------	-------------

## Comparison

### FCOM = Compare

**Integer/Real Memory to ST(0)**

escape MF 0	mod 010 r/m
-------------	-------------

**ST(i) to ST(0)**

escape 000	11010 ST(i)
------------	-------------

### FCOMP = Compare and Pop

**Integer/Real Memory to ST(0)**

escape MF 0	mod 011 r/m
-------------	-------------

**ST(i) to ST(0)**

escape 000	11010 ST(i)
------------	-------------

**FCOMPP = Compare ST(i) to ST(0) and Pop Twice**

**Compare ST(i) to ST(0) and pop twice**

escape 110	11011001
------------	----------

**FTST = Test ST(0)**

**Test ST(0)**

escape 001	11100100
------------	----------

**FXAM = Examine ST(0)**

**Examine ST(0)**

escape 001	11100101
------------	----------

## Constants

**FLDZ = Load + 0.0 into ST(0)**

**Load + 0.0 into ST(0)**

escape 000	11101110
------------	----------

**FLD1 = Load + 1.0 into ST(0)**

**Load + 1.0 into ST(0)**

escape 001	11101000
------------	----------

**FLDP1 = Load  $\pi$  into ST(0)  $\pi$  into ST(0)**

**Load**

escape 001	11101011
------------	----------

**FLDL2T = Load  $\log_2 10$  into ST(0)  $2^{10}$  into ST(0)**

**Load log**

escape 001	11101001
------------	----------

**FLDLG2 = Load  $\log_{10} 2$  into ST(0)**

Load log

escape 001	11101100
------------	----------

**FLDLN2 = Load  $\log_e 2$  into ST(0)**

Load log

escape 001	11101101
------------	----------

## Arithmetic

**FADD = Addition**

Integer/Real Memory with ST(0)

escape MF 0	mod 000 r/m
-------------	-------------

ST(i) and ST(0)

escape dPO	11000 ST(i)
------------	-------------

**FSUB = Subtraction**

Integer/Real Memory with ST(0)

escape MF 0	mod 10r r/m
-------------	-------------

ST(i) and ST(0)

escape dPO	1110r r/m
------------	-----------

**FMUL = Multiplication**

Integer/Real Memory with ST(0)

escape MF 0	mod 001 r/m
-------------	-------------

ST(i) and ST(0)

escape dPO	11001 r/m
------------	-----------

**FDIV = Division**

**Integer/Real Memory with ST(0)**

escape MF 0	mod 11r r/m
-------------	-------------

**ST(i) and ST(0)**

escape dP0	1111 r r/m
------------	------------

**FSQRT = Square Root of ST(0)****Square Root of ST(0)**

escape 001	11111010
------------	----------

**FSCALE = Scale ST(0) by ST(1)****Scale ST(0) by ST(1)**

escape 001	11111101
------------	----------

**FPREM = Partial Remainder of ST(0) + ST(1)****Partial Remainder of ST(0) + ST(1)**

escape 001	11111000
------------	----------

**FRNDINT = Round ST(0) to Integer****Round ST(0) to Integer**

escape 001	11111100
------------	----------

**FXTRACT = Extract Components of ST(0)****Extract Components of ST(0)**

escape 001	11110100
------------	----------

**FABS = Absolute Value of ST(0)****Absolute Value of ST(0)**

escape 001	11100001
------------	----------

**FCHS = Change Sign of ST(0)****Change Sign of ST(0)**

escape 001	11100000
------------	----------

# Transcendental

**FPTAN = Partial Tangent of ST(0)**

Partial Tangent of ST(0)

escape 001	11110010
------------	----------

**FPATAN = Partial Arctangent of ST(0) ÷ ST(1)**

Partial Arctangent of ST(0) ÷ ST(1)

escape 001	11110011
------------	----------

**F2XM1 =  $2^{\text{ST}(0)-1}$  ST(0)-1**

escape 001	11110000
------------	----------

**FYL2X = ST(1) x Log<sub>2</sub> [ST(0)]<sub>2</sub> [ST(0)]**

ST(1) x log

escape 001	11110001
------------	----------

**FYL2XP1 = ST(1) x Log<sub>2</sub> [ST(0) + 1]<sub>2</sub> [ST(0) + 1]**

ST(1) x log

escape 001	11111001
------------	----------

# Processor Control

**FINT = Initialize NPX**

Initialize NPX

escape 011	11100011
------------	----------

**FSETPM = Enter Protected Mode**

Enter Protected Mode

escape 011	11100100
------------	----------

## **FSTSWAX = Store Control Word**

### **Store Control Word**

escape 111	11100000
------------	----------

## **FLDCW = Load Control Word**

### **Load Control Word**

escape 001	mod 101 r/m
------------	-------------

## **FSTCW = Store Control Word**

### **Store Control Word**

escape 001	mod 111 r/m
------------	-------------

## **FSTSW = Store Status Word**

### **Store Status Word**

escape 101	mod 101 r/m
------------	-------------

## **FCLEX = Clear Exceptions**

### **Clear Exceptions**

escape 011	11100010
------------	----------

## **FSTENV = Store Environment**

### **Store Environment**

escape 001	mod 110 r/m
------------	-------------

## **FLDENV = Load Environment**

### **Load Environment**

escape 001	mod 100 r/m
------------	-------------

## **FSAVE = Save State**

### **Save State**

escape 101	mod 110 r/m
------------	-------------

## **FRSTOR = Restore State**

**Restore State**

escape 101	mod 100 r/m
------------	-------------

**FINCSTP = Increment Stack Pointer**

**Increment Stack Pointer**

escape 001	11110111
------------	----------

**FDECSTP = Decrement Stack Pointer**

**Decrement Stack Pointer**

escape 001	11110110
------------	----------

**FFREE = Free ST(i)**

**Free ST(i)**

escape 101	11000ST(i)
------------	------------

**FNOP = No Operation**

**No Operation**

escape 001	11010000
------------	----------

## **Notes:**

# SECTION 7. CHARACTERS, KEYSTROKES, AND COLORS

## Contents

Characters, Keystrokes, and Color .....	7-3
NOTES .....	7-13

## **Notes:**

# Characters, Keystrokes, and Color

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
00	0	Blank (Null)	Ctrl 2		Black	Black	Non-Display
01	1	☺	Ctrl A		Black	Blue	Underline
02	2	☻	Ctrl B		Black	Green	Normal
03	3	♥	Ctrl C		Black	Cyan	Normal
04	4	♦	Ctrl D		Black	Red	Normal
05	5	♣	Ctrl E		Black	Magenta	Normal
06	6	♠	Ctrl F		Black	Brown	Normal
07	7	●	Ctrl G		Black	Light Grey	Normal
08	8	•	Ctrl H, Backspace, Shift Backspace		Black	Dark Grey	Non-Display
09	9	○	Ctrl I		Black	Light Blue	High Intensity Underline
0A	10	○	Ctrl J, Ctrl ↵		Black	Light Green	High Intensity
0B	11	♂	Ctrl K		Black	Light Green	High Intensity
0C	12	♀	Ctrl L,		Black	Light Red	High Intensity
0D	13	♪	Ctrl M, ↵, Shift ↵		Black	Light Magenta	High Intensity
0E	14	♫	Ctrl N		Black	Yellow	High Intensity
0F	15	☼	Ctrl O		Black	White	High Intensity
10	16	►	Ctrl P		Blue	Black	Normal
11	17	◀	Ctrl Q		Blue	Blue	Underline
12	18	↕	Ctrl R		Blue	Green	Normal
13	19	!!	Ctrl S		Blue	Cyan	Normal
14	20	¶	Ctrl T		Blue	Red	Normal
15	21	§.	Ctrl U			Magenta	Normal
16	22	▬	Ctrl V		Blue	Brown	Normal
17	23	▬	Ctrl W		Blue	Light Grey	Normal

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
18	24	↑	Ctrl X		Blue	Dark Grey	High Intensity
19	25	↓	Ctrl Y		Blue	Light Blue	High Intensity Underline
1A	26	→	Ctrl Z		Blue	Light Green	High Intensity
1B	27	←	Ctrl [, Esc, Shift Esc, Ctrl Esc		Blue	Light Cyan	High Intensity
1C	28	└─	Ctrl \		Blue	Light Red	High Intensity
1D	29	↔	Ctrl ]		Blue	Light Magenta	High Intensity
1E	30	▲	Ctrl 6		Blue	Yellow	High Intensity
1F	31	▼	Ctrl —		Blue	White	High Intensity
20	32	Blank Space	Space Bar, Shift, Space, Ctrl Space, Alt Space		Green	Black	Normal
21	33	!	!	Shift	Green	Blue	Underline
22	34	"	"	Shift	Green	Green	Normal
23	35	#	#	Shift	Green	Cyan	Normal
24	36	\$ `	\$	Shift	Green	Red	Normal
25	37	%	%	Shift	Green	Magenta	Normal
26	38	&	&	Shift	Green	Brown	Normal
27	39	'	'		Green	Light Grey	Normal
28	40	(	(	Shift	Green	Dark Grey	High Intensity
29	41	)	)	Shift	Green	Light Blue	High Intensity Underline
2A	42	*	*	Note 1	Green	Light Green	High Intensity
2B	43	+	+	Shift	Green	Light Cyan	High Intensity
2C	44	'	'		Green	Light Red	High Intensity
2D	45	—	—		Green	Light Magenta	High Intensity
2E	46	.	.	Note 2	Green	Yellow	High Intensity

## 7-4 Characters, Keystrokes, and Color

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
2F	47	/	/		Green	White	High Intensity
30	48	0	0	Note 3	Cyan	Black	Normal
31	49	1	1	Note 3	Cyan	Blue	Underline
32	50	2	2	Note 3	Cyan	Green	Normal
33	51	3	3	Note 3	Cyan	Cyan	Normal
34	52	4	4	Note 3	Cyan	Red	Normal
35	53	5	5	Note 3	Cyan	Magenta	Normal
36	54	6	6	Note 3	Cyan	Brown	Normal
37	55	7	7	Note 3	Cyan	Light Grey	Normal
38	56	8	8	Note 3	Cyan	Dark Grey	High Intensity
39	57	9	9	Note 3	Cyan	Light Blue	High Intensity Underline
3A	58	:	:	Shift	Cyan	Light Green	High Intensity
3B	59	;	;		Cyan	Light Cyan	High Intensity
3C	60	<	<	Shift	Cyan	Light Red	High Intensity
3D	61	=	=		Cyan	Light Magenta	High Intensity
3E	62	>	>	Shift	Cyan	Yellow	High Intensity
3F	63	?	?	Shift	Cyan	White	High Intensity
40	64	@	@	Shift	Red	Black	Normal
41	65	A	A	Note 4	Red	Blue	Underline
42	66	B	B	Note 4	Red	Green	Normal
43	67	C	C	Note 4	Red	Cyan	Normal
44	68	D	D	Note 4	Red	Red	Normal
45	69	E	E	Note 4	Red	Magenta	Normal
46	70	F	F	Note 4	Red	Brown	Normal
47	71	G	G	Note 4	Red	Light Grey	Normal
48	72	H	H	Note 4	Red	Dark Grey	High Intensity
49	73	I	I	Note 4	Red	Light Blue	High Intensity Underline
4A	74	J	J	Note 4	Red	Light Green	High Intensity

Value		As Characters			As Text Attributes			
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter	
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground		
4B	75	K	K	Note 4	Red	Light Cyan	High Intensity	
4C	76	L	L	Note 4	Red	Light Red	High Intensity	
4D	77	M	M	Note 4	Red	Light Magenta	High Intensity	
4E	78	N	N	Note 4	Red	Yellow	High Intensity	
4F	79	O	O	Note 4	Red	White	High Intensity	
50	80	P	P	Note 4	Magenta	Black	Normal	
51	81	Q	Q	Note 4	Magenta	Blue	Underline	
52	82	R	R	Note 4	Magenta	Green	Normal	
53	83	S	S	Note 4	Magenta	Cyan	Normal	
54	84	T	T	Note 4	Magenta	Red	Normal	
55	85	U	U	Note 4	Magenta	Magenta	Normal	
56	86	V	V	Note 4	Magenta	Brown	Normal	
57	87	W	W	Note 4	Magenta	Light Grey	Normal	
58	88	X	X	Note 4	Magenta	Dark Grey	High Intensity	
59	89	Y	Y	Note 4	Magenta	Light Blue	High Intensity Underline	
5A	90	Z	Z	Note 4	Magenta	Light Green	High Intensity	
5B	91	[	[		Magenta	Light Cyan	High Intensity	
5C	92	\	\		Magenta	Light Red	High Intensity	
5D	93	]	]		Magenta	Light Magenta	High Intensity	
5E	94	^	^	Shift	Magenta	Yellow	High Intensity	
5F	95	—	—	Shift	Magenta	White	High Intensity	
60	96	.	.		Yellow	Black	Normal	
61	97	a	a	Note 5	Yellow	Blue	Underline	
62	98	b	b	Note 5	Yellow	Green	Normal	
63	99	c	c	Note 5	Yellow	Cyan	Normal	
64	100	d	d	Note 5	Yellow	Red	Normal	
65	101	e	e	Note 5	Yellow	Magenta	Normal	
66	102	f	f	Note 5	Yellow	Brown	Normal	

## 7-6 Characters, Keystrokes, and Color

Value		As Characters			As Text Attributes		IBM Monochrome Display Adapter
					Color/Graphics Monitor Adapter	Background	
Hex	Dec	Symbol	Keystrokes	Modes			
67	103	g	g	Note 5	Yellow	Light Grey	Normal
68	104	h	h	Note 5	Yellow	Dark Grey	High Intensity
69	105	i	i	Note 5	Yellow	Light Blue	High Intensity Underline
6A	106	j	j	Note 5	Yellow	Light Green	High Intensity
6B	107	k	k	Note 5	Yellow	Light Cyan	High Intensity
6C	108	l	l	Note 5	Yellow	Light Red	High Intensity
6D	109	m	m	Note 5	Yellow	Light Magenta	High Intensity
6E	110	n	n	Note 5	Yellow	Yellow	High Intensity
6F	111	o	o	Note 5	Yellow	White	High Intensity
70	112	p	p	Note 5	White	Black	Reverse Video
71	113	q	q	Note 5	White	Blue	Underline
72	114	r	r	Note 5	White	Green	Normal
73	115	s	s	Note 5	White	Cyan	Normal
74	116	f	f	Note 5	White	Red	Normal
75	117	u	u	Note 5	White	Magenta	Normal
76	118	v	v	Note 5	White	Brown	Normal
77	119	w	w	Note 5	White	Light Grey	Normal
78	120	x	x	Note 5	White	Dark Grey	Reverse Video
79	121	y	y	Note 5	White	Light Blue	High Intensity Underline
7A	122	z	z	Note 5	White	Light Green	High Intensity
7B	123	{	{	Shift	White	Light Cyan	High Intensity
7C	124	:	:	Shift	White	Light Red	High Intensity
7D	125	}	}	Shift	White	Light Magenta	High Intensity
7E	126	~	~	Shift	White	Yellow	High Intensity
7F	127	Δ	Ctrl —		White	White	High Intensity

Value		As Characters			As Text Attributes			
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter	
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground		
* * * * 80 to FF Hex are Flashing in both Color & IBM Monochrome * * * *								
80	128	Ç	Alt 128	Note 6	Black	Black	Non-Display	
81	129	ü	Alt 129	Note 6	Black	Blue	Underline	
82	130	é	Alt 130	Note 6	Black	Green	Normal	
83	131	â	Alt 131	Note 6	Black	Cyan	Normal	
84	132	ä	Alt 132	Note 6	Black	Red	Normal	
85	133	à	Alt 133	Note 6	Black	Magenta	Normal	
86	134	å	Alt 134	Note 6	Black	Brown	Normal	
87	135	ç	Alt 135	Note 6	Black	Light Grey	Normal	
88	136	ê	Alt 136	Note 6	Black	Dark Grey	Non-Display	
89	137	ë	Alt 137	Note 6	Black	Light Blue	High Intensity Underline	
8A	138	è	Alt 138	Note 6	Black	Light Green	High Intensity	
8B	139	ï	Alt 139	Note 6	Black	Light Cyan	High Intensity	
8C	140	î	Alt 140	Note 6	Black	Light Red	High Intensity	
8D	141	ì	Alt 141	Note 6	Black	Light Magenta	High Intensity	
8E	142	Ä	Alt 142	Note 6	Black	Yellow	High Intensity	
8F	143	Å	Alt 143	Note 6	Black	White	High Intensity	
90	144	É	Alt 144	Note 6	Blue	Black	Normal	
91	145	æ	Alt 145	Note 6	Blue	Blue	Underline	
92	146	Æ	Alt 146	Note 6	Blue	Green	Normal	
93	147	ô	Alt 147	Note 6	Blue	Cyan	Normal	
94	148	ö	Alt 148	Note 6	Blue	Red	Normal	
95	149	ò	Alt 149	Note 6	Blue	Magenta	Normal	
96	150	ú	Alt 150	Note 6	Blue	Brown	Normal	
97	151	ù	Alt 151	Note 6	Blue	Light Grey	Normal	
98	152	ÿ	Alt 152	Note 6	Blue	Dark Grey	High Intensity	
99	153	ö	Alt 153	Note 6	Blue	Light Blue	High Intensity Underline	
9A	154	ü	Alt 154	Note 6	Blue	Light Green	High Intensity	



Value		As Characters		As Text Attributes			
				Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter	
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
B7	183	█	Alt 183	Note 6	Cyan	Light Grey	Normal
B8	184	█	Alt 184	Note 6	Cyan	Dark Grey	High Intensity
B9	185	█	Alt 185	Note 6	Cyan	Light Blue	High Intensity Underline
BA	186	█	Alt 186	Note 6	Cyan	Light Green	High Intensity
BB	187	█	Alt 187	Note 6	Cyan	Light Cyan	High Intensity
BC	188	█	Alt 188	Note 6	Cyan	Light Red	High Intensity
BD	189	█	Alt 189	Note 6	Cyan	Light Magenta	High Intensity
BE	190	█	Alt 190	Note 6	Cyan	Yellow	High Intensity
BF	191	█	Alt 191	Note 6	Cyan	White	High Intensity
CO	192	█	Alt 192	Note 6	Red	Black	Normal
C1	193	█	Alt 193	Note 6	Red	Blue	Underline
C2	194	█	Alt 194	Note 6	Red	Green	Normal
C3	195	█	Alt 195	Note 6	Red	Cyan	Normal
C4	196	█	Alt 196	Note 6	Red	Red	Normal
C5	197	█	Alt 197	Note 6	Red	Magenta	Normal
C6	198	█	Alt 198	Note 6	Red	Brown	Normal
C7	199	█	Alt 199	Note 6	Red	Light Grey	Normal
C8	200	█	Alt 200	Note 6	Red	Dark Grey	High Intensity
C9	201	█	Alt 201	Note 6	Red	Light Blue	High Intensity Underline
CA	202	█	Alt 202	Note 6	Red	Light Green	High Intensity
CB	203	█	Alt 203	Note 6	Red	Light Cyan	High Intensity
CC	204	█	Alt 204	Note 6	Red	Light Red	High Intensity
CD	205	█	Alt 205	Note 6	Red	Light Magenta	High Intensity
CE	206	█	Alt 206	Note 6	Red	Yellow	High Intensity
CF	207	█	Alt 207	Note 6	Red	White	High Intensity
DO	208	█	Alt 208	Note 6	Magenta	Black	Normal

## 7-10 Characters, Keystrokes, and Color

Value		As Characters			As Text Attributes		IBM Monochrome Display Adapter
					Color/Graphics Monitor Adapter		
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
D1	209		Alt 209	Note 6	Magenta	Blue	Underline
D2	210		Alt 210	Note 6	Magenta	Green	Normal
D3	211		Alt 211	Note 6	Magenta	Cyan	Normal
D4	212		Alt 212	Note 6	Magenta	Red	Normal
D5	213		Alt 213	Note 6	Magenta	Magenta	Normal
D6	214		Alt 214	Note 6	Magenta	Brown	Normal
D7	215		Alt 215	Note 6	Magenta	Light Grey	Normal
D8	216		Alt 216	Note 6	Magenta	Dark Grey	High Intensity
D9	217		Alt 217	Note 6	Magenta	Light Blue	High Intensity Underline
DA	218		Alt 218	Note 6	Magenta	Light Green	High Intensity
DB	219		Alt 219	Note 6	Magenta	Light Cyan	High Intensity
DC	220		Alt 220	Note 6	Magenta	Light Red	High Intensity
DD	221		Alt 221	Note 6	Magenta	Light Magenta	High Intensity
DE	222		Alt 222	Note 6	Magenta	Yellow	High Intensity
DF	223		Alt 223	Note 6	Magenta	White	High Intensity
E0	224	$\alpha$	Alt 224	Note 6	Yellow	Black	Normal
B1	225	$\beta$	Alt 225	Note 6	Yellow	Blue	Underline
E2	226	$\Gamma$	Alt 226	Note 6	Yellow	Green	Normal
E3	227	$\pi$	Alt 227	Note 6	Yellow	Cyan	Normal
E4	228	$\Sigma$	Alt 228	Note 6	Yellow	Red	Normal
E5	229	$\sigma$	Alt 229	Note 6	Yellow	Magenta	Normal
E6	230	$\mu$	Alt 230	Note 6	Yellow	Brown	Normal
E7	231	$\tau$	Alt 231	Note 6	Yellow	Light Grey	Normal
E8	232	$\Phi$	Alt 232	Note 6	Yellow	Dark Grey	High Intensity
E9	233	$\theta$	Alt 233	Note 6	Yellow	Light Blue	High Intensity Underline
EA	234	$\Omega$	Alt 234	Note 6	Yellow	Light Green	High Intensity
EB	235	$\delta$	Alt 235	Note 6	Yellow	Light Cyan	High Intensity

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
EC	236	∞	Alt 236	Note 6	Yellow	Light Red	High Intensity
ED	237	φ	Alt 237	Note 6	Yellow	Light Magenta	High Intensity
EE	238	ε	Alt 238	Note 6	Yellow	Yellow	High Intensity
EF	239	∩	Alt 239	Note 6	Yellow	White	High Intensity
F0	240	≡	Alt 240	Note 6	White	Black	Reverse Video
F1	241	±	Alt 241	Note 6	White	Blue	Underline
F2	242	≥	Alt 242	Note 6	White	Green	Normal
F3	243	≤	Alt 243	Note 6	White	Cyan	Normal
F4	244	⌚	Alt 244	Note 6	White	Red	Normal
F5	245	⌚⌚	Alt 245	Note 6	White	Magenta	Normal
F6	246	÷	Alt 246	Note 6	White	Brown	Normal
F7	247	≈	Alt 247	Note 6	White	Light Grey	Normal
F8	248	○	Alt 248	Note 6	White	Dark Grey	Reverse Video
F9	249	●	Alt 249	Note 6	White	Light Blue	High Intensity Underline
FA	250	•	Alt 250	Note 6	White	Light Green	High Intensity
FB	251	√	Alt 251	Note 6	White	Light Cyan	High Intensity
FC	252	η	Alt 252	Note 6	White	Light Red	High Intensity
FD	253	2	Alt 253	Note 6	White	Light Magenta	High Intensity
FE	254	■	Alt 254	Note 6	White	Yellow	High Intensity
FF	255	BLANK	Alt 255	Note 6	White	White	High Intensity

## NOTES

1. Asterisk (\*) can be typed using two methods: press the PrtSc key or, in the shift mode, press the 8 key.
2. Period (.) can be typed using two methods: press the . key or, in the shift or Num Lock mode, press the Del key.
3. Numeric characters 0-9 can be typed using two methods: press the numeric keys on the top row of the keyboard or, in the shift or Num Lock mode, press the numeric keys in the keypad portion of the keyboard.
4. Uppercase alphabetic characters (A-Z) can be typed in two modes: the shift mode or the Caps Lock mode.
5. Lowercase alphabetic characters (a-z) can be typed in two modes: in the normal mode or in Caps Lock and shift mode combined.
6. The three digits after the Alt key must be typed from the numeric keypad. Character codes 0-255 may be entered in this fashion (with Caps Lock activated, character codes 97-122 will display uppercase.)

DECIMAL VALUE	➡	0	16	32	48	64	80	96	112
⬇	HEXA DECIMAL VALUE	0	1	2	3	4	5	6	7
0	0	BLANK (NULL)	▶	BLANK (SPACE)	0	@	P	‘	p
1	1	😊	◀	!	1	A	Q	a	q
2	2	😊	↔	“	2	B	R	b	r
3	3	♥	!!	#	3	C	S	c	s
4	4	♦	Π	\$	4	D	T	d	t
5	5	♣	§	%	5	E	U	e	u
6	6	♠	▬	&	6	F	V	f	v
7	7	•	↑↓	'	7	G	W	g	w
8	8	•	↑	(	8	H	X	h	x
9	9	○	↓	)	9	I	Y	i	y
10	A	○	→	*	:	J	Z	j	z
11	B	♂	←	+	;	K	[	k	{
12	C	♀	└	,	<	L	\	l	‘
13	D	♪	↔	-	=	M	]	m	}
14	E	♪	▲	.	>	N	^	n	~
15	F	☀	▼	/	?	O	_	o	△



## **Notes:**

# **SECTION 8. COMMUNICATIONS**

## **Contents**

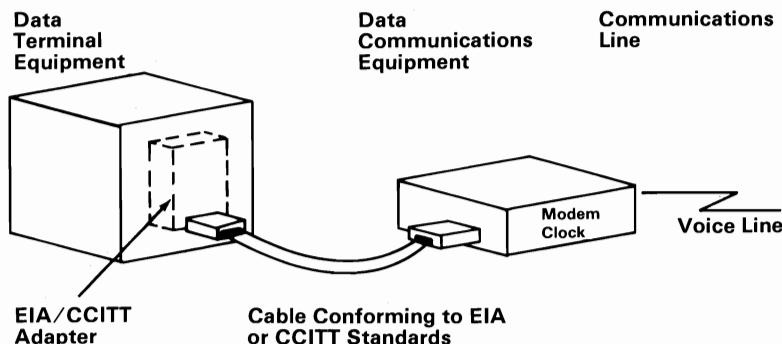
<b>Communications</b>	.....	<b>8-3</b>
<b>Establishing a Data Link</b>	.....	<b>8-6</b>

## **Notes:**

# Communications

Information-processing equipment used for communication is called data terminal equipment (DTE.) Equipment used to connect the DTE to the communication line is called data communication equipment (DCE.)

An adapter connects the data terminal equipment to the data communication line as shown in the following figure:



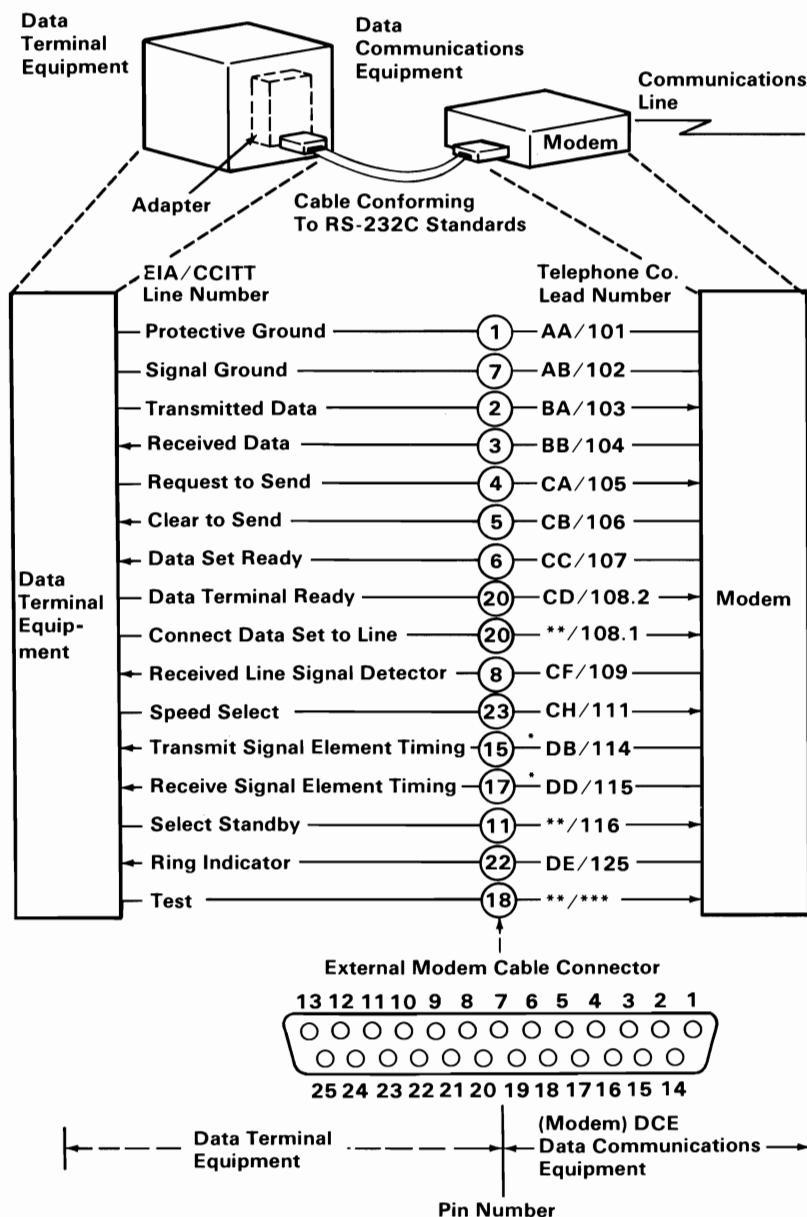
The EIA/CCITT adapter allows the DTE to be connected to the DCE using EIA or CCITT standardized connections. An external modem is shown in the figure; however, other types of DCE also can be connected to the DTE using EIA or CCITT standardized connections.

EIA standards are labeled RS-x (recommended standards-x), and CCITT standards are labeled V.x or X.x, where x is the number of the standard.

The EIA RS-232 interface standard defines the connector type, pin numbers, line names, and signal levels used to connect data terminal equipment to data communications equipment for the purpose of transmitting and receiving data. Since the RS-232 standard was developed, it has been revised three times. The three revised standards are RS-232A, RS-232B, and the presently used RS-232C.

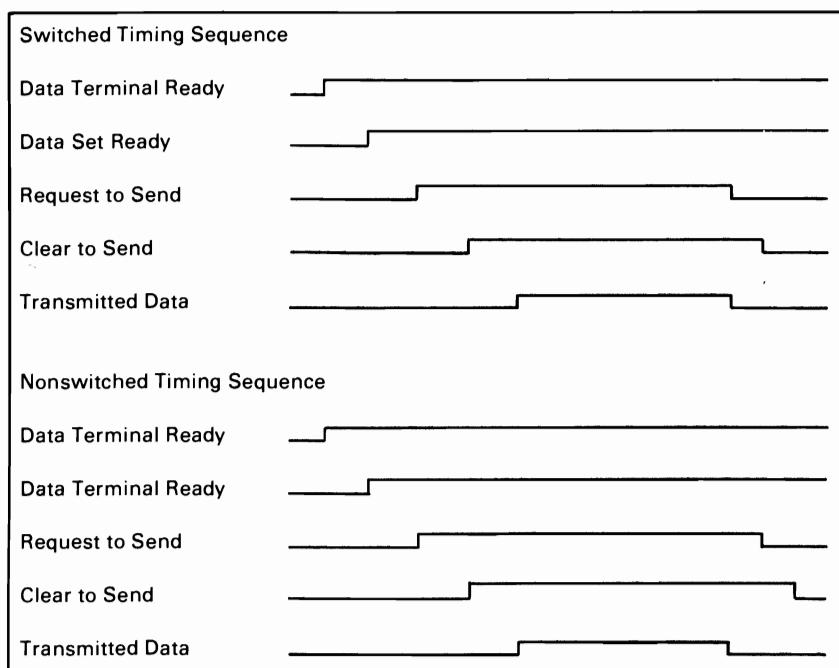
The CCITT V.24 interface standard is equivalent to the RS-232C standard; therefore, the descriptions of the EIA standards also apply to the CCITT standards.

The following is an illustration of data terminal equipment connected to an external modem using connections defined by the RS-232C interface standard:



# Establishing a Data Link

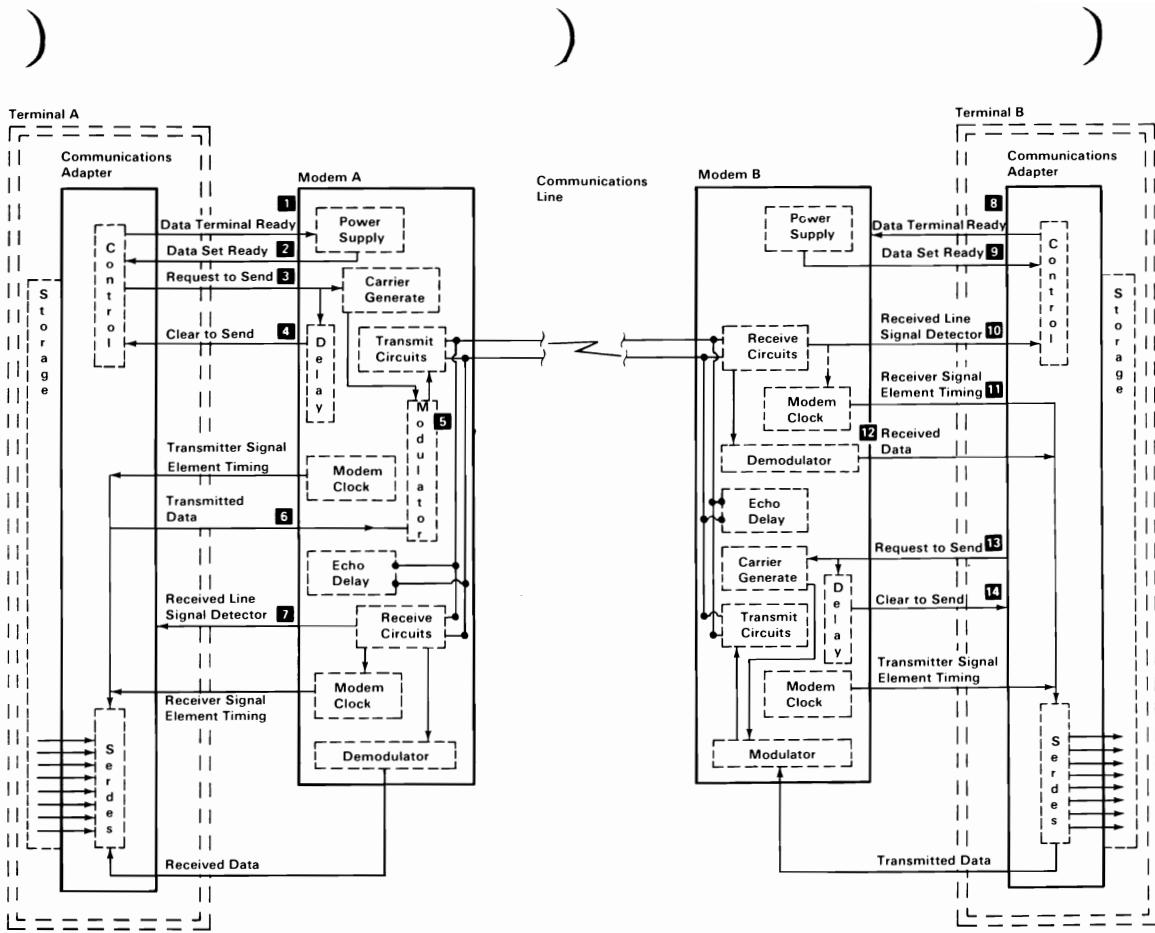
The following bar graphs represent normal timing sequences of operation during the establishment of communication for both switched (dial-up) and nonswitched (direct line) networks.



The following examples show how a link is established on a nonswitched point-to-point line, a nonswitched multipoint line, and a switched point-to-point line.

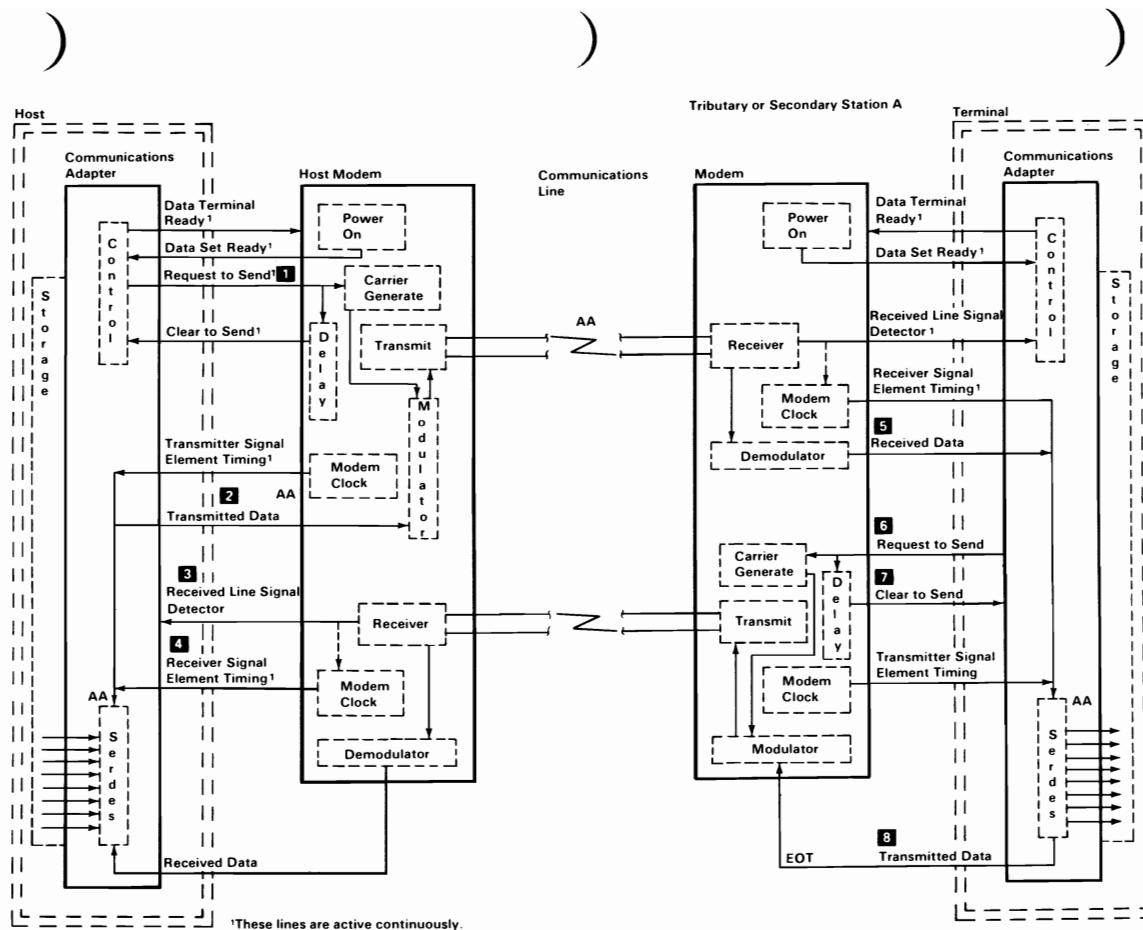
## Establishing a Link on a Nonswitched Point-to-Point Line

1. The terminals at both locations activate the 'data terminal ready' lines **1** and **8**.
2. Normally the 'data set ready' lines **2** and **9** from the modems are active whenever the modems are powered on.
3. Terminal A activates the 'request to send' line **3**, which causes the modem at terminal A to generate a carrier signal.
4. Modem B detects the carrier, and activates the 'received line signal detector' line (sometimes called data carrier detect) **10**. Modem B also activates the 'receiver signal element timing' line (sometimes called receive clock) **11** to send receive clock signals to the terminal. Some modems activate the clock signals whenever the modem is powered on.
5. After a specified delay, modem A activates the 'clear to send' line **4**, which indicates to terminal A that the modem is ready to transmit data.
6. Terminal A serializes the data to be transmitted (through the serdes) and transmits the data one bit at a time (synchronized by the transmit clock) onto the 'transmitted data' line **6** to the modem.
7. The modem modulates the carrier signal with the data and transmits it to the modem B **5**.
8. Modem B demodulates the data from the carrier signal and sends it to terminal B on the 'received data' line **12**.
9. Terminal B deserializes the data (through the serdes) using the receive clock signals (on the 'receiver signal element timing' line) **11** from the modem.
10. After terminal A completes its transmission, it deactivates the 'request to send' line **3**, which causes the modem to turn off the carrier and deactivate the 'clear to send' line **4**.
11. Terminal A and modem A now become receivers and wait for a response from terminal B, indicating that all data has reached terminal B. Modem A begins an echo delay (50 to 150 milliseconds) to ensure that all echoes on the line have diminished before it begins receiving. An echo is a reflection of the transmitted signal. If the transmitting modem changed to receive too soon, it could receive a reflection (echo) of the signal it just transmitted.
12. Modem B deactivates the 'received line signal detector' line **10** and, if necessary, deactivates the receive clock signals on the 'receiver signal element timing' line **11**.
13. Terminal B now becomes the transmitter to respond to the request from terminal A. To transmit data, terminal B activates the 'request to send' line **13**, which causes modem B to transmit a carrier to modem A.
14. Modem B begins a delay that is longer than the echo delay at modem A before turning on the 'clear to send' line. The longer delay (called request-to-send to clear-to-send delay) ensures that modem A is ready to receive when terminal B begins transmitting data. After the delay, modem B activates the 'clear to send' line **14** to indicate that terminal B can begin transmitting its response.
15. After the echo delay at modem A, modem A senses the carrier from modem B (the carrier was activated in step 13 when terminal B activated the 'request to send' line) and activates the 'received line signal detector' line **7** to terminal A.
16. Modem A and terminal A are now ready to receive the response from terminal B. Remember, the response was not transmitted until after the request-to-send to clear-to-send delay at modem B (step 14).



## Establishing a Link on a Nonswitched Multipoint Line

1. The control station serializes the address for the tributary or secondary station (AA) and sends its address to the modem on the 'transmitted data' line **2**.
2. Since the 'request to send' line and, therefore, the modem carrier, is active continuously **1**, the modem immediately modulates the carrier with the address, and, thus, the address is transmitted to all modems on the line.
3. All tributary modems, including the modem for station A, demodulate the address and send it to their terminals on the 'received data' line **5**.
4. Only station A responds to the address; the other stations ignore the address and continue monitoring their 'received data' line. To respond to the poll, station A activates its 'request to send' line **6** which causes the modem to begin transmitting a carrier signal.
5. The control station's modem receives the carrier and activates the 'received line signal detector' line **3** and the 'receiver signal element timing' line **4** (to send clock signals to the control station). Some modems activate the clock signals as soon as they are powered on.
6. After a short delay to allow the control station modem to receive the carrier, the tributary modem activates the 'clear to send' line **7**.
7. When station A detects the active 'clear to send' line, it transmits its response. (For this example, assume that station A has no data to send; therefore, it transmits an EOT **8**.)
8. After transmitting the EOT, station A deactivates the 'request to send' line **6**. This causes the modem to deactivate the carrier and the 'clear to send' line **7**.
9. When the modem at the control station (host) detects the absence of the carrier, it deactivates the 'received line signal detector' line **3**.
10. Tributary station A is now in receive mode waiting for the next poll or select transmission from the control station.

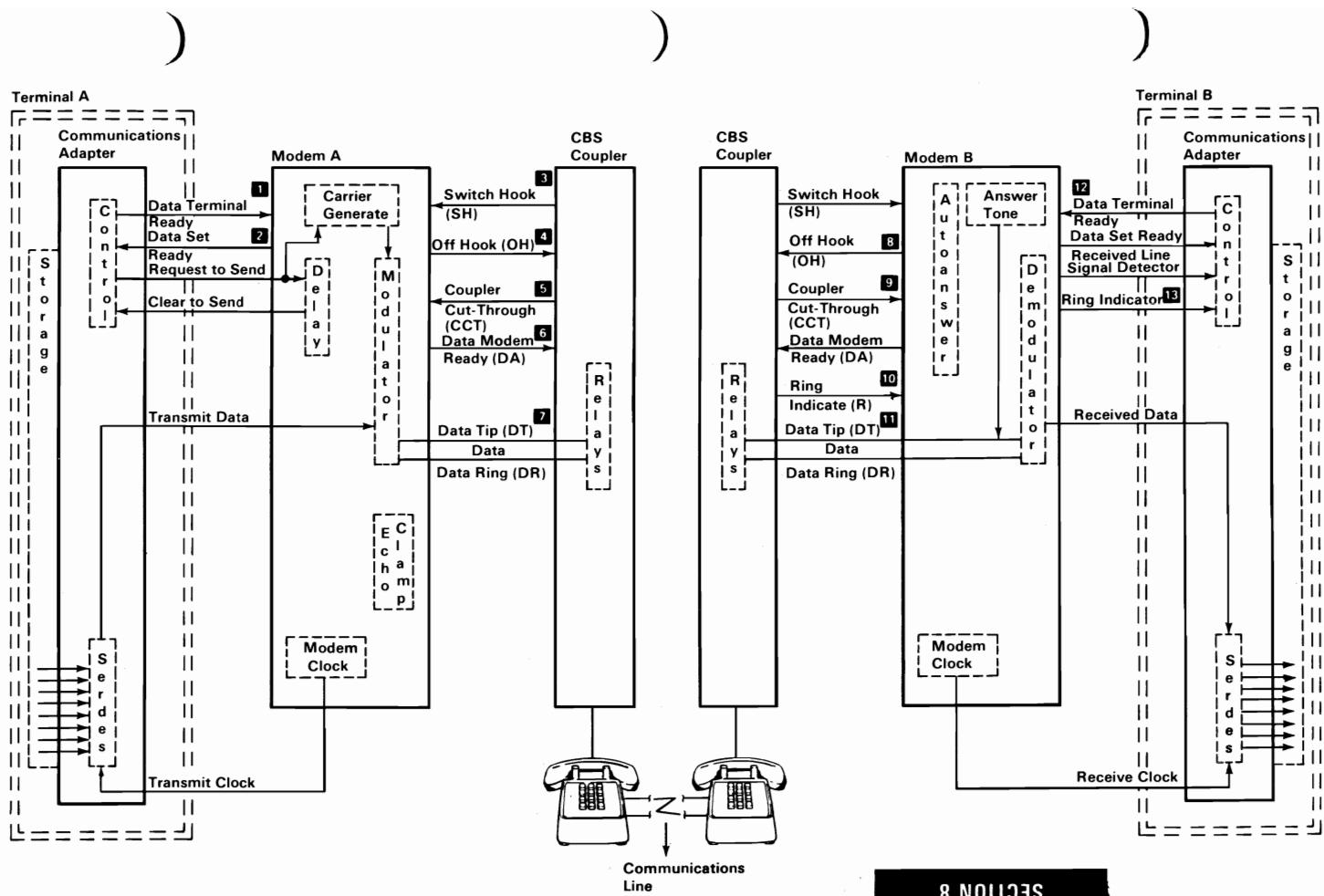


<sup>1</sup>These lines are active continuously.

## Establishing a Link on a Switched Point-To-Point Line

1. Terminal A is in communications mode; therefore, the 'data terminal ready' line **1** is active. Terminal B is in communication mode waiting for a call from terminal A.
2. When the terminal A operator lifts the telephone handset, the 'switch hook' line from the coupler is activated **3**.
3. Modem A detects the 'switch hook' line and activates the 'off hook' line **4**, which causes the coupler to connect the telephone set to the line and activate the 'coupler cut-through' line **5** to the modem.
4. Modem A activates the 'data modem ready' line **6** to the coupler (the 'data modem ready' line is on continuously in some modems).
5. The terminal A operator sets the exclusion key or talk/data switch to the talk position to connect the handset to the communications line. The operator then dials the terminal B number.
6. When the telephone at terminal B rings, the coupler activates the 'ring indicate' line to modem B **10**. Modem B indicates that the 'ring indicate' line was activated by activating the 'ring indicator' line **13** to terminal B.
7. Terminal B activates the 'data terminal ready' line to modem B **12**, which activates the autoanswer circuits in modem B. (The 'data terminal ready' line might already be active in some terminals.)
8. The autoanswer circuits in modem B activate the 'off hook' line to the coupler **8**.
9. The coupler connects modem B to the communications line through the 'data tip' and 'data ring' lines **11** and activates the 'coupler cut-through' line **9** to the modem. Modem B then transmits an answer tone to terminal A.
10. The terminal A operator hears the tone and sets the exclusion key or talk/data switch to the data position (or performs an equivalent operation) to connect modem A to the communications line through the 'data tip' and 'data ring' lines **7**.
11. The coupler at terminal A deactivates the 'switch hook' line **3**. This causes modem A to activate the 'data set ready' line **2** indicating to terminal A that the modem is connected to the communications line.

The sequence of the remaining steps to establish the data link is the same as the sequence required on a nonswitched point-to-point line. When the terminals have completed their transmission, they both deactivate the 'data terminal ready' line to disconnect the modems from the line.



## **Notes:**

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# SECTION 9. IBM PERSONAL COMPUTER COMPATIBILITY

## Contents

<b>Hardware Considerations</b> .....	<b>9-3</b>
System Board .....	9-3
20Mb Fixed Disk Drive .....	9-4
High Capacity Diskette Drive .....	9-4
Adapters .....	9-4
Keyboard .....	9-4
The IBM Personal Computer AT Does Not Support .....	9-5
<b>Application Guidelines</b> .....	<b>9-5</b>
High-Level Language Considerations .....	9-5
Assembler Language Programming Considerations .....	9-6
Multi-tasking Provisions .....	9-11
Interfaces .....	9-11
Classes .....	9-13
Timeouts .....	9-15
SYS REQ Key .....	9-15
Subsystem Structure .....	9-15
Subsystem Startup and Lockout .....	9-16
SYS REQ Key Functions .....	9-17
SYS Key Interfaces .....	9-18
Copy Protection .....	9-22
Bypassing BIOS .....	9-22
Diskette Drive Differences .....	9-22
Write Current .....	9-23
Machine-Sensitive Code .....	9-23

# **Notes:**

This section shows the differences between the IBM Personal Computer AT and the rest of the IBM Personal Computer family. It also contains information necessary to design hardware and programs that will be compatible with all IBM Personal Computers.

## Hardware Considerations

In order to design compatible hardware or programs, hardware differences between the IBM Personal Computers must be considered. The following are hardware features of the IBM Personal Computer AT that are not supported by the rest of the IBM Personal Computer Family.

### System Board

The IBM Personal Computer AT system board uses an Intel 80286 microprocessor which is generally compatible with the Intel 8088 microprocessor used in the rest of the IBM Personal Computers. Programming considerations because of the faster processing capability of the 80286 are discussed later in "Application Guidelines."

The system board expansion slots in the IBM Personal Computer AT have a 36-pin connector in addition to the 62-pin connector. Adapters designed to make use of the 36-pin connector are not compatible with the rest of the IBM Personal Computers.

On the I/O channel:

- The system clock signal should only be used for synchronization and not for applications requiring a fixed frequency.
- The 14.31818 MHz oscillator is not synchronous with the system clock.
- 'ALE' is activated during DMA cycles.

- The 'I/O write' signal is not active during refresh cycles.
- Pin B04 supports IRQ 9.

## **20Mb Fixed Disk Drive**

The fixed disk drive used in the IBM Personal Computer AT can store up to 20Mb of data. Reading from and writing to this drive is initiated in the same way as with the Personal Computer XT; however, the IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter may be addressed from different BIOS locations.

## **High Capacity Diskette Drive**

This diskette drive is capable of reading and writing diskettes in 160/180Kb, 320/360Kb, and 1.2Mb mode. However, if a diskette, formatted in either the 160/180Kb or 320/360Kb mode is written on by this diskette drive, that information may only be read by a high capacity diskette drive.

**Note:** Diskettes, designed for use in this drive, in the 1.2Mb mode may not be used in either a 160/180Kb or a 320/360Kb diskette drive.

## **Adapters**

The IBM Personal Computer AT 128KB Memory Expansion Option, the IBM Personal Computer AT 512KB Memory Expansion Option, the IBM Personal Computer AT Prototype Adapter, and the IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter use the additional 36 pin system board expansion slot and are not compatible with the rest of the IBM Personal Computer Family.

## **Keyboard**

The IBM Personal Computer AT Keyboard is an 84-key unit that can perform all functions of the other IBM Personal Computer keyboards, but is not plug-compatible with any of the other keyboards.

## The IBM Personal Computer AT Does Not Support

- Expansion Unit
- IBM Asynchronous Communications Adapter
- IBM 64/256KB Memory Expansion Adapter
- IBM Printer Adapter
- Other keyboards

## Application Guidelines

The following information should be used to develop application programs for the IBM Personal Computer family.

### High-Level Language Considerations

The IBM-supported languages of BASIC, FORTRAN, COBAL, Pascal, and APL are the best choices for writing compatible programs.

If a program uses specific features of the hardware, that program may not be compatible with all IBM Personal Computers. Specifically, the use of assembler language subroutines or hardware-specific commands (In, Out, Peek, Poke, ...) must follow the assembler language rules (see "Assembler Language Programming").

Any program that requires precise timing information should obtain it through a DOS or language interface; for example, TIME\$ in BASIC. If greater precision is required, the assembler techniques in "Assembly Language Programming" are available. The use of programming loops may prevent a program from being compatible with other IBM Personal Computers.

## Assembler Language Programming Considerations

The following OP codes work differently on the IBM Personal Computer AT than they do on other IBM Personal Computers.

- If the system microprocessor executes a POPF instruction in either the real or the virtual address mode with CPL $\leq$ IOPL, then a pending maskable interrupt (the INTR pin active) may be improperly recognized after executing the POPF instruction even if maskable interrupts were disabled before the POPF instruction and the value popped had IF=0. If the interrupt is improperly recognized, the interrupt is still correctly executed. This errata has no effect when interrupts are enabled in either real or virtual address mode. This errata has no effect in the virtual address mode when CPL>IOPL.

The POPF instruction may be simulated with the following code macro:

```
POPFF    Macro      ;use POPFF instead of POPF
                    ;simulate popping flags
                    ;using IRET

EB 01     JMP $+3   ;jump around IRET

CF         IRET      ;POP CS, IP, flags

0E         PUSH CS   ;push CS

E8 FB FF  CALL $-2  ;CALL within segment
                    ;program will continue here
```

- PUSH SP pushes the current stack pointer. The microprocessor used in the IBM Personal Computer and the IBM Personal Computer XT pushes the new stack pointer.
- Single step interrupt (when TF=1) does not occur on the interrupt instruction (OP code hex CC,CD). The microprocessor in the IBM Personal Computer and the IBM Personal Computer XT does interrupt on the INT instruction.
- The divide error exception (interrupt 0) pushes the CS:IP of the instruction, causing the exception. The IBM Personal Computer and the IBM Personal Computer XT push the CS:IP following the instruction, causing the exception.
- Shift counts are masked to 5 bits. Shift counts greater than 31 are treated mod 32, that is, a shift count of 36 shifts the operand 4 places.

Assembler language programs should perform all I/O operations through ROM BIOS or DOS function calls.

- Program interrupts are used for access to these functions. This practice removes the absolute addressing from the program. Only the interrupt number is required.
- The math coprocessor detects six different exception conditions that can occur during instruction execution. If the appropriate exception mask within the coprocessor is not set, the coprocessor sets its error signal. This error signal generates a hardware interrupt (interrupt 13) and causes the 'BUSY' signal to the coprocessor to be held in the busy state. The 'BUSY' signal may be cleared by an 8-bit I/O Write command to address hex F0 with D0 through D7 equal to 0.

The power-on-self test code in the system ROM enables hardware interrupt 13 and sets up its vector to point to a routine in ROM. The ROM routine clears the 'BUSY' signal's latch and then transfers control to the address pointed to by the NMI interrupt vector. This allows code written for any IBM Personal Computer to work on an IBM Personal Computer AT. The NMI interrupt handler should read the coprocessor's status to determine if the NMI was caused by

the coprocessor. If the interrupt was not generated by the coprocessor, control should be passed to the original NMI interrupt handler.

- Back to back I/O commands to the same I/O ports will not permit enough recovery time for I/O chips. To insure enough time, a JMP SHORT \$+2 must be inserted between IN/OUT instructions to the same I/O chip.

**Note:** MOV AL,AH type instruction does not allow enough recovery time. An example of the correct procedure follows:

OUT IO\_\_ADD,AL

JMP SHORT \$+2

MOV AL,AH

OUT IO\_\_ADD,AL

- In the IBM Personal Computer AT IRQ 9 is redirected to INT hex 0A (hardware IRQ 2). This insures that hardware designed to use IRQ 2 will operate in the IBM Personal Computer AT.
- The system can mask hardware sensitivity. New devices can change the ROM BIOS to accept the same programming interface on the new device.
- In cases where BIOS provides parameter tables, such as for video or diskette, a program may substitute new parameter values by building a new copy of the table and changing the vector to point to that table. However, the program should copy the current table, using the current vector, and then modify those locations in the table that need to be changed. In this way, the program will not inadvertently change any values that should be left the same.
- Disk\_\_Base consists of 11 parameters required for diskette operation. They are pointed at by the data variable, Disk\_\_Pointer, at absolute address 0:78. It is strongly recommended that the values supplied in ROM be used. If it

becomes necessary to modify any of the parameters, build another parameter block and modify the address in Disk-Pointer to point to the new block. The parameters were established to operate both the High Capacity Diskette Drive and the Double Sided Diskette Drive. Three of the parameters in this table are under control of BIOS in the following situations. The Gap Length Parameter is no longer retrieved from the parameter block. Gap length used during diskette read, write, and verify operations is derived from within diskette BIOS. Gap length for format operations is still obtained from the parameter block. Special considerations are required for formatting operations. See the prologue of Diskette BIOS for the required details. If a parameter block contains a head settle time parameter value of 0 milliseconds, and a write operation is being performed, at least 15 milliseconds of head settle time will be enforced for a High Capacity Diskette Drive and 20 milliseconds will be enforced for a Double Sided Diskette Drive. If a parameter block contains a motor start wait parameter of less than 1 second for a write or format operation or 625 milliseconds for a read or verify operation, Diskette BIOS will enforce those times listed above.

- The following procedure is used to determine the type of media inserted in the High Capacity Diskette Drive:
  1. Read Track 0, Head 0, Sector 1 to allow diskette BIOS to establish the media/drive combination. If this is successful, continue with the next step.
  2. Read Track 0, Sector 15. If an error occurs, a double sided diskette is in the drive. If a successful read occurs, a high capacity diskette is in the drive.
  3. If Step 1 fails, issue the reset function (AH=0) to diskette BIOS and retry. If a successful read cannot be done, the media needs to be formatted or is defective.

ROM BIOS and DOS do not provide for all functions. The following are the allowable I/O operations with which IBM will maintain compatibility in future systems.

- Control of the sound using port hex 61, and the sound channel of the timer/counter. A program can control timer/counter channels 0 and 2, ports hex 40, 42, and 43. A program must not change the value in port hex 41, because this port controls the dynamic-memory refresh. Channel 0 provides the time-of-day interrupt, and can also be used for timing short intervals. Channel 2 of the timer/counter is the output for the speaker and cassette ports. This channel may also be used for timing short intervals, although it cannot interrupt at the end of the period.
- Control of the Game Control Adapter, port hex 201

**Note:** Programs should use the timer for delay on the paddle input rather than a program loop.

- Interrupt Mask Register (IMR), port hex 21, can be used to selectively mask and unmask the hardware features.

The following information pertains to absolute memory locations.

- Interrupt Vectors (hex 0)--A program may change these to point at different processing routines. When an interrupt vector is modified, the original value should be retained. If the interrupt, either hardware or program, is not directed toward this device handler, the request should be passed to the next item in the list.
- Video Display Buffers (hex B0000 and B8000)-- For each mode of operation defined in the video display BIOS, the memory map will remain the same. For example, the bit map for the 320 x 200 medium-resolution graphics mode of the Color/Graphics Monitor adapter will be retained on any future adapter that supports that mode. If the bit map is modified, a different mode number will be used.
- ROM BIOS Data Area (40:0)--Any variables in this area will retain their current definition, whenever it is reasonable to do so. IBM may use these data areas for other purposes when the variable no longer has meaning in the system. In general, ROM BIOS data variables should be read or modified through BIOS calls whenever possible, and not with direct access to the variable.

A program that requires timing information should use either the time-of-day clock or the timing channels of the timer/counter. The input frequency to the timer will be maintained at 1.19 MHz, providing a constant time reference. Program loops should be avoided.

Programs that use copy protection schemes should use the ROM BIOS diskette calls to read and verify the diskette and should not be timer dependent. Any method can be used to create the diskette, although manufacturing capability should be considered. The verifying program can look at the diskette controller's status bytes in the ROM BIOS data area for additional information about embedded errors. More information about copy protection may be found under 'Copy Protection' later in this section.

Any DOS program must be relocatable and insensitive to the size of DOS or its own load addresses. A program's memory requirement should be identified and contiguous with the load module. A program should not assume that all of memory is available to it.

## Multi-tasking Provisions

The IBM Personal Computer AT BIOS contains a feature to assist multi-tasking implementation. "Hooks" are provided for a multi-tasking dispatcher. Whenever a busy (wait) loop occurs in the BIOS, a hook is provided for the system to break out of the loop. Also, whenever an interrupt is serviced by the BIOS, which causes a corresponding wait loop to be exited, another hook is provided for the system.

Thus a system may be written which employs the bulk of the device driver code. The following is valid only in the microprocessor's real address mode. Several steps must be taken by the system code in order to allow this support. First, the system is responsible for the serialization of access to the device driver. The BIOS code is not reentrant. Second, the system is responsible for matching corresponding wait and post calls.

## Interfaces

There are four interfaces to be used by the multi-tasking dispatcher:

### Startup

The first thing to be done is for the startup code to hook interrupt hex 15. The dispatcher is responsible to check for function codes AH = hex 90 and 91. The "Wait" and "Post" sections describe these codes. The dispatcher must pass all other functions through to the previous user of interrupt hex 15. This can be done via a JMP or a CALL. If the function code is hex 90 or 91, then the dispatcher should do the appropriate processing and return via the IRET instruction.

### Serialization

It is up to the multi-tasking system to insure that the device driver code is used in a serial fashion. Multiple entries into the code can result in very serious errors.

### Wait (Busy)

Whenever the BIOS is about to enter a busy loop, it first issues an interrupt 15 with a function code of hex 90 in AH. This signals a WAIT condition. At this point, the dispatcher should save the task status and dispatch another task. This allows overlapped execution of tasks when the hardware is busy. The following is an outline of the code which has been added to the BIOS to implement this function.

#### EXAMPLE DEVICE BUSY LOOP

DO UNTIL

**MOV AX, hex 90XX**

;WAIT code in AH and

;TYPE code in AL  
**INT hex 15** ;issue call  
**JC TIMEOUT** ;optional: for timeout or  
;if carry is set, timeout  
;occurred  
**NORMAL TIMEOUT LOGIC** ;normal timeout

UNTIL INTERRUPT COMPLETE FLAG IS SET

### **POST (Interrupt)**

Whenever the BIOS has set an interrupt flag for a corresponding busy loop, an interrupt 15 occurs with a function code hex 91 in AH. This signals a POST condition. At this point, the dispatcher should set the task status to "ready to run" and return to the interrupt routine. The following BIOS has been added to code to implement this function.

INTERRUPT PROCESSING

SET INTERRUPT COMPLETE FLAG FOR BUSY LOOP

**MOV AX,hex 91XX** ; post code AH and  
; type code AL  
**INT hex 15** ; issue call

### **Classes**

The following types of wait loops are supported:

- The class for 0->7Fh is serially reusable. This means that for the devices that use these codes, access to the BIOS must be restricted to only one task at a time.
- The class for 80h->BFh is reentrant. There is no restriction on the number of tasks which may access the device.
- The class for C0h->FFh is non-interrupt. There is no corresponding interrupt for the wait loop. Therefore, it is the responsibility of the dispatcher to determine what satisfies this condition to exit the loop.

## Function Code Classes

<b>type code (AL)</b>	<b>Description</b>
<b>00h-&gt;7Fh</b>	serially reusable devices; operating system must serialize access
<b>80h-&gt;0BFh</b>	reentrant devices; ES:BX is used to distinguish different calls (multiple I/O calls are allowed simultaneously)
<b>0C0h-&gt;0FFh</b>	wait only calls; there is no complementary "POST" for these waits--these are timeout only. Times are function number dependent.

## Function Code Assignments

The following are specific assignments for the IBM Personal Computer AT BIOS. They are grouped according to the classes described under "Function Code Classes".

<b>Type Code (AL)</b>	<b>Timeout</b>	<b>Description</b>
00H	yes (6 sec)	IBM Personal Computer AT fixed disk

01H	yes (2 sec)	IBM Personal Computer AT diskette
02H	no	IBM Personal Computer AT keyboard
0FDH	yes (1 sec-write)	diskette motor start
--	(625 msec-read)	--
0FEH	yes (?? sec)	printer

The asynchronous support has been omitted. The IBM Personal Computer AT Serial/Parallel Adapter will generate interrupts, but BIOS does not support it in the interrupt mode. Therefore, the support should be included in the multi-tasking system code if that device is to be supported.

## Timeouts

In order to support timeouts properly, it is necessary for the multi-tasking dispatcher to be aware of time. If a device enters a busy loop, it generally should remain there for a specific amount of time before indicating an error. The dispatcher should return to the BIOS wait loop with the carry bit set if a timeout occurred.

## SYS REQ Key

The following describes the use of the SYS REQ key in a multi-tasking environment. It assumes that tasks used are cooperative in some manner. The system must employ a task monitor to allow the user to select various tasks. This selection may be for starting tasks, terminating tasks, supplying input to tasks from the keyboard, or any other function that requires user input.

## **Subsystem Structure**

The following figure shows three subsystems which have multiple tasks. They are arranged in order of hierarchy. Tasks in subsystem B can only run when Task "Other" A is active in subsystem A and tasks in subsystem C can only run when Task "Other" B is active in subsystem B.

Task 1A	Task 2A	Task 3A	Task "Other" A		
Subsystem B Inhibited			Task 1B	Task 2B	Task B "Other" Task 1C Task 2C
Subsystem C Inhibited					

### **Multiple Task Subsystems**

The order in which subsystems were installed (loaded into main storage) determines their priority. The first one installed is higher on the hierarchy. An inhibit mechanism provided at startup time enforces the hierarchy. As a subsystem starts, it broadcasts to the rest of the subsystems, previously installed, that it is starting and at the same time, provides the address of a lock. This lock must be set (incremented) by subsystems higher in the hierarchy whenever they wish to run one of their own tasks. This flag must be set for each subsystem lower on the hierarchy, for example, when subsystem A is about to start Task 2A, the dispatcher must set subsystem B inhibit and subsystem C inhibit.

### **Subsystem Startup and Lockout**

In order for multiple subsystems to cooperate, there must be communication between subsystems when a subsystem is loaded into storage and initialized.

The subsystem being loaded tells the previously loaded subsystems that it is being loaded and broadcasts the address of its synchronization lock. Higher priority subsystems use this lock to exclude the new subsystem from accessing any system resources (DOS, interrupts, etc.).

After a subsystem is loaded, it must "listen" for any subsystems that may be loaded later so that it can lock them out when it is running. The following describes the code sequence for startup.

### Startup Interface

**MOV AX,SEG SYSLOCK** ;segment of lock

**MOV ES,AX** --

**MOV BX,OFFSET SYSLOCK** ;offset of lock

**MOV AX,2000H** ;AH=20H, AL=0

**INT 15H** --

### Lockout Interface

The register ES:BX points to a byte which initially contains a value of 0. Whenever a higher priority subsystem wishes to run, it increments the lock. When it completes running, it decrements the lock. This allows proper synchronization of resources and subsystems.

### SYS REQ Key Functions

During initialization, the subsystem also needs to connect to the SYS REQ key function. It is necessary for the SYS key code to be included in each subsystem. This startup section determines if the SYS support is already loaded and loads the support if necessary.

The SYS functions provide a means for the subsystem's main screen or menu to be displayed. If the subsystem requires no user action, then these functions need not be provided.

### SYS Key Modes

There are two SYS key modes: multiple press and super shift.

**Multiple Press Mode:** This mode allows the user to sequence through subsystems. Subsystems are displayed in the reverse order of their installation.

**Super Shift Mode:** This mode allows the user direct access to any subsystem regardless of the priority. The user activates this mode by holding the SYS key pressed and pressing another key which designates another subsystem.

## Multiple Key Sequence

If a subsystem is to be used on the IBM Personal Computer and the IBM Personal Computer XT, a multiple key sequence must be used to access the SYS key functions.

## SYS Key Interfaces

There are four interfaces needed by the SYS code to support a subsystem: startup, activation, cancellation, and completion. The subsystem activates two of these: startup and completion. The SYS code in conjunction with user input activates the other two.

The following is a description, in tabular form, of the states, transitions, and actions needed to implement the SYS REQ functions.

## Subsystem Entry Points

subsys A	code A
subsys B	code B
subsys C	code C

## Entry Points

# subsystems    current subsystem #

num    cur

## State/Transition Table

Current State	Input	Next State	Action
Idle	SYS REQ	Active	activate subsys 'cur'
	SYS code	Active Super	activate subsys 'code'
	Startup	Idle	increment 'num' set 'cur' to 'num' insert entry point and code
Active	SYS REQ	Active	cancel subsys 'cur' decrement 'cur' activate subsys 'cur'
	Completion 'cur'	Idle	set 'cur' to 'num'
	Startup	Active	increment 'num' insert entry point and code
Active Super	SYS code	Active Super	activate subsys 'code'
	Completion 'cur'	Idle	set 'cur' to 'num'
	Startup	Active	increment 'num' insert entry point and code

## **Startup**

At startup, a call is issued to determine if the SYS REQ key support is already loaded and to initialize the support for the new subsystem.

The parameters for the startup routine are the address of the entry point and the function code (direct-access mode). If the operation was successful, the carry flag is set.

The following shows the calling sequence.

```
MOV AX,SEG entry_point ;address for SYS to call  
MOV ES,AX ;  
MOV BX,OFFSET entry_point ;  
MOV CX,XXXX ;super shift mode code  
MOV AX,2010H ;AH=20H, AL=10  
INT 15H ;
```

If the carry flag is not set, the initialization code needs to hook the vector for interrupt 15H, save the previous address, and reissue the initialization call.

## **Activation**

This is a signal from the SYS REQ processing module that a subsystem's monitor is to be activated.

This entry into the subsystem dispatcher signals that the monitor task should be activated. It should be treated as a signal to set a flag for the subsystem rather than an opportunity to gain control of the system asynchronously as it may not be a proper time for the subsystem to run. The subsystem may have to wait until a higher priority subsystem allows it to have control before the subsystem's monitor gets control. The subsystem entry point is CALLED with the AH register set to 0.

## Cancellation

This signal from the SYS REQ processing module tells the subsystem monitor to ignore the previous activation signal and take the necessary action to return to its previous state.

This entry into the subsystem dispatcher signals that the monitor task should be deactivated. The subsystem may not have control of the system. It is necessary for the subsystem to note that a cancellation has occurred and to wait until it has a valid opportunity to run through its dispatcher code in a normal fashion. The subsystem entry point is CALLED with the AH register set to 1.

## Completion

The following call signals completion. Completion constitutes any action taken by the user when the subsystem's menu is displayed.

This completion call causes the activation pointer to be reset to the lowest priority subsystem. All lower priority subsystems also receive a cancellation notification.

```
MOV AX,SEG entry_point      ;address for SYS to call  
MOV ES,AX                   ;  
MOV BX,OFFSET entry_point   ;ES:BX must contain the same  
                            ;values as the startup call  
MOV AX,2011H                 ;AH=20H, AL=11H  
INT 15H                     ;
```

# **Copy Protection**

Some modes of copy protection will not work on the IBM Personal Computer AT due to the following conditions:

- Bypassing BIOS
- Diskette drive differences
- Write current differences

## **Bypassing BIOS**

Copy protection, which depends on the following will not work on the IBM Personal Computer AT:

**Track Density:** The High Capacity Diskette Drive records tracks at a density of 96TPI. This drive has to double step in the 48TPI mode, which is performed by BIOS.

**Data Transfer Rate:** BIOS selects the proper data transfer rate for the media being used.

**Disk Base:** Copy protection, which creates its own disk base will not work on the High Capacity Diskette Drive.

## **Diskette Drive Differences**

Copy protection, which depends on the following will not work on the High Capacity Diskette Drive:

**Rotational Speed:** Copy protection using the time between two events on a diskette will not work on the High Capacity Diskette Drive.

**Access Time:** Diskette BIOS must set the track to track access time for the different types of media used on the IBM Personal Computer AT.

**Head Geometry:** See 'High Capacity Diskette Drive' earlier in this section.

**Diskette Change Signal:** Copy protection may not be able to reset this signal.

## Write Current

The IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter selects the proper write current for the media being used.

## Machine-Sensitive Code

Programs may program for machine specific features, but they must test for specific machine type. Location hex 0FFF:0E contains the machine identification:

Hex	Machine Identification
OFF	IBM Personal Computer
OFE	IBM Personal Computer XT
OFD	IBM PCjr
OFC	IBM Personal Computer AT

### Machine Identification Code

IBM will define methods for uniquely determining the specific machine type or I/O feature for any new device.

## **Notes:**

# Glossary

**$\mu$ .** Prefix micro; 0.000 001.

**$\mu s$ .** Microsecond; 0.000 001 second.

**A.** Ampere.

**ac.** Alternating current.

**accumulator.** A register in which the result of an operation is formed.

**active high.** Designates a signal that has to go high to produce an effect. Synonymous with positive true.

**active low.** Designates a signal that has to go low to produce an effect. Synonymous with negative true.

**adapter.** An auxiliary device or unit used to extend the operation of another system.

**address bus.** One or more conductors used to carry the binary-coded address from the processor throughout the rest of the system.

**algorithm.** A finite set of well-defined rules for the solution of a problem in a finite number of steps.

**all points addressable (APA).** A mode in which all points of a displayable image can be controlled by the user.

**alphameric.** Synonym for alphanumeric.

**alphanumeric (A/N).** Pertaining to a character set that contains letters, digits, and usually other characters, such as punctuation marks. Synonymous with alphameric.

**alternating current (ac).** A current that periodically reverses its direction of flow.

**American National Standard Code for Information Exchange (ASCII).** The standard code, using a coded character set consisting of 7-bit coded characters (8 bits including parity check), used for information exchange between data processing systems, data communication systems, and associated equipment. The ASCII set consists of control characters and graphic characters.

**ampere (A).** The basic unit of electric current.

**A/N.** Alphanumeric

**analog.** (1) Pertaining to data in the form of continuously variable physical quantities. (2) Contrast with digital.

**AND.** A logic operator having the property that if P is a statement, Q is a statement, R is a statement,..., then the AND of P, Q, R,...is true if all statements are true, false if any statement is false.

**AND gate.** A logic gate in which the output is 1 only if all inputs are 1.

**AND operation.** The boolean operation whose result has the boolean value 1, if and only if, each operand has the boolean value 1. Synonymous with conjunction.

**APA.** All points addressable.

**ASCII.** American National Standard Code for Information Exchange.

**assemble.** To translate a program expressed in an assembler language into a computer language.

**assembler.** A computer program used to assemble.

**assembler language.** A computer-oriented language whose instructions are usually in one-to-one correspondence with computer instructions.

**asynchronous transmission.** (1) Transmission in which the time of occurrence of the start of each character, or block of characters, is arbitrary; once started, the time of occurrence of each signal representing a bit within a character, or block, has the same relationship to significant instants of a fixed time frame. (2) Transmission in which each information character is individually transmitted (usually timed by the use of start elements and stop elements).

**audio frequencies.** Frequencies that can be heard by the human ear (approximately 15 hertz to 20 000 hertz).

**auxiliary storage.** (1) A storage device that is not main storage. (2) Data storage other than main storage; for example, storage on magnetic disk. (3) Contrast with main storage.

**BASIC.** Beginner's all-purpose symbolic instruction code.

**basic input/output system (BIOS).** The feature of the IBM Personal Computer that provides the level control of the major I/O devices, and relieves the programmer from concern about hardware device characteristics.

**baud.** (1) A unit of signaling speed equal to the number of discrete conditions or signal events per second. For example, one baud equals one bit per second in a train of binary signals, one-half dot cycle per second in Morse code, and one 3-bit value per second in a train of signals each of which can assume one of eight different states. (2) In asynchronous transmission, the unit of modulation rate corresponding to one unit of interval per second; that is, if the duration of the unit interval is 20 milliseconds, the modulation rate is 50 baud.

**BCC.** Block-check character.

**beginner's all-purpose symbolic instruction code (BASIC).** A programming language with a small repertoire of commands and a simple syntax, primarily designed for numeric applications.

**binary.** (1) Pertaining to a selection, choice, or condition that has two possible values or states. (2) Pertaining to a fixed radix numeration system having a radix of 2.

**binary digit.** (1) In binary notation, either of the characters 0 or 1. (2) Synonymous with bit.

**binary notation.** Any notation that uses two different characters, usually the binary digits 0 and 1.

**binary synchronous communications (BSC).** A uniform procedure, using a standardized set of control characters and control character sequences for synchronous transmission of binary-coded data between stations.

**BIOS.** Basic input/output system.

**bit.** Synonym for binary digit

**bits per second (bps).** A unit of measurement representing the number of discrete binary digits transmitted by a device in one second.

**block.** (1) A string of records, a string of words, or a character string formed for technical or logic reasons to be treated as an entity. (2) A set of things, such as words, characters, or digits, treated as a unit.

**block-check character (BCC).** In cyclic redundancy checking, a character that is transmitted by the sender after each message block and is compared with a block-check character computed by the receiver to determine if the transmission was successful.

**boolean operation.** (1) Any operation in which each of the operands and the result take one of two values. (2) An operation that follows the rules of boolean algebra.

**bootstrap.** A technique or device designed to bring itself into a desired state by means of its own action; for example, a machine routine whose first few instructions are sufficient to bring the rest of itself into the computer from an input device.

**bps.** Bits per second.

**BSC.** Binary synchronous communications.

**buffer.** (1) An area of storage that is temporarily reserved for use in performing an input/output operation, into which data is read or from which data is written. Synonymous with I/O area. (2) A portion of storage for temporarily holding input or output data.

**bus.** One or more conductors used for transmitting signals or power.

**byte.** (1) A sequence of eight adjacent binary digits that are operated upon as a unit. (2) A binary character operated upon as a unit. (3) The representation of a character.

**C.** Celsius.

**capacitor.** An electronic circuit component that stores an electric charge.

**CAS.** Column address strobe.

**cathode ray tube (CRT).** A vacuum tube in which a stream of electrons is projected onto a fluorescent screen producing a luminous spot. The location of the spot can be controlled.

**cathode ray tube display (CRT display).** (1) A CRT used for displaying data. For example, the electron beam can be controlled to form alphanumeric data by use of a dot matrix. (2) The data display produced by the device as in (1).

**CCITT.** International Telegraph and Telephone Consultative Committee.

**Celsius (C).** A temperature scale. Contrast with Fahrenheit (F).

**central processing unit (CPU).** Term for processing unit.

**channel.** A path along which signals can be sent; for example, data channel, output channel.

**character generator.** (1) In computer graphics, a functional unit that converts the coded representation of a graphic character into the shape of the character for display. (2) In word processing, the means within equipment for generating visual characters or symbols from coded data.

**character set.** (1) A finite set of different characters upon which agreement has been reached and that is considered complete for some purpose. (2) A set of unique representations called characters. (3) A defined collection of characters.

**characters per second (cps).** A standard unit of measurement for the speed at which a printer prints.

**check key.** A group of characters, derived from and appended to a data item, that can be used to detect errors in the data item during processing.

**closed circuit.** A continuous unbroken circuit; that is, one in which current can flow. Contrast with open circuit.

**CMOS.** Complementary metal oxide semiconductor.

**code.** (1) A set of unambiguous rules specifying the manner in which data may be represented in a discrete form. Synonymous with coding scheme. (2) A set of items, such as abbreviations, representing the members of another set. (3) To represent data or a computer program in a symbolic form that can be accepted by a data processor. (4) Loosely, one or more computer programs, or part of a computer program.

**coding scheme.** Synonym for code.

**collector.** An element in a transistor toward which current flows.

**column address strobe (CAS).** A signal that latches the column addresses in a memory chip.

**compile.** (1) To translate a computer program expressed in a problem-oriented language into a computer-oriented language. (2) To prepare a machine-language program from a computer program written in another programming language by making use of the overall logic structure of the program, or generating more than one computer instruction for each symbolic statement, or both, as well as performing the function of an assembler.

**complementary metal oxide semiconductor (CMOS).** A logic circuit family that uses very little power. It works with a wide range of power supply voltages.

**computer.** A functional unit that can perform substantial computation, including numerous arithmetic operations or logic operations, without intervention by a human operator during a run.

**computer instruction code.** A code used to represent the instructions in an instruction set. Synonymous with machine code.

**computer program.** A sequence of instructions suitable for processing by a computer.

**computer word.** A word stored in one computer location and capable of being treated as a unit.

**configuration.** (1) The arrangement of a computer system or network as defined by the nature, number, and the chief characteristics of its functional units. More specifically, the term configuration may refer to a hardware configuration or a software configuration. (2) The devices and programs that make up a system, subsystem, or network.

**conjunction.** Synonym for AND operation.

**contiguous.** Touching or joining at the edge or boundary; adjacent.

**control character.** A character whose occurrence in a particular context initiates, modifies, or stops a control operation.

**control operation.** An action that affects the recording, processing, transmission, or interpretation of data; for example, starting or stopping a process, carriage return, font change, rewind, and end of transmission.

**control storage.** A portion of storage that contains microcode.

**cps.** Characters per second.

**CPU.** Central processing unit.

**CRC.** Cyclic redundancy check.

**CRT.** Cathode ray tube.

**CRT display.** Cathode ray tube display.

**CTS.** Clear to send. Associated with modem control.

**cursor.** (1) In computer graphics, a movable marker that is used to indicate a position on a display. (2) A displayed symbol that acts as a marker to help the user locate a point in text, in a system command, or in storage. (3) A movable spot of light on the screen of a display device, usually indicating where the next character is to be entered, replaced, or deleted.

**cyclic redundancy check (CRC).** (1) A redundancy check in which the check key is generated by a cyclic algorithm. (2) A system of error checking performed at both the sending and receiving station after a block-check character has been accumulated.

**cylinder.** (1) The set of all tracks with the same nominal distance from the axis about which the disk rotates. (2) The tracks of a disk storage device that can be accessed without repositioning the access mechanism.

**daisy-chained cable.** A type of cable that has two or more connectors attached in series.

**data.** (1) A representation of facts, concepts, or instructions in a formalized manner suitable for communication, interpretation, or processing by human or automatic means. (2) Any representations, such as characters or analog quantities, to which meaning is, or might be assigned.

**data base.** A collection of data that can be immediately accessed and operated upon by a data processing system for a specific purpose.

**data processing system.** A system that performs input, processing, storage, output, and control functions to accomplish a sequence of operations on data.

**data transmission.** Synonym for transmission.

**dB.** Decibel.

**dBa.** Adjusted decibels.

**dc.** Direct current.

**debounce.** An electronic means of overcoming the make/break bounce of switches to obtain one smooth change of signal level.

**decibel.** (1) A unit that expresses the ratio of two power levels on a logarithmic scale. (2) A unit for measuring relative power.

**decoupling capacitor.** A capacitor that provides a low impedance path to ground to prevent common coupling between circuits.

**Deutsche Industrie Norm (DIN).** (1) German Industrial Norm. (2) The committee that sets German dimension standards.

**digit.** (1) A graphic character that represents an integer; for example, one of the characters 0 to 9. (2) A symbol that

represents one of the non-negative integers smaller than the radix. For example, in decimal notation, a digit is one of the characters 0 to 9.

**digital.** (1) Pertaining to data in the form of digits. (2) Contrast with analog.

**DIN.** Deutsche Industrie Norm.

**DIN connector.** One of the connectors specified by the DIN committee.

**DIP.** Dual in-line package.

**DIP switch.** One of a set of small switches mounted in a dual in-line package.

**direct current (dc).** A current that always flows in one direction.

**direct memory access (DMA).** A method of transferring data between main storage and I/O devices that does not require processor intervention.

**disable.** To stop the operation of a circuit or device.

**disabled.** Pertaining to a state of a processing unit that prevents the occurrence of certain types of interruptions. Synonymous with masked.

**disk.** Loosely, a magnetic disk unit.

**disk drive.** A mechanism for moving a disk pack and controlling its movements.

**disk pack.** A removable assembly of magnetic disks.

**diskette.** A thin, flexible magnetic disk and a semirigid protective jacket, in which the disk is permanently enclosed. Synonymous with flexible disk.

**diskette drive.** A mechanism for moving a diskette and controlling its movements.

**display.** (1) A visual presentation of data. (2) A device for visual presentation of information on any temporary character imaging device. (3) To present data visually. (4) See cathode ray tube display.

**display attribute.** In computer graphics, a particular property that is assigned to all or part of a display; for example, low intensity, green color, blinking status.

**DMA.** Direct memory access.

**dot matrix.** (1) In computer graphics, a two-dimensional pattern of dots used for constructing a display image. This type of matrix can be used to represent characters by dots. (2) In word processing, a pattern of dots used to form characters. This term normally refers to a small section of a set of addressable points; for example, a representation of characters by dots.

**dot printer.** Synonym for matrix printer.

**dot-matrix character generator.** In computer graphics, a character generator that generates character images composed of dots.

**DSR.** Data set ready. Associated with modem control.

**DTR.** In the IBM Personal Computer, data terminal ready. Associated with modem control.

**dual in-line package (DIP).** A widely used container for an integrated circuit. DIPs have pins in two parallel rows. The pins are spaced 1/10 inch apart. See also DIP switch.

**duplex.** (1) In data communication, pertaining to a simultaneous two-way independent transmission in both directions. (2) Contrast with half-duplex.

**duty cycle.** In the operation of a device, the ratio of on time to idle time. Duty cycle is expressed as a decimal or percentage.

**dynamic memory.** RAM memory using transistors and capacitors as the memory elements. This memory requires a refresh (recharge) cycle every few milliseconds. Contrast with static memory.

**EBCDIC.** Extended binary-coded decimal interchange code.

**ECC.** Error checking and correction.

**edge connector.** A terminal block with a number of contacts attached to the edge of a printed-circuit board to facilitate plugging into a foundation circuit.

**EIA.** Electronic Industries Association.

**electromagnet.** Any device that exhibits magnetism only while an electric current flows through it.

**enable.** To initiate the operation of a circuit or device.

**end of block (EOB).** A code that marks the end of a block of data.

**end of file (EOF).** An internal label, immediately following the last record of a file, signaling the end of that file. It may include control totals for comparison with counts accumulated during processing.

**end-of-text (ETX).** A transmission control character used to terminate text.

**end-of-transmission (EOT).** A transmission control character used to indicate the conclusion of a transmission, which may have included one or more texts and any associated message headings.

**end-of-transmission-block (ETB).** A transmission control character used to indicate the end of a transmission block of data when data is divided into such blocks for transmission purposes.

**EOB.** End of block.

**EOF.** End of file.

**EOT.** End-of-transmission.

**EPROM.** Erasable programmable read-only memory.

**erasable programmable read-only memory (EPROM).** A PROM in which the user can erase old information and enter new information.

**error checking and correction (ECC).** The detection and correction of all single-bit errors, plus the detection of double-bit and some multiple-bit errors.

**ESC.** The escape character.

**escape character (ESC).** A code extension character used, in some cases, with one or more succeeding characters to indicate by some convention or agreement that the coded representations following the character or the group of characters are to be interpreted according to a different code or according to a different coded character set.

**ETB.** End-of-transmission-block.

**ETX.** End-of-text.

**extended binary-coded decimal interchange code (EBCDIC).** A set of 256 characters, each represented by eight bits.

## **F. Fahrenheit.**

**Fahrenheit (F).** A temperature scale. Contrast with Celsius (C).

**falling edge.** Synonym for negative-going edge.

**FCC.** Federal Communications Commission.

**fetch.** To locate and load a quantity of data from storage.

**FF.** The form feed character.

**field.** (1) In a record, a specified area used for a particular category of data. (2) In a data base, the smallest unit of data that can be referred to.

**fixed disk.** In the IBM Personal Computer, synonym for disk drive.

**flag.** (1) Any of various types of indicators used for identification. (2) A character that signals the occurrence of some condition, such as the end of a word. (3) Deprecated term for mark.

**flexible disk.** Synonym for diskette.

**flip-flop.** A circuit or device containing active elements, capable of assuming either one of two stable states at a given time.

**font.** A family or assortment of characters of a given size and style; for example, 10 point Press Roman medium.

**foreground.** (1) In multiprogramming, the environment in which high-priority programs are executed. (2) On a color display screen, the characters as opposed to the background.

**form feed.** (1) Paper movement used to bring an assigned part of a form to the printing position. (2) In word processing, a function that advances the typing position to the same character position on a predetermined line of the next form or page.

**form feed character.** A control character that causes the print or display position to move to the next predetermined first line on the next form, the next page, or the equivalent.

**format.** The arrangement or layout of data on a data medium.

**frame.** (1) In SDLC, the vehicle for every command, every response, and all information that is transmitted using SDLC procedures. Each frame begins and ends with a flag. (2) In data transmission, the sequence of contiguous bits bracketed by and including beginning and ending flag sequences.

**g. Gram.**

**G.** (1) Prefix giga; 1 000 000 000. (2) When referring to computer storage capacity,  $1\ 073\ 741\ 824$ . ( $1\ 073\ 741\ 824 = 2$  to the 30th power.)

**gate.** (1) A combinational logic circuit having one output channel and one or more input channels, such that the output channel state is completely determined by the input channel states. (2) A signal that enables the passage of other signals through a circuit.

**Gb.**

1 073 741 824 bytes.

**general-purpose register.** A register, usually explicitly addressable within a set of registers, that can be used for different purposes; for example, as an accumulator, as an index register, or as a special handler of data.

**giga (G).** Prefix 1 000 000 000.

**gram (g).** A unit of weight (equivalent to 0.035 ounces).

**graphic.** A symbol produced by a process such as handwriting, drawing, or printing.

**graphic character.** A character, other than a control character, that is normally represented by a graphic.

**half-duplex.** (1) In data communication, pertaining to an alternate, one way at a time, independent transmission. (2) Contrast with duplex.

**hardware.** (1) Physical equipment used in data processing, as opposed to programs, procedures, rules, and associated documentation. (2) Contrast with software.

**head.** A device that reads, writes, or erases data on a storage medium; for example, a small electromagnet used to read, write, or erase data on a magnetic disk.

**hertz (Hz).** A unit of frequency equal to one cycle per second.

**hex.** Common abbreviation for hexadecimal.

**hexadecimal.** (1) Pertaining to a selection, choice, or condition that has 16 possible different values or states. These values or states are usually symbolized by the ten digits 0 through 9 and the six letters A through F. (2) Pertaining to a fixed radix numeration system having a radix of 16.

**high impedance state.** A state in which the output of a device is effectively isolated from the circuit.

**highlighting.** In computer graphics, emphasizing a given display group by changing its attributes relative to other display groups in the same display field.

**high-order position.** The leftmost position in a string of characters. See also most-significant digit.

**housekeeping.** Operations or routines that do not contribute directly to the solution of the problem but do contribute directly to the operation of the computer.

**Hz. Hertz**

**image.** A fully processed unit of operational data that is ready to be transmitted to a remote unit; when loaded into control storage in the remote unit, the image determines the operations of the unit.

**immediate instruction.** An instruction that contains within itself an operand for the operation specified, rather than an address of the operand.

**index register.** A register whose contents may be used to modify an operand address during the execution of computer instructions.

**indicator.** (1) A device that may be set into a prescribed state, usually according to the result of a previous process or on the occurrence of a specified condition in the equipment, and that usually gives a visual or other indication of the existence of the prescribed state, and that may in some cases be used to determine the selection among alternative processes; for example, an overflow indicator. (2) An item of data that may be interrogated to determine whether a particular condition has been satisfied in the execution of a computer program; for example, a switch indicator, an overflow indicator.

**inhibited.** (1) Pertaining to a state of a processing unit in which certain types of interruptions are not allowed to occur. (2) Pertaining to the state in which a transmission control unit or an audio response unit cannot accept incoming calls on a line.

**initialize.** To set counters, switches, addresses, or contents of storage to 0 or other starting values at the beginning of, or at prescribed points in, the operation of a computer routine.

**input/output (I/O).** (1) Pertaining to a device or to a channel that may be involved in an input process, and, at a different time, in an output process. In the English language, "input/output" may be

used in place of such terms "input/output data", "input/output signal", and "input/output terminals", when such usage is clear in a given context. (2) Pertaining to a device whose parts can be performing an input process and an output process at the same time. (3) Pertaining to either input or output, or both.

**instruction.** In a programming language, a meaningful expression that specifies one operation and identifies its operands, if any.

**instruction set.** The set of instructions of a computer, of a programming language, or of the programming languages in a programming system.

**interface.** A device that alters or converts actual electrical signals between distinct devices, programs, or systems.

**interleave.** To arrange parts of one sequence of things or events so that they alternate with parts of one or more other sequences of the same nature and so that each sequence retains its identity.

**interrupt.** (1) A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed. (2) In a data transmission, to take an action at a receiving station that causes the transmitting station to terminate a transmission. (3) Synonymous with interruption.

**I/O.** Input/output.

**I/O area.** Synonym for buffer.

**irrecoverable error.** An error that makes recovery impossible without the use of recovery techniques external to the computer program or run.

**joystick.** In computer graphics, a lever that can pivot in all directions and that is used as a locator device.

**k.** Prefix kilo; 1000.

**K.** When referring to storage capacity, 1024. (1024 = 2 to the 10th power.)

**Kb.** 1024 bytes.

**kg.** Kilogram; 1000 grams.

**kHz.** Kilohertz; 1000 hertz.

**kilo (k).** Prefix 1000

**kilogram (kg).** 1000 grams.

**kilohertz (kHz).** 1000 hertz

**latch.** (1) A simple logic-circuit storage element. (2) A feedback loop in sequential digital circuits used to maintain a state.

**least-significant digit.** The rightmost digit. See also low-order position.

**LED.** Light-emitting diode.

**light-emitting diode (LED).** A semiconductor device that gives off visible or infrared light when activated.

**load.** In programming, to enter data into storage or working registers.

**low power Schottky TTL.** A version (LS series) of TTL giving a good compromise between low power and high speed. See also transistor-transistor logic and Schottky TTL.

**low-order position.** The rightmost position in a string of characters. See also least-significant digit.

**m.** (1) Prefix milli; 0.001. (2) Meter.

**M.** (1) Prefix mega; 1 000 000. (2) When referring to computer storage capacity, 1 048 576. (1 048 576 = 2 to the 20th power.)

**mA.** Milliampere; 0.001 ampere.

**machine code.** The machine language used for entering text and program instructions onto the recording medium or into storage and which is subsequently used for processing and printout.

**machine language.** (1) A language that is used directly by a machine. (2) Deprecated term for computer instruction code.

**magnetic disk.** (1) A flat circular plate with a magnetizable surface layer on which data can be stored by magnetic recording. (2) See also diskette.

**main storage.** (1) Program-addressable storage from which instructions and other data can be loaded directly into registers for subsequent execution or processing. (2) Contrast with auxiliary storage.

**mark.** A symbol or symbols that indicate the beginning or the end of a field, of a word, of an item of data, or of a set of data such as a file, a record, or a block.

**mask.** (1) A pattern of characters that is used to control the retention or elimination of portions of another pattern of characters. (2) To use a pattern of characters to control the retention or elimination of portions of another pattern of characters.

**masked.** Synonym for disabled.

**matrix.** (1) A rectangular array of elements, arranged in rows and columns, that may be manipulated according to the rules of matrix algebra. (2) In computers, a logic network in the form of an array of input leads and output leads with logic elements connected at some of their intersections.

**matrix printer.** A printer in which each character is represented by a pattern of dots; for example, a stylus printer, a wire printer. Synonymous with dot printer.

**Mb.** 1 048 576 bytes.

**mega (M).** Prefix 1 000 000.

**megahertz (MHz).** 1 000 000 hertz.

**memory.** Term for main storage.

**meter (m).** A unit of length (equivalent to 39.37 inches).

**MFM.** Modified frequency modulation.

**MHz.** Megahertz; 1 000 000 hertz.

**micro ( $\mu$ ).** Prefix 0.000 001.

**microcode.** (1) One or more microinstructions. (2) A code, representing the instructions of an instruction set, implemented in a part of storage that is not program-addressable.

**microinstruction.** (1) An instruction of microcode. (2) A basic or elementary machine instruction.

**microprocessor.** An integrated circuit that accepts coded instructions for execution; the instructions may be entered, integrated, or stored internally.

**microsecond ( $\mu s$ ).** 0.000 001 second.

**milli (m).** Prefix 0.001.

**milliampere (mA).** 0.001 ampere.

**millisecond (ms).** 0.001 second.

**mnemonic.** A symbol chosen to assist the human memory; for example, an abbreviation such as "mpy" for "multiply".

**mode.** (1) A method of operation; for example, the binary mode, the interpretive mode, the alphanumeric mode. (2) The most frequent value in the statistical sense.

**modem (modulator-demodulator).** A device that converts serial (bit by bit) digital signals from a business machine (or data communication equipment) to analog signals that are suitable for transmission in a telephone network. The inverse function is also performed by the modem on reception of analog signals.

**modified frequency modulation (MFM).** The process of varying the amplitude and frequency of the 'write' signal. MFM pertains to the number of bytes of storage that can be stored on the recording media. The number of bytes is twice the number contained in the same unit area of recording media at single density.

**modulation.** The process by which some characteristic of one wave (usually high frequency) is varied in accordance with another wave or signal (usually low frequency). This technique is used in modems to make business-machine signals compatible with communication facilities.

**modulation rate.** The reciprocal of the measure of the shortest nominal time interval between successive significant instants of the modulated signal. If this measure is expressed in seconds, the modulation rate is expressed in baud.

**module.** (1) A program unit that is discrete and identifiable with respect to compiling, combining with other units, and loading. (2) A packaged functional hardware unit designed for use with other components.

**modulo check.** A calculation performed on values entered into a system. This calculation is designed to detect errors.

**monitor.** (1) A device that observes and verifies the operation of a data processing system and indicates any significant departure from the norm. (2) Software or hardware that observes, supervises, controls, or verifies the operations of a system.

**most-significant digit.** The leftmost (non-zero) digit. See also high-order position.

**ms.** Millisecond; 0.001 second.

**multiplexer.** A device capable of interleaving the events of two or more activities, or capable of distributing the events of an interleaved sequence to the respective activities.

**multiprogramming.** (1) Pertaining to the concurrent execution of two or more computer programs by a computer. (2) A mode of operation that provides for the interleaved execution of two or more computer programs by a single processor.

**n.** Prefix nano; 0.000 000 001.

**NAND.** A logic operator having the property that if P is a statement, Q is a statement, R is a statement,..., then the NAND of P, Q ,R,... is true if at least one statement is false, false if all statements are true.

**NAND gate.** A gate in which the output is 0 only if all inputs are 1.

**nano (n).** Prefix 0.000 000 001.

**nanosecond (ns).** 0.000 000 001 second.

**negative true.** Synonym for active low.

**negative-going edge.** The edge of a pulse or signal changing in a negative direction. Synonymous with falling edge.

**non-return-to-zero change-on-ones recording (NRZI).** A transmission encoding method in which the data terminal equipment changes the signal to the opposite state to send a binary 1 and leaves it in the same state to send a binary 0.

**non-return-to-zero (inverted) recording (NRZI).** Deprecated term for non-return-to-zero change-on-ones recording.

**NOR.** A logic operator having the property that if P is a statement, Q is a statement, R is a statement,..., then the NOR of P, Q, R,... is true if all statements are false, false if at least one statement is true.

**NOR gate.** A gate in which the output is 0 only if at least one input is 1.

**NOT.** A logical operator having the property that if P is a statement, then the NOT of P is true if P is false, false if P is true.

**NRZI.** Non-return-to-zero change-on-ones recording.

**ns.** Nanosecond; 0.000 000 001 second.

**NUL.** The null character.

**null character (NUL).** A control character that is used to accomplish media-fill or time-fill, and that may be inserted into or removed from, a sequence of characters without affecting the meaning of the sequence; however, the control of the equipment or the format may be affected by this character.

**odd-even check.** Synonym for parity check.

**offline.** Pertaining to the operation of a functional unit without the continual control of a computer.

**one-shot.** A circuit that delivers one output pulse of desired duration for each input (trigger) pulse.

**open circuit.** (1) A discontinuous circuit; that is, one that is broken at one or more points and, consequently, cannot conduct current. Contrast with closed circuit. (2) Pertaining to a no-load condition; for example, the open-circuit voltage of a power supply.

**open collector.** A switching transistor without an internal connection between its collector and the voltage supply. A connection from the collector to the voltage supply is made through an external (pull-up) resistor.

**operand.** (1) An entity to which an operation is applied. (2) That which is operated upon. An operand is usually identified by an address part of an instruction.

**operating system.** Software that controls the execution of programs; an operating system may provide services such as resource allocation, scheduling, input/output control, and data management.

**OR.** A logic operator having the property that if P is a statement, Q is a statement, R is a statement,..., then the OR of P, Q, R,...is true if at least one statement is true, false if all statements are false.

**OR gate.** A gate in which the output is 1 only if at least one input is 1.

**output.** Pertaining to a device, process, or channel involved in an output process, or to the data or states involved in an output process.

**output process.** (1) The process that consists of the delivery of data from a data processing system, or from any part of it. (2) The return of information from a data processing system to an end user, including the translation of data from a machine language to a language that the end user can understand.

**overcurrent.** A current of higher than specified strength.

**overflow indicator.** (1) An indicator that signifies when the last line on a page has been printed or passed. (2) An indicator that is set on if the result of an arithmetic operation exceeds the capacity of the accumulator.

**overrun.** Loss of data because a receiving device is unable to accept data at the rate it is transmitted.

**overvoltage.** A voltage of higher than specified value.

**parallel.** (1) Pertaining to the concurrent or simultaneous operation of two or more devices, or to the concurrent performance of two or more activities. (2) Pertaining to the concurrent or simultaneous occurrence of two or more related activities in multiple devices or channels. (3) Pertaining to the simultaneity of two or more processes. (4) Pertaining to the simultaneous processing of the individual parts of a whole, such as the bits of a character and the characters of a word, using separate facilities for the various parts. (5) Contrast with serial.

**parameter.** (1) A variable that is given a constant value for a specified application and that may denote the application. (2) A name in a procedure that is used to refer to an argument passed to that procedure.

**parity bit.** A binary digit appended to a group of binary digits to make the sum of all the digits either always odd (odd parity) or always even (even parity).

**parity check.** (1) A redundancy check that uses a parity bit. (2) Synonymous with odd-even check.

**PEL.** Picture element.

**personal computer.** A small home or business computer that has a processor and keyboard and that can be connected to a television or some other monitor. An optional printer is usually available.

**phototransistor.** A transistor whose switching action is controlled by light shining on it.

**picture element (PEL).** The smallest displayable unit on a display.

**polling.** (1) Interrogation of devices for purposes such as to avoid contention, to determine operational status, or to determine readiness to send or receive data. (2) The process whereby stations are invited, one at a time, to transmit.

**port.** An access point for data entry or exit.

**positive true.** Synonym for active high.

**positive-going edge.** The edge of a pulse or signal changing in a positive direction. Synonymous with rising edge.

**potentiometer.** A variable resistor with three terminals, one at each end and one on a slider (wiper).

**power supply.** A device that produces the power needed to operate electronic equipment.

**printed circuit.** A pattern of conductors (corresponding to the wiring of an electronic circuit) formed on a board of insulating material.

**printed-circuit board.** A usually copper-clad plastic board used to make a printed circuit.

**priority.** A rank assigned to a task that determines its precedence in receiving system resources.

**processing program.** A program that performs such functions as compiling, assembling, or translating for a particular programming language.

**processing unit.** A functional unit that consists of one or more processors and all or part of internal storage.

**processor.** (1) In a computer, a functional unit that interprets and executes instructions. (2) A functional unit, a part of another unit such as a terminal or a processing unit, that interprets and executes instructions. (3) Deprecated term for processing program. (4) See microprocessor.

**program.** (1) A series of actions designed to achieve a certain result. (2) A series of instructions telling the computer how to handle a problem or task. (3) To design, write, and test computer programs.

**programmable read-only memory (PROM).** A read-only memory that can be programmed by the user.

**programming language.** (1) An artificial language established for expressing computer programs. (2) A set of characters and rules with meanings assigned prior to their use, for writing computer programs.

**programming system.** One or more programming languages and the necessary software for using these languages with particular automatic data-processing equipment.

**PROM.** Programmable read-only memory.

**propagation delay.** (1) The time necessary for a signal to travel from one point on a circuit to another. (2) The time delay between a signal change at an input and the corresponding change at an output.

**protocol.** (1) A specification for the format and relative timing of information exchanged between communicating parties. (2) The set of rules governing the operation of functional units of a communication system that must be followed if communication is to be achieved.

**pulse.** A variation in the value of a quantity, short in relation to the time schedule of interest, the final value being the same as the initial value.

**radio frequency (RF).** An ac frequency that is higher than the highest audio frequency. So called because of the application to radio communication.

**radix.** (1) In a radix numeration system, the positive integer by which the weight of the digit place is multiplied to obtain the weight of the digit place with the next higher weight; for example, in the decimal numeration system the radix of each digit place is 10. (2) Another term for base.

**radix numeration system.** A positional representation system in which the ratio of the weight of any one digit place to the weight

of the digit place with the next lower weight is a positive integer (the radix). The permissible values of the character in any digit place range from 0 to one less than the radix.

**RAM.** Random access memory. Read/write memory.

**random access memory (RAM).** Read/write memory.

**RAS.** In the IBM Personal Computer, row address strobe.

**raster.** In computer graphics, a predetermined pattern of lines that provides uniform coverage of a display space.

**read.** To acquire or interpret data from a storage device, from a data medium, or from another source.

**read-only memory (ROM).** A storage device whose contents cannot be modified. The memory is retained when power is removed.

**read/write memory.** A storage device whose contents can be modified. Also called RAM.

**recoverable error.** An error condition that allows continued execution of a program.

**red-green-blue-intensity (RGBI).** The description of a direct-drive color monitor that accepts input signals of red, green, blue, and intensity.

**redundancy check.** A check that depends on extra characters attached to data for the detection of errors. See cyclic redundancy check.

**register.** (1) A storage device, having a specified storage capacity such as a bit, a byte, or a computer word, and usually intended for a special purpose. (2) A storage device in which specific data is stored.

**retry.** To resend the current block of data (from the last EOB or ETB) a prescribed number of times, or until it is entered correctly or accepted.

**reverse video.** A form of highlighting a character, field, or cursor by reversing the color of the character, field, or cursor with its background; for example, changing a red character on a black background to a black character on a red background.

**RF.** Radio frequency.

**RF modulator.** The device used to convert the composite video signal to the antenna level input of a home TV.

**RGBI.** Red-green-blue-intensity.

**rising edge.** Synonym for positive-going edge.

**ROM.** Read-only memory.

**ROM/BIOS.** The ROM resident basic input/output system, which provides the level control of the major I/O devices in the computer system.

**row address strobe (RAS).** A signal that latches the row address in a memory chip.

**RS-232C.** A standard by the EIA for communication between computers and external equipment.

**RTS.** Request to send. Associated with modem control.

**run.** A single continuous performance of a computer program or routine.

**schematic.** The representation, usually in a drawing or diagram form, of a logical or physical structure.

**Schottky TTL.** A version (S series) of TTL with faster switching speed, but requiring more power. See also transistor-transistor logic and low power Schottky TTL.

**SDLC.** Synchronous Data Link Control

**sector.** That part of a track or band on a magnetic drum, a magnetic disk, or a disk pack that can be accessed by the magnetic heads in the course of a predetermined rotational displacement of the particular device.

**SERDES.** Serializer/deserializer.

**serial.** (1) Pertaining to the sequential performance of two or more activities in a single device. In English, the modifiers serial and parallel usually refer to devices, as opposed to sequential and consecutive, which refer to processes. (2) Pertaining to the sequential or consecutive occurrence of two or more related activities in a single device or channel. (3) Pertaining to the sequential processing of the individual parts of a whole, such as the bits of a character or the characters of a word, using the same facilities for successive parts. (4) Contrast with parallel.

**serializer/deserializer (SERDES).** A device that serializes output from, and deserializes input to, a business machine.

**setup.** (1) In a computer that consists of an assembly of individual computing units, the arrangement of interconnections between the units, and the adjustments needed for the computer to operate. (2) The preparation of a computing system to perform a job or job step. Setup is usually performed by an operator and often involves performing routine functions, such as mounting tape reels. (3) The preparation of the system for normal operation.

**short circuit.** A low-resistance path through which current flows, rather than through a component or circuit.

**signal.** A variation of a physical quantity, used to convey data.

**sink.** A device or circuit into which current drains.

**software.** (1) Computer programs, procedures, and rules concerned with the operation of a data processing system. (2) Contrast with hardware.

**source.** The origin of a signal or electrical energy.

**square wave.** An alternating or pulsating current or voltage whose waveshape is square.

**square wave generator.** A signal generator delivering an output signal having a square waveform.

**SS.** Start-stop.

**start bit.** (1) A signal to a receiving mechanism to get ready to receive data or perform a function. (2) In a start-stop system, a signal preceding a character or block that prepares the receiving device for the reception of the code elements.

**start-of-text (STX).** A transmission control character that precedes a text and may be used to terminate the message heading.

**start-stop system.** A data transmission system in which each character is preceded by a start bit and is followed by a stop bit.

**start-stop (SS) transmission.** (1) Asynchronous transmission such that a group of signals representing a character is preceded by a start bit and followed by a stop bit. (2) Asynchronous transmission in which a group of bits is preceded by a start bit that prepares the receiving mechanism for the reception and registration of a character and is followed by at least one stop bit that enables the receiving mechanism to come to an idle condition pending the reception of the next character.

**static memory.** RAM memory using flip-flops as the memory elements. Data is retained as long as power is applied to the flip-flops. Contrast with dynamic memory.

**stop bit.** (1) A signal to a receiving mechanism to wait for the next signal. (2) In a start-stop system, a signal following a character or block that prepares the receiving device for the reception of a subsequent character or block.

**storage.** (1) A storage device. (2) A device, or part of a device, that can retain data. (3) The retention of data in a storage device. (4) The placement of data into a storage device.

**strobe.** An instrument that emits adjustable-rate flashes of light. Used to measure the speed of rotating or vibrating objects.

**STX.** Start-of-text.

**symbol.** (1) A conventional representation of a concept or a representation of something by reason of relationship, association, or convention. (2) A representation of something by reason of relationship, association, or convention.

**synchronization.** The process of adjusting the corresponding significant instants of two signals to obtain the desired phase relationship between these instants.

**Synchronous Data Link Control (SDLC).** A protocol for management of data transfer over a data link.

**synchronous transmission.** (1) Data transmission in which the time of occurrence of each signal representing a bit is related to a fixed time frame. (2) Data transmission in which the sending and receiving devices are operating continuously at substantially the same frequency and are maintained, by means of correction, in a desired phase relationship.

**syntax.** (1) The relationship among characters or groups of characters, independent of their meanings or the manner of their

interpretation and use. (2) The structure of expressions in a language. (3) The rules governing the structure of a language. (4) The relationships among symbols.

**text.** In ASCII and data communication, a sequence of characters treated as an entity if preceded and terminated by one STX and one ETX transmission control character, respectively.

**time-out.** (1) A parameter related to an enforced event designed to occur at the conclusion of a predetermined elapsed time. A time-out condition can be cancelled by the receipt of an appropriate time-out cancellation signal. (2) A time interval allotted for certain operations to occur; for example, response to polling or addressing before system operation is interrupted and must be restarted.

**track.** (1) The path or one of the set of paths, parallel to the reference edge on a data medium, associated with a single reading or writing component as the data medium moves past the component. (2) The portion of a moving data medium such as a drum, or disk, that is accessible to a given reading head position.

**transistor-transistor logic (TTL).** A popular logic circuit family that uses multiple-emitter transistors.

**translate.** To transform data from one language to another.

**transmission.** (1) The sending of data from one place for reception elsewhere. (2) In ASCII and data communication, a series of characters including headings and text. (3) The dispatching of a signal, message, or other form of intelligence by wire, radio, telephone, or other means. (4) One or more blocks or messages. For BSC and start-stop devices, a transmission is terminated by an EOT character. (5) Synonymous with data transmission.

**TTL.** Transistor-transistor logic.

**V.** Volt.

**video.** Computer data or graphics displayed on a cathode ray tube, monitor, or display.

**volt.** The basic practical unit of electric pressure. The potential that causes electrons to flow through a circuit.

(  
W. Watt.

watt. The practical unit of electric power.

**word.** (1) A character string or a bit string considered as an entity. (2) See computer word.

**write.** To make a permanent or transient recording of data in a storage device or on a data medium.

**write precompensation.** The varying of the timing of the head current from the outer tracks to the inner tracks of the diskette to keep a constant 'write' signal.

# **Notes:**

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- 80287 Support Library Reference Manual
  - INTEL Corporation. *122129*
- National Semiconductor Corporation. *NS16450*
- Motorola Microprocessor's Data Manual
  - Motorola Inc. *Series B*

## **Notes:**

# Index

## A

AAA 6-8  
AAD 6-9  
AAM 6-9  
AAS 6-9  
access time, track-to-track 9-22  
ADC 6-6  
ADD 6-6  
additional ROM modules 5-12  
address generation, DMA 1-13  
address latch enable 1-26  
address latch enable, buffered 1-23  
address mode  
    real 1-4  
address space, I/O 1-15  
address, segment 1-4  
addresses, CMOS RAM 1-45  
addresses, page register 1-13  
AEN 1-23, 1-26  
ALE 9-3  
alternate key 5-19  
AND 6-10  
APL 9-5  
application guidelines 9-5  
arithmetic instructions 6-6, 6-27  
ARPL 6-22  
ASCII, extended 5-12

## B

BALE 1-22, 1-23  
bandwith 1-7  
BASIC 9-5  
basic assurance test 4-4  
BASIC interrupts 5-6  
BAT 4-4  
battery connector 1-58  
BHE 1-13  
BIOS fixed disk parameters 1-51  
BIOS memory map 5-10  
BIOS programming hints 5-10  
block diagram  
    keyboard interface 1-38  
    system xv  
    system board 1-6  
    system timer 1-9  
board, system 1-3  
BOUND 6-19  
break code 4-4, 4-10  
break key 5-19  
buffer, keyboard 4-3  
buffered address latch enable 1-23  
buffers, video display 9-10  
bus controller 1-23  
bus cycle 1-7  
busy loop 9-11  
bypassing BIOS 9-22  
byte high enable 1-13

## C

CALL 6-14  
cancellation, multi-tasking 9-21  
capacitor, variable 1-31  
caps lock key 5-19  
CBW 6-10

channel, I/O 1-15  
channels, DMA 1-7, 1-12, 1-15  
character codes 5-13  
classes, wait loop 9-13  
CLC 6-19  
CLD 6-20  
CLI 6-20  
CLK 1-22  
clock  
    real-time 1-45  
clock cycle 1-7  
clock line, keyboard 1-43, 4-5, 4-14, 4-15  
clock, system 1-22  
CMC 6-19  
CMOS RAM 1-45  
CMOS RAM addresses 1-45  
CMOS RAM configuration 1-48  
CMOS RAM I/O operations 1-54  
CMP 6-8  
CMPS 6-12, 6-13  
COBAL 9-5  
code  
    device driver 9-11  
    machine identification 9-23  
    machine-sensitive 9-23  
codes  
    character 5-13  
    extended 5-17  
    multi-tasking function 9-11  
color burst signal 1-31  
command codes, DMA controller 1-14  
commands  
    I/O 9-8  
    keyboard 4-12  
    keyboard controller 1-40  
    keyboard system 4-5  
comparison instructions 6-25  
compatibility, hardware 9-3  
completion, multi-tasking 9-21  
condition, wait 9-12  
configuration record 1-45  
configuration, CMOS RAM 1-48

connectors  
    battery 1-58  
    I/O channel 1-15, 1-17, 1-18, 1-19  
    keyboard 1-58, 4-23  
    power LED and keylock 1-58  
    power supply 1-57  
    power supply output 3-6  
    speaker 1-57  
    system board 1-57  
constants instructions 6-26  
control  
    game 9-10  
    sound 9-10  
control key 5-19  
control transfer instructions 6-13  
controller, keyboard 1-31  
controllers  
    bus 1-23  
    DMA 1-7, 1-12, 1-13, 1-22  
    interrupt 1-10  
    refresh 1-7  
controls, math coprocessor 1-29  
coprocessor programming 2-3  
coprocessor, math 2-3  
copy protection 9-11, 9-22  
Ctrl state 5-17  
CTS 6-20  
CWD 6-10  
cycle  
    bus 1-7  
    clock 1-7  
    microprocessor 1-7

## D

DACK0-DACK3 1-26  
DACK5-DACK7 1-26  
DAS 6-9  
data area, ROM BIOS 9-10  
data communication equipment 8-3  
data input, keyboard 4-15

data line, keyboard 1-43, 4-5, 4-14, 4-15  
data output, keyboard 4-15  
data stream 4-14  
data terminal equipment 8-3  
data transfer instructions 6-3, 6-24  
data transfer rate, diskette 9-22  
DEC 6-8  
decodes, memory 1-22, 1-23  
default segment workspace 5-9  
descriptors 1-5  
device driver code 9-11  
diagnostic checkpoint port 1-29  
direct memory access 1-12  
disk pointer 9-8  
disk\_base 9-8, 9-22  
diskette change signal 9-23  
diskette data transfer rate 9-22  
diskette rotational speed 9-22  
diskette track density 9-22  
diskette write current 9-23  
DIV 6-9  
divide error exception 9-7  
DMA 1-12  
DMA address generation 1-13  
DMA channels 1-7, 1-12, 1-15  
DMA controller 1-7, 1-22  
DMA controller command codes 1-14  
DMA controller 1 1-12  
DMA controller 2 1-13  
DMA controllers 1-12  
DOS 9-6  
DOS function calls 9-7  
DOS interrupts 5-6  
DRQ0-DRQ3 1-25  
DRQ5-DRQ7 1-25  
dummy load 3-4

## **E**

EIA/CCITT 8-3  
encoding, keyboard 5-12  
ENTER 6-18  
ESC 6-20  
exception, divide error 9-7  
extended ASCII 5-12  
extended codes 5-17

## **F**

FABS 6-28  
FADD 6-27  
fan out 3-6  
FCHS 6-28  
FCLEX 6-30  
FCOM 6-25  
FCOMP 6-25  
FCOMPP 6-26  
FDECSTP 6-31  
FDIV 6-27  
FFREE 6-31  
FIFO 4-3  
FINCSTP 6-31  
FINT 6-29  
FLD 6-24  
FLDCW 6-30  
FLDENV 6-30  
FLDLG2 6-27  
FLDLN2 6-27  
FLDL2T 6-26  
FLDP1 6-26  
FLDZ 6-26  
FLD1 6-26  
FMUL 6-27  
FNOP 6-31  
FORTRAN 9-5

FPATAN 6-29  
FPREM 6-28  
FPTAN 6-29  
French keyboard 4-19  
FRNDINT 6-28  
FRSTOR 6-30  
FSAVE 6-30  
FSCALE 6-28  
FSETPM 6-29  
FSQRT 6-28  
FST 6-24  
FSTCW 6-30  
FSTENV 6-30  
FSTP 6-25  
FSTSW 6-30  
FSTSWAX 6-30  
FSUB 6-27  
FTST 6-26  
function calls, DOS 9-7  
function codes, multi-tasking 9-14  
FXAM 6-26  
FXCH 6-25  
FXTRACT 6-28  
FYL2X 6-29  
FYL2XP1 6-29  
F2XM1 6-29

## G

game control 9-10  
gap length parameter 9-9  
generator, refresh request 1-8  
German keyboard 4-20  
graphics modes 5-8  
guidelines, application 9-5

# H

hard code 5-10  
hardware compatibility 9-3  
hardware interrupts 5-6  
HLT 6-20  
hooks 9-11



# I

I/O address map 1-28  
I/O address space 1-15  
I/O CH CK 1-23, 1-30  
I/O CH RDY 1-24  
I/O channel 1-15  
I/O channel check 1-23  
I/O channel connectors 1-15, 1-17, 1-18, 1-19  
I/O channel ready 1-24  
I/O channel signals 1-22  
I/O chip select 1-27  
I/O commands 9-7  
I/O CS16 1-27  
I/O ports, keyboard controller 1-43  
I/O read 1-24  
I/O write 1-24  
IDIV 6-9  
IIMUL 6-9  
IMR 9-10  
IMUL 6-9  
IN 6-5  
INC 6-7  
inhibit keyboard 1-37  
input buffer, keyboard controller 1-40  
input port, keyboard controller 1-44  
input requirements 3-3  
inputs, power supply 3-3  
INS 6-12, 6-13



instructions  
    arithmetic 6-6, 6-27  
    comparison 6-25  
    constants 6-26  
    control transfer 6-13  
    data transfer 6-3, 6-24  
    logic 6-10  
    processor control 6-19  
    protection control 6-21  
    shift rotate 6-10  
    string manipulation 6-12

INT 6-18

interface, keyboard 4-3

interfaces, multi-tasking 9-12

interfaces, SYS code 9-18

interrupt controller 1-10

interrupt mask register 9-10

interrupt service routine 1-24

interrupt vectors 9-10

interrupt, single step 9-7

interrupts 1-15, 5-5  
    BASIC 5-6  
    DOS 5-6  
    hardware 5-6  
    program 5-3  
    system 1-10

INTO 6-19

IOR 1-24

IOW 1-24

IRET 6-19

IRQ 2 9-8

IRQ 9 9-4, 9-8

IRQ14-IRQ15 1-24

IRQ3-IRQ7 1-24

IRQ9 1-24

Italian keyboard 4-21

## J

JB/JNAE 6-16  
JBE/JNA 6-16

JCXZ 6-18  
JE/JZ 6-16  
JL/JNGE 6-16  
JLE/JNG 6-16  
JMP 6-14  
JNB/JAE 6-17  
JNBE/JA 6-17  
JNE/JNZ 6-16  
JNL/JGE 6-17  
JNLE/JG 6-17  
JNO 6-17  
JNP/JPO 6-17  
JNS 6-17  
JO 6-16  
joystick support 5-6  
JP/JPE 6-16  
JS 6-16  
jumper, RAM 1-30

## K

key scan codes 4-10  
keyboard  
    buffer 4-3  
    clock line 1-43, 4-5, 4-14, 4-15  
    commands 4-12  
    connector 1-58, 4-23  
    controller 1-31  
    controller commands 1-40  
    controller I/O ports 1-43  
    controller input buffer 1-40  
    controller input port 1-44  
    controller output buffer 1-40  
    controller output port 1-44  
    controller status register 1-38  
    controller test input port 1-44  
    data input 4-15  
    data line 1-43, 4-5, 4-14, 4-15  
    data output 4-15  
    encoding 5-12

inhibit switch 1-37  
interface 4-3  
interface block diagram 1-38  
layout 1-33, 4-10, 5-14  
outputs 4-10  
routine 5-21  
specifications 4-23  
system commands 4-5  
keyboard, French 4-19  
keyboard, German 4-20  
keyboard, Italian 4-21  
keyboard, Spanish 4-22  
keyboard, U.K. English 4-18  
keyboard, U.S. English 4-17  
keylock 4-3  
keys 4-3  
    alternate 5-19  
    break 5-19  
    caps lock 5-19  
    combinations 5-20  
    control 5-19  
    number lock 5-20  
    pause 5-19  
    print screen 5-19  
    scroll lock 5-20  
    shift 5-18  
    SYS REQ 9-15  
    system request 5-6, 5-20  
keys, typematic 4-4

## L

LAHF 6-6  
LAR 6-22  
layout system board 1-60  
layout, keyboard 1-33, 4-10, 5-14  
LA17-LA23 1-22  
LDS 6-5  
LEA 6-5  
LEAVE 6-18

LED 4-4  
LES 6-6  
LGDT 6-21  
LIDT 6-21  
light emitting diodes 4-4  
line contention 4-15  
line, multipoint 8-5  
line, point-to-point 8-5  
LLDT 6-21  
LMSW 6-22  
load current 3-3  
LOCK 6-20  
LODS 6-12, 6-13  
logic instructions 6-10  
LOOP 6-17  
loop, busy 9-12  
LOOPNZ/LOOPNE 6-18  
loops, program 9-10  
LOOPZ/LOOPE 6-18  
LSL 6-22  
LTR 6-21

## M

machine identification code 9-23  
machine-sensitive code 9-23  
make code 4-3, 4-10  
mask off 1-29  
mask on 1-29  
master 1-26  
math coprocessor 2-3, 9-6  
math coprocessor controls 1-29  
MEM chip select 1-27  
MEM CS16 1-27  
memory 1-4  
memory decodes 1-22, 1-23  
memory locations, reserved 5-9  
memory map, BIOS 5-10  
MEMR 1-25  
MEMW 1-25

microprocessor 1-3, 1-4, 1-7  
microprocessor cycle 1-7  
modes, graphic 5-8  
modules, RAM 1-12  
modules, ROM/EPROM 1-11  
MOV 6-3  
MOVS 6-12, 6-13  
MUL 6-9  
multi-tasking  
    cancellation 9-21  
    completion 9-21  
    function codes 9-14  
    interfaces 9-12  
    provisions 9-11  
    serialization 9-12  
    startup 9-12, 9-20  
    subsystems 9-16  
multipoint line 8-5

## N

NEG 6-8  
network, nonswitched 8-5  
network, switched 8-5  
NMI 1-10, 1-29  
no load protection 3-5  
non-maskable interrupt 1-29  
nonswitched network 8-5  
NOT 6-12  
Num Lock state 5-17  
number lock key 5-20

## O

operations, CMOS RAM I/O 1-54  
OR 6-11

OSC 1-27, 1-31  
oscillator 1-27  
OUT 6-5  
output buffer, keyboard controller 1-40  
output port, keyboard controller 1-44  
output protection 3-4  
output voltage sense levels 3-6  
output voltage sequencing 3-4  
outputs, keyboard 4-10  
outputs, power supply 3-3  
OUTS 6-13

## P

page register addresses 1-13  
parameter  
    gap length 9-9  
    passing 5-4  
    tables 9-8  
parameters, BIOS fixed disk 1-51  
PASCAL 9-5  
pause key 5-19  
performance, system 1-7  
point-to-point line 8-5  
POP 6-4  
POPA 6-4  
POPF 6-6, 9-6  
POR 4-4  
port, diagnostic checkpoint 1-29  
POST 9-12  
power good signal 3-5, 3-6  
power LED and keylock connector 1-58  
power on reset 4-4  
power supply  
    connectors 1-57  
    inputs 3-3  
    output connectors 3-6  
    outputs 3-3  
print screen key 5-19  
priorities, shift key 5-20

processor control instructions 6-19  
program interrupts 5-3  
program loops 9-11  
programming hints, BIOS 5-10  
programming, coprocessor 2-3  
protected mode 1-5, 5-6  
protection control instructions 6-21  
protection, no load 3-5  
provisions, multitasking 9-11  
**PUSH** 6-4  
**PUSH SP** 9-7  
**PUSHA** 6-4  
**PUSHF** 6-6

## R

**RAM** jumper 1-30  
**RAM** modules 1-12  
**RAM** subsystem 1-12  
**RAM, CMOS** 1-45  
rate, typematic 4-4, 4-7  
real address mode 1-4, 2-5  
real mode 5-3  
real-time clock 1-45  
record, configuration 1-45  
**refid=admod.virtual** 1-4  
**REFRESH** 1-26  
refresh controller 1-7  
refresh request generator 1-8  
regulation tolerance 3-3  
requirements, input 3-3  
reserved memory locations 5-9  
reserved scan codes 1-36  
**RESET DRV** 1-23  
reset, system 5-21  
**RET** 6-15  
**ROM BIOS** 9-7  
**ROM BIOS** data area 9-10  
ROM modules, additional 5-12  
ROM scan codes 5-12

ROM subsystem 1-11  
ROM/EPROM modules 1-11  
rotational, speed 9-22  
routine, interrupt service 1-24  
routine, keyboard 5-21  
RS-232 8-3

## S

SAHF 6-6  
SA0-SA19 1-22  
SBB 6-7  
SBHE 1-26  
scan code translation 1-32  
scan codes 4-12  
scan codes, key 4-10  
scan codes, ROM 5-12  
SCAS 6-12, 6-13  
scroll lock key 5-20  
SD)-(SD15 1-23  
segment address 1-4  
segments 1-4  
sense levels, output voltage 3-6  
sequencing, output voltage 3-4  
serialization, multi-tasking 9-12  
SGDT 6-21  
shift counts 9-7  
shift key 5-18  
shift key priorities 5-20  
shift rotate instructions 6-10  
Shift state 5-17  
shift states 5-18  
SIDT 6-21  
signals  
diskette change 9-23  
power good 3-5, 3-6  
system clock 9-3  
signals, I/O channels 1-22  
single step interrupt 9-7  
SLDT 6-21

SMEMR 1-25  
SMEMW 1-25  
SMSW 6-22  
sound control 9-10  
Spanish keyboard 4-22  
speaker 1-30  
speaker connector 1-57  
speaker tone generation 1-9  
special vectors 5-6  
specifications, keyboard 4-23  
startup, multi-tasking 9-12, 9-18  
states  
    Ctrl 5-17  
    Num Lock 5-17  
    Shift 5-17  
status register, keyboard controller 1-38  
STC 6-19  
STD 6-20  
STI 6-20  
STOS 6-12, 6-13  
STR 6-22  
string manipulation instructions 6-12  
SUB 6-7  
subsystem, RAM 1-12  
subsystem, ROM 1-11  
subsystems, multi-tasking 9-16  
support joystick 5-6  
switched network 8-5  
switches  
    keyboard inhibit 1-37  
    type of display 1-31  
SYS code interfaces 9-18  
SYS REQ key 9-15  
system BIOS usage 5-3  
system block diagram xv  
system board 1-3  
system board block diagram 1-6  
system board connectors 1-57  
system board layout 1-60  
system bus high enable 1-26  
system clock 1-22  
system clock signal 9-3  
system interrupts 1-10

system performance 1-7  
system request key 5-6, 5-20  
system reset 5-21  
system timer block diagram 1-9  
system timers 1-8

## T

T/C 1-26  
table, translation 1-34  
tables, parameter 9-8  
terminal count 1-26  
TEST 6-11  
test input port, keyboard controller 1-44  
timeouts 9-15  
timer/counter 1-9  
timer/counters 1-8  
timers, system 1-8  
tone generation, speaker 1-9  
track density, diskette 9-22  
track-to-track access time 9-22  
translation table 1-34  
translation, scan code 1-32  
tri-state 1-26  
type of display adapter switch 1-31  
typematic keys 4-4  
typematic rate 4-4, 4-7

## U

U.K. English keyboard 4-18  
U.S. English keyboard 4-17

# V

variable capacitor 1-31  
vectors, special 5-6  
VERR 6-22  
video display buffers 9-10  
virtual address mode 1-4, 2-5

# W

WAIT 6-20  
wait condition 9-12  
wait loop classes 9-13  
workspace, default segment 5-9  
write current, diskette 9-23

# X

XCHG 6-5  
XLAT 6-5  
XOR 6-11

# Z

zero wait state 1-27

# **Numerals**

0WS 1-27  
80286 1-3, 1-4, 1-7  
8042 1-31  
82288 1-23  
8237A-5 1-12  
8254-2 1-8  
8259A 1-10



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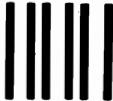
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