## ECE 514, Fall 2008

## Exam 3: Due 2pm at ECE front desk, December 5, 2008

Name:	75 mins.; Total 50 pts
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1. (12 pts.) Suppose that X represents the amount of money deposited into a bank account, and Y represents the amount of interest earned after a year. We don't have direct access to X and Y individually, but we can see the total account balance after a year, Z (so that Z = X + Y). We wish to estimate the vector [X,Y]' from Z (assuming X and Y are real-valued). Assume that X and Y are independent.

- a. Suppse that X and Y are exponentially distributed with mean 1 and 1/2, respectively. Find the LMMSE estimator. (The answer is a function of Z.)
- b. Suppose now that X and Y are Gaussian random variables, where the means are 1 and 1/2, respectively, and the variances are 1 and 1/4, respectively. Find the MMSE (conditional mean) estimator. (The answer is a function of Z.)
- c. Why can't we apply the ML rule studied in class to parts a or b?

- **2.** (12 pts.) Let  $X = [X_1, X_2]'$  represent a random vector, taking values in  $\mathbb{R}^2$ , with zero mean and correlation matrix  $R_X$ . We wish to design a storage system that only stores a single real random variable Y such that (1)  $Y = v'X = v_1X_1 + v_2X_2$ , (2) the variance of Y is 1, and (3) the reconstruction  $\hat{X} = uY$  is such that the mean-squared error  $\mathsf{E}[\|\hat{X} X\|^2]$  is minimized. (Both the vectors  $v = [v_1, v_2]'$  and  $u = [u_1, u_2]'$  need to be designed.)
  - a. First fix v and design u (in terms of v). In other words, given v, find the vector u such that  $E[\|\hat{X} X\|^2]$  is minimized. State explicitly how your answer depends on v and  $R_X$ .
  - b. Having optimized u in terms of v in part a, now find the optimal v. State explicitly how your answer depends on  $R_X$ . You may assume that the eigenvalues of  $R_X$  are distinct.

- **3.** (13 pts.) Consider the square-wave function s(t),  $t \in \mathbb{R}$ , taking values in  $\{1, -1\}$ , such that s(t) = 1 for  $t \in [0, 1)$ , s(t) = -1 for  $t \in [1, 2)$ , and so on. Note that s(t) is periodic with period 2. Let  $\Theta$  be a random variable uniformly distributed on [0, 1), and consider the random process  $X_t = s(t \Theta)$ .
  - a. For each fixed  $\tau$ , does  $E[X_tX_{t+\tau}]$  depend on t?
  - b. For each fixed t, is the function  $R(\tau) = \mathsf{E}[X_t X_{t+\tau}]$  periodic (as a function of  $\tau$ )? If it is, what is its period?
  - c. Compute  $R(\tau)$  for  $\tau \in [0, 1)$ .
  - d. Is  $\{X_t\}$  WSS? Justify fully.

**4.** (13 pts.) Consider a continuous-time random process  $X = \{X_t : t \in [0, T_X]\}$ , where  $T_X > 0$ . We cannot directly observe X. Instead, we wish to estimate X based on the observed process  $Y = \{Y_t : t \in [0, T_Y]\}$ , where  $T_Y > 0$ . The estimator we wish to derive is the linear minimum mean-squared error (Wiener) filter. In other words, we wish to find a function  $h : [0, T_X] \times [0, T_Y] \to \mathbb{R}$  (representing the Wiener filter) such that if we define

$$\hat{X}_t = \int_0^{T_Y} h(t, \tau) Y_\tau \, d\tau, \quad t \in [0, T_X],$$

then for all  $\tilde{h}:[0,T_X]\times[0,T_Y]\to\mathbb{R}$  with

$$\tilde{X}_t = \int_0^{T_Y} \tilde{h}(t,\tau) Y_\tau \, d\tau, \quad t \in [0, T_X],$$

we have

$$\mathsf{E}\left[\int_0^{T_X}|X_t-\hat{X}_t|^2\,dt\right] \le \mathsf{E}\left[\int_0^{T_X}|X_t-\tilde{X}_t|^2\,dt\right].$$

Assume that both X and Y are zero-mean (*not* necessarily WSS) and we know the autocorrelation functions  $R_X$  and  $R_Y$  and crosscorrelation function  $R_{XY}$ .

- a. Write down the *orthogonality principle* for this problem, involving an equation with h analogous to equations (8.11) and (10.33).
  - *Hint:* Think about what inner product is relevant here. For convenience, let M be the subspace of all processes  $\tilde{X} = {\tilde{X}_t : t \in [0, T_X]}$  as defined above (linear functions of Y).
- b. Prove the *orthogonality principle* for this problem: that the equation in part a is sufficient for *h* to be optimal.
  - Hint: Study the arguments in Sections 8.4 and 10.8.
- c. Use the equation in part a to derive an equation involving  $R_Y$ ,  $R_{XY}$ , and h (the Wiener filter), analogous to equations (8.9) and (10.36).
- d. Write down the value of the minimum mean-squared error  $\mathsf{E}[\int_0^{T_X} |X_t \hat{X}_t|^2 \, dt]$  in terms of  $h, R_X$ , and  $R_{XY}$ .
  - *Hint:* Look at the equation in Example 8.15. You may directly write down the analog of this involving integrals.