

Name: mohammed maher hassan

Id: 120170672

Eng: Nael Dokhan

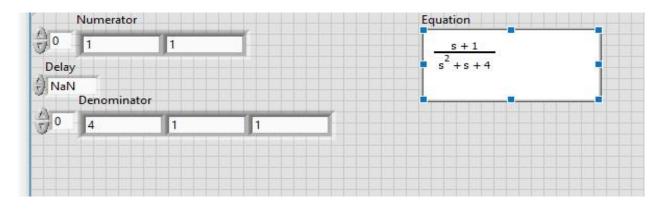
Lab 4

Q1: sol

matlab

Continuous-time transfer function.

Labview



2)

Matlab

```
>> num1 = [1 2];
den1 = [1 2 3];
num2 = [1 3];
den2 = [1 -4 1];
[num ,den] = series(num1,den1,num2,den2)
G= tf(num,den)

num =

0 0 1 5 6

den =

1 -2 -4 -10 3

G =

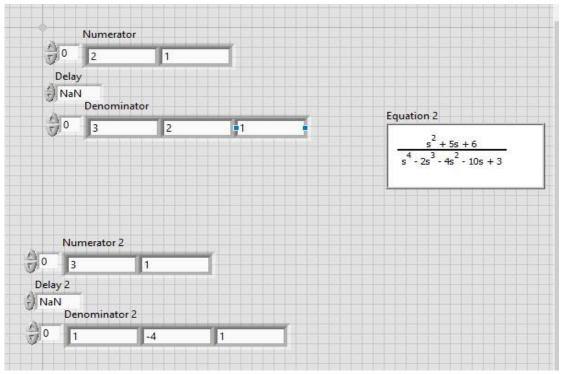
s^2 + 5 s + 6

s^4 - 2 s^3 - 4 s^2 - 10 s + 3

Continuous-time transfer function.

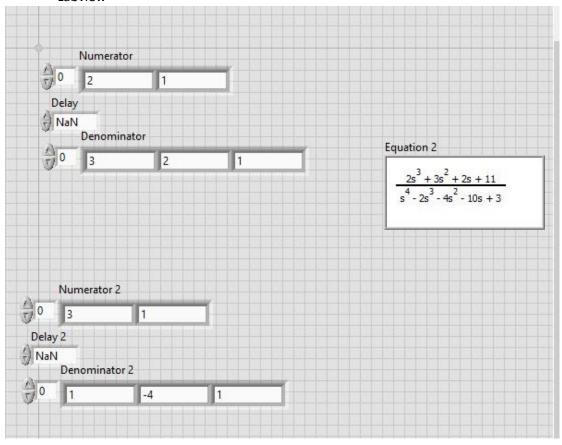
labview
```

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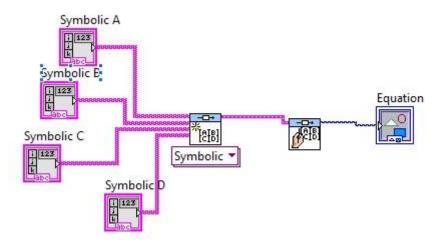


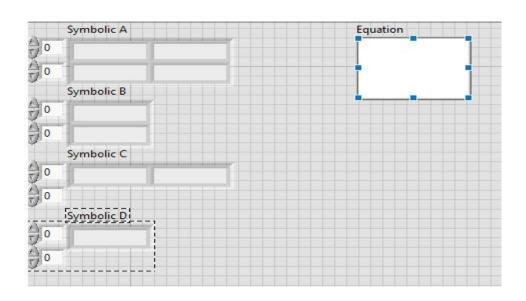
3)matlab

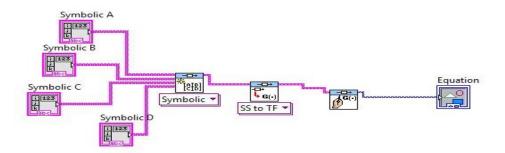
Labview

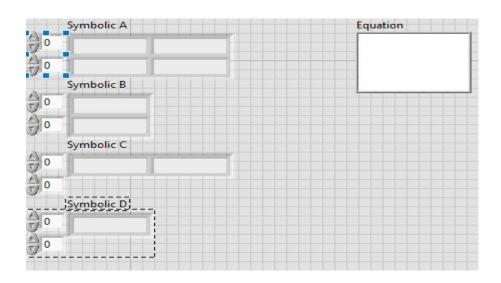


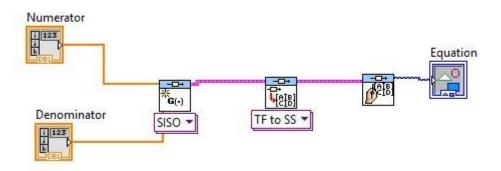
```
>> num1 =[1 2];
 den1 = [1 2 3];
 num2 = [1 3];
 den2 = [1 -4 1];
 [num ,den] = feedback(num1,den1,num2,den2,-1)
 printsys (num, den)
 num =
      0 1 -2 -7 2
 den =
      1 -2 -3 -5 9
 num/den =
        s^3 - 2 s^2 - 7 s + 2
    s^4 - 2 s^3 - 3 s^2 - 5 s + 9
ç >>
       Numerator
      Delay
     A NaN
        Denominator
                                          Equation 2
                                            s^3 - 2s^2 - 7s + 2
      Numerator 2
    0 3
    Delay 2
    NaN (
     Denominator 2
                -4
```

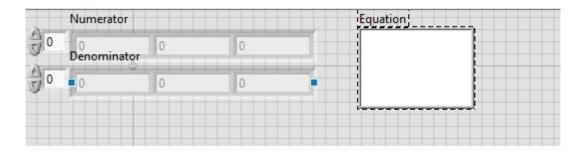






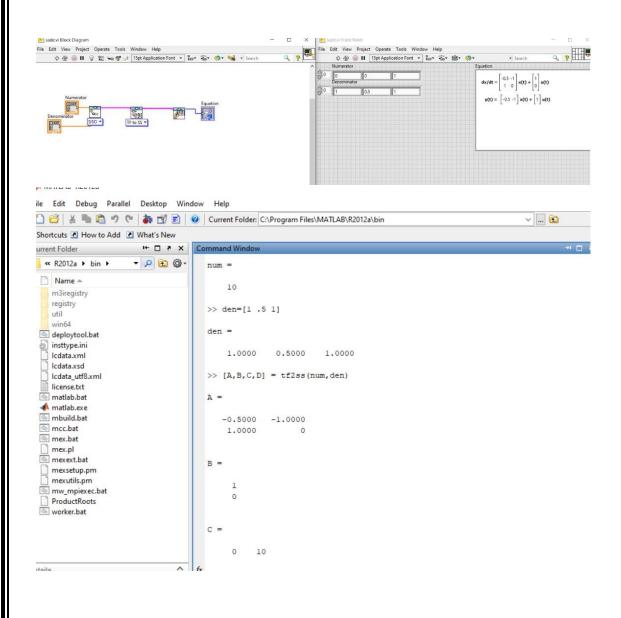






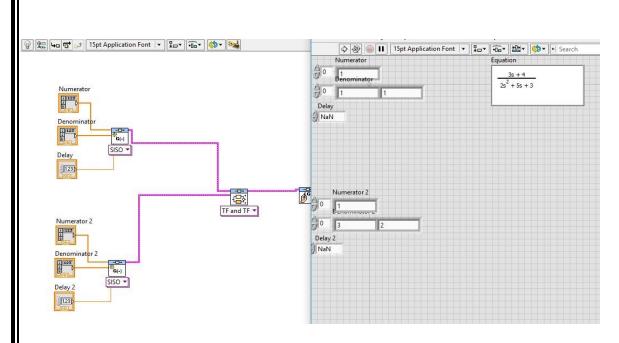
Q2:

Sol:

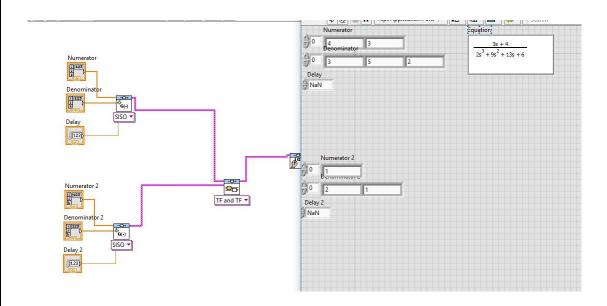


```
>> num1 =[1];den1 =[1 1];
 num2 = [1]; den2 = [2 3];
 [num3,den3] =parallel(num1,den1,num2,den2);
 G1 = tf(num3, den3);
 num3 = [3 \ 4]; den3 = [2 \ 5 \ 3];
 [num4, den4] =series(num3, den3, [1], [1 2]);
 [num, den] = feedback (num4, den4, [1], [1], 1);
 [num, den] = feedback(num, den, [1], [1], 1)
 printsys (num, den);
 G =tf2ss(num, den)
 num =
      0 0 3 4
 den =
      2 9 7 -2
 num/den =
            3s + 4
    2 s^3 + 9 s^2 + 7 s - 2
 G =
    -4.5000
              -3.5000
                        1.0000
     1.0000
              1.0000
                               0
x
          0
```

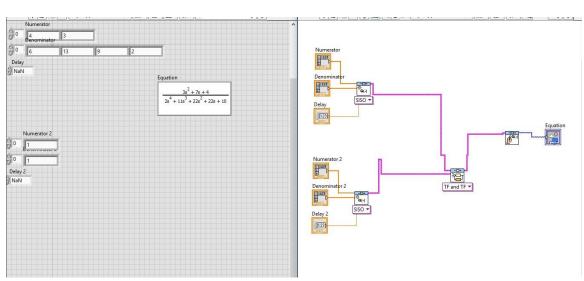
Step 1; parallel



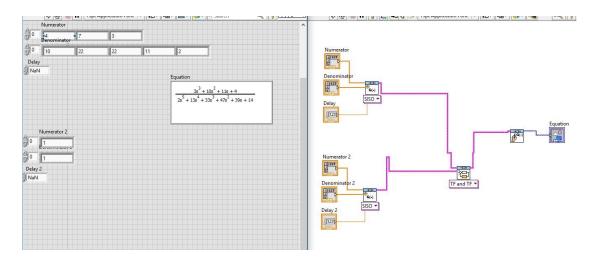
Step2; series

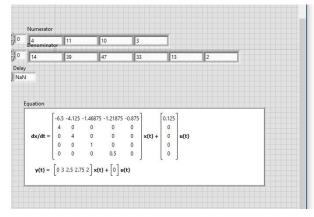


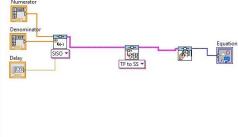
Step 3 :feedback

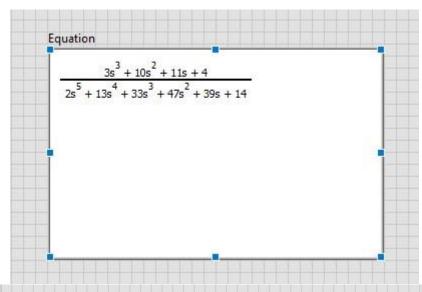


Step 4:feedback









Equation
$$\mathbf{dx/dt} = \begin{bmatrix} -6.5 & -4.125 & -1.46875 & -1.21875 & -0.875 \\ 4 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0.5 & 0 \end{bmatrix} \mathbf{x(t)} + \begin{bmatrix} 0.125 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \mathbf{u(t)}$$

$$\mathbf{y(t)} = \begin{bmatrix} 0 & 3 & 2.5 & 2.75 & 2 \end{bmatrix} \mathbf{x(t)} + \begin{bmatrix} 0 \end{bmatrix} \mathbf{u(t)}$$