Title	Visual	Narration
1.Start	Person with white cane walking Frame: only legs and cane visible (MidShot)	Audio: from video sound of footsteps and cane User comment about previous experience and the difficulty of finding locations
2. Transition		Audio: Sound of microphone Audio: Music starts
3. Introduction	-Robot at the entrance moving forward Fixed frame Wide shot -Change camera angle	-Ladies and gentlemen, welcome aboard Accessibility Robotics conference (name of the conference maybe accessibility conference). As our venue will differ from the ones you have previously attended, please give us your full attention as we demonstrate our guidance instructions (or capabilities). -Our accessibility crew understands how challenging finding specific locations in unknown environments can be, this is why our robot will be here to guide you throughout your journey with us. It will be easy to interact with, no training necessary
4. Pairing with the robot	User on phone main menu, open the app, check location of main station and pair with robot (Frame : Close up)	After arriving, ensure that the app is open and that you are paired with the robot. It will be waiting for you at a specific location near the entrance.
5. Choosing location	User chooses location from the app	Please choose the room of the session you want to attend, and it will guide you there. It has each room located in its map Sound from the app (voice-over)
6. User feedback	User image if available	Feedback about the ease of use of the app and the flexibility of the settings
7. Localizing the robot	User holding a phone, raising his head and turning around to the right orientation (to face the robot) Camera : Zoom out	The robot will be easy to find, press speak and it will emit a beep. Sound: beep from the robot
8. Localizing the user - A	Image of the robot camera Camera:Pan	Thanks to its advanced perception capabilities and fiducial tracking technology, it will be able to find you in the crowd.
9. Localizing the user - B	User looks at the phone then displays the QR code, hand towards the robot (robot not shown)	Now, take a moment to find the QR code in the app and display it.
10. Adjusting the height	Robot's torso moves up and down	Please place your phone at the height you want your arm to be, the height of the handle will adjust accordingly
11. Robot reaching the user	Robot adjusts orientation Robot moves forward	To face you, a specific algorithm will tell the robot how much to turn. To reach you, it will compute the distance and move closer to you
12. Robot-user contact - A	Robot moves hand towards user Camera:Pan	When close enough, the robot's arm will reach you.
13. Robot-user contact - B	User holds the handle - details of the handle shown Frame : Slow motion - Pan	Please hold our custom-made 3D-printed handle
14. Pressure sensor demonstration	User shows 3 positions on the handle (not touching, pressing normally, firmly pressing)	To ensure your safety, we have included a pressure sensor. Press normally to start the navigation. In case of an emergency, press more firmly or just take your hands off the handle.
15. Guidance preparation	Robot's arm goes to guiding position - user and robot shown	Before we take off, the robot will wait for a moment to make sure you are ready to follow it.
16. Path finding	Robot and user moving side by side Camera : follow the motion	It will compute the path to the chosen location
17. Speaking about obstacles	Robot facing an obstacle	In the event we encounter an obstacle, the robot will quietly announce it.
18. Arriving to location	Robot and user facing the door Camera : Pan from side to back	The robot will let you know once we arrive to destination. For your safety, it will wait for a moment until you leave or unpair.
19. User feedback	User image if available	Feedback about the ease of navigation
20. Selecting new destination	User using the app, screen shown	We remind you that you can reach the robot again whenever you need it, just specify your current location and your next destination
21. Autonomy message	Image of the robot Camera : zoom in	A. Robotics crew will be available if you need further assistance. But hopefully, you will be able to enjoy your autonomy with our robot.
22. User feedback	User image	Feedback about where else to use it
23. Instructions in the app	Show the app	Thank you for your attention, refer to the introduction instructions located on the app for more information
24. Introducing the team	Team members with names and roles displayed	All A. ROBOTICS crew members wish you a pleasant conference.
25. End	Logo	