Package 'MsdeParEst'

August 10, 2017

Type Package

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Description

Parametric estimation in mixed-effects stochastic differential equations

Details

This package is dedicated to parametric estimation in the following mixed-effects stochastic differential equations:

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j \ a(X_j(t))dW_j(t),$$

 $j=1,\ldots,M$, where the $(W_j(t))$ are independant Wiener processes and the $(X_j(t))$ are observed without noise. The volatility function a(x) is known and can be either a(x)=1 (Ornstein-Uhlenbeck process) or $a(x)=\sqrt{x}$ (Cox-Ingersoll-Ross process).

Different estimation methods are implemented depending on whether there are random effects in the drift and/or in the diffusion coefficient:

- 1. The diffusion coefficient is fixed $\sigma_j \equiv \sigma$ and the parameters in the drift are Gaussian random variables:
 - (a) either $\alpha_j \equiv \alpha$ and $\beta_j \sim N(\mu, \Omega), j = 1, \dots, M$,
 - (b) or $\beta_i \equiv \beta$ and $\alpha_i \sim N(\mu, \Omega), j = 1, \dots, M$,
 - (c) or $(\alpha_j, \beta_j) \sim N(\mu, \Omega), j = 1, \dots, M$.

 μ , Ω and potentially the fixed effects σ , α , β are estimated as proposed in [1] and [4]. The extension to mixtures of Gaussian distributions is also implemented by following [3].

2. The coefficients in the drift are fixed $\alpha_j \equiv \alpha$ and $\beta_j \equiv \beta$ and the diffusion coefficient $1/\sigma_j^2$ follows a Gamma distribution $1/\sigma_j^2 \sim \Gamma(a, \lambda), j = 1, \dots, M$. a, λ , and potentially the fixed effects α and β are estimated by the method published in [2].

bx 3

3. There are random effects in the drift and in the diffusion, such that $1/\sigma_j^2 \sim \Gamma(a,\lambda)$ and

- (a) either $\alpha_j \equiv \alpha$ and $\beta_j | \sigma_j \sim N(\mu, \sigma_j^2 \Omega)$,
- (b) or $\beta_j \equiv \beta$ and $\alpha_j | \sigma_j \sim N(\mu, \sigma_j^2 \Omega)$,
- (c) or $(\alpha_j, \beta_j) | \sigma_j \sim N(\mu, \sigma_j^2 \Omega)$.
- a, λ, μ, Ω and potentially the fixed effects α and β are estimated by following [5].

Some examples and more details on how to use the different functions of the package are available on the package's vignette by typing **vignette(''MsdeParEst'')** in the R console.

References

- [1] Maximum Likelihood Estimation for Stochastic Differential Equations with Random Effects, Delattre, M., Genon-Catalot, V. and Samson, A. *Scandinavian Journal of Statistics* 40(2) 2012 322-343.
- [2] Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, Delattre, M., Genon-Catalot, V. and Samson, A. *ESAIM:PS 19 2015* 671-688
- [3] Mixtures of stochastic differential equations with random effects: application to data clustering, Delattre, M., Genon-Catalot, V. and Samson, A. *Journal of Statistical Planning and Inference 173* 2016 109-124.
- [4] Parametric inference for discrete observations of diffusion processes with mixed effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *Stochastic Processes and their Applications*. To appear. (Available pre-publication hal-0133263, 2016).
- [5] Estimation of the joint distribution of random effects for a discretely observed diffusion with random effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01446063 2017*.

bx

Computation Of The Drift Coefficient

Description

Computation of the drift coefficient

Usage

bx(x)

Arguments

x vector of data

Value

b The drift is $b(x,\phi) = \phi_1 b_1(x) + \phi_2 b_2(x)$, the output is the vector $(b_1,b_2)^t$

4 class.pred-class

class.mixture.pred-class

S4 class for the parametric estimation results when the random effects in the drift follow mixture of normal distributions

Description

S4 class for the parametric estimation results when the random effects in the drift follow mixture of normal distributions

Slots

estim object of class Mixture.fit.class containing the results of the model estimation phipred numeric 1, 2, or c(1,2)

Xpred matrix of predicted trajectories (dimensions)

idexpred matrix of values on which the estimation of the density of the random effects is done

class.pred-class

S4 class for the estimation results in the mixed SDE with random effects in the drift, in the diffusion or both

Description

S4 class for the estimation results in the mixed SDE with random effects in the drift, in the diffusion or both

Slots

estim object of class Fit.class containing the results of the model estimation

phipred matrix of simulated values for the random effects in the drift that are used for prediction (dimensions)

Xpred matrix of simulated trajectories used for prediction (dimensions)

idexpred vector of indexes of the true trajectories that are used for prediction

contrastGamma 5

contrastGamma	Contrast based on the Euler approximation of the likelihood for parameter estimation when there is one random effect in the diffusion coefficient and no random effect in the drift
	coefficient and no random effect in the drift.

Description

Computation of the contrast based on the Euler approximation of -2 log-likelihood for the estimation of the mixed SDE:

$$dXj(t) = (\alpha - \beta X_j(t))dt + \sigma_j a(X_j(t))dW_j(t)$$

with Gamma distribution for $1/\sigma_j^2$ and fixed parameters in the drift.

Usage

```
contrastGamma(a, lambda, U, V, S, K, drift.fixed)
```

Arguments

а	value of the shape of the Gamma distribution.
lambda	value of the scape of the Gamma distribution.
U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
K	number of times of observations.
drift.fixed	values of the fixed effects in the drift.

Value

L value of the contrast

References

Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, M. Delattre, V. Genon-Catalot and A. Samson, *ESAIM: Probability and Statistics 2015*, Vol 19, **671 – 688**

Parametric inference for discrete observations of diffusion processes with mixed effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint 2016*, *hal-01332630*

6 contrastNormal

Description

Computation of the contrast used for the estimation of the parameters of the Gaussian conditional distribution of the random effects in the drift α_j, β_j when the SDE includes random effects in the drift and in the diffusion coefficient:

$$dXj(t) = (\alpha_j - \beta_j Xj(t))dt + \sigma_j a(Xj(t))dWj(t).$$

Usage

```
contrastNormal(mu, omega, U, V, S, K, estimphi, drift.random)
```

Arguments

mu	value of the mean of the Gaussian distribution.
omega	value of the standard deviation of the Gaussian distribution.
U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
K	number of times of observations.
estimphi	matrix of the M x 2 estimated parameters (α_j, β_j) .
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.

Value

L value of the contrast

References

Estimaton of the joint distribution of random effects for a discretely observed diffusion with random effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint, hal-01446063*.

discr 7

discr

Simulation Of Random Variables

Description

Simulation of (discrete) random variables from a vector of probability (the nonparametrically estimated values of the density renormalised to sum at 1) and a vector of real values (the grid of estimation)

Usage

```
discr(x, p)
```

Arguments

- x n real numbers
- p vector of probability, length n

Value

y a simulated value from the discrete distribution

ΕM

EM algorithm for mixtures of stochastic differential equations with random effects in the drift and a fixed effect in the diffusion coefficient

Description

EM algorithm for parameter estimation in the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma a(X_j(t))dW_j(t)$$

with random effects in the drift α_j , β_j following a mixture of Gaussian distributions.

Usage

```
EM(U, V, S, K, drift.random, start, Niter = 10, drift.fixed = NULL,
    sigma = NULL)
```

8 *EM*

Arguments

U matrix of M sufficient statistics U (see UVS).

V list of the M sufficient statistics matrix V (see UVS).

S vector of the M sufficient statistics S (see UVS).

K number of times of observations.

drift.random random effects in the drift: 1 if one additive random effect, 2 if one multiplica-

tive random effect or c(1,2) if 2 random effects.

start list of starting values: mu, omega, mixt.prop, respectively for the mean and

the standard deviation of the Gaussian distributions and the mixing proportions. mixt.prop is a vector of length N, where N stands for the number of mixture components. mu is a N x 2 matrix, first (resp. second) column is the mean of α_j (resp. β_j) if α_j (resp. β_j) is random, the fixed effect value otherwise. omega is a N x 2 matrix, the components corresponding to a fixed effect should be set to

0.

Niter number of iterations. Defaults to 10.

drift.fixed NULL if the fixed effects in the drift are estimated, vector of the N values of the

fixed effect otherwise. Default to NULL.

sigma value for the diffusion parameter if known (not estimated), NULL otherwise.

Defaults to NULL.

Value

mu estimated value of the mean at each iteration of the algorithm. Niter x N x 2

array.

omega estimated value of the standard deviation at each iteration of the algorithm. Niter

x N x 2 array.

mixt.prop estimated value of the mixture proportions at each iteration of the algorithm.

Niter x N matrix.

sigma value of the diffusion parameter.

probindi posterior component probabilites. M x N matrix.

BIChere BIC indicator

AIChere AIC indicator

References

Mixtures of stochastic differential equations with random effects: application to data clustering, M. Delattre, V. Genon-Catalot and A. Samson, *Journal of Statistical Planning and Inference 2016*, Vol 173, **109–124**

EstParamGamma 9

EstParamGamma	Estimation In Mixed Stochastic Differential Equations with fixed ef-
	fects in the drift and one random effect in the diffusion coefficient

Description

Parameter estimation of the mixed SDE with Gamma distribution of the diffusion random effect and fixed effects in the drift:

$$dXj(t)=(\alpha-\beta Xj(t))dt+\sigma_ja(Xj(t))dWj(t), 1/\sigma_j^2\sim\Gamma(a,lambda),$$
 done with likelihoodGamma.

Usage

```
EstParamGamma(U, V, S, SigDelta, K, drift.param = NULL)
```

Arguments

U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
SigDelta	vector of the M constant terms of the individual likelihood (see UVS).
K	number of times of observations.
drift.param	values of the fixed effects in the drift if know, NULL if the fixed effects are estimated. Defaults to NULL.

Value

mu	values of the fixed effects in the drift.
a	estimated value of the shape of the Gamma distribution.
lambda	estimated value of the scale of the Gamma distribution.
BIChere	BIC indicator.
AIChere	AIC indicator.

References

Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, M. Delattre, V. Genon-Catalot and A. Samson, *ESAIM: Probability and Statistics* 2015, Vol 19, **671 – 688**

10 EstParamNormal

EstParamNormal	Estimation In Mixed Stochastic Differential Equations with random
	effects in the drift and fixed effect in the diffusion coefficient

Description

Estimation of the parameters of the mixed SDE:

```
dX_j(t) = (\alpha_j - \beta_j X_j(t)) dt + \sigma a(X_j(t)) dW_j(t),
```

with Normal distribution of the random effects in the drift α_j, β_j and fixed parameter σ in the diffusion. Done with likelihoodNormal.

Usage

```
EstParamNormal(U, V, S, SigDelta = 0, K, drift.fixed = NULL, sigma = NULL,
    drift.random, discrete = 1)
```

Arguments

U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
SigDelta	vector of the M constant terms of the individual likelihood (see UVS). Required only if discrete = 1. Defaults to 0 .
K	number of times of observations.
drift.fixed	NULL if thz fixed effect in the drift is estimated, value of the fixed effect otherwise. Default to NULL.
sigma	value of the fixed effect in the diffusion if known (not estimated), NULL otherwise. Defaults to NULL.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.
discrete	1 for discrete observations, 0 otherwise. If discrete = 0, the exact likelihood associated with continuous observations is discretized. If discrete = 1, the likelihood of the Euler scheme of the mixed SDE is computed. Defaults to 1.

Value

mu	estimated value of the mean of the Normal distribution
omega	estimated value of the standard deviation of the Normal distribution
sigma	value of the diffusion coefficient
BIChere	BIC indicator
AIChere	AIC indicator

EstParamNormalGamma 11

References

Maximum likelihood estimation for stochastic differential equations with random effects, M. Delattre, V. Genon-Catalot and A. Samson, *Scandinavian Journal of Statistics* 2012, Vol 40, 322–343

EstParamNormalGamma Estimation In Mixed Stock

Estimation In Mixed Stochastic Differential Equations with random effects in the drift and in the diffusion coefficient

Description

Estimation of the parameters of the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t)$$

with Normal conditional distribution of the random effects in the drift $\alpha_j, \beta_j | \sigma_j \sim N(\mu, \sigma_j^2 \Omega)$ and the square root of an inverse Gamma distributed random effect in the diffusion $\sigma_j^2 \sim Gamma(a, \lambda)$.

Usage

EstParamNormalGamma(U, V, S, SigDelta, K, drift.random, drift.fixed = NULL)

Arguments

U matrix of M sufficient statistics U (see UVS).

V list of the M sufficient statistics matrix V (see UVS).

S vector of the M sufficient statistics S (see UVS).

SigDelta vector of the M constant terms of the individual likelihood (see UVS).

K number of times of observations.

drift.random random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or c(1,2) if 2 random effects.

drift.fixed NULL if the fixed effect(s) in the drift is (are) estimated, value of the fixed effect(s) otherwise. Default to NULL.

Value

mu estimated value of the mean of the Normal distribution
omega estimated value of the standard deviation of the Normal distribution
a estimated value of the shape of the Gamma distribution.
lambda estimated value of the scale of the Gamma distribution.
BIChere BIC indicator
AIChere AIC indicator

References

Estimaton of the joint distribution of random effects for a discretely observed diffusion with random effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint*, hal-01446063.

12 Fit.class-class

Fit.class-class	S4 class for the estimation results in the mixed SDE with random effects in the drift, in the diffusion or both

Description

S4 class for the estimation results in the mixed SDE with random effects in the drift, in the diffusion or both

Slots

```
model character 'OU' or 'CIR'
drift.random numeric 0, 1, 2, \text{ or } c(1,2)
diffusion.random numeric 0 or 1
gridf matrix of values on which the estimation of the density of the random effects in the drift is
gridg matrix of values on which the estimation of the density of the random effects in the diffusion
     is done
mu numeric estimator of the mean mu of the drift random effects
omega numeric estimator of the variance of the drift random effects
a numeric estimator of the shape of the Gamma distribution for the diffusion random effect
lambda numeric estimator of the scale of the Gamma distribution for the diffusion random effect
sigma2 numeric estimated value of \sigma^2 if the diffusion coefficient is not random
index index of the used trajectories
estimphi matrix of the estimator of the drift random effects
estimpsi2 vector of the estimator of the diffusion random effects \sigma_i^2
estimf estimator of the (conditional) density of \phi, matrix form
estimg estimator of the density of \phi, matrix form
estim.drift.fix 1 if the user asked for the estimation of fixed parameter in the drift
estim.diffusion.fix 1 if the user asked for the estimation of fixed diffusion coefficient
discrete 1 if the estimation is based on the likelihood of discrete observations, 0 otherwise
bic numeric bic
aic numeric aic
times vector of observation times, storage of input variable
X matrix of observations, storage of input variable
```

likelihoodGamma 13

likelihoodGamma	Computation of the Euler approximation of -2 log-likelihood when there is one random effect in the diffusion coefficient and fixed effects in the drift.
	v

Description

Computation of the Euler approximation of -2 log-likelihood of the mixed SDE:

$$dX_j j(t) = (\alpha - \beta X_j(t))dt + \sigma_j a(X_j(t))dW_j(t)$$

with inverse Gamma distribution for σ_j^2 and fixed parameters α,β in the drift.

Usage

```
likelihoodGamma(a, lambda, U, V, S, SigDelta, K, drift.fixed)
```

Arguments

a	value of the shape of the Gamma distribution.
lambda	value of the scape of the Gamma distribution.
U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
SigDelta	vector of the M constant terms of the individual likelihood (see $\ensuremath{UVS}\xspace).$
K	number of times of observations.
drift.fixed	values of the fixed effects in the drift.

Value

L value of -2 x log-likelihood

References

Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, M. Delattre, V. Genon-Catalot and A. Samson, *ESAIM: Probability and Statistics 2015*, Vol 19, **671 – 688**

Parametric inference for discrete observations of diffusion processes with mixed effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint 2016*, hal-01332630

14 likelihoodMixtureNormal

likelihoodMixtureNormal

Computation of the Log Likelihood in mixtures of Mixed Stochastic Differential Equations

Description

Computation of -2 log-likelihood the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma a(X_j(t))dW_j(t)$$

with random effects in the drift α_j , β_j following a mixture of Gaussian distributions.

Usage

```
likelihoodMixtureNormal(mu, omega, sigma, mixt.prop, U, V, S, K, estimphi,
    drift.random)
```

Arguments

mu	mean of the random effects. N x 2 matrix, first (resp. second) column is the mean of α_j (resp. β_j) in each mixture component if α_j (resp. β_j) is random, the fixed effect value otherwise.
omega	standard deviation of the random effects. N x 2 matrix, the components corresponding to a fixed effect should be set to 0 .
sigma	value of the diffusion parameter.
mixt.prop	vector of mixture proportions.
U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
K	number of times of observations.
estimphi	matrix of the estimators of the random effects in the drift.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplica-

tive random effect or c(1,2) if 2 random effects.

Value

L value of -2 x loglikelihood

References

Mixtures of stochastic differential equations with random effects: application to data clustering, M. Delattre, V. Genon-Catalot and A. Samson, *Journal of Statistical Planning and Inference 2016*, Vol 173, **109–124**

likelihoodNormal 15

1 3	Likelihood In Mixed Stochastic Differential fects in the drift and fixed effect in the diffu-
-----	---

Description

```
Computation of -2 log-likelihood of the mixed SDE
```

```
dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma a(X_j(t))dW_j(t)
```

with Normal distribution of the drift random effects α_j, β_j and fixed effect in the diffusion coefficient.

Usage

```
likelihoodNormal(mu, omega, sigma, U, V, S, SigDelta = 0, K, estimphi,
  drift.random, discrete = 1)
```

Arguments

mu	current value of the mean of the normal distribution.
omega	current value of the standard deviation of the normal distribution.
sigma	current value of the diffusion coefficient.
U	vector of the M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
SigDelta	vector of the M constant terms of the individual likelihood (see UVS). Required only if discrete = 1. Defaults to 0.
K	number of times of observations.
estimphi	matrix of estimators of the random effects.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.
discrete	1 for discrete observations, 0 otherwise. If discrete = 0, the exact likelihood associated with continuous observations is discretized. If discrete = 1, the likelihood of the Euler scheme of the mixed SDE is computed. Defaults to 1.

Value

L value of -2 x loglikelihood

References

Maximum likelihood estimation for stochastic differential equations with random effects, M. Delattre, V. Genon-Catalot and A. Samson, *Scandinavian Journal of Statistics 2012*, Vol 40, **322–343** Parametric inference for discrete observations of diffusion processes with mixed effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint*, hal-01332630

16 likelihoodNormalGamma

likelihoodNormalGamma Computation Of The Log Likelihood of the Euer scheme in Mixed Stochastic Differential Equations with random effects in the drift and in the diffusion.

Description

Computation of -2 log-likelihood of the Euler scheme the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t),$$

with Normal conditional distribution of the random effects in the drift $\alpha_j, \beta_j | \sigma_j \sim N(\mu, \sigma_j^2 \Omega)$ and inverse Gamma distribution of the random effect in the diffusion $1/\sigma_j^2 \sim Gamma(a, \lambda)$.

Usage

likelihoodNormalGamma(a, lambda, mu, omega, U, V, S, SigDelta, K, drift.random)

Arguments

а	current value of the shape of the Gamma distribution.
lambda	current value of the scape of the Gamma distribution.
mu	current value of the mean of the normal distribution.
omega	current value of the standard deviation of the normal distribution.
U	vector of the M sufficient statistics U (see UVS).
٧	list of the M sufficient statistics V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
SigDelta	vector of the M constant terms of the individual likelihood (see UVS). Required only if discrete $= 1$. Defaults to 0.
K	number of times of observations.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.

Value

L value of -2 x loglikelihood

References

Estimation of the joint distribution of random effects for a discretely observed diffusion with random effects, M. Delattre, V. Genon-Catalot and C. Laredo, *Preprint*, hal-01446063.

likelihoodNormalindi 17

likelihoodNormalindi	Computation of the individual Log-Likelihoods in Mixed Stochastic Differential Equations

Description

Computation of -2 log-likelihood of individual j in the mixed SDE with Normal distribution of the drift random effects and fixed effect in the diffusion:

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma a(X_j(t))dW_j(t).$$

Usage

likelihoodNormalindi(mu, omega, sigma, Uj, Vj, Sj, K, estimphij, drift.random)

Arguments

mu	vector of mean of the random effects. First (resp. second) value is the mean of α_j (resp. β_j) if α_j (resp. β_j) is random, the fixed effect value otherwise.
omega	standard deviation of the random effects. The components corresponding to a fixed effect should be set to 0 .
sigma	value of the diffusion parameter.
Uj	vector of the sufficient statistics U for individual j (see UVS).
Vj	matrix of the sufficient statistics V for individual j (see UVS).
Sj	value of the sufficient statistic S for individual j (see UVS).
K	number of times of observations.
estimphij	vector of estimators of the random effects for individual j.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.

Value

L value of -2 x loglikelihood

References

Maximum likelihood estimation for stochastic differential equations with random effects, M. Delattre, V. Genon-Catalot and A. Samson, *Scandinavian Journal of Statistics 2012*, Vol 40, **322–343**

18 Mixture.fit.class-class

```
Mixture.fit.class-class
```

model character 'OU' or 'CIR'

X matrix of observations, storage of input variable

S4 class for the estimation results when the random effects in the drift follow mixture of normal distributions

Description

S4 class for the estimation results when the random effects in the drift follow mixture of normal distributions

Slots

```
drift.random numeric 1, 2, \text{ or } c(1,2)
gridf matrix of values on which the estimation of the density of the random effects is done
mu array estimated value of the mean of the drift random effects at each iteration of the EM algo-
     rithm (Niter x nb.mixt x 2)
omega array estimated value of the standard deviation of the drift random effects at each iteration
     of the EM algorithm (Niter x nb.mixt x 2)
mixt.prop matrix estimated value of the mixing proportions at each iteration of the EM algorithm
     (Niter x nb.mixt)
sigma2 numeric estimated value of \sigma^2
index index of the used trajectories
estimphi matrix of the estimator of the drift random effects
probindi matrix of posterior component probabilities
estimf matrix estimator of the density of the drift random effects
estim.drift.fix numeric 1 if the user asked for the estimation of fixed parameter in the drift
bic numeric bic
aic numeric aic
times vector of observation times, storage of input variable
```

mixture.sim 19

mixture.sim

Simulation Of A Mixture Of Normal Distributions

Description

Simulation of M random variables from a mixture of Gaussian distributions

Usage

```
mixture.sim(M, param, prob)
```

Arguments

M number of simulated variables

param vector of parameters with the means and standard-deviations of the normal dis-

tributions

prob mixture components probabilities

Details

```
If the distribution is p1N(\mu 1, \sigma 1^2) + (1 - p1)N(\mu 2, \sigma 2^2) param=\mathbf{c}(\mu 1, \sigma 1, \mu 2, \sigma 2) and prob=\mathbf{c}(\mathbf{p}1, \mathbf{l}-\mathbf{p}1)
```

Value

Y vector of simulated variables

msde.fit

Estimation Of The Random Effects In Mixed Stochastic Differential Equations

Description

Parametric estimation of the joint density of the random effects in the mixed SDE

$$dX_{i}(t) = (\alpha_{i} - \beta_{i}X_{i}(t))dt + \sigma_{i} a(X_{i}(t))dW_{i}(t),$$

 $j=1,\ldots,M$, where the $(W_j(t))$ are independent Wiener processes and the $(X_j(t))$ are observed without noise. There can be random effects either in the drift (α_j,β_j) or in the diffusion coefficient σ_j or both.

Usage

```
msde.fit(times, X, model = c("OU", "CIR"), drift.random = c(1, 2),
    drift.fixed = NULL, diffusion.random = 0, diffusion.fixed = NULL,
    mixture = 0, nb.mixt = 1, Niter = 10, discrete = 1)
```

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Arguments

times	vector of observation times	
X	matrix of the M trajectories (each row is a trajectory with as much columns as observations)	
model	name of the SDE: 'OU' (Ornstein-Uhlenbeck) or 'CIR' (Cox-Ingersoll-Ross)	
drift.random	random effects in the drift: 0 if only fixed effects, 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects. Default to $c(1,2)$	
drift.fixed	NULL if the fixed effect(s) in the drift is (are) estimated, value of the fixed effect(s) otherwise. Default to NULL	
diffusion.random		
	1 if σ is random, 0 otherwise. Default to 0	
diffusion.fixed		
	NULL if σ is estimated (if fixed), value of σ otherwise. Default to NULL	
mixture	1 if the random effects in the drift follow a mixture distribution, 0 otherwise. Default to 0	
nb.mixt	number of mixture components for the distribution of the random effects in the drift. Default to 1 (no mixture)	
Niter	number of iterations for the EM algorithm if the random effects in the drift follow a mixture distribution. Default to 10	
discrete	1 for using a contrast based on discrete observations, 0 otherwise. Default to 1	

Details

Estimation of the random effects density from M independent trajectories of the SDE:

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j \ a(X_j(t))dW_j(t),$$

 $j=1,\ldots,M,$ where the $(W_j(t))$ are independant Wiener processes and the $(X_j(t))$ are observed without noise.

Specification of the random effects:

The drift includes no, one or two random effects:

- 1. if drift.random = 0: $\alpha_j \equiv \alpha$ and $\beta_j \equiv \beta$ are fixed
- 2. if drift.random = 1: $\beta_j \equiv \beta$ is fixed and α_j is random
- 3. if drift.random = 2: $\alpha_j \equiv \alpha$ is fixed and β_j is random
- 4. if drift.random = c(1,2): α_j and β_j are random

The diffusion includes either a fixed effect or a random effect:

- 1. if diffusion.random = 0: $\sigma_j \equiv \sigma$ is fixed
- 2. if diffusion.random = 1: σ_j is random

Distribution of the random effects

If there is no random effect in the diffusion (diffusion.random = 0), there is at least on random effect in the drift that follows

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- 1. a Gaussian distribution (nb.mixt=1): $\alpha_j \sim N(\mu, \Omega)$ or $\beta_j \sim N(\mu, \Omega)$ or $(\alpha_j, \beta_j) \sim N(\mu, \Omega)$,
- 2. or a mixture of Gaussian distributions (nb.mixt=K, K>1): $\alpha_j \sim \sum_{k=1}^K p_k N(\mu_k, \Omega_k)$ or $\beta_j \sim \sum_{k=1}^K p_k N(\mu_k, \Omega_k)$ or $(\alpha_j, \beta_j) \sim \sum_{k=1}^K p_k N(\mu_k, \Omega_k)$, where $\sum_{k=1}^K p_k = 1$.

If there is one random effect in the diffusion (diffusion.random = 1), $1/\sigma_j^2 \sim \Gamma(a,\lambda)$, and the coefficients in the drift are conditionally Gaussian: $\alpha_j|\sigma_j \sim N(\mu,\sigma_j^2\Omega)$ or $\beta_j|\sigma_j \sim N(\mu,\sigma_j^2\Omega)$ or $(\alpha_j,\beta_j)|\sigma_j \sim N(\mu,\sigma_j^2\Omega)$, or they are fixed $\alpha_j \equiv \alpha,\beta_j \equiv \beta$.

SDEs

Two diffusions are implemented:

- 1. the Ornstein-Uhlenbeck model (OU) $a(X_j(t)) = 1$
- 2. the Cox-Ingersoll-Ross model (CIR) $a(X_j(t)) = \sqrt{X_j(t)}$

Estimation

- If discrete = 0, the estimation is based on the exact likelihood associated with continuous observations ([1],[3]). This is only possible if diffusion.random = 0.
- If discrete = 1, the likelihood of the Euler scheme of the mixed SDE is computed.
- If nb.mixt > 1, an EM algorithm is implemented and the number of iterations of the algorithm must be specified with Niter.

Value

index	is the vector of subscript in 1,,M used for the estimation. most of the time index=1:M, except for the CIR that requires positive trajectories.
estimphi	matrix of estimators of the drift random effects $\hat{\alpha}_j$, or $\hat{\beta}_j$ or $(\hat{\alpha}_j, \hat{\beta}_j)$
estimpsi2	vector of estimators of the squared diffusion random effects $\hat{\sigma}_j^2$
gridf	grid of values for the plots of the random effects distribution in the drift, matrix form
gridg	grid of values for the plots of the random effects distribution in the diffusion, matrix form
estimf	estimator of the density of α_j , β_j or (α_j, β_j) . Matrix form.
estimg	estimator of the density of σ_j^2 . Matrix form.
mu	estimator of the mean of the random effects normal density
omega	estimator of the standard deviation of the random effects normal density
а	estimated value of the shape of the Gamma distribution
lambda	estimated value of the scale of the Gamma distribution
sigma2	value of the diffusion coefficient if it is fixed
bic	BIC criterium
aic	AIC criterium
model	initial choice
drift.random	initial choice

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diffusion.random

initial choice

drift.fixed initial choice

estim.drift.fix

1 if the fixed effects in the drift are estimated, 0 otherwise.

estim.diffusion.fixed

1 if the fixed effect in the diffusion is estimated, 0 otherwise.

discrete initial choice
times initial choice
X initial choice

For mixture distributions in the drift:

mu estimated value of the mean at each iteration of the algorithm. Niter x N x 2

array.

omega estimated value of the standard deviation at each iteration of the algorithm. Niter

x N x 2 array.

mixt.prop estimated value of the mixture proportions at each iteration of the algorithm.

Niter x N matrix.

probindi posterior component probabilites. M x N matrix.

References

See

[1] Maximum Likelihood Estimation for Stochastic Differential Equations with Random Effects, Delattre, M., Genon-Catalot, V. and Samson, A. *Scandinavian Journal of Statistics* 40(2) 2012 322-343

[2] Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, Delattre, M., Genon-Catalot, V. and Samson, A. *ESAIM:PS 19 2015* 671-688

[3] Mixtures of stochastic differential equations with random effects: application to data clustering, Delattre, M., Genon-Catalot, V. and Samson, A. *Journal of Statistical Planning and Inference 173* 2016 109-124

[4] Parametric inference for discrete observations of diffusion processes with mixed effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01332630 2016*

[5] Estimation of the joint distribution of random effects for a discretely observed diffusion with random effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01446063 2017*

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msde.pred

Prediction Of Mixed Stochastic Differential Equations Trajectories

Description

This function proposes to keep two thirds of the data (randomly chosen) to do the parametric estimation of the density of the parameters and of the fixed parameters of model $dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t)$ using the same method as in the estimation function msde. fit and then to predict new trajectories from the estimated model. The plot reflect the adequation between the last third of the data and the simulated one.

Usage

```
msde.pred(times, X, model = c("OU", "CIR"), drift.random,
   drift.fixed = NULL, diffusion.random = 0, diffusion.fixed = NULL,
   mixture = 0, nb.mixt = 1, Niter = 10, discrete = 1,
   plot.pred = TRUE, level = 0.05, newwindow = FALSE)
```

Arguments

newwindow

times	vector of observation times
X	matrix of the M trajectories (each row is a trajectory with as much columns as observations)
model	name of the SDE: 'OU' (Ornstein-Uhlenbeck) or 'CIR' (Cox-Ingersoll-Ross)
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects
drift.fixed	default NULL, fixed effect in the drift: value of the fixed effect when there is only one random effect and it is not estimated, NULL otherwise
diffusion.rand	om
	default 0, 1 if one random effect in the diffusion, 0 if there is no random effect in the diffusion
diffusion.fixe	d
	default NULL, fixed effect in the diffusion: value of the fixed effect when there is no random effect in the diffusion and it is not estimated, NULL otherwise
mixture	1 if the random effects in the drift follow a mixture distribution, 0 otherwise. Default to 0.
nb.mixt	default 1, number of mixture components for the distribution of the random effects in the drift
Niter	default 10, number of iterations for the EM algorithm if mixture = 1
discrete	default 1, 1 for discrete observations, 0 otherwise. If discrete = 0, and diffusion.random = 0, the exact likelihood associated with continuous observations is discretized. If discrete = 1, the likelihood of the Euler scheme of the mixed SDE is computed.
plot.pred	logical(1), if TRUE, the results are depicted grafically
level	alpha for the predicion intervals, default 0.05

logical(1), if TRUE, a new window is opened for the plot

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Value

res	is the vector of subscript in $1,,M$ where the estimation of phi has been done, most of the time $index=1:M$
Xpred	is the vector of subscript in $1,,M$ where the estimation of phi has been done, most of the time $index=1:M$
indexpred	matrix of estimators of $\phi = \alpha, or\beta, or(\alpha, \beta)$ from the efficient statitics (see UVS), matrix of two lines if drift.random =c(1,2), numerical type otherwise
phipred	matrix of estimators of $\psi^2=\sigma^2$ from the efficient statistics (see UVS), matrix of one line

References

See Maximum Likelihood Estimation for Stochastic Differential Equations with Random Effects, Delattre, M., Genon-Catalot, V. and Samson, A. *Scandinavian Journal of Statistics* 40(2) 2012 322-343

Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, Delattre, M., Genon-Catalot, V. and Samson, A. ESAIM:PS 19 2015 671-688

Mixtures of stochastic differential equations with random effects: application to data clustering, Delattre, M., Genon-Catalot, V. and Samson, A. *Journal of Statistical Planning and Inference 173* 2016 **109-124**

Parametric inference for discrete observations of diffusion processes with mixed effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01332630 2016*

Estimation of the joint distribution of random effects for a discretely observed diffusion with random effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01446063 2017*

Examples

```
## Not run:
# Example 1: one random effect in the drift and one random effect in the diffusion coefficient.
## End(Not run)
```

msde.sim

Simulation Of A Mixed Stochastic Differential Equation

Description

Simulation of M independent trajectories of a mixed stochastic differential equation (SDE) with linear drift

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t), j = 1, ..., M.$$

There may be two random effects (α_j, β_j) in the drift and one random effect σ_j in the diffusion coefficient.

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Usage

```
msde.sim(M, T, N = 100, model, drift.random, diffusion.random, mixture = 0,
    drift.param, diffusion.param, nb.mixt = 1, mixt.prop = 1, t0 = 0,
    X0 = 0.01, delta = T/N, op.plot = 0, add.plot = FALSE)
```

Arguments

M number of trajectories.T horizon of simulation.

N number of simulation steps, default Tx100.

model name of the SDE: 'OU' (Ornstein-Uhlenbeck) or 'CIR' (Cox-Ingersoll-Ross).

drift.random effects in the drift: 0 if no random effect, 1 if one additive random effect,

2 if one multiplicative random effect or c(1,2) if 2 random effects.

diffusion.random

random effect in the diffusion coefficient: 0 if no random effect, 1 if one multi-

plicative random effect.

mixture 1 if the random effects in the drift follow a mixture of Normal distributions, 0

otherwise. Default to 0.

drift.param fixed effects in the drift: value of the fixed effect when there is only one random

effect, 0 otherwise. If drift.random =2, fixed can be 0 but β has to be a non negative random variable for the estimation. vector (not mixture) or matrix (mixture)

of parameters of the distribution of the random effects in the drift.

diffusion.param

diffusion parameter if the diffusion coefficient is fixed, vector of parameters of

the distribution of the diffusion random effect otherwise.

nb.mixt number of mixture components if the drift random effects follow a mixture dis-

tribution, default nb.mixt=1.

mixt.prop vector of mixture proportions if the drift random effects follow a mixture distri-

bution, default mixt.prop=1.

time origin, default 0.

x0 initial value of the process, default X0=0.001.

delta time step of the simulation (T/N).

op.plot 1 if a plot of the trajectories is required, default 0.

add.plot 1 for add trajectories to an existing plot

Details

Simulation of M independent trajectories of the SDE (the Brownian motions W_j are independent), with linear drift. There may be one or two random effects in the drift:

If drift.random = 0, α and β are fixed effects ($\alpha_j \equiv \alpha$ and $\beta_j \equiv \beta$)

If drift.random = 1, β is a fixed effect ($\beta_i \equiv \beta$), and the drift function is written ($\alpha_i - \beta X_i(t)$)

If drift.random = 2, α is a fixed effect ($\alpha_i \equiv \alpha$), and the drift function is written ($\alpha - \beta_i X_i(t)$)

If drift.random = c(1,2), both effects are random, and the drift function is written $(\alpha_i - \beta_i X_i(t))$

26 out

Two diffusions are implemented:

Ornstein-Uhlenbeck model (OU): $a(X_j(t)) = 1$

Cox-Ingersoll-Ross model (CIR): $a(X_j(t)) = \sqrt{X_j(t)}$

There may be either a fixed or a random effect in the diffusion coefficient:

If diffusion.random = 0, σ is a fixed effect ($\sigma_j \equiv \sigma$). In that case, the random effects in the drift follow a Normal distribution or a mixture of Normal distributions.

If diffusion.random = 1, σ_j is a random effect. In that case, σ_j^2 follow an inverse Gamma distribution with parameters diffusion.param=c(shape,scale), and conditional on σ_j , the random effects in the drift follow a Normal distribution with mean mu and variance $Omega*\sigma_j^2$

Value

X matrix $(M \times (N+1))$ of the M trajectories.

phi vector (or matrix) of the M simulated random effects.

References

This function mixedsde.sim is based on the package sde, function sde.sim. See Simulation and Inference for stochastic differential equation, S.Iacus, *Springer Series in Statistics* 2008 Chapter 2

See Also

http://cran.r-project.org/package=sde

out

Transfers the class object to a list

Description

Method for the S4 classes

Usage

out(x)

Arguments

x Fit.class or Mixture.fit.class class

```
plot,Fit.class,ANY-method
```

Plot method for the estimation class object

Description

Plot method for the S4 class Fit.class

Usage

```
## S4 method for signature 'Fit.class,ANY'
plot(x, newwindow = FALSE, ...)
```

Arguments

x Fit.class class

newwindow logical(1), if TRUE, a new window is opened for the plot

... optional plot parameters

plot, Mixture. fit. class, ANY-method

Plot method for the mixture estimation class object

Description

Plot method for the S4 class Mixture.fit.class

Usage

```
## S4 method for signature 'Mixture.fit.class,ANY'
plot(x, newwindow = FALSE, ...)
```

Arguments

x Mixture.fit.class class

newwindow logical(1), if TRUE, a new window is opened for the plot

... optional plot parameters

28 probind

probind	Computation of the component probabilities

Description

Computation of the individual component probabilities in the mixed SDE

$$dXj(t) = (\alpha_j - \beta_j Xj(t))dt + \sigma a(Xj(t))dWj(t)$$

with random effects in the drift following a mixture of Gaussian distributions, and fixed effect in the diffusion.

Usage

```
probind(mu, omega, mixt.prop, sigma, U, V, S, K, estimphi, drift.random)
```

Arguments

mu	mean of the random effects. N x 2 matrix, first (resp. second) column is the mean of α_j (resp. β_j) in each mixture component if α_j (resp. β_j) is random, the fixed effect value otherwise.
omega	standard deviation of the random effects. N x 2 matrix, the components corresponding to a fixed effect should be set to 0 .
mixt.prop	vector of mixture proportions.
sigma	value of the diffusion parameter.
U	matrix of M sufficient statistics U (see UVS).
٧	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
K	number of times of observations.
estimphi	matrix of estimators of the fixed/random effects. 2 x M matrix.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.

Value

probindi M x N matrix of individual component probabilities.

Mixtures of stochastic differential equations with random effects: application to data clustering, M. Delattre, V. Genon-Catalot and A. Samson, *Journal of Statistical Planning and Inference 2016*, Vol 173, **109–124**

Q_EM 29

Q_EM	Computation of the E-step of the EM algorithm for mixtures of
	stochastic differential equations with random effects

Description

Computation of the E-step of the EM algorithm for parameter estimation in the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma a(X_j(t))dW_j(t)$$

with random effects in the drift following a mixture of Gaussian distributions, and a fixed effect in the diffusion.

Usage

```
Q_EM(mu, omega, sigma, probindi, U, V, S, K, estimphi, drift.random)
```

Arguments

mu	mean of the random effects. N x 2 matrix, first (resp. second) column is the mean of α_j (resp. β_j) in each mixture component if α_j (resp. β_j) is random, the fixed effect value otherwise.
omega	standard deviation of the random effects. N x 2 matrix, the components corresponding to a fixed effect should be set to 0.
sigma	value of the diffusion parameter.
probindi	M x N matrix of individual component probabilites.
U	matrix of M sufficient statistics U (see UVS).
V	list of the M sufficient statistics matrix V (see UVS).
S	vector of the M sufficient statistics S (see UVS).
K	number of times of observations.
estimphi	matrix of estimators of the fixed/random effects. 2 x M matrix.
drift.random	random effects in the drift: 1 if one additive random effect, 2 if one multiplicative random effect or $c(1,2)$ if 2 random effects.

Value

Q value of the E-step.

References

Mixtures of stochastic differential equations with random effects: application to data clustering, M. Delattre, V. Genon-Catalot and A. Samson, *Journal of Statistical Planning and Inference 2016*, Vol 173, **109–124**

summary, Fit. class-method

Short summary of the results of class object Fit.class

Description

Method for the S4 class Fit.class

Usage

```
## S4 method for signature 'Fit.class'
summary(object)
```

Arguments

object

Fit.class class

summary,Mixture.fit.class-method

Short summary of the results of class object Mixture.fit.class

Description

Method for the S4 class Mixture.fit.class

Usage

```
## S4 method for signature 'Mixture.fit.class'
summary(object)
```

Arguments

object

Mixture.fit.class class

Computation Of The Sufficient Statistics

UVS

Description

Computation of the sufficient statistics of the (approximate) likelihood of the mixed SDE

$$dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t).$$

Usage

```
UVS(X, model, times)
```

Arguments

X matrix of the M trajectories.

model name of the SDE: 'OU' (Ornstein-Uhlenbeck) or 'CIR' (Cox-Ingersoll-Ross).

times times vector of observation times.

Details

Computation of the sufficient statistics of the (approximate) likelihood of the mixed SDE $dX_j(t) = (\alpha_j - \beta_j X_j(t))dt + \sigma_j a(X_j(t))dW_j(t) = (\alpha_j, \beta_j)b(X_j(t))dt + \sigma_j a(X_j(t))dW_j(t)$ with $b(x) = (1, -x)^t$:

$$U: U(Tend) = \int_0^{Tend} b(X(s))/a^2(X(s))dX(s)$$

$$V: V(Tend) = \int_0^{Tend} b(X(s))^2 / a^2(X(s)) ds$$

$$S: S(X(t_1), ..., X(t_n)) = 1/delta \sum_{j=1}^{n} (X(t_j) - X(t_{j-1}))^2 / a^2 (X(t_{j-1}))$$

SigDelta: $SigDelta(X(t_1),...,X(t_n)) = nlog(delta) + \sum_{j=1}^{n} log(a(X(t_j)))$

Value

U vector of the M statistics U(Tend)

V list of the M matrices V(Tend)

S vector of the M quadratic variations $S(X(t_1),...,X(t_n))$

SigDelta vector of the M constant contributions to the Euler scheme approximation to the

likelihood SigDelta $(X(t_1),...,X(t_n))$

References

See

Maximum Likelihood Estimation for Stochastic Differential Equations with Random Effects, Delattre, M., Genon-Catalot, V. and Samson, A. *Scandinavian Journal of Statistics* 40(2) 2012 **322-343** Estimation of population parameters in stochastic differential equations with random effects in the diffusion coefficient, Delattre, M., Genon-Catalot, V. and Samson, A. *ESAIM:PS* 19 2015 **671-688**

32 valid,Fit.class-method

Mixtures of stochastic differential equations with random effects: application to data clustering, Delattre, M., Genon-Catalot, V. and Samson, A. *Journal of Statistical Planning and Inference 173* 2016 **109-124**

Parametric inference for discrete observations of diffusion processes with mixed effects, Delattre, M., Genon-Catalot, V. and Laredo, C. *hal-01332630 2016*

Estimation of the joint distribution of random effects for a discretely observed diffusion with random effects, Delattre, M., Genon-Catalot, V. and Laredo, C. hal-01446063 2017

valid

Description

Validation of the chosen model. For the index numj, Mrep=100 new trajectories are simulated with the value of the estimated random effect number numj. Two plots are given: on the left the simulated trajectories and the true one (red) and one the left the corresponding qq-plot for each time.

Usage

```
valid(x, ...)
```

Arguments

x Fit.class or Mixture.fit.class class... other optional parameters

valid, Fit. class-method

Validation of the chosen model.

Description

Validation of the chosen model. For the index numj, Mrep=100 new trajectories are simulated with the value of the estimated random effect number numj. Two plots are given: on the left the simulated trajectories and the true one (red) and one the left the corresponding qq-plot for each time.

Usage

```
## S4 method for signature 'Fit.class'
valid(x, Mrep = 100, newwindow = FALSE,
    plot.valid = TRUE, numj, ...)
```

Arguments

Mrep number of trajectories to be drawn

newwindow logical(1), if TRUE, a new window is opened for the plot plot.valid logical(1), if TRUE, the results are depicted grafically

numj optional number of series to be validated

... optional plot parameters

```
valid, Mixture. fit. class-method
```

Validation of the chosen model for the mixture class.

Description

Validation of the chosen model. For the index numj, Mrep=100 new trajectories are simulated with the value of the estimated random effect number numj. Two plots are given: on the left the simulated trajectories and the true one (red) and one the left the corresponding qq-plot for each time.

Usage

```
## S4 method for signature 'Mixture.fit.class'
valid(x, Mrep = 100, newwindow = FALSE,
    plot.valid = TRUE, numj, ...)
```

Arguments

Y	Mixture.fit.class clas	2

Mrep number of trajectories to be drawn

newwindow logical(1), if TRUE, a new window is opened for the plot plot.valid logical(1), if TRUE, the results are depicted grafically

numj optional number of series to be validated

... optional plot parameters

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