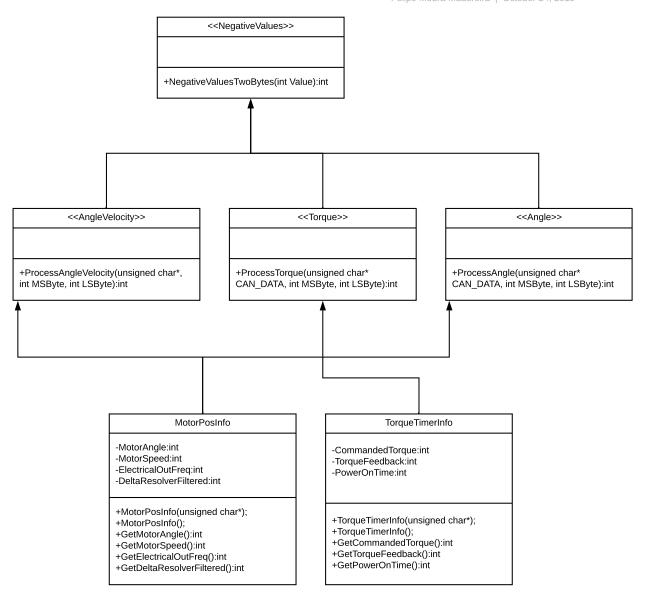
Felipe Moura Madureira | October 24, 2019



CommandMessage

- -TorqueCommand:int
- -SpeedCommand:int
- -DirectionCommand:bool
- -InverterEnable:bool
- -InverterDischarge:bool
- -SpeedMode:bool
- -CommandedTorqueLimit:int
- -struct can_frame frame;

+CommandMessage(int
TorqueCommand, int SpeedCommand, bool Direction, bool InverterEnable, bool InverterDischarge, bool SpeedMode, int CommandedTorqueLimit);

+SetParameter(int, signed short int):void