

Article

Task Scheduling Approach in Cloud Computing Environment Using Hybrid Differential Evolution

Mohamed Abdel-Basset¹, Reda Mohamed¹, Waleed Abd Elkhalik¹ , Marwa Sharawi²  and Karam M. Sallam^{3,*} 

¹ Faculty of Computers and Informatics, Zagazig University, Zagazig 44519, Sharqiyah, Egypt

² College of Engineering and Applied Sciences, American University of Kuwait, Salmiya 20002, Kuwait

³ School of IT and Systems, University of Canberra, Canberra, ACT 2601, Australia

* Correspondence: karam.sallam@canberra.edu.au

Abstract: Task scheduling is one of the most significant challenges in the cloud computing environment and has attracted the attention of various researchers over the last decades, in order to achieve cost-effective execution and improve resource utilization. The challenge of task scheduling is categorized as a nondeterministic polynomial time (NP)-hard problem, which cannot be tackled with the classical methods, due to their inability to find a near-optimal solution within a reasonable time. Therefore, metaheuristic algorithms have recently been employed to overcome this problem, but these algorithms still suffer from falling into a local minima and from a low convergence speed. Therefore, in this study, a new task scheduler, known as hybrid differential evolution (HDE), is presented as a solution to the challenge of task scheduling in the cloud computing environment. This scheduler is based on two proposed enhancements to the traditional differential evolution. The first improvement is based on improving the scaling factor, to include numerical values generated dynamically and based on the current iteration, in order to improve both the exploration and exploitation operators; the second improvement is intended to improve the exploitation operator of the classical DE, in order to achieve better results in fewer iterations. Multiple tests utilizing randomly generated datasets and the CloudSim simulator were conducted, to demonstrate the efficacy of HDE. In addition, HDE was compared to a variety of heuristic and metaheuristic algorithms, including the slime mold algorithm (SMA), equilibrium optimizer (EO), sine cosine algorithm (SCA), whale optimization algorithm (WOA), grey wolf optimizer (GWO), classical DE, first come first served (FCFS), round robin (RR) algorithm, and shortest job first (SJF) scheduler. During trials, makespan and total execution time values were acquired for various task sizes, ranging from 100 to 3000. Compared to the other metaheuristic and heuristic algorithms considered, the results of the studies indicated that HDE generated superior outcomes. Consequently, HDE was found to be the most efficient metaheuristic scheduling algorithm among the numerous methods researched.



Citation: Abdel-Basset, M.; Mohamed, R.; Abd Elkhalik, W.; Sharawi, M.; Sallam, K.M. Task Scheduling Approach in Cloud Computing Environment Using Hybrid Differential Evolution. *Mathematics* **2022**, *10*, 4049. <https://doi.org/10.3390/math10214049>

Academic Editors: Wanquan Liu, Xuefang Li and Xianchao Xiu

Received: 3 September 2022

Accepted: 27 October 2022

Published: 31 October 2022

Publisher's Note: MDPI stays neutral with regard to jurisdictional claims in published maps and institutional affiliations.



Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

1. Introduction

Healthcare services (HCS) based on cloud computing and IoT are now seen as one of the most significant medical fields, due to the spread of epidemics and health crises, where the best use of HCS can save many lives [1]. Through the use of cloud computing, HCS users can gain access to online computing resources, such as software, hardware, and applications that are managed in accordance with their needs. As a result, cloud computing in the context of the Internet of Things has greatly benefited all users, especially those in the healthcare services industry who wish to deliver medical services via the Internet [2]. The rapid adoption and ease of use in all industries, the proliferation of the Internet of Things

concept, and the continued advancement of infrastructure and technology will all increase user demand for cloud computing, doubling the volume of data and requests from users. Task scheduling becomes a more challenging issue. Delivering resources in accordance with user requests and upholding quality of service (QoS) requirements for the end-user is a demanding task [3].

Broadly speaking, cloud computing is made up of a large number of datacenters that house numerous physical machines (host). Each host runs several virtual machines (VMs) that are in charge of executing user tasks with varying quality of services (QoS). Users are able to gain access to cloud resources on a pay-as-you-go basis, through the use of cloud service providers [4]. An IoT environment connected to a cloud computing paradigm makes efficient use of the physical resources already available, thanks to virtualization technology. Thus, multiple users of healthcare services (HCS) can store and access a variety of medical resources using a single physical infrastructure, which includes both hardware and software. One of the most significant issues with healthcare services is the task scheduling problem (TSP), which causes users of healthcare services in a cloud computing environment to experience delays in receiving medical requests. The waiting period, the turnaround time for medical requests, CPU waste, and resource waste are some of the factors that contribute to the delay in processing medical requests. TSP is a NP-hard problem responsible for allocating computing resources to application tasks in an effective manner [2].

When the size of the tasks and the number of VMs both increase, the amount of computing time required to select the best scheduling for those tasks to the VMs increases exponentially. Some classic scheduling techniques, such as first come first served (FCFS), round-robin (RR), and shortest job first (SJF), are able to provide solutions to scheduling, but cannot fulfil the demands of cloud computing because its scheduling problem is NP-hard [5,6]. As traditional scheduling algorithms are unable to solve NP-hard optimization problems, more recently, modern optimization algorithms, also known as metaheuristic algorithms, have been used instead. These algorithms can produce optimal or near-optimal solutions in a reasonable amount of time compared to traditional scheduling algorithms.

Several metaheuristic algorithms have been employed for tackling task scheduling in cloud computing environments; for example, in [6], a new variant of the classic particle swarm optimization (PSO), namely ranging function and tuning function based PSO (RTPSO), was proposed, to achieve better task scheduling. In RTPSO, the inertia weight factors were improved to generate small and large values, for better local search and global search. In addition, RTPSO was integrated with the bat algorithm for further improvements; this variant was named RTPSO-B. Both RTPSO and RTPSO have been compared with various well-established algorithms, such as the genetic algorithm (GA), ant-colony optimization algorithm (ACO), and classical PSO. This comparison showed the efficiency of RTPSO-B in terms of its makespan, cost, and the utilization of resources.

The flower pollination algorithm (FPA) was also applied to tackle the task scheduling in cloud computing. Bezdan, T. et al. [7] improved the exploration operator of the classical FPA by replacing the worst individuals with new ones generated randomly within the search space, to avoid becoming stuck in local minima at the start of the optimization process. This improved FPA was called EEFPA and employed to find the best scheduling of tasks in cloud computing environments, which will minimize the makespan as a major objective. EEFPA was the best scheduler, compared to the other similar approaches considered in the study. Choudhary et al. [8] developed a task scheduling algorithm for bi-objective workflow scheduling in cloud computing that is based on hybridizing the gravitational search algorithm (GSA) and heterogeneous earliest finish time (HEFT); this algorithm was named as HGSA. This algorithm was developed in an effort to shorten the makespan and the computational cost. However, it is possible that GSA may not perform accurately for more complicated tasks.

Raghavan et al. [9] adapted the bat algorithm (BA) to tackle the task scheduling problem in cloud computing, with an objective function for reducing the total cost of the

workflow. On the other hand, BA had a subpar performance in the high dimension [6]. Tawfeek et al. [10] devised ant colony optimization to deal with task scheduling in cloud computing, with the goal of reducing the makespan. This algorithm was compared to two traditional algorithms, such as FCFS and RR, and it performed better than both of them. The problem with this algorithm is that it converges slowly, and hence will take several iterations to obtain feasible solutions. Hamad and Omara [11] proposed a task scheduling algorithm based on the genetic algorithm (GA), to find the optimal assignment of tasks in cloud computing, which will optimize the makespan and cost, as well as the resource utilization.

The grey wolf optimizer (GWO) was proposed, to schedule the tasks in cloud computing to utilize the resources more efficiently and minimize the total completion time [12]. This algorithm was compared with several scheduling methods, such as the FCFS, ACO, performance budget ACO (PBACO), and min-max algorithms. The experimental findings showed that GWO was the best-performing scheduler and PBACO was the second best. However, the performance of GWO at large scale was not evaluated and, hence, it is not preferable when the number of tasks is at a large scale. Chen, X. et al. [13] presented a task scheduler based on the improved whale optimization algorithm (IWOA). The standard WOA was improved in IWOA using two factors, namely the nonlinear convergence factor and adaptive population size. IWOA was better than the compared algorithms in terms of accuracy and convergence speed when scheduling small-scale tasks or large-scale tasks in cloud computing environments.

Alsaify, S.A. et al. [14] proposed two variants of PSO: The first, named LJFP-PSO, is based on initializing a population using a heuristic algorithm known as longest job to fastest processor (LJFP); while the second variant, known as MCT-PSO, is based on employing the minimum completion time (MCT) algorithm to initialize the population and to achieve a better makespan, total execution time, degree of imbalance, and total energy consumption when tackling the task scheduling problem in cloud computing. The glowworm swarm optimization (GSO) was used to solve the problem of task scheduling in cloud computing. The goal of this solution was to minimize the overall execution cost of jobs, while keeping the total completion time within the deadline [15]. According to the findings of a simulation, the GSO based task scheduling (GSOTS) algorithm achieved better results than the shortest task first (STF), the largest task first (LTF), and the particle swarm optimization (PSO) algorithms in terms of lowering the total completion time and the cost of executing tasks. There are several other metaheuristics-based task scheduling algorithms in the cloud computing environment, including the cuckoo search algorithm (CSA) [16], electromagnetism optimization (EMO) algorithm [17], sea lion optimization (SLO) algorithm [18], adaptive symbiotic organisms search (ASOS) [19], hybrid whale optimization algorithm (HWOA) [20], artificial flora optimization algorithm (AFOA) [21], modified particle swarm optimization (MPSO) [22], and differential evolution (DE) [23–30].

As mentioned, the task scheduling problem is classified as a nondeterministic polynomial time (NP)-hard problem and cannot be solved using traditional methods due to their inability to find a near-optimal solution in a reasonable time. Although, metaheuristic algorithms could have a significant effect when tackling these problems, they still suffer from falling into local minima and from a low convergence speed. As a result, a new task scheduler, known as hybrid differential evolution (HDE), is presented in this study, as a solution to the task scheduling challenge in the cloud computing environment. This scheduler is based on two proposed improvements to differential evolution. The first improvement is based on expanding the scaling factor to include dynamically generated numerical values based on the current iteration, in order to improve both the exploration and exploitation operators; the second improvement is intended to improve the exploitation operator of the classical DE, in order to achieve better results in fewer iterations. To demonstrate the efficacy of HDE, multiple tests were performed using randomly generated datasets and the CloudSim simulator. HDE was compared to a number of heuristic and metaheuristic algo-

rithms, to show that it is a strong alternative for overcoming the task scheduling problem in cloud computing. The main contributions of this study are as follows:

- Improving the scaling factor and the exploitation operator of the classical DE, to propose a new task scheduler known as hybrid differential evolution for the challenge of task scheduling in the cloud computing environment.
- Conducting several experiments using randomly generated datasets and the CloudSim simulator, to verify the efficiency of HDE.
- The experimental findings show that HDE was the most effective metaheuristic scheduling algorithm among the compared approaches.

The remaining sections of this work are structured as follows: Section 2 describes the classical differential evolution, Section 3 presents the objective function formulation, Section 4 details the steps of the proposed algorithm, Section 5 depicts the results of the experiments and performance comparison, and Section 6 presents the conclusions drawn from this study, as well as observations regarding future research.

2. Task Scheduling in the Cloud Computing Environment

Cloud computing is made up of a large number of datacenters that house numerous physical machines (host). Each host runs several virtual machines (VMs) that are in charge of executing user tasks with varying quality of services (QoS). Figure 1 depicts the task scheduling in a cloud computing environment [4]. Supposing that there are n cloudlets (Tasks), $T = T_1, T_2, T_3, \dots, T_n$, which are executed using m virtual machines (VMs), $VM = VM_1, VM_2, VM_3, \dots, VM_m$. These tasks have various lengths and the VMs are heterogeneous in terms of bandwidth, RAM, and CPU time. The cloud broker makes a request to the cloud information service, to obtain details about the services needed to carry out the tasks it has been given, and then schedules the tasks on the services that have been found. The numerous variables and QoS criteria of the broker influence the choice of the tasks to be provided. The cloud broker is the key element of the task scheduling process, it mediates talks between the user and the provider and decides when to schedule tasks for certain resources. However, there are several issues that need to be considered. The tasks that users submit are first added to the top queue in the system and must wait while the resources are employed. As a result, the system's queue grows longer, which lengthens the waiting period. However, a more effective approach than the first come first served (FCFS) principle should be used to manage this queue. Second, when the service provider manages the tasks, numerous parameters can be taken into account as multiobjective optimization or single objective optimization, such as the makespan, which directly affects resource consumption [4]. Therefore, a strong task scheduling algorithm should be created and implemented in the cloud broker, to not only meet the QoS requirements imposed by cloud users, but also to achieve good load balancing between the virtual machines, in order to improve resource utilization [4].

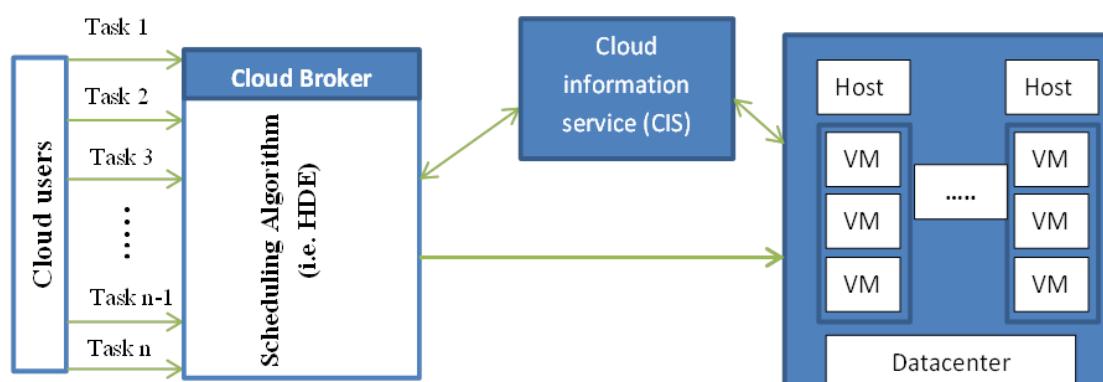


Figure 1. Task scheduling process in the cloud computing environment [4].

3. Differential Evolution

Storn [31] presented a population-based optimization method dubbed differential evolution (DE). DE is comparable to genetic algorithms, in terms of its mutation, crossover, and selection operators. Before commencing the process of optimization, the differential evolution generates a set of solutions, referred to as individuals, each of which has D dimensions and is randomly dispersed within the search space of the optimization problem. This takes place before the optimization procedure begins. After that, as will become clear in the following paragraphs, the mutation and crossover operators are applied, in order to search through the space available in an effort to locate more effective solutions.

3.1. Mutation Operator

This operator is applied to generate a mutant vector \vec{v}_i^t for each solution in the population. There are several updating schemes that can be applied to generate the mutant vector, one of the most common schemes generates the mutant vector according to the following formula:

$$\vec{v}_i^t = \vec{X}_a(t) + F * \left(\vec{X}_k(t) - \vec{X}_j(t) \right) \quad (1)$$

where a , k , and j stand for the indices of three individuals picked randomly from the population at the current iteration t . F is a positive scaling factor that involves a constant value greater than 0.

3.2. Crossover Operator

After generating the mutant vector \vec{v}_i^t using the crossover operator under a crossover probability (CR), the trial vector \vec{u}_i^t is generated using both the mutant vector and the solution of the i th individual, according to the following equation:

$$u_{i,j}^t = \begin{cases} v_{i,j}^t & \text{if } (r_1 \leq CR) \parallel (j = j_r) \\ X_{i,j}(t) & \text{otherwise} \end{cases} \quad (2)$$

where j_r is a random integer generated between 1 and D , j indicates the current dimension, and CR is a constant value between 0 and 1, which specifies the percentage of dimensions copied from the mutant vector to the trial vector.

3.3. Selection Operator

Finally, this operator is presented to compare the vector \vec{u}_i^t to vector $\vec{X}_i(t)$, with the fittest being used in the next iteration. Generally, the selection operator for a minimization problem is mathematically formulated as follows:

$$\vec{X}_i(t+1) = \begin{cases} \vec{u}_i^t & \text{if } (f(\vec{u}_i^t) < f(\vec{X}_i(t))) \\ \vec{X}_i(t) & \text{otherwise} \end{cases} \quad (3)$$

4. Objective Function Formulation

Supposing that there are n cloudlets (Tasks), $T = T_1, T_2, T_3, \dots, T_n$, which are executed using m virtual machines (VMs), $VM = VM_1, VM_2, VM_3, \dots, VM_m$. Then, the solutions obtained by a scheduler represent the assignment process of the tasks to the VMs in the order that will minimize the two objectives: makespan, and total execution time. Problems that have two or three objectives are classified as multiobjective. There are two methods, namely a priori or a posteriori, suggested to deal with multiobjective problems [32,33]. In the priori method, the multiobjective problems are treated as a single objective problem, by assigning a weight to each objective, based on the significance of each objective for the decision-makers. On the other hand, the posteriori method proposes that all objectives have the same significance, so it generates a set of solutions, namely

non-dominated solutions, that trade off between different objectives. In this study, the priori approach was employed to convert the multiobjective problem into single objective using a weighting variable τ that includes a constant value generated between 0 and 1, to determine the importance of an objective, for example, the makespan, in the fitness function, and the complement of this variable ($1 - \tau$) indicates the weight of the other objective. For instance, the objective function under this weighting variable is formulated as follows:

$$f = (1 - \tau) \times \eta + \tau \times \beta \quad (4)$$

where β represents the makespan objective, and η stands for the total execution time. τ stands for the weighting variable, which is employed to convert this problem from multi-objective to single-objective, to become solvable using the met heuristic algorithms designed for single-objective problems, such as differential evolution. In the future, the posteriori approach will be applied to this problem, in an attempt to achieve better results for all objectives at the same time.

After describing the main components of the objective function, let us describe each one carefully. Starting with the makespan objective, at the beginning time, each VM_j has a variable Et_j assigned a value of 0, and then the tasks are distributed using a scheduler to those VMs. Each VM executes their assigned tasks and the execution time needed by each task to be executed under the j th VM is added to the variable Et_j . Finally, after finishing the tasks assigned to all VMs, the values stored in the variable Et for each VM are compared with each other, and the maximum value represents the makespan. Finally, the makespan, defined as the maximum of Et of all VMs, can be computed using the following expression:

$$\beta = \max(\vec{Et}) \quad (5)$$

The second objective η is the total execution time consumed to complete the tasks assigned to all the VMs and can be computed according to the following formula:

$$\eta = \sum_{j=1}^m Et_j \quad (6)$$

Finally, the proposed algorithm described in the next section is employed to minimize the objective function described in Equation (4), to find the near-optimal scheduling of tasks that minimizes both the makespan and total execution time, hence providing a better quality of service to the users.

5. The Proposed Algorithm

This section presents the main steps employed to adapt the differential evolution for tackling the task scheduling problem in cloud computing; these steps are listed as follows: initialization, evaluation, adaptive mutation factor, and additional exploitation operator.

5.1. Initialization

Before starting the optimization process with any metaheuristic algorithm, a number N of solutions with n dimensions (each dimension represents a task in the scheduling problem) for each solution are defined and randomly initialized between 0 and m , to assign each task to a virtual machine. For example, Figure 2 presents a simple example, to illustrate how to represent a solution for the task scheduling problem. In this figure, we create a solution with 10 tasks, where n is 10, and randomly assign a VM to each task in this solution, where the number of available VMs is up to 7. From this figure, it is obvious that the virtual machine with an index of 2 will execute tasks 2 and 9, and the VM with an index of 0 will be assigned to execute tasks 1 and 5, while the other tasks, in order, will

be assigned to the VMs: 1, 4, 3, 5, 6, and 5, respectively. In brief, the mathematical formula of the initialization step is defined as follows:

$$\vec{X}_i = \vec{r} * m \mid i = 0, 2, 3, 4, \dots, (N - 1) \quad (7)$$

where \vec{r} stands for a vector involving decimal numbers generated randomly between 0 and 1, and $*$ indicates the multiplication operator. Following that step, the evaluation stage commences, to evaluate the quality of each solution and determine the best so-far solution that can reach the lowest value for the objective function described in Equation (4).

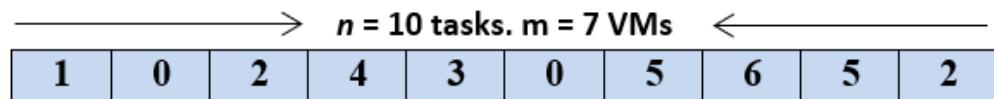


Figure 2. A solution representation for task scheduling in cloud computing. This figure starts by numbering the cells with 0 and ends with an index of 9 for the last cell, such that the cell 0 indicates the first task, and the second cell indicates the second task, and so on.

5.2. Adaptive Scaling Factor (F)

The mutation stage in the differential evolution has a scaling factor, namely F , responsible for determining the step sizes. This factor in the classical DE algorithm includes a constant positive value, and this value is unchanged during the whole optimization process. Hence, if the population diversity is high and the value of this scaling factor is also high, the step size will take the solution a long distance from the current solution, this even occurs at the beginning of the optimization process, to encourage the algorithm to extensively explore the search space, to find the promising regions that might contain the best-so-far solution. Afterwards, the population diversity might be decreased when increasing the current iteration, while the scaling factor remains constant. However, what will happen if the population diversity remains high during the entire optimization process? Let us imagine together, if the population diversity remains high and the scaling factor is constant, then the generated step sizes are also high and, hence, the algorithm will always search for a better solution in regions far from the current solution, which might contain the near-optimal solution near to it. A similar problem occurs when the scaling factor is small and the population diversity is high. Therefore, in this study, we reformulated this factor to be dynamically updated according to the current iteration, to maximize the exploration operator of the classical DE algorithm at the beginning of the optimization process, and to search for the most promising region within the search space; and then, by increasing the current iteration, this exploration operator will be gradually converted into the exploitation operator, to focus more on this promising region, in order to achieve a better solution, in addition to accelerating the convergence. Based on this, the shortcomings of the classical DE with a constant scaling factor are largely avoided. Finally, the adaptive scaling factor is generated based on the current iteration, using the following formula:

$$F' = \alpha * \left(\frac{T - t}{T} \right) \quad (8)$$

where T indicates the maximum iteration, and t stands for the current iteration. α is a predefined constant value.

5.3. Convergence Improvement Strategy

The mutation scheme described previously for generating the mutant vector in the classical DE is based on three solutions selected randomly from the current population. As a consequence of this, the exploration operator may be directed to explore the regions surrounding one of these solutions, despite the fact that the near-optimal solution may be in a region close to the best-so-far solution. Therefore, in this study, an additional strategy, namely a convergence improvement strategy (CIS), is proposed to exploit the regions

around the best-so-far solution, to improve the convergence ability of the standard DE. This strategy initially generates a vector, namely \vec{v}_i^t , including numerical values generated around the best-so-far solution, using the following formula:

$$\vec{v}_i^t = \vec{X}^*(t) + \vec{r} * \left(\vec{X}_i(t) - \vec{r}_1 * \vec{X}^*(t) \right) \quad (9)$$

where $\vec{X}^*(t)$ indicates the best-so-far solution at the current iteration t , and \vec{r} and \vec{r}_1 are two vectors including numerical values generated randomly between 0 and 1. Following this, another vector, namely a trial vector \vec{T}_i^t , will be generated based on conducting a crossover operation between $\vec{X}^*(t)$ and \vec{v}_i^t under a crossover probability (P) predetermined according to experiments. Briefly, the trial vector will be generated according to the following formula:

$$T_{i,j}^t = \begin{cases} v_{i,j}^t & \text{if } (r_2 \leq P) \\ X_j^*(t) & \text{otherwise} \end{cases} \quad (10)$$

where r_2 is a numerical value generated randomly between 0 and 1. Finally, the fitness value of the trial vector, \vec{T}_i^t , will be compared with that of the current solution $\vec{X}_i(t)$, and if the fitness of this trial vector is better, then it will be used in the next iteration; otherwise, the current solution is retained in the next generation, even when reaching a better one. However, applying this strategy to all individuals in the population might deteriorate the exploration operator of the classical DE, because it might reduce the population diversity. Therefore, this strategy has to be applied to a number of the solutions, to avoid this shortcoming; this number is estimated using the following formula:

$$N' = N * \kappa \quad (11)$$

where N is the number of individuals in the population, and κ is the percentage of the individuals that will be extracted to be updated using the convergence improvement strategy. Finally, the steps of the CIS strategy are listed in Algorithm 1.

Algorithm 1. Convergence improvement strategy (CIS)

1. **for** $i = 0$ to N'
 2. Generate the mutant vector \vec{v}_i^t using Equation (9)
 3. **for** $j = 0$ to n
 4. r_2 : a number generated randomly between 0 and 1
 5. **if** $(r_2 < P)$
 6. $T_{i,j}^t = v_{i,j}^t$
 7. **else**
 8. $T_{i,j}^t = X_j^*(t)$
 9. **End if**
 10. **end for**
 11. **if** $\left(f\left(\vec{T}_i^t\right) < f\left(\vec{X}_i^t\right) \right)$
 12. $\vec{X}_i^t = \vec{T}_i^t$
 13. **end if**
 14. Replace the best-so-far solution $\vec{X}^*(t)$ with \vec{T}_i^t if \vec{T}_i^t is better
 15. **end for**
-

5.4. Hybrid Differential Evolution

The classical DE is hybridized with the convergence improvement strategy and adaptive scaling factor, to produce a new variant dubbed hybrid differential evolution (HDE), having a better search ability, for a better solution when tackling the task scheduling in

cloud computing. Another advantage of HDE is that it has the ability to accelerate the convergence speed in the direction of the near-optimal solution. The steps of HDE are described in Algorithm 2. This algorithm starts by initializing N solutions within the search space of the scheduling problem in cloud computing; the search space of this problem ranges between 0 and the number of virtual machines ($m - 1$). Then, the initialized solutions are evaluated, and the best-so-far solution $\vec{X}^*(t)$ that has the lowest fitness value is identified, to be employed for guiding some of the solutions within the optimization process towards a better solution. Line 3 within Algorithm 2 initializes the current iteration t with a value of 0. After this, the optimization process is triggered to update the initialized solutions to reach better solutions, whereby this process starts by defining the termination condition as shown in Line 4. Then, Lines 5–6 update the adaptive scaling factor, which is responsible for improving the exploration and exploitation capability of the proposed algorithm. Following this, updating of the solutions is implemented, to generate the trial vector based on both the current solution and the mutant vector. In the next step, this trial vector is compared with the current solution, to extract the one that will be preserved in the population for the next generation. This process is repeated until satisfying the termination condition. Finally, the flowchart of HDE is shown in Figure 3.

Algorithm 2. Hybrid differential evolution (HDE)

1. Initializes N solutions, \vec{X}_i , $i = 1, 2, \dots, N$, using Equation (7)
 2. Evaluate the initialized solutions and identified $\vec{X}^*(t)$
 3. $t = 0$
 4. **while** ($t < T$)
 5. Update F' using Equation (8)
 6. $F = F'$
 7. **for** $i = 0$ to N
 8. Generate the mutant vector \vec{v}_i^t using Equation (1)
 9. j_r = an integer generated randomly between 1 and n
 10. **for** $j = 0$ to n
 11. r_2 : a number generated randomly between 0 and 1
 12. **if** ($r_2 < CR \parallel j = j_r$)
 13. $u_{i,j}^t = \vec{v}_{i,j}^t$
 14. **else**
 15. $u_{i,j}^t = \vec{X}_{i,j}(t)$
 16. **End if**
 17. **end for**
 18. **if** ($f\left(\vec{u}_i^t\right) < f\left(\vec{X}_i^t\right)$)
 19. $\vec{X}_i^t = \vec{u}_i^t$
 20. **end if**
 21. Replace the best-so-far solution $\vec{X}^*(t)$ with T_i^t if T_i^t is better
 22. **end for**
 23. Updating N' solutions using the CIS algorithm (Algorithm 1)
 24. $t = t + 1$
 25. **end while**
 - Return** $\vec{X}^*(t)$
-

5.5. Time Complexity of HDE

In this part of the article, the time complexity is expressed using big-O notation, so that the superior speed of the suggested approach can be demonstrated. To begin, the following are the primary factors that have the most significant impact on the acceleration of the proposed algorithm: the population size, N , the number of tasks, n , the maximum iteration,

T , and the time complexity of Algorithm 1. Generally, the time complexity of HDE can be expressed as follows:

$$T(\text{HDE}) = T(\text{DE}) + T(\text{CIS}) \quad (12)$$

The time complexity of the standard DE mostly depends solely on the first three factors: N , n , and T , as shown in Algorithm 2, which is formulated as follows:

$$T(\text{DE}) = O(T * n * N) \quad (13)$$

The time complexity of the CIS also depends on the first three factors, with the exception of N , which is replaced by N' . In general, the time complexity of CIS can be expressed as follows:

$$T(\text{CIS}) = O(T * n * N') \quad (14)$$

By substitution, Equation (12) can be reformulated as follows:

$$T(\text{HDE}) = O(T * n * N) + O(T * n * N') \quad (15)$$

From this equation, the term that has the highest growth rate is $O(T * n * N)$, because N is always greater than N' . Therefore, the time complexity of HDE in big-O is $O(T * n * N)$.

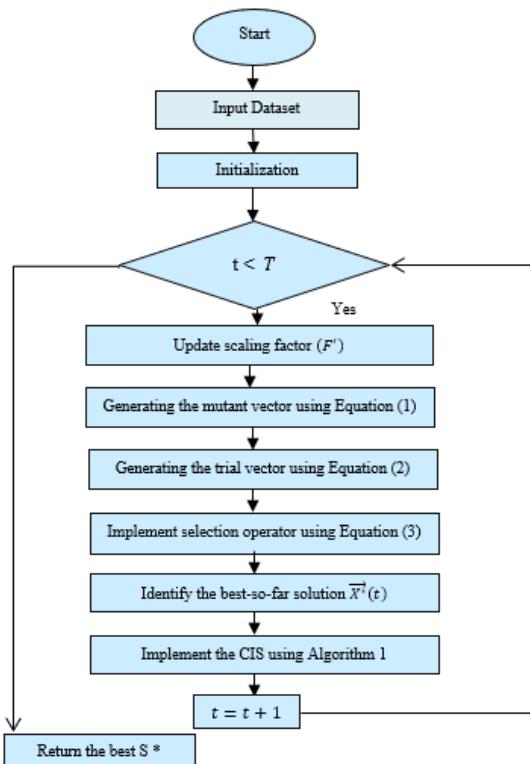


Figure 3. The flowchart of the proposed algorithm: HDE (* is used to identify the best solution).

6. Results and Simulation

Several experiments were conducted in this study to show the efficiency of the proposed algorithm: HDE was compared to several heuristic and metaheuristic approaches; the metaheuristic algorithms were the sine cosine algorithm (SCA) [34], whale optimization algorithm (WOA) [35], slime mold algorithm (SMA) [36], equilibrium optimizer (EO) [37], grey wolf optimizer (GWO) [38], and classical DE [39]; the heuristic algorithms were first come first served (FCFS) [40], round robin (RR) algorithm [41], and shortest job first (SJF) scheduler [40]. These algorithms were executed in 30 independent runs on datasets generated randomly, with the number of tasks ranging between 100 and 3000; these tasks are

labeled as T100 for the task size 100, T200 for the task size 200, and so on. Five VMs were selected for scheduling these task data sets, where the communication time and execution time for each task were randomly generated to determine the ability of each VM to implement each task, while taking into consideration that the workload of this task is different of the other tasks. The performance evaluation metrics used in this study to compare the algorithms were the best, average, worst, and standard deviation of the obtained outcomes within 30 independent repetitions, in addition to a Wilcoxon rank sum test, which was employed to identify whether there were any differences between the outcomes obtained by the proposed and those of the rival optimizers. All of the algorithms were built using the programming language Java on a personal computer, which had the following capabilities: Windows 10 operating system, Intel® CoreTM i7-4700MQ processor running at 2.40 GHz, and 16 GB of memory installed.

The parameters of all the compared algorithms were set to the values found in the cited papers, to ensure a fair comparison. However, there were two main parameters that had to be the same for all the algorithms, and they were the population size (N), and the maximum number of iterations (T), which were set to 25 and 1500, respectively. Regarding the parameters of the classical DE and the proposed algorithm, HDE, several experiments were conducted to estimate the optimal value for each of their parameters. Broadly speaking, the classical DE has two main parameters: F and Cr , which were extracted according to several conducted experiments. From these experiments, it was observed that the best values for these parameters were 0.01 for Cr and 0.1 for the scaling factor (F). Regarding the parameter values of HDE, the Cr and α parameters were set to the same values as the Cr and F in the classical DE. However, HDE has two additional parameters: P and κ , which were estimated by conducting experiments. These experiments showed that the best values for these parameters, P and κ , were 0.01 and 0.2, respectively. Table 1 presents the parameter values of both HDE and DE.

Table 1. Parameter settings of HDE and DE.

	DE	HDE
T	1500	1500
N	25	25
F	0.1	0.1
Cr	0.01	0.01
P		0.01
κ		0.2

6.1. Comparison with Metaheuristic Algorithms

Due to the fact that meta-heuristic algorithms are stochastic optimization techniques, they require at least 10 separate runs to produce statistically significant results. In this study, each algorithm was run roughly thirty times independently, and the average results of each algorithm are reported. In Table A1 are shown the metrics of the best fitness values for each algorithm in the last iteration over all independent runs. These metrics include the mean, best, and worst values, as well as the standard deviation (SD). The top results in this table are highlighted in bold. This table demonstrates that HDE is comparable to DE and superior to all other algorithms for the 100-task size. With growing task sizes, HDE's superiority becomes more apparent, and it may be the best option for any tasks with lengths more than 100. Additionally, to further show the efficiency of HDE, the average of the best, worst, and mean fitness values obtained for all the tasks sizes were computed and are presented in Figure 4, which affirms that HDE was the best for all shown metrics. Figure 5 shows the average (Avg) standard deviation (SD) obtained by each algorithm on all tasks sizes. Inspecting this figure shows that HDE was more stable than the other algorithms. After discussing the effectiveness of HDE in terms of the fitness value, we will move on to discuss its capacity to reduce the makespan in the next paragraph.

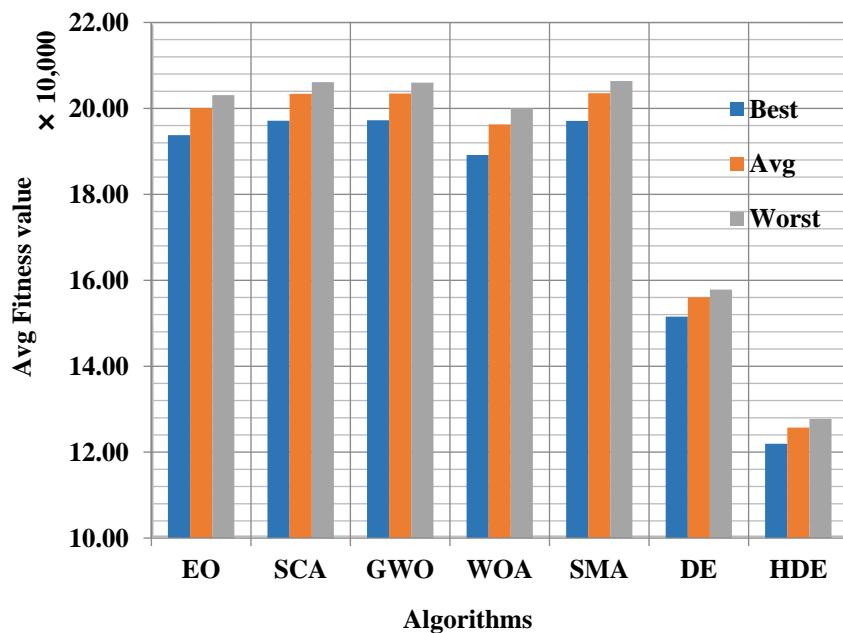


Figure 4. Comparison among algorithms by fitness value.

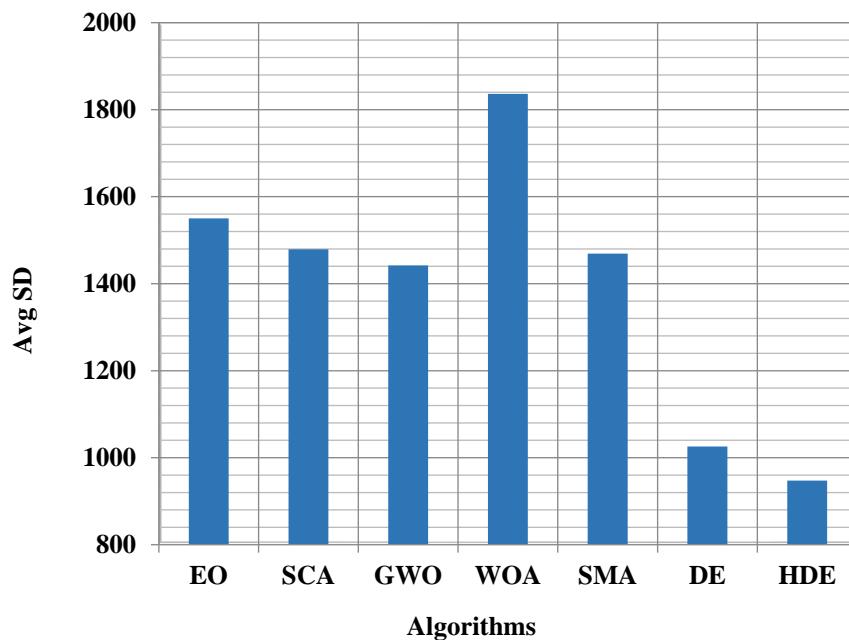


Figure 5. Comparison in terms of average SD of the fitness values.

The metrics that represent the best makespan values for each method in the last iteration across all independent runs are presented in Table A2. The best, worst, and average values, as well as the standard deviation, are the metrics that were included in this study. The best outcomes are displayed in bold within this table. This table illustrates that HDE was superior to all other algorithms for the 100-task size and was on par with DE in terms of its performance. The superiority of HDE became more evident with increasing task sizes, and it is possible that it is the best choice for all tasks with lengths greater than 100. In addition, in order to demonstrate the effectiveness of HDE in a more comprehensive manner, the mean, best, and worst makespan values that were obtained for each of the different task sizes were computed and are shown in Figure 6. This figure demonstrates that HDE was the optimal method for each of the metrics that are presented. Figure 7

displays the average of the standard deviation (SD) values that were obtained by each algorithm for all task sizes. Taking a closer look at this figure reveals that HDE was far more reliable than the other algorithms. Now we have finished talking about how effective HDE was in terms of the fitness value and makespan, in the following paragraph, we will move on to talking about how it had the ability to reduce the total execution time required by all VMs, until finishing the tasks that had been given to them.

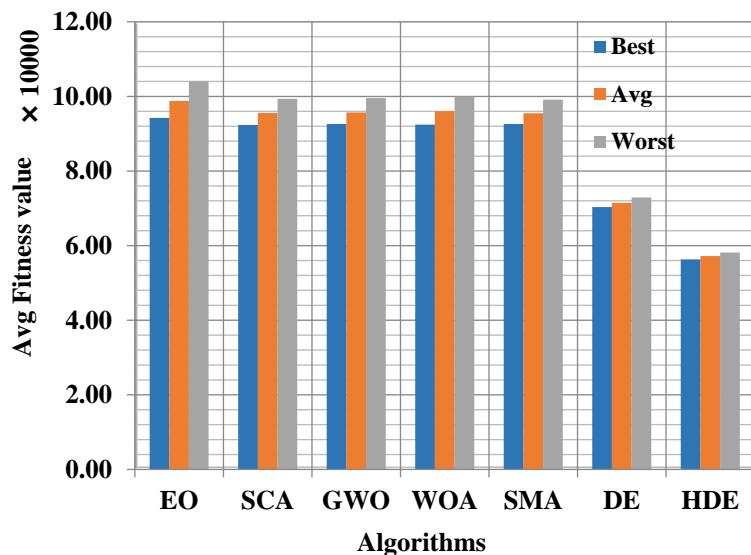


Figure 6. Comparison among algorithms by makespan.

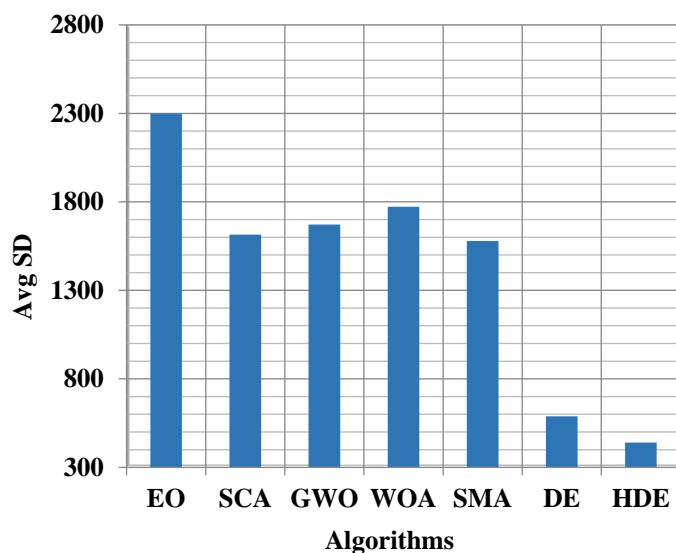


Figure 7. Comparison with metaheuristics in terms of the average SD of makespan.

The average, worst, best, and SD values obtained as a result of analyzing the total execution time values obtained by the various investigated metaheuristic algorithms within 30 independent runs are reported in Table A3. Based on the results in this table, it is clear that HDE performed just as well as DE and was superior to all the other algorithms when it comes to a size of 100 tasks. It is probable that HDE is the optimal option for all tasks with lengths that are larger than 100. The superiority of HDE became more readily apparent as the size of the tasks was increased. The average of the mean, best, and worst total execution values that were obtained for each of the various task sizes was computed and are given in Figure 8, in order to showcase the efficacy of HDE in a more thorough manner. This was done in order to prove that HDE was effective. This figure illustrates that HDE was

the best strategy for each of the metrics that are presented. Figure 9 depicts the average of the standard deviation (SD) values that were obtained using each method for all of the various task sizes. When taking a closer look at this figure, it can be noticed that HDE was significantly more trustworthy than any of the other algorithms. Finally, from all the previous experiments and discussions, it is concluded that HDE is a strong alternative scheduler to find the near-optimal scheduling of tasks in cloud computing, with the aim of minimizing both the makespan and the total execution time.

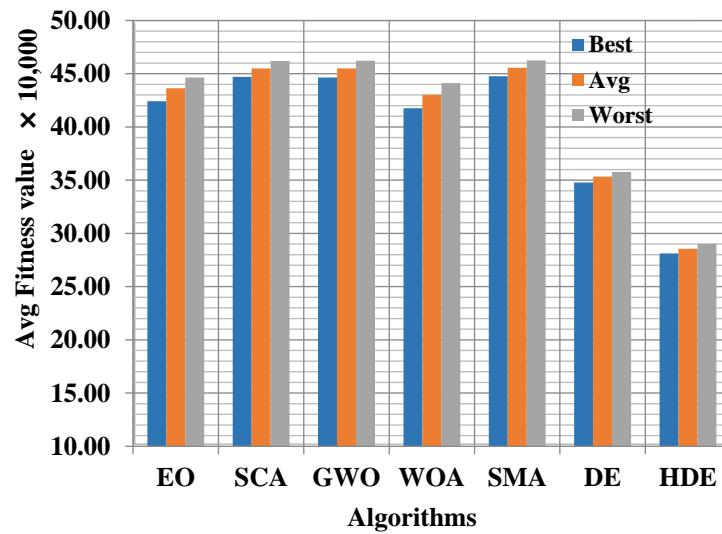


Figure 8. Comparison among algorithms for the total execution time.

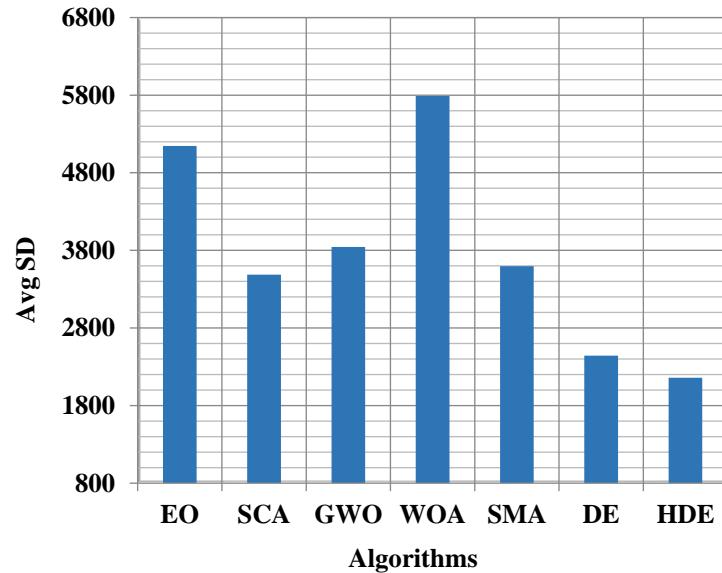


Figure 9. Comparison in terms of the average SD of total execution time.

Table A4 compares the proposed HDE algorithm to the other types using a Wilcoxon rank-sum test with 5% as the level of confidence [42]. The null hypothesis and the alternative hypothesis were both tested in this experiment. The null hypothesis suggests that there is no difference between the two methods being compared; this hypothesis is true when the p -value shown in Table A4 is greater than the confidence level. In contrast, the alternative hypothesis asserts that there is a difference between the results obtained using a pair of algorithms; this hypothesis is supported when p -value is less than the confidence level. Table A4 displays the results of comparing HDE to the other algorithms evaluated in this test. According to this table, the alternative hypothesis holds true in all instances,

highlighting the difference between the outcomes of the proposed algorithm and those of other algorithms.

The boxplot represented in Figure 10 is discussed in this paragraph. The boxplot shows a five-number summary, including the lowest, maximum, median, and the first and third quartiles for the fitness values achieved by each algorithm during 30 independent runs. Examining this figure demonstrates that HDE was superior in terms of all five-number summaries for all of the investigated task lengths.

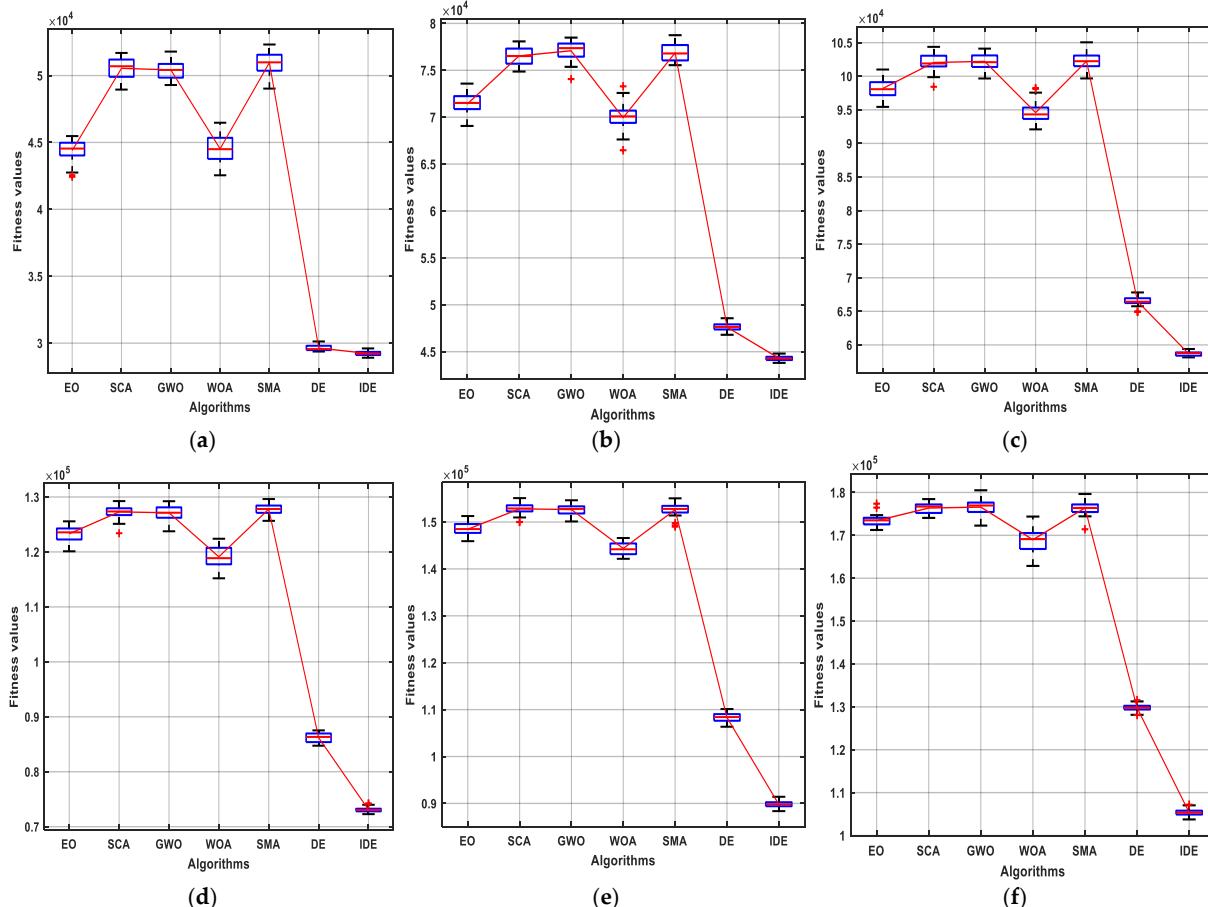


Figure 10. Comparison among algorithms in terms of the Boxplot: (a) Comparison for the task size of 200; (b) Comparison for the task size of 300; (c) Comparison for the task size of 400; (d) Comparison for the task size of 500; (e) Comparison for the task size of 600; (f) Comparison for the task size of 700.

Finally, HDE and the other algorithms were compared based on their respective convergence rates for the fitness function. On the basis of the convergence rates obtained by each algorithm, and presented in Figure 11, for task lengths 100, 200, 300, 400, 500, 600, 700, 800, and 900, HDE achieved superior convergence to the optimal solution for all depicted task lengths. Figure 12 shows a comparison among the algorithms in terms of CPU time. The figure provides the total CPU time in seconds for running each algorithm with different task sizes. HDE had a slightly higher computational cost than traditional DE, but it can provide a better QoS to users, because it can achieve a smaller makepan value for the majority of task sizes.

6.2. Simulation Results

The CloudSim platform was utilized in order to carry out simulations of the task scheduling process. Researchers from all over the world make use of the CloudSim platform because it is a full-fledged simulation toolset that enables modelling and simulation of real-world cloud infrastructure and application provisioning [12]. In this paper, CloudSim

was provided with the parameters settings described in Table 2. In addition, the number of tasks ranged between 100 and 1000, with a step 100, to check the scalability of the proposed algorithm in comparison to the other metaheuristic algorithms. After conducting the simulation process, the makespan values obtained under various metaheuristic algorithms implemented within the Cloudsim platform are presented in Table 3 for each task size. Inspecting this table shows the effectiveness of HDE in comparison to the other algorithms, since it had the lowest makespan values for all the task sizes. This is confirmed by the last row in the same table which contains the average of each column within the table; this row reveals that HDE could achieve average makespan values up to 151,479.2179, which is the smallest in comparison to the others in the same row.

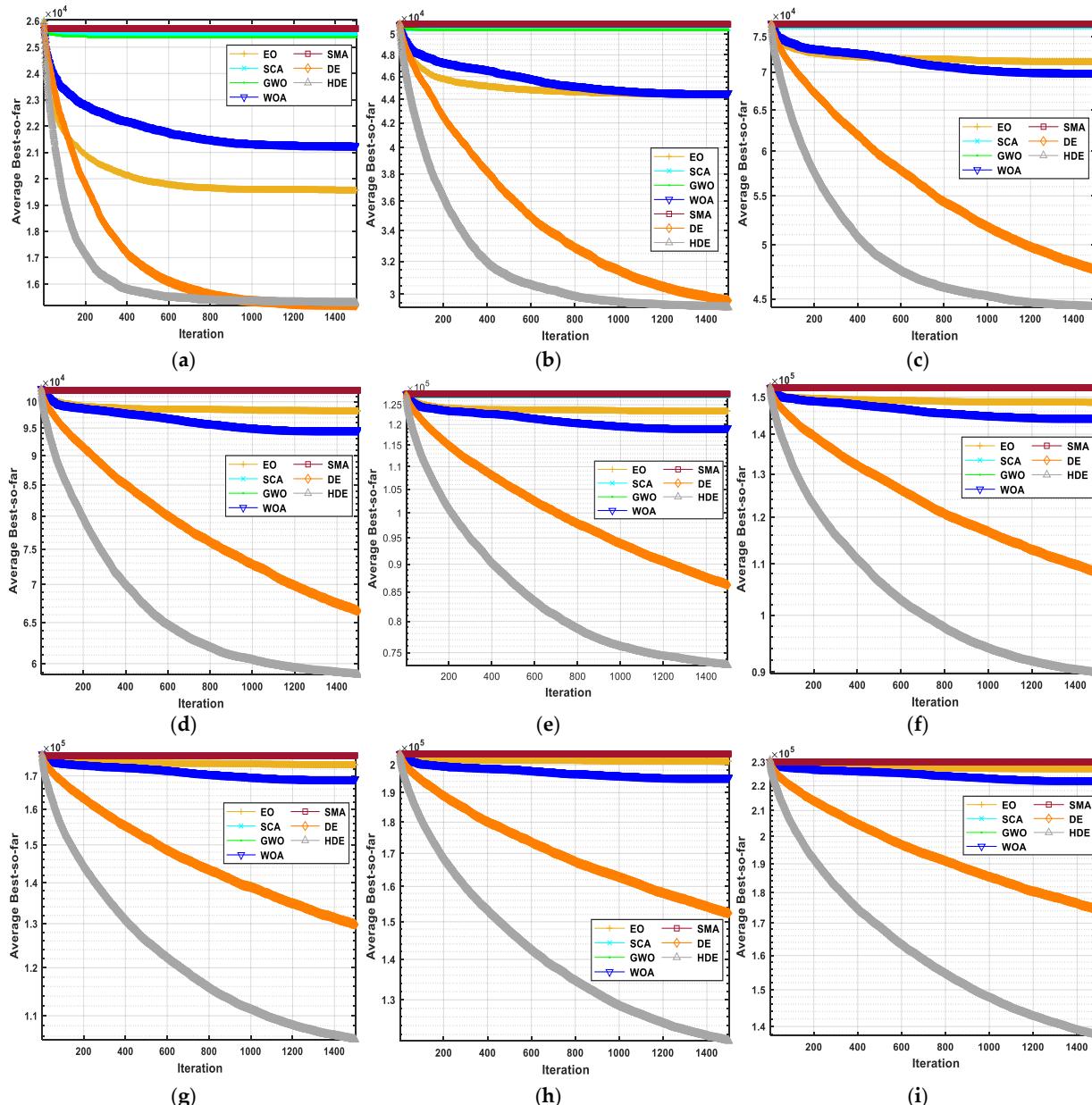


Figure 11. Comparison of algorithms in terms of convergence speed: (a) Comparison for the task size of 100; (b) Comparison for the task size of 200; (c) Comparison for the task size of 300; (d) Comparison for the task size of 400; (e) Comparison for the task size of 500; (f) Comparison for the task size of 600; (g) Comparison for the task size of 700; (h) Comparison for the task size of 800; (i) Comparison for the task size of 900.

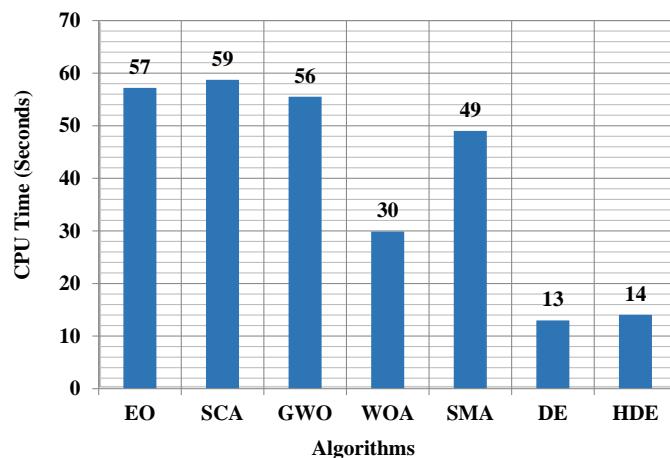


Figure 12. Comparison of algorithms in terms of CPU time.

6.3. Comparison with Some Heuristic Algorithms

In this section, the proposed algorithm is compared with some well-known heuristic schedulers, such as FCFS, SJF, and round robin, to further verify the superiority of HDE in tackling the task scheduling problem in cloud computing. The results of each method were independently tested around thirty times. In Table A5, the average, worst, and best values are shown, as well as the standard deviations, that were achieved by the proposed approach and by each heuristic algorithm for each task size. The results of this table show that HDE performed significantly better than any of the heuristic algorithms. In addition, in order to demonstrate the effectiveness of HDE in a more comprehensive manner, the average of the best, worst, and mean makespan values obtained for all task sizes were computed and are shown in Figure 13. This figure confirms that HDE was the most effective method for all of the metrics presented. Figure 14 depicts the average (Avg) and standard deviation (SD) of the makespan values obtained by each algorithm across all task sizes. Taking a closer look at this figure reveals that HDE was significantly more reliable than the other algorithms. It is worth mentioning that the heuristic algorithms have a negligible computation cost compared to metaheuristic algorithms, but their solutions are poor when compared to the metaheuristics algorithms. As a result, to provide a better quality of service to the users, while excluding the computational cost, the proposed algorithm is the most effective. On the other hand, if the computational cost is more important than the quality of service, then the heuristic algorithms, specifically FCFS, are the best.

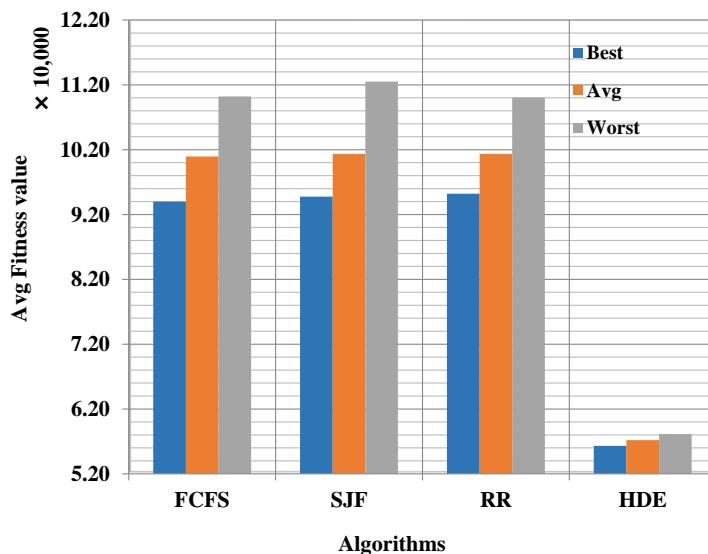


Figure 13. Comparison among algorithms for makespan.

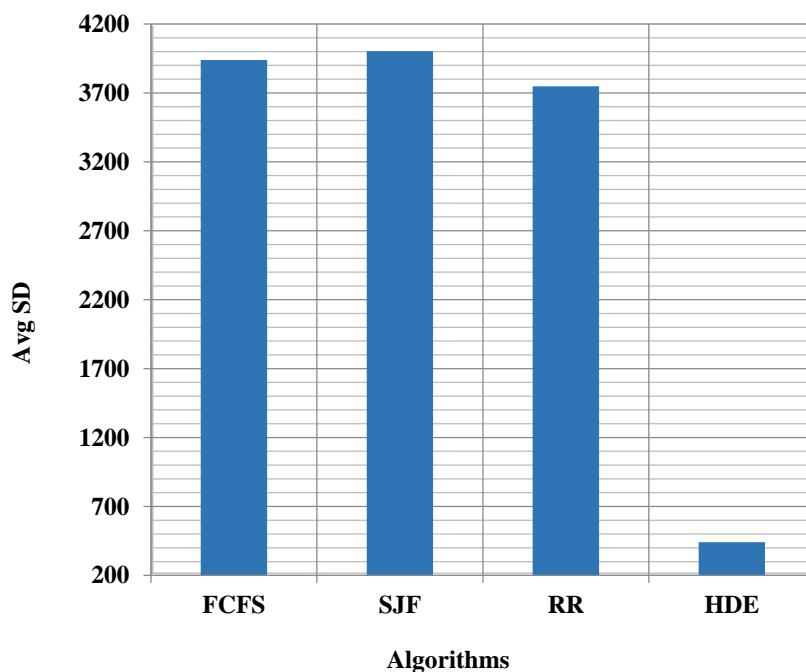


Figure 14. Comparison with heuristic algorithms in terms of the average SD of makespan.

Table 2. Parameters of the CloudSim platform.

Parameters	Value	Parameters	Value	Parameters	Value
Cloudlets		Virtual Machines			Hosts
Length of task	10,000–50,000	Number of VMs	5	No of Hosts	2
Number of tasks	100–1000	MIPs	250	RAM	2048
Filesize	300	RAM	512	Bandwidth	10,000
Outputsize	300	Bandwidth	1000	Policy type	Time Shared
Data Center		Policy type	Time Shared	Storage	1,000,000
No of DataCenter	5	VMM	Xen		
		Operating system	Linux		
		No of CPUs	1		

Table 3. Comparison among algorithms in terms of the makespan values for the Cloudsim-based simulation.

TS	EO	SCA	GWO	WOA	SMA	DE	HDE
T100	41,505.943	49,620.716	55,322.872	49,135.560	51,289.568	28,106.492	28,190.252
T200	104,498.731	102,703.632	98,004.431	96,811.803	100,997.74	54,684.484	53,803.068
T300	152,025.60	150,194.280	145,015.012	142,787.62	150,218.468	89,242.483	80,850.832
T400	200,391.084	202,607.707	191,254.443	192,639.200	195,546.292	124,179.684	108,165.464
T500	257,677.947	247,760.576	240,555.543	234,875.059	245,394.340	156,930.84	133,873.052
T600	295,715.628	310,647.336	294,597.264	286,597.052	296,876.432	199,452.735	164,761.723
T700	352,201.252	334,329.304	342,978.004	317,822.051	328,948.300	236,092.719	190,732.984
T800	389,077.392	376,469.660	398,101.811	384,081.343	378,277.532	277,318.875	219,123.340
T900	467,415.788	417,388.984	421,371.248	434,179.028	428,612.683	322,661.800	252,311.644
T1000	487,985.68	473,096.840	477,129.911	491,821.971	474,688.392	358,680.556	282,979.820
Avg:	274,849.5045	266,481.9035	266,433.0539	263,075.0687	265,084.9747	184,735.0668	151,479.2179

The bold values indicate the best values.

7. Conclusions and Future Work

This paper presents a new scheduler, namely hybrid differential evolution (HDE), for the task scheduling problem in the cloud computing environment. This scheduler is based on two proposed improvements to the classical differential evolution. The first improvement is based on improving the scaling factor, to involve numerical values generated dynamically based on the current iteration, to improve both the exploration and exploitation operators; meanwhile the second improvement is designed to further improve the exploitation operator of the classical DE, to achieve better outcomes in a smaller number of iterations. Several experiments were performed using randomly generated datasets and the CloudSim simulator, to verify the efficiency of HDE. In addition, HDE was compared with several heuristic and metaheuristic algorithms, such as the slime mold algorithm (SMA), equilibrium optimizer (EO), sine cosine algorithm (SCA), whale optimization algorithm (WOA), grey wolf optimizer (GWO), classical DE, first come first served (FCFS), round robin (RR) algorithm, and shortest job first (SJF) scheduler. Makespan and total execution time values were obtained for various task sizes, ranging between 100 and 3000, during the experiments. The findings of the experiments indicated that HDE produced effective results when compared to the other metaheuristic and heuristic algorithms that were investigated. As a result, HDE was the most effective metaheuristic scheduling algorithm among the many approaches that were investigated. In future work, HDE will be employed to tackle several other optimization problems, such as the DNA fragment assembly problem, image segmentation problem, 0-1 knapsack problem, and task scheduling problem in fog computing.

Author Contributions: Conceptualization, M.A.-B., R.M. and W.A.E.; methodology, M.A.-B., R.M., W.A.E. and K.M.S.; software, M.A.-B., R.M. and W.A.E.; validation, M.A.-B., R.M., W.A.E., M.S. and K.M.S.; formal analysis, M.A.-B., R.M., W.A.E. and K.M.S.; investigation, M.A.-B., R.M., W.A.E. and K.M.S.; data curation, M.A.-B., R.M., W.A.E., M.S. and K.M.S.; writing—original draft preparation, M.A.-B., R.M. and W.A.E.; writing—review and editing M.A.-B., R.M., W.A.E., M.S. and K.M.S.; visualization, M.A.-B., R.M., W.A.E. and K.M.S.; supervision, M.A.-B.; funding acquisition, M.S. All authors have read and agreed to the published version of the manuscript.

Funding: This research received no external funding.

Data Availability Statement: Not applicable.

Conflicts of Interest: The authors declare no conflict of interest.

Appendix A. Comparison with Some Heuristic and Metaheuristic Algorithms

Table A1. Comparison with some metaheuristic algorithms for the fitness values.

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T100	Best	18,265.116	24,611.809	24,088.115	19,972.837	24,613.264	15,150.553	15,137.092
	Avg	19,571.000	25,528.000	25,375.000	21,258.000	25,704.000	15,196.000	15,274.000
	Worst	21,498.010	26,402.739	26,051.051	22,205.813	26,752.888	15,257.978	15,558.919
	SD	713.524	463.258	424.731	558.666	521.104	30.572	91.663
T200	Best	42,426.362	48,950.808	49,292.426	42,546.316	49,025.035	29,373.841	28,909.445
	Avg	44,394.000	50,538.000	50,422.000	44,527.000	50,967.000	29,627.000	29,231.000
	Worst	45,476.446	51,690.914	51,790.672	46,474.198	52,320.876	30,126.857	29,605.929
	SD	828.993	778.633	618.134	1021.092	811.779	184.835	184.273
T300	Best	69,067.191	74,866.300	74,062.850	66,476.677	75,546.109	46,803.516	43,810.658
	Avg	71,383.000	76,534.000	77,081.000	69,943.000	76,864.000	47,615.000	44,284.000
	Worst	73,579.777	78,080.754	78,483.051	73,289.182	78,743.006	48,568.449	44,801.076
	SD	1134.455	867.221	1041.396	1443.511	874.786	430.618	255.008
T400	Best	95,440.911	98,432.590	99,668.262	92,093.906	99,673.090	64,938.822	58,147.125
	Avg	98,176.000	102,045.000	102,211.000	94,585.000	102,252.000	66,478.000	58,708.000
	Worst	101,000.236	104,376.315	104,112.797	98,252.609	105,053.622	67,814.981	59,395.477
	SD	1348.619	1285.976	1075.139	1514.400	1256.732	701.588	323.410

Table A1. Cont.

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T500	Best	120,119.573	123,408.542	123,758.958	115,201.767	125,660.988	84,738.675	72,282.977
	Avg	123,307.000	127,282.000	127,133.000	119,111.000	127,791.000	86,195.000	73,084.000
	Worst	125,568.639	129,252.182	129,228.583	122,399.771	129,623.395	87,526.696	74,219.055
	SD	1440.633	1187.152	1291.705	1697.175	919.858	809.404	463.869
T600	Best	145,919.544	149,987.437	150,121.722	142,155.751	148,997.028	106,351.443	88,355.874
	Avg	148,462.000	152,813.000	152,648.000	144,351.000	152,621.000	108,316.000	89,783.000
	Worst	151,270.871	155,095.573	154,638.766	146,586.770	155,053.210	110,123.047	91,415.701
	SD	1292.904	1264.745	1003.265	1346.239	1435.543	980.036	646.848
T700	Best	171,248.666	174,068.432	172,269.168	162,866.453	171,421.871	128,092.342	103,753.063
	Avg	173,404.000	176,365.000	176,581.000	168,979.000	176,401.000	129,789.000	105,350.000
	Worst	177,380.381	178,450.265	180,508.600	174,375.747	179,642.085	131,573.149	107,198.432
	SD	1388.031	1166.368	1703.244	2689.929	1563.520	800.844	750.188
T800	Best	197,457.353	200,198.689	199,590.942	190,388.160	200,882.988	149,519.095	117,842.491
	Avg	201,048.000	203,729.000	203,492.000	195,286.000	203,970.000	152,379.000	120,551.000
	Worst	204,902.594	206,534.694	207,776.148	200,825.073	206,878.190	154,292.126	123,731.662
	SD	1683.470	1656.565	1899.381	2196.411	1523.478	1199.194	1176.508
T900	Best	223,704.461	226,558.832	226,409.487	217,996.729	226,114.867	172,082.041	135,865.435
	Avg	226,980.000	229,924.000	230,362.000	222,388.000	229,935.000	174,181.000	137,631.000
	Worst	229,921.195	233,724.590	233,488.493	225,639.051	233,651.341	176,793.002	139,246.915
	SD	1673.049	1834.109	1787.159	1794.545	1706.194	1229.686	863.086
T1000	Best	247,875.320	249,814.443	250,647.285	242,389.074	250,741.549	194,418.935	152,868.454
	Avg	251,792.000	253,414.000	253,521.000	246,631.000	253,945.000	196,598.000	155,350.000
	Worst	254,529.450	257,498.878	256,169.629	250,551.728	256,575.530	198,807.888	157,666.486
	SD	1615.810	1823.711	1598.983	1604.413	1469.167	1146.393	1329.473
T1200	Best	272,161.798	275,012.674	273,177.920	266,930.950	275,918.637	215,439.409	168,684.208
	Avg	276,665.000	278,762.000	278,623.000	272,150.000	279,459.000	218,984.000	172,241.000
	Worst	279,816.799	282,024.626	282,025.504	277,318.739	281,727.579	220,993.332	175,396.503
	SD	1654.505	1979.462	2136.547	2217.506	1530.659	1458.254	1543.670
T1500	Best	297,700.056	301,895.921	300,516.283	289,987.072	301,107.227	240,484.692	188,831.791
	Avg	302,389.000	304,816.000	305,067.000	297,244.000	304,918.000	243,074.000	192,415.000
	Worst	306,262.646	306,790.966	307,331.538	300,181.346	308,731.491	245,362.366	195,299.922
	SD	2105.256	1457.285	1731.171	2124.410	1735.142	1424.956	1558.728
T2000	Best	324,305.532	328,468.897	328,886.931	318,205.762	325,580.330	265,211.125	209,699.639
	Avg	329,160.000	331,652.000	331,396.000	323,903.000	330,530.000	268,229.000	212,927.000
	Worst	332,916.550	335,830.685	334,367.352	329,829.207	334,457.438	270,526.428	216,136.640
	SD	2167.010	1789.437	1634.825	2473.637	1970.316	1248.839	1521.468
T2500	Best	349,691.604	350,883.081	352,358.092	343,367.024	351,080.666	286,532.304	224,756.706
	Avg	353,786.000	355,235.000	355,558.000	348,528.000	355,706.000	289,731.000	228,761.000
	Worst	357,011.837	359,479.690	358,061.266	352,923.652	360,249.932	292,567.734	233,007.159
	SD	1762.202	1972.154	1614.774	2190.929	2216.089	1639.396	1996.000
T3000	Best	374,687.613	374,116.100	378,044.013	368,165.769	374,348.289	308,332.567	247,888.247
	Avg	380,344.000	382,277.000	382,538.000	375,197.000	381,730.000	314,351.000	250,242.000
	Worst	384,988.196	386,465.343	386,075.515	380,355.337	386,174.587	317,335.349	253,382.767
	SD	2444.072	2658.810	2068.051	2672.652	2505.108	2100.287	1509.886

The bold values indicate the best values.

Table A2. Comparison among algorithms for the makespan values.

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T100	Best	9438.672	11,947.637	12,712.777	10,884.463	11,975.781	6944.882	6944.882
	Avg	10,516.000	12,859.000	13,645.000	11,750.000	12,807.000	7010.000	7013.000
	Worst	12,883.040	14,826.337	15,092.457	12,654.819	13,823.656	7137.436	7129.975
	SD	653.494	683.114	571.680	447.619	553.510	40.354	43.224
T200	Best	22,547.028	23,002.456	23,210.790	21,671.230	23,050.308	13,431.827	13,185.932
	Avg	24,472.000	24,684.000	25,148.000	23,759.000	24,660.000	13,594.000	13,348.000
	Worst	26,066.689	26,378.086	27,355.248	25,403.570	26,345.011	14,041.473	13,538.203
	SD	829.519	960.601	1163.940	882.523	888.877	129.345	91.631

Table A2. *Cont.*

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T300	Best	36,947.699	34,559.880	34,731.946	34,232.690	35,303.618	21,389.497	19,972.977
	Avg	38,439.000	36,801.000	37,327.000	36,425.000	36,938.000	21,878.000	20,194.000
	Worst	40,431.356	38,900.228	41,404.623	39,453.807	39,017.019	22,363.346	20,472.578
	SD	976.881	909.559	1666.857	1116.936	854.587	228.565	127.459
T400	Best	48,955.367	45,647.852	46,915.152	46,597.809	46,455.141	29,617.292	26,444.417
	Avg	51,779.000	48,799.000	48,556.000	48,947.000	48,528.000	30,500.000	26,731.000
	Worst	55,070.040	51,597.179	52,287.562	51,820.391	50,765.243	31,290.145	27,121.008
	SD	1509.922	1383.763	1272.435	1346.970	1208.233	400.760	161.878
T500	Best	61,001.750	57,658.760	57,566.241	58,607.792	59,016.133	38,674.036	32,957.020
	Avg	64,916.000	60,584.000	60,244.000	60,900.000	60,608.000	39,487.000	33,269.000
	Worst	67,560.243	64,112.117	62,532.085	63,017.762	62,815.301	40,093.788	33,819.042
	SD	1560.291	1421.079	1234.821	1193.972	940.158	417.670	224.071
T600	Best	73,229.925	69,331.153	69,586.533	69,647.496	68,512.668	48,727.438	40,158.207
	Avg	76,445.000	72,328.000	72,067.000	72,844.000	72,158.000	49,612.000	40,845.000
	Worst	80,532.895	77,530.876	75,054.437	77,227.793	749,26.269	50,879.790	41,495.153
	SD	1701.605	1594.430	1333.427	1659.749	1515.736	541.237	292.474
T700	Best	84,822.010	81,046.928	80,384.642	79,314.560	79,554.619	58,557.297	47,217.700
	Avg	88,690.000	83,167.000	83,246.000	84,249.000	82,848.000	59,386.000	47,921.000
	Worst	93,188.460	85,347.315	86,615.127	87,747.237	86,999.870	60,544.019	48,675.067
	SD	2128.515	1231.305	1612.775	1790.731	1662.438	460.926	330.657
T800	Best	96,380.442	92,521.921	92,321.704	91,262.035	93,067.232	68,677.526	53,779.212
	Avg	100,603.000	95,559.000	95,873.000	96,413.000	96,213.000	69,688.000	54,867.000
	Worst	106,564.905	98,404.951	99,524.222	100,831.242	101,401.679	70,661.792	56,282.630
	SD	2414.587	1423.826	2017.753	2166.084	2066.140	513.065	545.623
T900	Best	108,229.730	103,645.560	104,628.113	105,548.365	104,277.133	78,792.104	61,758.499
	Avg	113,582.000	107,669.000	107,999.000	109,495.000	107,688.000	79,775.000	62,626.000
	Worst	120,148.440	112,419.694	114,072.174	111,749.833	111,998.498	81,359.462	63,399.167
	SD	2850.589	2007.737	2051.189	1641.801	1715.424	624.858	408.529
T1000	Best	118,736.975	115,138.440	115,625.172	116,100.770	116,206.118	88,832.449	69,515.446
	Avg	123,279.000	118,956.000	119,125.000	120,234.000	118,929.000	90,012.000	70,684.000
	Worst	129,183.176	122,706.004	122,156.907	124,499.643	124,431.728	93,798.984	71,658.817
	SD	2489.881	1666.849	1659.843	2417.331	1778.316	874.974	620.257
T1200	Best	129,795.983	126,954.152	126,249.252	127,570.871	127,972.633	98,118.160	76,652.611
	Avg	134,908.000	130,688.000	130,519.000	132,035.000	130,779.000	100,158.000	78,409.000
	Worst	141,397.459	135,719.950	134,650.907	139,766.474	136,984.431	101,266.796	79,725.686
	SD	2309.279	1870.231	2018.753	2729.933	2251.355	774.466	705.732
T1500	Best	138,804.579	138,898.602	139,292.203	139,693.196	138,606.731	109,581.936	85,953.213
	Avg	145,796.000	142,250.000	142,775.000	143,012.000	142,380.000	111,340.000	87,520.000
	Worst	153,587.370	145,607.443	150,992.953	147,576.341	146,704.239	114,272.274	89,009.316
	SD	3283.758	1526.583	2390.077	1991.793	1614.124	1072.070	721.108
T2000	Best	151,784.006	151,264.096	150,594.060	149,722.432	151,191.472	121,190.063	95,349.975
	Avg	157,611.000	155,420.000	154,648.000	155,396.000	154,322.000	122,618.000	96,813.000
	Worst	166,344.617	160,214.293	159,508.888	161,005.512	159,349.068	123,936.506	98,162.927
	SD	3677.971	2504.031	2137.704	2628.660	1852.858	637.741	698.603
T2500	Best	160,529.235	160,637.179	162,072.574	161,144.576	161,100.021	130,477.400	102,136.632
	Avg	169,506.000	165,738.000	166,038.000	166,450.000	165,581.000	132,810.000	104,022.000
	Worst	179,163.135	171,771.518	169,385.501	173,371.558	169,513.351	134,690.256	106,190.281
	SD	4406.047	2343.341	1588.846	2503.864	2282.155	925.081	933.183
T3000	Best	172,070.805	172,887.505	173,311.921	174,193.094	173,026.585	142,122.392	112,625.384
	Avg	181,066.000	177,940.000	178,119.000	178,707.000	177,882.000	144,111.000	113,811.000
	Worst	187,904.224	184,878.509	182,574.837	183,514.827	181,860.483	147,212.405	115,274.338
	SD	3690.548	2693.045	2364.794	2069.685	2493.556	1188.774	701.579

The bold values indicate the best values.

Table A3. Comparison among algorithms for total execution time.

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T100	Best	38,115.003	50,570.643	49,339.028	40,070.182	52,314.209	34,167.699	34,184.939
	Avg	40,701.000	55,087.000	52,746.000	43,443.000	55,795.000	34,298.000	34,550.000
	Worst	43,980.020	57,190.514	56,010.407	46,197.991	57,836.610	34,461.035	35,226.454
	SD	1093.390	1509.796	1560.900	1514.701	1342.057	74.832	228.008
T200	Best	86,987.143	105,072.258	103,976.815	87,848.691	108,440.506	66,302.970	65,521.241
	Avg	90,879.000	110,862.000	109,394.000	92,988.000	112,350.000	67,038.000	66,290.000
	Worst	95,059.361	114,933.861	113,761.796	98,376.422	115,141.894	67,843.837	67,119.554
	SD	2114.152	2408.720	2660.714	2577.679	1907.367	414.783	429.283
T300	Best	140,739.328	164,556.186	161,414.947	141,130.001	165,788.713	105,870.995	99,269.263
	Avg	148,252.000	169,244.000	169,843.000	148,151.000	170,026.000	107,669.000	100,496.000
	Worst	151,986.556	172,666.021	175,454.835	155,885.560	174,514.307	109,713.690	101,829.995
	SD	2883.541	1929.747	3292.297	3351.197	2029.973	1011.817	610.498
T400	Best	197,268.901	220,893.125	220,314.876	194,313.759	223,848.304	146,681.999	132,120.112
	Avg	206,434.000	226,286.000	227,406.000	201,072.000	227,607.000	150,428.000	133,321.000
	Worst	212,775.565	233,178.780	233,772.309	213,052.367	234,076.000	153,333.362	134,949.635
	SD	3429.782	2590.382	2766.779	4734.105	2765.688	1528.621	718.928
T500	Best	250,376.325	276,708.351	275,486.339	245,134.200	28,0346.649	191,901.169	164,043.543
	Avg	259,553.000	282,911.000	283,207.000	254,935.000	284,552.000	195,182.000	165,984.000
	Worst	268,501.754	288,230.427	288,712.693	264,972.627	289,984.941	198,374.617	168,523.978
	SD	4225.905	2899.368	3376.512	4857.550	2312.076	1837.159	1043.599
T600	Best	305,869.915	333,578.543	335,046.072	298,840.145	331,419.196	240,743.608	200,817.097
	Avg	316,503.000	340,612.000	340,669.000	311,202.000	340,368.000	245,292.000	203,972.000
	Worst	322,769.104	345,645.788	346,242.900	320,955.422	346,933.177	249,268.571	207,896.980
	SD	4545.269	2832.242	2863.235	4729.092	3649.364	2146.239	1492.645
T700	Best	357,976.309	386,497.338	386,666.396	348,756.713	384,774.422	290,119.422	235,668.911
	Avg	371,070.000	393,829.000	394,363.000	366,683.000	394,693.000	294,062.000	239,351.000
	Worst	378,442.442	401,305.913	400,091.078	380,151.696	402,525.765	297,527.211	243,753.678
	SD	4873.732	3716.885	3533.207	8468.329	3321.936	1805.772	1741.489
T800	Best	426,788.885	443,078.326	445,461.575	413,981.425	446,848.296	337,406.050	267,323.474
	Avg	435,421.000	456,128.000	454,603.000	425,991.000	455,402.000	345,326.000	273,815.000
	Worst	447,835.415	462,814.404	465,671.838	440,590.901	462,478.406	350,468.826	281,112.735
	SD	5155.694	4975.650	4760.611	6537.117	3175.612	3129.091	2672.983
T900	Best	477,747.825	508,820.405	507,406.435	474,814.038	505,128.246	388,859.617	308,781.618
	Avg	491,572.000	515,186.000	515,877.000	485,805.000	515,177.000	394,463.000	312,644.000
	Worst	500,984.743	522,422.130	524,740.549	497,009.192	523,713.793	401,004.355	316,484.309
	SD	5365.567	3128.123	4096.034	5414.481	4544.028	3238.249	1943.345
T1000	Best	537,828.097	557,237.156	556,031.484	524,852.018	558,305.219	439,473.809	347,358.806
	Avg	551,656.000	567,151.000	567,112.000	541,558.000	568,982.000	445,298.000	352,903.000
	Worst	563,670.866	575,833.134	574,415.860	553,355.183	575,042.293	451,669.178	358,351.049
	SD	6829.226	4411.820	4635.891	6413.167	3339.505	2816.904	3011.747
T1200	Best	588,406.658	616,501.616	609,146.791	585,013.689	612,946.921	489,188.988	383,424.603
	Avg	607,433.000	624,268.000	624,202.000	599,085.000	626,378.000	496,245.000	391,183.000
	Worst	621,660.221	633,980.837	632,138.961	612,439.335	634,727.265	501,846.993	398,628.411
	SD	6446.235	4055.883	5021.459	7582.436	5868.540	3414.373	3541.414
T1500	Best	645,910.065	678,355.899	671,733.428	640,448.075	677,639.783	545,069.758	428,881.806
	Avg	667,774.000	684,136.000	683,749.000	657,119.000	684,171.000	550,454.000	437,170.000
	Worst	690,938.157	694,111.491	693,117.184	666,430.377	695,449.033	556,975.679	443,311.339
	SD	8351.155	3736.241	5531.450	6816.146	4114.685	3010.062	3530.292
T2000	Best	712,207.300	733,380.764	737,130.722	702,518.639	731,200.908	599,158.246	476,515.523
	Avg	729,441.000	742,861.000	743,809.000	717,086.000	741,682.000	607,988.000	483,857.000
	Worst	741,210.983	752,039.100	753,733.583	730,721.668	749,436.738	613,091.297	491,408.639
	SD	6883.118	4637.338	4247.121	6992.119	4927.330	3101.014	3462.359
T2500	Best	765,728.675	787,262.395	785,012.916	755,291.076	791,036.794	646,478.360	510,870.211
	Avg	783,772.000	797,394.000	797,769.000	773,376.000	799,331.000	655,880.000	519,819.000
	Worst	796,845.810	805,270.438	809,131.565	789,947.532	808,619.056	661,680.775	528,913.206
	SD	7897.303	4431.070	5327.938	8487.814	4819.742	3862.820	4496.779

Table A3. Cont.

TS		EO	SCA	GWO	WOA	SMA	DE	HDE
T3000	Best	830,030.908	843,649.488	851,616.785	810,725.718	843,766.365	696,078.733	563,250.918
	Avg	845,325.000	859,065.000	859,517.000	833,672.000	857,376.000	711,579.000	568,580.000
	Worst	860,345.325	868,701.031	866,711.674	846,150.448	867,698.102	718,347.423	575,635.766
	SD	7084.137	5029.439	3972.881	8360.492	5830.941	5256.236	3441.967

The bold values indicate the best value.

Table A4. Comparison using a Wilcoxon rank sum test between HDE and each compared algorithm, in terms of fitness values.

TS		EO	SCA	GWO	WOA	SMA	DE
T100	<i>h-</i>	3.01986×10^{-11}	6.35455×10^{-5}				
	<i>p-</i>	1	1	1	1	1	1
T200	<i>h-</i>	3.01986×10^{-11}	7.77255×10^{-9}				
	<i>p-</i>	1	1	1	1	1	1
T300	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T400	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T500	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T600	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T700	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T800	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T900	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1
T1000	<i>h-</i>	3.01986×10^{-11}					
	<i>p-</i>	1	1	1	1	1	1

The Bold font indicates that there is a difference between the outcomes of HDE and those of the competitors.

Table A5. Comparison with heuristic algorithms for the total execution time and makespan.

		FCFS		SJF		RR		HDE	
TS		MS	Total Execution	MS	Total Execution	MS	Total Execution	MS	Total Execution
T100	Best	12,344.292	53,662.706	12,398.820	55,392.648	13,303.341	55,738.997	6944.882	34,184.939
	Avg	14,910.000	58,624.000	14,562.000	59,537.000	15,390.000	59,010.000	7013.000	34,550.000
	Worst	17,044.315	62,160.312	18,442.821	64,955.074	20,028.542	62,707.336	7129.975	35,226.454
	SD	1285.666	2349.561	1369.898	2201.344	1582.706	1824.601	43.224	228.008
T200	Best	22,844.658	110,292.306	24,328.549	112,870.669	24,911.324	111,094.478	13,185.932	65,521.241
	Avg	27,145.000	115,596.000	28,231.000	117,153.000	27,956.000	117,593.000	13,348.000	66,290.000
	Worst	31,734.097	121,304.186	33,372.631	124,674.725	30,746.313	122,266.950	13,538.203	67,119.554
	SD	1896.645	2616.447	2440.761	2513.921	1461.083	2916.001	91.631	429.283
T300	Best	36,401.175	167,860.710	35,551.337	169,794.780	37,405.544	170,045.361	19,972.977	99,269.263
	Avg	40,855.000	174,596.000	40,437.000	175,831.000	40,835.000	174,987.000	20,194.000	100,496.000
	Worst	48,259.582	181,227.236	46,488.415	184,826.161	45,607.496	182,173.616	20,472.578	101,829.995
	SD	3164.196	3007.580	2540.009	3417.183	2145.982	2568.089	127.459	610.498
T400	Best	48,561.026	222,538.649	47,999.873	226,957.706	47,704.192	223,741.723	26,444.417	132,120.112
	Avg	53,428.000	233,554.000	53,169.000	233,803.000	52,562.000	232,425.000	26,731.000	133,321.000
	Worst	61,278.109	246,043.696	61,410.113	241,419.656	56,838.183	240,902.340	27,121.008	134949.635
	SD	3014.512	4164.430	2703.758	3817.347	2201.783	4461.438	161.878	718.928
T500	Best	60,671.925	284,463.880	60,666.928	282,672.617	61,382.773	283,534.055	32,957.020	164,043.543
	Avg	65,297.000	291,399.000	66,204.000	291,909.000	65,410.000	291,712.000	33,269.000	165,984.000
	Worst	73,599.101	301,398.628	76,683.101	300,649.387	74,272.381	297,917.527	33,819.042	168,523.978
	SD	3065.808	3745.909	4217.987	4207.052	3169.840	2995.869	224.071	1043.599

Table A5. Cont.

TS		FCFS		SJF		RR		HDE	
		MS	Total Execution	MS	Total Execution	MS	Total Execution	MS	Total Execution
T600	Best	71,384.337	338,853.354	71,876.123	339,199.141	72,118.680	338,253.551	40,158.207	200,817.097
	Avg	77,058.000	348,454.000	78,169.000	347,967.000	77,937.000	347,189.000	40,845.000	203,972.000
	Worst	83,617.806	361,268.968	91,370.647	360,625.466	86,283.611	353,966.290	41,495.153	207,896.980
	SD	3655.534	5785.572	4347.694	5222.763	3596.340	3873.134	292.474	1492.645
T700	Best	82,871.222	389,875.874	83,096.043	393,296.088	81,664.036	394,618.246	47,217.700	235,668.911
	Avg	88,977.000	403,648.000	88,430.000	402,422.000	89,694.000	404,010.000	47,921.000	239,351.000
	Worst	101,824.324	415,541.874	97,387.359	412,616.229	100,040.623	421,919.793	48,675.067	243,753.678
	SD	3883.562	6357.864	3321.412	4165.120	4360.224	5737.322	330.657	1741.489
T800	Best	95,526.392	451,999.107	95,363.041	449,490.324	92,544.224	449,997.947	53,779.212	267,323.474
	Avg	102,116.000	464,544.000	101,688.000	464,338.000	102,840.000	463,833.000	54,867.000	273,815.000
	Worst	110,433.706	473,190.025	113,090.328	473,467.814	114,386.119	475,437.101	56,282.630	281,112.735
	SD	3423.486	4557.432	4046.083	5894.821	4732.558	6066.622	545.623	2672.983
T900	Best	108,219.570	507,238.701	106,632.715	512,446.913	107,182.309	512,662.893	61,758.499	308,781.618
	Avg	113,943.000	524,054.000	114,563.000	523,459.000	114,571.000	524,364.000	62,626.000	312,644.000
	Worst	122,612.509	542,323.705	126,840.703	539,681.496	123,633.119	538,450.021	63,399.167	316,484.309
	SD	4002.028	6410.736	4548.561	6594.319	4337.906	5915.235	408.529	1943.345
T1000	Best	115,252.394	562,357.362	115,970.112	563,944.718	117,570.996	564,348.540	69,515.446	347,358.806
	Avg	123,900.000	575,167.000	124,553.000	577,018.000	124,977.000	576,748.000	70,684.000	352,903.000
	Worst	132,163.539	584,019.817	139,114.933	594,497.693	134,407.616	590,320.838	71,658.817	358,351.049
	SD	3776.393	5114.537	4821.304	6486.320	4500.341	5778.815	620.257	3011.747
T1200	Best	126,473.499	622,184.636	128,882.364	619,891.703	129,100.117	620,290.715	76,652.611	383,424.603
	Avg	137,267.000	637,357.000	137,832.000	636,864.000	136,112.000	634,428.000	78,409.000	391,183.000
	Worst	148,752.105	656,539.187	150,051.311	650,397.990	143,371.287	647,445.075	79,725.686	398,628.411
	SD	4887.727	8273.490	4775.503	6534.292	3190.396	6837.603	705.732	3541.414
T1500	Best	138,646.670	679,212.397	142,046.487	679,305.037	145,002.492	684,350.824	85,953.213	428,881.806
	Avg	149,618.000	693,741.000	150,234.000	695,673.000	151,079.000	696,135.000	87,520.000	437,170.000
	Worst	165,002.833	707,135.205	164,234.551	708,533.638	160,514.410	708,776.628	89,009.316	443,311.339
	SD	6078.265	7948.496	5151.143	7429.044	4560.286	5537.040	721.108	3530.292
T2000	Best	153,066.964	737,643.035	153,299.956	734,958.438	152,479.492	740,924.563	95,349.975	476,515.523
	Avg	161,641.000	754,762.000	162,568.000	754,581.000	159,989.000	752,314.000	96,813.000	483,857.000
	Worst	175,933.006	763,273.414	184,308.530	766,039.466	170,141.689	770,347.951	98,162.927	491,408.639
	SD	5660.829	6387.341	5766.332	7228.589	4479.952	7333.449	698.603	3462.359
T2500	Best	161,397.176	794,939.206	165,571.473	792,458.130	166,885.056	799,726.645	102,136.632	510,870.211
	Avg	173,614.000	809,173.000	172,776.000	810,402.000	174,375.000	812,225.000	104,022.000	519,819.000
	Worst	184,331.464	824,648.829	183,006.363	827,132.424	189,002.607	824,028.335	106,190.281	528,913.206
	SD	5457.343	7346.403	4412.046	7584.300	5523.036	6417.060	933.183	4496.779
T3000	Best	176,200.277	852,165.434	177,661.627	853,232.663	178,819.097	859,423.967	112,625.384	563,250.918
	Avg	184,378.000	866,586.000	186,939.000	871,015.000	186,791.000	872,513.000	113,811.000	568,580.000
	Worst	196,778.207	885,253.124	201,877.303	892,941.694	201,607.603	888,088.876	115,274.338	575,635.766
	SD	5833.666	7420.404	5587.624	9231.738	6381.138	7657.639	701.579	3441.967

Bold value indicates the best result.

References

- El-Shafeiy, E.; Abohany, A. A new swarm intelligence framework for the Internet of Medical Things system in healthcare. In *Swarm Intelligence for Resource Management in Internet of Things*; Academic Press: Cambridge, MA, USA, 2020; pp. 87–107. [CrossRef]
- Hassan, K.M.; Abdo, A.; Yakoub, A. Enhancement of Health Care Services based on cloud computing in IOT Environment Using Hybrid Swarm Intelligence. *IEEE Access* **2022**, *10*, 105877–105886. [CrossRef]
- Nayar, N.; Ahuja, S.; Jain, S. Swarm intelligence and data mining: A review of literature and applications in healthcare. In Proceedings of the Third International Conference on Advanced Informatics for Computing Research, Shimla, India, 15–16 June 2019.
- Ben Alla, H.; Ben Alla, S.; Touhafi, A.; Ezzati, A. A novel task scheduling approach based on dynamic queues and hybrid meta-heuristic algorithms for cloud computing environment. *Clust. Comput.* **2018**, *21*, 1797–1820. [CrossRef]
- Singh, H.; Tyagi, S.; Kumar, P.; Gill, S.S.; Buyya, R. Metaheuristics for scheduling of heterogeneous tasks in cloud computing environments: Analysis, performance evaluation, and future directions. *Simul. Model. Pr. Theory* **2021**, *111*, 102353. [CrossRef]

6. Huang, X.; Li, C.; Chen, H.; An, D. Task scheduling in cloud computing using particle swarm optimization with time varying inertia weight strategies. *Clust. Comput.* **2020**, *23*, 1137–1147. [[CrossRef](#)]
7. Bezdan, T.; Zivkovic, M.; Antonijevic, M.; Zivkovic, T.; Bacanin, N. Enhanced Flower Pollination Algorithm for Task Scheduling in Cloud Computing Environment. In *Machine Learning for Predictive Analysis*; Springer: Berlin/Heidelberg, Germany, 2021; pp. 163–171. [[CrossRef](#)]
8. Choudhary, A.; Gupta, I.; Singh, V.; Jana, P.K. A GSA based hybrid algorithm for bi-objective workflow scheduling in cloud computing. *Futur. Gener. Comput. Syst.* **2018**, *83*, 14–26. [[CrossRef](#)]
9. Raghavan, S.; Sarwesh, P.; Marimuthu, C.; Chandrasekaran, K. Bat algorithm for scheduling workflow applications in cloud. In Proceedings of the 2015 International Conference on Electronic Design, Computer Networks & Automated Verification (EDCAV), Shillong, India, 29–30 January 2015; pp. 139–144.
10. Tawfeek, M.A.; El-Sisi, A.; Keshk, A.E.; Torkey, F.A. Cloud task scheduling based on ant colony optimization. In Proceedings of the 8th International Conference on Computer Engineering & Systems (ICCES), Cairo, Egypt, 26–28 November 2013; IEEE: Piscataway, NJ, USA, 2013.
11. Hamad, S.A.; Omara, F.A. Genetic-Based Task Scheduling Algorithm in Cloud Computing Environment. *Int. J. Adv. Comput. Sci. Appl.* **2016**, *7*, 550–556. [[CrossRef](#)]
12. Bacanin, N.; Bezdan, T.; Tuba, E.; Strumberger, I.; Tuba, M.; Zivkovic, M. Task Scheduling in Cloud Computing Environment by Grey Wolf Optimizer. In Proceedings of the 27th Telecommunications Forum (TELFOR), Belgrade, Serbia, 26–27 November 2019; pp. 1–4. [[CrossRef](#)]
13. Chen, X.; Cheng, L.; Liu, C.; Liu, Q.; Liu, J.; Mao, Y.; Murphy, J. A WOA-Based Optimization Approach for Task Scheduling in Cloud Computing Systems. *IEEE Syst. J.* **2020**, *14*, 3117–3128. [[CrossRef](#)]
14. Alsaidy, S.A.; Abbood, A.D.; Sahib, M.A. Heuristic initialization of PSO task scheduling algorithm in cloud computing. *J. King Saud Univ. Comput. Inf. Sci.* **2020**, *34*, 2370–2382. [[CrossRef](#)]
15. Alboaneen, D.A.; Tianfield, H.; Zhang, Y. Glowworm swarm optimisation based task scheduling for cloud computing. In Proceedings of the Second International Conference on Internet of Things, Data and Cloud Computing, Porto, Portugal, 24–26 April 2017.
16. Durgadevi, P.; Srinivasan, D.S. Task scheduling using amalgamation of metaheuristics swarm optimization algorithm and cuckoo search in cloud computing environment. *J. Res.* **2015**, *1*, 10–17.
17. Belgacem, A.; Beghdad-Bey, K.; Nacer, H. Task scheduling optimization in cloud based on electromagnetism metaheuristic algorithm. In Proceedings of the 3rd International Conference on Pattern Analysis and Intelligent Systems (PAIS), Tebessa, Algeria, 24–25 October 2018; pp. 1–7. [[CrossRef](#)]
18. Masadeh, R.; Alsharman, N.; Sharieh, A.; Mahafzah, B.; Abdulrahman, A. Task scheduling on cloud computing based on sea lion optimization algorithm. *Int. J. Web Inf. Syst.* **2021**, *17*, 99–116. [[CrossRef](#)]
19. Abdullahi, M.; Ngadi, A.; Dishing, S.I.; Abdulhamid, S.M. An adaptive symbiotic organisms search for constrained task scheduling in cloud computing. *J. Ambient Intell. Humaniz. Comput.* **2022**, *1–12*. [[CrossRef](#)]
20. Strumberger, I.; Bacanin, N.; Tuba, M.; Tuba, E. Resource Scheduling in Cloud Computing Based on a Hybridized Whale Optimization Algorithm. *Appl. Sci.* **2019**, *9*, 4893. [[CrossRef](#)]
21. Bacanin, N.; Tuba, E.; Bezdan, T.; Strumberger, I.; Tuba, M. Artificial Flora Optimization Algorithm for Task Scheduling in Cloud Computing Environment. In Proceedings of the International Conference on Intelligent Data Engineering and Automated Learning, Manchester, UK, 14–16 November 2019; pp. 437–445. [[CrossRef](#)]
22. Mansouri, N.; Zade, B.M.H.; Javidi, M.M. Hybrid task scheduling strategy for cloud computing by modified particle swarm optimization and fuzzy theory. *Comput. Ind. Eng.* **2019**, *130*, 597–633. [[CrossRef](#)]
23. Ge, J.; He, Q.; Fang, Y. Cloud computing task scheduling strategy based on improved differential evolution algorithm. In *AIP Conference Proceedings*; AIP Publishing LLC.: Melville, NY, USA, 2017. [[CrossRef](#)]
24. Li, Y.; Wang, S.; Hong, X.; Li, Y. Multi-objective task scheduling optimization in cloud computing based on genetic algorithm and differential evolution algorithm. In Proceedings of the 37th Chinese Control Conference (CCC), Wuhan, China, 25–27 July 2018; IEEE: New York, NY, USA, 2018.
25. Zhou, Z.; Li, F.; Yang, S. A Novel Resource Optimization Algorithm Based on Clustering and Improved Differential Evolution Strategy Under a Cloud Environment. *ACM Trans. Asian Low-Resource Lang. Inf. Process.* **2021**, *20*, 1–15. [[CrossRef](#)]
26. Tsai, J.-T.; Fang, J.-C.; Chou, J.-H. Optimized task scheduling and resource allocation on cloud computing environment using improved differential evolution algorithm. *Comput. Oper. Res.* **2013**, *40*, 3045–3055. [[CrossRef](#)]
27. Chen, J.; Han, P.; Liu, Y.; Du, X. Scheduling independent tasks in cloud environment based on modified differential evolution. *Concurr. Comput. Pr. Exp.* **2021**, *e6256*. [[CrossRef](#)]
28. Elaziz, M.A.; Xiong, S.; Jayasena, K.; Li, L. Task scheduling in cloud computing based on hybrid moth search algorithm and differential evolution. *Knowl.-Based Syst.* **2019**, *169*, 39–52. [[CrossRef](#)]
29. Shi, X.; Zhang, X.; Xu, M. A self-adaptive preferred learning differential evolution algorithm for task scheduling in cloud computing. In Proceedings of the 2020 IEEE International Conference on Advances in Electrical Engineering and Computer Applications (AEECA), Dalian, China, 25–27 August 2020; IEEE: Piscataway, NJ, USA, 2020.
30. Rana, N.; Abd Latiff, M.S.; Abdulhamid, S.I.M.; Misra, S. A hybrid whale optimization algorithm with differential evolution optimization for multi-objective virtual machine scheduling in cloud computing. *Eng. Optim.* **2021**, *54*, 1–18. [[CrossRef](#)]

31. Storn, R. International Computer Science Institute, Differential evolution-a simple and efficient adaptive scheme for global optimization over continuous spaces. *Tech. Rep. Int. Comput. Sci. Inst.* **1995**, *11*, 353–358.
32. Branke, J.; Deb, K.; Dierolf, H.; Osswald, M. Finding knees in multi-objective optimization. In Proceedings of the International Conference on Parallel Problem Solving from Nature, Birmingham, UK, 18–22 September 2004.
33. Marler, R.T.; Arora, J.S. Survey of multi-objective optimization methods for engineering. *Struct. Multidiscip. Optim.* **2004**, *26*, 369–395. [[CrossRef](#)]
34. Mirjalili, S. SCA: A Sine Cosine Algorithm for solving optimization problems. *Knowl. Based Syst.* **2016**, *96*, 120–133. [[CrossRef](#)]
35. Mirjalili, S.; Lewis, A. The whale optimization algorithm. *Adv. Eng. Softw.* **2016**, *95*, 51–67. [[CrossRef](#)]
36. Li, S.; Chen, H.; Wang, M.; Heidari, A.A.; Mirjalili, S. Slime mould algorithm: A new method for stochastic optimization. *Future Gener. Comput. Syst.* **2020**, *111*, 300–323. [[CrossRef](#)]
37. Faramarzi, A.; Heidarinejad, M.; Stephens, B.; Mirjalili, S. Equilibrium optimizer: A novel optimization algorithm. *Knowl.-Based Syst.* **2020**, *191*, 105190. [[CrossRef](#)]
38. Mirjalili, S.; Mirjalili, S.M.; Lewis, A. Grey wolf optimizer. *Adv. Eng. Softw.* **2014**, *69*, 46–61. [[CrossRef](#)]
39. Price, K.V. Differential evolution. In *Handbook of Optimization*; Springer: Berlin/Heidelberg, Germany, 2013; pp. 187–214.
40. Bibu, G.D.; Nwankwo, G.C. Comparative analysis between first-come-first-serve (FCFS) and shortest-job-first (SJF) scheduling algorithms. *Int. J. Comput. Sci. Mob. Comput.* **2019**, *8*, 176–181.
41. Jang, S.H.; Kim, T.Y.; Kim, J.K.; Lee, J.S. The study of genetic algorithm-based task scheduling for cloud computing. *Int. J. Control Autom.* **2012**, *5*, 157–162.
42. Haynes, W. Wilcoxon rank sum test. In *Encyclopedia of Systems Biology*; Springer: New York, NY, USA, 2013; pp. 2354–2355.