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	, v que - ,	Abgrace	agy			
Pos	ition, Velocity	, Acceleration - al	l are constrain	ed between -100	0 and 1000. If	
any	value is outsi	de this range, it w	vill be ignored.			
>	If you want t	o ignore one axis	, just enter valu	ue outside this ra	inge.	
M	ovenen	tive	w-1/ a	lo ago	× ×	
	apter	t We Java f.	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \			
	has switch_we on will be uned	apon method. If quipped	null is passed in	nside this, then t	he existing	