

## Problem Solving Using Search:

- \* Search Strategy
  - Blind / Uninformed
  - Heuristic
- \* Constraint Satisfaction Problems (No final state, only Final state test)
  - ↳ Finite Search Tree
  - ↳ All solution same depth. So path doesn't matter. (All equal)
- \* 2- Player Games

## Search FORMULATION:

- \* Initial State
- \* Final State or Final State Test (CSP)
- \* Actions (Successor function - checks if action/state are legal).

## OPTIMIZE:

1. Cost of a solution  
eg: Number of steps from IS to FS.
2. Cost of finding a solution.  
eg: 2 search strategy. Both find same solution. One does by expanding full tree, other doesn't.

## MEASURE OF DIFFICULTY OF A SEARCH PROBLEM:

1. Number of possible states (State space),
2. Branching factor
3. Depth of solution

## SEARCH PROCESS:

Repeat:

1. Find a fringe / frontier node based on the strategy.
2. Expand the node
  - Check if FS
  - Generate Children

## SEARCH STRATEGIES:

### EVALUATION:

- \* Completeness : Find solution if exists
- \* Time Complexity : Number of nodes expanded
- \* Space Complexity : Maximum number of nodes in memory,
- \* Optimality : Always find least-cost solution.

Complexity expressed in terms of

\*  $b$  : branching factor

\*  $d$  : depth of least-cost solution

\*  $m$  : maximum depth of search tree.

$$N(b, d) = 1 + b + b^2 + \dots + b^d$$

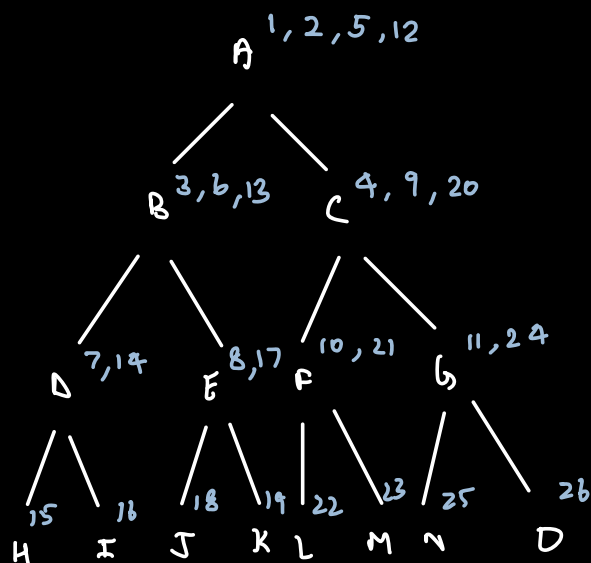
$$bN(b, d) = b + b^2 + \dots + b^{d+1}$$

$$N(b, d) = \frac{b^{d+1} - 1}{b - 1} \quad O(b^d)$$

BLIND SEARCH STRATEGIES:

	BFS	DFS	LIMITED DFS( $l$ )	ITERATIVE DEEPENING
Complete	✓	✗	$d \leq l$	✓
Optimal	✓	✗	✗	✓
TC	$b^d$	$b^m$	$b^l$	$b^d$
SC	$b^d$	$b_m$	$b_l$	$b_d$

ID:

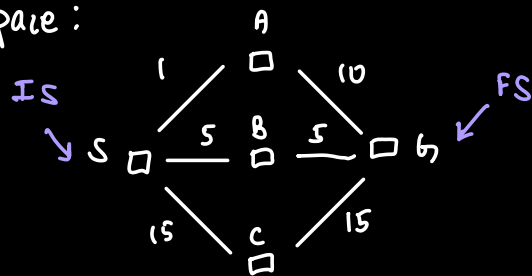


# HEURISTIC SEARCH STRATEGIES:

$h(n)$ : Heuristic

	UNIFORM COST SEARCH	GREEDY BEST FIRST SEARCH	A* SEARCH
Complete	✓	✗	✓
Optimal	✓	✗	✓ (if $h(n)$ is admissible)
TC	$\frac{\sqrt{c^* / \epsilon}}{b}$		
SC	$\frac{\sqrt{c^* / \epsilon}}{b}$		
COST	$g(n)$ Distance travelled till 'n'	$h(n)$ Straight line distance from n to goal	Evaluation : $f(n) = g(n) + h(n)$ function

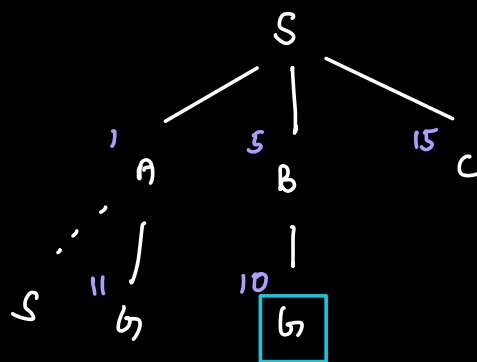
State space:



Choose least  
costly fringe  
node to expand

UCS:

Choose least  
costly fringe  
node to expand  
(generalize BFS)



$$g(B) = 5$$

$$g(G) = 10$$

GOAL

S - B - G

(cost is 10)

$\epsilon$ : Smallest cost of any action

Optimal cost:  $c^*$

Optimal Depth  $\leq \lceil c^* / \epsilon \rceil$

BFS  $\subseteq$  UCS

$S_0$   $b^d$  and  $d = \lceil c^* / \epsilon \rceil$

HEURISTIC: Admissible

$h(n) \leq h^*(n)$  [least cost to go from  $n$  to goal]

$h(n) \geq 0$

$\hookrightarrow h(n) = 0$  for a goal state  $n$ .

$h(n) \equiv$  admissible  $\Rightarrow A^*$  is optimal

## CONSTRAINT SATISFACTION PROBLEMS (CSPs):

PRIMAL / CONSTRAINT GRAPH:

connect nodes that are in a constraint.

TYPES:

Unary vs Binary vs Higher-constraints

Hard vs Soft.

STRATEGY: DFS

IMPROVEMENTS:

1. BACKTRACK SEARCH:

Avoid children that violate constraints.

Iterate through constraints and see if assignment violates it.

Variable

Domain

Constraints

## 2. VALUE ORDERING:

Least constraining value; Choose value that rules out the fewest values of remaining variables.

## 3. VARIABLE ORDERING:

Most constrained variable; Choose variable with fewest legal values.

## 4. FORWARD CHECKING (FC):

- \* Maintain set of possible values for each variable.
- \* Update as you assign.
- \* Declare "bad state" if variable loses all values.

## 5. ARC CONSISTENCY (AC):

- \* Draw arcs between constrained variables with their allowed values

\* Arc  $x \rightarrow y$  is consistent if

$\forall$  value of  $x$ , there is a compatible value for  $y$ .

$$O(n^2 d^3)$$

## TWO PLAYER GAMES:

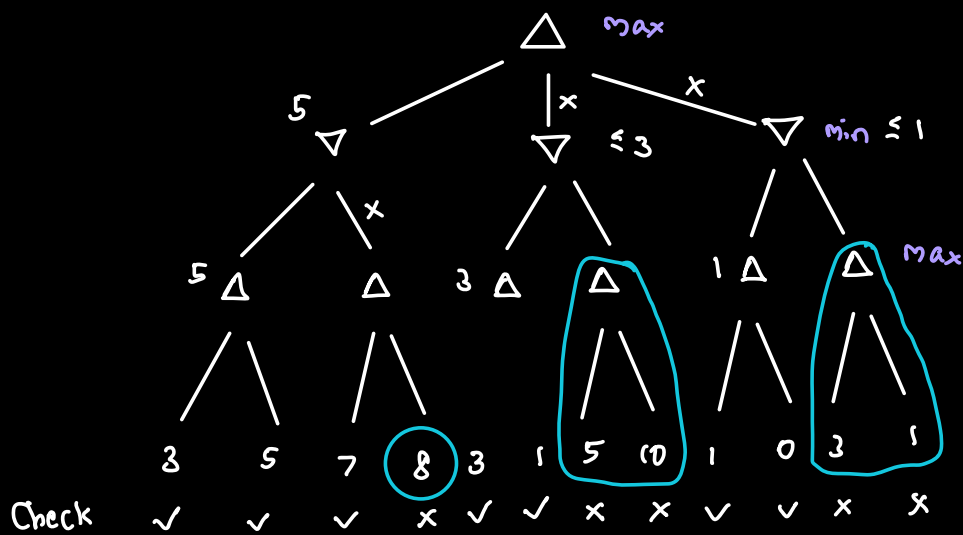
See it as one player move followed by another.  
Terminal states (Not Goal / Final)

## MINIMAX ALGORITHM:

Player 1 maximizes, 2 minimizes.

DFS.  $O(b^d)$ .

## $\alpha$ - $\beta$ PRUNING:

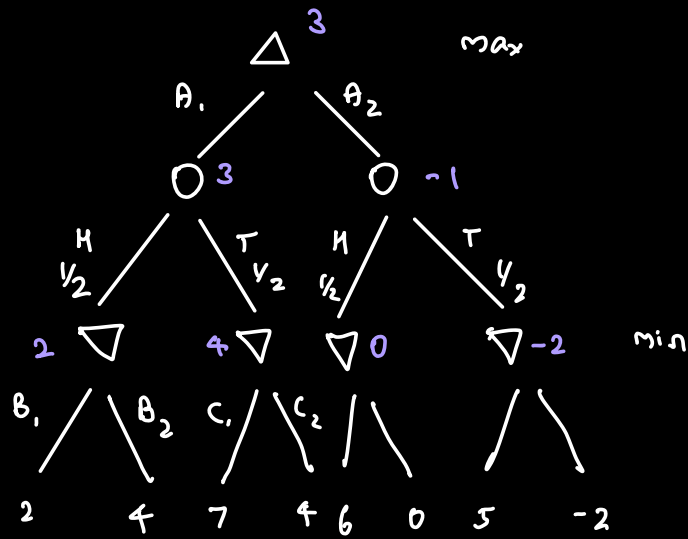


Best case:  $O(b^{d/2})$



# GAMES WITH CHANCE:

Expected Minimax:



## PROPOSITIONAL LOGIC:

### SYNTAX:

1.  $\alpha \Rightarrow \beta$

$\neg \beta \Rightarrow \neg \alpha$  CONTRAPOSITIVE

2.  $\alpha \Rightarrow \beta$

$\neg \alpha \vee \beta$

3.  $\neg (\alpha \wedge \beta)$

$\neg \alpha \vee \neg \beta$

4.  $\neg (\alpha \vee \beta)$

$\neg \alpha \wedge \neg \beta$

DE MORGAN'S LAW

a. Boolean Variables

b.  $\wedge, \vee, \neg, \Rightarrow, \Leftrightarrow$

c. Variable is sentence

$S_1, S_2$  are sentences, then

$\neg S_1, S_1 \wedge S_2 \dots$

sentences.

### NORMAL FORMS:

	UNIVERSAL	TRACTABLE (SAT is easy)
CNF	✓	
DNF	✓	✓
HORN		✓
NNF	✓	
DNF CIRCUITS	✓	✓

CNF: Conjunction of clauses  
( $\wedge$ )

DNF: Disjunction of terms

HORN:  $\leq 1$  Positive literal per clause  
Conjunction of such clauses

NNF: Negation only to literals

DNNF: AND Gate inputs are separate.

### SEMANTICS:

$M(\alpha)$ : set of worlds where  $\alpha$  holds at

↓

Meaning of  $\alpha$   $\left\{ \omega : \omega \models \alpha \right\}$   
Models of  $\alpha$

Opposite:  $\omega \not\models \alpha$

$\alpha$  equivalent to  $\beta$

$$M(\alpha) = M(\beta)$$

$\exists \alpha$  is contradictory / inconsistent

$$M(\alpha) = \emptyset$$

\*  $\alpha$  is valid / tautology

$$M(\alpha) = \text{all worlds}$$

\*  $\alpha$  and  $\beta$  are mutually exclusive

$$M(\alpha) \cap M(\beta) = \emptyset$$

\*  $\alpha$  implies  $\beta$

$$M(\alpha) \subseteq M(\beta)$$

## INFERENCE:

KB:  $\Delta$

Query:  $\alpha$

$\Delta \models \alpha$  reads :  $\Delta$  implies  $\alpha$ ,  $\Delta$  entails  $\alpha$   
 $\alpha$  follows from  $\Delta$ .

## INFERENCE METHODS:

### 1. TRUTH TABLE (MODEL ENUMERATION):

$\Delta \text{ imply } \alpha : M(\Delta) \subseteq M(\alpha)$   
(Brute Force)

### REFUTATION THEOREM:

$\Delta \models \alpha : \Delta \text{ implies } \alpha$

$\Delta \wedge \neg \alpha$  contradictory  $M(\Delta \wedge \neg \alpha) = \emptyset$

### 2. INFERENCE RULES:

#### INFERENCE RULES R

$\Delta \vdash_R \alpha : \alpha$  derived from  $\Delta$  using R.

Complete:

If  $\Delta \models \alpha$  then  $\Delta \vdash_R \alpha$

Sound:

If  $\Delta \vdash_R \alpha$  then  $\Delta \models \alpha$

## INFERENCE RULES:

### 1. MODUS PONENS:

$$\frac{\alpha, \alpha \Rightarrow \beta}{\beta}$$

### 2. OR - INTRODUCTION:

$$\frac{\alpha, \beta}{\alpha \vee \beta}$$

### 3. AND - INTRODUCTION:

$$\frac{\alpha, \beta}{\alpha \wedge \beta}$$

## RESOLUTION:

$$\frac{\alpha \vee \beta, \neg \beta \vee \gamma}{\alpha \vee \gamma}$$

Unit Resolution  $\rightarrow$  One of the 2 clauses is unit.

Linear time! But it is not refutation

complete.

Is  $\Delta \models \alpha$ ?

1.  $\Delta \wedge \neg \alpha$  convert to CNF

2.  $\Delta \wedge \neg \alpha$  prove unsat

\* Contradiction  $\Rightarrow \Delta \models \alpha$

↳ no contradiction  $\Rightarrow \Delta \not\models \alpha$

### CONVERTING SENTENCES INTO CNF:

Any sentence can be converted into CNF.

1. Get rid of all connections but for  $\wedge, \vee, \neg$

$$\alpha \Rightarrow \beta \rightarrow \neg \alpha \vee \beta \quad \text{①}$$

$$\alpha \Leftrightarrow \beta \rightarrow (\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)$$

use ①

2. Use de Morgan's law to push negations inside

$$\neg(\alpha \wedge \beta) \rightarrow \neg \alpha \vee \neg \beta$$

$$\neg(\alpha \vee \beta) \rightarrow \neg \alpha \wedge \neg \beta$$

3. Distribute  $\vee$  over  $\wedge$

$$(\alpha \wedge \beta) \vee \gamma \rightarrow (\alpha \vee \gamma) \wedge (\beta \vee \gamma)$$

### 3. By REDUCTION SAT (Satisfiability) - SEARCH

a. COMPLETE METHOD: Systematic Search (dfs)

Always completes

DPLL Algorithm:

1. ORIGINAL CNF  $\Delta$

$$\left. \begin{array}{l} \rightarrow \Delta \wedge A \\ \rightarrow \Delta \wedge \neg A \end{array} \right\} \rightarrow \text{Branching on variable } A.$$

2. UNIT RESOLUTION

b. INCOMPLETE METHOD: Local Search

Completes if sat.

If unsat, might loop infinitely.

\* MIN-CONFLICTS / HILL CLIMBING:

for  $i = 1 \dots N$ : (Number of restarts)

Choose random starting point.

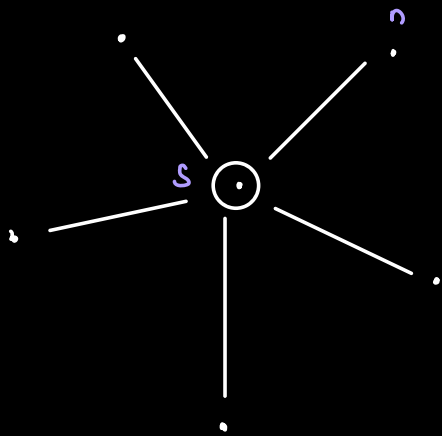
While the violated constraints decrease:

Find neighbor with least violated constraints

Move to that neighbor.



## \* SIMULATED ANNEALING:



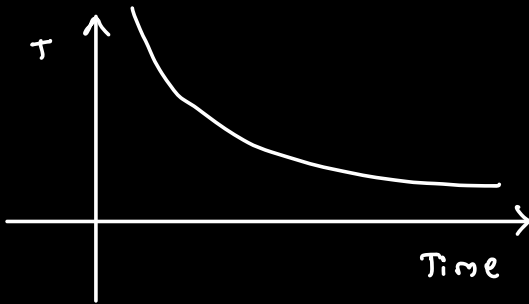
Pick random neighbor (n)

$\Delta E$  : violations (n) - violations (s)

↳  $\Delta E < 0$  : go to n

↳ otherwise

go to n with  $P \propto \frac{1}{e^{\Delta E/T}}$



T : Temperature

As time proceeds, chances to go to n decreases.

## Randomization:

→ Avoids local minima

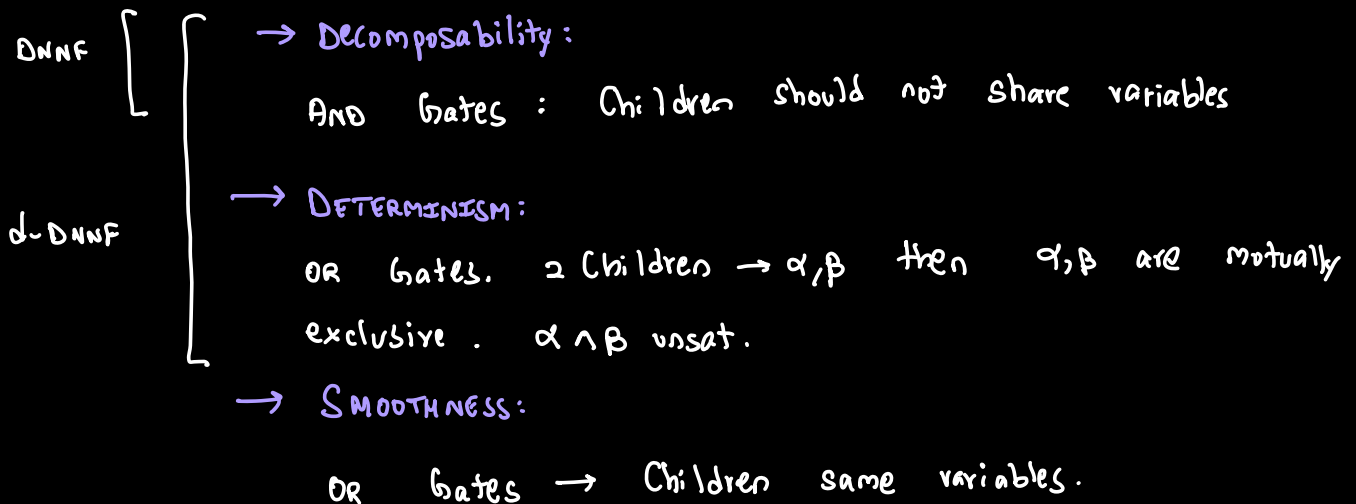
→ Reaches almost all nodes.

#### 4. CONVERTING KB (Knowledge Base) into "tractable forms"

(Knowledge Compilation)

"Compile it" into a "tractable circuit".

NNF :



SOLVES:

#SAT / MODEL COUNTING:

$\rightarrow$  Counts # of assignments that solve CNF.

HOW TO SOLVE #SAT:

1. BASE CASE:

True gets 1, False gets 0

Every literal gets 1.

(+ve / -ve)

2. AND Gates : Multiply

OR Gates : Add