TENSORS:

More than 2 axes.

KEY NOTES ;

1.
$$C = A + b \rightarrow ADDED$$
 TO EACH ROW
$$C:j = A:j + b:j$$

2. ELEMENT - WILE PRODUCT: A . B.

TO GET A SOLUTION FOR ALL B,

AX MUST SPAN ALL IRM.

FOR THIS THE COLUMN OF A 10 Should have most be attended of 10 should have most of the most of the sound of t

IF N > M, THEN EACH SUBLET OF M

INDEPENDENT COWMNS => 1 SOLUTION

SO NOT UNIQUE.

UNIQUE => N = M

SINDULAR MATRIX:

SQUARE MATRIX WITH LINEBRLY DEPENDENT COLUMNS.

NORMS:

$$\Gamma_b: \|x\|^b = \left(\frac{2}{5}|x|^b\right)^{b}$$

EUCLIDEAN NORM:

$$L^{2} NDRM ||x||$$

$$\left(\underbrace{2}_{i} |x_{i}|^{2} \right)^{1/2}$$

Squared L2 NORM is preferred.

L' NORM :

If difference between 0 and non-zero is of atmost importance , use LI NORM.

$$||x_1|| = \angle |x_2|$$

MAY NORM:

FROBENIUS NORM:

MATRICES:

DIAGONAL MATRIX:

$$D_{ij} = 0 \quad \forall \quad i \neq j$$

$$D = \begin{bmatrix} 0 & x \\ y & y \\ 0 & y \end{bmatrix}$$

$$D^{-1} : \begin{bmatrix} y_{a} & & & & & & & & \\ & y_{b} & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\$$

SYMMETRIC MATRIX:

ORTHOGONAL MATRIX:

Columns are mutually orthonormal
$$A^{T}A = AA^{T} = I$$

$$= > A^{-1} = A^{T}.$$

MATRIX DECOMPOSITION:

E INENDECOMPOSITION:

$$A : \lambda V$$

$$\lambda \rightarrow eigenvalues$$

$$V \rightarrow eigenvectors$$

$$A = V \operatorname{diag}(X) V^{-1}$$

$$A = V \Delta V^{-1}$$

If A -> real Symmetric matrix

Q: orthogonal

D: diagonal

PROPERTIES:

* A is singular iff
$$\lambda_i = 0$$
 for some i.
* $f(x) = x^T A x$, A : Symmetric , $\|x\|_2 = 1$ $x = eigenvectors$

$$A = A^T \qquad A x = \lambda x$$

$$f(x) = x^T \lambda x$$

$$= \lambda x^T x$$

$$= \lambda x^T x$$

$$= \lambda \|x\|_2$$

$$= \lambda$$

$$f(x) \xrightarrow{I/P} f(x) \xrightarrow{O/P} \lambda_i$$

POSSTENE PER SVETE 209

POSITIVE SENIDEFINITE:

SINGULAR VALUE DECOMPOSITION:

$$A = V D V T$$

$$V \times V$$

$$V \times V$$

$$V \times V$$

$$V \times V$$

U, v : orthogonal

D : Diagonal

U columns: left - singular vectors = EV of AAT

V columns: right - singular vectors = EV OF ATA

O : singular values = (Evalues of AFA/AAT.

MODAE - PENROSE PSEUDO INVERSE:

$$Ax = y$$

 $x = A^{\dagger} y$
 $[A^{-1}]$ doesn't exist]

if
$$cols(A) > rows(A)$$
:
 $x = A^{+}y$ gives one of the

 $cols(A) > rows(A)$:

11x112 is least.

if
$$rows(a) > rols(a)$$
:

no solution

we get ∞ such that $||Ax - y||_2$ is least.

TRACE:

DETERMINANT :

$$det(x) = 0$$
 => contracts space to 0 volume
 $det(x) = 1$ => transformation preserves
volume.

E ILENOBUMPOSITION:

EINENVALUES:

UES:

$$\mathcal{L}_{\lambda_{i}} := \text{trace } (A)$$

$$A_{x} := \lambda_{\lambda}$$

$$(A - \lambda_{x})^{x} := 0$$

$$B$$

$$B_{11} \times_{1} + B_{12} \times_{2} + ... + B_{1n} \times_{n} = 0$$

$$B_{21} \times_{1} + B_{22} \times_{2} + ... + B_{2n} \times_{n} = 0$$

$$\vdots$$

$$B_{n} \times_{1} + B_{n_{2}} \times_{2} + ... + B_{nn} \times_{n} = 0$$

$$B_{1}^{T} \times_{1} + B_{2}^{T} \times_{2} + ... + B_{nn} \times_{n} = 0$$

$$B_{1}^{T} \times_{1} + B_{2}^{T} \times_{2} + ... + B_{nn}^{T} \times_{2} = 0$$

$$Column$$

$$We know \times_{1} \text{ opt } 0$$

$$So \quad B_{1}, B_{2}, ... B_{n} \text{ are linearly dependent}$$
a square matrix

As B is a square matrix

1:near dependence => det=0

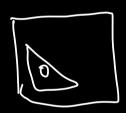
IT IS A SINGULAR MATRIX

DRINOGONAL MATRICES:

Rotates space

-> complex & Yalues

TRIANDULAR MATRICES:



-> Repeated Evalues

-> < n independent Evectors.

SYMMETRIC MATRICES:

Always real Evalues.

E. Vectors orthogonal

 $\theta = \theta^{T}$

Usual A = SAS-1

SYMMETRIC:

$$A = Q \wedge Q^{-1} = Q \wedge Q^{T}$$

Orthogonal

Why real eigenvalues?

$$A_{x} = \lambda_{x}$$
 $\stackrel{\text{always}}{=}$ $A_{x} = \overline{\lambda}_{x}$

be assume real matrices

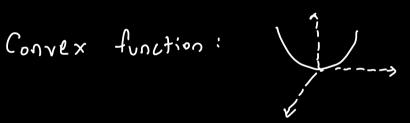
$$\bar{x}^T \theta : \bar{x}^T \bar{\lambda}^T$$

$$\overline{\chi}^T A \times = \lambda \overline{\chi}^T X$$
 $\overline{\chi}^T A \times = \lambda \overline{\chi}^T X$

Ly its 0 only if all x is 0.

POSITIVE DEPINITE: [MATRIX 5]

$$x^T S x 70$$
 for all $x \neq 0$



QUADRATIC: Convex can be

S, T -> positive detinite

$$\times^{\mathsf{T}}(S+\mathsf{T}) \times : \times^{\mathsf{T}} S \times \times \times^{\mathsf{T}} T \times > 0$$

(S+T) is positive definite/

S-1 has eigenvalues 1/2 (Symmetric).

So S-1 :5 PD//

A: S-1 B S

SIMILAR MATRICES

S: non Singular

A and B are Similar matrices

=> Same eigenvalues.

E INENDECOMPOSITION:

n Independent eigenvectors

Put them in columns of S

$$AS = A \begin{cases} \frac{1}{x_1} & \frac{1}{x_2} & \dots & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} \\ \frac{1}{x_n} & \frac{1}{x_n} & \frac{1}{x_n} & \frac{1$$

eigenvalue matrix

possible only

if eigenvertors

are independent

DECORPOSISTION

$$A^2 \times = \lambda A \times = \lambda^2 \times$$

Eigenvalues of
$$A^2 = \lambda^2$$

or

$$A^2: S \wedge S^{-1} S \wedge \hat{S}' = S \wedge 2 S^{-1}$$

THEOREM:

$$A^{k} \rightarrow 0$$
 as $k \rightarrow \infty$

if all $|\lambda_{i}| < 1$.

A is sure to have a different eigenvectors, if λ_i s are different.

or may not have a independent eigenvectors.

eg: I has n evalues of (1,1,...)

all vectors are evectors

Lochroose of independent.

- Not for triangle matrices.

SINDULAR VALUE DECOMPOSITION:

We have a set of orthogonal Basis

J Apply A

Generate a set of orthogonal Basis again

new orthogonal Basis

v, A A+, u,

v2 A A+, u2

 $A+, \rightarrow sane direction as u,$ $A+, = \sigma, u,$ $A+, = \sigma, u,$

$$A \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

MATRIC IS POSITIVE DEFINITE IF

$$S^{T}AS > 0$$

$$S^{T}(A^{T}A)S$$

$$(AS)^{T}(AS)$$

$$||AS||^{2} > 0 //$$

$$AA^{T} = U \wedge U^{T}$$

$$Sance eigenvalues as ATA (but only m instead of a) if man, remaining are 0t.

$$(A^{T}A)\vec{V} = \lambda \vec{V}$$$$

$$(A^{T}A)\vec{V} = \lambda \vec{V}$$

$$(AB^{T})(A\vec{V}) = \lambda (A\vec{V})$$

$$(AB^{T})(A$$

91 = rank

$$\begin{bmatrix}
\mathbf{v}_1 & \dots & \mathbf{v}_n
\end{bmatrix} = \begin{bmatrix}
\mathbf{u}_1 & \dots & \mathbf{u}_n
\end{bmatrix}
\begin{bmatrix}
\mathbf{v}_1 & \dots & \mathbf{v}_n
\end{bmatrix}$$

WHAT IF TC = Cj

and vi and vi can be 2

Orthogonal from a plane

of possible vectors.

Will u; and uj be orthogonal always?

A+, = o, u,

u, = At.

Uz: AVZ

 $u_{1}^{T}u_{2}:\left(\frac{AV_{1}}{\sigma_{1}}\right)^{T}\left(\frac{AV_{2}}{\sigma_{2}}\right):\frac{\varphi_{1}^{T}A^{T}AV_{2}}{\sigma_{1}\sigma_{2}}$ $:\frac{v_{1}^{T}\sigma_{2}^{2}V_{2}}{\sigma_{1}\sigma_{2}}$

= 0 //

(Computation)

NEVER USE ATA IN REAL LIPE TO FIND U OTV

as ATA has a lot of rounding off.

So Svo says

AX = U & V X

A matrix transformation is a

rotation/reflection -> Stretch -> rotation/reflection

of all vectors.

PRODUCT OF O - DETERMINANT OF A.

 $\sigma_1 \in \lambda_1 \in \lambda_2 \in \sigma_L$

2,22: 0,0,