book: Which functions are easier to optimize?

PROPERTY 1: How consitive is the function?

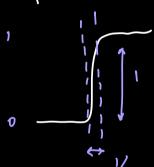






Sharp bump is not good for UD.

A small step in x -> Large change in flx).



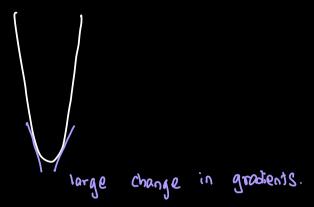
1. LIPSCHITZNESS: [Function doesn't change much for a step]

f is L-lipschitz if  $(f: \mathbb{R}^d \to \mathbb{R})$ 

+ x,y |f(x) - f(y)| ≤ L ||x-y||,

La distance between & and A.

## What if function is:



2. SMDOTHNESS: [Gradient should also not change quickly]

f is  $\beta$ -smooth if  $\forall \alpha, y \quad || \nabla f(\alpha) - \nabla f(y) ||_2 \leq \beta \cdot ||\alpha - y||_2$ 

SMOOTHNESS IS STRICTER THAN LIPSCHITZNESS

if f is B-smooth => f is L-Lipschitz.

only if the input values

are bounded!

Example:

f: 
$$\mathbb{R} \to \mathbb{R}$$
  
 $f(x) = ax^2 + bx + c$   
 $f'(x) = 2ax + b$   
If  $f'(x) = f'(y) = 2a|x - y|$   
 $=> f$  is  $(2a) = Smooth$   
 $f(x) = f(y) = ax^2 + bx + c - (ay^2 + by + c)$   
 $= a(x^2 - y^2) + b(x - y)$   
 $= (x - y) [a(x + y) + b]$   
So if  $(x - y)$  is bounded, we can  
 $Sort$  of  $Sort$  is Lipschitz.  
But cannot be proven explicitly  
 $Sort$  for  $Sort$   $Sort$ 

THEOREM 1: MONOTONICITY OF 60

f :s a  $\beta$ -smooth function, if  $\eta \leq \frac{1}{\beta}$ . Then,  $f(x_{i+1}) \leq f(x_i) - \eta || \nabla f(x_i)||^2$ 

"6D monotonically decreases the function value".

x: = x:-, - m of (a:-,)

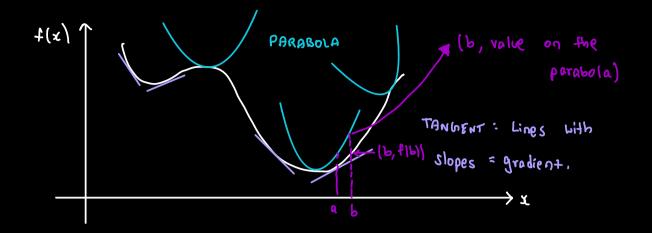
11 \rangle f(x) - \rangle f(y) 112 \le \beta \cdot 1) \angle 2

PROOF OF MONOTONICSTY :

Assume univariate function f: R -> R

Smoothness upper bound: f is  $\beta$ -smooth  $(f:R\rightarrow R)$   $\forall a,b$   $f(b) \leq f(a) + f'(a) \cdot (b-a) + \frac{\beta}{2} (b-a)^2$   $\Rightarrow$  So we can create a parabola as a function of  $\beta$ , such that parabola is above the function.

[ $\beta$  ensures that the parabola is above but as close as possible]



PROOF: Based on Taylor's Theorem

$$f(x+h) = f(x) + f'(x) \cdot h + f''(x) \cdot \frac{h^2}{2} + ...$$

Taylor's theorem

: 
$$f(x+h) = f(x) + f'(x) \cdot h + \int_{0}^{1} f'(x+h)$$
  
-  $f'(x)$ .

with a remainder term

PROOF OF MONOTONICITY FOR UNIVERSITE CASE:

$$t(x^{i+1}) = t(x^i - \lambda t_i(x^i))$$

Use smoothness opper bound:

$$f(b) \leq f(a) + f'(a) \cdot (b-a) + \frac{\beta}{2} (b-a)^2$$

$$f(x_{i+1}) = f(x_i) - \eta f_1(x_i)^2$$

$$= f(x_i) - \eta f_1(x_i)^2 + \frac{1}{\beta} \eta^2 f_1(x_i)^2$$

$$= f(x_i) - \eta f_1(x_i)^2 + \frac{1}{\beta} \eta^2 f_1(x_i)^2$$

$$= f(x_i) - \eta f_1(x_i)^2 + \frac{1}{\beta} \eta^2 f_1(x_i)^2$$

$$= f(x_i) - \eta f_1(x_i)^2$$

Smoothness upper bound for multivariate functions:  $f: Rd \rightarrow R$ 

If 
$$f$$
 is  $\beta$ -smooth, then 
$$\forall x,y \quad f(y) \leq f(x) + \langle \nabla f(x),y-x\rangle + \frac{\beta}{2} ||y-x||_2^2$$
 (inner-product)

PROOF OF MONOTONICITY FOR ALL FUNCTIONS:  $f(x_{i+1}) = f(x_i - \eta \nabla f(x_i))$   $\downarrow$  x

$$\begin{aligned}
&\{ t(x_i) - \frac{1}{u} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u_{5} b} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) - u \| \Delta t(x_i) \|_{2}^{2} + \frac{1}{u} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) + \Delta t(x_i) \|_{2}^{2} + \frac{1}{u} \| \Delta t(x_i) \|_{2}^{2} \\
&\{ t(x_i) + \Delta t(x_i) + \Delta t(x_i) \|_{2}^{2} + \frac{1}{u} \|_{2}$$

## Summary:

$$\rightarrow$$
 60 makes progress as long as  $\eta \leq 1/\beta$   
(Theory to practice):

## Practical tricks:

1. Find largest 
$$\eta$$
 such that

 $f(x_i - \eta \nabla f(x_i)) \leq f(x_i) - \frac{\eta}{2} \| \nabla f(x_i) \|^2$  (2)

 $(eg: start with  $\eta = 1$ 

if (a) holds, continue, else try  $\eta = \frac{1}{2}$ ,...

2. Can also do "Backtracking line search"

to pick right  $\eta$ .$ 

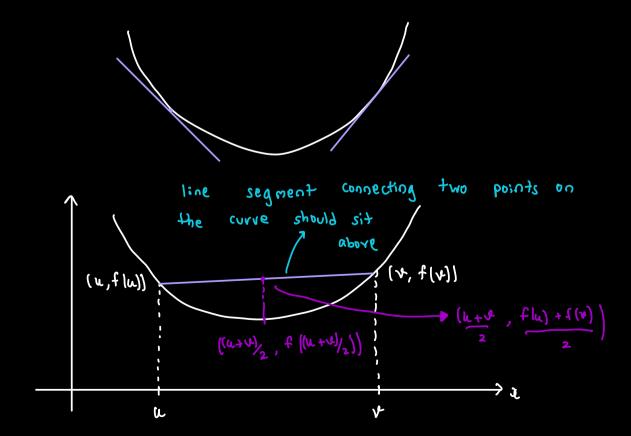
-> Monotonicity 7> We converge to the global minimum.



## CONVEX FUNCTIONS

[Magic Ingredient in optimization]

Convex:  $f: \mathbb{R}^d \to \mathbb{R}$  is convex if the tangent plane at any point is below the curve.



Equivalently:

$$\rightarrow \forall u, v , \lambda \in (0,1) \quad f(\lambda u + (1-\lambda)v) \leq \lambda \cdot f(u) + (1-\lambda) \cdot f(v)$$

$$\rightarrow \forall u, v, f(u) + \langle \nabla f(u), v - u \rangle \leq f(v)$$
 $\downarrow \qquad \qquad \qquad \downarrow$ 

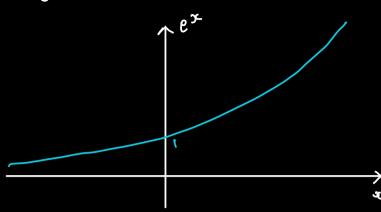
the tangent function

$$g: \mathbb{R} \to \mathbb{R} , \quad \omega \in \mathbb{R}^d$$

$$g_{\omega}: \mathbb{R}^d \to \mathbb{R}$$

$$g_{(x)} = g(\langle \omega, \alpha \rangle)$$

Example: e is a convex function.



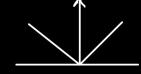
$$g_{\omega}: \mathbb{R}^d \to \mathbb{R}$$
 as

=> 
$$x^2$$
 is a convex function =>  $f(x) = \langle w, x \rangle^2$  is a convex function.

=> 
$$(x-a)^2$$
 is a convex function

=> 
$$f(\omega)$$
:  $(<\omega, >>-a)^2$  is a convex function.





WHY CONVEXITY:

$$L(\theta) := \frac{1}{n} \stackrel{n}{\underset{i=1}{\overset{n}{\rightleftharpoons}}} l(h_{\theta}(\alpha_i), \Psi_i)$$

Dataset 
$$(x, y)$$
,  $(x_2, y_2)$ ...,  $(x_n, y_n)$ 

Least Squares Regression:

halx; 
$$\{\theta, x_i\}$$
 inner-product  $l(ha(x_i), g_i) = (\langle \theta, x_i \rangle - y_i)^2$ 

LSR ERM: 
$$L(\theta) = \frac{1}{2} \left( \langle \theta, x_i \rangle - \psi_i \right)^2$$

is a convex function in 0.

L, ERM: 
$$L_{1}(\theta) = \frac{1}{2} \frac{2}{3} | \langle \theta, \alpha; \gamma - \psi; |$$

is a convex function in B.

"LALSO" : 
$$L(\theta) = \frac{1}{2} \left( 2\theta, x_i > -4i \right)^2 + \lambda \left( |\theta_i| + |\theta_i| + \dots + |\theta_n| \right)$$

CONVEX OPTIMIZATION IS EVERYWHERE!

THEOREM: If I is B- Smooth and convex, then

(if 
$$\eta \in V_B$$
)  $f(\alpha_k) \leq f(\alpha_k) + \frac{2\beta \cdot ||\alpha_0 - \alpha_k||}{k}$   
global  $\gamma$  number of iterations optimum

(Remark: Minimizing a convex function is "easy")

for a given accuracy and we know p,

we know the number of iterations needed,

to reach within that accuracy of the

global optimum.

(Aemork: If f is L-Lipschitz, then 
$$f(x_k) \in f(x_k) + L \cdot ||x_0 - x_k||$$