

## GRAPHICAL MODELS:

CONDITION INDEPENDENCE (CI):

$$x \perp y \mid z$$

Distribution  $D: (x_1, x_2 \dots x_d) \in \{0,1\}^d$

Structure: Rooted Tree.

KL - DIVERGENCE / CROSS - ENTROPY:

Distance between 2 distributions over some  
space,  $\Omega \rightarrow d_1, d_2$

$$KL(d_1 \parallel d_2) = \sum_{s \in \Omega} d_1(s) \log \frac{d_2(s)}{d_1(s)}$$

$d_i(s)$ : Probability  $s$  happens under  $d_i$ .

Goal: Given distribution  $P$  on  $\sum^d$  generated from  
unknown Bayes net (Tree:  $T^*$ ), find the  $T$   
and Bayes Net  $P_T$  such that

$$KL(P, P_T) \leq \epsilon.$$

$$\sum = \{0,1\}$$

How - LIU BOUND:

For any tree  $T$ ,

$$K_L(P | P_T) \leq J_P - \sum_{(i,j) \text{ is an edge in } T} I(x_i, x_j)$$

function of  $P$

Mutual Information:

$I(x_i; x_j)$  measures how much information  $x_i$  has about  $x_j$ .



can be estimated from samples  
[Independent of  $T$ ].

### How - LIU ALGORITHM

→ Use samples to estimate  $I(x_i; x_j)$  for all  $i, j$ .

→ Form a weighted graph where weights are exactly  $I(x_i; x_j)$

→ Compute the max. spanning tree  $T'$  in  $G$

→ Output  $P_{T'}$ .

## UNDIRECTED GRAPHICAL MODELS:

### MARKOV RANDOM FIELDS:

Given  $D = (x_1, x_2 \dots x_d) \in \{0,1\}^d$

$G$ : Dependency graph for  $D$ .

$D$ satisfies	Pairwise Markov Property	Local	Global
With respect to $G$			
If $i, j$ have no edge, then	$x_i \perp x_j \mid x_{\text{rest}}$	$x_i \perp x_j \mid x_{\{\text{neighbors of } i\}}$	$x_i \perp x_j \mid x_{\{\text{any separating set}\}}$
			↓ vertices removing which $i, j$ disconnected.

Global  $\Rightarrow$  Local  $\Rightarrow$  Pairwise.

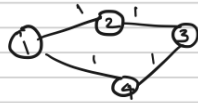
Remark: We'll say  $D$  has dependency graph  $G$  if it satisfies Markov property with respect to  $G$ .

Goal: Find  $D$  such that each vertex has degree  $\leq k$ .

### Learning Boltzmann Machines

$D$  on  $\{1, -1\}^d$

$$Pr[X=x] \propto \exp\left(\sum_{\{i,j\} \in G} w_{ij} x_i x_j\right)$$



$$Pr[X=x] \propto \exp(x_1 x_2 + x_2 x_3 + x_3 x_4 + x_4 x_1)$$

Distributions as defined above,  
They satisfy Markov property  
wrt  $G$ .

### Gaussian Graphical Models

$D$  on  $\mathbb{R}^d$

Dist  $D$  is  $N(0, \Sigma)$

$\Sigma$  is the covariance matrix.  
 $X \sim N(0, \Sigma)$

$$\Sigma_{ij} = E[X_i X_j]$$

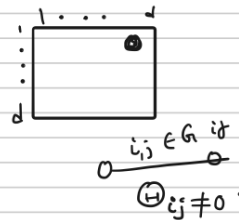
$\Sigma_{ij} = 0 \Rightarrow X_i, X_j$  are independent.

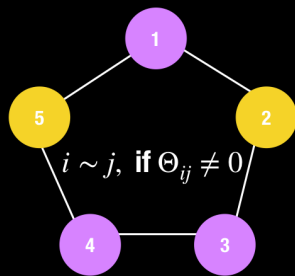
(Dempsey 1972):

Precision Matrix:

$$\Theta = \Sigma^{-1}$$

Thm: Gaussian dist  
has dependency graph  
with  $\text{Supp}(\Theta)$ .





**Example:**  $(X_1 | X_2, X_5)$  independent  
of  $(X_3 | X_2, X_5)$

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**Markov property:**  $\Theta_{ij} = 0 \Rightarrow X_i, X_j$  are independent  
conditioned on neighbors of  $i$ .

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## Structure Learning for GGMs

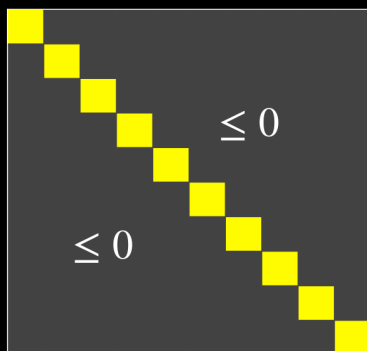
Given samples  $X^1, X^2, \dots, X^n$  from a GGM of degree  $d \ll p$ ,  
can we efficiently find the dependency graph with  $n \ll p$ ?

(Think:  $n = O_d(\log p)$ .)

## Attractive GGMs

GGM is attractive if all covariances are non-negative.

(Equivalently,  $\Theta$  has non-positive off-diagonals.)



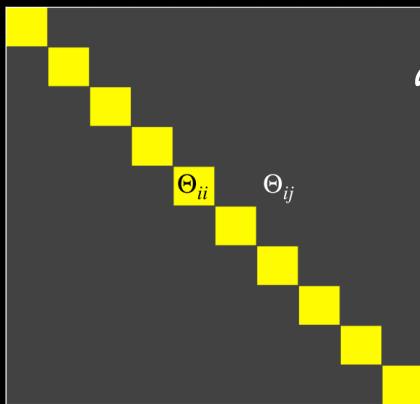
$\Theta$  : Precision Matrix

### Ex: Gaussian Free Fields

- Many applications via Gaussian processes

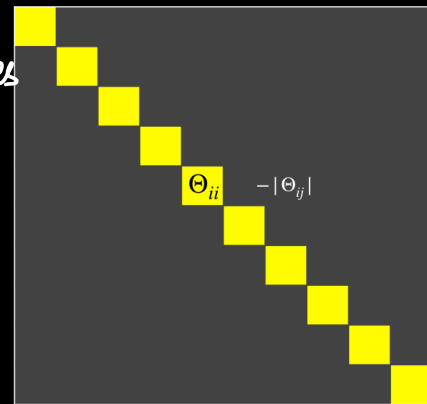
# Walk-Summable GGMs

GGM walk-summable if making off-diagonals of precision matrix negative preserves positive semi-definiteness.



$\Theta$  : Precision Matrix

all eigenvalues  $> 0$



Offdiagonals negative  $\geq 0$

## GREEDYPRUNE

1. Recover neighborhood of each vertex in parallel.
2. Grow a candidate neighborhood.
3. Prune out some vertices.

## GREEDY-GROWING

1. Set  $S \leftarrow \emptyset$
2. While  $S$  is small enough:
  1. Find  $j$  to minimize estimate of  $Var(X_1 | X_{S \cup j})$ .
  2.  $S \leftarrow S \cup \{j\}$ .

→ That  $j$  and  $x_1$  are clearly dependent as  $j$  minimizes  $x_1$ 's variance.

Intuition: Add vertex that gives maximum decrease in conditional variance.

$\hookrightarrow$  For each  $\text{var}(x_i | x_j)$  we need  $1/\epsilon^2$  samples  
 to get  $(1-\epsilon)$  accuracy.

If  $\text{var}(x_i | x_2, x_3, x_4) \rightarrow 3/\epsilon^2$

### GREEDY-PRUNING

1. For each  $j$  in  $S$ :

1. If  $\text{Var}(X_1 | X_{S \setminus \{j\}}) < (1 + \tau) \text{Var}(X_1 | X_S)$ ,  
 drop  $j$  from  $S$ .

Intuition: If dropping a vertex, does not hurt  
 too much, drop it.

Can learn Attractive and Walk-Summable GGMs

with  $O(d^2 \log p / \epsilon^6)$  samples and quadratic

run-time.   
 $d$  - degree (max)   
 $p$  - total number of parameters

$$\kappa(\Theta) = \min_{i,j:\Theta_{ij} \neq 0} \frac{|\Theta_{ij}|}{\sqrt{\Theta_{ii}\Theta_{jj}}}$$

## SUMMARY:

### 1. KL-Divergence:

$$KL(d_1 || d_2) = \sum_{s \in \Omega} d_1(s) \log \frac{d_2(s)}{d_1(s)}$$

### 2. Chow-Liu Bound:

$$KL(P || P_T) = J_P - \sum_{(i,j) \text{ is an edge in } T} I(x_i, x_j)$$

### 3. Chow-Liu Algorithm:

- Find  $I(x_i, x_j)$  - graph
- Max Spanning Tree  $\rightarrow T$

### 4. Markov Random Fields:

D (Markov Property) with respect to  $G$ : if no edge  $i, j$   
 $x_i \perp x_j \mid x_{\{\text{neighbors of } i\}}$

### 5. Learning Boltzmann Machines: D on $\{1, -1\}^d$

$$Pr[x=x] \propto e^{\sum_{(i,j) \in G} w_{ij} x_i x_j}$$

### 6. Gaussian Graphical models:

$$D: N(0, \Sigma) \quad \Sigma_{ij} = E[x_i x_j]$$

$$\Sigma_{ij} = 0 \Rightarrow \text{independent}$$

$$\Theta = \Sigma^{-1}$$

$$\text{Support}(\Theta) \rightarrow G \quad i, j \in G \text{ if } \Theta_{ij} \neq 0$$



7. Attractive:  $\leq_{ij} > 0$ ,  $\oplus_{ij} \leq 0 \forall i \neq j$

8. Halk Summable:  $\oplus_{ij} \rightarrow -\oplus_{ij} \forall i \neq j \Rightarrow$  Still positive Semi Definite.

9. Greedy Prune

For each vertex  $i \rightarrow$  find neighborhood in parallel

$\rightarrow \arg \min_j \text{var}(x_i | x_{S \cup j})$

$\rightarrow \text{var}(x_i | x_{S - \{j\}}) < (1 + \epsilon) \text{var}(x_i | x_S)$

$\rightarrow$  learns 2 types  $O(d^2 \log p / \epsilon^4)$  samples, quadratic time

$d$  - max degree

$p$  - number of parameters

$$k(\oplus) = \min_{i,j: \oplus_{ij} \neq 0} \frac{|\oplus_{ij}|}{\sqrt{\oplus_{ii} \oplus_{jj}}}$$