Q1: PROVE THE MATRICES ARE UNITARY

MATRIX U IS UNITARY IFF UU+= I

$$(i) \times = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$T = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\begin{pmatrix} i & 0 \\ 0 & i \end{pmatrix} = \begin{pmatrix} i \\ 0 \end{pmatrix}$$

$$y^{+}y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix} = I$$

$$Z^{\dagger}Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\begin{bmatrix} (v) & \exists z & \begin{bmatrix} v & 0 \\ 0 & 1 \end{bmatrix} \\ \begin{bmatrix} v & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v & 0 \\ 0$$

(v) 
$$H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$
  
 $H^{\dagger} H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \times \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$ 

(vi) 
$$R_{\chi}(\theta) = \begin{bmatrix} \cos \theta/2 & -i \sin \theta/2 \\ -i \sin \theta/2 & \cos \theta/2 \end{bmatrix}$$

$$R_{x}^{+}[\theta] P_{x}(\theta) = \begin{bmatrix} \cos\theta/2 & i\sin\theta/2 \\ i\sin\theta/2 & \cos\theta/2 \end{bmatrix} \begin{bmatrix} \cos\theta/2 & -i\sin\theta/2 \\ -i\sin\theta/2 & \cos\theta/2 \end{bmatrix}$$

$$= \begin{bmatrix} (o_{0}^{1} \Theta_{1}^{1} - i^{2} \sin^{2} \Theta_{1}^{1} & -i^{2} \sin^{2} \Theta_{1}^{1} & (o_{0} \Theta_{1}^{1} + i \sin^{2} \Theta_{1}^{1}) \\ (o_{0} \Theta_{1}^{1} - i \sin^{2} \Theta_{1}^{1} & -i^{2} \sin^{2} \Theta_{1}^{1} + (o_{0}^{1} \Theta_{1}^{1}) \\ (o_{0} \Theta_{1}^{1} - i \cos^{2} \Theta_{1}^{1} & -i^{2} \sin^{2} \Theta_{1}^{1} + (o_{0}^{1} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + (o_{0}^{1} \cos^{2} \Theta_{1}^{1} - i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} - i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} - i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} - i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \sin^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1}) \\ = \sum (o_{0}^{1} \cos^{2} \Theta_{1}^{1} + i \cos^{2} \Theta_{1}^{1})$$

$$R_{2}[\theta]^{+}R_{2}(\theta) = \begin{bmatrix} e^{i\theta/2} & 0 \\ 0 & e^{-i\theta/2} \end{bmatrix} \begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$$

$$= \begin{bmatrix} e^{i\theta} & 0 \\ 0 & e^{i\theta} \end{bmatrix} = \pm \begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$$

$$(ix) R_{y} = \begin{bmatrix} 1 & 0 \\ 0 & e^{iy} \end{bmatrix}$$

$$R_{\psi}^{\dagger}R_{\psi} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & e^{-i\psi} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & e^{i\psi} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & e^{0} \end{bmatrix} = I$$

$$S^{+}S = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix}$$

$$S^{+}S = \begin{bmatrix} 1 & 0 \\ 0 & -i \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\begin{cases} xi \\ 7 \\ 0 \\ e^{i\pi/4} \end{cases}$$

$$T^{+}T = \begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & e^{0} \end{bmatrix}$$

Q2: GIVEN: U IS UNITARY

TO PROVE: U+ is UNITARY

TO PROVE: (U+)+ U+ = I

$$V^{+} = \overline{U}^{T}$$

$$(U^{+})^{+} = (\overline{U}^{T})^{T}$$

WE KNOW THAT (U) = U

Us T(TU) ANA

$$U = {}^{\dagger} ( {}^{\dagger} U ) \quad o2$$

$$I = {}^{\dagger} V U = {}^{\dagger} ( {}^{\dagger} U ) \quad o2$$

THEREFORE UT IS UNITARY.

Q3:  $V_1$ ,  $V_2$  ARE UNITARY  $V_1^+ U_1 = V_1 V_1^+ = I$   $V_2^+ V_2 = V_2 V_2^+ = I$ 

So  $V_1 V_2$  be the product

To PROVE:  $(V_1 V_2) (V_1 V_2)^{\dagger} = I$   $(V_1 V_2) (V_1 V_2)^{\dagger} = (V_1 V_2) (V_2^{\dagger} V_1^{\dagger})$   $= V_1 (V_2 V_2^{\dagger}) V_1^{\dagger}$   $= V_2 V_1^{\dagger}$   $= V_3 V_1^{\dagger}$   $= V_4 V_1^{\dagger}$ 

THEREFORE, THE PRODUCT OF TWO UNITARY
MATRICES IS UNITARY.

$$U^{+} = (R + iQ)^{+} = (\overline{R} - i\overline{Q})^{\top} = R^{\top} - iQ^{\top}$$

$$[\overline{R} = R, \overline{Q} = Q]$$

U IS UNITARY:

$$UU^{+} = I_{N} \Rightarrow (R+iQ) (R^{T}-iQ^{T}) = I_{N}$$

$$\Rightarrow RR^{T} + QQ^{T}+i(QR^{T}-RQ^{T}) = I_{N}$$

$$RR^{T} + QQ^{T} = I_{N}$$

$$QR^{T} - RQ^{T} = O_{N} \qquad QR^{T} = RQ^{T}$$

$$U' = \begin{bmatrix} R & Q \\ -Q & R \end{bmatrix} \qquad \begin{pmatrix} U' \end{pmatrix}^{+} = \begin{bmatrix} R^{T} & -Q^{T} \\ Q^{T} & R^{T} \end{bmatrix}$$

PAULI MATRIX:

PAVLE MATRIX:
$$y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$y = R + i R = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} + i \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$y' = \begin{bmatrix} 0 & 0 & 0 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{I}$$

HENCE Y' IS UNITARY FOR PAULE MATRIX.

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = X = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \qquad \qquad T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

TO PROVE: X,Y,Z AND I FORM AN ORTHONORMAL BASIS
FOR THE SPACE OF 2×2 MATRIX.

WE NEED TO PROVE THESE:

1. X ) X , Z AND I ARE ORTHONORMAL

2. X, Y, Z AND I FORM A BOSIL

21. X, Y, Z AND I ARE LINEORLY INDEPENDENT

27. EYERY 2x2 MATRIX CAN BE WRITTEN

AS A COMBINATION OF X/Y/2 AND I.

PROOF :

1. 
$$\times$$
 ,  $\times$  ,  $\times$ 

$$x^{T}x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = I$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$y^{t}y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$z^{t}z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$Z^{+}y^{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & -\bar{c} \\ \bar{c} & 0 \end{bmatrix} = \begin{bmatrix} 0 & -\bar{c} \\ -\bar{c} & 0 \end{bmatrix} \longrightarrow 0$$

$$y^{+}I = y^{+} = \begin{bmatrix} 0 & -i \\ 0 & 0 \end{bmatrix} \longrightarrow 0$$

$$I^{+} A : IA : A : \begin{bmatrix} ! & 0 \end{bmatrix} \longrightarrow 0$$

$$Z^{\dagger}I : Z^{\dagger} : \begin{bmatrix} 0 \\ 0 \end{bmatrix} \longrightarrow 0$$

$$I^{\dagger}z = Iz = 2 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \longrightarrow 0$$

< x | y > = < y | x > = < x | z > = < z | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x | x > = < x |

HENCE X, Y, Z, I ARE ORTHONORMAL/

21. X, Y, Z AND I ARE LENEARLY INDEPENDENT

They are linearly independent if

$$a \times +b +c +d = a \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} +$$

$$\begin{bmatrix}
c + d & a - bi \\
a + bi & d - c
\end{bmatrix} = \begin{bmatrix}
0 & 0 \\
0 & 0
\end{bmatrix}$$

THEREPORE X, Y, Z AND I ORE LINGARLY

INDEPENDENT//

$$M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\begin{cases} \begin{bmatrix} 0 & -1 \end{bmatrix} & + \begin{bmatrix} 0 & 1 \end{bmatrix} & \\ 0 & 1 \end{bmatrix} & + \begin{bmatrix} 0 & 1 \end{bmatrix} & \\ 0 & 1 \end{bmatrix}$$

$$= \begin{cases} \alpha + \delta & \alpha - i\beta \\ \alpha + \beta i & -\delta + \delta \end{cases}$$

$$\delta = \left(\frac{\alpha + d}{2}\right) \quad \delta = \left(\frac{\alpha - d}{2}\right)$$

$$\alpha = \left(\frac{b+c}{2}\right) \quad \beta = \left(\frac{c-b}{2i}\right) = \left(\frac{b-c}{2}\right)i$$

SO ANY GIVEN 2×2 MATRIX CAN BE EXPRESSED

AS THE LINEAR COMBINATION OF X,Y, Z AND I.

COMBINING THE THREE PROOFS, WE CON PROVE THAT

THE FOUR PAULY MATRICES X, Y, Z OND I FORM AN

ORTHONORMAL BASIS FOR THE SPACE OF 2×2 MATRICES.