```
In [1]:
        import numpy as np
            import pandas as pd
            import matplotlib.pyplot as plt
            import os
            import cv2
            import gc
            from PIL import Image
            train_on_gpu = True
            from sklearn.utils import resample
            from sklearn.utils import shuffle
            from sklearn.metrics import roc auc score
            import torchvision.transforms as transforms
            from torch.utils.data.sampler import SubsetRandomSampler
            import torch
            import torch.nn as nn
            import torch.nn.functional as F
            from torch.utils.data import TensorDataset, DataLoader, Dataset
            import torchvision
            import torch.optim as optim
            import torchvision.models as models
            import tensorflow as tf
            from tensorflow.keras.preprocessing.image import ImageDataGenerator
            from tensorflow.keras.models import Sequential
            from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Denso
            from tensorflow.keras.optimizers import Adam
            from tensorflow.keras.callbacks import EarlyStopping# This Python 3 env
            /opt/conda/lib/python3.10/site-packages/scipy/__init__.py:146: UserWar
            ning: A NumPy version >=1.16.5 and <1.23.0 is required for this versio
            n of SciPy (detected version 1.23.5
              warnings.warn(f"A NumPy version >={np_minversion} and <{np_maxversio</pre>
            n}"
```

```
In [3]: # helper method for clearing GPU memory
def clear_memory():
    gc.collect()
    torch.cuda.empty_cache()
```

id label

Out[4]:

```
      0
      f38a6374c348f90b587e046aac6079959adf3835
      0

      1
      c18f2d887b7ae4f6742ee445113fa1aef383ed77
      1

      2
      755db6279dae599ebb4d39a9123cce439965282d
      0

      3
      bc3f0c64fb968ff4a8bd33af6971ecae77c75e08
      0

      4
      068aba587a4950175d04c680d38943fd488d6a9d
      0
```

Number of training images: 220025 Number of test images: 57458

```
In [6]: # load the images
  img_train = os.listdir(folder_train)
  img_test = os.listdir(folder_test)
```

```
In [7]: # print the first 10 images
fig = plt.figure(figsize=(25, 4))
for i in range(10):
    ax = fig.add_subplot(1, 10, i + 1, xticks=[], yticks=[])
    im = Image.open(folder_train + img_train[i])
    plt.imshow(im)
    label = df_train.loc[df_train['id'] == img_train[i].split('.')[0],
    ax.set_title(f'#{i+1} - Label: {label}')
```













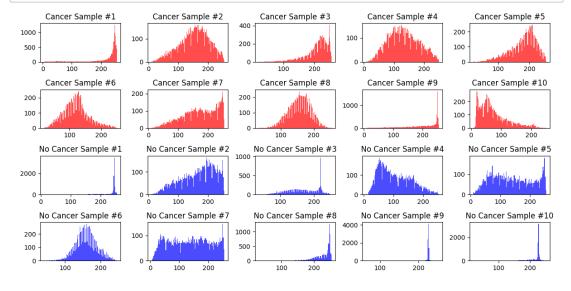








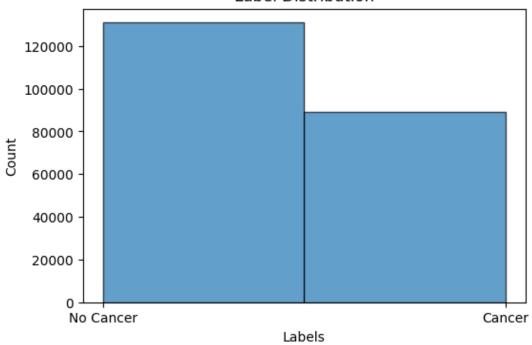
```
In [8]:
            # sample first 10 images for both labels
            cancer_samples = df_train[df_train['label'] == 1].head(10)
            no_cancer_samples = df_train[df_train['label'] == 0].head(10)
            # plot histograms of image pixel values for cancer and no cancer images
            plt.figure(figsize=(12, 6))
            for i in range(10):
                plt.subplot(4, 5, i + 1)
                cancer_img = cv2.imread(folder_train + cancer_samples.iloc[i]['id']
                plt.hist(cancer_img.ravel(), bins=128, color='red', alpha=0.7)
                plt.title(f'Cancer Sample #{i+1}')
                plt.subplot(4, 5, i + 11)
                no_cancer_img = cv2.imread(folder_train + no_cancer_samples.iloc[i]
                plt.hist(no_cancer_img.ravel(), bins=128, color='blue', alpha=0.7)
                plt.title(f'No Cancer Sample #{i+1}')
            plt.tight_layout()
            plt.show()
```



```
In [11]:  # plot histogram of label distribution
    def plot_label_dist(df):
        plt.figure(figsize=(6, 4))
        plt.hist(df['label'], bins=2, edgecolor='black', alpha=0.7)
        plt.xticks(np.arange(2), ['No Cancer', 'Cancer'])
        plt.xlabel('Labels')
        plt.ylabel('Count')
        plt.title('Label Distribution')
        plt.show()
```

In [12]: plot_label_dist(df_train)





```
In [13]: # calculate the imbalance ratios
def calc_imbalance(df_train):

    df_train_cancer = df_train[df_train['label'] == 1]
    df_train_no_cancer = df_train[df_train['label'] == 0]

    cancer = len(df_train_cancer)
    no_cancer = len(df_train_no_cancer)

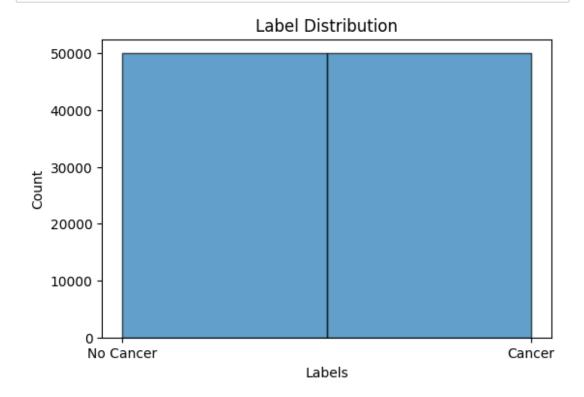
    imbalance_ratio = no_cancer / cancer
    cancer_ratio = cancer / (cancer + no_cancer)

    print("Imbalance ratio:", round(imbalance_ratio, 3))
    print("Ratio of cancer:", round(cancer_ratio, 3))
```

```
In [14]: ▶ calc_imbalance(df_train)
```

Imbalance ratio: 1.469
Ratio of cancer: 0.405

```
In [15]: # sample positive and negative images
sample_size = 50000
df_train_neg = df_train[df_train['label'] == 0].sample(sample_size, rand)
df_train_pos = df_train[df_train['label'] == 1].sample(sample_size, rand)
# create a new shuffeled training dataset
df_train_sample = shuffle(pd.concat([df_train_pos, df_train_neg], axis=)
```



```
In [17]:
          # wrapper class for PyTorch dataset
             class PyTorchData(Dataset):
                # set the necessary super class properties
                def __init__(self, df, folder = './', transform=None):
                    super().__init__()
                     self.df = df.values
                    self.data dir = folder
                     self.transform = transform
                # returns the length of the dataset
                def __len__(self):
                    return len(self.df)
                 # returns the image with the given index and applies a transformation
                 def __getitem__(self, index):
                    img name,label = self.df[index]
                    img_path = os.path.join(self.data_dir, img_name+'.tif')
                    image = cv2.imread(img_path)
                     if self.transform is not None:
                        image = self.transform(image)
                    return image, label
         In [18]:
                transforms.ToPILImage(),
                transforms.RandomHorizontalFlip(),
                transforms.RandomVerticalFlip(),
                transforms.RandomRotation(20),
                transforms.ToTensor(),
                transforms.Normalize(mean=[0.5, 0.5, 0.5], std=[0.5, 0.5, 0.5])
             ])
            train_torch = PyTorchData(df_train_sample, folder_train, transform_train
In [19]: ▶ batch_size = 128
            # set training and validation indices
             indices = list(range(len(train_torch)))
             split = int(np.floor(0.15 * len(train_torch)))
             train idx, valid idx = indices[split:], indices[:split]
             # random samplers
             train sampler = SubsetRandomSampler(train idx)
             valid_sampler = SubsetRandomSampler(valid_idx)
             # prepare data Loaders
             train_loader = DataLoader(train_torch, batch_size=batch_size, sampler=t
             valid loader = DataLoader(train torch, batch size=batch size, sampler=v
```

Device: cuda:0

```
In [23]:
         def __init__(self):
                     super(CNN,self).__init__()
                     self.conv1 = nn.Sequential(
                                     nn.Conv2d(3, 32, 3, stride=1, padding=1),
                                     nn.BatchNorm2d(32),
                                     nn.ReLU(inplace=True),
                                     nn.MaxPool2d(2,2))
                     self.conv2 = nn.Sequential(
                                     nn.Conv2d(32, 64, 3, stride=1, padding=1),
                                     nn.BatchNorm2d(64),
                                     nn.ReLU(inplace=True),
                                     nn.MaxPool2d(2,2))
                     self.conv3 = nn.Sequential(
                                     nn.Conv2d(64, 128, 3, stride=1, padding=1),
                                     nn.BatchNorm2d(128),
                                     nn.ReLU(inplace=True),
                                     nn.MaxPool2d(2,2))
                     self.conv4 = nn.Sequential(
                                     nn.Conv2d(128, 256, 3, stride=1, padding=1),
                                     nn.BatchNorm2d(256),
                                     nn.ReLU(inplace=True),
                                     nn.MaxPool2d(2,2))
                     self.conv5 = nn.Sequential(
                                     nn.Conv2d(256, 512, 3, stride=1, padding=1),
                                     nn.BatchNorm2d(512),
                                     nn.ReLU(inplace=True),
                                     nn.MaxPool2d(2,2))
                     self.fc=nn.Sequential(
                             nn.Linear(512*3*3, 256),
                             nn.ReLU(inplace=True),
                             nn.BatchNorm1d(256),
                             nn.Dropout(0.4),
                             nn.Linear(256, 1))
                 def forward(self,x):
                     x=self.conv1(x)
                     x=self.conv2(x)
                     x=self.conv3(x)
                     x=self.conv4(x)
                     x=self.conv5(x)
                     x=x.view(x.shape[0],-1)
                     x=self.fc(x)
                     return x
```

```
In [24]: # create CNN
model = CNN().to(device)
print(model)
```

```
CNN(
  (conv1): Sequential(
    (0): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1))
    (1): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True, track r
unning_stats=True)
    (2): ReLU(inplace=True)
    (3): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
l_mode=False)
  (conv2): Sequential(
    (0): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1))
    (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track r
unning_stats=True)
    (2): ReLU(inplace=True)
    (3): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
1_mode=False)
  (conv3): Sequential(
    (0): Conv2d(64, 128, kernel size=(3, 3), stride=(1, 1), padding=
    (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track
running stats=True)
    (2): ReLU(inplace=True)
    (3): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
1 mode=False)
  (conv4): Sequential(
    (0): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=
(1, 1))
    (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track
running stats=True)
    (2): ReLU(inplace=True)
    (3): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, cei
1 mode=False)
  (conv5): Sequential(
    (0): Conv2d(256, 512, kernel size=(3, 3), stride=(1, 1), padding=
(1, 1))
    (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track
running stats=True)
    (2): ReLU(inplace=True)
    (3): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, cei
l_mode=False)
  )
  (fc): Sequential(
    (0): Linear(in features=4608, out features=256, bias=True)
    (1): ReLU(inplace=True)
    (2): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True, track_
running stats=True)
    (3): Dropout(p=0.4, inplace=False)
    (4): Linear(in_features=256, out_features=1, bias=True)
 )
)
```

```
In [26]:  # hyperparameters to tune
learning_rates = [0.001, 0.0005, 0.0002]
```

```
results = []
             best_model_idx = None
             best auc = 0.0
             best_model_cnn = None
             # iterate all values for the hyperparameter
             for idx, lr in enumerate(learning_rates):
                 # use GPU if available
                 model = CNN().to(device)
                 # define optimizer and loss function
                 optimizer = optim.Adam(model.parameters(), lr=lr)
                 criterion = nn.BCEWithLogitsLoss()
                 # save results over epochs
                 train_losses = []
                 valid losses = []
                 valid_aucs = []
                 n_{epochs} = 10
                 # iterate all epochs
                 for epoch in range(1, n_epochs+1):
                     valid_aucs_epoch = []
                     model.train()
                     train_loss = 0.0
                     # process the training images
                     for data, target in train_loader:
                         optimizer.zero_grad()
                         data, target = data.to(device), target.to(device)
                         output = model(data)
                         loss = criterion(output.view(-1), target.float())
                         loss.backward()
                         optimizer.step()
                         train_loss += loss.item() * data.size(0)
                     model.eval()
                     valid loss = 0.0
                     # process the validation images
                     for data, target in valid_loader:
                         data, target = data.to(device), target.to(device)
                         output = model(data)
                         loss = criterion(output.view(-1), target.float())
                         valid_loss += loss.item() * data.size(0)
                         y_actual = target.data.cpu().numpy()
                         y_pred = torch.sigmoid(output).detach().cpu().numpy()
                         valid_aucs_epoch.append(roc_auc_score(y_actual, y_pred))
                     # determine values for current epoch
                     train_loss /= len(train_loader.sampler)
                     valid_loss /= len(valid_loader.sampler)
                     valid_auc = np.mean(valid_aucs_epoch)
```

```
train_losses.append(train_loss)
    valid_losses.append(valid_loss)
    valid_aucs.append(valid_auc)

print('Learning Rate: {:.6f} | Epoch: {} | Training Loss: {:.6f

# save results for current value of hyperparameter
    results.append({'learning_rate': lr, 'train_losses': train_losses,

# save best model
    avg_auc = np.mean(valid_aucs)
    if avg_auc > best_auc:
        best_auc = avg_auc
        best_model_idx = idx
        best_model_cnn = model

# print best hyperparameter
print("Best learning rate according to hyperparameter search: ", learning rate according to hyperparameter search: ")
```

```
Learning Rate: 0.001000 | Epoch: 1 | Training Loss: 0.364841 | Validat
ion Loss: 0.419545 | Validation AUC: 0.9330
Learning Rate: 0.001000 | Epoch: 2 | Training Loss: 0.299543 | Validat
ion Loss: 0.361044 | Validation AUC: 0.9544
Learning Rate: 0.001000 | Epoch: 3 | Training Loss: 0.258450 | Validat
ion Loss: 0.259592 | Validation AUC: 0.9635
Learning Rate: 0.001000 | Epoch: 4 | Training Loss: 0.234784 | Validat
ion Loss: 0.230376 | Validation AUC: 0.9719
Learning Rate: 0.001000 | Epoch: 5 | Training Loss: 0.217326 | Validat
ion Loss: 0.434614 | Validation AUC: 0.9695
Learning Rate: 0.001000 | Epoch: 6 | Training Loss: 0.205396 | Validat
ion Loss: 0.200996 | Validation AUC: 0.9757
Learning Rate: 0.001000 | Epoch: 7 | Training Loss: 0.196464 | Validat
ion Loss: 0.235432 | Validation AUC: 0.9695
Learning Rate: 0.001000 | Epoch: 8 | Training Loss: 0.190326 | Validat
ion Loss: 0.261167 | Validation AUC: 0.9751
Learning Rate: 0.001000 | Epoch: 9 | Training Loss: 0.180515 | Validat
ion Loss: 0.185495 | Validation AUC: 0.9792
Learning Rate: 0.001000 | Epoch: 10 | Training Loss: 0.177566 | Valida
tion Loss: 0.270730 | Validation AUC: 0.9624
Learning Rate: 0.000500 | Epoch: 1 | Training Loss: 0.368175 | Validat
ion Loss: 0.352323 | Validation AUC: 0.9460
Learning Rate: 0.000500 | Epoch: 2 | Training Loss: 0.294182 | Validat
ion Loss: 0.326843 | Validation AUC: 0.9581
Learning Rate: 0.000500 | Epoch: 3 | Training Loss: 0.270776 | Validat
ion Loss: 0.257698 | Validation AUC: 0.9588
Learning Rate: 0.000500 | Epoch: 4 | Training Loss: 0.247782 | Validat
ion Loss: 0.251780 | Validation AUC: 0.9612
Learning Rate: 0.000500 | Epoch: 5 | Training Loss: 0.228117 | Validat
ion Loss: 0.221368 | Validation AUC: 0.9712
Learning Rate: 0.000500 | Epoch: 6 | Training Loss: 0.213633 | Validat
ion Loss: 0.252928 | Validation AUC: 0.9666
Learning Rate: 0.000500 | Epoch: 7 | Training Loss: 0.205048 | Validat
ion Loss: 0.370398 | Validation AUC: 0.9512
Learning Rate: 0.000500 | Epoch: 8 | Training Loss: 0.196067 | Validat
ion Loss: 0.205297 | Validation AUC: 0.9739
Learning Rate: 0.000500 | Epoch: 9 | Training Loss: 0.189115 | Validat
ion Loss: 0.218027 | Validation AUC: 0.9705
Learning Rate: 0.000500 | Epoch: 10 | Training Loss: 0.184064 | Valida
tion Loss: 0.209741 | Validation AUC: 0.9768
Learning Rate: 0.000200 | Epoch: 1 | Training Loss: 0.388876 | Validat
ion Loss: 0.329632 | Validation AUC: 0.9336
Learning Rate: 0.000200 | Epoch: 2 | Training Loss: 0.314051 | Validat
ion Loss: 0.344805 | Validation AUC: 0.9292
Learning Rate: 0.000200 | Epoch: 3 | Training Loss: 0.281803 | Validat
ion Loss: 0.328516 | Validation AUC: 0.9575
Learning Rate: 0.000200 | Epoch: 4 | Training Loss: 0.257448 | Validat
ion Loss: 0.304889 | Validation AUC: 0.9551
Learning Rate: 0.000200 | Epoch: 5 | Training Loss: 0.235736 | Validat
ion Loss: 0.535648 | Validation AUC: 0.9450
Learning Rate: 0.000200 | Epoch: 6 | Training Loss: 0.220897 | Validat
ion Loss: 0.227795 | Validation AUC: 0.9709
Learning Rate: 0.000200 | Epoch: 7 | Training Loss: 0.209556 | Validat
ion Loss: 0.309369 | Validation AUC: 0.9656
Learning Rate: 0.000200 | Epoch: 8 | Training Loss: 0.211374 | Validat
ion Loss: 0.264006 | Validation AUC: 0.9737
Learning Rate: 0.000200 | Epoch: 9 | Training Loss: 0.194780 | Validat
```

```
ion Loss: 0.213892 | Validation AUC: 0.9722

Learning Rate: 0.000200 | Epoch: 10 | Training Loss: 0.185912 | Validation Loss: 0.178583 | Validation AUC: 0.9801

Best learning rate according to hyperparameter search: 0.001
```

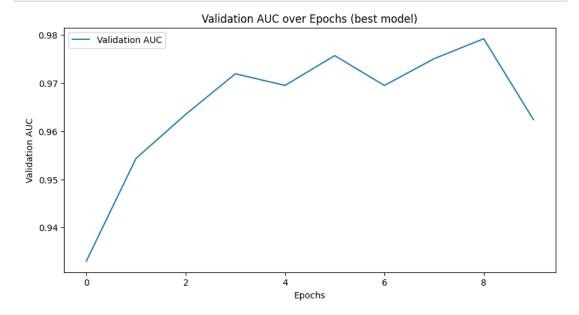
```
In [28]: # plot training and validation loss over epochs for best model

def plot_losses(train_losses, valid_losses, title):
    plt.figure(figsize=(10, 5))
    plt.plot(train_losses, label="Train Loss")
    plt.plot(valid_losses, label="Valid Loss")
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.title(title)
    plt.legend()
    plt.show()
```



```
In [30]: # plot validation auc over epochs for best model

def plot_aucs(aucs, title):
    plt.figure(figsize=(10, 5))
    plt.plot(aucs, label="Validation AUC")
    plt.xlabel('Epochs')
    plt.ylabel('Validation AUC')
    plt.title(title)
    plt.legend()
    plt.show()
```



```
In [34]: ▶ # reuse best learning rate from first CNN
             lr = learning_rates[best_model_idx]
             model_dense = DenseNetModified().to(device)
             # set optimizer and loss function
             optimizer = optim.Adam(model_dense.parameters(), lr=lr)
             criterion = nn.BCEWithLogitsLoss()
             # store final results
             train losses dense = []
             valid losses dense = []
             valid_aucs_dense = []
             n = 10
             # iterate all epochs
             for epoch in range(1, n epochs+1):
                 valid_aucs_epoch = []
                 model dense.train()
                 train_loss = 0.0
                 # process training images
                 for data, target in train loader:
                     optimizer.zero_grad()
                     data, target = data.to(device), target.to(device)
                     output = model_dense(data)
                     loss = criterion(output.view(-1), target.float())
                     loss.backward()
                     optimizer.step()
                     train_loss += loss.item() * data.size(0)
                 model dense.eval()
                 valid_loss = 0.0
                 # process validation images
                 for data, target in valid_loader:
                     data, target = data.to(device), target.to(device)
                     output = model dense(data)
                     loss = criterion(output.view(-1), target.float())
                     valid_loss += loss.item() * data.size(0)
                     y actual = target.data.cpu().numpy()
                     y_pred = torch.sigmoid(output).detach().cpu().numpy()
                     valid_aucs_epoch.append(roc_auc_score(y_actual, y_pred))
                 # store final results
                 train_loss /= len(train_loader.sampler)
                 valid_loss /= len(valid_loader.sampler)
                 valid_auc = np.mean(valid_aucs_epoch)
                 train_losses_dense.append(train_loss)
                 valid losses dense.append(valid loss)
                 valid_aucs_dense.append(valid_auc)
```

```
print('Learning Rate: {:.6f} | Epoch: {} | Training Loss: {:.6f} | **
```

/opt/conda/lib/python3.10/site-packages/torchvision/models/_utils.py:2
08: UserWarning: The parameter 'pretrained' is deprecated since 0.13 a
nd may be removed in the future, please use 'weights' instead.
 warnings.warn(

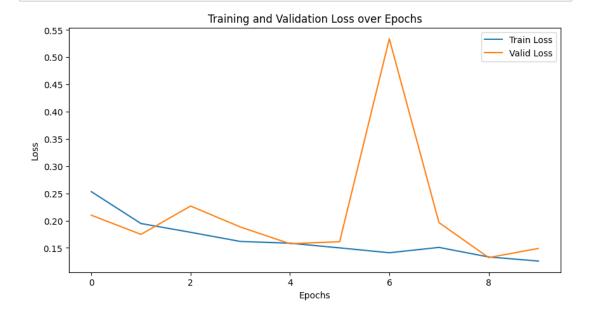
/opt/conda/lib/python3.10/site-packages/torchvision/models/_utils.py:2 23: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=DenseNet121_Weights.IMAGENET1K_V1`. You can also use `weights=DenseNet121_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

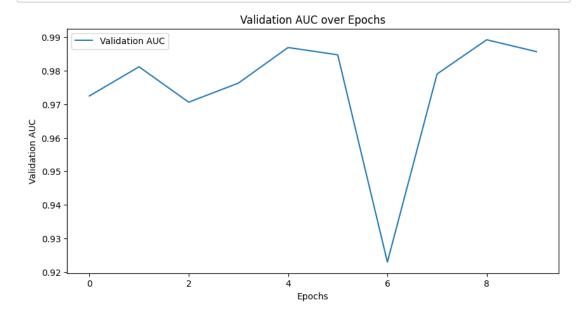
Downloading: "https://download.pytorch.org/models/densenet121-a639ec9 7.pth" to /root/.cache/torch/hub/checkpoints/densenet121-a639ec97.pth 100%| 30.8M/30.8M [00:00<00:00, 94.9MB/s]

Learning Rate: 0.001000 | Epoch: 1 | Training Loss: 0.253261 | Validat ion Loss: 0.210021 | Validation AUC: 0.9725 Learning Rate: 0.001000 | Epoch: 2 | Training Loss: 0.194694 | Validat ion Loss: 0.174802 | Validation AUC: 0.9812 Learning Rate: 0.001000 | Epoch: 3 | Training Loss: 0.178575 | Validat ion Loss: 0.226813 | Validation AUC: 0.9706 Learning Rate: 0.001000 | Epoch: 4 | Training Loss: 0.161805 | Validat ion Loss: 0.188352 | Validation AUC: 0.9763 Learning Rate: 0.001000 | Epoch: 5 | Training Loss: 0.158523 | Validat ion Loss: 0.157636 | Validation AUC: 0.9870 Learning Rate: 0.001000 | Epoch: 6 | Training Loss: 0.149996 | Validat ion Loss: 0.161290 | Validation AUC: 0.9848 Learning Rate: 0.001000 | Epoch: 7 | Training Loss: 0.141029 | Validat ion Loss: 0.533926 | Validation AUC: 0.9229 Learning Rate: 0.001000 | Epoch: 8 | Training Loss: 0.150861 | Validat ion Loss: 0.196374 | Validation AUC: 0.9791 Learning Rate: 0.001000 | Epoch: 9 | Training Loss: 0.133298 | Validat ion Loss: 0.132151 | Validation AUC: 0.9893 Learning Rate: 0.001000 | Epoch: 10 | Training Loss: 0.125797 | Valida tion Loss: 0.148961 | Validation AUC: 0.9857

In [35]: ▶ plot_losses(train_losses_dense, valid_losses_dense, 'Training and Valid



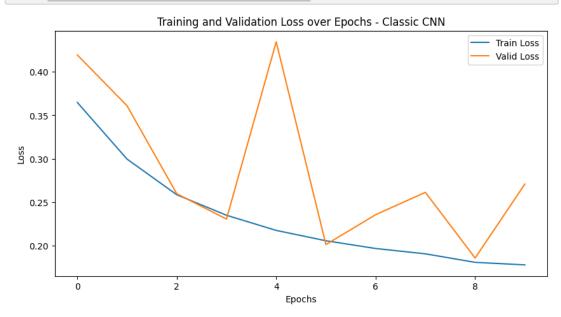
In [36]: ▶ plot_aucs(valid_aucs_dense, 'Validation AUC over Epochs')



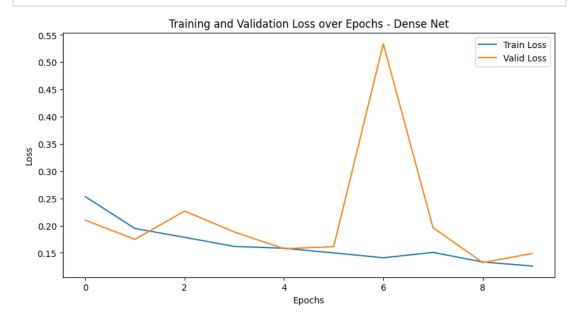
In [37]: ▶ print("Best learning rate according to hyperparameter search on Classic

Best learning rate according to hyperparameter search on Classic CNN m odel: 0.001

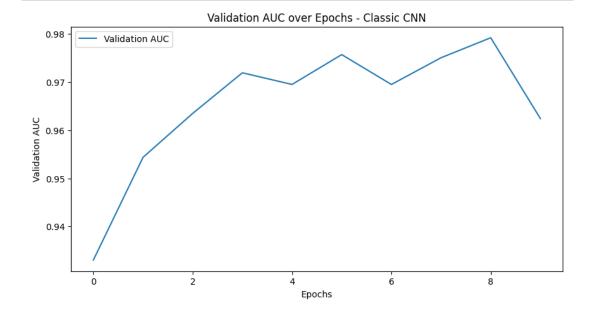




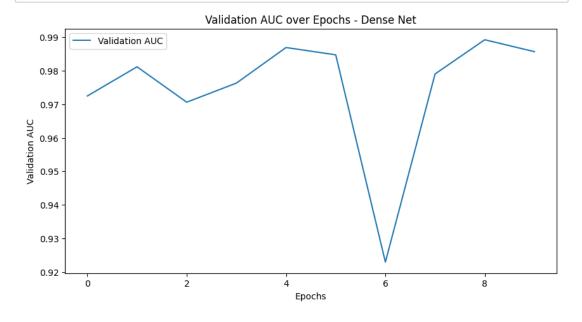
In [39]: ▶ plot_losses(train_losses_dense, valid_losses_dense, 'Training and Validation



In [40]: ▶ plot_aucs(best_result['valid_aucs'], 'Validation AUC over Epochs - Class



In [41]: ▶ plot_aucs(valid_aucs_dense, 'Validation AUC over Epochs - Dense Net')



In [42]: ▶ clear_memory()

```
In []: ▶ # turn of gradients
           model_dense.eval()
           preds = []
           # iterate all test images
           for batch_i, (data, target) in enumerate(test_loader):
               data, target = data.to(device), target.to(device)
               output = model_dense(data)
               pr = output.detach().cpu().numpy()
               for i in pr:
                   preds.append(i)
           # add predicted labels to submission file
           df_sample_sub['label'] = preds
In []: ▶ # convert probabilities to float
           for i in range(len(df_sample_sub)):
               df_sample_sub.label[i] = np.float(df_sample_sub.label[i])
df_sample_sub.to_csv('submission.csv', index=False)
```