CliquePercolation

Jens Lange

2019-10-22

The CliquePercolation package entails a number of functions related to the clique percolation community detection algorithms for unweighted and weighted networks (as described in Palla et al. 2005 and Farkas et al., 2007).

The package entails functions for...

- helping to optimize parameters of the algorithms
- running the algorithms
- plotting the results.

This document provides an introduction to this workflow with some random example data sets.

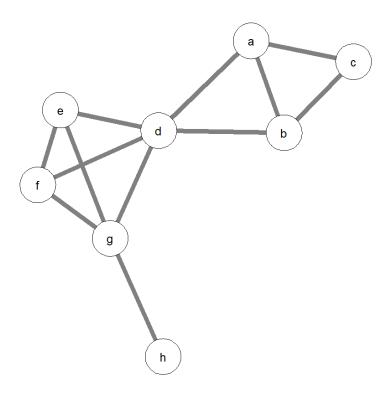
An Introduction to the Clique Percolation Community Detection Algorithm

Interconnected entities can be represented as networks. Each network entails two sets, namely *nodes*, which are the entities, and *edges*, which are the connections between entities. For instance, nodes could represent people and edges could represent whether they are friends or not. Or nodes could represent cities and edges could represent whether there is a street connecting the cities. Such networks, in which edges are either present or absent, are called *unweighted*. In other cases, nodes could represent people and edges could represent the frequency with which these people meet. Or nodes could represent questionnaire items and edges could represent the correlations of these items. In such a case, the edges are not only present or absent, but may count the frequency or strength of interactions. Such networks are called *weighted*.

Analyzing the structure of such networks is a key task across sciences. One structural feature that is often investigated is the identification of strongly connected subgraphs in the network, which is called *community detection* (Fortunato, 2010). Most community detection algorithms thereby put each node in only one community. However, it is likely that nodes are often shared by a number of communities. This could occur, for instance, when a friend is part of multiple groups. One community detection algorithm that is aimed at identifying overlapping communities is the *clique percolation method*, which has been developed for unweighted (Palla et al., 2005) and weighted networks (Farkas et al., 2007).

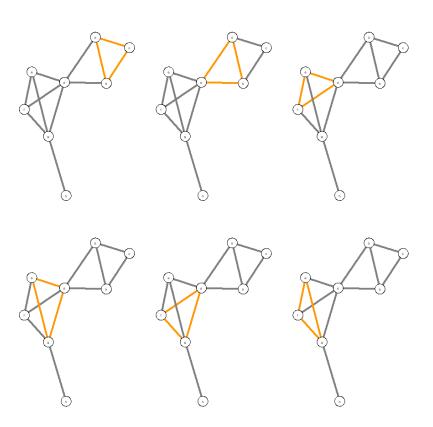
The clique percolation algorithm for unweighted networks proceeds as follows:

First, you identify a network of nodes and edges. I will use an unweighted network with eight nodes.



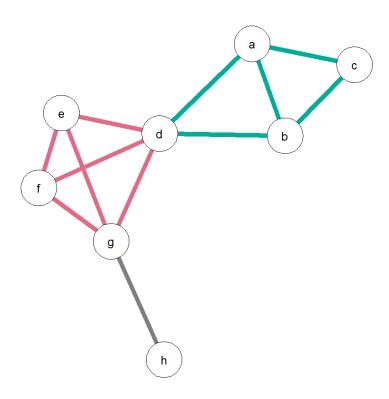
Unweighted network with eight nodes.

Second, you identify k-cliques, which are fully connected networks with k nodes. The smallest possible k would be k = 3. Otherwise, the cliques would be only edges. Applying k = 3 to the example leads to the identification of six 3-cliques, namely



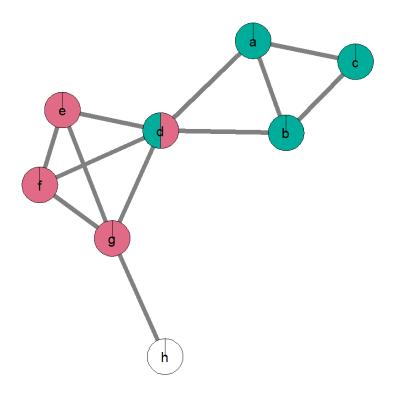
Six 3-cliques in unweighted network.

• Finally, a community is defined as a set of adjacent k-cliques, that is, k-cliques that share exactly *k-1* nodes. With k = 3, two 3-cliques are adjacent if they share exactly two nodes (equivalent to an edge). In the example, this implies that there are two communities (see below). The green edges entail the 3-cliques a–b–c and a–b–d. The pink edges entail the 3-cliques d–e–f, d–e–g, d–f–g, and e–f–g.



Two communities in unweighted network.

This also showcases that the clique percolation algorithm can lead to nodes that are *shared* by communities. In the current example, node d is part of both the green and the pink community. Nodes a, b, and c are part of only the green community and nodes e, f, and g are part of only the pink community. Importantly, clique percolation can also lead to nodes that are part of no community. These are called *isolated nodes*, in the current example, node h. One way to plot the community partition on the original network would be to color the nodes according to the communities they belong to. Shared nodes have multiple colors and isolated nodes remain white.



Community partition by node coloring in unweighted network.

For weighted networks, this algorithm has just one intermediate additional step. Specifically, after identifying the k-cliques, they are considered further only if their *Intensity* exceeds a specified threshold I. The Intensity of a k-clique is defined as the geometric mean of the edge weights, namely

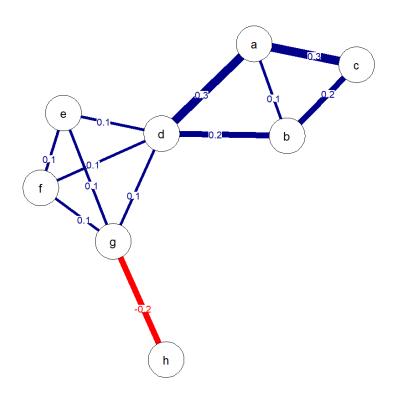
Intensity_C =
$$\left(\prod_{i < j; i, j \in C} w_{ij}\right)^{2/k(k-1)}$$

Where C is the clique, i and j are the nodes, w is the edge weight, and k is the clique size. For instance, a 3-clique with edge weights 0.1, 0.2, and 0.3 would have

Intensity_C =
$$(0.1 * 0.2 * 0.3)^{2/3(3-1)} \approx 0.18$$

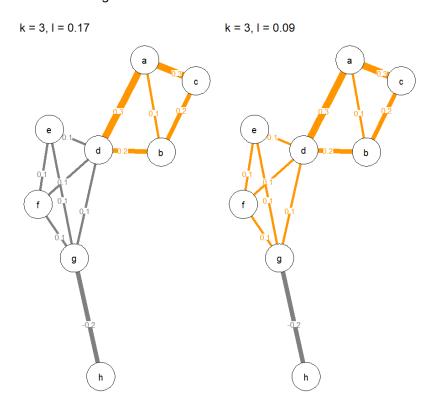
To show the influence of I, here is the network from the previous example, but this time I added edge weights.

4/21/2020



Weighted network with eight nodes.

If I = 0.17, only two cliques (a-b-c, a-b-d) would survive the threshold. If only these are further considered, the clique percolation method would find only one community (the formerly green community) and four nodes would be isolated (e, f, g, h). If, however, I = 0.09, all cliques would survive the threshold, leading to the same community partition as for the unweighted network.



Surviving cliques in weighted network depending on I.

Even though this is not described in Farkas et al. (2007), the program that the developers of the clique percolation method designed, CFinder, adds yet another intermediate step to this procedure. Specifically, the Intensity threshold I is applied not only to the k-cliques but additionally to the *overlap* of the k-cliques. For instance, in the case of the 3-cliques in our example, the overlap of the 3-cliques a–b–c and a–b–d is the edge a–b. If I = 0.17, the two 3-cliques would survive the threshold. Subsequently, it is checked whether the a–b edge also exceeds the threshold. In the current case, it would not, because the edge weights is only 0.1. Given that the edge does not exceed the threshold, the two 3-cliques are not considered adjacent. Therefore, instead of putting them in the same community, the two 3-cliques are considered to be two separate communities with two shared nodes in CFinder.

Optimizing k and I

A challenging task is to choose optimal k and I when running the clique percolation algorithms. For unweighted networks, only an optimal k needs to be found, as I is not used. Below, I will outline guidelines to choose optimal k and I for weighted networks. Note that for unweighted networks the same guidelines apply, yet, only for k. Guidelines are provided in Palla et al. (2005) and Farkas et al. (2007), which are based on ideas in percolation theory. This can be better illustrated for weighted networks. For each k, a large I will lead to the exclusion of most if not all k-cliques for further consideration. The other extreme, a very low I, will lead to the inclusion of most if not all k-cliques for further consideration and then often leads to a gigantic component to which all nodes belong. The optimal I for each k is just above the point of the emergence of the gigantic component. It is supported that at this point, the size distribution of the communities follows a power-law. To reach this point with the broadest possible distribution, one can check the *ratio* of the largest to second largest community sizes. If the largest community is twice as large as the second largest, an optimal I for a specific k was found.

Notably, applying this threshold requires a large number of communities, otherwise this point might not be very stable. For somewhat smaller, yet still rather large networks, Farkas et al. (2007) propose to instead check the *variance* of the community sizes after excluding the largest community. The formula they provide is

$$\chi = \sum^{n_{\alpha} \neq n_{max}} \frac{n_{\alpha}^{2}}{(\sum^{\beta} n_{\beta})^{2}}$$

where χ is the variance, n_{α} is a set of communities excluding the largest one, and n_{β} is a set of communities that does neither include n_{α} nor the largest community. For instance, if there are four communities with 9, 7, 6, and 3 nodes, respectively, then one would exclude the largest community, and determine the variance of the last three by

$$\chi = \frac{7^2}{(6+3)^2} + \frac{6^2}{(7+3)^2} + \frac{3^2}{7+6^2} \approx 1.02$$

The idea is as follows. When I is higher, there will be many equally small communities of size k. When I is very low, there will be a gigantic community and many equally small ones. Thus, after excluding the largest community, for higher and smaller I, χ will be small. In contrast, when the community size distribution is broad (i.e., close to a power law), then the variance of the communities (after excluding the largest community) will be higher. Thus, the point of the maximal variance is another way to optimize I for respective k.

Nevertheless, also a stable estimate of χ requires a number of communities. If the network is very small, such that only a few communities can be expected, also the χ threshold is unreliable. Moreover, it would be undesirable to have, for instance, two communities of which one is twice as large as the other. Instead, equally sized communities would be preferred. An alternative way to optimize I for different k for very small networks would be to rely on the *entropy* of the community partition. I adopt an entropy measure based on Shannon

Information. The idea is to find the most surprising community partition, defined as a low probability of knowing to which community a randomly picked node belongs. If there is only one community, surprisingness would be zero, because it would be certain that a randomly picked node belongs to this community. If there are two communities of sizes 15 and 3, it would still not be very surprising, because most likely a randomly picked node will belong to the larger community. Surprisingness would be higher, however, when the communities are equal in size. Entropy based on Shannon Information captures this idea in the formula

$$Entropy = -\sum_{i=1}^{N} p_i * \log_2 p_i$$

where N is the number of communities and p_i is the probability of being in community i. For the four community sizes above (9, 7, 6, 3), the result would be

Entropy =
$$-\left(\left(\frac{9}{9+7+6+3} * log_2 \frac{9}{9+7+6+3}\right) + \left(\frac{7}{9+7+6+3} * log_2 \frac{7}{9+7+6+3}\right) + \left(\frac{6}{9+7+6+3} * log_2 \frac{6}{9+7+6+3}\right) + \left(\frac{3}{9+7+6+3} * log_2 \frac{3}{9+7+6+3}\right)\right)$$

$$\approx 1.91$$

As pointed out, with only one community, this formula equals zero. When calculating entropy, isolated nodes are treated as another pseudo-community and shared nodes are split equally among the communities they belong to (e.g., a node shared by two communities is added as 0.5 nodes to each of them). As such, entropy favors equally sized communities with few isolated nodes in very small networks. This is exactly what would be desired. The I that has the maximum entropy for the respective k can be used to optimize k and I. As for very small networks, a specific amount of communities may be found just by chance alone, you can also run permutation tests. Specifically, the edges of the network are randomly shuffled a number of times and for each of these random permutations, the highest entropy of a range of I values is determined separately for each k. Over all permutations, this leads to a distribution of entropy values for each k separately. Only entropy values that exceed the confidence interval of the distribution of each k can be considered more surprising than would already be expected by chance alone. Initial simulation studies support the performance of entropy and the permutation test in very small networks. Yet, more research is required. Especially for large and very large networks, the entropy threshold should not be used. As it prefers equally sized community sizes, it would penalize the broad power law distribution of community sizes that is preferred for these networks.

Finally, for unweighted networks, the approach is rather similar. Yet, given that only a few k can be tested (e.g., 3 to 6) many thresholds will not be very sensitive. Nevertheless, a small k (e.g., k = 3) will often result in the emergence of a giant component to which most of the nodes belong. Increasing k (e.g., k = 6) will often lead to a large number of smaller communities. The optimal k is when there is no giant component for very large networks, when variance is maximal for large networks, or when entropy is maximal for very small networks.

In sum, the clique percolation method proceeds by identifying k-cliques and by putting adjacent k-cliques (k-cliques that share k-1 nodes) into a community. For weighted networks, it is additionally checked whether the Intensity of the k-cliques exceeds the Intensity threshold I. If not, they are removed from consideration. Finally, in the CFinder program, the k-1 overlap of k-cliques is also checked in terms of whether it exceeds the Intensity threshold. If not, the k-cliques are considered separately and not as a single community. Optimal k and I can be determined with the ratio test for large networks, variance for small networks, or entropy for very small networks.

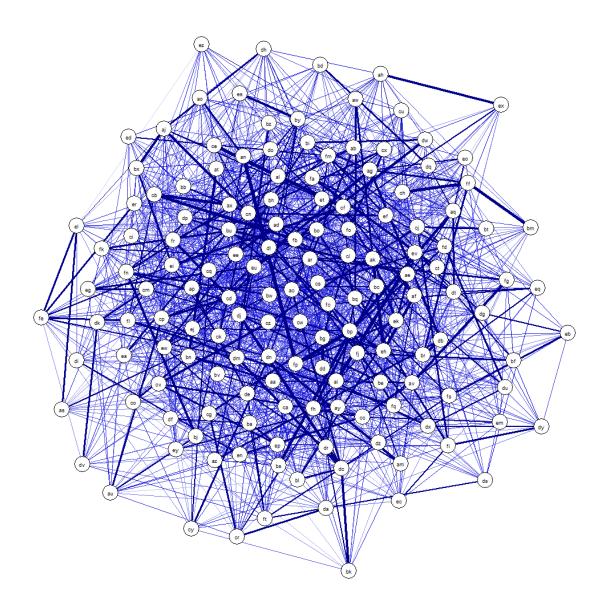
The CliquePercolation package

The CliquePercolation package entails functions to conduct the clique percolation community detection algorithms for unweighted and weighted networks and to interpret the results. In what follows, an example is used to explain the workflow suggested by the package.

CliquePercolation accepts only networks that were analyzed with the qgraph package (Epskamp et al., 2012). Moreover, I will use the Matrix package for the example below. Thus, we need to load the following packages in R to run the example

```
library(CliquePercolation)
library(qgraph)
library(Matrix)
```

First, I will create an example network. When you want to apply the clique percolation method, you will already have a network. Importantly, it needs to be a qgraph object. The network I am using is weighted, with edge weights drawn from a random distribution with mean of 0.3 and a standard deviation of 0.1.



Weighted network with 150 nodes.

To run the clique percolation algorithm for weighted networks, we initially need to optimize k and I. To this end, the *cpThreshold* function can be used. For a specific network (i.e., a qgraph object), it determines the ratio of the largest to second largest community, χ , and/or entropy over a range of k and I values. It does so by running the clique percolation algorithm for either unweighted (method = "unweighted") or weighted networks (method = "weighted"). The algorithm as implemented in CFinder can also be requested (method = "weighted.CFinder"). For each k and I combination, cpThreshold determines the respective threshold and saves the results in a data frame, specifying the respective k, I, the number of communities, the number of isolated nodes, and the requested thresholds. Note that the ratio threshold can be determined only when there are at least two communities and χ can be determined only when there are at least three communities. Otherwise, the function will return NA values in these cases. Entropy can always be determined. In the current case, as the network is rather large, I will request only the ratio and χ thresholds. I will do so for k values of 3 and 4 and I values of 0.40 to 0.01 in steps of 0.005. Even smaller steps might in many cases be preferred,

given that even small changes of 0.005 can lead to rather different (and potentially optimal) values. However, to save computation time, I took these larger steps. The range of I values was chosen based on the fact that my mean edge weight was set to 0.3 when generating the network. Thus, I = 0.40 should allow me to find a broad community size distribution. However, to be sure, one could start by setting the highest tested value of I to the maximum edge weight in the network. This is recommended by Farkas et al. (2007). But then, very high I values will rarely lead to the identification of any k-clique. The k.range and I.range are entered as vectors of numbers. The requested thresholds are also entered as a vector of strings. Depending on the network, this function may need lots of time to run (the code below ran for 15 minutes on my laptop). To see how long it takes, a progress bar is implemented.

The cpThreshold function is used as follows

```
thresholds <- cpThreshold(W, method = "weighted", k.range = c(3,4),

I.range = c(seq(0.40, 0.01, by = -0.005)),

threshold = c("largest.components.ratio", "chi"))
```

We can now access the data frame that is saved in the object thresholds

```
thresholds
```

To decide in favor of optimal I values for each k, we now check at which I the ratio threshold is jumping abruptly to a high level, thereby crossing the ratio 2. The I just before the jump should ideally also be the point of the highest χ . For k=3, the ratio first crossed 2 at I=0.35 with χ being rather large. This solution has 45 communities and nine isolated nodes. For k=4, the ratio first crossed 2 at I=0.27. The χ is not very large and subsequently the nodes never reach a stage at which they are all part of a single community, most likely because k is too large to allow that to happen. This already indicates that k=4 is probably too high. This solution has 62 communities and 29 isolated nodes. Also the number of isolated nodes is rather high. Still, we can now use these optimized values to run the clique percolation method. For this, we apply the *cpAlgorithm* function. Specifically, the cpAlgorithm function takes a network (i.e., a qgraph object) and runs the clique percolation algorithm for unweighted (method = "unweighted") or weighted networks (method = "weighted"). The algorithm as implemented in CFinder can also be requested (method = "weighted.CFinder"). Additionally, we enter the optimal k and I values determined via cpThreshold. Thus, we run cpAlgorithm twice, namely

```
cpk3I.35 <- cpAlgorithm(W, k = 3, method = "weighted", I = 0.35)
cpk4I.27 <- cpAlgorithm(W, k = 4, method = "weighted", I = 0.27)
```

Each of these objects is a list, entailing the results of the clique percolation method. Each element can be requested via the \$. For instance, the list of communities with the node numbers as identifiers of the nodes for the k = 3 solution can be requested by typing

```
cpk3I.35$list.of.communities.numbers
```

As an example, community 45 entails nodes 9, 12, and 33. We also named the nodes via letters. The same results with these labeled nodes can be requested via

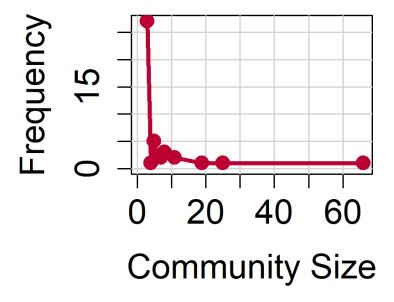
```
cpk3I.35$list.of.communities.labels
```

The nodes 9, 12, and 33 in community 45 are named "ai", "al", and "bg".

To decide in favor of one solution, we can investigate the community size distribution. This should be maximally broad, similar to a power law. To look at the community size distribution, we can use another

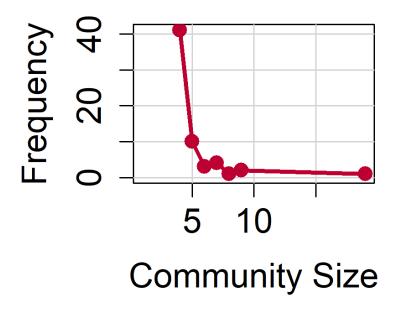
function, namely *cpCommunitySizeDistribution*. It takes the list of communities generated by cpAlgorithm and turns it into a distribution plot. As the plot may not please you visually, the function also returns a data frame with the frequency data. Thus, you are free to plot these data in any way you want. The default line color of the distribution is red, but could be changed via the color.line argument.

cpCommunitySizeDistribution(cpk3I.35\$list.of.communities.numbers)



Community size distribution with k = 3 and l = 0.35.

cpCommunitySizeDistribution(cpk4I.27\$list.of.communities.numbers)



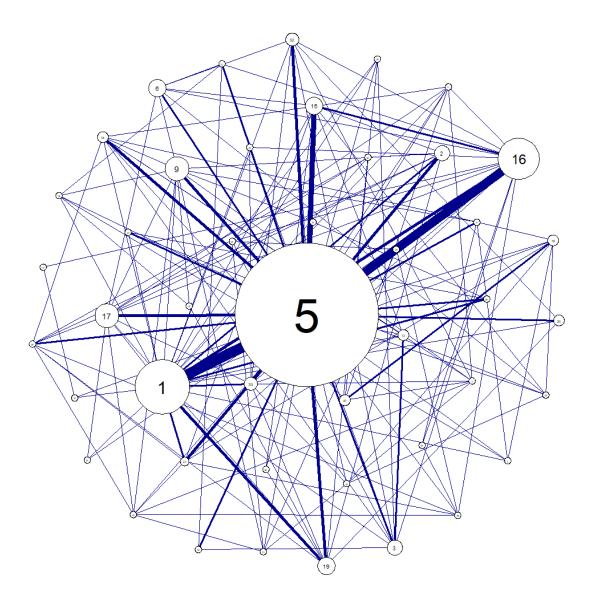
Community size distribution with k = 4 and l = 0.27.

Especially the distribution for k = 3 looks very much like a power law, given that multiple very large community sizes occur rarely. Thus, we decide in favor of k = 3 and l = 0.35 as the optimal parameters for clique percolation.

The results object not only includes lists with the communities, but also vectors for shared nodes and isolated nodes, again both with numbers as identifies of nodes (shared.nodes.numbers, isolated.nodes.numbers) or the labels (shared.nodes.labels, isolated.nodes.labels). In the example, 94 nodes are shared among communities and 9 are isolated.

Oftentimes, researchers are interested in plotting the solution of the clique percolation method in another network, such that a node represents a community, and the edges between nodes represent the number of nodes that two communities share (i.e., the community graph). Plotting this network can be done with the *cpCommunityGraph* function. It also takes the list of communities from cpAlgorithm and turns it into the community network. To showcase which node represents which network, the node sizes can be plotted proportional to the largest node (node.size.method = "proportional"). To do this, we set the size of the largest node via max.node.size and the others are scaled accordingly. If the proportional visualization is not preferred, we can also plot all nodes with equal size (node.size.method = "normal"). As the community network is plotted via qgraph, one can also add all other arguments available in qgraph to make the graph more pleasing. Moreover, next to plotting the community network, the function also returns the weights matrix of the community graph. This matrix could then be used for other purposes.

The current community network can be plotted as follows, by additionally using a spatial arrangement and edge coloring from qgraph.



Community network with k = 3 and l = 0.35.

The weights matrix can be accessed via

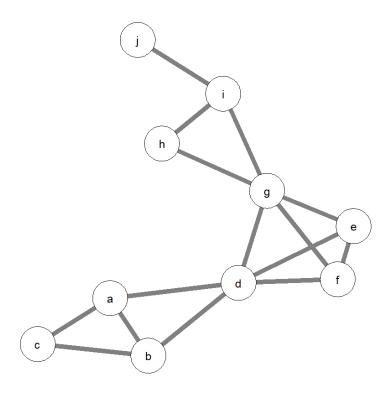
commnetwork\$community.weights.matrix

As was already clear from the community size distribution, most communities are rather small, while community 5 is very large. Yet there is overlap among many communities, that, in the case of an actual network, should then be interpreted thematically.

Very small networks

For very small networks, the above procedures may not all apply. First, the ratio and χ thresholds cannot be determined or are not very informative for very small networks. Second, a community network may not be the most informative representation of the results, if there are only very few communities to begin with.

To showcase the somewhat altered workflow with very small networks, we will use a very small, unweighted network.



Unweighted network with ten nodes.

Again, we will first use cpThreshold. As the network is unweighted, we need to specify only the k.range but not the I.range. As the network is very small, we will request entropy instead of the ratio and χ .

```
thresholds.small <- cpThreshold(W, method = "unweighted", k.range = c(3,4), threshold = "entropy")
```

You can now access the data frame that is saved in the object thresholds.small

I display it here because, as compared to the previous example, it is short. For k = 3, there are three communities and one isolated node with an entropy of 1.88. For k = 4, there is one community and six isolated nodes with an entropy of 0.97.

Now, we can estimate whether this entropy is higher than would already be expected by chance. The permutation test for very small networks is implemented in the function *cpPermuteEntropy*. For a specific network (i.e., a qgraph object) and a cpThreshold object, cpPermuteEntropy creates n permutations of the network, performs cpThreshold for each, extracts the highest entropy for each k, and determines the

confidence interval of the entropy for each k. n = 100 and the 95% confidence interval are the default settings. Larger n are certainly desired but can lead to large computation time. A progress bar again indicates how long it will take. It can be used as follows

It produces a list with two objects. First, the confidence intervals for each k can be accessed by

```
permute$Confidence.Interval
#> k 95% CI lower 95% CI upper
#> 1 3    1.23706573    1.3655954
#> 2 4    0.04708604    0.1671041
```

4/21/2020

Furthermore, the function also takes the original cpThreshold object specified in cpThreshold.object and removes all rows that do not exceed the upper bound of the confidence interval. This altered data frame is available by

In the current example, both solutions, for k = 3 and k = 4, exceed the upper bound of the confidence interval and are thus still in the data frame.

Now we can choose an optimal k. Even though both exceed the upper bound of the confidence interval, the number of isolated nodes for k = 4 is rather high, leading us to accept k = 3 as the optimal k.

Using this optimal k, we run the cpAlgorithm

```
cpk3 <- cpAlgorithm(W, k = 3, method = "unweighted")</pre>
```

By inspecting the results with

```
cpk3$list.of.communities.labels
#> [[1]]
#> [1] "d" "e" "f" "g"
#>
#> [[2]]
#> [1] "g" "h" "i"
#>
#> [[3]]
#> [1] "a" "b" "c" "d"
```

we see that we indeed have three communities, one entailing nodes a, b, c, and d, one entailing nodes d, e, f, and g, and one entailing nodes g, h, and i.

By using

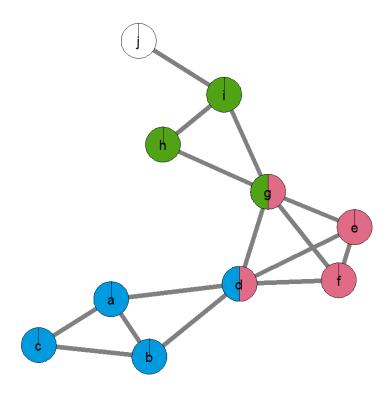
```
cpk3$shared.nodes.labels
#> [1] "d" "g"
```

we see that node d and g are shared nodes and by using

```
cpk3$isolated.nodes.labels
#> [1] "j"
```

we see that node j is isolated.

Finally, we would like to plot the results of the clique percolation algorithm. However, using the community graph for a network with only three communities would not be very informative. In the current case, the community network would have three nodes with two edges. For very small networks, an alternative may be reasonable, namely plotting the community partition directly on the original network that was analyzed. This can be achieved with the *cpColoredGraph* function. It takes the community partition from cpAlgorithm and assigns qualitatively different colors to the communities with the help of the colorspace package (Zeileis et al., subm.). It is based on the HCL color space, generating palettes of colors that are rather balanced and visually pleasing. Isolated nodes will be displayed white. Shared nodes will be divided in multiple colors, one for each community they belong to. Original ggraph arguments can be used to make the network appear as before.



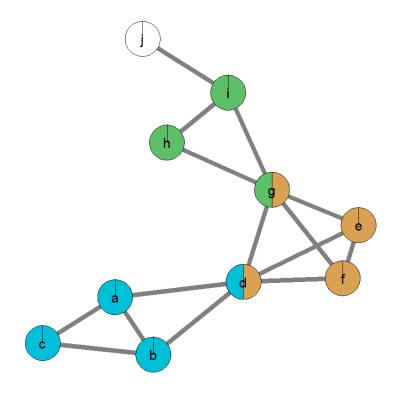
Community coloring I.

The function also returns the colors assigned to the communities and the colors assigned to the nodes. The colors assigned to the nodes are a list with vectors for each node. If a node is shared, all its colors are in the vector. These results can be accessed by

```
colored.net1$colors.communities
colored.net1$colors.nodes
```

The function used for generating qualitatively different colors in the package colorspace is called qualitative_hcl. It generates colors of a range of hue values, holding chroma and luminance constant. cpColoredGraph uses the recommended defaults from qualitative_hcl. However, these defaults can be overwritten, if different colors are desired. For instance, to plot the graph from before with colors in the range from yellow to blue, lower chroma, and higher luminance, the following code could be used

```
colored.net2 <- cpColoredGraph(W, list.of.communities = cpk3$list.of.communities.labels, h.cp = c(50, 210), c.cp = 70, l.cp = 70, edge.width = 4)
```



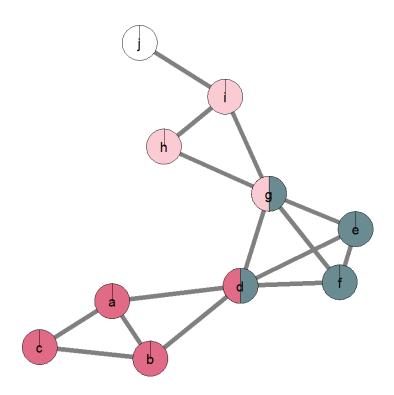
Community coloring II.

Oftentimes, the clique percolation algorithm is probably run on a network, for which there are predefined sets of nodes. For instance, it could be that in the example network, nodes a, b, c, d, g, h, and i are from one set (e.g., one questionnaire) and nodes e, f, and j are from another set (e.g., another questionnaire). Such sets of nodes can be taken into account, when plotting the network. For this, the list.of.sets argument needs to be specified, a list of vectors in which each vector codes one set of nodes. If this is done, cpColoredGraph assigns qualitatively different colors to the sets. Then, it checks whether the identified communities are pure (i.e., they entail nodes from only one set) or they are mixed (i.e., they entail nodes from multiple sets). For pure communities of each respective set, it takes the assigned color and fades it toward white, using colorspace's sequential_hcl. It does so such that there are as many non-white colors as there are pure communities of a set. Larger communities will be assigned stronger colors.

If a community is mixed with nodes from different sets, the colors of these sets will be mixed proportionally to the number of nodes from each set. For instance, if a community entails two nodes from one set and one node 4/21/2020

from another set, the colors will be mixed 2:1. For this, the colors are mixed subtractively (how paint mixes), which is difficult to implement. The mixing is done with an algorithm taken from Scott Burns (see http://scottburns.us/subtractive-color-mixture/ and http://scottburns.us/fast-rgb-to-spectrum-conversion-for-reflectances/). In short, colors are translated into reflectance curves. This is achieved by taking optimized reflectance curves of red, green, and blue and integrating them according to the RGB value of the color. The reflectance curves of the colors that have to be mixed are averaged via the weighted geometric mean. The resulting reflectance curve is translated back to RGB. According to substantive tests performed by Scott Burns, the mixing works nicely and is computationally efficient. Yet, it may not always produce precise results.

In the current example, with the list of sets mentioned above, two communities will be pure (a-b-c-d, g-h-i) and one will be mixed (d-e-f-g). The two pure communities will hence be faded from the assigned colored towards white, making the smaller community (g-h-i) lighter. The mixed community will be mixed in 1:1, as there are two nodes from each set. This could be achieved with the following code (using the first coloring).

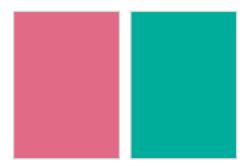


Community coloring III.

Now you can access another element, that cpColoredGraph returns, namely a vector with the colors assigned to the sets.

```
colored.net3$basic.colors.sets
```

Note that the colors are not identical to the colors in the network, as they were faded for two communities and mixed for another community. The actual colors assigned to the sets look like this

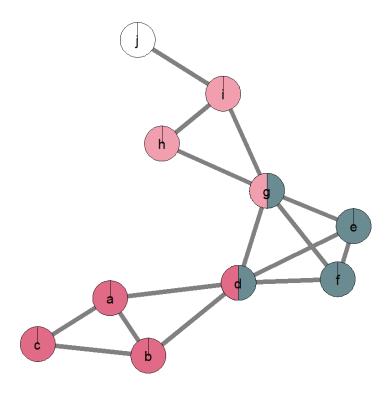


Color patches.

The community entailing d, e, f, and g is a mix of both colors.

Finally, the fading for pure communities always generates the faded palette for the number of pure communities of a set plus 1 (the plus one prevents that one community becomes white, which is reserved for isolated nodes). As such, if there are different numbers of pure communities for different sets in a network, or if across different networks there are different numbers of pure communities for the same set, their luminance values are not directly comparable. To make them comparable, we can assign a scale to the fading, such that we specify how many faded colors the set palettes should have. This can be achieved by specifying the set palettes.size argument. For instance, if it is set to 5, then for all pure communities of all sets, cpColoredGraph will generate five faded colors. Larger communities will get the stronger colors asf. As such, if there are more pure communities of one set than for another set in the same network, there will be lighter communities for the set with more than with less pure communities. Moreover, if one set of nodes produces more communities in one network than in another, its nodes will overall be lighter in the network in which it produced more communities.

In our example network, there were two pure communities of one set. Per default cpColoredGraph generated two faded non-white colors and assigned them to the communities. Thus, one community is rather strongly colored and the other is almost white. This overestimates that they are rather similar in size. Scaling them such that all pure communities are assigned colors from a set of five colors can be achieved as follows



Community coloring IV.

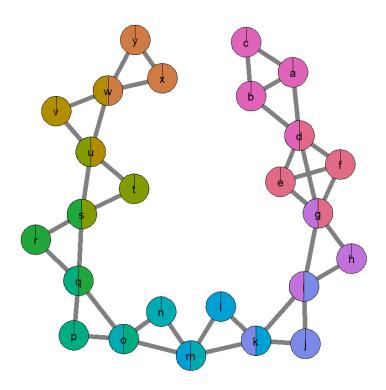
The larger community kept its color, but the smaller community g, h, i is now somewhat darker.

For cpColoredGraph, there is always a palette of qualitatively different colors generated, either for the elements in list.of.communities (when list.of.sets = NULL) or the elements in list.of.sets (when list.of.sets is not NULL). Zeileis et al. (subm.) argue that the palettes generated with qualitative_hcl in colorspace can produce only palettes of maximally six colors that people can still distinguish visually.

For instance, let's say we have a somewhat larger network with 11 communities. Plotted with qualitative colors generated via qualitative hcl, the solution would look as follows

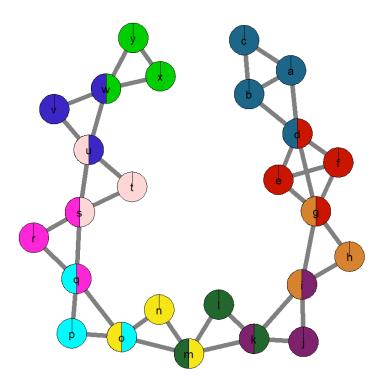
```
#generate network with 11 communities
```

```
= TRUE)
W <- forceSymmetric(W)</pre>
rownames(W) <- letters[seq(from = 1, to = nrow(W))]</pre>
colnames(W) <- letters[seq(from = 1, to = nrow(W))]</pre>
W <- qgraph(W, DoNotPlot = TRUE)</pre>
#run the clique percolation method
cpk3.large <- cpAlgorithm(W, k = 3, method = "unweighted")</pre>
#plot the network colored according to community partition (with qualitative_hcl)
                         cpColoredGraph(W,
colored.net.large1
                  <-
                                           list.of.communities
cpk3.large$list.of.communities.labels,
                                                    edge.width = 4,
layout = "spring", repulsion = 0.9)
#> Warning in cpColoredGraph(W, list.of.communities = cpk3.large$list.of.communities.labels,
: There are more than 6 communities. The colors might be hard to distinguish.
           Set larger.six = TRUE to get maximally different colors.
#>
#>
           Yet, colors might be visually a little less pleasing.
```



Large network with 11 communities colored with qualitative_hcl.

The warning message already mentions the problem and foreshadows a solution. The colors become harder to distinguish, making it difficult to identify the communities. To generate a larger set of qualitatively different colors that are maximally different, the createPalette function from the package Polychrome (Coombes et al., 2019) can be used. It generates maximally different colors from HCL space. When specifying larger.six = TRUE (default is FALSE) in cpColoredGraph, the qualitatively different colors for the communities or sets are generated with createPalette. The rest of the procedure is identical. In the current example, the network would look as follows



Large network with 11 communities colored with createPalette.

Indeed, the communities are easier to identify. However, given that the goal is to generate maximally different colors, the display may be visually less pleasing and balanced.

Note that for larger networks with more than six communities, plotting results with cpColoredGraph may not be preferable anyways. Instead, plotting the community network via cpCommunityGraph might be more informative.

References

Coombes, K. R., Brock, G., Abrams, Z. B., & Abruzzo, L. V. (2019). Polychrome: Creating and assessing qualitative palettes with many colors. *Journal of Statistical Software*, *90*, 1-26.

Epskamp, S., Cramer, A. O. J., Waldorp, L. J., Schmittmann, V. D., & Borsboom, D. (2012). qgraph: Network visualization of relationships in psychometric data. *Journal of Statistical Software*, 48, 1-18.

Farkas, I., Abel, D., Palla, G., & Vicsek, T. (2007). Weighted network modules. *New Journal of Physics*, 9, 180-180.

Fortunato, S. (2010). Community detection in graphs. Physics Reports, 486, 75-174.

Palla, G., Derenyi, I., Farkas, I., & Vicsek, T. (2005). Uncovering the overlapping community structure of complex networks in nature and society. *Nature*, *435*, 814-818.

Zeileis, A., Fisher, J. C., Hornik, K., Ihaka, R., McWhite, C. D., Murrell, P., Stauffer, R., & Wilke, C. O. (subm.). colorspace: A toolbox for manipulating and assessing colors and palettes. https://arxiv.org/abs/1903.06490