



Madeline Thomas
BIOS 611
Final Project

Quantifying and
Categorizing
Frutiger Aero
and Related
Aesthetics



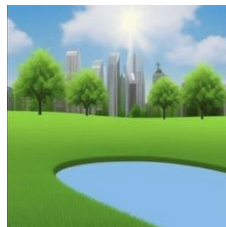
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Hello!



- My name is Madeline
- I'm a scientist 🧪
- I work in a computational chemistry lab
 - which I have come to realize is just data science + some clever computational techniques applied to chemistry
- I also love art + design!
- In the past year, I became interested in an aesthetic called *Frutiger Aero*





Project Motivation

- I am making a **website** (not live yet)
 - All **HTML** and **JS** based
 - **mobile** and **desktop** compatible
- A collection of **browser-based** **login-free**, **ad-free**, and **free-free** games designed to **calm** you down when you are overwhelmed (not be **addictive**)
- Made with art **drawn by ME!**
+ music by the amazing [Alzea](#)
- This website is also inspired by *Frutiger Aero*
 1. Because I like it
 2. Because many people report a nostalgic, calming effect when engaging with this style of media

Fruit Snack Sorter Game



Project Motivation



- Hence, I have been looking at lots of *Frutiger Aero* – related media for inspiration
- As I told people about my project, many of them asked me, what is *Frutiger Aero*?
 - Honestly, this was hard to answer without showing photos



Which got me thinking...

Is there a way I could understand this aesthetic more *scientifically*?



In other words, could I **quantify** and **categorize** *Frutiger Aero* and its related aesthetics?

- First, I needed to understand precisely what sort of **data** (media) I would need to **gather** and how I would **label** it

Background

Frutiger Eco

Frutiger Aero

DORFic

Technozen

Dark Aero

Frutiger Metro

+ more not listed

Background

Frutiger Aero
2017
by Sofi Xian

A retrospective, internet-created aesthetic label describing a specific movement from the mid-2000s to the early-2010s

Adrian *Frutiger*

: a Swiss designer who created the Frutiger typeface in 1976 (+other typefaces)



Windows *Aero*

: Microsoft's design language introduced with *Windows Vista* (2006) and *Windows 7* (2009)

A: Authentic

E: Energetic

R: Reflective

O: Open



Background

D O R Fic
Daylight Orange Red Graphic

DORFic

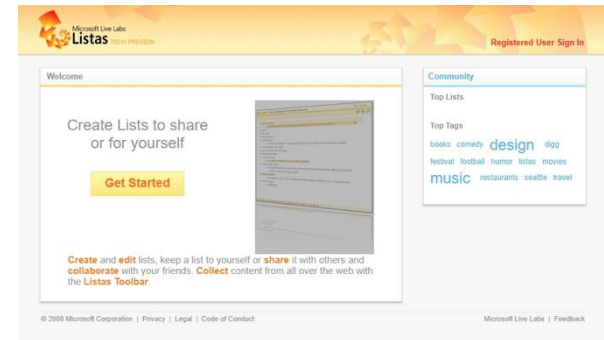
2023

On Aesthetics Wiki

FIBER NAT
Fiber Optic Technology



Nintendo
eShop



Background

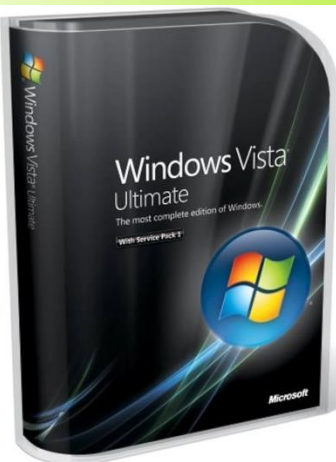
All the **futuristic** elements of Frutiger Aero *without* nature (more emphasis on **technology**)

Dark Aero
?



Gaming

Windows Longhorn (2001-2006)
1st "dark aero"
Beta version of Windows Vista



Programming



DJs

Background

Frutiger Metro

2023

On Aesthetics Wiki

vector graphics



clean geometric outlines



maximalist, non-photorealistic design



separate from the meaning of "Zen"
in Buddhism
→ more associated with the west's
interest in minimalist Asian aesthetics

Background



Influenced by mid-late 2000s Japanese tech

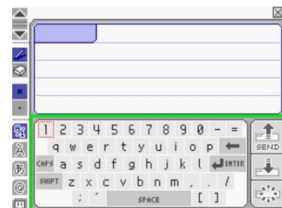
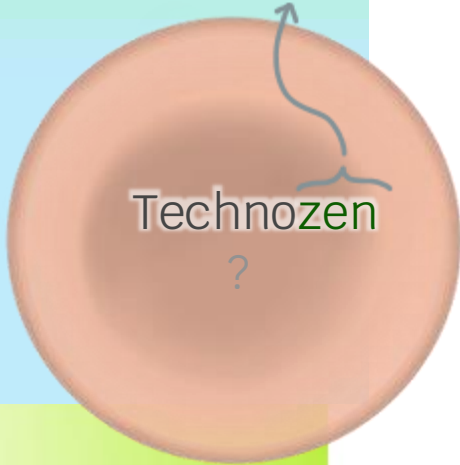
cozy, yet professional

harmony between
technology and **nature**

✧ technology should *improve* life, not *dominate* it

minimalistic

white light



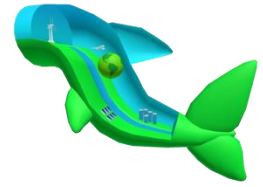
Background

Frutiger Eco
?

Eco

Stemming from **ecology**

- renewable energy
- futuristic, healthy coexistence with nature
- utopian future



Plan

- Goal: *quantify* and *categorize* Frutiger Aero and its related aesthetics
- *Build* (or *implement externally*) 2 tools:

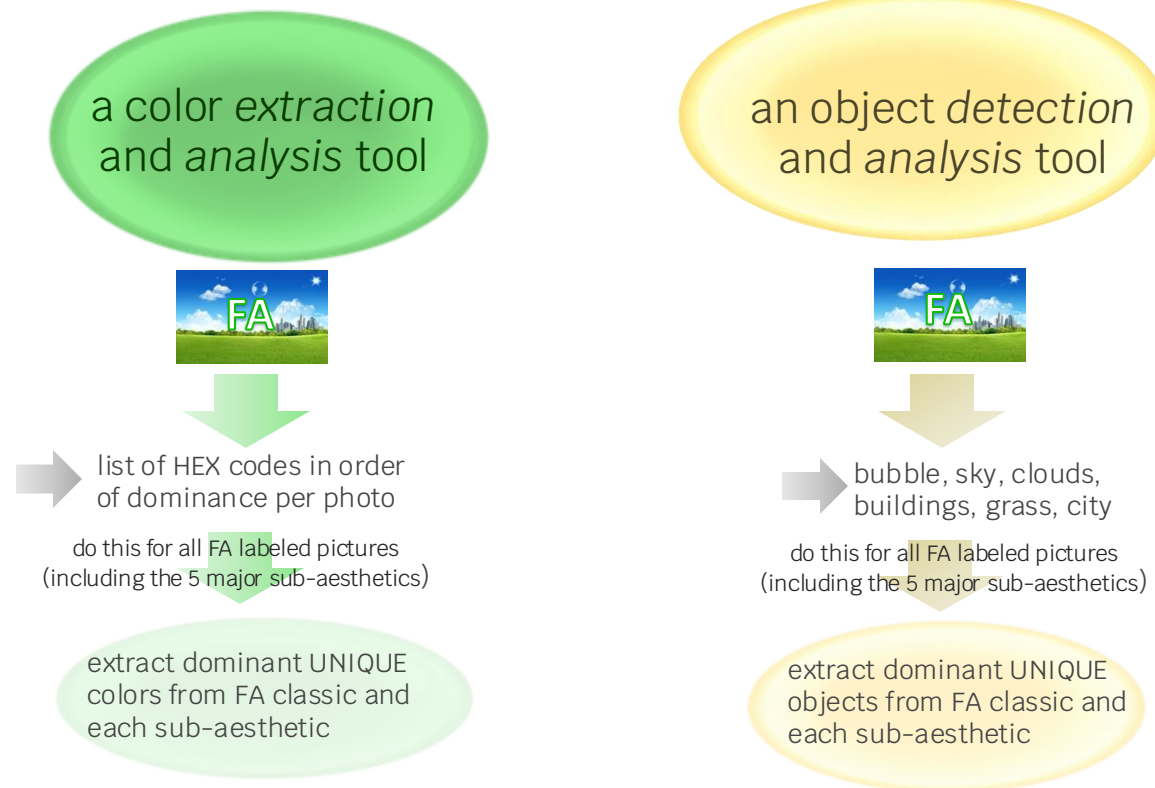


Image Collection

Image Sources: Images Collected:



+ hand-labeled images



skeuomorphic design

digital object try to closely emulate their real-world counterparts

flat design

uses 2D elements, bright colors, and simple shapes with a focus on functionality



Image Pre-Processing

- Done for all image folders (**FA_** and **N_**)

Pre-Processing:

- convert all images to PNGs
 - Language: **Python**
 - Library: **Pillow** (a **PIL**: Python Imaging Library fork)
 - Workflow:
 - load image
 - convert to **RGB** (standardize color)
 - save as **.png**
- compare all images to ensure no duplicates
 - Language: **Python**
 - Libraries: **imagehash**, **Pillow**
 - Workflow:
 - compute a **hash** (with **average_hash()**) per image
 - if a hash already exists in the image record -> delete the duplicate,
- rename images (by folder): **0.png**, **1.png**, ...
 - Language: **Bash**

What is a *hash*?

data input
(any size)



hash
function



hash value
("the **hash**")
(string, fixed length)

***one-way** (not reversible)
same input always
produces the same hash
(**deterministic**)

a color *extraction*
and *analysis* tool



list of HEX codes in order
of dominance per photo

do this for all FA labeled pictures
(including the 5 major sub-aesthetics)

extract dominant UNIQUE
colors from FA classic and
each sub-aesthetic

libraries

colorfindr
extracts colors from images

magrittr
the pipe operator (%>%)

grDevices
color conversion

Image Color Extraction

- Done only for folders under images starting with **FA** (classic + 5 sub-aesthetics)

Script:

extract_all_FA.R

- Libraries: colorfindr, dplyr, magrittr, grDevices
- Workflow
 - loop over all folders starting with **FA** and for each .png
 - load images and extract colors with get_colors()
 - expand pixels by frequency (weight by brightness)
 - apply k-means clustering (k=8) to group similar colors in RGB space
 - output the top 8 colors (hex) to #color.txt files (where for 1.png, #=1)

a color *extraction*
and *analysis* tool



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Image Color Extraction

Example



32.png

extract_all_FA.R

#99D855	#BCE69B	#5CAA2B
#D9F2EA	#B2E5EB	#86CBDE
#62AAC7	#387A9B	

(done for 350 images)

a color *extraction*
and *analysis* tool



list of HEX codes in order
of dominance per photo

do this for all FA labeled pictures
(including the 5 major sub-aesthetics)

extract dominant UNIQUE
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library

readr

efficiently read and write
text files in R

Image Color Analysis

- Done only for folders under images starting with **FA** (classic + 5 sub-aesthetics)

Script:

`extract_FA_colors.R`

- Libraries: dplyr, magrittr, grDevices, `readr`
- Workflow:
 - read all the `*color.txt` files under `FA_*` folders
 - convert hex to normalized RGB values
 - weight the colors by frequency across the images for a given folder
 - perform k-means clustering ($k = 30$) in RGB space
 - save cluster centroids (30 colors as hex codes) as the dominant aesthetic colors to `colors.txt`

an object *detection*
and *analysis* tool



→ bubble, sky, clouds,
buildings, grass, city

do this for all FA labeled pictures
(including the 5 major sub-aesthetics)

extract dominant UNIQUE
objects from FA classic and
each sub-aesthetic

Image Object Detection

- Done only for folders under images starting with **FA** (classic + 5 sub-aesthetics)

Script:

FA_google_vision.py

- Libraries: **pathlib**, **requests**, **base64**, **os**
- Workflow
 - loop over all folders starting with **FA** and for each .png
 - read the image file and encode it in **Base64**
 - send to the **Google Cloud Vision API** for **LABEL_DETECTION** (with a max of 10 labels)
 - receive a **JSON** response with the detected object labels with confidence scores
 - write the results to **#object.txt** files (where for 1.png, #=1)

an object *detection* and *analysis* tool



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Image Object Detection

Google Cloud Vision API

- cloud-based ML service that analyzes image content

Base64

- a method to convert binary image data to plain text
- allows image to safely be included in your web request (JSON body)

JSON

- (JavaScript Object Notation)
- a text format for structured data exchange
- use for API requests and response

LABEL_DETECTION

- a feature of the Google Vision API that returns descriptive tags for images, each with a confidence score (0-1) showing how certain the model is

an object *detection* and *analysis* tool



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Image Object Detection

How does the Google Cloud Vision API's
LABEL_DETECTION work?

1. Image Request

- image is sent to Vision API endpoint as a Base64-encoded string (put in JSON body)

2. Cloud Processing

- Google uses its pre-trained **deep learning (DL)** models to analyze the image with **convolutional neural networks (CNNs)**
- these DL models compare the visual features (colors, shapes, textures, etc.) to millions of examples
- finally, it predicts which entities are present in the image

3. JSON Response

- API returns a JSON object with a list of labelAnnotations, each with
 - **description** (human-readable name [sky])
 - **score** (confidence 0-1)
 - **topicality** (how central is the label to context of the image)
 - **mid** (optional Knowledge Graph ID for concept)

Image Object Detection

artificial neural networks: many connected “neurons”, each intermediate connection with a weight

Deep Learning (DL)

a subtype of ML; uses *artificial neural networks* with many layers to learn complex patterns from large amounts of data

Convolutional Neural Networks (CNNs)

a subtype of DL; designed to analyze visual data

1. Convolutional Layer + ReLU

: 1st, (+ intermediate), input, filter, feature map

* *convolution*: moving across image and checking for patterns by region (receptive field); output = feature map (convolved feature)

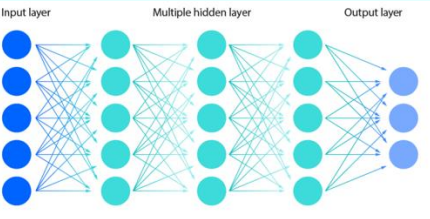
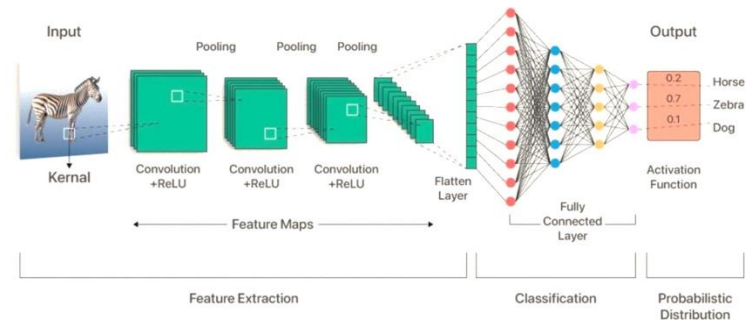
*** has many of these layers w/ increasing *receptive fields* (filter size + information from previous layers)

2. Pooling Layer

: intermediate, conduct dim red on input parameters

3. Fully-connected Layer

: final; performs classification w/ the features extracted + filters



filter (kernel)

small matrix of numbers (ex. 3x3) used by convolutions to detect patterns in images

ReLU (Rectified Linear Unit)

an *activation function* (a mathematical rule that determines how strongly a neuron should be activated) applied after each convolution (adds nonlinearity)

$$f(x) = \max(0, x)$$

an object *detection* and *analysis* tool



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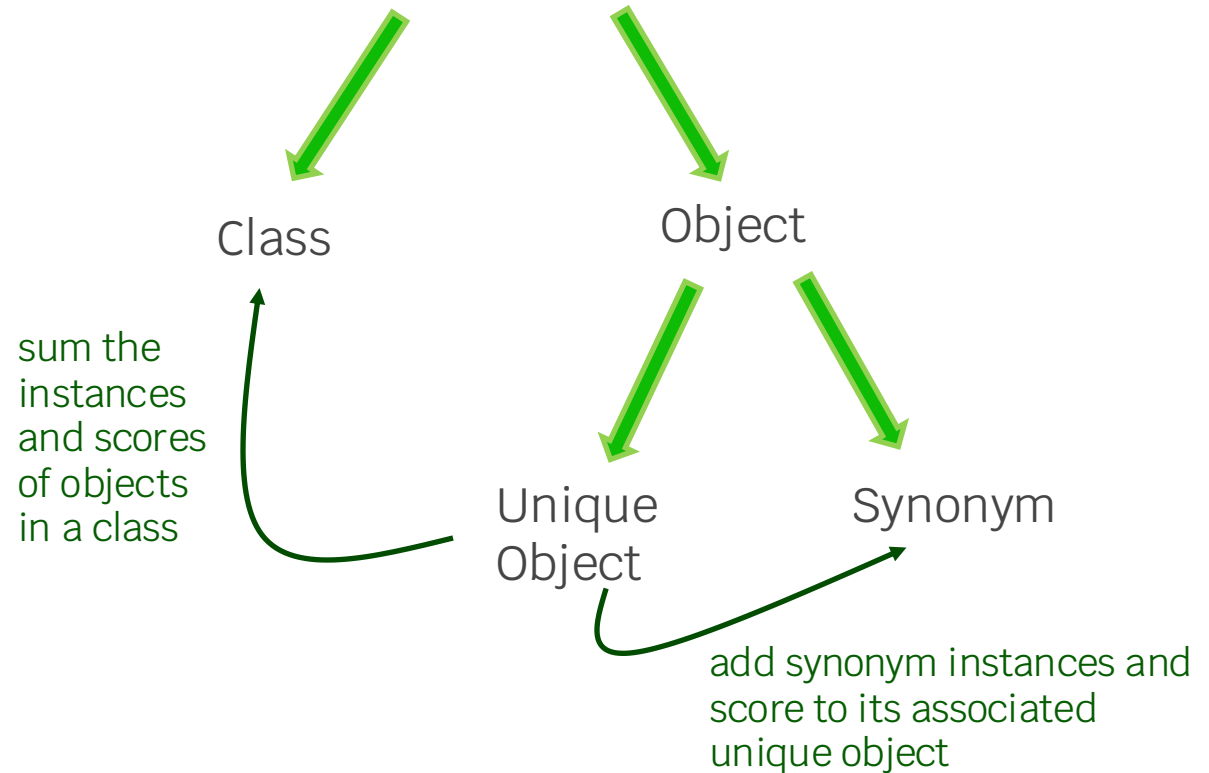
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Image Object Analysis

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Characterizing Object Data By-Hand

Object Labels Generated with Google Vision



an object *detection*
and *analysis* tool



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Image Object Analysis

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Embedding Vectors for Object Labels

Object Labels Generated with Google Vision

Send each label to Vertex AI

- Model: text-embedding-005
- API request contains only the text label
- Returns 768-dimensional vector + Save results

Plot

Load all vectors from each aesthetic

Run **3D t-SNE** to map 768 → 3 dimensions

- Plot with **Plotly**
- Hover label = object name
- Point size \propto instance count
- One interactive 3D scatter per aesthetic

Concluding Thoughts



- I made something cool!
 - *cool* for designers and artists
 - and *cool* for programmers and data scientists!
- It is also useful for me!
 - I will use it as a game design inspiration board

Some of the *Cool* Data Science in my Project

- Data Cleaning
- Feature Engineering
- PCA
- t-SNE
- Interactive Visualizations
- Convolutional Neural Networks
- Embedding Vectors

