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2021 ANAHEIM, CALIFORNIA



Grid-aware Aggregation and Realtime Disaggregation of Distributed Energy Resources in Radial Networks

Panel Session: Optimization for distribution grid operations

Nawaf Nazir (Pacific Northwest National Lab)

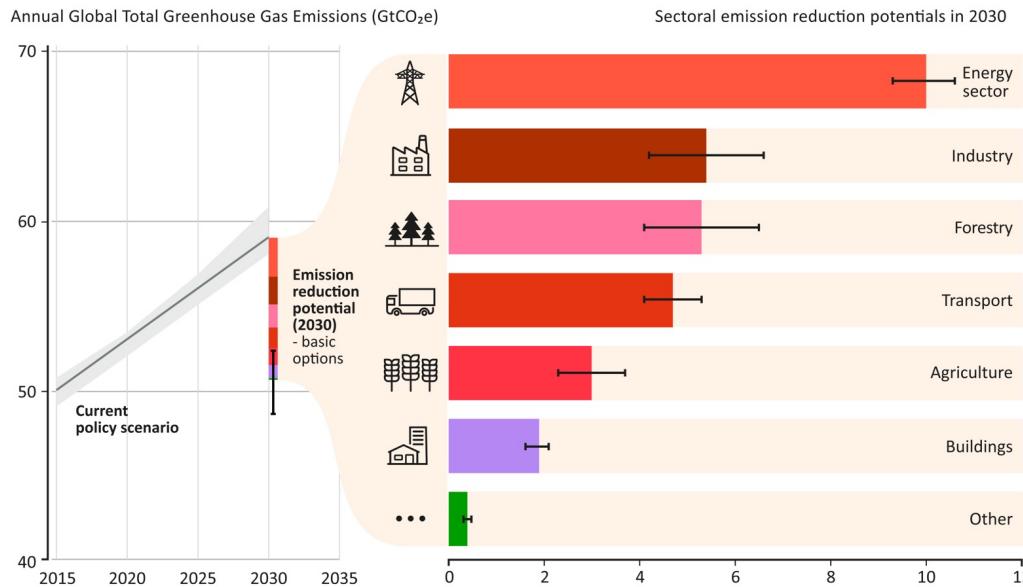
Mads Almassalkhi (University of Vermont/Pacific Northwest National Lab)

October 26, 2021

11:00 AM - 12:30 PM

Beneficial electrification and flexible demand

Electrifying energy, transportation, and building sectors are key to GHG reductions



Combine renewables and efficiency with **electrification of end use**. [1]

Flexible demand enables significantly more renewable generation and reduces duck-curve ramping effects [2]

59GW of DR today will become **200GW of flexible demand by 2030** [3]

Need to manage millions of behind-the-meter loads

[1] UN Environmental Program, Emission Gap Report 2019 (source for figure, too)

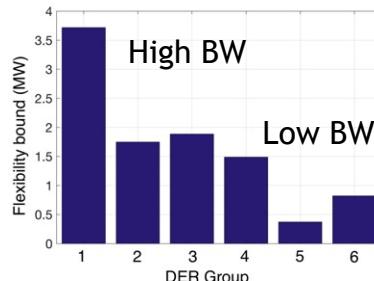
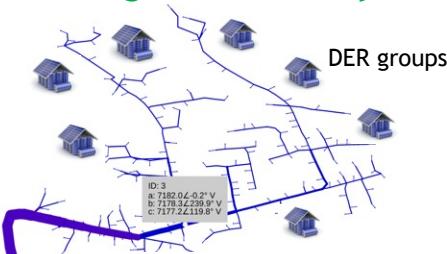
[2] Goldenberg, et al, "Demand Flexibility: The Key To Enabling A Low-cost, Low-carbon Grid," Tech. Rep., Rocky Mountain Institute, 2018.

[3] Hledik et al, "The National Potential for Load Flexibility: Value And Market Potential Through 2030," Tech. Rep., The Brattle Group, 2019.

What is the role of the distribution grid/network?

Utility (grid information/data)

- Needs to ensure grid reliability
- Wants to protect grid data
- **Lack direct access to devices**
- **Knows grid availability**

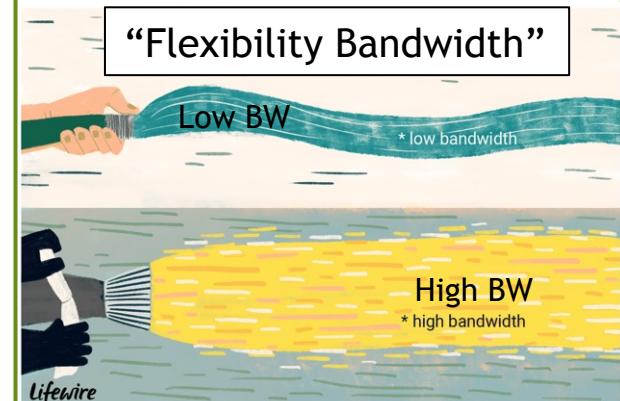


Fundamental
asymmetries in
information & control

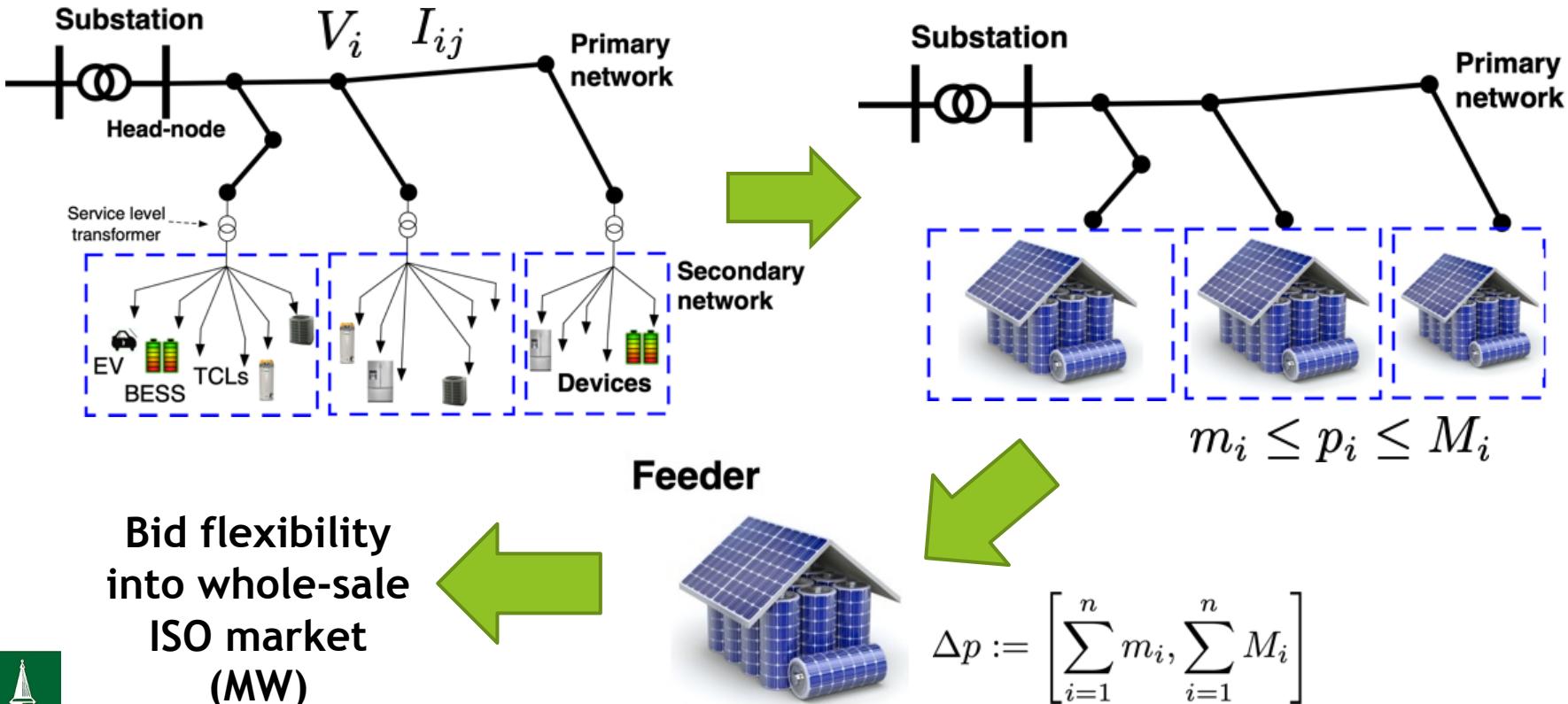


Aggregators (device control)

- Needs to ensure device QoS
- Wants to provide market services
- **Lack direct access to grid data**
- **Knows device availability**



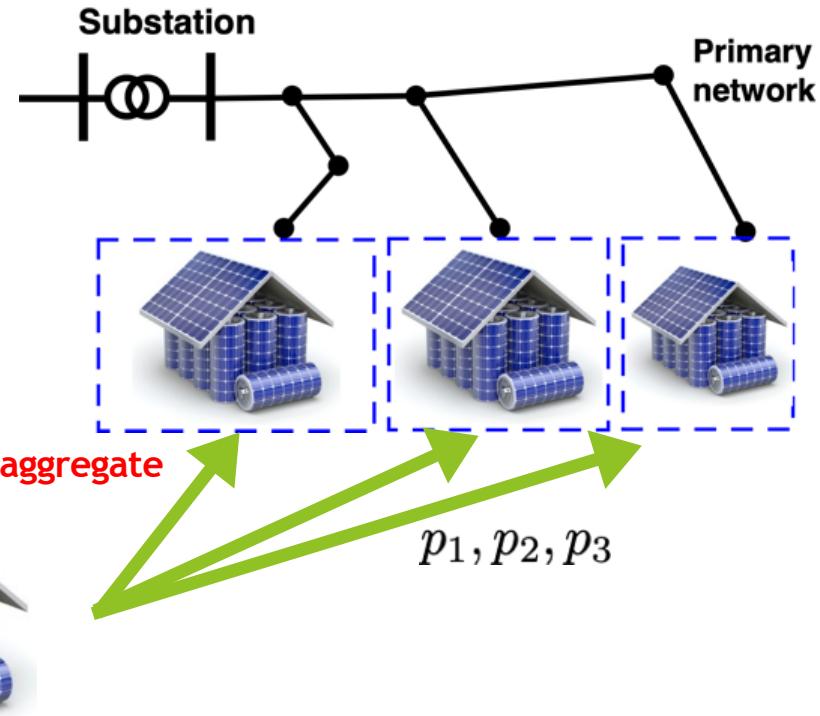
Motivating example: aggregation



Motivating example: disaggregation

Can we solve disaggregation in real-time?

- Solve grid optimization problem repeatedly
 - + Guarantees grid reliability!
 - Can DisAgg problem be solved fast [W, X, Y, Z]?
 - Can we provide admissibility guarantees?



Requested
flexibility from
ISO (MW)



[W] Almassalkhi, et al., "Hierarchical, Grid-Aware, and Economically Optimal Coordination of Distributed Energy Resources in Realistic Distribution Systems," Energies, 2020.

[X] Nawaf Nazir, Pavan Racherla, and Mads Almassalkhi, "Optimal multi-period dispatch of distributed energy resources in unbalanced distribution feeders", IEEE Trans. on Power Systems, 2020

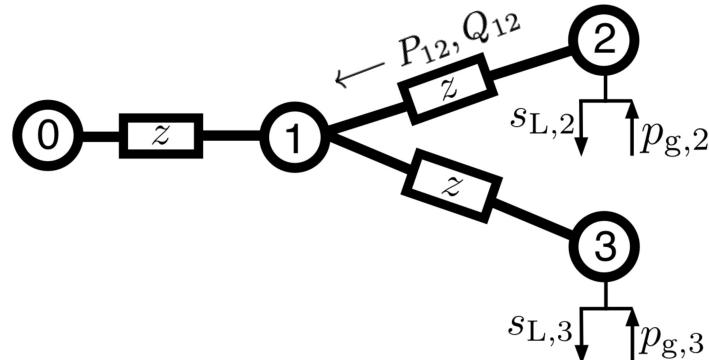
[Y] Nawaf Nazir and M. Almassalkhi, "Voltage positioning using co-optimization of controllable grid assets," IEEE Trans. on Power Systems, 2020.

[Z] S. Brahma, Nawaf Nazir, et al., "Optimal and resilient coordination of virtual batteries in distribution feeders," IEEE Trans. on Power Systems, 2020

Finding set of admissible (active) injections

Simple 3-node balanced distribution feeder with 2 controllable nodes modeled with *DistFlow*:

$$v_i := |V_i|^2 \text{ and } l_{ij} := |I_{ij}|^2$$



$$v_j = v_i + 2r_{ij}P_{ij} + 2x_{ij}Q_{ij} - |z_{ij}|^2l_{ij}$$

$$P_{ij} = p_j + \sum_{h:h \rightarrow j} (P_{jh} - r_{jh}l_{jh})$$

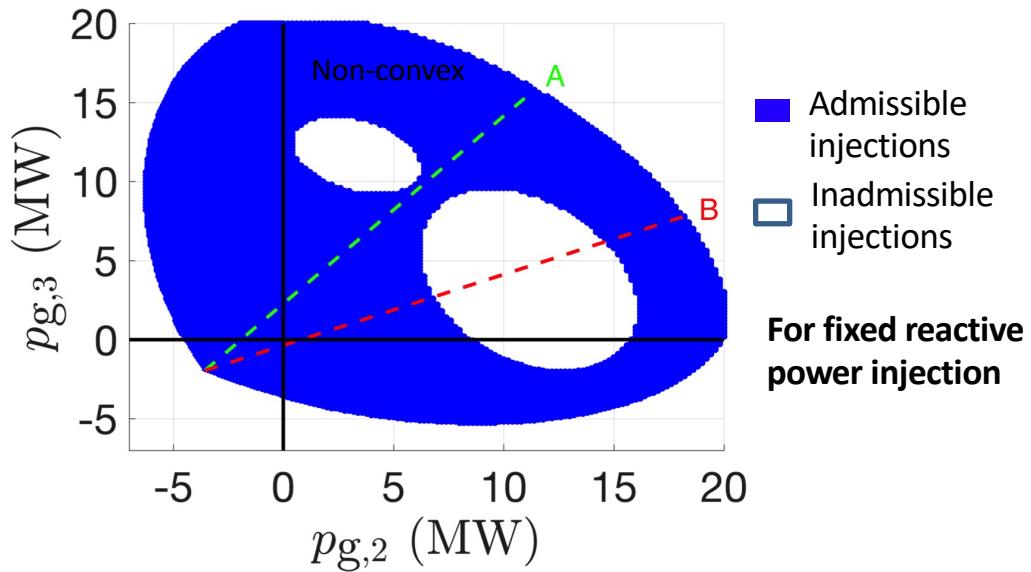
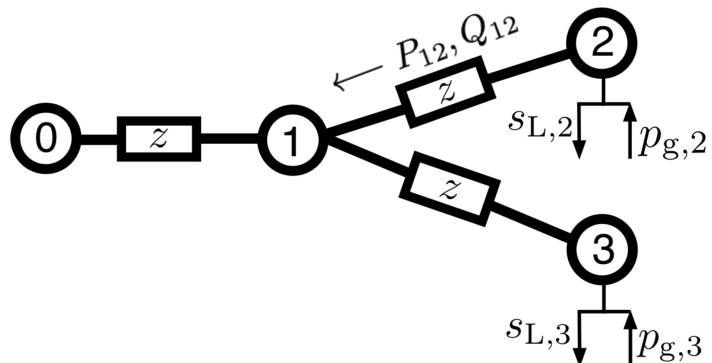
$$Q_{ij} = q_j + \sum_{h:h \rightarrow j} (Q_{jh} - x_{jh}l_{jh})$$

$$l_{ij}(P_{ij}, Q_{ij}, v_j) = \frac{P_{ij}^2 + Q_{ij}^2}{v_j}, \quad \text{The only nonlinear relation}$$

Network limits: $v_i \in [\underline{v}_i, \bar{v}_i]$, $l_{ij} \in [\underline{l}_{ij}, l_{ij}]$

Finding set of admissible (active) injections

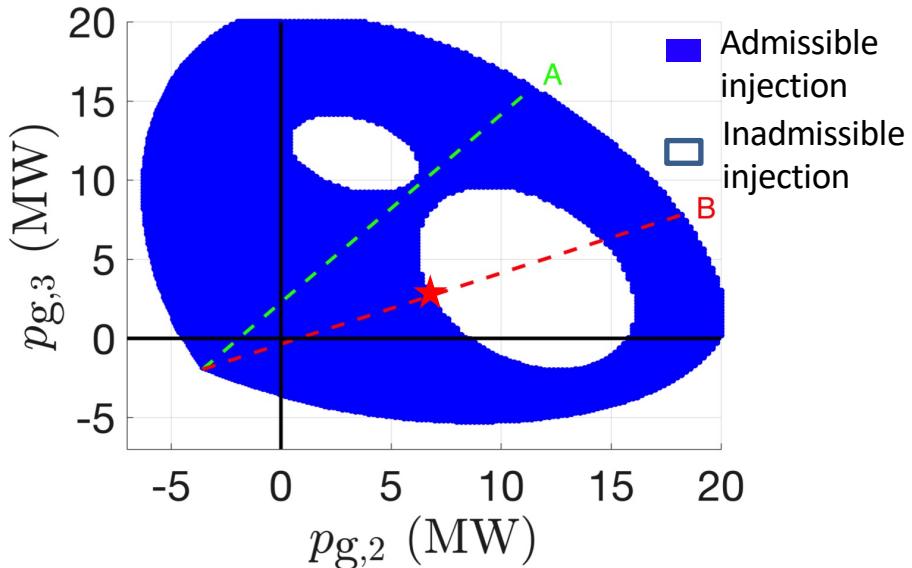
Simple 3-node balanced distribution feeder with 2 controllable nodes



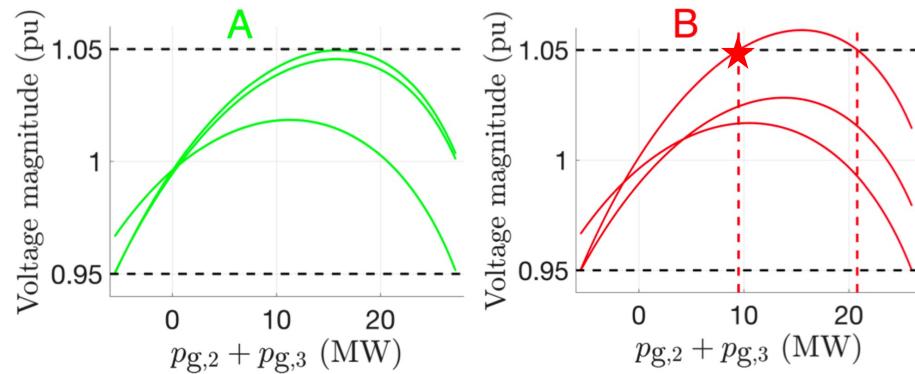
Network limits: $v_i \in [\underline{v}_i, \bar{v}_i]$, $l_{ij} \in [\underline{l}_{ij}, \bar{l}_{ij}]$

Finding set of admissible (active) injections

Simple 3-node balanced distribution feeder example:



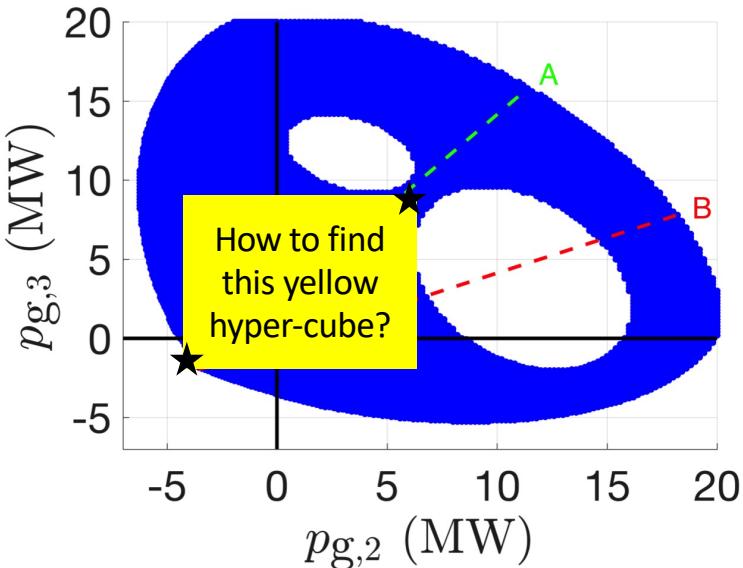
Network limits: $v_i \in [\underline{v}_i, \bar{v}_i], l_{ij} \in [\underline{l}_{ij}, \bar{l}_{ij}]$



The two controllable active power resources are limited in aggregate by the network – i.e., their individual limits are coupled

Finding set of admissible (active) injections

Goal: find largest hyperrectangle to determine p_g limits (decoupled)



- Admissible injection
- Inadmissible injection

$$v_j = v_i + 2r_{ij}P_{ij} + 2x_{ij}Q_{ij} - |z_{ij}|^2 l_{ij}$$

$$P_{ij} = p_j + \sum_{h:h \rightarrow j} (P_{jh} - r_{jh}l_{jh})$$

$$Q_{ij} = q_j + \sum_{h:h \rightarrow j} (Q_{jh} - x_{jh}l_{jh})$$

$$l_{ij}(P_{ij}, Q_{ij}, v_j) = \frac{P_{ij}^2 + Q_{ij}^2}{v_j},$$

Idea: replace non-convex constraint with a convex inner approximation

Convex inner approximation via proxy variables

If we can find envelope $l_{lb,ij} \leq l_{ij}(P_{ij}, Q_{ij}, v_j) = \frac{P_{ij}^2 + Q_{ij}^2}{v_j}, \leq l_{ub,ij}$

Then, we can create proxy variables that upper (+) and lower (-) bound the actual (P, Q, V)

$$P^+ := Cp - D_R l_{lb}$$

$$P^- := Cp - D_R l_{ub}$$

$$Q^+ := Cq - D_{X_+} l_{lb} - D_{X_-} l_{ub}$$

$$Q^- := Cq - D_{X_+} l_{ub} - D_{X_-} l_{lb}$$

$$V^+ := v_0 \mathbf{1}_n + M_p p + M_q q - H_+ l_{lb} - H_- l_{ub}$$

$$V^- := v_0 \mathbf{1}_n + M_p p + M_q q - H_+ l_{ub} - H_- l_{lb}$$

Given a nominal operating point, $x_{ij}^0 := (P_{ij}^0, Q_{ij}^0, v_j^0)$

$$l_{ij} \approx l_{ij}^0 + \mathbf{J}_{ij}^\top \delta_{ij} + \frac{1}{2} \delta_{ij}^\top \mathbf{H}_{e,ij} \delta_{ij}$$

$$\delta_{ij} := \begin{bmatrix} P_{ij} - P_{ij}^0 \\ Q_{ij} - Q_{ij}^0 \\ v_j - v_j^0 \end{bmatrix}, \quad \mathbf{J}_{ij} := \left[\begin{bmatrix} \frac{\partial l_{ij}}{\partial P_{ij}} \\ \frac{\partial l_{ij}}{\partial Q_{ij}} \\ \frac{\partial l_{ij}}{\partial v_j} \end{bmatrix} \right]_{x_{ij}^0} = \begin{bmatrix} \frac{2P_{ij}^0}{v_j^0} \\ \frac{2Q_{ij}^0}{v_j^0} \\ -\frac{(P_{ij}^0)^2 + (Q_{ij}^0)^2}{(v_j^0)^2} \end{bmatrix}$$

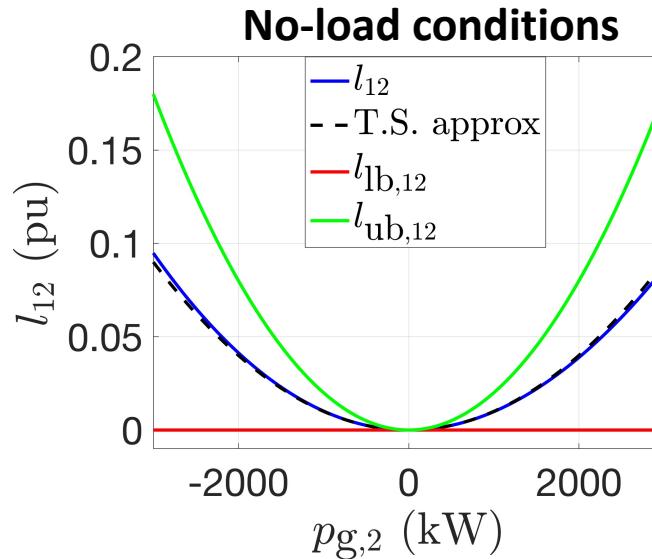
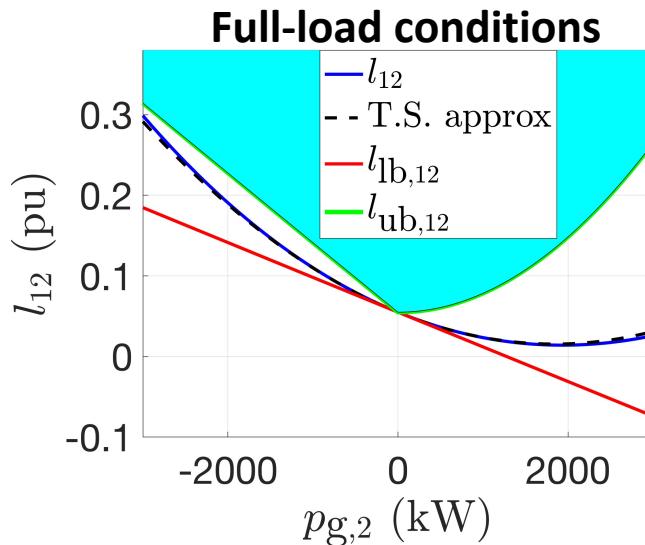
$$\mathbf{H}_{e,ij} := \begin{bmatrix} \frac{2}{v_j^0} & 0 & \frac{-2P_{ij}^0}{(v_j^0)^2} \\ 0 & \frac{2}{v_j^0} & \frac{-2Q_{ij}^0}{(v_j^0)^2} \\ \frac{-2P_{ij}^0}{(v_j^0)^2} & \frac{-2Q_{ij}^0}{(v_j^0)^2} & 2 \frac{(P_{ij}^0)^2 + (Q_{ij}^0)^2}{(v_j^0)^3} \end{bmatrix} \succeq 0^*$$

and from this model, we can explicitly define upper and lower bounds on l_{ij} that yield a convex inner approximation.

Convex inner approximation via proxy variables

$$l_{lb,ij} := f_{lb,ij}(P_{ij}^-, Q_{ij}^-, v_j^-, P_{ij}^+, Q_{ij}^+, v_j^+, x_{ij}^0) \leq l_{ij} \leq f_{ub,ij}(P_{ij}^-, Q_{ij}^-, v_j^-, P_{ij}^+, Q_{ij}^+, v_j^+, x_{ij}^0) \leq l_{ub,ij}$$

Has been shown to be affine Has been shown to be convex (SOC)



For mathematical details, please see:

Nawaf Nazir and Mads Almassalkhi. "Grid-aware aggregation and realtime disaggregation of distributed energy resources in radial networks." (Rev02)

Convex inner approximation via proxy variables

$$P^+ := C_p - D_R l_{lb}$$

$$P^- := C_p - D_R l_{ub}$$

$$Q^+ := C_q - D_{X_+} l_{lb} - D_{X_-} l_{ub}$$

$$Q^- := C_q - D_{X_+} l_{ub} - D_{X_-} l_{lb}$$

$$V^+ := v_0 \mathbf{1}_n + M_p p + M_q q - H_+ l_{lb} - H_- l_{ub}$$

$$V^- := v_0 \mathbf{1}_n + M_p p + M_q q - H_+ l_{ub} - H_- l_{lb}$$

$$0 \leq l_{lb,ij} := f_{lb,ij}(P_{ij}^-, Q_{ij}^-, v_j^-, P_{ij}^+, Q_{ij}^+, v_j^+, x_{ij}^0)$$

Current limits $f_{ub,ij}(P_{ij}^-, Q_{ij}^-, v_j^-, P_{ij}^+, Q_{ij}^+, v_j^+, x_{ij}^0) \leq l_{ub,ij} \leq \bar{l}_{ij}$

Voltage limits $\underline{V} \leq V^- \leq \bar{V}$

Active power limits $\underline{p}_i \leq p_i \leq \bar{p}_i$

$\mathcal{X}(x^0)$

Feasible set
represents a convex
inner approximation

Determining active injection limits (corners)

p_i^+ maximum active power injection at *each* node:

$$p^+(x^0) = \arg \max_p \sum_{i=1}^N f_i(p_i)$$

s.t. $p \in \mathcal{X}(x^0)$

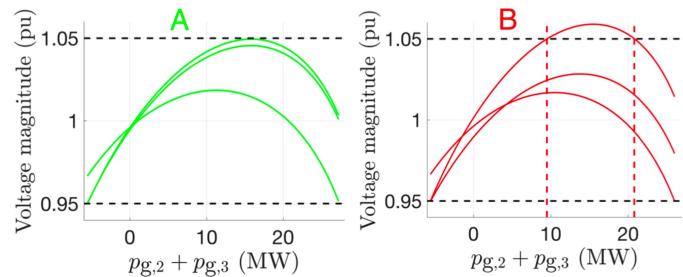
p_i^- minimum active power injection at *each* node:

$$p^-(x^0) = \arg \min_p \sum_{i=1}^N f_i(p_i)$$

s.t. $p \in \mathcal{X}(x^0)$

Theorem: If $p_i \in [p_i^-, p_i^+] \forall i \Rightarrow \underline{V} \leq V^-(p) \leq V(p) \leq V^+(p) \leq \bar{V}$

Proof is conditioned upon: $dV^+/dp, dV/dp \geq 0$



Monotonicity conditions:

More load \rightarrow higher voltage

Less load \rightarrow lower voltage

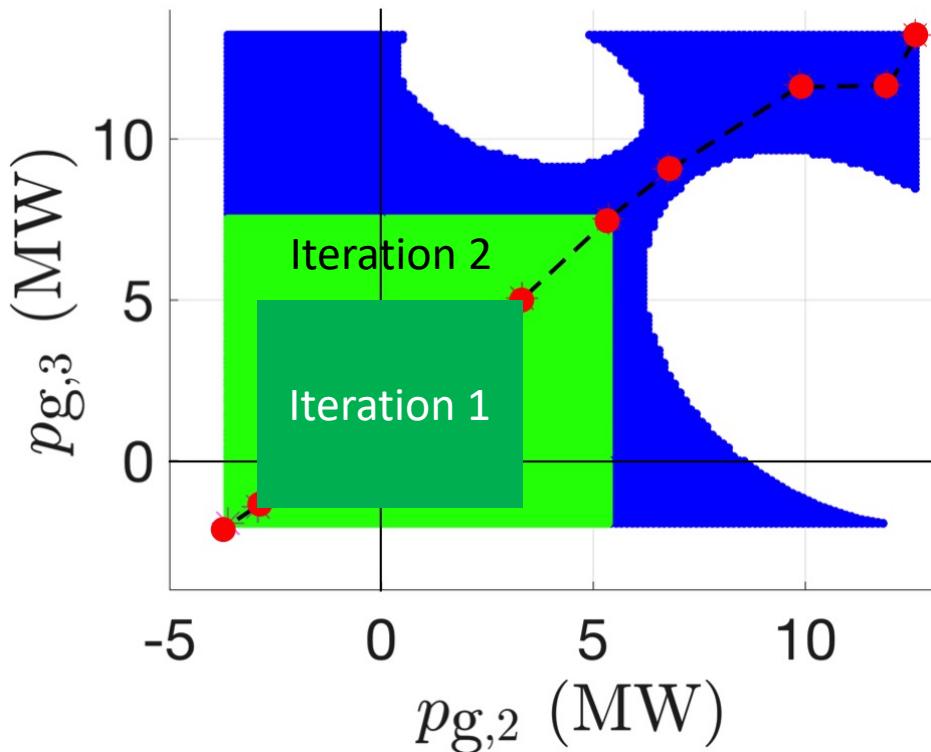
Bonus: *objective is feeder's hosting capacity!*

For mathematical proofs, please see:

Nawaf Nazir and Mads Almassalkhi. "Grid-aware aggregation and realtime disaggregation of distributed energy resources in radial networks." (Rev02)

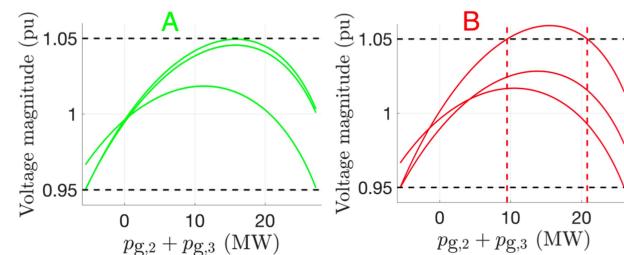
Algorithm for growing region

Requires coordination



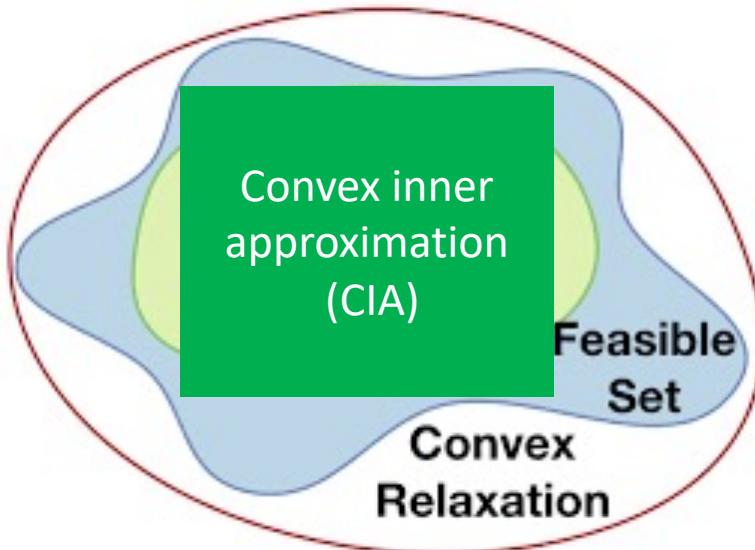
Blue injection pairs are admissible
White violates voltage constraints
Green satisfies monotonicity conditions
Red dots are feasible iterates

Example: after 2nd iteration, monotonicity conditions fail to hold and CIA is found.



Note: for iterations ≥ 3 , coordination is required (along piecewise affine path)

What about conservativeness?



Original Image source: D. Lee, H. D. Nguyen, K. Dvijotham and K. Turitsyn,
"Convex Restriction of Power Flow Feasibility Sets," in *IEEE Transactions on Control of Network Systems*, vol. 6, no. 3, pp. 1235-1245, Sept. 2019.

Comparing hosting capacity results*

System	CIA (MW)	NLP (MW)	CR (MW)
13-node	[-1.5, 9.1]	[-1.5, 9.7]	[-1.5, 12]
37-node	[-2.7, 5.3]	[-2.7, 5.3]	[-2.7, 16]
123-node	[-4.5, 13.9]	[-4.5, 14]	[-4.5, 24]

Convex relaxation (CR) over-estimates maximum reactive power capability

Nonlinear (NLP) has no optimality guarantees AND does not guarantee that entire range is admissible (i.e., no holes)

Proposed (CIA) method is not overly conservative and entire range is admissible

*Nawaf Nazir and Mads Almassalkhi. "Grid-aware aggregation and realtime disaggregation of distributed energy resources in radial networks." (Rev02)

What about existence of solution?

Leverage sufficient conditions from [*] in two ways:

- ▶ At each iteration, verify existence of (new) operating point x_0 with explicit test condition
- ▶ Augment CIA formulation with N linear inequalities and N SOC constraints (still convex)

$$\boxed{\begin{aligned} \sum_{j=1}^N t_{ij} &< \chi \quad \forall i = 1, \dots, N \\ \left\| \begin{bmatrix} a_{ij}^w & b_{ij}^w \\ b_{ij}^w & -a_{ij}^w \end{bmatrix} \begin{bmatrix} p_{g,j} \\ q_{g,j} \end{bmatrix} \right\|_2 &\leq t_{ij} \quad \forall j = 1, \dots, N. \end{aligned} \tag{C3}}$$

Added conservativeness from existence guarantees: *small impact*

Type	13-node	37-node	123-node
Without C3 (MW)	[-1.5, 9.1]	[-2.7, 5.3]	[-4.5, 13.9]
With C3 (MW)	[-1.5, 8.8]	[-2.7, 5.3]	[-4.5, 13.8]

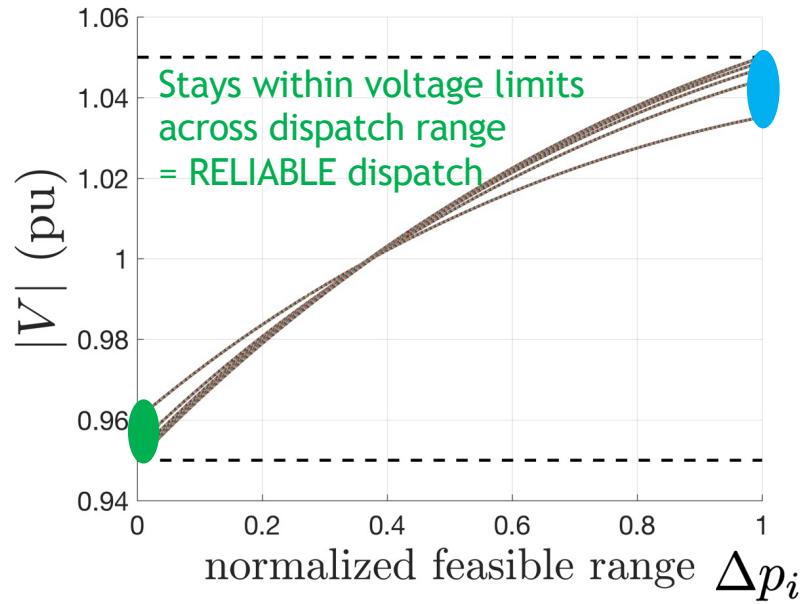
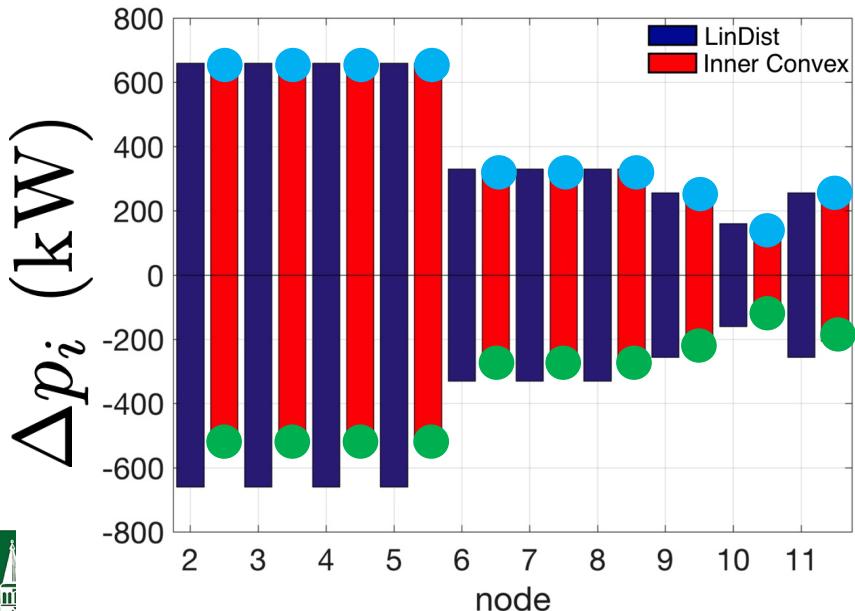
[*] C. Wang, A. Bernstein, J. LeBoudec, and M. Paolone, "Explicit conditions on existence and uniqueness of load-flow solutions in distribution networks," *IEEE Transactions on Smart Grid*, vol. 9, no. 2, pp. 953-962, 2018.



When found, inner approximations offer guarantees

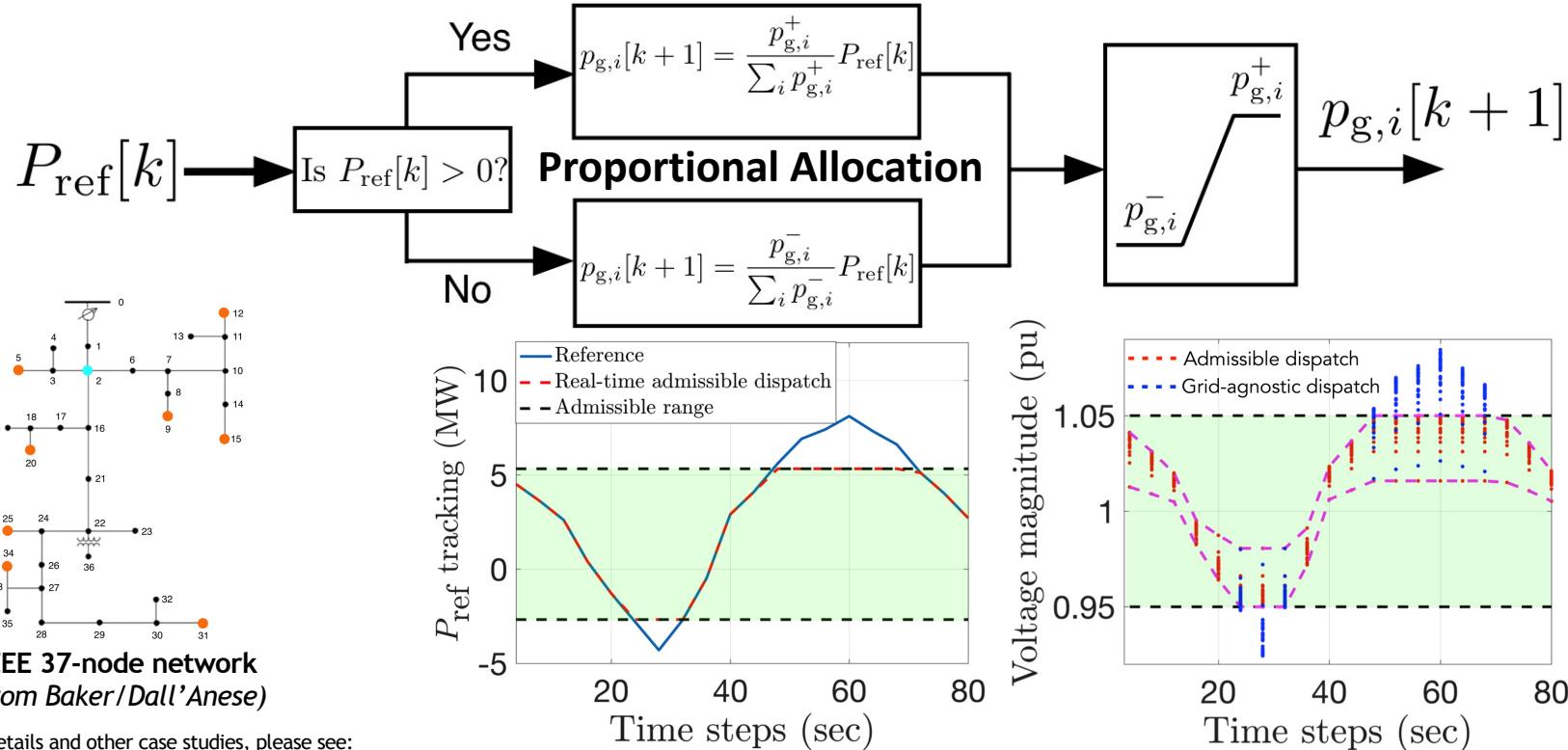
- Consider flexible resources on 10 nodes in a small network: a *10-dimensional hypercube*

$$\Delta p_i := [p_i^-, p_i^+]$$



Can now do disaggregation in realtime

Nodal hosting capacities $[p_i^-, p_i^+]$ enable an open-loop, distributed, and grid-aware DER control policy



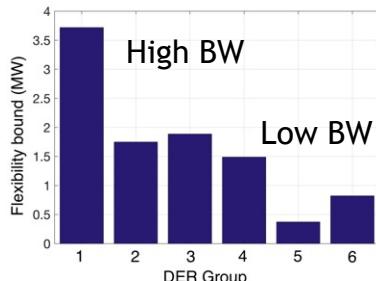
For details and other case studies, please see:

N. Nazir and M. Almassalkhi, "Convex inner approximation of the feeder hosting capacity limits on dispatchable demand," IEEE Conference on Decision and Control (CDC), 2019.
-, "Grid-aware aggregation and realtime disaggregation of distributed energy resources in radial networks", under review in IEEE Transactions on Power Systems (Rev02), 2021

Putting it all together

Utility (grid information/data)

- Needs to ensure grid reliability
- Wants to protect grid data
- **Lack direct access to devices**
- **Knows grid availability**

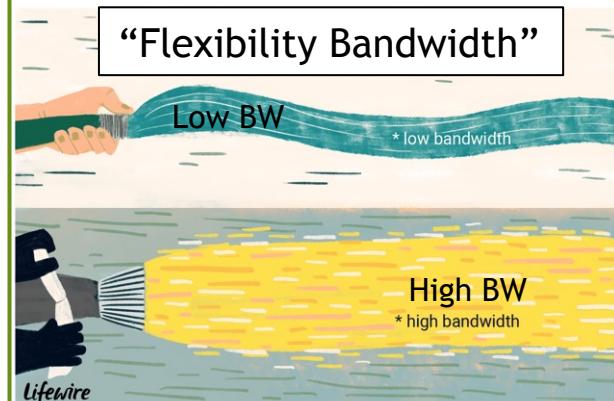


Fundamental
asymmetries in
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Aggregators (device control)

- Needs to ensure device QoS
- Wants to provide market services
- **Lack direct access to grid data**
- **Knows device availability**



Future direction

- Consider wind farm collector networks and reactive power capability of network
- Extend to market context with multiple aggregators within DSO network
- Study extension to unbalanced and meshed networks
- Consider role of feedback and available measurements/data for aggregators

Thank you! Questions/comments?



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<https://madsalma.github.io>



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