

Probability

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Chapter 1

Module 8: Introduction

1.1 Introduction To Probability

Definition 1.1.1: Probability

A mathematical description of randomness and uncertainty / The likelihood of an event occurring.
The notation for Probability is $\mathbf{P}(X)$ where X is the event.
Probability is always between $0 \leq \mathbf{P}(X) \leq 1$ or $0\% \leq \mathbf{P}(X) \leq 100\%$.

There are two ways of determining probability:

- Theoretical / Classical - Determined by the nature of the experiment
- Empirical / Observational - Determined by the results of the experiment

1.2 Relative Frequency

Definition 1.2.1: Relative Frequency

Relative frequency is the number of times an event occurs divided by the total number of trials.

$$\mathbf{P}(X) = \frac{\text{Number of times event occurs}}{\text{Total number of trials}}$$

Theorem 1.2.1 The Law of Large Numbers

As the number of trials increases, the relative frequency of an event approaches the theoretical probability of the event.

Chapter 2

Module 9: Find the Probability of Events

2.1 Sample Spaces and Events

Definition 2.1.1: Random Experiment

An experiment whose outcome is determined by chance.

Definition 2.1.2: Sample Space

The list of possible outcomes of a random experiment, denoted by S .

Definition 2.1.3: Event

A statement about the nature of the outcome after the experiment has been conducted, denoted by any capital letter except S .

2.2 Equally Likely Outcomes

$$\mathbb{P}(A) = \frac{\text{Number of outcomes in } A}{\text{Number of outcomes in } S}$$

Where A is an event and S is the sample space.

2.3 Probability Rules

2.3.1 Rule 1: Probability is a Number Between 0 and 1

For any event A , $0 \leq \mathbb{P}(A) \leq 1$.

2.3.2 Rule 2: Addition Rule

$\mathbb{P}(S) = 1$, that is the sum of the probabilities of all possible outcomes is 1.

2.3.3 Rule 3: Complement Rule

$\mathbb{P}(A') = 1 - \mathbb{P}(A)$, that is the probability of the complement of an event is 1 minus the probability the event occurs.

2.3.4 Rule 4: Addition Rule for Mutually Exclusive Events

Definition 2.3.1: Mutually Exclusive / Disjoint events

Events that cannot happen at the same time.

$$\mathbb{P}(A \text{ or } B) = \mathbb{P}(\text{event } A \text{ occurs or event } B \text{ occurs or both occur})$$

If A and B are mutually exclusive, then $\mathbb{P}(A \text{ or } B) = \mathbb{P}(A) + \mathbb{P}(B)$

2.3.5 Rule 5: Multiplication Rule for Independent Events

$$\mathbb{P}(A \text{ and } B) = \mathbb{P}(\text{event } A \text{ occurs and event } B \text{ occurs})$$

Definition 2.3.2: Independent Events

Two events A and B are said to be independent if the occurrence of one event does not affect the probability of the other event occurring.

Definition 2.3.3: Dependent Events

Two events A and B are said to be dependent if the occurrence of one event affects the probability of the other event occurring.

If A and B are two independent events, then $\mathbb{P}(A \text{ and } B) = \mathbb{P}(A) \times \mathbb{P}(B)$

2.3.6 Rule 6: General Addition Rule

For any two events A and B , $\mathbb{P}(A \text{ or } B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \text{ and } B)$

Chapter 3

Module 10: Conditional Probability and Independence

Definition 3.0.1: Conditional Probability

The probability an event occurs as a result of another event. I.e. Probability of event B , given event A is,

$$\mathbb{P}(B | A) = \frac{\mathbb{P}(A \text{ and } B)}{\mathbb{P}(A)}$$

3.1 Independence

When two events are independent, the probability of one event occurring does not affect the probability of the other event, i.e.

$$\mathbb{P}(B | A) = \mathbb{P}(B)$$

$$\mathbb{P}(A | B) = \mathbb{P}(A)$$

$$\mathbb{P}(B | A) = \mathbb{P}(B | A')$$

$$\mathbb{P}(A \text{ and } B) = \mathbb{P}(A) \times \mathbb{P}(B)$$

3.2 The General Multiplication Rule

For any two events A and B

$$\mathbb{P}(A \text{ and } B) = \mathbb{P}(A) \times \mathbb{P}(B | A)$$

3.3 Probability Trees

Definition 3.3.1: Probability Tree

A diagram that shows the sample space of a random experiment and the probability of each outcome.

3.3.1 Bayes' Theorem

$$\mathbb{P}(A | B) = \frac{\mathbb{P}(A) \times \mathbb{P}(B | A)}{\mathbb{P}(A) \times \mathbb{P}(B | A) + \mathbb{P}(A') \times \mathbb{P}(B | A')}$$

Chapter 4

Module 11: Random Variables

Definition 4.0.1: Random Variable

Assigns a unique numerical value to the outcome of a random experiment.

Definition 4.0.2: Discrete Random Variable

A random variable that can take on a finite number of values. Discrete random variables are usually counts.

Definition 4.0.3: Continuous Random Variable

A random variable that can take on an infinite number of values. Continuous random variables are usually measurements.

4.1 Discrete Random Variables

4.1.1 Notation

For a given event X , the probability of X is denoted by $\mathbb{P}(X)$. For a given value x , the probability of X is denoted by $\mathbb{P}(X = x)$, i.e. the probability that X takes on the value x .

4.1.2 Probability Distribution

Definition 4.1.1: Probability Distribution

The list of all possible values of a random variable and their corresponding probabilities.

Any probability distribution must satisfy the following two conditions:

- $0 \leq \mathbb{P}(X = x) \leq 1$ - The probability of any value of X is between 0 and 1.
- $\sum_x \mathbb{P}(X = x) = 1$ - The sum of the probabilities of all possible values of X is 1.

4.1.3 Key Words

- At least / No less than - $x \geq$
- At most / No more than - $x \leq$
- Less than / fewer than - $x <$
- More than / greater than - $x >$

- Exactly - $x =$

4.1.4 Mean and Variance of a Discrete Random Variable

4.1.4.1 Mean

Definition 4.1.2: Mean / Expected value of a Discrete Random Variable

The average value of a random variable, denoted by μ .

For a given random variable X , the mean is given by

$$\mu_X = \sum_{i=1}^n x_i p_i$$

Where x_i is the value of X and p_i is the probability of X taking on the value x_i .

4.1.4.1.1 Applications of the Mean

- The mean of a random variable is the long-term average value of the random variable.
- The mean of a random variable is the centre of the probability distribution of the random variable.

4.1.4.2 Variance

Definition 4.1.3: Variance

The average of the squared differences between each value of a random variable and the mean of the random variable, denoted by σ^2 .

For a given random variable X , the variance is given by

$$\sigma_X^2 = \sum_{i=1}^n (x_i - \mu_X)^2 p_i$$

And standard deviation is given by

$$\sigma_X = \sqrt{\sigma_X^2}$$

Where x_i is the value of X and p_i is the probability of X taking on the value x_i .

4.1.4.3 Rules for Mean and Variance of Random Discrete Variables

4.1.4.3.1 Adding or Subtracting a Constant to a Random Variable

If $Y = X + c$, then $\mu_Y = \mu_X + c$, $\sigma_Y^2 = \sigma_X^2$ and $\sigma_Y = \sigma_X$.

If $Y = X - c$, then $\mu_Y = \mu_X - c$, $\sigma_Y^2 = \sigma_X^2$ and $\sigma_Y = \sigma_X$.

4.1.4.3.2 Multiplying a Random Variable by a Constant > 1

If $Y = cX$, $c > 1$, then $\mu_Y = c\mu_X$, $\sigma_Y^2 = c^2\sigma_X^2$ and $\sigma_Y = c\sigma_X$

4.1.4.3.3 Multiplying a Random Variable by a Constant < 1

If $Y = cX$, $c < 1$, then $\mu_Y = c\mu_X$, $\sigma_Y^2 = c^2\sigma_X^2$ and $\sigma_Y = c\sigma_X$

4.1.4.3.4 Linear Transformation of a Random Variable

If $Y = a + bX$, then $\mu_Y = a + b\mu_X$, $\sigma_Y^2 = b^2\sigma_X^2$ and $\sigma_Y = |b|\sigma_X$

4.1.4.3.5 Sum of Two Random Variables

If $Z = X + Y$, then $\mu_Z = \mu_X + \mu_Y$, $\sigma_Z^2 = \sigma_X^2 + \sigma_Y^2$ and $\sigma_Z = \sqrt{\sigma_X^2 + \sigma_Y^2}$. Only if X and Y are independent.

4.1.5 Binomial Random Variables

Definition 4.1.4: Binomial Random Variable

A random variable that counts the number of successes in a fixed number of independent trials, denoted by $X \sim \text{Bin}(n, p)$. Where n is the number of trials and p is the probability of success.

Definition 4.1.5: Binomial Experiment

Random experiments that satisfy the following conditions:

- A fixed number of trials, denoted by n .
- Each trial is independent of the others.
- There are only two possible outcomes for each trial, success or failure.
- There is a constant probability of success, denoted by p , for each trial, which can be expressed as the complement of the probability of failure, $q = 1 - p$.

Note:-

The number (X) of success in a sample of size n taken without replacement from a population with proportion p of successes is approximately binomial with n and p as long as the sample size is at most 10% of the population size (N). I.e.

$$n \leq 0.1N$$

Or

$$N \geq 10n$$

To calculate the probability of a binomial random variable, we use the formula

$$\mathbf{P}(X = x) = \binom{n}{x} p^x q^{n-x}, \text{ where } x = 0, 1, 2, \dots, n$$

Where n is the number of trials, x is the number of successes, p is the probability of success and q is the probability of failure.

If X is Binomial with parameters n and p , then

$$\mu_X = np$$

And

$$\begin{aligned} \sigma_X^2 &= np(1-p) \\ \sigma_X &= \sqrt{np(1-p)} \end{aligned}$$

4.2 Continuous Random Variables

4.2.1 Uniform Distribution

Definition 4.2.1: Uniform Distribution

,denoted by $X \sim U(a, b)$

For a random variable X , if is uniformly distributed over the interval a and b then its probability distribution density function is given by

$$f(x) = \begin{cases} \frac{1}{b-a}, & a < x < b \\ 0, & \text{otherwise} \end{cases}$$

The mean and variance of a uniformly distributed random variable is given by

$$\begin{aligned} \mu_X &= \frac{a+b}{2} \\ \sigma_X^2 &= \frac{(b-a)^2}{12} \\ \sigma_X &= \sqrt{\frac{(b-a)^2}{12}} \end{aligned}$$