Supplementary Material for SEER: Auto-Generating Information Extraction Rules from User-Specified Examples

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Algorithm 3: Learn Primitives
Terminologies : A suggestion set is s = (P_s, R_s), where P_s \subset P, the set of all
                                                                                         Global Variables: E_n: all the negative examples, e_n \in E_n
                 the positive examples, and R_s contains rules capturing all
                                                                                         Terminologies
                                                                                                             |e| denotes the number of tokens in e; e[i, j] denotes
                                                                                                              the ordered list of the i'th to j'th tokens from e,
                                                                                                              1 \le i, j \le |e|
                                                                                         Inputs
                                                                                                             : k is the token to learn from; R is the current path from the
                                                                                                              root to some primitive in the tree being generated; e is the
                                                                                                              positive example k is in
                                                                                         Output
                                                                                                             : P_k, set of primitives capturing k given the current path R
                                                                                         Function LearnPrimitives (k, R, e)
                                                                                              P_k := []
                                                                                              /* Maintain diversity: iterate over all types
                                                                                                                                                                         */
                                                                                                   (pre-built, dictionary, etc)
                                                                                              foreach t in all possible primitive types do
                                                                                                   Let A_k be the set of primitives that capture k of type t
                                                                                                   Let P_{\iota}^{j} be the highest scoring primitive from A_{k} s.t.
                                                                                                     CapturesNegative(R, p_{A_k} \in A_k, e) is false
                                                                                                   P_k := P_k \cup P'_k
                                                                                              return P_k
                                                                                         Inputs
                                                                                                             : R is the current path from the root to some primitive in
                                                                                                              the tree being generated; p_{A_k} \in A_k; e: the positive example the tree generation is learning from
                                                                                         Output
                                                                                                             : Returns true if appending p_{A_k} to the R will lead to
                                                                                                              creating rules capturing a negative example
                                                                                         Function CapturesNegative (R, p_{A_k}, e)
                                                                                              R' := R.append(p_{A_k})
                                                                                              Let e_p[1, m] be the tokens R' captures
                                                                                              if IsRuleCaptures(e_n[1,k], R') and e_n[k,|e_n|] = e_p[m,|e_p|] then
                                                                                                     ^{\prime *} The rule that is forming will capture e_n
                                                                                                   return true
                                                                                              return false
```

A suggestion set is $s = (P_s, R_s)$, where $P_s \subset P$, the set of all the positive examples, and R_s contains rules capturing all examples in P_s

Algorithm 4: Forming Suggestion Sets with Intersection

T: set of trees to intersect

Output:

I: a list of suggestion sets

Function *Intersect(T)*

```
foreach t \in T, t learned from example e do
     if I = \emptyset then I := I \cup \{(\{e\}, t)\}
     else
           IsAdded := false
           foreach s = (P_s, T_i) \in I do
                if IsIntersectable(T_i, t) then
                     s := (P_s \cup \{e\}, Traverse(T_i, t, null))
                     IsAdded := true
                     break
            ^{\prime *} Disjunct when t does not intersect
           if not I sAdded then I := I \cup \{(\{e\}, t)\}
return I
```

```
Algorithm 1: Seer's Learning Algorithm
```

```
:E_p: Set of positive examples; E_n: Set of negative examples
Inputs
Output
                : S, a list of suggestion sets, s.t. each P_s is unique and the
                union of all P_s = E_p (covers all positive examples)
Function Learn (E_p, E_n)
Let T be a list of trees
     foreach e in E_n do
          /st Generate tree for example e
          T_e := GenerateTree(e)
         T.add(T_e)
     /* Groups and disjuncts rules and then trim
    Let S be a list of suggestion sets
    S := Trim(Intersect(T))
```

Algorithm 2: Tree Generation for an Example

```
Global Variables: E_n: all the negative examples
Input
                   :e, the example the tree generation will learn from
Output
                   :T, the generated tree
Function GenerateTree (e)
     Let K_e be a list of tokens
     K_e = Tokenize(e)
    Let T be a tree and C_T be a pointer to nodes in T
    Let R be a list of primitives from the root to C_T
    T = GrowTree(C_T, K_e[0], R, e)
    return T
Function GrowTree\left(C_{T},\,k,\,R,\,e\right)
     P_k = LearnPrimitives(k, R, e)
     C_T.children := C_T.children \cup P_k
     foreach c in C<sub>T</sub>.children do
          R.append(c.primitive)
          if not IsLastToken(t) or not IsCaptureNegativeExample(R) then
               Let P_k be a primitive
              P_k := GrowTree(c, r.nextToken(), R, e)
          R.remove(c.primitive)
          if P_k = null then C_T.remove(c)
    if not IsLastToken(t) and C_T.children \neq \emptyset then return null
    return C_T. primitive
```

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```

Algorithm 5: SEER's Intersection & Merge Algorithm

```
Input:
  P_1, P_2: primitives from the input trees to intersect T_1 and T_2; The tree
 variables T_1 and T_2 point to the root primitives.
  P_i: primitive in the resulting intersect tree T_i
Output:
  P_i: a primitive node due to an intersection or null
Function Call:
  Traverse(T_1, T_2, null)
Function Traverse (P_1, P_2, P_i)
     if (IsTokenGap(P_1)) and not IsTokenGap(P_2)) or (not\ IsTokenGap(P_1))
      and IsTokenGap(P_2)) then
          Let P_{TG} be the token gap and P be the non-token gap
          P'_i := Primitive(P_{TG})
          \vec{P_i}.children := \vec{P_i}.children \cup \{P'_i\}
          foreach c \in P_{TG}.children do
           Traverse(c, P, P'_i)
     else if IsIntersects(P_1, P_2) or IsMergeable(P_1, P_2) then
          P'_{i} := IntersectMergePrimitives(P_{1}, P_{2})
          P_i.children := P_i.children \cup \{P'_i\}
          foreach c_1, c_2 : c_1 \in P_1.children, c_2 \in P_2.children do
           Traverse(c_1, c_2, P'_i)
     /* Eliminate non-intersectable paths
                                                                                */
     if P_i.children = \emptyset and not(areBothLeaves(P_1, P_2)) then
      Remove(P_i)
    return P_i
```

Algorithm 6: Trimming From Suggestion Sets

```
Input
                 : S: list of suggestion sets
Output
                 :S, with less rules
Function Trim(S)
    foreach s := (P_s, R_s) \in S do
         G := Classify(R_s)
         R_{final} := []
         foreach g \in G do
              /* g is a list of rules
              Let r be the highest scoring rule from g
             R_{final} := R_{final} \cup \{r\}
         /* Rank rules by their scores in desc. order
         Sort(R_{final})
         R_s := R_{final}
    return S
Function Classify(R_s)
    Let G be a list of grouped rules
    G := []
    foreach r \in R_s do
         IsAdded := false
         foreach G_i \in G do
              /* The classification group of a rule is the
                  set of composing primitives of that rule */
              if ClassificationGroup(G_i) = ClassificationGroup(r) then
                   G_i := G_i \cup \{r\}
                  IsAdded := true
                  break
         if not IsAdded then
              G_i' := \{r\}
             G := G \cup \{G'_i\}
    return G
```

```
Algorithm 7: Refinement Computation
```

```
Terminologies
                    :The cover rules of an extraction, x, are the rules that can
                     capture x
Global Variables: LIMIT: the max num of refinements to show
Inputs
                    :S = (P_s, R_s): a suggestion set, where each rule r has its
                     own set of extractions X_r
Output
                    : F, the set of refinements
Function GetRefinements (S)
    \begin{aligned} & F := [] \\ & C := X_{r_1} \cup X_{r_2} \cup ... \cup X_{r_n}, r_i \in R_s, 1 \le i \le |R_s| \end{aligned}
          if IsAdd(x, F) then F := F \cup \{x\}
          if |F| > LIMIT then break
     return F
Function IsAdd(x, F)
     foreach x_f \in F do
       if CoverRules(x_f) = CoverRules(x) then return false
     return true
```

Algorithm 8: Disable Refinements

```
:s is a suggestion set, where s = (P_s, R_s); F is the list of all
Inputs
                  refinements
Function Disable Refinement(s, F)
    /* Get the rules the user has rejected
                                                                      */
    R_{rejected} := GetRejectedRules(s.R_s)
    R_{display} := Difference(s.R_s, R_{rejected})
    /* For each refinement that the user hasn't accepted
        or rejected, disable appropriate refinements
    foreach f \in F do
         if not IsUserAcceptOrReject(f) then
             R_f := CoveringRules(f)
/* If all the covering rules cannot be
                 displayed, then disable.
             isAllNotDisplayed := isEmpty(intersection(R_f, R_{display}))
             /* If all the covering rules can be displayed,
                 then disable.
             isAllDisplayed := isEmpty(difference(R_{display}, R_f))
             if isAllNotDisplayed or isAllDisplayed then
                  Disable(f)
             else
                  Enable(f)
```