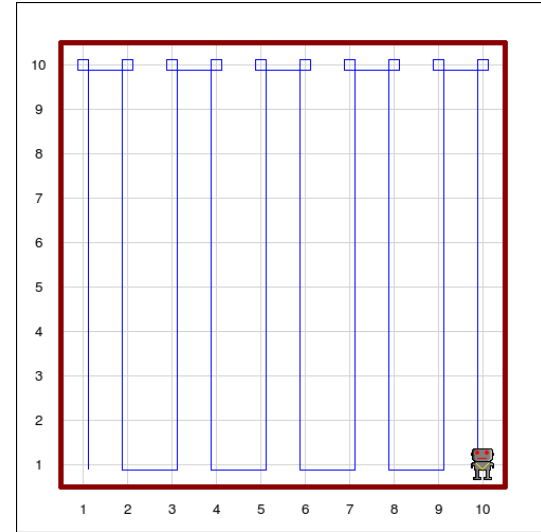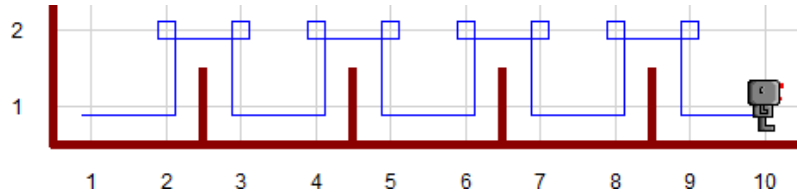# Week 1
# Today's Tasks

# Task 1: ZigZag

- Create a default world.
- Add a robot.
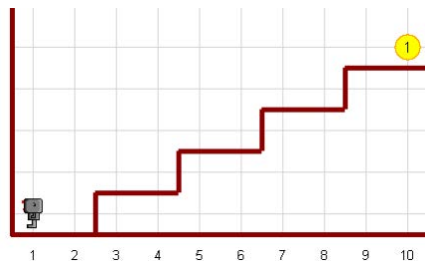- Make the robot visit the entire world in a zigzag fashion.
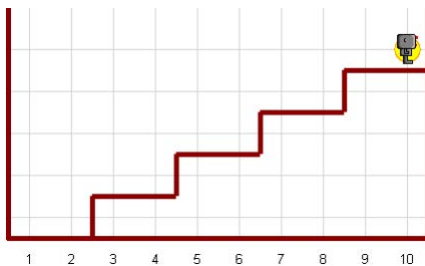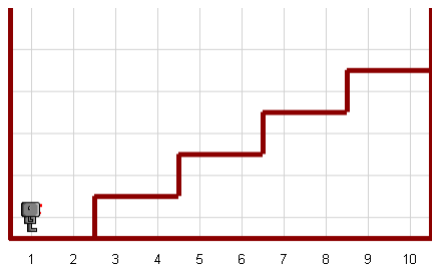
# Task 2: Hurdle

- Load the world named 'hurdles1.wld'.
- Add a robot.
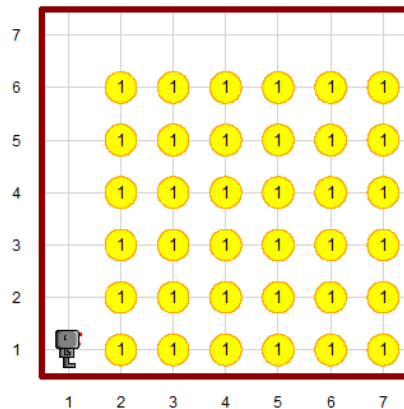- Make the robot jump all hurdles and pick up the beeper.

# Task 3: Newspaper delivery

- Load the world named 'newspaper.wld'.
- Add a robot with one beeper.
- Make the robot deliver newspapers and return to his starting point.

# Task 4: Harvest

- Load the world named 'harvest1.wld'.
- Add a robot.
- Make the robot harvest all the carrots (beepers).

# Let's start!