Practice problems (don't turn in):

- 1. Dijkstra's algorithm: This is not covered in the lectures because it's the sort of thing many of you have seen before, possibly multiple times (GT undergrads see it at least 3 times in their algorithms, data structures, and combinatorics class). If you haven't seen it, or need a refresher, look at Chapter 4.4 of [DPV].
 - (a) What is the input and output for Dijkstra's algorithm?
 - (b) What is the running time of Dijkstra's algorithm using min-heap (aka priority queue) data structure? (Don't worry about the Fibonacci heap implementation or running time using it.)
 - (c) What is the main idea for Dijkstra's algorithm?
- 2. [DPV] Problem 3.3 (Topological ordering example)
- 3. [DPV] Problem 3.4 (SCC algorithm example)
- 4. [DPV] Problem 3.5 (Reverse of graph)
- 5. [DPV] Problem 3.8 (Pouring water)

Instructions: In the algorithm design problems: use the algorithms from class, such as DFS, BFS, Dijkstra's, connected components, etc., as a black-box subroutine for your algorithm. So say what you are giving as input, then what algorithm you are running, and what's the output you're taking from it. Here's an example:

I take the input graph G, I first find the vertex with largest degree, call it v^* . I take the complement of the graph G, call it \overline{G} . Run Dijkstra's algorithm on \overline{G} with $s=v^*$ and then I get the array dist[v] of the shortest path lengths from s to every other vertex in the graph \overline{G} . I square each of these distances and return this new array.

We don't want you to go into the details of these algorithms and tinker with it, just use it as a black-box as I did with Dijkstra's algorithm above. If you attempt to modify one of these algorithms you will not receive full credit, even if it is correct. Make sure to explain your algorithm in words, no pseudocode.

Problem 1 [DPV] Problem 3.15 (Computopia)

Note, linear time means O(n+m) where n=|V| and m=|E|. Part (a):

Part (b):

Problem 2 [DPV] Problem 4.14 (shortest paths through v_0)

A faster algorithm is worth more. Be sure to state/explain the running time of your algorithm. Hint: Use Dijkstra's algorithm as a black-box. How many runs of Dijkstra's algorithm do you need?

Answer: (Explain your algorithm in words and analyze its running time. No pseudocode.)

Problem 3 Global Destination

In this problem: use the algorithms from class, such as DFS, BFS, Dijkstra's, connected components, etc., as a black-box subroutine for your algorithm; see the instructions on the front page. Make sure to explain your algorithm in words. (Note, this is problem 3.22 in [DPV].)

Let G = (V, E) be a **directed** graph given in its adjacency list representation. A vertex v is called a **global destination** if every other vertex has a path to v.

Part (a). Give an algorithm that takes as input a directed graph G = (V, E) and a specific vertex s, and determines if s is a global destination. Your algorithm should have linear running time, i.e., O(n+m) = O(|V| + |E|).

Part (b). More Global Destination:

Given an input graph G = (V, E) determine if G has a global destination or not. The running time of your algorithm should still be O(|V| + |E|). In this problem you are no longer given s, and you need to determine whether or not G contains a global destination.