

Investment problem

$$\max_{i(t)} \int_0^T e^{-\rho t} \left\{ p k(t) - c i(t) - \frac{d}{2} i(t)^2 \right\} dt \quad st \quad \dot{k}(t) = i(t) - \delta k(t)$$

given boundary conditions

$$k(0) = k_0 \quad k(T) = k_T \quad T : \text{given}$$

Necessary conditions

$$\begin{aligned} \dot{k} &= i - \delta k \\ \dot{\psi} &= (\rho + \delta)\psi - p \end{aligned}$$

```
• # can take a while....  
• # might need to install DifferentialEquations & Plots with  
• # ]add Differential Equations Plots  
• begin  
•     using DifferentialEquations  
•     using Plots  
•     using Base.Iterators: product  
• end
```

```
• # tell plots to use GR b/c it's fastest  
• gr();
```

23.33333333333332

```
• begin  
•     # parameters  
•     px=0.5  
•     c=3  
•     d=1  
•     ρ=0.07  
•     δ=0.05  
•  
•     # steady state  
•     ssi = (px / (ρ+δ) - c) / d  
•     ssk = ssi/δ  
• end
```

dot_ki! (generic function with 1 method)

```
• begin  
•     doti(k,i) = (ρ+δ)*(i - ssi)  
•     dotk(k,i) = i - δ*k  
•  
•     # solvers in DifferentialEquations.jl require functions that
```

```

• # take the form 'f!(dy, y, params, t)'
• function dot_ki!(dy, y, parm, t)
•     k,i = y
•     dy[1] = dotk(k,i)
•     dy[2] = doti(k,i)
•     return dy
• end
end

```

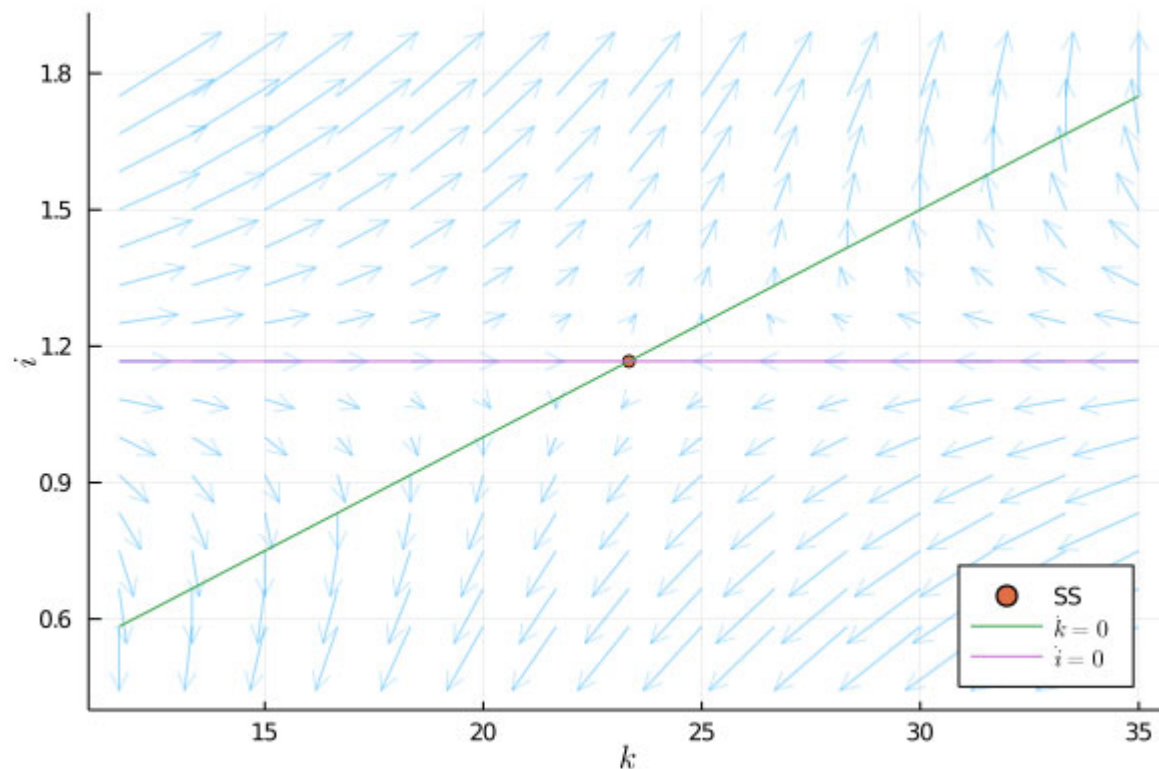
15×15 Array{Float64,2}:

0.0	0.166667	0.333333	0.5	...	2.16667	2.33333
-0.166667	-2.22045e-16	0.166667	0.333333		2.0	2.16667
-0.333333	-0.166667	0.0	0.166667		1.83333	2.0
-0.5	-0.333333	-0.166667	0.0		1.66667	1.83333
-0.666667	-0.5	-0.333333	-0.166667		1.5	1.66667
-0.833333	-0.666667	-0.5	-0.333333	...	1.33333	1.5
-1.0	-0.833333	-0.666667	-0.5		1.16667	1.33333
⋮				⋮		
-1.5	-1.33333	-1.16667	-1.0		0.666667	0.833333
-1.66667	-1.5	-1.33333	-1.16667	...	0.5	0.666667
-1.83333	-1.66667	-1.5	-1.33333		0.333333	0.5
-2.0	-1.83333	-1.66667	-1.5		0.166667	0.333333
-2.16667	-2.0	-1.83333	-1.66667		-4.44089e-16	0.166667
-2.33333	-2.16667	-2.0	-1.83333		-0.166667	-4.44089e-16

```

• # create a "mesh"
• begin
•     # grid of points in K, I space
•     kspace = range(ssk/2, stop = 1.5*ssk, length=15)
•     ispace = range(ssi/2, stop = 1.5*ssi, length=15)
•
•     kspace = product(kspace, ispace)
•     KK = [k for (k,i) in kspace]
•     II = [i for (k,i) in kspace]
•
•     SCALE = 2
•     dotII = [doti(k,i) for (k,i) in kspace].*SCALE
•     dotKK = [dotk(k,i) for (k,i) in kspace].*SCALE
• end

```



```

• begin
•   plt_quiv = plot(;legend=:bottomright, xlabel="\$k\$", ylabel="\$i\$")
•
•   # motion vectors
•   # note, use 'vec' b/c need to input a vector
•   quiver!(plt_quiv, vec(KK), vec(II); quiver=(vec(dotKK),vec(dotII)), alpha=0.2)
•
•   # steady state
•   # also note that we have to give vectors to scatter
•   scatter!(plt_quiv, [ssk],[ssi], label="SS")
•
•   # nullclines
•   plot!(plt_quiv, kspace, k -> k*δ, label="\$\\dot k = 0\$")
•   plot!(plt_quiv, kspace, k -> ssi, label="\$\\dot i = 0\$")
• end

```

ODEProblem{Float64,1,0m} with uType Array{Float64,1} and tType Float64. In-place timespan: (0.0, 25.0)
u0: [12.0, 1.19]

```

• begin
•   # initial conditions
•   # (k₀ i₀)
•   y0 = [12.0, 1.19]
•
•   # time-span for problem
•   # NOTE: this MUST be in Floats, not Ints!
•   tmax = 25.0
•   tspan = (0.0, tmax)
•
•   # define a problem
•   prob = ODEProblem(dot_ki!, y0, tspan);
• end

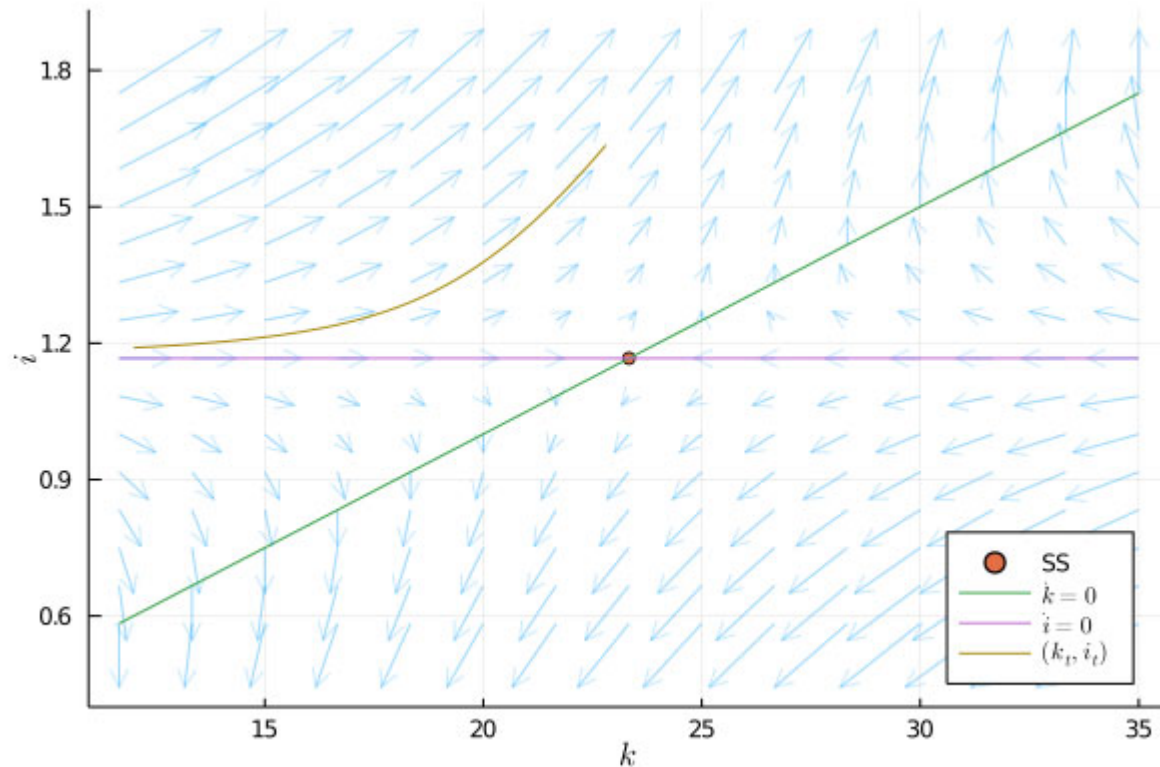
```

```

sol = retcode: Success
Interpolation: specialized 4th order "free" interpolation
t: 7-element Array{Float64,1}:
 0.0
 0.19573878328137712
 2.153126616095148
 6.6929381211746595
12.54812413836499
19.311471520641916
25.0
u: 7-element Array{Array{Float64,1},1}:
 [12.0, 1.19]
 [12.11497648059986, 1.1905545559837427]
 [13.211198665368997, 1.196879239196716]
 [15.431517391727429, 1.2187598669073956]
 [17.82701675624822, 1.2718442542485149]
 [20.358703731436886, 1.4034711175727574]
 [22.803708674093624, 1.6353150483207328]

```

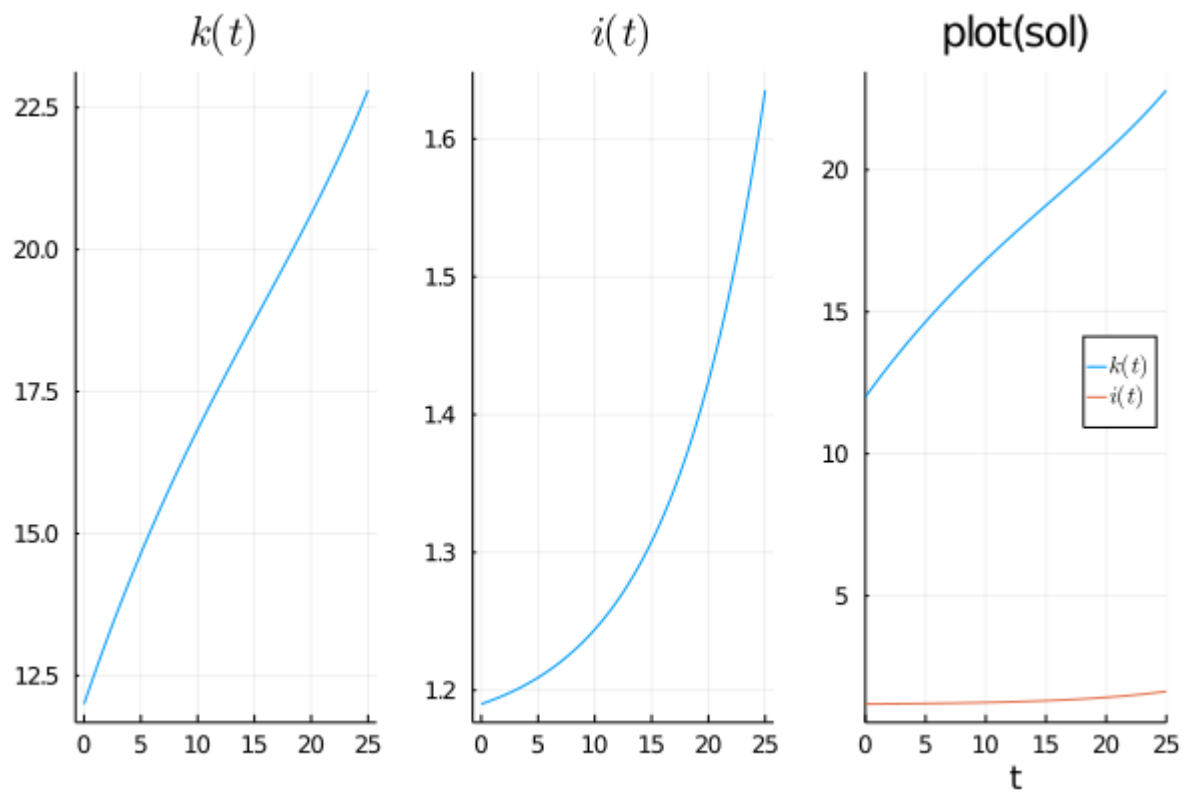
- *# solve the problem using the 'Tsit5()' method*
- *# Note how much better our tolerances are*
- `sol = solve(prob, Tsit5())`



- ```

• begin
• TT = 0 : 0.1 : tmax
• kpath = first.(sol.(TT))
• ipath = last.(sol.(TT))
•
• # need to copy plot b/c of updating in Pluto
• pltq = deepcopy(plt_quiv)
• plot!(pltq, kpath, ipath; label="\$(k_t, i_t)\$")
• end

```



```

• plot(
• plot(TT, t -> sol(t)[1], title="\$k(t)\$", legend=:none),
• plot(TT, t -> sol(t)[2], title="\$i(t)\$", legend=:none),
• plot(
• sol,
• labels=["\$k(t)\$" "\$i(t)\$"], # NOTE: labels are row matrix!
• legend=:right,
• title="plot(sol)"
•),
• layout=(1,3)
•)

```