



量子场论

相互作用、 格林函数与路径积分

本章建立 **量子场论** 中量子“相互作用场”的正则和路径积分描述

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**Wick定理、约化公式和格林函数的极点****Wick定理****约化公式****格林函数的极点****路径积分****量子场算符本征态的矩阵元****时间演化算符的矩阵元****波函数****格林函数与生成泛函****玻色场的生成泛函****费米场的生成泛函****拉格朗日体系** **$\lambda\phi^4$ 理论与四费米理论** **$\lambda\phi^4$ 理论的费曼图****4费米理论的费曼图**



Wick定理

S矩阵与正规乘积

S矩阵与场的产生湮灭算符展开

$$\Phi_\alpha = a^\dagger \cdots b^\dagger \Phi_0$$

$$\Phi_\beta = d^\dagger \cdots f^\dagger \Phi_0$$

$$S_{\beta\alpha} = (\Phi_\beta, S\Phi_\alpha) = (\Phi_\beta, \mathbf{T} e^{-i \int_{-\infty}^{\infty} dt V(\psi, \pi)} \Phi_\alpha) = (\Phi_\beta, U(\infty, -\infty) \Phi_\alpha)$$

$$\psi(x) = \sum_{\sigma} \int \frac{d^3 p}{(2\pi)^{3/2}} [\underbrace{e^{-ip \cdot x} u(\vec{p}, \sigma) a(\vec{p}, \sigma)}_{\psi^+} + \underbrace{e^{ip \cdot x} v(\vec{p}, \sigma) a^{c\dagger}(\vec{p}, \sigma)}_{\psi^-}] \quad \pi(x) = \pi^+(x) + \pi^-(x)$$

需要处理很多个产生湮灭算符的真空中期望值的方法！

正规乘积： $\mathbf{N}(UVW \cdots Z) = \delta_P U' V' W' \cdots Z'$ 上章用的符号是 : :

其中 $U' V' W' \cdots Z'$ 中的算符排列顺序是在原来 $UVW \cdots Z$ 的算符排列顺序基础之上，将所有的消灭算符排在所有产生算符的左边（面对大家，也就是纸面上的右边），而消灭算符之间的相对顺序和产生算符之间的相对顺序则保持不变。

从 $UVW \cdots Z$ 调换到 $U' V' W' \cdots Z'$ ， 费米子交换偶数次 $\delta_P = 1$, 否则 $\delta_P = -1$ 。



Wick定理

算符的收缩: $\psi_l(x)\psi_{l'}(x') \stackrel{\square}{=} \mathbf{T}(\psi_l(x)\psi_{l'}(x')) - \mathbf{N}(\psi_l(x)\psi_{l'}(x'))$

相邻的双线性场算符的收缩等于运算后的真空期望值

$$\psi_l(x)\psi_{l'}(x') \stackrel{\square}{=} (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0)$$

证明: 不妨设 $t > t'$

$$\begin{aligned}
 \mathbf{T}(\psi_l(x)\psi_{l'}(x')) &= \mathbf{T}(\psi_l(x))\psi_{l'}(x') = \mathbf{N}(\psi_l(x))(\psi_{l'}^+(x') + \psi_{l'}^-(x')) \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}^+(x')) + \mathbf{N}(\psi_l^-(x)\psi_{l'}^-(x')) + \psi_l^+(x)\psi_{l'}^-(x') \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}^+(x')) + \mathbf{N}(\psi_l^-(x)\psi_{l'}^-(x')) \pm \psi_{l'}^-(x')\psi_l^+(x) + [\psi_l^+(x), \psi_{l'}^-(x')]_\mp \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}^+(x')) + \mathbf{N}(\psi_l^-(x)\psi_{l'}^-(x')) + \mathbf{N}(\psi_l^+(x)\psi_{l'}^-(x')) + [\psi_l^+(x), \psi_{l'}^-(x')]_\mp \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}^+(x')) + \mathbf{N}(\psi_l(x)\psi_{l'}^-(x')) + (\Phi_0, [\psi_l^+(x), \psi_{l'}^-(x')]_\mp\Phi_0) \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}(x')) + (\Phi_0, \psi_l^+(x)\psi_{l'}^-(x')\Phi_0) \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}(x')) + (\Phi_0, \psi_l(x)\psi_{l'}(x')\Phi_0) \\
 &= \mathbf{N}(\psi_l(x)\psi_{l'}(x')) + (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0)
 \end{aligned}$$



Wick定理

算符的收缩: $\psi_l(x)\psi_{l'}(x') \stackrel{\boxed{\quad}}{\equiv} \mathbf{T}(\psi_l(x)\psi_{l'}(x')) - \mathbf{N}(\psi_l(x)\psi_{l'}(x'))$

相邻的双线性场算符的收缩等于运算后的真空期望值

$$\psi_l(x)\psi_{l'}(x') \stackrel{\boxed{\quad}}{=} (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0)$$

证明: 不妨设 $t > t'$

$$\begin{aligned}\mathbf{T}(\psi_l(x)\psi_{l'}(x')) &= \mathbf{T}(\psi_l(x))\psi_{l'}(x') = \mathbf{N}(\psi_l(x))(\psi_{l'}^+(x') + \psi_{l'}^-(x')) \\ &= \mathbf{N}(\psi_l(x)\psi_{l'}(x')) + [\psi_l^+(x), \psi_{l'}^-(x')]_{\mp} \\ &= \mathbf{N}(\psi_l(x)\psi_{l'}(x')) + (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0)\end{aligned}$$

推论: 相互之间的对易或反对易性质导致

- ▶ 相邻的不同场的场算符之间的收缩等于零
- ▶ 相邻的消灭算符之间,产生算符之间的收缩等于零



Wick定理

算符的收缩: $\psi_l(x)\psi_{l'}(x') \equiv \overline{\psi_l(x)\psi_{l'}(x')} = T(\psi_l(x)\psi_{l'}(x')) - N(\psi_l(x)\psi_{l'}(x'))$

相邻的双线性场算符的收缩等于运算后的真空期望值

相邻的不同场之间的收缩等于零; 消灭算符之间,产生算符之间的收缩等于零

定义不相邻的场算符的收缩: $N(U \overline{VW} \cdots YZ) \equiv \delta_P \overline{VZ} N(UW \cdots Y)$

其中的上划线是指将两端的算符V和Z进行收缩操作,对上划线中间的算符 $W \cdots Y$ 不发生作用,只是考虑因子 $\delta_P = (-1)^n$, n是将V和Z调到一起所交换的费米子算符的数目.

推论: $N(U \overline{VW} \cdots \overline{XY} Z) \equiv \delta_P \overline{VZ} \overline{WY} N(U \cdots X)$

预备定理:如果算符Z的时间值比所有算符都早,则有

$$N(UV \cdots XY)Z = N(UV \cdots XYZ) + N(UV \cdots XYZ) + N(UV \cdots XYZ) + \cdots + N(UV \cdots XYZ)$$

证明: 如果Z是湮灭算符

$$\overline{UZ} = T(UZ) - N(UZ) = UZ - UZ = 0 \Rightarrow \text{预备定理恒成立, 只需讨论Z是产生算符的情况!}$$



Wick定理

算符的收缩: $\psi_l(x)\psi_{l'}(x') \equiv T(\psi_l(x)\psi_{l'}(x')) - N(\psi_l(x)\psi_{l'}(x'))$

定义不相邻的场算符的收缩: $N(UVW\cdots YZ) \equiv \delta_P VZ N(UW\cdots Y)$

$\delta_P = (-1)^n$, n 是将 V 和 Z 调到一起所交换的费米子算符的数目.

推论: $N(UVW\cdots XY Z) \equiv \delta_P VZ WY N(U\cdots X)$

预备定理:如果算符 Z 的时间值比所有算符都早,则有

$$N(UV\cdots XY)Z = N(UV\cdots XYZ) + N(UV\cdots XYZ) + N(UV\cdots XYZ) + \cdots + N(UV\cdots XYZ)$$

Z 是产生算符;若 $UV\cdots XY$ 是产生算符,则因它们的收缩为零,结果恒成立

证明: Z 是产生算符;若 $UV\cdots XY$ 是湮灭算符的情形成立,则对一产生算符 P

$$PN(UV\cdots XY)Z = PN(UV\cdots XYZ) + PN(UV\cdots XYZ) + PN(UV\cdots XYZ) + \cdots + PN(UV\cdots XYZ)$$

$$\text{利用 } PZ = 0 \Rightarrow N(PUV\cdots XYZ) = 0 \quad \text{上式等号左右两边的P都可以移入正规乘积,加上本行式子得到下面结果}$$

$$N(PUV\cdots XY)Z = N(PUV\cdots XYZ) + N(PUV\cdots XYZ) + N(PUV\cdots XYZ) + \cdots + N(PUV\cdots XYZ)$$

\Rightarrow 进一步可以假设 U 是产生算符, $V\cdots XY$ 是湮灭算符 重复一遍上面证明,结果仍然成立

\Rightarrow 预备定理成立,这时 $UV\cdots XY$ 产生湮灭算符都有 只需讨论 $UV\cdots XY$ 是湮灭算符的情况!



Wick定理

算符的收缩: $\psi_l(x)\psi_{l'}(x') \equiv T(\psi_l(x)\psi_{l'}(x')) - N(\psi_l(x)\psi_{l'}(x'))$

相邻的双线性场算符的收缩等于运算后的真空期望值

相邻的不同场之间的收缩等于零; 消灭算符之间, 产生算符之间的收缩等于零

定义不相邻的场算符的收缩: $N(UVW\cdots YZ) \equiv \delta_P VZ N(UW\cdots Y)$

$\delta_P = (-1)^n$, n 是将 V 和 Z 调到一起所交换的费米子算符的数目.

推论: $N(UVW\cdots XY Z) \equiv \delta_P VZ WY N(U\cdots X)$

预备定理: 如果算符 Z 的时间值比所有算符都早, 则有

$$N(UV\cdots XY)Z = N(UV\cdots XYZ) + N(UV\cdots XYZ) + N(UV\cdots XYZ) + \cdots + N(UV\cdots XYZ)$$

证明: Z 是产生算符; $UV\cdots XY$ 湮灭算符: 归纳法

$$n=1: N(Y)Z = YZ = T(YZ) = N(YZ) + YZ$$

\Rightarrow 预备定理成立, 假设对 n 成立, 只需推出对 $n+1$ 也成立! 对湮灭算符 R :

$$RN(UV\cdots XY)Z = \underbrace{RN(UV\cdots XYZ)}_{\text{计算见下行}} + RN(UV\cdots XYZ) + RN(UV\cdots XYZ) + \cdots + RN(UV\cdots XYZ)$$

$$RN(UV\cdots XYZ) = \delta_P T(RZ) UV\cdots XY = \delta_P (N(RZ) + RZ) UV\cdots XY = N(RUV\cdots XYZ) + N(RUV\cdots XYZ)$$

$$N(RUV\cdots XY)Z = N(RUV\cdots XYZ) + N(RUV\cdots XYZ) + N(RUV\cdots XYZ) + \cdots + N(RUV\cdots XYZ)$$



Wick定理

Wick定理:

预备定理:如果算符 Z 的时间值比所有算符都早,则有

$$\mathbf{N}(UV \cdots XY)Z = \mathbf{N}(UV \cdots XYZ) + \mathbf{N}(UV \cdots XYZ) + \mathbf{N}(UV \cdots XYZ) + \cdots + \mathbf{N}(UV \cdots XYZ) \quad \square$$

定理1:

$$\mathbf{T}(UV \cdots XYZ) = \mathbf{N}(UV \cdots XYZ)$$

无收缩项

$$+ \mathbf{N}(UV \cdots XYZ) + \cdots + \mathbf{N}(UV \cdots XYZ) + \quad \square$$

一次收缩项

$$+ \mathbf{N}(UV \cdots XYZ) + \cdots \quad \square$$

二次收缩项

$$+ \cdots \quad \square$$

全部收缩项

证明: 归纳法

$n = 2$ 阶成立! 假设对 n 阶已经成立. 右乘时间早于所有其它算符时间的算符 R

$$\mathbf{T}(UV \cdots XYZ)R = \mathbf{T}(UV \cdots XYZR)$$

$$\mathbf{N}(UV \cdots XYZ)R = \mathbf{N}(UV \cdots XYZR) + \mathbf{N}(UV \cdots XYZR) + \mathbf{N}(UV \cdots XYZR) + \cdots \quad \square$$

$$\mathbf{N}(UV \cdots XYZ)R = \delta_P U V \mathbf{N}(W \cdots XYZ)R = \mathbf{N}(UV \cdots XYZR) + \mathbf{N}(UV W \cdots XYZR) + \cdots$$

..... $\Rightarrow n + 1$ 阶也成立!



Wick定理

Wick定理:

定理1:

$$\begin{aligned}
 T(UV \cdots XYZ) &= N(UV \cdots XYZ) && \text{无收缩项} \\
 &\quad + N\left(\overbrace{UV \cdots XYZ}^{\square}\right) + \cdots + N\left(\overbrace{UV \cdots XYZ}^{\square}\right) + && \text{一次收缩项} \\
 &\quad + N\left(\overbrace{UV \cdots XYZ}^{\square}\right) + \cdots && \text{二次收缩项} \\
 &\quad + \cdots \\
 &\quad + N\left(\overbrace{UVW \cdots XYZ}^{\square}\right) + \cdots && \text{全部收缩项}
 \end{aligned}$$

定理2:

若 T 乘积中含 N 乘积, 展开仍成立, 但需将各 N 乘积内部各算符之间的收缩略去.

此时若 N 乘积内部是纯湮灭或纯产生算符, 本来就不存在内部的收缩。

若 N 乘积是一对湮灭产生算符, N 乘积就等于 T 乘积减去收缩。再多用归纳法。

$$\Phi_\alpha = a^\dagger \cdots b^\dagger \Phi_0 \qquad \qquad \Phi_\beta = d^\dagger \cdots f^\dagger \Phi_0$$

$$S_{\beta\alpha} = (\Phi_\beta, S\Phi_\alpha) = (\Phi_\beta, \mathbf{T} e^{-i \int_{-\infty}^{\infty} dt V(\psi, \pi)} \Phi_\alpha)$$

$$\psi(x) = \sum_{\sigma} \int \frac{d^3 p}{(2\pi)^{3/2}} \underbrace{[e^{-ip \cdot x} u(\vec{p}, \sigma) a(\vec{p}, \sigma)]}_{\psi^+} + \underbrace{[e^{ip \cdot x} v(\vec{p}, \sigma) a^{\dagger}(\vec{p}, \sigma)]}_{\psi^-} \qquad \pi(x) = \pi^+(x) + \pi^-(x)$$



Wick定理

场的收缩:

$$\psi(x) = \sum_{\sigma} \int \frac{d^3 p}{(2\pi)^{3/2}} [e^{-ip \cdot x} u(\vec{p}, \sigma) a(\vec{p}, \sigma) + e^{ip \cdot x} v(\vec{p}, \sigma) a^{\dagger}(\vec{p}, \sigma)]$$

$$\boxed{\psi_l(x)\psi_{l'}(x')} = (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0) = \theta(t-t')[\psi_l^+(x), \psi_{l'}^-(x')]_{\mp} \pm \theta(t'-t)[\psi_l^+(x'), \psi_{l'}^-(x)]_{\mp}$$

标量场: $u(\vec{p}) = v(\vec{p}) = \frac{1}{\sqrt{2}(\vec{p}^2+M^2)^{1/4}}$ $f(z) = \frac{1}{2\pi i} \oint_{\text{逆时针}} dw \frac{f(w)}{w-z}$

$$\begin{aligned} \boxed{\phi(x)\phi^\dagger(y)} &= \int \frac{d^3 p d^3 p' \{ [e^{-ip \cdot x} a(\vec{p}), e^{ip' \cdot y} a^\dagger(\vec{p}')] \theta(x^0 - y^0) + [e^{-ip' \cdot y} a^c(\vec{p}'), e^{ip \cdot x} a^{\dagger c}(\vec{p})] \theta(y^0 - x^0) \}}{(2\pi)^3 2(\vec{p}^2 + M^2)^{1/4} (\vec{p}'^2 + M^2)^{1/4}} \\ &= \int \frac{d^3 p e^{i\vec{p} \cdot (\vec{x} - \vec{y})}}{2(2\pi)^3 \sqrt{\vec{p}^2 + M^2}} [e^{-i\sqrt{\vec{p}^2 + M^2}(x^0 - y^0)} \theta(x^0 - y^0) + e^{i\sqrt{\vec{p}^2 + M^2}(x^0 - y^0)} \theta(y^0 - x^0)] \\ &= \int \frac{d^3 p e^{i\vec{p} \cdot (\vec{x} - \vec{y})}}{2(2\pi)^3} \int_{-\infty}^{\infty} \frac{dp^0}{2i\pi \sqrt{\vec{p}^2 + M^2}} \frac{e^{-ip^0(x^0 - y^0)}}{-p^0 - \sqrt{\vec{p}^2 + M^2} + i0^\dagger + \frac{1}{p^0 + \sqrt{\vec{p}^2 + M^2} - i0^\dagger}} \\ &= \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \frac{i}{p^2 - M^2 + i0^\dagger} = \frac{x}{-----} \frac{y}{-----} \end{aligned}$$



Wick定理

场的收缩:

$$\psi(x) = \sum_{\sigma} \int \frac{d^3 p}{(2\pi)^{3/2}} [e^{-ip \cdot x} u(\vec{p}, \sigma) a(\vec{p}, \sigma) + e^{ip \cdot x} v(\vec{p}, \sigma) a^\dagger(\vec{p}, \sigma)]$$

$$\psi_l(x)\psi_{l'}(x') = (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0) = \theta(t-t')[\psi_l^+(x), \psi_{l'}^-(x')]_{\mp} \pm \theta(t'-t)[\psi_{l'}^+(x'), \psi_l^-(x)]_{\mp}$$

$$\text{旋量场: } u(\vec{p}, \sigma) = \sqrt{M/p^0} D(L(p)) u(0, \sigma) \quad v(\vec{p}, \sigma) = \sqrt{M/p^0} D(L(p)) v(0, \sigma)$$

$$\begin{aligned} \psi(x) \bar{\psi}_{l'}(y) &= \int \frac{d^3 p d^3 p'}{(2\pi)^3} \sum_{\sigma \sigma'} \{ [e^{-ip \cdot x} u_l(\vec{p}, \sigma) a(\vec{p}, \sigma), e^{ip' \cdot y} \bar{u}_{l'}(\vec{p}', \sigma') a^\dagger(\vec{p}', \sigma')]_+ \theta(x^0 - y^0) \\ &\quad - [e^{-ip' \cdot y} \bar{v}_{l'}(\vec{p}', \sigma') a^c(\vec{p}', \sigma'), e^{ip \cdot x} v_l(\vec{p}, \sigma) a^\dagger(\vec{p}, \sigma)]_+ \theta(y^0 - x^0) \} \end{aligned}$$

$$= \int \frac{d^3 p}{(2\pi)^3} \frac{e^{i\vec{p} \cdot (\vec{x}-\vec{y})}}{\sum_{\sigma}} [e^{-i\sqrt{\vec{p}^2+M^2}(x^0-y^0)} u_l(\vec{p}, \sigma) \bar{u}_{l'}(\vec{p}, \sigma) \theta(x^0-y^0) - e^{i\sqrt{\vec{p}^2+M^2}(x^0-y^0)} \bar{v}_{l'}(-\vec{p}, \sigma) v_l(-\vec{p}, \sigma) \theta(y^0-x^0)]$$

$$N_{\bar{l}\bar{l}}(\vec{p}) \equiv \sum_{\sigma} u_l(\vec{p}, \sigma) u_{l'}^*(\vec{p}, \sigma) = \sum_{\sigma} u_l(\vec{p}, \sigma) \bar{u}_{l'}(\vec{p}, \sigma) \beta = \frac{1}{2p^0} [p^{\mu} \gamma_{\mu} + M] \beta \quad M_{\bar{l}\bar{l}}(\vec{p}) \equiv \sum_{\sigma} v_l(\vec{p}, \sigma) v_{l'}^*(\vec{p}, \sigma) = \sum_{\sigma} v_l(\vec{p}, \sigma) \bar{v}_{l'}(\vec{p}, \sigma) \beta = \frac{1}{2p^0} [p^{\mu} \gamma_{\mu} - M] \beta$$

$$= \int \frac{d^3 p}{(2\pi)^3} \frac{e^{i\vec{p} \cdot (\vec{x}-\vec{y})}}{\sum_{\sigma}} \int_{-\infty}^{\infty} \frac{dp^0}{2i\pi 2\sqrt{\vec{p}^2 + M^2}} e^{-ip^0(x^0-y^0)} \left[-\frac{p^0 \gamma^0 - \vec{p} \cdot \vec{\gamma} + M}{p^0 - \sqrt{\vec{p}^2 + M^2} + i0^\dagger} - \frac{-p^0 \gamma^0 + \vec{p} \cdot \vec{\gamma} - M}{p^0 + \sqrt{\vec{p}^2 + M^2} - i0^\dagger} \right]_{ll'}$$

$$= \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \left[\frac{i(p_{\mu} \gamma^{\mu} + M)}{p^2 - M^2 + i0^\dagger} \right]_{ll'} = \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \left[\frac{i}{p_{\mu} \gamma^{\mu} - M + i0^\dagger} \right]_{ll'} = \frac{x}{y}$$



场的收缩：

$$\psi(x) = \sum \int \frac{d^3 p}{(2\pi)^{3/2}} [e^{-ip \cdot x} u(\vec{p}, \sigma) a(\vec{p}, \sigma) + e^{ip \cdot x} v(\vec{p}, \sigma) a^{\dagger}(\vec{p}, \sigma)]$$

$$\psi_l(x)\psi_{l'}(x') = (\Phi_0, \mathbf{T}(\psi_l(x)\psi_{l'}(x'))\Phi_0) = \theta(t-t')[\psi_l^+(x), \psi_{l'}^-(x')]_\mp \pm \theta(t'-t)[\psi_{l'}^+(x'), \psi_l^-(x)]_\mp$$

$$\text{有质矢量场: } u^\mu(\vec{p}, \sigma) = v^{\mu*}(\vec{p}, \sigma) = (2p^0)^{-1/2} e^\mu(\vec{p}, \sigma) \quad e^\mu(\vec{p}, \sigma) \equiv L_\nu^\mu(\vec{p}) e^\nu(0, \sigma)$$

$$\begin{aligned}
v^\mu(x)v^{\nu\dagger}(y) &= \int \frac{d^3p d^3p'}{2(2\pi)^3(\vec{p}^2+M^2)^{1/4}(\vec{p}'^2+M^2)^{1/4}} \sum_{\sigma\sigma'} \{ [e^{-ip\cdot x} e^\mu(\vec{p},\sigma) a(\vec{p},\sigma), e^{ip'\cdot y} e^{\nu*}(\vec{p}',\sigma') a^\dagger(\vec{p}',\sigma')] \\
&\quad + [e^{-ip'\cdot y} e^\nu(\vec{p}',\sigma') a^c(\vec{p}',\sigma'), e^{ip\cdot x} e^\mu(\vec{p},\sigma) a^{c\dagger}(\vec{p},\sigma)] \theta(y^0-x^0) \} \\
&= \int \frac{d^3p e^{i\vec{p}\cdot(\vec{x}-\vec{y})}}{2(2\pi)^3\sqrt{\vec{p}^2+M^2}} \sum_\sigma [e^{-i\sqrt{\vec{p}^2+M^2}(x^0-y^0)} e^\mu(\vec{p},\sigma) e^{\nu*}(\vec{p},\sigma) \theta(x^0-y^0) + e^{i\sqrt{\vec{p}^2+M^2}(x^0-y^0)} e^\nu(-\vec{p},\sigma) e^{\mu*}(-\vec{p},\sigma) \theta(y^0-x^0)] \\
&= \int \frac{d^3p e^{i\vec{p}\cdot(\vec{x}-\vec{y})}}{(2\pi)^3} \int_{-\infty}^{\infty} \frac{dp^0}{2i\pi 2\sqrt{\vec{p}^2+M^2}} e^{-ip^0(x^0-y^0)} \left[-\frac{-g^{\mu\nu} + p^\mu p^\nu/M^2}{p^0 - \sqrt{\vec{p}^2+M^2} + i0^\dagger} + \frac{-g^{\mu\nu} + p^\mu p^\nu/M^2}{p^0 + \sqrt{\vec{p}^2+M^2} - i0^\dagger} \right] \\
&\equiv \int \frac{d^4p}{(2\pi)^4} e^{-ip\cdot(x-y)} \frac{i(-g^{\mu\nu} + p^\mu p^\nu/M^2)}{p^2 - M^2 + i0^\dagger} = \begin{array}{c} x \\ \sim \sim \sim \sim \sim \sim \\ y \end{array}
\end{aligned}$$



约化公式

态之间的编时乘积的格林函数 $(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$
 $U(t, t') = \Omega^{\dagger}(t) \Omega(t')$ $\psi_H(x) = \Omega(t) \psi(x) \Omega^{\dagger}(t)$ $\Psi_{\alpha}^{\pm} = \Omega(\mp\infty) \Phi_{\alpha}$

$$S_{\beta\alpha} = (\Phi_{\beta}, U(\infty, -\infty) \Phi_{\alpha}) = (\Phi_{\beta}, \mathbf{T} e^{-i \int d^4x V(\psi, \pi)} \Phi_{\alpha})$$

$$S_{\beta\alpha}[J] \equiv (\Phi_{\beta}, \mathbf{T} e^{-i \int d^4x V_J(\psi, \pi)} \Phi_{\alpha}) \Leftarrow V_J(\psi, \pi) \equiv V(\psi, \pi) + \psi_l(x) J_l(x)$$

$$\frac{\delta S_{\beta\alpha}[J]}{\delta J_{l_1}(x_1) \delta J_{l_2}(x_2) \cdots \delta J_{l_n}(x_n)} \Big|_{J_l(x)=0} = (-i)^n (\Phi_{\beta}, \mathbf{T} \psi_{l_1}(x_1) \psi_{l_2}(x_2) \cdots \psi_{l_n}(x_n) e^{-i \int d^4x V(\psi, \pi)} \Phi_{\alpha}) \\ = (-i)^n (\Phi_{\beta}, \mathbf{T} \psi_{l_1}(x_1) \psi_{l_2}(x_2) \cdots \psi_{l_n}(x_n) U(\infty, -\infty) \Phi_{\alpha}) \text{ Wick定理 } \underline{\text{所有可能的全部收缩项之和}}$$

$$\stackrel{t_1 \geq t_2 \geq \cdots \geq t_n}{=} (-i)^n (\Phi_{\beta}, U(\infty, t_1) \psi_{l_1}(x_1) U(t_1, t_2) \psi_{l_2}(x_2) U(t_2, t_3) \cdots U(t_{n-1}, t_n) \psi_{l_n}(x_n) U(t_n, -\infty) \Phi_{\alpha}) \\ = (-i)^n (\Phi_{\beta}, \Omega^{\dagger}(\infty) \Omega(t_1) \psi_{l_1}(x_1) \Omega^{\dagger}(t_1) \Omega(t_2) \psi_{l_2}(x_2) \Omega^{\dagger}(t_2) \cdots \Omega(t_n) \psi_{l_n}(x_n) \Omega^{\dagger}(t_n) \Omega(-\infty) \Phi_{\alpha}) \\ = (-i)^n (\Psi_{\beta}^{-}, \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \\ = (-i)^n (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$$



约化公式

编时乘积的格林函数(Ψ_0^- , $\mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+$)

以后会证明: 若已知所有的格林函数, 则就可以得到体系的作用量!

对前 n 个粒子在无穷将来 $t_1, \dots, t_n \rightarrow \infty$, 后 l 个粒子在无穷过去 $t_{n+1}, \dots, t_{n+l} \rightarrow -\infty$ 的情况:

$$\begin{aligned}
 & (\Psi_0^-, \mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) |_{\text{前 } n \text{ 个粒子在无穷将来, 后 } l \text{ 个粒子在无穷过去的情况}} \\
 &= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0) \\
 &\quad \times \sum_{\mathcal{P}_{1,\dots,n}} \sum_{\mathcal{P}_{n+1,\dots,n+l}} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0) \\
 &\quad \times (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)
 \end{aligned}$$

► 编时因子 $\theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0)$ 是不可以被去掉的!

► $(\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) =$
 $(\Psi_0^-, \psi_{H,l_1}(x_1 + a) \cdots \psi_{H,l_n}(x_n + a) \psi_{H,l_{n+1}}(x_{n+1} + a) \cdots \psi_{H,l_{n+l}}(x_{n+l} + a) \Psi_0^+)$



约化公式

编时乘积的格林函数(Ψ_0^- , $\mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+$)

讨论前n个粒子在无穷将来，后l个粒子在无穷过去的情况：

$$(\Psi_0^-, \mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \Big|_{\text{前n个粒子在无穷将来，后l个粒子在无穷过去的情况}}$$

$$\begin{aligned} &= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0) \\ &\times \sum_{\mathcal{P} \atop 1, \dots, n} \sum_{\mathcal{P} \atop n+1, \dots, n+l} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0) \\ &\times (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \end{aligned}$$

$$\begin{aligned} &= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0) \\ &\times \sum_{\mathcal{P} \atop 1, \dots, n} \sum_{\mathcal{P} \atop n+1, \dots, n+l} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0) \\ &\times \int d\gamma d\gamma' (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_\gamma^-)(\Psi_\gamma^+, \Psi_{\gamma'}^+) (\Psi_{\gamma'}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \end{aligned}$$



约化公式

$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$ | 前 n 个粒子在无穷将来, 后 l 个粒子在无穷过去的情况

$$= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0)$$

$$\times \sum_{\mathcal{P} \atop 1, \dots, n} \sum_{\mathcal{P} \atop n+1, \dots, n+l} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0)$$

$$\times \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d\vec{p}_1 \cdots d\vec{p}_{n+l} (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-)$$

$$\times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

$\Psi_0^\pm = \Psi_0$ $\Psi_{\vec{p}, \sigma}^\pm = \Psi_{\vec{p}, \sigma}$ 进态和出态的粒子无穷分离 $\psi_{H,l_i}(x_i) = e^{iP \cdot x_i} \psi_H(0) e^{-iP \cdot x_i}$

$$(\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-) = (\Psi_0, \psi_{H,l_1}(x_1) \Psi_{\vec{p}_1, \sigma_1}^-) \cdots (\Psi_0, \psi_{H,l_n}(x_n) \Psi_{\vec{p}_n, \sigma_n}^-)$$

$$= e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n} (\Psi_0, \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}^-) \cdots (\Psi_0, \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n}^-)$$

$$(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$= (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{H,l_{n+1}}(x_{n+1}) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0)$$

$$= e^{ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{H,l_{n+l}}(0) \Psi_0)$$



约化公式

为什么只考虑n和l粒子的中间态?

$$\begin{aligned}
 & \int d\gamma d\gamma' (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_\gamma^-)(\Psi_\gamma^-, \Psi_{\gamma'}^+) (\Psi_{\gamma'}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \\
 = & \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d\vec{p}_1 \cdots d\vec{p}_{n+l} (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-) \\
 & \times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^+, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \\
 (\Psi_0^-, \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-) &= (\Psi_0, \psi_{H,l_1}(x_1) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0, \psi_{H,l_n}(x_n) \Psi_{\vec{p}_n, \sigma_n}) \\
 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+, \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) &= (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{H,l_{n+1}}(x_{n+1}) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0)
 \end{aligned}$$

♣ 如果考虑 $m > n$ 粒子的中间态: 因子化后会出现真空态与单粒子态的内积,因而为零

♠ 如果考虑 $m < n$ 粒子的中间态: 无穷分离时因子化后的会出现单个场的真空期望值, 因而为零



约化公式

多粒子态的归一化: 记 $\Phi_{p_1, \sigma_1, n; p_2, \sigma_2, n_2; \dots} = \Phi_{p_1, p_2, \dots}$

真空态 Φ_0 和 **单粒子态** Φ_q

$$(\Phi_0, \Phi_0) = 1 \quad (\Phi_{q'}, \Phi_q) = \delta(q' - q) \equiv \delta^3(\vec{q}' - \vec{q}) \delta_{\sigma' \sigma} \delta_{n' n}$$

对两粒子态 $\Phi_{q_1 q_2}(\Phi_{q'_1 q'_2}, \Phi_{q_1 q_2}) = \frac{1}{2!} [\delta(q'_1 - q_1) \delta(q'_2 - q_2) \pm \delta(q'_2 - q_1) \delta(q'_1 - q_2)]$

负号对两个粒子都是费米子的情形,正号对其它情形(两个粒子都是玻色子或一个玻色子一个是费米子).

一般情况: $(\Phi_{q'_1 q'_2 \dots q'_M}, \Phi_{q_1 q_2 \dots q_N}) = \frac{\delta_{MN}}{N!} \sum_{\mathcal{P}} \delta_{\mathcal{P}} \prod_i \delta(q_i - q'_{\mathcal{P}i})$

求和对所有可能的对指标 $1, 2, \dots, N$ 的交换排序 \mathcal{P} 实行. 对交换排序中涉及奇数次费米子交换时, $\delta_{\mathcal{P}} = -1$, 其它情况的交换排序 $\delta_{\mathcal{P}} = 1$.

约定: $(\Phi_{\alpha'}, \Phi_{\alpha}) = \delta(\alpha' - \alpha)$ $\int d\alpha \dots \equiv \sum_{n_1 \sigma_1 n_2 \sigma_2 \dots} \int d\vec{p}_1 \int d\vec{p}_2 \dots$

$$\Phi = \int d\alpha \Phi_{\alpha}(\Phi_{\alpha}, \Phi) \quad 1 = \int d\alpha \Phi_{\alpha})(\Phi_{\alpha} \quad \text{多粒子态构成完备集!}$$



约化公式

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0)$$

$$\times \sum_{\mathcal{P} \atop \substack{1, \dots, n \\ \mathcal{P} \atop n+1, \dots, n+l}} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0)$$

$$\times \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip_1x_1 - \cdots - ip_nx_n + ip_{n+1}x_{n+1} + \cdots + ip_{n+l}x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1}^-, \dots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+, \dots, \vec{p}_{n+l}, \sigma_{n+l}) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+ \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^+ \psi_{H,l_{n+l}}(0) \Psi_0)$$

$$\sum_{\mathcal{P} \atop \substack{1, \dots, n}} \theta(x_1^0 - x_2^0) \cdots \theta(x_{n-1}^0 - x_n^0) = 1 \quad \sum_{\mathcal{P} \atop \substack{n+1, \dots, n+l}} \theta(x_{n+1}^0 - x_{n+2}^0) \cdots \theta(x_{n+l-1}^0 - x_{n+l}^0) = 1$$

$$= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0)$$

$$\times \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip_1x_1 - \cdots - ip_nx_n + ip_{n+1}x_{n+1} + \cdots + ip_{n+l}x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1}^-, \dots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+, \dots, \vec{p}_{n+l}, \sigma_{n+l}) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+ \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^+ \psi_{H,l_{n+l}}(0) \Psi_0)$$



约化公式

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \theta(x_1^0) \cdots \theta(x_n^0) \theta(-x_{n+1}^0) \cdots \theta(-x_{n+l}^0)$$

$$\times \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip_1 x_1 - \cdots - ip_n x_n + ip_{n+1} x_{n+1} + \cdots + ip_{n+l} x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1}^-, \cdots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \cdots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^- \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^- \psi_{H,l_{n+l}}(0) \Psi_0)$$

$$\theta(x_i^0 - x_{i+1}^0) = -\frac{1}{2i\pi} \int_{-\infty}^{\infty} d\omega_i \frac{e^{-i\omega_i(x_i^0 - x_{i+1}^0)}}{\omega_i + i0^+}$$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int_{-\infty}^{\infty} d\omega_1 \cdots d\omega_{n+l} \frac{e^{-i\omega_1 x_1^0 - \cdots - i\omega_n x_n^0 + i\omega_{n+1} x_{n+1}^0 + \cdots + i\omega_{n+l} x_{n+l}^0}}{(\omega_1 + i0^+) \cdots (\omega_{n+l} + i0^+)}$$

$$\times \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip_1 x_1 - \cdots - ip_n x_n + ip_{n+1} x_{n+1} + \cdots + ip_{n+l} x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1}^-, \cdots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \cdots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^- \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^- \psi_{H,l_{n+l}}(0) \Psi_0)$$



约化公式

$$(\Psi_0^-, \mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) |_{\text{前} n \text{个粒子在无穷将来, 后} l \text{个粒子在无穷过去的情况}}$$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int_{-\infty}^{\infty} \frac{d\omega_1 \cdots d\omega_{n+l} e^{-i\omega_1 x_1^0 - \cdots - i\omega_n x_n^0 + i\omega_{n+1} x_{n+1}^0 + \cdots + i\omega_{n+l} x_{n+l}^0}} {(\omega_1 + i0^+) \cdots (\omega_{n+l} + i0^+)}$$

$$\times \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}^+) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n}^+) \\ \times (\Psi_{\vec{p}_1, \sigma_1}^+, \dots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+, \dots, \vec{p}_{n+l}, \sigma_{n+l}) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^- \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^- \psi_{H,l_{n+l}}(0) \Psi_0)$$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int_{-\infty}^{\infty} \frac{d\omega_1 \cdots d\omega_{n+l}} {(\omega_1 + i0^+) \cdots (\omega_{n+l} + i0^+)}$$

$$\times \int d\vec{p}'_1 \cdots d\vec{p}'_{n+l} e^{-ip'_1 \cdot x_1 - \cdots - ip'_n \cdot x_n + ip'_{n+1} \cdot x_{n+1} + \cdots + ip'_{n+l} \cdot x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}^+) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n}^+) \\ \times (\Psi_{\vec{p}_1, \sigma_1}^+, \dots, \vec{p}_n, \sigma_n, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^+, \dots, \vec{p}_{n+l}, \sigma_{n+l}) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^- \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^- \psi_{H,l_{n+l}}(0) \Psi_0)$$

$$\vec{p}'_i = \vec{p}_i \quad i = 1, 2, \dots, n+l$$

$$p_i^{0'} = \sqrt{\vec{p}_i^2 + M_i^2} + \omega_i \quad i = 1, 2, \dots, n+l$$



约化公式

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int_{-\infty}^{\infty} \frac{d\omega_1 \cdots d\omega_{n+l}}{(\omega_1 + i0^+) \cdots (\omega_{n+l} + i0^+)}$$

$$\times \int d\vec{p}_1 \cdots d\vec{p}_{n+l} e^{-ip'_1 \cdot x_1 - \cdots - ip'_n \cdot x_n + ip'_{n+1} \cdot x_{n+1} + \cdots + ip'_{n+l} \cdot x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}} \psi_{H,l_{n+1}}(0) \Psi_0) \cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}} \psi_{H,l_{n+l}}(0) \Psi_0)$$

$$\vec{p}'_i = \vec{p}_i \quad i = 1, 2, \dots, n+l$$

$$p_i^{0'} = \sqrt{\vec{p}_i^2 + M_i^2} + \omega_i \quad i = 1, 2, \dots, n+l$$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d^4 p_1 \cdots d^4 p_{n+l} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1})$$

$$\cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n}) (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}} \psi_{H,l_{n+1}}(0) \Psi_0)$$

$$\cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}} \psi_{H,l_{n+l}}(0) \Psi_0) (p_1^0 - \sqrt{\vec{p}_1^2 + M_1^2} + i0^+)^{-1} \cdots (p_{n+l}^0 - \sqrt{\vec{p}_{n+l}^2 + M_{n+l}^2} + i0^+)^{-1}$$



约化公式

$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+)|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$

$$= \frac{(-1)^{n+l}}{(2i\pi)^{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \int d^4 p_1 \cdots d^4 p_{n+l} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} (\Psi_0^- \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1})$$

$$\cdots (\Psi_0^- \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n}) (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}^- \psi_{H,l_{n+1}}(0) \Psi_0)$$

$$\cdots (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}^- \psi_{H,l_{n+l}}(0) \Psi_0) (p_1^0 - \sqrt{\vec{p}_1^2 + M_1^2} + i0^+)^{-1} \cdots (p_{n+l}^0 - \sqrt{\vec{p}_{n+l}^2 + M_{n+l}^2} + i0^+)^{-1}$$

$$\frac{1}{(p^0 - \sqrt{\vec{p}^2 + M^2} + i0^+)} = \frac{(p^0 + \sqrt{\vec{p}^2 + M^2} - i0^+)}{(p^0)^2 - (\vec{p}^2 + M^2 - i0^+)} = \frac{2\sqrt{\vec{p}^2 + M^2}}{p^2 - M^2 + i0^+} + \text{非极点项}$$

$$= \int \frac{d^4 p_1}{(2\pi)^4} \cdots \frac{d^4 p_{n+l}}{(2\pi)^4} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ \frac{2i(2\pi)^3 p_1^0 (\Psi_0, \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1})}{p_1^2 - M_1^2 + i0^+}$$

$$\cdots \frac{2i(2\pi)^3 p_n^0 (\Psi_0, \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})}{p_n^2 - M_n^2 + i0^+} (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+)$$

$$\times \frac{2i(2\pi)^3 p_{n+1}^0 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{H,l_{n+1}}(0) \Psi_0)}{p_{n+1}^2 - M_{n+1}^2 + i0^+} \cdots \frac{2i(2\pi)^3 p_{n+l}^0 (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{H,l_{n+l}}(0) \Psi_0)}{p_{n+l}^2 - M_{n+l}^2 + i0^+} + \text{非物理极点项} \right\}$$



约化公式

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \int \frac{d^4 p_1}{(2\pi)^4} \cdots \frac{d^4 p_{n+l}}{(2\pi)^4} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ \frac{2i(2\pi)^3 p_1^0 (\Psi_0, \psi_{H,l_1}(0) \Psi_{\vec{p}_1, \sigma_1})}{p_1^2 - M_1^2 + i0^+} \right.$$

$$\cdots \frac{2i(2\pi)^3 p_n^0 (\Psi_0, \psi_{H,l_n}(0) \Psi_{\vec{p}_n, \sigma_n})}{p_n^2 - M_n^2 + i0^+} (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+)$$

$$\times \frac{2i(2\pi)^3 p_{n+1}^0 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{H,l_{n+1}}(0) \Psi_0)}{p_{n+1}^2 - M_{n+1}^2 + i0^+} \cdots \frac{2i(2\pi)^3 p_{n+l}^0 (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{H,l_{n+l}}(0) \Psi_0)}{p_{n+l}^2 - M_{n+l}^2 + i0^+} + \text{非物理极点项} \Big\}$$

$$= \int \frac{d^4 p_1}{(2\pi)^4} \cdots \frac{d^4 p_{n+l}}{(2\pi)^4} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ \frac{2i(2\pi)^3 p_1^0 (\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1})}{p_1^2 - M_1^2 + i0^+} \right.$$

$$\cdots \frac{2i(2\pi)^3 p_n^0 (\Psi_0, \psi_{l_n}(0) \Psi_{\vec{p}_n, \sigma_n})}{p_n^2 - M_n^2 + i0^+} (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) \quad \text{去掉了下标H!}$$

$$\times \frac{2i(2\pi)^3 p_{n+1}^0 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0)}{p_{n+1}^2 - M_{n+1}^2 + i0^+} \cdots \frac{2i(2\pi)^3 p_{n+l}^0 (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{n+l}(0) \Psi_0)}{p_{n+l}^2 - M_{n+l}^2 + i0^+} + \text{非物理极点项} \Big\}$$



约化公式

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \int \frac{d^4 p_1}{(2\pi)^4} \cdots \frac{d^4 p_{n+l}}{(2\pi)^4} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ \frac{2i(2\pi)^3 p_1^0 (\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1})}{p_1^2 - M_1^2 + i0^+} \right. \\ \cdots \frac{2i(2\pi)^3 p_n^0 (\Psi_0, \psi_{l_n}(0) \Psi_{\vec{p}_n, \sigma_n})}{p_n^2 - M_n^2 + i0^+} (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) \\ \times \frac{2i(2\pi)^3 p_{n+1}^0 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0)}{p_{n+1}^2 - M_{n+1}^2 + i0^+} \cdots \frac{2i(2\pi)^3 p_{n+l}^0 (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0) \Psi_0)}{p_{n+l}^2 - M_{n+l}^2 + i0^+} \left. + \text{非物理极点项} \right\}$$

$$(\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l})\Psi_0^+) \Big|_{\text{前}n\text{个粒子在无穷将来, 后}l\text{个粒子在无穷过去的情况}}$$

$$= \int \frac{d^4 p_1 \cdots d^4 p_{n+l}}{(i\pi)^{n+l}} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} + \cdots + ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ p_1^0 (\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots p_n^0 (\Psi_0, \psi_{l_n}(0) \Psi_{\vec{p}_n, \sigma_n}) \right.$$

$$\times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) p_{n+1}^0 (\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0) \cdots p_{n+l}^0 (\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0) \Psi_0)$$

$$+ \text{物理零点项} \Big\}$$



约化公式

$$\begin{aligned}
 & (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) |_{\text{前 } n \text{ 个粒子在无穷将来, 后 } l \text{ 个粒子在无穷过去的情况}} \\
 & = \int \frac{d^4 p_1 \cdots d^4 p_{n+l}}{(i\pi)^{n+l}} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n + ip_{n+1} \cdot x_{n+1} - \cdots - ip_{n+l} \cdot x_{n+l}} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ p_1^0(\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots p_{n+l}^0(\Psi_0, \psi_{l_{n+l}}(0) \Psi_{\vec{p}_{n+l}, \sigma_{n+l}}) \right. \\
 & \times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) p_{n+l}^0(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0) \Psi_0) \\
 & \left. + \text{物理零点项} \right\}
 \end{aligned}$$

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

不再要求 前 n 个粒子在无穷将来, 后 l 个粒子在无穷过去

$$\equiv \int \frac{d^4 p_1 \cdots d^4 p_{n+l}}{(2\pi)^{4n+4l}} e^{-ip_1 \cdot x_1 - \cdots - ip_n \cdot x_n - ip_{n+1} \cdot x_{n+1} - \cdots - ip_{n+l} \cdot x_{n+l}} G_{00}(p_1, \dots, p_n, p_{n+1}, \dots, p_{n+l})$$

$$(-p_1^2 + M_1^2) \cdots (-p_{n+l}^2 + M_{n+l}^2) G_{00}(p_1, \dots, p_n, -p_{n+1}, \dots, -p_{n+l})$$

$$\begin{aligned}
 & = (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ p_1^0(\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots p_{n+l}^0(\Psi_0, \psi_{l_{n+l}}(0) \Psi_{\vec{p}_{n+l}, \sigma_{n+l}}) (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) \right. \\
 & \left. \times p_{n+l}^0(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0) \Psi_0) + \text{物理零点项} \right\}
 \end{aligned}$$



约化公式

$$\begin{aligned}
 & (-p_1^2 + M_1^2) \cdots (-p_{n+l}^2 + M_{n+l}^2) G_{00}(p_1, \dots, p_n, -p_{n+1}, \dots, -p_{n+l}) \\
 & = (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}} \left\{ p_1^0(\Psi_0, \psi_{l_1}(0)\Psi_{\vec{p}_1, \sigma_1}) \cdots p_n^0(\Psi_0, \psi_{l_n}(0)\Psi_{\vec{p}_n, \sigma_n}) (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) \right. \\
 & \quad \left. \times p_{n+1}^0(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0)\Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0)\Psi_0) + \text{物理零点项} \right\} \\
 & = \int d^4x_1 \cdots d^4x_{n+l} e^{ip_1 \cdot x_1 + \dots + ip_n \cdot x_n - ip_{n+1} \cdot x_{n+1} - \dots - ip_{n+l} \cdot x_{n+l}} \times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) \\
 & \quad \times (\Psi_0^-, \mathbf{T}\psi_{H, l_1}(x_1) \cdots \psi_{H, l_{n+l}}(x_{n+l})\Psi_0^+) \\
 & \lim_{p_i^2 \rightarrow M_i^2} \int d^4x_1 \cdots d^4x_{n+l} e^{ip_1 \cdot x_1 + \dots + ip_n \cdot x_n - ip_{n+1} \cdot x_{n+1} - \dots - ip_{n+l} \cdot x_{n+l}} \times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) \\
 & \quad \times (\Psi_0^-, \mathbf{T}\psi_{H, l_1}(x_1) \cdots \psi_{H, l_{n+l}}(x_{n+l})\Psi_0^+) \\
 & = (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}} p_1^0(\Psi_0, \psi_{l_1}(0)\Psi_{\vec{p}_1, \sigma_1}) \cdots p_n^0(\Psi_0, \psi_{l_n}(0)\Psi_{\vec{p}_n, \sigma_n}) \\
 & \quad \times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) p_{n+1}^0(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0)\Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{q}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0)\Psi_0)
 \end{aligned}$$



约化公式

$$\int d^4x_1 \cdots d^4x_{n+l} e^{ip_1 \cdot x_1 + \cdots + ip_n \cdot x_n - ip_{n+1} \cdot x_{n+1} - \cdots - ip_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2)$$

$$\times (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$= (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}} \textcolor{blue}{p_1^0}(\Psi_0, \psi_{l_1}(0) \Psi_{\vec{p}_1, \sigma_1}) \cdots p_n^0(\Psi_0, \psi_{l_n}(0) \Psi_{\vec{p}_n, \sigma_n})$$

$$\times (\Psi_{\vec{p}_1, \sigma_1, \dots, \vec{p}_n, \sigma_n}^-, \Psi_{\vec{p}_{n+1}, \sigma_{n+1}, \dots, \vec{p}_{n+l}, \sigma_{n+l}}^+) \textcolor{blue}{p_{n+1}^0}(\Psi_{\vec{p}_{n+1}, \sigma_{n+1}}, \psi_{l_{n+1}}(0) \Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \psi_{l_{n+l}}(0) \Psi_0)$$

实标量场: $\phi(x) = \int \frac{d^3p}{(2\pi)^{3/2} \sqrt{2p^0}} [e^{-ip \cdot x} a(\vec{p}) + e^{ip \cdot x} a^\dagger(\vec{p})] \quad a(\vec{p}) \Phi_{\vec{q}} = \delta(p - q) \Phi_0$

$$a(\vec{p}) \Psi_{\vec{q}} = Z_\phi \delta(p - q) \Psi_0 \quad (2\pi)^{3/2} \sqrt{2q^0} (\Psi_0, \phi(0) \Psi_{\vec{q}}) = Z_\phi \quad \textcolor{blue}{Z_\phi = 0} \text{ 束缚态}$$

$$(\Psi_{\vec{q}_1, \dots, \vec{q}_n}^-, \Psi_{\vec{q}_{n+1}, \dots, \vec{q}_{n+l}}^+)$$

$$= \frac{i^{n+l}}{(2\pi)^{3(n+l)/2} Z_\phi^{n+l} \sqrt{2q_1^0 \cdots 2q_{n+l}^0}} \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n \cdot x_n - iq_{n+1} \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}}$$

$$\times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\phi_H(x_1) \cdots \phi_H(x_{n+l}) \Psi_0^+)$$



约化公式

$$\text{复标量场: } \phi(x) = \int \frac{d^3 p}{(2\pi)^{3/2} \sqrt{2p^0}} [e^{-ip \cdot x} a(\vec{p}) + e^{ip \cdot x} a^{\dagger}(\vec{p})]$$

$$\int d^4 x_1 \cdots d^4 x_{n+l} e^{ip_1 \cdot x_1 + \cdots + ip_n^c \cdot x_n - ip_{n+1}^c \cdot x_{n+1} - \cdots - ip_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^- , \mathbf{T}\phi_H(x_1) \cdots$$

$$\phi_H(x_{n'}) \phi_H^\dagger(x_{n'+1}) \cdots \phi_H^\dagger(x_n) \phi_H(x_{n+1}) \cdots \phi_H(x_{n+l'}) \phi_H^\dagger(x_{n+l'+1}) \cdots \phi_H^\dagger(x_{n+l}) \Psi_0^+)$$

$$= (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}} p_1^0(\Psi_0, \phi(0)\Psi_{\vec{p}_1}) \cdots p_n^0(\Psi_0, \phi(0)\Psi_{\vec{p}_n}) p_{n+1}^{c0}(\Psi_0, \phi^\dagger(0)\Psi_{\vec{p}_{n+1}^c}) \cdots p_n^{c0}(\Psi_0, \phi^\dagger(0)\Psi_{\vec{p}_n^c})$$

$$\times (\Psi_{\vec{p}_1, \dots, \vec{p}_n, \vec{p}_{n+1}^c, \dots, \vec{p}_n^c}^+, \Psi_{\vec{p}_{n+1}, \dots, \vec{p}_{n+l'}, \vec{p}_{n+l'+1}, \dots, \vec{p}_{n+l}}^+) p_{n+1}^{c0}(\Psi_{\vec{p}_{n+1}^c}, \phi(0)\Psi_0) \cdots p_{n+l'}^{c0}(\Psi_{\vec{p}_{n+l'}^c}, \phi(0)\Psi_0)$$

$$\times p_{n+l'+1}^0(\Psi_{\vec{p}_{n+l'+1}}, \phi^\dagger(0)\Psi_0) \cdots p_{n+l}^0(\Psi_{\vec{p}_{n+l}, \sigma_{n+l}}, \phi^\dagger(0)\Psi_0)$$

$$a(\vec{p})\Psi_{\vec{q}} = Z_\phi \delta(p - q)\Psi_0 \quad (2\pi)^{3/2} \sqrt{2q^0}(\Psi_0, \phi(0)\Psi_{\vec{q}}) = (2\pi)^{3/2} \sqrt{2q^0}(\Psi_{\vec{q}}, \phi^\dagger(0)\Psi_0) = Z_\phi$$

$$a^c(\vec{p})\Psi_{\vec{q}^c} = Z_\phi \delta(p - q^c)\Psi_0 \quad (2\pi)^{3/2} \sqrt{2q^{c0}}(\Psi_0, \phi^\dagger(0)\Psi_{\vec{q}^c}) = (2\pi)^{3/2} \sqrt{2q^{c0}}(\Psi_{\vec{q}^c}, \phi(0)\Psi_0) = Z_\phi$$

$$(\Psi_{\vec{q}_1, \dots, \vec{q}_n, \vec{q}_{n+1}^c, \dots, \vec{q}_n^c}^+, \Psi_{\vec{q}_{n+1}, \dots, \vec{q}_{n+l'}, \vec{q}_{n+l'+1}, \dots, \vec{q}_{n+l}}^+) = \frac{[i/(2\pi)^{3/2} \sqrt{2}]^{n+l}}{Z_\phi^{n+l} \sqrt{q_1^0 \cdots q_n^0 q_{n+1}^{c0} \cdots q_{n+l}^0}} \int d^4 x_1 \cdots d^4 x_{n+l}$$

$$\times e^{iq_1 x_1 + \cdots + iq_{n+l} x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\phi_H(x_1) \cdots \phi_H^\dagger(x_n) \phi_H(x_{n+1}) \cdots \phi_H^\dagger(x_{n+l}) \Psi_0^+)$$



约化公式

$$\int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_{n'}}(x_{n'}) \bar{\psi}_{H,l_{n'+1}}(x_{n'+1}) \cdots \bar{\psi}_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \psi_{H,l_{n+l'}}(x_{n+l'}) \bar{\psi}_{H,l_{n+l'+1}}(x_{n+l'+1}) \cdots \bar{\psi}_{H,l_{n+l}}(x_{n+l}) \Psi_0^+) \\ = (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_n^c \sigma_{n+1}^c \cdots \sigma_{n+l}} q_1^0(\Psi_0, \psi_{l_1}(0)\Psi_{\vec{q}_1, \sigma_1}) \cdots q_n^0(\Psi_0, \bar{\psi}_{l_n}(0)\Psi_{\vec{q}_n^c, \sigma_n^c}) \\ \times (\Psi_{\vec{q}_1, \sigma_1}^-, \dots, \vec{q}_n^c, \sigma_n^c, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c}^+, \dots, \vec{q}_{n+l}, \sigma_{n+l}^c) q_{n+1}^0(\Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c}, \psi_{n+1}(0)\Psi_0) \cdots q_{n+l}^0(\Psi_{\vec{q}_{n+l}, \sigma_{n+l}^c}, \bar{\psi}_{l_{n+l}}(0)\Psi_0)$$

旋量场: $\psi_l(x) = (2\pi)^{-3/2} \sum_{\sigma} \int d\vec{p} [u_l(\vec{p}, \sigma) e^{-ip \cdot x} a(\vec{p}, \sigma) + v_l(\vec{p}, \sigma) e^{ip \cdot x} a^{\dagger}(\vec{p}, \sigma)]$

$$\bar{\psi}_l(x) = (2\pi)^{-3/2} \sum_{\sigma} \int d\vec{p} [\bar{u}_l(\vec{p}, \sigma) e^{ip \cdot x} a^{\dagger}(\vec{p}, \sigma) + \bar{v}_l(\vec{p}, \sigma) e^{-ip \cdot x} a^c(\vec{p}, \sigma)]$$

$$a(\vec{p})\Psi_{\vec{q}} = Z_{\psi} \delta(p - q) \Psi_0$$

$$a^c(\vec{p})\Psi_{\vec{q}^c} = Z_{\psi} \delta(p - q^c) \Psi_0$$

$$(2\pi)^{3/2}(\Psi_0, \psi_l(0)\Psi_{\vec{q}, \sigma}) = Z_{\psi} u_l(\vec{q}, \sigma)$$

$$(2\pi)^{3/2}(\Psi_{\vec{q}, \sigma}, \bar{\psi}_l(0)\Psi_0) = Z_{\psi} \bar{u}_l(\vec{q}, \sigma)$$

$$(2\pi)^{3/2}(\Psi_0, \bar{\psi}_l(0)\Psi_{\vec{q}^c, \sigma^c}) = Z_{\psi} \bar{v}_l(\vec{q}^c, \sigma^c)$$

$$(2\pi)^{3/2}(\Psi_{\vec{q}^c, \sigma^c}, \psi_l(0)\Psi_0) = Z_{\psi} v_l(\vec{q}^c, \sigma^c)$$



约化公式

$$\int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} \cdots - iq_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2)$$

$$\times (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \bar{\psi}_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \bar{\psi}_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$=(-2^{5/2} i\pi^{3/2})^{n+l} Z_\psi^{n+l} q_1^0 \cdots q_n^{c0} q_{n+1}^{c0} \cdots q_{n+l}^0 \sum_{\sigma_1 \cdots \sigma_n^c \sigma_{n+1}^c \cdots \sigma_{n+l}} u_{l_1}(\vec{q}_1, \sigma_1) \cdots \bar{v}_{l_n}(\vec{q}_n, \sigma_n^c)$$

$$\times (\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_n, \sigma_n^c}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+) v_{l_{n+1}}(\vec{q}_{n+1}, \sigma_{n+1}^c) \cdots \bar{u}_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l})$$

$$u(\vec{p}, \sigma) = \sqrt{M/p^0} D(L(p)) u(0, \sigma) \quad v(\vec{p}, \sigma) = \sqrt{M/p^0} D(L(p)) v(0, \sigma) \quad D(L(p)) \beta D^\dagger(L(p)) = \beta$$

$$\beta = \gamma^0 = \begin{pmatrix} 0 & -I \\ -I & 0 \end{pmatrix} \quad u(0, \frac{1}{2}) = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{-1}{\sqrt{2}} \\ 0 \end{bmatrix} \quad u(0, -\frac{1}{2}) = \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ 0 \\ \frac{-1}{\sqrt{2}} \end{bmatrix} \quad v(0, \frac{1}{2}) = \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \quad v(0, -\frac{1}{2}) = \begin{bmatrix} \frac{-1}{\sqrt{2}} \\ 0 \\ \frac{-1}{\sqrt{2}} \\ 0 \end{bmatrix}$$

$$\bar{u}(\vec{p}, \sigma) u(\vec{p}, \sigma') = \frac{M}{p^0} \bar{u}(0, \sigma) \beta D^\dagger(L(p)) \beta D(L(p)) u(0, \sigma') = \frac{M}{p^0} \bar{u}(0, \sigma) u(0, \sigma') = \frac{M}{p^0} \delta_{\sigma \sigma'}$$

$$\bar{v}(\vec{p}, \sigma) v(\vec{p}, \sigma') = \frac{M}{p^0} \bar{v}(0, \sigma) \beta D^\dagger(L(p)) \beta D(L(p)) v(0, \sigma') = \frac{M}{p^0} \bar{v}(0, \sigma) v(0, \sigma') = -\frac{M}{p^0} \delta_{\sigma \sigma'}$$



约化公式

$$(\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_n, \sigma_n^c}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+)$$

$$= (-1)^{-n'+l'-l} (2^{5/2} i\pi^{3/2})^{-n-l} Z_\psi^{-n-l} (M_1 \cdots M_{n+l})^{-1} \bar{u}_{l_1}(\vec{q}_1, \sigma_1) \cdots v_{l_n}(\vec{q}_n^c, \sigma_n^c) \\ \times \bar{v}_{l_{n+1}}(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots u_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l}) \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} \\ \times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \bar{\psi}_{H,l_n}(x_n) \psi_{H,l_{n+1}}(x_{n+1}) \cdots \bar{\psi}_{H,l_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$= (-1)^{-n'+l'-l} (2^{5/2} i\pi^{3/2})^{-n-l} Z_\psi^{-n-l} (M_1 \cdots M_{n+l})^{-1} \bar{u}_{l_1}(\vec{q}_1, \sigma_1) \cdots v_{l_n}(\vec{q}_n^c, \sigma_n^c) \\ \times \bar{v}_{l_{n+1}}(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots u_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l}) \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} \\ \times [(-i\partial_{x_1} - M_1)(i\partial_{x_1} - M_1)]_{l_1 \bar{l}_1} \cdots [(-i\partial_{x_n} - M_n)(i\partial_{x_n} - M_n)]_{\bar{l}_n l_n} [(-i\partial_{x_{n+1}} - M_{n+1})(i\partial_{x_{n+1}} - M_{n+1})]_{l_{n+1} \bar{l}_{n+1}} \\ \cdots [(-i\partial_{x_{n+l}} - M_{n+l})(i\partial_{x_{n+l}} - M_{n+l})]_{\bar{l}_{n+l} l_{n+l}} (\Psi_0^-, \mathbf{T}\psi_{H,\bar{l}_1}(x_1) \cdots \bar{\psi}_{H,\bar{l}_n}(x_n) \psi_{H,\bar{l}_{n+1}}(x_{n+1}) \cdots \psi_{H,\bar{l}_{n+l}}(x_{n+l}) \Psi_0^+)$$



约化公式

$$(\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_n, \sigma_n}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+)$$

$$= (-1)^{-n'+l'-l} (2^{5/2} i\pi^{3/2})^{-n-l} Z_\psi^{-n-l} (M_1 \cdots M_{n+l})^{-1} \bar{u}_{l_1}(\vec{q}_1, \sigma_1) \cdots v_{l_n}(\vec{q}_n, \sigma_n)$$

$$\times \bar{v}_{l_{n+1}}(\vec{q}_{n+1}, \sigma_{n+1}) \cdots u_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l}) \int d^4 x_1 \cdots d^4 x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}}$$

$$\times [(-i\partial_{x_1} - M_1)(i\partial_{x_1} - M_1)]_{l_1 \bar{l}_1} \cdots [(-i\partial_{x_n} - M_n)(i\partial_{x_n} - M_n)]_{l_n \bar{l}_n} [(-i\partial_{x_{n+1}} - M_{n+1})(i\partial_{x_{n+1}} - M_{n+1})]_{l_{n+1} \bar{l}_{n+1}}$$

$$\cdots [(-i\partial_{x_{n+l}} - M_{n+l})(i\partial_{x_{n+l}} - M_{n+l})]_{l_{n+l} \bar{l}_{n+l}} (\Psi_0^-, \mathbf{T}\psi_{H, \bar{l}_1}(x_1) \cdots \bar{\psi}_{H, \bar{l}_n}(x_n) \psi_{H, \bar{l}_{n+1}}(x_{n+1}) \cdots \psi_{H, \bar{l}_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$= (-1)^{-n'+l'-l} (2^{5/2} i\pi^{3/2})^{-n-l} Z_\psi^{-n-l} (M_1 \cdots M_{n+l})^{-1} \bar{u}_{l_1}(\vec{q}_1, \sigma_1) \cdots v_{l_n}(\vec{q}_n, \sigma_n)$$

$$\times \bar{v}_{l_{n+1}}(\vec{q}_{n+1}, \sigma_{n+1}) \cdots u_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l}) \int d^4 x_1 \cdots d^4 x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}}$$

$$\times [(-\not{q}_1 - M_1)(i\partial_{x_1} - M_1)]_{l_1 \bar{l}_1} \cdots [(-i\partial_{x_n} - M_n)(\not{q}_n^c - M_n)]_{l_n \bar{l}_n} [(\not{q}_{n+1}^c - M_{n+1})(i\partial_{x_{n+1}} - M_{n+1})]_{l_{n+1} \bar{l}_{n+1}}$$

$$\cdots [(-i\partial_{x_{n+l}} - M_{n+l})(-\not{q}_{n+l} - M_{n+l})]_{l_{n+l} \bar{l}_{n+l}} (\Psi_0^-, \mathbf{T}\psi_{H, \bar{l}_1}(x_1) \cdots \bar{\psi}_{H, \bar{l}_n}(x_n) \psi_{H, \bar{l}_{n+1}}(x_{n+1}) \cdots \psi_{H, \bar{l}_{n+l}}(x_{n+l}) \Psi_0^+)$$

$$(\not{q}_{n+l} - M_{n+l})u(\vec{q}_{n+l}, \sigma_{n+l}) = 0 \quad \bar{u}(\vec{q}_1, \sigma)(\not{q}_1 - M_1) = 0 \quad (\not{q}_n^c + M_n)v(\vec{q}_n, \sigma_n^c) = 0 \quad \bar{v}(\vec{q}_{n+1}, \sigma_{n+1})(\not{q}_{n+1}^c + M_{n+1}) = 0$$



约化公式

$$(\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_{n'}, \sigma_{n'}, \vec{q}_{n'+1}^c, \sigma_{n'+1}^c, \dots, \vec{q}_n^c, \sigma_n^c}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c, \dots, \vec{q}_{n+l'}^c, \sigma_{n+l'}^c, \vec{q}_{n+l'+1}, \sigma_{n+l'+1}, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+)$$

$$= (-1)^{-n'+l'-l} [(2\pi)^{\frac{3}{2}} l]^{-n-l} Z_\psi^{-n-l} \bar{u}_{l_1}(\vec{q}_1, \sigma_1) \cdots \bar{u}_{l_{n'}}(\vec{q}_{n'}, \sigma_{n'}) v_{l_{n'+1}}(\vec{q}_{n'+1}^c, \sigma_{n'+1}^c) \cdots v_{l_n}(\vec{q}_n^c, \sigma_n^c)$$

$$\times \bar{v}_{l_{n+1}}(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots \bar{v}_{l_{n+l'}}(\vec{q}_{n+l'}^c, \sigma_{n+l'}^c) u_{l_{n+l'+1}}(\vec{q}_{n+l'+1}, \sigma_{n+l'+1}) \cdots u_{l_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l})$$

$$\times \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_{n'} \cdot x_{n'} + iq_{n'+1}^c \cdot x_{n'+1} + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l'}^c \cdot x_{n+l'} - iq_{n+l'+1} \cdot x_{n+l'+1} - \cdots - iq_{n+l} \cdot x_{n+l}}$$

$$\times (i\partial_{x_1} - M_1)_{l_1 \bar{l}_1} \cdots (i\partial_{x_{n'}} - M_{n'})_{l_{n'} \bar{l}_{n'}} (-i\partial_{x_{n'+1}} - M_{n'+1})_{\bar{l}_{n'+1} l_{n'+1}} \cdots (-i\partial_{x_n} - M_n)_{\bar{l}_n l_n}$$

$$\times (i\partial_{x_{n+1}} - M_{n+1})_{l_{n+1} \bar{l}_{n+1}} \cdots (i\partial_{x_{n+l'}} - M_{n+l'})_{l_{n+l'} \bar{l}_{n+l'}} (-i\partial_{x_{n+l'+1}} - M_{n+l'+1})_{\bar{l}_{n+l'+1} l_{n+l'+1}} \cdots (-i\partial_{x_{n+l}} - M_{n+l})_{\bar{l}_{n+l} l_{n+l}}$$

$$\times (\Psi_0^-, \mathbf{T}\psi_{H, \bar{l}_1}(x_1) \cdots \bar{\psi}_{H, \bar{l}_n}(x_n) \psi_{H, \bar{l}_{n+1}}(x_{n+1}) \cdots \bar{\psi}_{H, \bar{l}_{n+l}}(x_{n+l}) \Psi_0^+)$$



约化公式

$$\begin{aligned}
 & \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) \\
 & \times (\Psi_0^-, \mathbf{T} v_{H,\mu_1}(x_1) \cdots v_{H,\mu_n}^\dagger(x_n) v_{H,\mu_{n+1}}(x_{n+1}) \cdots v_{H,\mu_{n+l}}^\dagger(x_{n+l}) \Psi_0^+) \\
 & = (-16i\pi^3)^{n+l} \sum_{\sigma_1 \cdots \sigma_n^c \sigma_{n+1} \cdots \sigma_{n+l}^c} q_1^0(\Psi_0 v_{\mu_1}(0) \Psi_{\vec{q}_1, \sigma_1}) \cdots q_n^0(\Psi_0 v_{\mu_n}(0) \Psi_{\vec{q}_n^c, \sigma_n^c}) \\
 & \times (\Psi_{\vec{q}_1, \sigma_1}^-, \cdots, \vec{q}_n^c, \sigma_n^c, \Psi_{\vec{q}_{n+1}^c, \sigma_{n+1}^c}^+, \cdots, \vec{q}_{n+l}, \sigma_{n+l}) q_{n+1}^0(\Psi_{\vec{q}_{n+1}^c, \sigma_{n+1}^c}^+, v_{\mu_{n+1}}(0) \Psi_0) \cdots q_{n+l}^0(\Psi_{\vec{q}_{n+l}, \sigma_{n+l}}^+, v_{\mu_{n+l}}(0) \Psi_0)
 \end{aligned}$$

矢量场: $v^\mu(x) = (2\pi)^{-3/2} \sum_{\sigma=\pm 1} \int \frac{d\vec{p}}{\sqrt{2p^0}} [e^\mu(\vec{p}, \sigma) a(\vec{p}, \sigma) e^{-ip \cdot x} + e^{\mu*}(\vec{p}, \sigma) a^{*\dagger}(\vec{p}, \sigma) e^{ip \cdot x}]$

$$(2\pi)^{3/2} \sqrt{2q^0} (\Psi_0, v^\mu(0) \Psi_{\vec{q}, \sigma}) = Z e^\mu(\vec{q}, \sigma) \quad (2\pi)^{3/2} \sqrt{2q^{*0}} (\Psi_{\vec{q}^c, \sigma^c}, v^\mu(0) \Psi_0) = Z e^{\mu*}(\vec{q}^c, \sigma^c)$$

$$(2\pi)^{3/2} \sqrt{2q^{*\dagger 0}} (\Psi_0, v^{\mu\dagger}(0) \Psi_{\vec{q}^c, \sigma^c}) = Z e^\mu(\vec{q}^c, \sigma^c) \quad (2\pi)^{3/2} \sqrt{2q^0} (\Psi_{\vec{q}, \sigma}, v^{\mu\dagger}(0) \Psi_0) = Z e^{\mu*}(\vec{q}, \sigma)$$

$$\begin{aligned}
 & \int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} \times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T} v_{H,\mu_1}(x_1) \cdots v_{H,\mu_{n+l}}^\dagger(x_{n+l}) \Psi_0^+) \\
 & = (-4i\pi^{3/2})^{n+l} Z_v^{n+l} \sqrt{q_1^0 \cdots q_{n+l}^0} \sum_{\sigma_1 \cdots \sigma_{n+l}} e_{\mu_1}(\vec{q}_1, \sigma_1) \cdots e_{\mu_n}(\vec{q}_n^c, \sigma_n^c) (\Psi_{\vec{q}_1, \sigma_1}^-, \cdots, \vec{q}_n^c, \sigma_n^c, \Psi_{\vec{q}_{n+1}^c, \sigma_{n+1}^c}^+, \cdots, \vec{q}_{n+l}, \sigma_{n+l}) \\
 & \times e_{\mu_{n+1}}^*(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots e_{\mu_{n+l}}^*(\vec{q}_{n+l}, \sigma_{n+l})
 \end{aligned}$$



约化公式

$$\int d^4x_1 \cdots d^4x_{n+l} e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} \times (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}v_{H\mu_1}(x_1) \cdots v_{H\mu_{n+l}}^\dagger(x_{n+l}) \Psi_0^+)$$

$$= (-4i\pi^{3/2})^{n+l} Z_v^{n+l} \sum_{\sigma_1 \cdots \sigma_{n+l}^c} \sqrt{q_1^0} e_{\mu_1}(\vec{q}_1, \sigma_1) \cdots \sqrt{q_n^0} e_{\mu_n}(\vec{q}_n^c, \sigma_n^c) (\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_n^c, \sigma_n^c}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+)$$

$$\times \sqrt{q_{n+1}^0} e_{\mu_{n+1}}^*(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots \sqrt{q_{n+l}^0} e_{\mu_{n+l}}^*(\vec{q}_{n+l}, \sigma_{n+l})$$

$$(\Psi_{\vec{q}_1, \sigma_1, \dots, \vec{q}_n^c, \sigma_n^c}^-, \Psi_{\vec{q}_{n+1}, \sigma_{n+1}^c, \dots, \vec{q}_{n+l}, \sigma_{n+l}}^+) \quad e^\mu(\vec{p}, \sigma) e_\mu(\vec{p}, \sigma') = -\delta_{\sigma\sigma'} \quad \text{作业28}$$

$$= \frac{e^{\mu_1}(\vec{q}_1, \sigma_1) \cdots e^{\mu_n}(\vec{q}_n^c, \sigma_n^c) e^{*\mu_{n+1}}(\vec{q}_{n+1}^c, \sigma_{n+1}^c) \cdots e^{*\mu_{n+l}}(\vec{q}_{n+l}, \sigma_{n+l})}{(4i\pi^{3/2})^{n+l} Z_v^{n+l} \sqrt{q_1^0} \cdots \sqrt{q_n^0} \sqrt{q_{n+1}^0} \cdots \sqrt{q_{n+l}^0}} \int d^4x_1 \cdots d^4x_{n+l}$$

$$\times e^{iq_1 \cdot x_1 + \cdots + iq_n^c \cdot x_n - iq_{n+1}^c \cdot x_{n+1} - \cdots - iq_{n+l} \cdot x_{n+l}} (\partial_1^2 + M_1^2) \cdots (\partial_{n+l}^2 + M_{n+l}^2) (\Psi_0^-, \mathbf{T}v_{H,\mu_1}(x_1) \cdots v_{H,\mu_{n+l}}^\dagger(x_{n+l}) \Psi_0^+)$$



格林函数的极点

态之间的编时乘积的格林函数($\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,1}(x_1) \psi_{H,2}(x_2) \cdots \psi_{H,n}(x_n) \Psi_{\alpha}^{+}$)

Wick定理: $\mathbf{T}(UV \cdots XYZ) = \mathbf{N}(UV \cdots XYZ)$

无收缩项

$$+ \mathbf{N}(UV \cdots \overbrace{XYZ}) + \cdots + \mathbf{N}(UV \cdots \overbrace{XYZ}) + \quad \text{一次收缩项}$$

$$+ \mathbf{N}(UV \cdots \overbrace{XYZ}) + \cdots \quad \text{二次收缩项}$$

+ ...

$$+ \mathbf{N}(UVW \cdots \overbrace{XYZ}) + \cdots \quad \text{全部收缩项}$$

若T乘积中含N乘积,展开仍成立,但需将各N乘积内部各算符之间的收缩略去.

应用Wick定理: $U(t, t') = \Omega^{\dagger}(t)\Omega(t')$ $\Psi_{\alpha}^{\pm} = \Omega(\mp\infty)\Phi_{\alpha}$

$$(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$$

$$= (\Omega(\infty)\Phi_{\beta}, \mathbf{T} \Omega(t_1)\psi_{l_1}(x_1)U(t_1, t_2)\psi_2(x_2)U(t_2, t_3) \cdots U(t_{n-1}, t_n)\psi_{l_n}(x_n)\Omega^{\dagger}(t_n)\Omega(-\infty)\Phi_{\alpha})$$

$$= (\Phi_{\beta}, \mathbf{T} \psi_{l_1}(x_1)\psi_2(x_2) \cdots \psi_{l_n}(x_n)U(\infty, -\infty)\Phi_{\alpha}) = \text{所有可能的特别收缩项之和}$$

保留下来的正规乘积中的湮灭算符必须正好湮灭 Φ_{α} 态到某个态,产生算符的厄米共轭必须正好湮灭 Φ_{β} 态到同样的态! 特别地,

$$(\Psi_{\beta}^{-}, \Psi_{\alpha}^{+}) = (\Phi_{\beta}, U(\infty, -\infty)\Phi_{\alpha})$$

$$(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) = (\Phi_0, \mathbf{T} \psi_{l_1}(x_1)\psi_2(x_2) \cdots \psi_{l_n}(x_n)U(\infty, -\infty)\Phi_0)$$



格林函数的极点

编时乘积的格林函数($\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}$)

考虑 $x_1^0, \dots, x_r^0 > 0, x_{r+1}^0, \dots, x_n^0 < 0$

$(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$

$$= \theta(\min[x_1^0 \cdots x_r^0] - \max[x_{r+1}^0 \cdots x_n^0]) \Leftarrow \text{这里已把前r个场晚于后n-r个场的要求通过}\theta\text{函数施加进去了}$$

$$\times (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(x_1) \cdots \psi_{H,l_r}(x_r)\} \mathbf{T}\{\psi_{H,l_{r+1}}(x_{r+1}) \cdots \psi_{H,l_n}(x_n)\} \Psi_{\alpha}^{+})$$

$$= \theta(\min[x_1^0 \cdots x_r^0] - \max[x_{r+1}^0 \cdots x_n^0])$$

$$\times \int d\gamma (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(x_1) \cdots \psi_{H,l_r}(x_r)\} \Psi_{\gamma}) (\Psi_{\gamma}, \mathbf{T}\{\psi_{H,l_{r+1}}(x_{r+1}) \cdots \psi_{H,l_n}(x_n)\} \Psi_{\alpha}^{+})$$

= 单粒子中间态项 + 多粒子中间态项

Ψ_{γ} 是一组多粒子态完备集；是 H 的本征态



格林函数的极点

单粒子中间态项: $x_1^0, \dots, x_r^0 > 0, x_{r+1}^0, \dots, x_n^0 < 0$

$$\theta(\min[x_1^0 \dots x_r^0] - \max[x_{r+1}^0 \dots x_n^0])$$

$$\times \sum_{\sigma} \int d\vec{p} (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(x_1) \cdots \psi_{H,l_r}(x_r)\} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(x_{r+1}) \cdots \psi_{H,l_n}(x_n)\} \Psi_{\alpha}^{+})$$

$$\psi_{H,l_i}(x_i) = e^{iP \cdot x_i} \psi_{H,l_i}(0) e^{-iP \cdot x_i} \quad \psi_{H,l_i}(x_i - x) = e^{-iP \cdot x} \psi_{H,l_i}(x_i) e^{iP \cdot x}$$

$$\psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_r}(x_r) = e^{iP \cdot x_1} \psi_{H,l_1}(0) \psi_{H,l_2}(x_2 - x_1) \cdots \psi_{H,l_r}(x_r - x_1) e^{-iP \cdot x_1}$$

$$\psi_{H,l_{r+1}}(x_{r+1}) \psi_{H,l_{r+2}}(x_{r+2}) \cdots \psi_{H,l_n}(x_n) = e^{iP \cdot x_{r+1}} \psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(x_{r+2} - x_{r+1}) \cdots \psi_{H,l_n}(x_n - x_{r+1}) e^{-iP \cdot x_{r+1}}$$

$$e^{-iP \cdot x_1} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} e^{iP \cdot x_{r+1}} = e^{-iP \cdot x_1} \Psi_{\vec{p},\sigma}) (e^{-iP \cdot x_{r+1}} \Psi_{\vec{p},\sigma} = e^{-ip \cdot (x_1 - x_{r+1})} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma}$$

$$= \theta(\min[x_1^0 \dots x_r^0] - \max[x_{r+1}^0 \dots x_n^0])$$

$$\times \sum_{\sigma} \int d\vec{p} e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1}} (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(0) \psi_{H,l_2}(x_2 - x_1) \cdots \psi_{H,l_r}(x_r - x_1)\} \Psi_{\vec{p},\sigma})$$

$$\times (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(x_{r+2} - x_{r+1}) \cdots \psi_{H,l_n}(x_n - x_{r+1})\} \Psi_{\alpha}^{+})$$



格林函数的极点

单粒子中间态项: $x_i = x_1 + y_i$ ($i = 2, 3, \dots, r$) $x_i = x_{r+1} + y_i$ ($i = r+2, \dots, n$)

$$\theta(\min[x_1^0 \cdots x_r^0] - \max[x_{r+1}^0 \cdots x_n^0])$$

$$\times \sum_{\sigma} \int d\vec{p} (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(x_1) \cdots \psi_{H,l_r}(x_r)\} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(x_{r+1}) \cdots \psi_{H,l_n}(x_n)\} \Psi_{\alpha}^{+})$$

$$= \theta(\min[x_1^0 \cdots x_r^0] - \max[x_{r+1}^0 \cdots x_n^0])$$

$$\times \sum_{\sigma} \int d\vec{p} e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1}} (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(0) \psi_{H,l_2}(x_2 - x_1) \cdots \psi_{H,l_r}(x_r - x_1)\} \Psi_{\vec{p},\sigma})$$

$$\times (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(x_{r+2} - x_{r+1}) \cdots \psi_{H,l_n}(x_n - x_{r+1})\} \Psi_{\alpha}^{+})$$

$$\min[x_1^0, \dots, x_r^0] - \max[x_{r+1}^0, \dots, x_n^0] = x_1^0 - x_{r+1}^0 + \min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0]$$

$$= \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])} \quad \theta(\tau) = - \int_{-\infty}^{\infty} \frac{d\omega}{2i\pi} \frac{e^{-i\omega\tau}}{\omega + i0^+}$$

$$\times \sum_{\sigma} \int d\vec{p} (\Psi_{\beta}^{-} \mathbf{T}\{\psi_{H,l_1}(0) \psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_{\alpha}^{+})$$

$$\times e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1} - i\omega(x_1^0 - x_{r+1}^0)}$$



格林函数的极点

$$\begin{aligned}
 & (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \quad x_1^0, \dots, x_r^0 > 0, \quad x_{r+1}^0, \dots, x_n^0 < 0 \\
 & = \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])} e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1} - i\omega(x_1^0 - x_{r+1}^0)} \\
 & \times \sum_{\sigma} \int d\vec{p} (\Psi_{\beta}^{-} \mathbf{T} \{\psi_{H,l_1}(0) \psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{p}\sigma}^{+}) (\Psi_{\vec{p}\sigma} \mathbf{T} \{\psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_{\alpha}^{+}) \\
 & \quad x_i = x_1 + y_i \quad (i = 2, 3, \dots, r) \quad x_i = x_{r+1} + y_i \quad (i = r+2, \dots, n) \\
 & (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) = \int \frac{d^4 q_1 \cdots d^4 q_n}{(2\pi)^{4n}} e^{-iq_1 \cdot x_1 - \cdots - iq_n \cdot x_n} G_{\beta\alpha}(q_1, \dots, q_n) \\
 & \quad -i(q_1 \cdot x_1 + \cdots + q_n \cdot x_n) \\
 & = -i[(q_1 + \cdots + q_r) \cdot x_1 + (q_{r+1} + \cdots + q_n) \cdot x_{r+1} + q_2 \cdot y_2 + \cdots + q_r \cdot y_r + q_{r+2} \cdot y_{r+2} + \cdots + q_n \cdot y_n] \\
 & (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \quad \tilde{q}_1 \equiv q_1 + \cdots + q_r \quad \tilde{q}_{r+1} \equiv q_{r+1} + \cdots + q_n \\
 & = \int \frac{d^4 \tilde{q}_1 d^4 \tilde{q}_{r+1} d^4 q_2 \cdots d^4 q_r d^4 q_{r+2} \cdots d^4 q_n}{(2\pi)^{4n}} e^{-i\tilde{q}_1 \cdot x_1 - i\tilde{q}_{r+1} \cdot x_{r+1} - iq_2 \cdot y_2 - \cdots - iq_r \cdot y_r - iq_{r+2} \cdot y_{r+2} - \cdots - iq_n \cdot y_n} \\
 & \quad \times G_{\beta\alpha}(q_1, \dots, q_n)
 \end{aligned}$$



格林函数的极点

$$(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})|_{\text{单粒子中间态}} \quad x_1^0, \dots, x_r^0 > 0, \quad x_{r+1}^0, \dots, x_n^0 < 0$$

$$= \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])} \int d\vec{p} e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1} - i\omega(x_1^0 - x_{r+1}^0)}$$

$$\times \sum (\Psi_{\beta}^{-} \mathbf{T} \{\psi_{H,l_1}(0) \psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{p},\sigma}^{+}) (\Psi_{\vec{p},\sigma} \mathbf{T} \{\psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_{\alpha}^{+})$$

$$(\Psi_{\beta}^{-}, \overset{\sigma}{\mathbf{T}} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \quad \tilde{q}_1 \equiv q_1 + \cdots + q_r \quad \tilde{q}_{r+1} \equiv q_{r+1} + \cdots + q_n$$

$$= \int \frac{d^4 \tilde{q}_1 d^4 \tilde{q}_{r+1} d^4 q_2 \cdots d^4 q_r d^4 q_{r+2} \cdots d^4 q_n}{(2\pi)^{4n}} e^{-i\tilde{q}_1 \cdot x_1 - i\tilde{q}_{r+1} \cdot x_{r+1} - iq_2 \cdot y_2 - \cdots - iq_r \cdot y_r - iq_{r+2} \cdot y_{r+2} - \cdots - iq_n \cdot y_n}$$

$$\times G_{\beta\alpha}(q_1, \dots, q_n) \quad y_i = x_i - y_1 \quad (i = 2, 3, \dots, r) \quad y_i = x_i - x_{r+1} \quad (i = r+2, \dots, n)$$

$$G_{\beta\alpha}(q_1, \dots, q_n) = \int d^4 x_1 \cdots d^4 x_n e^{i\tilde{q}_1 \cdot x_1 + i\tilde{q}_{r+1} \cdot x_{r+1} + iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n} \\ \times (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$$

$$= \int d^4 x_1 d^4 x_{r+1} d^4 y_2 \cdots d^4 y_r d^4 y_{r+2} \cdots d^4 y_n (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \\ \times e^{i\tilde{q}_1 \cdot x_1 + i\tilde{q}_{r+1} \cdot x_{r+1} + iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n}$$



格林函数的极点

$$(\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})|_{\text{单粒子中间态}} \quad x_1^0, \dots, x_r^0 > 0, \quad x_{r+1}^0, \dots, x_n < 0$$

$$= \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])} \int d\vec{p} e^{i(p_{\beta} - p)x_1 + i(p - p_{\alpha})x_{r+1} - i\omega(x_1^0 - x_{r+1}^0)}$$

$$\times \sum_{\sigma} (\Psi_{\beta}^{-} \mathbf{T} \{ \psi_{H,l_1}(0) \psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r) \} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T} \{ \psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n) \} \Psi_{\alpha}^{+})$$

$$\tilde{q}_1 \equiv q_1 + \cdots + q_r \quad \tilde{q}_{r+1} \equiv q_{r+1} + \cdots + q_n \quad y_i = x_i - y_1 \quad (i=2, \dots, r) \quad y_i = x_i - x_{r+1} \quad (i=r+2, \dots, n)$$

$$G_{\beta\alpha}(q_1, \dots, q_n) = \int d^4x_1 d^4x_{r+1} d^4y_2 \cdots d^4y_r d^4y_{r+2} \cdots d^4y_n (\Psi_{\beta}^{-}, \mathbf{T} \psi_{H,l_1}(x_1) \psi_{H,l_2}(x_2) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+}) \\ \times e^{i\tilde{q}_1 \cdot x_1 + i\tilde{q}_{r+1} \cdot x_{r+1} + iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n} \Downarrow \text{下面只考虑了前r个场晚于后n-r个场的情形} \Downarrow$$

$$G_{\beta\alpha}(q_1, \dots, q_n)|_{\text{单粒子中间态}} = \int d^4y_2 \cdots d^4y_r d^4y_{r+2} \cdots d^4y_n e^{iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n} \\ \times \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])} \int d\vec{p} (2\pi)^8 \delta(\vec{p} - \vec{p}_{\beta} - \vec{q}_1) \\ \times \delta(-\sqrt{\vec{p}^2 + M^2} - \omega + p_{\beta}^0 + \tilde{q}_1^0) \delta(-\vec{q}_{r+1} + \vec{p}_{\alpha} - \vec{p}) \delta(\tilde{q}_{r+1}^0 - p_{\alpha}^0 + \sqrt{\vec{p}^2 + M^2} + \omega)$$

$$\times \sum_{\sigma} (\Psi_{\beta}^{-} \mathbf{T} \{ \psi_{H,l_1}(0) \psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r) \} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T} \{ \psi_{H,l_{r+1}}(0) \psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n) \} \Psi_{\alpha}^{+})$$



格林函数的极点

$G_{\alpha\beta}(q_1, \dots, q_n)|_{\text{单粒子中间态}}$

$$= \int d^4y_2 \cdots d^4y_r d^4y_{r+2} \cdots d^4y_n e^{iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n} \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])}$$

$$\times \sum_{\sigma} \int d\vec{p} (\Psi_{\beta}^- \mathbf{T}\{\psi_{H,l_1}(0)\psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(0)\psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_{\vec{p},\sigma})$$

$$\times (2\pi)^8 \delta(\vec{p} - \vec{p}_{\beta} - \vec{q}_1 - \cdots - \vec{q}_r) \delta(-\sqrt{\vec{p}^2 + M^2} - \omega + p_{\beta}^0 + q_1^0 + \cdots + q_r^0)$$

$$\times \delta(-\vec{q}_{r+1} - \cdots - \vec{q}_n + \vec{p}_{\alpha} - \vec{p}) \delta(q_{r+1}^0 + \cdots + q_n^0 - p_{\alpha}^0 + \sqrt{\vec{p}^2 + M^2} + \omega)$$

$$q \equiv q_1 + \cdots + q_r + p_{\beta} = -q_{r+1} - \cdots - q_n + p_{\alpha}$$

$$\sum M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n)$$

$$= i(2\pi)^7 \delta^4(q_1 + \cdots + q_n + p_{\beta} - p_{\alpha}) \frac{\sigma}{q^0 - \sqrt{\vec{q}^2 + M^2} + i0^+}$$

$$\frac{1}{q^0 - \sqrt{\vec{q}^2 + M^2} + i0^+} = \frac{q^0 + \sqrt{\vec{q}^2 + M^2} - i0^+}{(q^0)^2 - (\vec{q}^2 + M^2 - i0^+)} = \frac{2\sqrt{\vec{q}^2 + M^2}}{q^2 - M^2 + i0^+} + \text{非极点项}$$

$$2q^0 \sum M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n)$$

$$= i(2\pi)^7 \delta^4(q_1 + \cdots + q_n + p_{\beta} - p_{\alpha}) \frac{\sigma}{q^2 - M^2 + i0^+}$$



格林函数的极点

$$G_{\beta\alpha}(q_1, \dots, q_n) = \int d^4x_1 \cdots d^4x_n e^{iq_1 \cdot x_1 + \dots + iq_n \cdot x_n} (\Psi_\beta^-, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_\alpha^+)$$

$G_{\beta\alpha}(q_1, \dots, q_n)$ | 单粒子中间态

$$= \int d^4y_2 \cdots d^4y_r d^4y_{r+2} \cdots d^4y_n e^{iq_2 \cdot y_2 + \dots + iq_r \cdot y_r + iq_{r+2} \cdot y_{r+2} + \dots + iq_n \cdot y_n} \frac{i}{2\pi} \int_{-\infty}^{\infty} \frac{d\omega}{\omega + i0^+} e^{-i\omega(\min[0, y_2^0, \dots, y_r^0] - \max[0, y_{r+1}^0, \dots, y_n^0])}$$

$$\times \sum_{\sigma} \int d\vec{p} (\Psi_\beta^- \mathbf{T}\{\psi_{H,l_1}(0)\psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{p},\sigma}) (\Psi_{\vec{p},\sigma} \mathbf{T}\{\psi_{H,l_{r+1}}(0)\psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi)$$

$$\times (2\pi)^8 \delta(\vec{p} - \vec{p}_\beta - \vec{q}_1 - \dots - \vec{q}_r) \delta(-\sqrt{\vec{p}^2 + M^2} - \omega + p_\beta^0 + q_1^0 + \dots + q_r^0)$$

$$\times \delta(-\vec{q}_{r+1} - \dots - \vec{q}_n + \vec{p}_\alpha - \vec{p}) \delta(q_{r+1}^0 + \dots + q_n^0 - p_\alpha^0 + \sqrt{\vec{p}^2 + M^2} + \omega)$$

$$q \equiv q_1 + \dots + q_r + p_\beta = -q_{r+1} - \dots - q_n + p_\alpha$$

$$2q^0 \sum_{\sigma} M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n)$$

$$= i(2\pi)^7 \delta^4(q_1 + \dots + q_n + p_\beta - p_\alpha) \frac{\sigma}{q^2 - M^2 + i0^+} + \text{非极点项}$$

$$M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) = \int d^4y_2 \cdots d^4y_r e^{iq_2 \cdot y_2 + \dots + iq_r \cdot y_r} (\Psi_\beta^-, \mathbf{T}\{\psi_{H,l_1}(0)\psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{q},\sigma})$$

$$M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n) = \int d^4y_{r+2} \cdots d^4y_n e^{iq_{r+2} \cdot y_{r+2} + \dots + iq_n \cdot y_n} (\Psi_{\vec{q},\sigma}, \mathbf{T}\{\psi_{H,l_{r+1}}(0)\psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_\alpha^+)$$



格林函数的极点

$$G_{\beta\alpha}(q_1, \dots, q_n) = \int d^4x_1 \cdots d^4x_n e^{iq_1 \cdot x_1 + \cdots + iq_n \cdot x_n} (\Psi_{\beta}^{-}, \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_{\alpha}^{+})$$

$$M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) = \int d^4y_2 \cdots d^4y_r e^{iq_2 \cdot y_2 + \cdots + iq_r \cdot y_r} (\Psi_{\beta}^{-}, \mathbf{T}\{\psi_{H,l_1}(0)\psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{q},\sigma})$$

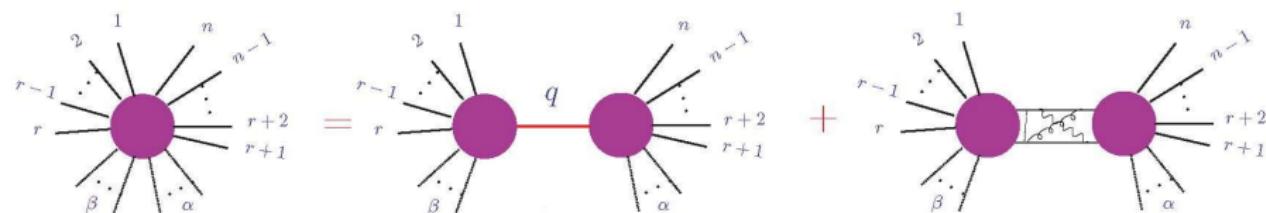
$$M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n) = \int d^4y_{r+2} \cdots d^4y_n e^{iq_{r+2} \cdot y_{r+2} + \cdots + iq_n \cdot y_n} (\Psi_{\vec{q},\sigma}, \mathbf{T}\{\psi_{H,l_{r+1}}(0)\psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_{\alpha}^{+})$$

$$G_{\beta\alpha}(q_1, \dots, q_n) = \sum_{\sigma} \int \frac{d^4q}{(2\pi)^4} \left[(2\pi)^4 \delta(q_1 + \cdots + q_r + p_{\beta} - q) (2\pi)^{\frac{3}{2}} (2q^0)^{\frac{1}{2}} M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) \right]$$

$$\times \frac{i}{q^2 - M^2 + i0^+} \quad \text{通常单粒子态的贡献是最主要的!} \Rightarrow \underline{\text{单粒子为主}} \quad \underline{\text{有效拉氏量}}$$

$$\times \left[(2\pi)^4 \delta(q + q_{r+1} + \cdots + q_n - p_{\alpha}) (2\pi)^{\frac{3}{2}} (2q^0)^{\frac{1}{2}} M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n) \right]$$

+ 多粒子中间态项 + 非极点项





格林函数的极点

$$G_{\beta\alpha}(q_1, \dots, q_n) = \int d^4x_1 \cdots d^4x_n e^{iq_1 \cdot x_1 + \dots + iq_n \cdot x_n} (\Psi_\beta^- \cdot \mathbf{T}\psi_{H,l_1}(x_1) \cdots \psi_{H,l_n}(x_n) \Psi_\alpha^+)$$

$$= i(2\pi)^7 \delta^4(q_1 + \dots + q_n + p_\beta - p_\alpha) (q^2 - M^2 + i0^+)^{-1} 2q^0 \sum_{\sigma} M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n)$$

+ 多粒子中间态项 + 非极点项

$$M_{\beta|\vec{q},\sigma}(q_2, \dots, q_r) = \int d^4y_2 \cdots d^4y_r e^{iq_2 \cdot y_2 + \dots + iq_r \cdot y_r} (\Psi_\beta^-, \mathbf{T}\{\psi_{H,l_1}(0)\psi_{H,l_2}(y_2) \cdots \psi_{H,l_r}(y_r)\} \Psi_{\vec{q},\sigma})$$

$$M_{-\vec{q},\sigma|\alpha}(q_{r+2}, \dots, q_n) = \int d^4y_{r+2} \cdots d^4y_n e^{iq_{r+2} \cdot y_{r+2} + \dots + iq_n \cdot y_n} (\Psi_{\vec{q},\sigma}, \mathbf{T}\{\psi_{H,l_{r+1}}(0)\psi_{H,l_{r+2}}(y_{r+2}) \cdots \psi_{H,l_n}(y_n)\} \Psi_\alpha^+)$$

$$\int d^4x d^4y e^{iq \cdot x + iq' \cdot y} (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x)\psi_{H,l_2}(y) \Psi_0^+) = \int d^4x d^4y e^{iq \cdot (x-y) + i(q+q') \cdot y} (\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x)\psi_{H,l_2}(y) \Psi_0^+)$$

$$= i(2\pi)^7 \delta^4(q + q') \frac{2q^0 \sum_{\sigma} (\Psi_0^-, \psi_{H,l_1}(0) \Psi_{\vec{q},\sigma}) (\Psi_{\vec{q},\sigma}, \psi_{H,l_2}(0) \Psi_0^+)}{q^2 - M^2 + i0^+} + \text{其它项}$$

$$(\Psi_0^-, \mathbf{T}\psi_{H,l_1}(x)\psi_{H,l_2}(y) \Psi_0^+) = \int \frac{d^4q}{2\pi} e^{-iq \cdot (x-y)} \frac{2iq^0 \sum_{\sigma} (\Psi_0^-, \psi_{H,l_1}(0) \Psi_{\vec{q},\sigma}) (\Psi_{\vec{q},\sigma}, \psi_{H,l_2}(0) \Psi_0^+)}{q^2 - M^2 + i0^+} + \dots$$



格林函数的极点

两点函数的谱函数: X :标量 $\psi(x) = e^{iP \cdot x} \psi(0) e^{-iP \cdot x}$ Ψ_0 完全可替换为 Ψ_α

$$(\Psi_0, X(x)X^\dagger(y)\Psi_0) = \sum_n (\Psi_0, X(x)\Psi_n)(\Psi_n, X^\dagger(y)\Psi_0) = \sum_n e^{-ip_n \cdot (x-y)} |(\Psi_0, X(0)\Psi_n)|^2$$

$$= \int d^4 p e^{-ip \cdot (x-y)} \underbrace{\sum_n \delta^4(p-p_n) |(\Psi_0, X(0)\Psi_n)|^2}_{(2\pi)^{-3}\theta(p^0)\rho(p^2)} \underbrace{p_n^0 \geq 0}_{\Delta+(x-y,\mu^2)}$$

$$(\Psi_0, X^\dagger(y)X(x)\Psi_0) = \sum_n (\Psi_0, X^\dagger(y)\Psi_n)(\Psi_n, X(x)\Psi_0) = \sum_n e^{ip_n \cdot (x-y)} |(\Psi_n, X(0)\Psi_0)|^2$$

$$= \int d^4 p e^{ip \cdot (x-y)} \underbrace{\sum_n \delta^4(p-p_n) |(\Psi_n, X(0)\Psi_0)|^2}_{(2\pi)^{-3}\theta(p^0)\tilde{\rho}(p^2)} \underbrace{p_n^0 \geq 0}_{\Delta+(y-x,\mu^2)}$$

$$(\Psi_0, [X(x), X^\dagger(y)]\Psi_0) = \int_0^\infty d\mu^2 [\rho(\mu^2) \Delta_{+}(x-y, \mu^2) - \tilde{\rho}(\mu^2) \Delta_{+}(y-x, \mu^2)] \xrightarrow{\text{类空: 求导}} \rho(\mu^2) = \tilde{\rho}(\mu^2)$$

$$(\Psi_0, \mathbf{T} X(x)X^\dagger(y)\Psi_0) = \int_0^\infty d\mu^2 \rho(\mu^2) \underbrace{[\theta(x^0-y^0)\Delta_{+}(x-y, \mu^2) + \theta(y^0-x^0)\Delta_{+}(y-x, \mu^2)]}_{\Delta_F(x-y, \mu^2)}$$



格林函数的极点

$$\rho(p^2) \equiv (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_0, X(0)\Psi_n)|^2 = (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_n, X(0)\Psi_0)|^2$$

$$(\Psi_0, \mathbf{T} X(x) X^\dagger(y) \Psi_0) = \int_0^\infty d\mu^2 \rho(\mu^2) \Delta_F(x-y, \mu^2) \quad \Delta_+(x-y, \mu^2) \equiv \int \frac{d^4 p}{(2\pi)^3} e^{-ip \cdot (x-y)} \theta(p^0) \delta(p^2 - \mu^2)$$

$$(\Psi_0, [X(x), X^\dagger(y)] \Psi_0) = \int_0^\infty d\mu^2 \rho(\mu^2) [\Delta_+(x-y, \mu^2) - \Delta_+(y-x, \mu^2)]$$

$$\frac{\partial}{\partial x^0} \Delta_+(x-y, \mu^2) \Big|_{x^0=y^0} = \int \frac{d^4 p}{(2\pi)^3} e^{i\vec{p} \cdot (\vec{x}-\vec{y})} \theta(p^0) (-ip^0) \delta((p^0)^2 - \vec{p}^2 - \mu^2) = -\frac{i}{2} \delta(\vec{x} - \vec{y})$$

$$\frac{\partial}{\partial x^0} \Delta_+(y-x, \mu^2) \Big|_{x^0=y^0} = \int \frac{d^4 p}{(2\pi)^3} e^{-i\vec{p} \cdot (\vec{x}-\vec{y})} \theta(p^0) (ip^0) \delta((p^0)^2 - \vec{p}^2 - \mu^2) = \frac{i}{2} \delta(\vec{x} - \vec{y})$$

$$(\Psi_0, [\dot{X}(x), X^\dagger(y)] \Big|_{x^0=y^0} \Psi_0) = -i\delta(\vec{x}-\vec{y}) \int_0^\infty d\mu^2 \rho(\mu^2)$$

如果 $\dot{X}\dot{X}^\dagger = -\ddot{X}X^\dagger$ 是动能项, \dot{X} 对应的广义动量就是 $-X^\dagger$ 。 $\dot{\phi} = \frac{\delta H}{\delta \pi}$

$$[\dot{X}(x), X^\dagger(y)] \Big|_{x^0=y^0} = -i\delta(\vec{x}-\vec{y}) \Rightarrow \int_0^\infty d\mu^2 \rho(\mu^2) = 1 \quad \text{只对基本场成立!}$$



格林函数的极点

$$\rho(p^2) \equiv (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_0, X(0)\Psi_n)|^2 = (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_n, X(0)\Psi_0)|^2$$

$$(\Psi_0, \mathbf{T} X(x) X^\dagger(y) \Psi_0) = \int_0^\infty d\mu^2 \rho(\mu^2) \Delta_F(x-y, \mu^2) \quad \Delta_+(x-y, \mu^2) \equiv \int \frac{d^4 p}{(2\pi)^3} e^{-ip \cdot (x-y)} \theta(p^0) \delta(p^2 - \mu^2)$$

$$\Delta_F(x-y, \mu^2) \equiv [\theta(x^0 - y^0) \Delta_+(x-y, \mu^2) + \theta(y^0 - x^0) \Delta_+(y-x, \mu^2)]$$

$$= \int \frac{d^4 p}{(2\pi)^3} \delta((p^0)^2 - (\vec{p})^2 - \mu^2) \theta(p^0) [e^{-ip \cdot (x-y)} \theta(x^0 - y^0) + e^{ip \cdot (x-y)} \theta(y^0 - x^0)]$$

$$= \int \frac{d^4 p}{2p^0 (2\pi)^3} \delta(p^0 - \sqrt{\vec{p}^2 + \mu^2}) \theta(p^0) [e^{-ip \cdot (x-y)} \theta(x^0 - y^0) + e^{ip \cdot (x-y)} \theta(y^0 - x^0)]$$

$$= \int \frac{d\vec{p}}{2\sqrt{(\vec{p})^2 + \mu^2} (2\pi)^3} e^{i\vec{p} \cdot (\vec{x}-\vec{y})} [e^{-i\sqrt{\vec{p}^2 + \mu^2}(x^0 - y^0)} \theta(x^0 - y^0) + e^{i\sqrt{\vec{p}^2 + \mu^2}(x^0 - y^0)} \theta(y^0 - x^0)]$$

$$= \int \frac{d\vec{p}}{2\sqrt{(\vec{p})^2 + \mu^2} (2\pi)^3} \int_{-\infty}^{\infty} \frac{dp^0}{2i\pi} e^{-ip^0(x^0 - y^0) + i\vec{p} \cdot (\vec{x} - \vec{y})} \left[-\frac{1}{p^0 - \sqrt{\vec{p}^2 + \mu^2} + i0^+} + \frac{1}{p^0 + \sqrt{\vec{p}^2 + \mu^2} - i0^+} \right]$$

$$= \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \frac{i}{p^2 - \mu^2 + i0^+} \quad (\Psi_0, \mathbf{T} X(x) X^\dagger(y) \Psi_0) = \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \int_0^\infty d\mu^2 \frac{i\rho(\mu^2)}{p^2 - \mu^2 + i0^+}$$



格林函数的极点

$$\rho(p^2) \equiv (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_0, X(0)\Psi_n)|^2 = (2\pi)^3 \sum_n \delta^4(p-p_n) |(\Psi_n, X(0)\Psi_0)|^2 \geq 0$$

$$(\Psi_0, \mathbf{T} X(x) X^\dagger(y) \Psi_0) = \int \frac{d^4 p}{(2\pi)^4} e^{-ip \cdot (x-y)} \Delta_X(p^2 + i0^+) \quad \Delta_X(z) = \int_0^\infty d\mu^2 \frac{i\rho(\mu^2)}{z - \mu^2}$$

若中间态谱中最低质量 M 的单粒子态 $\Psi_{\vec{p}_\alpha}$ $(\Psi_0, X(0)\Psi_{\vec{p}_\alpha}) \neq 0$, 其对谱函数贡献:

$$(2\pi)^3 \int d\vec{p}_\alpha \delta(p^0 - \sqrt{\vec{p}_\alpha^2 + M^2}) \delta(\vec{p} - \vec{p}_\alpha) |(\Psi_0, X(0)\Psi_{\vec{p}_\alpha})|^2 \\ = (2\pi)^3 \delta(p^0 - \sqrt{\vec{p}^2 + M^2}) |(\Psi_0, X(0)\Psi_{\vec{p}})|^2 = (2\pi)^3 \theta(p^0) 2p^0 \delta((p^0)^2 - \vec{p}^2 - M^2) |(\Psi_0, X(0)\Psi_{\vec{p}})|^2 \\ = Z_\alpha \delta(p^2 - M^2) \quad Z_\alpha \equiv (2\pi)^3 \theta(p^0) 2p^0 |(\Psi_0, X(0)\Psi_{\vec{p}})|^2 \geq 0$$

$$\rho(\mu^2) = Z_\alpha \delta(\mu^2 - M^2) + \sigma(\mu^2) \quad 1 = Z_\alpha + \int_{M_0^2}^\infty d\mu^2 \sigma(\mu^2) \quad \text{M}_0 \geq \text{M} \text{为其它粒子或连续谱出现的下限} \quad Z_\alpha \leq 1$$

$$\Delta_X(z) = \frac{iZ_\alpha}{z - M^2} + \int_{M_0^2}^\infty d\mu^2 \frac{i\rho(\mu^2)}{z - \mu^2} \quad \text{可能有割线!} \quad -i\Delta_X(M^2 \pm 0^+) = \pm\infty \quad -i\Delta_X(M^2 \pm i0^+) = \mp i\infty$$