

# Recent advances in deal.II: matrix-free, multigrid, non-matching, and simplex support

## 9th deal.II Users and Developers Workshop

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*in collaboration with Maximilian Bergbauer, Niklas Fehn, Dmytro Sashko, Magdalena Schreter, ...*

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June 18, 2021

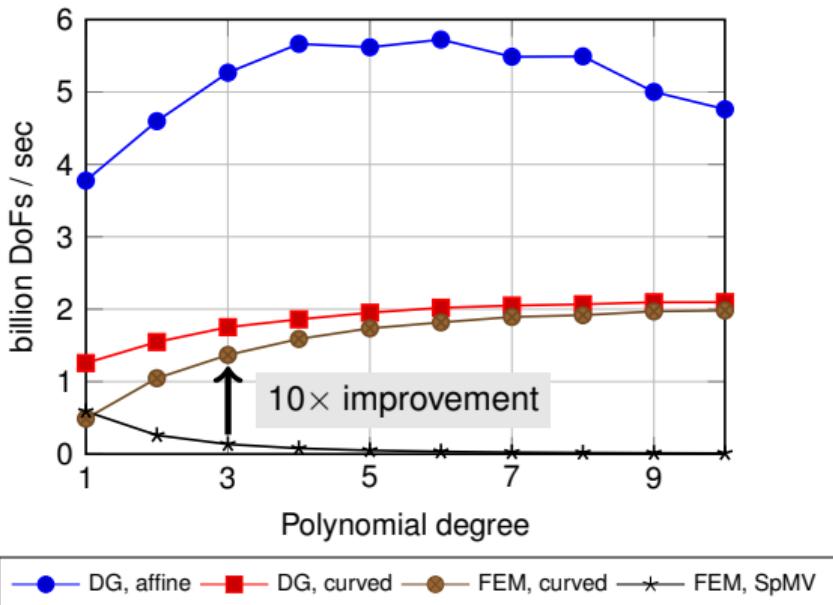
Part 1:

## Matrix-free methods

# Why matrix-free methods?

- ▶ Performance of matrix-vector product essential for iterative solvers
- ▶ Classical approach: sparse matrix (CRS, SELL-C)
- ▶ Sparse matrices bad fit for modern hardware: **memory-bandwidth** limited
- ▶ Inappropriate format for higher polynomial degrees,  $p \geq 2$
- ▶ Matrix-free algorithm: trade computations for less memory transfer
  - ▶ Specify operation at quadrature points
  - ▶ Combine with reference cell interpolation matrices
  - ▶ Indirect access into vector entries for continuous FEM

Throughput of matrix-vector product (unknowns processed per second) in 3D



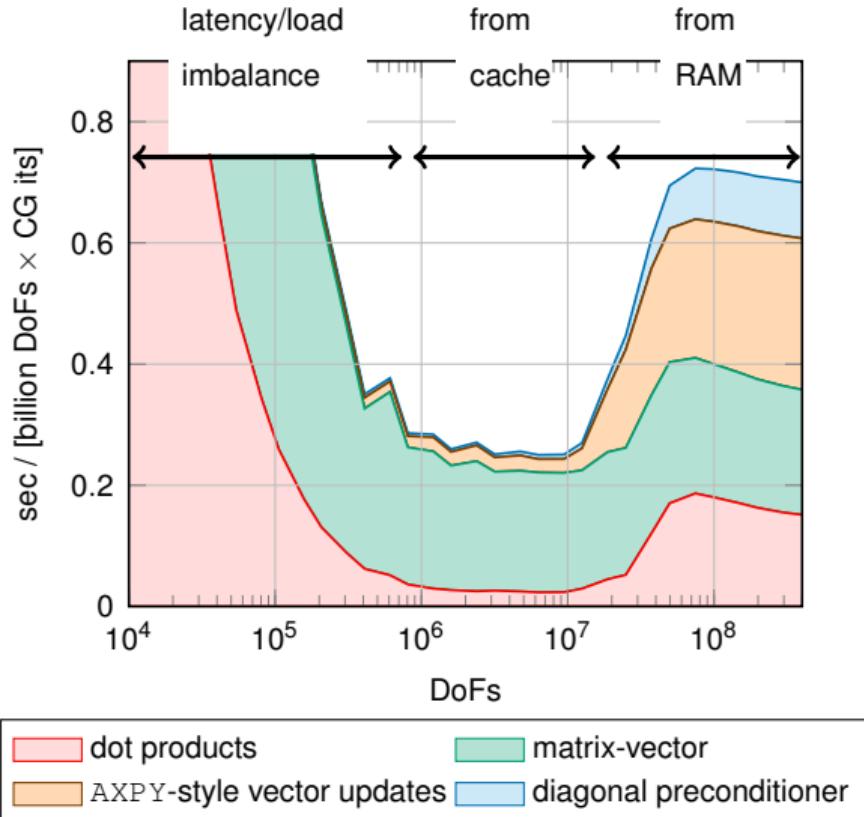
System: 1 node of  $2 \times 24$  cores of Intel Xeon Platinum 8174 (Skylake)

Memory bw: 205 GB/s, arithmetic peak 3.5 TFlop/s

- ▶ Matrix-free infrastructure
  - ▶ Container of various pre-computed quantities in class `MatrixFree`
  - ▶ Evaluator classes `FEEvaluation` and `FEFaceEvaluation`
  - ▶ Optimized for **fast integrals through sum factorization techniques**
- ▶ Matrix-free solver infrastructure highly attractive for degrees  $\geq 2$ 
  - ▶ Highly optimized for continuous and discontinuous elements via cell and face integrals
  - ▶ Primarily CPU-based optimizations (**SIMD, memory access**), basic support for GPUs
- ▶ Mesh adaptivity, native parallel vectors + basic MPI facilities
- ▶ Various flavors of **multigrid solvers**, see below
- ▶ step-37, step-48, step-50, step-59, step-64, step-66, step-67, step-75, step-76

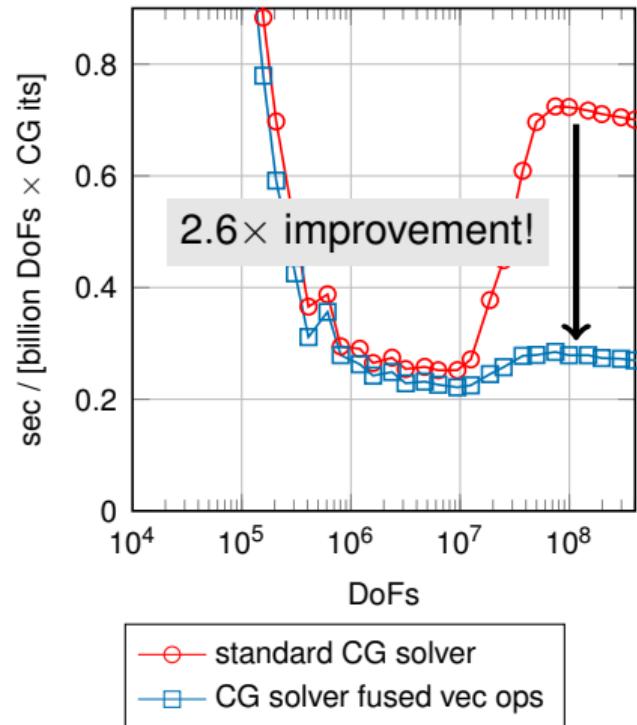
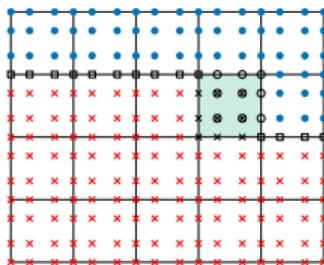
# Performance of matrix-free solver: $2 \times 64$ core AMD Epyc

- ▶ CEED benchmark problem BP4
  - ▶ 3D Poisson, deformed geometry, continuous elements
  - ▶ Degree  $p = 5$ , quadrature with  $n_q = 7$  per direction
  - ▶ Conjugate gradient + diagonal preconditioner
  - ▶ Metric terms computed on the fly from tri-quadratic geometry
- ▶ 1 node of dual-socket AMD Epyc 7742
  - ▶ bandwidth from RAM: 400 GB/s theory,  $\sim 300$  GB/s achievable
  - ▶ 4.6 TFlop/s
- ▶ Matrix-vector product no longer dominant operation for large sizes
- ▶ Vector operations take significant share of time when from RAM



## Ongoing work: Overlap mat-vec with vector operations

- ▶ Performance opportunities at leading edge:  
Combine arithmetic intensive matrix-vector product with memory-heavy vector operations
- ▶ MatrixFree::cell\_loop can run **vector updates before**  $A_{pk}$  first touches vector entries, **dot products after**  $A_{pk}$  last touches vector entries
  - ▶ 87% of vector entries accessed 1× per CG it
  - ▶ **2–3× performance improvement**
- ▶ Algorithms to be improved: SolverCG, PreconditionChebyshev work-in-progresss, maybe also SolverBiCGStab?



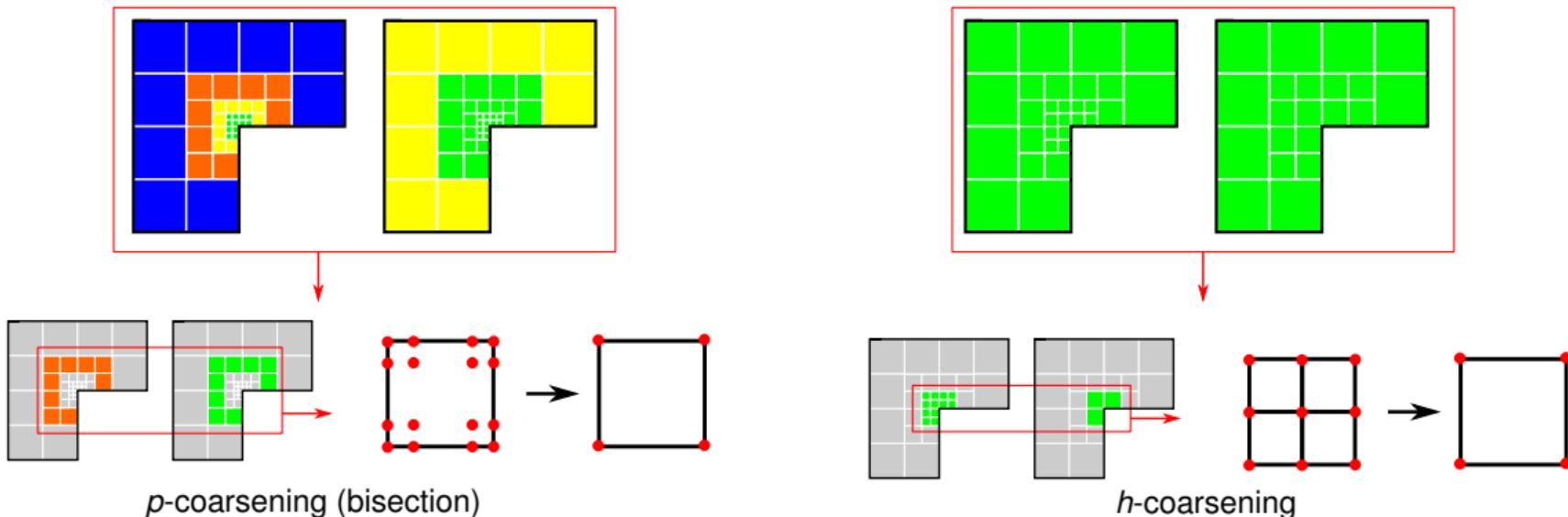
Part 2:

## Global coarsening multigrid support

# Global coarsening

Global coarsening builds multigrid levels for entire domain, coarsening *all* cells of a triangulation regardless of how many times they have been refined.

■  $p = 1$  ■  $p = 2$  ■  $p = 3$  ■  $p = 4$



- ▶ set up each two-level transfer operator:

```
MGLevelObject<MGTTwoLevelTransfer<dim, VectorType>> transfers;  
  
// loop over all levels and set up geometric transfer or ...  
transfers[level + 1].reinit_geometric_transfer(dof_handlers[level + 1],  
                                              dof_handlers[level],  
                                              constraints[level + 1],  
                                              constraints[level]);  
  
// ... polynomial transfer  
transfers[level + 1].reinit_polynomial_transfer(dof_handlers[level + 1],  
                                              dof_handlers[level],  
                                              constraints[level + 1],  
                                              constraints[level]);
```

- ▶ set up final global-coarsening transfer operator:

```
MGTransferGlobalCoarsening<dim, VectorType> transfer(  
    transfers,  
    [&] (const auto l, auto &vec) {operators[l]->initialize_dof_vector(vec);});
```

- ▶ create polynomial coarsening sequence:

```
std::vector<unsigned int>
MGTransferGlobalCoarseningTools::create_polynomial_coarsening_sequence (
    const unsigned int max_degree,
    const PolynomialCoarseningSequenceType & p_sequence);
```

... “*go to one*”, “*bisect*”, “*decrease by one*”

- ▶ create geometric coarsening sequence:

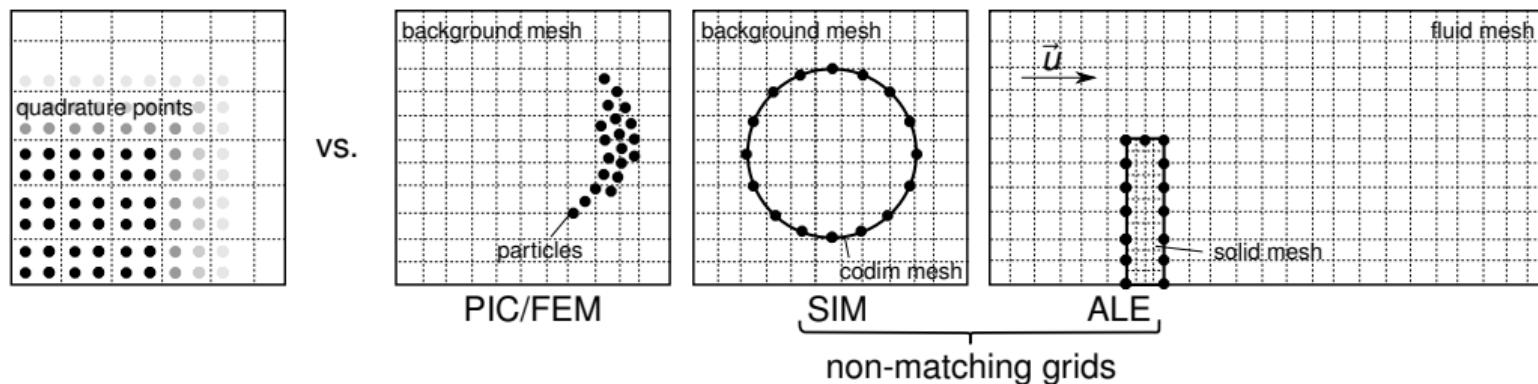
```
template<int dim, int spacedim>
std::vector<std::shared_ptr<const Triangulation<dim, spacedim> > >
MGTransferGlobalCoarseningTools::create_geometric_coarsening_sequence (
    const Triangulation< dim, spacedim > & tria);
```

... *result: sequence of triangulations*

Part 3:

## Non-matching support

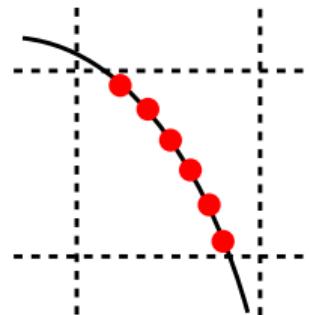
- ▶ new class: **FEPPointEvaluation**
- ▶ interface is similar to FEEvaluation (with `evaluate()`/`integrate()`)
- ▶ specialized for evaluation in points at arbitrary locations within a cell



## Example: evaluate surface tension

sharp-interface method:

$$(\mathbf{v}, \kappa \mathbf{n})_{\Gamma} \approx \sum_q \mathbf{v}(\mathbf{x}_q) \cdot (\kappa(\mathbf{x}_q) \mathbf{n}(\mathbf{x}_q)) (JxW)_q$$



... with  $\mathbf{n} = \nabla\phi / |\nabla\phi|$  and  $\kappa = \Delta\phi$ , based on level-set field  $\phi$

in code:

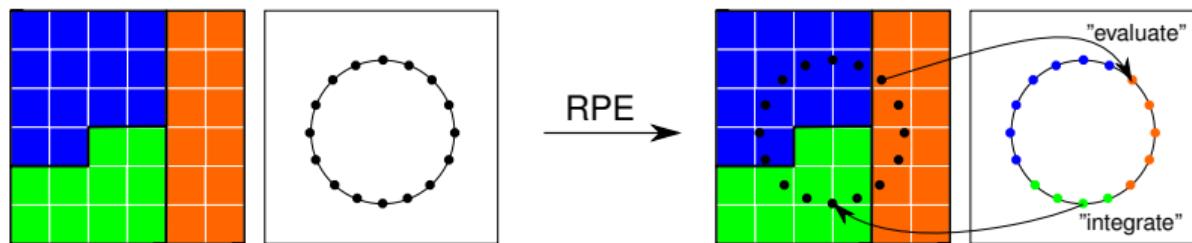
```
phi_normal.reinit(cell, reference_points); // same for phi_curv/phi_force

phi_normal.evaluate(normal_values, EvaluationFlags::values);
phi_curv.evaluate(curvature_values, EvaluationFlags::values);

for (unsigned int q = 0; q < n_points; ++q)
    phi_force.submit_value(phi_curv.get_value(q) * phi_normal.get_value(q) * JxW[q], q);

phi_force.integrate(force_values, EvaluationFlags::values);
```

- ▶ `ParticleA::get_surrounding_cell()` and `get_reference_location()`
- ▶ `GridTools::find_(all_)active_cell(s)_around_point()`
- ▶ **RemotePointEvaluation** → for surface and volume coupling of non-matching grids



**find cells + set up communication pattern** (with the help of bounding boxes)

... also used in `VectorTools::point_values()`

see also application codes: adaflo, ASPECT, ExaDG, and MeltPoolDG

Part 4:

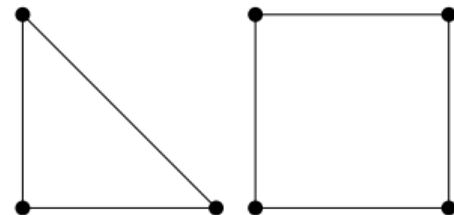
## Experimental simplex and mixed mesh support<sup>1</sup>

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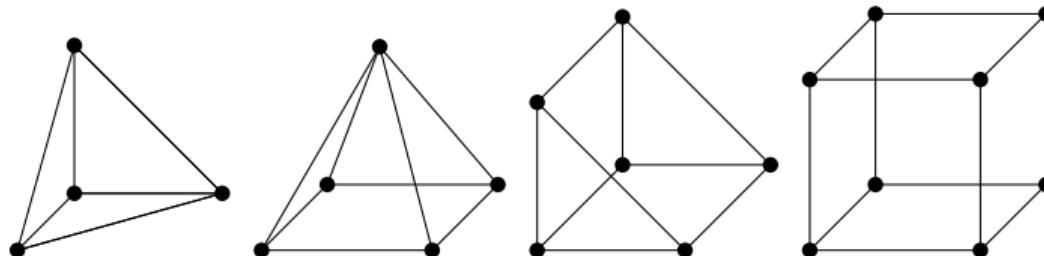
<sup>1</sup> with contributions by Pasquale Africa, Wolfgang Bangerth, Nicolas Barnafi, Maximilian Bergbauer, Bruno Blais, Michele Bucelli, Elias Dejene, Marco Fedele, Marc Fehling, Niklas Fehn, Ivan Fumagalli, Nicola Giuliani, Luca Heltai, Vladimir Ivannikov, Katharina Kormann, Martin Kronbichler, Olivier Guevremont, Timo Heister, Wenyu Lei, Nils Much, Peter Munch, Daniel Pauckner, Laura Prieto, Sebastian Proell, Magdalena Schreter, David Wells, Jiaqi Zhang, ...

## Reference-cell types

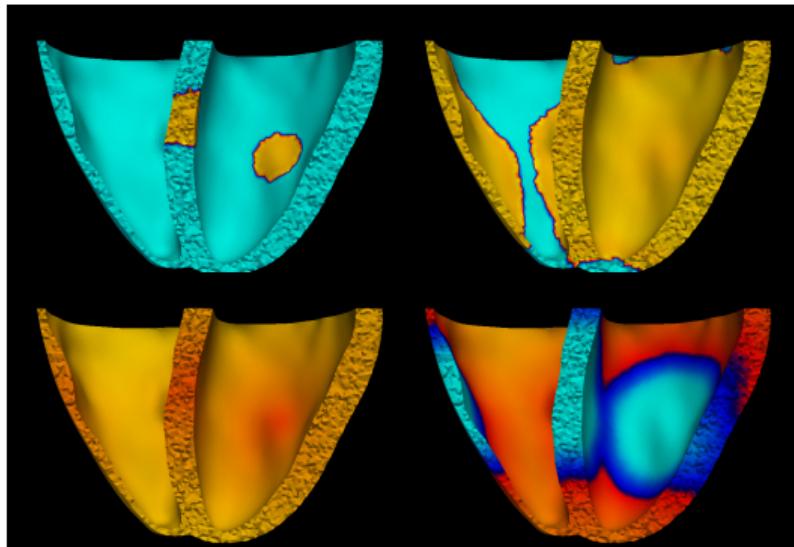
- ▶ reference-cell types in 0D: vertex
- ▶ reference-cell types in 1D: line
- ▶ reference-cell types in 2D: triangle, quadrilateral



- ▶ reference-cell types in 3D: tetrahedron, pyramid, wedge/prism, hexahedron



Monodomain model for Cardiac Electrophysiology in a left+right ventricle geometry:



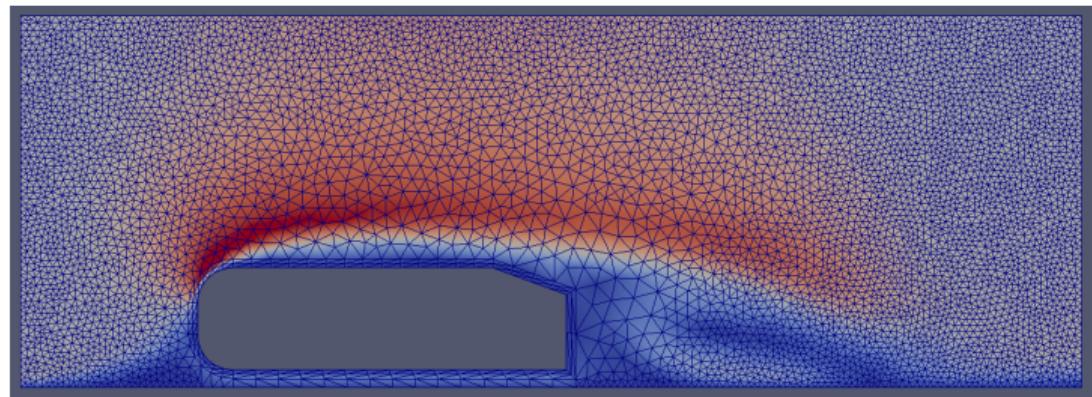
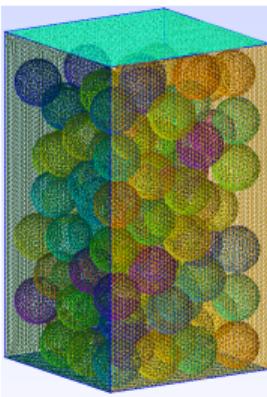
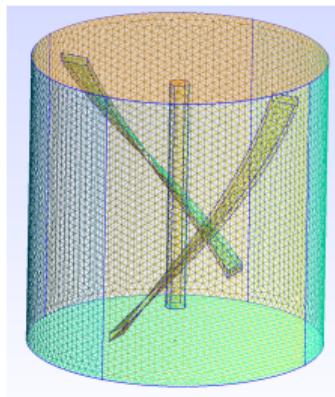
... submitted by Pasquale Africa (life<sup>x</sup>)<sup>2</sup>

transmembrane potential

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<sup>2</sup><https://lifex.gitlab.io/lifex/>; MOX - Department of Mathematics - Politecnico di Milano; founded by "iHEART, ERC Advanced Grant, Project ID: 740132 (PI: Prof. A. Quarteroni)"

Simulation of an impeller, of a porous domain, and of an Ahmed body:

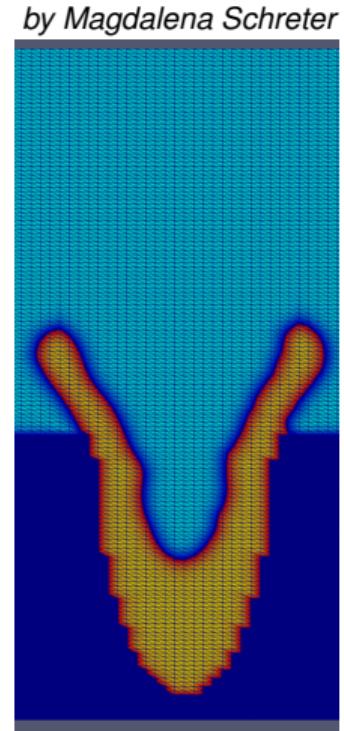
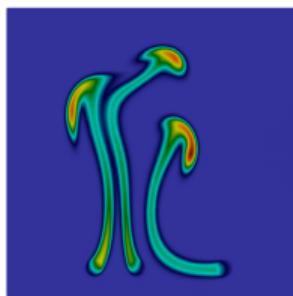
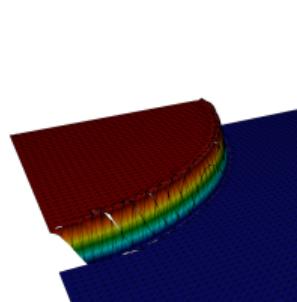
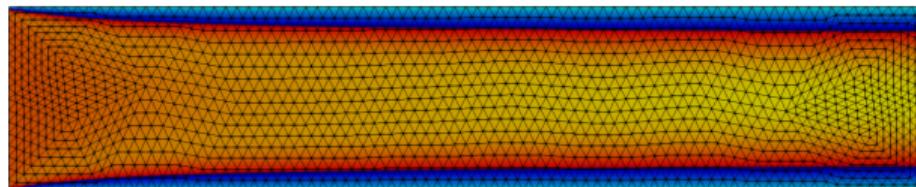
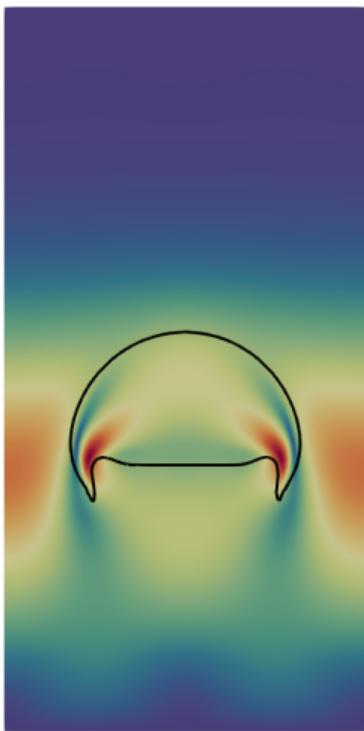


... submitted by Bruno Blais and Olivier Guevremont (Lethe-CFD)<sup>3</sup>

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<sup>3</sup><https://github.com/lethe-cfd/lethe>; Polytechnique Montreal

## Application examples (cont.)

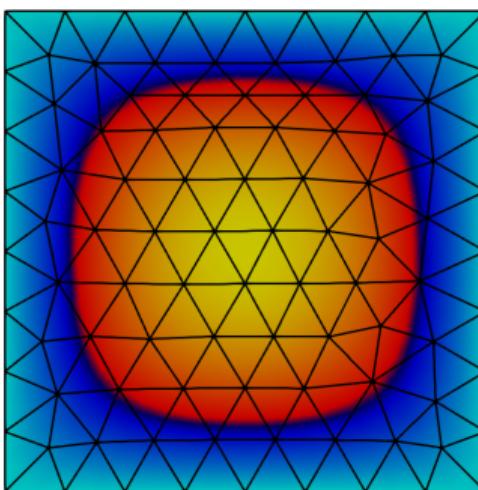
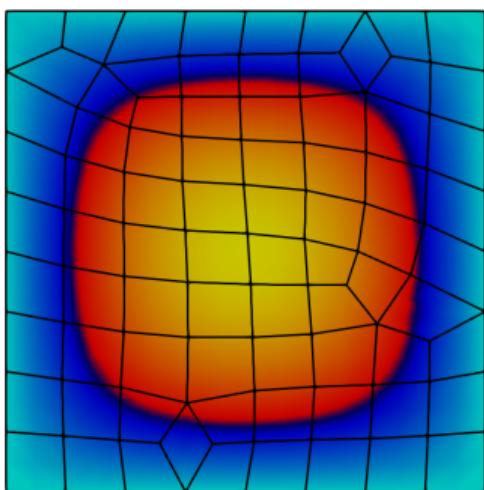


see also: [adaflo](#) and [MeltPoolDG](#)<sup>4</sup>

<sup>4</sup><https://github.com/kronbichler/adaflo> and <https://github.com/MeltPoolDG/MeltPoolDG>

## Example: simplex mesh

Solution of the Poisson problem on a pure quadrilateral and a pure triangle “Gmsh” mesh:



### Gmsh journals:

```
Rectangle(1) =  
{0, 0, 0, 1, 1, 0};  
Recombine Surface{1};  
Mesh 2;  
Save "box_2D_quad.msh";
```

```
Rectangle(1) =  
{0, 0, 0, 1, 1, 0};  
Mesh 2;  
Save "box_2D_tri.msh";
```

... online module page “Simplex support” → “Example: simplex mesh”

### New classes:

- ▶ finite elements: `FE_SimplexP`, `FE_SimplexDGP`, ...      ... with  $p \leq 2$
- ▶ quadrature rules: `QDuffy`, `QGaussSimplex`, `QWitherdenVincentSimplex`, ...
- ▶ mapping: `MappingFE`, `MappingFEFields`

### Generalized classes:

- ▶ `Triangulation`<sup>5</sup>      ... parallel: `p::s::T` and `p::f::T`
- ▶ `GridIn`/`GridOut`/`DataOut`: `vtk`, `vtu`, `Gmsh`, `hdf5`, `ExodusII`

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<sup>5</sup>limited support for adaptivity

## step-3

```
#include <deal.II/fe/fe_q.h>

const FE_Q<2> fe;
const QGauss<2> quadrature_formula;
```

```
FEValues<2> fe_values(fe, ...);
```

```
VectorTools::interpolate_boundary_values(
    dof_handler, 0, ...);
```

```
data_out.build_patches();
```

## step-3 with simplex mesh

```
#include <deal.II/fe/fe_simplex_p.h>
#include <deal.II/fe/mapping_fe.h>

const MappingFE<2> mapping;
const FE_SimplexP<2> fe;
const QGaussSimplex<2> quadrature_formula;
```

```
FEValues<2> fe_values(mapping, fe, ...);
```

```
VectorTools::interpolate_boundary_values(
    mapping, dof_handler, 0, ...);
```

```
data_out.build_patches(mapping, 2);
```

If you need flexibility to switch between cell types, use smart pointers!

```
std::unique_ptr<Mapping<dim, spacedim>> mapping;
std::unique_ptr<FiniteElement<dim, spacedim>> fe;
std::unique_ptr<Quadrature<dim>> quadrature;
```

*... which are set up centrally and are passed around via a ScratchData!*

RECOMMENDATION: do not use GeometryInfo!

The class TriaAccessor has been extended with new methods. E.g.:

```
for(const auto & cell : tria)
    for(const auto v :
        GeometryInfo<dim>::face_indices())
    // do something
```

*old*

```
for(const auto & cell : tria)
    for(const auto v :
        cell->face_indices())
    // do something
```

*new*

... to query the number of subentities and to iterate over them.

Last resort: to get the type of cells (ReferenceCell) via:

```
if(cell->reference_cell() == ReferenceCells::Hexahedron)
    // do something
```

**WARNING:** you cannot rely on default mappings! Be explicit! E.g.:

```
FEValues::FEValues(fe, quad, flags);
```

```
FEValues::FEValues(mapping, fe, quad, flags);
```

```
VectorTools::interpolate(  
    dof, function, vec);
```

```
VectorTools::interpolate(  
    mapping, dof, function, vec);
```

```
DataOut::build_patches(subdivisions);
```

```
DataOut::build_patches(mapping, subdivisions);
```

*implicit (MappingQGeneric(1))*

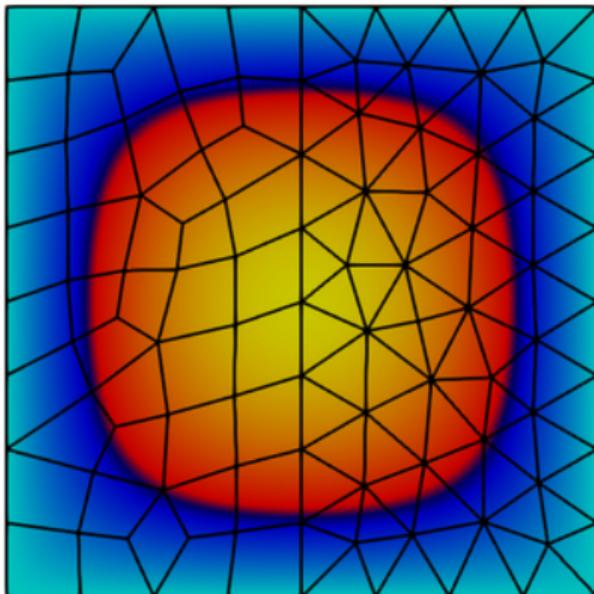
*explicit*

*... there are many functions with default argument mapping!!!*

## Example: mixed mesh

Solution of the Poisson problem on a mixed “Gmsh” mesh:

▷ using *hp* infrastructure



Gmsh journal:

```
Rectangle(1) = {0, 0, 0, 0.5, 1, 0};  
Rectangle(2) = {0.5, 0, 0, 0.5, 1, 0};  
Recombine Surface{1};  
Physical Surface("All") = {1, 2};  
Mesh 2;  
Coherence Mesh;  
Save "box_2D_mixed.msh";
```

... online module page “Simplex support” → “Example: mixed mesh”

- ▶ “Simplex support” module page
- ▶ upcoming release paper
- ▶ test folder “tests/simplex” with ported versions of steps:  
1-4, 6-8, 12, 17, 18, 20, 23, 31, 38, 40, 55, 67, 68, and 74
- ▶ application codes: adaflo, Lethe-CFD, and MeltPoolDG

### EXPERIMENTAL simplex and mixed mesh support ... help wanted!

- ▶ limitations: no adaptivity, limited number of low-order element & quadrature rules ...
- ▶ possible bugs
- ▶ possible changing interfaces (in particular for mixed meshes)

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Questions?