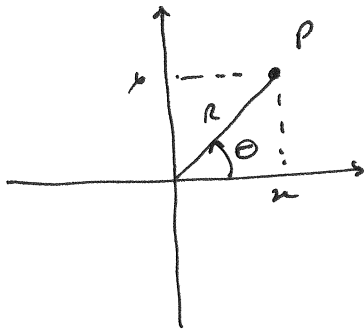


Movimento de uma partícula na base das coordenadas polares:



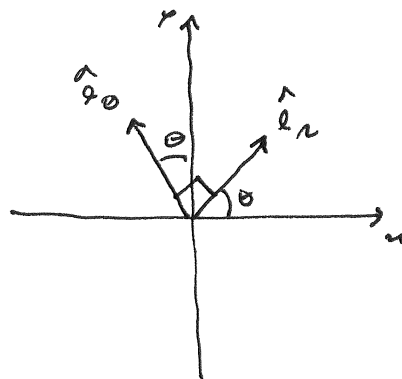
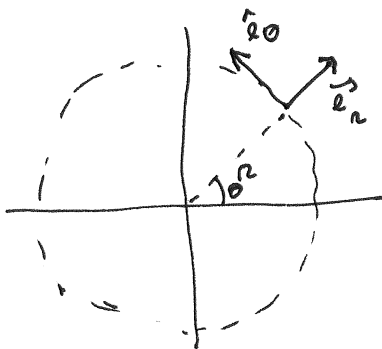
$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

vetor posição:

vetor unitário \hat{e}_r

$$\begin{aligned} \vec{r} &= (x, y) = (r \cos \theta, r \sin \theta) = r (\cos \theta, \sin \theta) \\ &= r \hat{e}_r \end{aligned}$$

Base das coordenadas polares



$$\hat{e}_r = (\cos \theta, \sin \theta)$$

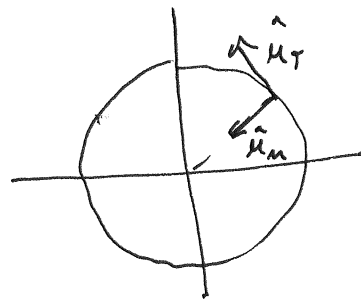
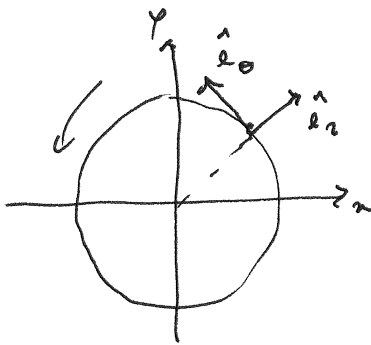
$$\hat{e}_\theta = (-\sin \theta, \cos \theta)$$

Derivada em ordem ao Tempo:

$$\begin{aligned}\frac{d\hat{e}_r}{dt} &= (-\dot{\theta} r \sin\theta, \dot{\theta} r \cos\theta) = \dot{\theta} (-r \sin\theta, r \cos\theta) \\ &= \dot{\theta} \hat{e}_\theta\end{aligned}$$

$$\begin{aligned}\frac{d\hat{e}_\theta}{dt} &= (-\dot{\theta} r \cos\theta, -\dot{\theta} r \sin\theta) = -\dot{\theta} (r \cos\theta, r \sin\theta) \\ &= -\dot{\theta} \hat{e}_r\end{aligned}$$

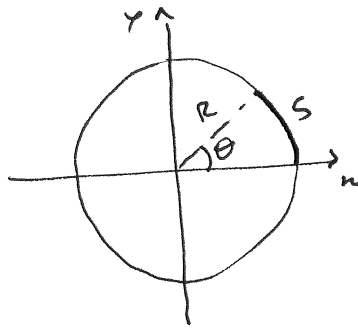
Relação entre \hat{e}_r e \hat{e}_θ e \hat{u}_r e \hat{u}_θ no movimento circular



$$\hat{e}_\theta = \hat{u}_\theta \quad (\text{tangente aos sentidos})$$

$$\hat{e}_r = -\hat{u}_r$$

Relação entre quant. dadas lineares e angulares
no movimento circular :



linear	angular
$s = R\theta$	θ
$v = \frac{ds}{dt}$ $= R\dot{\theta}$ $= R\omega$	$\omega = \dot{\theta}$
$a_t = \frac{dv}{dt}$ $= R\ddot{\theta}$ $= R\alpha$ $a_n = \frac{v^2}{R}$ $= \omega^2 R$	$\alpha = \ddot{\theta}$

Velocidade na base das coordenadas polares (movimento geral):

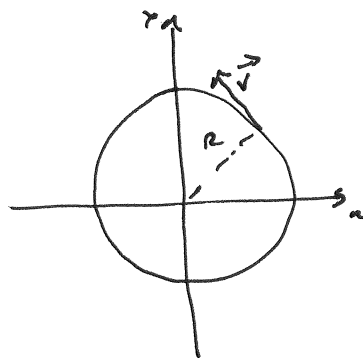
$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{d}{dt}(r \hat{e}_r) = \dot{r} \hat{e}_r + r \frac{d\hat{e}_r}{dt} = \underbrace{\dot{r} \hat{e}_r}_{\text{comp. radial}} + \underbrace{r \dot{\theta} \hat{e}_\theta}_{\text{comp. azimutal}}$$

Aceleração na base das coord. polares (movimento geral):

$$\begin{aligned} \vec{a} = \frac{d\vec{v}}{dt} &= \frac{d}{dt}(\dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta) \\ &= \ddot{r} \hat{e}_r + \dot{r} \dot{\theta} \hat{e}_\theta + \dot{r} \dot{\theta} \hat{e}_\theta + r \ddot{\theta} \hat{e}_\theta - r \dot{\theta}^2 \hat{e}_r \\ &= (\ddot{r} - r \dot{\theta}^2) \hat{e}_r + (2\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{e}_\theta \end{aligned}$$

Caso particular do movimento circular:

$$r = \text{const} \rightarrow \begin{cases} \dot{r} = 0 \\ \ddot{r} = 0 \end{cases}$$



velocidade: $\vec{v} = r \dot{\theta} \hat{e}_\theta$

aceleração: $\vec{a} = -r \dot{\theta}^2 \hat{e}_r + r \ddot{\theta} \hat{e}_\theta$

$$= r \dot{\theta}^2 \hat{u}_n + r \ddot{\theta} \hat{u}_t$$

$$= r \omega^2 \hat{u}_n + r \alpha \hat{u}_t$$

$$= a_n \hat{u}_n + a_t \hat{u}_t$$