

$$\vec{V} = z\hat{i} + x\hat{j} + y\hat{k}$$

base das coord. cilíndricas:

$$\begin{aligned} x &= \rho \cos \phi \\ y &= \rho \sin \phi \\ z &= z \end{aligned} \quad \begin{cases} \hat{e}_\rho = \cos \phi \hat{i} + \sin \phi \hat{j} + 0 \hat{k} \\ \hat{e}_\phi = -\sin \phi \hat{i} + \cos \phi \hat{j} + 0 \hat{k} \\ \hat{e}_z = 0 \hat{i} + 0 \hat{j} + 1 \hat{k} \end{cases}$$

$$\begin{cases} \hat{i} = \cos \phi \hat{e}_\rho - \sin \phi \hat{e}_\phi + 0 \hat{e}_z \\ \hat{j} = \sin \phi \hat{e}_\rho + \cos \phi \hat{e}_\phi + 0 \hat{e}_z \\ \hat{k} = 0 \hat{e}_\rho + 0 \hat{e}_\phi + 1 \hat{e}_z \end{cases}$$

1º passo:

$$\Rightarrow \vec{V} = z\hat{i} + z\rho \cos \phi \hat{j} + \rho \sin \phi \hat{k}$$

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

2º passo:

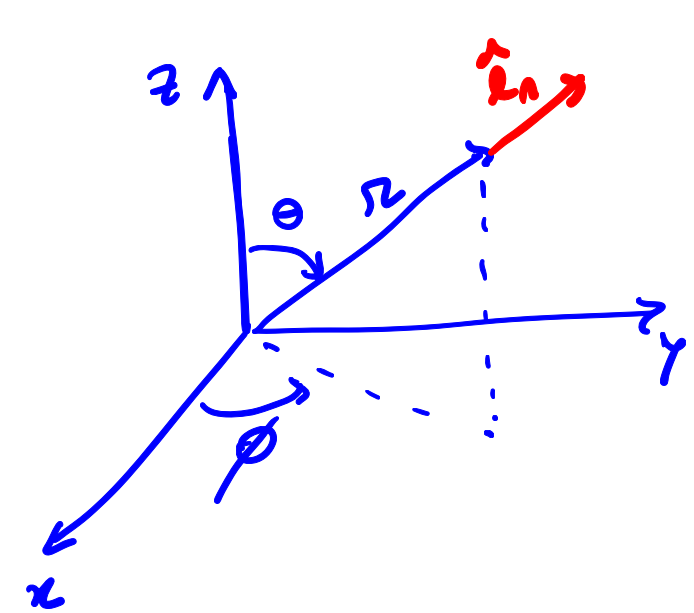
$$= z(\cos \phi \hat{e}_\rho - \sin \phi \hat{e}_\phi) + z\rho \cos \phi (\sin \phi \hat{e}_\rho + \cos \phi \hat{e}_\phi) + \rho \sin \phi \hat{e}_z$$

3º passo:

$$= (z \cos \phi + z\rho \cos \phi \sin \phi) \hat{e}_\rho + (-z \sin \phi + z\rho \cos \phi \cos \phi) \hat{e}_\phi + \rho \sin \phi \hat{e}_z$$

$$= (z \cos \phi + \rho \sin 2\phi) \hat{e}_\rho + (-z \sin \phi + z\rho \cos^2 \phi) \hat{e}_\phi + \rho \sin \phi \hat{e}_z$$

Vector position em coordenadas esféricas



$$r = \sqrt{x^2 + y^2 + z^2}$$

$$= |\vec{r}|$$

$$\vec{r} = r \hat{e}_r + 0 \hat{e}_\theta + 0 \hat{e}_\phi$$

$$\hat{e}_r = \frac{\vec{r}}{|\vec{r}|} \Rightarrow \vec{r} = |\vec{r}| \hat{e}_r = r \hat{e}_r$$

$$\Rightarrow \vec{r} = r \hat{e}_r$$