



Introdução à Programação 2020/2021

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- Dynamic Memory
- new operator
- Standard Template Library



- When we are writing a program, we often don't know how much data it will have to process.
- In these cases, we should only allocate memory as we actually need it at runtime, and release it again as soon as possible.
- This is the principle of dynamic memory management, which also has the advantage that a program doesn't need to be rewritten in order to process larger amounts of data.
- Under normal conditions, it is not possible to allocate more than 8MiB in the stack. For example, code like the following inside a function will give rise to an abnormal program termination:

```
int n = 10000000; // ten million
char s[n];        // too large
```

In these cases one needs to use dynamic memory allocation.



- A good understanding of how dynamic memory really works in C++ is essential to becoming a good C++ programmer.
- Memory in your C++ program is divided into two parts:
 - **stack** – All variables declared inside the function will take up memory from the stack.
 - **heap** – This is unused memory of the program and can be used to allocate the memory dynamically when program runs.
- We can allocate memory at run time within the heap for the variable of a given type using the special operator **new** which returns the address of the space allocated.
- If you are not in need of dynamically allocated memory anymore, you can use **delete** operator.



// Example 1

```
char* pvalue = NULL;           // Pointer initialized with null
pvalue = new char[20];         // Request memory for the variable
...
delete [] pvalue;              // Delete array pointed by pvalue
```

//Example 2

```
int** a = new int*[3];         // Allocate memory for a 3x4 array
for(int i = 0; i < 3; ++i)
    a[i] = new int[4];
...
for(int i = 0; i < 3; ++i) { // Delete array pointed by pvalue
    delete [] a[i];
}
delete [] a;
```

// Generally

```
ObjectType *obj = new ObjectType;
```



- The size of the executable file of the following program

```
int a[1000000];  
int main(void)  
{  
    return a[3];  
}
```

is very small (less than 10KiB)

- The size of the executable file of the following program

```
int a[1000000] = { 3 };  
int main(void)  
{  
    return a[3];  
}
```

is very large (4MiB).

- So, if possible, do not initialize large global variables.



Memory map

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highest addr	kernel memory area (inaccessible)	not used
	stack (grows to lower addresses)	for local variables and other function data
	empty	shrinks when the stack or heap grows
	heap (grows to higher addresses)	for dynamic memory allocation
	persistent data (read-write)	for global variables
	initialized persistent data (read only)	for constants
	empty	not used
	text (code)	program code
lowest addr	empty	guard region (never used)



- Talk about dynamic memory lead us to think about the STL. Why?
- Most computer programs exist to process data that may represent a wide variety of real-world information
- Whatever it represents, data is stored in memory and manipulated in similar ways
- University computer science programs typically include a course called “Data Structures and Algorithms”
- The term data structures refers to the ways data is stored in memory, and algorithms refers to how it is manipulated
- Standard C++ includes its own built- in container class library called the Standard Template Library (STL)
- STL can be used as a standard approach to storing and processing data
- [Introduction to Standard Template Library in C++](#)



- The three most important entity in STL are containers, algorithms, and iterators
 - A container is a way that stored data is organized in memory - the STL containers are implemented by template classes, so they can be easily customized to hold different kinds of data
 - Algorithms in the STL are procedures that are applied to containers to process their data in various ways (example: sort, copy, search, and merge data) - algorithms are represented by template functions
 - Iterators are a generalization of the concept of pointers: they point to elements in a container - are a key part of the STL because they connect algorithms with containers



- A container is a way to store data, whether the data consists of built-in types such as int and float, or of class objects
- The STL makes seven basic kinds of containers available, as well as three more that are derived from the basic kinds
- We can create our own container based on the basic kinds
- Two main categories:
 - sequence - vector, list, and deque (and stack, queue, and priority queue)
 - associative - set, multiset, map, and multimap
- Why not use C++ arrays in all data storage situations? The answer is efficiency and code simplicity...