



# TECNOLOGIAS PARA SISTEMAS DE ENERGIA ESPACIAIS

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A close-up photograph of a toroidal coil, which is a ring-shaped inductor. It is constructed from many turns of thick, reddish-brown copper wire. The coil is positioned against a light gray background. Two thin, silver-colored metal leads extend from the right side of the coil. The word "MAGNETISM" is superimposed in white, bold, sans-serif capital letters in the center of the image.

# MAGNETISM

Aula 3

# MAGNETIC FLUX DENSITY

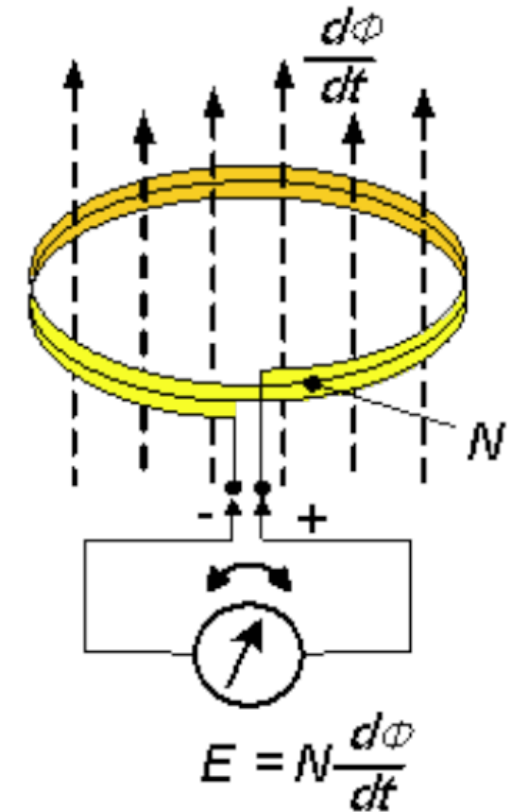
Magnetic Flux can be expressed by

$$\text{Magnetic flux density} = \frac{\text{magnetic flux}}{\text{area}}$$

the magnetic flux unity is called Henry x Ampere=Weber (Wb), and the magnetic Flux density,  $B$ , Wb/m<sup>2</sup> which is called Tesla.

$$B = \frac{\phi}{A}$$

$$B/H = \mu_0 \mu_r$$



# MAGNETIC FIELD

E – Electric Field  
H – Magnetic Field  
B – Magnet Flux Density  
D – Electric Flux Density

**Table 28-1**

## Some Approximate Magnetic Fields

At surface of neutron star	$10^8 \text{ T}$
Near big electromagnet	$1.5 \text{ T}$
Near small bar magnet	$10^{-2} \text{ T}$
At Earth's surface	$10^{-4} \text{ T}$
In interstellar space	$10^{-10} \text{ T}$
Smallest value in magnetically shielded room	$10^{-14} \text{ T}$

The Si units for the magnetic field density B, is newton per coulomb-meter per second, and this is normally called T (Tesla).

$$1 \text{ tesla} = 1T = 1 \frac{\text{newton}}{(\text{coulomb})(\frac{\text{meter}}{\text{second}})} = \frac{\text{newton}}{(\frac{\text{coulomb}}{\text{second}})(\text{meter})} = \frac{N}{A \cdot m}$$

Sometimes the magnetic field can also be expressed in Gauss which is  $1 \text{ Tesla} = 10_4 \text{ Gauss}$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial E}{\partial t}$$

Slide 23, class 2

# SLOWLY VARYING MAGNETIC FIELD

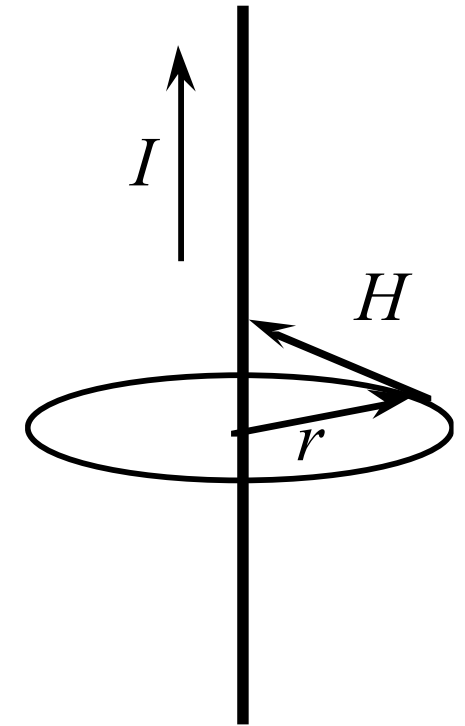
Magnetic fields can be described by ampere's law:

$$\oint \vec{H} d\vec{l} = \vec{J} + \frac{\partial \vec{D}}{\partial t} \rightarrow \oint \vec{H} d\vec{l} = N\vec{I} \quad \left( \frac{\partial \vec{D}}{\partial t} = 0 \right)$$

$$\oint \vec{H} d\vec{l} = 2\pi r H = N\vec{I}$$

$$H = \frac{NI}{2\pi r}$$

$$B/H = \mu_0 \mu_r$$



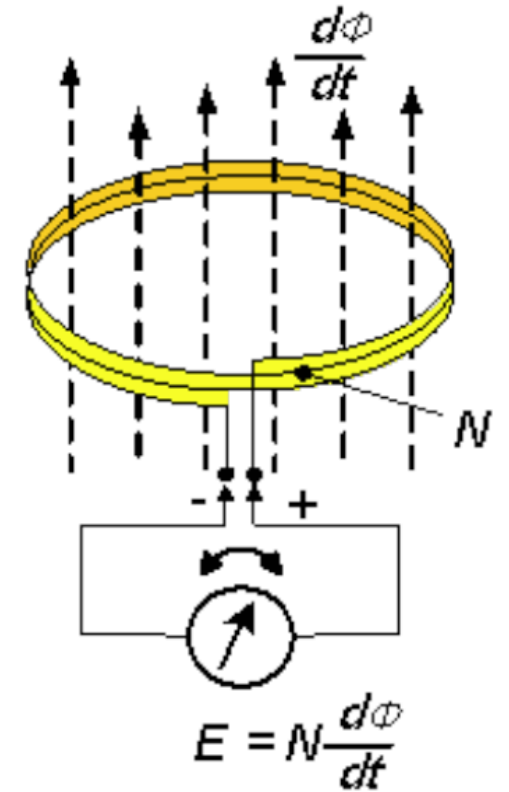
$NI$  is normally called magneto-motive force

Força magnetomotriz

# RELUCTANCE

Reluctance is equivalent to the “magnetic resistance” to the presence of the magnetic flux:

$$\text{Reluctance}, S = \frac{F_M}{\phi} = \frac{NI}{\phi} = \frac{Hl}{BA} = \frac{l}{\mu_0 \mu_r A}$$





# MAGNETIC CIRCUITS SUMMARY

In summary we can say, that the magnetic field strength  $H$  can be written as:

$$\int H dl = NI$$

$N$  is the number of turns and  $I$  the current through the solenoid.  $H$  can be related to the magnetic flux density by:

$$B = \mu_0 \mu_r H$$

Since the magnetic flux can be calculated by:

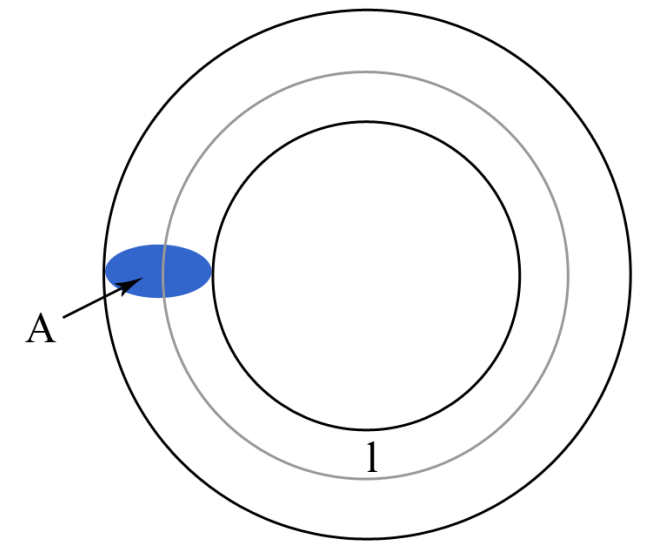
$$\Phi = BA$$

We can write:

$$\frac{\Phi}{A} = \mu_0 \mu_r H$$

And thus

$$H = \frac{\Phi}{\mu_0 \mu_r A}$$



# MAGNETIC CIRCUITS SUMMARY

Assuming  $H$  as uniform we have:

$$Hl = NI$$

And combining with the last equations we have:

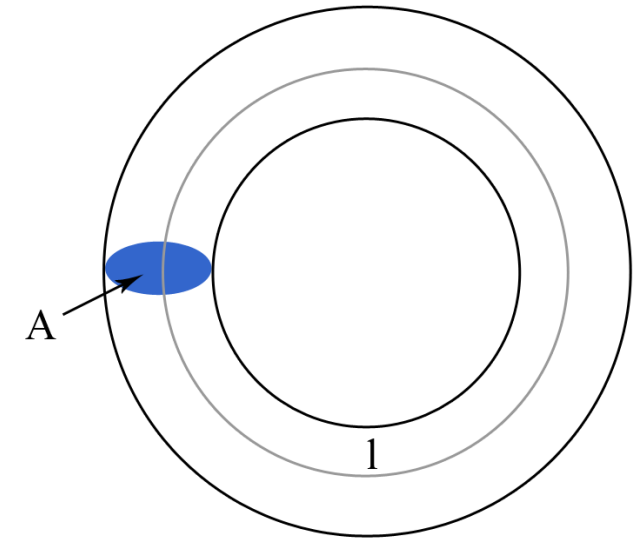
$$NI = \frac{\Phi l}{\mu_0 \mu_r A}$$

thus:

$$\Phi = NI / \frac{l}{\mu_0 \mu_r A}$$

We can thus write write:

$$\mathfrak{R} = \frac{l}{\mu_0 \mu_r A}$$





Lenz's Law - seeing that the magnetic field induced by a current induced by a change in magnetic flux (Faraday's Law) counteracts the change in flux.

# INDUCTANCE

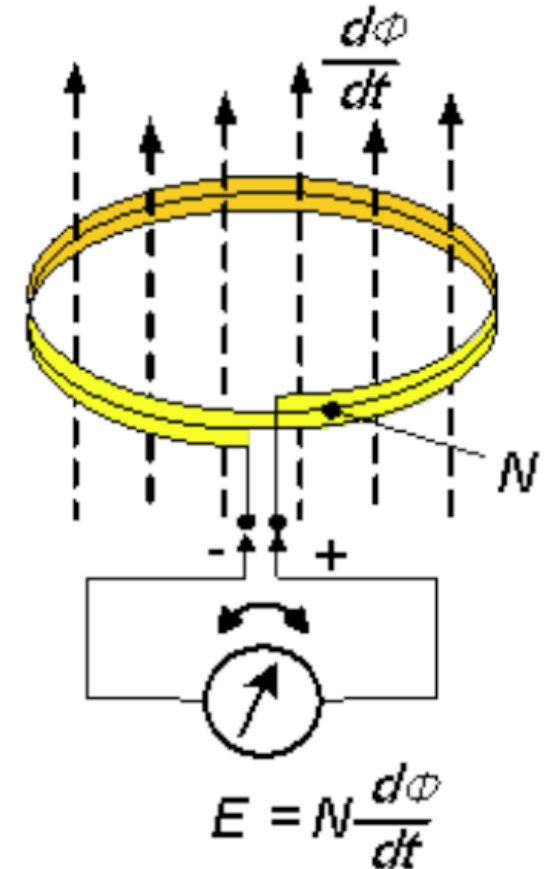
Looking back at Faradays law, we can write it as:

$$e = -\frac{\partial \Phi}{\partial t} \text{ (Lenz law)}$$

There is a relationship between the magnetic flux and the current, and that can be related by a constant, called inductance, L:

$$\Phi = BA = Li,$$

L is expressed in Henry's [H],



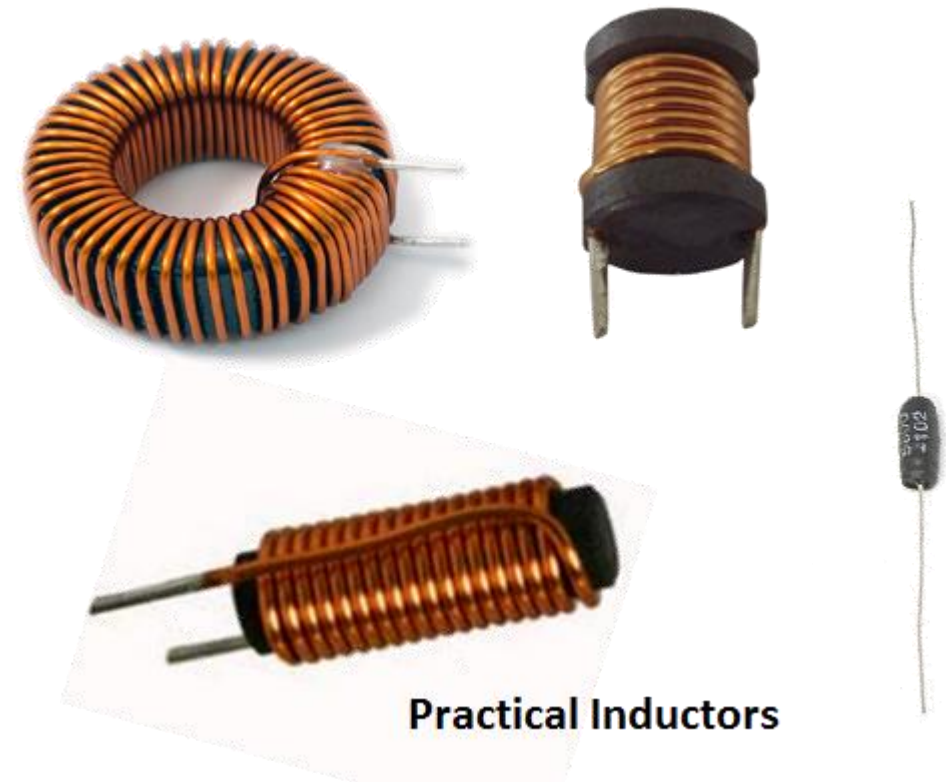
# INDUCTANCE

By deriving each part of the equation we have:

$$\frac{\partial \Phi}{\partial t} = L \frac{\partial i}{\partial t} \text{ and thus } e = -L \frac{\partial i}{\partial t}$$

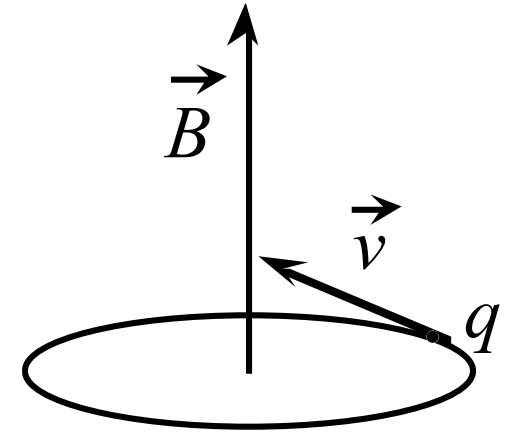
This equations give rise to the well known value of:

$$v = L \frac{\partial i}{\partial t}$$

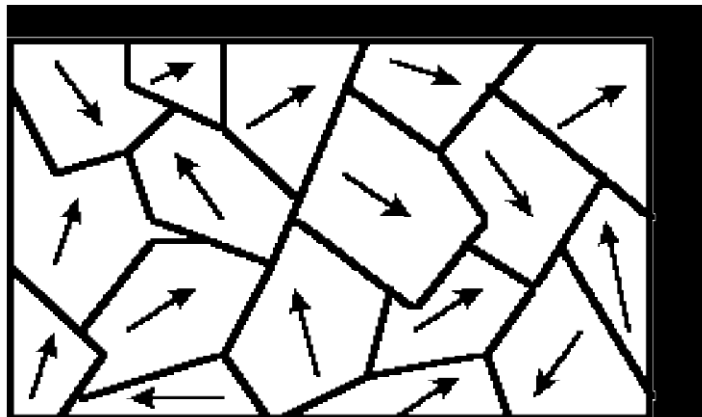


# FERROMAGNETIC MATERIALS

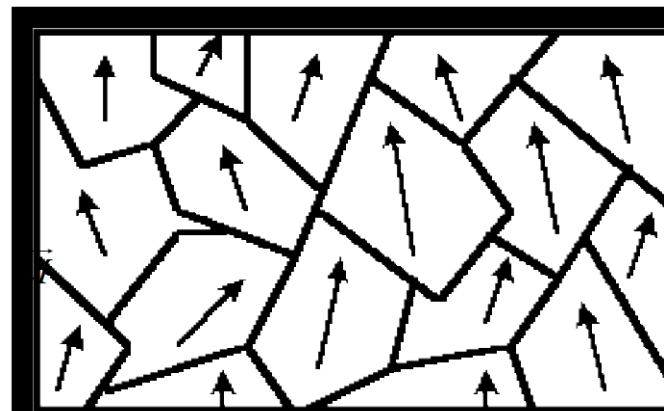
There are materials where its relative permeability,  $\mu_r$ , is several orders of magnitude higher than vacuum, and normally they are non-linear, these materials are called ferromagnetic, one of the most important materials is Iron.



Despolarizado



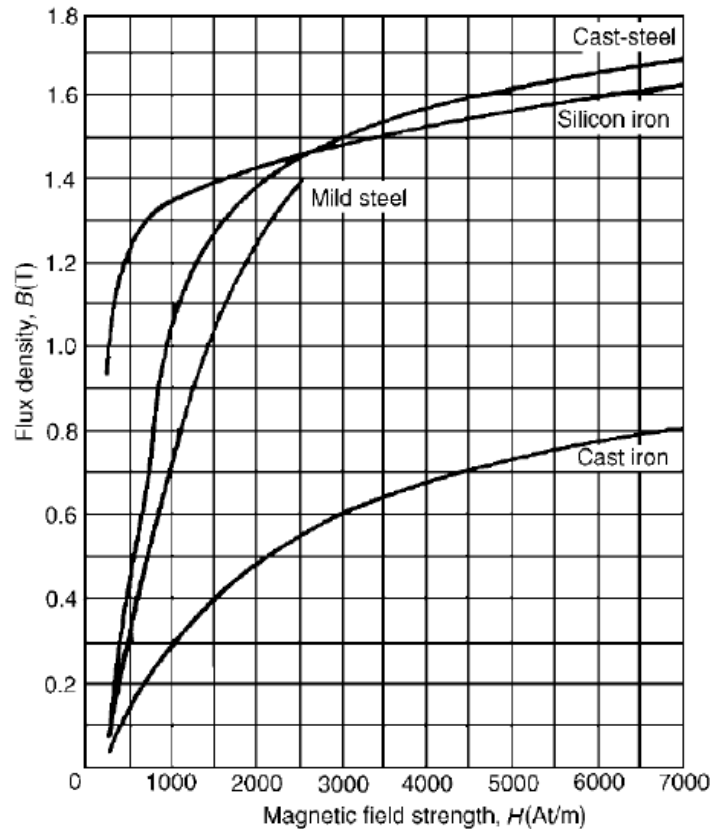
Polarizado



This phenomena changes for a certain temperature (called Curie point)

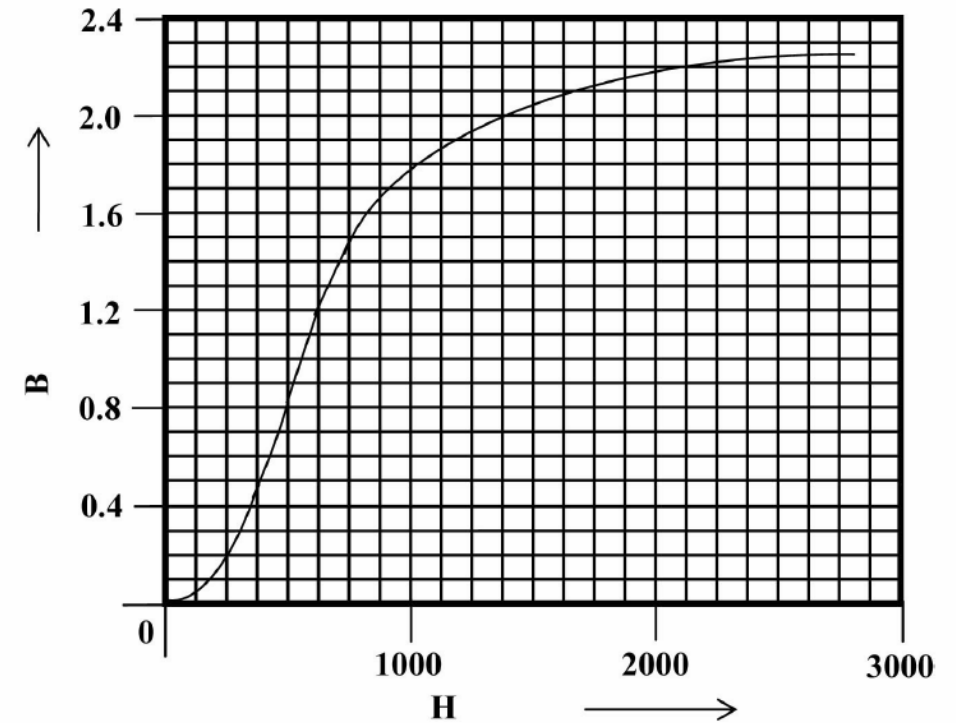
# FERROMAGNETIC MATERIALS

The magnetization curve in most material is:



Magnetic flux density

$$\vec{B} = \mu \vec{H}$$

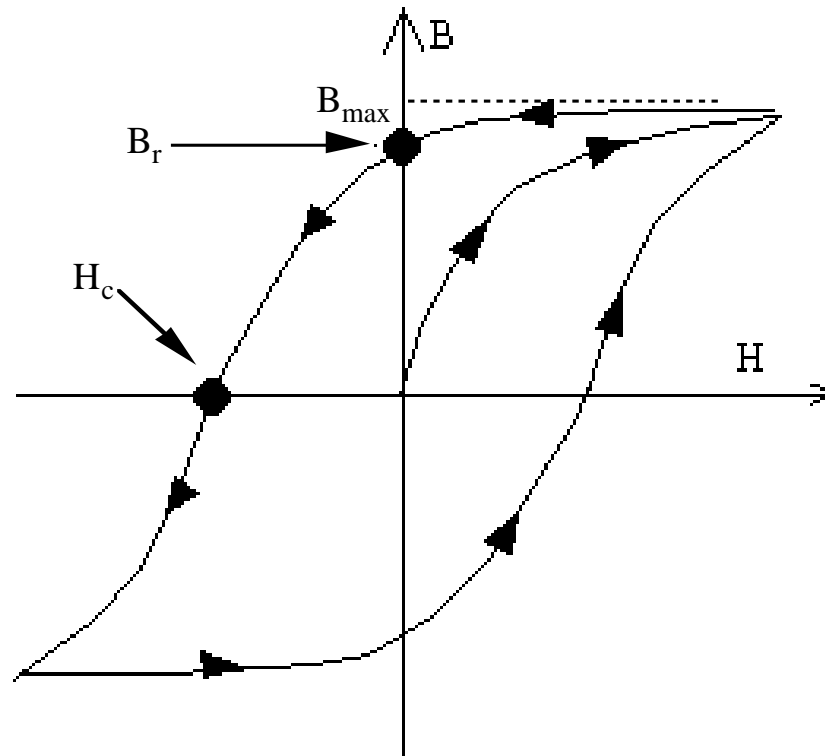


In this case in the linear part of the curve we have:  $3.2 \text{ mT/Am}$ , and thus the permeability is

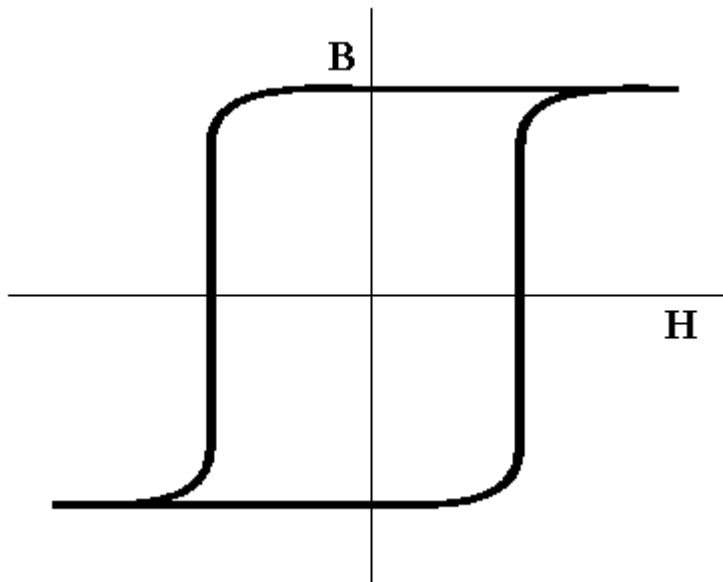
$$\mu_r = \frac{1}{\mu_0} \frac{dB}{dH} \approx 2546 \quad \text{permeabilidade}$$

# HYSTERESIS

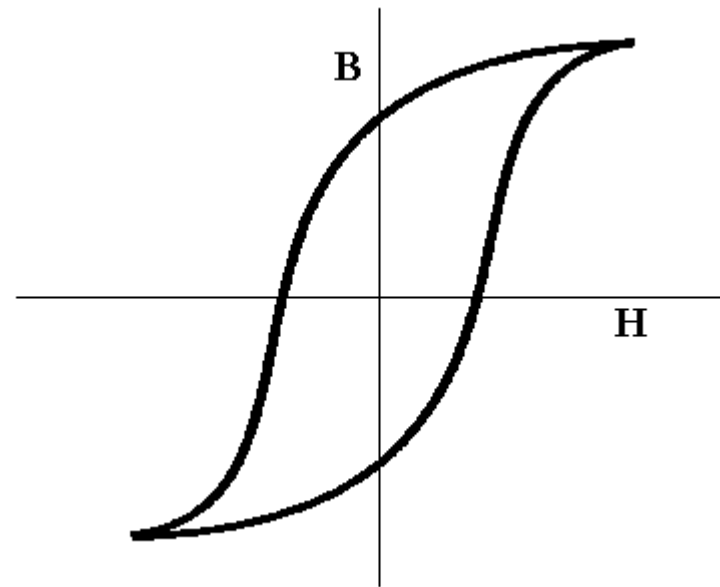
It is normal to find hysteresis in these materials, with different approaches.



# HYSTERESIS



Hard material

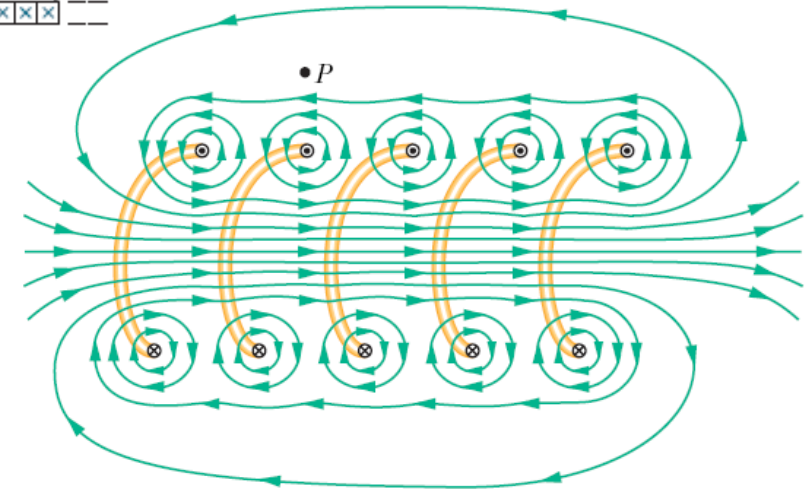
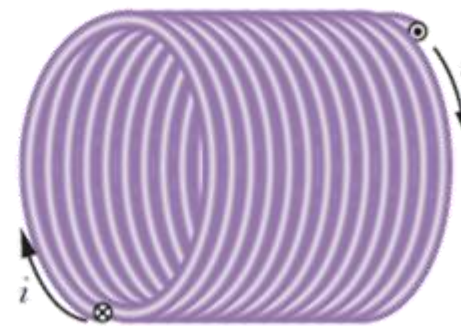
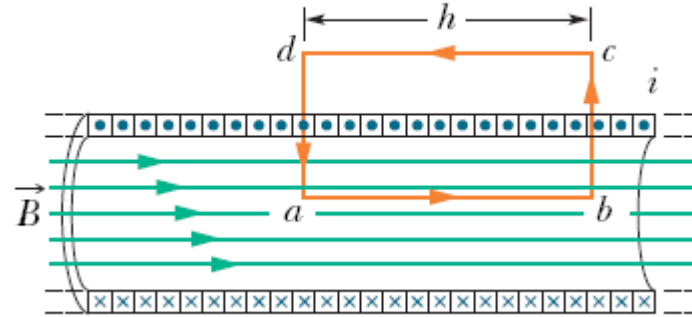


Soft material

# SOLENOIDS

$$H = \frac{B}{\mu}$$

$$\Phi = BA$$



$$\oint \vec{B} d\vec{s} = \mu_0 i_{enc}$$

$$\oint \vec{B} d\vec{s} = \int_a^b \vec{B} d\vec{s} + \int_b^c \vec{B} d\vec{s} + \int_c^d \vec{B} d\vec{s} + \int_d^a \vec{B} d\vec{s}$$

$$i_{enc} = IN$$

$$Bh = \mu_0 IN$$

$$B = \frac{\mu_0 IN}{h}$$

$$\Phi = \mu_0 \frac{NIA}{h}$$

$$\Phi = Li = L \frac{I}{N}$$

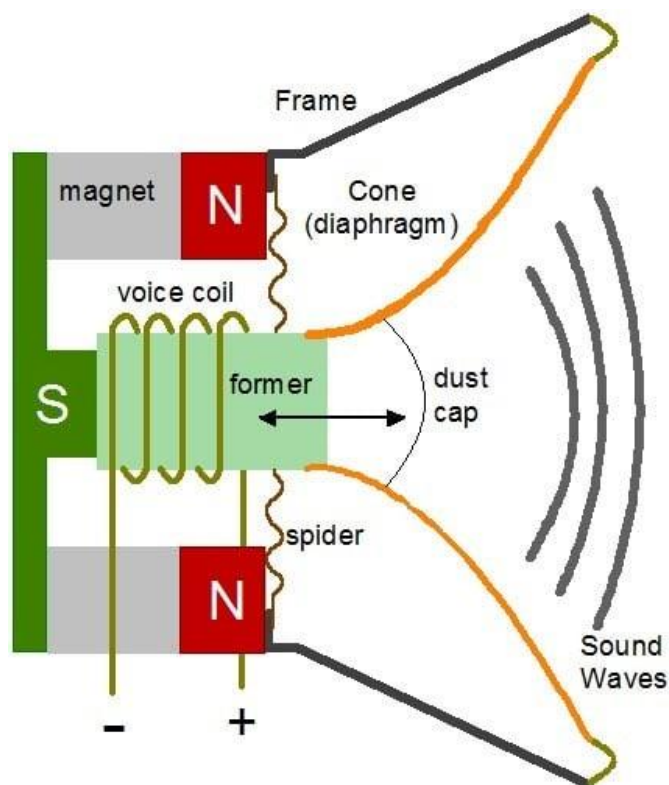
$$L = \mu_0 \frac{N^2 A}{h}$$

Here  $n=N/h$  is the number of turns per unit length of the solenoid



# SOLENOIDS

$$H = \frac{B}{\mu}$$
$$\Phi = BA$$



The force between magnetic field and current is:

$$\vec{F}_B = q\vec{v} \times \vec{B}$$

$$Force F = BIl \text{ newtons}$$

# MAGNETIC CIRCUITS SUMMARY

Consider a toroid with the mean length of 20cm, the cross section of 2 cm<sup>2</sup>, and the relative magnetic permeability of 6700. What is the magnetic flux and the magnetic flux density if the coil has 10 turns and the current is 2 amperes ?

$$\mathfrak{R} = \frac{l}{\mu_0 \mu_r A} = \frac{0,2}{4\pi 10^{-7} 6700 \cdot 2 \times 10^{-4}} = 1,19 \times 10^5 \text{ At/Wb}$$

Since

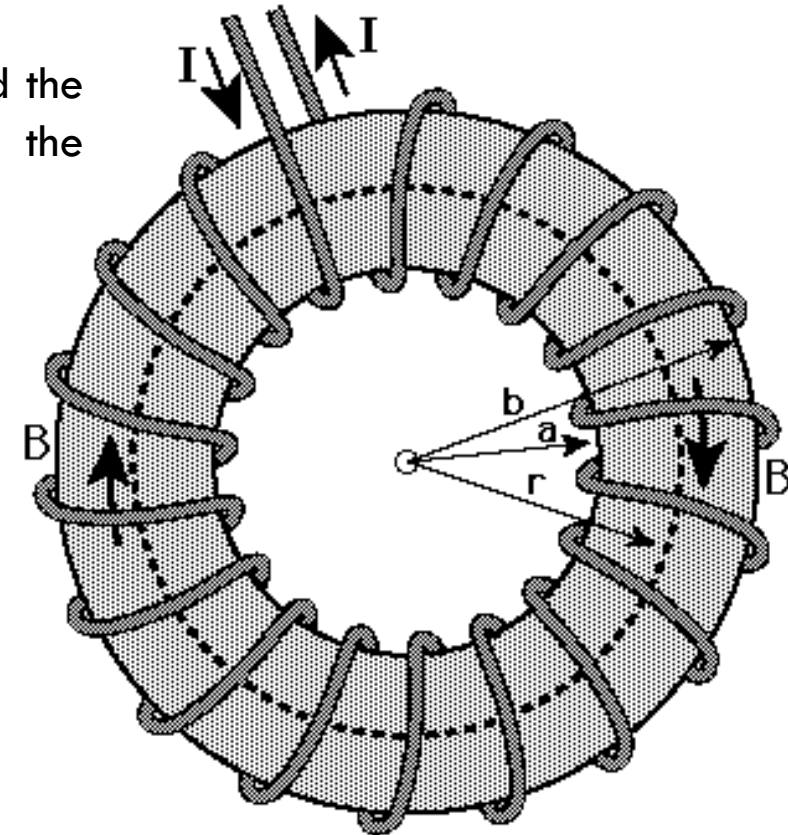
$$\mathfrak{R} = \frac{NI}{\Phi}$$

We can then calculate the flux as:

$$\Phi = \frac{NI}{\mathfrak{R}} = \frac{10 \times 2}{1,19 \times 10^5} = 1,68 \times 10^{-4} \text{ Wb}$$

The magnetic flux density will then be:

$$B = \frac{\Phi}{A} = 0,84 \text{ Wb/m}^2$$



At-Ampere turns

# STORED ENERGY IN INDUCTORS

Energy can be calculated by first consider the power in the component terminals:

$$p = \frac{dW_L}{dt} = vi$$

But in an inductor we have:

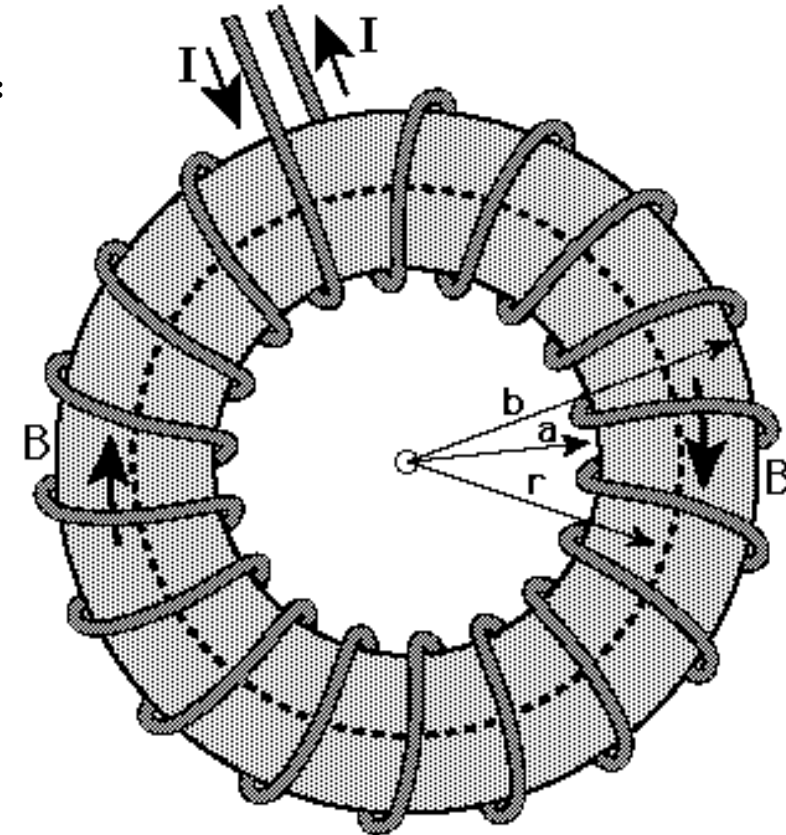
$$v = L \frac{di}{dt}$$

In this case we can thus calculate:

$$dW_L = Li \frac{di}{dt} dt = Lidi$$

By integration we can thus calculate the stored energy as:

$$W_L = \frac{1}{2} \int_0^I \frac{d}{dt} (Li^2) dt = \frac{1}{2} [Li^2]_0^I = \frac{1}{2} Li^2$$



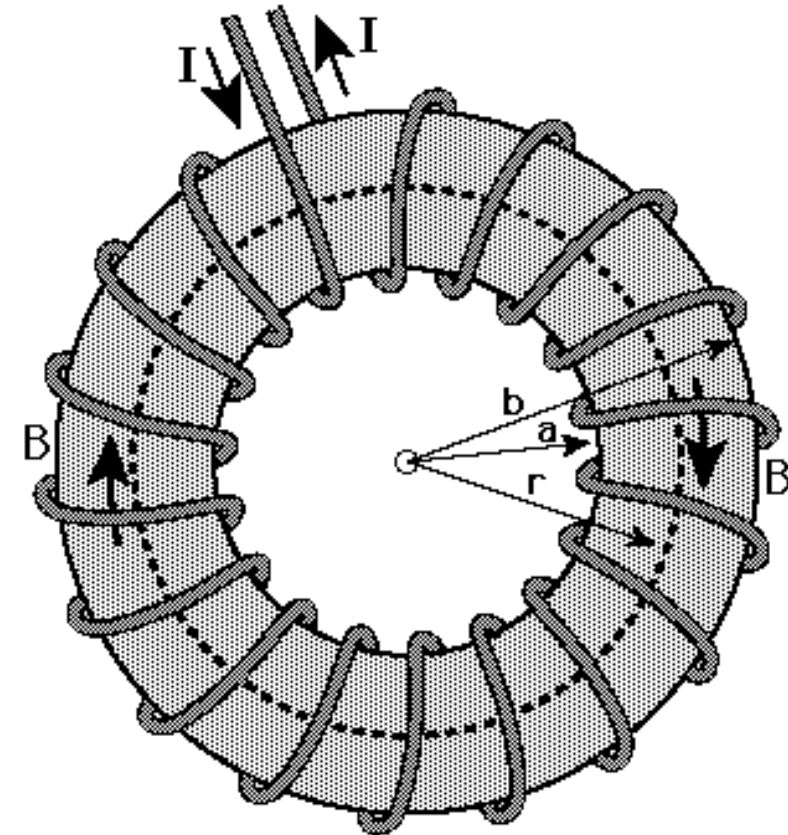
# STORED ENERGY IN INDUCTORS

Using the concept presented before we can also say that the stored energy per volume can be calculated as:

$$\frac{W}{Vol} = \frac{1}{2}BH$$

For a typical 1T field we can calculate the stored energy per volume which will be:

$$5000 \frac{J}{m^3}$$

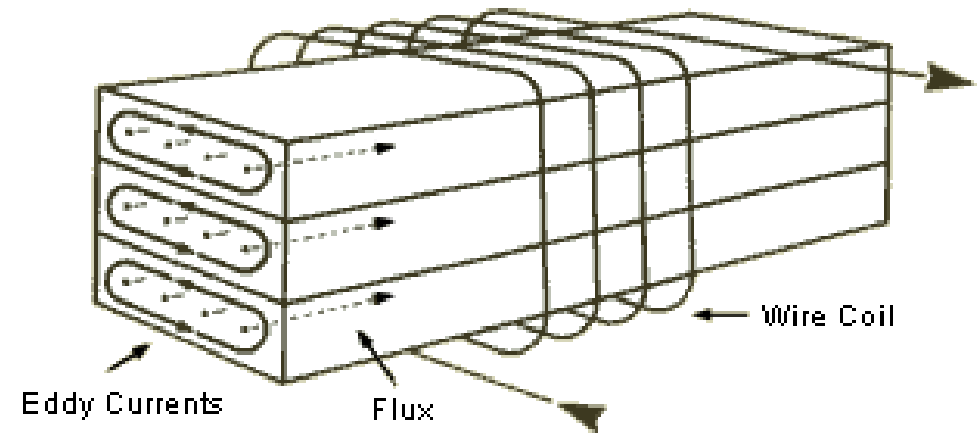
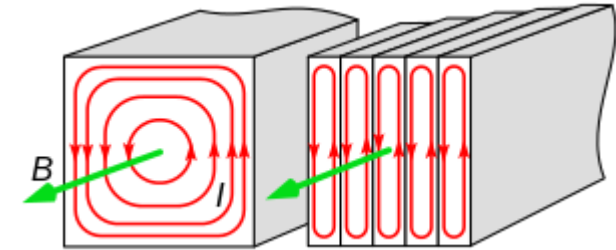
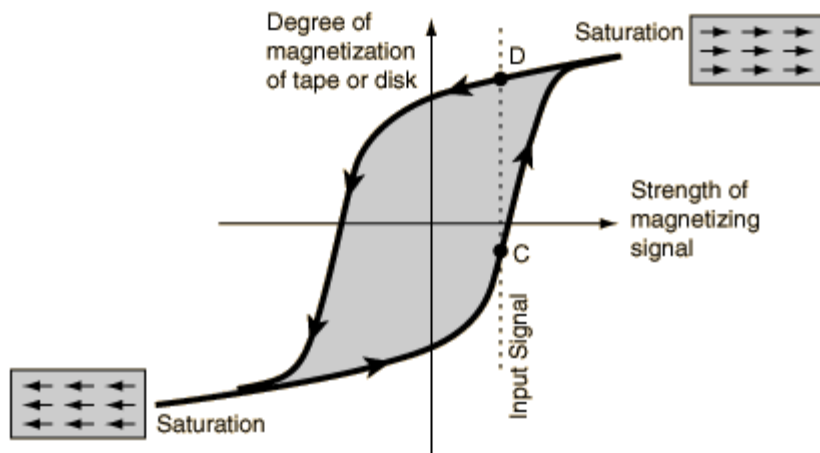


# MAGNETIC LOSSES

Losses in magnetic components can happen due to two main sources:

1. Hysteresis Losses
2. Inductive Losses (Eddy Currents)

Correntes de Foucault



# MAGNETIC LOSSES

**Hysteresis losses** can be calculated as the difference between the stored energy when the hysteresis cycle is driven in both directions, this difference can be expressed by:

$$p_H = k_1 f$$

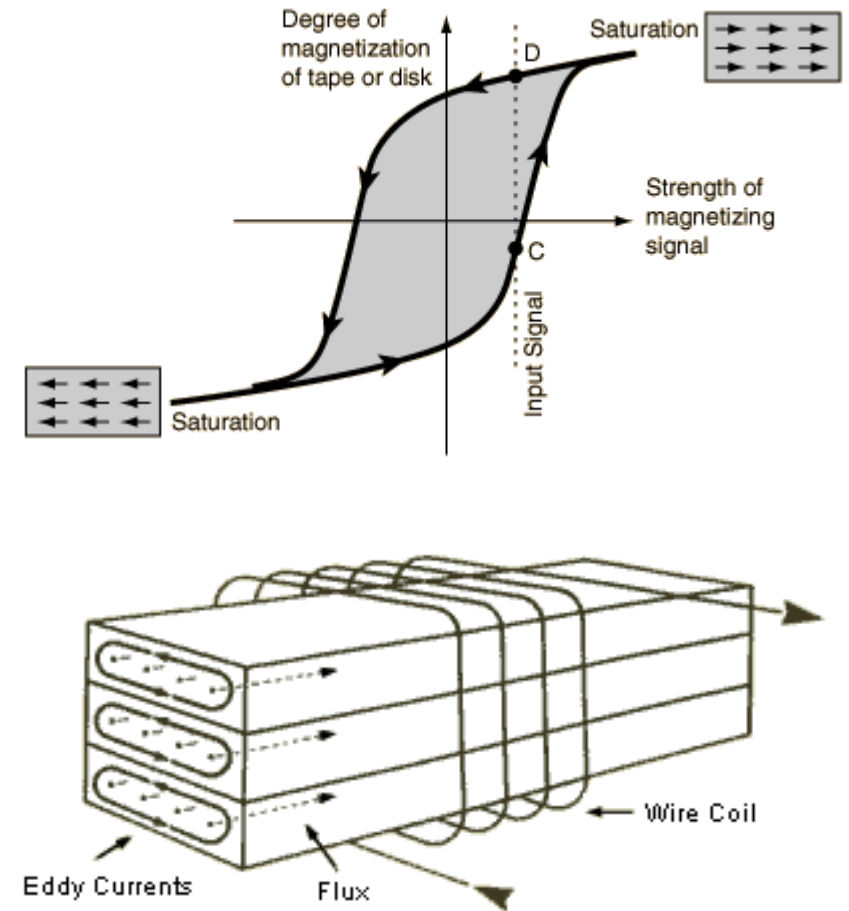
**Eddy Current Losses** are due to the magnetomotive force been induced in the ferromagnetic core, these currents are called eddy currents. This magneto force can be calculated by:

$$e = kf\Phi$$

The power losses can then be calculated by:

$$p_i = k_i f^2 \Phi^2$$

$$p_m = p_h + p_i$$





# MAGNETIC CIRCUITS

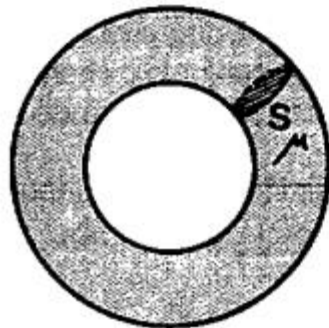


Fig. 63 — Circuito magnético homogéneo.

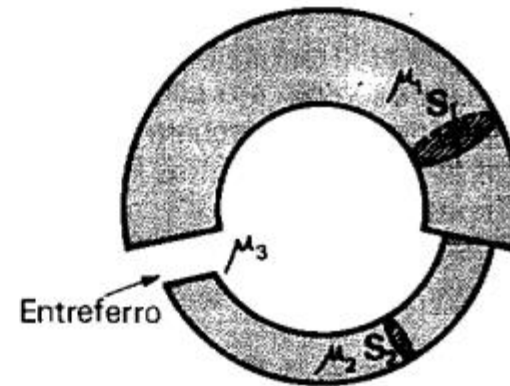
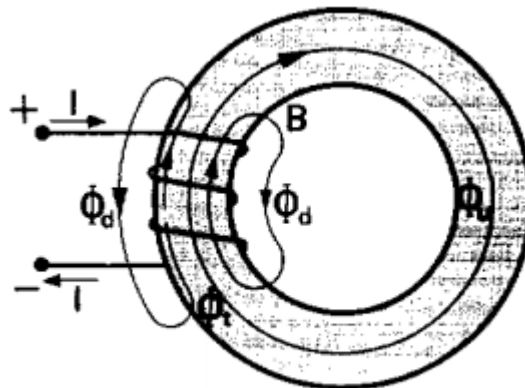


Fig. 64 — Circuito heterogéneo.



Dispersão magnética



# MAGNETIC CIRCUITS

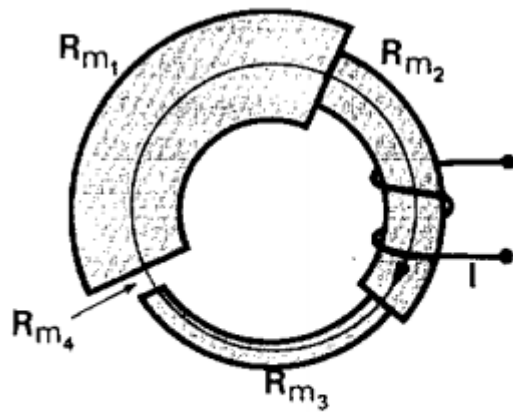


Fig. 69 — Circuitos magnéticos em série.

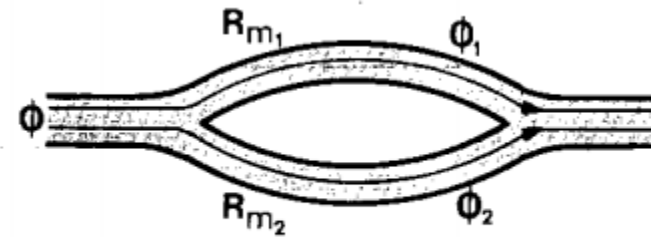


Fig. 70 — Circuitos magnéticos em paralelo.

# MAGNETIC CIRCUITS

- 1 — Considere o seguinte circuito magnético constituído por um núcleo de ferro rectangular e de secção quadrangular e que tem uma bobina de 300 espiras colocada num dos seus troços.

Determine o valor da corrente eléctrica que deve percorrer a bobina de modo que se obtenha uma indução de 1 T no ferro, sendo dada a curva de magnetização do ferro utilizado (curva dada em 2-3º) e as dimensões do núcleo que estão dadas em milímetros.

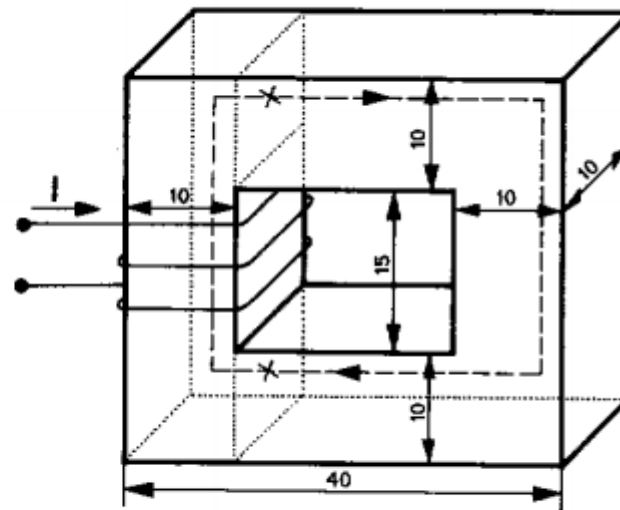


Fig. 71

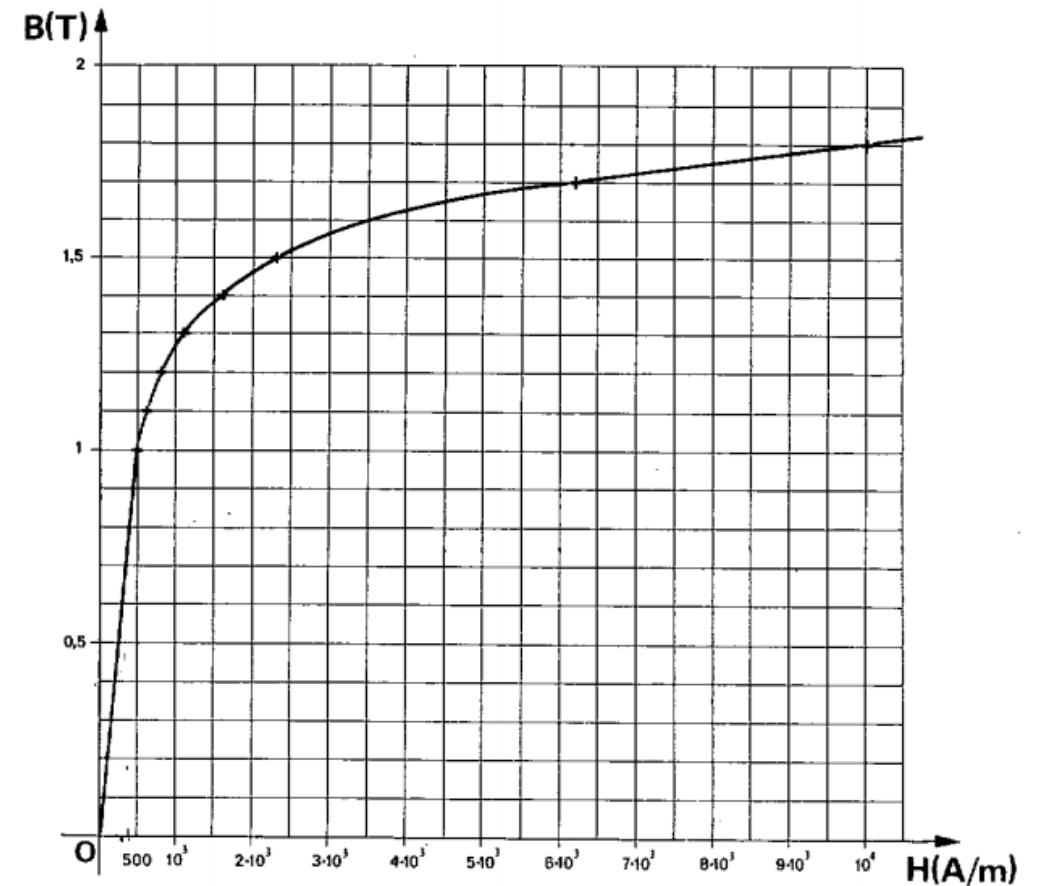


Fig. 54 — Curva de magnetização.

# MAGNETIC CIRCUITS

- 1 — Considere o seguinte circuito magnético constituído por um núcleo de ferro rectangular e de secção quadrangular e que tem uma bobina de 300 espiras colocada num dos seus troços.

Determine o valor da corrente eléctrica que deve percorrer a bobina de modo que se obtenha uma indução de 1 T no ferro, sendo dada a curva de magnetização do ferro utilizado (curva dada em 2-3º) e as dimensões do núcleo que estão dadas em milímetros.

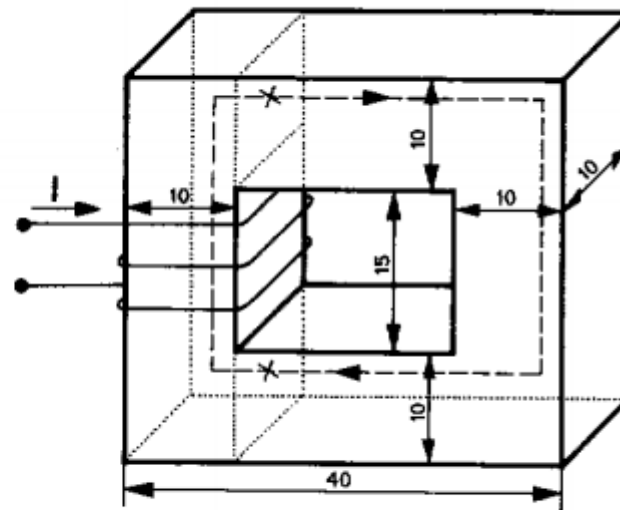


Fig. 71

Assuming  $H$  as uniform we have:

$$Hl = NI$$

For  $B=1\text{ T}$  this implies  $H=500\text{ Ae/m}$

$$l = (40 - 10) + (40 - 10) + (15 + 10) + (15 + 10) \\ = 110\text{ mm} = 0,11\text{ m}$$

thus:

$$Hl = 500 * 0,11 = 55\text{ Ae}$$

$$NI = 300I$$

$$Hl = NI \Rightarrow 55 = 300I$$

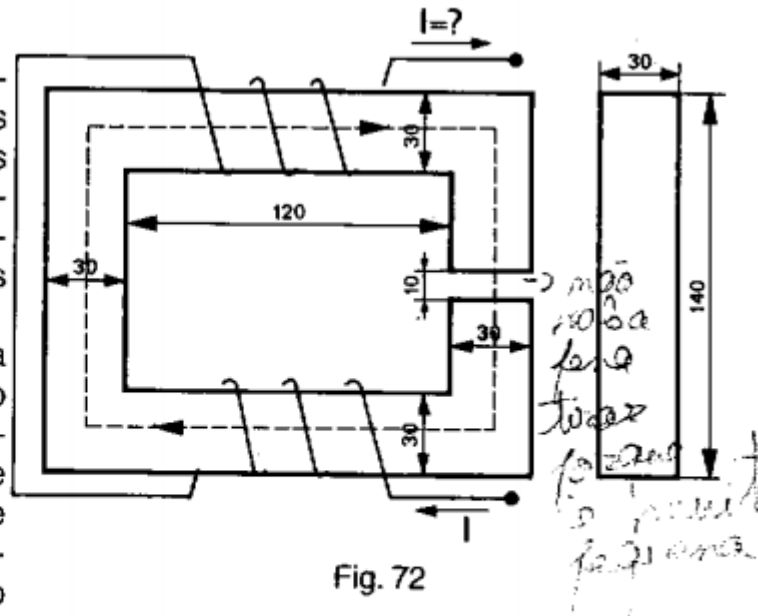
$$I = 0,18\text{ A}$$

# MAGNETIC CIRCUITS

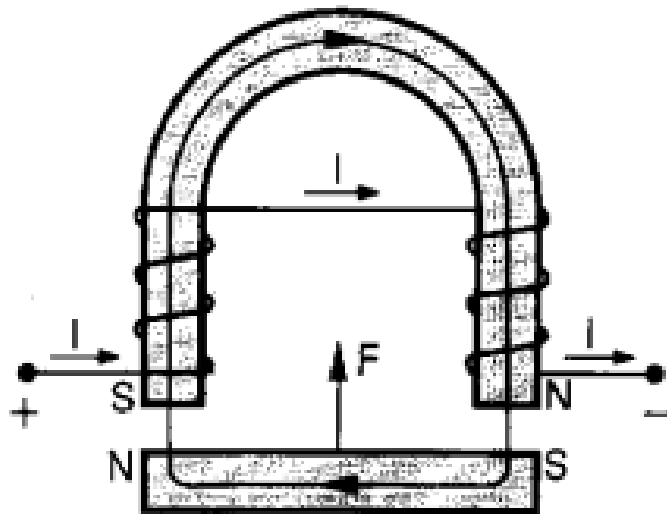
- 2 — Considere o circuito magnético representado cujas dimensões estão expressas em milímetros. As duas bobinas estão ligadas em série tendo cada uma delas 500 espiras.

Assim, sendo dada a curva de magnetização do ferro (a mesma do caso anterior) e a permeabilidade do ar, calcule a corrente que deve percorrer as bobinas para criar uma indução de 1,2 T no entreferro.

$$\mu_0 = \frac{1}{8 \cdot 10^5}$$



# MAGNETIC CIRCUITS



The force in this case will be:

$$F = \frac{B^2 A}{2\mu_0} = 400000B^2 A$$