

APPM 4600 - Lab 1

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1 Introduction

This is the lab 1 (Jan 14, 2025) report. Completed working with Hannah and Bryce

2 Pre-Lab

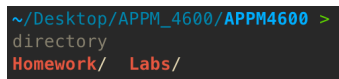
2.1 Part I



```
> python3 --version
Python 3.13.0
~/Desktop/APPM_4600 >
ancestor directory
Users/ mmiller/ Desktop/
```

Figure 1: Python3 installed.

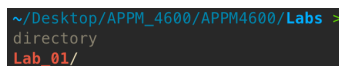
2.2 Part II



```
~/Desktop/APPM_4600/APPM4600 >
directory
Homework/ Labs/
```

Figure 2: APPM4600 directory created with Homework and Labs subdirectories.

2.3 Part III



```
~/Desktop/APPM_4600/APPM4600/Labs >
directory
Lab_01/
```

Figure 3: Lab 1 directory created.

2.4 Part IV

I have read through the remaining part of the lab document.

3 Lab-Day: Welcome to Python

The following subsections pertain to Part III of the lab: Welcome to Python.

3.1 Some Basics

```
Python 3.11.0 (main, Oct 7 2024, 05:02:14) [Clang 15.0.0 (clang-1500.1.0.2.5)] on darwin
Type "help", "copyright", "credits" or "license()" for more information.
>>>
```

Figure 4: Using the Python3 shell.

3.1.1 Vectors

```
python3
Python 3.11.0 (main, Oct 7 2024, 05:02:14) [Clang 15.0.0 (clang-1500.1.0.2.5)] on darwin
Type "help", "copyright", "credits" or "license()" for more information.
>>> x = [1,2,3]
>>> print(x)
[1, 2, 3]
>>> print(x[0])
1
>>> print(x[1])
2
>>> print(x[2])
3
>>> import numpy as np
>>> y = np.array([1,2,3])
>>> print(y)
[1 2 3]
>>> print(y[0])
1
>>> print(y[1])
2
>>> print(y[2])
3
>>>
```

Figure 5: Using generic python lists as well as numpy arrays.

3.1.2 Printing

```
>>> 3*y
array([3, 6, 9])
>>> print('This is 3y: ', 3*y)
This is 3y: [3 6 9]
>>>
```

Figure 6: Practicing printing values.

3.2 Plotting

The following is the code producing a plot of a sine function and a cosine function.

```
2 # Importing Libraries
3 import numpy as np
4 import matplotlib.pyplot as plt
5
6 # Part 3.2 Code: Plotting
7 X = np.linspace(0, 2 * np.pi, 100)
8 Ya = np.sin(X)
9 Yb = np.cos(X)
10
11 plt.plot(X, Ya)
12 plt.plot(X, Yb)
13 plt.show()
```

Figure 7: Plotting Code

The above code in **Figure 7** produces the plot below in **Figure 8**.

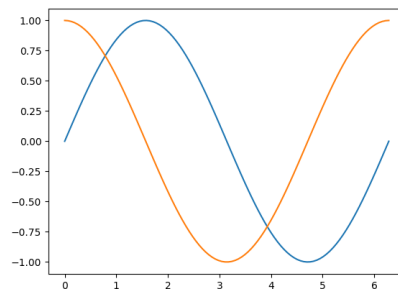


Figure 8: Sine and Cosine Plot.

The variable **X** is essentially a 1-D *numpy* array created using *numpy*'s **linspace** function. **X** is an array of length 100 meaning that it has 100 evenly spaced numbers beginning at 0 and ending at 2π .

3.3 Exercises: The Basics

3.3.1

The following is the code and output for Question 1.

```

16 # Question 1:
17 x = np.linspace(0, 9, 10)
18 y = np.arange(0, 10, 1)
19 print(x)
20 print(y)

```

Figure 9: Code for Question 1.

```

> python3 Lab_01.py
[0. 1. 2. 3. 4. 5. 6. 7. 8. 9.]
[0 1 2 3 4 5 6 7 8 9]
~/Desktop/APPM_4600/APPM4600/Labs/Lab_01 >
directory
venv/

```

Figure 10: Output for Question 1.

3.3.2

The following is the code and output for Question 2.

```

24 # Question 2:
25 print(x[:3])
26 print(y[:3])

```

Figure 11: Code for Question 2.

```

[0. 1. 2.]
[0 1 2]
~/Desktop/APPM_4600/APPM4600/Labs/Lab_01 >
directory
venv/

```

Figure 12: Output for Question 2.

3.3.3

The following is the code and output for Question 3.

```

28 # Question 3:
29 print("The first three elements of x are: ", x[:3])

```

Figure 13: Code for Question 3.

```

The first three elements of x are: [0. 1. 2.]
~/Desktop/APP4600/APP4600/Labs/Lab_01 > 
directory
venv/

```

Figure 14: Output for Question 3.

3.3.4

The following is the code and output for Question 4.

```

3 # Question 4:
4 w = 10**(-np.linspace(1,10,10))
5 x1 = np.arange(0, len(w), 1)
6 plt.semilogy(x,w)
7 plt.show()

```

Figure 15: Code for Question 4.

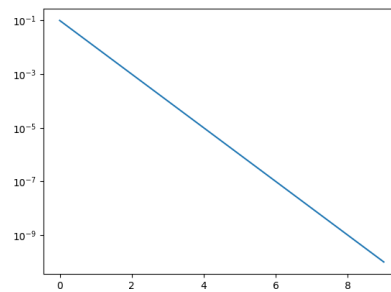


Figure 16: Output for Question 4.

As shown above in the plot in Figure 12, the values of \mathbf{w} are: 1.e-01, 1.e-02, 1.e-03, 1.e-04, 1.e-05, 1.e-06, 1.e-07, 1.e-08, 1.e-09, and 1.e-10.

3.3.5

The following is the code and output for Question 4.

```

3 # Question 5:
4 s = 3*w
5 plt.semilogy(x,s)
6 plt.show()

```

Figure 17: Code for Question 5.

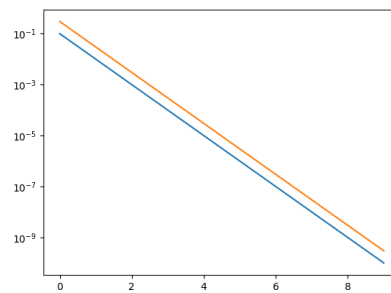


Figure 18: Output for Question 5.

4 Practical Code Design

4.0.1 Question I

The following is the code and the output for Question 1 of Part 4.

```

'''
driver1()
Param:
Return:
This function serves as the driver for the dot product subroutine
'''
def driver1():
    n = 3
    y = [1,0,0]
    w = [0,1,0]
    # evaluate the dot product of y and w
    dp = dotProduct(y,w,n)
    # print the output
    print('the dot product is : ', dp)
    return

```

Figure 19: Code for Question 1.

```

> python3 testDot.py
the dot product is : 212660.24304678725
the dot product is : 0.0
~/Desktop/APPM_4600/APPM4600/Labs/Lab_01 > █
directory
venv/

```

Figure 20: Output for Question 1.

4.0.2 Question II

The following is the code and the output for Question 2 of Part 4.

```

'''
driver2()
Param:
Return:
This function serves as the driver for the dot product subroutine for matrix
multiplication.
'''
def driver2():
    small_matrix = np.array([[1,2],[3,4]])
    small_vector = np.array([5,6])

    large_matrix = np.random.randint(0,10, (100,100))
    large_vector = np.random.randint(0,10, 100)

    dps = dotProduct(small_matrix, small_vector, 2)
    print('the matrix multiplication is: ', dps)

    dpl = dotProduct(large_matrix, large_vector, 100)
    print('the matrix multiplication is: ', dpl)
    return

```

Figure 21: Code for Question 2.

```

python3 testDot.py
the dot product is : 212660.24304678725
the dot product is : 0.0
the matrix multiplication is: [23, 34]
the matrix multiplication is: [1960, 2815, 1798, 2136, 1911, 2100, 2106, 2240, 1883, 2005, 2413, 2227,
2201, 2214, 2483, 1972, 2386, 2441, 1824, 2056, 2142, 2036, 1983, 1877,
7210, 2110, 2035, 2267, 2003, 2062, 2140, 2131, 2271, 2040, 1878, 2125,
2003, 2006, 2121, 1937, 2115, 1718, 2067, 1731, 1874, 1925, 1937, 1963,
2303, 2030, 2119, 1804, 2185, 1897, 1872, 2240, 2377, 2144, 2189, 2128,
1872, 2007, 2023, 1804, 2149, 2327, 2130, 2076, 2420, 2040, 2179, 2322,
2322, 2003, 1991, 2199, 1895, 2122, 2025, 2115, 2300, 1908, 2088, 2317,
2277, 2031, 2103, 2337, 2136, 2019, 1935, 2094, 2051, 2419, 2172, 2400,
1974, 2119, 2093, 2146]
~/Desktop/APPM_4600/APPM4600/Labs/Lab_01 > █
directory
venv/

```

Figure 22: Output for Question 2.

4.0.3 Question III

Both the dot product and matrix multiplication subroutines can be accomplished using *numpy*'s **dot** function. This function can calculate the inner product of two vectors as well as matrix multiplication of any matrices or matrix vector combination. I believe that the *numpy* function is faster based on the fact it is a widely used and very well maintained python library but I am not certain as I am not too sure how to measure and compare the speed of my code versus the library.