

# **AMP | Advanced Mission Planning**

**Pre-Planning & Real-Time Warfighting Mission Capabilities in a Multi-Domain Battlespace** 

# **PHANTOM** WORKS



Automated Mission Planning Tools Cooperative Pre-Mission Dynamic Planning Across Assets

2 DCP | Decentralized Collaborative Planner

Leverage Existing Planning Capabilities
Machine Level Coordination
Automated Mission Planning Across Disparate Nodes
Dynamic Planning for Multi-Domain Operations

3 IRMA | IR Management Aid

Pilot Aid for Real-Time IR Situational Awareness Susceptibility & Cues to Delay Tracks

4 DART | Depression Angle Reference
Tracking Algorithm

Pilot Aid for Airborne RCS Assessment & Mission Systems

5 SLEDGE | Simulated Layered Effectiveness & Detectability Graphical Environment

Mission Planning Visualization Hub Interactive All-Domain, Multi-Spectral, & Multi-Static Threats



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# **DCP | Decentralized Collaborative Planner**

### **Rapid Decision Planning & Execution Across Multi-Domain Nodes**

## **Kill-Chain Advantage**

- Streamline multi-domain premission and dynamic real-time planning and increase mission effectiveness
- Enhanced scalability & resilience of the real-time mission via distributed planning
- Maintain multi-domain kill chain timelines in a rapidly changing tactical environment

**Streamlined Dynamic Planning to Enable New Capabilities for the** Warfighter

#### Overview

Service that leverages existing domain-specific planning capabilities to provide machine-tomachine level coordination for automated mission planning across disparate nodes

### **Capabilities**

- Disparate node task planning
- Configurable task decomposition methods
- Operational & tactical nodes for cooperative air-space planning
- Autonomous mission management

#### **Architecture Functionality**

- Meta task request or assignment from UI or parent node
- Decompose task into sub-task with constraints
- Flow task into mission planner component to request availability & performance metrics
- Aggregate & generate COA coordinate & assignments
- Manage response to mission alerts

## **Specifications**

#### Software Service

- Hierarchical Task Network (HTN) technology
- Provide cooperative mission planning & execution
- Dynamic resource management
- Sensing, communication, & weapon resources across planning nodes / domains

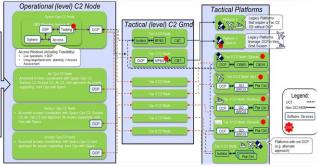
#### Machine-to-Machine (M2M) Coordination

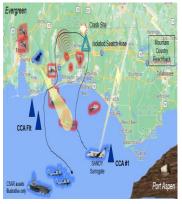
- · Tactically relevant
- · Adjust to battlespace as changes occur

#### **Industry & Government Specs**

- OMS
- UCI









ELINT

UAS C2

DCP

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