

Adaptable APIs and TAK Integration

Generating Sharable Interoperability from OV-1 through Runtime

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30 Aug 2023



System of systems Technology Integration Tool Chain for Heterogeneous Electronic Systems

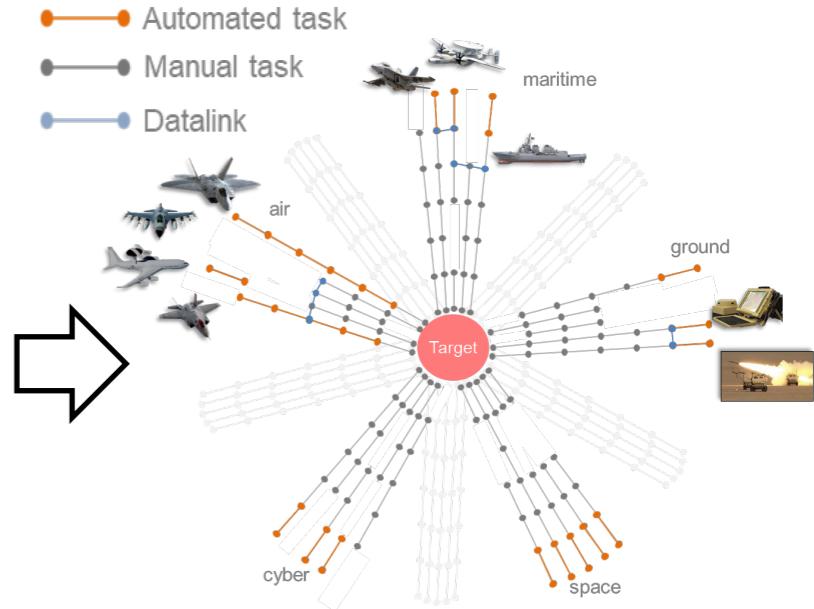
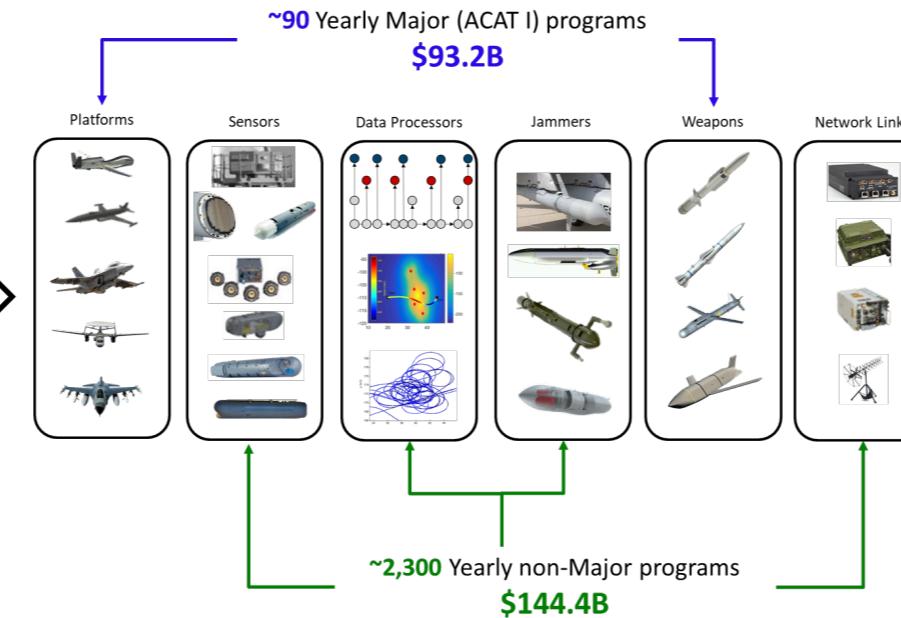


DoD creates “MWS-locked” capabilities



DoD delivers capability over years of process

Individual capabilities are **stove-piped** within major weapon systems

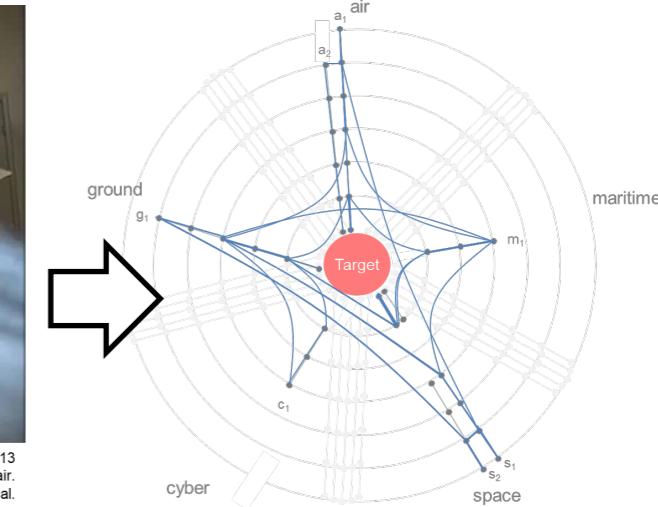


New capabilities from existing systems cannot be created faster than the threat adapts

Warfighters want adaptable machine-to-machine capabilities they can connect at mission planning time



HOWARD, R. et al. (2005). Apollo 13, Universal City, CA, Universal.



STITCHES A word on military standards/specifications

- MIL SPEC standardization started post WWII for:
 - “the ability to swap out vehicle subsystems in the highly likely event that they were to be damaged in combat”
- 1994: **45,500 mil specs existed**
- SecDef Perry mandated MIL SPEC reform
 - Reduced MIL SPECS to **~28,300 by 2003**
 - Encouraged non-govt standards and industry-wide practices
 - Specifications and standards listed in DoD Instruction 5000.2 are not mandatory for use and should be viewed as guidance

The Current State of Human Factors Standardization

In June 1994, Secretary of Defense William Perry issued new rules for the use of military specifications and standards. The memorandum stated:

Performance specifications shall be used when purchasing new systems, major modifications, upgrades to current systems, and non-developmental and commercial item for programs in any acquisition category. If it is not practicable to use a performance specification, a non-government standard shall be used. Since there will be cases when military specifications are needed to define an exact design solution because there is no acceptable non-governmental standard or because the use of a performance specification or non-government standard is not cost effective, the use of military specifications and standards is authorized as a last resort, with an appropriate waiver.

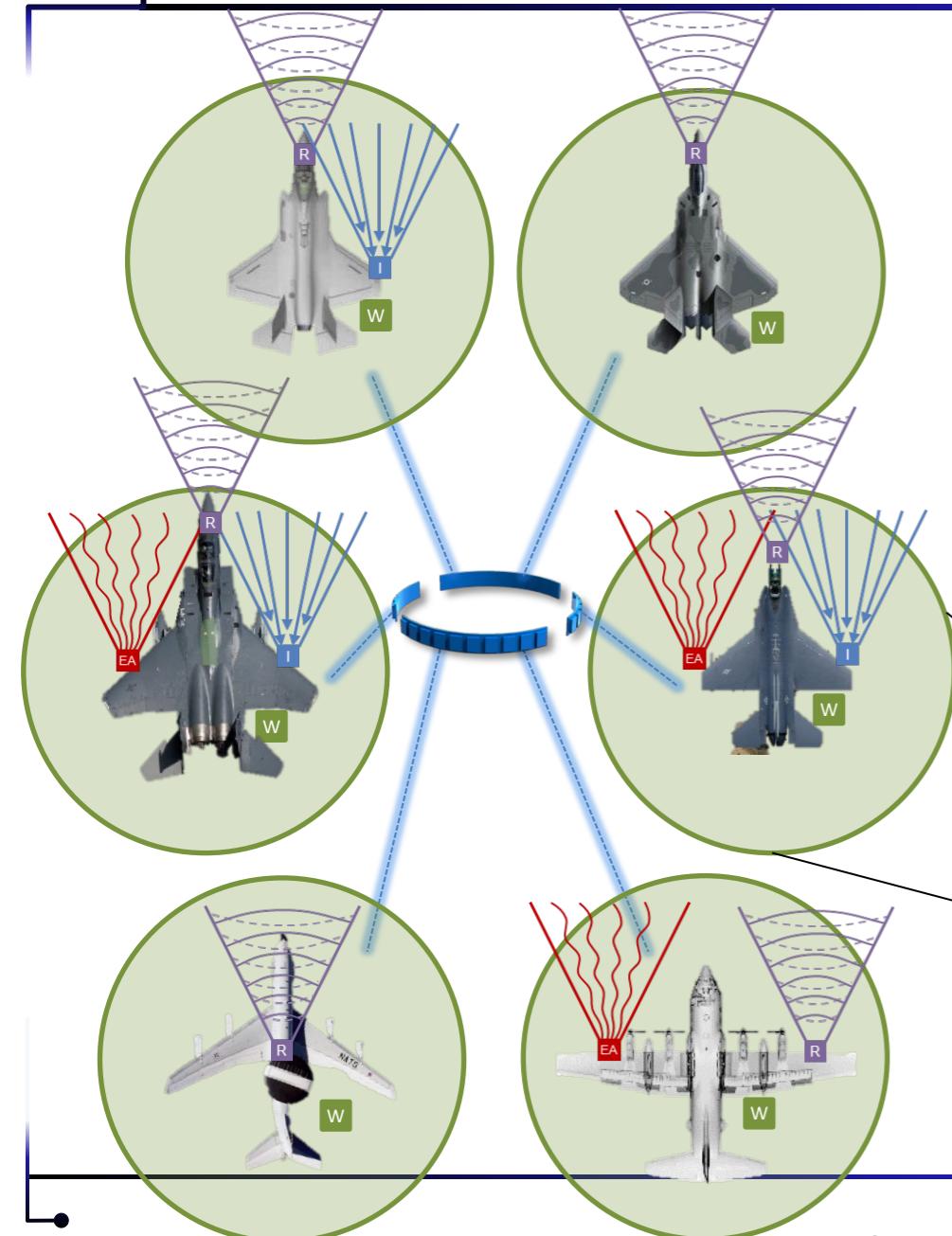
Other key provisions of the memorandum were:

- To encourage contractors to propose non-government standards and industry-wide practices that meet the intent of the military specifications and standards
- That specifications and standards listed in DoD Instruction 5000.2 are not mandatory for use and should be viewed as guidance
- That first-tier references cited in contracts are mandatory for use while lower tier references are for guidance only, and are not contractually binding

<http://iac.dtic.mil/hsiac>

continued on next page...

Challenge Acquisition Requirements: Program Managers and acquisition decision makers at all levels shall challenge requirements because **the problem of unique military systems does not begin with the standards**. The problem is rooted in the **requirements determination phase** of the acquisition cycle. - William J. Perry, 29 June 1994



Adding interoperability between aircraft takes years

- Aircraft are upgraded independently creating unique messages
- Machine-to-machine interfaces in an aircraft are highly coupled
- Even coupling between versions of the same spec (e.g., Link-16) is problematic

This interoperability problem occurs within the aircraft as well

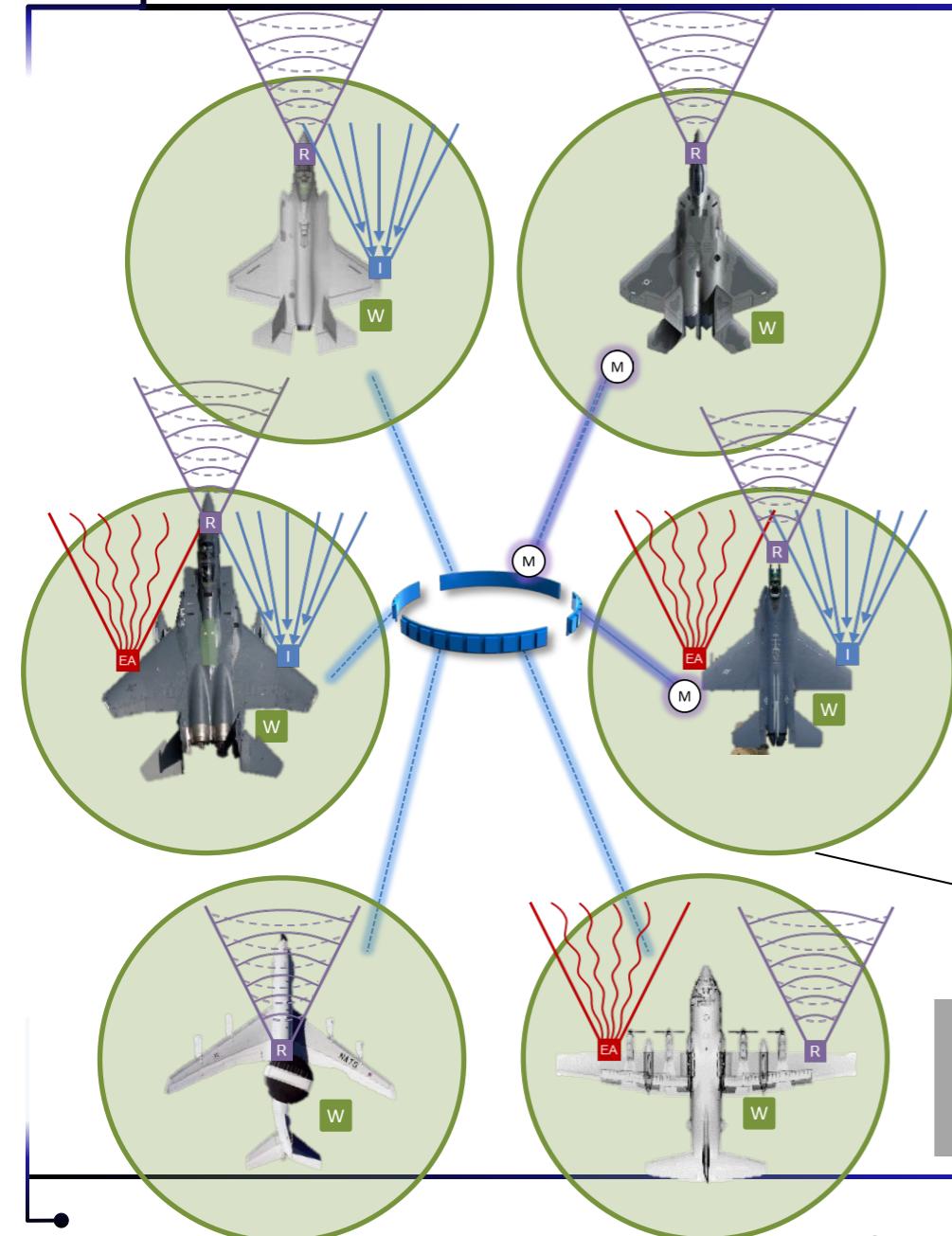
- Components are tightly coupled together using a local message standard that doesn't match the documentation
- Adding new technology (e.g., sensor) requires upgrades to multiple components, increasing expense and time

Each aircraft is collection of independent subsystems designed at different eras requiring interoperability

Interoperability is programmed into each system System upgrades compete in 2-3 year block cycles

Global standards have similar issues

- No interoperability between generations of the standard
- Uncertain interoperability between implementations



STITCHES efficiently generates message translators

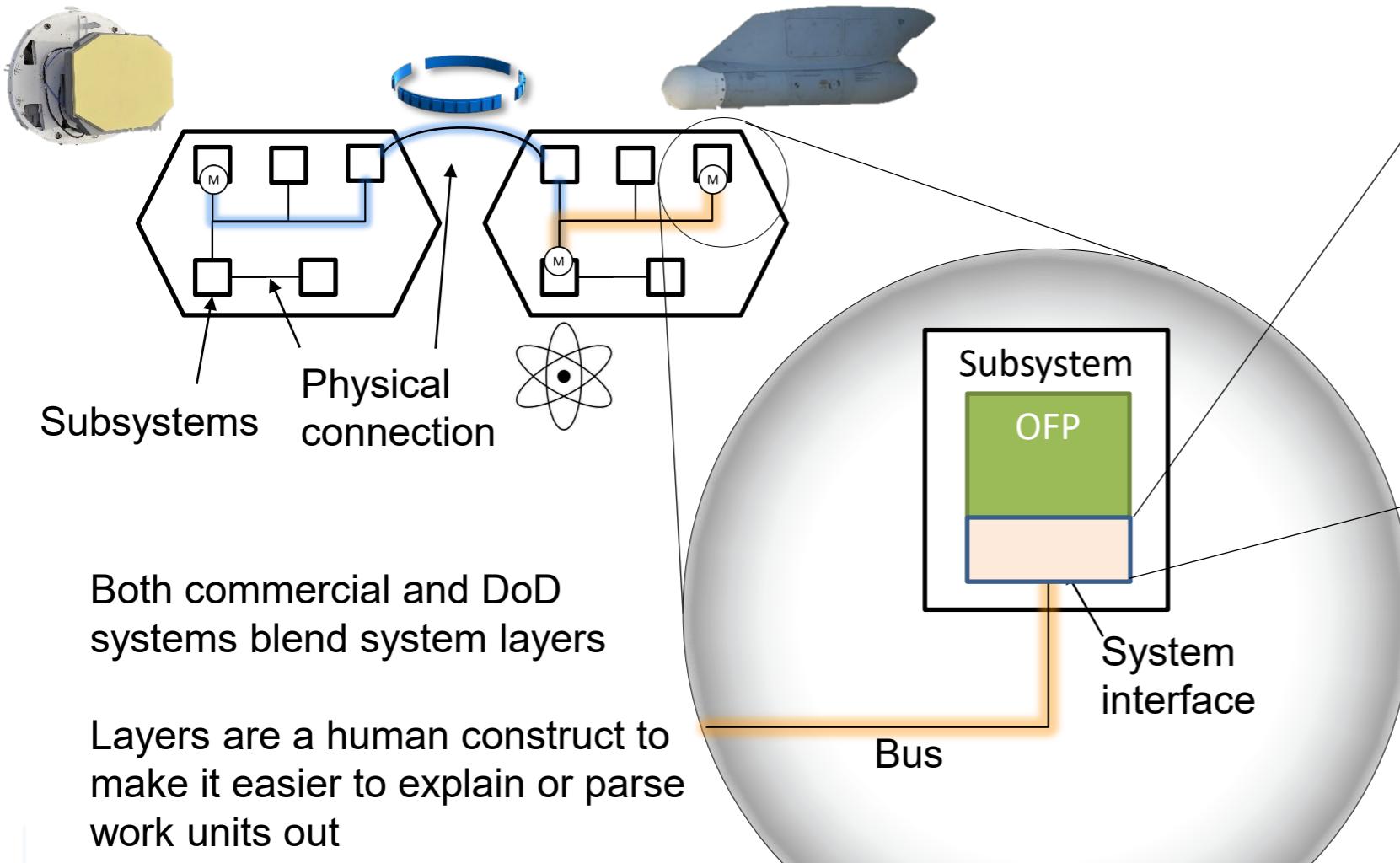
- System software is modified once for STITCHES compatibility
- Generated code is uploaded like mission data files (MDFs)
- Allows for fast and easy reconfiguration of mission capabilities

Auto-generate efficient glue code to

- Interoperate between new subsystems and existing components; old and new generations of the “same” open specification
- Transform platform data to comm’s message formats or encode any message inside fixed format standards like Link-16

STITCHES MDFs **efficiently translate data and control data flow** in order to create interoperability between and within connected platforms

A System of System where many systems customize interfaces



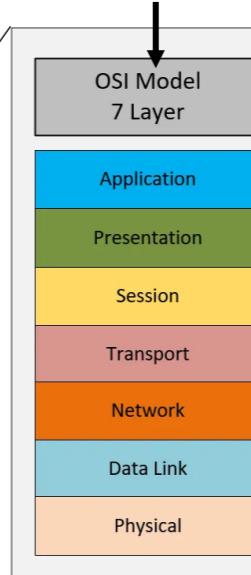
Both commercial and DoD systems blend system layers

Layers are a human construct to make it easier to explain or parse work units out

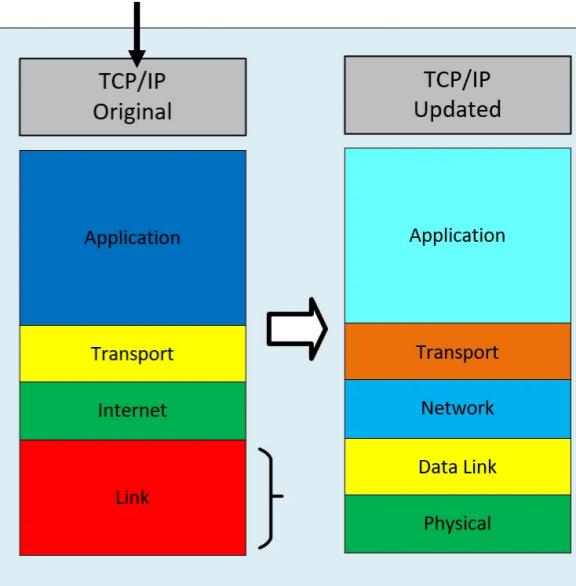
Each 'layer' is accessed via well formed messages

OFP: Operational Flight Program

Failed in 80's



"ARPA" internet



Every system has an interface based on their community:

- MIL-STD 1553
- MIL-STD 1773
- MIL-STD 1760
- ARINC 429
- Fiberchannel
- IEEE 1394
- SOAP, XML, Ethernet...any API

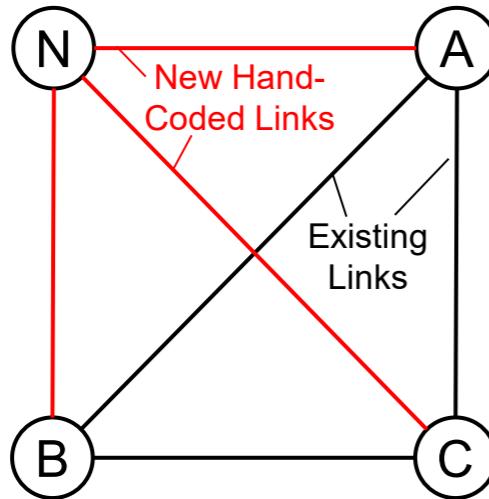
None of these standardize data content

STITCHES Interface Translator Technologies

(A) (B) (C) Existing Interfaces

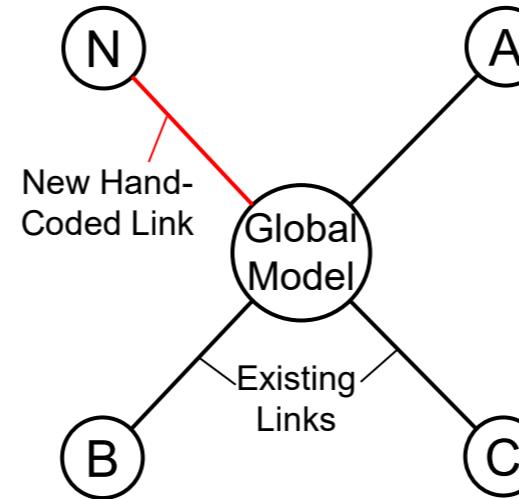
(N) New Interface

Link-by-Link Translation



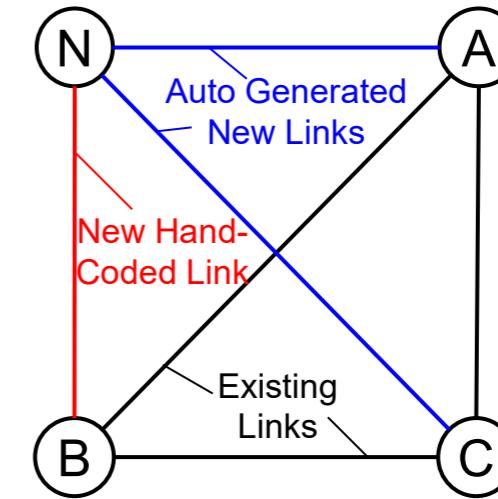
- ✗ Inefficient integration
 - L hand-coded translations (some may already exist)
- ✓ Efficient translation
 - 1 step between each interface
- Many examples

Common Model Translation



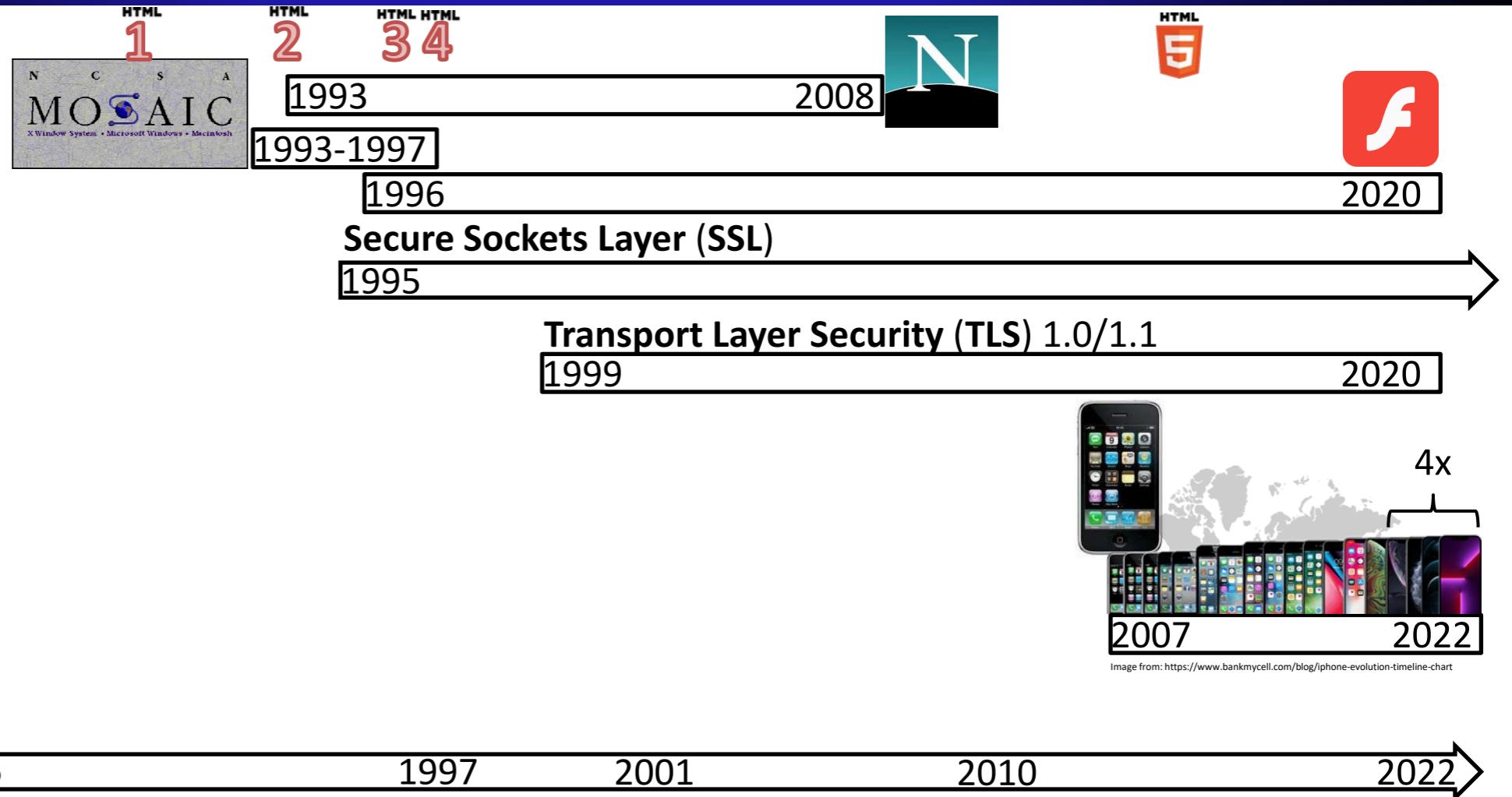
- ✓ Efficient integration
 - 1 hand-coded translation
 - Possible model update
- ✗ Inefficient translation
 - 2 steps between non-global-model interfaces
- E.G. Gateways

Field Transform Graph

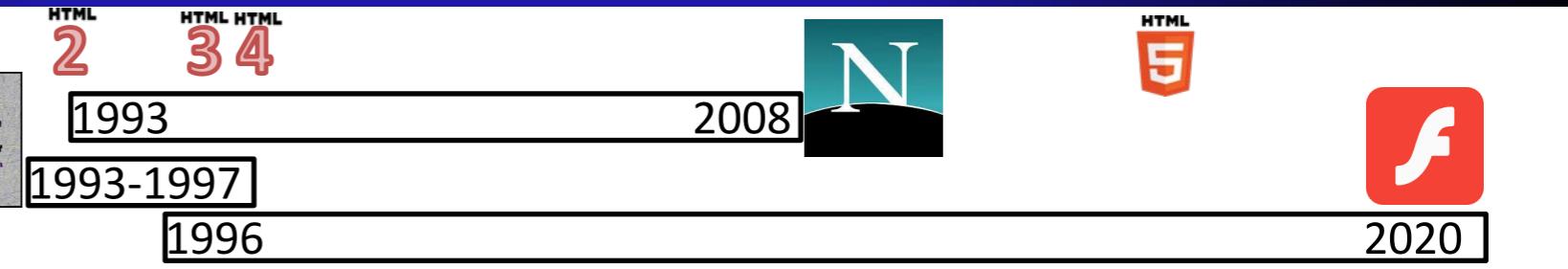
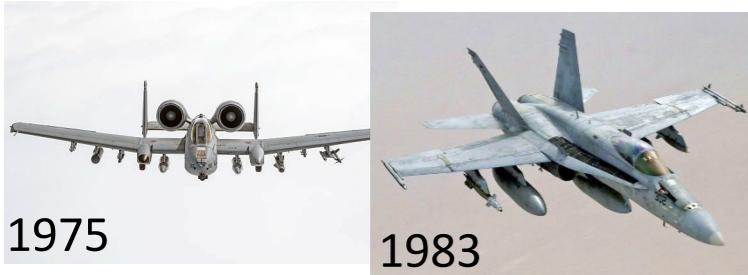


- ✓ Efficient integration
 - 1 hand-coded translation (L chances it already exists)
- ✓ Efficient translation
 - 1 step between each interface
- STITCHES

STITCHES “I want it to work like the internet”

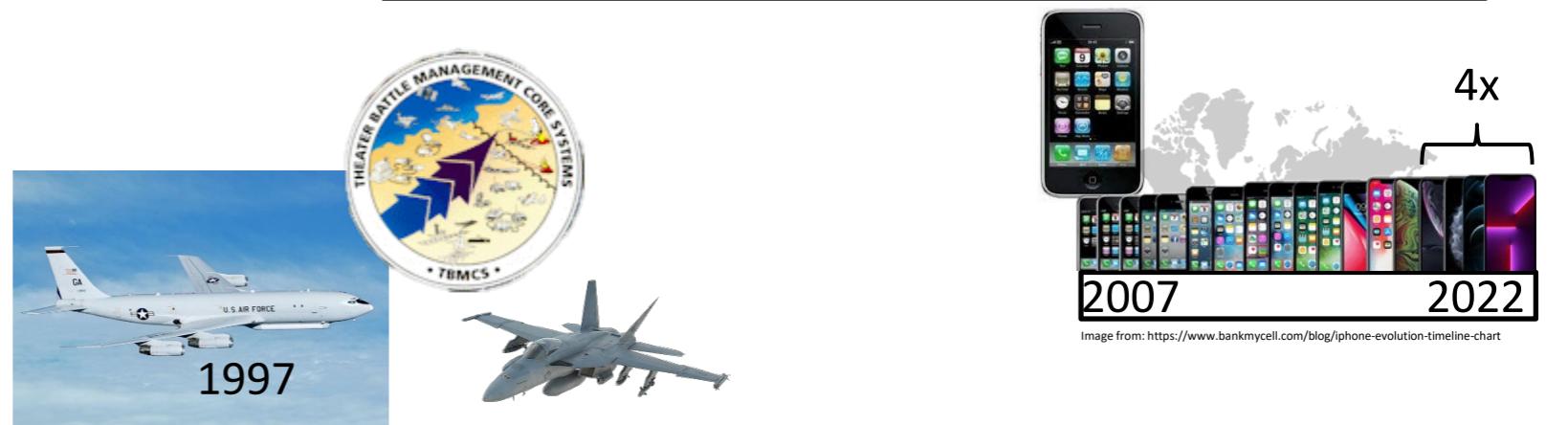


STITCHES “I want it to work like the internet”

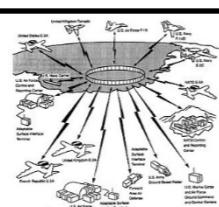


Secure Sockets Layer (SSL)
1995

Transport Layer Security (TLS) 1.0/1.1
1999

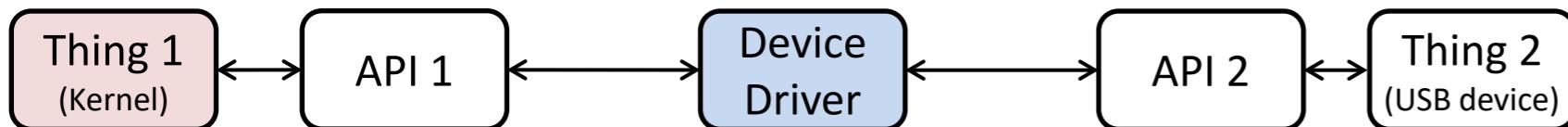


1975 1980 1986 1997 2001 2010 2022



20 April, 1998: Infamous Blue Screen of Death (BSOD) appeared while unveiling Windows 98 USB plug-and-play features

Issue was a bug in a device driver that implemented an API to the kernel incorrectly



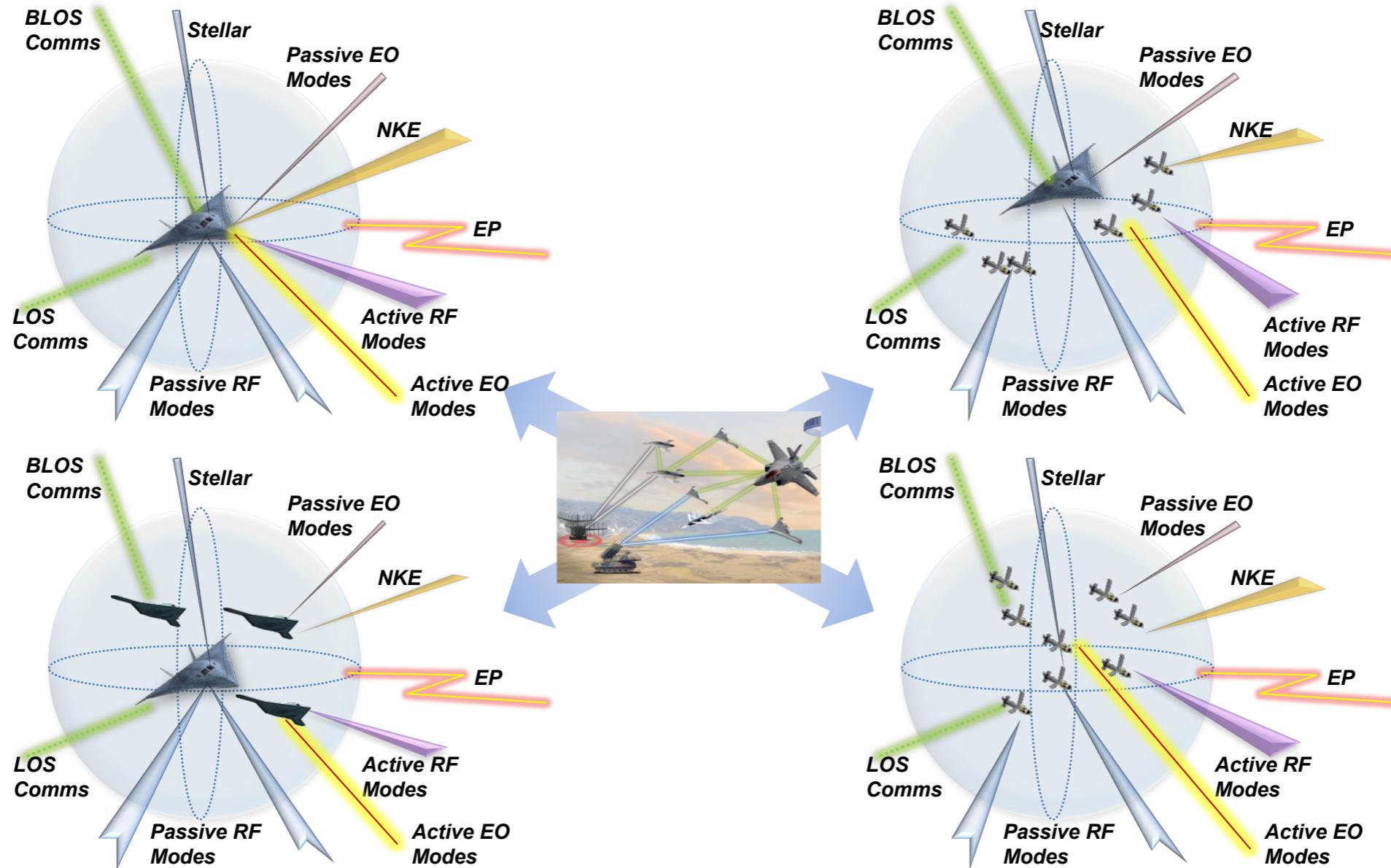
Microsoft launched 3 efforts to solve/minimize implementation conflicts

Solution: **SLAM**. THE most successful and longest use of **Formal Verification**

"The goal of the SLAM project is to check whether or not a program obeys "API usage rules" that specify what it means to be a good client of an API." T. Ball and S. K. Rajaman, Jan 1 2002



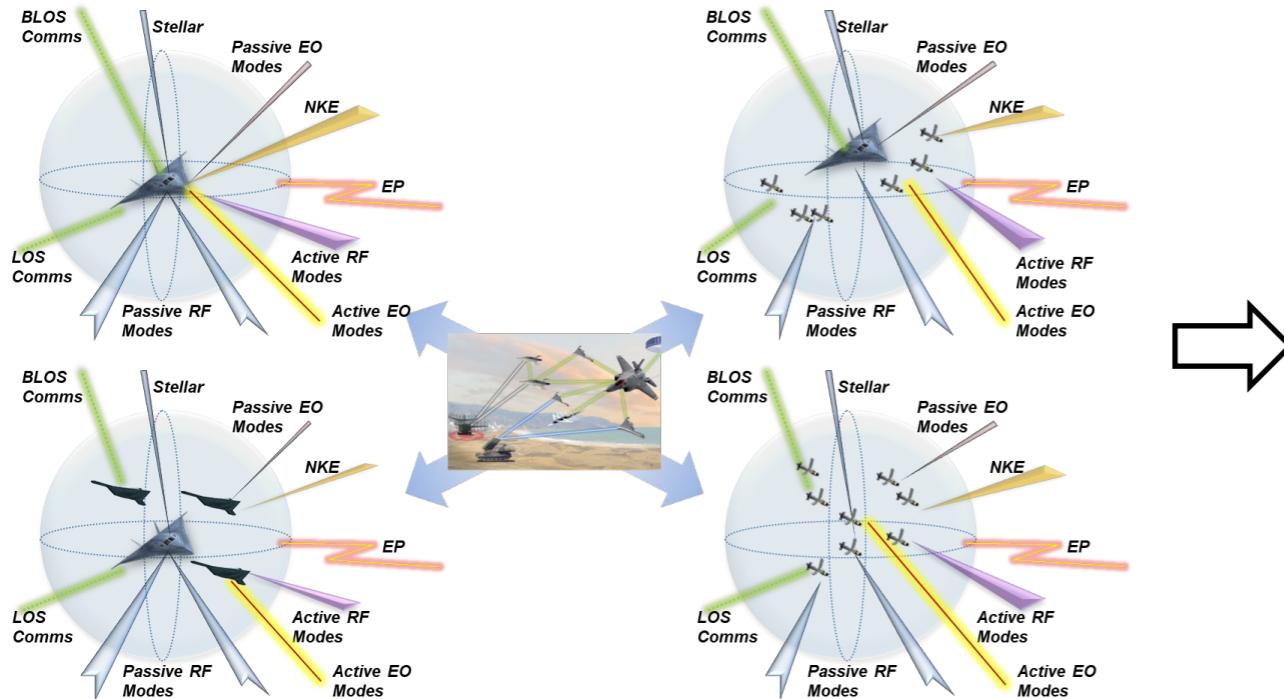
"Things like even software verification, this has been the Holy Grail of computer science for many decades but now in some very key areas, for example, driver verification we're building tools that can do actual proof about the software and how it works in order to guarantee the reliability." Bill Gates, April 18, 2002.



Courtesy of Dr. Joshua Bernstein, Northrop Grumman Electronic Systems

PED: Processing, Exploitation, Dissemination

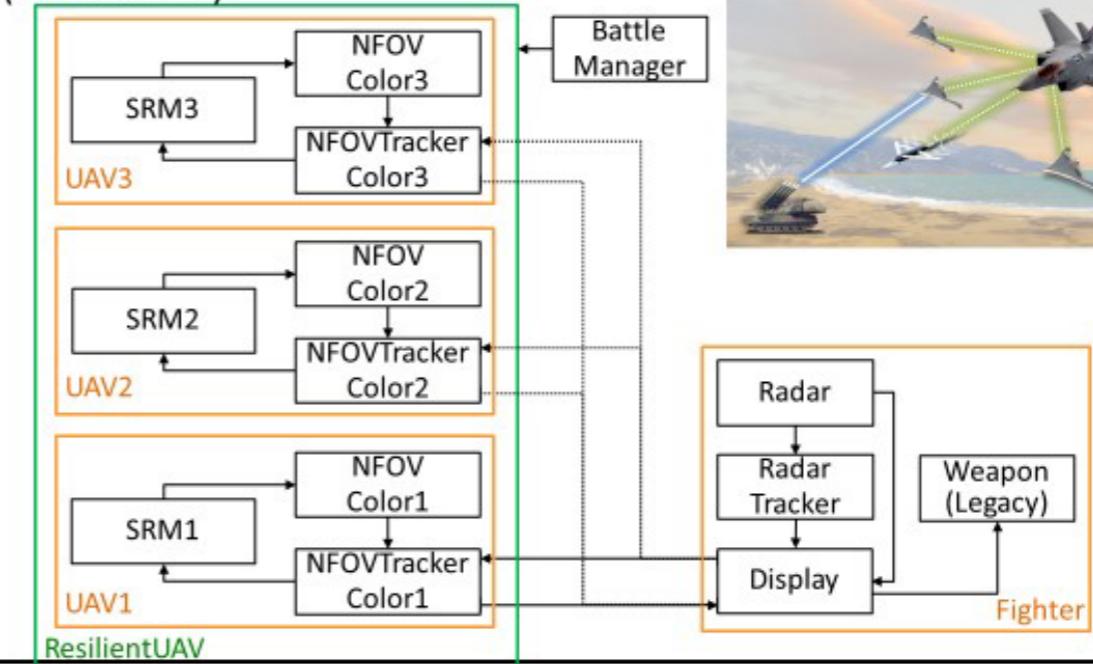
Distribution Statement A: Approved for Public Release, Distribution Unlimited



Concept

Build a System of Systems (SoS) Tutorial: Introduction

You Will Compose This Resilient Hierarchical Fighter-UAV SoS
(Threads 1-9):



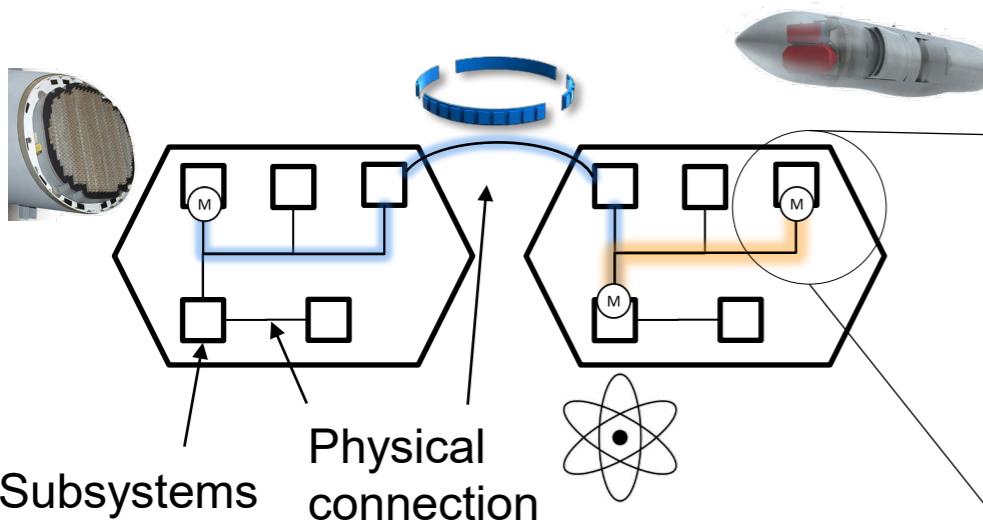
Distribution A: Approved for public release; distribution unlimited.

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STITCHES' Training Material

STITCHES Current integration requires updates to several systems

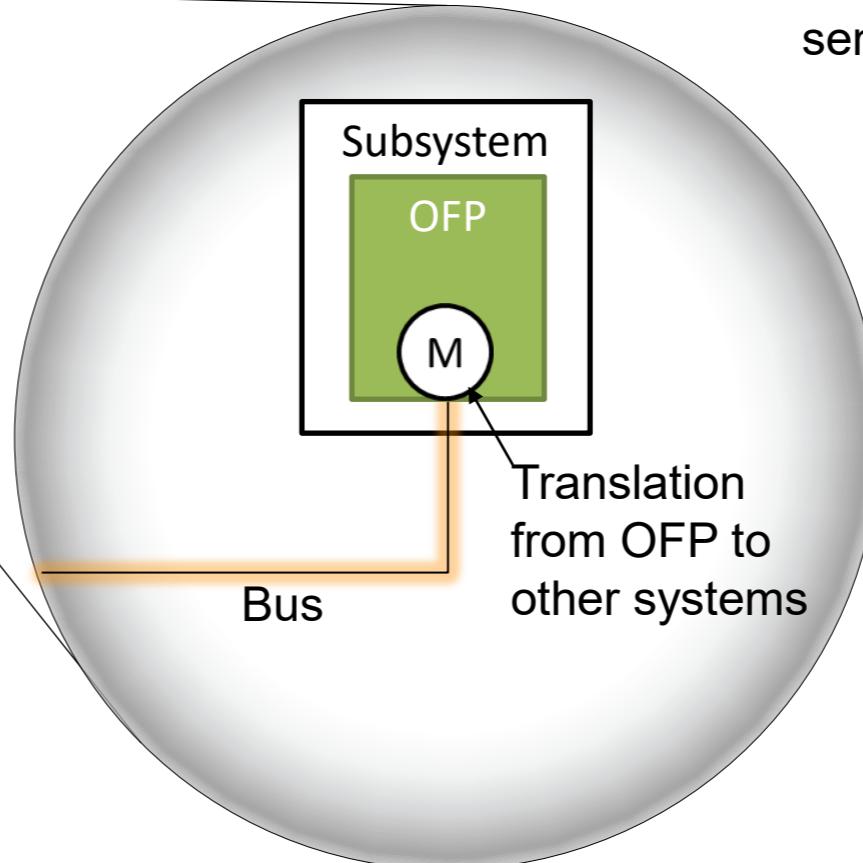
A System of System is created by a user



3 generalized types of integration

- Intra-subsystem (new algorithm)
- Intra-aircraft (new subsystem)
- Inter-aircraft (new external connection)

A translator is created for every new connection in the System of System

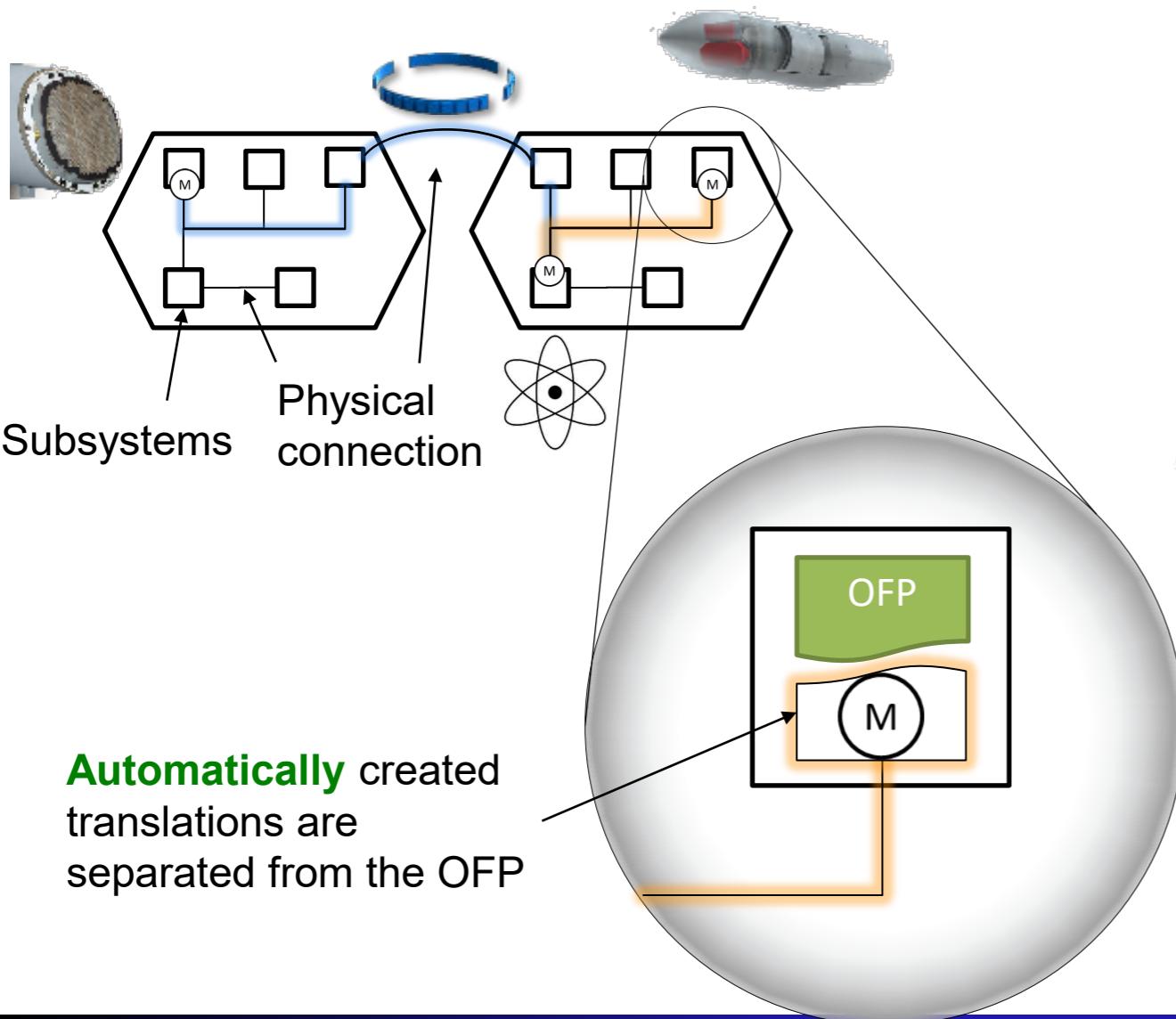


Any translation happens inside the OFP before a message is sent out on the bus

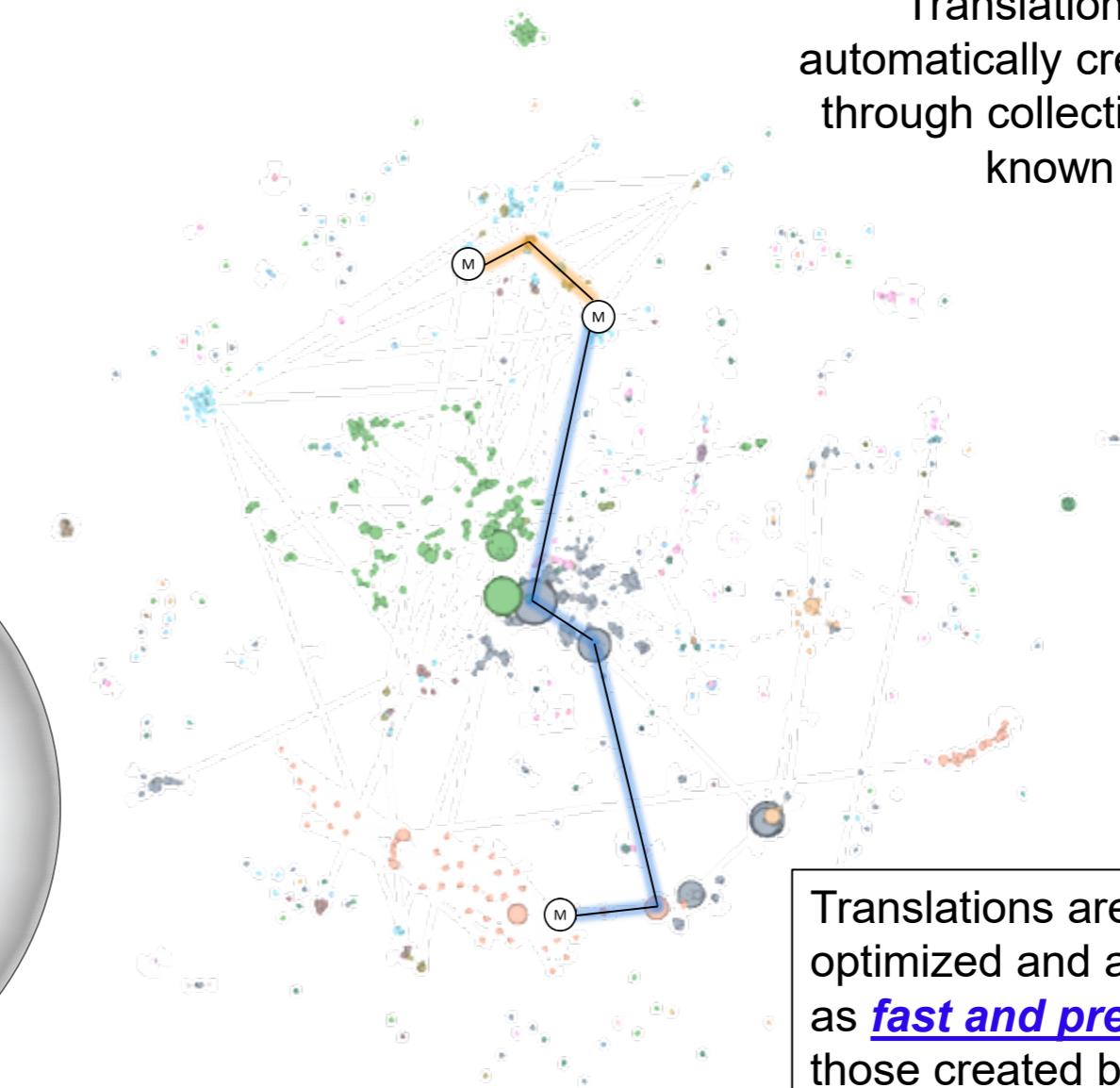
Often datalinks (Link-16) must update their standard to pass new messages

STITCHES DARPA created a new toolchain called STITCHES

A System of System is created by a user



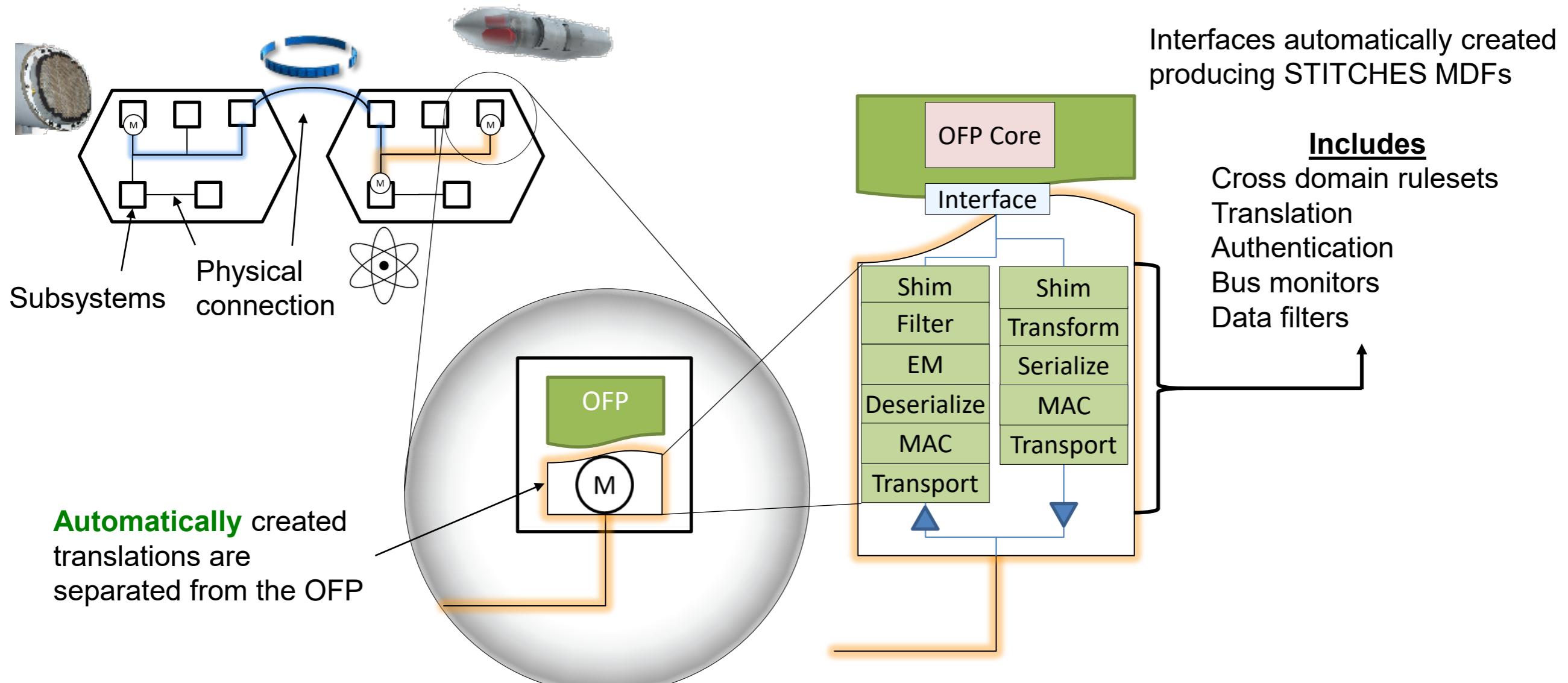
Translations are automatically created through collection of known pairs



Translations are optimized and at least as fast and precise as those created by hand

STITCHES DARPA created a new toolchain called STITCHES

A System of System is created by a user



EM: Execution Monitor

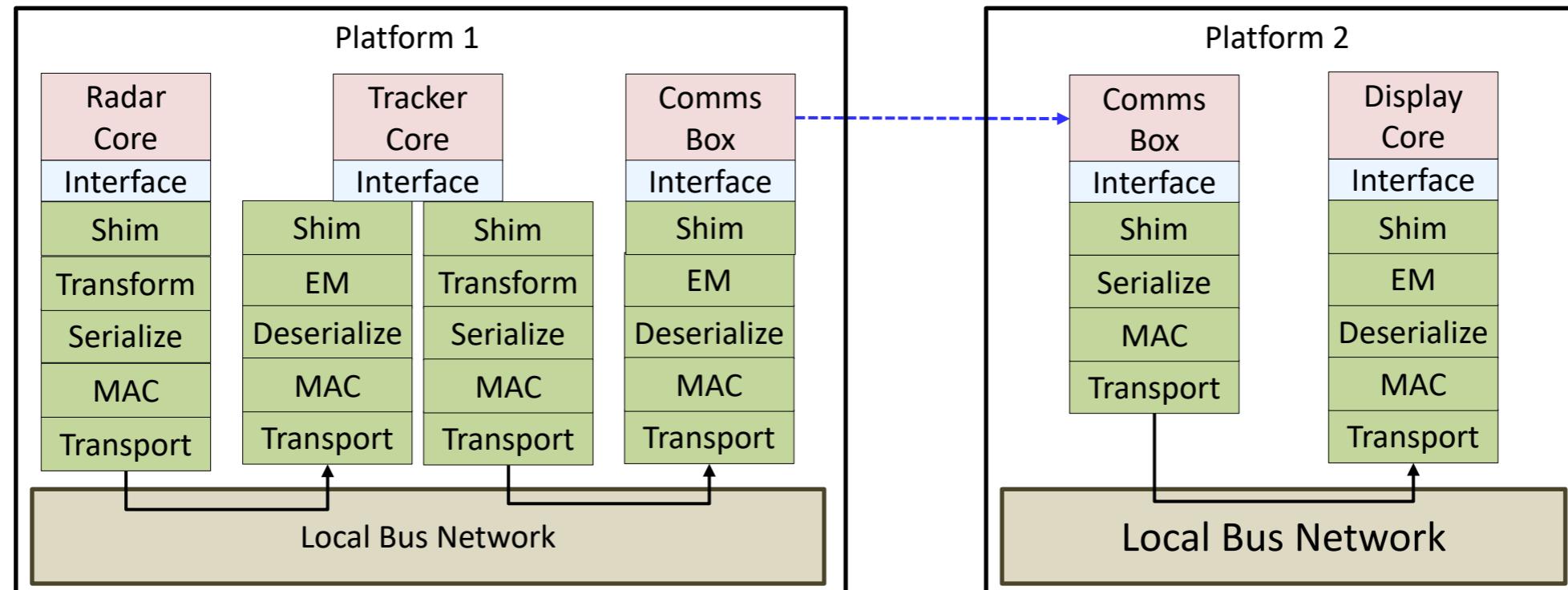
MAC: Machine Authenticated Code

Subsystem Core Developed by Subsystem Engineers

Interface Developed by Subsystem Engineer with STITCHES Autogenerated Libraries

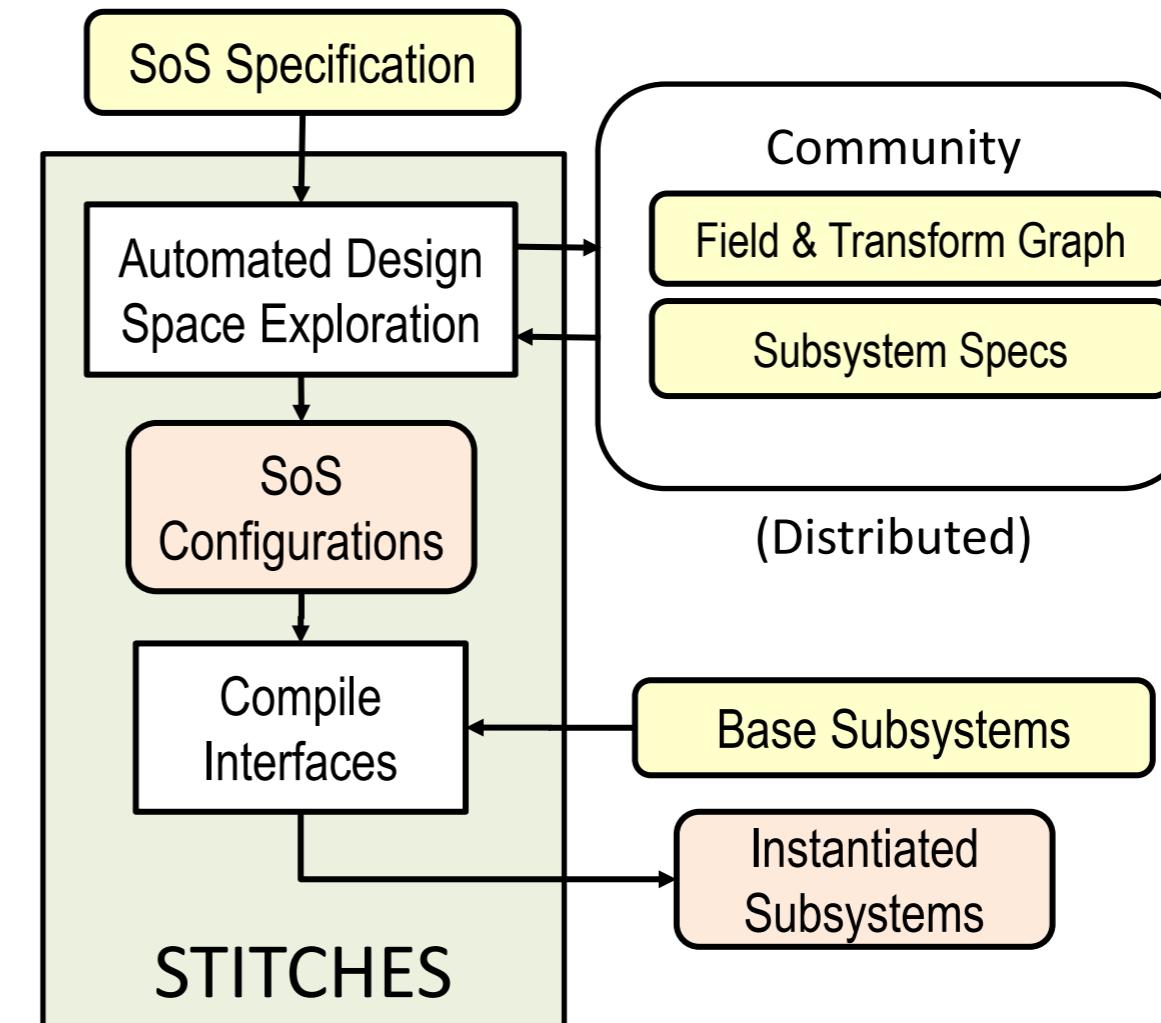
Developed once per Core Version, Works for all SoS Configurations

HCAL Autogenerated by STITCHES; Tailored to Each SoS Configuration



MAC: Message Authentication Code
EM: Execution Monitor

- Design Space Exploration
 - Process FTG to construct transformation chains
 - Specify interface stack by forming & solving optimization problems
- Compiler
 - Construct interface stack structure
 - Optimize transforms for this instance of the interface
 - Provide cyber security through whitelist property enforcement
 - Generate C++/C90/Java code & compile into binaries



Result: High performance interfaces optimized for each application



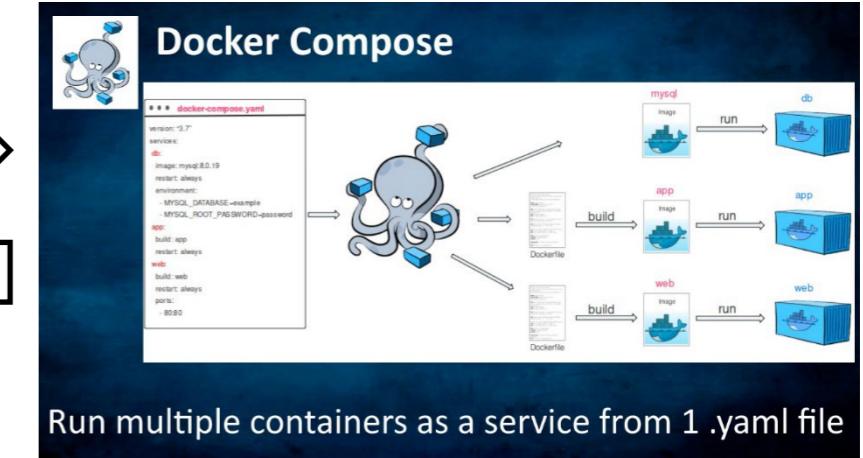
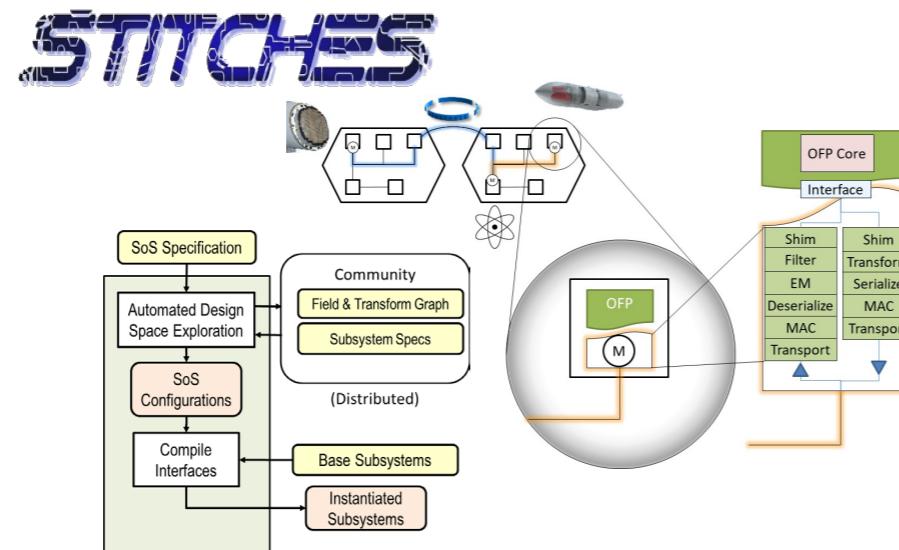
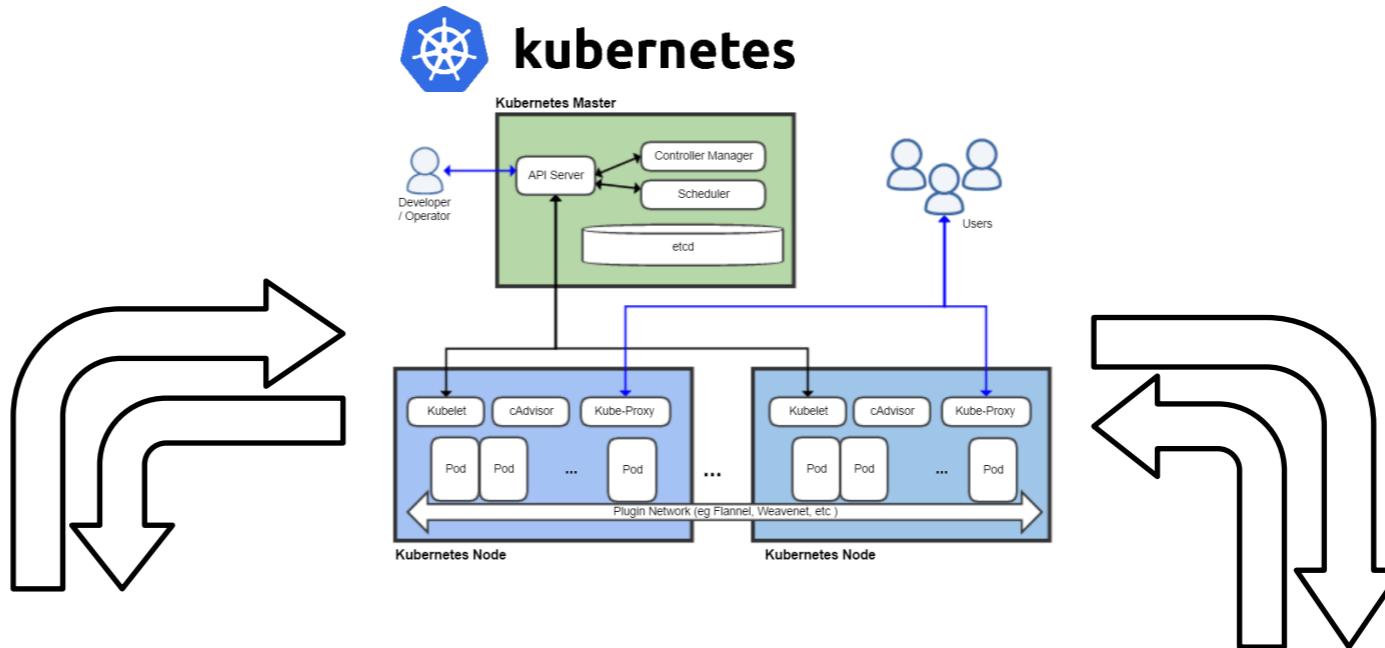
Stitches Synergy with Commercial composition and containers

Each can call the other's available APIs and configure, deploy, start, stop, etc

High level specifications define the deployment of software

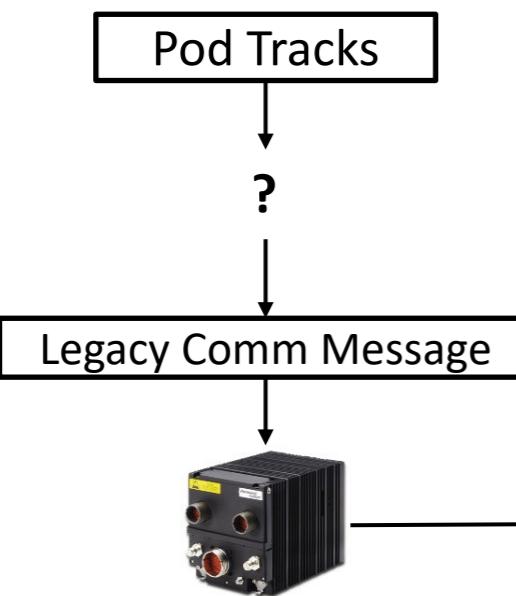
Sharable inputs and APIs feed the deployment engines

Each is user configurable



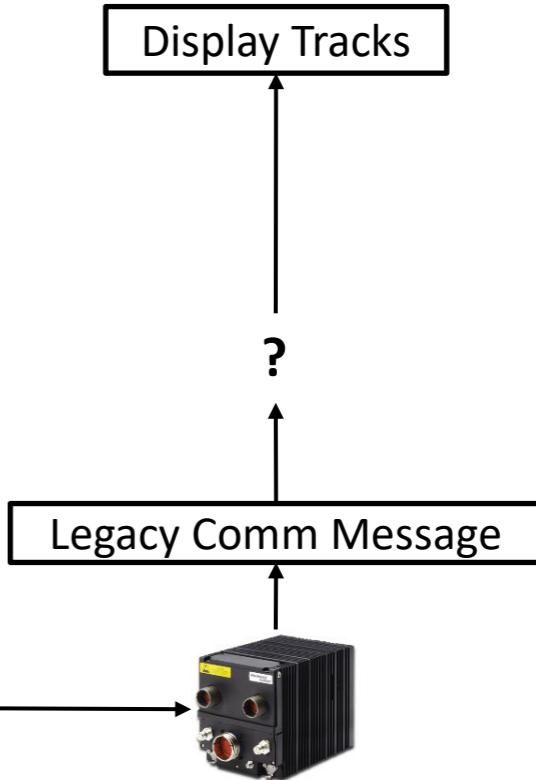


Interoperability via Legacy Comms, What if desired messages aren't supported?



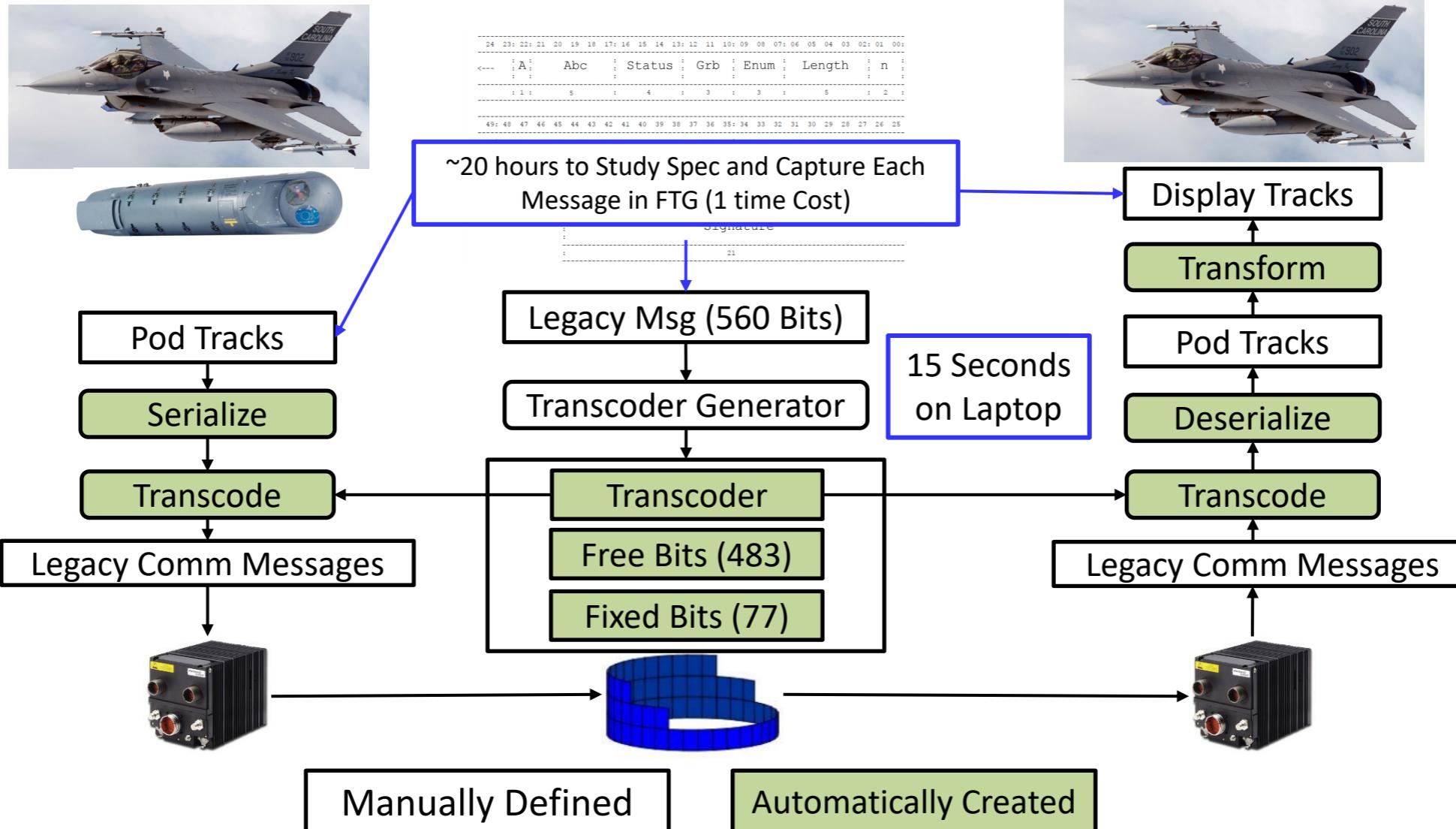
```
24 23:22:21 20 19 18 17:16 15 14 13:12 11 10:09 08 07:06 05 04 03 02:01 00:  
--- :A: Abc : Status : Grb : Enum : Length : n :  
--- : 1 : 5 : 4 : 3 : 3 : 5 : 2 :  
49:48 47 46 45 44 43 42 41 40 39 38 37 36 35:34 33 32 31 30 29 28 27 26 25  
--- : Data Payload : Data Payload :  
--- : 14 : 10 :  
--- : 69 68 67 66 65 64 63 62 61 60 59 58 57 56 55 54 53 52 51 50  
--- : Signature :  
--- : 21 :  
---
```

Legacy Comm Message





Auto-generate Transcoder to “Encode” Messages into Legacy Communication Messages



Capability Flown in Live Flight since January 2018 with Legacy Comm's System

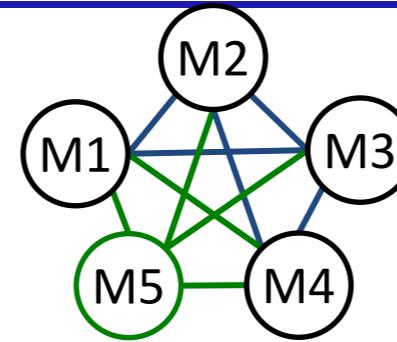
STITCHES Solves a Number of Critical Issues

- STITCHES is Open Sourced!
- Global interoperability without global consensus on interface specification
 - Stateless interactions (message transformations)
 - Stateful interactions (multiple source messages required to form destination message)
- Efficient reuse in and evolution of the architecture
- Near real-time construction of the SoS from specification
- Allow legacy subsystems and existing Open Architectures to interoperate with each other and new subsystems on different standards
- Optimized implementation of interfaces that are small and fast
 - Support for high speed packed representations
- Support for tunneling data through legacy communication systems (e.g., Link16)
- Cyber defenses via autogenerated run-time execution monitors that filter out messages due that don't meet the data and SoS configuration specifications

STYLICES

Local Message Standards

- **Flexible** – You can add new messages easily because no global coordination
- **Inefficient** - Require N^2 Transforms (all pairs) for Interoperability

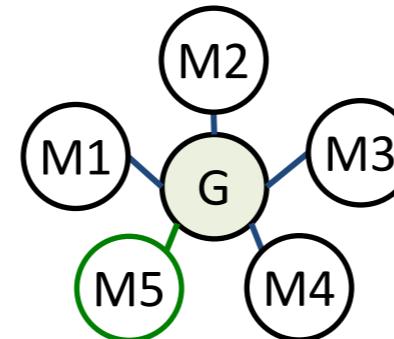


Transform $M2 \leftarrow M1$: $M2 = T21(M1)$
 Transform $M5 \leftarrow M1$: $M5 = T51(M1)$

$M\#$ = Message #

Global Open Standards

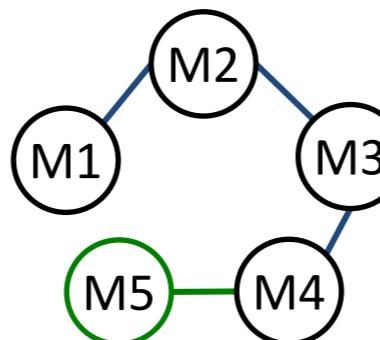
- **Efficient** – N Transforms to/from the Global Standard
- **Not Flexible** – Can't change to accommodate new technology without tremendous effort



Transform $M2 \leftarrow M1$: $M2 = T2G(TG1(M1))$
 Transform $M5 \leftarrow M1$: $M5 = T5G(TG1(M1))$

Incremental Standards (STITCHES)

- **Efficient** – $\sim N$ Transforms for Interoperability
- **Flexible** – You can add new messages easily without significant coordination
- Allows multiple generations of the architecture to function at once

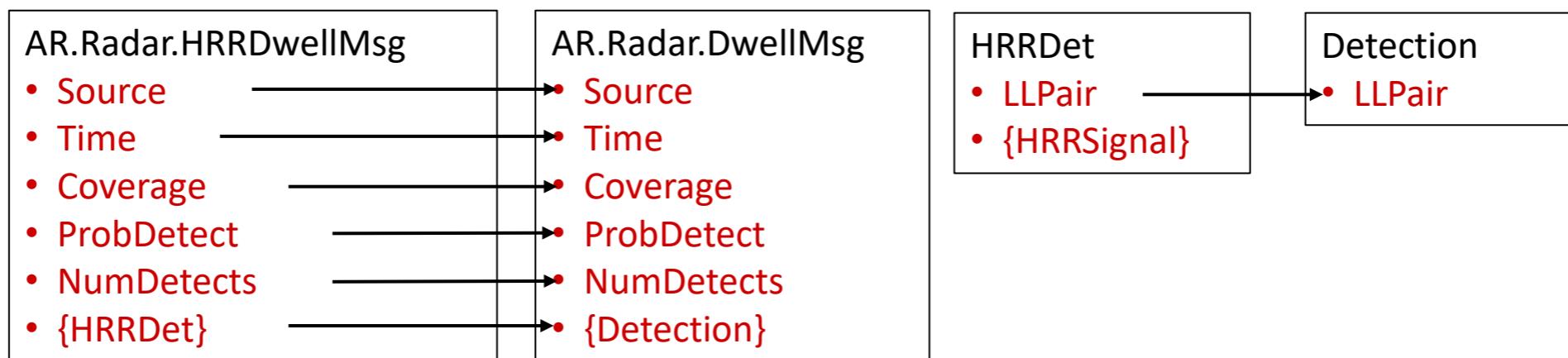


Transform $M2 \leftarrow M1$: $M2 = T21(M1)$
 Transform $M5 \leftarrow M1$: $M5 = T54(T43(T32(T21(M1))))$

Store the set of these relationships in a Fields and Transform Graph (FTG)

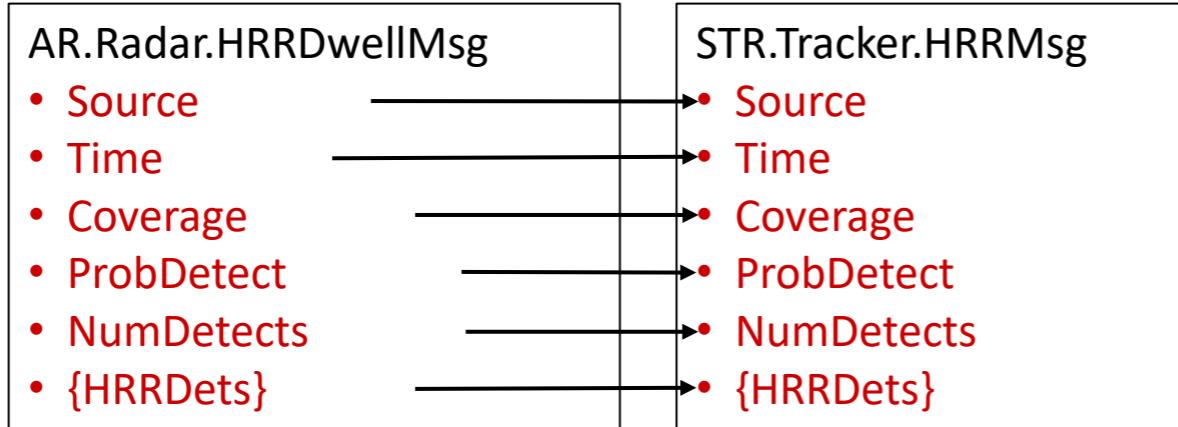
- Create a STITCHES enabled subsystem (Time: ~Days; Freq: Once per SS version)
 - Start with an existing subsystem (SS) core
 - SS engineer models the interface in the FTG (creates nodes)
 - STITCHES auto-generates SS Interface (SSI) skeleton; SS engineer completes SSI
 - SS Engineer adds FTG links to other nodes to connect to a community
 - Check in the FTG (includes annotations and verification)
- Create a new SoS (Time: ~Hours; Frequency: Once per SoS)
 - SoS engineer defines the SoS Specification (SSes and their connections)
 - If needed, SoS engineer must add any missing required links in the FTG
 - Check in New FTG including incremental verification (with tools such as AGREE)
 - SoS engineer runs STITCHES on the SoS Specification to Build the SoS (generate code)
- FTG provides re-use without common interfaces
 - An FTG Node is re-used in many messages
 - Messages are re-used in many subsystem interfaces
 - Subsystems are re-used in many SoSes

- Let's remember our simple 3 Subsystem ISR SoS
 - Radar: Produces AR.Radar.DwellMsg
 - Tracker: Consumes STR.Tracker.SensorMsg; Produces: STR.Tracker.TrackMsg
 - Display: Consumes: G.Display.SensorMsg, G.Display.TrackMsg
 - Connections: Radar -> Tracker; Radar->Display; Tracker->Display
- Now let's add in an upgraded radar (Includes an HRR signature)
 - Construct transform that assigns each subfield from the new to the old message

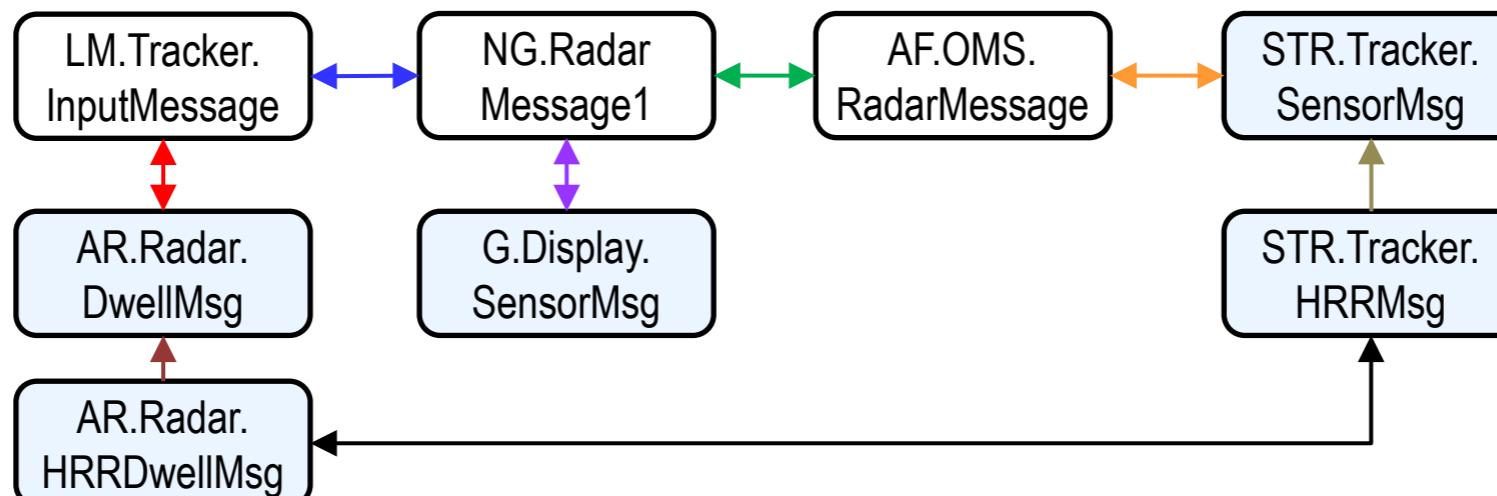


- Now can use the new radar anywhere that you can use the old radar
(but won't get access to the HRR signal)

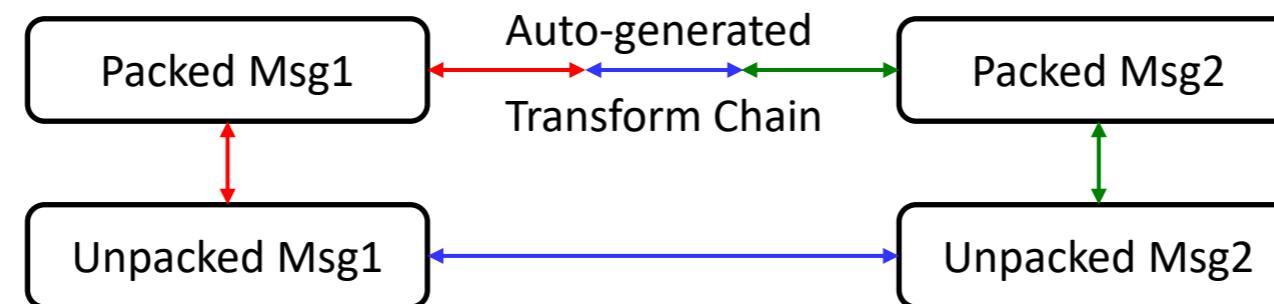
- Now Let's Add in an Upgraded Tracker (That can use HRR Signatures)
 - Construct Transform That Assigns Each Subfield from the HRR Source to HRR Destination



- Now the New Tracker can use the HRR Signals from the new Radar



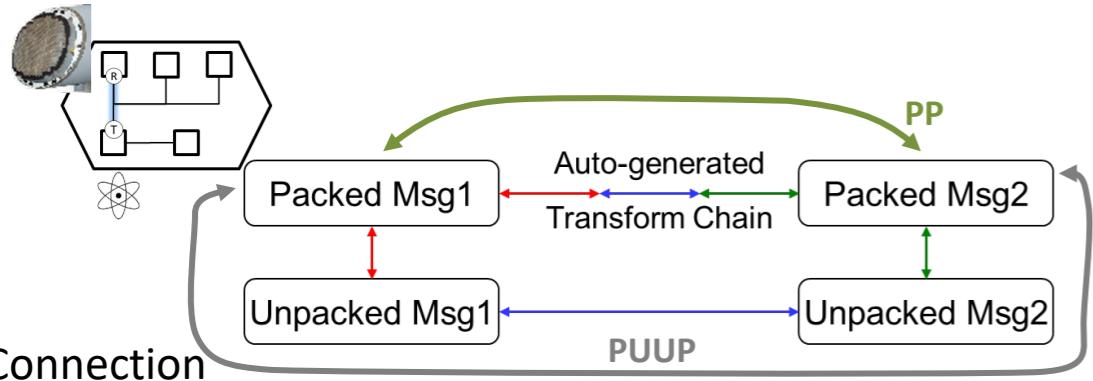
- Many real systems mix their interface definition with their implementation
 - Result is a serialized (Packed) form of the interface that can represent multiple different interface messages (e.g., STANAG 4607) with descriptor words for run time resolution
 - Packed messages are often used for run-time efficiency - they tend to be the big / high rate messages in the system. So don't want to unpack if not necessary
- Mirrored Unpacked Nodes Provide an Effective and Efficiency Solution
 - Create a Second Unpacked Node that Contains a Structured Version of the Interface
 - Create Transforms between the Unpacked and Packed Nodes
 - Interact with other Interfaces via their Unpacked Representations
 - Auto-generate the Desired (high performance) Packed-to-Packed Transforms





STITCHES Version 6R8.6 Optimized Performance:

[Packed → Unpacked → Unpacked → Packed] vs. [Packed → Packed]



Connection	PUUP vs PP	Speed (Mbps)			Latency (ms)		
		Java8	C++11	C90	Java8	C++11	C90
R1 -> T1 (No Transform)	PUUP	9899	13372	14705	0.6	0.3	0.2
R1 -> T1 (No Transform)	PP	9856	13186	14679	0.5	0.3	0.2
R1 -> T2 (Only Change Time)	PUUP	5555	13397	14481	0.8	0.3	0.2
R1 -> T2 (Only Change Time)	PP	5661	13308	14364	0.8	0.3	0.2
R1 -> T3 (Switch Order Lat, Lon)	PUUP	3216	5431	7128	1.0	0.4	0.3
R1 -> T3 (Switch Order Lat, Lon)	PP	3238	5519	6736	1.0	0.4	0.3
R1 -> T4 (Change All Fields)	PUUP	1595	3346	4137	1.7	0.5	0.4
R1 -> T4 (Change All Fields)	PP	2315	3202	4281	1.0	0.5	0.4

R: Radar Message

T#: Tracker interface #