### **Programming assignment 2: Linear regression**

```
In [1]: import numpy as np
    from sklearn.datasets import load_boston
    from sklearn.model_selection import train_test_split
```

#### Your task

In this notebook code skeleton for performing linear regression is given. Your task is to complete the functions where required. You are only allowed to use built-in Python functions, as well as any <code>numpy</code> functions. No other libraries / imports are allowed.

#### Load and preprocess the data

I this assignment we will work with the Boston Housing Dataset. The data consists of 506 samples. Each sample represents a district in the city of Boston and has 13 features, such as crime rate or taxation level. The regression target is the median house price in the given district (in \$1000's).

More details can be found here: <a href="http://lib.stat.cmu.edu/datasets/boston">http://lib.stat.cmu.edu/datasets/boston</a>

```
In [2]: X , y = load_boston(return_X_y=True)

# Add a vector of ones to the data matrix to absorb the bias term
# (Recall slide #7 from the lecture)
X = np.hstack([np.ones([X.shape[0], 1]), X])
# From now on, D refers to the number of features in the AUGMENTED dataset
# (i.e. including the dummy '1' feature for the absorbed bias term)

# Split into train and test
test_size = 0.2
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=test_size)
```

### Task 1: Fit standard linear regression

#### Task 2: Fit ridge regression

```
In [4]: def fit_ridge(X, y, reg_strength):
            """Fit ridge regression model to the data.
            Parameters
            X : array, shape [N, D]
               (Augmented) feature matrix.
            y : array, shape [N]
               Regression targets.
            reg_strength : float
                L2 regularization strength (denoted by lambda in the lecture)
            Returns
            w : array, shape [D]
                Optimal regression coefficients (w[0] is the bias term).
            11 11 11
            # TODO
            return np.matmul(np.matmul(np.linalg.inv(np.matmul(np.transpose(X),X) + reg strength*np.identity
         (X.shape[1])), np.transpose(X)), y);
```

# Task 3: Generate predictions for new data

# Task 4: Mean squared error

# Compare the two models

The reference implementation produces

- MSE for Least squares ≈ 23.98
- MSE for Ridge regression  $\approx$  21.05

You results might be slightly (i.e.  $\pm\,1\%$ ) different from the reference soultion due to numerical reasons.

```
In [7]: # Load the data
        np.random.seed(1234)
        X , y = load_boston(return_X_y=True)
        X = np.hstack([np.ones([X.shape[0], 1]), X])
        test size = 0.2
        X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=test_size)
        # Ordinary least squares regression
        w ls = fit least squares(X train, y train)
        y_pred_ls = predict_linear_model(X_test, w_ls)
        mse ls = mean squared error(y test, y pred ls)
        print('MSE for Least squares = {0}'.format(mse_ls))
        # Ridge regression
        reg_strength = 1
        w_ridge = fit_ridge(X_train, y_train, reg_strength)
        y_pred_ridge = predict_linear_model(X_test, w_ridge)
        mse_ridge = mean_squared_error(y_test, y_pred_ridge)
        print('MSE for Ridge regression = {0}'.format(mse_ridge))
        MSE for Least squares = 23.98430761177853
        MSE for Ridge regression = 21.051487033771117
```

### MACHINE LEARNING HOMEWORK SHEET 03 LINEAR REGRESSION

NAME: MAHALAKSHMI

Tum ID: 9e73yuw

SABANAYAGIAM

DATE: 4, 11,2018

Problem 2:

Let there be of data points and m features,

W -> mx1

p(n) > Nxm

y -> NXI

Let T be diagonal matrix with  $t_1, t_2 ... t_N$  as diagonal values.  $T \to N \times N$ 

Energeted (w) = 
$$\frac{1}{2} \sum_{i=1}^{N} t_i (\phi(x_i) W - y_i)^2$$

This can be written in matrix vector form,

Eweighted (W) = 
$$\frac{1}{2} \left[ (\phi(x)W - Y)^T T (\phi(x)W - Y) \right]$$

2 /TT 400 W

coince T=T ast is a diagonal motion.

to find w that minimizes Eweighted (W), TH Eweighted (W) =0

$$W^{T}\phi^{T}_{OO}T\phi(x) = Y^{T}T\phi(x)$$

taking Transpose on both the sides,  $\phi(x) T \phi(x) W = \phi(x) T Y$ W= (PON) TON) P(X) TY >0

For this w the error function is minimum. 1. weighting factor to in terms of variance of noise on the data: Lets assume noise is normally distributed N(0,0°)

=) y: = q(xi) W + G; Eis noise

Substituting y in W from O,

W= (pex) T pers) T don't (pex) W+E)

= (\$\frac{1}{(n)} + \frac{1}{(n)} - \frac{1}{(n)} + \frac{1}{(

= IN + (tile) To(x)) die, TE
variance of Whis should be small for unbiased estimator var[www]; = var[wj] +[(p(x) T dox)) d(x) ]ji

= \frac{2}{2} [ (\phi[x) \tau \phi(x)) \dagger \phi[x) \tau]; \sigma\_{i}^{2}

For this to be small, weight Ti should be inversely proportional to si. Ti a /oir (given noise variance).

thus, the weight should be large around the data points unter less noise for it to be a good estimator (unbiased)

& data points for which there are exact copies in the dataset. In case of biased sample where many copies of some sample data points exists in the sample, the weight for those samples should be marrianum to avoid & high bias.

It pi is the probability of observing ith sample then weight of i should be proportional to 1/pi " wix 1/pi so that sampling bias is minimized.

Problem 3:

The ridge regression estimates can be obtained by ordinary least squares regression on an augmented dataset.

Design matrix & ERNXM
y -> NXI vector

with  $\phi \circ y$ , westimate of ordinary coest squares is  $w = (\phi^T \phi)^T \phi^T y \to 0$ 

Augumenting M additional Rows with O,

Augamenting y with Myeros,

Ye = [Y]
(N+M) X1

Sub statuting  $\Phi_R$  &  $\Psi_R$  in  $\mathbb{O}$ ,  $W = \left( \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \right) \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Gamma \end{bmatrix}$   $= \left( \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \right) \begin{bmatrix} \Phi \\ \nabla \nabla \Gamma \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Gamma \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Gamma \end{bmatrix}$   $= \left( \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} + A \Gamma^2 \right) \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Psi \end{bmatrix}$   $= \left( \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} + A \Gamma^2 \right) \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Psi \end{bmatrix}$   $= \left( \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} + A \Gamma^2 \right) \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Psi \end{bmatrix}$   $= \left( \begin{bmatrix} \Phi \\ \Psi \end{bmatrix} + A \Gamma^2 \right) \begin{bmatrix} \Phi \\ \nabla \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \nabla \Psi \end{bmatrix}$   $= \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix}$   $= \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix}$   $= \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix}$   $= \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \end{bmatrix} \begin{bmatrix} \Psi \\ \Psi \end{bmatrix} \begin{bmatrix} \Psi$ 

Thus Ridge sugression estimate is obtained from OLS regression estimate on augmented dataset by augmenting of with M rows of Th I and your number of with M rows of the I and your with M rows.

Problem 4:

Litelihood 
$$p(y|\phi,\omega,\beta) = \prod_{i=1}^{N} N(y_i|\omega^i\varphi(x_i),\beta^i)$$

prior  $p(\omega,\beta) = N(\omega|m_0,\frac{s_0}{p})^{\epsilon_1} \epsilon_2 \epsilon_3 \epsilon_4 \epsilon_5$ 

To prove:

 $p(\omega,\beta|D) = N(\omega|m_0,\frac{s_0}{p})^{\epsilon_2} \epsilon_3 \epsilon_4 \epsilon_5$ 
 $p(\omega,\beta|D) = N(\omega|m_0,\frac{s_0}{p})^{\epsilon_3} \epsilon_4 \epsilon_5$ 
 $p(\omega,\beta) = \prod_{i=1}^{N} N(y_i|\omega^i\varphi(x_i),\beta^i)$ 
 $p(\omega,\beta) = \prod_{i=1}^{N} N(\omega^i\varphi(x_i),\beta^i)$ 
 $p(\omega,\beta) = \prod_{i=1}^{N}$ 

Comparing exponents in ① and ②,
$$\frac{1}{2}\left[(y-xw)^{T}(y-xw)+(w-mo)^{2}\right]+b_{0}=(w-mv)^{2}+b_{N}\rightarrow 3$$

Comparing the constants,

$$(\sqrt{\beta})^{N+1} + \frac{1}{\sqrt{G_0}} = \frac{a_0}{\sqrt{G_0}} = \frac{a_0}{\sqrt{G_0}}$$

Comparing B exponents,
$$ao-1+N = an-1$$

$$aN = ao + N$$