

Inferential Statistics

Population

Population is the set of all individuals, items or data of interest

Population Parameter:- A characteristic (numerical)

that describes a population is referred to as a population parameter.



→ Whole population do not have ~~access to~~ access to whole population investigate



Limited to working with a sample of individuals in the population.

Inferential statistics:- characteristics of sample

to infer or draw conclusions on what the unknown parameters in the given population would be.

→ Inferential statistics uses the sample data

to draw conclusions (or inferences) about, or estimate parameters of, the environment from which the data came.

→ Inferential statistics is concerned with making generalizations based on a set of data, by going beyond information contained in the set.

→ How to select sample from population for drawing / study the population characteristics.
( leads development of Sampling theory)

Inferential statistics considers:-

(i) Sampling Theory :- Selecting sample from some collection that is too large to examined completely.

(ii) Estimation Theory :-

Making some prediction on or estimate of population parameter based on the available data.

(iii) Hypothesis Testing :- Inferential procedure that uses sample data to evaluate the

credibility of a hypothesis about a population.

Hypothesis Testing = ~~Hypothesis~~
~~Decision Theory~~

= Decision Theory.

(iv) Regression Analysis:— Find mathematical

expressions that best represent the collected
data.

→ Sampling Theory →

Population: collection of data to be studied

is called population.

Population can be finite or infinite.

⇒ Due to different reason it is difficult to study and some time impossible to examine the entire population.



In such case study is carried out on ~~small~~ with small part of the population called

sample



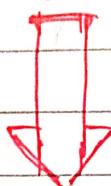
Fact about entire population can be inferred from the result obtained from the sample



Sampling

Process of obtaining samples from population is called sampling.

Sampling is concerned related with the selection of a subset of the members of population to estimate/infer the characteristics of the whole ~~the~~ population.



Reliability of the inference/conclusion drawn about population depends whether the sample is chosen to represent the population sufficiently well.



One way to ensure sample sufficiently represent the population is each ~~one~~ member of population has same chance of being in the sample. Samples constructed in this manner are called random samples.

→ Random Sampling

Population Random Variable : X

Population Size : N

→ Sample size, n , is obtained by from population through realization of random variable X . Let $x_1, x_2, x_3, \dots, x_n$ be the values of random variable X .

i.e. $x_1, x_2, x_3, \dots, x_n$ is a sample

— Assume that the each value is independent of each other. This sample is realization of values as sequence x_1, x_2, \dots, x_n of independent and identically distributed random variable (i.i.d.), each of have same as population distribution as X .

— Random sample of size n as a sequence of independent and identically distributed

random variables X_1, X_2, \dots, X_n .

- Once sample has been taken, the values denoted by $x_1, x_2, x_3, \dots, x_n$. (obtained sample)

Sample statistics : Any quantity obtained from a sample for the purpose of estimating a population is called a sample statistic (or simply statistics).

$\hat{\theta}$ is estimator of θ is function of a population denoted by random variable X is function of random sample X_1, X_2, \dots, X_n

$$\hat{\theta} = f(X_1, X_2, \dots, X_n)$$

Most common estimators are the sample mean and the sample variance.

Sample Mean

C Ideally sample mean has

Mean and Variance obtained from
Sample is same as population
mean and Variance.

x_1, x_2, \dots, x_n is random variables for

sample of size n. We define sample mean

\bar{X} as the following random variable

$$\bar{X} = \frac{x_1 + x_2 + x_3 + \dots + x_n}{n} = \frac{1}{n} \sum_{i=1}^n x_i \quad (1)$$

x_i are random Variable that are assumed

to have pdf/pmf ($f_{x_i}(x_i)$) as the population

Random Variable X .

— Then Sample mean, when Sample values are

Obtained as $x_1, x_2, x_3, \dots, x_n$, is given as

$$\bar{X} = \frac{x_1 + x_2 + x_3 + \dots + x_n}{n} \quad (2)$$

M_x : mean value of population random Variable X .

* Sample mean, \bar{X} , is random Variable.

(\Rightarrow different sample sizes gives different means)

→ Since sample mean, \bar{X} , is random variable
the sample mean have mean value, given by

$$E(\bar{X}) = E\left[\frac{1}{n} \sum_{i=1}^n X_i\right] = \frac{1}{n} \sum_{i=1}^n E(X_i)$$

$$\boxed{E(\bar{X}) = \frac{1}{n} \sum_{i=1}^n \mu_x = \mu_x} \quad \text{--- (3)}$$

since $\{X_i\}_{i=1}^n$ are i.i.d and have same pdf/bmf
as population random variable X .

Thus Sample mean = population mean

Sample mean is an unbiased estimate
 \Downarrow

Estimated value of parameter is the same
as true value.

Variance of the sample mean — Sampling is
done with replacement i.e. for each draw sample
population is not change.

Now Variance of sample mean

$$\sigma_{\bar{X}}^2 = E[(\bar{X} - \mu_x)^2] = E\left[\left(\frac{\underline{X_1 + X_2 + \dots + X_n}}{n} - \mu_x\right)^2\right]$$

$$\sigma_x^2 = \frac{1}{n^2} \sum_{i=1}^n E[X_i^2] + \frac{1}{n^2} \sum_{i=1}^n \sum_{j \neq i} E[X_i X_j]$$

$$= \frac{2\mu_x}{n} \sum_{i=1}^n E[X_i] + \mu_x^2$$

Since $\{X_i\}_{i=1}^n$ are v.i.d.r.v. $E[X_i X_j] = E[X_i] E[X_j] = \mu_x^2$

$$E[X_i] = \bar{E}[X]$$

Therefore,

$$E[X_i] = E[X^2]$$

~~$$\sigma_x^2 = \frac{1}{n^2} \sum_{i=1}^n (E[X_i])^2$$~~

$$\sigma_x^2 = \frac{1}{n^2} n \cdot E[X^2] + \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \mu_x^2$$

$$= \frac{2\mu_x}{n} \sum_{i=1}^n \mu_x + \mu_x^2$$

$$\sigma_x^2 = \frac{1}{n} E[X^2] + \frac{1}{n^2} [(n-1)\mu_x^2 + (n-1)\mu_x^2 + \dots + (n-1)\mu_x^2]$$

sum of n-term

$$= \frac{2\mu_x}{n} \sum_{i=1}^n \mu_x + \mu_x^2$$

$$\sigma_x^2 = \frac{1}{n} E[X^2] + \frac{1}{n^2} [n(n-1) \mu_x^2] - \frac{2\mu_x}{n} \sum_{i=1}^n \mu_x + \mu_x^2$$

$$\sigma_x^2 = \frac{1}{n} E[X^2] + \frac{n(n-1)}{n^2} \mu_x^2 - \mu_x^2$$

$$\sigma_x^2 = \frac{1}{n} E[X^2] - \frac{1}{n} \mu_x^2$$

$$\sigma_x^2 = \frac{1}{n} (E[X^2] - \mu_x^2)$$

$$\boxed{\sigma_x^2 = \frac{\sigma_x^2}{n}}$$

True
 σ_x^2 : Population Variance

(4)

Sampling without Replacement

Population size $\leq N$

Sample size $\leq n$

The Variance of Sample mean

$$\sigma_{\bar{x}}^2 = \frac{\sigma_x^2}{n} \left(\frac{N-n}{N} \right)$$

Note — Since sample mean is r.v and obtained

by sum of \leq random variables



From central limit theorem that it tends to be

Asymptotically \approx normal regardless of the

distribution of the random variables in samples

— In general assumption of normal distribution is true
for $n \geq 30$

— Define standard normal score of the sample mean

$$Z = \frac{\bar{X} - \mu_{\bar{X}}}{\sigma_{\bar{X}}} = \frac{\bar{X} - \mu_x}{\sigma_x / \sqrt{n}} \quad \text{then when } n \geq 30 \text{ we}$$

obtain

$$F_{\bar{X}}(x) = P[\bar{X} \leq z] = \Phi\left(\frac{x - \mu_x}{\sigma_x / \sqrt{n}}\right)$$

Ex-1

RV X follow the exponential distribution.

$$\text{with pdf } f_X(x) = 2e^{-2x}; x \geq 0$$

With this distribution 36 samples are obtained.

In order to calculate sample mean \bar{X} .

Calculate the following

$$(i) E[\bar{X}^2] \text{ and } E[\bar{X}]$$

$$(ii) P\left[\frac{1}{4} \leq \bar{X} \leq \frac{3}{4}\right] = ?$$

i.e. Probability that sample mean lies between

~~is~~ $\frac{1}{4}$ and $\frac{3}{4}$.

Solutions— (i) Since X follow the exponential distribution,

then true mean $E[X] = \frac{1}{2}$ and

$$\text{true variance } \sigma_x^2 = \frac{1}{4}$$

Since sample mean \bar{X} is unbiased

$$\therefore E[\bar{X}] = E[X] = \frac{1}{2} = M_{\bar{X}}$$

$$(ii) E[\bar{X}^2] = \text{var}(\bar{X}) + \{E[\bar{X}]\}^2 \\ = \sigma_{\bar{X}}^2 + M_{\bar{X}}^2$$

$$E[\bar{X}^2] = \frac{\sigma_x^2}{n} + M_{\bar{X}}^2 \quad (\text{Since } M_{\bar{X}} = M_X)$$

$$= \frac{1/4}{36} + \left(\frac{1}{2}\right)^2 \quad \sigma_{\bar{X}}^2 = \frac{\sigma_x^2}{n}$$

$$= \frac{1/4}{144} + \frac{1}{4}$$

$$E[\bar{X}^2] = \frac{35}{144}$$

$$\bar{X} = \frac{M_{\bar{X}} - \sigma_{\bar{X}} \sim N(0, 1)}{\sigma_{\bar{X}}} \rightarrow \text{DF} \neq \phi$$

$$P\left[\frac{1}{4} \leq \bar{X} \leq \frac{3}{4}\right] = 1$$

$$\bar{X} \sim N(M_{\bar{X}}, \frac{\sigma_x^2}{n})$$

$$P\left[\frac{1}{4} \leq \bar{X} \leq \frac{3}{4}\right] = F_{\bar{X}}\left(\frac{3}{4}\right) - F_{\bar{X}}\left(\frac{1}{4}\right)$$

$$= \Phi\left(\frac{3-1/2}{\sqrt{1/144}}\right) - \Phi\left(\frac{1-1/2}{\sqrt{1/144}}\right)$$

$$= \Phi(3) - \Phi(-3) = 2\Phi(3) - 1$$

8 The Sample Variance

Variance \Rightarrow indicates the spread of values around the mean.

Estimate of Variance

The sample variance is denoted by s^2 and defined by

$$s^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 \quad \text{--- (1)}$$

$$\text{Since } x_i - \bar{x} = (x_i - E[X]) - (\bar{x} - E[X])$$

$$(x_i - \bar{x})^2 = (x_i - E[X])^2 + (\bar{x} - E[X])^2 \\ - 2(x_i - E[X])(\bar{x} - E[X])$$

$$\begin{aligned} \sum_{i=1}^n (x_i - \bar{x})^2 &= \sum_{i=1}^n (x_i - E[X])^2 + \sum_{i=1}^n (\bar{x} - E[X])^2 \\ &- 2(\bar{x} - E[X]) \sum_{i=1}^n (x_i - E[X]) \\ &= \sum_{i=1}^n (x_i - E[X])^2 + n(\bar{x} - E[X])^2 \\ &- 2n(\bar{x} - E[X])^2 \end{aligned}$$

$$\sum_{i=1}^n (x_i - \bar{x})^2 = \sum_{i=1}^n (x_i - E[X])^2 - n(\bar{x} - E[X])^2 \quad \text{--- (2)}$$

Now from (1) and (2) we have

$$s^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 = \frac{1}{n} \sum_{i=1}^n (x_i - E[X])^2 - (\bar{x} - E[X])^2 \quad \text{--- (3)}$$

Now from (3) we have

$$E[S^2] = E\left[\frac{1}{n} \sum_{i=1}^n (x_i - E[x])^2 - (\bar{x} - E[\bar{x}])^2\right]$$

$$= \frac{1}{n} \sum_{i=1}^n E[(x_i - E[x])^2] - E[(\bar{x} - E[\bar{x}])^2]$$

$$= \sigma_x^2 = \sigma_x^2 - \frac{\sigma_x^2}{n}$$

$$E[S^2] = \frac{(n-1)}{n} \sigma_x^2$$

σ_x^2 : Population Variance

Sample Variance is biased estimate

Unbiased estimate

For unbiased estimate define new r.v.
as

$$\hat{s}^2 = \frac{n}{n-1} S^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

$$E[\hat{s}^2] = \sigma_x^2 = \text{Population Variance}$$

\hat{s}^2 is an unbiased estimate of the Variance

[This is for infinite population or
finite population with replacement]

Sampling With Replacement from
a finite population of size N .

mean of sample variance

$$\boxed{E[S^2] = \left(\frac{N}{N-1}\right) \left(\frac{n-1}{n}\right) \sigma_x^2}$$

Sampling Distributions

When sample size, n , is large, then

from central limit theorem allows to expect

Sample mean follow normal distribution

with ~~standardized~~ z-score given by:

$$\left[Z = \frac{\bar{X} - \mu_x}{\sigma_x} = \frac{\bar{X} - \mu_x}{\sigma_x / \sqrt{n}} \right] \quad (1)$$

Normalizing assumption is valid for ~~large~~

~~large~~ $n \geq 30$

($n < 30$) \Rightarrow When $n < 30$, we use student's t-distribution

t-distribution by defining the normalized

sample mean as:

$$T = \frac{\bar{X} - \mu_{Tx}}{\hat{s} / \sqrt{n}} = \frac{\bar{X} - \mu_{Tx}}{s / \sqrt{n-1}} \quad (2)$$

for sample size n , the student's t-distribution

is said to have $n-1$ degree of freedom.

The pdf of the student's t-distribution is given

by

$$f_T(t) = \frac{\Gamma(\frac{v+1}{2})}{\sqrt{v\pi} \Gamma(v/2)} \left(\frac{t^2 + 1}{v} \right)^{-\frac{(v+1)}{2}} \quad (3)$$

Where $\Gamma_{(n)}$ is Gamma function of n

$v = n - 1$ is the number of degrees of freedom,

which is the number of independent samples.

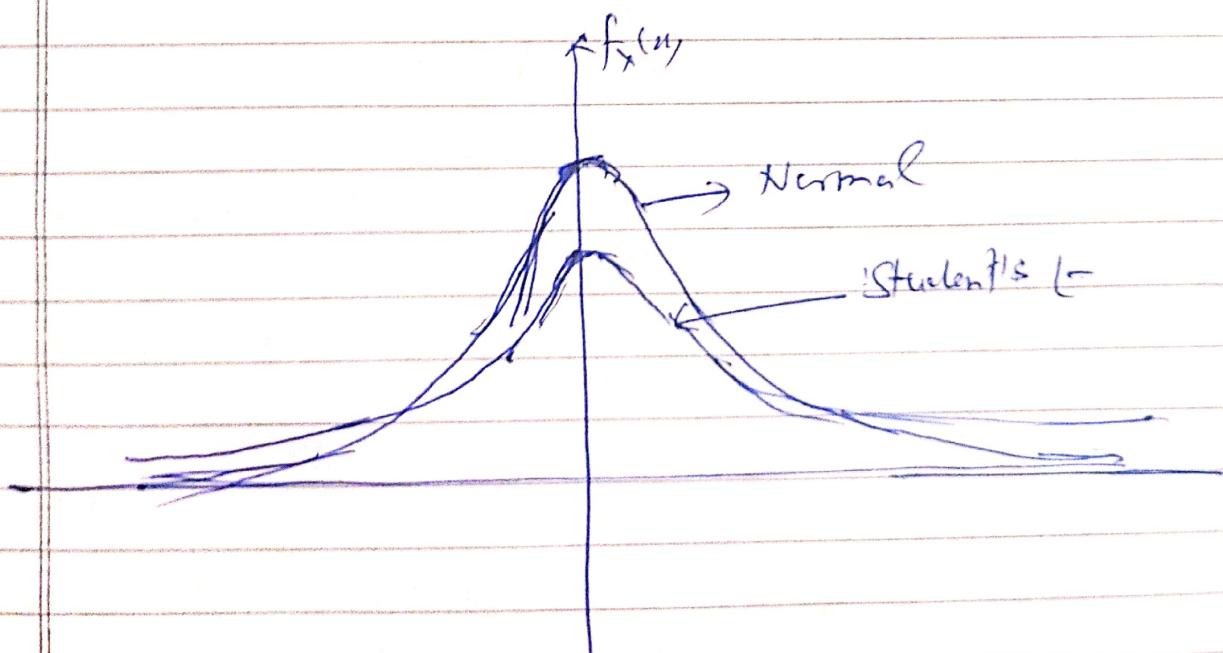
$$\Gamma(k+1) = \begin{cases} k! & , \text{ any } k \\ k! & , \text{ if } k \text{ integer} \end{cases}$$

$$\Gamma(2) = \Gamma(1) = 1$$

$$\Gamma(1/2) = \sqrt{\pi}$$

Student t-distribution is heavy tailed compared to

Standard normal distribution





Estimation Theory

Estimation \Rightarrow making some prediction or estimate on population parameter based on the available sample data.

Estimation Goal is

To estimate a variable that is not directly observable but is observed only through some other ~~variables~~ measurable variables.

e.g. A random variable X has ~~exists~~ distribution that depends on some parameter θ .
 \Rightarrow A statistic $g(x)$ is called estimator of θ , if any value observed value $x \in X$, ~~exists~~ $g(x)$ is considered to be an estimate of θ .

↳ Estimation of parameter can be defined as a rule or function that assigns a value to θ for each realization of x .

Another way look to estimation

• **Fitting probability law/distribution of data**

where often the data consist of a collection

of ~~not realized~~^{realized} variables generated by

the probability distribution under consideration.

Observation data is modeled as realization

realization of i.i.d. $\{X_i\} = \{x_1, x_2, \dots, x_n\}$

with $x_1, x_2, x_3, \dots, x_n \sim F(x|\theta)$

$x_1, x_2, x_3, \dots, x_n \sim F(x|\theta) / f(x|\theta)$

i.e. distribution depends on parameter θ .

That is to be estimated.

e.g. $p(n|\lambda) = \frac{\lambda^n e^{-\lambda}}{n!}, n=0, 1, 2, \dots$ (Poisson pmf with parameter λ)

pdf: $f_x(x|\mu) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}}$; $-\infty < x < \infty$, Normal distribution
Here parameters ~~μ, σ^2~~ μ, σ

pdf: $f_x(x|\theta) = \theta e^{-\theta x}; x \geq 0$, exponential distribution with parameter θ

$$f(x|\lambda, k) = \frac{\lambda^k x^{k-1}}{(k-1)!} e^{-\lambda x}; x \geq 0$$

Erlang distribution with parameter $\{\lambda, k\}$

Properties of Estimator:-

→ The estimation of the parameter θ is the value of θ obtained from realization of x .

e.g. sample mean \bar{x}, \hat{x} , is an estimator

of the population mean μ .

Properties of Estimator:-

① Bias → Bias of estimator $\hat{\theta}$ is defined by

$$\text{Bias}(\hat{\theta}) = E[\hat{\theta}] - \theta$$

→ An unbiased estimator of population parameter is a statistic whose mean or expected value is equal to the parameter being estimated.

Thus estimator $\hat{\theta}$ is defined to be

$$\boxed{\text{Bias}(\hat{\theta}) = E[\hat{\theta}] - \theta}$$

Unbiased if $\boxed{E[\hat{\theta}] = \theta}$ $\boxed{E[\hat{\theta}] = \theta}$

(ii) Efficiency :-

If sampling distributions of two statistics have the same mean, the statistic with the smaller variance is said to be more efficient estimator of the mean.

e.g. let \hat{X}_1 and \hat{X}_2 are unbiased estimators of X , then \hat{X}_1 is more efficient estimator of X than \hat{X}_2 if $\sigma_{\hat{X}_1}^2 < \sigma_{\hat{X}_2}^2$

(iii) consistency :- (if we assume use

an estimator of the sample mean in the form

$$\hat{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

where X_i , $i=1, 2, 3, \dots, n$ are observed at ~~data~~ data used to estimate θ .

" \hat{X} " is said to an efficient estimator of θ if it is ~~center~~ converges in probability to θ ;

that is

$$\lim_{n \rightarrow \infty} P[|\hat{x} - \theta| \geq \epsilon] = 0$$

Thus as $n \rightarrow \infty$ the unbiased consistent estimator
get closer to the true parameter.

Point Estimate, Interval Estimate and confidence intervals

— In Point estimate a single value is assigned to the estimate.

e.g. e.g. sample mean, variance of sample mean

— Interval estimate \rightarrow ^{Estimate} not coincide ~~to~~ with the parameter they are estimating.

↳ In this parameter being estimated lies within certain interval; called "confidence interval" with a certain probability.

↳ parameter estimate lie within two numbers, with certain degree of confidence

9 - percent Confidence interval :-

↳ 9% confidence interval is ^{on} interval with which the ~~prob~~ estimate ~~will~~ will lie with probability $\frac{9}{100}$.

\Rightarrow population parameter have probability

$\frac{q}{100}$ belonging to the $q\%$ confidence interval.

parameter, q , is called the confidence level :-

~~95% 95%~~

95% confidence interval for the mean μ is a random interval that contains μ with probability 0.95.

\Rightarrow interval \Rightarrow uncertainty in estimate.

Sample Mean

Sample mean follows the normal distribution

for $n \geq 30$

For sample mean $q\%-$ confidence interval is defined as follows

Sampling with replacement from infinite population

$$\bar{X} - k \sigma_{\bar{X}} \leq \mu_X \leq \bar{X} + k \sigma_{\bar{X}}$$

\uparrow
Population mean

Equivalently

$$\boxed{\bar{X} - \frac{k\sigma_x}{\sqrt{n}} \leq M_x \leq \bar{X} + \frac{k\sigma_x}{\sqrt{n}}}$$

where k is constant that depends on α

and is called confidence coefficient or critical

Value

$k \Rightarrow$ Number of standard deviation on either

side either side of the mean that the confidence interval is expected to cover.

Confidence limit

$$\bar{X} \pm k\sigma_{\bar{X}} = \bar{X} \pm \frac{k\sigma_x}{\sqrt{n}}$$

And error of estimate is

$$\boxed{k\sigma_{\bar{X}} = \frac{k\sigma_x}{\sqrt{n}}}$$

Sampling without Replacement — Sampling without

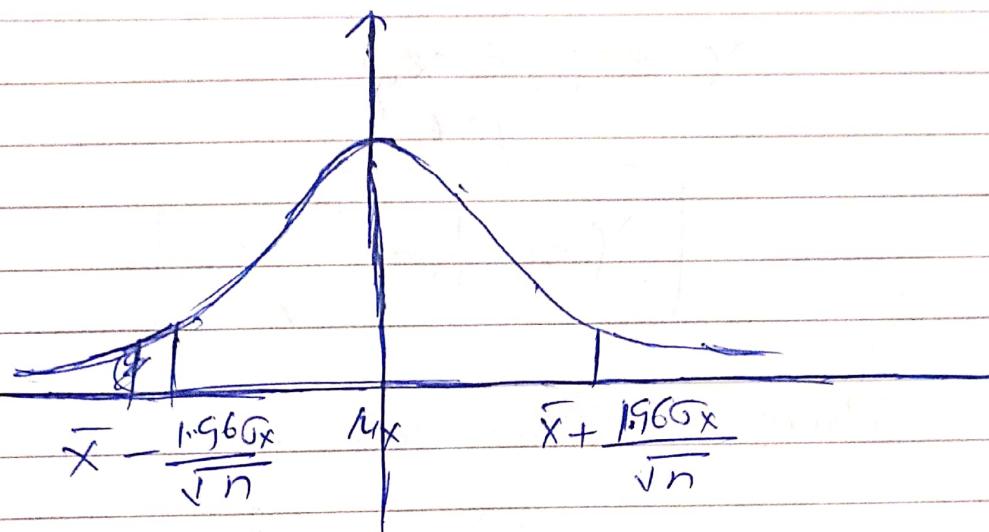
replacement from a finite population of ~~size~~

size N ; we obtain

$$\boxed{\bar{X} - \frac{k\sigma_x}{\sqrt{n}} \sqrt{\frac{N-n}{N-1}} \leq M_x \leq \bar{X} + \frac{k\sigma_x}{\sqrt{n}} \sqrt{\frac{N-n}{N-1}}}$$

Table 8.1: Values of k for different confidence Level

Confidence Level	99.99%	99.9%	99%	95%	90%	80%
k	3.89	3.29	2.58	1.96	1.64	1.28



Interval estimate and Point estimate

Interval estimate = Point estimate $\pm k_q \times \text{Sample standard deviation}$

k_q is value of confidence coefficient k_q for specified confidence level q .

Ex: If $\sigma_x = 1$, determine the number of observations required to ensure that at the 99% confidence level, $\bar{x} - 0.1 \leq E(\bar{x}) \leq \bar{x} + 0.1$, where

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

Solution: The variance of the sample

mean is $\sigma_{\bar{X}}^2 = \frac{\sigma_x^2}{n}$, From table 1

for the 99% confidence level the confidence

coefficient is $k = 2.58$ Thus

$$P \left[\bar{X} - \frac{2.58 \sigma_x}{\sqrt{n}} \leq E(\bar{X}) = \mu_x \leq \bar{X} + \frac{2.58 \sigma_x}{\sqrt{n}} \right] = 0.99$$

$$\frac{2.58 \sigma_x}{\sqrt{n}} = 0.1$$

$$\sigma_x = 1 \text{ (given)}$$

$$\frac{2.58 \times 1}{\sqrt{n}} = 0.1$$

$$\therefore \sqrt{n} = 25.8$$

$$\therefore n = (25.8)^2$$

$$n = (25.0)^2$$

$$\therefore \boxed{n = 665.64}$$

Thus, n must be integer, and we have

$$\boxed{n = 666}$$

Maximum Likelihood

Estimation

To obtain best estimation of parameter(s)

that characterizes a random variable

X

→ Choose the value(s) of parameter(s) that matches the observed values most probable

Let X be a r.v. whose distribution is depends on single parameter θ . Let $x_1, x_2, x_3, \dots, x_n$ be an observed random sample. (Let X is discrete with pmf $p_x(x, \theta)$, the probability that random sample consists of these values is given by

$$L(\theta) = L(\theta; x_1, x_2, x_3, \dots, x_n)$$

$$= p_x(x_1, \theta) \cdot p_x(x_2, \theta) \cdots p_x(x_n, \theta)$$

$$L(\theta) = p_x(x_1, \theta) \cdot p_x(x_2, \theta) \cdot p_x(x_3, \theta) \cdots p_x(x_n, \theta)$$

Joint distribution for getting x_1, x_2, \dots, x_n (1)

This ① is called likelihood function and

it is function of θ , and observed values

$$x_1, x_2, \dots, x_n$$

- If x is with cont. with p.d.f $f_x(x)$, then the likelihood function is given by

~~L(θ)~~

$$L(\theta) = f_x(x_1, \theta) \cdot f_x(x_2, \theta) \cdot f_x(x_3, \theta) \cdots f_x(x_n, \theta) \quad (2)$$

The maximum likelihood estimate of θ is

given as solution of following :

$$\hat{\theta} = \arg \max_{\theta} L(x_1, x_2, \dots, x_n, \theta)$$

- For n parameters : of likelihood function contains n parameters:

$$L(\theta_1, \theta_2, \dots, \theta_k; x_1, x_2, x_3, \dots, x_n) = \prod_{i=1}^n f_x(x_i, \theta_1, \theta_2, \dots, \theta_n)$$

$$\frac{\partial L}{\partial \theta_1} = 0, \quad \frac{\partial L}{\partial \theta_2} = 0, \quad \dots, \quad \frac{\partial L}{\partial \theta_k} = 0$$

Ex. Suppose a random sample of size n is

drawn from the Bernoulli distribution.

What is the maximum likelihood estimate of p , the success probability?

Soluⁿ Let X be Bernoulli r.v. with probability of success with p . Then the pmf of X is

$$P(X=x|p) = p^x (1-p)^{1-x}, \quad x=0, 1; \\ 0 \leq p \leq 1$$

The sample values x_1, x_2, \dots, x_n are sequence of 0's and 1's and the likelihood function is

$$\begin{aligned} L(p; x_1, x_2, \dots, x_n) &= \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} \\ &= p^{\sum x_i} (1-p)^{\sum (1-x_i)} \\ &= p^{\sum x_i} (1-p)^{n - \sum x_i} \end{aligned}$$

$$\text{Let } y = \sum x_i$$

$$\therefore L(p; x_1, x_2, x_3, \dots, x_n) = p^y (1-p)^{n-y} \quad (1)$$

on b.c.s.e.

now taking logⁿ of both sides.

$$\cancel{\log L(p; x_1, x_2, \dots, x_n)} = y \log p + (n-y) \log (1-p)$$

Taking partial derivative w.r.t p we obtain

$$\begin{aligned} \frac{\partial}{\partial p} \log L(p; x_1, x_2, x_3, \dots, x_n) &= \frac{y}{p} + \frac{(n-y)}{1-p} \\ &= \frac{y}{p} - \frac{n-y}{1-p} \end{aligned}$$

Now maximize L

$$\frac{\partial}{\partial p} \log L(p; x_1, x_2, x_3, \dots, x_n) = 0$$

$$\therefore \frac{y}{p} - \frac{n-y}{1-p} = 0$$

$$y(1-p) - (n-y)p = 0$$

$$\therefore y - \hat{p}y - np + y\hat{p} = 0$$

$$\therefore y - n\hat{p} = 0$$

$$\therefore \hat{p} = \frac{y}{n}$$

$\hat{p} = \frac{1}{n} \sum_{i=1}^n x_i$

Thus \hat{p} is mean of sample values.

Minimum Mean Square Error

Estimation

\hat{x} be an estimator of random variable x .

The estimator e is defined as

$$e = x - \hat{x}$$

e is also random variable, provides measure of how well is estimator performs.

Goodness of an estimator (How define it)?

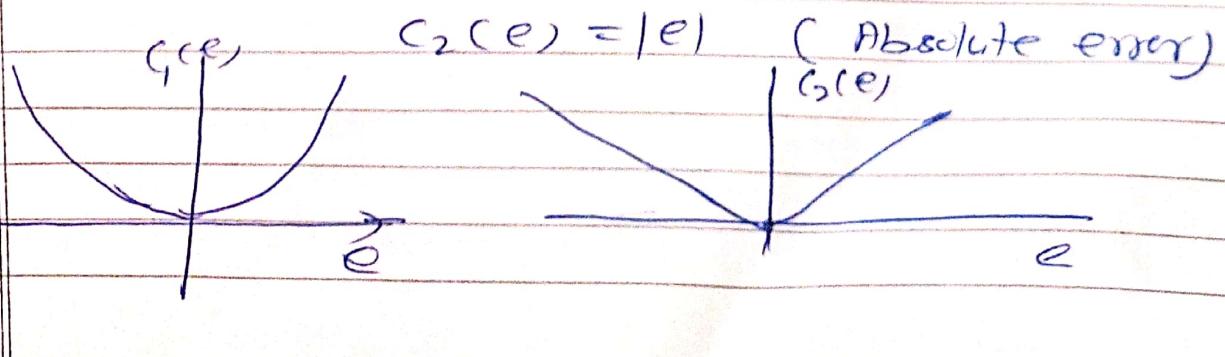


Define an appropriate cost function
~~cost~~ $C(e)$ of e .



Estimator is chosen such that $C(e)$ is minimum. The choice of cost function is subjective:

$$\cancel{C(e)} \quad C_1(e) = e^2 \quad (\text{Squared error})$$



Mean Square Error:-

$$C(e) = E(e^2)$$

- * Find the estimate in terms of first order and second order moment

Ex

- Given random variable Y estimated from the random variable X by the following linear function of X :

$$\hat{Y} = aX + b$$

Determine the value of a and b that minimize the mean square error.

Solution:-

$$e_{ms} = E[(Y - \hat{Y})^2] = E[(Y - (aX + b))^2]$$

$$\begin{aligned}\frac{\partial e_{ms}}{\partial a} &= E[2(Y - (aX + b))X] \\ &= E[-2X\{Y - (aX + b)\}] = 0\end{aligned}$$

$$\frac{\partial e_{ms}}{\partial b} = E[2(-1)\{Y - (aX + b)\}] = 0$$

$$\therefore E[XY] = aE[X^2] + bE[X]$$

$$E[XY] = aE[X] + b$$

$$\therefore a^* = \frac{E[XY] - E[X]E[Y]}{E[X]^2} = \frac{\rho_{XY}}{\sigma_X^2} = \frac{\rho_{XY}\sigma_Y}{\sigma_X^2}$$

$$a^* = \frac{\rho_{XY}\sigma_Y}{\sigma_X^2} \quad b^* = E[Y] - \frac{\rho_{XY}E[X]}{\sigma_X^2}$$

$$b^* = E[Y] - \frac{\rho_{XY}\sigma_Y E[X]}{\sigma_X^2}$$

$$e_{mms} = e_{ms}|_{a^*} = \sigma_Y^2 - \rho_{XY}^2 \sigma_Y^2 = \sigma_Y^2(1 - \rho_{XY}^2)$$