# Theory of Computation: CS-202

### Outline

- ☐ Two Important Normal Forms
  - ☐ Chomsky Normal Form
  - ☐ Greibach Normal Form
- Push Down Automata
  - Deterministic Push Down Automata
  - ☐ Non Deterministic Push Down Automata

# Chomsky Normal Form

• A Context free Grammar G is in Chomsky normal form if all the productions are of the form

$$A \rightarrow BC$$
  
or  $A \rightarrow a$   
Where, A, B, C  $\subseteq$  V and  $a \subseteq T$ 

Consider the grammar G with production:

 $S \rightarrow AS \mid a$ 

 $A \rightarrow SA|b$ 

is in Chomsky Normal Form.

Consider the grammar G with production:

 $S \rightarrow AS \mid AAS$ 

 $A \rightarrow SA|aS$ 

is not in Chomsky Normal Form.

Convert the grammar  $G=(\{A,B,C\}, \{a,b,c\}, S, P)$  into Chomsky Normal Form.

 $P: S \rightarrow AB a$ 

 $A \rightarrow aab$ 

 $B \rightarrow Ac$ 

$$\Rightarrow S \rightarrow ABB_{a}$$

$$A \rightarrow B_{a}B_{a}B_{b}$$

$$B \rightarrow AB_{c}$$

$$B_{a} \rightarrow a, B_{b} \rightarrow b, B_{c} \rightarrow c$$

$$\Rightarrow S \rightarrow AD_1$$

$$D_1 \rightarrow BB_a$$

$$A \rightarrow D_2 B_b$$

$$D_2 \rightarrow B_a B_a, B \rightarrow A B_c$$

$$B_a \rightarrow a, B_b \rightarrow b, B_c \rightarrow c$$

## Greibach Normal Form

A Context free Grammar G is in Greibach Normal Form if all the productions are of the form

$$A \rightarrow a\alpha$$
  
or  $A \rightarrow a$   
Where,  $A \subseteq V$  and  $a \subseteq T$ ,  $\alpha \subseteq V^*$ 

Construct a grammar in Greibach normal form equivalent to the grammar

$$S \rightarrow AB$$
,  $A \rightarrow aA \mid bB \mid b$ ,  $B \rightarrow b$ 

The given grammar is not in Greibach normal form However, using the substitution rule, we can immediately get the equivalent grammar

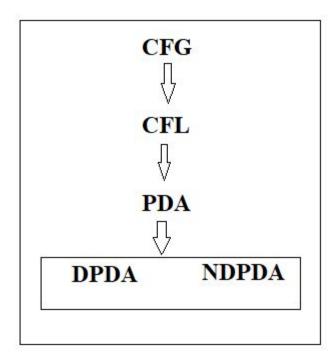
$$S \to aAB|bBB|bB$$

$$A \to aA|bB|b$$

$$B \to b$$

Which is in Greibach normal form

### Context free Grammar, Language and PDA



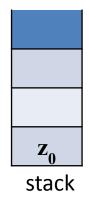
#### Formal Definition of a deterministic PDA

#### A <u>pushdown automaton (PDA)</u> is defined by the seven-tuples:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, z_0, F)$$

- Q A <u>finite</u> set of states
- $\Sigma$  A <u>finite set of</u> input alphabet
- $\Gamma$  A <u>finite</u> set of stack alphabet
- $q_0$  The initial/starting state,  $q_0$  is in Q
- $z_0$  A starting stack symbol, is in  $\Gamma$
- F A set of final/accepting states, which is a subset of Q
- $\delta$  A transition function, where

$$δ$$
: Q x (Σ U {ε}) x Γ → Q x Γ\*



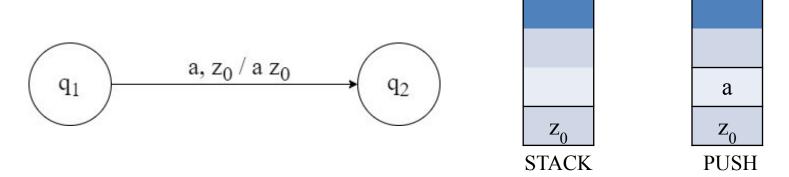
## Block diagram of PDA

Input tape b b a a 3 Read header Finite Control Unit  $\mathbf{Z}_{0}$ stack

## Moves of the PDA: Push, Pop, Skip

#### Push:

$$\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$$

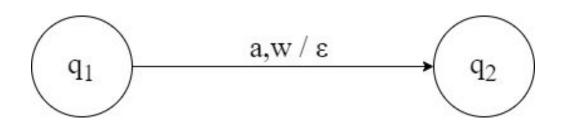


$$\delta(q_1, a, z_0) = (q_2, az_0)$$

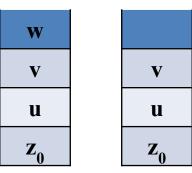
### Moves of the PDA (Cont..)

#### Pop:

$$\delta$$
: Q x (Σ U {ε}) x  $\Gamma \rightarrow Q$  x  $\Gamma^*$ 

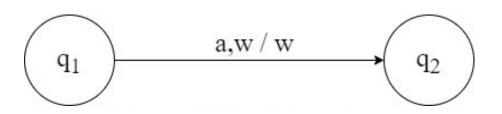


 $\delta(q_1, a, w) = (q_2, \varepsilon)$ 



### Moves of the PDA (Cont..)

Skip:  $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$ 



$$\delta(q_1, a, w) = (q_2, w)$$

## Moves of the PDA (Cont..)

#### Final:

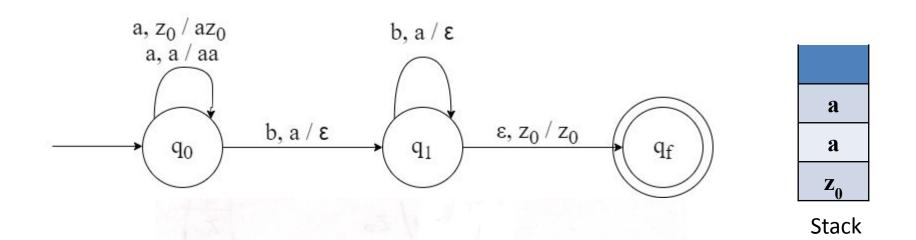
$$δ$$
: Q x (Σ U {ε}) x  $Γ$  → Q x  $Γ$ \*

$$\delta(q_1, \varepsilon, z_0) = (q_f, z_0)$$

Or 
$$\delta(q_1, \epsilon, z_0) = (q_f, \epsilon)$$

# Design a PDA for the language $L=\{a^nb^n, n\geq 1\}$

		L	l <sub>a</sub>	
a	a	l D	D	3



# Design a PDA for the language $L=\{a^nb^n, n\geq 1\}$

#### Transition steps for L

$$\delta(q_0, a, z_0) = (q_0, az_0)$$

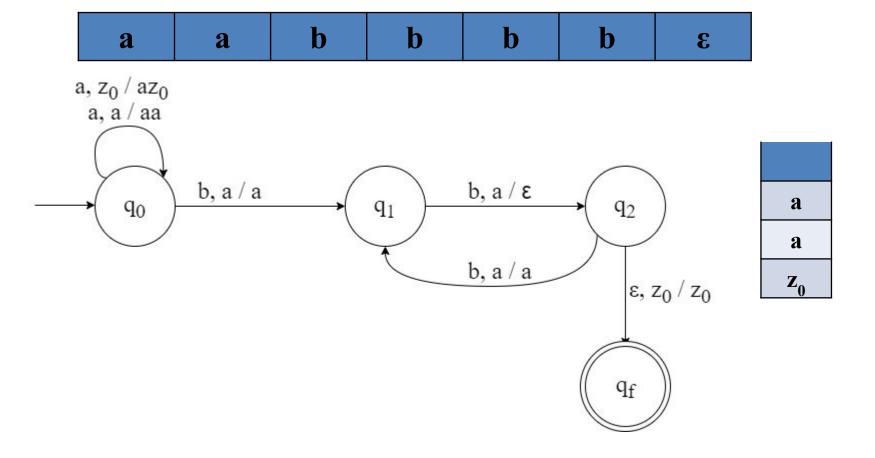
$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, \varepsilon, z_0) = (q_f, z_0)$$

# Design a PDA for the language $L=\{a^nb^{2n}, n\geq 0\}$



# Design a PDA for the language $L=\{a^nb^{2n}, n\geq 0\}$

$$\delta(q_{0}, a, z_{0}) = (q_{0}, az_{0})$$

$$\delta(q_{0}, a, a) = (q_{0}, aa)$$

$$\delta(q_{0}, b, a) = (q_{1}, a)$$

$$\delta(q_{1}, b, a) = (q_{2}, \epsilon)$$

$$\delta(q_{2}, b, a) = (q_{1}, a)$$

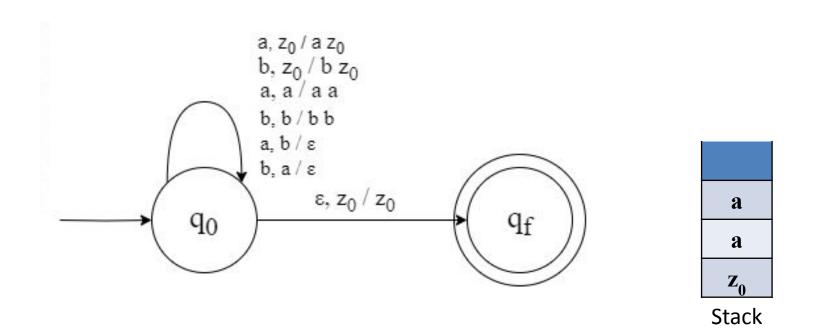
$$\delta(q_{1}, \epsilon, z_{0}) = (q_{1}, a)$$

$$\delta(q_{1}, \epsilon, z_{0}) = (q_{1}, a)$$

$$\delta(q_{1}, \epsilon, z_{0}) = (q_{1}, a)$$

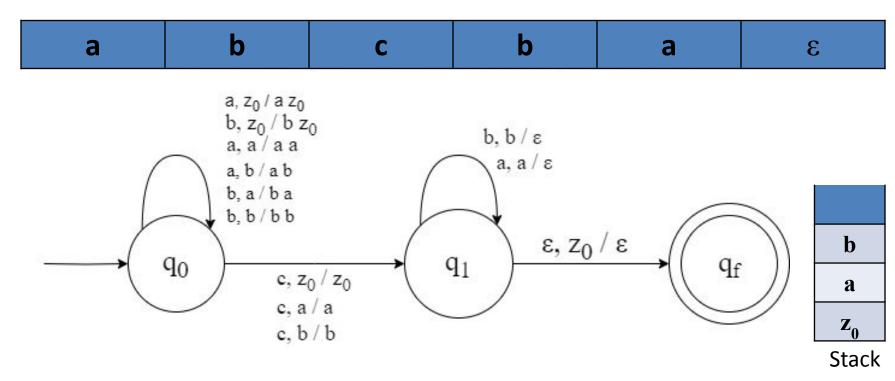
$$L=\{w = (a, b)^* : n_a(w) = n_b(w)\}$$

a a b E



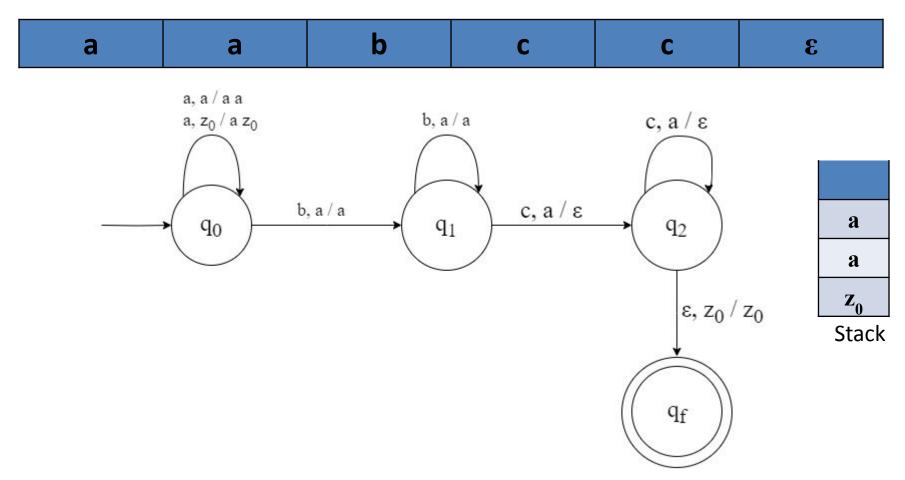
$$L=\{wcw^R, w \in (a, b)^*\}$$

Input tape



$$L=\{a^nb^mc^n, n, m\geq 1\}$$

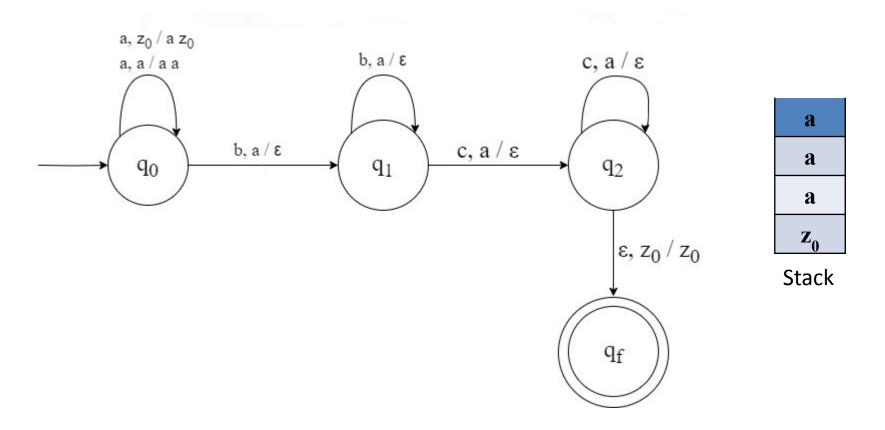
Input tape



 $L = \{a^{m+n}b^mc^n, m, n \ge 1\}$ 

Input tape

|--|



# Practice problem

Design a PDA for the language  $L=\{a^nb^mc^md^n \ m, n\geq 1\}$ 

#### Suggested readings

- 1. An introduction to FORMAL LANGUAGES and AUTOMATA by PETER LINZ.
- 2. Introduction to Automata Theory, Languages, And Computation by JOHN E. HOPCROFT, RAJEEV MOTWANI, JEFFREY D. ULLMAN
- 3. Theory of computer science: automata, languages and computation by K.L.P MISHRA

# Thank you