

Artificial Intelligence with Arduino Portenta H7

Real-time Object Detection with Vision Shield

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May 24, 2024

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Introduction

Project Overview

This presentation focuses on the project titled **Real-time Object Detection with a Vision Shield**, which demonstrates the integration of artificial intelligence (AI) with embedded systems.

Project Objectives

- Develop a system for real-time object detection using Arduino Portenta H7 and Vision Shield.
- Implement AI algorithms on embedded devices for efficient and accurate object detection.

Importance

Real-time object detection has applications in surveillance, industrial automation, robotics, and IoT, among others.

Components

Description

The project involves the following components:

- **Arduino Portenta H7:** The core microcontroller unit providing processing power and resources for AI algorithms.
- **Vision Shield:** An accessory for the Portenta H7, equipped with a camera module and display for image capture and processing.
- **AI Model:** A pre-trained model deployed on the Portenta H7 for object detection tasks.

Role

- **Arduino Portenta H7:** Provides computational power and interfaces with the Vision Shield.
- **Vision Shield:** Captures live video frames and displays annotated results.
- **AI Model:** Analyzes video frames for real-time object detection and display detected objects on the Vision Shield's built-in display in real-time.

Figures

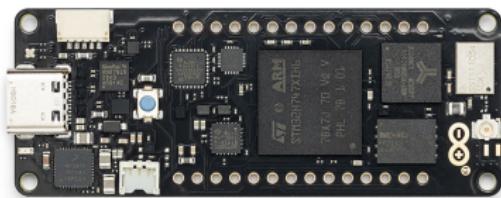


Figure1: Arduino PortentaH7

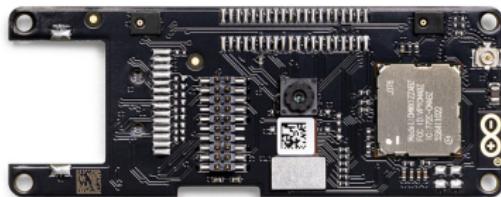


Figure2: PortentaH7 Vision
Shield

Methodology - Hardware Setup

- **Step 1: Connect the Vision Shield to the Arduino Portenta H7**

- Align the Vision Shield with the high-density connectors on the Portenta H7.
- Press down firmly to ensure a secure connection.

- **Step 2: Connect the Arduino Portenta H7 to the Laptop**

- Use a USB Type-C cable to connect the Portenta H7 to your laptop.
- Ensure the connection is stable and the board is powered on.

- **Step 3: Install Necessary Libraries and Dependencies**

- Open the Arduino IDE on your laptop.
- Navigate to the Library Manager (Sketch → Include Library → Manage Libraries).
- Install the required libraries for the Vision Shield and Portenta H7.

- **Step 4: Verify the Hardware Connection**

- Ensure the LED on the Portenta H7 starts blinking green.
- If the board does not respond, double-press the reset button to enter bootloader mode.

Methodology - AI Model Deployment

- **Loading the Pre-trained AI Model**

- Obtain a pre-trained AI model optimized for object detection.
- Ensure the model is compatible with the resources of the Portenta H7.

- **Optimizing the Model for Embedded Deployment**

- Convert the model to a format that can be efficiently run on the microcontroller.
- Use frameworks like TensorFlow Lite for Microcontrollers.
- Perform quantization to reduce the model size and inference time.

- **Deploying the Model on the Portenta H7**

- Load the converted model onto the Portenta H7's flash memory.
- Utilize Arduino libraries to interface with the model.

- **Real-time Inference on the Portenta H7**

- Capture images from the Vision Shield's camera.
- Pass the images to the AI model for inference.
- Interpret the output to identify and classify objects in real-time.

Methodology - Real-time Object Detection

- **Capturing Live Video Frames:**

- The Vision Shield's camera captures live video frames.
- Frames are continuously fed into the Portenta H7 for processing.

- **Processing Frames in Real-time:**

- Each frame is processed by the AI model deployed on the Portenta H7.
- The model performs object detection, identifying and classifying objects in the frame.

- **Annotating Detected Objects:**

- Detected objects are annotated directly on the video feed.
- Bounding boxes and labels are overlaid to highlight detected objects.

- **Displaying Output:**

- The annotated video feed is displayed on the Vision Shield's built-in display.
- Real-time feedback provides immediate visual confirmation of detected objects.

Expected Outcome

- Live video feed from the Vision Shield's camera module.
- Real-time annotation of detected objects on the video feed.
- Accurate and efficient object detection and classification.
- Instant visual feedback displayed on the Vision Shield's built-in display.
- Potential for further customization and integration into larger systems.

Applications

Real-time object detection with the Arduino Portenta H7 and Vision Shield has numerous applications across various industries:

- **Surveillance and Security Systems:** Enhance security measures by detecting and identifying intruders or suspicious objects in real-time.
- **Industrial Automation and Quality Control:** Ensure product quality by identifying defects or anomalies on manufacturing lines.
- **Robotics and Autonomous Navigation:** Enable robots and autonomous vehicles to perceive and react to their surroundings, enhancing safety and efficiency.
- **Smart Home Devices and IoT Applications:** Create intelligent devices capable of recognizing and responding to human activities or environmental changes.

Real-time object detection provides valuable insights and automation capabilities in diverse fields, making it a versatile and powerful technology for modern applications.

Conclusion

- The project showcases the potential of AI-enabled embedded systems for real-time object detection.
- By leveraging the computational power of the Arduino Portenta H7 and the image processing capabilities of the Vision Shield, complex tasks like object detection can be performed efficiently and accurately in real-time.
- The project opens up possibilities for a wide range of applications in industries such as surveillance, industrial automation, robotics, and IoT, where real-time object detection is crucial for decision-making and automation.

Thank you
for your attention