

CSE 4/531

Solution 03

1. (20 points) Let M be an $n \times n$ matrix with each entry having a real number. Design a dynamic programming algorithm to find a longest sequence $S = (m_{i_1, j_1}, m_{i_2, j_2}, \dots, m_{i_k, j_k})$ such that $i_r < i_{r+1}, j_r < j_{r+1}$, and $m_{i_r, j_r} > m_{i_{r+1}, j_{r+1}}$ for all $1 \leq r \leq k$. You should make your algorithm run as fast as possible.

ANS: Without loss generality, we assume that the last number m_{i_k, j_k} of S is $M[i, j]$ for some $1 \leq i, j \leq n$. It means that $i_k = i, j_k = j$ and $m_{i_k, j_k} = M[i, j]$. Because of decreasing property for indexes $(i_r, j_r), 1 \leq r \leq k$, we have $i_{k-1} \leq i - 1$ and $j_{k-1} \leq j - 1$. It also implies that $(m_{i_1, j_1}, m_{i_2, j_2}, \dots, m_{i_{k-1}, j_{k-1}})$ is a longest decreasing sequence of a sub-matrix $M[1 \sim i', 1 \sim j']$ for some $1 \leq i' < i$ and $1 \leq j' < j$.

From the above discussion, we immediately have the following recursive formula: Let $L[i, j]$ denote the length of a longest decreasing sequence $S = (m_{i_1, j_1}, m_{i_2, j_2}, \dots, m_{i_k, j_k})$ with (1): $m_{i_k, j_k} = M[i, j]$, (2): $i_k = i$ and (3): $j_k = j$ in the matrix $M[1 \sim i, 1 \sim j]$.

$$L[i, j] = \max_{\substack{i' < i, j' < j \text{ and} \\ M[i', j'] > M[i, j]}} \{1 + L[i', j']\}. \quad (1)$$

Next, how to complete the table L ? The following two pseudocodes are approaches to find the length of a longest sequence of M and a longest sequence S . Also, we provide the time complexity analysis for this question.

Algorithm 1 Compute the length of a longest sequence of M

```

1: for  $1 \leq i \leq n$  do
2:    $L[i, 1] := 1$ 
3: end for
4: for  $1 \leq i \leq n$  do
5:    $L[1, j] := 1$ 
6: end for
7: for  $1 \leq i \leq n$  do
8:   for  $1 \leq j \leq n$  do
9:     Find a pair of indexes  $(i', j')$  satisfying Equation (1).
10:     $L[i, j] := 1 + L[i', j']$ 
11:   end for
12: end for

```

Since we have n^2 entries in L and each entry $L[i, j], 1 \leq i, j \leq n$ takes $(i - 1) \times (j - 1)$ time to find the best i' and j' , the total time complexity is

$$\sum_{1 \leq i, j \leq n} (i - 1) \times (j - 1) = O(n^4).$$

Algorithm 2 FindLongestSequence(L, M)

```
1: Find a maximum  $L[i, j]$  in  $L$ .
2:  $i_r := i$  and  $j_r := j$ .
3: Assign  $M[i_r, j_r]$  to  $S$ .
4: while  $i_r > 1$  &&  $j_r > 1$  do
5:   search the sub-matrix  $L[1 \sim i_r - 1, 1 \sim j_r - 1]$  to find a pair  $(i, j)$  with  $L[i_r, j_r] = L[i, j] + 1$ .
6:    $i_r := i$ .
7:    $j_r := j$ .
8:   Add  $M[i_r, j_r]$  to the head of  $S$ .
9: end while
   return  $S$ ;
```

2. (20 points) Let P be a convex polygon with n vertices. A triangulation of P is an addition of a set of non-crossing diagonals (which connect non-neighbor vertices of P) such that the interior of P is partitioned by the set of diagonals into a set of triangles. The weight of each diagonal is the Euclidean distance of the two vertices it connects. The weight of a triangulation is the total weight of its added diagonals. Design a dynamic programming algorithm to find a minimum weighted triangulation of P . You should make your running time as short as possible.

ANS: This question is similar to Minimum Weight of Matrix Multiplication Problem. Hence we have a similar recursive formula:

Assume the polygon $P = (1, 2, \dots, n)$. Then, let $T[i, j]$ be the weight of a minimum triangulation for the polygon $(i, i+1, \dots, j-1, j)$ and $w(a, b)$ be the Euclidean distance between a and b . We can observe that given a minimum weighted triangulation for P with cost $T(1, n)$, the edge $(1, n)$ will company with some point k to form the triangle $\triangle_{1,k,n}$ and $T[1, n] = T[1, k] + w(\triangle_{1,k,n}) + T[k, n]$ where $w(\triangle_{i,k,j})$ is $w(i, j) + w(j, k) + w(i, k)$. Then we have

$$T[i, j] = \begin{cases} \min_{i < k < j} \{T[i, k] + T[k, j] + w(\triangle_{i,k,j})\} & \text{if } i < j \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

Next, how to complete the table T ? The following two pseudocodes are approaches to find the weight of a minimum triangulation of P and a minimum triangulation of P . Also, we provide the time complexity analysis for this question.

Algorithm 3 Compute Minimum Triangulation of P

```
1: Initialize two  $n \times n$  matrices  $T$  and  $K$ .
2: for  $1 \leq i \leq n$  do
3:   for  $i+2 \leq j \leq n$  do
4:     find a best  $k$  for the Equation (2).
5:      $T[i, j] = T[i, k] + T[k, j] + w(\triangle_{i,k,j})$ .
6:      $K[i, j] = k$ .
7:   end for
8: end for
```

Each entry $T[i, j]$ has to take $(j - i - 1)$ time to find the best k and we have $O(n^2)$ entries for T . So, the total time complexity is

$$\sum_{1 \leq i < j \leq n} (j - i - 1) = O(n^3).$$

Algorithm 4 FindMinTriangulation($1, n, K$)

```
1: Set  $i := 1$ ,  $j := n$  and  $k = K[i, j]$ .
2: Draw two diagonals  $(i, k)$  and  $(k, n)$  in  $P$ .
3: FindMinTriangulation( $i, k, K$ ).
4: FindMinTriangulation( $k, j, K$ ).
```

3. (20 points) Let $G = (V, E)$ be a directed graph modeling a communication network. Each link e in E is associated with two parameters, $w(e)$ and $d(e)$, where $w(e)$ is a non-negative number representing

the cost of sending a unit-sized packet through e , and $d(e)$ is an integer between 1 and D representing the time (or delay) needed for transmitting a packet through e . Design an algorithm to find a route for sending a packet between a given pair of nodes in G such that the total delay is no more than k and the total cost is minimized. Your algorithm should run in $O(k(|E| + |V|))$ time and $O(k|V|)$ space (additional to space for storing the graph).

ANS: Suppose the given starting point is v_s , the ending point is v_e . If there is an edge $e(u, v)$ which is an edge from u to v , let $d(u, v) = d(e)$, $w(u, v) = w(e)$. Here suppose we use Adjacency List representation of graph. Let C be a $|V| \times k$ matrix. Each $C[v, j]$ represents the minimum cost from v_s to v with delay j . Let M be a $|V| \times k$ matrix. Each $M[v, j]$ records the last element before v in the path from v_s to v with the minimum cost $C[v, j]$. Then we have

$$C[v, j] = \begin{cases} 0 & \text{if } v = v_s \\ \min_{u: v \in \text{Adj}[u]} \{C[u, j - d(u, v)] + w(u, v)\} & \text{if } \exists u, \text{ s.t. } d(u, v) < j \\ \infty & \text{if } \forall u, d(u, v) \geq j \end{cases}$$

So we use BFS to traverse the vertices of the graph, each time we come up with a vertex u , we update matrix C for all the vertices it directs into. The problem can be solved follow these steps:

- Initialization.

$$\begin{aligned} C[v_s, j] &= 0, M[v_s, j] = v_s, j = 1, \dots, k \\ C[v, j] &= \infty, v \neq v_s, j = 1, \dots, k \end{aligned}$$

- BFS travel the vertices of the graph.
- Each time we come up with a vertex u , $\forall v \in \text{Adj}[u]$,
 - If $u = v_s$, $d(u, v) \leq k$, then $C[v, j] = w(u, v)$, $M[v, j] = v_s$, $j = d(u, v), \dots, k$.
 - If $u = v_s$, $d(u, v) > k$, then do nothing.
 - If $u \neq v_s$, $d(u, v) < k$, $C[u, j - d(u, v)] + w(u, v) < C[v, j]$, then $C[v, j] = C[u, j - d(u, v)] + w(u, v)$, $M[v, j] = u$, $j = d(u, v) + 1, \dots, k$.
 - If $u \neq v_s$, $d(u, v) \geq k$, then do nothing.

The pseudocode of the algorithm is shown in Algorithm 5.

The initialization process need $O(k|V|)$ time. BFS takes $O(|V| + |E|)$ time to visit each vertex. But when we visit each vertex, we compute up to k entries of C and k entries of M . So the total running time would be $O(k(|V| + |E|))$. The extra space needed is for storing C and M . They are $|V| \times k$ matrices, so the space need is $O(k|V|)$.

Algorithm 5 Minimum Cost within k delay.

Input: A directed graph $G = (V, E)$, each e in E has two parameters $w(e)$ and $d(e)$, integer k , two vertices v_s and v_e .

Output: A path from v_s to v_e with minimum cost and delay within k .

```
1: Let  $C$  be a  $|V| \times k$  matrix.
2: Let  $M$  be a  $|V| \times k$  matrix.
3: Let  $Q$  be an empty queue.
4: Let  $color$  be a vector with length  $|V|$ .
5: for  $j = 1$  to  $k$  do
6:    $C[v_s, j] = 0$ ;
7:    $M[v_s, j] = v_s$ ;
8: end for
9: for  $v \in V, v \neq v_s$  do
10:   $color[v] = white$ ;
11:  for  $j = 1$  to  $k$  do
12:     $C[v, j] = \infty$ ;
13:  end for
14: end for
15:  $color[v_s] = grey$ ;
16: for each  $v \in Adj[v_s]$  do
17:   $color[v] = grey$ ;
18:   $Enqueue(Q, v)$ ;
19:  if  $d(v_s, v) \leq k$  then
20:    for  $j = d(v_s, v), \dots, k$  do
21:       $C[v, j] = w(v_s, v)$ ;
22:       $M[v, j] = v_s$ ;
23:    end for
24:  end if
25: end for
26:  $color[v_s] = black$ ;
27: while  $Q \neq \emptyset$  do
28:   $u = Dequeue(Q)$ ;
29:  for each  $v \in Adj[u]$  do
30:    if  $color[v] = white$  then
31:       $color[v] = grey$ ;
32:       $Enqueue(Q, v)$ ;
33:    end if
34:    if  $d(u, v) < k$  then
35:      for  $j = d(u, v) + 1$  to  $k$  do
36:        if  $C[u, j - d(u, v)] + w(u, v) < C[v, j]$  then
37:           $C[v, j] = C[u, j - d(u, v)] + w(u, v)$ ;
38:           $M[v, j] = u$ ;
39:        end if
40:      end for
41:    end if
42:  end for
43:   $color[u] = black$ ;
44: end while
45:  $OutputPath(M)$ ;
```

```
1: function  $OUTPUTPATH(M)$ 
2:    $mincost = \min\{C[v_e, j], j = 1, \dots, k\}$ ;
3:   if  $mincost = \infty$  then
4:     return No such path!
5:   end if
6:   Let  $j$  be the index s.t.  $C[v_e, j] = mincost$ ;
7:    $u = v_e$ ;
8:   Let  $S$  be an empty stack.
9:   while  $u \neq v_s$  do
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10:     Push( $S, u$ );
11:      $j = j - d(u, v)$ ;
12:      $u = M[u, j]$ ;
13:   end while
14:   Push( $S, v_s$ );
15:   while  $S \neq \emptyset$  do
16:     Print  $Pop(S)$ ;
17:   end while
18: end function

```

4. (20 points) Let T be a rooted tree with n nodes and each node v associated with a weight $w(v)$. A subset of nodes S is an independent set of T if no node in S is the child or parent of another node in S . Design a dynamic programming algorithm to find an independent set of T with maximum weight, where the weight of an independent set is the total weight of its nodes. You should make your algorithm run as fast as possible.

ANS: Let (1): r be the root of T , (2): T_v denote the subtree rooted at v , (3): $N_T^1(v)$ denote the children of v in T and (4): $N_T^2(v)$ denote the descendants of v which is two edges away from v in T .

Observation 1 Given a maximum independent set S containing r , S can be partitioned into $\{S_v | v \in N_T^2(r)\}$ and each S_v is also a maximum independent set of T_v .

Observation 2 Given a maximum independent set S not containing r , S can be partitioned into $\{S_v | v \in N_T^1(r)\}$ and each S_v is also a maximum independent set of T_v .

From the above two observations, we immediately have the following recursive formula:

$$M(T_r) = \max \left\{ w(r) + \sum_{v \in N_T^2(r)} M(T_v), \sum_{v \in N_T^1(r)} M(T_v) \right\}$$

Next, how to complete the table M ? The following two pseudocodes are approaches to find the weight of a maximum independent set of T and a maximum independent set of T . First, let $l_T(v)$ be the level of v in T , we can recursively define $l_T(v)$ as follows:

1. for the root r of T , $l_T(r) = 1$ and
2. $\{l_T(v) = l_T(v) + 1 | v \in N_T^1(v)\}$.

Algorithm 6 Compute the Weight of a Maximum Independent Set of T

```

1:  $L := \max\{l_T(v) | v \in T\}$ 
2: for  $i = L$  to 1 do
3:   for each  $v$  with  $l_T(v) = i$  do
4:     if  $v$  is a leaf then
5:        $M(T_v) = 1$ .
6:     else
7:        $M(T_v) = \max \left\{ w(v) + \sum_{v' \in N_T^2(v)} M(T_{v'}), \sum_{v' \in N_T^1(v)} M(T_{v'}) \right\}$ .
8:     end if
9:   end for
10: end for

```

Because we have $O(n)$ rooted trees in this dynamic programming formula and each tree rooted at v takes $O(|N_T^1(v)| + |N_T^2(v)|)$ time to execute summations in the recursive formula. Also, we have $\sum_{v \in T} |N_T^1(v)| = O(n)$ and $\sum_{v \in T} |N_T^2(v)| = O(n)$. So, the total time complexity is

$$\sum_{v \in T} |N_T^1(v)| + |N_T^2(v)| = O(n).$$

Algorithm 7 FindMaxIndependentSet(T)

```
1: Let  $r$  be the root of  $T$  and  $X$  be a empty set.
2: if  $M(T_r) == w(r) + \sum_{v \in N_T^2(r)} M(T_v)$  then
3:    $X := X \cup \{r\}$ 
4:   for each  $v \in N_T^2(r)$  do
5:      $X := X \cup \text{FindMaxIndependentSet}(T_v)$ .
6:   end for
7: else
8:   for each  $v \in N_T^1(r)$  do
9:      $X := X \cup \text{FindMaxIndependentSet}(T_v)$ .
10:  end for
11: end if
    return  $X$ ;
```

5. (20 points) Let $A = a_1 \cdots a_m$ and $B = b_1 \cdots b_n$ be two strings with length m and n respectively. Design a dynamic programming based algorithm to convert A into B with minimum cost using the following rules. For a cost of 1, one can delete any letter from a string. For a cost of 2, one can insert a letter in any position. For a cost of 3, one can replace any letter by any other letter. For example, you can convert $A = abcabc$ to $B = abacab$ via the following sequence of operations: $abcabc$ with a cost of 3 can be converted to $abaabc$, which with a cost of 1 can be converted to $ababc$, which with a cost of 1 can be converted to $abac$, which with a cost of 2 can be converted to $abacb$, which with a cost of 2 can be converted to $abacab$. Thus the total cost for this conversion is 9 (may not be the cheapest one).

ANS: Let C be a $(m+1) \times (n+1)$ matrix recording the minimum cost of converting $A[1..i]$ to $B[1..j]$. Let M be a $(m+1) \times (n+1)$ matrix recording the last operation. Then

- If A is empty, then to convert A to B , at least we need to insert every element in B into A with cost $5 \times B.length$. And if we want to get the minimum cost, that is enough. So $C[0, j] = 5j$.
- If B is empty, at least we need to delete every element in A with cost $3 \times A.length$. And if we want to get the minimum cost, that is enough. So $C[i, 0] = 3i$.
- If $a_i = b_j$, all we need to do is to convert $A[1..i-1]$ to $B[1..j-1]$. So, $C[i, j] = C[i-1, j-1]$.
- If $a_i \neq b_j$, there are three choices:
 - (a) delete $A[i]$, convert $A[1..i-1]$ to $B[1..j]$ with total cost $C[i-1, j] + 3$;
 - (b) convert $A[1..i]$ to $B[1..j-1]$, then insert $B[j]$ with total cost $C[i, j-1] + 5$;
 - (c) convert $A[1..i-1]$ to $B[1..j-1]$, then replace $A[i]$ with $B[j]$ with total cost $C[i-1, j-1] + 7$.

We'll choose the one with minimum cost.

$$C[i, j] = \begin{cases} 5j, & \text{if } i = 0; \\ 3i, & \text{if } j = 0; \\ C[i-1, j-1], & \text{if } i > 0, j > 0, a_i = b_j; \\ \min\{C[i-1, j] + 3, C[i, j-1] + 5, C[i-1, j-1] + 7\}, & \text{if } i > 0, j > 0, a_i \neq b_j. \end{cases}$$

To compute $C[i, j]$ we need $C[i-1, j]$, $C[i, j-1]$ and $C[i-1, j-1]$. So the algorithm will compute C from left to right, form up to bottom.

To output the solution, use $(m+1) \times (n+1)$ matrix to record the last operation. If $A[i] = B[j]$, we do nothing in this step, so $M[i, j] = N$. In case of $A[i] \neq B[j]$, if the delete operation leads to the minimum cost, let $M[i, j] = D$; if the insert operation leads to the minimum cost, let $M[i, j] = I$; if the replace operation leads to the minimum cost, let $M[i, j] = R$. The pseudocode of the algorithm is show in Algorithm 8.

In the algorithm, we compute each entry of matrix C and M . It takes constant time to compute each entry. So the total running time would be $\Theta(mn)$.

Algorithm 8 Convert String.

Input: String $A = a_1 \cdots a_m$ and $B = b_1 \cdots b_n$.

Output: Steps of converting A into B with minimum cost.

```
1: Let  $C$  be a  $(m+1) \times (n+1)$  matrix.
2: Let  $M$  be a  $(m+1) \times (n+1)$  matrix.
3: for  $i = 0$  to  $m$  do
4:    $C[i, 0] = 3i$ ;
5: end for
6: for  $j = 0$  to  $n$  do
7:    $C[0, j] = 5j$ ;
8: end for
9: for  $i = 1$  to  $m$  do
10:  for  $j = 1$  to  $n$  do
11:    Update( $L, M, i, j$ );
12:  end for
13: end for
14: Output( $L, M$ );
```

```
1: function UPDATE( $L, M, i, j$ )
2:   if  $a_i = b_j$  then
3:      $C[i, j] = C[i-1, j-1]$ ;
4:      $M[i, j] = N$ ; ▷ No operation is made.
5:   else
6:     if  $C[i-1, j] + 3 = \min\{C[i-1, j] + 3, C[i-1, j-1] + 7, C[i, j-1] + 5\}$  then
7:        $C[i, j] = C[i-1, j] + 1$ ;
8:        $M[i, j] = D$ ; ▷ Delete.
9:     else if  $C[i-1, j-1] + 7 = \min\{C[i-1, j] + 3, C[i-1, j-1] + 7, C[i, j-1] + 5\}$  then
10:       $C[i, j] = C[i-1, j-1] + 7$ ;
11:       $M[i, j] = R$ ; ▷ Replace.
12:     else
13:        $C[i, j] = C[i, j-1] + 5$ ;
14:        $M[i, j] = I$ ; ▷ Insert.
15:     end if
16:   end if
17: end function
18: function OUTPUT( $L, M$ ) ▷ Print in reverse order.
19:    $i = m, j = n$ ;
20:   while  $j > 0$  do
21:     Switch( $M(i, j)$ ):
22:       Case N:  $i--; j--$ ; break;
23:       Case R:  $A[i] = b_j$ ; Print  $A$ ;  $i--; j--$ ; break;
24:       Case I:  $A = A[1..i]b_jA[i+1..A.length]$ ; Print  $A$ ;  $j--$ ; break;
25:       Case D:  $A = A[1..i-1]A[i+1..A.length]$ ; Print  $A$ ;  $i--$ ; break;
26:     end switch
27:   end while
28: end function
```