

Mahban Gholijafari

AMIRKABIR UNIVERSITY OF TECHNOLOGY (TEHRAN POLYTECHNIC) | ELECTRICAL ENGINEERING DEPARTMENT

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Summary

B.Sc. Electrical Engineering student at Amirkabir University of Technology, IRAN's Top-ranked University, with a 3.88 GPA. Passionate about Robotics. Worked as a researcher and IoT engineer, implementing multiple projects by MATLAB, having Electrical Circuits I and II courses teaching assistant experience for three semesters, and currently working on a Fuzzy-PID controller as a thesis project.

Research Interests: Machine Learning, Mathematics, Control, Robotics, Image Processing and Computer Vision, Digital Signal Processing

Education

B.Sc. Electrical Engineering

AMIRKABIR UNIVERSITY OF TECHNOLOGY (TEHRAN POLYTECHNIC)

- GPA: 3.88/4.0 (17.95/20)
- Field(s) of Study: Control Engineering
- Thesis: Construction and Control of a Three-Link Robot using a Fuzzy-PID Controller

Tehran, Iran

May 2018 - May 2022

High school Diploma in Mathematics and Physics

FARZANEGAN II (NATIONAL ORGANIZATION FOR DEVELOPMENT OF EXCEPTIONAL TALENT)

- GPA: 19.81/20

Tehran, Iran

July 2014 - July 2018

Teaching Experience

Teaching Assistant

AMIRKABIR UNIVERSITY

- Electric Circuits I, EE
- Lecturer: **Dr. M. Khosravi**
- Spring 2022 - Present

Teaching Assistant

AMIRKABIR UNIVERSITY

- Electric Circuits II, EE
- Lecturer: **Dr. M. Karrari**
- Fall 2021 - Present

Work & Volunteer Experience

IoT Engineer

TECNIKAN

- Smart Home
- Obtained skills: C(programming language), C++, MySQL, ATmelAVR, Linux
- Simple template of handsfree-drawer using stepper motor and ATmega16: **Github**

Tehran, Iran

May 2022 - October 2022

Member of the Innovation Center at Electrical Engineering Department

SCIENCE AND TECHNOLOGY PARK - AMIRKABIR UNIVERSITY OF TECHNOLOGY

- Executive team member

Tehran, Iran

April 2022 - Present

Member of Student Committee

ICRoM - K. N. TOOSI UNIVERSITY OF TECHNOLOGY

- Executive team member
- The 10th RSI international conference on robotics and mechatronics

Tehran, Iran

August 2022 - Present

Researcher (Internship)

AMIRKABIR UNIVERSITY OF TECHNOLOGY

- Tank gauging using fiber optic technology
- Fiber optic sensors have been around for more than thirty years and have been successfully implemented in different areas like strain monitoring, inertial navigation, chemical substance detecting, and underwater acoustic sensing. These sensors have many characteristic advantages such as their contact with explosive materials or in fire-hazardous environments, small size and weight, electrical insulation, electromagnetic interference resistance, and prompt response.

Tehran, Iran

July 2021 - September 2021

Skills

MATLAB Control System Toolbox, Signal Processing Toolbox, Simscape Multibody, App Designer, Fuzzy Logic Toolbox

C & C++ AVR Microcontroller, ARM Microcontroller, STM32CubeMX, Linux, Arduino, QT

Python Jupyter Notebooks, NumPy, TensorFlow, Matplotlib, Tkinter

Robotics Altium Designer, SOLIDWORKS, Code Vision AVR, PLC Ladder Logic, SIMATIC STEP 7, Proteus

Other Skills GitHub, Microsoft Office, \LaTeX , Basketball, Teamwork, Problem Solving

Selected Academic Projects

Construction and Control of a Three-Link Robot Using a Fuzzy-PID Controller

BACHELOR OF SCIENCE THESIS

July 2022 - Present

- Supervisor: **Dr. M. Shafiee**
- Implemented by **MATLAB & SOLIDWORKS**
- Requirements: forward kinematics analysis, inverse kinematics analysis, dynamic calculation, trajectory planning, and controller design.

Construction and Control of a RRR Robot Manipulator

INTRODUCTION TO ROBOTICS COURSE PROJECT

April 2022 - July 2022

- Lecturer: **Dr. I. Sharifi**
- Design of the controller with **MATLAB** and design of the robot with **SOLIDWORKS: GitHub**
- Aiming to design a different controller for the RS006L-A Kawasaki 3DOF robotic arm model using inverse kinematics analysis and dynamic.

Design a Fuzzy Logic Controller for a Rotary Flexible Joint Robotic Arm

INTRODUCTION TO COMPUTATIONAL INTELLIGENCE COURSE PROJECT

December 2021 - February 2022

- Lecturer: **Dr. I. Sharifi**
- Design a fuzzy logic controller with **MATLAB : GitHub**
- Designing a fuzzy logic feedback controller (FLC) in order to control a desired tip angle position of a rotary flexible joint robotic arm.

Deep Residual Learning for Image Recognition

INTRODUCTION TO COMPUTATIONAL INTELLIGENCE COURSE PROJECT

December 2021 - January 2022

- Lecturer: **Dr. H. Talebi**
- Image classification using **ResNet & Python: GitHub**

Computational Intelligence Laboratory Projects

INTRODUCTION TO COMPUTATIONAL INTELLIGENCE

December 2021 - February 2022

- Codes and reports: **GitHub**
- Topics: Neural network - Hopfield network - RBF - K-means algorithm - Fuzzy controller designing

Nonlinear Control of the Inverted Pendulum

MODERN CONTROL COURSE PROJECT

November 2021 - January 2022

- Lecturer: **Dr. H. Atrianfar**
- Study the controllability and observability, and then linearization of the system. Design of a controller and observer with **MATLAB: GitHub**

Honors & Rewards

Ranked 3rd among Control Bachelor's Students, by order of GPA

AMIRKABIR UNIVERSITY OF TECHNOLOGY (TEHRAN POLYTECHNIC)

July 2022

Ranked 576 among 144,000 students in National University Entrance Exam of Iran

NATIONAL ORGANIZATION FOR EDUCATIONAL TESTING

July 2018

1st place in Junior Soccer B-Light Weight Super Team

ROBO CUP IRAN OPEN

April 2015

Selected Licenses & Certifications

Machine Learning

STANFORD ONLINE

- Machine learning offered through Coursera using **MATLAB**
- Credential ID 2BZ6MYJRWKCU

Python Data Structures

UNIVERSITY OF MICHIGAN

- Offered through Coursera
- Credential ID HEUPGQBQZA6F

Robotics: Aerial Robotics

UNIVERSITY OF PENNSYLVANIA

- Offered through Coursera
- Credential ID A9MS269BRS9A

Supervised Machine Learning

DEEPLARNING.AI & STANFORD ONLINE

- Regression and classification offered through Coursera using **Python**
- Credential ID: DDNC3ZNW6M8E

Programming for Everybody

UNIVERSITY OF MICHIGAN

- Getting started with Python offered through Coursera
- Credential ID J8552RZL8LE4

Altium Designer

TEHRAN INSTITUTE OF TECHNOLOGY

- Credential ID 633797

Selected Academic Courses

Introduction to Robotics

- Grade: A+

Digital Signal Processing

- Grade: A+

Engineering Mathematics

- Grade: A+

Computer Programming

- Grade: A+

Computational Intelligence

- Grade: A+

Instrumentation

- Grade: A+

Linear Algebra

- Grade: A+

Engineering Economics

- Grade: A+

Language

TOEFL iBT Score: **108**, Reading: 25; Listening: 29; Speaking: 26; Writing: 28

References

Available per Request