

> Supplementary code for the proof of Lemma 1

> Consider a system of differential equations with the following right-hand sides

```
> eqs := [  
  -kn1 * X * T1 - kn2 * X * T2 + kf1 * D1 + kf2 * D2,  
  -kn1 * X * T1 + kf1 * D1 - kn1 * T1 * D2 + kf1 * Y,  
  -kn2 * X * T2 + kf2 * D2 - kn2 * T2 * D1 + kf2 * Y,  
  kn1 * X * T1 - kf1 * D1 - kn2 * T2 * D1 + kf2 * Y,  
  kn2 * X * T2 - kf2 * D2 - kn1 * T1 * D2 + kf1 * Y,  
  kn1 * T1 * D2 + kn2 * T2 * D1 - (kf1 + kf2) * Y  
];  
eqs := [-kn1 X T1 - kn2 X T2 + D1 kf1 + D2 kf2, -kn1 T1 D2 - kn1 X T1 + D1 kf1 + kf1 Y, (1)  
  -kn2 T2 D1 - kn2 X T2 + D2 kf2 + kf2 Y, -kn2 T2 D1 + kn1 X T1 - D1 kf1 + kf2 Y,  
  -kn1 T1 D2 + kn2 X T2 - D2 kf2 + kf1 Y, kn1 T1 D2 + kn2 T2 D1 - (kf1 + kf2) Y]
```

> where X, T1, T2, D1, D2, Y are the state variables and kn1, kn2, kf1, kf2 are scalar parameters. The goal is to obtain a couple of useful relations between the coordinates of the steady states and the parameters.

```
>  
with(Groebner) :  
  
gb := Basis(eqs, plex(T1, T2, X, Y, D1, D2, kn1, kn2, kf1, kf2)) :  
  
factor(gb[1]);  
      -(D1 kf1 + D2 kf2 + X kf1 + X kf2) (D1 D2 - XY) (2)
```

> If the left bracket vanishes, then, by the positivity of the parameters and nonnegativity of the steady state, $D1 = D2 = X = 0$, so the right bracket vanishes as well. Therefore, the right bracket vanishes in any case, and we can adjoin it to the list of equations.

Error, missing operator or `;`

```
>  
eqs := [op(eqs), X * Y - D1 * D2]:  
  
gb := Basis(eqs, plex(Y, T1, T2, X, D1, D2, kn1, kn2, kf1, kf2)) :  
  
factor(gb[1]);  
      -(-kn2 X T2 + D2 kf2) (D1 - D2) (3)
```

> If $D1 \neq D2$, we get an desired relation between T2, X, D2, and $kn2/kf2$. Otherwise, we add $D1 = D2$ to the system:

Error, missing operator or `;`

```
> eqs_ext := [op(eqs), D1 - D2]:  
gb := Basis(eqs_ext, plex(Y, T1, D1, T2, X, D2, kn1, kn2, kf1, kf2));  
factor(gb[1]);
```

$$\begin{aligned}
gb := [& D2 T2 X kn2 + T2 X^2 kn2 - D2^2 kf2 - D2 X kf2, D1 - D2, D2 T1 kf2 kn1 \\
& - D2 T2 kf1 kn2 - T2 X kf1 kn2 - T2 X kf2 kn2 + D2 kf1 kf2 + D2 kf2^2, kn1 X T1 + kn2 X T2 \\
& - D2 kf1 - D2 kf2, -D2 T2 kn2 - kn2 X T2 + D2 kf2 + kf2 Y, -kn1 T1 D2 + kn2 X T2 \\
& - D2 kf2 + kf1 Y, -D2^2 + XY] \\
& - (D2 + X) (-kn2 X T2 + D2 kf2)
\end{aligned} \tag{4}$$

> If the left bracket vanishes, $D2 = X = 0$,
so the right bracket vanishes as well
. Thus the right bracket vanishes in any case.
Now we can do the same for $T1$:

$$\begin{aligned}
> gb := Basis(eqs, plex(Y, T2, T1, X, D1, D2, kn1, kn2, kf1, kf2)) : \\
factor(gb[1]); \\
& - (-kn1 X T1 + D1 kf1) (D1 - D2)
\end{aligned} \tag{5}$$

$$\begin{aligned}
> gb := Basis(eqs_ext, plex(Y, T2, D2, T1, X, D1, kn1, kn2, kf1, kf2)) : \\
factor(gb[1]); \\
& - (D1 + X) (-kn1 X T1 + D1 kf1)
\end{aligned} \tag{6}$$

>