# PDF 13 to 16 Integral Formulas

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# Contents

1	PDF 13 5			
	1.1	Line Integral	5	
	1.2	Physical Aspect	5	
	1.3	Line Integral of a Vector Field	6	
2	PD	F 14	7	
	2.1	Gradient Theorem	7	
	2.2	Green's Theorem	8	
	2.3	Area Calculations	8	
3	PDF 15			
	3.1	Piecewise Parametrized Smooth Curve	9	
			9	
	3.2		10	
		3.2.1 Theorem	10	
	3.3	Vector Integral	10	
		3.3.1 special cases	10	
4	PD	F 16	13	
	4.1	Transforms	13	
	4.2		14	
	4.3	Surface Integrals of Vector Fields	14	
	4.4		15	
	4.5	Stokes Theorem	15	

4 CONTENTS

## **PDF 13**

## 1.1 Line Integral

For some scalar field  $f\colon U\to\mathbb{R}$  where U R n  $U\subseteq\mathbb{R}^n$ , the line integral along a piecewise smooth curve  $C\subset U$  is defined as:

$$\int_{C} f \, \mathrm{d}s = \int_{a}^{b} f(\vec{r}(t)) |r'(t)| \, \mathrm{d}t$$
(1.1)

where  $\vec{r}$ :  $[a, b] \to C$  is an arbitrary bijective parametrization of the curve C such that  $\vec{r}(a)$  and  $\vec{r}(b)$  give the endpoints of C and a < b.

## 1.2 Physical Aspect

$$m = \int_{C} \delta(x, y) \, \mathrm{d}s \tag{1.2}$$

$$(\bar{x}, \bar{y}) = \begin{cases} \bar{x} = \frac{1}{m} \int_{C} x \, \delta(x, y) \, ds \\ \bar{y} = \frac{1}{m} \int_{C} y \, \delta(x, y) \, ds \end{cases}$$
(1.3)

## 1.3 Line Integral of a Vector Field

For a vector field  $\mathbf{F} \colon U \subseteq \mathbf{R}^n \to \mathbf{R}^n$ , the line integral along a piecewise smooth curve  $C \subset U$ , in the direction of  $\vec{r}$ , is defined as:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$
(1.4)

where  $\cdot$  is the dot product, and  $\mathbf{r} \colon [a, b] \to C$  is a bijective parametrization of the curve C such that  $\mathbf{r}(a)$  and  $\mathbf{r}(b)$  give the endpoints of C.

Line integral of a vector field, also can be shown as below:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{C} \mathbf{p} \, dx + \mathbf{q} \, dy + \mathbf{r} \, dz$$
(1.5)

## **PDF 14**

#### 2.1 Gradient Theorem

The gradient theorem, also known as the fundamental theorem of calculus for line integrals, says that a line integral through a gradient field can be evaluated by evaluating the original scalar field at the endpoints of the curve. The theorem is a generalization of the second fundamental theorem of calculus to any curve in a plane or space (generally n-dimensional) rather than just the real line.

$$\mathbf{F} = \nabla f \Rightarrow \begin{cases} P = \frac{\partial f}{\partial x} \\ Q = \frac{\partial f}{\partial y} \\ R = \frac{\partial f}{\partial z} \end{cases}$$
 (2.1)

For  $\mathbf{F} \colon U \subseteq \mathbf{R}^n \to \mathbf{R}$  as a differentiable function and any continuous curve in U which starts at a point a and ends at a point b, then

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{a}^{b} \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$
(2.2)

where  $\nabla f$  denotes the gradient vector field of **F**.

To check if a vector is a gradient vector:

$$\frac{\partial p}{\partial y} = \frac{\partial q}{\partial x} \qquad \frac{\partial p}{\partial z} = \frac{\partial r}{\partial x} \qquad \frac{\partial q}{\partial z} = \frac{\partial r}{\partial y}$$
 (2.3)

#### 2.2 Green's Theorem

Let C be a positively oriented, piecewise smooth, simple closed curve in a plane, and let D be the region bounded by C. If P and Q are functions of (x,y) defined on an open region containing D and have continuous partial derivatives there, then

$$\oint_C P \, \mathrm{d}x + Q \, \mathrm{d}y = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathrm{d}A \tag{2.4}$$

where the path of integration along C is anticlockwise.

If curve C is divided into pieces like  $C = C_1 \bigcup C_2$ , then

$$\int_{C} P \, dx + Q \, dy = \int_{C_{1}} P \, dx + Q \, dy + \int_{C_{2}} P \, dx + Q \, dy$$

$$= \iint_{D} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$
(2.5)

### 2.3 Area Calculations

$$A = \oint_C x \, \mathrm{d}y = -\oint_C y \, \mathrm{d}x = \frac{1}{2} \oint_C x \, \mathrm{d}y - y \, \mathrm{d}x \tag{2.6}$$

## **PDF** 15

### 3.1 Piecewise Parametrized Smooth Curve

$$\vec{r}(u,v) = (x(u,v), y(u,v), z(u,v)), \quad (u,v) \in R$$
 (3.1)

$$\vec{r}_u = (\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u}) \qquad \vec{r}_v = (\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v})$$
 (3.2)

### **3.1.1** Sample

Let z = f(x, y), the smooth parametrized curve will be:

$$\vec{r}(u,v) = (u,v,f(u,v))$$
 (3.3)

Partial Derivatives will be:

$$\vec{r}_{u} = \left(\frac{\partial u}{\partial u}, \frac{\partial v}{\partial u}, \frac{\partial f(u, v)}{\partial u}\right)$$

$$= (1, 0, \frac{\partial f}{\partial u}) = \vec{i} + \frac{\partial f}{\partial u} \vec{k}$$
(3.4)

$$\vec{r}_v = \left(\frac{\partial u}{\partial v}, \frac{\partial v}{\partial v}, \frac{\partial f(u, v)}{\partial v}\right) = (0, 1, \frac{\partial f}{\partial v}) = \vec{j} + \frac{\partial f}{\partial v} \vec{k}$$
(3.5)

Cross Product of the partial derivatives:

$$\vec{r}_{u} \times \vec{r}_{v} = \left(\frac{-\partial f}{\partial u}, \frac{-\partial f}{\partial v}, 1\right)$$

$$= \frac{-\partial f}{\partial u}\vec{i} + \left(\frac{-\partial f}{\partial v}\vec{j}\right) + \vec{k} \neq 0$$
(3.6)

#### 3.2 Area

$$A(S) = \iint_{R} |\vec{r}_{u} \times \vec{r}_{v}| \, dA$$
(3.7)

#### 3.2.1 Theorem

Let z = f(x, y), then:

$$A(S) = \iint\limits_{R} \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2 + 1} \ dA$$
 (3.8)

### 3.3 Vector Integral

$$\iint_{S} G(x, y, z) d\sigma = \iint_{R} G(\vec{r}(u, v)) |\vec{r}_{u} \times \vec{r}_{v}| dA \quad \vec{r}(u, v) \in R$$
 (3.9)

### 3.3.1 special cases

1

Let  $S : \vec{r}(u, v) = (f(u, v), g(u, v), h(u, v))$ , then:

$$\iint_{S} G(x, y, z) d\sigma = \iint_{S} G(f(u, v), g(u, v), h(u, v)) |\vec{r}_{u} \times \vec{r}_{v}| dA \quad (3.10)$$

2

Let z = f(x, y), then:

$$\iint_{S} G(x, y, z) d\sigma = \iint_{S} G(x, y, f(x, y)) \sqrt{\left(\frac{\partial f}{\partial x}\right)^{2} + \left(\frac{\partial f}{\partial y}\right)^{2} + 1} dxdy (3.11)$$

#### Solved Exercise (use as a template)

Let 
$$z = \sqrt{x^2 + y^2}$$
;  $(0 \le z \le 1)$ , then  $\iint_S x^2 d\sigma = ?$   
Solution:  
$$\int_{y=r}^{x} \frac{1}{\sin \theta} = \int_{y=r}^{x} \frac{1}{\sin \theta} = \int_{y=r}^{y=r} \frac{1}{\sin \theta} = \int$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \Rightarrow \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} (0 \le r \le 1); (0 \le \theta \le 2\pi)$$

$$\vec{r}(r, \theta) = (r \cos \theta, r \sin \theta, r)$$

$$\vec{r}(r) = (\cos \theta, \sin \theta, r)$$

$$\vec{r}(r) = (\cos \theta, \sin \theta, r)$$

$$\vec{r}(r) = (-r \sin \theta, r \cos \theta, 0)$$

$$\vec{r}(r) = (-r \sin \theta, r \cos \theta, 0)$$

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$$\vec{r}(r) = (-r \cos \theta, -r \sin \theta, r)$$

$$\vec{r}(r) = (-r \cos \theta, -r \sin \theta, r)$$

$$\vec{r}(r) = (-r \cos \theta, -r \sin$$

# **PDF** 16

### 4.1 Transforms

#### Del (nabla)

Symbol:

$$\nabla$$
 (4.1)

Definition:

$$\nabla f := \frac{\partial f}{\partial x}\vec{i} + \frac{\partial f}{\partial y}\vec{j} + \frac{\partial f}{\partial z}\vec{k} \tag{4.2}$$

$$\nabla := \frac{\partial}{\partial x}\vec{i} + \frac{\partial}{\partial y}\vec{j} + \frac{\partial}{\partial z}\vec{k}$$
 (4.3)

#### Divergence

Symbol:

$$div (4.4)$$

Definition:

Let **F** be  $\mathbf{F}(x,y,z) = P(x,y,z)\vec{i} + Q(x,y,z)\vec{j} + R(x,y,z)\vec{k}$ , then:

$$\operatorname{div} \mathbf{F} := \frac{\partial P}{\partial x} \vec{i} + \frac{\partial Q}{\partial y} \vec{j} + \frac{\partial R}{\partial z} \vec{k}$$
(4.5)

$$\operatorname{div} \mathbf{F} := \nabla \cdot \mathbf{F} \tag{4.6}$$

curl

Symbol:

$$curl (4.7)$$

Definition:

Let **F** be  $\mathbf{F}(x,y,z) = P(x,y,z)\vec{i} + Q(x,y,z)\vec{j} + R(x,y,z)\vec{k}$ , then:

$$\operatorname{curl} \mathbf{F} := \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)\vec{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}\right)\vec{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\vec{k}$$
(4.8)

$$\operatorname{curl} \mathbf{F} \coloneqq \nabla \cdot \mathbf{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$
 (4.9)

## 4.2 Theorems

- 1.  $\operatorname{curl}(\nabla f) = 0$
- 2.  $\operatorname{div}(\operatorname{curl} \mathbf{F}) = 0$
- 3. (a) Let  $\lambda \in \mathbb{R}$ , then:  $\nabla(f + \lambda g) = \nabla f + \lambda \nabla g$ 
  - (b)  $\operatorname{curl}(\mathbf{F} + \lambda \mathbf{G}) = \operatorname{curl} \mathbf{F} + \lambda \operatorname{curl} \mathbf{G}$
  - (c)  $\operatorname{div}(\mathbf{F} + \lambda \mathbf{G}) = \operatorname{div} \mathbf{F} + \lambda \operatorname{div} \mathbf{G}$
- 4.  $\operatorname{div}(\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot \operatorname{curl} \mathbf{F} \mathbf{F} \cdot \operatorname{curl} \mathbf{G}$
- 5.  $\operatorname{div}(f\mathbf{F}) = f \operatorname{div}\mathbf{F} + \mathbf{F} \cdot \nabla f$
- 6.  $\operatorname{curl}(f\mathbf{F}) = f \operatorname{curl} \mathbf{F} + \nabla f \times \mathbf{F}$

## 4.3 Surface Integrals of Vector Fields

$$\iint_{S} \mathbf{F} \cdot \vec{n} \, d\sigma \tag{4.10}$$

#### 4.4. DIVERGENCE THEOREM

$$\iint_{S} \mathbf{F} \cdot \vec{n} \, d\sigma = \iint_{S} \mathbf{F} \cdot \frac{\vec{r}_{u} \times \vec{r}_{v}}{|\vec{r}_{u} \times \vec{r}_{v}|} \, d\sigma$$
$$= \iint_{D} \left[ \mathbf{F} \cdot \frac{\vec{r}_{u} \times \vec{r}_{v}}{|\vec{r}_{u} \times \vec{r}_{v}|} \right] |\vec{r}_{u} \times \vec{r}_{v}| \, dA$$

 $= \iint \mathbf{F} \cdot (\vec{r}_u \times \vec{r}_v) \, dA$ 

$$\Rightarrow \iint_{\mathcal{C}} \mathbf{F} \cdot \vec{n} \, d\sigma = \iint_{\mathcal{D}} \mathbf{F} \cdot (\vec{r}_u \times \vec{r}_v) \, dA$$
 (4.11)

15

Let  $z = g(x, y); (x, y) \in R$  and  $\mathbf{F} = (P, Q, R)$ , then:

$$\iint_{S} \mathbf{F} \cdot \vec{n} \, d\sigma = \iint_{R} \left( -P \frac{\partial g}{\partial x} - Q \frac{\partial g}{\partial y} + R \right) \, dA \tag{4.12}$$

## 4.4 Divergence Theorem

$$\iint_{S} \mathbf{F} \cdot \vec{n} \, d\sigma = \iiint_{R} \operatorname{div} \mathbf{F} \, dV \tag{4.13}$$

## 4.5 Stokes Theorem

$$\int_{\partial G} \mathbf{F} \cdot d\vec{r} = \iint_{G} (\operatorname{curl} \mathbf{F}) \cdot \vec{n} \, d\sigma \tag{4.14}$$