1 DP

1.1 DSU on Tree

```
vector<int> *pvec[MAX];
vector<int> G[MAX];
int sz[MAX],color[MAX],color_counter[MAX];
pair<ll,int> Info[MAX];
int Subtree(int u,int p=-1)
{
    sz[u]=1;
    int i;
    for(i=0; i<G[u].size(); i++)
    {
        if(G[u][i]==p) continue;
        sz[u]=sz[u]+sz(G[u][i],u);
    }
    return sz[u];
}
pair<ll,int>dfs(int u,int p=-1,bool keep=false)
{
    int i,j,k,child,hchild=-1;
    for(i=0; i<G[u].size(); i++)
    {
        if(G[u][i]==p) continue;
        if(hchild==-1||sz[hchild]<sz[G[u][i]])
        {
            hchild=G[u][i];
        }
    }
    for(i=0; i<G[u].size(); i++)
    {
        if(G[u][i]==p||G[u][i]==hchild) continue;
        dfs(G[u][i],u,false);
    }
    if(hchild!=-1)
    {
        Info[u]=dfs(hchild,u,true);
        pvec[u]=pvec[hchild];
    }
    else
    {
        pvec[u]=new vector<int> ();
    }
    pvec[u]->push_back(u);
    color_counter[color[u]]++;
    if(color_counter[color[u]]>Info[u].second)
    {
        Info[u].second=color_counter[color[u]];
        Info[u].first=color[u];
    }
    else if(color_counter[color[u]]==Info[u].second)
    {
        Info[u].first=Info[u].first+color[u];
    }
    for(i=0; i<G[u].size(); i++)
    {
        if(G[u][i]==p||G[u][i]==hchild) continue;
        child=G[u][i];
        for(j=0; j<(*pvec[child]).size(); j++)
        {
            k=(*pvec[child])[j];
            pvec[u]->push_back(k);
            color_counter[color[k]]++;
            if(color_counter[color[k]]>Info[u].second)
            {
                Info[u].second=color_counter[color[k]];
                Info[u].first=color[k];
            }
            else
                if(color_counter[color[k]]==Info[u].second)
            {
                Info[u].first=Info[u].first+color[k];
            }
        }
    }
    if(!keep)
    {
        for(j=0; j<(*pvec[u]).size(); j++)
        {
            k=(*pvec[u])[j];
            color_counter[color[k]]--;
        }
    }
    return Info[u];
}
```

1.2 Divide and Conquer Optimization

```
int m, n;
vector<long long> dp_before(n), dp_cur(n);
long long C(int i, int j);
// compute dp_cur[l], ... dp_cur[r] (inclusive)
void compute(int l, int r, int optl, int optr) {
    if (l > r)
        return;
    int mid = (l + r) >> 1;
    pair<long long, int> best = {LLONG_MAX, -1};
    for (int k = optl; k <= min(mid, optr); k++) {
    best = min(best, {(k ? dp_before[k - 1] : 0) +
        C(k, mid), k});
    }
    dp_cur[mid] = best.first;
    int opt = best.second;
    compute(l, mid - 1, optl, opt);
    compute(mid + 1, r, opt, optr);
}   int solve() {
    for (int i = 0; i < n; i++)
        dp_before[i] = C(0, i);
    for (int i = 1; i < m; i++) {
        compute(0, n - 1, 0, n - 1);
        dp_before = dp_cur;
    }
    return dp_before[n - 1];
}
```

1.3 Li Chao Tree

```
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 200005
#define MOD 1000000007
#define INF 10000000000
#define EPS 0.0000000001
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
class LiChaoTree
{
    long long L,R;
    bool minimize;
    int lines;
    struct Node
    {
        complex<long long> line;
        Node *children[2];
        Node(complex<long long> ln=
            {0,1000000000000000000})
        {
            line=ln;
            children[0]=0;
            children[1]=0;
        }
    } *root;
    long long dot(complex<long long> a,
        complex<long long> b)
    {
        return (conj(a) * b).real();
    }
    long long f(complex<long long> a, long long x)
    {
        return dot(a, {x, 1});
    }
    void clear(Node* &node)
    {
        if(node->children[0])
        {
            clear(node->children[0]);
        }
        if(node->children[1])
        {
            clear(node->children[1]);
        }
        delete node;
    }
    void add_line(complex<long long> nw, Node*
        &node, long long l, long long r)
    {
        if(node==0)
        {
            node=new Node(nw);
            return;
        }
        long long m = (l + r) / 2;
        bool lef = (f(nw, l) < f(node->line,
            l)&&minimize)||((!minimize)&&f(nw, l) >
            f(node->line, l));
        bool mid = (f(nw, m) < f(node->line,
            m)&&minimize)||((!minimize)&&f(nw, m) >
            f(node->line, m));
        if(mid)
        {
            swap(node->line, nw);
        }
        if(r - l == 1)
        {
            return;
```

```
        }
        else if(lef != mid)
        {
            add_line(nw, node->children[0], l, m);
        }
        else
        {
            add_line(nw, node->children[1], m, r);
        }
    }
    long long get(long long x, Node* &node, long
        long l, long long r)
    {
        long long m = (l + r) / 2;
        if(r - l == 1)
        {
            return f(node->line, x);
        }
        else if(x < m)
        {
            if(node->children[0]==0) return
                f(node->line, x);
            if(minimize) return min(f(node->line,
                x), get(x, node->children[0], l, m));
            else return max(f(node->line, x), get(x,
                node->children[0], l, m));
        }
        else
        {
            if(node->children[1]==0) return
                f(node->line, x);
            if(minimize) return min(f(node->line,
                x), get(x, node->children[1], m, r));
            else return max(f(node->line, x), get(x,
                node->children[1], m, r));
        }
    }
public:
    LiChaoTree(long long l=-1000000001,long long
        r=1000000001,bool mn=false)
    {
        L=l;
        R=r;
        root=0;
        minimize=mn;
        lines=0;
    }
    void AddLine(pair<long long,long long> ln)
    {
        add_line({ln.first,ln.second},root,L,R);
        lines++;
    }
    int number_of_lines()
    {
        return lines;
    }
    long long getOptimumValue(long long x)
    {
        return get(x,root,L,R);
    }
    ~LiChaoTree()
    {
        if(root!=0) clear(root);
    }
};
int main()
{
    return 0;
}
```

2 DS

2.1 BIT 2D

```
void update(int x, int y, int val) {
  int y1;
  while (x <= max_x) {
    y1 = y;
    while (y1 <= max_y) {
      tree[x][y1] += val;
      y1 += (y1 & -y1);
    }
    x += (x & -x);
  }
}
```

2.2 CD-anikda

```
// p[u] = parent of u in centroid tree
// d[x][u] = distance from u to a parent of u at
    level x of centroid tree
//          if u is in subtree of centroid c, then
    d[lvl[c]][u] = dist(c, l)
// Taken from Rezwan Arefin
// If (x, y) edge exist, then x must be in adj[y]
    and y must be in adj[x]
const int maxn = 1e5 + 10;
vector<int> adj[maxn];
int lvl[maxn], sub[maxn], p[maxn], vis[maxn],
    d[18][maxn], ans[maxn];

void calc(int u, int par) { sub[u] = 1;
        for(int v : adj[u]) if(v - par && !vis[v])
                calc(v, u), sub[u] += sub[v];
}
int centroid(int u, int par, int r) {
        for(int v : adj[u]) if(v - par && !vis[v])
                if(sub[v] > r) return centroid(v, u,
                    r);
        return u;
}
void dfs(int l, int u, int par) {
        if(par + 1) d[l][u] = d[l][par] + 1;
        for(int v : adj[u]) if(v - par && !vis[v])
                dfs(l, v, u);
}
void decompose(int u, int par) {
        calc(u, -1);
        int c = centroid(u, -1, sub[u] >> 1);
        vis[c] = 1, p[c] = par, lvl[c] = 0;
        if(par + 1) lvl[c] = lvl[par] + 1;
        dfs(lvl[c], c, -1);
        for(int v : adj[c]) if(v - par && !vis[v])
                decompose(v, c);
}

void update(int u) {
        for(int v = u; v + 1; v = p[v])
                ans[v] = min(ans[v], d[lvl[v]][u]);
}
int query(int u) {
        int ret = 1e9;
        for(int v = u; v + 1; v = p[v])
                ret = min(ret, ans[v] +
                    d[lvl[v]][u]);
        return ret;
}
```

2.3 HLD-Usaco

```
#include "bits/stdc++.h"
using namespace std;

const int N = 2e5+5;
const int D = 19;
const int S = (1<<D);

int n, q, v[N];
vector<int> adj[N];

int sz[N], p[N], dep[N];
int st[S], id[N], tp[N];

void update(int idx, int val) {
        st[idx += n] = val;
        for (idx /= 2; idx; idx /= 2)
                st[idx] = max(st[2 * idx], st[2 *
                    idx + 1]);
}

int query(int lo, int hi) {
        int ra = 0, rb = 0;
        for (lo += n, hi += n + 1; lo < hi; lo /=
            2, hi /= 2) {
                if (lo & 1)
                        ra = max(ra, st[lo++]);
                if (hi & 1)
                        rb = max(rb, st[--hi]);
        }
        return max(ra, rb);
}

int dfs_sz(int cur, int par) {
        sz[cur] = 1;
        p[cur] = par;
        for(int chi : adj[cur]) {
                if(chi == par) continue;
                dep[chi] = dep[cur] + 1;
                p[chi] = cur;
                sz[cur] += dfs_sz(chi, cur);
        }
        return sz[cur];
}

int ct = 1;

void dfs_hld(int cur, int par, int top) {
        id[cur] = ct++;
        tp[cur] = top;
        update(id[cur], v[cur]);
        int h_chi = -1, h_sz = -1;
        for(int chi : adj[cur]) {
                if(chi == par) continue;
                if(sz[chi] > h_sz) {
```

```
                    h_sz = sz[chi];
                    h_chi = chi;
                }
        }
        if(h_chi == -1) return;
        dfs_hld(h_chi, cur, top);
        for(int chi : adj[cur]) {
                if(chi == par || chi == h_chi)
                    continue;
                dfs_hld(chi, cur, chi);
        }
}

int path(int x, int y){
        int ret = 0;
        while(tp[x] != tp[y]){
                if(dep[tp[x]] < dep[tp[y]])swap(x,y);
                ret = max(ret,
                    query(id[tp[x]],id[x]));
                x = p[tp[x]];
        }
        if(dep[x] > dep[y])swap(x,y);
        ret = max(ret, query(id[x],id[y]));
        return ret;
}
dfs_sz(1, 1);dfs_hld(1, 1, 1);
```

2.4 HLD-anikda

```
LazySegmentTree Tree ;
int sz[MAX];
int in[MAX];
int rin[MAX];
int out[MAX];
int head[MAX];
int par[MAX];
vector<int>g[MAX];
void dfs_sz(int u,int p) {
    sz[u] = 1;
    par[u] = p;
    for(auto &v: g[u]) {
        if(v==p)continue;
        dfs_sz(v,u);
        sz[u] += sz[v];
        if(sz[v] > sz[g[u][0]])
            swap(v,g[u][0]);
    }
}
int t;
void dfs_hld(int u,int p) {
    in[u] = ++t;
    rin[in[u]] = u;
    for(auto v: g[u]) {
        if(v==p)continue;
        head[v] = (v == g[u][0] ? head[u] : v);
        dfs_hld(v,u);
    }
    out[u] = t;
}
bool isParent(int p,int u){
    return in[p]<=in[u]&&out[u]<=out[p];
}
int n ;
int pathQuery(int u,int v){
    int ret = -inf;
    while(true){
        if(isParent(head[u],v))break;
        ret=max(ret,Tree.queryRange(1,1,n,in[head[u]],in[u]));
        u=par[head[u]];
    }
    swap(u,v);
    while(true){
        if(isParent(head[u],v))break;
        ret=max(ret,Tree.queryRange(1,1,n,in[head[u]],in[u]));
        u=par[head[u]];
    }
    if(in[v]<in[u])swap(u,v);
    ret =
        max(ret,Tree.queryRange(1,1,n,in[u],in[v]));
    return ret;
}
void updateSubTree(int u,int val){
    Tree.updateRange(1,1,n,in[u],out[u],val);
}
void buildHLD(int root){
    dfs_sz(root,root);
    head[root]=root;
    dfs_hld(root,root);
}
// call buildHLD
```

2.5 Implicit Treap

```
#include<bits/stdc++.h>
#include<math.h>
#include<vector>
#include<stdlib.h>
using namespace std;
#define MAX 200005
#define MOD 998244353
#define NINF -1000000000000000000
template <class T>
class implicit_treap
{
    struct item
    {
        int prior, cnt;
        T value;
        bool rev;
        item *l,*r;
        item(T v)
        {
            value=v;
            rev=false;
            l=NULL;
            r=NULL;
            cnt=1;
            prior=rand();
        }
    } *root,*node;
    int cnt (item * it)
    {
        return it ? it->cnt : 0;
    }

    void upd_cnt (item * it)
    {
        if (it)
            it->cnt = cnt(it->l) + cnt(it->r) + 1;
    }

    void push (item * it)
    {
        if (it && it->rev)
        {
            it->rev = false;
            swap (it->l, it->r);
            if (it->l) it->l->rev ^= true;
            if (it->r) it->r->rev ^= true;
        }
    }

    void merge (item * & t, item * l, item * r)
    {
        push (l);
        push (r);
        if (!l || !r)
            t = l ? l : r;
        else if (l->prior > r->prior)
            merge (l->r, l->r, r), t = l;
        else
            merge (r->l, l, r->l), t = r;
        upd_cnt (t);
    }

    void split (item * t, item * & l, item * & r,
        int key, int add = 0)
    {
        if (!t)
            return void( l = r = 0 );
        push (t);
        int cur_key = add + cnt(t->l);
        if (key <= cur_key)
            split (t->l, l, t->l, key, add), r = t;
        else
            split (t->r, t->r, r, key, add + 1 +
                cnt(t->l)), l = t;
        upd_cnt (t);
    }
    void insert(item * &t,item * element,int key)
    {
        item *l,*r;
        split(t,l,r,key);
        merge(l,l,element);
        merge(t,l,r);
        l=NULL;
        r=NULL;
    }
    T elementAt(item * &t,int key)
    {
        push(t);
        T ans;
        if(cnt(t->l)==key) ans=t->value;
        else if(cnt(t->l)>key)
            ans=elementAt(t->l,key);
        else ans=elementAt(t->r,key-1-cnt(t->l));
        return ans;
    }
    void erase (item * & t, int key)
    {
        push(t);
        if(!t) return;
```

```
        if (key == cnt(t->l))
            merge (t, t->l, t->r);
        else if(key<cnt(t->l))
            erase(t->l,key);
        else
            erase(t->r,key-cnt(t->l)-1);
        upd_cnt(t);
    }
    void reverse (item * &t, int l, int r)
    {
        item *t1, *t2, *t3;
        split (t, t1, t2, l);
        split (t2, t2, t3, r-l+1);
        t2->rev ^= true;
        merge (t, t1, t2);
        merge (t, t, t3);
    }
    void cyclic_shift(item * &t,int L,int R)
    {
        if(L==R) return;
        item *l,*r,*m;
        split(t,t,l,L);
        split(l,l,m,R-L+1);
        split(l,l,r,R-L);
        merge(t,t,r);
        merge(t,t,l);
        merge(t,t,m);
        l=NULL;
        r=NULL;
        m=NULL;
    }
    void output (item * t,vector<T> &arr)
    {
        if (!t) return;
        push (t);
        output (t->l,arr);
        arr.push_back(t->value);
        output (t->r,arr);
    }
public:
    implicit_treap()
    {
        root=NULL;
    }
    void insert(T value,int position)
    {
        node=new item(value);
        insert(root,node,position);
    }
    void erase(int position)
    {
        erase(root,position);
    }
    void reverse(int l,int r)
    {
        reverse(root,l,r);
    }
    T elementAt(int position)
    {
        return elementAt(root,position);
    }
    void cyclic_shift(int L,int R)
    {
        cyclic_shift(root,L,R);
    }
    int size()
    {
        return cnt(root);
    }
    void output(vector<T> &arr)
    {
        output(root,arr);
    }
};
```

2.6 Mo Algorithm

```
#include<bits/stdc++.h>
using namespace std;
#define MOD 998244353
#define MAX 200005
#define MAX_BIT 50
#define PRECISION 0.00000000001
#define INF 2000000000
void remove(int idx); // TODO: remove value at idx
    from data structure
void add(int idx);   // TODO: add value at idx from
    data structure
int get_answer(); // TODO: extract the current
    answer of the data structure
int block_size;
struct Query {
    int l, r,k, idx;
    bool operator<(Query other) const
    {
        if(l/block_size!=other.l/block_size) return
            (l<other.l);
        return (l/block_size&1)? (r<other.r) :
            (r>other.r);
    }
};
vector<int> mo_s_algorithm(vector<Query> queries) {
    vector<int> answers(queries.size());
    sort(queries.begin(), queries.end());

    // TODO: initialize data structure

    int cur_l = 0;
    int cur_r = -1;
    // invariant: data structure will always
        reflect the range [cur_l, cur_r]
    for (Query q : queries) {
        while (cur_l > q.l) {
            cur_l--;
            add(cur_l);
        }
        while (cur_r < q.r) {
            cur_r++;
            add(cur_r);
        }
        while (cur_l < q.l) {
            remove(cur_l);
            cur_l++;
        }
        while (cur_r > q.r) {
            remove(cur_r);
            cur_r--;
        }
        answers[q.idx] = get_answer();
    }
    return answers;
}

int main()
{
    return 0;
}
```

2.7 Treap

```
#include<bits/stdc++.h>
#include<math.h>
#include<vector>
#include<stdlib.h>
using namespace std;
#define MAX 400005
#define MOD 998244353
#define INF 2000000000
template <class T>
class treap
{
    struct item
    {
        int prior, cnt;
        T key;
        item *l,*r;
        item(T v)
        {
            key=v;
            l=NULL;
            r=NULL;
            cnt=1;
            prior=rand();
        }
    } *root,*node;
    int cnt (item * it)
    {
        return it ? it->cnt : 0;
    }

    void upd_cnt (item * it)
    {
        if (it)
            it->cnt = cnt(it->l) + cnt(it->r) + 1;
    }

    void split (item * t, T key, item * & l, item *
        & r)
    {
        if (!t)
            l = r = NULL;
        else if (key < t->key)
            split (t->l, key, l, t->l), r = t;
        else
            split (t->r, key, t->r, r), l = t;
        upd_cnt(t);
    }

    void insert (item * & t, item * it)
    {
        if (!t)
            t = it;
        else if (it->prior > t->prior)
```

```
        split (t, it->key, it->l, it->r), t = it;
    else
        insert (it->key < t->key ? t->l : t->r,
            it);
    upd_cnt(t);
}

void merge (item * & t, item * l, item * r)
{
    if (!l || !r)
        t = l ? l : r;
    else if (l->prior > r->prior)
        merge (l->r, l->r, r), t = l;
    else
        merge (r->l, l, r->l), t = r;
    upd_cnt(t);
}

void erase (item * & t, T key)
{
    if (t->key == key)
        merge (t, t->l, t->r);
    else
        erase (key < t->key ? t->l : t->r, key);
    upd_cnt(t);
}

T elementAt(item * &t,int key)
{
    T ans;
    if(cnt(t->l)==key) ans=t->key;
    else if(cnt(t->l)>key)
        ans=elementAt(t->l,key);
    else ans=elementAt(t->r,key-1-cnt(t->l));
    upd_cnt(t);
    return ans;
}

item * unite (item * l, item * r)
{
    if (!l || !r) return l ? l : r;
    if (l->prior < r->prior) swap (l, r);
    item * lt, * rt;
    split (r, l->key, lt, rt);
    l->l = unite (l->l, lt);
    l->r = unite (l->r, rt);
    upd_cnt(l);
    upd_cnt(r);
    return l;
}
void heapify (item * t)
{
    if (!t) return;
    item * max = t;
    if (t->l != NULL && t->l->prior >
        max->prior)
        max = t->l;
    if (t->r != NULL && t->r->prior >
        max->prior)
        max = t->r;
    if (max != t)
    {
        swap (t->prior, max->prior);
        heapify (max);
    }
}

item * build (T * a, int n)
{
    if (n == 0) return NULL;
    int mid = n / 2;
    item * t = new item (a[mid], rand ());
    t->l = build (a, mid);
    t->r = build (a + mid + 1, n - mid - 1);
    heapify (t);
    return t;
}
void output (item * t,vector<T> &arr)
{
    if (!t) return;
    output (t->l,arr);
    arr.push_back(t->key);
    output (t->r,arr);
}
public:
treap()
{
    root=NULL;
}
treap(T *a,int n)
{
    build(a,n);
}
void insert(T value)
{
    node=new item(value);
    insert(root,node);
}
void erase(T value)
{
    erase(root,value);
}
T elementAt(int position)
{
    return elementAt(root,position);
}
int size()
{
    return cnt(root);
}
void output(vector<T> &arr)
{
    output(root,arr);
}
int range_query(T l,T r) //(l,r]
{
    item *previous,*next,*current;
    split(root,l,previous,current);
    split(current,r,current,next);
    int ans=cnt(current);
    merge(root,previous,current);
    merge(root,root,next);
    previous=NULL;
    current=NULL;
    next=NULL;
    return ans;
}
};
```

3 Flow

3.1 Dinic's Algorithm

```
#include<bits/stdc++.h>
#include<vector>
using namespace std;
#define MAX 100
#define HUGE_FLOW 1000000000
#define BEGIN 1
#define DEFAULT_LEVEL 0
struct FlowEdge {
    int v, u;
    long long cap, flow = 0;
    FlowEdge(int v, int u, long long cap) : v(v),
        u(u), cap(cap) {}
};

struct Dinic {
    const long long flow_inf = 1e18;
    vector<FlowEdge> edges;
    vector<vector<int>> adj;
    int n, m = 0;
    int s, t;
    vector<int> level, ptr;
    queue<int> q;

    Dinic(int n, int s, int t) : n(n), s(s), t(t) {
        adj.resize(n);
        level.resize(n);
        ptr.resize(n);
    }

    void add_edge(int v, int u, long long cap) {
        edges.emplace_back(v, u, cap);
        edges.emplace_back(u, v, 0);
        adj[v].push_back(m);
        adj[u].push_back(m + 1);
        m += 2;
    }

    bool bfs() {
        while (!q.empty()) {
            int v = q.front();
            q.pop();
            for (int id : adj[v]) {
                if (edges[id].cap - edges[id].flow <
                    1)
                    continue;
                if (level[edges[id].u] != -1)
                    continue;
                level[edges[id].u] = level[v] + 1;
                q.push(edges[id].u);
            }
        }
        return level[t] != -1;
    }

    long long dfs(int v, long long pushed) {
        if (pushed == 0)
            return 0;
        if (v == t)
            return pushed;
```

```
        for (int& cid = ptr[v]; cid <
            (int)adj[v].size(); cid++) {
            int id = adj[v][cid];
            int u = edges[id].u;
            if (level[v] + 1 != level[u] ||
                edges[id].cap - edges[id].flow < 1)
                continue;
            long long tr = dfs(u, min(pushed,
                edges[id].cap - edges[id].flow));
            if (tr == 0)
                continue;
            edges[id].flow += tr;
            edges[id ^ 1].flow -= tr;
            return tr;
        }
        return 0;
    }

    long long flow() {
        long long f = 0;
        while (true) {
            fill(level.begin(), level.end(), -1);
            level[s] = 0;
            q.push(s);
            if (!bfs())
                break;
            fill(ptr.begin(), ptr.end(), 0);
            while (long long pushed = dfs(s,
                flow_inf)) {
                f += pushed;
            }
        }
        return f;
    }
};
int main()
{
    return 0;
}
```

3.2 Edmond's Blossom Algorithm

```
/***Copied from
    https://codeforces.com/blog/entry/49402***/

/*
GETS:
V->number of vertices
E->number of edges
pair of vertices as edges (vertices are 1..V)

GIVES:
output of edmonds() is the maximum matching
match[i] is matched pair of i (-1 if there isn't a
    matched pair)
 */

#include <bits/stdc++.h>
using namespace std;
const int M=500;
struct struct_edge
{
    int v;
    struct_edge* n;
};
typedef struct_edge* edge;
struct_edge pool[M*M*2];
edge top=pool,adj[M];
int V,E,match[M],qh,qt,q[M],father[M],base[M];
bool inq[M],inb[M],ed[M][M];
void add_edge(int u,int v)
{
    top->v=v,top->n=adj[u],adj[u]=top++;
    top->v=u,top->n=adj[v],adj[v]=top++;
}
int LCA(int root,int u,int v)
{
    static bool inp[M];
    memset(inp,0,sizeof(inp));
    while(1)
    {
        inp[u=base[u]]=true;
        if (u==root) break;
        u=father[match[u]];
    }
    while(1)
    {
        if (inp[v=base[v]]) return v;
        else v=father[match[v]];
    }
}
void mark_blossom(int lca,int u)
{
    while (base[u]!=lca)
    {
        int v=match[u];
        inb[base[u]]=inb[base[v]]=true;
        u=father[v];
        if (base[u]!=lca) father[u]=v;
    }
}
void blossom_contraction(int s,int u,int v)
{
    int lca=LCA(s,u,v);
    memset(inb,0,sizeof(inb));
    mark_blossom(lca,u);
    mark_blossom(lca,v);
    if (base[u]!=lca)
        father[u]=v;
    if (base[v]!=lca)
        father[v]=u;
    for (int u=0; u<V; u++)
        if (inb[base[u]])
        {
            base[u]=lca;
            if (!inq[u])
                inq[q[++qt]=u]=true;
        }
}
int find_augmenting_path(int s)
{
    memset(inq,0,sizeof(inq));
    memset(father,-1,sizeof(father));
    for (int i=0; i<V; i++) base[i]=i;
    inq[q[qh=qt=0]=s]=true;
    while (qh<=qt)
    {
        int u=q[qh++];
        for (edge e=adj[u]; e; e=e->n)
        {
            int v=e->v;
            if (base[u]!=base[v]&&match[u]!=v)
                if ((v==s)||(match[v]!=-1 &&
                    father[match[v]]!=-1))
                    blossom_contraction(s,u,v);
                else if (father[v]==-1)
                {
                    father[v]=u;
                    if (match[v]==-1)
                        return v;
                    else if (!inq[match[v]])
                        inq[q[++qt]=match[v]]=true;
                }
        }
    }
    return -1;
}
int augment_path(int s,int t)
{
    int u=t,v,w;
    while (u!=-1)
    {
        v=father[u];
        w=match[v];
        match[v]=u;
        match[u]=v;
        u=w;
    }
    return t!=-1;
}
int edmonds()
{
    int matchc=0;
    memset(match,-1,sizeof(match));
    for (int u=0; u<V; u++)
        if (match[u]==-1)
            matchc+=augment_path(u,find_augmenting_path
    return matchc;
}
int main()
{
    FILE *in=stdin;
    int u,v;
    fscanf(in,"%d",&V);
    while(fscanf(in,"%d %d",&u,&v)!=EOF)
    {

        if (!ed[u-1][v-1])
        {
            add_edge(u-1,v-1);
            ed[u-1][v-1]=ed[v-1][u-1]=true;
        }
    }
    printf("%d\n",2*edmonds());
    for (int i=0; i<V; i++)
        if (i<match[i])
            printf("%d %d\n",i+1,match[i]+1);
    return 0;
}
```

3.3 Hungarian Algorithm

```
#include <bits/stdc++.h>
```

```
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define MOD 1000000007
#define GMAX 19
#define INF 20000000000000000
#define EPS 0.000000001
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
class HungarianAlgorithm
{
    int N,inf,n,max_match;
    int *lx,*ly,*xy,*yx,*slack,*slackx,*prev;
    int **cost;
    bool *S,*T;
    void init_labels()
    {
        for(int x=0;x<n;x++) lx[x]=0;
        for(int y=0;y<n;y++) ly[y]=0;
        for (int x = 0; x < n; x++)
            for (int y = 0; y < n; y++)
                lx[x] = max(lx[x], cost[x][y]);
    }
    void update_labels()
    {
        int x, y, delta = inf; //init delta as
            infinity
        for (y = 0; y < n; y++) //calculate delta
            using slack
            if (!T[y])
                delta = min(delta, slack[y]);
        for (x = 0; x < n; x++) //update X labels
            if (S[x]) lx[x] -= delta;
        for (y = 0; y < n; y++) //update Y labels
            if (T[y]) ly[y] += delta;
        for (y = 0; y < n; y++) //update slack array
            if (!T[y])
                slack[y] -= delta;
    }
    void add_to_tree(int x, int prevx)
//x - current vertex,prevx - vertex from X before x
    in the alternating path,
//so we add edges (prevx, xy[x]), (xy[x], x)
    {
        S[x] = true; //add x to S
        prev[x] = prevx; //we need this when
            augmenting
        for (int y = 0; y < n; y++) //update
            slacks, because we add new vertex to S
            if (lx[x] + ly[y] - cost[x][y] <
                slack[y])
            {
                slack[y] = lx[x] + ly[y] -
                    cost[x][y];
                slackx[y] = x;
            }
    }
    void augment() //main function of the algorithm
    {
        if (max_match == n) return; //check wether
            matching is already perfect
        int x, y, root; //just counters and root
            vertex
        int q[N], wr = 0, rd = 0; //q - queue for
            bfs, wr,rd - write and read
//pos in queue
        //memset(S, false, sizeof(S)); //init set S
        for(int i=0;i<n;i++) S[i]=false;
        //memset(T, false, sizeof(T)); //init set T
        for(int i=0;i<n;i++) T[i]=false;
        //memset(prev, -1, sizeof(prev)); //init
            set prev - for the alternating tree
        for(int i=0;i<n;i++) prev[i]=-1;
        for (x = 0; x < n; x++) //finding root of
            the tree
        {
            if (xy[x] == -1)
            {
                q[wr++] = root = x;
                prev[x] = -2;
                S[x] = true;
                break;
            }
        }
        for (y = 0; y < n; y++) //initializing
            slack array
        {
            slack[y] = lx[root] + ly[y] -
                cost[root][y];
            slackx[y] = root;
        }
        while (true) //main cycle
        {
            while (rd < wr) //building tree with bfs
                cycle
            {
                x = q[rd++]; //current vertex from X
                    part
                for (y = 0; y < n; y++) //iterate
                    through all edges in equality
                    graph
                {
                    if (cost[x][y] == lx[x] + ly[y]
                        && !T[y])
                    {
                        if (yx[y] == -1) break; //an
                            exposed vertex in Y
                            found, so
//augmenting path exists!
                        T[y] = true; //else just add
                            y to T,
                        q[wr++] = yx[y]; //add vertex
                            yx[y], which is matched
//with y, to the queue
                        add_to_tree(yx[y], x); //add
                            edges (x,y) and (y,yx[y])
                            to the tree
                    }
                }
                if (y < n) break; //augmenting path
                    found!
            }
            if (y < n) break; //augmenting path
                found!
            update_labels(); //augmenting path not
                found, so improve labeling
            wr = rd = 0;
            for (y = 0; y < n; y++)
            {
                //in this cycle we add edges that
                    were added to the equality graph
                    as a
//result of improving the labeling, we add edge
    (slackx[y], y) to the tree if
//and only if !T[y] && slack[y] == 0, also with
    this edge we add another one
//(y, yx[y]) or augment the matching, if y was
    exposed
                if (!T[y] && slack[y] == 0)
                {
                    if (yx[y] == -1) //exposed vertex
                        in Y found - augmenting path
                        exists!
                    {
                        x = slackx[y];
                        break;
                    }
                    else
                    {
                        T[y] = true; //else just add
                            y to T,
                        if (!S[yx[y]])
                        {
                            q[wr++] = yx[y]; //add
                                vertex yx[y], which is
                                matched with
//y, to the queue
                            add_to_tree(yx[y],
                                slackx[y]); //and add
                                edges (x,y) and (y,
//yx[y]) to the tree
                        }
                    }
                }
                if (y < n) break; //augmenting path
                    found!
            }
        }
        if (y < n) //we found augmenting path!
        {
            max_match++; //increment matching
//in this cycle we inverse edges along augmenting
    path
            for (int cx = x, cy = y, ty; cx != -2;
                cx = prev[cx], cy = ty)
            {
                ty = xy[cx];
                yx[cy] = cx;
                xy[cx] = cy;
            }
```

```
            augment(); //recall function, go to step
                1 of the algorithm
        }
    }//end of augment() function
public:
    HungarianAlgorithm(int vv,int inf=1000000000)
    {
        N=vv;
        n=N;
        max_match=0;
        this->inf=inf;
        lx=new int[N];
        ly=new int[N];//labels of X and Y parts
        xy=new int[N];//xy[x] - vertex that is
            matched with x,
        yx=new int[N];//yx[y] - vertex that is
            matched with y
        slack=new int[N];//as in the algorithm
            description
        slackx=new int[N];//slackx[y] such a
            vertex, that l(slackx[y]) + l(y) -
            w(slackx[y],y) = slack[y]
        prev=new int[N];//array for memorizing
            alternating paths
        S=new bool[N];
        T=new bool[N];//sets S and T in algorithm
        cost=new int*[N];//cost matrix
        for(int i=0; i<N; i++)
        {
            cost[i]=new int[N];
        }
    }
    ~HungarianAlgorithm()
    {
        delete []lx;
        delete []ly;
        delete []xy;
        delete []yx;
        delete []slack;
        delete []slackx;
        delete []prev;
        delete []S;
        delete []T;
        int i;
        for(i=0; i<N; i++)
        {
            delete [](cost[i]);
        }
        delete []cost;
    }
    void setCost(int i,int j,int c)
    {
        cost[i][j]=c;
    }
    int* matching(bool first=true)
    {
        int *ans;
        ans=new int[N];
        for(int i=0;i<N;i++)
        {
            if(first) ans[i]=xy[i];
            else ans[i]=yx[i];
        }
        return ans;
    }
    int hungarian()
    {
        int ret = 0; //weight of the optimal
            matching
        max_match = 0; //number of vertices in
            current matching
        for(int x=0;x<n;x++) xy[x]=-1;
        for(int y=0;y<n;y++) yx[y]=-1;
        init_labels(); //step 0
        augment(); //steps 1-3
        for (int x = 0; x < n; x++) //forming
            answer there
            ret += cost[x][xy[x]];
        return ret;
    }
};
int main()
{
    int t,T=1;
    scanf("%d",&T);
    for(t=0;t<T;t++)
    {
        int n,i,j;
        scanf("%d",&n);
        HungarianAlgorithm h(n);
        int own[n],opposite[n];
        for(i=0;i<n;i++)
        {
            scanf("%d",&own[i]);
        }
        for(j=0;j<n;j++)
        {
            scanf("%d",&opposite[j]);
        }
        for(i=0;i<n;i++)
        {
            for(j=0;j<n;j++)
            {
                int v;
                if(own[i]==opposite[j]) v=1;
                else if(own[i]>opposite[j]) v=2;
                else v=0;
                h.setCost(i,j,v);
            }
        }
        int ans=h.hungarian();
        printf("Case %d: %d\n",t+1,ans);
    }
    return 0;
}
```

3.4 Maximum Bipartite Matching

```
/** Source:
    https://iq.opengenus.org/hopcroft-karp-algorithm/
    **/
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define BEGIN 1
#define MOD 1000000007
#define INF INT_MAX
#define EPS 0.00000000001
#define CHAINS 18
#define NIL 0
#define NOT_VISITED 0
#define VISITING 1
#define VISITED 2
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
// A class to represent Bipartite graph for
// Hopcroft Karp implementation
class BGraph
{
    // m and n are number of vertices on left
    // and right sides of Bipartite Graph
    int m, n;

    // adj[u] stores adjacents of left side
    // vertex 'u'. The value of u ranges from 1 to
        m.
    // 0 is used for dummy vertex
    std::list<int> *adj;

    // pointers for hopcroftKarp()
    int *pair_u, *pair_v, *dist;

public:
    BGraph(int m, int n);   // Constructor
    void addEdge(int u, int v); // To add edge

    // Returns true if there is an augmenting path
    bool bfs();

    // Adds augmenting path if there is one
        beginning
    // with u
    bool dfs(int u);

    // Returns size of maximum matching
    int hopcroftKarpAlgorithm();
};

// Returns size of maximum matching
int BGraph::hopcroftKarpAlgorithm()
{
    // pair_u[u] stores pair of u in matching on
        left side of Bipartite Graph.
    // If u doesn't have any pair, then pair_u[u]
        is NIL
    pair_u = new int[m + 1];

    // pair_v[v] stores pair of v in matching on
        right side of Biparite Graph.
    // If v doesn't have any pair, then pair_u[v]
        is NIL
    pair_v = new int[n + 1];

    // dist[u] stores distance of left side vertices
    dist = new int[m + 1];

    // Initialize NIL as pair of all vertices
    for (int u = 0; u <= m; u++)
```

```
        pair_u[u] = NIL;
    for (int v = 0; v <= n; v++)
        pair_v[v] = NIL;

    // Initialize result
    int result = 0;

    // Keep updating the result while there is an
    // augmenting path possible.
    while (bfs())
    {
        // Find a free vertex to check for a
            matching
        for (int u = 1; u <= m; u++)

            // If current vertex is free and there is
            // an augmenting path from current vertex
            // then increment the result
            if (pair_u[u] == NIL && dfs(u))
                result++;
    }
    return result;
}

// Returns true if there is an augmenting path
    available, else returns false
bool BGraph::bfs()
{
    std::queue<int> q; //an integer queue for bfs

    // First layer of vertices (set distance as 0)
    for (int u = 1; u <= m; u++)
    {
        // If this is a free vertex, add it to queue
        if (pair_u[u] == NIL)
        {
            // u is not matched so distance is 0
            dist[u] = 0;
            q.push(u);
        }

        // Else set distance as infinite so that
            this vertex is considered next time for
            availibility
        else
            dist[u] = INF;
    }

    // Initialize distance to NIL as infinite
    dist[NIL] = INF;

    // q is going to contain vertices of left side
        only.
    while (!q.empty())
    {
        // dequeue a vertex
        int u = q.front();
        q.pop();

        // If this node is not NIL and can provide
            a shorter path to NIL then
        if (dist[u] < dist[NIL])
        {
            // Get all the adjacent vertices of the
                dequeued vertex u
            std::list<int>::iterator it;
            for (it = adj[u].begin(); it !=
                adj[u].end(); ++it)
            {
                int v = *it;

                // If pair of v is not considered so
                    far
                // i.e. (v, pair_v[v]) is not yet
                    explored edge.
                if (dist[pair_v[v]] == INF)
                {
                    // Consider the pair and push it
                        to queue
                    dist[pair_v[v]] = dist[u] + 1;
                    q.push(pair_v[v]);
                }
            }
        }
    }

    // If we could come back to NIL using
        alternating path of distinct
    // vertices then there is an augmenting path
        available
    return (dist[NIL] != INF);
}

// Returns true if there is an augmenting path
    beginning with free vertex u
bool BGraph::dfs(int u)
{
    if (u != NIL)
    {
        std::list<int>::iterator it;
        for (it = adj[u].begin(); it !=
            adj[u].end(); ++it)
        {
            // Adjacent vertex of u
            int v = *it;

            // Follow the distances set by BFS search
            if (dist[pair_v[v]] == dist[u] + 1)
            {
                // If dfs for pair of v also returnn
                    true then
                if (dfs(pair_v[v]) == true)
                {   // new matching possible, store
                    the matching
                    pair_v[v] = u;
                    pair_u[u] = v;
                    return true;
                }
            }
        }

        // If there is no augmenting path beginning
            with u then.
        dist[u] = INF;
        return false;
    }
    return true;
}

// Constructor for initialization
BGraph::BGraph(int m, int n)
{
    this->m = m;
    this->n = n;
    adj = new std::list<int>[m + 1];
}

// function to add edge from u to v
void BGraph::addEdge(int u, int v)
{
    adj[u].push_back(v); // Add v to us list.
}
```

3.5 Minimum Cost Maximum Flow

```
struct Edge
{
    int from, to, capacity, cost;
};

vector<vector<int>> adj, cost, capacity;

const int INF = 1e9;

void shortest_paths(int n, int v0, vector<int>& d,
    vector<int>& p) {
    d.assign(n, INF);
    d[v0] = 0;
    vector<bool> inq(n, false);
    queue<int> q;
    q.push(v0);
    p.assign(n, -1);

    while (!q.empty()) {
        int u = q.front();
        q.pop();
        inq[u] = false;
        for (int v : adj[u]) {
            if (capacity[u][v] > 0 && d[v] > d[u] +
                cost[u][v]) {
                d[v] = d[u] + cost[u][v];
                p[v] = u;
                if (!inq[v]) {
                    inq[v] = true;
                    q.push(v);
                }
            }
        }
    }
}

int min_cost_flow(int N, vector<Edge> edges, int K,
    int s, int t) {
    adj.assign(N, vector<int>());
    cost.assign(N, vector<int>(N, 0));
    capacity.assign(N, vector<int>(N, 0));
    for (Edge e : edges) {
        adj[e.from].push_back(e.to);
        adj[e.to].push_back(e.from);
        cost[e.from][e.to] = e.cost;
        cost[e.to][e.from] = -e.cost;
        capacity[e.from][e.to] = e.capacity;
    }

    int flow = 0;
    int cost = 0;
```

```
    vector<int> d, p;
    while (flow < K) {
        shortest_paths(N, s, d, p);
        if (d[t] == INF)
            break;

        // find max flow on that path
        int f = K - flow;
        int cur = t;
        while (cur != s) {
            f = min(f, capacity[p[cur]][cur]);
            cur = p[cur];
        }

        // apply flow
        flow += f;
        cost += f * d[t];
        cur = t;
        while (cur != s) {
            capacity[p[cur]][cur] -= f;
            capacity[cur][p[cur]] += f;
            cur = p[cur];
        }
    }

    if (flow < K)
        return -1;
    else
        return cost;
}
```

4 Geo

4.1 Convex Hull

```
#include<bits/stdc++.h>
#include<vector>
using namespace std;
struct pt {
    double x, y;
};

bool cmp(pt a, pt b) {
    return a.x < b.x || (a.x == b.x && a.y < b.y);
}

bool cw(pt a, pt b, pt c) {
    return
        a.x*(b.y-c.y)+b.x*(c.y-a.y)+c.x*(a.y-b.y) <
        0;
}

bool ccw(pt a, pt b, pt c) {
    return
        a.x*(b.y-c.y)+b.x*(c.y-a.y)+c.x*(a.y-b.y) >
        0;
}
vector<pt> a;
vector<pair<double,pair<double,double> > > pp;
void convex_hull(vector<pt>& a) {
    if (a.size() == 1)
        return;

    sort(a.begin(), a.end(), &cmp);
    pt p1 = a[0], p2 = a.back();
    vector<pt> up, down;
    up.push_back(p1);
    down.push_back(p1);
    for (int i = 1; i < (int)a.size(); i++) {
        if (i == a.size() - 1 || cw(p1, a[i], p2)) {
            while (up.size() >= 2 &&
                !cw(up[up.size()-2],
                up[up.size()-1], a[i]))
                up.pop_back();
            up.push_back(a[i]);
        }
        if (i == a.size() - 1 || ccw(p1, a[i], p2))
            {
            while(down.size() >= 2 &&
                !ccw(down[down.size()-2],
                down[down.size()-1], a[i]))
                down.pop_back();
            down.push_back(a[i]);
        }
    }

    a.clear();
    for (int i = 0; i < (int)up.size(); i++)
        a.push_back(up[i]);
    for (int i = down.size() - 2; i > 0; i--)
        a.push_back(down[i]);
}
```

4.2 Half Plane Intersection

```
#include <bits/stdc++.h>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 200005
#define MOD 1009
#define SMOD 998244353
#define ROOT 318
#define GMAX 19
#define INF 1000000000000000000
#define EPS 0.000000001
#define NIL 0
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
class HalfPlaneIntersection
{
    static double eps, inf;
public:
    struct Point
    {

        double x, y;
        explicit Point(double x = 0, double y = 0)
            : x(x), y(y) {}

        // Addition, substraction, multiply by
            constant, cross product.

        friend Point operator + (const Point& p,
            const Point& q)
        {
            return Point(p.x + q.x, p.y + q.y);
        }

        friend Point operator - (const Point& p,
            const Point& q)
        {
            return Point(p.x - q.x, p.y - q.y);
        }

        friend Point operator * (const Point& p,
            const double& k)
        {
            return Point(p.x * k, p.y * k);
        }

        friend double cross(const Point& p, const
            Point& q)
        {
            return p.x * q.y - p.y * q.x;
        }
    };

// Basic half-plane struct.
    struct Halfplane
    {

        // 'p' is a passing point of the line and
            'pq' is the direction vector of the line.
        Point p, pq;
        double angle;

        Halfplane() {}
        Halfplane(const Point& a, const Point& b) :
            p(a), pq(b - a)
        {
            angle = atan2l(pq.y, pq.x);
        }

        // Check if point 'r' is outside this
            half-plane.
        // Every half-plane allows the region to
            the LEFT of its line.
        bool out(const Point& r)
        {
            return cross(pq, r - p) < -eps;
        }

        // Comparator for sorting.
        // If the angle of both half-planes is
            equal, the leftmost one should go first.
        bool operator < (const Halfplane& e) const
        {
            if (fabsl(angle - e.angle) < eps) return
                cross(pq, e.p - p) < 0;
            return angle < e.angle;
        }

        // We use equal comparator for std::unique
            to easily remove parallel half-planes.
        bool operator == (const Halfplane& e) const
        {
            return fabsl(angle - e.angle) < eps;
        }

        // Intersection point of the lines of two
            half-planes. It is assumed they're never
            parallel.
```

```
    friend Point inter(const Halfplane& s,
        const Halfplane& t)
    {
        double alpha = cross((t.p - s.p), t.pq)
            / cross(s.pq, t.pq);
        return s.p + (s.pq * alpha);
    }
};
static vector<Point>
    hp_intersect(vector<Halfplane>& H)
{

    Point box[4] =  // Bounding box in CCW order
    {
        Point(inf, inf),
        Point(-inf, inf),
        Point(-inf, -inf),
        Point(inf, -inf)
    };

    for(int i = 0; i<4; i++) // Add bounding
        box half-planes.
    {
        Halfplane aux(box[i], box[(i+1) % 4]);
        H.push_back(aux);
    }

    // Sort and remove duplicates
    sort(H.begin(), H.end());
    H.erase(unique(H.begin(), H.end()),
        H.end());

    deque<Halfplane> dq;
    int len = 0;
    for(int i = 0; i < int(H.size()); i++)
    {

        // Remove from the back of the deque
            while last half-plane is redundant
        while (len > 1 &&
            H[i].out(inter(dq[len-1],
            dq[len-2])))
        {
            dq.pop_back();
            --len;
        }

        // Remove from the front of the deque
            while first half-plane is redundant
        while (len > 1 && H[i].out(inter(dq[0],
            dq[1])))
        {
            dq.pop_front();
            --len;
        }

        // Add new half-plane
        dq.push_back(H[i]);
        ++len;
    }

    // Final cleanup: Check half-planes at the
        front against the back and vice-versa
    while (len > 2 &&
        dq[0].out(inter(dq[len-1], dq[len-2])))
    {
        dq.pop_back();
        --len;
    }

    while (len > 2 &&
        dq[len-1].out(inter(dq[0], dq[1])))
    {
        dq.pop_front();
        --len;
    }

    // Report empty intersection if necessary
    if (len < 3) return vector<Point>();

    // Reconstruct the convex polygon from the
        remaining half-planes.
    vector<Point> ret(len);
    for(int i = 0; i+1 < len; i++)
    {
        ret[i] = inter(dq[i], dq[i+1]);
    }
    ret.back() = inter(dq[len-1], dq[0]);
    return ret;
    }
};
double HalfPlaneIntersection::eps=1e-9;
double HalfPlaneIntersection::inf=1e9;
int main()
{
    vector<HalfPlaneIntersection::Halfplane> V;
    vector<HalfPlaneIntersection::Point> P;
    int n;
    //FASTIO;
    int i,j;
    scanf("%d",&n);
    for(i=0; i<n; i++)
    {
        int c;
        scanf("%d",&c);
        HalfPlaneIntersection::Halfplane h;
        HalfPlaneIntersection::Point p;
        for(j=0; j<c; j++)
        {
            scanf("%lf %lf",&p.x,&p.y);
            P.push_back(p);
        }
        for(j=0; j<c; j++)
        {
            h=HalfPlaneIntersection::Halfplane(P[j],P[(j+1)%c]);
            V.push_back(h);
        }
        P.clear();
    }
    P=HalfPlaneIntersection::hp_intersect(V);
    double ans=0;
    n=P.size();
    for(i=0; i<n; i++)
    {
        ans=ans+P[i].x*P[(i+1)%n].y-P[i].y*P[(i+1)%n].x;
    }
    ans=ans/2;
    printf("%.4f",ans);
    return 0;
}
```

4.3 Line Segment Intersection

```
#include<bits/stdc++.h>
using namespace std;
const double EPS = 1E-9;
struct pt {
    double x, y;

    bool operator<(const pt& p) const
    {
        return x < p.x - EPS || (abs(x - p.x) < EPS
            && y < p.y - EPS);
    }
};

struct line {
    double a, b, c;

    line() {}
    line(pt p, pt q)
    {
        a = p.y - q.y;
        b = q.x - p.x;
        c = -a * p.x - b * p.y;
        norm();
    }

    void norm()
    {
        double z = sqrt(a * a + b * b);
        if (abs(z) > EPS)
            a /= z, b /= z, c /= z;
    }

    double dist(pt p) const { return a * p.x + b *
        p.y + c; }
};

double det(double a, double b, double c, double d)
{
    return a * d - b * c;
}

inline bool betw(double l, double r, double x)
{
    return min(l, r) <= x + EPS && x <= max(l, r) +
        EPS;
}

inline bool intersect_1d(double a, double b, double
    c, double d)
{
    if (a > b)
        swap(a, b);
    if (c > d)
        swap(c, d);
    return max(a, c) <= min(b, d) + EPS;
}

bool intersect(pt a, pt b, pt c, pt d, pt& left,
    pt& right)
{
    if (!intersect_1d(a.x, b.x, c.x, d.x) ||
        !intersect_1d(a.y, b.y, c.y, d.y))
        return false;
```

```
    line m(a, b);
    line n(c, d);
    double zn = det(m.a, m.b, n.a, n.b);
    if (abs(zn) < EPS) {
        if (abs(m.dist(c)) > EPS || abs(n.dist(a))
            > EPS)
            return false;
        if (b < a)
            swap(a, b);
        if (d < c)
            swap(c, d);
        left = max(a, c);
        right = min(b, d);
        return true;
    } else {
        left.x = right.x = -det(m.c, m.b, n.c, n.b)
            / zn;
        left.y = right.y = -det(m.a, m.c, n.a, n.c)
            / zn;
        return betw(a.x, b.x, left.x) && betw(a.y,
            b.y, left.y) &&
               betw(c.x, d.x, left.x) && betw(c.y,
                   d.y, left.y);
    }
}
int main()
{
    return 0;
}
```

4.4 Minimum Perimeter Triangle

```
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define MOD 1000000007
#define SMOD 998244353
#define INF 6000000000000000000
#define EPS 0.0000000001
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
struct pt
{
    double x, y;
    int id;
};

struct cmp_x
{
    bool operator()(const pt & a, const pt & b)
        const
    {
        return a.x < b.x || (a.x == b.x && a.y <
            b.y);
    }
};

struct cmp_y
{
    bool operator()(const pt & a, const pt & b)
        const
    {
        return a.y < b.y;
    }
};

int n;
vector<pt> a;
double mindist;
pair<int,pair<int, int> > best_pair;

void upd_ans(const pt & a, const pt & b,const pt &
    c)
{
    double distC = sqrt((a.x - b.x)*(a.x - b.x) +
        (a.y - b.y)*(a.y - b.y));
    double distA = sqrt((c.x - b.x)*(c.x - b.x) +
        (c.y - b.y)*(c.y - b.y));
    double distB = sqrt((a.x - c.x)*(a.x - c.x) +
        (a.y - c.y)*(a.y - c.y));
    if (distA + distB + distC < mindist)
    {
        mindist = distA + distB + distC;
        best_pair =
            make_pair(a.id,make_pair(b.id,c.id));
    }
}

vector<pt> t;

void rec(int l, int r)
{
    if (r - l <= 3 &&r - l >=2)
    {
        for (int i = l; i < r; ++i)
        {
            for (int j = i + 1; j < r; ++j)
            {
                for(int k=j+1;k<r;k++)
                {
                    upd_ans(a[i],a[j],a[k]);
                }
            }
        }
        sort(a.begin() + l, a.begin() + r, cmp_y());
        return;
    }

    int m = (l + r) >> 1;
    int midx = a[m].x;
    rec(l, m);
    rec(m, r);

    merge(a.begin() + l, a.begin() + m, a.begin() +
        m, a.begin() + r, t.begin(), cmp_y());
    copy(t.begin(), t.begin() + r - l, a.begin() +
        l);

    int tsz = 0;
    for (int i = l; i < r; ++i)
    {
        if (abs(a[i].x - midx) < mindist/2)
        {
            for (int j = tsz - 1; j >= 0 && a[i].y -
                t[j].y < mindist/2; --j)
            {
                if(i+1<r) upd_ans(a[i], a[i+1],
                    t[j]);
                if(j>0) upd_ans(a[i], t[j-1], t[j]);
            }
            t[tsz++] = a[i];
        }
    }
}
```

4.5 Minkowski

```
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define BEGIN 1
#define MOD 1000000007
#define INF 1000000000000000000
#define EPS 0.0000000001
#define CHAINS 18
#define NOT_VISITED 0
#define VISITING 1
#define VISITED 2
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
struct pt
{
    long long x, y;
    pt() {}
    pt(long long _x, long long _y):x(_x), y(_y) {}
    pt operator+(const pt & p) const
    {
        return pt(x + p.x, y + p.y);
    }
    pt operator-(const pt & p) const
    {
        return pt(x - p.x, y - p.y);
    }
    long long cross(const pt & p) const
    {
        return x * p.y - y * p.x;
    }
    long long dot(const pt & p) const
    {
        return x * p.x + y * p.y;
    }
    long long cross(const pt & a, const pt & b)
        const
    {
        return (a - *this).cross(b - *this);
    }
    long long dot(const pt & a, const pt & b) const
    {
        return (a - *this).dot(b - *this);
    }
    long long sqrLen() const
```

```
    {
        return this->dot(*this);
    }
};

class pointLocationInPolygon
{
    bool lexComp(const pt & l, const pt & r)
    {
        return l.x < r.x || (l.x == r.x && l.y <
            r.y);
    }

    int sgn(long long val)
    {
        return val > 0 ? 1 : (val == 0 ? 0 : -1);
    }

    vector<pt> seq;
    int n;
    pt translate;
    bool pointInTriangle(pt a, pt b, pt c, pt point)
    {
        long long s1 = abs(a.cross(b, c));
        long long s2 = abs(point.cross(a, b)) +
            abs(point.cross(b, c)) +
            abs(point.cross(c, a));
        return s1 == s2;
    }
public:
    pointLocationInPolygon()
    {

    }
    pointLocationInPolygon(vector<pt> & points)
    {
        prepare(points);
    }
    void prepare(vector<pt> & points)
    {
        seq.clear();
        n = points.size();
        int pos = 0;
        for(int i = 1; i < n; i++)
        {
            if(lexComp(points[i], points[pos]))
                pos = i;
        }
        translate.x=points[pos].x;
        translate.y=points[pos].y;
        rotate(points.begin(), points.begin() +
            pos, points.end());

        n--;
        seq.resize(n);
        for(int i = 0; i < n; i++)
            seq[i] = points[i + 1] - points[0];
    }

    bool pointInConvexPolygon(pt point)
    {
        point.x-=translate.x;
        point.y-=translate.y;

        if(seq[0].cross(point) != 0 &&
            sgn(seq[0].cross(point)) !=
            sgn(seq[0].cross(seq[n - 1])))
            return false;
        if(seq[n - 1].cross(point) != 0 &&
            sgn(seq[n - 1].cross(point)) !=
            sgn(seq[n - 1].cross(seq[0])))
            return false;

        if(seq[0].cross(point) == 0)
            return seq[0].sqrLen() >= point.sqrLen();

        int l = 0, r = n - 1;
        while(r - l > 1)
        {
            int mid = (l + r)/2;
            int pos = mid;
            if(seq[pos].cross(point) >= 0)l = mid;
            else r = mid;
        }
        int pos = l;
        return pointInTriangle(seq[pos], seq[pos +
            1], pt(0, 0), point);
    }
    ~pointLocationInPolygon()
    {
        seq.clear();
    }
};
class Minkowski
{

    static void reorder_polygon(vector<pt> & P)
    {
        size_t pos = 0;
        for(size_t i = 1; i < P.size(); i++)
        {
            if(P[i].y < P[pos].y || (P[i].y ==
                P[pos].y && P[i].x < P[pos].x))
                pos = i;
        }
        rotate(P.begin(), P.begin() + pos, P.end());
    }
public:
    static vector<pt> minkowski(vector<pt> P,
        vector<pt> Q)
    {
        // the first vertex must be the lowest
        reorder_polygon(P);
        reorder_polygon(Q);
        // we must ensure cyclic indexing
        P.push_back(P[0]);
        P.push_back(P[1]);
        Q.push_back(Q[0]);
        Q.push_back(Q[1]);
        // main part
        vector<pt> result;
        size_t i = 0, j = 0;
        while(i < P.size() - 2 || j < Q.size() - 2)
        {
            result.push_back(P[i] + Q[j]);
            auto cross = (P[i + 1] - P[i]).cross(Q[j
                + 1] - Q[j]);
            if(cross >= 0)
                ++i;
            if(cross <= 0)
                ++j;
        }
        return result;
    }
};
```

4.6 Pair of Intersecting Segments

```
#include<bits/stdc++.h>
#include<string.h>
#include<vector>
#include<string.h>
using namespace std;
#define MAX 100009
#define MAX_NODES 100005
#define MOD 1000000007
#define INF 200000000
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
const double EPS = 1E-9;

struct pt {
    double x, y;
};

struct seg {
    pt p, q;
    int id;

    double get_y(double x) const {
        if (abs(p.x - q.x) < EPS)
            return p.y;
        return p.y + (q.y - p.y) * (x - p.x) / (q.x
            - p.x);
    }
};

bool intersect1d(double l1, double r1, double l2,
    double r2) {
    if (l1 > r1)
        swap(l1, r1);
    if (l2 > r2)
        swap(l2, r2);
    return max(l1, l2) <= min(r1, r2) + EPS;
}

int vec(const pt& a, const pt& b, const pt& c) {
    double s = (b.x - a.x) * (c.y - a.y) - (b.y -
        a.y) * (c.x - a.x);
    return abs(s) < EPS ? 0 : s > 0 ? +1 : -1;
}

bool intersect(const seg& a, const seg& b)
{
    return intersect1d(a.p.x, a.q.x, b.p.x, b.q.x)
        &&
          intersect1d(a.p.y, a.q.y, b.p.y, b.q.y) &&
          vec(a.p, a.q, b.p) * vec(a.p, a.q, b.q)
              <= 0 &&
          vec(b.p, b.q, a.p) * vec(b.p, b.q, a.q)
              <= 0;
}

bool operator<(const seg& a, const seg& b)
```

```
{
    double x = max(min(a.p.x, a.q.x), min(b.p.x,
        b.q.x));
    return a.get_y(x) < b.get_y(x) - EPS;
}

struct event {
    double x;
    int tp, id;

    event() {}
    event(double x, int tp, int id) : x(x), tp(tp),
        id(id) {}

    bool operator<(const event& e) const {
        if (abs(x - e.x) > EPS)
            return x < e.x;
        return tp > e.tp;
    }
};

set<seg> s;
vector<set<seg>::iterator> where;

set<seg>::iterator prev(set<seg>::iterator it) {
    return it == s.begin() ? s.end() : --it;
}

set<seg>::iterator next(set<seg>::iterator it) {
    return ++it;
}

pair<int, int> solve(const vector<seg>& a) {
    int n = (int)a.size();
    vector<event> e;
    for (int i = 0; i < n; ++i) {
        e.push_back(event(min(a[i].p.x, a[i].q.x),
            +1, i));
        e.push_back(event(max(a[i].p.x, a[i].q.x),
            -1, i));
    }
    sort(e.begin(), e.end());

    s.clear();
    where.resize(a.size());
    for (size_t i = 0; i < e.size(); ++i) {
        int id = e[i].id;
        if (e[i].tp == +1) {
            set<seg>::iterator nxt =
                s.lower_bound(a[id]), prv =
                prev(nxt);
            if (nxt != s.end() && intersect(*nxt,
                a[id]))
                {
                    return make_pair(nxt->id, id);
                }
            if (prv != s.end() && intersect(*prv,
                a[id]))
            {
                return make_pair(prv->id, id);
            }

            where[id] = s.insert(nxt, a[id]);
        } else {
            set<seg>::iterator nxt =
                next(where[id]), prv =
                prev(where[id]);
            if (nxt != s.end() && prv != s.end() &&
                intersect(*nxt, *prv))
                return make_pair(prv->id, nxt->id);
            s.erase(where[id]);
        }
    }

    return make_pair(-1, -1);
}
```

4.7 Vertical Decomposition

```
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define MOD 1000000007
#define GMAX 19
#define INF 20000000000000000
#define EPS 0.000000001
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
typedef double dbl;

const dbl eps = 1e-9;

inline bool eq(dbl x, dbl y){
    return fabs(x - y) < eps;
}

inline bool lt(dbl x, dbl y){
    return x < y - eps;
}

inline bool gt(dbl x, dbl y){
    return x > y + eps;
}

inline bool le(dbl x, dbl y){
    return x < y + eps;
}

inline bool ge(dbl x, dbl y){
    return x > y - eps;
}

struct pt{
    dbl x, y;
    inline pt operator - (const pt & p)const{
        return pt{x - p.x, y - p.y};
    }
    inline pt operator + (const pt & p)const{
        return pt{x + p.x, y + p.y};
    }
    inline pt operator * (dbl a)const{
        return pt{x * a, y * a};
    }
    inline dbl cross(const pt & p)const{
        return x * p.y - y * p.x;
    }
    inline dbl dot(const pt & p)const{
        return x * p.x + y * p.y;
    }
    inline bool operator == (const pt & p)const{
        return eq(x, p.x) && eq(y, p.y);
    }
};

struct Line{
    pt p[2];
    Line(){}
    Line(pt a, pt b):p{a, b}{}
    pt vec()const{
        return p[1] - p[0];
    }
    pt& operator [](size_t i){
        return p[i];
    }
};

inline bool lexComp(const pt & l, const pt & r){
    if(fabs(l.x - r.x) > eps){
        return l.x < r.x;
    }
    else return l.y < r.y;
}

vector<pt> interSegSeg(Line l1, Line l2){
    if(eq(l1.vec().cross(l2.vec()), 0)){
        if(!eq(l1.vec().cross(l2[0] - l1[0]), 0))
            return {};
        if(!lexComp(l1[0], l1[1]))
            swap(l1[0], l1[1]);
        if(!lexComp(l2[0], l2[1]))
            swap(l2[0], l2[1]);
        pt l = lexComp(l1[0], l2[0]) ? l2[0] :
            l1[0];
        pt r = lexComp(l1[1], l2[1]) ? l1[1] :
            l2[1];
        if(l == r)
            return {l};
        else return lexComp(l, r) ? vector<pt>{l,
            r} : vector<pt>();
    }
    else{
        dbl s = (l2[0] - l1[0]).cross(l2.vec()) /
            l1.vec().cross(l2.vec());
        pt inter = l1[0] + l1.vec() * s;
        if(ge(s, 0) && le(s, 1) && le((l2[0] -
            inter).dot(l2[1] - inter), 0))
            return {inter};
        else
            return {};
    }
}
inline char get_segtype(Line segment, pt
    other_point){
    if(eq(segment[0].x, segment[1].x))
        return 0;
    if(!lexComp(segment[0], segment[1]))
        swap(segment[0], segment[1]);
    return (segment[1] -
        segment[0]).cross(other_point - segment[0])
        > 0 ? 1 : -1;
```

```
}

dbl union_area(vector<tuple<pt, pt, pt> >
    triangles){
    vector<Line> segments(3 * triangles.size());
    vector<char> segtype(segments.size());
    for(size_t i = 0; i < triangles.size(); i++){
        pt a, b, c;
        tie(a, b, c) = triangles[i];
        segments[3 * i] = lexComp(a, b) ? Line(a,
            b) : Line(b, a);
        segtype[3 * i] = get_segtype(segments[3 *
            i], c);
        segments[3 * i + 1] = lexComp(b, c) ?
            Line(b, c) : Line(c, b);
        segtype[3 * i + 1] = get_segtype(segments[3
            * i + 1], a);
        segments[3 * i + 2] = lexComp(c, a) ?
            Line(c, a) : Line(a, c);
        segtype[3 * i + 2] = get_segtype(segments[3
            * i + 2], b);
    }
    vector<dbl> k(segments.size()),
        b(segments.size());
    for(size_t i = 0; i < segments.size(); i++){
        if(segtype[i]){
            k[i] = (segments[i][1].y -
                segments[i][0].y) /
                (segments[i][1].x -
                segments[i][0].x);
            b[i] = segments[i][0].y - k[i] *
                segments[i][0].x;
        }
    }
    dbl ans = 0;
    for(size_t i = 0; i < segments.size(); i++){
        if(!segtype[i])
            continue;
        dbl l = segments[i][0].x, r =
            segments[i][1].x;
        vector<pair<dbl, int> > evts;
        for(size_t j = 0; j < segments.size(); j++){
            if(!segtype[j] || i == j)
                continue;
            dbl l1 = segments[j][0].x, r1 =
                segments[j][1].x;
            if(ge(l1, r) || ge(l, r1))
                continue;
            dbl common_l = max(l, l1), common_r =
                min(r, r1);
            auto pts = interSegSeg(segments[i],
                segments[j]);
            if(pts.empty()){
                dbl yl1 = k[j] * common_l + b[j];
                dbl yl = k[i] * common_l + b[i];
                if(lt(yl1, yl) == (segtype[i] == 1)){
                    int evt_type = -segtype[i] *
                        segtype[j];
                    evts.emplace_back(common_l,
                        evt_type);
                    evts.emplace_back(common_r,
                        -evt_type);
                }
            }
            else if(pts.size() == 1u){
                dbl yl = k[i] * common_l + b[i], yl1
                    = k[j] * common_l + b[j];
                int evt_type = -segtype[i] *
                    segtype[j];
                if(lt(yl1, yl) == (segtype[i] == 1)){
                    evts.emplace_back(common_l,
                        evt_type);
                    evts.emplace_back(pts[0].x,
                        -evt_type);
                }
                yl = k[i] * common_r + b[i], yl1 =
                    k[j] * common_r + b[j];
                if(lt(yl1, yl) == (segtype[i] == 1)){
                    evts.emplace_back(pts[0].x,
                        evt_type);
                    evts.emplace_back(common_r,
                        -evt_type);
                }
            }
            else{
                if(segtype[j] != segtype[i] || j >
                    i){
                    evts.emplace_back(common_l, -2);
                    evts.emplace_back(common_r, 2);
                }
            }
        }
        evts.emplace_back(l, 0);
        sort(evts.begin(), evts.end());
        size_t j = 0;
        int balance = 0;
        while(j < evts.size()){
            size_t ptr = j;
            while(ptr < evts.size() &&
                eq(evts[j].first, evts[ptr].first)){
                balance += evts[ptr].second;
                ++ptr;
            }
            if(!balance && !eq(evts[j].first, r)){
                dbl next_x = ptr == evts.size() ? r
                    : evts[ptr].first;
                ans -= segtype[i] * (k[i] * (next_x
                    + evts[j].first) + 2 * b[i]) *
                    (next_x - evts[j].first);
            }
            j = ptr;
        }
    }
    return ans/2;
}

int main()
{
    return 0;
}
```

5 Graph

5.1 Articulation Vertex

```
int n; // number of nodes
vector<vector<int>> adj; // adjacency list of graph

vector<bool> visited;
vector<int> tin, low;
int timer;

void dfs(int v, int p = -1) {
    visited[v] = true;
    tin[v] = low[v] = timer++;
    int children=0;
    for (int to : adj[v]) {
        if (to == p) continue;
        if (visited[to]) {
            low[v] = min(low[v], tin[to]);
        } else {
            dfs(to, v);
            low[v] = min(low[v], low[to]);
            if (low[to] >= tin[v] && p!=-1)
                IS_CUTPOINT(v);
            ++children;
        }
    }
    if(p == -1 && children > 1)
        IS_CUTPOINT(v);
}

void find_cutpoints() {
    timer = 0;
    visited.assign(n, false);
    tin.assign(n, -1);
    low.assign(n, -1);
    for (int i = 0; i < n; ++i) {
        if (!visited[i])
            dfs (i);
    }
}
```

5.2 Strongly Connected Components

```
vector<vector<int>> adj, adj_rev;
vector<bool> used;
vector<int> order, component;

void dfs1(int v) {
    used[v] = true;

    for (auto u : adj[v])
        if (!used[u])
            dfs1(u);

    order.push_back(v);
}

void dfs2(int v) {
    used[v] = true;
    component.push_back(v);

    for (auto u : adj_rev[v])
        if (!used[u])
            dfs2(u);
}

int main() {
    int n;
    // ... read n ...
```

```
    for (;;) {
        int a, b;
        // ... read next directed edge (a,b) ...
        adj[a].push_back(b);
        adj_rev[b].push_back(a);
    }

    used.assign(n, false);

    for (int i = 0; i < n; i++)
        if (!used[i])
            dfs1(i);

    used.assign(n, false);
    reverse(order.begin(), order.end());

    for (auto v : order)
        if (!used[v]) {
            dfs2 (v);

            // ... processing next component ...

            component.clear();
        }
}
```

6 Math

6.1 Combinatrics

```
#include<bits/stdc++.h>
using namespace std;
#define MAX 100000
#define MOD 1000000007
long long int fact[MAX+1],fact_inv[MAX+1];
long long int gcd(long long int a,long long int b)
{
    if(b==0) return a;
    else return gcd(b,a%b);
}
long long int egcd(long long int a, long long int
    b, long long int & x, long long int & y) {
    if (a == 0) {
        x = 0;
        y = 1;
        return b;
    }
    long long int x1, y1;
    long long int d = egcd(b % a, a, x1, y1);
    x = y1 - (b / a) * x1;
    y = x1;
    return d;
}
long long int ModuloInverse(long long int a,long
    long int n)
{
    long long int x,y;
    x=gcd(a,n);
    a=a/x;
    n=n/x;
    long long int res = egcd(a,n,x,y);
    x=(x%n+n)%n;
    return x;
}
void precal()
{
    int i;
    fact[0]=fact_inv[0]=1;
    for(i=1;i<=MAX;i++)
    {
        fact[i]=(fact[i-1]*i)%MOD;

    }
    i=MAX;
    fact_inv[i]=ModuloInverse(fact[i],MOD);
    for(i=MAX-1;i>0;i--)
    {
        fact_inv[i]=(fact_inv[i+1]*(i+1))%MOD;
    }
}
long long int C(int n,int r)
{
    long long int res=fact[n];
    res=(res*fact_inv[n-r])%MOD;
    res=(res*fact_inv[r])%MOD;
    return res;
}
int main()
{
    precal();
    while(true)
    {
        int n,r;
        scanf("%d %d",&n,&r);
        long long int res=C(n,r);
        long long int mod_inv=ModuloInverse(n,MOD);
        printf("%lld %lld\n",res,mod_inv);
    }
    return 0;
}
```

6.2 Discrete Root

```
#include<bits/stdc++.h>
#include<math.h>
using namespace std;
#define MAX 100000
int prime[MAX+1],Phi[MAX+1];
void sieve()
{
    int i,j;
    for(i=2; i*i<=MAX; i++)
    {
        if(prime[i]) continue;
        for(j=i; j*i<=MAX; j++)
        {
            if(prime[i*j]==0) prime[i*j]=i;
        }
    }
}
void PhiWithSieve()
{
    int i;
    for(i=2; i<=MAX; i++)
    {
        if(prime[i]==0)
        {
            Phi[i]=i-1;
        }
        else if((i/prime[i])%prime[i]==0)
        {
            Phi[i]=Phi[i/prime[i]]*prime[i];
        }
        else
        {
            Phi[i]=Phi[i/prime[i]]*(prime[i]-1);
        }
    }
}
int gcd(int a,int b)
{
    if(b==0) return a;
    else return gcd(b,a%b);
}
int powmod (int a, int b, int p) {
    int res = 1;
    while (b)
        if (b & 1)
            res = int (res * 1ll * a % p), --b;
        else
            a = int (a * 1ll * a % p), b >>= 1;
    return res;
}
int PrimitiveRoot(int p)
{
    vector<int>fact;
    int phi=Phi[p];
    int n=phi;
    while(n>1)
    {
        if(prime[n]==0)
        {
            fact.push_back(n);
            n=1;
        }
        else
        {
            int f=prime[n];
            while(n%f==0)
            {
                n=n/f;
            }
            fact.push_back(f);
        }
    }
    int res;
    for(res=p-1; res>1; --res)
    {
        for(n=0; n<fact.size(); n++)
        {
            if(powmod(res,phi/fact[n],p)==1)
            {
                break;
            }
        }
        if(n>=fact.size()) return res;
    }
    return -1;
}
int DiscreteLog(int a, int b, int m) {
    a %= m, b %= m;
    int n = sqrt(m) + 1;
    map<int, int> vals;
```

```
    for (int p = 1; p <= n; ++p)
        vals[powmod(a,(int) (1ll* p * n) %m , m)] =
            p;
    for (int q = 0; q <= n; ++q) {
        int cur = (powmod(a, q, m) * 1ll * b) % m;
        if (vals.count(cur)) {
            int ans = vals[cur] * n - q;
            return ans;
        }
    }
    return -1;
}
vector<int> DiscreteRoot(int n,int a,int k)
{
    int g = PrimitiveRoot(n);
    vector<int> ans;
    int any_ans = DiscreteLog(powmod(g,k,n),a,n);
    if (any_ans == -1)
    {
        return ans;
    }
    int delta = (n-1) / gcd(k, n-1);
    for (int cur = any_ans % delta; cur < n-1; cur
        += delta)
        ans.push_back(powmod(g, cur, n));
    sort(ans.begin(), ans.end());
    return ans;
}
```

6.3 Fast Fourier Transform

```
#include <bits/stdc++.h>
using namespace std;

#define MOD 1000000007
#define MAX 200005
#define PMAX 55
#define PRECISION 0.000001
#define INF 2000000000
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>

//////////////////////////////////////////////////////////////////////////////////
using cd = complex<double>;
const double PI = acos(-1);

void fft(vector<cd>& a, bool invert)
{
    int n = a.size();
    for(int i = 1, j = 0; i < n; i++){
        int bit = n>>1;
        for(; j&bit; bit>>=1){
            j^=bit;
        }
        j ^= bit;
        if(i < j)
            swap(a[i], a[j]);
    }

    for(int len = 2; len <= n; len <<= 1){
        double ang = 2*PI/len*(invert ? -1 : 1);
        cd wlen(cos(ang), sin(ang));
        for(int i = 0; i < n; i += len){
            cd w(1);
            for(int j = 0; j < len/2; j++){
                cd u = a[i+j], v = a[i+j+len/2]*w;
                a[i+j] = u+v;
                a[i+j+len/2] = u-v;
                w *= wlen;
            }
        }
    }

    if(invert){
        for(cd &x: a)
            x /= n;
    }
}
vector<int> multiply(vector<int> const& a,
    vector<int> const&b)
{
    vector<cd> fa(a.begin(), a.end());
    vector<cd> fb(b.begin(), b.end());
    int n = 1;
    while(n < a.size()+b.size())
        n <<= 1;
    fa.resize(n);
    fb.resize(n);
    fft(fa, false);
    fft(fb, false);

    for(int i = 0; i < n; i++)
        fa[i] *= fb[i];

    fft(fa, true);

    vector<int> result(n);
    for(int i = 0; i < n; i++)
        result[i] = round(fa[i].real());
    return result;
}
//Number Theoretic Transformation
/*
long long int gcd(long long int a,long long int b)
{
    if(b==0) return a;
    else return gcd(b,a%b);
}
//////////////////////////////////////////////////////////////////////////////////
long long int egcd(long long int a, long long int
    b, long long int & x, long long int & y) {
    if (a == 0) {
        x = 0;
        y = 1;
        return b;
    }
    long long int x1, y1;
    long long int d = egcd(b % a, a, x1, y1);
    x = y1 - (b / a) * x1;
    y = x1;
    return d;
}
long long int ModuloInverse(long long int a,long
    long int n)
{
    long long int x,y;
    x=gcd(a,n);
    a=a/x;
    n=n/x;
    long long int res = egcd(a,n,x,y);
    x=(x%n+n)%n;
    return x;
}

const int mod = 998244353;
const int root = 15311432;
const int root_1 = 469870224;
const int root_pw = 1 << 23;
void fft(vector<int> & a, bool invert) {
    int n = a.size();

    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for (; j & bit; bit >>= 1)
            j ^= bit;
        j ^= bit;

        if (i < j)
            swap(a[i], a[j]);
    }

    for (int len = 2; len <= n; len <<= 1) {
        int wlen = invert ? root_1 : root;
        for (int i = len; i < root_pw; i <<= 1)
            wlen = (int)(1LL * wlen * wlen % mod);

        for (int i = 0; i < n; i += len) {
            int w = 1;
            for (int j = 0; j < len / 2; j++) {
                int u = a[i+j], v = (int)(1LL *
                    a[i+j+len/2] * w % mod);
                a[i+j] = u + v < mod ? u + v : u + v
                    - mod;
                a[i+j+len/2] = u - v >= 0 ? u - v :
                    u - v + mod;
                w = (int)(1LL * w * wlen % mod);
            }
        }
    }

    if (invert) {
        int n_1 = (int) ModuloInverse(n, mod);
        for (int & x : a)
            x = (int)(1LL * x * n_1 % mod);
    }
}

vector<int> multiply(vector<int> const& a,
    vector<int> const&b)
{
    vector<int> fa(a.begin(), a.end());
    vector<int> fb(b.begin(), b.end());
    int n = 1;
    while(n < a.size()+b.size())
        n <<= 1;
    fa.resize(n);
    fb.resize(n);
    fft(fa, false);
    fft(fb, false);

    for(int i = 0; i < n; i++)
        fa[i] = (int) (1LL*fa[i]*fb[i]%mod);

    fft(fa, true);
```

```
    vector<int> result(n);
    for(int i = 0; i < n; i++)
        result[i] = fa[i];
    return result;
}
*/
////////////////////////////////////////////////////////////////////////////////
```

6.4 Polynomial Algebra

```
#include <bits/stdc++.h>

using namespace std;
namespace algebra {
        const int inf = 1e9;
        const int magic = 500; // threshold for
            sizes to run the naive algo

        namespace fft {
                const int maxn = 1 << 18;

                typedef double ftype;
                typedef complex<ftype> point;

                point w[maxn];
                const ftype pi = acos(-1);
                bool initiated = 0;
                void init() {
                        if(!initiated) {
                                for(int i = 1; i <
                                    maxn; i *= 2) {
                                        for(int j = 0;
                                            j < i; j++)
                                            {
                                                w[i +
                                                    j] =
                                                    polar(ftype(1),
                                                    pi *
                                                    j /
                                                    i);
                                            }
                                }
                                initiated = 1;
                        }
                }
                template<typename T>
                void fft(T *in, point *out, int n,
                    int k = 1) {
                        if(n == 1) {
                                *out = *in;
                        } else {
                                n /= 2;
                                fft(in, out, n, 2 * k);
                                fft(in + k, out + n,
                                    n, 2 * k);
                                for(int i = 0; i < n;
                                    i++) {
                                        auto t = out[i
                                            + n] * w[i
                                            + n];
                                        out[i + n] =
                                            out[i] - t;
                                        out[i] += t;
                                }
                        }
                }

                template<typename T>
                void mul_slow(vector<T> &a, const
                    vector<T> &b) {
                        vector<T> res(a.size() +
                            b.size() - 1);
                        for(size_t i = 0; i <
                            a.size(); i++) {
                                for(size_t j = 0; j <
                                    b.size(); j++) {
                                        res[i + j] +=
                                            a[i] * b[j];
                                }
                        }
                        a = res;
                }

                template<typename T>
                void mul(vector<T> &a, const
                    vector<T> &b) {
                        if(min(a.size(), b.size()) <
                            magic) {
                                mul_slow(a, b);
                                return;
                        }
                        init();
                        static const int shift = 15,
                            mask = (1 << shift) - 1;
                        size_t n = a.size() +
                            b.size() - 1;
                        while(__builtin_popcount(n)
                            != 1) {
                                n++;
                        }
                        a.resize(n);
                        static point A[maxn], B[maxn];
                        static point C[maxn], D[maxn];
                        for(size_t i = 0; i < n; i++)
                            {
                                A[i] = point(a[i] &
                                    mask, a[i] >>
                                    shift);
                                if(i < b.size()) {
                                        B[i] =
                                            point(b[i]
                                            & mask,
                                            b[i] >>
                                            shift);
                                } else {
                                        B[i] = 0;
                                }
                        }
                        fft(A, C, n); fft(B, D, n);
                        for(size_t i = 0; i < n; i++)
                            {
                                point c0 = C[i] +
                                    conj(C[(n - i) %
                                    n]);
                                point c1 = C[i] -
                                    conj(C[(n - i) %
                                    n]);
                                point d0 = D[i] +
                                    conj(D[(n - i) %
                                    n]);
                                point d1 = D[i] -
                                    conj(D[(n - i) %
                                    n]);
                                A[i] = c0 * d0 -
                                    point(0, 1) * c1 *
                                    d1;
                                B[i] = c0 * d1 + d0 *
                                    c1;
                        }
                        fft(A, C, n); fft(B, D, n);
                        reverse(C + 1, C + n);
                        reverse(D + 1, D + n);
                        int t = 4 * n;
                        for(size_t i = 0; i < n; i++)
                            {
                                int64_t A0 =
                                    llround(real(C[i])
                                    / t);
                                T A1 =
                                    llround(imag(D[i])
                                    / t);
                                T A2 =
                                    llround(imag(C[i])
                                    / t);
                                a[i] = A0 + (A1 <<
                                    shift) + (A2 << 2
                                    * shift);
                        }
                        return;
                }
        }
        template<typename T>
        T bpow(T x, size_t n) {
                return n ? n % 2 ? x * bpow(x, n -
                    1) : bpow(x * x, n / 2) : T(1);
        }
        template<typename T>
        T bpow(T x, size_t n, T m) {
                return n ? n % 2 ? x * bpow(x, n -
                    1, m) % m : bpow(x * x % m, n /
                    2, m) : T(1);
        }
        template<typename T>
        T gcd(const T &a, const T &b) {
                return b == T(0) ? a : gcd(b, a % b);
        }
        template<typename T>
        T nCr(T n, int r) { // runs in O(r)
                T res(1);
                for(int i = 0; i < r; i++) {
                        res *= (n - T(i));
                        res /= (i + 1);
                }
                return res;
        }

        template<int m>
        struct modular {
                int64_t r;
                modular() : r(0) {}
```

```
        modular(int64_t rr) : r(rr)
            {if(abs(r) >= m) r %= m; if(r <
            0) r += m;}
        modular inv() const {return
            bpow(*this, m - 2);}
        modular operator * (const modular
            &t) const {return (r * t.r) % m;}
        modular operator / (const modular
            &t) const {return *this *
            t.inv();}
        modular operator += (const modular
            &t) {r += t.r; if(r >= m) r -=
            m; return *this;}
        modular operator -= (const modular
            &t) {r -= t.r; if(r < 0) r += m;
            return *this;}
        modular operator + (const modular
            &t) const {return modular(*this)
            += t;}
        modular operator - (const modular
            &t) const {return modular(*this)
            -= t;}
        modular operator *= (const modular
            &t) {return *this = *this * t;}
        modular operator /= (const modular
            &t) {return *this = *this / t;}

        bool operator == (const modular &t)
            const {return r == t.r;}
        bool operator != (const modular &t)
            const {return r != t.r;}

        operator int64_t() const {return r;}
};
template<int T>
istream& operator >> (istream &in,
    modular<T> &x) {
        return in >> x.r;
}

template<typename T>
struct poly {
        vector<T> a;

        void normalize() { // get rid of
            leading zeroes
                while(!a.empty() && a.back()
                    == T(0)) {
                        a.pop_back();
                }
        }

        poly(){}
        poly(T a0) : a{a0}{normalize();}
        poly(vector<T> t) :
            a(t){normalize();}

        poly operator += (const poly &t) {
                a.resize(max(a.size(),
                    t.a.size()));
                for(size_t i = 0; i <
                    t.a.size(); i++) {
                        a[i] += t.a[i];
                }
                normalize();
                return *this;
        }
        poly operator -= (const poly &t) {
                a.resize(max(a.size(),
                    t.a.size()));
                for(size_t i = 0; i <
                    t.a.size(); i++) {
                        a[i] -= t.a[i];
                }
                normalize();
                return *this;
        }
        poly operator + (const poly &t)
            const {return poly(*this) += t;}
        poly operator - (const poly &t)
            const {return poly(*this) -= t;}

        poly mod_xk(size_t k) const { // get
            same polynomial mod x^k
                k = min(k, a.size());
                return vector<T>(begin(a),
                    begin(a) + k);
        }
        poly mul_xk(size_t k) const { //
            multiply by x^k
                poly res(*this);
                res.a.insert(begin(res.a), k,
                    0);
                return res;
        }
        poly div_xk(size_t k) const { //
            divide by x^k, dropping
            coefficients
                k = min(k, a.size());
                return vector<T>(begin(a) +
                    k, end(a));
        }
        poly substr(size_t l, size_t r)
            const { // return
            mod_xk(r).div_xk(l)
                l = min(l, a.size());
                r = min(r, a.size());
                return vector<T>(begin(a) +
                    l, begin(a) + r);
        }
        poly inv(size_t n) const { // get
            inverse series mod x^n
                assert(!is_zero());
                poly ans = a[0].inv();
                size_t a = 1;
                while(a < n) {
                        poly C = (ans *
                            mod_xk(2 *
                            a)).substr(a, 2 *
                            a);
                        ans -= (ans *
                            C).mod_xk(a).mul_xk(a);
                        a *= 2;
                }
                return ans.mod_xk(n);
        }
        poly operator *= (const poly &t)
            {fft::mul(a, t.a); normalize();
            return *this;}
        poly operator * (const poly &t)
            const {return poly(*this) *= t;}

        poly reverse(size_t n, bool rev = 0)
            const { // reverses and leaves
            only n terms
                poly res(*this);
                if(rev) { // If rev = 1 then
                    tail goes to head
                        res.a.resize(max(n,
                            res.a.size()));
                }
                std::reverse(res.a.begin(),
                    res.a.end());
                return res.mod_xk(n);
        }

        pair<poly, poly> divmod_slow(const
            poly &b) const { // when divisor
            or quotient is small
                vector<T> A(a);
                vector<T> res;
                while(A.size() >= b.a.size())
                    {
                        res.push_back(A.back()
                            / b.a.back());
                        if(res.back() != T(0))
                            {
                                for(size_t i =
                                    0; i <
                                    b.a.size();
                                    i++) {
                                        A[A.size()
                                            - i
                                            - 1]
                                            -=
                                            res.bac
                                            *
                                            b.a[b.a
                                            - i
                                            - 1];
                                }
                        }
                        A.pop_back();
                }
                std::reverse(begin(res),
                    end(res));
                return {res, A};
        }

        pair<poly, poly> divmod(const poly
            &b) const { // returns quotiend
            and remainder of a mod b
                if(deg() < b.deg()) {
                        return {poly{0},
                            *this};
                }
                int d = deg() - b.deg();
                if(min(d, b.deg()) < magic) {
                        return divmod_slow(b);
                }
```

```
        poly D = (reverse(d + 1) *
            b.reverse(d + 1).inv(d +
            1)).mod_xk(d +
            1).reverse(d + 1, 1);
        return {D, *this - D * b};
}

poly operator / (const poly &t)
    const {return divmod(t).first;}
poly operator % (const poly &t)
    const {return divmod(t).second;}
poly operator /= (const poly &t)
    {return *this = divmod(t).first;}
poly operator %= (const poly &t)
    {return *this =
    divmod(t).second;}
poly operator *= (const T &x) {
        for(auto &it: a) {
                it *= x;
        }
        normalize();
        return *this;
}
poly operator /= (const T &x) {
        for(auto &it: a) {
                it /= x;
        }
        normalize();
        return *this;
}
poly operator * (const T &x) const
    {return poly(*this) *= x;}
poly operator / (const T &x) const
    {return poly(*this) /= x;}

void print() const {
        for(auto it: a) {
                cout << it << ' ';
        }
        cout << endl;
}
T eval(T x) const { // evaluates in
    single point x
        T res(0);
        for(int i = int(a.size()) -
            1; i >= 0; i--) {
                res *= x;
                res += a[i];
        }
        return res;
}

T& lead() { // leading coefficient
        return a.back();
}
int deg() const { // degree
        return a.empty() ? -inf :
            a.size() - 1;
}
bool is_zero() const { // is
    polynomial zero
        return a.empty();
}
T operator [](int idx) const {
        return idx >= (int)a.size()
            || idx < 0 ? T(0) :
            a[idx];
}

T& coef(size_t idx) { // mutable
    reference at coefficient
        return a[idx];
}
bool operator == (const poly &t)
    const {return a == t.a;}
bool operator != (const poly &t)
    const {return a != t.a;}

poly deriv() { // calculate
    derivative
        vector<T> res;
        for(int i = 1; i <= deg();
            i++) {
                res.push_back(T(i) *
                    a[i]);
        }
        return res;
}
poly integr() { // calculate
    integral with C = 0
        vector<T> res = {0};
        for(int i = 0; i <= deg();
            i++) {
                res.push_back(a[i] /
                    T(i + 1));
        }
        return res;
}
size_t leading_xk() const { // Let
    p(x) = x^k * t(x), return k
        if(is_zero()) {
                return inf;
        }
        int res = 0;
        while(a[res] == T(0)) {
                res++;
        }
        return res;
}
poly log(size_t n) { // calculate
    log p(x) mod x^n
        assert(a[0] == T(1));
        return (deriv().mod_xk(n) *
            inv(n)).integr().mod_xk(n);
}
poly exp(size_t n) { // calculate
    exp p(x) mod x^n
        if(is_zero()) {
                return T(1);
        }
        assert(a[0] == T(0));
        poly ans = T(1);
        size_t a = 1;
        while(a < n) {
                poly C = ans.log(2 *
                    a).div_xk(a) -
                    substr(a, 2 * a);
                ans -= (ans *
                    C).mod_xk(a).mul_xk(a
                a *= 2;
        }
        return ans.mod_xk(n);
}
poly pow_slow(size_t k, size_t n) {
    // if k is small
        return k ? k % 2 ? (*this *
            pow_slow(k - 1,
            n)).mod_xk(n) : (*this *
            *this).mod_xk(n).pow_slow(k
            / 2, n) : T(1);
}
poly pow(size_t k, size_t n) { //
    calculate p^k(n) mod x^n
        if(is_zero()) {
                return *this;
        }
        if(k < magic) {
                return pow_slow(k, n);
        }
        int i = leading_xk();
        T j = a[i];
        poly t = div_xk(i) / j;
        return bpow(j, k) * (t.log(n)
            * T(k)).exp(n).mul_xk(i *
            k).mod_xk(n);
}
poly mulx(T x) { // component-wise
    multiplication with x^k
        T cur = 1;
        poly res(*this);
        for(int i = 0; i <= deg();
            i++) {
                res.coef(i) *= cur;
                cur *= x;
        }
        return res;
}
poly mulx_sq(T x) { //
    component-wise multiplication
    with x^{k^2}
        T cur = x;
        T total = 1;
        T xx = x * x;
        poly res(*this);
        for(int i = 0; i <= deg();
            i++) {
                res.coef(i) *= total;
                total *= cur;
                cur *= xx;
        }
        return res;
}
vector<T> chirpz_even(T z, int n) {
    // P(1), P(z^2), P(z^4), ...,
    P(z^2(n-1))
        int m = deg();
        if(is_zero()) {
                return vector<T>(n, 0);
        }
        vector<T> vv(m + n);
```

```
        T zi = z.inv();
        T zz = zi * zi;
        T cur = zi;
        T total = 1;
        for(int i = 0; i <= max(n -
            1, m); i++) {
            if(i <= m) {vv[m - i]
                = total;}
            if(i < n) {vv[m + i] =
                total;}
            total *= cur;
            cur *= zz;
        }
        poly w = (mulx_sq(z) *
            vv).substr(m, m +
            n).mulx_sq(z);
        vector<T> res(n);
        for(int i = 0; i < n; i++) {
            res[i] = w[i];
        }
        return res;
}
vector<T> chirpz(T z, int n) { //
    P(1), P(z), P(z^2), ...,
    P(z^(n-1))
        auto even = chirpz_even(z, (n
            + 1) / 2);
        auto odd =
            mulx(z).chirpz_even(z, n
            / 2);
        vector<T> ans(n);
        for(int i = 0; i < n / 2;
            i++) {
            ans[2 * i] = even[i];
            ans[2 * i + 1] =
                odd[i];
        }
        if(n % 2 == 1) {
            ans[n - 1] =
                even.back();
        }
        return ans;
}
template<typename iter>
vector<T> eval(vector<poly> &tree,
    int v, iter l, iter r) { //
    auxiliary evaluation function
        if(r - l == 1) {
            return {eval(*l)};
        } else {
            auto m = l + (r - l) /
                2;
            auto A = (*this %
                tree[2 *
                v]).eval(tree, 2 *
                v, l, m);
            auto B = (*this %
                tree[2 * v +
                1]).eval(tree, 2 *
                v + 1, m, r);
            A.insert(end(A),
                begin(B), end(B));
            return A;
        }
    }
    vector<T> eval(vector<T> x) { //
        evaluate polynomial in (x1, ...,
        xn)
            int n = x.size();
            if(is_zero()) {
                return vector<T>(n,
                    T(0));
            }
            vector<poly> tree(4 * n);
            build(tree, 1, begin(x),
                end(x));
            return eval(tree, 1,
                begin(x), end(x));
    }
    template<typename iter>
    poly inter(vector<poly> &tree, int
        v, iter l, iter r, iter ly, iter
        ry) { // auxiliary interpolation
        function
            if(r - l == 1) {
                return {*ly / a[0]};
            } else {
                auto m = l + (r - l) /
                    2;
                auto my = ly + (ry -
                    ly) / 2;
                auto A = (*this %
                    tree[2 *
                    v]).inter(tree, 2
                    * v, l, m, ly, my);
                auto B = (*this %
                    tree[2 * v +
                    1]).inter(tree, 2
                    * v + 1, m, r, my,
                    ry);
                return A * tree[2 * v
                    + 1] + B * tree[2
                    * v];
            }
        }
};
template<typename T>
poly<T> operator * (const T& a, const
    poly<T>& b) {
        return b * a;
}

template<typename T>
poly<T> xk(int k) { // return x^k
        return poly<T>{1}.mul_xk(k);
}

template<typename T>
T resultant(poly<T> a, poly<T> b) { //
    computes resultant of a and b
        if(b.is_zero()) {
            return 0;
        } else if(b.deg() == 0) {
            return bpow(b.lead(),
                a.deg());
        } else {
            int pw = a.deg();
            a %= b;
            pw -= a.deg();
            T mul = bpow(b.lead(), pw) *
                T((b.deg() & a.deg() & 1)
                ? -1 : 1);
            T ans = resultant(b, a);
            return ans * mul;
        }
    }
    template<typename iter>
    poly<typename iter::value_type> kmul(iter
        L, iter R) { // computes
        (x-a1)(x-a2)...(x-an) without building
        tree
            if(R - L == 1) {
                return vector<typename
                    iter::value_type>{-*L, 1};
            } else {
                iter M = L + (R - L) / 2;
                return kmul(L, M) * kmul(M,
                    R);
            }
    }
    template<typename T, typename iter>
    poly<T> build(vector<poly<T>> &res, int v,
        iter L, iter R) { // builds evaluation
        tree for (x-a1)(x-a2)...(x-an)
            if(R - L == 1) {
                return res[v] =
                    vector<T>{-*L, 1};
            } else {
                iter M = L + (R - L) / 2;
                return res[v] = build(res, 2
                    * v, L, M) * build(res, 2
                    * v + 1, M, R);
            }
    }
    template<typename T>
    poly<T> inter(vector<T> x, vector<T> y) {
        // interpolates minimum polynomial from
        (xi, yi) pairs
            int n = x.size();
            vector<poly<T>> tree(4 * n);
            return build(tree, 1, begin(x),
                end(x)).deriv().inter(tree, 1,
                begin(x), end(x), begin(y),
                end(y));
    }
};

using namespace algebra;

const int mod = 1e9 + 7;
typedef modular<mod> base;
typedef poly<base> polyn;

using namespace algebra;

signed main() {
    ios::sync_with_stdio(0);
    cin.tie(0);
    int n = 100000;
    polyn a;
    vector<base> x;
```

```
        for(int i = 0; i <= n; i++) {
                a.a.push_back(1 + rand() % 100);
                x.push_back(1 + rand() % (2 * n));
        }
        sort(begin(x), end(x));
        x.erase(unique(begin(x), end(x)), end(x));
        auto b = a.eval(x);
        cout << clock() / double(CLOCKS_PER_SEC) <<
            endl;
        auto c = inter(x, b);
        polyn md = kmul(begin(x), end(x));
        cout << clock() / double(CLOCKS_PER_SEC) <<
            endl;
        assert(c == a % md);
        return 0;
}
```

7 String

7.1 Aho Corasick

```
const int K = 26;

struct Vertex {
    int next[K];
    bool leaf = false;
    int p = -1;
    char pch;
    int link = -1;
    int go[K];

    Vertex(int p=-1, char ch='$') : p(p), pch(ch) {
        fill(begin(next), end(next), -1);
        fill(begin(go), end(go), -1);
    }
};

vector<Vertex> t(1);

void add_string(string const& s) {
    int v = 0;
    for (char ch : s) {
        int c = ch - 'a';
        if (t[v].next[c] == -1) {
            t[v].next[c] = t.size();
            t.emplace_back(v, ch);
        }
        v = t[v].next[c];
    }
    t[v].leaf = true;
}

int go(int v, char ch);

int get_link(int v) {
    if (t[v].link == -1) {
        if (v == 0 || t[v].p == 0)
            t[v].link = 0;
        else
            t[v].link = go(get_link(t[v].p),
                t[v].pch);
    }
    return t[v].link;
}

int go(int v, char ch) {
    int c = ch - 'a';
    if (t[v].go[c] == -1) {
        if (t[v].next[c] != -1)
            t[v].go[c] = t[v].next[c];
        else
            t[v].go[c] = v == 0 ? 0 :
                go(get_link(v), ch);
    }
    return t[v].go[c];
}
```

7.2 Manacher's Algorithm

```
#include<bits/stdc++.h>
#include<vector>
using namespace std;
int main()
{
    int T,l;
    char s[MAX];
    gets(s);
    int n=strlen(s);
    vector<int> d1(n);
    for (int i = 0, l = 0, r = -1; i < n; i++)
    {
        int k = (i > r) ? 1 : min(d1[l + r - i], r
            - i + 1);
        while (0 <= i - k && i + k < n && s[i - k]
            == s[i + k])
        {
            k++;
        }
        d1[i] = k--;
        if (i + k > r)
        {
            l = i - k;
            r = i + k;
        }
    }
    vector<int> d2(n);
    for (int i = 0, l = 0, r = -1; i < n; i++)
    {
        int k = (i > r) ? 0 : min(d2[l + r - i +
            1], r - i + 1);
        while (0 <= i - k - 1 && i + k < n && s[i -
            k - 1] == s[i + k])
        {
            k++;
        }
        d2[i] = k--;
        if (i + k > r)
        {
            l = i - k - 1;
            r = i + k ;
        }
    }
    return 0;
}
```

7.3 Suffix Array

```
#include<bits/stdc++.h>
#include<string.h>
using namespace std;
#define MAX 100000
vector<int> sort_cyclic_shifts(char *s) {
    int n = strlen(s);
    const int alphabet = 256;
    vector<int> p(n), c(n), cnt(max(alphabet, n),
        0);
    for (int i = 0; i < n; i++)
        cnt[s[i]]++;
    for (int i = 1; i < alphabet; i++)
        cnt[i] += cnt[i-1];
    for (int i = 0; i < n; i++)
        p[--cnt[s[i]]] = i;
    c[p[0]] = 0;
    int classes = 1;
    for (int i = 1; i < n; i++) {
        if (s[p[i]] != s[p[i-1]])
            classes++;
        c[p[i]] = classes - 1;
    }
    vector<int> pn(n), cn(n);
    for (int h = 0; (1 << h) < n; ++h) {
        for (int i = 0; i < n; i++) {
            pn[i] = p[i] - (1 << h);
            if (pn[i] < 0)
                pn[i] += n;
        }
        fill(cnt.begin(), cnt.begin() + classes, 0);
        for (int i = 0; i < n; i++)
            cnt[c[pn[i]]]++;
        for (int i = 1; i < classes; i++)
            cnt[i] += cnt[i-1];
        for (int i = n-1; i >= 0; i--)
            p[--cnt[c[pn[i]]]] = pn[i];
        cn[p[0]] = 0;
        classes = 1;
        for (int i = 1; i < n; i++) {
            int ind=p[i] + (1 << h);
            if(ind>=n) ind=ind-n;
            pair<int, int> cur = {c[p[i]], c[ind]};
            ind=p[i-1] + (1 << h);
            if(ind>=n) ind=ind-n;
            pair<int, int> prev = {c[p[i-1]],
                c[ind]};
            if (cur != prev)
                ++classes;
            cn[p[i]] = classes - 1;
        }
        c.swap(cn);
    }
    return p;
}
vector<int> suffix_array_construction(char *s) {
    int n=strlen(s);
    s[n]='#';
    vector<int> sorted_shifts =
        sort_cyclic_shifts(s);
    sorted_shifts.erase(sorted_shifts.begin());
    return sorted_shifts;
}
vector<int> lcp_construction(char *s, vector<int>
    const& p) {
    int n = strlen(s);
    vector<int> rank(n, 0);
    for (int i = 0; i < n; i++)
```

```
        rank[p[i]] = i;

    int k = 0;
    vector<int> lcp(n-1, 0);
    for (int i = 0; i < n; i++) {
        if (rank[i] == n - 1) {
            k = 0;
            continue;
        }
        int j = p[rank[i] + 1];
        while (i + k < n && j + k < n && s[i+k] ==
            s[j+k])
            k++;
        lcp[rank[i]] = k;
        if (k)
            k--;
    }
    return lcp;
}
int lcp(int i, int j) {
    int ans = 0;
    for (int k = log_n; k >= 0; k--) {
        if (c[k][i] == c[k][j]) {
            ans += 1 << k;
            i += 1 << k;
            j += 1 << k;
        }
    }
    return ans;
}
```

7.4 Suffix Automaton

```
#include <bits/stdc++.h>
#include <vector>
#include<math.h>
#include<string.h>
using namespace std;
#define MAX 300005
#define BEGIN 1
#define MOD 1000000007
#define INF 1000000000000000000
#define EPS 0.0000000001
#define CHAINS 18
#define NOT_VISITED 0
#define VISITING 1
#define VISITED 2
#define FASTIO
    ios_base::sync_with_stdio(false);cin.tie(NULL)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
#include <ext/pb_ds/detail/standard_policies.hpp>
class SuffixAutomaton
{
    bool complete;
    int last;
    set<char> alphabet;
    struct state
    {
        int len, link, endpos,
            first_pos,shortest_non_appearing_string,height;
        long long substrings,length_of_substrings;
        bool is_clone;
        map<char, int> next;
        vector<int> inv_link;
        state(int leng=0,int li=0)
        {
            len=leng;
            link=li;
            first_pos=-1;
            substrings=0;
            length_of_substrings=0;
            endpos=1;
            shortest_non_appearing_string=0;
            is_clone=false;
            height=0;
        }
    };
    vector<state> st;
    void process(int node)
    {
        map<char, int> ::iterator mit;
        st[node].substrings=1;
        st[node].shortest_non_appearing_string=st.size();
        if((int) st[node].next.size()<(int)
            alphabet.size())
            st[node].shortest_non_appearing_string=1;
        for(mit=st[node].next.begin();
            mit!=st[node].next.end(); ++mit)
        {
            if(st[mit->second].substrings==0)
                process(mit->second);
            st[node].height=max(st[node].height,1+st[mit->second].height);
            st[node].substrings=st[node].substrings+st[mit->second].substrings;
            st[node].length_of_substrings=st[node].length_of_substrings+st[mit->second].length_of_substrings
            st[node].shortest_non_appearing_string=min(st[node].shortest_non_appearing_string,1+st[mit->second
        }
        if(st[node].link!=-1)
        {
            st[st[node].link].inv_link.push_back(node);
        }
    }
    void set_suffix_links(int node)
    {
        int i;
        for(i=0; i<st[node].inv_link.size(); i++)
        {
            set_suffix_links(st[node].inv_link[i]);
            st[node].endpos=st[node].endpos+st[st[node].inv_link[i]].endpos;
        }
    }
    void output_all_occurrences(int v, int
        P_length,vector<int> &pos)
    {
        if (!st[v].is_clone)
            pos.push_back(st[v].first_pos - P_length
                + 1);
        for (int u : st[v].inv_link)
            output_all_occurrences(u, P_length, pos);
    }
    void kth_smallest(int node,int k,vector<char>
        &str)
    {
        if(k==0) return;
        map<char, int> ::iterator mit;
        for(mit=st[node].next.begin();
            mit!=st[node].next.end(); ++mit)
        {
            if(st[mit->second].substrings<k)
                k=k-st[mit->second].substrings;
            else
            {
                str.push_back(mit->first);
                kth_smallest(mit->second,k-1,str);
                return;
            }
        }
    }
    int find_occurrence_index(int node,int
        index,vector<char> &str)
    {
        if(index==str.size()) return node;
        if(!st[node].next.count(str[index])) return
            -1;
        else return
            find_occurrence_index(st[node].next[str[ind
    }
    void klen_smallest(int node,int k,vector<char>
        &str)
    {
        if(k==0) return;
        map<char, int> ::iterator mit;
        for(mit=st[node].next.begin();
            mit!=st[node].next.end(); ++mit)
        {
            if(st[mit->second].height>=k-1)
            {
                str.push_back(mit->first);
                klen_smallest(mit->second,k-1,str);
                return;
            }
        }
    }
    void minimum_non_existing_string(int
        node,vector<char> &str)
    {
        map<char, int> ::iterator mit;
        set<char>::iterator sit;
        for(mit=st[node].next.begin(),sit=alphabet.begi
            sit!=alphabet.end(); ++sit,++mit)
        {
            if(mit==st[node].next.end()||mit->first!=(*
            {
                str.push_back(*sit);
                return;
            }
            else
                if(st[node].shortest_non_appearing_stri
            {
                str.push_back(*sit);
                minimum_non_existing_string(mit->second
                return;
            }
        }
    }
    void find_substrings(int node,int
        index,vector<char> &str,vector<pair<long
        long,long long> > &sub_info)
    {
        sub_info.push_back(make_pair(st[node].substring
        if(index==str.size()) return;
```

```
        if(st[node].next.count(str[index]))
        {
            find_substrings(st[node].next[str[index]],index+1,str,sub_info);
            return;
        }
        else
        {
            sub_info.push_back(make_pair(0,0));
        }
    }
    void check()
    {
        if(!complete)
        {
            process(0);
            set_suffix_links(0);
            int i;
            complete=true;
        }
    }
public:
    SuffixAutomaton(set<char> &alpha)
    {
        st.push_back(state(0,-1));
        last=0;
        complete=false;
        set<char>::iterator sit;
        for(sit=alpha.begin(); sit!=alpha.end();
            sit++)
        {
            alphabet.insert(*sit);
        }
        st[0].endpos=0;
    }
    void sa_extend(char c)
    {
        int cur = st.size();
        //printf("New node (%d,%c)\n",cur,c);
        st.push_back(state(st[last].len + 1));
        st[cur].first_pos=st[cur].len-1;
        int p = last;
        while (p != -1 && !st[p].next.count(c))
        {
            st[p].next[c] = cur;
            //printf("Set edge %d -> %d
                (%c)\n",p,cur,c);
            p = st[p].link;
        }
        if (p == -1)
        {
            st[cur].link = 0;
            //printf("Set link %d -> %d\n",cur,0);
        }
        else
        {
            int q = st[p].next[c];
            if (st[p].len + 1 == st[q].len)
            {
                st[cur].link = q;
                //printf("Set link %d ->
                    %d\n",cur,q);
            }
            else
            {
                int clone = st.size();
                //printf("Create clone node %d from
                    %d\n",clone,q);
                //printf("Set link %d ->
                    %d\n",clone,st[q].link);
                st.push_back(state(st[p].len +
                    1,st[q].link));
                st[clone].next = st[q].next;
                st[clone].is_clone=true;
                st[clone].endpos=0;
                st[clone].first_pos=st[q].first_pos;
                while (p != -1 && st[p].next[c] == q)
                {
                    //printf("Change transition %d ->
                        %d : %d -> %d
                        (%c)\n",p,q,p,clone,c);
                    st[p].next[c] = clone;
                    p = st[p].link;
                }
                //printf("Change link %d -> %d : %d
                    -> %d\n",q,st[q].link,q,clone);
                //printf("Set link %d ->
                    %d\n",cur,clone);
                st[q].link = st[cur].link = clone;
            }
        }
        last = cur;
        complete=false;
    }
    ~SuffixAutomaton()
    {
        int i;
        for(i=0; i<st.size(); i++)
        {
            st[i].next.clear();
            st[i].inv_link.clear();
        }
        st.clear();
        alphabet.clear();
    }
    void kth_smallest(int k,vector<char> &str)
    {
        check();
        kth_smallest(0,k,str);
    }
    int FindFirstOccurrenceIndex(vector<char> &str)
    {
        check();
        int ind=find_occurrence_index(0,0,str);
        if(ind==0) return -1;
        else if(ind==-1) return st.size();
        else return st[ind].first_pos+1-(int)
            str.size();
    }
    void FindAllOccurrenceIndex(vector<char>
        &str,vector<int> &pos)
    {
        check();
        int ind=find_occurrence_index(0,0,str);
        if(ind!=-1)
            output_all_occurrences(ind,str.size(),pos);
    }
    int Occurrences(vector<char> &str)
    {
        check();
        int ind=find_occurrence_index(0,0,str);
        if(ind==0) return 1;
        else if(ind==-1) return 0;
        else return st[ind].endpos;
    }
    void klen_smallest(int k,vector<char> &str)
    {
        check();
        if(st[0].height>=k) klen_smallest(0,k,str);
    }
    void minimum_non_existing_string(vector<char>
        &str)
    {
        check();
        int ind=find_occurrence_index(0,0,str);
        if(ind!=-1)
            minimum_non_existing_string(ind,str);
    }
    long long cyclic_occurrence(vector<char> &str)
    {
        check();
        int i,j,len;
        long long ans=0;
        int n=str.size();
        set<int> S;
        set<int>::iterator it;
        for(i=0,j=0,len=0; i<n*2-1; i++)
        {
            //printf("%d->%c\n",i,str[i%n]);
            if(st[j].next.count(str[i%n]))
            {
                len++;
                j=st[j].next[str[i%n]];
            }
            else
            {
                while(j!=-1&&(!st[j].next.count(str[i%n
                {
                    j=st[j].link;
                }
                if(j!=-1)
                {
                    len=st[j].len+1;
                    j=st[j].next[str[i%n]];
                }
                else
                {
                    len=0;
                    j=0;
                }
            }
            while(st[j].link!=-1&&st[st[j].link].len>=n
            {
                j=st[j].link;
                len=st[j].len;
            }
            if(len>=n) S.insert(j);
        }
        for(it=S.begin();it!=S.end();++it)
```

```
        {
            ans=ans+st[*it].endpos;
        }
        return ans;
    }
};
vector<char> X;
int main()
{
    int i;
    set<char> alpha;
    for(i=0; i<26; i++)
    {
        alpha.insert('a'+i);
    }
    SuffixAutomaton sa(alpha);
    char c;
    for(i=0;; i++)
    {
        scanf("%c",&c);
        if(!('a'<=c&&c<='z')) break;
        sa.sa_extend(c);
    }
    int n,j;
    scanf("%d ",&n);
    for(j=0; j<n; j++)
    {
        for(i=0;; i++)
        {
            scanf("%c",&c);
            if(!('a'<=c&&c<='z')) break;
            X.push_back(c);
        }
        long long ans=sa.cyclic_occurrence(X);
        X.clear();
        printf("%I64d\n",ans);
    }
    return 0;
}
```