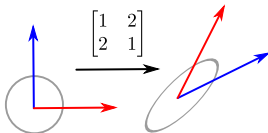


$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 0 & \star & \star \\ 0 & 1 & \star & \star \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A\mathbf{x} = \mathbf{0}$$

# MAT A22

## Linear Algebra 1

$$|\mathbf{u} \cdot \mathbf{v}| \leq \|\mathbf{u}\| \|\mathbf{v}\|$$

$A = [a_{ij}]$   
 $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$   
 $A(a\mathbf{u} + b\mathbf{v}) = aA\mathbf{u} + bA\mathbf{v}$

$A\mathbf{x} = \lambda\mathbf{x}$

$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$

# MAT A22: Linear Algebra 1 for Mathematical Sciences (Winter 2022)

Welcome to Week 10 of the course.

Questions? Thoughts? Comments?

Readings:

- ▶ 7.1 Examples and Elementary Properties
- ▶ 7.2 Kernel and Image of a Linear Transformation

News and Reminders:

- ▶ Three more weeks to go! Woo-hoo!
- ▶ Assignment #5 is due Thursday March 24th at 13:00

# Definition of Linear Transformations

## Definition

Let  $V$  and  $W$  be vector spaces, and  $T : V \rightarrow W$  a function. Then  $T$  is called a **linear transformation** if it satisfies the following two properties.

1.  $T$  preserves addition.

For all  $\vec{v}_1, \vec{v}_2 \in V$ ,  $T(\vec{v}_1 + \vec{v}_2) = T(\vec{v}_1) + T(\vec{v}_2)$ .

2.  $T$  preserves scalar multiplication.

For all  $\vec{v} \in V$  and  $r \in \mathbb{R}$ ,  $T(r\vec{v}) = rT(\vec{v})$ .

Note that the sum  $\vec{v}_1 + \vec{v}_2$  is in  $V$ , while the sum  $T(\vec{v}_1) + T(\vec{v}_2)$  is in  $W$ . Similarly,  $r\vec{v}$  is scalar multiplication in  $V$ , while  $rT(\vec{v})$  is scalar multiplication in  $W$ .

# Important Properties of Linear Transformations

## Theorem

Let  $V$  and  $W$  be vector spaces and  $T : V \rightarrow W$  a linear transformation.

1.  $T$  preserves the zero vector.

$$T(\vec{0}) = \vec{0}.$$

2.  $T$  preserves additive inverses.

$$\text{For all } \vec{v} \in V, T(-\vec{v}) = -T(\vec{v}).$$

3.  $T$  preserves linear combinations.

$$\text{For all } \vec{v}_1, \vec{v}_2, \dots, \vec{v}_m \in V \text{ and all } k_1, k_2, \dots, k_m \in \mathbb{R},$$

$$T(k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_m \vec{v}_m) = k_1 T(\vec{v}_1) + k_2 T(\vec{v}_2) + \dots + k_m T(\vec{v}_m).$$

## A Linear Map of Polynomials (Solution 1)

### Problem

Let  $T : \mathcal{P}_2 \rightarrow \mathbb{R}$  be a linear transformation such that

$$T(x^2 + x) = -1; T(x^2 - x) = 1; T(x^2 + 1) = 3.$$

Find  $T(4x^2 + 5x - 3)$ .

## Solution 1

Suppose  $a(x^2 + x) + b(x^2 - x) + c(x^2 + 1) = 4x^2 + 5x - 3$ . Then

$$(a + b + c)x^2 + (a - b)x + c = 4x^2 + 5x - 3.$$

## Solution 1

Suppose  $a(x^2 + x) + b(x^2 - x) + c(x^2 + 1) = 4x^2 + 5x - 3$ . Then

$$(a + b + c)x^2 + (a - b)x + c = 4x^2 + 5x - 3.$$

Solving for  $a$ ,  $b$ , and  $c$  results in the unique solution  $a = 6$ ,  $b = 1$ ,  $c = -3$ .

## Solution 1

Suppose  $a(x^2 + x) + b(x^2 - x) + c(x^2 + 1) = 4x^2 + 5x - 3$ . Then

$$(a + b + c)x^2 + (a - b)x + c = 4x^2 + 5x - 3.$$

Solving for  $a$ ,  $b$ , and  $c$  results in the unique solution  $a = 6$ ,  $b = 1$ ,  $c = -3$ . Thus

$$\begin{aligned} T(4x^2 + 5x - 3) &= T(6(x^2 + x) + (x^2 - x) - 3(x^2 + 1)) \\ &= 6T(x^2 + x) + T(x^2 - x) - 3T(x^2 + 1) \\ &= 6(-1) + 1 - 3(3) = -14. \end{aligned}$$



## A Linear Map of Polynomials (Solution 2)

### Solution 2

Notice that  $S = \{x^2 + x, x^2 - x, x^2 + 1\}$  is a basis of  $\mathcal{P}_2$ , and thus  $x^2$ ,  $x$ , and  $1$  can each be written as a linear combination of elements of  $S$ .

## A Linear Map of Polynomials (Solution 2)

### Solution 2

Notice that  $S = \{x^2 + x, x^2 - x, x^2 + 1\}$  is a basis of  $\mathcal{P}_2$ , and thus  $x^2$ ,  $x$ , and  $1$  can each be written as a linear combination of elements of  $S$ .

$$x^2 = \frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x)$$

$$x = \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x)$$

$$1 = (x^2 + 1) - \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x).$$

## A Linear Map of Polynomials (Solution 2)

### Solution 2

Notice that  $S = \{x^2 + x, x^2 - x, x^2 + 1\}$  is a basis of  $\mathcal{P}_2$ , and thus  $x^2$ ,  $x$ , and  $1$  can each be written as a linear combination of elements of  $S$ .

$$\begin{aligned}x^2 &= \frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x) \\x &= \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x) \\1 &= (x^2 + 1) - \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x).\end{aligned}$$

Then working with these (alternative basis) elements, we get:

$$\begin{aligned}T(x^2) &= T\left(\frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x)\right) \\&= \frac{1}{2}(-1) + \frac{1}{2}(1) = 0.\end{aligned}$$

## A Linear Map of Polynomials (Solution 2)

### Solution 2

Notice that  $S = \{x^2 + x, x^2 - x, x^2 + 1\}$  is a basis of  $\mathcal{P}_2$ , and thus  $x^2$ ,  $x$ , and  $1$  can each be written as a linear combination of elements of  $S$ .

$$\begin{aligned}x^2 &= \frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x) \\x &= \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x) \\1 &= (x^2 + 1) - \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x).\end{aligned}$$

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## A Linear Map of Polynomials (Solution 2)

### Solution 2

Notice that  $S = \{x^2 + x, x^2 - x, x^2 + 1\}$  is a basis of  $\mathcal{P}_2$ , and thus  $x^2$ ,  $x$ , and  $1$  can each be written as a linear combination of elements of  $S$ .

$$\begin{aligned}x^2 &= \frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x) \\x &= \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x) \\1 &= (x^2 + 1) - \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x).\end{aligned}$$

Then working with these (alternative basis) elements, we get:

$$\begin{aligned}T(x^2) &= T\left(\frac{1}{2}(x^2 + x) + \frac{1}{2}(x^2 - x)\right) \\&= \frac{1}{2}(-1) + \frac{1}{2}(1) = 0. \\T(x) &= T\left(\frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x)\right) \\&= \frac{1}{2}(-1) - \frac{1}{2}(1) = -1. \\T(1) &= T\left((x^2 + 1) - \frac{1}{2}(x^2 + x) - \frac{1}{2}(x^2 - x)\right) \\&= 3 - \frac{1}{2}(-1) - \frac{1}{2}(1) = 3.\end{aligned}$$

# Action on a Spanning Set

## Theorem

*Let  $V$  and  $W$  be vector spaces, where*

$$V = \text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}.$$

*Suppose that  $S$  and  $T$  are linear transformations from  $V$  to  $W$ .  
If  $S(\vec{v}_i) = T(\vec{v}_i)$  for all  $i$ ,  $1 \leq i \leq n$ , then  $S = T$ .*

## Why does this matter?

This theorem tells us that a linear transformation is completely determined by its actions on a spanning set.

## Determined by a Spanning Set

### Proof.

We must show that  $S(\vec{v}) = T(\vec{v})$  for each  $\vec{v} \in V$ . Let  $\vec{v} \in V$ . Then (since  $V$  is spanned by  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ ), there exist  $k_1, k_2, \dots, k_n \in \mathbb{R}$  so that

$$\vec{v} = k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_n \vec{v}_n.$$

## Determined by a Spanning Set

### Proof.

We must show that  $S(\vec{v}) = T(\vec{v})$  for each  $\vec{v} \in V$ . Let  $\vec{v} \in V$ . Then (since  $V$  is spanned by  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ ), there exist  $k_1, k_2, \dots, k_n \in \mathbb{R}$  so that

$$\vec{v} = k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_n \vec{v}_n.$$

It follows that

$$\begin{aligned} S(\vec{v}) &= S(k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_n \vec{v}_n) \\ &= k_1 S(\vec{v}_1) + k_2 S(\vec{v}_2) + \dots + k_n S(\vec{v}_n) \\ &= k_1 T(\vec{v}_1) + k_2 T(\vec{v}_2) + \dots + k_n T(\vec{v}_n) \\ &= T(k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_n \vec{v}_n) \\ &= T(\vec{v}). \end{aligned}$$

Therefore,  $S = T$ .





# Isomorphisms

## Example

$\mathcal{P}_1 = \{ax + b \mid a, b \in \mathbb{R}\}$  has addition and scalar multiplication defined as follows:

$$(a_1x + b_1) + (a_2x + b_2) = (a_1 + a_2)x + (b_1 + b_2),$$

$$k(a_1x + b_1) = (ka_1)x + (kb_1),$$

for all  $(a_1x + b_1), (a_2x + b_2) \in \mathcal{P}_1$  and  $k \in \mathbb{R}$ . This feels a lot like:

$$\mathbb{R}^2 = \left\{ \begin{bmatrix} a \\ b \end{bmatrix} \mid a, b \in \mathbb{R} \right\}$$

where addition and scalar multiplication are defined as follows:

$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} + \begin{bmatrix} a_2 \\ b_2 \end{bmatrix} = \begin{bmatrix} a_1 + a_2 \\ b_1 + b_2 \end{bmatrix} \quad k \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} ka_1 \\ kb_1 \end{bmatrix}$$

for all  $\begin{bmatrix} a_1 \\ b_1 \end{bmatrix}$  and  $\begin{bmatrix} a_2 \\ b_2 \end{bmatrix} \in \mathbb{R}^2$  and  $k \in \mathbb{R}$ .

# The Definition of Isomorphism

## Definition

Let  $V$  and  $W$  be vector spaces and  $T : V \rightarrow W$  a linear transformation.  $T$  is an **isomorphism** if and only if  $T$  is both one-to-one and onto (i.e.,  $\text{null}(T) = \{0\}$  and  $\text{image}(T) = W$ ). If  $T : V \rightarrow W$  is an isomorphism, then the vector spaces  $V$  and  $W$  are said to be **isomorphic**, and we write  $V \cong W$ .

## Example

The identity operator  $I : V \rightarrow V$  given  $I(\vec{v}) = \vec{v}$  on any vector space is an isomorphism.

## Onto but Not One-to-One

### Problem

Let  $T : M_{22} \rightarrow \mathbb{R}^2$  be a linear transformation defined by

$$T \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a + d \\ b + c \end{bmatrix} \text{ for all } \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{22}.$$

Prove that  $T$  is onto but not one-to-one.

## Solutions

Let  $\begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2$ . Since  $T \begin{bmatrix} x & y \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$ ,  $T$  is onto.

Observe that  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \in \ker(T)$ , so  $\ker(T) \neq \vec{0}_{22}$ .

# Invertible Matrices

## Problem

Suppose  $U$  is an *invertible*  $m \times m$  matrix and let  $T : M_{mn} \rightarrow M_{mn}$  be defined by

$$T(A) = UA \text{ for all } A \in M_{mn}.$$

Prove the following:

1.  $T$  is linear
2.  $T$  is one-to-one
3.  $T$  is onto

# Polynomials and $\mathbb{R}^{n+1}$

## Problem

The map  $T : \mathcal{P}_n \rightarrow \mathbb{R}^{n+1}$  defined below is an isomorphism.

$$T(a_0 + a_1x + a_2x^2 + \cdots + a_nx^n) = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

To verify this, prove that:

1.  $T$  is a linear transformation
2.  $T$  is one-to-one
3.  $T$  is onto

## $2 \times 2$ Symmetric Matrices

### Problem

*Let  $V$  denote the set of  $2 \times 2$  real symmetric matrices. Then  $V$  is a vector space with dimension three. Find an isomorphism  $T : \mathcal{P}_2 \rightarrow V$  with the property that  $T(1) = I_2$  (the  $2 \times 2$  identity matrix).*

## Solution

$$V = \left\{ \begin{bmatrix} a & b \\ b & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$



## Solution

$$V = \left\{ \begin{bmatrix} a & b \\ b & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Let

$$B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Then  $B$  is independent, and  $\text{span}(B) = V$ , so  $B$  is a basis of  $V$ . Also,  $\dim(V) = 3 = \dim(\mathcal{P}_2)$ .

## Solution

$$V = \left\{ \begin{bmatrix} a & b \\ b & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Let

$$B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Then  $B$  is independent, and  $\text{span}(B) = V$ , so  $B$  is a basis of  $V$ . Also,  $\dim(V) = 3 = \dim(\mathcal{P}_2)$ . However, we want a basis of  $V$  that contains  $l_2$ .

## Solution (Continued)

Let

$$B' = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Since  $B'$  consists of  $\dim(V)$  symmetric independent matrices,  $B'$  is a basis of  $V$ . Note that  $I_2 \in B'$ .

## Solution (Continued)

Let

$$B' = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}.$$

Since  $B'$  consists of  $\dim(V)$  symmetric independent matrices,  $B'$  is a basis of  $V$ . Note that  $I_2 \in B'$ . Define

$$T(1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, T(x) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, T(x^2) = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

Then for all  $ax^2 + bx + c \in \mathcal{P}_2$ ,

$$T(ax^2 + bx + c) = \begin{bmatrix} c & b \\ b & a + c \end{bmatrix},$$

and  $T(1) = I_2$ .

## Extra Problems: An Unexpected Isomorphism

### Problem

Let  $\mathbb{R}^+ = \{x \in \mathbb{R} : x > 0\} = (0, \infty)$  denote the positive numbers.  
Consider the following operations “box plus” and “box dot” on  $\mathbb{R}^+$ .

$$\lambda \boxdot x = x^\lambda \qquad x \boxplus y = xy$$

Prove that  $\mathbb{R}^+$  (with  $\boxplus$  and  $\boxdot$ ) is isomorphic  $\mathbb{R}$  (with  $+$  and  $\cdot$ ) via  $T(2) = 1$ .