

Data Modeling & Analysis Techniques

Probability Distributions



Continuous Distributions

- Uniform Distribution
- Normal Distribution
- Exponential Distribution



Continuous Distributions-Uniform

- Continuous distributions for event probability
 - Uniform distribution
 - Models the likelihood that a particular outcome will result from an experiment where every outcome value is equally likely
 - Parameterized by the range of possible outcomes, [a..b]
 - Probability density function:

$$p(x;a,b) = \frac{1}{b-a}$$

• Mean: $\mu = (a+b)/2$ Variance: $\sigma^2 = (b-a)^2/12$



Problem

- The pdf of a Uniform Distribution of X is f(x)= 5; 4.9=< x <= 5.1</p>
- What is the probability that a measurement of current is between 4.95 and 5.0 milliamperes.



Distributions

Normal distribution

- Models the likelihood of results if the results are either distributed with a "Bell curve" or, alternatively, the result of the summation of a large number of random effects. This is a good approximation for a wide range of natural processes or noise phenomena as we will see a little later
- Parameterized by a mean, μ , and standard deviation σ
- Probability density function:

$$p(x; M, S) = \frac{1}{\sqrt{2pS^2}} e^{-\frac{(x-M)^2}{2S^2}}$$

• Mean: μ Variance: σ^2



Distributions

- Continuous distributions for event frequency
 - Normal distribution
 - Models the number of times an event happens in a very large (infinite) number of experiments
 - Parameterized by a mean, μ , and standard deviation σ
 - Probability density function:

$$p(x; M, S) = \frac{1}{\sqrt{2\rho S^2}} e^{-\frac{(x-M)^2}{2S^2}}$$



Normal Distribution Example



Distributions

- Continuous distributions for inter-event timing
 - Exponential distribution
 - Models the likelihood of an event happening for the first time at time x in a Poisson process (i.e. a process where events occur with the same likelihood at any point in time, independent of the time since the last occurrence.

 - Probability density function:

• Mean: $1/\mu$ Variance: $1/\lambda^2$

Exponential Distribution Example

Commonly, car cooling systems are controlled by electrically driven fans. Assuming that the lifetime T in hours of a particular make of fan can be modelled by an exponential distribution with $\lambda=0.0003$ find the proportion of fans which will give at least 10000 hours service. If the fan is redesigned so that its lifetime may be modelled by an exponential distribution with $\lambda=0.00035$, would you expect more fans or fewer to give at least 10000 hours service?



Answer

We know that $f(t) = 0.0003e^{-0.0003t}$ so that the probability that a fan will give at least 10000 hours service is given by the expression

$$P(T > 10000) = \int_{10000}^{\infty} f(t) dt = \int_{10000}^{\infty} 0.0003 e^{-0.0003t} dt = -\left[e^{-0.0003t}\right]_{10000}^{\infty} = e^{-3} \approx 0.0498$$

Hence about 5% of the fans may be expected to give at least 10000 hours service. After the redesign, the calculation becomes

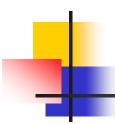
and so only about 3% of the fans may be expected to give at least 10000 hours service.

Hence, after the redesign we expect fewer fans to give 10000 hours service.



Exponential Distribution Example

- The print jobs at UTA network follows an exponential distribution with λ = 0.2 per minute.
- What is the probability you will have print jobs arrive
 - Less than 3 min
 - More than 7 min
 - Bet 3 and 7 min



Moments

 Moments represent important aspects of the distribution and can be used to characterize mean, variance, etc.

$$E \stackrel{\acute{e}}{e} (x - a)^r \stackrel{\grave{u}}{u}$$

- In some cases the standard definition is difficult to compute
 - Moment generating function can sometimes help



Moment Generating Function

 The moment generating function for a random variable X is defined as

$$m_X(t) = E \not \in e^{xt} \not \in$$

The rth moment of X around 0 can then be computed as:

$$\lim_{t\to 0}\frac{\partial^r}{\partial t^r}m_X(t)$$

 Note that sometimes this can not be computed since the limit might not be defined



Moment Generating Function

- The moment generating function allows to compute, e.g., the mean and the variance
 - Mean:

$$m = \lim_{t \to 0} \frac{\partial}{\partial t} \int e^{xt} p(x) dx$$

Variance:

$$S^{2} = \lim_{t \to 0} \frac{\partial^{2}}{\partial t^{2}} \int e^{(x-m)t} p(x) dx$$

Example: Poisson Distribution



Probability mass function

$$P(x; /) = \frac{/ ^{x}e^{-/}}{x!}$$

$$P(x; /) = \frac{/^{x}e^{-/}}{x!}$$
• Moment generating function
$$m_{X}(t) = E[e^{xt}] = e^{/(e^{t}-1)}$$

Mean

$$m = \lim_{t \to \infty} \frac{\partial}{\partial t} e^{/(e^t - 1)} = 1$$

Variance
$$\frac{\partial^2}{\partial t^2} e^{t - m - 1} = 1$$

$$S^2 = \lim_{t \to 0} \frac{\partial^2}{\partial t^2} e^{t - m - 1} = 1$$



Multivariate Distributions

- Multivariate distributions sometimes arise when combining the outcomes of multiple random variables
 - Sometimes we are interested of the joint effect of multiple random variables
 - Distribution of the product of two random variables
 - Distribution of the joint additive effect of multiple variables



Multivariate Distributions

- For some operations combining multiple variables we can determine the moments of the distribution relatively easily
 - Usually assumptions made about random variables
 - Independently distributed
 - Moments of the distributions of the individual variables are known
 - If variables are not independent we have to use conditional distributions and the laws of probability

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Distribution of the Product

 The mean and variance of the distribution of the product of two independent random variables can be determined

Distribution of the Product

$$\begin{split} \mathbf{S}_{xy}^{2} &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{a}}_{j} \left(\left(x_{i} y_{j} - m_{x} m_{y} \right)^{2} P(x_{i}) P(y_{j}) \right) = \mathring{\mathbf{a}}_{i} \left(P(x_{i}) \mathring{\mathbf{a}}_{j} \left(\left((x_{i} - m_{x}) + m_{x}) ((y_{j} - m_{y}) + m_{y}) - m_{x} m_{y} \right)^{2} P(y_{j}) \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{a}}_{j} \left(\left((x_{i} - m_{x}) (y_{j} - m_{y}) + (x_{i} - m_{x}) m_{y} + (y_{j} - m_{y}) m_{x} + m_{x} m_{y} \right) - m_{x} m_{y} \right)^{2} P(y_{j}) \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{a}}_{j} \left(\left((x_{i} - m_{x}) (y_{j} - m_{y}) + (x_{i} - m_{x}) m_{y} + (y_{j} - m_{y}) m_{x} \right)^{2} P(y_{j}) \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{a}}_{j} \left((x_{i} - m_{x})^{2} (y_{j} - m_{y})^{2} + (x_{i} - m_{x})^{2} (y_{j} - m_{y}) m_{y} + (x_{i} - m_{x}) (y_{j} - m_{y})^{2} m_{x} + (x_{i} - m_{x}) (y_{j} - m_{y}) m_{x} m_{y} \mathring{\mathbf{e}} \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{a}}_{j} \left((x_{i} - m_{x})^{2} (y_{j} - m_{y})^{2} + (x_{i} - m_{x})^{2} (y_{j} - m_{y}) m_{y} + (x_{i} - m_{x}) (y_{j} - m_{y})^{2} m_{x} + (x_{i} - m_{x}) (y_{j} - m_{y}) m_{x} m_{y} \mathring{\mathbf{e}} \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{a}}_{j} \left((x_{i} - m_{x})^{2} (y_{j} - m_{y})^{2} + (y_{j} - m_{y}) m_{y} + (x_{i} - m_{x}) (y_{j} - m_{y})^{2} m_{x} + (x_{i} - m_{x}) (y_{j} - m_{y}) m_{x} m_{y} \mathring{\mathbf{e}} \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{e}}_{i} \mathring{\mathbf{e}}^{2} + (x_{i} - m_{x})^{2} m_{y}^{2} + (y_{j} - m_{y})^{2} m_{x}^{2} + (x_{i} - m_{x})^{2} m_{y}^{2} m_{y}^{2} + (y_{j} - m_{y})^{2} m_{y} m_{y} \mathring{\mathbf{e}} \right) \\ &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{e}}_{i} \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} + (x_{i} - m_{x})^{2} m_{y}^{2} P(y_{j}) + \mathring{\mathbf{a}}_{j} \left((x_{i} - m_{x}) (y_{j} - m_{y})^{2} m_{y} p) \right) + \mathring{\mathbf{a}}_{j} \left((x_{i} - m_{x})^{2} m_{y}^{2} m_{y}^{2} + (y_{j} - m_{y}) m_{y} p) \right) + \mathring{\mathbf{e}}_{j} \mathring{\mathbf{e}}^{2} \\ &= \mathring{\mathbf{e}}_{i} \mathring{\mathbf{e}}^{2} P(x_{i}) \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} + (x_{i} - m_{x}) m_{y} m_{y} p) + (x_{i} - m_{x})^{2} m_{y}^{2} \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} P(y_{j}) + \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} P(y_{j}) + \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} \mathring{\mathbf{e}}^{2} P(y_{j}) \right) + (x_{i} - m_{x$$



Distribution of the Sum

 The mean and variance of the distribution of the sum of two independent random variables can be determined

$$\begin{split} & \mathcal{M}_{X+Y} = \mathring{a}_{i} \mathring{a}_{j} \Big((x_{i} + y_{j}) P(x_{i}) P(y_{j}) \Big) = \mathring{a}_{i} P(x_{i}) \mathring{a}_{j} \Big(x_{i} P(y_{j}) + y_{j} P(y_{j}) \Big) \\ & = \mathring{a}_{i} P(x_{i}) \Big(x_{i} \mathring{a}_{j} P(y_{j}) + \mathring{a}_{j} \Big(y_{j} P(y_{j}) \Big) \Big) = \mathring{a}_{i} P(x_{i}) \Big(x_{i} + \mathcal{M}_{Y} \Big) \\ & = \mathring{a}_{i} P(x_{i}) x_{i} + \mathcal{M}_{Y} \mathring{a}_{i} P(x_{i}) = \mathcal{M}_{X} + \mathcal{M}_{Y} \end{split}$$

Distribution of the Sum

$$\begin{split} S_{X+Y}^{2} &= \mathring{\mathbf{a}}_{i} \mathring{\mathbf{a}}_{j} \Big[\Big((x_{i} + y_{j}) - (m_{X} + m_{Y}) \Big)^{2} P(x_{i}) P(y_{j}) \Big] = \mathring{\mathbf{a}}_{i} \Big[P(x_{i}) \mathring{\mathbf{a}}_{j} \Big[\Big((x_{i} + y_{j})^{2} - 2(x_{i} + y_{j})(m_{X} + m_{Y}) + (m_{X} + m_{Y})^{2} \Big) P(y_{j}) \Big] \Big] \\ &= \mathring{\mathbf{a}}_{i} \Big[P(x_{i}) \mathring{\mathbf{a}}_{j} \Big[\Big((x_{i}^{2} + 2x_{i}y_{j} + y_{j}^{2}) - 2(x_{i}m_{X} + y_{j}m_{X} + x_{i}m_{Y} + y_{j}m_{Y}) + (m_{X}^{2} + 2m_{Y}m_{X} + m_{Y}^{2}) \Big] P(y_{j}) \Big] \Big] \\ &= \mathring{\mathbf{a}}_{i} \Big[P(x_{i}) \mathring{\mathbf{a}}_{j} \Big[\Big((x_{i}^{2} - 2x_{i}m_{X} + m_{X}^{2}) + (y_{j}^{2} - 2y_{j}m_{Y} + m_{Y}^{2}) + 2x_{i}y_{j} - 2(y_{j}m_{X} + x_{i}m_{Y}) + 2m_{Y}m_{X} \Big) P(y_{j}) \Big] \Big] \\ &= \mathring{\mathbf{a}}_{i} P(x_{i}) \Big[(x_{i} - m_{X})^{2} \mathring{\mathbf{a}}_{j} P(y_{j}) + \mathring{\mathbf{a}}_{j} (y_{j} - m_{Y})^{2} P(y_{j}) + 2x_{i} \mathring{\mathbf{a}}_{j} y_{j} P(y_{j}) - 2m_{X} \mathring{\mathbf{a}}_{j} y_{j} P(y_{j}) - 2x_{i}m_{Y} \mathring{\mathbf{a}}_{j} P(y_{j}) + 2m_{Y}m_{X} \mathring{\mathbf{a}}_{j} P(y_{j}) \Big] \\ &= \mathring{\mathbf{a}}_{i} P(x_{i}) \Big[(x_{i} - m_{X})^{2} + S_{Y}^{2} + 2x_{i}m_{Y} - 2m_{X}m_{Y} - 2x_{i}m_{Y} + 2m_{Y}m_{X} \Big) \\ &= \mathring{\mathbf{a}}_{i} P(x_{i}) \Big[(x_{i} - m_{X})^{2} + S_{Y}^{2} + 2x_{i}m_{Y} - 2m_{X}m_{Y} - 2x_{i}m_{Y} + 2m_{Y}m_{X} \Big) \\ &= \mathring{\mathbf{a}}_{i} P(x_{i}) \Big[(x_{i} - m_{X})^{2} + S_{Y}^{2} \Big] = \mathring{\mathbf{a}}_{i} (x_{i} - m_{X})^{2} P(x_{i}) + S_{Y}^{2} \mathring{\mathbf{a}}_{i} P(x_{i}) = S_{X}^{2} + S_{Y}^{2} \end{aligned}$$



- The Pareto distribution has two parameters, a shape parameter α and a minimum x_m
 - Models many social and physical phenomena
 - Wealth distribution (80-20 rule), hard drive failures, daily maximum rainfalls, size of fires, etc.
 - Probability density $p(x; \partial, x_m) = \begin{cases} \frac{\partial x_m^{\partial}}{x^{(\partial+1)}} & x \ge x_m \\ 0 & otherwise \end{cases}$

• Cumulative density function
$$P(y < x) = \begin{cases} 1 - \left(\frac{x_m}{x}\right)^a & x \ge x_m \\ 0 & otherwise \end{cases}$$



- The Pareto distribution is heavy tailed for some parameter settings
 - Infinite mean for $\alpha \le 1$
 - Infinite variance for α≤2
- For many interesting problems the parameters fall into this region
 - E.g. 80-20 rule has *α*≈1.161
- Heavy tailed distributions exist and model existing problems
 - Has implications on sums and products of functions and the central limit theorem