

Longtime no discover
Push an object

you change its velocity and not position

$F \propto$ rate of change of momentum

only for bacteria.
F & position.

degrees of freedom

Classical physics is one position of this range

Classical physics is a nontrivial extension of Quantum Mechanics.

Statistical physics - ensemble etc.

non-relativistic.
* * *
 \hbar, c, g, α
0 ∞ no
switch off gross error

Classical electromagnetic waves
Physical & mechanical

Classical physics $c = \infty$ $\hbar = 0$

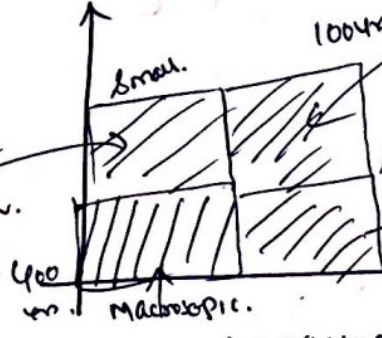
You know Complex number

If all measurements are real then why we need complex numbers.
We need Matrices; combinations of numbers; the word Imaginary, does not mean anything.
Phy mean: $2+3i$
" of -3 .

dynamics: putates in favor

Very slow velocities.
length scales. Macroscopic.

Non-relativistic
Quantum mech.



Relativistic Q.M. $\Rightarrow E=mc^2$
no. of particles is no longer conserved

Relativistic mechanics or physics.

Non-relativistic
Classical mechanics
or Newtonian.

Internal gravitational fields

Thermodynamics: Ideal gas:

QM: Hydrogen atom.

Relativistic is no longer for single particle.

Emergent properties: water molecules. Phases.

Electron is wave or particle?
It is meaningless.
Failure of language.
What is this chalk?

only for backemias.
f.d position.

degrees of freedom:

Collection of Particles:

Single Particle - three co-ordinates -

three degrees of freedom

Two Particles - six degrees of freedom,

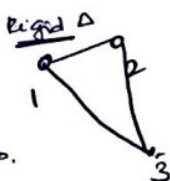
does not matter - Cartesian or Polar or cylindrical.

N- Particle System has $3N$ co-ordinates -

Generalised. - NO constraints

Plane - two degree of freedom
line - single degree of freedom

Constraints -



distance is fixed.

$r_{12} = \text{constant}$ (5 degrees of freedom)

$r_{23} = \text{constant}$ (Seven)

$r_{13} = \text{constant}$ (Six)

N , $3N$ co-ordinates.

$$r_{ij} = \text{const for } 1 \leq i, j \leq N$$

No. of Constraints = $N_C = \frac{N(N-1)}{2}$

No. of Independent degrees of freedom.

$3N - \frac{N(N-1)}{2}$ (If $N=4$, $N=8$)

(N_C)

This is a rigid body.
Distance between any pairs is fixed.

Some of the constraints are redundant

Independent degrees of freedom (Six degrees of freedom)

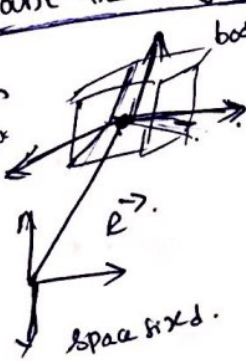
Remaining constraints are redundant

Cannot have negative degrees of freedom lines in N and that increases \sqrt{N} .

Count the degrees of freedom:

$3 \times 5 = 15$
 $3 \times 8 = 24$

Centre of mass is at some point



body fixed.

twisted or turn.

co-ordinates fixed

space fixed.

Body fixed co-ordinate system.

twisted or turned.

Space fixed

3 Euler rotations

directions & three angles

to reach the other co-ordinate system

Spectra of diatomic molecules. two degree of rotational
three degree of translational.

A constraint does not always eliminate degrees of freedom (particle moves in

Eliminate degree of freedom \Leftarrow Holonomic constraints ; Integrable $f(x, y, z, t) = 0$ (Can't be used to eliminate)

\Leftarrow Non-holonomic " (They could involve velocities, which case not all clear)
Beads of Atoms - One dimension
Gas molecules - move in 3D space
Particle on surface of Solid sphere

Point particle Chalk under the action of earth's gravity = Can you Predict its future motion

(Point particle moving in space)

Horizontal velocity \Rightarrow elliptic path \Rightarrow escapes with hyperbolic orbit

Initial position or force \Rightarrow does not sufficient

you need Initial velocities and position \Rightarrow Newton's second order equation.

Both Initial position and velocities dynamics is happening phase space.

degrees of freedom. (Slips).

This is the idea behind dynamics

A. The number of independent degrees of freedom has to be determined first

B. the corresponding generalized velocities have also to be added on the set of dynamical variables.

Generalized co-ordinates q_1, q_2, \dots, q_n
velocities $\dot{q}_1, \dot{q}_2, \dots, \dot{q}_n$
 $\frac{dq_i}{dt} = \dot{q}_i$ } N independent degrees of freedom

To solve the equations of motion, you need to know certain amount of initial data. The value of these generalized co-ordinates & generalized velocities at an initial instant of time. In this sense Newtonian mech dynamics are deterministic.