

1) The impulse response of a discrete-time LTI system is given by

$$\{ h(n) = 0.25 \text{ for } 0 \leq n \leq 30$$

$$h(n) = 0 \text{ for other values of } n. \}$$

Make an accurate sketch of the output of the system when the input signal is

$$\{ x(n) = 1 \text{ for } 0 \leq n \leq 30$$

$$x(n) = 0 \text{ for other values of } n. \}$$

2) Impulse response $h[n]$ of discrete time LTI

system. $h[n] = 0, n < 0$

$$1, 0 \leq n \leq 4$$

$$-1, 4 < n \leq 6$$

$$0, n > 6$$

$$x[n] = 0, n < 2$$

$$1, n = 2$$

$$0, n = 3$$

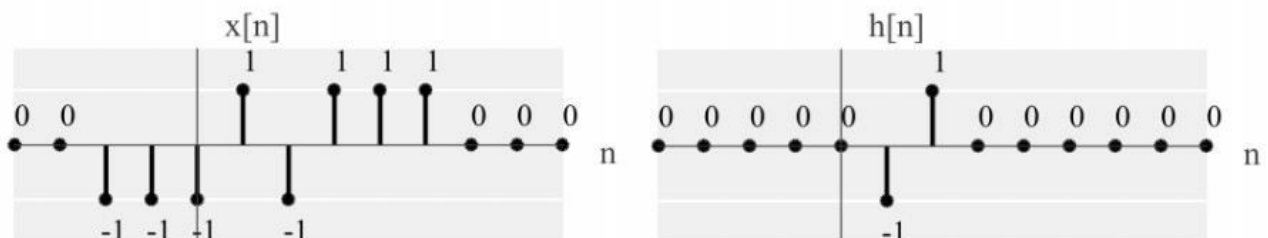
$$-1, n = 4$$

$$0, n > 4$$

Sketch the output $y[n]$.

3) Consider the following discrete-time signal $x[n]$ and an LTI system with impulse response

$h[n]$. Assume the zeros continue forever for $n \rightarrow -\infty$ and $n \rightarrow \infty$.



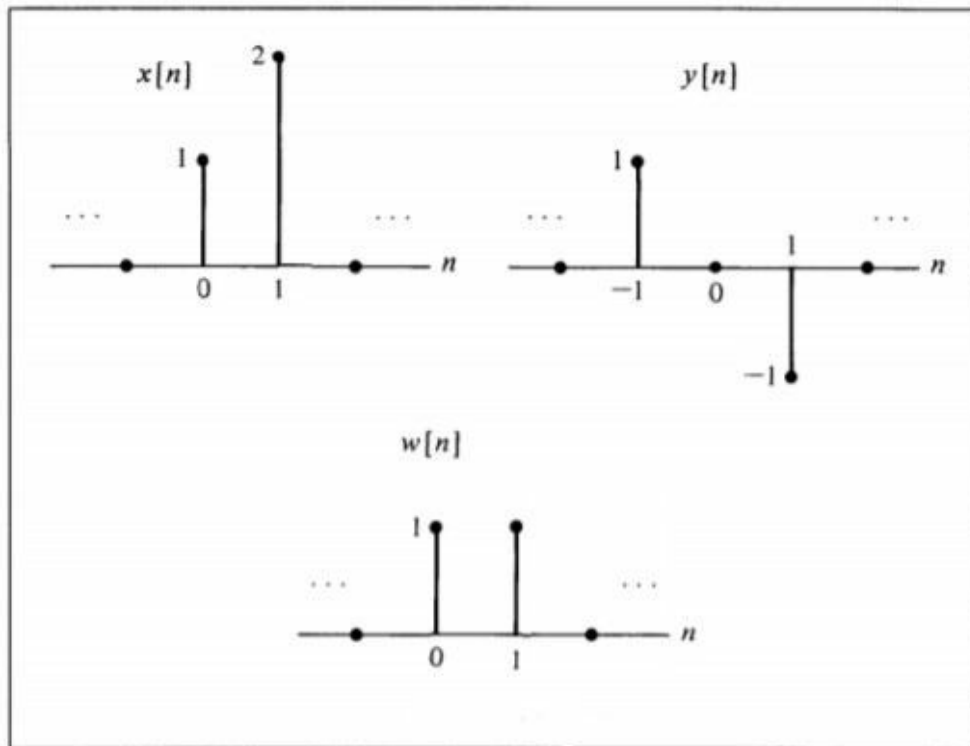
a) Sketch the system output $y[n] = x[n] * h[n]$.

b) Sketch $y[n] = h[n] * h[-n]$.

c) Is the system with impulse response $h[n]$ causal?

4)

Consider the three discrete-time signals shown in Figure



(a) Verify the distributive law of convolution:

$$(x + w) * y = (x * y) + (w * y)$$

(b) You may have noticed a similarity between the convolution operation and multiplication, but they are *not* equivalent. Verify that

$$(x * y) \cdot w \neq x * (y \cdot w)$$

5) A linear system S has the relationship $y[n] = \sum_k x[k] * g[n - 2k]$, k ranging from $-\infty$ to ∞ , between its input $x[n]$ and its output $y[n]$, where $g[n] = u[n] - u[n - 4]$

(a) Determine $y[n]$ when $x[n] = \delta[n - 1]$.

(b) Determine $y[n]$ when $x[n] = \delta[n - 2]$.

(c) Is S LTI?

6) Find $x(n) * \delta(n - n_0) = x(n - n_0)$. What do you observe?

7) Define FIR and IIR systems. Given that $h[n]$ is the impulse response of an LTI IIR system, does there exist an input $x[n]$ for which the output $y[n] = x[n] * h[n]$ is non zero for finite values?

8) An LTI system with input $x[n]$ and output $y[n]$ has impulse response $h[n] = \delta[n] + 2\delta[n - 1] + 3\delta[n - 2]$. Find the system's output $y[n]$ when $x[n] = -2 + 3\cos((\pi/4)n + \pi/3) + 10\cos((3\pi/4)n - \pi/5)$.

9) An LTI system with input $x[n]$ and output $y[n]$ has impulse response $h[n] = \delta[n]$

+ $2\delta[n - 1] + 3\delta[n - 2]$. Find the system's

[a] Frequency response $H(e^{j\omega})$, and

[b] Steady-state output $y[n]$ when

$x[n] = -2 + 3\cos((\pi/4)n + \pi/3) + 10\cos((3\pi/4)n - \pi/5)$.

10) A system has causal finite impulse response,

$h[n] = 1$ for $n = 0, 1$;

-1 for $n = 2, 3$;

a) Find $H(e^{j\omega})$

b) Find the output when input $x[n] = 2\delta[n] - \delta[n - 2] + 3\delta[n - 3]$

11) Given an LTI system,

$h[n] = a^n$, $0 \leq n$

0 , $n > 0$

$|a| < 1$

and $x[n] = u[n] - u[n - N]$

find $y[n]$, $H(e^{j\omega})$ and $Y(j\omega)$ and determine whether the system is causal or not.

12) Define what is an eigenfunction of an LTI system. Derive the eigen value λ corresponding to the input e^{sn} , given that the impulse response is $h[n]$.