EP 1027: Maxwell's Equations and Electromagnetic Waves

Instructor: Shubho Roy¹ (Dept. of Physics)

Lecture 8

April 9, 2019

¹Email: sroy@iith.ac.in, Office: C 313 D, Office hrs: Walk in/ by email appointment

 Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom

- Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom
- Magentic fields in media: the "H field" and new Ampere's law

- Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom
- Magentic fields in media: the "H field" and new Ampere's law
- ► Maxwell Equations in matter

- Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom
- Magentic fields in media: the "H field" and new Ampere's law
- ► Maxwell Equations in matter
- ► Energy Conservation law for EM forces: Poynting vector

- Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom
- Magentic fields in media: the "H field" and new Ampere's law
- ► Maxwell Equations in matter
- ► Energy Conservation law for EM forces: Poynting vector
- ► Force on charge distribution: Maxwell Stress tensor

- Recap of Maxwell's Eqns (in vacuum), Potential formulation, Gauge freedom
- Magentic fields in media: the "H field" and new Ampere's law
- Maxwell Equations in matter
- ► Energy Conservation law for EM forces: Poynting vector
- ► Force on charge distribution: Maxwell Stress tensor
- ► Linear momentum and Angular momentum contained in FM fields

References/Readings

References/Readings

▶ Griffiths, D.J., Introduction to Electrodynamics, Ch. 6-8

► Maxwell's Equations

$$\begin{split} & \boldsymbol{\nabla} \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}, (\text{Gauss law}) \\ & \boldsymbol{\nabla} \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = 0, (\text{Faraday-Lenz law}) \\ & \boldsymbol{\nabla} \cdot \mathbf{B} = 0, \ (\text{"No source or sink" law}) \\ & \boldsymbol{\nabla} \times \mathbf{B} - \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} = \mu_0 \, \mathbf{j}. (\text{Ampere law}) \end{split}$$

► Maxwell's Equations

$$\begin{split} & \boldsymbol{\nabla} \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}, (\text{Gauss law}) \\ & \boldsymbol{\nabla} \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = 0, (\text{Faraday-Lenz law}) \\ & \boldsymbol{\nabla} \cdot \mathbf{B} = 0, \ (\text{"No source or sink" law}) \\ & \boldsymbol{\nabla} \times \mathbf{B} - \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} = \mu_0 \, \mathbf{j}. (\text{Ampere law}) \end{split}$$

The first and the last Maxwell's equation are truly equations of motion as their RHS contain the sources (ρ, \mathbf{j}) . They tell you, how or what kind of field you produce for a given source.

► Maxwell's Equations

$$\begin{split} & \boldsymbol{\nabla} \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}, (\text{Gauss law}) \\ & \boldsymbol{\nabla} \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = 0, (\text{Faraday-Lenz law}) \\ & \boldsymbol{\nabla} \cdot \mathbf{B} = 0, \ (\text{"No source or sink" law}) \\ & \boldsymbol{\nabla} \times \mathbf{B} - \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} = \mu_0 \, \mathbf{j}. (\text{Ampere law}) \end{split}$$

- The first and the last Maxwell's equation are truly equations of motion as their RHS contain the sources (ρ, \mathbf{j}) . They tell you, how or what kind of field you produce for a given source.
- The second and third Maxwell's equations have no sources, i.e. they must hold for all situations. So, these are not equations of motion, rather they are *constraints* that must hold for all bona fide solutions of the equation of motion. (Bianchi Identities)

▶ Since $\nabla \times \mathbf{E} = -\frac{\partial B}{\partial t} \neq 0$ anymore, seems we can't define an electrostatic scalar potential!

- ▶ Since $\nabla \times \mathbf{E} = -\frac{\partial B}{\partial t} \neq 0$ anymore, seems we can't define an electrostatic scalar potential!
- ▶ But, $\nabla \cdot \mathbf{B} = 0$ is still there, so we still got the vector potential, \mathbf{A} ,

$$\mathbf{B} = \mathbf{\nabla} \times \mathbf{A}$$
.

Plug this in Maxwell Eq. 2, aka Faraday's law, we get:.

- ▶ Since $\nabla \times \mathbf{E} = -\frac{\partial B}{\partial t} \neq 0$ anymore, seems we can't define an electrostatic scalar potential!
- ▶ But, $\nabla \cdot \mathbf{B} = 0$ is still there, so we still got the vector potential, \mathbf{A} ,

$$\mathbf{B} = \mathbf{\nabla} \times \mathbf{A}$$
.

Plug this in Maxwell Eq. 2, aka Faraday's law, we get:.

$$\begin{split} \boldsymbol{\nabla} \times \left(\mathbf{E} + \frac{\partial \mathbf{A}}{\partial t} \right) &= 0, \\ \Longrightarrow \ \mathbf{E} + \frac{\partial \mathbf{A}}{\partial t} &= - \boldsymbol{\nabla} \boldsymbol{\Phi} \\ \Longrightarrow \ \mathbf{E} &= - \boldsymbol{\nabla} \boldsymbol{\Phi} - \frac{\partial \mathbf{A}}{\partial t}. \end{split}$$

Φ is the new Electric potential.

▶ Plugging, $\mathbf{E} = -\nabla \Phi - \frac{\partial \mathbf{A}}{\partial \mathbf{t}}$, $\mathbf{B} = \nabla \times \mathbf{A}$ in Gauss law and Ampere law (i.e. the Maxwell Eq.s 1 and

4),
$$\nabla^2 \Phi + \frac{\partial \left(\nabla \cdot \mathbf{A} \right)}{\partial t} = -\frac{\rho}{\epsilon_0},$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) \mathbf{A} - \nabla \left(\nabla \cdot \mathbf{A} + \frac{1}{c^2} \frac{\partial \Phi}{\partial t} \right) = -\mu_0 \mathbf{j}$$

Plugging, $\mathbf{E}=-\nabla \Phi-\frac{\partial \mathbf{A}}{\partial \mathbf{t}},~\mathbf{B}=\nabla \times \mathbf{A}$ in Gauss law and Ampere law (i.e. the Maxwell Eq.s 1 and

$$\nabla^2 \Phi + \frac{\partial \left(\nabla \cdot \mathbf{A} \right)}{\partial t} = -\frac{\rho}{\epsilon_0},$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) \mathbf{A} - \nabla \left(\nabla \cdot \mathbf{A} + \frac{1}{c^2} \frac{\partial \Phi}{\partial t} \right) = -\mu_0 \mathbf{j}$$

lacksquare Recall, f A is ambiguous upto addition of a gradient of a scalar, χ ,

$$\mathbf{A}' = \mathbf{A} + \mathbf{\nabla} \chi$$
 $\mathbf{\nabla} \times \mathbf{A}' = \mathbf{\nabla} \times \mathbf{A} = \mathbf{B}.$

▶ Plugging, $\mathbf{E} = -\nabla \mathbf{\Phi} - \frac{\partial \mathbf{A}}{\partial \mathbf{t}}$, $\mathbf{B} = \nabla \times \mathbf{A}$ in Gauss law and Ampere law (i.e. the Maxwell Eq.s 1 and

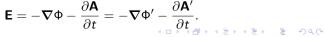
$$\begin{split} \boldsymbol{\nabla}^2 \boldsymbol{\Phi} + \frac{\partial \left(\boldsymbol{\nabla} \cdot \mathbf{A} \right)}{\partial t} &= -\frac{\rho}{\epsilon_0}, \\ \left(\boldsymbol{\nabla}^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) \mathbf{A} - \boldsymbol{\nabla} \left(\boldsymbol{\nabla} \cdot \mathbf{A} + \frac{1}{c^2} \frac{\partial \boldsymbol{\Phi}}{\partial t} \right) &= -\mu_0 \mathbf{j} \end{split}$$

lacktriangle Recall, f A is ambiguous upto addition of a gradient of a scalar, χ ,

$$\mathbf{A}' = \mathbf{A} + \mathbf{\nabla} \chi$$
 $\mathbf{\nabla} \times \mathbf{A}' = \mathbf{\nabla} \times \mathbf{A} = \mathbf{B}.$

This implies, Φ is ambiguous as well,

$$\Phi' = \Phi - rac{\partial \chi}{\partial t}$$



Freedom in redefining potentials,

$$\mathbf{A}' = \mathbf{A} + \mathbf{\nabla} \chi, \quad \Phi' = \Phi - \frac{\partial \chi}{\partial t}.$$

Called Gauge Freedom/ Gauge Symmetry.

Freedom in redefining potentials,

$$\mathbf{A}' = \mathbf{A} + \mathbf{\nabla} \chi, \quad \Phi' = \Phi - \frac{\partial \chi}{\partial t}.$$

Called Gauge Freedom/ Gauge Symmetry.

• Use this freedom to choose χ so that (Lorenz gauge condition),

$$\mathbf{\nabla}\cdot\mathbf{A}+rac{1}{c^2}rac{\partial\Phi}{\partial t}=0.$$

Freedom in redefining potentials,

$$\mathbf{A}' = \mathbf{A} + \mathbf{\nabla} \chi, \quad \Phi' = \Phi - \frac{\partial \chi}{\partial t}.$$

Called Gauge Freedom/ Gauge Symmetry.

 \triangleright Use this freedom to choose χ so that (Lorenz gauge condition),

$$\mathbf{\nabla} \cdot \mathbf{A} + \frac{1}{c^2} \frac{\partial \Phi}{\partial t} = 0.$$

Maxwell's Equations look like,

$$\Box \Phi = -\frac{\rho}{\epsilon_0},$$

$$\square \mathbf{A} = -\mu_0 \mathbf{i}$$
.

The operator,

$$\Box \equiv \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$

is called the **D'Alembertian (or wave operator)**



Net force on a current carrying loop in a uniform field, B

$$\mathbf{F} = I \oint d\mathbf{x} \times \mathbf{B} = 0.$$

Net force on a current carrying loop in a uniform field, B

$$\mathbf{F} = I \oint d\mathbf{x} \times \mathbf{B} = 0.$$

Torque on a current carrying loop (origin on loop plane)

$$\tau = \mathbf{m} \times \mathbf{B}, \ \mathbf{m} \equiv I \left(\int \hat{\mathbf{n}} dS \right)$$

Net force on a current carrying loop in a uniform field, B

$$\mathbf{F} = I \oint d\mathbf{x} \times \mathbf{B} = 0.$$

Torque on a current carrying loop (origin on loop plane)

$$\tau = \mathbf{m} \times \mathbf{B}, \ \mathbf{m} \equiv I \left(\int \hat{\mathbf{n}} dS \right)$$

Potential energy in a uniform field,

$$U = -\mathbf{m} \cdot \mathbf{B}$$

Net force on a current carrying loop in a uniform field, B

$$\mathbf{F} = I \oint d\mathbf{x} \times \mathbf{B} = 0.$$

Torque on a current carrying loop (origin on loop plane)

$$\tau = \mathbf{m} \times \mathbf{B}, \ \mathbf{m} \equiv I \left(\int \hat{\mathbf{n}} dS \right)$$

Potential energy in a uniform field,

$$U = -\mathbf{m} \cdot \mathbf{B}$$

Current loop mimics the behavior of a a magnetic counterpart of electric "dipole"

$$au = \mathbf{p} \times \mathbf{E}, \quad U = -\mathbf{p} \cdot \mathbf{E}$$

Net force on a current carrying loop in a uniform field, B

$$\mathbf{F} = I \oint d\mathbf{x} \times \mathbf{B} = 0.$$

Torque on a current carrying loop (origin on loop plane)

$$\tau = \mathbf{m} \times \mathbf{B}, \ \mathbf{m} \equiv I \left(\int \hat{\mathbf{n}} dS \right)$$

Potential energy in a uniform field,

$$U = -\mathbf{m} \cdot \mathbf{B}$$

 Current loop mimics the behavior of a a magnetic counterpart of electric "dipole"

$$\tau = \mathbf{p} \times \mathbf{E}, \quad U = -\mathbf{p} \cdot \mathbf{E}$$

Vector Potential due to a current loop

$$\mathbf{A}(\mathbf{x}) = \frac{\mu_0}{4\pi} \mathbf{m}(\mathbf{x}') \times \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^3}$$

Develop Magnetization: Moment per unit volume, M

- Develop Magnetization: Moment per unit volume, M
- Magentic vector potential:

$$\begin{split} \mathbf{A}(\mathbf{x}) &= \frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \; \left(\mathbf{M}(\mathbf{x}') \times \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^3} \right) \\ &= \frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \; \mathbf{M}(\mathbf{x}') \times \boldsymbol{\nabla}' \frac{1}{|\mathbf{x} - \mathbf{x}'|} \\ &= -\frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \; \boldsymbol{\nabla}' \times \left(\frac{\mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \right) + \frac{\mu_0}{4\pi} \int \mathbf{d}^3\mathbf{x}' \; \frac{\boldsymbol{\nabla}' \times \mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \\ &= \frac{\mu_0}{4\pi} \int dS' \; \frac{\mathbf{M}(\mathbf{x}') \times \hat{\mathbf{n}}}{|\mathbf{x} - \mathbf{x}'|} + \frac{\mu_0}{4\pi} \int \mathbf{d}^3\mathbf{x}' \; \frac{\boldsymbol{\nabla}' \times \mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \\ &= \frac{\mu_0}{4\pi} \int dS \; \frac{\mathbf{k}_{bound}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} + \mu_0 \int d^3\mathbf{x} \; \frac{\mathbf{j}_{bound}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|}. \end{split}$$

- Develop Magnetization: Moment per unit volume, M
- Magentic vector potential:

$$\begin{split} \mathbf{A}(\mathbf{x}) &= \frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \, \left(\mathbf{M}(\mathbf{x}') \times \frac{\mathbf{x} - \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|^3} \right) \\ &= \frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \, \mathbf{M}(\mathbf{x}') \times \nabla' \frac{1}{|\mathbf{x} - \mathbf{x}'|} \\ &= -\frac{\mu_0}{4\pi} \int d^3\mathbf{x}' \, \nabla' \times \left(\frac{\mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \right) + \frac{\mu_0}{4\pi} \int \mathbf{d}^3\mathbf{x}' \, \frac{\nabla' \times \mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \\ &= \frac{\mu_0}{4\pi} \int dS' \, \frac{\mathbf{M}(\mathbf{x}') \times \hat{\mathbf{n}}}{|\mathbf{x} - \mathbf{x}'|} + \frac{\mu_0}{4\pi} \int \mathbf{d}^3\mathbf{x}' \, \frac{\nabla' \times \mathbf{M}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} \\ &= \frac{\mu_0}{4\pi} \int dS \, \frac{\mathbf{k}_{bound}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} + \mu_0 \int d^3\mathbf{x} \, \frac{\mathbf{j}_{bound}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|}. \end{split}$$

► Ampere's law in media: The "H field" Maxwell equation

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{j}_{free} + \mathbf{j}_{bound} \right)$$

$$= \mu_0 \left(\mathbf{j}_{free} + \nabla \times \mathbf{M} \right),$$

Maxwell eqn. for Magnetic Field in Media: Boundary conditions

Maxwell eqn. for Magnetic Field in Media: Boundary conditions

Normal component of B continuous,

$$oldsymbol{
abla} \cdot oldsymbol{B} = 0,$$
 $\Longrightarrow B_{\perp}^{over} = B_{\perp}^{under}$

Maxwell eqn. for Magnetic Field in Media: Boundary conditions

► Normal component of *B* continuous,

$$oldsymbol{
abla} \cdot oldsymbol{\mathsf{B}} = 0,$$
 $\Longrightarrow \ B_{\perp}^{\mathit{over}} = B_{\perp}^{\mathit{under}}$

► Tangential component of *H* discontinous,

$$oldsymbol{
abla} imes oldsymbol{\mathsf{H}} = oldsymbol{\mathsf{j}}_{\mathit{free}} \ \Longrightarrow \ H^{\mathit{over}}_{\parallel} - H^{\mathit{under}}_{\parallel} = \hat{\mathbf{n}} imes \mathcal{K}_{\mathit{free}}.$$

Maxwell eqn. for Magnetic Field in Media: Boundary conditions

Normal component of B continuous,

$$oldsymbol{
abla} \cdot oldsymbol{\mathsf{B}} = 0,$$
 $\Longrightarrow \ B_{\perp}^{over} = B_{\perp}^{under}$

Tangential component of H discontinous,

$$oldsymbol{
abla} imes oldsymbol{\mathsf{H}} = oldsymbol{\mathsf{j}}_{\mathit{free}} \ \Longrightarrow \ H^{\mathit{over}}_{\parallel} - H^{\mathit{under}}_{\parallel} = \hat{f n} imes \mathcal{K}_{\mathit{free}}.$$

Potential continuous, normal derivative discontinous

$$A^{over} = A^{under},$$

$$\frac{\partial A^{over}}{\partial n} - \frac{\partial A^{under}}{\partial n} = -\mu_0 K$$



$$\begin{split} \boldsymbol{\nabla} \cdot \mathbf{D} &= \rho_{\textit{free}}, \\ \boldsymbol{\nabla} \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t}, \\ \boldsymbol{\nabla} \cdot \mathbf{B} &= 0, \\ \boldsymbol{\nabla} \times \mathbf{H} &= \mathbf{j}_{\textit{free}} + \frac{\partial \mathbf{D}}{\partial t}. \end{split}$$

Now the name "Displacement current" is obvious.

$$egin{aligned} oldsymbol{
abla} \cdot \mathbf{D} &=
ho_{\mathit{free}}, \ oldsymbol{
abla} imes \mathbf{E} &= -rac{\partial \mathbf{B}}{\partial t}, \ oldsymbol{
abla} \cdot \mathbf{B} &= 0, \ oldsymbol{
abla} \cdot \mathbf{H} &= \mathbf{j}_{\mathit{free}} + rac{\partial \mathbf{D}}{\partial t}. \end{aligned}$$

Now the name "Displacement current" is obvious.

Constitutive relations:

$$\mathbf{D} = \mathbf{D}(\mathbf{E}) = \epsilon \mathbf{E},$$

$$\mathbf{H} = \mathbf{H}(\mathbf{B}) = \frac{1}{\mu} \mathbf{B}.$$

$$egin{aligned} oldsymbol{
abla} \cdot oldsymbol{\mathsf{D}} &=
ho_{\mathit{free}}, \ oldsymbol{
abla} imes oldsymbol{\mathsf{E}} &= -rac{\partial oldsymbol{\mathsf{B}}}{\partial t}, \ oldsymbol{
abla} \cdot oldsymbol{\mathsf{B}} &= 0, \ oldsymbol{
abla} imes oldsymbol{\mathsf{H}} &= oldsymbol{\mathsf{j}}_{\mathit{free}} + rac{\partial oldsymbol{\mathsf{D}}}{\partial t}. \end{aligned}$$

Now the name "Displacement current" is obvious.

Constitutive relations:

$$\begin{array}{lll} \mathbf{D} & = & \mathbf{D}(\mathbf{E}) = \epsilon \, \mathbf{E}, \\ \mathbf{H} & = & \mathbf{H}(\mathbf{B}) = \frac{1}{\mu} \mathbf{B}. \end{array}$$

Boundary conditions...



► Energy Conservation: Work done

$$dW = q\mathbf{E} \cdot d\mathbf{x} + q\mathbf{v} \times \mathbf{B} \cdot d\mathbf{x}$$
$$= \int d^3\mathbf{x} \, \mathbf{E} \cdot \mathbf{j} dt$$

Energy Conservation: Work done

$$dW = q\mathbf{E} \cdot d\mathbf{x} + q\mathbf{v} \times \mathbf{B} \cdot d\mathbf{x}$$
$$= \int d^3\mathbf{x} \, \mathbf{E} \cdot \mathbf{j} dt$$

Vector identities simplify

$$\mathbf{E} \cdot \mathbf{j} = -\frac{\partial}{\partial t} \left(\underbrace{\frac{1}{2} \epsilon_0 E^2 + \frac{1}{2} \frac{1}{\mu_0} B^2}_{u_{EM}} \right) - \mathbf{\nabla} \cdot \underbrace{\left(\frac{1}{\mu_0} \mathbf{E} \times \mathbf{B}\right)}_{\mathbf{S}}$$

Energy Conservation: Work done

$$dW = q\mathbf{E} \cdot d\mathbf{x} + q\mathbf{v} \times \mathbf{B} \cdot d\mathbf{x}$$
$$= \int d^3\mathbf{x} \, \mathbf{E} \cdot \mathbf{j} dt$$

Vector identities simplify

$$\mathbf{E} \cdot \mathbf{j} = -\frac{\partial}{\partial t} \left(\underbrace{\frac{1}{2} \epsilon_0 E^2 + \frac{1}{2} \frac{1}{\mu_0} B^2}_{u_{EM}} \right) - \nabla \cdot \underbrace{\left(\frac{1}{\mu_0} \mathbf{E} \times \mathbf{B}\right)}_{\mathbf{S}}$$

► Total Energy Conservation

$$\frac{dW}{dt} = -\frac{dU_{EM}}{dt} - \frac{1}{\mu_0} \left(\oiint_\infty dS \; \hat{\mathbf{n}}.\mathbf{S} \right), \qquad U_{EM} = \int d^3\mathbf{x} \; u_{EM}$$

Work energy theorem,

$$\frac{dW}{dt} = \frac{dU_{kinetic}}{dt} = \frac{d}{dt} \int d^3 \mathbf{x} \, u_{kinetic},$$

Local energy conservation:

$$\frac{\partial u}{\partial t} + \nabla \cdot \mathbf{S} = 0, u = u_{kinetic} + u_{EM}$$



► Local energy conservation:

$$\frac{\partial u}{\partial t} + \nabla \cdot \mathbf{S} = 0, u = u_{kinetic} + u_{EM}$$

► Local energy conservation:

$$\frac{\partial u}{\partial t} + \nabla \cdot \mathbf{S} = 0, u = u_{kinetic} + u_{EM}$$

Energy density in Electric and magnetic fields ,

$$u_{\mathsf{EM}} = rac{\epsilon_0}{2} \mathsf{E}^2 + rac{1}{2\mu_0} \mathsf{B}^2$$

"Energy flux per unit time" in Electric and Magnetic Fields,

$$\mathbf{S} = rac{1}{\mu_0} (\mathbf{E} imes \mathbf{B})$$

Force on a charge-current distribution,:

$$\mathbf{F} = \int d^3\mathbf{x} \ \underline{\rho \mathbf{E} + \mathbf{j} \times \mathbf{B}}$$

Force on a charge-current distribution,:

$$\mathbf{F} = \int d^3\mathbf{x} \ \underline{\rho \mathbf{E} + \mathbf{j} \times \mathbf{B}}$$

Using Maxwell's Eq.s and vector identities:

$$\begin{split} \mathbf{f} &= \epsilon_0 \left(\mathbf{E} \boldsymbol{\nabla} \cdot \mathbf{E} + \mathbf{E} \cdot \boldsymbol{\nabla} \mathbf{E} \right) + \frac{1}{\mu_0} \left(\mathbf{B} \boldsymbol{\nabla} \cdot \mathbf{B} + \mathbf{B} \cdot \boldsymbol{\nabla} \mathbf{B} \right) \\ &- \boldsymbol{\nabla} u_{EM} - \frac{1}{c^2} \frac{\partial \mathbf{S}}{\partial t}, \end{split}$$

Force on a charge-current distribution,:

$$\mathbf{F} = \int d^3\mathbf{x} \ \underline{\rho \mathbf{E} + \mathbf{j} \times \mathbf{B}}$$

Using Maxwell's Eq.s and vector identities:

$$\begin{split} \mathbf{f} &= & \epsilon_0 \left(\mathbf{E} \boldsymbol{\nabla} \cdot \mathbf{E} + \mathbf{E} \cdot \boldsymbol{\nabla} \mathbf{E} \right) + \frac{1}{\mu_0} \left(\mathbf{B} \boldsymbol{\nabla} \cdot \mathbf{B} + \mathbf{B} \cdot \boldsymbol{\nabla} \mathbf{B} \right) \\ &- \boldsymbol{\nabla} u_{EM} - \frac{1}{c^2} \frac{\partial \mathbf{S}}{\partial t}, \end{split}$$

► To Simplify: Introduce the Maxwell stress tensor,

$$T_{ij} = \epsilon_0 \left(E_i E_j - \frac{1}{2} \delta_{ij} \mathbf{E}^2 \right) + \frac{1}{\mu_0} \left(B_i B_j - \frac{1}{2} \delta_{ij} \mathbf{B}^2 \right)$$

Force on a charge-current distribution,:

$$\mathbf{F} = \int d^3\mathbf{x} \ \underline{\rho \mathbf{E} + \mathbf{j} \times \mathbf{B}}$$

Using Maxwell's Eq.s and vector identities:

$$\begin{split} \mathbf{f} &= & \epsilon_0 \left(\mathbf{E} \boldsymbol{\nabla} \cdot \mathbf{E} + \mathbf{E} \cdot \boldsymbol{\nabla} \mathbf{E} \right) + \frac{1}{\mu_0} \left(\mathbf{B} \boldsymbol{\nabla} \cdot \mathbf{B} + \mathbf{B} \cdot \boldsymbol{\nabla} \mathbf{B} \right) \\ &- \boldsymbol{\nabla} u_{EM} - \frac{1}{c^2} \frac{\partial \mathbf{S}}{\partial t}, \end{split}$$

To Simplify: Introduce the Maxwell stress tensor,

$$T_{ij} = \epsilon_0 \left(E_i E_j - \frac{1}{2} \delta_{ij} \mathbf{E}^2 \right) + \frac{1}{\mu_0} \left(B_i B_j - \frac{1}{2} \delta_{ij} \mathbf{B}^2 \right)$$

► Nice result:

$$\mathbf{f} = \mathbf{\nabla} \cdot \mathbf{T} - \frac{1}{c^2} \frac{\partial \mathbf{S}}{\partial t}, \quad \mathbf{\nabla} \cdot \mathbf{T} = \partial_i T_{ij}.$$



▶ Net Force on a charge-current distribution,:

$$\mathbf{F} = \int dS \,\hat{\mathbf{n}} \cdot \mathbf{T} - \frac{d}{dt} \left(\int d^3 \mathbf{x} \, \frac{\mathbf{S}}{c^2} \right)$$

▶ Net Force on a charge-current distribution,:

$$\mathbf{F} = \int dS \,\hat{\mathbf{n}} \cdot \mathbf{T} - \frac{d}{dt} \left(\int d^3 \mathbf{x} \, \frac{\mathbf{S}}{c^2} \right)$$

► Recall,

$$\mathbf{f} = \frac{\partial \mathbf{p}_{charges}}{\partial t}$$

▶ Net Force on a charge-current distribution,:

$$\mathbf{F} = \int dS \,\hat{\mathbf{n}} \cdot \mathbf{T} - \frac{d}{dt} \left(\int d^3 \mathbf{x} \, \frac{\mathbf{S}}{c^2} \right)$$

► Recall,

$$\mathbf{f} = \frac{\partial \mathbf{p}_{charges}}{\partial t}$$

Then, local conservation of momentum

$$rac{\partial}{\partial t}\left(\mathbf{p}_{charges}+rac{1}{c^2}\mathbf{S}
ight)+\mathbf{
abla}\cdot(-\mathbf{T})=0.$$

T is a the momentum flux per unit area per unit time (Momentum current density).

► So far,

- ► So far,
- ► Energy density stored in EM fields

$$u_{EM} = \frac{\epsilon_0}{2} \mathbf{E}^2 + \frac{1}{2\mu_0} \mathbf{B}^2.$$

- ► So far,
- Energy density stored in EM fields

$$u_{EM}=rac{\epsilon_0}{2}\mathbf{E}^2+rac{1}{2\mu_0}\mathbf{B}^2.$$

Linear Momentum stored in EM fields:

$$oldsymbol{\pi}_{\mathit{EM}} = rac{1}{c^2} \mathbf{S} = \epsilon_0 \left(\mathbf{E} imes \mathbf{B}
ight).$$

- ► So far,
- Energy density stored in EM fields

$$u_{EM} = \frac{\epsilon_0}{2} \mathbf{E}^2 + \frac{1}{2\mu_0} \mathbf{B}^2.$$

Linear Momentum stored in EM fields:

$$oldsymbol{\pi}_{EM} = rac{1}{c^2} \mathbf{S} = \epsilon_0 \left(\mathbf{E} imes \mathbf{B}
ight).$$

▶ What about Angular momentum (per unit volume in the field)?.

$$I_{EM}\stackrel{?}{=}\mathbf{x} imes \mathbf{\pi}_{EM}$$