Design and Implementation of hidden Markov Models

Aim:

To Design and Implement the Hidden Markov Models.

Algorithms

Step 1: We Multiply the Initial Porobability of state i with the emission perobability to observe a forom state i at time t=1.

step 2: we find the Maximum value among all the perioduct siesalts and Assign it to the viterbi variable.

Step 3: Generate Instial, Pransition and Emission perchability Distribution from the Sample Data.

Step 4: Generate, a List of all unknown sequence.

Step 5: Score all unknown Sequences and steleof the best

Step 6: Termination the following equation Depicts the perobability of the Complete state sequence.

import OS

from home.home import Discrete HHH

Lidden-Var-name = ('Sunny!, 'faggy!, 'siainy')

Observation-var-name = ('no!, 'yes')

hidden-var = f

```
hidden_van_name[o] = 0;
 hidden-var-name [i]: 1;
  hidden-far-name[2]: 2,
observation-var = ?
          observation-val-name[o]:0,
         observation-war-rame[1]=1,
  target =[]
   Obs-seq = []
with Open (os. path. join (os. path. dianame (-file -), 'input-txt')) arf:
       hidden, observe = line strip(). split(',');
       tanget. append (hidden-van [hidden])
       Obs-seq.append (observation-var Tobserve)
B= (
         (0-8,0-2),
         (0-5,0-5),
        (0-1,0.9),
 hmm= Discrete HMM (len (hilden-var), len (objeration_war), B=B)
 hmm-train (obs_seq, verbose =1)
 hmm-show model ()
Print (checksum: ', hom. check -model ())
```

Result:

Thus the Design and Implementation of Hidden Harkov Model is Succenfull and Venified the Output.

```
File Edit Format Run Options Window Help
amport os
from hmm.hmm import DiscreteHMM
# Mapping input to variable's id
hidden var name = ('sunny', 'foggy', 'rainy')
observation var name = ('no', 'yes')
hidden var = [
   hidden var name[0]: 0,
   hidden var name[1]: 1,
   hidden var name [2]: 2,
observation var = (
   observation var name[0]: 0,
   observation var name[1]: 1,
target = []
obs seq = []
with open(os.path.join(os.path.dirname(_file_), 'input.txt')) as f:
   for line in f:
       hidden, observe = line.strip().split(',')
        target.append(hidden_var[hidden])
       obs seq.append(observation var[observe])
# Setting model
8 - (
        (0.8, 0.2),
        (0.5, 0.5),
        (0.1, 0.9),
hmm = DiscreteHMM(len(hidden var), len(observation var), B=B)
# Training the model best describe the observation
hmm.train(obs_seq, verbose=1)
hmm.show model()
print('checksum:', hmm.check model())
```

train.py - C:\Users\Smart\Downloads\weather_forecast\weather_forecast\train.py (3.9.7)

```
itnum
        1 : delta 3.332041
      2 : delta 0.428877
itnum
       3 : delta 0.309993
itnum
       4 : delta 0.215055
itnum
       5 : delta 0.143531
itnum
       6 : delta 0.094136
itnum
       7 : delta 0.066443
itnum
       8 : delta 0.052992
itnum
itnum
       9 : delta 0.043964
      10 : delta 0.037234
itnum
       11 : delta 0.032206
itnum
itnum 12 : delta 0.028408
      13 : delta 0.025485
itnum
itnum 14 : delta 0.023181
itnum
      15 : delta 0.021314
      16 : delta 0.019755
itnum
      17 : delta 0.018418
itnum
itnum
      18 : delta 0.017243
      19 : delta 0.016188
itnum
itnum 20 : delta 0.015226
itnum 21 : delta 0.014339
itnum 22 : delta 0.013514
itnum 23 : delta 0.012741
       24 : delta 0.012015
itnum
itnum 25 : delta 0.011332
itnum 26 : delta 0.010709
itnum 27 : delta 0.010213
itnum
      28 : delta 0.009814
-----A: Transition probability-----
[[0.5434 0.4386 0.018 ]
10.5016 0.0854 0.413 1
[0.2865 0.1642 0.5494]]
----B: Emission probability-----
[[0.9889 0.0111]
10.8347 0.16531
[0.1272 0.8728]]
-----pi: initital state distribution-----
checksum: True
```

----- RESTART: C:\Users\user\Desktop\ML\weather forecast\train.py