

# Smart Parking Garage Controller (Two DMC8 CPUs + Handshaking, DEEDS)

<https://github.com/mahfoudh-sidi/deeds-smart-parking/tree/main/project>

**Course:** Microprocessors and Microcontrollers

**Instructor:** Dr. AHMET GÜRHANLI

**Date:** 05 / 01/ 2026

Full Name	Student ID	Signature
Yousuf Jamal Abdurahman	22040102185	
MOHAMMED BELHAIBA	22040102094	
WAEL BENALI	22040102050	
MOHAMED AL MOHAMED ALNASER	22040102155	
Emmanuel Ikechukwu Chukwu	22040102198	
Mahfoudh Sidi oumar	22040102171	

## Project Brief

This project implements a Smart Parking Garage Controller in DEEDS using DMC8 assembly. The garage capacity is 5 cars. The system detects entry/exit requests, updates the car count, controls status indicators, and transfers the count to a second processor for display. The design is implemented as a two-CPU system to demonstrate inter-processor communication.

## System Architecture (Two CPUs)

**CPU\_A (Controller):** reads sensors, applies parking rules, drives LEDs, and transmits the current count.

**CPU\_B (Display):** receives the count and shows it on a one-digit display. This separation reflects real systems where the control unit and display unit are independent.

## Components and Connections

**Inputs (to CPU\_A):**

- S\_IN (entry) → CPU\_A IA.0
- S\_OUT (exit) → CPU\_A IA.1

#### Outputs (from CPU\_A):

- GATE LED → OC.0 (short pulse on a valid entry/exit)
- FULL LED → OC.1 (ON when count = 5)
- BLOCKED LED → OC.2 (ON when entry is attempted while full)

#### Display (from CPU\_B):

- One Hex Digit display → CPU\_B OC (low nibble) showing 0..5

## Inter-CPU Communication

The system uses polling to monitor sensors and handshake lines, and it uses a bidirectional STB/ACK handshaking protocol for reliable CPU-to-CPU communication.

The output of CPU\_A is used as the input of CPU\_B through a parallel bus and two control lines:

- Data: CPU\_A OA[7..0] → CPU\_B IA[7..0]
- STB (strobe): CPU\_A OB.0 → CPU\_B IB.0
- ACK (acknowledge): CPU\_B OB.0 → CPU\_A IB.0

Protocol summary: CPU\_A places the count on OA and raises STB. CPU\_B detects STB, reads the count, updates the display, then raises ACK. CPU\_A clears STB, and CPU\_B clears ACK. This prevents missed/overwritten data.

## Software Behavior (Summary)

#### CPU\_A:

- Polls IA.0/IA.1 and uses edge detection so each press is counted once.
- Maintains COUNT in the range 0..5.
- Valid entry: COUNT++, gate pulse.
- Valid exit: COUNT--, gate pulse.
- At COUNT=5: FULL ON.
- Entry attempt while full: BLOCKED ON; count does not increase.
- After each event, sends COUNT to CPU\_B using the handshake.

#### CPU\_B:

- Waits for STB, reads COUNT from IA, outputs it to the one-digit display, then ACKs.

## Testing and Expected Output

1. Entry test: toggle S\_IN repeatedly → display: 0 → 1 → 2 → 3 → 4 → 5, GATE pulses each time.
2. Full condition: at 5 → FULL LED stays ON.
3. Entry while full: press S\_IN → BLOCKED LED turns ON; display remains 5; entry is denied.
4. Exit test: press S\_OUT → display decreases (5 → 4 → ...), GATE pulses; FULL turns OFF when count < 5.