

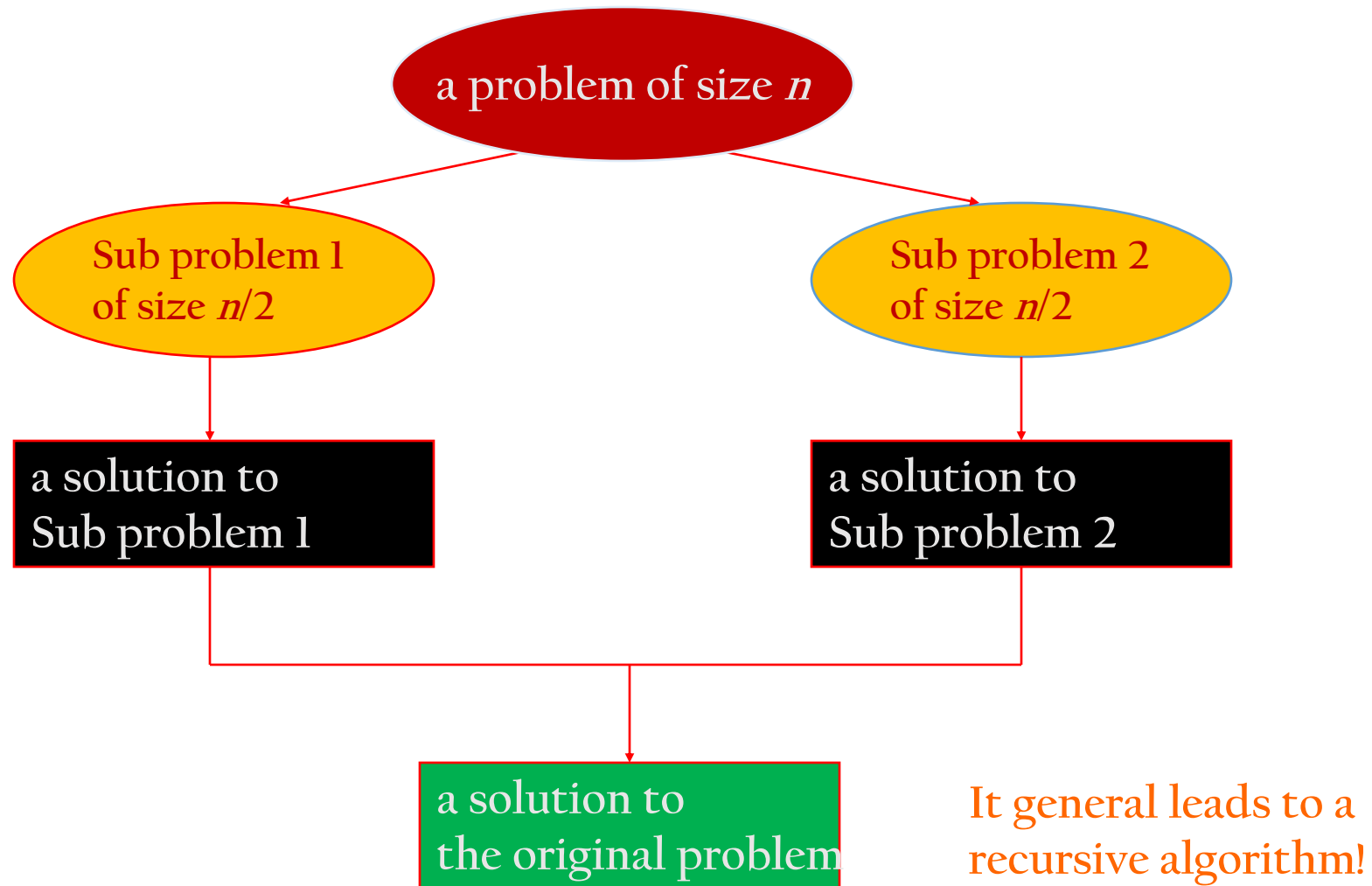
Chapter - 2

Divide and Conquer Algorithms

Essence of Divide and Conquer

- In divide and conquer approach, the problem in hand, is divided into smaller sub-problems and then each problem is solved independently.
- When we keep on dividing the sub problems into even smaller sub-problems, we may eventually reach a stage where no more division is possible.
- Those "atomic" smallest possible sub-problem (fractions) are solved. The solution of all sub-problems is finally merged in order to obtain the solution of an original problem.

Divide-and-Conquer Technique

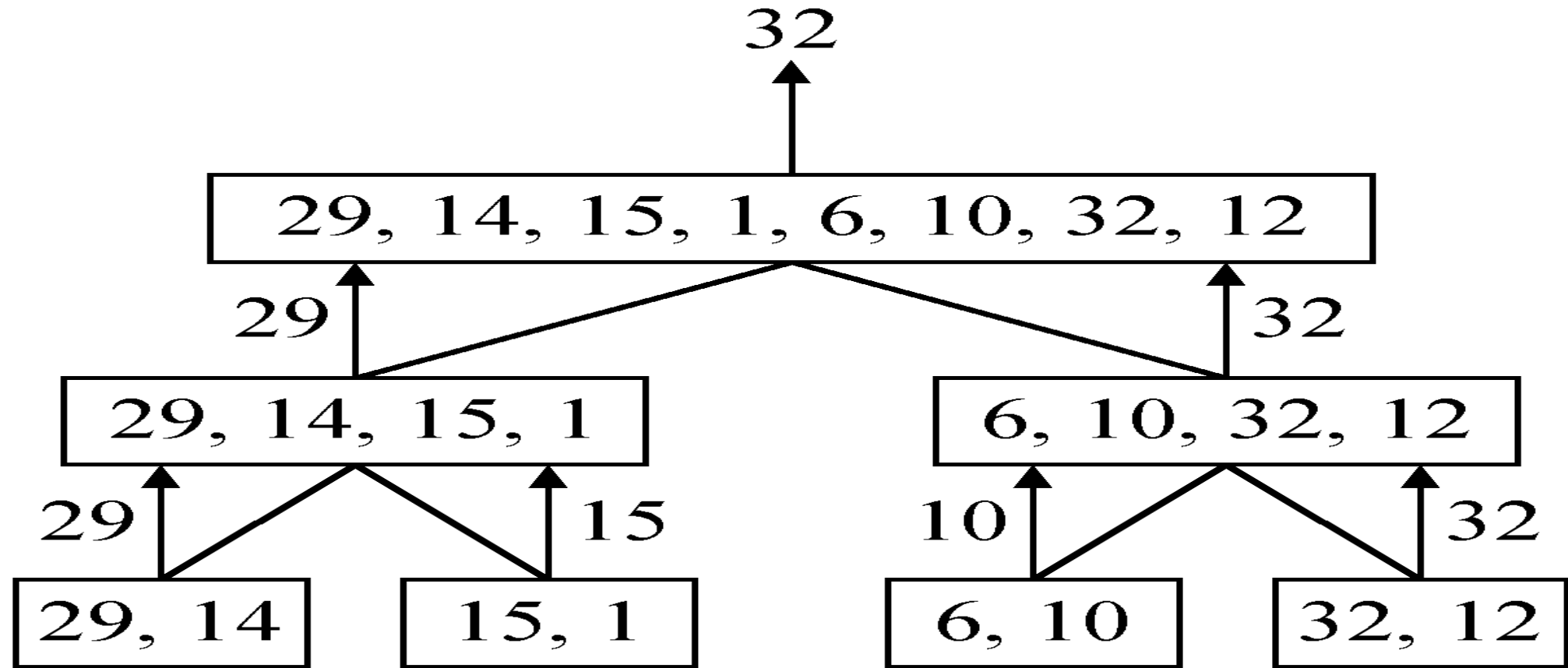


divide-and-conquer steps

- Broadly, we can understand *divide-and-conquer* approach in a three-step process.
 - 1) *Divide*: a problem to be solved is broken into a number of sub problems. Normally, the sub problems are similar to the original
 - 2) *Conquer*: the sub problems are then solved independently, usually recursively.
 - 3) *Combine*: finally, the solutions to the sub problems are combined to provide the answer to the original problem. The solutions to get a solution to the sub problems And finally a solution to the original problem.
- *Divide and Conquer* algorithms are normally recursive.

A simple example

- finding the maximum of a set S of n numbers



A general divide-and-conquer algorithm

Step 1: If the problem size is small, solve this problem directly; otherwise, split the original problem into 2 sub-problems with equal sizes.

Step 2: Recursively solve these 2 sub-problems by applying this algorithm.

Step 3: Merge the solutions of the 2 sub-problems into a solution of the original problem.

```
DAC(problem P)
{
    if Small(P) return S(P);
    else {
        divide P into smaller instances  $P_1, P_2, \dots, P_k, k \geq 1$ ;
        Apply DAC to each of these subproblems;
        return Combine(DAC( $P_1$ ), DAC( $P_2$ ), ..., DAC( $P_k$ ));
    }
}
```

Application of divide-and-conquer

- The following computer algorithms are based on **divide-and-conquer** programming approach –
 1. Finding Max and Min
 2. binary Search
 3. Merge Sort
 4. Quick Sort
 5. Strassen's Matrix Multiplication

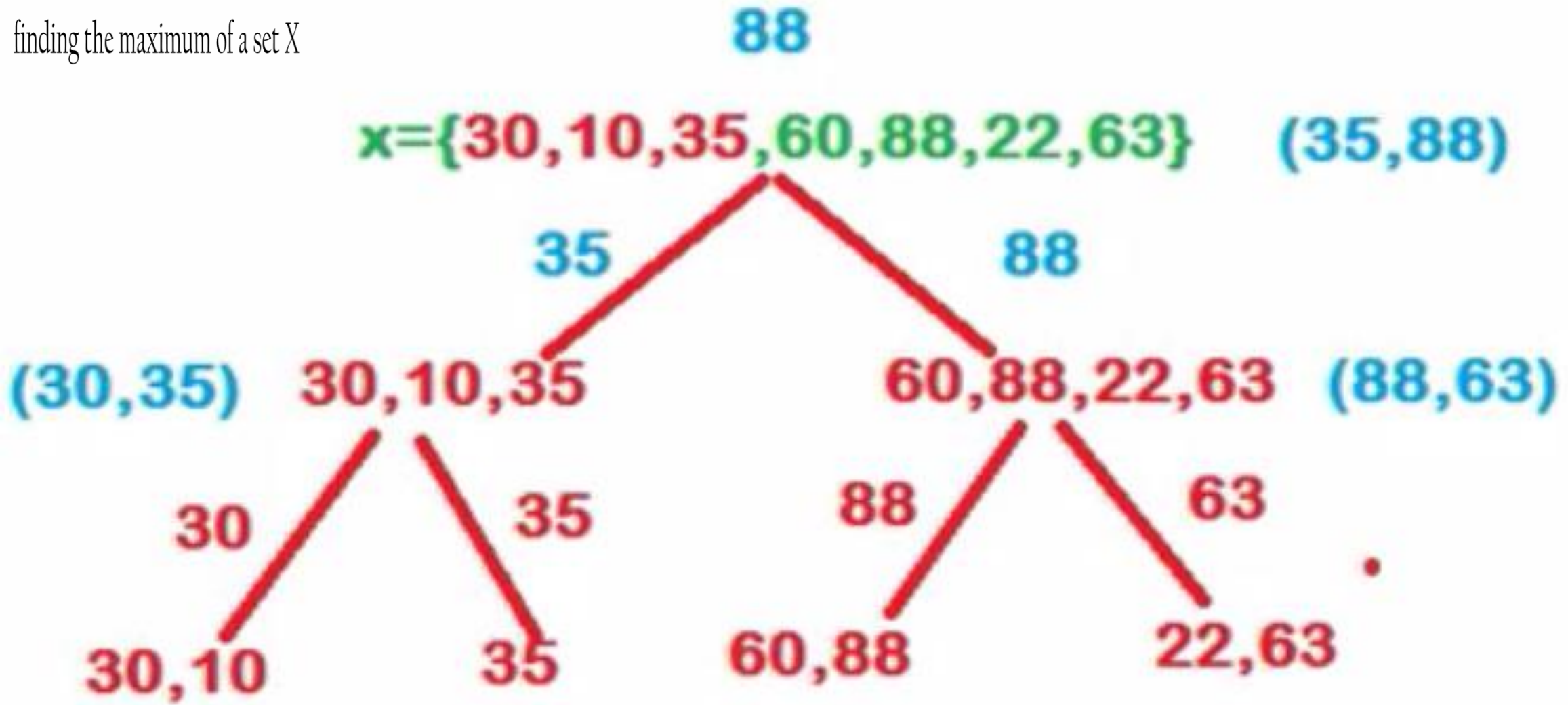
Note: There are various ways available to solve any computer problem, but the mentioned are a good example of divide and conquer approach.

Cont....

- *sorting*: ordering a list of values
- *searching*: finding the position of a value within a list
- Algorithm analysis should begin with a clear statement of the task to be performed.
- This allows us both to check that the algorithm is correct and to ensure that the algorithms we are comparing perform the same task.
- Although there are many ways that algorithms can be compared, we will focus on two that are of primary importance to many data processing algorithms:
- *time complexity*: how the number of steps required depends on the size of the input
- *space complexity*: how the amount of extra memory or storage required depends on the size of the input

1. Finding Max and Min

finding the maximum of a set X



Algorithm for maximum and minimum using divide-and-conquer

MaxMin(i, j, max, min)

// a[1:n] is a global array. Parameters i and j are integers, // $1 \leq i \leq j \leq n$. The effect is to set max and min to the largest and // smallest values in a[i:j].

```
{
  if (i=j) then max := min := a[i]; //Small(P)
  else if (i=j-1) then // Another case of Small(P)
    {
      if (a[i] < a[j]) then max := a[j]; min := a[i];
      else max := a[i]; min := a[j];
    }
  else
  {
    // if P is not small, divide P into sub-problems.
    // Find where to split the set.
    mid := ( i + j )/2;
    // Solve the sub-problems.
    MaxMin( i, mid, max, min );
    MaxMin( mid+1, j, max1, min1 );
    // Combine the solutions.
    if (max < max1) then max := max1;
    if (min > min1) then min := min1;
  }
}}
```

Complexity:

Now what is the number of element comparisons needed for MaxMin? If $T(n)$ represents this number, then the resulting recurrence relation is

$$T(n) = \begin{array}{ll} 0 & n=1 \\ 1 & n=2 \\ T(n/2) + T(n/2) + 2 & n>2 \end{array}$$

Note that $3n/2 - 2$ is the best, average, worst case number of comparison when n is a power of two.

2.

binary search

- **divide** sequence into two halves by comparing search key to midpoint
- **recursively** search in one of the two halves
- **combine** step is empty

Algorithm binary-search

Input: A sorted sequence of n elements stored in an array.

Output: The position of x (to be searched).

Step 1: If only one element remains in the array, solve it directly.

Step 2: Compare x with the middle element of the array.

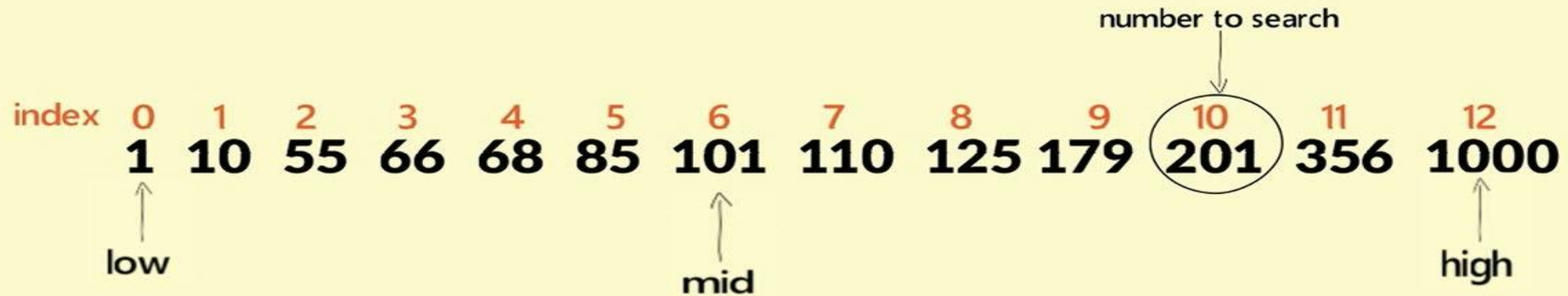
Step 2.1: If $x =$ middle element, then output it and stop.

Step 2.2: If $x <$ middle element, then recursively solve the problem with x and the left half array.

Step 2.3: If $x >$ middle element, then recursively solve the problem with x and the right half array.

Example of BinSearch

BINARY SEARCH ALGORITHM



$$\text{mid} = \frac{\text{low} + \text{high}}{2} = \frac{0 + 12}{2} = 6$$

Algorithm BinSearch(a, low, high, x)

```
// a[]: sorted sequence in nondecreasing order
// low, high: the bounds for searching in a []
// x: the element to be searched
// If  $x = a[j]$ , for some  $j$ , then return  $j$  else return  $-1$ 
if (low > high) then return  $-1$            // invalid range
if (low = high) then                      // if small P
    if ( $x == a[i]$ ) then return  $i$ 
    else return  $-1$ 
else // divide P into two smaller subproblems
    mid = (low + high) / 2
    if ( $x == a[mid]$ ) then return mid
    else if ( $x < a[mid]$ ) then
        return BinSearch(a, low, mid-1, x)
    else return BinSearch(a, mid+1, high, x)
```

Binary Search

Precondition: S is a sorted list

index binsearch(number n, index low, index high,

const keytype S[], keytype x)

if $\text{low} \leq \text{high}$ then

mid = $(\text{low} + \text{high}) / 2$

if $x = S[\text{mid}]$ then

return mid

elsif $x < S[\text{mid}]$ then

return binsearch(n, low, mid-1, S, x)

else

return binsearch(n, mid+1, high, S, x)

else

return 0

end binsearch

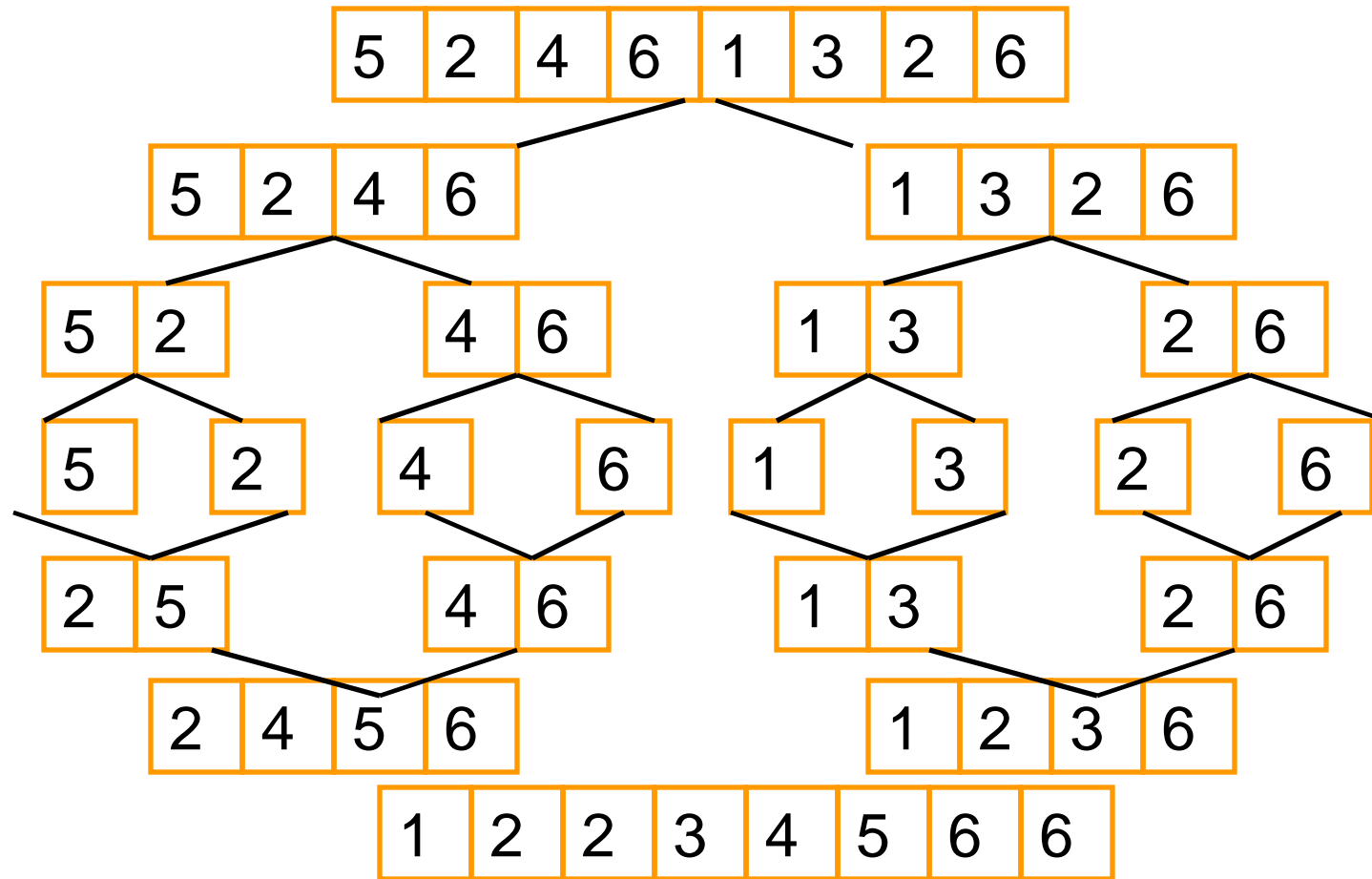
Analysis of Binary Search

- **Time efficiency $T(N) = T(N/2) + 1$**
 - Worst case: $O(\log(n))$
 - Best case: $O(1)$
- **Optimal for searching a sorted array**
- **Limitations: must be a sorted array
(not linked list)**

3. Merge sort

- **DIVIDE** the input sequence in half
- **RECURSIVELY** sort the two halves. Basis of the recursion is sequence with 1 key
- **COMBINE** the two sorted subsequences by merging them

Merge sort Example



Merge sort

- Split array $A[0..n-1]$ in two about equal halves and make copies of each half in arrays B and C
- Sort arrays B and C recursively
- Merge sorted arrays B and C into array A as follows:
 - Repeat the following until no elements remain in one of the arrays:
 - compare the first elements in the remaining unprocessed portions of the arrays
 - copy the smaller of the two into A, while incrementing the index indicating the unprocessed portion of that array
 - Once all elements in one of the arrays are processed, copy the remaining unprocessed elements from the other array into A.

Merge Sort algorithm

- The Merge Sort function keeps on splitting an array into two halves until a condition is met where we try to perform Merge Sort on a subarray of size 1, i.e., **p == r**.
- And then, it combines the individually sorted subarrays into larger arrays until the whole array is merged.

1.ALGORITHM-MERGE SORT

2.1. If $p < r$

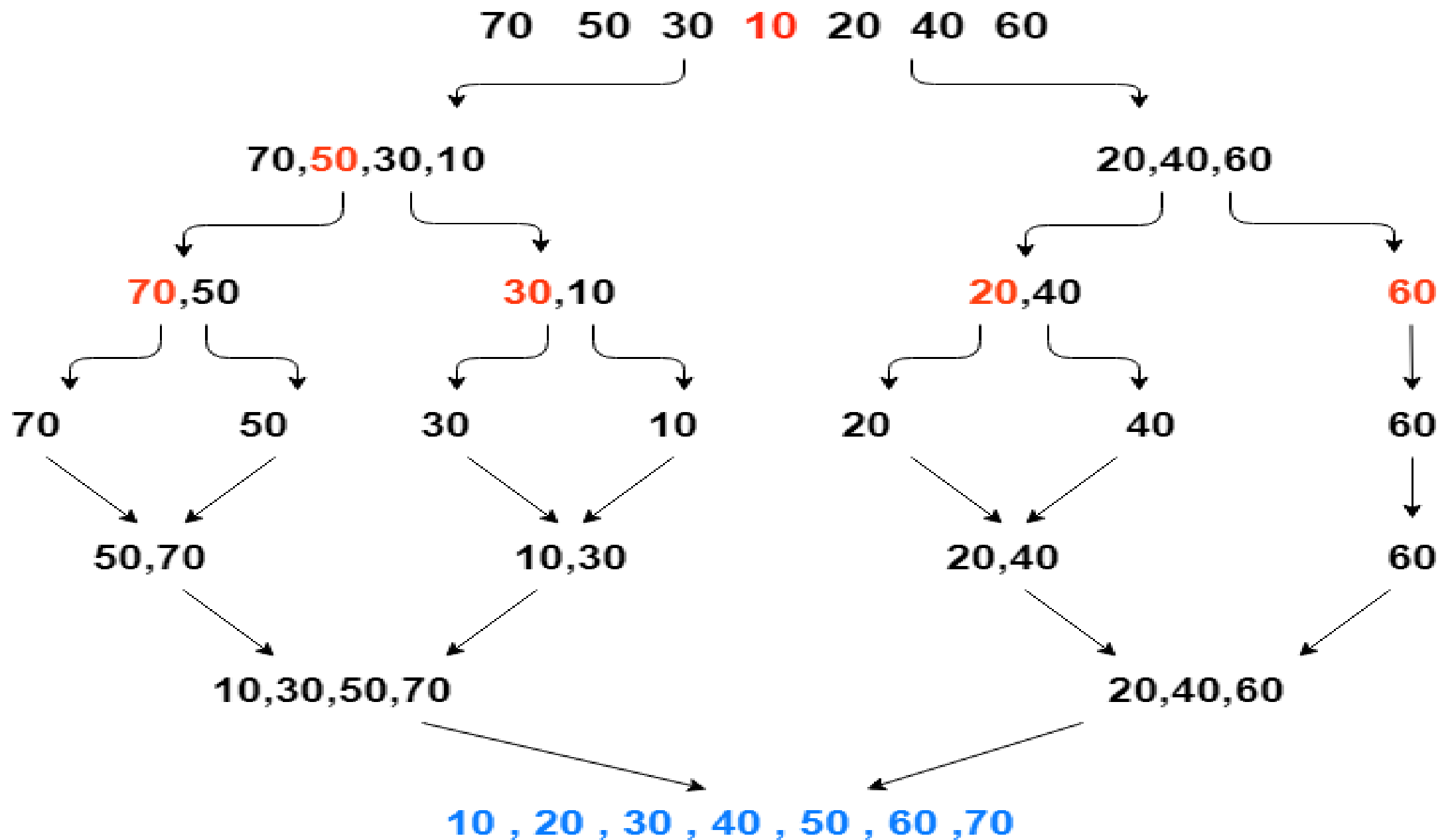
3.2. Then $q \rightarrow (p + r) / 2$

4.3. MERGE-SORT (A, p, q)

5.4. MERGE-SORT (A, q+1,r)

6.5. MERGE (A, p, q, r)

- Here we called **MergeSort(A, 0, length(A)-1)** to sort the complete array.
- As you can see in the image given below, the merge sort algorithm recursively divides the array into halves until the base condition is met, where we are left with only 1 element in the array. And then, the merge function picks up the sorted sub-arrays and merge them back to sort the entire array.
- The following figure illustrates the dividing (splitting) procedure.



Algorithm Merge-Sort

Input: A set S of n elements.

Output: The sorted sequence of the inputs in non decreasing order.

Step 1: If $|S| \leq 2$, solve it directly.

Step 2: Recursively apply this algorithm to solve the left half part and right half part of S , and the results are stored in S_1 and S_2 , respectively.

Step 3: Perform the two-way merge scheme on S_1 and S_2 .

Method of Solving Recurrences

1. Substitution method
2. Iteration method
3. Master method

3. Master Theorem (Simplified)

Theorem: (Simplified Master Theorem) Let $a \geq 1$, $b > 1$ be constants and let $T(n)$ be the recurrence

$$T(n) = aT(n/b) + n^k,$$

defined for $n \geq 0$. (As usual let us assume that n is a power of b . The basis case, $T(1)$ can be any constant value.) Then

Case 1: if $a > b^k$ then $T(n) \in \Theta(n^{\log_b a})$.

Case 2: if $a = b^k$ then $T(n) \in \Theta(n^k \log n)$.

Case 3: if $a < b^k$ then $T(n) \in \Theta(n^k)$.

master method:

- ❖ a is the number of subproblems that are solved recursively; i.e. the number of recursive calls.
- ❖ b is the size of each subproblem relative to n ; n/b is the size of the input to the recursive call.
- ❖ $f(n)$ is the cost of dividing and recombining the subproblems.

Master Theorem

- Let $T(n)$ be a monotonically increasing function that satisfies

$$T(n) = a T(n/b) + f(n)$$

$$T(1) = c$$

where $a \geq 1$, $b \geq 2$, $c > 0$. If $f(n)$ is $\Theta(n^d)$ where $d \geq 0$ then

$$T(n) = \begin{cases} \Theta(n^d) & \text{if } a < b^d \\ \Theta(n^d \log n) & \text{if } a = b^d \\ \Theta(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$

Master Theorem: Pitfalls

- You **cannot** use the Master Theorem if
 - $T(n)$ is not monotone, e.g. $T(n) = \sin(x)$
 - $f(n)$ is not a polynomial, e.g., $T(n)=2T(n/2)+2^n$
 - b cannot be expressed as a constant, e.g. $T(n) = T(\sqrt{n})$
- The three cases of the master theorem do not cover all possibilities.
- The master theorem provides a general method for solving recurrences

Master Theorem: Example 1

- Let $T(n) = T(n/2) + \frac{1}{2}n^2 + n$. What are the parameters?

$$a = 1$$

$$b = 2$$

$$d = 2$$

Therefore, which condition applies?

$1 < 2^2$, case 1 applies

- We conclude that

$$T(n) \in \Theta(n^d) = \Theta(n^2)$$

Master Theorem: Example 2

- Let $T(n) = 2 T(n/4) + \sqrt{n} + 42$. What are the parameters?

$$a = 2$$

$$b = 4$$

$$d = 1/2$$

Therefore, which condition applies?

$$2 = 4^{1/2}, \text{ case 2 applies}$$

- We conclude that

$$T(n) \in \Theta(n^d \log n) = \Theta(\log n \sqrt{n})$$

Master Theorem: Example 3

- Let $T(n) = 3T(n/2) + 3/4n + 1$. What are the parameters?

$$a = 3$$

$$b = 2$$

$$d = 1$$

Therefore, which condition applies?

$3 > 2^1$, case 3 applies

- We conclude that

$$T(n) \in \Theta(n^{\log_b a}) = \Theta(n^{\log_2 3})$$

- Note that $\log_2 3 \approx 1.584...$, can we say that $T(n) \in \Theta(n^{1.584})$

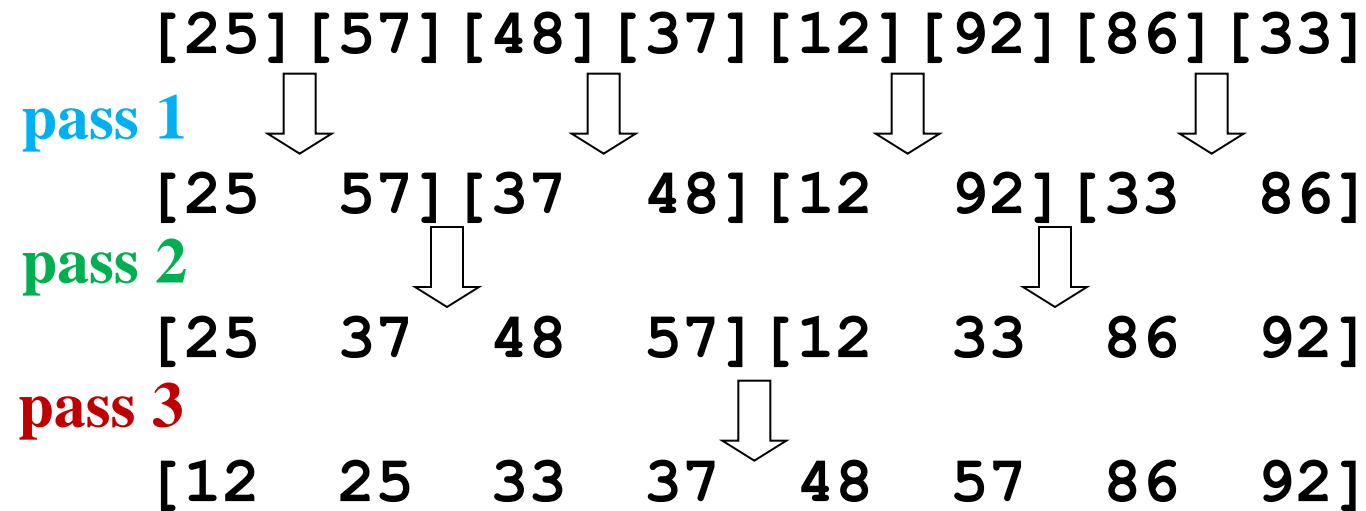
No, because $\log_2 3 \approx 1.5849...$ and $n^{1.584} \notin \Theta(n^{1.5849})$

Recurrence Relation for Merge sort

- Let $T(n)$ be worst case time on a sequence of n keys
- If $n = 1$, then $T(n) = \Theta(1)$ (constant)
- If $n > 1$, then $T(n) = 2 T(n/2) + \Theta(n)$
 - two sub problems of size $n/2$ each that are solved recursively
 - $\Theta(n)$ time to do the merge

Merge sort

- Sort into nondecreasing order



- $\log_2 n$ passes are required.
- time complexity: $O(n \log n)$

Time complexity

- Time complexity:

$T(n)$: # of comparisons

$$T(n) = \begin{cases} 2T(n/2) + 1 & , n > 2 \\ 1 & , n \leq 2 \end{cases}$$

- Calculation of $T(n)$:

Assume $n = 2^k$,

$$\begin{aligned} T(n) &= 2T(n/2) + 1 \\ &= 2(2T(n/4) + 1) + 1 \\ &= 4T(n/4) + 2 + 1 \\ &\quad \vdots \\ &= 2^{k-1}T(2) + 2^{k-2} + \dots + 4 + 2 + 1 \\ &= 2^{k-1} + 2^{k-2} + \dots + 4 + 2 + 1 \\ &= 2^k - 1 = n - 1 \end{aligned}$$

Time complexity of the general algorithm

- Time complexity:

$$T(n) = \begin{cases} 2T(n/2) + S(n) + M(n) & , n \geq c \\ b & , n < c \end{cases}$$

where $S(n)$: time for splitting

$M(n)$: time for merging

b : a constant

c : a constant

Best case: split in the middle — $\Theta(n \log n)$

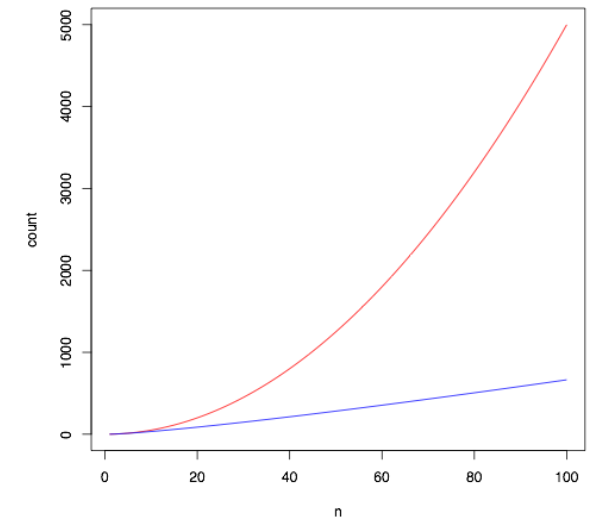
Worst case: sorted array! — $\Theta(n^2)$

Average case: random arrays — $\Theta(n \log n)$

Note: Considered the method of choice for internal sorting of large files ($n \geq 10000$)

Recap: Divide and Conquer Algorithms

- The divide and conquer strategy often reduces the number of iterations of the main loop from n to $\log_2 n$
 - binary search: $\mathcal{O}(\log_2 n)$
 - merge sort: $\mathcal{O}(n \times \log_2 n)$
 - Quick Sort: $\mathcal{O}(n \times \log_2 n)$
- It may not look like much, but the reduction in the number of iterations is significant for larger problems





5. Strassen's Matrix Multiplication

- First we will discuss the general method of matrix multiplication and later we will discuss Strassen's matrix multiplication algorithm

Problem Statement

- Let us consider two matrices A and B . We want to calculate the resultant matrix C by multiplying A and B .

Method

- First, we will discuss naïve method and its complexity. Here, we are calculating $C = A \times B$. Using Naïve method, two matrices (A and B) can be multiplied if the order of these matrices are $p \times q$ and $q \times r$. Following is the algorithm

Algorithm: Matrix-Multiplication (X, Y, Z)

for i = 1 to p do

for j = 1 to r do

Z[i,j] := 0

for k = 1 to q do

Z[i,j] := Z[i,j] + X[i,k] × Y[k,j]

Complexity

- Here, we assume that integer operations take **$O(1)$** time. There are three **for** loops in this algorithm and one is nested in other. Hence, the algorithm takes **$O(n^3)$** time to execute.

Strassen's Matrix Multiplication Algorithm

- In this context, using Strassen's Matrix multiplication algorithm, the time consumption can be improved a little bit.

Matrix Multiplication

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \times \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{bmatrix}$$

A B C

Multiplications: **8**

Additions: **4**

Addition of 2 matrices takes **$O(N^2)$** time.

$$T(N) = 8T(N/2) + O(N^2)$$

Time Complexity of the above method is **$O(N^3)$** .

Faster Matrix Multiplication

- Clever idea due to Strassen
- Start with a recursive version of the straight forward algorithm
 - divide A , B and C into 4 quadrants
 - compute the 4 quadrants of C by doing 8 matrix multiplications on the quadrants of A and B , plus $\Theta(n^2)$ scalar operations

Strassen's Matrix Multiplication

- There is a way to get all the required information with only 7 matrix multiplications, instead of 8.
- Recurrence for new algorithm is
 - $T(n) = 7T(n/2) + \Theta(n^2)$

You just need to remember 4 Rules :

- AHED (Learn it as 'Ahead')
- Diagonal
- Last **CR**
- First **CR**

Also, consider X as (Row **+**) and Y as (Column **-**)
matrix

$$\begin{aligned} p1 &= a(f - h) \\ p3 &= (c + d)e \\ p5 &= (a + d)(e + h) \\ p7 &= (a - c)(e + f) \end{aligned}$$

$$\begin{aligned} p2 &= (a + b)h \\ p4 &= d(g - e) \\ p6 &= (b - d)(g + h) \end{aligned}$$

The $A \times B$ can be calculated using above seven multiplications.
Following are values of four sub-matrices of result C

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \times \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} p5 + p4 - p2 + p6 & p1 + p2 \\ p3 + p4 & p1 + p5 - p3 - p7 \end{bmatrix}$$

$X \qquad Y \qquad C$

X , Y and C are square matrices of size $N \times N$

a , b , c and d are submatrices of A , of size $N/2 \times N/2$

e , f , g and h are submatrices of B , of size $N/2 \times N/2$

$p1$, $p2$, $p3$, $p4$, $p5$, $p6$ and $p7$ are submatrices of size $N/2 \times N/2$

$$X = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

$$Y = \begin{bmatrix} E & F \\ G & H \end{bmatrix}$$

- AHED
- Diagonals
- Last CR
- First CR

Check for Row (+)

$$X = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

Check for Column (-)

$$Y = \begin{bmatrix} E & F \\ G & H \end{bmatrix}$$

- AHED
- Diagonals
- Last CR
- First CR

Check for Row (+)

$$X = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

Check for Column (-)

$$Y = \begin{bmatrix} E & F \\ G & H \end{bmatrix}$$

- AHED
- Diagonals
- Last CR
- First CR

Idea: Reduce the number of recursive calls to 7.

Formula:

$$p1 = a(f-h)$$

$$p2 = (a+b)h$$

$$p3 = (c+d)e$$

$$p4 = d(g-e)$$

$$p5 = (a+d)(e+h)$$

$$p6 = (b-d)(g+h)$$

$$p7 = (a-c)(e+f)$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \times \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} p5 + p4 - p2 + p6 & p1 + p2 \\ p3 + p4 & p1 + p5 - p3 - p7 \end{bmatrix}$$

A B C

A, B and C are square matrices of size $N \times N$

a, b, c and d are submatrices of A, of size $N/2 \times N/2$

e, f, g and h are submatrices of B, of size $N/2 \times N/2$

$p1, p2, p3, p4, p5, p6$ and $p7$ are submatrices of size $N/2 \times N/2$

Complexity in Strassen matrix

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}_A \times \begin{bmatrix} e & f \\ g & h \end{bmatrix}_B = \begin{bmatrix} p_5 + p_4 - p_2 + p_6 & p_1 + p_2 \\ p_3 + p_4 & p_1 + p_5 - p_3 - p_7 \end{bmatrix}_C$$

Multiplications: **7**

Addition & Subtraction of 2 matrices takes **$O(N^2)$** time.

$$T(N) = 7T(N/2) + O(N^2)$$

Time Complexity of the above method is **$O(N^{\log 7})$**

example

	$\begin{bmatrix} 1 & 0 \\ -3 & 2 \end{bmatrix} \cdot \begin{bmatrix} -1 & 4 \\ 3 & 5 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ -3 & 2 \end{bmatrix} \cdot \begin{bmatrix} -1 & 4 \\ 3 & 5 \end{bmatrix}$	
1st Row Times 1st Column	$\begin{bmatrix} (1)(-1) + (0)(3) \\ -1 + 0 \\ -1 \end{bmatrix}$	$\begin{bmatrix} (1)(4) + (0)(5) \\ 4 + 0 \\ 4 \end{bmatrix}$	1st Row Times 2nd Column
2nd Row Times 1st Column	$\begin{bmatrix} (-3)(-1) + (2)(3) \\ 3 + 6 \\ 9 \end{bmatrix}$	$\begin{bmatrix} (-3)(4) + (2)(5) \\ -12 + 10 \\ -2 \end{bmatrix}$	2nd Row Times 2nd Column
	$\begin{bmatrix} 1 & 0 \\ -3 & 2 \end{bmatrix} \cdot \begin{bmatrix} -1 & 4 \\ 3 & 5 \end{bmatrix}$	$\begin{bmatrix} 1 & 0 \\ -3 & 2 \end{bmatrix} \cdot \begin{bmatrix} -1 & 4 \\ 3 & 5 \end{bmatrix}$	
Final Answer: $\begin{bmatrix} -1 & 4 \\ 9 & -2 \end{bmatrix}$			

General Divide-and-Conquer Recurrence

$$T(n) = aT(n/b) + f(n) \quad \text{where } f(n) \in \Theta(n^d), \quad d \geq 0$$

Master Theorem: If $a < b^d$, $T(n) \in \Theta(n^d)$
 If $a = b^d$, $T(n) \in \Theta(n^d \log n)$
 If $a > b^d$, $T(n) \in \Theta(n^{\log_b a})$

Note: The same results hold with O instead of Θ .

Examples: $T(n) = 4T(n/2) + n \Rightarrow T(n) \in ?$ $\Theta(n^2)$

$T(n) = 4T(n/2) + n^2 \Rightarrow T(n) \in ?$ $\Theta(n^2 \log n)$

$T(n) = 4T(n/2) + n^3 \Rightarrow T(n) \in ?$ $\Theta(n^3)$
 $T(n) = 7T(n/2) + n^2 \Rightarrow T(n) \in ?$ $\Theta(n^{\log_2 7}) = \Theta(n^{2.1})$
(Strassen's Algorithm for Matrix Multiplication)

A wide-angle photograph of a two-lane asphalt road stretching straight into the distance. The road is flanked by dry, yellowish-brown grass and low-lying shrubs. In the background, a range of rugged mountains is visible, with some peaks partially obscured by low-hanging clouds or mist. The sky is overcast with grey clouds. The overall mood is one of a long journey or a path leading to a destination.

Learning is key to success