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### Education

#### **Bachelor of Science in Computer Engineering**

Tehran, IR. Iran

AMIRKABIR UNIVERSITY OF TECHNOLOGY

Sep. 2017 - Exp. Jul. 2020

Software · Major:

Multi-Agent Deep Reinforcement Learning on Soccer Robot Thesis Title:

The goal of this project is to accomplish a simple task of a soccer match by using **DeepRL** on a **multi-agent robots**, to reach this goal; I implemented a 3D soccer simulator, a distributed multi-agent software architecture and a MARL method on the ROS framework.

#### **Bachelor of Science in Electrical Engineering**

Tehran, IR. Iran

Mar. 2015 - Exp. Jul. 2017

AMIRKABIR UNIVERSITY OF TECHNOLOGY

Telecommunication Maior:

- Entering Top Technical University of Iran as a Talented Student without taking national exam when I was 16.
- Withdrawal at the end of the second year to focus on Software Engineering

## Research Interests

Theory Artificial Intelligence, Reinforcement Learning, Game Theory, Ethics and Sociology

Practice Robotics, Multi-Agent Systems, Big-Data and Distributed Processing, Web and Information retrieval

# Research Experience\_

#### Multi-Agent Robotic & Al Researcher

4-Years

PARSIAN ROBOTIC LABORATORY - PROF. MOHAMMAD AZAM KHOSRAVI

Feb. 2015 - Feb. 2019

- Implementation of the AI and the Optimization algorithms for real-time vision-guided multi-agent soccer robotic A.K.A.ROBOCUP SSL.
- Implementation of a Reinforcement Learning for kick-off plan positioning.
- Implementation of a user-friendly Graphical Plan Designer and Plan Execution Engine that anyone can design a strategy without any code.
- More than 2 years of **Leadership Experience** in a team larger than 20 members.
- Developer and Maintainer of Grsim the official open-source simulator of Robocup-SSL (+21 contributors, +68 forks).
- Re-basing the Robocup SSL base code from monolithic to a multi-agent distributed architecture on ROS framework.
- Implementation of **Auto-Tuning** of **PID** controller by **PSO** and **Genetic** Algorithms.
- implementation of Path Planning for Multi-Agent soccer robots with a Visibility Graph and Extended RRT\* approach.

### **Publication**

#### **ROS-based Architecture for Multi-agent Soccer Robots**

FIRA World Cup and Summit

FIRA ROBOWORLDCUP AND CONGRESS 2019

2019

- Extended Abstract: Multi-Agent Architecture for Soccer Robots based on ROS, M.M. Rahimi et al. Link
- 3-Min Oral Presentation, M.M. Rahimi Link

### **Parsian Extended Team Description Paper**

RoboCup Competitions

2015 - 2019

THE ANNUAL ROBOCUP INTERNATIONAL SYMPOSIUM

- PARSIAN 2019 Extended Team Description Paper, K. Behzad et al.
- PARSIAN 2018 Extended Team Description Paper, M.M. Rahimi et al. Link
- PARSIAN 2017 Extended Team Description Paper, M.M. Rahimi et al. Link PARSIAN 2016 Extended Team Description Paper, M.M. Rahimi et al. Link
- PARSIAN 2015 Extended Team Description Paper, A. Zolanvari et al. Link

#### **OPEM: Open Source PEM Cell Simulation Tool**

JOSS

2018

THE JOURNAL OF OPEN SOURCE SOFTWARE

• Report about Implementation and Usage of the OPEM package.

· Published On The Journal of Open Source Software. Link

#### **QPage: Free Project For Creating Academic Homepage Without Any Code**

7enodo

2017

**DEVELOPER AND AUTHOR** 

- Report about Implementation and Usage of the QPage package.

· Published On Zenodo . Link

# **Program Committees**

2019	Advisory Board, Al WorldCup	S. Korea, KAIST
2019	League Co-Chair, Fira RoboWorld Cup	S. Korea, Changwon
2019	League Chair, FIRACup IranOpen	Iran, AUT
2018	Technical Committee, Fira RoboWorld Cup	Taiwan, NTNU
2018	Technical Committee, AI WorldCup	S. Korea, KAIST
2018	Technical Committee, Robocup IranOpen	Iran, QAIU
2018	Technical Committee, FIRACup IranOpen	Iran, AUT
2017	Technical Committee, FIRACup IranOpen	Iran, AUT
2017	Organization Committee, Robocup IranOpen	Iran, QAIU
2016	Organization Committee, FIRACup IranOpen	Iran, AUT

## **Honors & Awards**

#### INTERNATIONAL

2019	EurAl Full-Travel Grant, The 2019 ACAI Summer School: AI for Multi-Agent Worlds	
2018	Finalist, Top 14 Among 3,224 Teams, Alibaba (Tianchi) BigData Competition: Zero Shot Image Recognition	China
2018	Finalist, Top 40 Among 780 Teams, Russian Al Challenge: Code Ball (3D multi-agent soccer simulation)	Russia
2018	<b>3rd Place</b> , FIRA Robo World Cup: 2D Soccer Simulation	Taichung, Taiwan
2018	<b>3rd Place</b> , FIRA Robo World Cup: Robot Challenge Simulation	Taichung, Taiwan
2017	4th Place, RoboCup: Small Size League	Nagoya, Japan
2016	<b>6th Place</b> , RoboCup: Small Size League	Leipzig, Germany
2015	8th Place, RoboCup: Small Size League	Hefei, China
2014	<b>1st Place</b> , RoboCup: Junior Soccer League	Joao Pessoa, Brasil
2014	Spirit of RoboCup Award, RoboCup: Junior Soccer League	Joao Pessoa, Brasil
2014	Best Poster and Presentation Award, RoboCup: Junior Soccer League	Joao Pessoa, Brasil

#### **DOMESTIC**

2017	Technical Challenge Championship, IranOpen RoboCup: Small Size League	Tehran, Iran
2017	<b>3rd Place</b> , IranOpen RoboCup: Small Size League	Tehran, Iran
2017	4th Place Among 964 Teams, Sharif AI Challenge 2017	Tehran, Iran
2016	1st Place, IranOpen Fira RoboWorldCup: Soccer Robots (Mirosot)	Tehran, Iran
2016	1st Place, Amirkabir Al Competition : Othello Player	Tehran, Iran
2014	2nd Round Qualified, The Iranian Mathematical Olympiad	Tehran, Iran
2014	2nd Round Qualified, The Iranian Informatics Olympiad	Tehran, Iran

# **Teaching**.

#### **Artificial Intelligence Course - TA**

AMIRKABIR UNIVERSITY OF TECHNOLOGY - PROF. AHMAD NIKABADI

Sep. 2018 - Jun. 2019

2 - Semester

1 - Semester

- Teaching Evolutionary Search and Optimization Algorithm
- Prepare the **Final Project** and **Grading** of home-works

AMIRKABIR UNIVERSITY OF TECHNOLOGY - PROF. AMIR JAHANSHAHI

### **Advance Programming Course - TA**

Jan. 2018 - Jun. 2018

- Teaching Bash, Git, Web Front-End and Databases as side workshops
- Grade Home-works and review solutions in Class.

### **Basic Programming Course - TA**

1 - Semester

Amirkabir University of Technology - Prof. Amir Jahanshahi

Sep. 2017 - Jan. 2018

- Teaching C and C++
- Review solutions of home-works in class

### **Workshop Robotic Instructor**

4 - Summer

AMIRKABIR UNIVERSITY OF TECHNOLOGY - ROBOTIC SUMMER SCHOOL

2015 - 2018

- Being the Teacher of the event for four continuous year.
- Teaching Linux, Git, C++, Python, Qt Frameworks, ROS Framework and Gazebo in Basic and Advance level in eighteen 6-hour sessions.

# **Work Experience**

**BigData Engineer** Ongoing

MCI TELECOMMUNICATIONS (THE LARGEST TELECOM COMPANY IN MIDDLE-EAST)

- Work on Hadoop Ecosystem and tools like Hive, Yarn
- Work with distributed queues Zookeeper, Kafka and Avro
- Work with Elasticsearch, Logstash, Kibana and Beats for collecting data specially logs and metrics
- Analyse and process data with Spark and Flink
- · Visualise the result with Grafana

MCI TELECOMMUNICATIONS

- · distributed deployment and configuration management with Redhat Ansible
- Core R&D member for Bigdata solutions in MCI
- Individually developed and deployed the first distributed full stack ELK platform for Real-Time Monitoring of MCI DWBI Project.

**DW/BI Engineer** 6-month

• Working with Oracle RDBMS and Tools like: ODI - OBIEE - Oracle Cloud

- Built and deployed ETL packages, focusing on high-availability, Fault Tolerance, and Auto-Scaling.
- Developed KPI Dashboards to control system and product health.
- Development of **Telecom Interconnect** analysis area from scratch to **FACT & DIM** level

**Software Developer** 

BRTel(Blue-Ray Telecommunications)

Sep. 2015 - Sep. 2016

Jan. 2019 - Jun. 2019

Jun. 2019 - PRESENT

- Work with Rabbit-MQ and MySQL for fast and reliable message passing.
- implementation pf Value-Added Services based on SMS.
- Develop Android and IOS application for fan-service of Iranian soccer teams.
- Worked in a **Agile** team with **JIRA** management.

**Robotic Teacher** 1 - Year

Sep. 2014 - Sep. 2015 SALAM HIGH SCHOOL

- Teach embedded system programming on Micro-Controllers with C
- Teach basic algorithm, data structure and **C** Programming Language

#### High school Research, Junior Soccer Robots (RoboCup)

Sep. 2011 - Sep. 2014

3-Years

• A team of two omni-directional autonomous soccer robots.

- · Work with Atmega16 micro-controller and XBee, Gyroscope and Ultra-Sonic distance meter modules.
- Filtering IR sensors on 38khz.

SOFTWARE SPECIALIST

- Implement Two-way communication and collaboration between two soccer robots.
- Implement PID-Controller to fix robot direction and DC-Motor velocity control.

### Skills

· Calculus, Linear Algebra, and Discrete Mathematics since university **Mathematics** 

• Geometry, Number Theory and Combinatorics since high school

• System: C/C++(10 Years), Bash/Zsh(5 Years), Python(5 Years), JAVA(4 Years), Rust(2 Years), Go(2 Years)

Web: JavaScript(6 Years), NodeJS(2 Years), HTML/CSS(6 Years)

**Programming Languages** • Functional: Lisp(1 Year), Racket(1 Year)

Hardware: VHDL(3 Years), Verilog(1 Year)

Frameworks Qt(6 Years), ROS(3 Years), OpenCV(3 Years), Tensorflow(2 Years), Pytorch(1 Year), OpenAI GYM(1 Year)

**Simulations Platform** Gazebo(3 Year), Webots(2 Years), Mujoco(1 Year), V-Rep(1 Year)

**Version Control** Git(6 Years), Subversion(3 Years)

**Continuous Integration** Gitlab CI/CD(6 Years), Travis(4 Years), Circle CI(2 Years), Github Workflow(1 Year)

**Operating Systems** MacOs(8 Years), Ubuntu(6 Years), Redhat(2 Years), SunOs(1 Year)

**BigData Stack** Hadoop Ecosystem(1 Year), ELK Stack(1 Year), Kafka(1 Year), Spark(1 Year), Redis(1 Year)

**Databases** Oracle(2 Years), Postgres(1 Year), MySql(1 Year), Sqllite(6 Years) Persian(native), English(10 Years), Arabic(4 Years), Korean(1 Year) Languages

# **Open-Source Contribution**

#### **GENERAL**

#### OH-MY-ZSH - Community-Driven Framework for Managing your ZSH Configuration.

Contributer

ROBBYRUSSELL/OH-MY-ZSH

- · Add Spotify CLI support.
- Improve MacOs features

#### **PYCM - Multi-class Confusion Matrix Library in Python**

Contributer

SEPANDHAGHIGHI/PYCM

- · Fine-tune Models and fix bug.
- · Add OSX Support.
- · Add test and CI on Travis.

#### **QPAGE - Free Project For Creating Academic Homepage Without Any Code In 3min**

Co-Owner

SEPANDHAGHIGHI/QPAGE

- · Implementation of styles and templates.
- · Add UNIX/MacOs Support.

#### **OPEM - Open Source PEM Fuel Cell Simulation Tool**

Co-Owner

ECSIM/OPEM

- · MacOs Support and maintenance.
- Implement Static Simulation Analysis.
- Implement Test and CI on Travis.

#### **GOPEM - GUI for OPEM Simulation**

Creator

ECSIM/GOPEM

- Written in Python by pyQt and matplotlib
- · Implement test and CI on Travis.
- Easy Install package deployed by **PyInstaller**.

#### Spotify-AdBlocker - Listen to Spotify - W/O Ads!

Creator

MAH197/SPOTIFY-ADBLOCKER

- Written with AppleScript
- · Mute, Replace and Remove ads from Spotify.

#### SpotifyControl - Search and Play Music from Spotify in Terminal

Creator

MAHI97/SPOTIFYCONTROL

- Written with **AppleScript**
- Manage all Spotify functionality including search.

#### ROBOCUP & FIRACUP

#### GrSim - RoboCup Small Size Robot Soccer Simulator

Maintainer

ROBOCUP-SSL/GRSIM

- · Add OSX Support.
- Implement test and CI on Travis.
- Improve performance, fix bugs and add new rules and requirements.

#### FIRASim - FiraCup 2D Soccer Simulation Platform

Maintainer

FIRA-SIMUROSOT/FIRASIM

- · Implementation of Robot models.
- Add Win/Linux/OSX Support.
- Implement test and CI on Travis.
- Improve performance, fix bugs and add new rules and requirements.

#### SimPlus - The RoboCup Rescue Simulation environment for Robocup Junior Rescue

Contributer

ROBOCUP-SIMPLUS/SIMPLUS-VREP

- · Implementation of communication messages.
- Implementation of game server.
- Implementation of python client.
- Implementation of GRPC async protocol.

### SSL-VISION - Shared Vision System For The RoboCup Small Size League

Contributer

ROBOCUP-SSL/SSL-VISION

- Add OSX Support.
- · Implementation of new rules and requirements.

# **Remarkable Projects**

#### SSL Visual Planner - A User Friendly software to arrange plans for SSL league

Parsian Robotic Lab.

Prof. Mohammad Azam Khosravi

PARSIANROBOTICLAB/SSL-VISUAL-PLANNER

· Add OSX Support.

· Implementation in C++ and Qt

#### SSL FEdit – Formation Editor For SSL

Parsian Robotic Lab.

PARSIAN ROBOTIC | AB/SSI-FEDIT

· Migrated from RoboCup Soccer Simulation 2D

· Implemented in C++ and Qt.

Parsian Robotic Lab.

Prof. Mohammad Azam Khosravi

RAIC2019 - RussianAlCup, Soccer Platform using Long Term Prediction

Prof Mohammad Azam Khosravi

PARSIANROBOTICLAB/RAIC2019

• Implemented in Rust

· Prediction of Ball and Agents in 3D Soccer Environment

Simurosot-Middle - Simurosot Base Code MiroSot

• Multi-agent AI with Cooperation for Pass and Receive

Parsian Robotic Lab.

PARSIANROBOTICLAB/SIMUROSOT-MIDDLE

• Implemented in C++ and VisualStudio.

Strong debug tools with network tools.

Prof. Mohammad Azam Khosravi

ZeroShot Learning for ZJU AI Competition (GAN Approach)

Parsian Robotic Lab.

Prof. Mohammad Azam Khosravi

PARSIANROBOTICLAB/ZERO-SHOT-LEARNING

• GAN approach implementation

· Manifold implementation for classification

ClassicSearch - Implementation of Classic Search Algorithms for some Classic Problems

Artificial Intelligence Course.

Prof. Ahmand Nikabadi

Prof. Ahmand Nikabadi

Prof. Ahmand Nikabadi

MAHI97/CLASSICSEARCH

Written in C++

Implement Bidirectional, BFS, A\*, DFS and UCS Searches.

• Model and Solve 2D Navigation, Puzzle 15 and Water Buckets Problems.

Non-Classic-Search - Beyond Search Algorithems

Mahi97/Non-Classic-Search

· Written in Python

• Implement All sort of Hill Climbing, Genetic and Simulated Annealing

• Model and Solve 8 Queen, Math Equations and Graph Partitioning Problems.

Artificial Intelligence Course.

Artificial Intelligence Course.

OthelloPlayer - AI & Learning for Othello Game

MAHI97/OTHELLOPLAYER

Written in Java

• Implement All MinMax Tree with alpha-beta pruning.

• Implementation of Opening Book and Ending Scenarios.

· Implementation of Genetic Optimizer to find weight through self-playing.

InvertSearch - Positional Index and searching on Huge text data files with B-Trees

MAHI97/INVERTSEARCH

• Written in C++ and Qt

• All data structures like List and Vector implemented from Scratch.

• Using Balance trees for indexing and search.

Multi-thread Processing.

Data Structure Course. Prof. Mahdi Dehghan Takhtefoladi

Data Structure Course.

Prof. Mahdi Dehghan Takhtefoladi

FSM - Finite-State Machine, Automata, and Graph Computing

MAHI97/FSM

• Written in C++ and Qt

· Solve FSM language with backtracking.

· Remove Loop and improve the FSM.

Persian-Compiler - Just Another Persian Compiler

Compiler Course.

Prof. Mohammad Reza Razzazi

MAHI97/PERSIAN-COMPILER

• Written in pure C with help of Yacc and Flex

• Support Recursive function, array and pointers

NUMEX-Lang - The Pure Functional Interpreter for Pure Functional Language

MAH197/NUMEX-LANG

• Written in **Racket** (a functional PL driven from Lisp)

Programming Languages Course.

Prof. Mehran Soleyman Fallah

#### LSTM\_FPGA - Implementation of LSTM in FPGA with VHDL

FPGA Course.

MAH197/LSTM FPGA Prof. Morteza Saheb Zamani

- · Written in VHDL
- Deployed of the Xillinx Spartan 3 FPGA Hardware
- Train and Test for simple **Translation** from Greek to English

#### SAYEH - Basic Computer (Simple Architecture Yet Enough Hardware!)

Computer Architecture Course. Prof. Saeed Shiry Gheydari

MAH197/SAYEH

- Written in VHDL
- Implementation of **Memory** and **16-bit CPU** (ALU, Controller and Data Path)
- Implementation of Pipeline with Branch Prediction.
- Implementation of Cache with multiple strategy for SAYEH.

#### C-Compiler - A Compiler to Generate SAYEH Assembly Instruction from C Source Code

Computer Architecture Course.

Prof. Saeed Shiry Gheydari

MAH197/C-COMPILER

- Written in C++
- · Implementation of Lexical and Syntax Analysis
- Implementation of Assembler.

#### USART\_GUI - GUI Application that connect to any device for Read and Write via USART

Micro-Controller Course.

MAH197/USART\_GUI Prof. Mohammad Mahdi Homayounpour

- Written in C++ and Qt
- Support every OS and Platform for execution
- Support all sort of device that use USART with any Frequency

#### MircroProject - Receiving Morse Code from PC and Translate to Beep with any Frequency

Micro-Controller Course.

MAH197/MIRCROPROJECT

Prof. Mohammad Mahdi Homayounpour

- · Design Electronic PCB with Altium Designer
- Assemble and Program the PCB
- · Direct Connect to PC with USART

### P2PFileTransfer - (Torrent) Sending File Peer-to-Peer over from multiple source and receiver

Network Course.

MAHI97/P2PFILETRANSFER Prof. Masoud Sabaei

- Written in JAVA
- Distributed file transfer from multiple source to multiple destination

#### CalcNet - Distribute Calculation over Network

Network Course.

MAH197/CALCNET · Written in JAVA

· Use Master-Slave Architecture for task handling.

Prof. Masoud Sabaei