

**CSE 473: Pattern Recognition** 

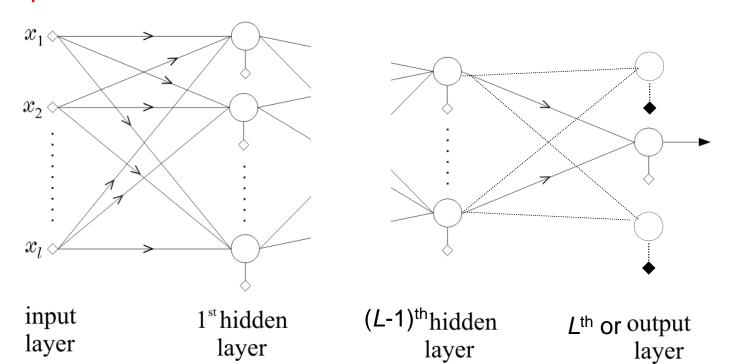
## Non-Linear Classifier

# Training of a Multi Layer Perceptron (MLP)

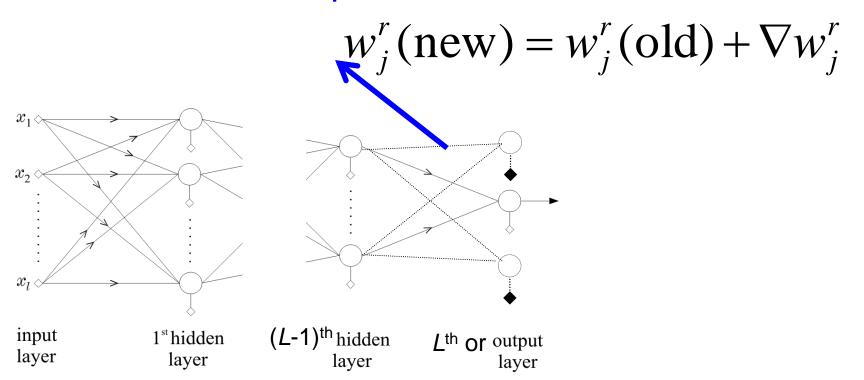
 use rationale and develop a structure that classifies correctly all the training patterns.

OR

 choose a structure and compute the synaptic weights to optimize a cost function.

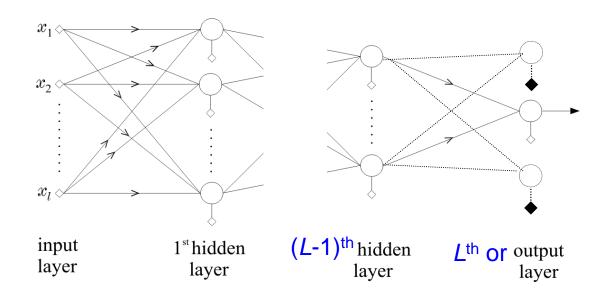


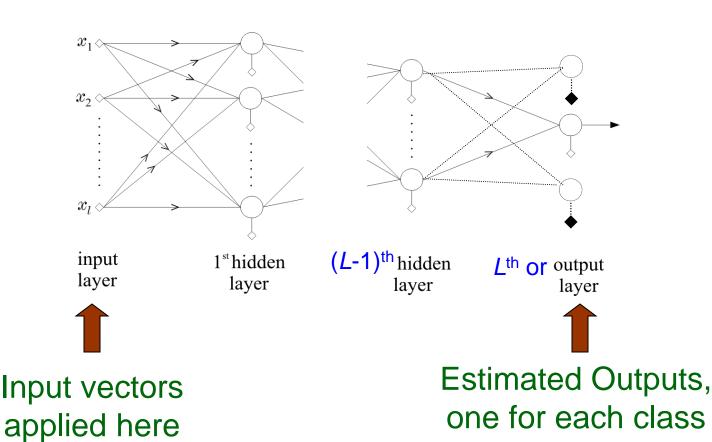
computes the weights iteratively, subject to a cost function is optimized

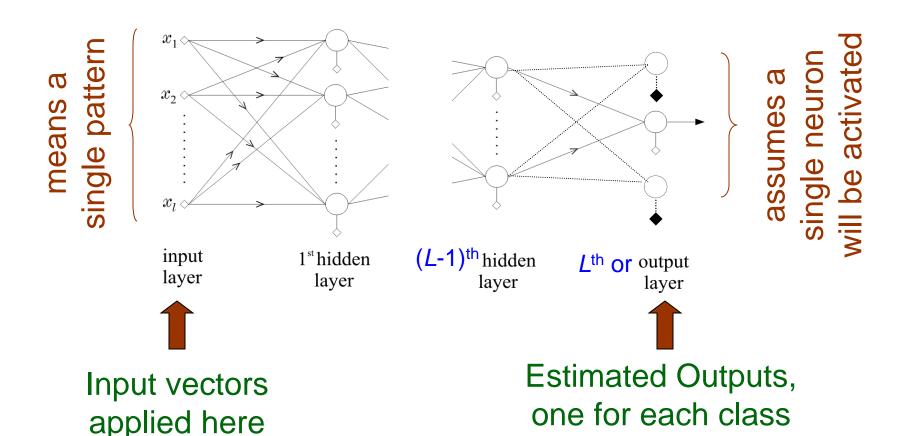


#### Assume:

- Multiple layers
- more than one neurons in each layer
- any number of classes







#### Let:

Data set has 4 classes

Training Sample#	Class#
Sample#1	1
Sample#2	3
Sample#3	2
Sample#4	4
Sample#5	2

#### Let:

Data set has 4 classes

Training Sample#	Class#	Class Vector
Sample#1	1	1000
Sample#2	3	0010
Sample#3	2	0100
Sample#4	4	0001
Sample#5	2	0100

- Recall the perceptron algorithm:
  - We update with this

$$\underline{w}(\text{new}) = \underline{w}(\text{old}) + \Delta \underline{w}$$

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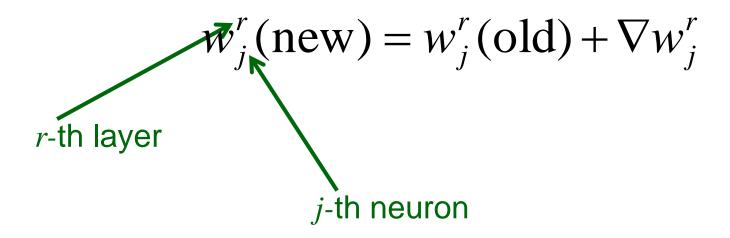
 Backpropagation updates multiple nodes for a number of layers:

$$w_j^r(\text{new}) = w_j^r(\text{old}) + \nabla w_j^r$$

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  - We update with this

$$\underline{w}(\text{new}) = \underline{w}(\text{old}) + \Delta \underline{w}$$

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- Another difference is the activation function:
- Perceptron algorithm uses unit activation function:

$$f(x) = \begin{cases} 1 & x > 0 \\ 0 & x < 0 \end{cases}$$

This function is not differentiable at x=0.

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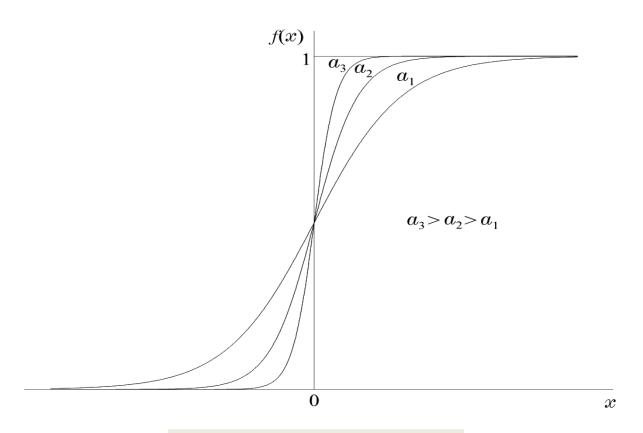
$$f(x) = \begin{cases} 1 & x > 0 \\ 0 & x < 0 \end{cases}$$

- This function is not differentiable at x=0.
- Backpropagation uses logistic function:

$$f(x) = \frac{1}{1 + \exp(-ax)}$$

**Logistic function** 

### The Logistic function



$$f(x) = \frac{1}{1 + \exp(-ax)}$$

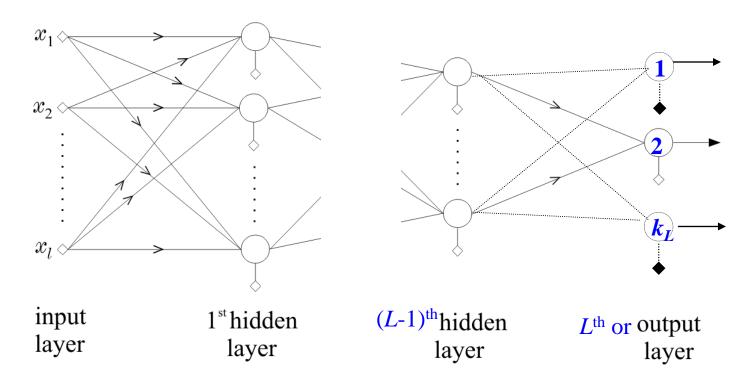
 Similar to perceptron algorithm: Backpropagation also iteratively updates weights

$$w_j^r(\text{new}) = w_j^r(\text{old}) + \nabla w_j^r$$

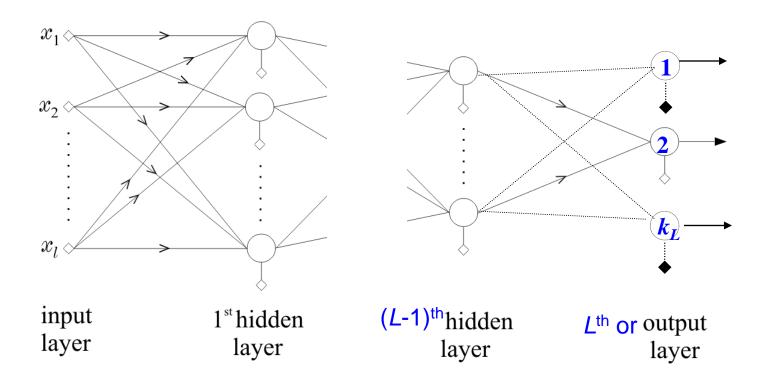
where, 
$$\nabla w_j^r = -\mu \frac{\partial J}{\partial w_j^r}$$

and 
$$J = \sum_{i=1}^{N} \mathcal{E}(i)$$

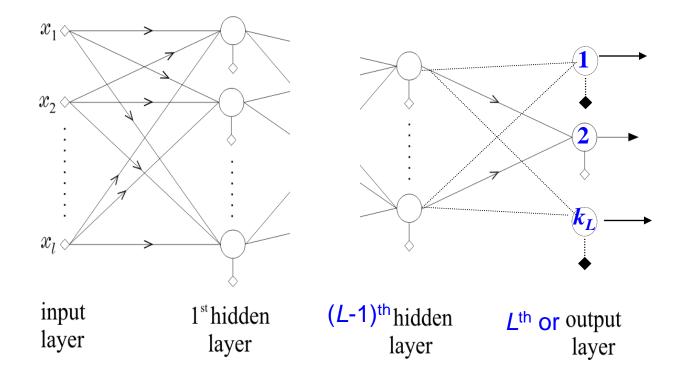
- L layers of neurons
- $k_r$  neurons in  $r^{\text{th}}$  layer
- $k_0$  nodes in the input layer = input feature dimension = l
- $k_L$  nodes in the output layer = output class dimension



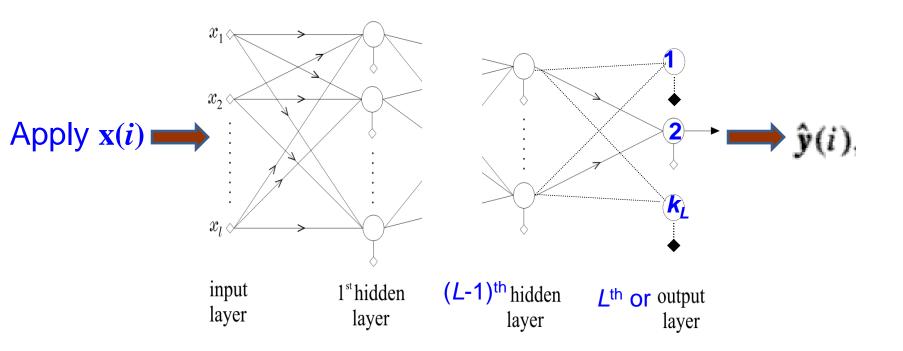
- Remember: The number of classes is more than 2, it is  $K_L$
- Class value of a sample is no longer a single variable, rather it is a vector of  $k_L$  dimension.



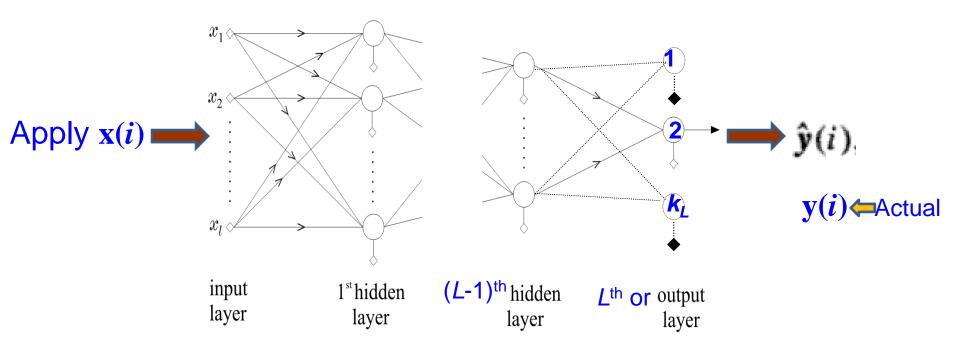
- N training samples:  $(\mathbf{x}(i), \mathbf{y}(i))$ , for i = 1, 2, 3, ..., N
- Features of *i*th training sample:  $\mathbf{x}(i) = [x_1(i), \dots, x_{k_0}(i)]^T$
- Class of *i*th training sample:  $\mathbf{y}(i) = [y_1(i), \dots, y_{k_I}(i)]^T$



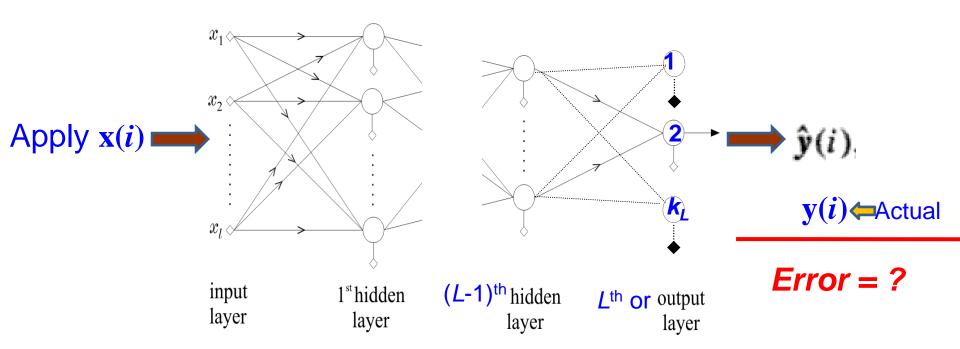
• During training, apply  $i^{th}$  training vector  $\mathbf{x}(i)$ , and output is  $\hat{\mathbf{y}}(i)$ , instead of  $\mathbf{y}(i)$ )



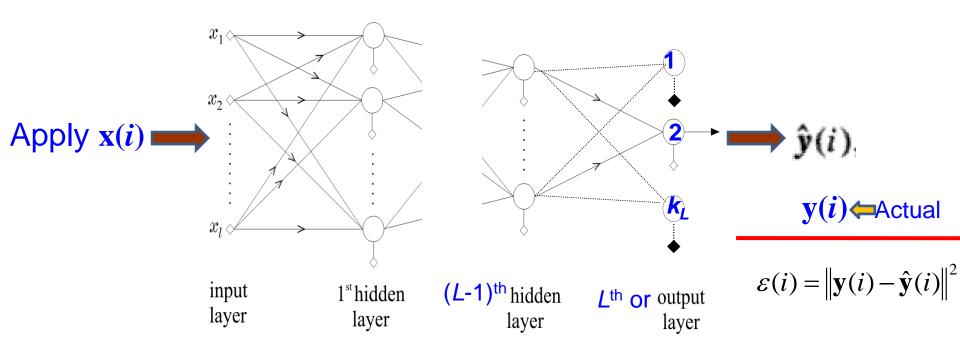
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- Error for *i*<sup>th</sup> vector:

$$\mathcal{E}(i) = \frac{1}{2} \sum_{m=1}^{k_L} e_m^2(i) \equiv \frac{1}{2} \sum_{m=1}^{k_L} (y_m(i) - \hat{y}_m(i))^2, \quad i = 1, 2, \dots, N$$

Total Error:

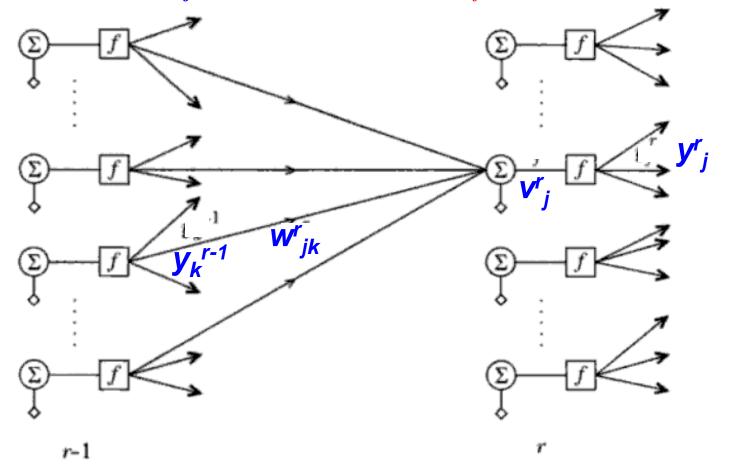
$$J = \sum_{i=1}^{N} \mathcal{E}(i)$$

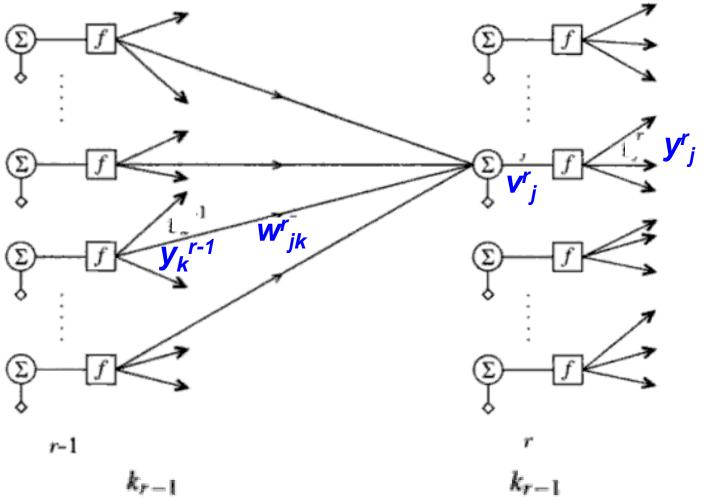
• We need to calculate 
$$\nabla \mathbf{w}_{j}^{r} = -\mu \frac{\partial J(i)}{\partial \mathbf{w}_{j}^{r}} = -\mu \sum_{i=1}^{N} \frac{\partial \mathcal{E}(i)}{\partial \mathbf{w}_{j}^{r}}$$

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• J depends on  $w_j^r$  and passes through  $v_j^r$ 





$$\upsilon_{j}^{r}(i) = \sum_{k=1}^{k_{r-1}} w_{jk}^{r} y_{k}^{r-1}(i) + w_{jo}^{r} \equiv \sum_{k=0}^{k_{r-1}} w_{jk}^{r} y_{k}^{r-1}(i)$$

$$\frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{w}_{j}^{r}} = \frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{v}_{j}^{r}(i)} \frac{\partial \boldsymbol{v}_{j}^{r}(i)}{\partial \boldsymbol{w}_{j}^{r}}$$

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Therefore, 
$$\frac{\partial}{\partial \textbf{\textit{w}}_{j}^{r}} \upsilon_{j}^{r}(i) \equiv \begin{bmatrix} \frac{\partial}{\partial w_{j0}^{r}} \upsilon_{j}^{r}(i) \\ \vdots \\ \frac{\partial}{\partial w_{jk_{r-1}^{r}}} \upsilon_{j}^{r}(i) \end{bmatrix}$$

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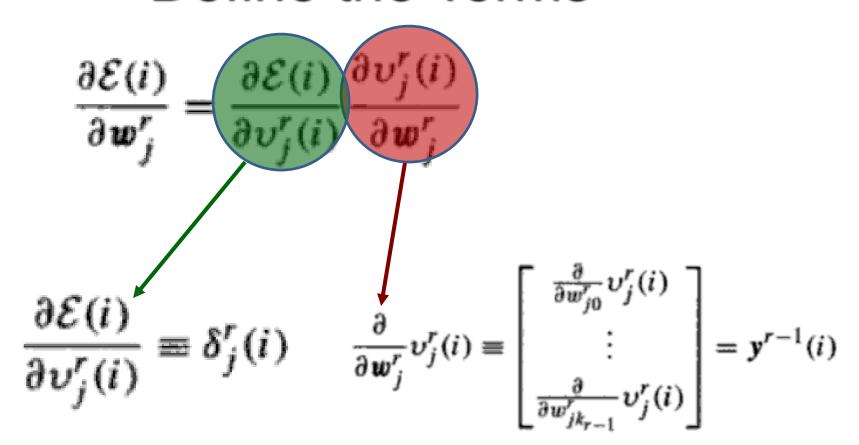
Recall, 
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$$\frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{w}_{j}^{r}} = \frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{v}_{j}^{r}(i)} \frac{\partial \boldsymbol{v}_{j}^{r}(i)}{\partial \boldsymbol{w}_{j}^{r}}$$

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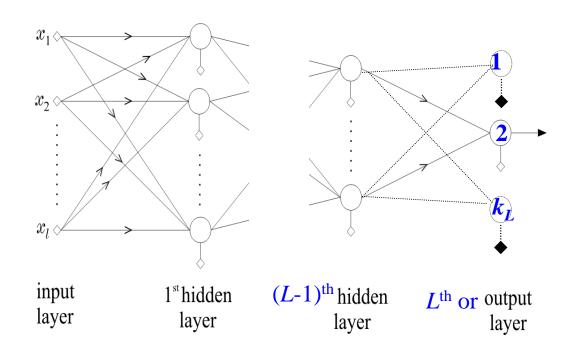
$$\frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{w}_{j}^{r}} = \underbrace{\frac{\partial \mathcal{E}(i)}{\partial \boldsymbol{v}_{j}^{r}(i)}}_{\begin{array}{c} \partial \boldsymbol{w}_{j}^{r}(i) \\ \\ \partial \boldsymbol{w}_{j}^{r}(i) \end{array} = \underbrace{\begin{bmatrix} \frac{\partial}{\partial \boldsymbol{w}_{j0}^{r}} \boldsymbol{v}_{j}^{r}(i) \\ \vdots \\ \frac{\partial}{\partial \boldsymbol{w}_{jk_{r-1}}^{r}} \boldsymbol{v}_{j}^{r}(i) \end{bmatrix}}_{} = \boldsymbol{y}^{r-1}(i)$$

$$\Delta \mathbf{w}_{j}^{r} = -\mu \sum_{i=1}^{N} \frac{\partial \varepsilon(i)}{\partial \mathbf{w}_{i}^{r}(i)}$$

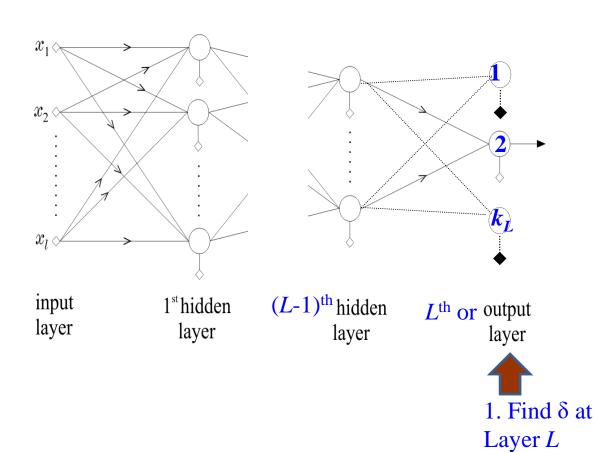
$$\Delta \mathbf{w}_{j}^{r} = -\mu \sum_{i=1}^{N} \frac{\partial \varepsilon(i)}{\partial \mathbf{w}_{j}^{r}(i)} \longrightarrow \Delta \mathbf{w}_{j}^{r} = -\mu \sum_{i=1}^{N} \delta_{j}^{r}(i) \mathbf{y}^{r-1}(i)$$

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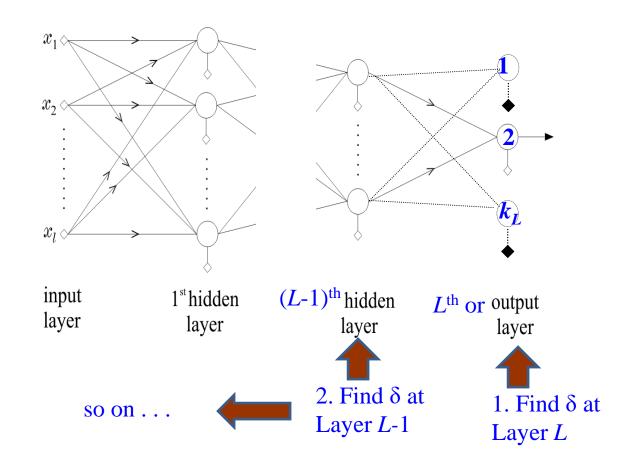
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• For  $r = L$ 

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$$\varepsilon(i) = \frac{1}{2} \sum_{m=1}^{k_L} e_m^2(i) \equiv \frac{1}{2} \sum_{m=1}^{k_L} (f(v_m^L(i)) - y_m(i))^2$$

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$$\delta_j^L(i) = \frac{1}{2} \times 2 \times (f(v_m^L(i)) - y_m(i)) \times f'(v_j^L(i))$$

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- Calculate  $\delta_{i}^{r-1}(i)$  from  $\delta_{j}^{r}(i)$

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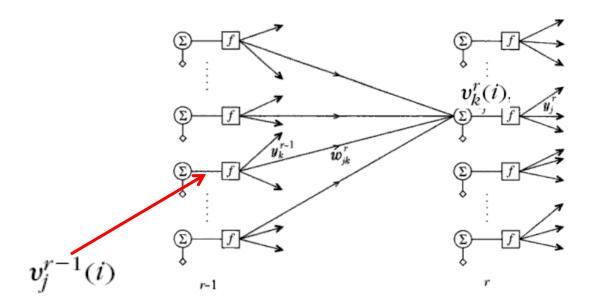
We know,

$$\delta_j^{r-1}(i) = \frac{\partial \mathcal{E}(i)}{\partial v_j^{r-1}(i)}$$

We need to calculate,

$$\delta_j^{r-1}(i) = \frac{\partial \mathcal{E}(i)}{\partial v_j^{r-1}(i)}$$

• However,  $v_j^{r-1}(i)$  influences all  $v_k^r(i)$ , for  $k = 1, 2, 3, ..., k_r$ 



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- Therefore,

$$\frac{\partial \mathcal{E}(i)}{\partial v_j^{r-1}(i)} = \sum_{k=1}^{k_r} \frac{\partial \mathcal{E}(i)}{\partial v_k^r(i)} \frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)}$$

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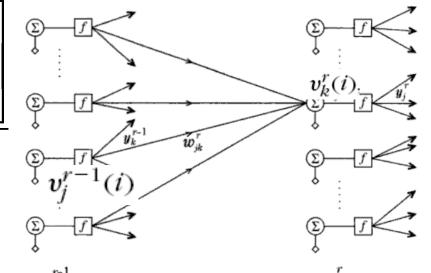
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$$\frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)} = \frac{\partial \left[\sum_{m=0}^{k_{r-1}} w_{km}^r y_m^{r-1}(i)\right]}{\partial v_j^{r-1}(i)}$$



where, 
$$y_m^{r-1}(i) = f(v_m^{r-1}(i))$$

$$\delta_j^{r-1}(i) = \sum_{k=1}^{k_r} \delta_k^r(i) \frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)}$$

$$\frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)} = \frac{\partial \left[\sum_{m=0}^{k_{r-1}} w_{km}^r y_m^{r-1}(i)\right]}{\partial v_j^{r-1}(i)} \text{ where, } y_m^{r-1}(i) = f(v_m^{r-1}(i))$$

then,

$$\frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)} = w_{kj}^r f'(v_j^{r-1}(i))$$

$$\delta_j^{r-1}(i) = \sum_{k=1}^{k_r} \delta_k^r(i) \frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)}$$

$$\frac{\partial v_k^r(i)}{\partial v_j^{r-1}(i)} = w_{kj}^r f'(v_j^{r-1}(i))$$

$$\mathcal{S}_{j}^{r-1}(i) = \sum_{k=1}^{k_{r}} \mathcal{S}_{k}^{r}(i) \frac{\partial v_{k}^{r}(i)}{\partial v_{j}^{r-1}(i)}$$
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$$\delta_j^{r-1}(i) = e_j^{r-1}(i) f'(v_j^{r-1}(i))$$

where, 
$$e_j^{r-1}(i) = \sum_{k=1}^{\kappa_r} \delta_k^r(i) w_{kj}^r$$

Only remaining is the derivative of the logistic function:

$$f'(x) = \alpha f(x)(1 - f(x))$$

# The Algorithm

- Initialization:
  - Start with small random weights
- Forward Computations:  $v_j^r(i)$ ,  $y_j^r(i) = f(v_j^r(i))$ ,
- Backward Computation:  $\delta_j^L(i)$  and  $\delta_j^{r-1}(i)$
- Update weight:

$$\boldsymbol{w}_{j}^{r}(\text{new}) = \boldsymbol{w}_{j}^{r}(\text{old}) + \Delta \boldsymbol{w}_{j}^{r}$$

$$\Delta \mathbf{w}_j^r = -\mu \sum_{i=1}^N \delta_j^r(i) \mathbf{y}^{r-1}(i)$$