

# CSE 473

## Pattern Recognition

# **Classifiers, Discriminant Functions and Decision Surfaces**

# Classifiers, Discriminant Functions and Decision Surfaces


- Remember the Bayesian classifier:

Decide  $\omega_i$  if  $P(\omega_i|\mathbf{x}) > P(\omega_j|\mathbf{x})$  for all  $j \neq i$ .

# Classifiers, Discriminant Functions and Decision Surfaces

- Remember the Bayesian classifier:

Decide  $\omega_i$  if  $P(\omega_i|\mathbf{x}) > P(\omega_j|\mathbf{x})$  for all  $j \neq i$ .


$$g_i(x) > g_j(x)$$

# Classifiers, Discriminant Functions and Decision Surfaces

- Remember the Bayesian classifier:

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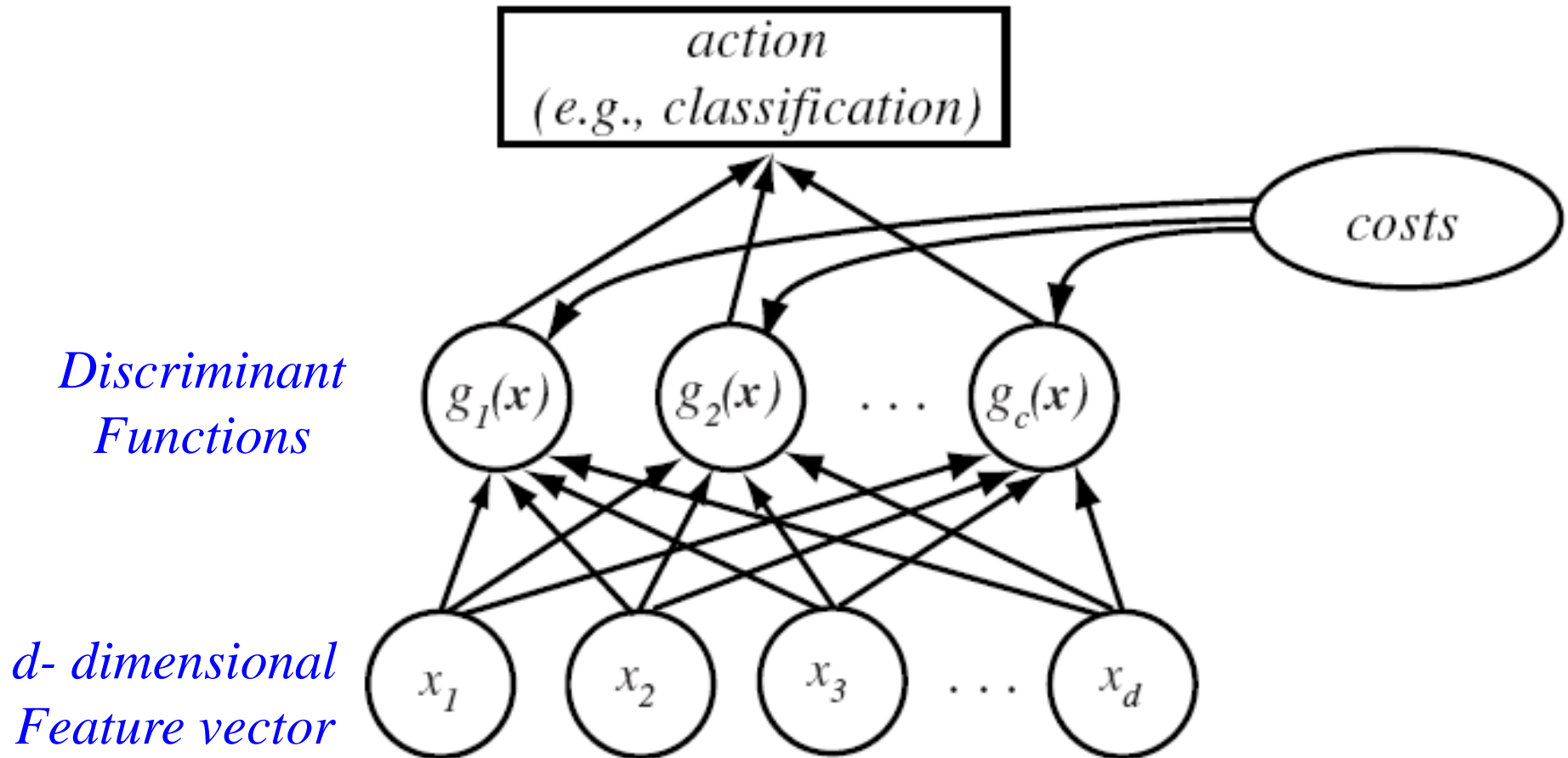
- This is equivalent to:

decide  $x$  to class  $\omega_i$

if  $g_i(x) > g_j(x) \quad \forall j \neq i$

where,  $g_i(x) = P(\omega_i|\mathbf{x})$ ,  $i = 1, \dots, c$

# Classifiers, Discriminant Functions and Decision Surfaces



# Classifiers, Discriminant Functions and Decision Surfaces

- *Based on minimum risk classification*
    - Let  $g_i(x) = -R(\alpha_i / x)$
- (max. discriminant corresponds to min. risk!)

# Classifiers, Discriminant Functions and Decision Surfaces

- For the minimum error rate, we take

$$g_i(x) = P(\omega_i / x)$$

(max. discrimination corresponds to max. posterior!)



# Classifiers, Discriminant Functions and Decision Surfaces

- For the minimum error rate, we take

$$g_i(x) = P(\omega_i / x)$$

some alternate representations but giving similar results

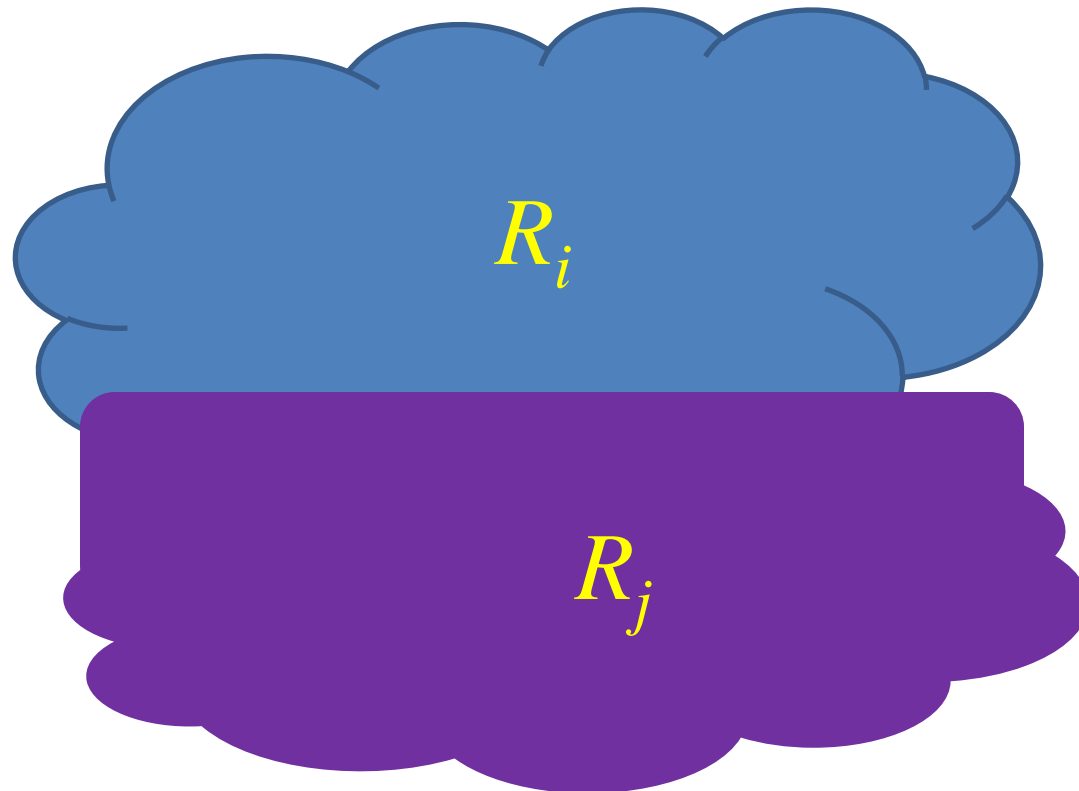
$$g_i(x) \equiv P(x / \omega_i) P(\omega_i)$$

$$g_i(x) \equiv \ln P(x / \omega_i) + \ln P(\omega_i)$$

(ln: natural logarithm!)

# Decision Surface

- Let,  $R_i$  and  $R_j$  : two regions identifying classes  $\omega_i$  and  $\omega_j$

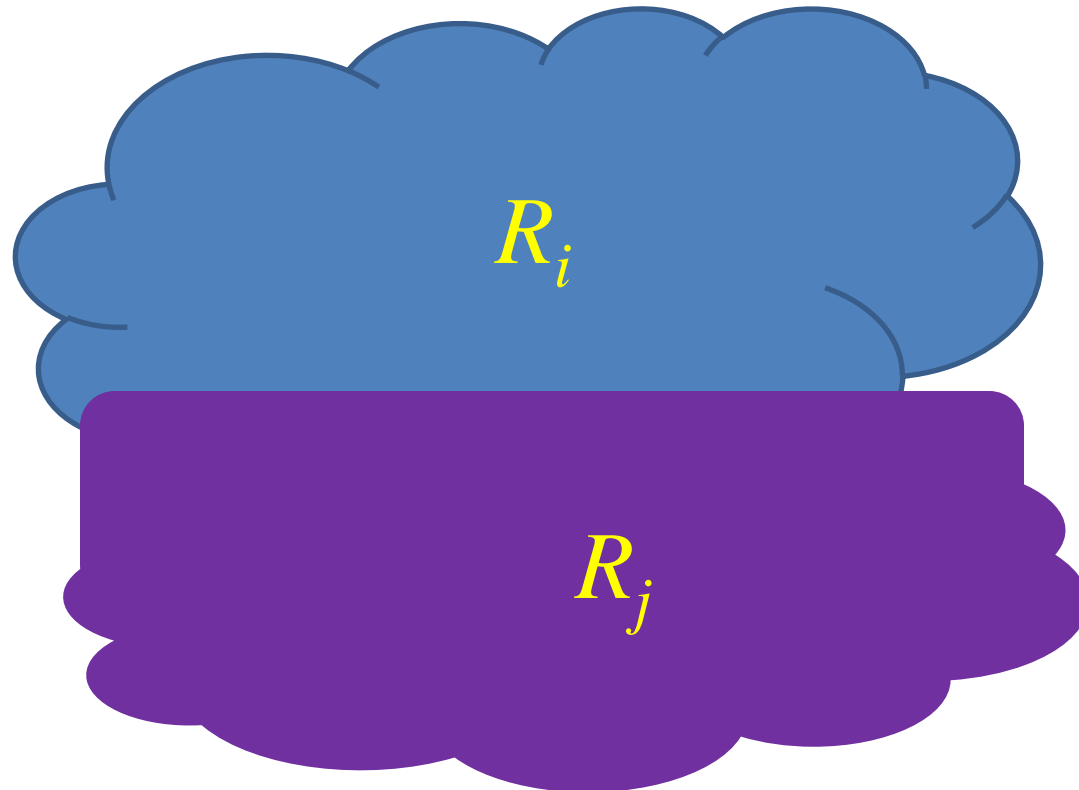


# Decision Surface

- Let,  $R_i$  and  $R_j$  : two regions identifying classes  $\omega_i$  and  $\omega_j$

Decision  
Rule

Decide  $\omega_i$  if  $P(\omega_i | x) > P(\omega_j | x)$

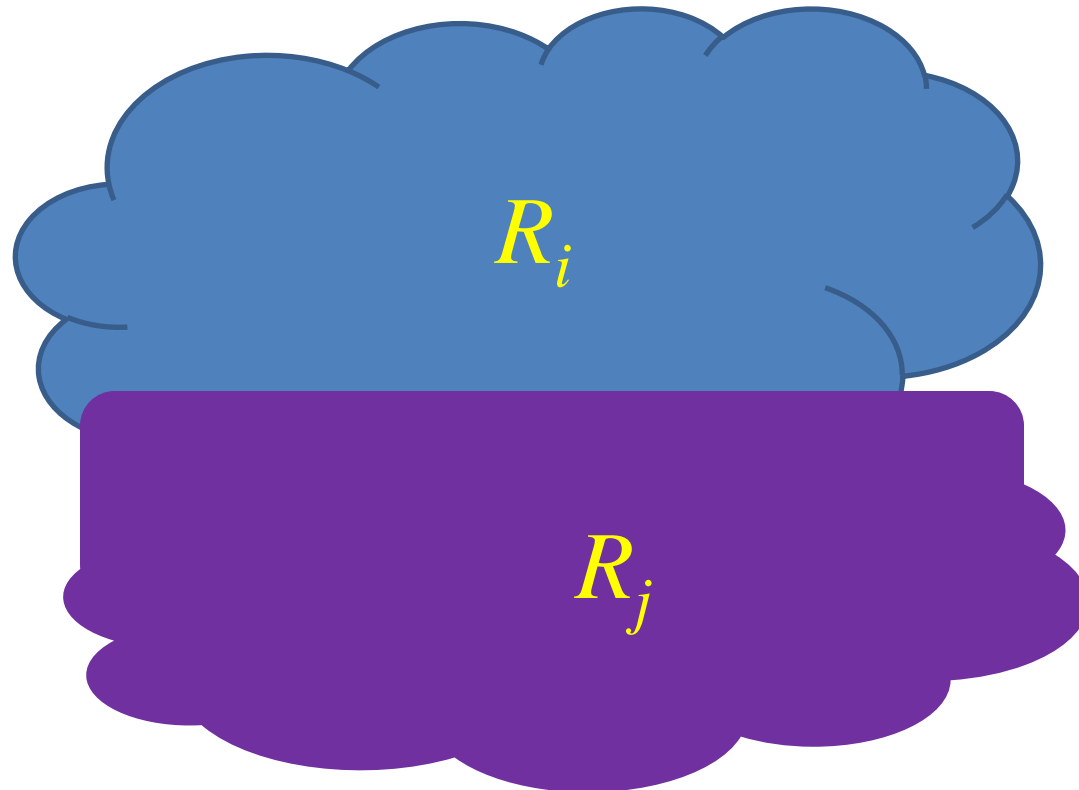


# Decision Surface

- Let,  $R_i$  and  $R_j$  : two regions identifying classes  $\omega_i$  and  $\omega_j$

Decision  
Rule

Decide  $\omega_i$  if  $P(\omega_i | x) - P(\omega_j | x) > 0$

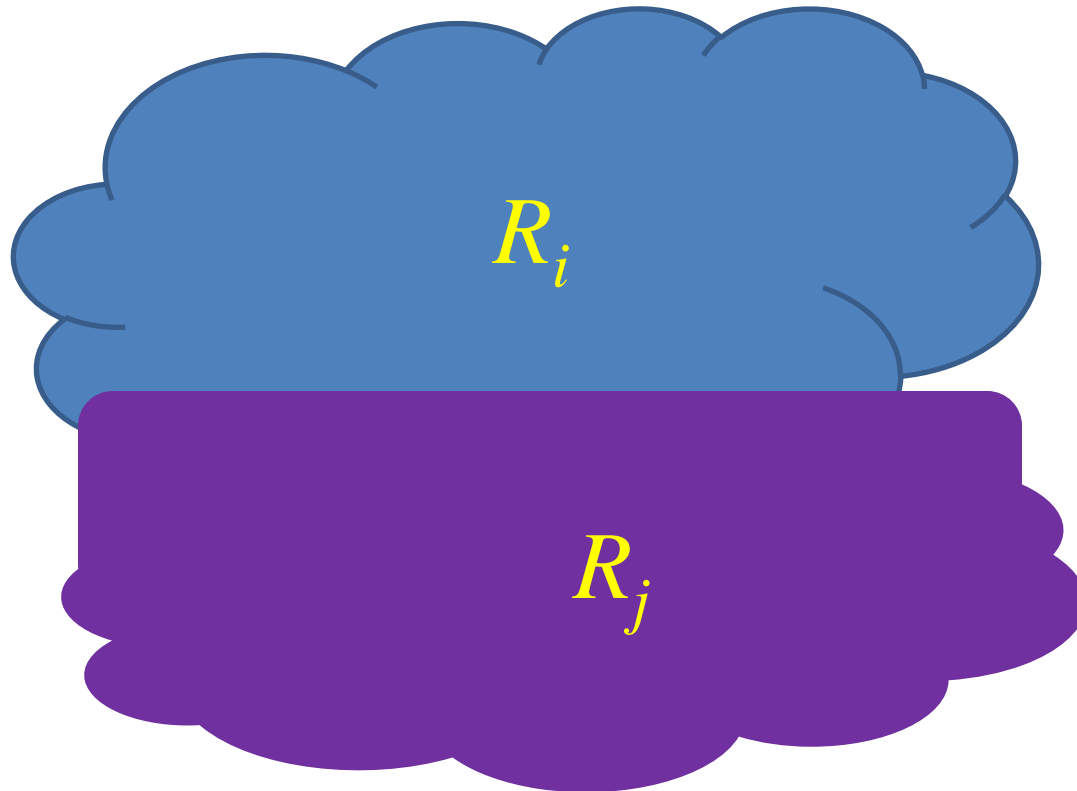


# Decision Surface

- Let,  $R_i$  and  $R_j$  : two regions identifying classes  $\omega_i$  and  $\omega_j$

Decision  
Rule

Decide  $\omega_i$  if  $g(x) \equiv P(\omega_i | x) - P(\omega_j | x) > 0$



# Decision Surface

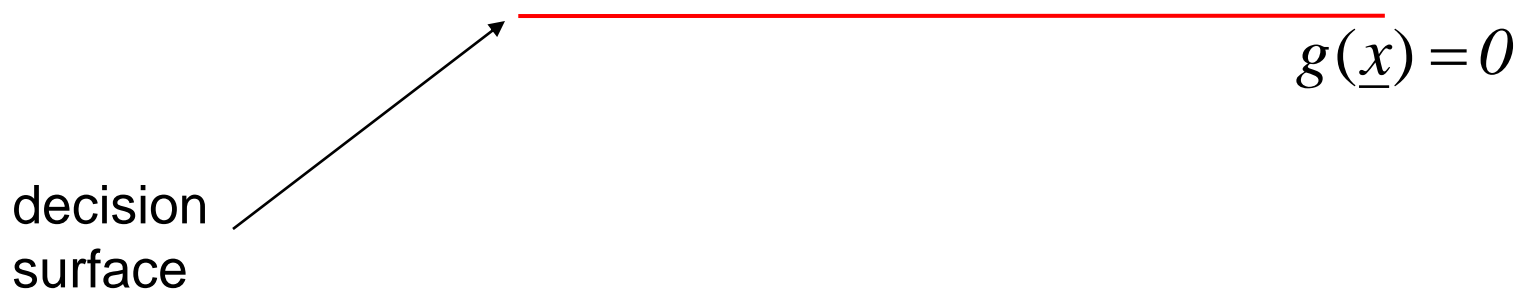
- Let,  $R_i, R_j$  : two regions identifying classes  $\omega_i$  and  $\omega_j$

$$g(\underline{x}) \equiv P(\omega_i|\underline{x}) - P(\omega_j|\underline{x}) = 0$$

# Decision Surface

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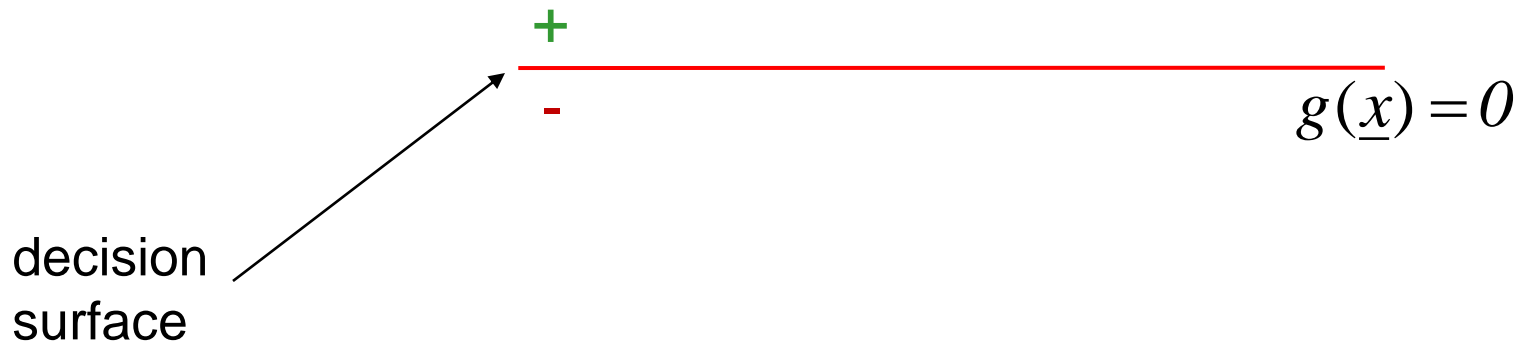
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# Decision Surface

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# Decision Surface

- If  $R_i, R_j$ : two regions identifying classes  $\omega_i$  and  $\omega_j$

$$g(\underline{x}) \equiv P(\omega_i|\underline{x}) - P(\omega_j|\underline{x}) = 0$$

$$R_i : P(\omega_i|\underline{x}) > P(\omega_j|\underline{x})$$

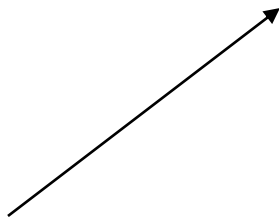
+

-

$$g(\underline{x}) = 0$$

$$R_j : P(\omega_j|\underline{x}) > P(\omega_i|\underline{x})$$

decision  
surface



# Decision Surface in Multi-categories

- Feature space is divided into  $c$  decision regions

*if*  $g_i(x) > g_j(x) \quad \forall j \neq i$  *then*  $x$  is in  $R_i$

( $R_i$  means: assign  $x$  to  $\omega_i$ )

# Decision Surface in Two-categories

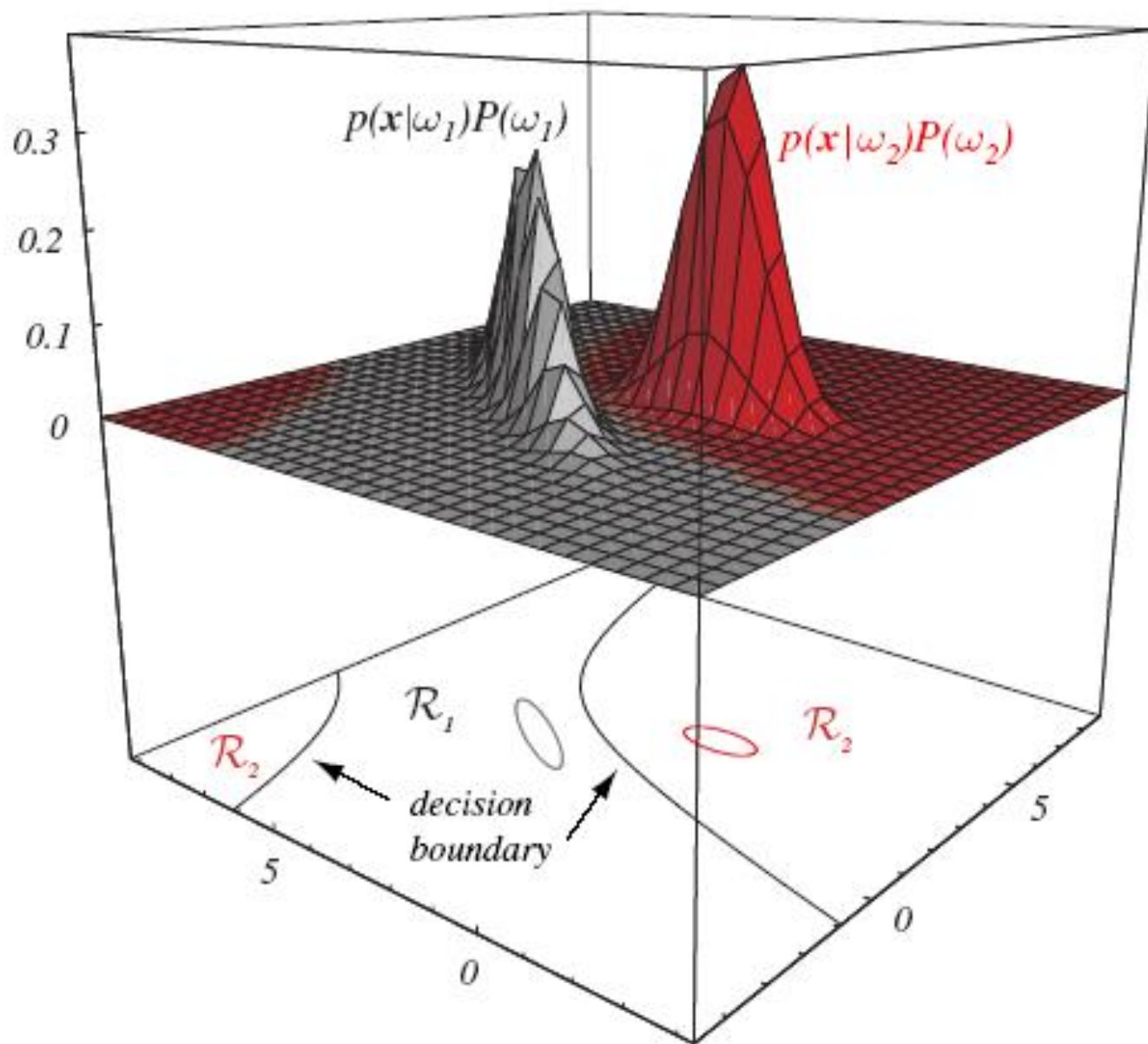
- The two-category case
  - A classifier is a “*dichotomizer*” that has two discriminant functions  $g_1$  and  $g_2$

Let  $g(x) \equiv g_1(x) - g_2(x)$

Decide  $\omega_1$  if  $g(x) > 0$  ; Otherwise decide  $\omega_2$

– The computation of  $g(x)$

$$\begin{aligned} g(x) &\equiv P(\omega_1 | x) - P(\omega_2 | x) \\ &= P(x | \omega_1)P(\omega_1) - P(x | \omega_2)P(\omega_2) \\ &\equiv \ln \frac{P(x | \omega_1)}{P(x | \omega_2)} + \ln \frac{P(\omega_1)}{P(\omega_2)} \end{aligned}$$



# The Normal Density

- Density which is analytically tractable
- Continuous density
- A lot of processes are asymptotically Gaussian
  - Handwritten characters, speech sounds, and many more
  - Any prototype corrupted by random process

# The Normal Density

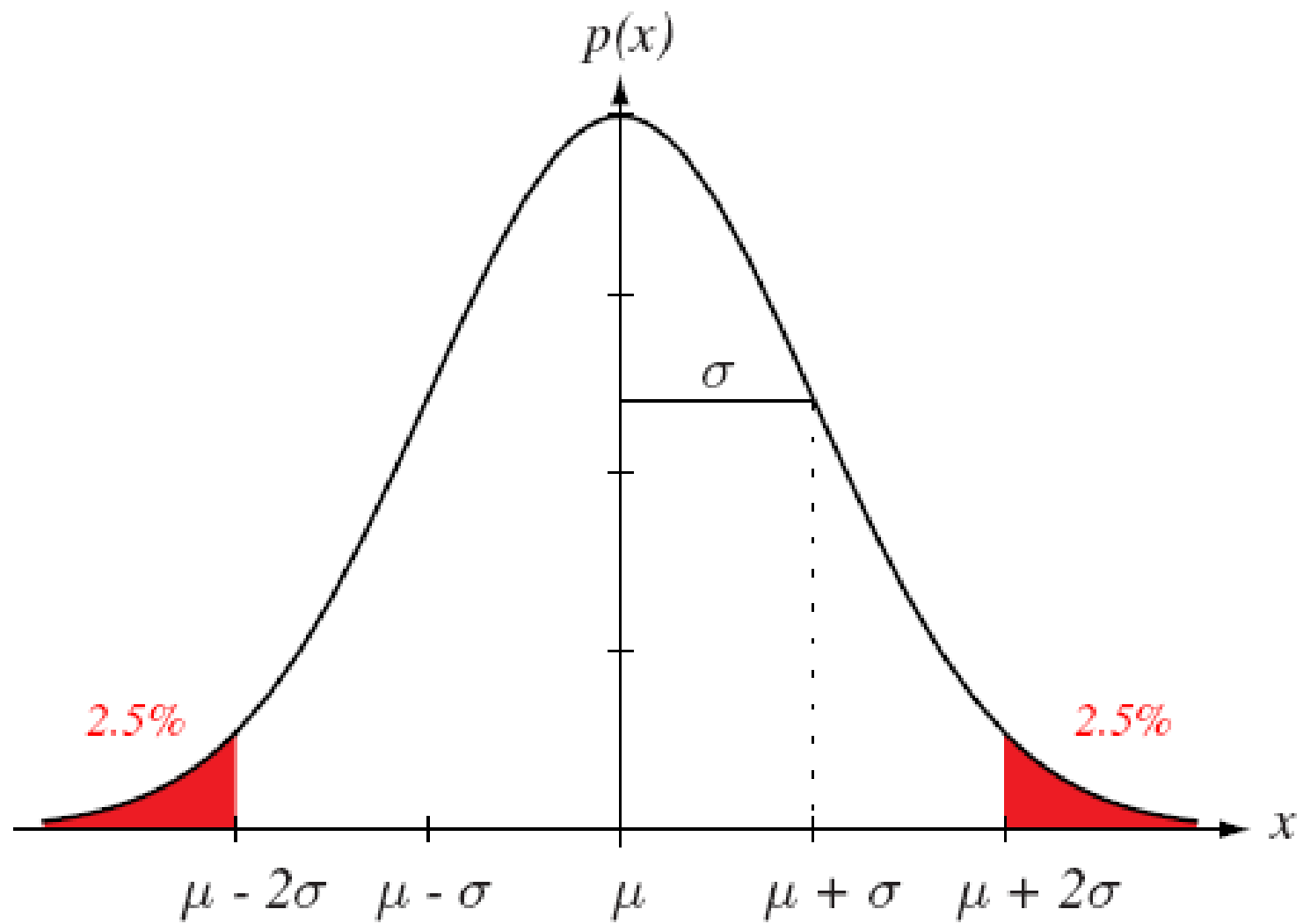
- Univariate density

$$P(x) = \frac{1}{\sqrt{2\pi} \sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right],$$

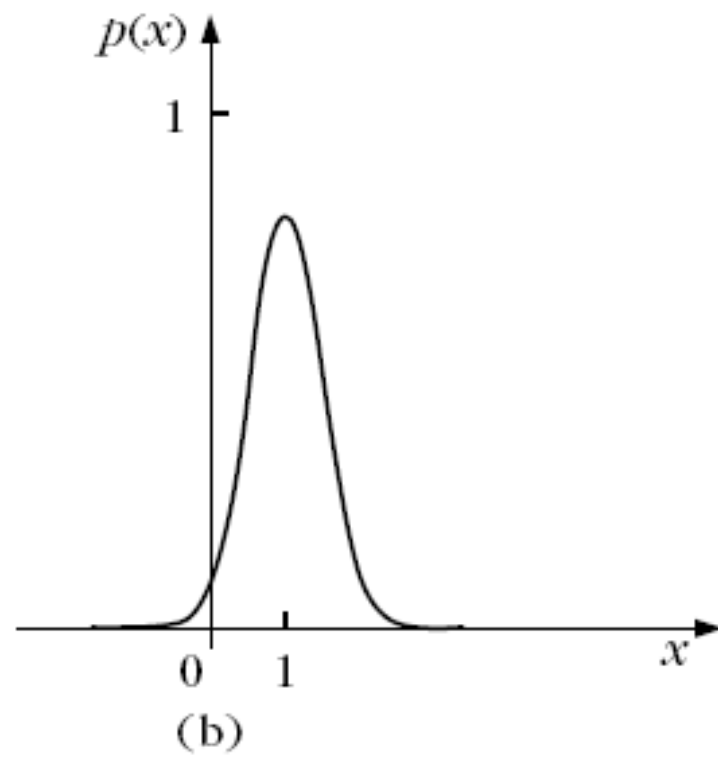
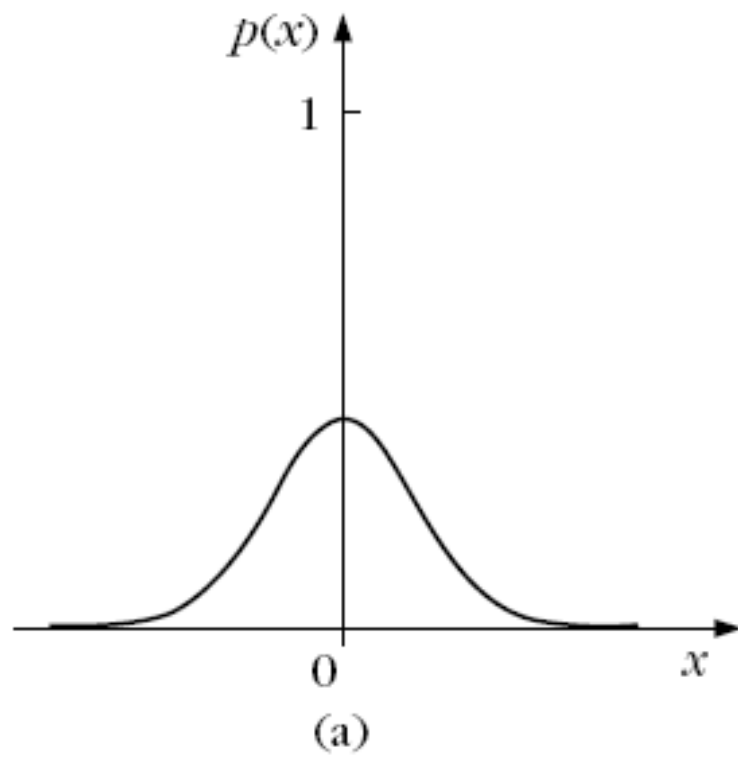
Where:

$\mu$  = mean (or expected value) of  $x$

$\sigma^2$  = expected squared deviation or variance







- Multivariate density

- Multivariate normal density in  $d$  dimensions is:

$$P(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left[ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^t \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

where:

$\mathbf{x} = (x_1, x_2, \dots, x_d)^t$  ( $t$  stands for the transpose vector form)

$\boldsymbol{\mu} = (\mu_1, \mu_2, \dots, \mu_d)^t$  mean vector

$\Sigma = d \times d$  covariance matrix

$|\Sigma|$  and  $\Sigma^{-1}$  are determinant and inverse respectively

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where:

$$\Sigma = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T]$$

$$\begin{aligned}\Sigma &= E\left[\begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \begin{bmatrix} x_1 - \mu_1, & x_2 - \mu_2 \end{bmatrix}\right] \\ &= \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix}\end{aligned}$$

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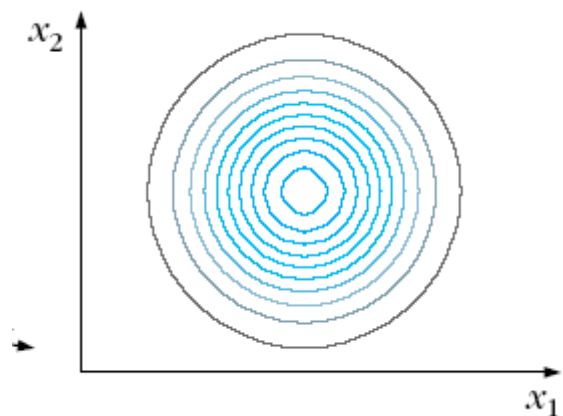
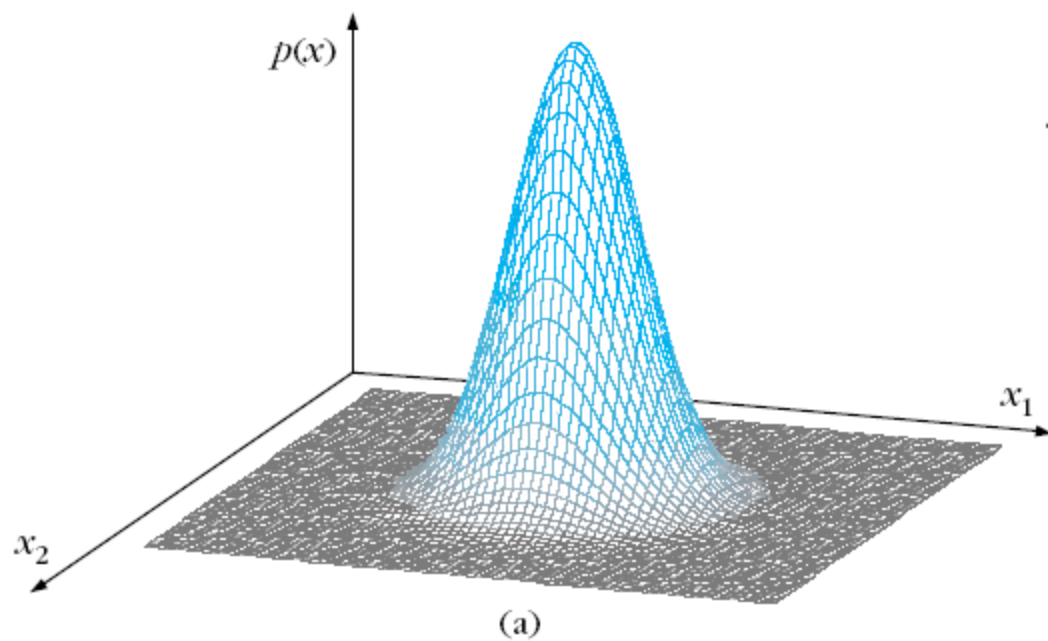
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$$E[x_i] = \mu_i, \ i = 1, 2,$$

$$\sigma_{12} = E[(x_1 - \mu_1)(x_2 - \mu_2)].$$

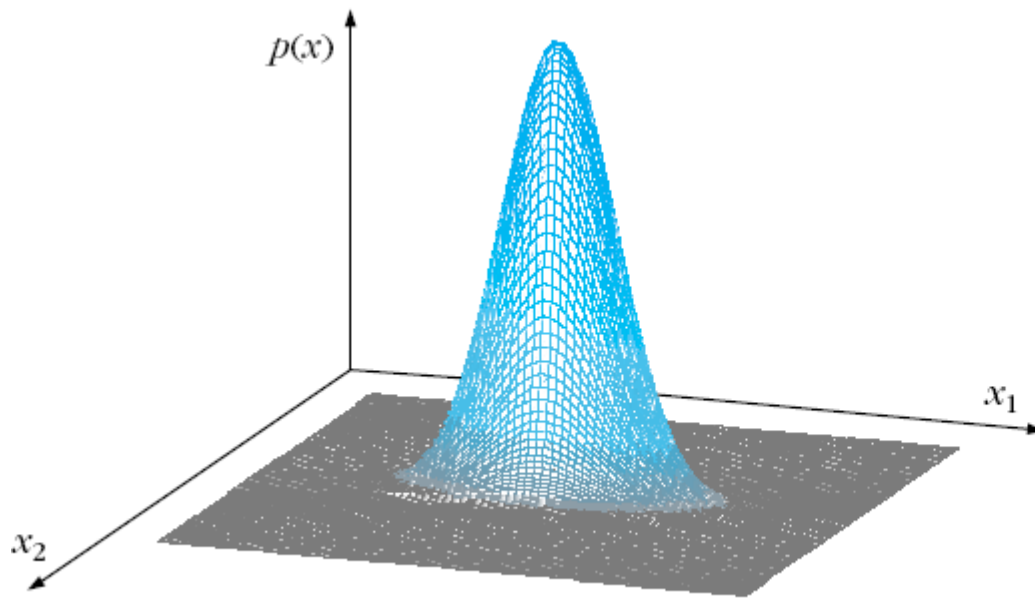
# 2D Gaussian Example - 1

$$\Sigma = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}$$

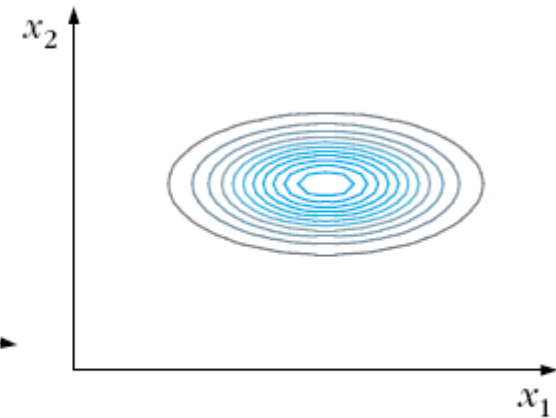


# 2D Gaussian Example - 2

$$\sigma_1^2 \gg \sigma_2^2$$



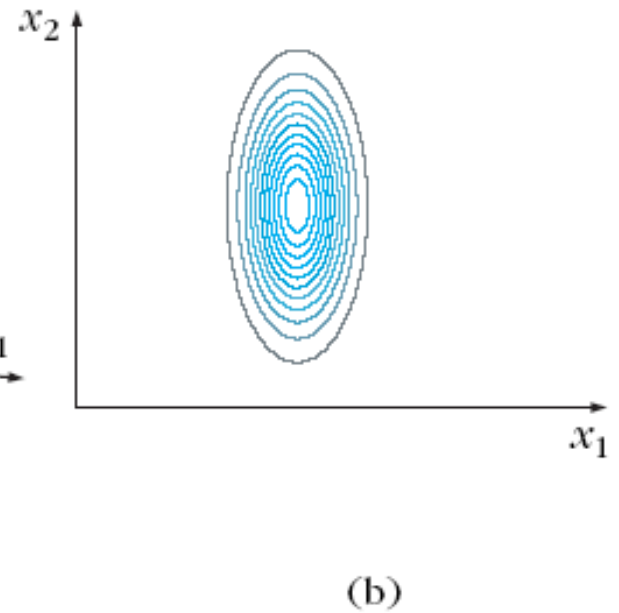
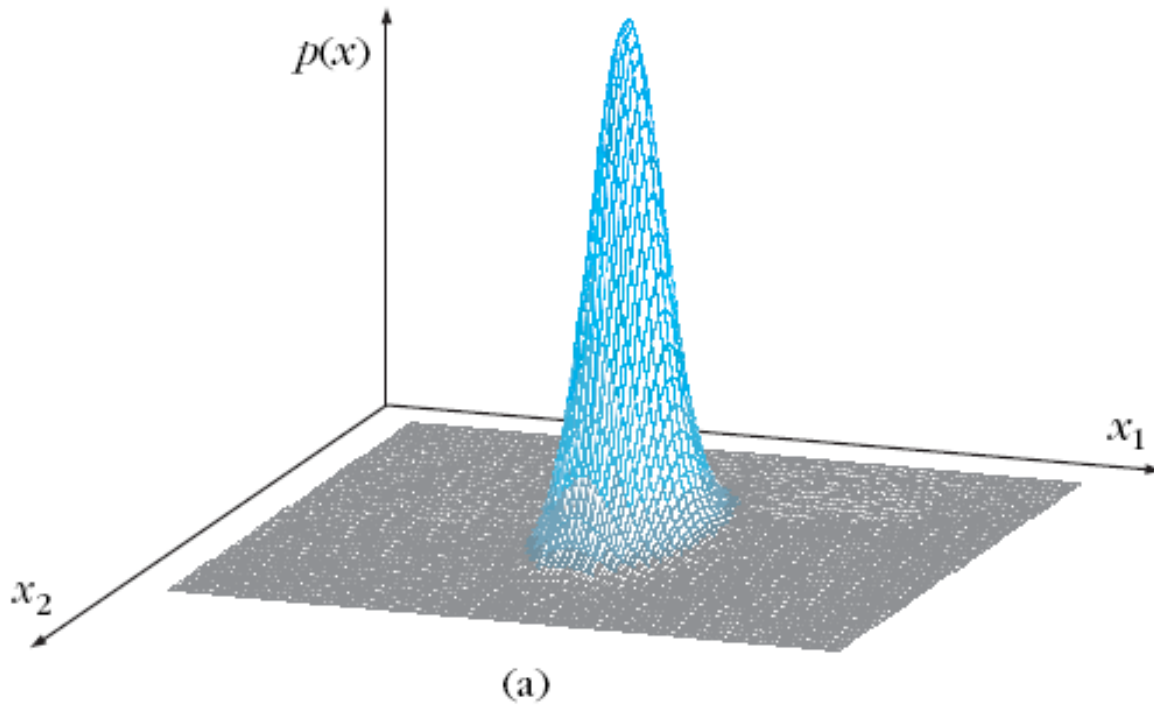
(a)



(b)

# 2D Gaussian Example - 3

$$\sigma_1^2 \ll \sigma_2^2$$



# Computer Exercise

- Use matlab to generate Gaussian plots
- Try with different  $\Sigma$  and  $\mu$



# Classification Example 2

<i>Tid</i>	Refund	Marital Status	Taxable Income	Evade
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

- A married person with income 120K did not refund the loan previously
- *Can we trust him?*

# Bayesian Classifiers

- We have multiple attributes ( $A_1, A_2, \dots, A_n$ )
  - Goal is to predict class  $C$
  - Specifically, we want to find the value of  $C$  that maximizes  $P(C / A_1, A_2, \dots, A_n)$
- Can we estimate  $P(C / A_1, A_2, \dots, A_n)$  directly from data?

# Bayesian Classifiers

- Approach:
  - compute the posterior probability  $P(C / A_1, A_2, \dots, A_n)$  for all values of  $C$  using the Bayes theorem

$$P(C | A_1 A_2 \dots A_n) = \frac{P(A_1 A_2 \dots A_n | C) P(C)}{P(A_1 A_2 \dots A_n)}$$

- Choose value of  $C$  that maximizes
$$P(C / A_1, A_2, \dots, A_n)$$
  - Equivalent to choosing value of  $C$  that maximizes
$$P(A_1, A_2, \dots, A_n / C) P(C)$$
- How to estimate  $P(A_1, A_2, \dots, A_n / C)$ ?

# Naïve Bayes Classifier

- Assume independence among attributes  $A_i$  when class is given:
  - $P(A_1, A_2, \dots, A_n / C_j) = P(A_1 / C_j) P(A_2 / C_j) \dots P(A_n / C_j)$
  - Can estimate  $P(A_i / C_j)$  for all  $A_i$  and  $C_j$
  - *the new pattern* is classified to  $C_j$  if  $P(C_j) \prod P(A_i / C_j)$  is maximum

# How to Estimate Probabilities from Data?

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- Class:  $P(C) = N_c/N$

- e.g.,  $P(\text{No}) = 7/10$ ,  
 $P(\text{Yes}) = 3/10$

- For discrete attributes:

$$P(A_i | C_k) = |A_{ik}| / N_c$$

- where  $|A_{ik}|$  is number of instances having attribute  $A_i$  and belongs to class  $C_k$
  - Examples:

$$P(\text{Status}=\text{Married}|\text{No}) = 4/7$$

$$P(\text{Refund}=\text{Yes}|\text{Yes})=0$$

# How to Estimate Probabilities from Data?

- For continuous attributes:
  - Discretize the range into bins
    - one ordinal attribute per bin
  - Two-way split:  $(A < v)$  or  $(A > v)$ 
    - choose only one of the two splits as new attribute
  - Probability density estimation:
    - Assume attribute follows a normal distribution
    - Use data to estimate parameters of distribution (e.g., mean and standard deviation)
    - Once probability distribution is known, can use it to estimate the conditional probability  $P(A_i | c)$

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- Normal distribution:

$$P(A_i | c_j) = \frac{1}{\sqrt{2\pi\sigma_{ij}^2}} e^{-\frac{(A_i - \mu_{ij})^2}{2\sigma_{ij}^2}}$$

- One for each  $(A_i, c_j)$  pair
- For (Income, Class=No):
  - If Class=No
    - sample mean = 110K
    - sample variance = 2975

# How to Estimate Probabilities from Data?

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- For (Income, Class=No):
  - If Class=No
    - sample mean = 110K
    - sample variance = 2975

$$P(\text{Income} = 120 | \text{No}) = \frac{1}{\sqrt{2\pi(54.54)}} e^{-\frac{(120-110)^2}{2(2975)}} = 0.0072$$



# Example of Naïve Bayes Classifier

Given a Test Record:  $X = (\text{Refund} = \text{No}, \text{Married}, \text{Income} = 120\text{K})$

naive Bayes Classifier:

$$P(\text{Refund}=\text{Yes}|\text{No}) = 3/7$$

$$P(\text{Refund}=\text{No}|\text{No}) = 4/7$$

$$P(\text{Refund}=\text{Yes}|\text{Yes}) = 0$$

$$P(\text{Refund}=\text{No}|\text{Yes}) = 1$$

$$P(\text{Marital Status}=\text{Single}|\text{No}) = 2/7$$

$$P(\text{Marital Status}=\text{Divorced}|\text{No}) = 1/7$$

$$P(\text{Marital Status}=\text{Married}|\text{No}) = 4/7$$

$$P(\text{Marital Status}=\text{Single}|\text{Yes}) = 2/7$$

$$P(\text{Marital Status}=\text{Divorced}|\text{Yes}) = 1/7$$

$$P(\text{Marital Status}=\text{Married}|\text{Yes}) = 0$$

For taxable income:

If class=No: sample mean=110

sample variance=2975

If class=Yes: sample mean=90

sample variance=25

$$\begin{aligned} P(X|\text{Class}=\text{No}) &= P(\text{Refund}=\text{No}|\text{Class}=\text{No}) \\ &\quad \times P(\text{Married}|\text{Class}=\text{No}) \\ &\quad \times P(\text{Income}=120\text{K}|\text{Class}=\text{No}) \\ &= 4/7 \times 4/7 \times 0.0072 = 0.0024 \end{aligned}$$

$$\begin{aligned} P(X|\text{Class}=\text{Yes}) &= P(\text{Refund}=\text{No}|\text{Class}=\text{Yes}) \\ &\quad \times P(\text{Married}|\text{Class}=\text{Yes}) \\ &\quad \times P(\text{Income}=120\text{K}|\text{Class}=\text{Yes}) \\ &= 1 \times 0 \times 1.2 \times 10^{-9} = 0 \end{aligned}$$

Since  $P(X|\text{No})P(\text{No}) > P(X|\text{Yes})P(\text{Yes})$

Therefore  $P(\text{No}|X) > P(\text{Yes}|X)$

$\Rightarrow \text{Class} = \text{No}$

# Example-2 of Naïve Bayes Classifier

Name	Give Birth	Can Fly	Live in Water	Have Legs	Class
human	yes	no	no	yes	mammals
python	no	no	no	no	non-mammals
salmon	no	no	yes	no	non-mammals
whale	yes	no	yes	no	mammals
frog	no	no	sometimes	yes	non-mammals
komodo	no	no	no	yes	non-mammals
bat	yes	yes	no	yes	mammals
pigeon	no	yes	no	yes	non-mammals
cat	yes	no	no	yes	mammals
leopard shark	yes	no	yes	no	non-mammals
turtle	no	no	sometimes	yes	non-mammals
penguin	no	no	sometimes	yes	non-mammals
porcupine	yes	no	no	yes	mammals
eel	no	no	yes	no	non-mammals
salamander	no	no	sometimes	yes	non-mammals
gila monster	no	no	no	yes	non-mammals
platypus	no	no	no	yes	mammals
owl	no	yes	no	yes	non-mammals
dolphin	yes	no	yes	no	mammals
eagle	no	yes	no	yes	non-mammals

Give Birth	Can Fly	Live in Water	Have Legs	Class
yes	no	yes	no	?

# Example-2 of Naïve Bayes Classifier

Name	Give Birth	Can Fly	Live in Water	Have Legs	Class
human	yes	no	no	yes	mammals
python	no	no	no	no	non-mammals
salmon	no	no	yes	no	non-mammals
whale	yes	no	yes	no	mammals
frog	no	no	sometimes	yes	non-mammals
komodo	no	no	no	yes	non-mammals
bat	yes	yes	no	yes	mammals
pigeon	no	yes	no	yes	non-mammals
cat	yes	no	no	yes	mammals
leopard shark	yes	no	yes	no	non-mammals
turtle	no	no	sometimes	yes	non-mammals
penguin	no	no	sometimes	yes	non-mammals
porcupine	yes	no	no	yes	mammals
eel	no	no	yes	no	non-mammals
salamander	no	no	sometimes	yes	non-mammals
gila monster	no	no	no	yes	non-mammals
platypus	no	no	no	yes	mammals
owl	no	yes	no	yes	non-mammals
dolphin	yes	no	yes	no	mammals
eagle	no	yes	no	yes	non-mammals

A: attributes

M: mammals

N: non-mammals

$$P(A | M) = \frac{6}{7} \times \frac{6}{7} \times \frac{2}{7} \times \frac{2}{7} = 0.06$$

$$P(A | N) = \frac{1}{13} \times \frac{10}{13} \times \frac{3}{13} \times \frac{4}{13} = 0.0042$$

$$P(A | M)P(M) = 0.06 \times \frac{7}{20} = 0.021$$

$$P(A | N)P(N) = 0.004 \times \frac{13}{20} = 0.0027$$

Give Birth	Can Fly	Live in Water	Have Legs	Class
yes	no	yes	no	?

$$P(A|M)P(M) >$$

$$P(A|N)P(N)$$

=> Mammals

# Naïve Bayes (Summary)

- Robust to isolated noise points
- Handle missing values by ignoring the instance during probability estimate calculations
- Robust to irrelevant attributes
- Independence assumption may not hold for some attributes
  - Use other techniques such as Bayesian Belief Networks (BBN)

# Naïve Bayes (Issues)

- Over simplification
  - Use other techniques such as Bayesian Belief Networks (BBN)

# Bayesian Belief Networks

- Let we have  $l$  random variables
- The joint probability is given by,

$$p(x_1, x_2, \dots, x_\ell) = p(x_\ell \mid x_{\ell-1}, \dots, x_1) \cdot p(x_{\ell-1} \mid x_{\ell-2}, \dots, x_1) \cdot \dots \\ \dots \cdot p(x_2 \mid x_1) \cdot p(x_1)$$

# Bayesian Belief Networks

The formula

$$p(x_1, x_2, \dots, x_\ell) = p(x_\ell \mid x_{\ell-1}, \dots, x_1) \cdot p(x_{\ell-1} \mid x_{\ell-2}, \dots, x_1) \cdot \dots \\ \dots \cdot p(x_2 \mid x_1) \cdot p(x_1)$$

can be written as

$$p(x_1, x_2, \dots, x_\ell) = p(x_1) \cdot \prod_{i=2}^{\ell} p(x_i \mid A_i)$$

where

$$A_i \subseteq \{x_{i-1}, x_{i-2}, \dots, x_1\}$$

- For example, if  $\ell=6$ , then we could assume:

$$p(x_6 \mid x_5, \dots, x_1) = p(x_6 \mid x_5, x_4)$$

Then:

$$A_6 = \{x_5, x_4\} \subseteq \{x_5, \dots, x_1\}$$



– Similarly, if we assume

$$p(x_5|x_4, \dots, x_1) = p(x_5|x_4)$$

$$p(x_4|x_3, x_2, x_1) = p(x_4|x_2, x_1)$$

$$p(x_3|x_2, x_1) = p(x_3|x_2)$$

$$p(x_2|x_1) = p(x_2)$$

Then:

$$A_5 = \{x_4\}, A_4 = \{x_2, x_1\}, A_3 = \{x_2\}, A_2 = \emptyset$$

- Similarly, if we assume

$$p(x_5|x_4, \dots, x_1) = p(x_5|x_4)$$

$$p(x_4|x_3, x_2, x_1) = p(x_4|x_2, x_1)$$

$$p(x_3|x_2, x_1) = p(x_3|x_2)$$

$$p(x_2|x_1) = p(x_2)$$

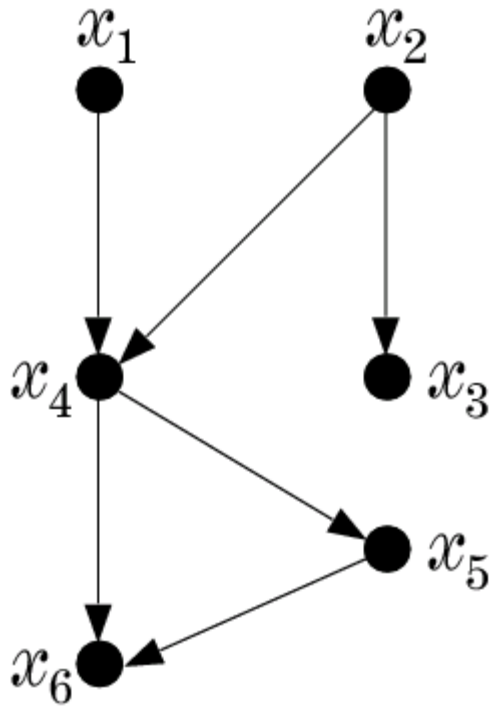
Then:

$$A_5 = \{x_4\}, A_4 = \{x_2, x_1\}, A_3 = \{x_2\}, A_2 = \emptyset$$

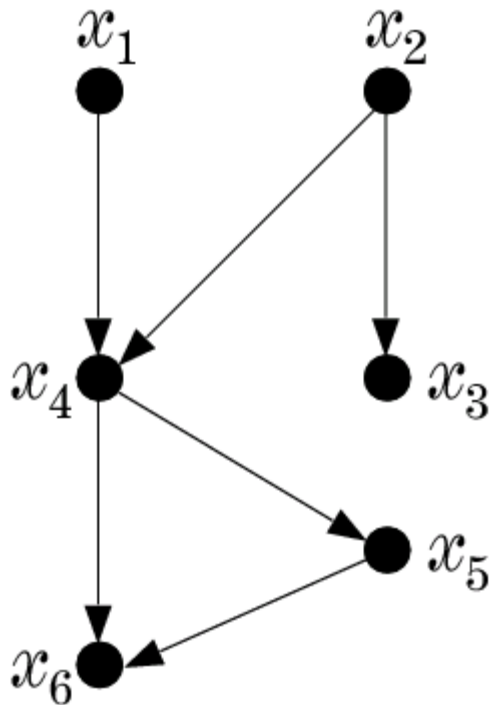
- The above is a generalization of the Naïve – Bayes. For the Naïve – Bayes the assumption is:

$$A_i = \emptyset, \text{ for } i=1, 2, \dots, \ell$$

- A graphical way to portray conditional dependencies



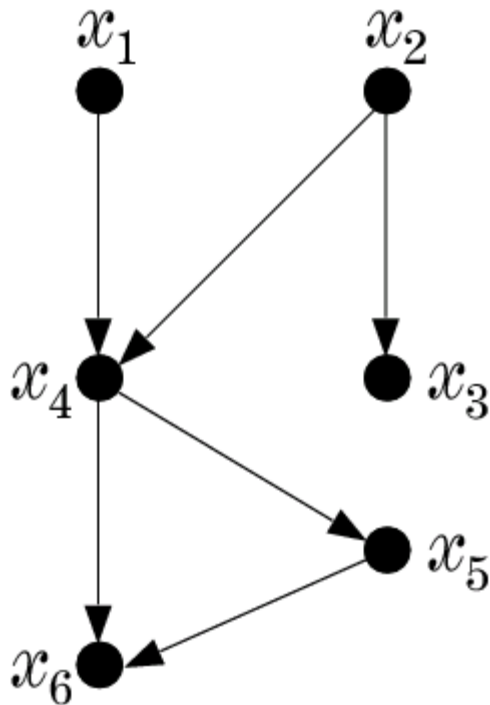
- A graphical way to portray conditional dependencies



➤ According to this figure we have :

- $x_6$  is conditionally dependent on  $x_4, x_5$ .
- $x_5$  on  $x_4$
- $x_4$  on  $x_1, x_2$
- $x_3$  on  $x_2$
- $x_1, x_2$  are conditionally independent on other variables.

- A graphical way to portray **conditional dependencies**



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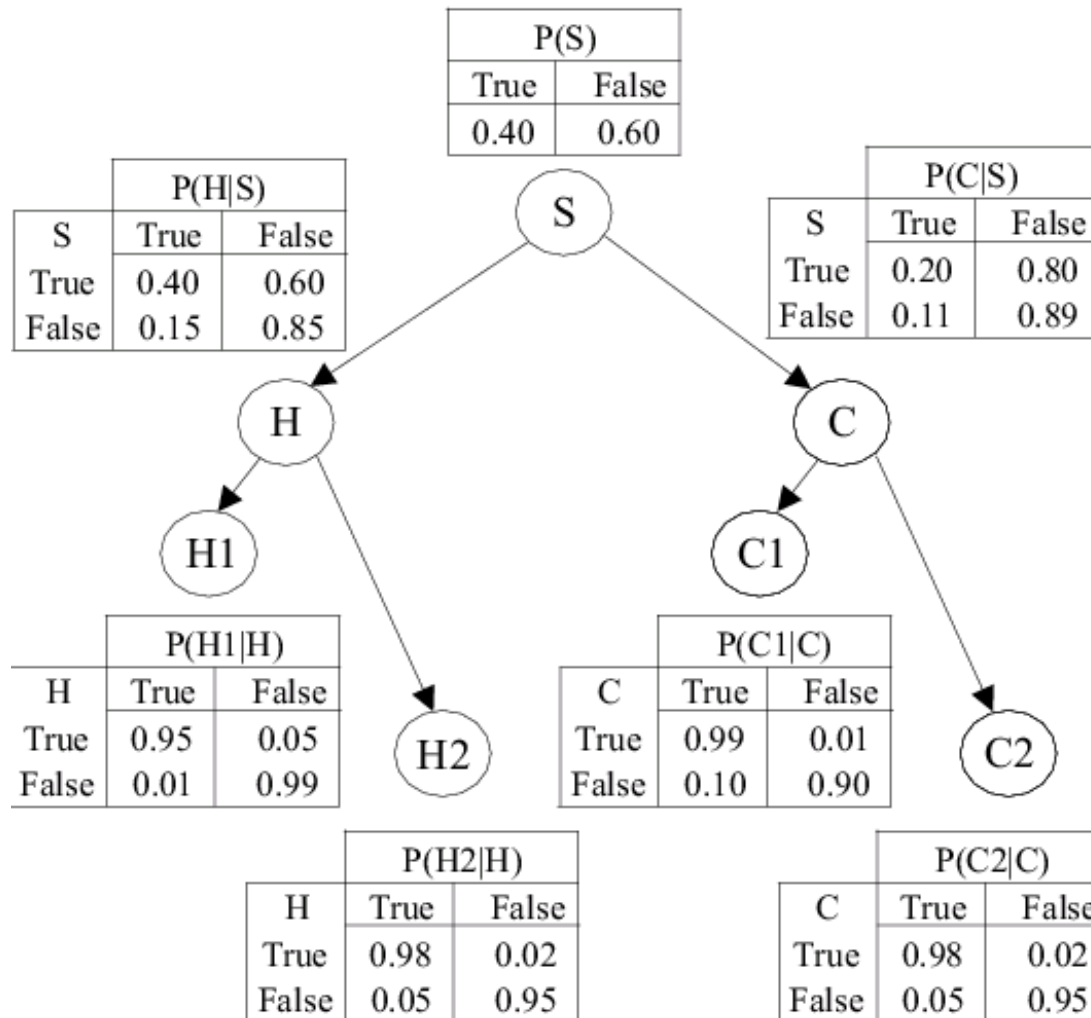
➤ For this case:

$$p(x_1, x_2, \dots, x_6) = p(x_6 \mid x_5, x_4) \cdot p(x_5 \mid x_4) \cdot p(x_3 \mid x_2) \cdot p(x_2) \cdot p(x_1)$$

- Bayesian Networks
  - a directed acyclic graph (DAG)
  - the nodes correspond to random variables
  - arc represents parent-child (*dependence*) relationship

- A Bayesian Network is specified by:
  - The **prior probabilities** of its root nodes.
  - The **conditional probabilities** of the non-root nodes, **given their parents**, for **ALL possible** combinations.

– A Bayesian Network from a medical application

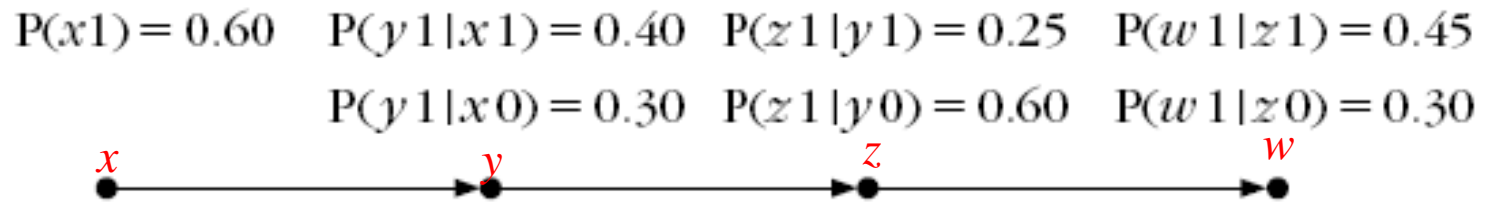


➤ This BBN models conditional dependencies concerning **smokers' (S)**, tendencies to develop **cancer (C)** and **heart disease (H)**, together with variables corresponding to **heart (H1, H2)** and **cancer (C1, C2)** medical tests



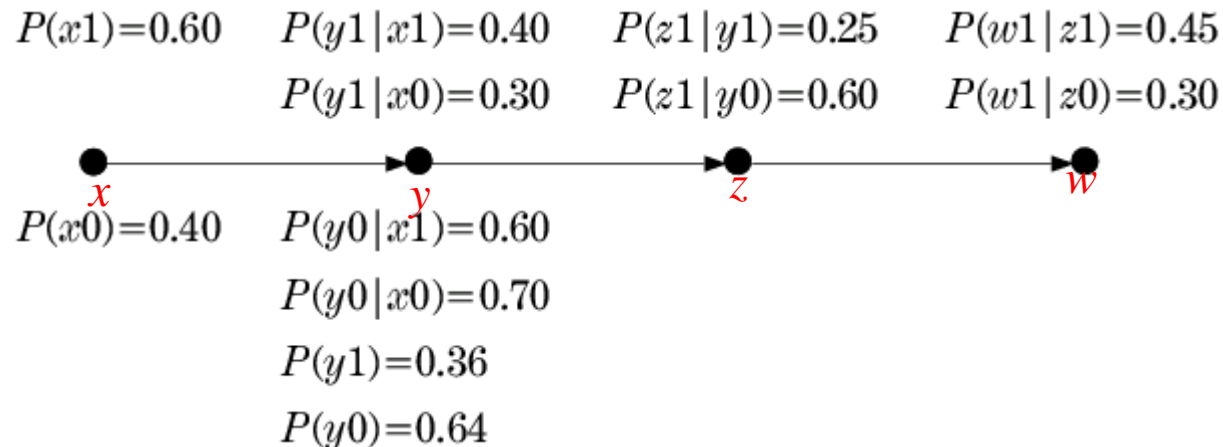
- any joint probability can be obtained by multiplying the prior (root nodes) and the conditional (non-root nodes) probabilities.
- **Training:** given a topology, probabilities are estimated from training data. There are also methods that learn the topology.
- **Probability Inference:** Given a pattern (evidence), the goal is to compute the conditional probabilities for some of the other variables (class)

- Example: Consider the Bayesian network of the figure:



- Random variables:  $x, y, w, z$
- $x_0$  means  $x = 0$
- $x_1$  means  $x = 1$

- We can calculate the other probabilities

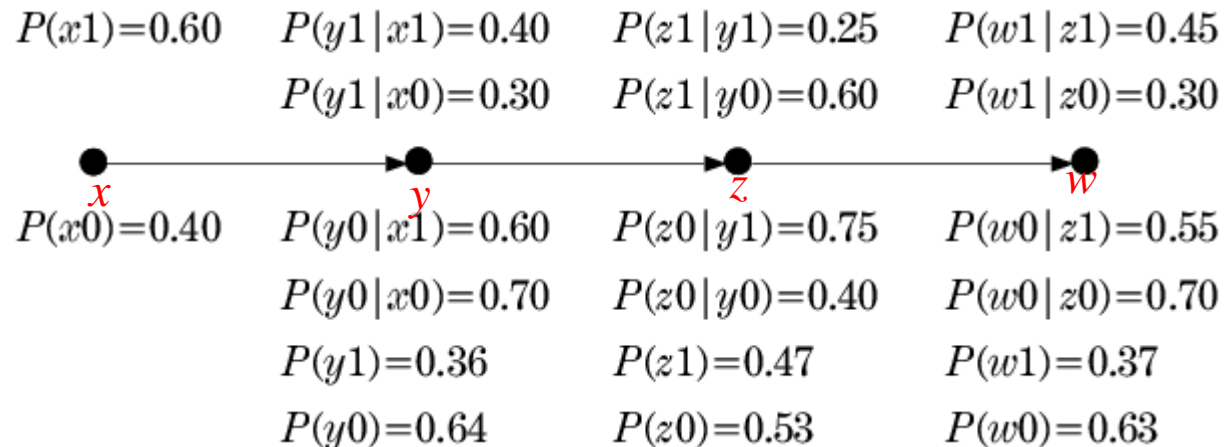


Example:  $p(y_1)$ :

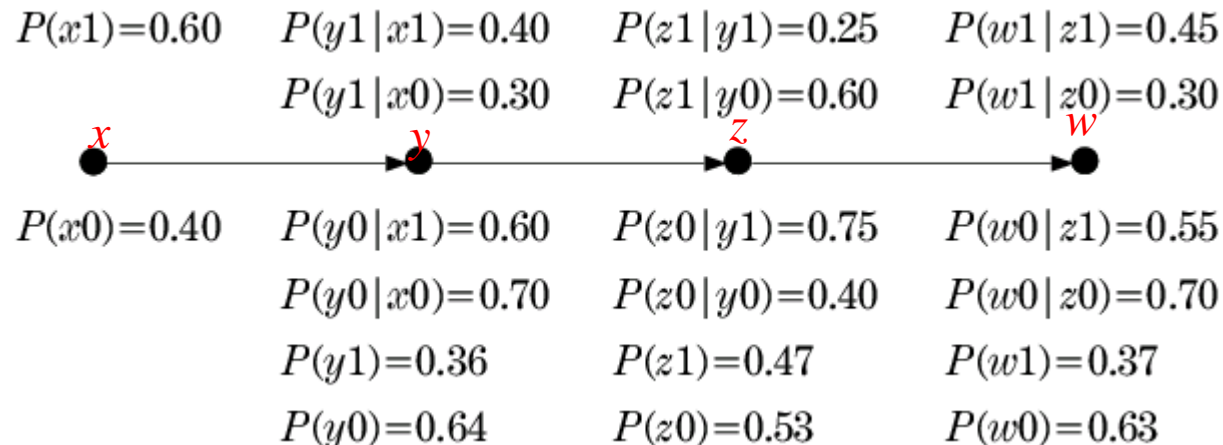
$$P(y1) = \sum_x P(y1, x) = P(y1, x1) + P(y1, x0)$$

$$P(y1) = P(y1|x1)P(x1) + P(y1|x0)P(x0) = (0.4)(0.6) + (0.3)(0.4) = 0.36$$

- We can calculate the other probabilities



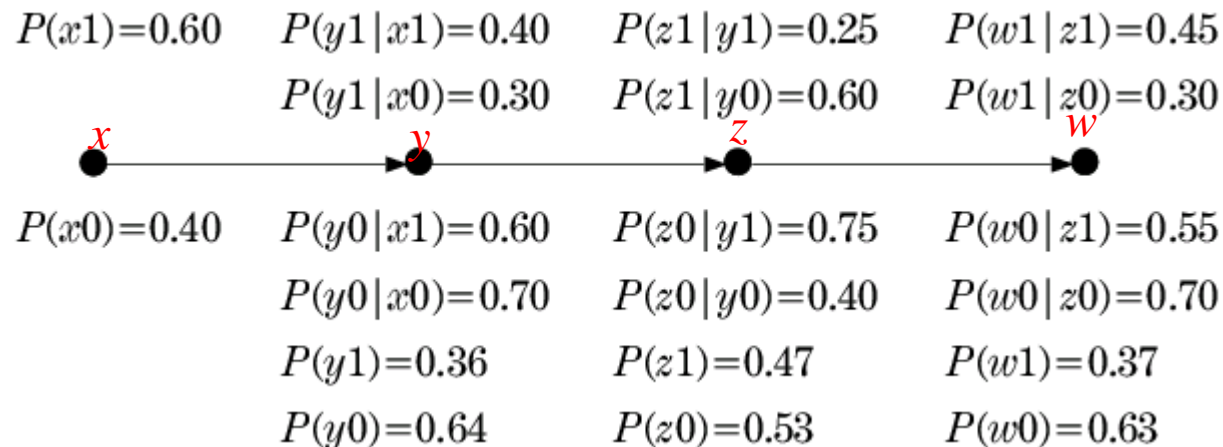
- Given this info, we can answer any probabilistic query:



a) If  $x$  is measured to be  $x=1$  ( $x1$ ), compute  $P(z1|x1)$  and  $P(w0|x1)$ .

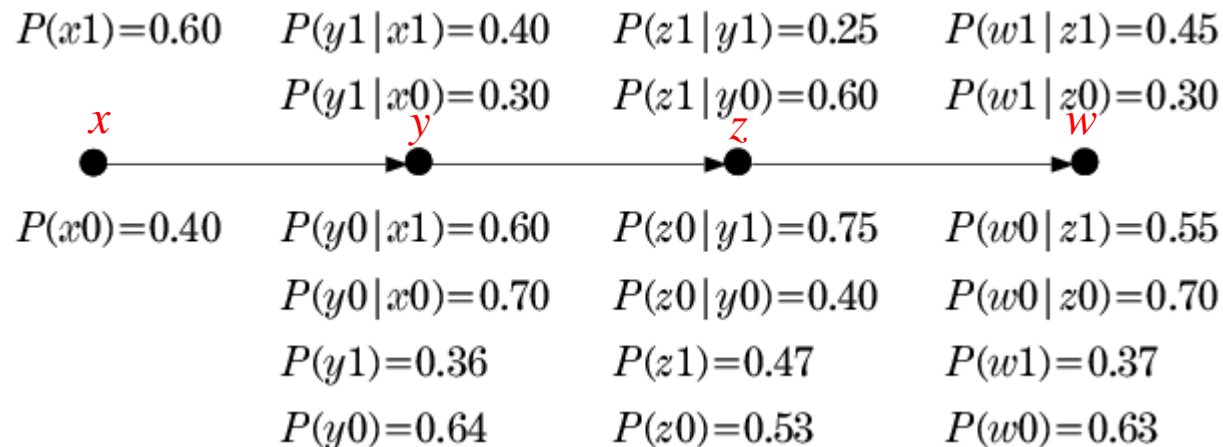
b) If  $w$  is measured to be  $w=1$  ( $w1$ ) compute  $P(z1|w1)$ .

a) If  $x$  is measured to be  $x=1$  ( $x_1$ ), compute  $P(z_1|x_1)$  and  $P(w_0|x_1)$ .



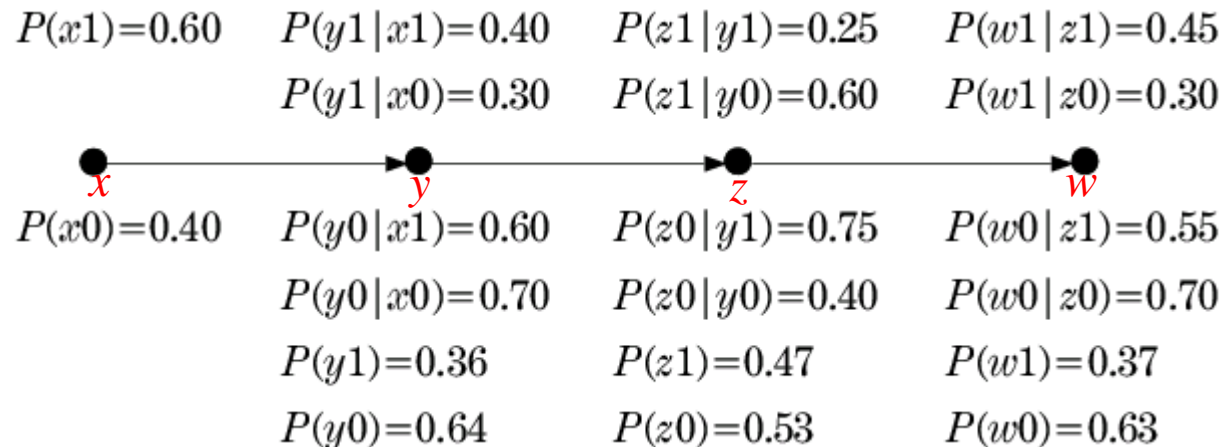
$$\begin{aligned}
 P(z_1|x_1) &= P(z_1|y_1, x_1)P(y_1|x_1) + P(z_1|y_0, x_1)P(y_0|x_1) \\
 &= P(z_1|y_1)P(y_1|x_1) + P(z_1|y_0)P(y_0|x_1) \\
 &= (0.25)(0.4) + (0.6)(0.6) = 0.46
 \end{aligned}$$

a) If  $x$  is measured to be  $x=1$  ( $x_1$ ), compute  $P(z_1|x_1)$  and  $P(w_0|x_1)$ .



$$\begin{aligned}
 P(w_0|x_1) &= P(w_0|z_1, x_1)P(z_1|x_1) + P(w_0|z_0, x_1)P(z_0|x_1) \\
 &= P(w_0|z_1)P(z_1|x_1) + P(w_0|z_0)P(z_0|x_1) \\
 &= (0.55)(0.46) + (0.7)(0.54) = 0.63
 \end{aligned}$$

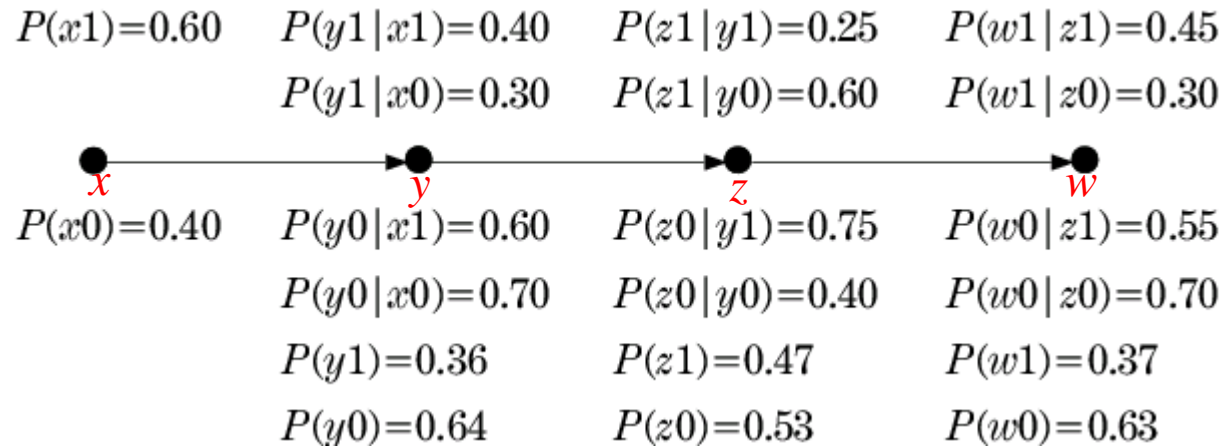
b) If  $w$  is measured to be  $w=1$  ( $w1$ ) compute  $P(z1|w1)$ .



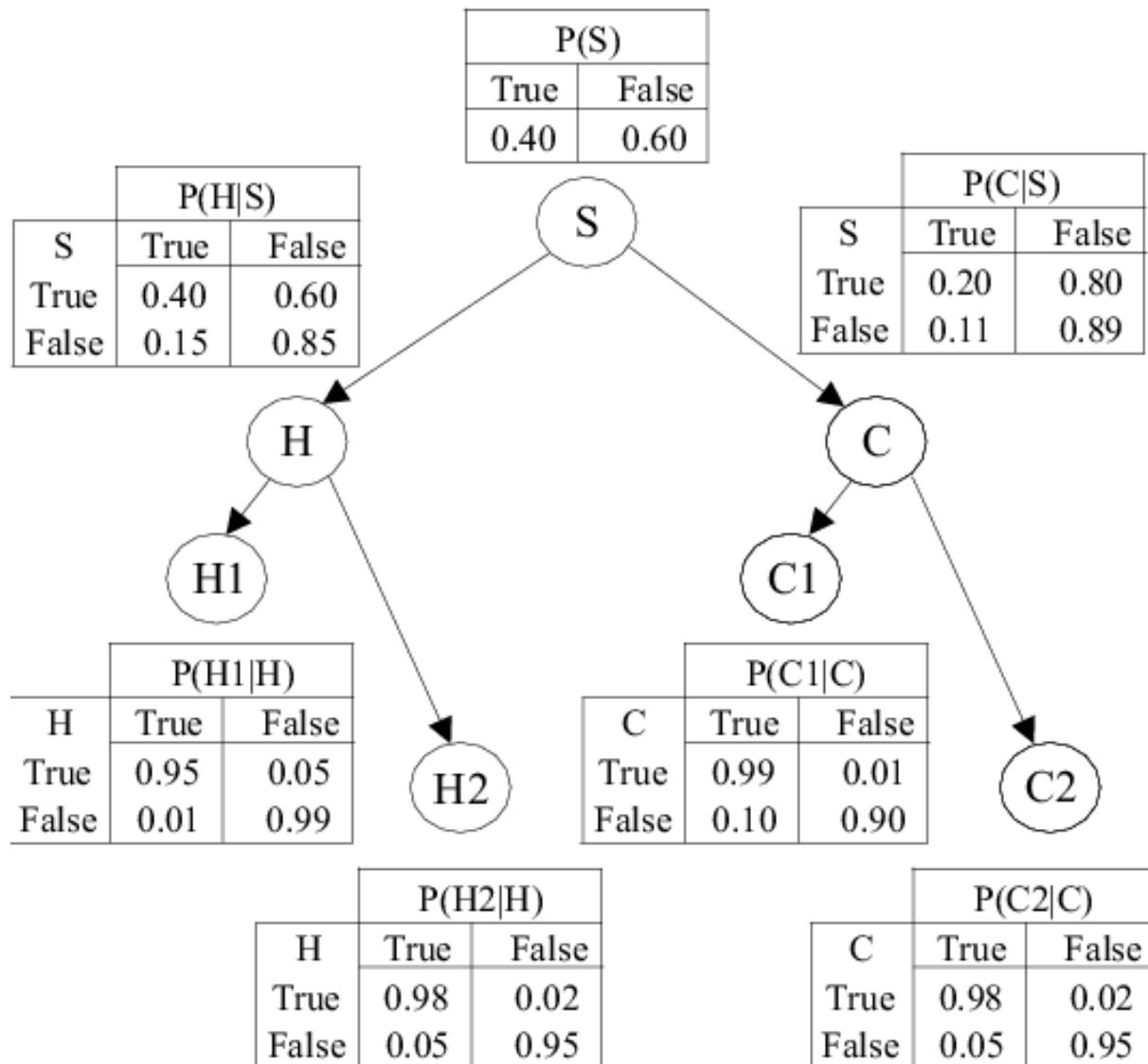
$$P(z1|w1) = \frac{P(w1|z1)P(z1)}{P(w1)} = \frac{(0.45)(0.47)}{0.37} = 0.57$$



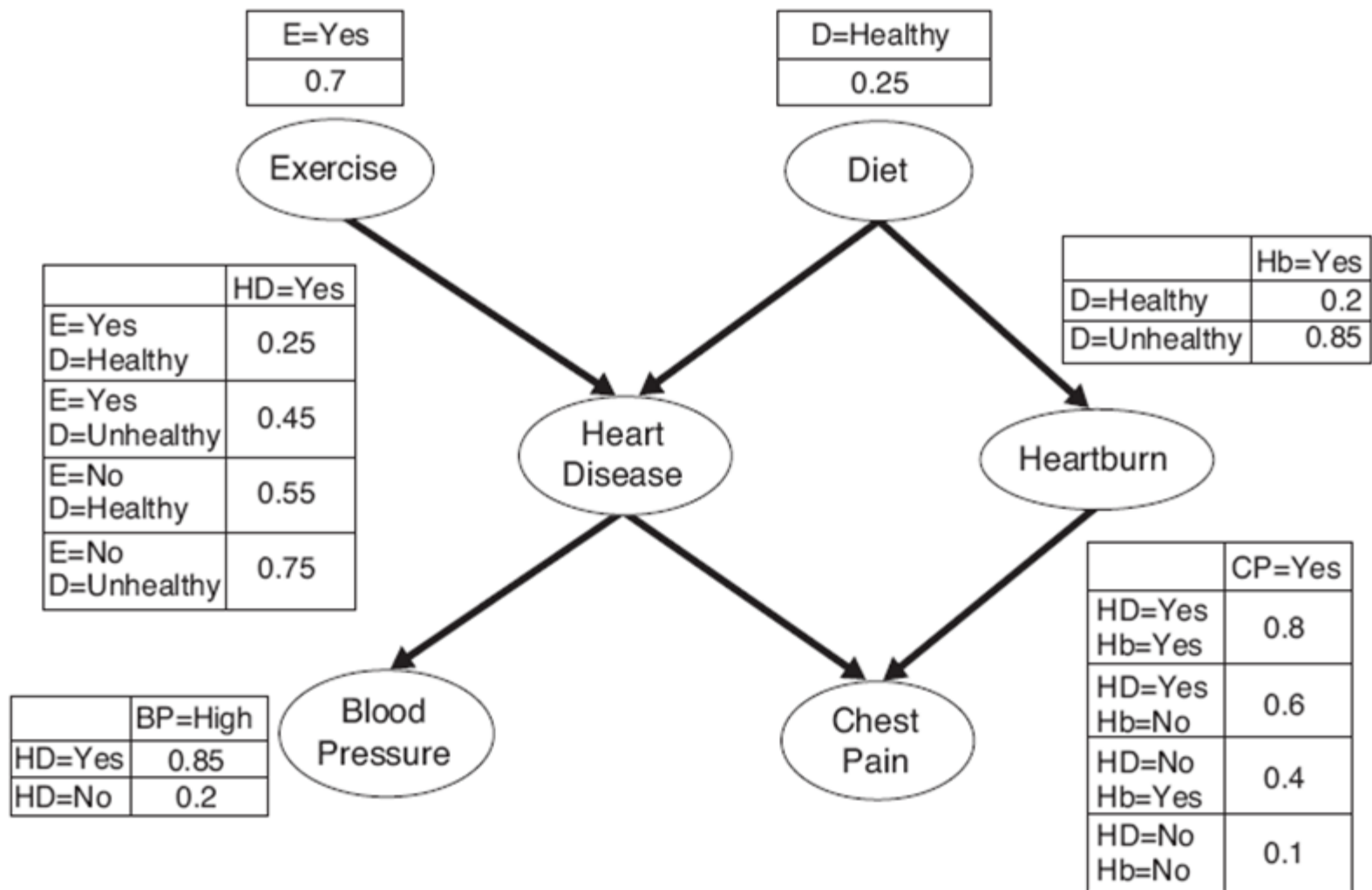
c) CAN WE CALCULATE  $P(x_0|w_1)$ ?



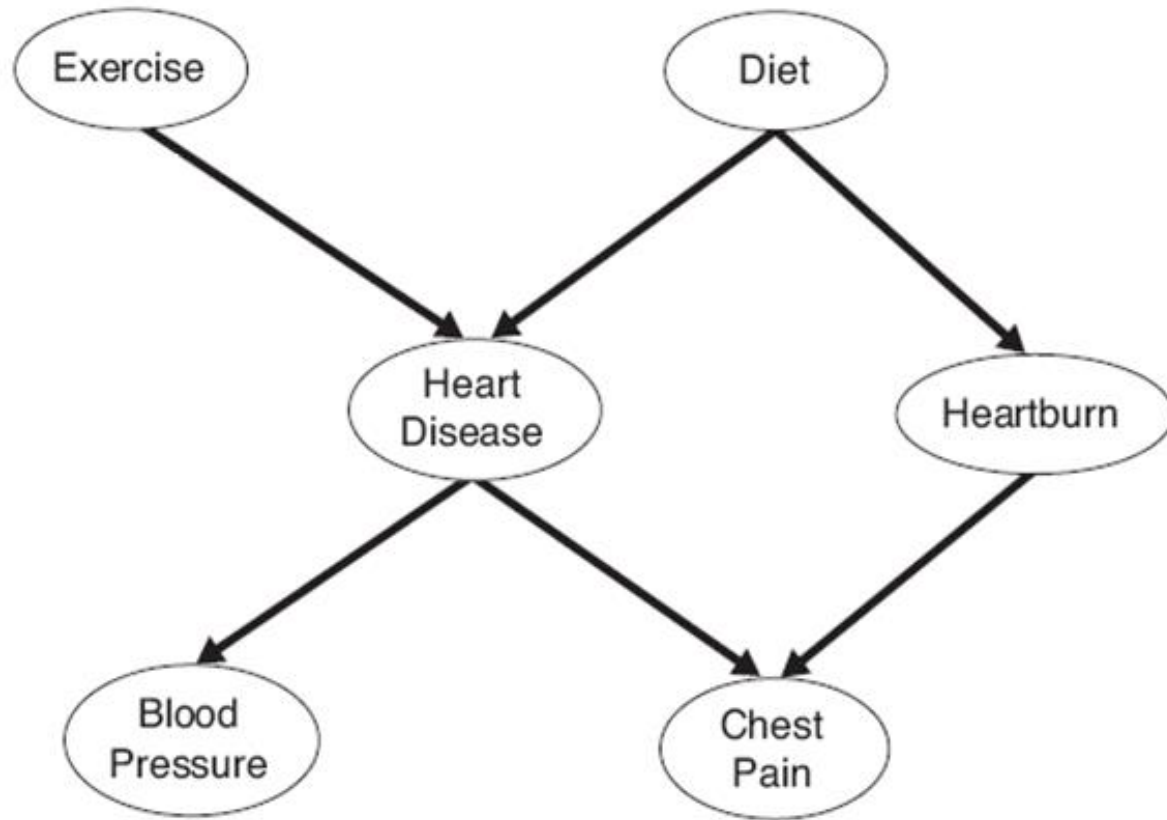
## What's about more complex networks?



## What's about more complex networks?

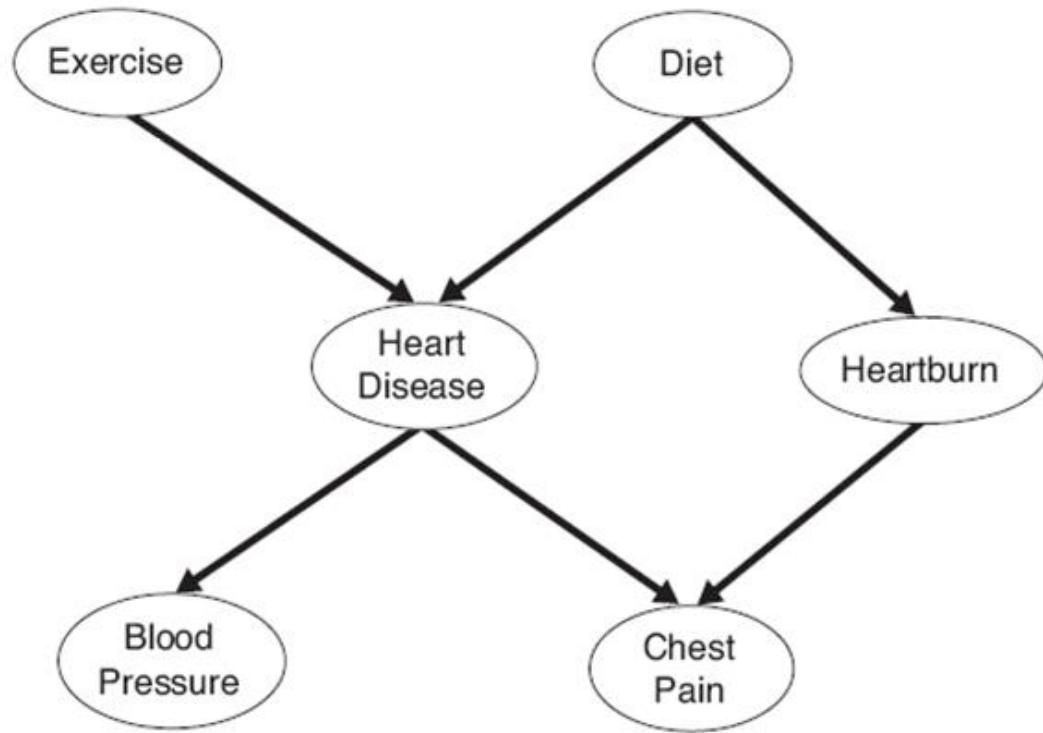


We will study this graph



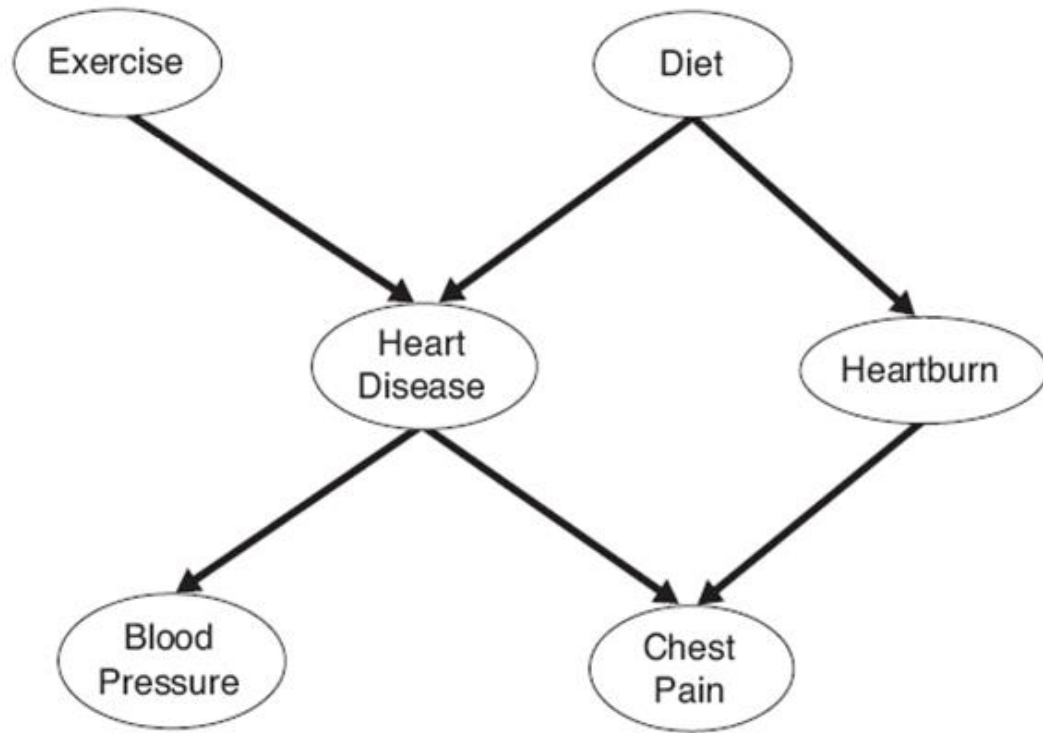
We can show:

- $P(D|E)=P(D)$
- $P(Hb|HD, E, D)=P(Hb|D)$
- $P(CP|Hb, HD, E, D)=P(CP|Hb, HD)$
- $P(BP|CP, Hb, HD, E, D)=P(BP|HD)$
- However,  $P(HD|E,D)$  cannot be simplified



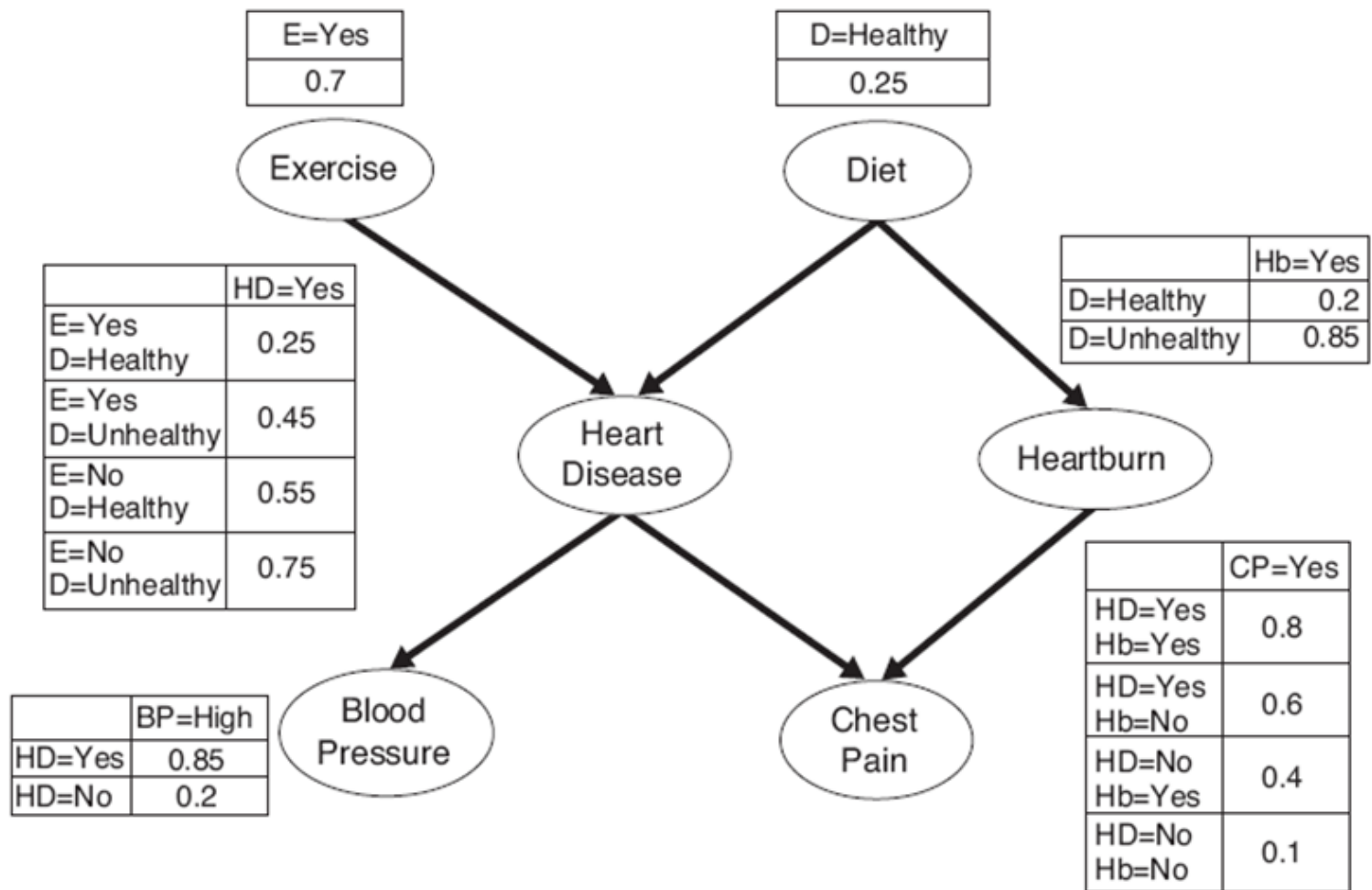
Exercise:

- $P(CP|HD, BP, E, D) = ?$



Exercise:

- $P(CP|HD, BP, E, D)$  = No simplification



Calculate  $P(\text{HD}=\text{yes})$  ?