# Lab 7 — More trees that you ever wanted

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## What we are going to focus on today

Practicing AVL trees

## Exercise #1: the importance of Balance [1.5 pts]

- BST performance depends on whether the tree is balanced or not
- In this exercise we will introduce the balance metric

## Exercise #1/2

- Implement a binary search tree with insertion and search operations as seen in class [0.2 pts]
  - It should extend the template provided on D2L with an insert() and a search() method
- 2. Implement code to measure balance for each node in the tree [0.4 pts]
- 3. Generate a 1000 random search tasks [0.3 pts]
  - 1. Generate the list of the first 1000 integers
  - 2. Generate 1000 different tasks by shuffling the list 1000 times
- 4. For each task, measure average performance (i.e. across searching each integer in the tree) and largest absolute balance value [0.3 pts]
- 5. Generate a scatterplot with absolute balance on the X axis and search time on the Y axis [0.3 pts]

#### Exercise #1 - What to deliver

• Submit a file named ex1.py with your answer to questions 1 to 5

## Exercise #2 – baby steps [1.5 pts]

• In this exercise, we'll start turning our BST into an AVL tree

### Exercise #2 /2

- Extend the BST implementation from exercise 1 by extending the insert() method:
- 1. Implement code to identify the pivot node on node insertion [0.3 pts]
- 2. Implement code to identify case 1 (pivot does not exist) [0.4 pts]
  - In this case, the code should print "Case #1: Pivot not detected"
  - The code should also update node balances
- 3. Implement code to identify case 2 (pivot exist but node is being inserted into shorter subtree) [0.6 pts]
  - In this case, the code should print "Case #2: A pivot exists, and a node was added to the shorter subtree"
  - The code should also update node balances

## Exercise #2 /3

- 4. Implement four test cases. Each test case consists into adding an appropriate sequence of nodes: [0.2 pts]
  - Adding a node results in case 1
  - Adding a node results in case 2
  - Adding a node results in case 3 (the code should print "Case 3 not supported")

#### Exercise #2 - What to deliver

• Submit a file named ex2.py with your answer to questions 1 to 4

## Exercise #3: more AVL trees [2 pts]

- Extend the baby AVL tree implemented in Exercise 3 to support case 3A by:
- Implementing an internal \_left\_rotate() method to support left rotation of nodes as discussed in class [0.5 pts]
- 2. Implementing an internal \_right\_rotate() method to support right rotation of nodes as discussed in class [0.5 pts]
- 3. Extending the insert() method to support case 3a: [0.8 pts]
  - 1. The code should also print "Case #3a: adding a node to an outside subtree"
  - 2. Remember to update the weights!
- 4. Extend the test cases from exercise 2 with two new more cases: [0.2 pts]
  - 1. One resulting in case 3a
  - 2. One resulting in case 3b (the code should print "Case 3b not supported")

#### Exercise #3 - What to deliver

• Submit a file named ex3.py with your answer to questions 1 to 4

## Exercise #4: a fully grown AVL tree [2 pts]

- Turn the AVL tree of Exercise 3 into a fully grown AVL tree by supporting case 3b:
- 1. Create a \_lr\_rotate() method to perform LR rotation [0.5 pts]
- 2. Create a \_rl\_rotate() method to implement RL rotation [0.5 pts]
- 3. Extend insert() to support case 3b, using the methods above [0.8 pts]
- 4. Create two extra test cases, both testing case 3b (now the code should not return an error!) [0.2 pts]

#### Exercise #4 - What to deliver

Submit a file named ex4.py with your answer to questions 1 to 4

#### How to submit

• Upload a zip file to the "Lab 7" dropbox on D2L, containing the required content for every exercise

## Grading rubric

- You get 3 pts for uploading a partial solution by end of lab
  - Must not be an empty file or irrelevant material
- Then, you'll have until 11:59PM of the day before the next lab to upload the complete solution. That will be graded as follows:
  - Exercises 1, 2: 1.5 pts each
  - Exercises 3, 4: 2 pts each
  - Can upload the complete solution to the same dropbox

## That's all folks!