view_frames Result Recorded at time: 211.929 odom Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base_link Broadcaster: /robot_state_publisher | Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.0 Average rate: 50.201 Average rate: 10000.0 Buffer length: 4.98 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 211.903 Most recent transform: 0.0 Oldest transform: 206.923 Oldest transform: 0.0 Oldest transform: 0.0 imu_link caster_back_link

base_scan