

# Self-Service Systems

# Cash Media Dispenser

Version 4

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# **Cash Media Dispenser**

Version 4

**Software Manual** 

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# CMD-V4 Cash Media Dispenser Version 4

## References

| AZM_NG Software Manual                                |  |  |
|---|--|--|
| PFHT 205  | Edition 2.7 of 2005-06-09  |  |
| Cash dispenser module – ProCash 1000; Software Manual |  |  |
| Doc. no.: 0170019430                                  | Edition: 1.3 of 2001-08-23   |  |
| AZM_NG SW description IBM emulation                   |  |  |
| Doc. no.:   | Edition: 1.0 from 29.01.1998   |  |
| WN Development Guide 01/00 - Project 6                | execution  |  |
| Doc. no.: 803a  | Edition: 1 of 2000-10-06   |  |
| Wincor Nixdorf Device Descriptor Definition           | on   |  |
| Doc. no.: 0170022314                                  | Edition: 2.2 of 2000-09-18   |  |
| Error stack for self-service components               |  |  |
| Doc. no.: 0170022507                                  | Edition: 1.1 of 2000-08-28   |  |
| ProCash CRS (Cash Recycling System);                  | Software Manual  |  |
| Doc. no.: BSCH 730                                    | Edition: 3.1 of 2001-07-06   |  |
| CMD-V4; Power Up Test and Self-test                   |  |  |
| Doc. no.:   | Edition: of2002  |  |
| CMD-V4; Analysis Tool - Device Informa                | tion; Trace; Error Log   |  |
| Doc. no.:   | Edition: of2002  |  |
| Schneider, Bruce:                                     |  |  |
| Angewandte Kryptographie (applied cryptography)       | Bonn: Addison-Wesley, 1996   |  |
|   | PFHT 205 Cash dispenser module – ProCash 1000; Doc. no.: 0170019430 AZM_NG SW description IBM emulation Doc. no.: WN Development Guide 01/00 – Project of Doc. no.: 803a Wincor Nixdorf Device Descriptor Definition Doc. no.: 0170022314 Error stack for self-service components Doc. no.: 0170022507 ProCash CRS (Cash Recycling System); Doc. no.: BSCH 730 CMD-V4; Power Up Test and Self-test Doc. no.: CMD-V4; Analysis Tool – Device Informat Doc. no.: Schneider, Bruce: Angewandte Kryptographie (applied |  |

## **Abbreviations**

!= Not Equal To

\$MOD\$ WN module identifier (SW)

AZM Dispensing module

AZM\_NG Dispensing module (new generation)

BCS Block Check Sum
CBC Cipher Check Sum

CMD-V4 Cash Media Dispenser - Version 4

CRS Cash Recycling System
DEA Data Encryption Algorithm
DES Data Encryption Standard

DK Printing cassette

ECB Electronic Code Book

ECM External counter management

EDA Express Delivery Application (OS/2 – IBM application)

EDM Encryption Decryption Mode

FW Firmware

HOST Higher-level system

ISO International Organization for Standardization

IV Initial Value
KCV Key Check Value
KEK Master Key (KEK)
KGK Key Generating Key

NA Power failure

OEM Original Equipment Manufacturer
PLD Programmable Logic Device

RR box Reject-/Retract box

SCOP Secure Cash Out Procedure SE Special electronics module

TAN Transaction number

TDES/ Triple-DES

3DES

UDS User Defined Status ÜMA Universal Serial Bus

VCMD Vertical Cash Media Dispenser EDM Encryption / decryption module

## Overview

## Purpose and scope of this document

This document provides detailed information about the characteristics and the command set of the **CMD-V4**.

This document only describes the characteristics and the commands that are not included in [L 1], [L 2], [L 3], [L 4] or that have been modified.

#### Introduction

The main characteristics of the CMD-V4 are:

## **Device type**

The different device types (indoor/outdoor, rearload/frontload) and the variable number of dispenser modules (1-6) enable each user to choose the device type that best suits his individual needs.

#### **Error tolerance**

Within the CMD-V4, each note is checked after dispensing. Any errors detected, such as double dispenses, are corrected internally.

#### Control

The physical interface complies with the RS232C standard. In a deviation from this standard, the system is connected via a 9-pin D-sub plug.

The protocol (data link layer of the basic reference model according to ISO 7498) is based on DIN 66348 part1 control procedure C.

#### **Firmware**

The controller of the CMD-V4 features a loader that can be used to load the correct firmware for the device variant in question.

When the devices are delivered, the current FW is already loaded. If so required, updates are provided in the WN intranet.

## **Serviceability**

#### **ERROR STACK**

An error stack is managed in a separate memory area on the controller board. There are also suitable commands available for concerted error stack management on the HOST.

#### FIRMWARE ID

The FW version number can be read on the controller status display without the need for additional tools

## Compatibility

Compatibility analysis takes account of both the application and the configuration.

#### **APPLICATION**

In the CMD-V4 standard mode (default setting), no adjustments need be made to existing applications.

#### CONFIGURATION

The CMD-V4 configuration is, as with previous versions, set for a specific customer during ATM manufacture.

However, the way in which it is configured differs from the previous procedure. The size of the jumper field has been reduced.

The first jumper (DOOR) is now used for security relevant settings only. It is made with the safe door open.

Connector for (number of dispensing units, shutter available (YES / NO), output direction and printing cassette) replace the remaining jumpers.

A default controls how the CMD-V4 is to behave.

## **Device description**

This chapter outlines the individual hardware components of the CMD-V4.

More detailed information is available in related documents.

#### Cassette rack

A combination of 4-cassette and 1-cassette racks (max. 6) is used to build any configuration required.

Number of racks required for a 5-cassette tower: 1 x 4-cassette + 1 x 1-cassette; 3-cassette tower: 3 x 1-cassette.

A single 4-cassette rack with corresponding 4-way distributor board but only using 2 dispensing units (positions 1+ 2) is operable if B is jumpered.

## Dispensing unit

The cassette racks accommodate 1-cassette and 2-cassette dispensing units.

Number of dispensing units required for a

5-cassette tower: 2 x 2-cassette + 1 x 1-

cassette;

3-cassette tower: 1 x 2-cassette + 1 x 1-

cassette.

The upper dispensing unit houses the measurement station. This checks whether double or overlapping notes have been dispensed.

## **Stacker**

Notes that are dispensed are transported via the stacker incl. measurement station. All 'good' notes are made available as a bundle in an open clamp via the stacker wheel.

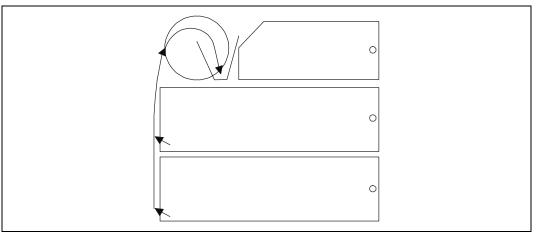


Diagram of the dispense transaction

When machines are installed outside Euroland, an optional single reject deflector can be integrated in the stacker.

## Handling "bad" notes

#### SINGLE REJECT DEFLECTOR AVAILABLE

Up to two 'bad' notes are initially parked in a separate tray. A replacement note is then dispensed.

After cash-out, the singled out notes are transported to the RR box.

Although the parked notes are not yet in the RR box, the reject counter (RACT) is incremented for each parked note.

#### SINGLE REJECT DEFLECTOR MISSING

Note dispensing is interrupted until all notes have reached the clamp. A note bundle reject then takes place.

The original dispense job command is repeated.

## **Vertical Cash Media Dispenser**

This device version has a modified stacker and output transport and no shutter. The single reject deflector is always available. As soon as a "bad" note is detected, it is singled out via the single reject deflector. All "good" notes are made available as a bundle in the stacking compartment via the stacker wheel and can be transported towards the cash output via the output transport.

There is no longer a separate retract tray in the VCMD.

## **Output transport**

The note bundle is held in the closed clamp. It is transported to its destination via gear tracks. In the VCMD, transport occurs via belt transport.

The version is shown in the diagram "Component positions".

## **Cash output**

The cash is first forwarded to a waiting position. The shutter – if installed – at the end of the transport route is opened. The bundle is then transported to the output position.

The note bundle is presented via integrated belt transport. Cash output is complete when

The note bundle is presented via integrated belt transport. Cash output is complete when the notes have been removed.

Notes which are not removed can be withdrawn and stored unsorted on the retract tray of the RR-box. The number of retracts is counted.

Optionally, a bundle can be retracted and stored securely in the stacking position. If this option is used, however, no further device operations are possible until the bundle is removed by an operator and the software has canceled the lock.

## **Cash trapping detection**

Depending on the device version, the systems can be equipped with cash trapping detection. This is meant to detect cash trapping devices that are directly attached to the original shutter with a short distance.

Specific shutter electronics are required for cash trapping detection. Data evaluation gives information about a possibly detected attachment or a manipulation. Error handling is expanded/modified.

The behavior of the cash trapping detection can be configured (see firmware configuration: SHUT\_PROTECT\_OPT). Like all firmware configuration options, the configuration becomes operative after the next RESET/CLEARING due to the non-volatile storage. Existence of a cash trapping detection is indicated in the device status <SHUT\_PROTECT>. If no cash trapping detection is available, the device works like a customary CMD-V4.

During initialization of the CMD main firmware (after Power on, RESET, or CLEARING), the function and initialization values are checked when a cash trapping detection is available and working <SHUT\_PROTECT\_OPT>=Y. If the result is negative, CLEARING, RESET or the first status request after Power on are acknowledged with status D ("Out of service") and in device status <SHUT\_PROTECT>=D is set.

Before every dispense transaction, the sensory mechanism for cash trapping detection is checked when one is present and in operation <SHUT\_PROTECT\_OPT>=Y and the shutter is closed. The sensors might have been manipulated during the last transaction. If the result is negative, the command is acknowledged with status E ("Device error") and in device status <SHUT\_PROTECT>=M is set.

For a reset of the error see section "Reset of a cash trapping detection error" (page 10).

## **Evaluation during cash presentation**

The command DCP (cash presentation) effects that the bundle is transported behind the shutter as before and that the shutter is opened.

Before note output, evaluation for cash trapping detection is started when the detection is activated. If no cash trapping device is detected, the bundle is presented as it has been before. Otherwise the shutter is closed, reopened and another detection process is started.

When the result remains negative after 2 repeats, then:

- the shutter is closed.
- the bundle is transported into the stacker.
- <MON>=P is set.
- the command is acknowledged with status E ("Device error").

The bundle can be transported into the retract cassette by the retract request command.

For a reset of the error see section "Reset of a cash trapping detection error" (page 10).

#### Status codes

#### E = Device error

| Cash trapping device detected | <shut_protect></shut_protect> | = K  |
|-------------------------------|-------------------------------|------|
|                               | SCOD                          | = 28 |
|                               | SHERR                         | = B  |
|                               | SHUT                          | = U  |

Until the next transport command (DC..., e.g. Retract, Open shutter, Close shutter, ...) RESET, CLEARING or Power on remains in device status <SCOD>=28, <SHUT>=U, <SHERR>=B. If the device works without any errors and a cash trapping detection error has not taken place yet, these commands are acknowledged with status A and in device status <SCOD>=00, <SHUT>=C, <SHERR>=N are set, <SHUT\_PROTECT> remains unchanged.

## Reset of a cash trapping detection error

After fault elimination or removal of the cash trapping device, a cash trapping detection error can be reset as follows:

- by DCT (shutter test) command. It is checked whether a cash trapping detection error is still present. If so, the transaction is terminated with the status E (Device error), <SCOD>=28, <SHUT>=U, <SHERR>=B are set and <SHUT\_PROTECT> remains unchanged.
- previous to the next dispense transaction, the system checks whether a cash trapping detection error is still present. If so, the transaction is terminated with the status E (Device error), <SCOD>=00, <SHUT>=C, <SHERR>=N are set and <SHUT\_PROTECT> remains unchanged.

#### **Cassettes**

In addition to the dispenser cassettes, a combined RR box is used in the CMD-V4. Both types also function in AZM\_NG and similar versions.

#### **Versions**

The following versions are available.

|             | Lever | Lock | Lead<br>seal | Tamper indicator | Ink dye (integrated degradation system) |
|-------------|-------|------|--------------|------------------|---|
| Standard    | X     |      | X            | Х                |   |
| Security I  |       | X    | X            | Х                |   |
| Security II |       | X    | X            | X                | X                                       |

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The status of the indicator is displayed in a window located at the upper left on the front of the cassette.

The display is normally **green**.

A **blue** display indicates that the cassette has either been inserted in a voltageless dispenser or has been manipulated or opened by force.

In this case, you should check the cassette contents before inserting the cassette.

When you open the cassette, the indicator is reset.

#### Dispenser cassette

The cassette contains an "INSERT" which can be adapted to the required banknote size without using any tools. The pressure is provided by a motor-operated pressure carriage. During operation, a "physically empty" cassette is detected.

Each dispenser cassette contains a non-volatile memory which stores the cassette number as well as cassette-specific parameters (e.g. currency, value and release date). The cassette number is preset in the factory. It can be changed by the user if required.

#### **RR BOX**

The combined RR box has a capacity of approximately 400 notes in the reject area and approximately 100 notes in the retract area.

There is no longer a separate retract area in the VCMD.

#### **PRECONDITIONS**

The operator must ensure that the CMD-V4 has the correct data and fill volumes before customer mode is activated!.

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Dispensing is not prevented if:

- the RR box is full,
- a logical dispenser cassette is now empty.

## **Compatibility to other WN cassettes**

Two cases must be considered: Forward and backward compatibility.

#### FORWARD COMPATIBILITY

There are no restrictions to the use of cassettes from the AZM\_NG family in the CMD-V4.

In detail these are cassettes with:

- No indicator
   Cassettes of this type are not equipped with an indicator.
- Tamper indicator (green/blue)

The indicator has the same meaning as on CMD-V4 cassettes.

- The indicator does not change to blue when a cassette that was inserted in a voltageless dispenser is removed.
- Re-insertion lock (green/red)
   These cassettes must always be opened before they are re-inserted.
   This hampers troubleshooting if it means that an additional person is needed to open the cassettes.

#### BACKWARD COMPATIBILITY

In principle, the CMD-V4 cassettes can also be used in the AZM\_NG family.

However, the indicator changes to blue each time a cassette is removed. The AZM\_NG family does not have the technology needed to operate the optimized tamper indicator on the CMD-V4 cassettes.

## Monitoring the available cassettes

All cassette positions are checked cyclically for changes. As soon as the CMD-V4 detects a change, this is noted (generally in the device status and, for individual cassettes, in the cassette status or in the CMD-V4 capabilities).

#### **Device status**

This documents whether the cassette inventory has changed since the last synchronization command 'Confirm cassettes installed'.

<CEX>=N No change <CEX>=Y Cassettes available changed

#### Cassette status

<nSTA> displays the statuses of a cassette:

<nSTA>= D The newly inserted cassette is faulty (e.g. stepper motor, EE-PROM or dispensing sensor)

<nSTA>= E Cassette is physically empty.

<nSTA>= M Cassette removed or incorrectly inserted.

<nSTA>= P Cassette is not ready. The banknote-specific features of the cassette must be declared to the measurement station via reference value calculation.

<nSTA>= R The cassette is ready. It is filled and the banknote-specific features have been declared to the measurement station. If it has been removed since, the contents may have changed.

#### CMD-V4 CHARACTERISTICS

**<C\_TYPE>** displays the cassette type for each dispenser module.

#### Cassette change

After a cassette change, the host and the CMD-V4 must first be synchronized. If this does not take place, dispensing jobs for certain cassette positions may be rejected with **context error**.

#### Example:

- Synchronization in the HOST, e. g. by service ID card. HOST switches from customer operation to the SERVICE status.
- Execution of cassette change.
- During the installation procedure, each cassette must be pushed into its position until
  it engages in its working position. The required pressure is then created. The operator
  is informed of the result via an acoustic signal:

## No. of tones Meaning

- 1 The correct pressure was created.
- 3 Action not successful; remove cassette and re-position it.
- Synchronization with the host.

Check whether cassettes have been changed. If they have, check the new cassette set. If necessary, update the banknote parameters and/or cassette contents in the CMD-V4 and reconcile them with the HOST.

Restart cassette monitoring in the CMD-V4 (confirm cassette inventory).

HOST reverts to customer operation.

#### Controller

The controller is responsible for complete control of the CMD-V4. From a rearload viewpoint, it is mounted at the left on the output transport.

The controller receives commands from the HOST, acknowledges them, checks them, and executes them. Afterwards, the command acknowledgment is sent to the HOST.

## **External messages**

As an option, the CMD-V4 controller can handle 2 external messages.

#### Door status

If the CMD-V4 is installed in a safe and the status of the safe door is to be reported to the HOST system, the first external input on the controller board can be used for the message line.

#### Safety switch

The second external input on the controller board can be used if operation of the CMD-V4 is to be protected by means of a safety switch.

#### **LOCKING HANDLE**

If the dispenser is not fully inserted into the safe, the FW queries the locking handle and prevents the clamp moving to the stop-over position. This only applies to out-safe versions.

## Status display

The 2-digit status display shows the current status of the CMD-V4.

The last status which occurred is always displayed. Status code "00" is displayed before a command that triggers mechanical movements.

Appendix B (page Fehler! Textmarke nicht definiert.Fehler! Textmarke nicht definiert.) lists possible displays and appropriate reactions.

#### **Function button**

In certain cases it is advisable to check whether the CMD-V4 is ready to operate without using further tools.

A function key is provided on the controller for this purpose. When the key is pressed, all possible functions are cyclically displayed on the status display. Releasing the key for a particular display activates the selected function.

|   | Function                     | Description  |  |  |  |
|---|------------------------------|--|--|--|--|
| 0 | Normal operation             | Return to normal mode (not a function).  |  |  |  |
| 1 | Reset                        | The result is displayed on the status display after a 'RESET' has been carried out.          |  |  |  |
| 2 | Overall test + 'RESET'       | The mechanical components of the CMD-V4 are moved one after another.                         |  |  |  |
| 3 | Test dispensing + RESET      | One banknote is dispensed from each available cassette and transported to the RR box.        |  |  |  |
|   |                              | <nact> is modified; <nndv> remains unchanged.</nndv></nact>                                  |  |  |  |
| 4 | FW release                   | The release number is displayed in alternating mode.   |  |  |  |
|   |                              | Example:   |  |  |  |
|   |                              | From the firmware ID (read with DIL)   |  |  |  |
|   |                              | \$MOD\$ 061203 1137 CMD_V4_0.BIN   |  |  |  |
|   |                              | version number 1137 is displayed as follows:   |  |  |  |
|   |                              | 11 for 1 seconds   |  |  |  |
|   |                              | 37 for 1 second  |  |  |  |
|   |                              | dark for 1 second  |  |  |  |
|   |                              | After nine attempts, the device returns to normal mode.                                      |  |  |  |
| 5 | Resetting statistics counter | The resettable counters are reset to 0 and the current date of the real time clock is saved. |  |  |  |
| 6 | Deactivation of encryption   | In case of an open door switch and DES_CLEAR_BUTTON=Y the encryption is deactivated.         |  |  |  |

## **Firmware**

#### Firmware modules

The FW that controls the CMD-V4 is contained in the following modules:

- Bootstrap loader
- Controller

## **Bootstrap loader**

Until the controller is completely loaded, the commands are processed by the bootstrap loader.

The following commands are executed by the loader:

Load firmware

After loading (see [L 1], chapter software transfer) a check verifies that the right component has been loaded.

If this is not the case, the response to the load command is a negative acknowledgment and the CMD-V4 remains in the status "FW missing".

## Controller

The control program of the CMD-V4 contains the complete command set.

In addition to general commands such as software provision, encryption and commands to support serviceability, the behavior can be set to defined values.

## USB - CMD-V4 as USB device

## Introduction

So far command transfer has been realized via the V24 interface by means of the ISO protocol (ISO7498). Due to the introduction of USB, the former 24V transfer has been replaced by USB whereupon the short package procedure of USB is used for flow control.

The CMD\_V4 is a full-speed USB device.

### Firmware behavior

Jobs are no longer transferred with the ISO protocol via USB. In its place, short package mode is used for flow control. The national USB chip that is used supports a maximum FIFO depth of 64 bytes. If more than 64 bytes are to be transferred to or from the CMD\_V4, the data is split into 64-byte blocks and sent separately. Any packet that contains less than 64 bytes of data is known as a short package. Only when a short package is received is the receive buffer with the receive data returned to the caller.

If the USB cable is connected to the CMD\_V4 controller and enumeration has been executed with the PC host, commands can subsequently only be sent and received via USB.

After disconnecting the USB cable from the CMD\_V4 controller or deactivating the PC host, the system switches back to V24, i.e. USB has higher priority than V.24.

In addition to the normal command channel, there is also a debug channel, which communicates warnings and error messages from the firmware to the PC host. The debug channel is immediately activated during device enumeration (CMD\_V4). The PC application can optionally evaluate the debug channel. The debug channel is not a service channel, i.e. it cannot be used to send data to the device.

## Implementation overview

USB module USBN9603 from National Semiconductor is used on the CMD\_V4. This component has one standard endpoint (EP0) and a maximum of six additional endpoints (EP1 – EP6).

| Endpoints / type        | Assignment                          |
|-------------------------|-------------------------------------|
| Endpoint 0 (EP0)        | Class/Vendor-Requests               |
| Endpoint 2 (EP2) / Bulk | IN endpoint from Host               |
| Endpoint 1 (EP1) / Bulk | OUT endpoint from Host              |
| Endpoint 3 (EP3) / Bulk | Debug channel IN endpoint from Host |
| Endpoint 4 (EP4)        | Not used                            |
| Endpoint 5 (EP5) / Bulk | Not used                            |
| Endpoint 6 (EP6) / Bulk | Not used                            |

The host (PC) is always the initiator of a transaction, i.e. the device (CMD\_V4) will always only respond to queries from the host and never launch a transaction itself.

The CMD\_V4 behaves as described in the USB specification [1] for full-speed devices.

## **Device descriptor**

| Offset | Field             | Length | Value  | Description   |
|--------|-------------------|--------|--------|---|
| 0      | bLength           | 1 byte | 0x12   | Descriptor length                                   |
| 1      | bDescriptorTyp    | 1 byte | 0x01   | Device  |
| 2      | bcdUSB            | 2 byte | 0x0110 | USB Spec 1.1  |
| 4      | bDeviceClass      | 1 byte | 0x00   | Each interface in a configuration has its own class |
| 5      | bDeviceSubClass   | 1 byte | 0x00   | Must be 0   |
| 6      | bDeviceProtokoll  | 1 byte | 0x00   | No protocol   |
| 7      | bMaxPacketSize0   | 1 byte | 0x08   | Maximum packet size for endpoint 0                  |
| 8      | idVendor          | 2 byte | 0xaa7  | VendorID from Wincor Nixdorf                        |
| 9      | idProduct         | 2 byte | 0x4100 | ProductID for CMD_V4                                |
| 12     | bcdDevice         | 2 byte | 0x1130 | FW release (ECO) number e.g. 11.30                  |
| 14     | iManufacturer     | 1 byte | 0x01   | String descriptor for manufacturer                  |
| 15     | iProduct          | 1 byte | 0x02   | String descriptor for product name                  |
| 16     | iSerialNumber     | 1 byte | 0x00   | String descriptor for serial number                 |
| 17     | bNumConfiguration | 1 byte | 0x01   | Number of configurations is 1                       |

## Configuration descriptor

| Offset | Field               | Length | Value  | Description  |
|--------|---------------------|--------|--------|--|
| 0      | bLength             | 1 byte | 0x09   | Descriptor length is 9 bytes   |
| 1      | bDescriptorTyp      | 1 byte | 0x02   | Configuration descriptor type  |
| 2      | wTotalLength        | 2 byte | 0x0027 | Total length is 39 bytes   |
| 4      | bNumInterfaces      | 1 byte | 0x01   | Number of interfaces is 1  |
| 5      | bConfigurationValue | 1 byte | 0x01   | Value as argument for SetConfiguration() is 1  |
| 6      | iConfiguration      | 1 byte | 0x00   | No string descriptor available   |
| 7      | bmAttributes        | 1 byte | 0xC0   | Configuration characteristics: D7: occupied(1) D6: Bus-powered D5: No Wakeup D4: occupied(0) |
| 8      | bMaxPower           | 1 byte | 0x00   | Max. current is 0 mA   |

## Interface descriptor

| Offset | Field              | Length | Value | Description                             |
|--------|--------------------|--------|-------|---|
| 0      | bLength            | 1 byte | 0x09  | Descriptor length                       |
| 1      | bDescriptorTyp     | 1 byte | 0x04  | Interface descriptor type               |
| 2      | bInterfaceNumber   | 1 byte | 0x00  | Interface number                        |
| 3      | bAlternateSetting  | 1 byte | 0x00  | No alternative setting                  |
| 4      | bNumEndpoints      | 1 byte | 0x03  | Number of used endpoints                |
| 5      | bInterfaceClass    | 1 byte | 0xff  | Vendor specific class                   |
| 6      | bInterfaceSubClass | 1 byte | 0x00  | Reserved                                |
| 7      | bInterfaceProtocol | 1 byte | 0x00  | Reserved                                |
| 8      | iInterface         | 1 byte | 0x00  | No string descriptor for this interface |

## **Endpoint descriptor (endpoint 2 job channel Device > PC)**

| Offset | Field            | Length | Value  | Description                                   |
|--------|------------------|--------|--------|---|
| 0      | bLength          | 1 byte | 0x07   | Descriptor length                             |
| 1      | bDescriptorTyp   | 1 byte | 0x05   | Endpoint descriptor type                      |
| 2      | bEndpointAddress | 1 byte | 0x82   | IN endpoint with number 2                     |
| 3      | bmAttributes     | 1 byte | 0x02   | Bulk endpoint                                 |
| 4      | wMaxPacketSize   | 2 byte | 0x0040 | Max. packet size is 64 bytes                  |
| 6      | bInterval        | 1 byte | 0x00   | Polling interval all 0 frames/<br>MicroFrames |

## **Endpoint descriptor (endpoint 1 job channel PC > Device )**

| Offset | Field            | Length | Value  | Description                                   |
|--------|------------------|--------|--------|---|
| 0      | bLength          | 1 byte | 0x07   | Descriptor length                             |
| 1      | bDescriptorTyp   | 1 byte | 0x05   | Endpoint descriptor type                      |
| 2      | bEndpointAddress | 1 byte | 0x01   | OUT endpoint with number 1                    |
| 3      | bmAttributes     | 1 byte | 0x02   | Bulk endpoint                                 |
| 4      | wMaxPacketSize   | 2 byte | 0x0040 | Max. packet size is 64 bytes                  |
| 6      | bInterval        | 1 byte | 0x00   | Polling interval all 0 frames/<br>MicroFrames |

## **Endpoint descriptor (endpoint 3 Debug channel Device > PC)**

| Offset | Field            | Length | Value  | Description                                   |
|--------|------------------|--------|--------|---|
| 0      | bLength          | 1 byte | 0x07   | Descriptor length                             |
| 1      | bDescriptorTyp   | 1 byte | 0x05   | Endpoint descriptor type                      |
| 2      | bEndpointAddress | 1 byte | 0x83   | IN endpoint with number 3                     |
| 3      | bmAttributes     | 1 byte | 0x02   | Bulk endpoint                                 |
| 4      | wMaxPacketSize   | 2 byte | 0x0040 | Max. packet size is 64 bytes                  |
| 6      | bInterval        | 1 byte | 0x00   | Polling interval all 0 frames/<br>MicroFrames |

## String descriptor (country code)

| Offset | Field          | Length | Value  | Description            |
|--------|----------------|--------|--------|------------------------|
| 0      | bLength        | 1 byte | 0x04   | Descriptor length      |
| 1      | bDescriptorTyp | 1 byte | 0x03   | String descriptor type |
| 2      | wLangID        | 2 byte | 0x0409 | Country code           |

## String descriptor (manufacturer string)

| Offset | Field          | Length | Value | Description            |
|--------|----------------|--------|-------|------------------------|
| 0      | bLength        | 1 byte | 0x04  | Descriptor length      |
| 1      | bDescriptorTyp | 1 byte | 0x03  | String descriptor type |
| 2      | bString        | 28     |       | Wincor Nixdorf         |

## String descriptor (product string)

| Offset | Field          | Length | Value | Description                      |
|--------|----------------|--------|-------|----------------------------------|
| 0      | bLength        | 1 byte | 0x04  | Descriptor length                |
| 1      | bDescriptorTyp | 1 byte | 0x03  | String descriptor type           |
| 2      | bString        | 12     |       | WN Cash Media Dispenser (CMD-V4) |

## Configuration

The CMD-V4 is configured via jumpers, sensors, connections and configuration commands. The speed of the V.24 line is adjusted automatically.

## **Jumper**

Application-specific configuration options on the controller board:

Observe door contact during encryption.

**Appendix E** (page 106) shows the assignment of the jumper field on the controller board.

The remaining positions on the jumper field are intended for extensions or as an aid to controller replacement. They are therefore not described here in detail.

#### Sensor

The **safe door** and **safety switch** external sensors affect FW behavior (when they have been activated via a jumper on the controller).

In addition, the evaluation of HW module IDs determines the current device version (e.g. frontload/rearload).

The safe switch detects whether the dispenser is completely inserted into the safe or not. If it is not, the DCW command for out-safe machines (clamp moves upwards out of the safe) is not permitted in the relevant status (acknowledgment status D).

## Firmware configuration job

A default defines how the CMD-V4 is to behave.

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The settings made are administered in a power failure-proof memory area which is generally not overwritten during a control software update.

#### Recover status

Default: Deactivated

Possible variants: Switching on / switching off

## Dual dispense evaluation by the measurement station

Default: Do not reject 2 GOOD notes

Possible variants: DEFAULT / always reject dual dispenses

#### Automatic baud rate switch: 19200 / 56000 baud

In CMD-V4, the baud rate is detected and switched automatically. Two line speeds (19200/56000 baud) are supported by the booter and the firmware. During each DIN protocol inquiry phase, synchronization takes place for both baud rates with the ENQ character.

The remaining V.24 line parameters (ODD/8/2) cannot be changed.

## **Encryption**

## **Encryption procedure, general**

The following section provides an insight into the procedures and techniques that are used for the encryption.

#### **DES**

The Data Encryption Standard (DES) serves as the basic principle for encryption processes. This standard is referred to as Data Encryption Algorithms (DEA) by ANSI and DEA-1 by ISO.

As a block cipher, DES transforms data with a block length of 8 bytes into enciphered data blocks of 8 bytes.

For a detailed explanation of the DES encryption, please refer to [L 11].

Based on a symmetric-key algorithm, DES uses the same key for encryption and decryption. Even though a 56-bit key is used, a key is displayed by 64 bits. The remaining 8 bits are used as parity check bits.

To indicate DES encryption and decryption, **e** for encryption and **d** for decryption are used.

## DES operating modes:

Below two ways to use the DES for encryption of longer data blocks are presented: the operation modes ECB and CBC.

These two operation modes are also used in other block ciphers, but are at this point specifically presented relating to DES.

## **ECB**

The electronic codebook (ECB) mode is the simplest of the encryption modes.

The plaintext is divided into blocks of the same length, 8 bytes in case of DES, and each block is encrypted separately under the same key K.

The disadvantage of ECB mode is that identical plaintext blocks are always encrypted into identical ciphertext blocks.

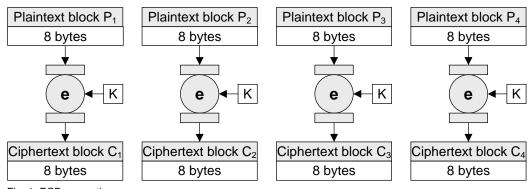


Fig. 1: ECB encryption

Keep in mind that the plaintext that needs to be encrypted is always filled up to a multiple of the block size.

### **CBC**

The Cipher-block chaining (CBC) mode interconnects the encryption of the blocks by incorporation of the result of the previous encryption into the result of the subsequent one.

Therefore each block of plaintext is XORed with the previous ciphertext block before being encrypted.

The first block is XORed to a start value, the initialization vector (IV) that does not necessarily need to be secret.

Compared to EBC mode, CBC mode effects a protection of the ciphertext over its complete length.

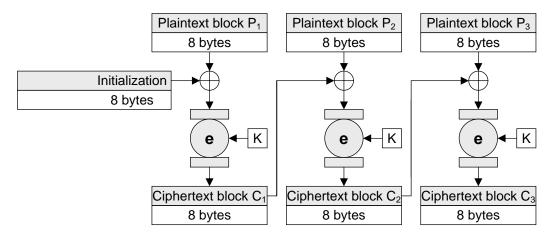


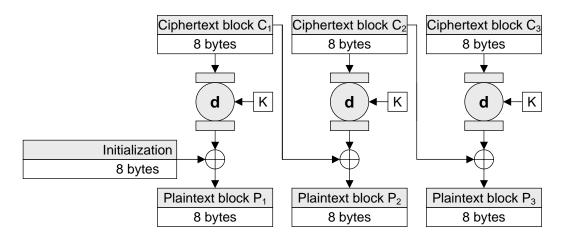
Fig. 2: CBC encryption

According to the EBC mode, you need to keep in mind that the plaintext that needs to be encrypted is always filled up to a multiple of the block size.

For decryption in CBC the result of a ciphertext decryption is XORed with the previous ciphertext block.

The decryption result of the first block is connected to a start value, the initialization vector (IV) that does not necessarily need to be secret.

For a correct CBC decryption the same IV must be used for both processes, enand decryption.



III. 3: CBC decryption

## **Triple-DES**

Due to the weaknesses of the 8-byte keys of DES, for outstandingly security relevant objects the Triple DES cipher is used. This uses 16-byte keys, also named double-sized keys. Data blocks encrypted with Triple DES have a length of 8 bytes and thus the same length as the ones that are encrypted in DES mode.

i 16-byte keys always indicate a Triple DES encryption.

If you split a 16-byte key in half, you can regard the two resulting 8-byte halves as two independent keys. The designation of a complete 16-byte key is  $\mathbf{K}\mathbf{K}$  and thus it is split into the left half  $\mathbf{K}_{L}$  and the right half  $\mathbf{K}_{R}$ .

Application of the Triple DES algorithm means that the DES cipher algorithm is applied three times under the subkeys  $K_L$  and  $K_R$ .

The Plaintext block P is successively DES encrypted under  $K_L$ , DES decrypted under  $K_R$  and again DES encrypted under  $K_L$ .

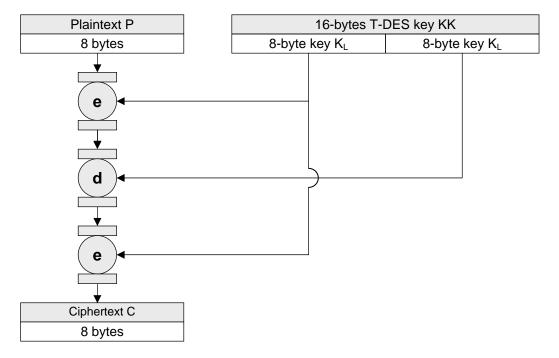


Fig.:4 Triple DES encryption

In case of two identical subkeys, a Triple DES encryption equates to a simple DES encryption.

Accordingly, in Triple DES mode decryption is carried out by decryption under the first subkey, encryption under the right subkey, and another decryption under the left subkey.

As due to the triply applied DES algorithm Triple DES remains a block cipher, the operation modes ECB and CBC are usable as well.

# **Encryption CMD-V4**

The interface to the CMD-V4 can operate with encryption.

Regarding commands and acknowledges, encryption is limited to the user data.

For identification, user data is double framed.

In general, commands for software transfer are not encrypted.

Two different modes are used:

#### Key exchange

For key exchanges, the ECB (Electronic codebook) mode is used.

### Data exchange

The encryption algorithm used for data exchange is the CBC (Cipher-block chaining) mode which contains the Triple DES Algorithm.

When encryption is active, user data length is a multiple of 8.

This also applies to commands without user data.

Consequently, it might be necessary to fill up the user data with filler bytes (00 H).

At least 2 filler bytes are needed because prior to encryption a CRC code is calculated over the user data (calculation according to BCS [L1]) and filed in the penultimate and ultimate buffer position.

This checks the synchronization of the used keys.

Initialization is shown in the following illustration.

| HOST   | (          | CMD-V4   |
|--|------------|--|
| <sedm>- Request status</sedm>                | =          |  |
|  | <b>←</b> = | Transport key TK missing   |
| Generate and pass TK                         | =          | Save TK when safe door is open<br>and shall be considered for<br>encryption. |
| Request EDM status                           | = <b>→</b> |  |
|  | <b>←</b> = | Line key LK missing  |
| Generate LK, encrypt it under TK and pass it | =          | Decrypt LK under TK and secure it  |
| Request EDM status                           | =          |  |
|  | <b>←</b> = | Key available  |
| Request initial value                        | = <b>→</b> | Generate IV, encrypt it under TK   |
| Decrypt IV under TK and secure it            | <b>←</b> = | and pass it  |
| encrypted data                               | = <b>→</b> |  |
|  | <b>←</b> = | encrypted data   |
| Key test                                     | =          |  |
|  | <b>←</b> = | Check pattern, positive acknowledgement if valid, key error otherwise.       |

Key synchronization HOST ←> CMD\_V4

On transport of the non-encoded transport key, the jumper "Observe door contact during encryption" on the controller is evaluated. If the jumper is activated, the transport key is only accepted when the safe door is open.

Prior to the activation of line encryption, the initiator must ensure himself that no attempts at manipulation of the data conductor have taken place.

Once encryption is activated, it can only - in case of an activated jumper - be deactivated via command when the safe door is open. When the safe door is open, encryption can also be deactivated by DES\_CLEAR\_BUTTON\_6=Y + pressing button 6.

## **Commands**

The operating phases of an ATM can be subdivided into customer transaction, supply and disposal, and servicing.

Commands are available in the CMD-V4 for each phase:

### **Customer transaction**

Reset Dispensing Transport Cancel Status

## Supply and disposal

Update system data
Determine reference values
Encryption
Software transfer

#### Service

Self-test Internal commands

## General

## Plausibility check

Before **each command** is executed, it is first checked for plausibility.

All unknown commands, commands with parameter values outside their valid range and parameter values with illegal data types are rejected with a "SYNTAX" status code. Commands or parameters which are not legal at present or which cannot be executed in the current hardware configuration are rejected with a "CONTEXT" status code.

The possible status codes and their causes are described in the command acknowledgments.

#### **Device lock**

The CMD-V4 takes two device locks into consideration during processing:

- Safety switch
- Lock due to cash being retained in the stacking position.

As soon as a lock is set, the CMD-V4 rejects any commands involving device operations.

### Removing locks:

Safety switch (S\_SW flag)

• Action: Push CMD-V4 completely into the safe.

Banknote retract (DLOC flag)

• Action: Remove cash, then remove lock via command.

If required, the lock flag can be canceled without removing the bundle first.

The command is then acknowledged with a device error, since the transport paths are blocked.

The bundle can then be re-offered or placed in the RR box.

## DA - Reset

### Command

| Length | Contents | Meaning                      |         |
|--------|----------|------------------------------|---------|
| 1      | D        | Device ID                    | (ASCII) |
| 1      | Α        | Command specification: RESET | (ASCII) |
| 1      | blank    | no additional specification  | (ASCII) |
|        | 00 H     | any filler bytes             | (HEXA)  |

## **Acknowledgement**

| Length | Contents | Meaning                                      |         |
|--------|----------|--|---------|
| 1      | D        | Device ID                                    | (ASCII) |
| 1      | Α        | Command specification: RESET                 | (ASCII) |
| 1      | blank    | no additional specification                  | (ASCII) |
| 1      | а        | Status code (-> Device status <sres>)</sres> | (ASCII) |
|        | 00 H     | any filler bytes                             | (HEXA)  |

## **Description**

A 'RESET' checks the ready status of the CMD-V4; this is only given after an error-free execution of the command!

Principally, a RESET involves the same routines as during Power on, apart from the power up tests. Only the routines during 'Power Up Test' are left out.

After a device reset the CMD-V4 is in a defined state.

Execution is canceled when the first error is detected.

## Memory reset

The internal markers are reset.

In addition to the general memory area, there are other areas (e.g. all status areas and the control program) that retain their contents even in the event of a power failure, thanks to backup battery capacity.

## Determination of the device type

The following cells are set in the device status of the CMD-V4 using the codes on the controller board:

| <type></type>           | Device type                            | (Front-/ Rearload/<br>Undefined)           |
|-------------------------|--|--|
| <n_vm></n_vm>           | No. of dispenser modules               | (16)                                       |
| <door></door>           | Status of door sensor                  |  |
| <s_sw></s_sw>           | Status of safety switch                |  |
| <shut></shut>           | Shutter status                         |  |
| <do_\$></do_\$>         | Observe door contact during encryption |  |
| <transport></transport> | Output transport variant               | in Safe front/rear,<br>out Safe front/rear |

## Checking the cassettes

First type and quantity of the available cassettes are determined. The corresponding cells in the cassette status are updated.

The values from the cassette memory are compared with the internal data. If there is a difference, the corresponding cassette status  $\langle nSTA \rangle = N$  is set.

To operate correctly, the device requires a minimum of 1 ready cash-out cassette and the reject/retract cassette.

If this minimum requirement is not met, it is indicated in the device status **<CAS> = N** and the command terminates with 'Out of service'.

## Checking device locks and initialization

First of all, the status of the safety switch is determined (open/closed) and recorded in the device status <S\_SW>.

The device is subsequently initialized.

During initialization an attempt is made to standardize the routing disk and to move the clamp to the stacking position and to open it.

Depending on the current status of the cash dispenser, it can result in banknotes being retracted and the shutter closing.

Then the device status is checked to determine whether the system is locked <DLOC> = Y.

Processing is terminated with the status 'Out of service' if the device lock is on, if the safety switch is 'open' or if initialization has failed.

Initialization is also carried out if the system is locked <DLOC> = Y, but cash, if available, is not retracted into the RR-box..

#### Checking the transport paths

All transport routes are checked. Banknotes being transported are stored in the RR-box. It is differentiated between:

- Customer money is stored in the retract compartment of the RR-box.
   The action is documented in the cassette status <RRET> + 1.
- Bank cash is removed via bundle reject.

The result of all actions is documented in the device status <SCLE> and <SRES>.

### Checking the printing cassette

'POWER\_ON-/RESET' checks the cassette empty sensor of the 'DK' (printing cassette) for emptiness. If a document is present, a print proof is created. Additionally a control is performed to ensure that the empty sensor does not detect the document again after the time-out period. If the empty sensor detects another document (printer prints next document), up to 5 dispensing procedures with subsequent time-out periods are executed when the empty sensor is covered again. If another document is detected at the cassette empty sensor, processing is aborted with the status 'Out of service'.

#### Handling jams

A paper jam is documented in the device status <TER> = J. The area in which the problem has to be solved is stated in <TS> (start and destination).

If the jam occurred during a dispensing command, it is checked whether the jam has been cleared in the corresponding transport.

To do this, at least one test note is taken from the lowest cash-out cassette and transported to the stacking compartment. If this note reaches its destination, it is disposed of as a REJECT in the RR box.

Following a JAM that occurs during dispensing, the transport path is checked with a test banknote during reset.

After 10 unsuccessful RESETs, mechanical movements cease. Instead, the command is acknowledged with 'D'.

This mode is only exited after power off/on, key reset, or a reset via the safety switch. This is to ensure that an engineer/operator has remedied irreparable damage caused by the firmware.

#### Checking the shutter (optional)

If available, the functionality of the shutter is checked in a 'shutter test'.

The result is documented in the device status **<SHUT>**.

The command is terminated with 'Out of service' if the test cycle is not completed successfully.

## Checking the photosensors

All photosensors are checked. The respective result is administrated internally.

## Checking the cash trapping detection

During initialization of the CMD main firmware (after Power on, RESET, or CLEARING), the function and initialization values are checked when a cash trapping detection is available and working <SHUT\_PROTECT\_OPT>=Y. In case of a negative result, CLEARING, RESET, or the first status request after the Power On are acknowledged with status D ("Out of service") and in device status <SHUT\_PROTECT>=D is set.

### **Status Codes**

#### A = OK

| No actions performed                    | $\langle SCLE \rangle = 0 \& \langle n\_STA \rangle = R$ |
|---|--|
| Documents successfully placed in RR-box | <scle> = 1 &amp; <n sta=""> = R</n></scle>               |

## B = Software missing

Control program not available

#### D = Out of service

| Cassettes cannot be processed                        | <cas> = N</cas>          |
|--|--------------------------|
| Safety switch open                                   | <\$_\$W> = 0             |
| Device lock set                                      | <DLOC $>$ = Y            |
| Transport error                                      | <ter> = J</ter>          |
| Operator request                                     | <or> = Y</or>            |
| Self-test active                                     | <tst> = Y</tst>          |
| Shutter error  | <sherr> = B</sherr>      |
| Printing cassette only                               |                          |
| 5 documents in RR-box, additional document available | <n_sta> = V</n_sta>      |
| Transport error                                      | <ter> = J</ter>          |
| only when cash trapping detection is activated       |                          |
| Cash trapping detection faulty                       | $<$ SHUT_PROTECT $>$ = D |
| and additionally                                     | <SHERR $>$ = B,          |
|  | <shut> = U,</shut>       |
|  | <scod> = 28</scod>       |

## E = Device error

Documents from printing cassette cannot be  $< n_STA > = V$  separated

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

# **DAB – Clearing**

## Command

| Length | Content | Meaning                            |         |
|--------|---------|------------------------------------|---------|
|        | S       |                                    |         |
| 1      | D       | Device ID                          | (ASCII) |
| 1      | Α       | Command specification: RESET       | (ASCII) |
| 1      | В       | Additional specification: Clearing | (ASCII) |
|        | 00 H    | Any filler bytes                   | (HEXA)  |

# Acknowledgement

| Length | Content<br>s | Meaning                            |         |
|--------|--------------|------------------------------------|---------|
| 1      | D            | Device ID                          | (ASCII) |
| 1      | Α            | Command specification: RESET       | (ASCII) |
| 1      | В            | Additional specification: Clearing | (ASCII) |
| 1      | а            | Status code                        | (ASCII) |
|        | 00 H         | Any filler bytes                   | (HEXA)  |

## **Description**

### Checking device locks and initialization

First of all, the status of the safety switch is determined (open/closed) and recorded in the device status <S SW>.

The device is subsequently initialized.

During initialization an attempt is made to standardize the routing disk and to move the clamp to the stacking position and to open it.

Depending on the current status of the cash dispenser, it can result in banknotes being retracted and the shutter closing.

Then the device status is checked to determine whether the system is locked <DLOC> = Y.

Processing is terminated with the status 'Out of service' if the device lock is on, if the safety switch is 'open', or if initialization has failed.

Initialization is also carried out if the system is locked <DLOC> = Y, but cash, if available, is not retracted into the RR-box..

## Checking the transport paths

All transport routes are checked. Banknotes being transported are stored in the RR-box. It is differentiated between:

- Customer money is stored in the retract compartment of the RR-box.
   The action is documented in the cassette status <RRET> + 1.
- Bank cash is removed via bundle reject.

The result of all actions is documented in the device status <SCLE> and <SRES>.

### **Checking the printing cassette**

A document ready for dispensing ('cassette empty sensor' being covered) is temporarily stored in the stacking department. Should the situation arise, upcoming documents (4 at the most) are transported into the stacking department as well.

The documents that collect there are removed via bundle reject.

If another document is detected at the cassette empty sensor, processing is aborted with the status 'Device not ready'.

### Handling jams

A paper jam is documented in the device status <TER> = J. The area in which the problem has to be solved is stated in <TS> (start and destination).

If the jam occurred during a dispensing command, it is checked whether the jam has been cleared in the corresponding transport.

To do this, at least one test note is taken from the lowest cash-out cassette and transported to the stacking compartment. If this note reaches its destination, it is disposed of as a REJECT in the RR box.

## Checking the shutter (optional)

If available, the functionality of the shutter is checked in a 'shutter test'.

The result is documented in the device status **<SHUT>**.

The command is terminated with 'Out of service' if the test cycle has not been completed successfully.

After 10 unsuccessful RESETs, mechanical movements cease. Instead, the command is acknowledged with 'D'.

This mode is only exited after power off/on, key reset, or a reset via the safety switch. This is to ensure that an engineer/operator has remedied irreparable damage caused by the firmware.

### Checking the photosensors

All photosensors are checked. The respective result is administrated internally.

## Checking the cash trapping detection

During initialization of the CMD main firmware (after Power on, RESET, or CLEARING), the function and initialization values are checked when a cash trapping detection is available and working <SHUT\_PROTECT\_OPT>=Y. In case of a negative result, CLEARING, RESET, or the first status request after the Power On are acknowledged with status D ("Out of service") and in device status <SHUT\_PROTECT>=D is set.

## **Status Codes**

#### A = OK

| No actions performed                    | $\langle SCLE \rangle = 0 \& \langle n\_STA \rangle = R$ |
|---|--|
| Documents successfully placed in RR-box | <scle> = 1 &amp; <n_sta> = R</n_sta></scle>              |

## B = Software missing

Control program not available

### D = Out of service

| Safety switch open                                   | <s_sw> = 0</s_sw>                 |
|--|-----------------------------------|
| Device lock set                                      | <DLOC $>$ = Y                     |
| Transport error                                      | <ter> = J</ter>                   |
| Operator request                                     | <or> = Y</or>                     |
| Self-test active                                     | <tst> = Y</tst>                   |
| Shutter error  | <sherr> = B</sherr>               |
| Printing cassette only                               |                                   |
| 5 documents in RR-box, additional document available | <n_sta> = V</n_sta>               |
| Transport error                                      | <ter> = J</ter>                   |
| only when cash trapping detection is activated       |                                   |
| Cash trapping detection faulty                       | <shut_protect> = D</shut_protect> |
| then additionally                                    | <sherr> = B,</sherr>              |

#### E = Device error

| Documents from printing cassette cannot be | $<$ n_STA $>$ = V |
|--|-------------------|
| separated                                  |                   |

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

<SHUT> = U, <SCOD> = 28

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

# **Dispensing**

## Command

| Length | Conten<br>ts | Meaning  |                    |
|--------|--------------|--|--------------------|
| 1      | D            | Device ID  | (ASCII)            |
| 1      | В            | Command specification: 'Dispensing'                | (ASCII)            |
| 1      | а            | Additional specification:                          | (ASCII)            |
|        |              | S = Standard C = Dispensing with notes in stacker  |                    |
|        |              | per cassette from which notes are to be dispensed: | (ASCII)            |
| 1      | d            | Cassette location (1-6)                            | (decimal in ASCII) |
| 1      | ,            | Separator  | (ASCII)            |
| 2      | dd           | Number of notes (01 - 60)                          | (decimal in ASCII) |
| 1      | : or ;       | Separator (after last cassette ";" = END)          | (ASCII)            |
|        | 00 H         | any filler bytes                                   | (HEXA)             |

The following agreement applies for numbering the cassette locations:

The top location for cash-cassettes is location number 1. The locations below that are numbered accordingly in ascending order.

# Acknowledgement

| Lengt    | Conten   | Meaning  |                    |
|----------|----------|--|--------------------|
| h        | ts       |  |                    |
| 1        | D        | Device ID  | (ASCII)            |
| 1        | В        | Command specification: 'Dispensing'  | (ASCII)            |
| 1        | а        | Additional specification:  | (ASCII)            |
|          |          | S = Standard C = Dispensing with notes in stacker  |                    |
| 1        | а        | Status code  | (ASCII)            |
| 1        | d        | per cassette processed: (in ascending order of cassette locations) Cassette location   | (decimal in ASCII) |
| <u> </u> | ď        | Separator  | (ASCII)            |
| 2        | ,<br>dd  | Number of notes in collecting tray   | (decimal in ASCII) |
| 1        |          | Separator  | (ASCII)            |
| 3        | ,<br>ddd | Number of notes in reject cassette   | (decimal in ASCII) |
| 1        | ,        | Separator  | (ASCII)            |
| 1        | a · or · | Filling level, status of cassette  O = Minimum quantity not yet reached L = Fallen below minimum quantity E = Cassette physically empty M = Too many notes with incorrect S dimensions N = Too many muiltiple dispenses = Note dispensing not possible | (ASCII)            |
| 7        | : or ;   | Separator<br>(after last cassette ";" = END)   | ,                  |
|          | 00 H     | any filler bytes   | (HEXA)             |

## **Description**

The description is organized into subcommands.

#### Checks

The command is rejected if

- its syntax is incorrect.
- a device lock is set.
- the shutter is not closed.
- the device is out of service.
- a cash trapping detection error is set.

#### Basic status check

A check is run to determine if:

- banknotes are in the collecting tray (only for additional specification: 'Standard').
- the transport paths are free.
- all requested cassette locations have the status nSTA = R (ready).
- or the printing cassette has the status nSTA = V (ready).

### Note dispensing and collecting



Dispensing is not prevented if:

- a logical dispenser cassette is now empty.
- the reject/ retract cassette is full.

The operator must ensure that the CMD-V4 has the correct data before customer mode is activated!.

## Additional specification: S (standard dispensing)

Prior to standard dispensing, the dispensing-specific counter readings of all the cassettes  $(\normalfont{<} nL_D > = 0; \normalfont{<} nREJ > = 0)$  are standardized.

## Additional specification: C (dispensing with notes in stacker)

This version can be advantageous if the specified denominations have not been achieved via the standard command and the required rest is to be dispensed via an altered HOST specification.

The required number of notes is dispensed from each cassette. The order specified in the command is complied with.



Up to max. 60 notes can be processed per transaction in the CMD-V4 and VCMD.

This value requires a note quality corresponding to the paper specification and does not apply for all types of notes and application areas.

This restriction must be monitored by the application. Up to max. 5 documents can be dispensed per transaction for the printing cassette.

With each successfully dispensed note the cassette-specific supply counter is decremented <nACT> - 1. If the counter is not decremented below the minimum number (0).

The dispensed notes are transported to the measurement station.

All 'good notes' are stored in the stacking department. The VCMD features a rejection of objectionable notes via single reject. Concerning CMD-V4, up to two objectionable notes can be singled out in case the device features a single reject function on the hardware side. Further objectionable notes are collected in the stacking compartment which, in case of the additional specification S, leads to a note bundle reject, an emptying of the reject tray (if available) and subsequently to a restarted dispense transaction. For those notes that have been rejected via single reject, replacement notes are provided via post dispensing.

Dispensing ends when:

- the required number of notes has been achieved.
- a cassette empties during a dispense process.
- a fault which cannot be eliminated occurs during current the dispensing process.

## Editing the acknowledgment

For each processed cassette position, the command acknowledgement reports the number of notes that have been transported from the respective cassette into the stacking compartment <nL\_D> or respectively into the reject cassette <nREJ> to the HOST. Additionally, the filling level is reported. It is evaluated from the reports of the minimum quantity sensor <nLOW> and the empty sensor <nSTA>.

If a note jam occurs during dispensing, it is probable that acknowledgment parameters are also transferred for cassette locations which have not been requested (trial dispense transaction).

During dispensing with notes in a stacker, the acknowledgment contains the total number of notes which have been retracted since the last standard dispensing.

The transferred number of notes in the acknowledgment corresponds to the values <nL D> and <nREJ> in the cassette status.

The acknowledgment parameters are not transferred if status codes B, C, and I are returned.

With D the acknowledgment parameters are only transferred if dispensing was started and an error occurred.

### **Status Codes**

## B = Software missing

Control program not available

## C = Syntax

invalid cassette location no. (unequal 1- 6) too many dispensing commands (more than 10) Number of notes > maximum value (60) Number of notes > maximum value (5) for printing cassette

#### I = Context

| Cassette error  | <nsta></nsta>   | unequal R  |
|---|-----------------|------------|
| Control command 'Dispensing with notes in stacker' (only for DBS) | <ts></ts>       | unequal 12 |
| Number of notes in stacker with notes in stacker > 60             |                 |            |
| Shutter blocked   | <sherr></sherr> | = B        |
| Shutter is not closed   | <shut></shut>   | = O/U      |
| Manipulation at output transport                                  | <ter></ter>     | = M        |
| Cash path not free or   | <tf></tf>       | = N        |
| Clearing after cash presentation not OK                           |                 |            |
| Error during dispensing with notes in stacker                     | <dis></dis>     | = J        |
|   |                 |            |
| D = Out of service  |                 |            |
| Safety switch open  | <s_sw></s_sw>   | = O        |
| Device lock set   | <dloc></dloc>   | = Y        |
| Minimum configuration missing                                     | <cas></cas>     | = N        |
| Single reject switch defective (facing the reject direction)      | <sr></sr>       | = R        |
| Banknote jam  | <ter></ter>     | = J        |
| Operator request  | <or></or>       | = Y        |
| Self-test active  | <tst></tst>     | = Y        |

| Cassette is empty                    | <n_sta></n_sta>                   | = E |
|--------------------------------------|-----------------------------------|-----|
| Too many wrong-sized notes*          | <dis></dis>                       | = M |
| Too many multiple dispenses *        | <dis></dis>                       | = S |
| Note cannot be dispensed *           | <dis></dis>                       | = N |
| Too many bundle rejects              | <dis></dis>                       | = E |
| Banknote jam during post dispensing  | <dis></dis>                       | = J |
| Cash trapping detection manipulated  | <shut_p<br>ROTECT&gt;</shut_p<br> | = M |
| Cash trapping device detected        | <shut_p<br>ROTECT&gt;</shut_p<br> | = K |
| Cash trapping detection faulty       | <shut_p<br>ROTECT&gt;</shut_p<br> | = D |
| Printing cassette only               |                                   |     |
| Document cannot be dispensed         | <n_sta></n_sta>                   | = V |
| Timeout: documents are not available | <n_sta></n_sta>                   | = R |

<sup>\*</sup> Within the acknowledgment parameter 'Filling level, status' for every command, this status value is also transferred cassette-specifically.

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

## **Special handling**

#### Undefined or invalid notes

If undefined or invalid notes arrive at the collecting tray, a bundle reject occurs with the additional specification S. Thereafter, the original command is repeated.

After 3 consecutive bundle rejects, the command is aborted with the status 'Device error' **<DIS> = E** (too many bundle rejects).

With the additional specification C (dispensing with notes in the stacker) such notes in the stacking compartment result in dispensing being terminated with the acknowledgment E = `Device error', < DIS = J>.

### Multiple dispense

In the CMD-V4 and VCMD all the dispensed notes are measured by a double note detector. Besides detecting the note length and thickness, this gauge can also recognize whether it is just one note or two or more overlapping notes or notes without a gap between them. When it is more than just one note, it is known as a multiple dispense. The multiple-note detection unit can detect multiple dispenses with correct single notes. To ensure that the reject rate at the CMD-V4 and VCMD remains low, it is possible to configure what should happen to valid multiple dispenses. Two methods can be set via SDO\_BAD (see Appendix X – K- Firmware configuration):

- **SDO\_BAD = Y**: all the multiple dispenses are singled out via the single reject and a replacement note is dispensed.
- SDO\_BAD = N: all the multiple dispenses which consist of two valid single notes are not singled out until the required number of notes has been achieved or exceeded.

The cassette-specific counter is corrected when a multiple dispense is detected <nACT> - 1.

Dispensing aborts with the status 'Device error' **<DIS> = S** (too many multiple dispenses) if more than five multiple dispenses have to be rejected.

### Dispensing of notes not possible

If the CMD-V4 does not succeed in dispensing a note, the dispense transaction is initiated again.

The dispensing attempt is repeated five times at the most. After that, the command is terminated under the status 'device error'  $\langle DIS \rangle = N$  (cassette is empty or note bundle is sticky).

The acknowledgment also includes the dispenser-specific counter per cassette (no. of notes in collecting tray / no. of notes in the reject cassette).

With this information it can decided in the HOST whether the desired amount can be dispensed via a new dispense process or whether the customer transaction must be cancelled.

### Banknote jam

A banknote jam may occur during the dispense process.

If a note jam occurs, power is applied to the transport motor for approx. another 2 s. This ensures that transportable notes reach the stacking compartment.

A trial dispensing process is then performed by dispensing one note from the bottom cassette and transporting it to the collecting tray.

- The note arrives the stacking compartment:

When the note arrives in the stacking compartment, the transport route is cleared. With the additional specification S (standard dispensing), a bundle reject is conducted and the original command repeated. With the additional specification C (dispensing with notes in the stacker) such notes in the collecting tray result in dispensing being terminated with the acknowledgment E = `Device error', <DIS = J>

The note does not arrive in the stacking compartment:

The procedure is repeated twice at the most. Afterwards, a non removable banknote jam is clearly ascertained. There is no further device operation.  $\langle TER \rangle = J$  indicates the lack of service in device status. The command is terminated with 'Out of service', a check is necessary.

The troubleshooting must be completed with 'RESET'. The flag is reset (**<TER>=0**) when this is done successfully.

## Special handling 'Printing cassette'

When several documents shall be dispensed from the printing cassette during one transaction, the AZM awaits a covering of the LKLx with a time-out period of 6 to 7 seconds with the motor running. When the LKLx is covered by the next document printed, this is rejected with a delay of 200 ms.

## Single reject deflector defective

An AZM\_NG recognizes a single reject deflector error if notes do not reach the destination chosen but arrive at a point in the opposite direction.

This circumstance is reported in the device status  $\langle SR \rangle = S/R$ . Further treatment depends upon the switch position.

Transport direction: collecting tray <SR> = S

In this case, the AZM\_NG can continue to operate with limited capacity.

As soon as a single reject becomes necessary, the notes dispensed up to that point are lost. A note bundle reject then takes place (including counter increment).

When dispensing with notes in a stacker, the command is acknowledged with E = Device error, <DIS = J>.

Standard dispensing is repeated. If the specified number of notes can be presented, the command is positively acknowledged.

Transport direction: reject cassette <SR> = R

In this case, further dispensing is impossible. All notes that have been dispensed up until this point are placed in a bundle (incl. counter increment).

The command is terminated with 'Out of service', a check is necessary. Correction must be completed with 'RESET'. The inhibit flag is reset (**<SR> = O**) when this is done successfully.

#### Note dimensions outside the tolerance values.

If the measurement station detects notes whose height does not lie within the prescribed tolerances, the note is probably a counterfeit.

In this case, the cassette-specific counter is corrected <nACT> - 1, the note is singled out via the single reject and a replacement note is dispensed.

Dispensing aborts with the status 'Device error'  $\langle DIS \rangle = M$  (too many notes with wrong dimensions) if several counterfeit notes are detected during dispensing from a cassette.

## Cash trapping detection check

With cash trapping device available and activated <SHUT\_PROTECT\_OPT>=Y and the shutter closed, the cash trapping detection sensors are checked prior to dispensing. The sensors might have been manipulated during the last transaction. If the result is negative, the command is terminated under status E ('Device error') and <SHUT\_PROTECT>=M.

If an error <SHUT\_PROTECT>=K ("Cash trapping detected") occurs, a check for cash trapping detection is performed, both with the shutter open and closed. If the result is negative, the command is terminated under status E ('Device error') and <SHUT\_PROTECT>=K.

For a reset of the error see section "Reset of a cash trapping detection error" (page 10).

The commands (DC..., e.g. Retract, Open shutter, Close shutter, ...), RESET, CLEARING or Power on are, upon error-free function and a pending cash trapping detection error, acknowledged with A and <SHUT\_PROTECT> remains unchanged.

## **Determine reference value**

## Command

| Length | Contents | Meaning  |                    |
|--------|----------|--|--------------------|
| 1      | D        | Device ID  | (ASCII)            |
| 1      | G        | Command specification: 'Determine reference value' | (ASCII)            |
| 1      | blank    | No additional specification                        | (ASCII)            |
| 1      | d        | Cassette location (1-6)                            | (decimal in ASCII) |
|        | 00 H     | any filler bytes                                   | (HEXA)             |

# Acknowledgement

| Length | Contents | Meaning   |                    |
|--------|----------|---|--------------------|
| 1      | D        | Device ID   | (ASCII)            |
| 1      | G        | Command specification: 'Determine reference value'                      | (ASCII)            |
| 1      | blank    | No additional specification   | (ASCII)            |
| 1      | а        | Status code   | (ASCII)            |
| 1      | d        | Cassette location   | (decimal in ASCII) |
| 1      | ,        | Separator   | (ASCII)            |
| 2      | dd       | Number of notes in stacking compartment                                 | (decimal in ASCII) |
| 1      | ,        | Separator   | (ASCII)            |
| 3      | ddd      | Number of notes in reject cassette                                      | (decimal in ASCII) |
| 1      | ,        | Separator   | (ASCII)            |
| 1      | а        | Filling level, status of cassette  O = Minimum quantity not yet reached | (ASCII)            |
| 1      | : or ;   | Separator (after last cassette ";" = END)                               | (ASCII)            |
|        | 00 H     | any filler bytes  | (HEXA)             |

## **Description**

The determination of the reference value can be performed for a maximum of 60 different unknown banknotes.

From the specified cassette the currency characteristics, the value of the banknotes and the release date will be read out and transferred to the measurement point. For cassette locations that have not yet been initialized or are faulty <nCUR> = \*\*\*, no reference value determination is performed.

From the current cassette, as many banknotes are dispensed as necessary for the reference value determination.

The process of determining the reference value will be terminated at the latest if the reference value cannot be determined within the maximum possible number of notes.

The command acknowledgement reports the number of notes that have been dispensed.

After termination of the command, all dispensed notes are in the stacking compartment.



After the reference value determination you need to compare the reported number of notes to the number of notes in the stacking compartment to exclude the possibility of multiple dispenses influencing the reference value.

Therefore the notes can:

- -be transported to the output.
- -taken out of the stacking compartment when the safe is open and the AZM\_NG extracted.

Subsequently, the notes can be relocated in the stacking compartment and be transported into the reject cassette via 'RESET'.

## **Status Codes**

## **B** = Software missing

Control program not available

## C = Syntax

invalid cassette location no. (unequal 1- 6)

#### I = Context

| Cassette status                        | <nsta></nsta> | unequal R, P |
|--|---------------|--------------|
| Cassette faulty or not yet initialized | <ncur></ncur> | = "***"      |
| Cash path not free                     | <tf></tf>     | = N          |

### D = Out of service

| Self-test active                | <tst></tst>   | = Y       |
|---------------------------------|---------------|-----------|
| Safety switch open              | $<$ S_SW $>$  | = O       |
| Device lock set                 | <dloc></dloc> | = Y       |
| Reject switch                   | <sr></sr>     | = R       |
| Reject cassette not processable | <rsta></rsta> | unequal R |
| Banknote jam                    | <ter></ter>   | = J       |

#### E = Device error

| Note cannot be dispensed  | <dis></dis>                       | = N |
|---|-----------------------------------|-----|
| Reference value could not be determined as the max. number of notes has been achieved | <nsta></nsta>                     | = P |
| Cassette has become physically empty.   | <nsta></nsta>                     | = E |
| Cash trapping detection manipulated   | <shut_p<br>ROTECT&gt;</shut_p<br> | = M |
| Cash trapping device detected   | <shut_p<br>ROTECT&gt;</shut_p<br> | = K |
| Cash trapping detection faulty  | <shut_p<br>ROTECT&gt;</shut_p<br> | = D |

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

## **Shutter commands**

#### Command

| Length | Conten ts | Meaning  |         |
|--------|-----------|--|---------|
| 1      | D         | Device ID  | (ASCII) |
| 1      | С         | Command specification: 'TRANSPORT'                           | (ASCII) |
| 1      | а         | Additional specification: Shutter commands  T = Shutter test | (ASCII) |
|        | 00 H      | any filler bytes   | (HEXA)  |

## **Acknowledgement**

| Length | Conten | Meaning                                    |         |
|--------|--------|--|---------|
|        | ts     |  |         |
| 1      | D      | Device ID                                  | (ASCII) |
| 1      | С      | Command specification: 'TRANSPORT'         | (ASCII) |
| 1      | а      | Additional specification: Shutter commands | (ASCII) |
| 1      | а      | Status code                                | (ASCII) |
|        | 00 H   | any filler bytes                           | (HEXA)  |

## **Description**

#### Shutter test

The operability of this module is checked by a quick motion of the shutter mechanics. The shutter flap is not opened in this process. The result is documented in the device status **<SHUT>**.

During the shutter test, a test of the cash trapping detection is performed as well when the detection is available and <SHUT\_PROTECT\_OPT>=Y. In case of <SHUT\_PROTECT>= M the test is performed exclusively when the shutter is open. For <SHUT\_PROTECT>= K, it does not matter whether the shutter is open or closed.

If no manipulation or cash trapping device is detected, <SHUT\_PROTECT>=O is set in device status.

A positive acknowledgement guarantees that the shutter is connected, the mechanics not blocked, and the shutter flap closed.

Otherwise, the command is acknowledged with 'Device error'.

### Status codes

## B = Software missing

Control program not available

#### I = Context

| Shutter not available            | <shut></shut> | = M, D    |
|----------------------------------|---------------|-----------|
| Cash path not free               | <tf></tf>     | = N       |
| and shutter not blocked          | <shut></shut> | unequal B |
| Cash path not free               | <tf></tf>     | = N       |
| and no manipulation in transport | <ter></ter>   | unequal M |

#### D = Out of service

| Banknote jam       | <ter></ter>   | = J |
|--------------------|---------------|-----|
| Self-test active   | <tst></tst>   | = Y |
| Device lock set    | <dloc></dloc> | = Y |
| Safety switch open | <s_sw></s_sw> | = O |

### E = Device error

| Manipulation in transport: (close shutter) | <ter></ter>                       | = M |
|--|-----------------------------------|-----|
| Shutter does not reach target position     | <sherr></sherr>                   | = B |
| Cash trapping detection faulty             | <shut_p<br>ROTECT&gt;</shut_p<br> | = D |
| Cash trapping manipulation                 | <shut_p<br>ROTECT&gt;</shut_p<br> | = M |
| Cash trapping device detected              | <shut_p<br>ROTECT&gt;</shut_p<br> | = K |
| and in case of SHUT_PROTECT = M / K        | <shut></shut>                     | = B |
|  | <sherr></sherr>                   | = U |

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

# **DEK – read FW configuration**

### Command

| Length | Content | Meaning   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID   | (ASCII) |
| 1      | Е       | Command specification: Status                         | (ASCII) |
| 1      | K       | Additional specification: Read firmware configuration | (ASCII) |
|        | 00 H    | Any filler bytes                                      | (HEXA)  |

## Acknowledgement

| Length | Content | Meaning   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID   | (ASCII) |
| 1      | E       | Command specification: Status                                     | (ASCII) |
| 1      | K       | Additional specification: Read firmware configuration             | (ASCII) |
| 1      | а       | Status code   | (ASCII) |
| n      | aaaa    | Configuration data See "Appendix X – FW configuration" (page 177) | (ASCII) |
|        | 00 H    | Any filler bytes  | (HEXA)  |

## **Description**

This command returns the current firmware configuration.

The status can be up to 2 Kbytes in size.

The individual elements **cannot** be addressed via the code word. The position of a code word is **not fixed**! The entire area is always transferred.

## **Status Codes**

## B = Software missing

Control program not available

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

# **DFG** – define FW configuration

### Command

| Length | Content | Meaning   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID   | (ASCII) |
| 1      | F       | Command specification: System parameter                 | (ASCII) |
| 1      | G       | Additional specification: Define firmware configuration | (ASCII) |
| n      | aaaa    | Parameter definition                                    | (ASCII) |
| 1      | ;       | End character   | (ASCII) |
|        | 00 H    | Any filler bytes  | (HEXA)  |

## **Acknowledgement**

| Length | Content | Meaning   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID   | (ASCII) |
| 1      | F       | Command specification: System parameter                 | (ASCII) |
| 1      | G       | Additional specification: Define firmware configuration | (ASCII) |
| 1      | а       | Status code   | (ASCII) |
|        | 00 H    | Any filler bytes  | (HEXA)  |

## **Description**

This command configures firmware execution and features.

Only one code word and its content are allowed to be specified in the command.

A subsequent reset is required to activate the set configuration(s).

"Appendix X - FW configuration" (page 177) contains a list of the code words used in the CMD-V4 incl. a list of value range per code word.

## Example: (User data only):

| SDO_BAD=Y; | Dual notes are rejected          |
|------------|----------------------------------|
|            | (more information: see page 173) |

## **Status Codes**

## B = Software missing

Control program not available

## C = Syntax

Status cell unknown Default value invalid

#### I = Context

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

## **Encryption**

The following commands are available for encryption:

- Key handling.
- Request initial value.
- Key test.
- Firmware configuration DES\_options

## **Key handling**

#### Command

| Length | Contents | Meaning   |         |
|--------|----------|---|---------|
| 1      | D        | Device ID   | (ASCII) |
| 1      | Н        | Command specification: 'Key handling'   | (ASCII) |
| 1      | а        | Additional specification:   | (ASCII) |
|        |          | <ul><li>T = transport key</li><li>L = line key</li><li>O = deactivating encryption</li></ul>              |         |
| 1      | :        | Separator   | (ASCII) |
| n      | xx xxH   | Key: n=8, or 00H in case oft additional specification 0 n= 16 in case of 3DES encryption (see DES_OPTION) | (HEXA)  |

#### Acknowledgement

| Length | Contents | Meaning   |         |
|--------|----------|---|---------|
| 1      | D        | Device ID   | (ASCII) |
| 1      | Н        | Command specification: 'Key handling'   | (ASCII) |
| 1      | a        | Additional specification:  T = transport key L = line key O = deactivating encryption | (ASCII) |
| 1      | а        | Status code   | (ASCII) |
|        | 00 H     | any filler bytes  | (HEXA)  |

#### Description

It is possible to configurate via the controller board whether the door switch is to be evaluated during encryption.

If YES, the corresponding actions are only executed by the SW-VEM of the CMD-V4 when the door switch gives the 'Open'-message!

#### **Status Codes**

#### B = Software missing

Control program not available

#### I = Context

Transport key is missing (only for additional specification L)

#### F = Safe is not opened.

Safe door is not opened (only for additional <DOOR> = M / C specification T, O)

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

## Request initial value

#### Command

| Length | Contents | Meaning   |         |
|--------|----------|---|---------|
| 1      | D        | Device ID                                       | (ASCII) |
| 1      | Н        | Command specification: 'Key handling'           | (ASCII) |
| 1      | I        | Additional specification: request initial value | (ASCII) |

#### Acknowledgement

| Length | Contents | Meaning   |         |
|--------|----------|---|---------|
| 1      | D        | Device ID                                       | (ASCII) |
| 1      | Н        | Command specification: 'Key handling'           | (ASCII) |
| 1      | _        | Additional specification: request initial value | (ASCII) |
| 1      | а        | Status code                                     | (ASCII) |
| 8      | xx xxH   | Initial value                                   | (HEXA)  |

## Description

In AZM\_NG, the initial value is generated as a random number and sent to the HOST within the acknowledgement.

The initial value is TK encrypted (ECB mode)

#### **Status Codes**

## B = Software missing

Control program not available

#### I = Context

LK missing

LK and TK missing

#### K = Key error

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

## **Key test**

#### Command

| Length | Contents | Meaning                               |         |
|--------|----------|---------------------------------------|---------|
| 1      | D        | Device ID                             | (ASCII) |
| 1      | Н        | Command specification: 'Key handling' | (ASCII) |
| 1      | С        | Additional specification: Key test    | (ASCII) |
| 8      | xx xxH   | Test pattern (00000000)               | (HEXA)  |
|        | 00 H     | any filler bytes                      | (HEXA)  |

#### **Acknowledgement**

| Length | Contents | Meaning                               |         |
|--------|----------|---------------------------------------|---------|
| 1      | D        | Device ID                             | (ASCII) |
| 1      | Н        | Command specification: 'Key handling' | (ASCII) |
| 1      | С        | Additional specification: Key test    | (ASCII) |
| 1      | а        | Status code                           | (ASCII) |
|        | 00 H     | any filler bytes                      | (HEXA)  |

### **Description**

For a test of the line keys of both partners, a 8-byte pattern (zeros) is encrypted in the HOST and sent to the CMD-V4.

This character string is decrypted and checked by the CMD-V4.

In case of correct line keys, this results in the initial pattern.

If this is not the case, a synchronization with the HOST is compulsory.

#### **Status Codes**

#### B = Software missing

Control program not available

#### I = Context

AZM does not operate with encryption

#### K = Key error

Key test negative, initial value must be requested
Wrong test pattern

The cross-reference list in Appendix A shows the possible status codes for each command (see "Appendix A").

#### DQC - read error stack

#### Command

| Length | Content | Meaning                                    |         |
|--------|---------|--|---------|
|        | s       |  |         |
| 1      | D       | Device ID                                  | (ASCII) |
| 1      | Q       | Command specification: Internal commands   | (ASCII) |
| 1      | С       | Additional specification: Read error stack | (ASCII) |
|        | 00 H    | Any filler bytes                           | (HEXA)  |

### Acknowledgement

| Length | Content | Meaning                                    |         |
|--------|---------|--|---------|
|        | s       |  |         |
| 1      | D       | Device ID                                  | (ASCII) |
| 1      | Q       | Command specification: Internal commands   | (ASCII) |
| 1      | С       | Additional specification: Read error stack | (ASCII) |
| 1      | а       | Status code                                | (ASCII) |
| n      | aaaa    | Data (see Appendix V (page 10))            | (ASCII) |
|        | 00 H    | Any filler bytes                           | (HEXA)  |

## **Description**

The error stack saves information about the most recent 10 errors. If a new error is added, the oldest error is deleted. Information about an error (see "Appendix V (page 10)") is output via the command DQC. Starting with the most recent error, information about the next, oldest error is output with each further request. Once the end of the error stack has been reached (the oldest error), the next command DQC is transferred without data. This displays that the end of the error stack has been reached and that the first error entry is displayed again with the next command. Therefore, 11 DQC commands are required (10x error entry and 1x end entry) to display the entire error stack. With a deleted error stack or not required entries, the entries only consist of filler bytes and the end separator. The size of an error stack page can be max. 2 Kbytes.

#### **Status Codes**

#### B = Software missing

Control program not available

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

## DQE - read error information

#### Command

| Length | Content | Meaning                                   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID                                 | (ASCII) |
| 1      | Q       | Command specification: Internal commands  | (ASCII) |
| 1      | Е       | Additional specification: Read error info | (ASCII) |
| 1      | ;       | End character                             | (ASCII) |
|        | 00 H    | any filler bytes                          | (HEXA)  |

## **Acknowledgement**

| Length | Content | Meaning                                   |          |
|--------|---------|---|----------|
|        | S       |   |          |
| 1      | D       | Device ID                                 | (ASCII)  |
| 1      | Q       | Command specification: Internal commands  | (ASCII)  |
| 1      | Е       | Additional specification: Read error info | (ASCII)  |
| 1      | а       | Status code                               | (ASCII)  |
| n      | bb bb   | Device info (see table)                   | (BINARY) |
|        | 00 H    | any filler bytes                          | (HEXA)   |

## **Description**

Returns all the data that are relevant for error analysis.

#### **Status Codes**

#### B = Software missing

Control program not available

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

### **Structure**

| char modId[] = "DIL=\$FRM\$ 010101 1000 CMD_BOOT.BIN: \$MOD\$ 010101 1000 CMD_V4_0.BIN;" |
|--|
| char ded[]="DED="  |
| char len[4];   |
| char sSw[1];   |
| char dLoc[1];  |
| char cas[1];   |
| char shErr[1];   |
| char shut[1];  |
| char mon[1];   |
| char ter[1];   |
| char ts[2];  |
| char tf[1];  |
| char sr[1];  |
| char dis[1];   |
| char cex[1];   |
| char door[1];  |
| char doS[1];   |
| char type[1];  |
| char nVm[1];   |
| char sedm[1];  |
| char ICmd[2];  |
| char ISta[1];  |
| char sCle[1];  |
| char sRes[1];  |
| char tst[1];   |
| char sCod[2];  |
| char or[1];  |
| char transport[1];   |
| char cOut[1];  |
| char shutProtect[1];   |
| char error[16];  |
| char warning[16];  |
| char semicolon[1];   |
| char dec[]="DEC="  |

| char len[4];   |
|--|
| char rSta[1];  |
| char rAct[4];  |
| char rRet[2];  |
| struct Cassette  |
| { // the following structure is repeated 8 times (for all cassettes supported) |
| char sta[1];   |
| char num[7];   |
| char cur[3];   |
| char rel[4];   |
| char val[8];   |
| char len[3];   |
| char tol[2];   |
| char act[4];   |
| char ndv[4];   |
| char low[4];   |
| char ld[2];  |
| char rej[3] ;  |
| } cassettes[Dispenser ::MAX_CASSETTES] ;                                       |
| char hall[]="HALL="  |
| { // the following structure is repeated 4 times                               |
| char handle[2]   |
| char state[2]  |
| }  |
| char semicolon   |
| char hall[]="DPHOTO="  |
| { // the following structure is repeated n times, up to the semi-colon         |
| char handle[2]   |
| char state[2]  |
| }  |
| char semicolon[1]  |
| char hall[]="PRESS="   |
| { // the following structure is repeated 8 times                               |
| char handle[2]   |
| char pressure[2]   |
| char current[2]  |

| char workPressure[2]  |
|---|
| char maxPressure[2]   |
| }   |
| char semicolon[1]   |
| char hall[]="DDU="  |
| char adValue1[1]  |
| char adValue2[1]  |
| char current1[1]  |
| char current2[1]  |
| char semicolon  |
| char photo[]="PHOTO="   |
| { // the following structure is repeated n times, up to the semi-colon  |
| char name[4]  |
| short iActual   |
| short iWork   |
| short iReference  |
| short changeFactor  |
| char Regulation   |
| char dirtState (MISSING = '0', OK = '1', PROD_WEAK = '2', TKD_WEAK = '3', DIRTY = '4', DEFECT = '5', UNKNOWN = '6') |
| short value   |
| char state (FREE=0, CLOSED=1, UNDEFINED=2)  |
| }   |
| char semicolon[1]   |
| char dek[]="DEK="   |
| char sdoBad[1]  |
| char maxNotes[2]  |
| char noSr[1]  |
| char semicolon[1]   |
| char tCount[]="TCOUNT="   |
| char transactions[2]  |
| char semicolon[1]   |
| char hws[]="DYTHWS="  |
| char hwsData[]=""   |
| Data up to semi-colon   |

## DQF - read stacker-EEPROM

#### Command

| Length | Content | Meaning                                      |         |         |
|--------|---------|--|---------|---------|
|        | s       |  |         |         |
| 1      | D       | Device ID                                    |         | (ASCII) |
| 1      | Q       | Command specification: Internal commands     |         | (ASCII) |
| 1      | F       | Additional specification: read stacker EEPRO | (ASCII) |         |
|        | 00 H    | any filler bytes                             | (HEXA)  | )       |

## **Acknowledgement**

| Length | Content | Meaning   |          |
|--------|---------|---|----------|
|        | s       |   |          |
| 1      | D       | Device ID   | (ASCII)  |
| 1      | Q       | Command specification: Internal commands              | (ASCII)  |
| 1      | Е       | Additional specification: Read error info             | (ASCII)  |
| 1      | а       | Status code   | (ASCII)  |
| 76     | bb bb   | Device info (see table 'Describe stacker-<br>EEPROM') | (BINARY) |
|        | 00 H    | any filler bytes                                      | (HEXA)   |

## **Description**

The data of the stacker EEPROM are displayed.

This command is only available for reasons of compatibility.

#### **Status Codes**

## B = Software missing

Control program not available

#### E = Device error

Stacker-EEPROM unreadable

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

## **DQI - Describe stacker-EEPROM**

#### Command

| Length | Content | Meaning                                       |          |         |
|--------|---------|---|----------|---------|
|        | s       |   |          |         |
| 1      | D       | Device ID                                     | (ASCII)  |         |
| 1      | Q       | Command specification: Internal commands      |          | (ASCII) |
| 1      | 1       | Additional specification: describe stacker EE | PROM     | (ASCII) |
| 76     | bb bb   | Device info (see table)                       | (BINARY) |         |
|        | 00 H    | any filler bytes                              | (HEXA)   | )       |

## **Acknowledgement**

| Length | Content | Meaning                                   |         |
|--------|---------|---|---------|
|        | S       |   |         |
| 1      | D       | Device ID                                 | (ASCII) |
| 1      | Q       | Command specification: Internal commands  | (ASCII) |
| 1      | I       | Additional specification: Read error info | (ASCII) |
| 1      | а       | Status code                               | (ASCII) |
|        | 00 H    | any filler bytes                          | (HEXA)  |

## **Description**

The data of the stacker EEPROM are written for the whole area.

The individual elements cannot be addressed via code words. The device info data are not checked for validity by the firmware.

#### Data structure in the stacker-EEPROM

The EEPROM is organized in 64 \* 16Bit ( word )

| Positio<br>n of the<br>word | Contents    | Meaning  |
|-----------------------------|-------------|--|
| 0                           | 0x0002      | Version number   |
| 1                           | 0x5557      | Checksum ( = version number ^ 0x5555 )   |
| 2 -24                       | XX          | Reserved for initial start-up (e.g. firmware filename, serial number, Singlereject, gradual correction routing disk, etc.) |
| 25 – 26                     | XXXX        | Reserved for development of measuring and test equipment   |
| 27 – 32                     | ,XXXXXXXXXX | Part number ( "," plus 11 bytes)   |
| 33 – 37                     | ,XXXXXXXX   | BAUZ/revision level ( "," plus 9 bytes)  |
|                             |             |  |
| • • •                       |             |  |
|                             |             |  |
| 63                          |             |  |

<sup>&</sup>quot;," = separator, ";" = end character, X = Byte

The positions 2 - 24 are reserved for the initial start-up of the device and are therefore initialized with the corresponding data.

The positions 25 - 26 are reserved for the development of measuring and test equipment.

The positions 27 - 37 are reserved for the part number and the revision level.

The different positions may only be overwritten by their owners.

The positions 0 – 24 are partly evaluated by previous firmware levels of the CMD-V4 (
Release prior to 16.00).

#### General example:

, 01750107630,000001976 separator part number separator revision level

#### Structure revision level:

For each revision level one bit is set in the memory and the information is returned as ASCII code via the interface.

#### Identification sign:

|    |    |    |    |              |   |   |   |   |   |              |   | 14 |
|----|----|----|----|--------------|---|---|---|---|---|--------------|---|----|
| 13 | 12 | 11 | 10 | <del>4</del> | ⊕ | 7 | 6 | 5 | 4 | <del>3</del> | 2 | 4  |

| 26 | 25 | <br> | <br>13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4  | 3 | 2 | 1                | Position of         |
|----|----|------|--------|----|----|----|---|---|---|---|---|----|---|---|------------------|---------------------|
|    |    |      |        |    |    |    |   |   |   |   |   |    |   |   |                  | identification sign |
| 0  | 0  | <br> | <br>0  | 0  | 0  | 0  | 1 | 1 | 0 | 0 | 1 | 0  | 1 | 1 | 1                | Value               |
| (  | 0  |      | (      | )  |    | 1  |   |   | ( | 9 |   | 7  |   |   | HexadecimalValue |                     |
| 3  | 30 |      | 3      | 0  |    | 31 |   |   | 3 | 9 |   | 37 |   |   | ASCII value      |                     |

#### **Status Codes**

#### B = Software missing

Control program not available

#### C = Syntax

invalid length

#### E = Device error

Stacker-EEPROM not writeable

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

## DQJ - read manufacturer's and controller identification

#### Command

| Length | Content | Meaning   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID   | (ASCII) |
| 1      | Q       | Command specification: Internal commands                                    | (ASCII) |
| 1      | J       | Additional specification: read manufacturer's and controller identification | (ASCII) |
|        | 00 H    | Any filler bytes  | (HEXA)  |

## **Acknowledgement**

| Length | Content s | Meaning   |         |
|--------|-----------|---|---------|
| 1      | D         | Device ID   | (ASCII) |
| 1      | Q         | Command specification: Internal commands                                    | (ASCII) |
| 1      | J         | Additional specification: read manufacturer's and controller identification | (ASCII) |
| 1      | а         | Status code   | (ASCII) |
| 4      | a a       | Manufacturer's ID corresponding to the type plate definitions               | (ASCII) |
|        |           | * = not initialized or checksum error                                       |         |
| 26     | aa        | Reserve   | (ASCII) |
| 1      | ,         | Separator   | (ASCII) |
| 2      | aa        | Controller ID   | (ASCII) |
|        |           | e.g. 01, 02 or 03 = Intel controller  |         |
|        |           | 80 = Reproduction of Innovasic controller                                   |         |
| 1      | ;         | End character   | (ASCII) |
|        | 00 H      | Any filler bytes  | (HEXA)  |

## **Description**

This command returns the manufacturer's and controller identification. The controller ID is read from the controller PCB register STEPID. The manufacturer's ID is stored in the memory contents of the writeable 32 byte area between the addresses E800:7FE0 and

E800:7FFF. The memory contents are to be written according to the manufacturer's ID during manufacturing of the controller board.

#### Structure of the manufacturer's ID

| Address position        | Type      | Meaning  |
|-------------------------|-----------|--|
| 0xEFFE0                 | byte [1]  | Checksum: sum ( all 32 bytes ) = 0   |
| 0xEFFE1                 | byte [1]  | 01 = Version 1: is assigned by Wincor Nixdorf  |
| 0xEFFE2<br>-<br>0xEFFE5 | char [4]  | Manufacturer's ID corresponding to the type plate definition.  Identification of the production plant by the 2- to 4-digt ID before the serial number. In case of the 2- or 3-digit serial number, the leading digits must be filled with 0.  e.g. 0050, 0051 or 0053 = Wincor-Nixdorf Paderborn |
| 0xEFFE6                 | byte [26] | 0 0 = Reserve filler byte  |
| 0xEFFFF                 |           |  |

#### **Status Codes**

#### B = Software missing

Control program not available

#### C = Syntax

invalid length

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

#### **GetAccessCode**

#### Command

| Length | Conten ts | Meaning                                 |         |
|--------|-----------|---|---------|
| 1      | D         | Device ID                               | (ASCII) |
| 1      | S         | Command specification: 'SPECIAL'        | (ASCII) |
| 1      | С         | Additional specification: GetAccessCode | (ASCII) |
|        | 00 H      | any filler bytes                        | (HEXA)  |

## **Acknowledgement**

| Length | Conten<br>ts | Meaning                                 |         |
|--------|--------------|---|---------|
| 1      | D            | Device ID                               | (ASCII) |
| 1      | S            | Command specification: 'SPECIAL'        | (ASCII) |
| 1      | С            | Additional specification: GetAccessCode | (ASCII) |
| 1      | а            | Status code                             | (ASCII) |
| 8      | xxxxH        | Random number                           | (HEXA)  |
|        | 00 H         | any filler bytes                        | (HEXA)  |

## **Description**

In the CMD-V4, an 8 byte random number is generated, transferred within the acknowledgement, and **<ACCESS\_CODE>=I** set. The random number must be requested anew prior to each 'SetAccessCode' command. Transmission of the acknowledgement is delayed after a faulty activation procedure. A delay time of 5 seconds is fixed and with every further failed activation procedure the delay time will extend by the fixed preset value.

#### Status codes

#### B = Software missing

Control program not available

I = Context

no PC8xxx system

<TRANSPORT>

unequal E, F, G

### SetAccessCode

#### Command

| Length | Conten<br>ts | Meaning                                 |         |
|--------|--------------|---|---------|
| 1      | D            | Device ID                               | (ASCII) |
| 1      | S            | Command specification: 'SPECIAL'        | (ASCII) |
| 1      | D            | Additional specification: SetAccessCode | (ASCII) |
| 8      | xxxxH        | Access code                             | (HEXA)  |
|        | 00 H         | any filler bytes                        | (HEXA)  |

## **Acknowledgement**

| Length | Conten | Meaning                                 |         |
|--------|--------|---|---------|
|        | ts     |   |         |
| 1      | D      | Device ID                               | (ASCII) |
| 1      | S      | Command specification: 'SPECIAL'        | (ASCII) |
| 1      | D      | Additional specification: SetAccessCode | (ASCII) |
| 1      | а      | Status code                             | (ASCII) |
|        | 00 H   | any filler bytes                        | (HEXA)  |

## **Description**

The transmitted AccessCode is checked by the firmware. The random number must be requested anew prior to each 'SetAccessCode' command. In case of correct check, <ACCESS\_CODE>=Y is set and the number of failed attempts cleared, if not, the <ACCESS\_CODE>=I and the number of failed attempts is incremented.

#### Status codes

### B = Software missing

Control program not available

I = Context

no PC8xxx system <TRANSPORT> unequal E, F, G

Random number not requested

## K = Key error

Key test negative, a new random number must be requested

## DYR - read internal statistics

## Command

| Length | Content | Meaning                                   |         |
|--------|---------|---|---------|
|        | s       |   |         |
| 1      | D       | Device ID                                 | (ASCII) |
| 1      | Υ       | Command specification: Internal commands  | (ASCII) |
| 1      | R       | Additional specification: Read statistics | (ASCII) |
|        | 00 H    | any filler bytes                          | (HEXA)  |

## Acknowledgement

| Length | Content | Meaning                                   |         |
|--------|---------|---|---------|
|        | S       |   |         |
| 1      | D       | Device ID                                 | (ASCII) |
| 1      | Υ       | Command specification: Internal commands  | (ASCII) |
| 1      | R       | Additional specification: Read statistics | (ASCII) |
| 1      | а       | Status code                               | (ASCII) |
| n      | а       | Statistics data (see the following table) | (ASCII) |
|        | 00 H    | any filler bytes                          | (HEXA)  |

### Structure of the statistics data

(persistent = not deletable)
All long values are listed in the sequence LSB to MSB.

| Byte position                  | Cell                              | Meaning  |                    |
|--------------------------------|-----------------------------------|--|--------------------|
| 0                              | yearOfBirth                       | Year persistent statistics                           | (BCD)              |
|                                |                                   | commenced  |                    |
| 1                              | monthOfBirth                      | Month  | (BCD)              |
| 2                              | dateOfBirth                       | Day  | (BCD)              |
| 3                              | hourOfBirth                       | Hour   | (BCD)              |
| 4                              | minuteOfBirth                     | Minute   | (BCD)              |
| 5                              | secondOfBirth                     | Second   | (BCD)              |
| 6 – 9 (6=lsb,<br>9=msb)        | persistentNoteCo<br>unter         | persistent note counter at DDU                       | unsigned<br>long ( |
| 10 – 13                        | PersistentTrans-<br>actionCounter | persistent counter 'Clamp reaching shutter'          | unsigned long (    |
| 14                             | yearOfReset                       | Year persistent statistics commenced                 | (BCD)              |
| 15                             | monthOfReset                      | Month  | (BCD)              |
| 16                             | dateOfReset                       | Day  | (BCD)              |
| 17                             | hourOfReset                       | Hour   | (BCD)              |
| 18                             | minuteOfReset                     | Minute   | (BCD)              |
| 19                             | secondOfReset                     | Second   | (BCD)              |
| 20 – 23<br>(20=lsb,<br>23=msb) | resettableNote<br>Counter         | resettable note counter at DDU                       | unsigned<br>long ( |
| 24 – 27                        | resettableTrans-<br>actionCounter | resettable counter 'Clamp reaches shutter'           | unsigned<br>long ( |
| 28 – 31                        | bundleReject<br>Counter[0]        | resettable counter 'Cassette 1 causes bundle reject' | unsigned<br>long ( |
| 32 – 35                        | bundleReject<br>Counter[1]        | resettable counter 'Cassette 2 causes bundle reject' | unsigned<br>long ( |
| 36 – 39                        | bundleReject<br>Counter[2]        | resettable counter 'Cassette 3 causes bundle reject' | unsigned<br>long ( |
| 40 – 43                        | bundleReject<br>Counter[3]        | resettable counter 'Cassette 4 causes bundle reject' | unsigned<br>long ( |
| 44 – 47                        | bundleReject<br>Counter[4]        | resettable counter 'Cassette 5 causes bundle reject' | unsigned<br>long ( |

| Byte position | Cell                       | Meaning  |                     |
|---------------|----------------------------|--|---------------------|
| 48 – 51       | bundleReject<br>Counter[5] | resettable counter 'Cassette 6 causes bundle reject' | unsigned<br>long (  |
| 52 – 55       | bundleReject<br>Counter[6] | resettable counter 'Cassette 7 causes bundle reject' | unsigned<br>long (  |
| 56 – 59       | bundleReject<br>Counter[7] | resettable counter 'Cassette 8 causes bundle reject' | unsigned<br>long (  |
| 60 – 63       | SingleReject<br>Counter[0] | resettable counter 'Cassette 1 causes single reject' | unsigned<br>long (  |
| 64 – 67       | SingleReject<br>Counter[1] | resettable counter 'Cassette 2 causes single reject' | unsigned<br>long (  |
| 68 – 71       | SingleReject<br>Counter[2] | resettable counter 'Cassette 3 causes single reject' | unsigned<br>long (  |
| 72 – 75       | SingleReject<br>Counter[3] | resettable counter 'Cassette 4 causes single reject' | unsigned<br>long (  |
| 76 – 79       | SingleReject<br>Counter[4] | resettable counter 'Cassette 5 causes single reject' | unsigned<br>long (  |
| 80 – 83       | SingleReject<br>Counter[5] | resettable counter 'Cassette 6 causes single reject' | unsigned<br>long (  |
| 84 – 87       | SingleReject<br>Counter[6  | resettable counter 'Cassette 7 causes single reject' | unsigned<br>long (  |
| 88 – 91       | SingleReject<br>Counter[7  | resettable counter 'Cassette 8 causes single reject' | unsigned<br>long (  |
| 92 – 93       | jamLocks                   | resettable counter 'Flag detected'                   | unsigned<br>short ( |

## **Description**

The current note counters (32 bit wide) are delivered.

All cells are stored in the controller's static, write-protected RAM (the so-called CMOS). The cells are re-created if the CMOS is found to be invalid (via checksum + version).

#### This is the case:

- In first use (production)
- When the battery jumper has been removed for long periods ( > 5min )
- After initiating a CMOS reset by jumper 'CL CMOS'
- After deleting the CMOS per DXRAL command
- If the CMOS is corrupt (e.g. electrical faults, firmware error, etc.)

Following contents are stored:

- 2 transaction counters (1\*permanent, 1\*resettable):
   If the clamp reaches the shutter without an error (Hall sensor 4),
   the counter is incremented by 1.
- 2 note counters (1\*permanent, 1\*resettable):
   With every note recognized by the thickness measurement station, the counter is incremented by 1.

When the note is detected to be double, the counter is incremented by 2.

16 Reject counter (all resettable):

There is one counter for bundle rejects and one for single rejects at each cassette location, i.e. 8 cassettes \* 2 counters = 16 entries

If a dispense transaction has to be canceled and a bundle reject takes place, the bundle reject counter of the cassette that is currently in use (which is normally responsible for cancellation) is incremented by 1.

The single-reject counter of the cassette where the note is from is incremented by 1 for each single-rejected note.

When the note is detected to be double, the counter is incremented by 2.

– 2 \* date/time:

One date/time on the real-time clock is maintained for the permanent counters and for the resettable counters.

All counters are 32 bit wide, hence they can count 2\*32 events. (Exception 'jamLocks') All resettable counters are reset to 0 with key function 5.

At the same time, the date/time for these counters is updated.

For performance reasons, counter data is currently saved with a slight delay, so that power failures at unsuitable moments may corrupt the counters.

The date ID notes when the counters were deleted.

i Double notes count as 2 notes.

#### Status Codes

#### B = Software missing

Control program not available

**Appendix A** (page 88) shows the possible status codes for each command in a cross-reference list.

**Appendix X** (page 155) shows the possible device and cassette states for each command in a cross-reference list.

## DYS - Resetting internal statistics

#### Command

| Length | Content | Meaning                                    |         |
|--------|---------|--|---------|
| 1      | D       | Device ID                                  | (ASCII) |
| 1      | Υ       | Command specification: Internal commands   | (ASCII) |
| 1      | S       | Additional specification: Reset statistics | (ASCII) |
|        | 00 H    | any filler bytes                           | (HEXA)  |

## Acknowledgement

| Length | Content | Meaning                                    |         |
|--------|---------|--|---------|
|        | s       |  |         |
| 1      | D       | Device ID                                  | (ASCII) |
| 1      | Υ       | Command specification: Internal commands   | (ASCII) |
| 1      | S       | Additional specification: Reset statistics | (ASCII) |
| 1      | а       | Status code                                | (ASCII) |
|        | 00 H    | any filler bytes                           | (HEXA)  |

## **Description**

This command resets the resettable counters and the date/time for these counters is simultaneously updated for these counters. See description "DYR - read internal statistics".

#### **Status Codes**

### B = Software missing

Control program not available

# **Appendix A: Cross reference**

## Command/status

| CMD     | Referenc<br>e   | Meaning                          | A / Q - OK | B – SW missing | C – Syntax | D/T-Out of service | E / U - Device Error | F – Safe not open | <b>G</b> – Time out | <b>H</b> – Withdrawal | I – Context | × K – Key-Error | S – SCOP-Error |
|---------|---|----------------------------------|------------|----------------|------------|--------------------|----------------------|-------------------|---------------------|-----------------------|-------------|-----------------|----------------|
| Dablank | Page: 35  | Reset / Power up                 | Χ          | Х              | Χ          | Х                  |                      |                   |                     |                       |             | Χ               |                |
| DAB     | Page: 40  | Clearing                         | Χ          | Х              | Х          | Х                  |                      |                   |                     |                       |             | Х               |                |
|         |   |                                  |            |                |            |                    |                      |                   |                     |                       |             |                 |                |
| DBS     | Page: Fehler! Textmar ke nicht definiert. Fehler! Textmar ke nicht definiert. | Dispense                         | x          | X              | X          | X                  | X                    |                   |                     |                       | X           | X               |                |
| DBC     | Page: Fehler! Textmar ke nicht definiert. Fehler! Textmar ke nicht definiert. | DispenseAdditional               | X          | X              | X          | X                  | X                    |                   |                     |                       | X           | X               |                |
|         |   |                                  |            |                |            |                    |                      |                   |                     |                       |             |                 |                |
| DCA     | [L 1]   | Transport: Wait for cash removal | Χ          | Х              | Χ          | Χ                  | Χ                    |                   | Х                   |                       | Χ           | Χ               |                |
| DCB     | [L 1]   | Transport: Bundle reject         | Χ          | Χ              | Χ          | Χ                  | Χ                    |                   |                     |                       | Χ           | Χ               |                |
| DCC     | [L 1]   | Transport: Close shutter         | Χ          | Χ              | Χ          | Χ                  | Χ                    |                   |                     |                       | Χ           | Χ               |                |

| CMD | Referenc<br>e | Meaning                                 | A / Q - OK | B – SW missing | C – Syntax | D/T - Out of service | E / U - Device Error | F – Safe not open | <b>G</b> – Time out | <b>H</b> – Withdrawal | I – Context | K – Key-Error | S – SCOP-Error |
|-----|---------------|---|------------|----------------|------------|----------------------|----------------------|-------------------|---------------------|-----------------------|-------------|---------------|----------------|
| DCE | [L 1]         | Transport: Output cash                  | Χ          | Χ              | Χ          |                      |                      |                   |                     |                       |             | Х             |                |
| DCO | [L 1]         | Transport: Open shutter                 | Χ          | Χ              | Χ          | Χ                    | Χ                    |                   |                     |                       | Χ           | Χ             |                |
| DCP | [L 1]         | Transport: Offer cash                   | Χ          | Χ              | Χ          | Х                    | Χ                    |                   | Χ                   |                       | Χ           | Χ             |                |
| DCQ | [L 1]         | Transport: Cash retract without storage | X          | X              | X          | X                    | X                    |                   |                     | X                     | X           | X             |                |
| DCR | [L 1]         | Transport: Cash retract with storage    | X          | X              | X          | Χ                    | X                    |                   |                     | X                     | X           | X             |                |
| DCT | Page: 57      | Transport:<br>Shutter – Test            |            | Х              | Χ          |                      |                      |                   |                     |                       |             | Х             |                |

| DCW     | [L 1]    | Transport:<br>Target = Stop Over      | X | Х | Х | Х | Х |  | X | Х |
|---------|----------|---------------------------------------|---|---|---|---|---|--|---|---|
|         |          |                                       |   |   |   |   |   |  |   |   |
| DDblank | [L 1]    | Cancel                                | Χ | Х | Χ |   |   |  | Х | Х |
|         |          |                                       |   |   |   |   |   |  |   |   |
| DEC     | [L 1]    | Cassette status                       | Χ | Х | Χ |   |   |  |   | Х |
| DED     | [L 1]    | Device status                         | Χ | Х | Χ |   |   |  |   | Х |
| DEF     | [L 3]    | Features                              | Χ | Х | Х |   |   |  |   | Х |
| DEK     | Page: 57 | Read firmware configuration           | Χ | Х |   |   |   |  |   |   |
| DES     | [L 2]    | Read SCOP status                      | Χ | Х |   |   |   |  |   |   |
|         |          |                                       |   |   |   |   |   |  |   |   |
| DFA     | [L 1]    | Confirm number of notes               | Χ | Х | Х |   |   |  | X | Х |
| DFB     | [L 1]    | Confirm no. of notes (without errors) | Χ | Х | X |   |   |  | Χ | Х |
| DFC     | [L 1]    | Confirm existing cassettes            | Χ | Х | Χ |   |   |  | Χ | Х |

| CMD     | Referenc<br>e | Meaning                           | <b>A / Q</b> – OK | B – SW missing | <b>-</b> ၁ | D/T - Out of service | E / U - Device Error | F – Safe not open | <b>G</b> – Time out | <b>H</b> – Withdrawal | _ | K – Key-Error | S – SCOP-Error |
|---------|---------------|-----------------------------------|-------------------|----------------|------------|----------------------|----------------------|-------------------|---------------------|-----------------------|---|---------------|----------------|
| DFD     | [L 1]         | Note parameter II                 | Χ                 | Χ              | Х          |                      |                      |                   |                     |                       | Х | Х             |                |
| DFG     | Page: 61      | Write firmware configuration      | Χ                 | Х              | X          |                      |                      |                   |                     |                       | X | Х             |                |
| DFI     | [L 1]         | Cassette ID (Standard)            | Χ                 | Х              | Х          |                      |                      |                   |                     |                       | Х | X             |                |
| DFL     | [L 1]         | Set minimum quantity              | Χ                 | Χ              | Х          |                      |                      |                   |                     |                       | Х | Χ             |                |
| DFN     | [L 1]         | Number of notes                   | Χ                 | Х              | Х          |                      |                      |                   |                     |                       | Х | Χ             |                |
| DFO     | [L 1]         | Number of notes (without check)   | Χ                 | Х              | Х          |                      |                      |                   |                     |                       | Х | Χ             |                |
| DFP     | [L 1]         | Note parameter I                  | Χ                 | Χ              | Χ          |                      |                      |                   |                     |                       | Χ | Χ             |                |
| DFR     | [L 1]         | Reset lock flag                   | Χ                 | Х              | Χ          | Χ                    |                      |                   |                     |                       | Χ | Χ             |                |
| DFT     | [L 1]         | Delete retract counter            | Χ                 | Х              | Χ          |                      |                      |                   |                     |                       | Χ | Χ             |                |
| DFX     | [L 1]         | Write value into cassette         | Χ                 | Х              | Χ          |                      |                      |                   |                     |                       | Χ | Χ             |                |
| DFY     | [L 1]         | Read value from cassette          | Χ                 | Х              | X          |                      |                      |                   |                     |                       | X | Х             |                |
| DFZ     | [L 1]         | 'Power on' -<br>RESET without PUT | Х                 | Х              | Χ          |                      |                      |                   |                     |                       | Χ | X             |                |
|         |               |                                   |                   |                |            |                      |                      |                   |                     |                       |   |               |                |
| DGblank | Page: 54      | Determine reference value         | X                 | Х              | Χ          | X                    | X                    |                   |                     |                       | Χ | X             |                |
|         |               |                                   |                   |                |            |                      |                      |                   |                     |                       |   |               |                |
| DHC     | Page: 66      | Key test                          | Χ                 | Χ              | Χ          |                      |                      |                   |                     |                       | Χ | Х             |                |
| DHI     | Page: 65      | Request initial value             | Χ                 | Χ              | Χ          |                      |                      |                   |                     |                       | Χ | Χ             |                |
| DHL     |               | Load line code                    | Χ                 | Χ              | Χ          |                      |                      |                   |                     |                       | Χ |               |                |
| DHO     | Page: 63      | Switch encryption off             | Χ                 | Χ              | Χ          |                      |                      | Χ                 |                     |                       | Χ | Χ             |                |
| DHT     | Page: 63      | Load transport key                | Χ                 | Χ              | Χ          |                      |                      | Χ                 |                     |                       |   | Χ             |                |
| DHZ     | [L 2]         | Transparent ChipCard access       | X                 | Х              | Х          |                      | Х                    |                   |                     |                       | Х |               |                |
|         |               |                                   |                   |                |            |                      |                      |                   |                     |                       |   |               |                |

| CMD | Referenc<br>e   | Meaning   | <b>A / Q</b> – OK | B – SW missing | C – Syntax | D/T - Out of service | <b>E / U</b> – Device Error | F – Safe not open | <b>G</b> – Time out | <b>H</b> – Withdrawal | I – Context | K – Key-Error | S – SCOP-Error |
|-----|---|---|-------------------|----------------|------------|----------------------|-----------------------------|-------------------|---------------------|-----------------------|-------------|---------------|----------------|
| DIC | [L 1]   | Software transfer:<br>Activate booter                           | Χ                 |                | Х          |                      |                             |                   |                     |                       |             |               |                |
| DID | [L 1]   | Software transfer: Data   | Χ                 | Х              | Х          |                      |                             |                   |                     |                       | Χ           |               |                |
| DIH | [L 2]   | Software transfer:<br>Firmware 'HASH'                           | Χ                 |                | Х          |                      | X                           |                   |                     |                       |             |               | Х              |
| DIL | [L 1]   | Software transfer: Read firmware ID                             | Χ                 |                | Х          |                      |                             |                   |                     |                       | X           |               |                |
|     |   |   |                   |                |            |                      |                             |                   |                     |                       |             |               |                |
| DQA | [L 1]   | Set the real-time clock   | Χ                 | Х              | Х          |                      |                             |                   |                     |                       |             |               |                |
| DQB | [L 1]   | Read the real-time clock  | Χ                 | Х              | Х          |                      |                             |                   |                     |                       |             |               |                |
| DQC | Page: 68  | Read error stack  | Χ                 | Х              | Х          |                      |                             |                   |                     |                       |             |               |                |
| DQE | Page: Fehler! Textmar ke nicht definiert. Fehler! Textmar ke nicht definiert. | Internal commands:<br>Read error information                    | X                 | Х              | X          |                      |                             |                   |                     |                       |             |               |                |
| DQF | Page: 74  | Internal commands: read EE-PROM                                 | Χ                 | Х              | Х          |                      | X                           |                   |                     |                       |             |               |                |
| DQI | Page: 75  | Internal commands:<br>Write EEPROM                              | Χ                 | Х              | Х          |                      | X                           |                   |                     |                       |             |               |                |
| DQJ | Page: 78  | Internal commands:<br>Read out<br>manufacturer/controller<br>ID | Х                 | х              | х          |                      | X                           |                   |                     |                       |             |               |                |
| DQR | [L 8]   | Internal commands:<br>Read Recovery Info                        | Х                 | Х              | Х          |                      |                             |                   |                     |                       |             |               |                |

| СМД | Referenc<br>e | Meaning                                     | A / Q - OK | B – SW missing | C – Syntax | D / T - Out of service | E / U - Device Error | F – Safe not open | <b>G</b> – Time out | <b>H</b> – Withdrawal | I – Context | K – Key-Error | S – SCOP-Error |
|-----|---------------|---|------------|----------------|------------|------------------------|----------------------|-------------------|---------------------|-----------------------|-------------|---------------|----------------|
| DSC | Page: 80      | Read access code                            | Χ          | Х              | Χ          |                        |                      |                   |                     |                       | Χ           |               |                |
| DSD | Page: 81      | Set access code                             | Χ          | Х              | Χ          |                        |                      |                   |                     |                       | Χ           | Χ             |                |
|     |               |   |            |                |            |                        |                      |                   |                     |                       |             |               |                |
| Dxa | [L 1]         | Self-test commands                          | Χ          | Х              | Х          |                        |                      |                   |                     |                       | Х           |               |                |
| Dya | [L 1]         | Test commands                               | Χ          | Х              | Χ          |                        |                      |                   |                     |                       | Χ           |               |                |
| DYR | Page: 80      | Test commands: Read internal statistics     | Χ          | Х              | X          |                        |                      |                   |                     |                       |             |               |                |
| DYS | Page: 87      | Test commands:<br>Reset internal statistics | Χ          | Х              | Х          |                        |                      |                   |                     |                       |             |               |                |

## **Booter commands**

The following commands are processed in the booter:

Dix Software transfer DEF Read properties

## **Execution times**

All times stated below do not include the ISO wait of max. 3 \* 8 seconds.

| CMD     | Meaning  | 304.8       |
|---------|----------|-------------|
|         |          | mm<br>(12") |
| Dablank | RESET    | 60 s        |
| DAB     | Clearing | 60 s        |

| CMD     | Meaning                                 | 304.8<br>mm<br>(12") |
|---------|---|----------------------|
|         |   |                      |
| DBC     | Additional dispense                     | 60 s                 |
| DBS     | Dispensing: standard                    | 60 s                 |
|         |   |                      |
| DCA     | Transport: Wait for cash removal        | 15 s                 |
| DCB     | Transport: Bundle reject                | 20 s                 |
| DCC     | Transport: Close shutter                | 20 s                 |
| DCE     | Transport: Output cash                  | 20 s                 |
| DCO     | Transport: Open shutter                 | 20 s                 |
| DCP     | Transport: Offer cash                   | 20 s                 |
| DCQ     | Transport: Cash retract without storage | 25 s                 |
| DCR     | Transport: Cash retract with storage    | 25 s                 |
| DCT     | Transport: Shutter test                 | 20 s                 |
| DCW     | Transport: Target = Stop Over           | 20 s                 |
|         |   |                      |
| DDblank | Cancel                                  | 15 s                 |
|         |   |                      |
| DEC     | Cassette status                         | 15 s                 |
| DED     | Device status                           | 15 s                 |
| DEF     | Features                                | 15 s                 |
| DEK     | Read firmware configuration             | 15 s                 |
| DES     | Read SCOP status                        | 15 s                 |
|         |   |                      |
| DFA     | Confirm number of notes                 | 15 s                 |
| DFB     | Confirm no. of notes (without errors)   | 15 s                 |
| DFC     | Confirm existing cassettes              | 15 s                 |
| DFD     | Note parameter II                       | 15 s                 |
| DFG     | Write firmware configuration            | 15 s                 |
| DFI     | Cassette ID (Standard)                  | 15 s                 |
| DFL     | Set minimum quantity                    | 15 s                 |
| DFN     | Number of notes                         | 15 s                 |
| DFO     | Number of notes (without check)         | 15 s                 |
| DFP     | Note parameter I                        | 15 s                 |

1 note from 1st cass. 1 note from 1st cass.

+ waiting time

+ waiting time

| CMD     | Meaning  | 304.8<br>mm |  |
|---------|--|-------------|--|
| 555     |  | (12")       |  |
| DFR     | Reset lock flag  | 15 s        |  |
| DFT     | Delete retract counter                                     | 15 s        |  |
| DFX     | Write value into cassette 1                                |             |  |
| DFY     | Read value from cassette                                   | 15 s        |  |
| DFZ     | 'Power on' - RESET without PUT                             | 15 s        |  |
|         |  |             |  |
| DGblank | Determine reference value                                  | 60 s        |  |
|         |  |             |  |
| DHC     | Key test   | 15 s        |  |
| DHI     | Request initial value                                      | 15 s        |  |
| DHL     | Load line code   | 15 s        |  |
| DHO     | Switch encryption off                                      | 15 s        |  |
| DHT     | Load transport key   | 15 s        |  |
| DHZ     | Transparent ChipCard access                                | 15 s        |  |
|         |  |             |  |
| DIC     | Software transfer: Activate booter                         | 15 s        |  |
| DID     | Software transfer: Data                                    | 15 s        |  |
| DIH     | Software transfer: Firmware 'HASH'                         | 180 s       |  |
| DIL     | Software transfer: Read firmware ID                        | 240 s       |  |
|         |  |             |  |
| DQA     | Set the real-time clock                                    | 15 s        |  |
| DQB     | Read the real-time clock                                   | 15 s        |  |
| DQC     | Internal commands: Read error stack                        | 15 s        |  |
| DQE     | Internal commands: Read error information                  | 15 s        |  |
| DQF     | Internal commands: Read EE-PROM                            | 15 s        |  |
| DQI     | Internal commands: Write EEPROM                            | 15 s        |  |
| DQJ     | Internal commands: Read out manufacturer and controller ID | 15 s        |  |
| DQR     | Internal commands: Read Recovery information               | 15 s        |  |
|         |  |             |  |
| DSC     | Read Access code   | 60 s        |  |
| DSD     | Set access code  | 15 s        |  |
|         |  |             |  |

| CMD | Meaning                                      | 304.8<br>mm<br>(12") |
|-----|--|----------------------|
| Dxa | Self-test commands                           | xx s                 |
| Dya | Internal commands                            | xx s                 |
| DYR | Internal commands: Read internal statistics  | 15 s                 |
| DYS | Internal commands: Reset internal statistics | 15 s                 |

# **Appendix B: Status display codes**

## Displays in normal operation

| No. | Meaning  | Reaction  |
|-----|--|---|
| off | No power supply  | Switching the device on   |
|     | Boot up (after RESET or electronic self-test)  |   |
| bu  | burn; program controller   |   |
| C1  | compare; check controller  |   |
| Ю   | Controller OK  |   |
| 00  | No error   |   |
| 01  | Software faulty  | If possible, read hardware<br>status, switch device off/on,<br>read hardware status (field stop<br>info), download if necessary |
| 05  | Communication problem with ChipCard controller   | Check/replace lines to the ChipCard controller, ChipCard controller   |
| 06  | Communication problem with ChipCard / or wrong ChipCard inserted (ChipCard number not '226-0PR') | Check/replace ChipCard on the controller  |
| 09  | Locking handle open  | Push dispenser completely into the safe, if necessary adjust switch   |
| 10  | Controller defective or  | replace controller  |

| No. | Meaning   | Reaction   |
|-----|---|--|
| 10  | Battery empty or battery jumper not connected: only with self-test commands for battery testing | Mount battery jumper or replace battery  |
| 11  | Software is missing (download)  | Perform download   |
| 12  | Safety switch open  | Insert CMD-V4  |
| 13  | Device lock present   | Remove notes from CMD-V4; then per SW: <b>RESET lock flag</b>                                    |
| 14  | Minimum configuration of CMD-V4 not available (RR-box + at least 1 cash-out cassette)           | Insert cassettes; if necessary, determine reference values or cassette defective                 |
| 15  | Cassette board has invalid coding, is not inserted or defective                                 | Replace cassette distributor board, check cables   |
| 16  | Output transport coding invalid   | Perform coding on output transport cable connector.  |
| 17  | Belt drive of clamp defective M3 or jam   | Press the function button on the CMD controller until '01' appears on the display.               |
|     |   | Call service personnel if the error is still displayed after the RESET.                          |
| 18  | Banknote jam during dispensing  | Clear paper jam; then perform a RESET.   |
| 19  | Clamp transport defective/blocked   | Press the function button on the CMD controller until '01'                                       |
|     | VCMD: Note jam in output transport  | appears on the display.  Call service personnel if the error is still displayed after the RESET. |
| 20  | Single reject switch defective/blocked MA2/1, MA2/2, SM1  | Remove block; then RESET; if nec. replace stacker or controller                                  |
| 21  | Faulty measuring station <b>DDU</b>   | Press the function button on the CMD controller until '01' appears on the display.               |
|     |   | Call service personnel if the error is still displayed after the RESET.                          |
| 22  | Photosensor amplifier faulty or photosensor initialization not successful                       | Clear cash paths; then perform a RESET or replace controller.                                    |

| No. | Meaning  | Reaction   |
|-----|--|--|
| 23  | Routing disk defective/blocked SM2/SM3  VCMD: Note bundle reject switch defective/blocked SM6  | Press the function button on the CMD controller until '01' appears on the display. Call service personnel if the error is still displayed after the RESET. |
| 24  | Reject/reject drive defective/blocked MA6  | If necessary, replace cassette, output transport or controller.  |
| 25  | Dispensing motor <b>DCM1</b> faulty  | Replace output transport or controller.  |
| 26  | Stacker wheel drive defective/blocked <b>SM9</b> VCMD:  Comb-type lifting bar defective/blocked <b>SM5</b> Switching of dispensing/transport defective/blocked <b>M3</b> | Remove block; then RESET; if nec. replace stacker or controller  |
| 28  | Shutter error  | Eliminate error; then perform a RESET.   |
| 29  | Cash-out photosensor covered (manipulation)  | Eliminate error; then perform a RESET.   |
| 3x  | Too many problems during dispensing from cassette $x$ ( $x = 1 - 6$ )  | Check cash paths; then perform a RESET; if nec. dispense test note(s)  |
| 4x  | note dispensing from cassette x not possible (x = 1 - 6); possibly fauty note contact pressure with new cassette   | Check the contents of cassette x; RESET  |
| 5x  | too many bad notes from cassette $x$ ( $x = 1 - 6$ )   | Check the contents of cassette x; RESET  |
| 6x  | Cassette x defective (x = 1 - 6)   | Write error (cassette EEPROM) Replace cassette x, RESET; or contact pressure cannot be built up, insert CMD-V4.  |

## **Contaminated photosensors/sensors**

| No. | Meaning  | Designation |
|-----|--|-------------|
| 7x  | Dispensing sensor of cassette $x$ ( $x = 1 - 6$ ) or pressure sensor defective | PSDx        |
| 8x  | Empty sensor of cassette x (x = 1 - 6)   | PSEx        |
| 90  | Stacker wheel input  | PS 1        |
| 91  | Tray monitoring  | PS 18       |
| 93  | 'Tray empty' (single reject)   | PS 2        |
|     | VCMD: Monitoring of entrance reject box  | PS21        |
| 95  | Removal photosensor  | PS 27       |
|     | VCMD:  | PS 26       |
| 9A  | Bundle rear edge control, shutter sensor                                       | PS 28       |

**Reaction:** Clean the relevant photosensor / measurement station.

Then check the CMD-V4's operability by performing a RESET.

Appendix D - Electrical & mechanical components describes the positions of the components:

Outdoor (page 104) Indoor (page 104)

## Photosensors covered during initialization

| No. | No.   | Meaning   | Designation |
|-----|-------|---|-------------|
| Т   | T + 1 | Blink alternately, repeated several times             |             |
| L   | .Ex   | Empty sensor of cassette x (x = 1 - 2)                | PSEx        |
| L   | Ax    | Dispensing sensor of cassette x (x = 1 - 2)           | PSDx        |
| L   | Х     | Photosensor x (see contaminated Photosensors/Sensors) | PS x        |

## Displays when function button is pressed

| No. | Meaning  |
|-----|--|
| 0   | Normal operation   |
| 1   | Reset  |
| 2   | Overall test + 'RESET'   |
| 3   | Trial dispensing process + RESET (can also be configured without trial dispensing process) |
| 4   | Display firmware release number  |
| 5   | Reset statistics (the internal resettable counters are set to 0 and the date stored)       |
| 6   | In case of an open door switch and DES_CLEAR_BUTTON=Y the encryption is deactivated.       |

When the function key is pressed, the available function range is output to the status display in a loop.

See also chapter "Function pushbuttons" (page 16)

## **Booter outputs to the 7-segment display**

| T     |         | T + 1  |          | in temporal alternation                               |
|-------|---------|--------|----------|---|
| High  | Low     | High   | Low      |   |
| -     | -       |        |          | Booter indicates power-up and test of loaded FW       |
| С     | I       |        |          | Indicates CMOS deletion via jumper                    |
| b     | E       |        |          | Battery empty or battery jumper not connected         |
| i     | 0       |        |          | Display following correct CMOS clearing               |
| 1     | 1       |        |          | Booter operating without error                        |
| .1    | 1       |        |          | Alternate booter operating without error              |
| .1    | 1       | 1      | 1        | FW download (decimal points blinking)                 |
| 1     | .1      | 1      | 1        | FW download (decimal points blinking)                 |
| Error | without | uncond | ditional | break   |
| 1     | 1       | 0      | 1        | Booter CMOS invalid (inactive in booter releases from |
|       |         |        |          | 15.11.02)   |
| 1     | 1       | 0      | 2        | SCOP-CMOS invalid (inactive in booter releases from   |
|       |         |        |          | 15.11.02)   |
| 1     | 1       | 0      | 3        | Stacker EEPROM incorrectly written                    |
| 1     | 1       | 0      | 4        | FW length or CRC not OK                               |
| 1     | 1       | 0      | 5        | SCOP-Line error                                       |

| 1    | 1        | 0       | 6        | AVT error                          |
|------|----------|---------|----------|------------------------------------|
| 1    | 1        | 0       | 7        | SCOP-FW not Valid                  |
| 1    | 1        | 0       | 8        | FW name in stacker EEPROM not OK   |
| 1    | 1        | 0       | 9        | Error writing or deleting flash    |
| 1    | 1        | 1       | 2        | Program memory cells lose content  |
| 1    | 1        | 1       | 3        | SCOP jumper changed without reboot |
| Erro | r with u | ıncondi | tional b | reak                               |
| 0    | 1        |         |          | Booter defective(interrupt or NMI) |
| 0    | 1        | -       | 2        | Writing to wrong CMOS area         |
| 1    | 0        | b       | t        | Booter defective (Flash error)     |
| 1    | 0        | Е       | Е        | No stacker EEPROM connected        |
| 8    | 8        | 8       | 8        | Undefined interrupt occurred       |
| n    |          | Ν       |          | NMI                                |

# **Appendix D: Electrical and mechanical components**

#### **Electrical elements**

#### Stacker and output transport

| Component | Designation  | Location                           |
|-----------|--|------------------------------------|
| D         | Permanent magnets (3 units) – without sensors                | Clamp                              |
| DPS 1/3   | <b>VCMD:</b> Dispensing/transport switching sensor           | Stacker input                      |
| DPS 2     | Stacker wheel position query                                 | Stacker wheel input                |
| DPS 4     | Sensor: position of retract compartment                      | RR box                             |
|           | VCMD: Dispensing/transport switching                         | Stacker wheel input                |
| DPS 5     | Sensor: home position  | Routing disk drive, left           |
| DPS 6     | Sensor: home position  | Routing disk drive, right          |
| DPS 7     | Home position of sliding surface                             | Single reject                      |
| DPS 8     | Sensor: Position   | Routing disk drive, left           |
| DPS 9     | Sensor: Position   | Routing disk drive, right          |
| DPS 8 / 9 | VCMD: Sensor of comb-type lifting bar                        | Above reject box                   |
| DPS 10    | Hybrid photosensor   | Shutter                            |
| DPS 11    | Hybrid photosensor   | Shutter                            |
| DPS 14    | Home position of switch                                      | Single reject                      |
| DPS 15    | Switch position: single reject                               | Single reject                      |
| HS 1      | (Hall sensor) home position                                  | Clamp positioning                  |
| HS 2      | (Hall sensor) Initial RR position (behind the routing disk)  | Clamp positioning                  |
| HS 3      | (Hall sensor) Reversal in FL direction (if required.)        | Clamp positioning                  |
| HS 4      | (Hall sensor), 'Stop over' position and clamp final position | Clamp positioning                  |
| PS 1      | Stacker wheel input  | Stacker wheel input                |
| PS 2      | 'Tray empty' check   | Single reject                      |
| PS 18     | Tray monitoring/ input monitoring 'clamp empty'              | Swivel drive for clamp flap/RR box |
| PS 21     | VCMD: Monitoring of entrance reject box                      | RR box                             |

| Component | Designation                              | Location   |
|-----------|--|--|
| PS 26     | VCMD: Removal photosensor                | Output transport                                 |
| PS 27     | Removal photosensor                      | Clamp positioning                                |
| PS 28     | Bundle rear edge control                 | Clamp positioning                                |
| DCM 1     | Main drive motor                         | Stacker wheel input                              |
| DCM 2     | Traction motor + planetary gears         | Clamp  |
| DCM 3     | Belt drive + planetary gears             | Clamp  |
|           | VCMD: Dispensing/transport switching     | Stacker wheel input                              |
| DCM 7     | DC motor (outdoor)                       | Shutter  |
| MA 2      | Switch control magnet                    | Single reject                                    |
| MA 6      | Magnet for retract compartment           | Reject box                                       |
| SW 1      | RR box inserted                          | Reject box                                       |
| SW 2      | Safety switch                            | Slide rack                                       |
|           | VCMD: Safety switch stacker cover        | Cover plate in front of the bundle reject switch |
| SW 3      | Locking switch                           | Above reject box                                 |
|           | VCMD: second function key                | at the control panel on the chassis              |
| SW 4      | VCMD: Safety switch                      | Slide rack                                       |
| SM 1      | Pressure on sliding surface for emptying | Single reject                                    |
| SM 2      | Routing disk motor                       | Routing disk drive, left                         |
| SM 3      | Routing disk motor                       | Routing disk drive, right                        |
| SM 5      | VCMD: Comb-type lifting bar              | Stacker wheel input                              |
| SM 6      | VCMD: Bundle reject deflector            | Above reject box                                 |
| SM 7      | Stepper motor (indoor)                   | Shutter  |
| SM 9      | Stacker wheel stepper motor              | Stacker wheel input                              |
| CG 1      | Timing disk                              | on main motor DCM1                               |

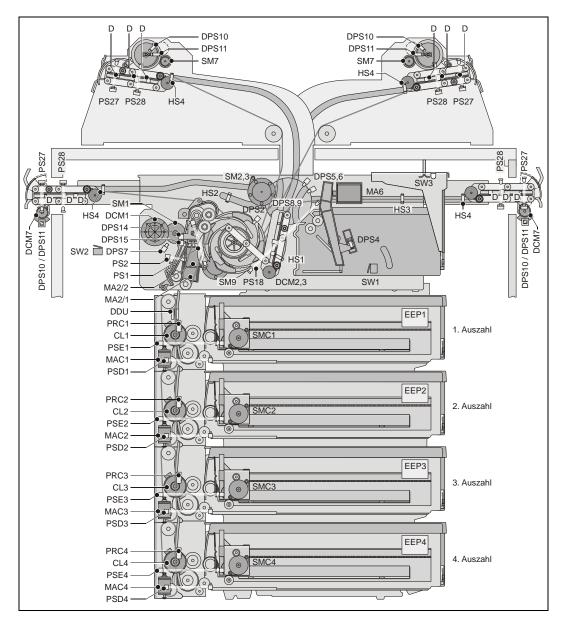
<u>Note</u>: The switch SW2 switches off the power elements for CMD-V4 and VCMD via the electronics. This is monitored by the firmware and displayed via indicator 12. As soon as the switch has been switched back the original position, the power elements are switched on and the firmware triggers a reset.

Switch SW4 at the VCMD switches off the main motor DCM1. This is not monitored by the firmware.

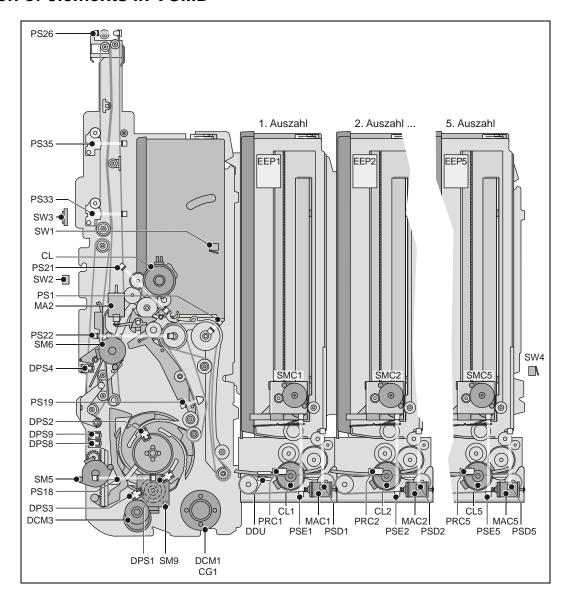
### Components of dispensing unit and cassette

| Component | Designation                           | Location                                    |
|-----------|---------------------------------------|---|
| MACx      | Retaining magnet                      | Dispensing unit; cassette x (x = 1 - 8)     |
| CLx       | Dispensing clutch                     | Dispensing unit; cassette x (x = 1 - 8)     |
| PSDx      | Dispensing sensor                     | Dispensing unit; cassette x ( $x = 1 - 8$ ) |
| PSEx      | Empty sensor                          | Dispensing unit; cassette x (x = 1 - 8)     |
| DDU       | Length measurement, measuring station | at top dispensing unit                      |
| SMCx      | Stepper motor for pressure            | in cassette x (x = $1 - 8$ )                |
| PRCx      | Pressure sensor                       | Dispensing unit; cassette x (x = 1 - 8)     |
| EEPx      | EEPROM                                | in cassette x $(x = 1 - 8)$                 |

## Position of the elements in the CMD\_V4



#### Position of elements in VCMD



# **Appendix E: Jumper settings on controller**

### Jumper field

| Designation | Jumper connected  |
|-------------|---|
| DOOR        | Observe door contact during encryption  |
| SCOP        | Activate SCOP handling (with HW extension installed)  |
| Jump A      | Standard line parameter (19200, 8, 2, ODD); Trigger RESET (subsequently removing jumper again)  |
| Jump B      | Operate 4-cassette rack as 2-cassette rack (the two lower dispensing units may not be installed when a 4-way distributor board is used) |
| Jump C      | Reserve   |
| Jump D      | Reserve   |
| CI CMOS     | Delete CMOS; trigger RESET (subsequently removing jumper again)   |
| NEN         | NEN signal is generated by the CMD-V4 (open: SE controls power-saving mode)   |
| Battery     | CMOS-support battery active   |
| Jump PLD    | Reserve input to Programmable Logic Device  |

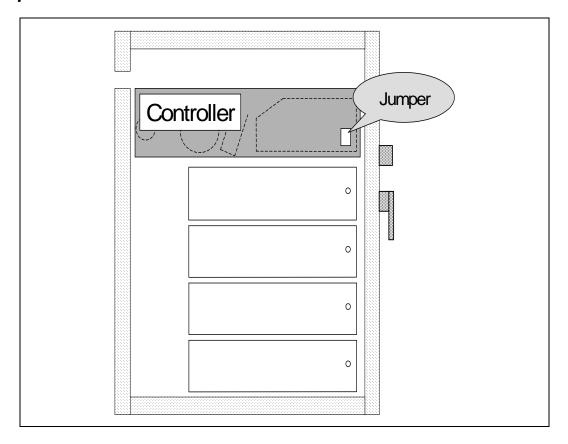
Door / SCOP should always only be selected with one jumper. If this is not the case (both jumpers connected), SCOP handling has priority over standard encryption!

The dispense amount is a component of the SCOP procedure. When the procedure is activated, the system automatically switches to the controller's standard command set.

## **Default settings**

| Jumper connected                               |
|--|
| NEN  |
| Battery  |
| Jumper connected on one side (on one PIN only) |
| DOOR (option for activating DOOR or SCOP)      |

# **Jumper positions**

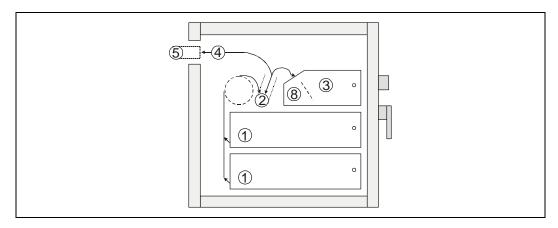


The jumper positions are labeled.

# **Appendix F: Transport positions**

#### **Outdoor**

#### Rearload

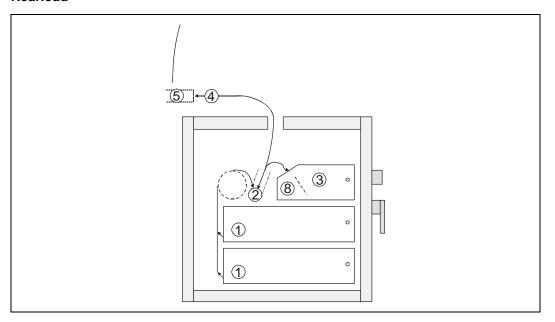


- 1 Cassette
- 2 collecting compartment
- 3 Reject

- 4 Stop over (cash-out)
- 5 Removal position
- 8 Retract

#### Indoor

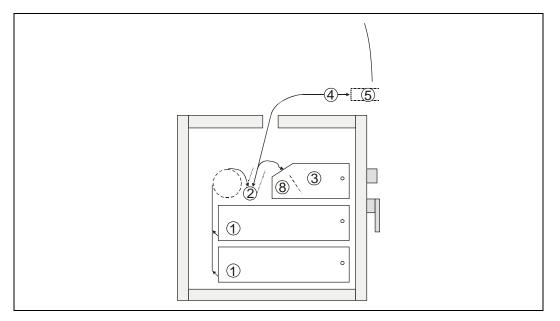
#### Rearload



- 1 Cassette
- 2 collecting compartment
- 3 Reject

- 4 Stop over (cash-out)
- 5 Removal position
- 6 Retract

#### **Frontload**



- 1 Cassette
- 2 collecting compartment
- 3 Reject

- 4 Stop over (cash-out)
- 5 Removal position
- 6 Retract

# **Appendix G: Error Number Table**

The internal 64-bit error number is returned in 128-bit (16-byte) ASCII format. The first 4 bytes represent the class which the error signaling object belongs to, the bytes 5 - 8 the object that triggered the error, bytes 9 - 12 represent the class-specific error code, and bytes 13 - 16 an optional error value for further error ascertainment. Each error is thus described uniquely and can be located in the following tables. There is not a detailed description of the optional error values since numerous values can only be interpreted by the developer. The description of the error code occasionally refers to possible optional values.

| Code                         | Class       |
|------------------------------|-------------|
| 0x <b>0000</b> XXXXXXXXXXXXX | NO_CLASS    |
| Code                         | Component   |
| 0x00000000XXXXXXXX           | NO_ID       |
| 0x0000 <b>0060</b> XXXXXXXX  | IO_TABLE    |
| 0x0000 <b>4010</b> XXXXXXXX  | KONTRON     |
| 0x0000 <b>4050</b> XXXXXXXX  | NOTE_BUNDLE |

| Code                        | Class           |   |
|-----------------------------|-----------------|---|
| 0x <b>0001</b> XXXXXXXXXXXX | COMPONENT       |   |
| Code                        | ERROR           | Meaning   |
| 0x0001XXXX <b>0010</b> XXXX | NOT_INITIALIZED | checkAllObjects() found a component, that is disabled. Special conditions prevented the components from being usable. |
| 0x0001XXXX <b>0020</b> XXXX | DOUBLE_ID       | <pre>checkAllObjects() found a component-id, that is already in use. This a programmer's error.</pre>                 |

| Code                         | Class     |
|------------------------------|-----------|
| 0x <b>0008</b> XXXXXXXXXXXXX | STATISTIC |
| Code                         | Component |
| 0x0008 <b>4030</b> XXXXXXXX  | STATISTIC |

| Code                        | Class        |
|-----------------------------|--------------|
| 0x <b>0010</b> XXXXXXXXXXXX | AD_CONVERTER |

| Code                        | Component    |
|-----------------------------|--------------|
| 0x0010 <b>1400</b> XXXXXXXX | AD_CONVERTER |

| Code                             | Class                  |   |
|----------------------------------|------------------------|---|
| 0x <b>0020</b> XXXXXXXXXXXX      | AT89S53                |   |
| Code                             | Component              |   |
| 0x0020 <b>1300</b> XXXXXXXX      | DDU_CONTROLLER_HW      |   |
| 0x0020 <b>1870</b> XXXXXXXX      | STACKER_CONTROLLER_HW  |   |
|                                  |                        |   |
| Code                             | ERROR                  | Meaning   |
| Code 0x0020XXXX <b>0010</b> XXXX | ERROR ERASE_FLSH_ERROR | Meaning flash rom could not be erased, value is 0 |
|                                  |                        | 3   |

| Code                        | Class                  |                                     |
|-----------------------------|------------------------|-------------------------------------|
| 0x <b>0030</b> XXXXXXXXXXXX | AT90S2313              |                                     |
| Code                        | Component              |                                     |
| 0x0030 <b>1800</b> XXXXXXXX | MAIN_MOTOR_HW          |                                     |
| Code                        | ERROR                  | Meaning                             |
| 0x0030XXXX <b>0010</b> XXXX | CONTROLER_OPEN_ERROR   | flash rom could not be accessed     |
| 0x0030XXXX <b>0020</b> XXXX | BURN_FW_ERROR          | error during firmware burning       |
| 0x0030XXXX <b>0030</b> XXXX | VERIFY_BURNED_FW_ERROR | error during verifying the firmware |
| 0x0030XXXX <b>0040</b> XXXX | CONTROLER_SEARCH_ERROR | controller could not be found       |

| Code                        | Class   |
|-----------------------------|---------|
| 0x <b>0035</b> XXXXXXXXXXXX | MAX7301 |

| Code                        | Class       |
|-----------------------------|-------------|
| 0x <b>0037</b> XXXXXXXXXXXX | TLE6208     |
| Code                        | Component   |
| 0x0037 <b>0102</b> XXXXXXXX | TLE6208 LED |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0040</b> XXXXXXXXXXX  | BEEPER    |
| Code                        | Component |
| 0x0040 <b>0B10</b> XXXXXXXX | BEEPER    |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0050</b> XXXXXXXXXXXX | BOOT_CMOS |

| Code                        | Class                  |   |
|-----------------------------|------------------------|---|
| 0x <b>005A</b> XXXXXXXXXXXX | BUNDLE_REJECT_FORK     |   |
| Code                        | Component              |   |
| 0x005A <b>18C0</b> XXXXXXXX | BUNDLE_REJECT_FORK     |   |
| Code                        | ERROR                  | Meaning   |
| 0x005AXXXX <b>0001</b> XXXX | INITIALIZATION_FAILED  | serious errors occurred during the initialization, position not reached (photo-sensor, motor defect, not connected or hw damaged) |
| 0x005AXXXX <b>0002</b> XXXX | DRIVE_TO_REJECT_FAILED | it was not possible to move the bundle reject fork to the reject position (photosensor, motor defect or hw damaged)               |
| 0x005AXXXX <b>0003</b> XXXX | DRIVE_TO_OUTPUT_FAILED | it was not possible to move the bundle reject fork to the output position (photosensor, motor defect or hw damaged)               |
| 0x005AXXXX <b>0004</b> XXXX | MOVE_FAILED            | the fork could not move to a desired position (photo-sensor, motor defect or hw damaged)  |
| 0x005AXXXX <b>0005</b> XXXX | MOTOR_FAILURE          | the step motor of the bundle reject fork coud not be started (hw damaged or not connected)  |
| 0x005AXXXX <b>0006</b> XXXX | SELFTEST_FAILED        | the self test failed, fork could be blocked, motor defect or hw damaged   |
| 0x005AXXXX <b>0007</b> XXXX | REJECT_TO_EDGE_JITTER  | the step-differences during the self test<br>between two reject-to-edge measurements<br>were greater than MAX_STEP_JITTER         |
| 0x005AXXXX <b>0008</b> XXXX | OUTPUT_AREA_JITTER     | the step-differences during the self test<br>between two output area measurements were<br>greater than MAX_STEP_JITTER            |
| 0x005AXXXX <b>0009</b> XXXX | REJECT_AREA_JITTER     | the step-differences during the self test<br>between two reject area measurements were<br>greater than MAX_STEP_JITTER            |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0060</b> XXXXXXXXXXXX | BUTTON    |
| Code                        | Component |
| 0x0060 <b>0B00</b> XXXXXXXX | BUTTON    |

| Code                        | Class                         | ]   |
|-----------------------------|-------------------------------|---|
| 0x <b>0070</b> XXXXXXXXXXXX | CASSETTE                      |   |
| Code                        | Component                     | 1   |
| 0x0070 <b>1710</b> XXXXXXXX | CASSETTE_1                    |   |
| 0x0070 <b>1720</b> XXXXXXXX | CASSETTE_2                    |   |
| 0x0070 <b>1730</b> XXXXXXXX | CASSETTE_3                    |   |
| 0x0070 <b>1740</b> XXXXXXXX | CASSETTE_4                    |   |
| 0x0070 <b>1750</b> XXXXXXXX | CASSETTE_5                    |   |
| 0x0070 <b>1760</b> XXXXXXXX | CASSETTE_6                    |   |
| 0x0070 <b>1770</b> XXXXXXXX | CASSETTE_7                    |   |
| 0x0070 <b>1780</b> XXXXXXXX | CASSETTE_8                    |   |
| Code                        | ERROR                         | Meaning   |
| 0x0070XXXX <b>0010</b> XXXX | OUT_CONTEXT_ERROR             | dispense is refused due to invalid state (EMPTY or MISSING stored in value) State                   |
| 0x0070XXXX <b>0030</b> XXXX | DOUBLE_NOTES                  | too many multiple notes, value holds number of dispense-retries                                     |
| 0x0070XXXX <b>0040</b> XXXX | INVALID_NOTES                 | too many invalid notes, value holds number of dispense-retries                                      |
| 0x0070XXXX <b>0050</b> XXXX | EMPTY_ERROR                   | cassette become empty during dispense, value is 0   |
| 0x0070XXXX <b>0060</b> XXXX | EMPTY_ERROR_INT               | same circumstances like EMPTY_ERROR   |
| 0x0070XXXX <b>0065</b> XXXX | NO_INT_RESPONSE               | no response from interrupt, internal FW-error value is 0  |
| 0x0070XXXX <b>0070</b> XXXX | NO_DISPENSE_ERROR             | no note could be dispensed, value holds number of dispense-retries                                  |
| 0x0070XXXX <b>0090</b> XXXX | NOTE_STUCK_ERROR              | note did note leave the dispense-sensor within a certain time, so it looks like a jam, value is 0   |
| 0x0070XXXX <b>00A0</b> XXXX | BAD_NOTE_ERROR                | a very short note must be invalid, value is 0   |
| 0x0070XXXX <b>00B0</b> XXXX | IS_EMPTY_ERROR                | <pre>photo-sensor error in empty-check, internal<br/>FW-error, value holds bool isEmpty()=0/1</pre> |
| 0x0070XXXX <b>00C0</b> XXXX | CHECK_EEPROM_ERROR            | error when reading eeprom-data occurred, value holds number of read-cycles                          |
| 0x0070XXXX <b>00D0</b> XXXX | PRINT_TIMEOUT                 | the receipt to be printed was not available in time   |
| 0x0070XXXX <b>00E0</b> XXXX | TRANSPORT_LOCK                | dispense is stopped by a transport-lock ( unexpected note PS19 or PS27 )                            |
| 0x0070XXXX <b>00F0</b> XXXX | SAFETY_SWITCH_DURING_DISPENSE | open safety-switch detected during dispense   |
| 0x0070XXXX <b>0100</b> XXXX | EEPROM_DEFECT                 | eeprom defect   |

| Code                        | Class               |   |
|-----------------------------|---------------------|---|
| 0x <b>0075</b> XXXXXXXXXXXX | CASSETTE_EEPROM     |   |
| Code                        | Component           |   |
| 0x0075 <b>0E10</b> XXXXXXXX | EEPROM_CASSETTE_1   |   |
| 0x0075 <b>0E20</b> XXXXXXXX | EEPROM_CASSETTE_2   |   |
| 0x0075 <b>0E30</b> XXXXXXXX | EEPROM_CASSETTE_3   |   |
| 0x0075 <b>0E40</b> XXXXXXXX | EEPROM_CASSETTE_4   |   |
| 0x0075 <b>0E50</b> XXXXXXXX | EEPROM_CASSETTE_5   |   |
| 0x0075 <b>0E60</b> XXXXXXXX | EEPROM_CASSETTE_6   |   |
| 0x0075 <b>0E70</b> XXXXXXXX | EEPROM_CASSETTE_7   |   |
| 0x0075 <b>0E80</b> XXXXXXXX | EEPROM_CASSETTE_8   |   |
| Code                        | ERROR               | Meaning                                       |
| 0x0075XXXX <b>0010</b> XXXX | READ_VERSION_ERROR  | read error during reading the version number  |
| 0x0075XXXX <b>0020</b> XXXX | CHECKSUM_ERROR      | error during checking the checksum            |
| 0x0075XXXX <b>0030</b> XXXX | WRONG_VERSION       | version number is invalid                     |
| 0x0075XXXX <b>0040</b> XXXX | WRITE_VERSION_ERROR | write error during writing the version number |
| 0x0075XXXX <b>0050</b> XXXX | EEPROM_ERASED       | the eeprom has been erased                    |

| Code                        | Class                        |   |
|-----------------------------|------------------------------|---|
| 0x <b>0080</b> XXXXXXXXXXXX | CIRCLE_FORK                  |   |
| Code                        | Component                    |   |
| 0x0080 <b>1920</b> XXXXXXXX | CIRCLE_FORK                  |   |
| Code                        | ERROR                        | Meaning   |
| 0x0080XXXX <b>0010</b> XXXX | NO_INITIAL_EDGE              | an initial edge was not found. Value is always 0                                  |
| 0x0080XXXX <b>0020</b> XXXX | NO_SEPARATE_EDGE             | a separate edge was not found. Value holds stepperIdx (0/1)                       |
| 0x0080XXXX <b>0030</b> XXXX | NO_FINE_TUNE_EDGE            | the edge for fine tuning was not found. Value holds stepperIdx (0/1)              |
| 0x0080XXXX <b>0040</b> XXXX | NO_FINE_TUNE_EDGE_DARK_LIGHT | a dark/light change was not found. Value holds stepperIdx (0/1)                   |
| 0x0080XXXX <b>0050</b> XXXX | AUTO_CORRECT_NOT_POSSIBLE    | an automatic correction of the position is not possible. Value holds the position |
| 0x0080XXXX <b>0060</b> XXXX | CHECK_POSITION_ERROR         | a check of the position is not possible.<br>Value holds the position              |
| 0x0080XXXX <b>0070</b> XXXX | INIT_NOT_POSSIBLE            | initialization was unsuccessful   |

| Code                        | Class                               |   |
|-----------------------------|-------------------------------------|---|
| 0x <b>0090</b> XXXXXXXXXXXX | CLAMP                               |   |
| Code                        | Component                           |   |
| 0x0090 <b>1930</b> XXXXXXXX | CLAMP                               |   |
| Code                        | ERROR                               | Meaning   |
| 0x0090XXXX <b>0010</b> XXXX | UNEXPECTED_SENSOR                   | an unexpected sensor was found. Value holds the unexpected position                       |
| 0x0090XXXX <b>0020</b> XXXX | NO_SENSOR_OR_JAM                    | next sensor not found in time, jam<br>possible. Value holds the target position           |
| 0x0090XXXX <b>0030</b> XXXX | NO_2 <sup>ND</sup> _EDGE            | the second edge was not found in time.<br>Value holds the target position                 |
| 0x0090XXXX <b>0040</b> XXXX | NO_3 <sup>RD</sup> _EDGE            | the third edge was not found in time. Value holds the target position                     |
| 0x0090XXXX <b>0050</b> XXXX | UNDEFINIED_SENSOR_EDGE_STATE        | undefined sensor edge state   |
| 0x0090XXXX <b>0060</b> XXXX | STACKER_RECOVERY_ERROR              | clamp cannot unlock after recovery  |
| 0x0090XXXX <b>0070</b> XXXX | ADD_TIME_REACHED                    | max. additional time for unlock clamp reached   |
| 0x0090XXXX <b>0100</b> XXXX | SB_CLAMP_START_ERROR                | cannot find the clamp in backward direction, because of an error while starting the clamp |
| 0x0090XXXX <b>0110</b> XXXX | SB_UNDEFINIED_SENSOR_EDGE_STAT<br>E | undefinied sensor edge state by backward-<br>searching for the clamp                      |
| 0x0090XXXX <b>0200</b> XXXX | SF_CLAMP_START_ERROR                | cannot find the clamp in forward direction, because of an error while starting the clamp  |
| 0x0090XXXX <b>0210</b> XXXX | SF_UNDEFINIED_SENSOR_EDGE_STAT<br>E | undefinied sensor edge state by forward-<br>searching for the clamp                       |

| Code                        | Class             |
|-----------------------------|-------------------|
| 0x <b>00A0</b> XXXXXXXXXXXX | CLUTCH            |
| Code                        | Component         |
| 0x00A0 <b>0590</b> XXXXXXXX | CLUTCH_REJECT_BOX |
| 0x00A0 <b>0C10</b> XXXXXXXX | CLUTCH_CASSETTE_1 |
| 0x00A0 <b>0C20</b> XXXXXXXX | CLUTCH_CASSETTE_2 |
| 0x00A0 <b>0C30</b> XXXXXXXX | CLUTCH_CASSETTE_3 |
| 0x00A0 <b>0C40</b> XXXXXXXX | CLUTCH_CASSETTE_4 |
| 0x00A0 <b>0C50</b> XXXXXXXX | CLUTCH_CASSETTE_5 |
| 0x00A0 <b>0C60</b> XXXXXXXX | CLUTCH_CASSETTE_6 |
| 0x00A0 <b>0C70</b> XXXXXXXX | CLUTCH_CASSETTE_7 |
| 0x00A0 <b>0C80</b> XXXXXXXX | CLUTCH_CASSETTE_8 |

| Code                        | Class |
|-----------------------------|-------|
| 0x <b>00B0</b> XXXXXXXXXXXX | CMD   |

| Code                        | Class      |                                |
|-----------------------------|------------|--------------------------------|
| 0x00C0XXXXXXXXXXXXX         | CMOS       |                                |
| Code                        | ERROR      | Meaning                        |
| 0x00C0XXXX <b>0010</b> XXXX | CMOS_RESET | content invalid or new version |

| Code                        | Class                                 |   |
|-----------------------------|---------------------------------------|---|
| 0x00E0XXXXXXXXXXXXX         | COLLECTOR                             |   |
| Code                        | Component                             |   |
| 0x00E0 <b>1960</b> XXXXXXXX | COLLECTOR                             |   |
| Code                        | ERROR                                 | Meaning   |
| 0x00E0XXXX <b>0001</b> XXXX | DISABLED                              | component not in use due to hw-error  |
| 0x00E0XXXX <b>0010</b> XXXX | INVALID_NOTE                          | invalid note in stacker   |
| 0x00E0XXXX <b>0020</b> XXXX | START_COLLECT_ERROR                   | most probably a belt motor error  |
| 0x00E0XXXX <b>0021</b> XXXX | STOP_COLLECT_ERROR                    | most probably a belt motor error  |
| 0x00E0XXXX <b>0030</b> XXXX | TRANSPORT_IN_BOX_LIGHT_JAM            | <pre>photo-sensor did not become covered in<br/>reject/retract</pre>                      |
| 0x00E0XXXX <b>0031</b> XXXX | TRANSPORT_IN_BOX_DARK_JAM             | <pre>photo-sensor did not become free in<br/>reject/retract</pre>                         |
| 0x00E0XXXX <b>0033</b> XXXX | UNEXPECTED_NOTE_IN_REJECT_<br>RETRACT | an unexpected note appeared in the dispense-transport during reject/retract               |
| 0x00E0XXXX <b>0035</b> XXXX | CLEAR_SINGLE_REJECT_DARK_JAM          | photo-sensor did not become free in clearing singlereject tray                            |
| 0x00E0XXXX <b>0036</b> XXXX | CLEAR_SINGLE_REJECT_LIGHT_JAM         | photo-sensor did not become covered in clearing singlereject tray                         |
| 0x00E0XXXX <b>0040</b> XXXX | SWITCH_RR_BOX_ERROR                   | magnet did not switch, value is desired direction   |
| 0x00E0XXXX <b>0045</b> XXXX | SWITCH_RR_BOX_REJECT_POS_ERROR        | magnet did not switch tray in reject position   |
| 0x00E0XXXX <b>0050</b> XXXX | TRANSPORT_IN_BOX_ERROR                | transport in box failed, e.g. belt motor error  |
| 0x00E0XXXX <b>0060</b> XXXX | FORK_ERROR                            | fork not off in clearing of singlereject tray   |
| 0x00E0XXXX <b>0062</b> XXXX | FORK_NOT_OFF                          | fork is not off, although switched off  |
| 0x00E0XXXX <b>0064</b> XXXX | FORK_NOT_ON                           | fork is not on, although switched on  |
| 0x00E0XXXX <b>0080</b> XXXX | CLEAR_SINGLE_REJECT_ERROR             | error in clearing singlereject tray, e.g. motor failure                                   |
| 0x00E0XXXX <b>0090</b> XXXX | CLAMP_EMPTY_ERROR                     | <pre>internal fw-error, call of isClampEmpty() failed, photo-sensors not accessible</pre> |
| 0x00E0XXXX <b>00A0</b> XXXX | COLLECTOR_INIT_ERROR                  | the initialization failed, the stacker or the reject box might be damaged                 |

| Code                         | Class            |
|------------------------------|------------------|
| 0x <b>00E2</b> XXXXXXXXXXXXX | COLLECTOR_EEPROM |
| Code                         | Component        |
| 0x00E2 <b>0E90</b> XXXXXXXX  | COLLECTOR EEPROM |

| Code                        | ERROR               | Meaning                                       |
|-----------------------------|---------------------|---|
| 0x00E2XXXX <b>0010</b> XXXX | READ_VERSION_ERROR  | read error during reading the version number  |
| 0x00E2XXXX <b>0020</b> XXXX | CHECKSUM_ERROR      | error during checking the checksum            |
| 0x00E2XXXX <b>0030</b> XXXX | WRONG_VERSION       | version number is invalid                     |
| 0x00E2XXXX <b>0040</b> XXXX | WRITE_VERSION_ERROR | write error during writing the version number |
| 0x00E2XXXX <b>0050</b> XXXX | EEPROM_ERASED       | the eeprom has been erased                    |
| 0x00E2XXXX <b>0060</b> XXXX | INIT_ERROR          | write error during init sequence              |

| Code                        | Class                                 | 1   |  |
|-----------------------------|---------------------------------------|---|--|
| 0x <b>00E8</b> XXXXXXXXXXXX | COLLECTOR_HDM                         |   |  |
| Code                        | Component                             |   |  |
| 0x00E8 <b>1968</b> XXXXXXXX | COLLECTOR_HDM                         |   |  |
| Code                        | ERROR                                 | Meaning   |  |
| 0x00E8XXXX <b>0001</b> XXXX | DISABLED                              | component not in use due to hw-error  |  |
| 0x00E8XXXX <b>0002</b> XXXX | PHOTO_SENSORS_FAILED                  | Photo sensor task failed, no photo sensor access/release (hardware broken?)               |  |
| 0x00E8XXXX <b>0010</b> XXXX | INVALID_NOTE                          | invalid note in stacker   |  |
| 0x00E8XXXX <b>0011</b> XXXX | NOTE_JAM                              | Bundle could not be moved into reject box, possible note or photo sensor jam              |  |
| 0x00E8XXXX <b>0020</b> XXXX | START_COLLECT_ERROR                   | most probably a belt motor error  |  |
| 0x00E8XXXX <b>0021</b> XXXX | STOP_COLLECT_ERROR                    | most probably a belt motor error  |  |
| 0x00E8XXXX <b>0025</b> XXXX | MAIN_MOTOR_FAILED                     | Main motor could not be started, hardware broken?   |  |
| 0x00E8XXXX <b>0030</b> XXXX | TRANSPORT_IN_BOX_LIGHT_JAM            | <pre>photo-sensor did not become covered in<br/>reject/retract</pre>                      |  |
| 0x00E8XXXX <b>0031</b> XXXX | TRANSPORT_IN_BOX_DARK_JAM             | <pre>photo-sensor did not become free in<br/>reject/retract</pre>                         |  |
| 0x00E8XXXX <b>0033</b> XXXX | UNEXPECTED_NOTE_IN_REJECT_<br>RETRACT | an unexpected note appeared in the dispense-transport during reject/retract               |  |
| 0x00E8XXXX <b>0035</b> XXXX | CLEAR_SINGLE_REJECT_DARK_JAM          | photo-sensor did not become free in clearing singlereject tray                            |  |
| 0x00E8XXXX <b>0036</b> XXXX | CLEAR_SINGLE_REJECT_LIGHT_JAM         | photo-sensor did not become covered in clearing singlereject tray                         |  |
| 0x00E8XXXX <b>0040</b> XXXX | SWITCH_RR_BOX_ERROR                   | magnet did not switch, value is desired direction   |  |
| 0x00E8XXXX <b>0050</b> XXXX | TRANSPORT_IN_BOX_ERROR                | transport in box failed, e.g. belt motor error  |  |
| 0x00E8XXXX <b>0060</b> XXXX | FORK_ERROR                            | fork not off in clearing of singlereject tray   |  |
| 0x00E8XXXX <b>0062</b> XXXX | FORK_NOT_OFF                          | fork is not off, although switched off  |  |
| 0x00E8XXXX <b>0064</b> XXXX | FORK_NOT_ON                           | fork is not on, although switched on  |  |
| 0x00E8XXXX <b>0080</b> XXXX | CLEAR_SINGLE_REJECT_ERROR             | error in clearing singlereject tray, e.g. motor failure                                   |  |
| 0x00E8XXXX <b>0090</b> XXXX | CLAMP_EMPTY_ERROR                     | <pre>internal fw-error, call of isClampEmpty() failed, photo-sensors not accessible</pre> |  |

| 0x00E8XXXX <b>00A0</b> XXXX | COLLECTOR_INIT_ERROR                     | the initialization failed, the stacker or the reject box might be damaged |
|-----------------------------|--|---|
| 0x00E8XXXX <b>00B0</b> XXXX | CONTROLGEAR_DISPENSE_POS_NOT_<br>REACHED | control-gear cannot reach dispense-position                               |

| Code                        | Class                |   |
|-----------------------------|----------------------|---|
| 0x <b>00EA</b> XXXXXXXXXXXX | COLLECTOR_SLIM_CASH  |   |
| Code                        | Component            |   |
| 0x00EA <b>196A</b> XXXXXXXX | COLLECTOR_SLIM_CASH  |   |
| Code                        | ERROR                | Meaning   |
| 0x00EAXXXX <b>0001</b> XXXX | DISABLED             | component not in use due to hw-error  |
| 0x00EAXXXX <b>0002</b> XXXX | PHOTO_SENSORS_FAILED | Photo sensor task failed, no photo sensor access/release (hardware broken?) |
| 0x00EAXXXX <b>0010</b> XXXX | INVALID_NOTE         | Invalid or unexpected note in output direction                              |
| 0x00EAXXXX <b>0011</b> XXXX | NOTE_JAM             | Note could not move to target position, possible note or photo sensor jam   |
| 0x00EAXXXX <b>0020</b> XXXX | START_COLLECT_ERROR  | not used  |
| 0x00EAXXXX <b>0021</b> XXXX | STOP_COLLECT_ERROR   | not used  |
| 0x00EAXXXX <b>0025</b> XXXX | MAIN_MOTOR_FAILED    | Main motor could not be started, hardware broken?                           |
| 0x00EAXXXX <b>0060</b> XXXX | FORK_ERROR           | not used  |
| 0x00EAXXXX <b>0062</b> XXXX | FORK_NOT_OFF         | fork is not off, although switched off                                      |
| 0x00EAXXXX <b>0064</b> XXXX | FORK_NOT_ON          | fork is not on, although switched on  |
| 0x00EAXXXX <b>00A0</b> XXXX | COLLECTOR_INIT_ERROR | the initialization failed, the stacker or the reject box might be damaged   |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>00F0</b> XXXXXXXXXXXX | CODEC_IBM |
| Code                        | Component |
| 0x00F0 <b>0310</b> XXXXXXXX | CODEC_IBM |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>00F8</b> XXXXXXXXXXXX | CODEC_NCR |
| Code                        | Component |
| 0x00F8 <b>0350</b> XXXXXXXX | CODEC_NCR |

| Code                        | Class        |
|-----------------------------|--------------|
| 0x <b>0100</b> XXXXXXXXXXXX | CODEC_WINCOR |
| Code                        | Component    |
| 0x0100 <b>0300</b> XXXXXXXX | CODEC_WINCOR |

| Code                        | Class         |
|-----------------------------|---------------|
| 0x <b>0110</b> XXXXXXXXXXXX | CODEC_SERVICE |
| Code                        | Component     |
| 0x0110 <b>0330</b> XXXXXXXX | CODEC_SERVICE |

Class

|                             | the state of the s |   |
|-----------------------------|--|---|
| 0x <b>0120</b> XXXXXXXXXXX  | CODEC_SELF_TEST (old<br>CODEC_TEST)  |   |
| 0x <b>0128</b> XXXXXXXXXXXX | (old) CODEC_SELF_TEST  |   |
| Code                        | Component  |   |
| 0x0120 <b>0340</b> XXXXXXXX | CODEC_SELFTEST   |   |
| 0x0128 <b>0340</b> XXXXXXXX | CODEC_SELFTEST   |   |
| Code                        | ERROR  | Meaning   |
| 0x0120XXXX <b>0000</b> XXXX | NO_ERROR   | no error  |
| 0x0120XXXX <b>0001</b> XXXX | SELFTEST_COMMAND_UNKNOWN   | command decode error in class CodecWincor                         |
| 0x0120XXXX <b>0002</b> XXXX | COMMAND_RESULT_UNEQUAL   | hardware task result differs form selftest result                 |
| 0x0120XXXX <b>0003</b> XXXX | OPEN_SECURITY_SWITCH   | security switch is open   |
| 0x0120XXXX <b>0004</b> XXXX | RTC_TIME_INVALID   | result of time is zero (rtos.getTimeSince(startTime))             |
| 0x0120XXXX <b>0010</b> XXXX | PHOTO_SENSOR_INIT_FAILED   | photo sensor init failed  |
| 0x0120XXXX <b>0011</b> XXXX | CMOS_BATTERY_EMPTY   | cmos battery is empty or jumper not installed                     |
| 0x0120XXXX <b>0020</b> XXXX | CMOS_CLEAR_BASE  | free, not used  |
| 0x0120XXXX <b>0021</b> XXXX | CMOS_CLEAR_FAILED  | cmos write/read failed  |
| 0x0120XXXX <b>0022</b> XXXX | NO_RESET_AFTER_CMOS_CLEAR  | after cmos clear reset is the only executable command             |
| 0x0120XXXX <b>0040</b> XXXX | RR_BOX_MAGNET_BASE   | free, not used  |
| 0x0120XXXX <b>0041</b> XXXX | RR_BOX_MAGNET_NOT_OFF  | RR_BOX magnet (MA6) switched off but not in reject (GL4) position |
| 0x0120XXXX <b>0042</b> XXXX | RR_BOX_MAGNET_NOT_ON   | RR_BOX magnet (MA6) switched on but not in retract (GL4) position |
| 0x0120XXXX <b>0043</b> XXXX | RR_BOX_MAGNET_ON_TIMEOUT   | RR_BOX magnet (MA6) switched on time out of range                 |
| 0x0120XXXX <b>0044</b> XXXX | RR_BOX_MAGNET_OFF_TIMEOUT  | RR_BOX magnet (MA6) switched off time out of range                |
| 0x0120XXXX <b>0060</b> XXXX | SINGLE_REJECT_MAGNET_BASE  | free, not used  |

Code

| 0x0120XXXX0061XXXX SINGLE_REJECT_MAGNET_NOT_ON single reject magnet (MA2) switched on but 0x0120XXXX0063XXXX TIMBOUT TIMBOUT 0x0120XXXX0065XXXX SINGLE_REJECT_MAGNET_ON_ 0x0120XXXX0065XXXX SINGLE_REJECT_MAGNET_OF_ TIMBOUT T | П                           | CINCIE DETECT MACNET NOT         | simple maint mannet (MAC) suitabad aff but  |
|--|-----------------------------|----------------------------------|---|
| DATE TO THE DOCUMENT OF THE DO | 0x0120XXXX <b>0061</b> XXXX | SINGLE_REJECT_MAGNET_NOT_<br>OFF | _   |
| Oxto 120XXXX0064XXXX SINGLE_REJECT_MAGNET_OFF_ SINGLE_REJECT_MAGNET_OFF_ SINGLE_REJECT_MO_HM_SWITCH_OFF SINGLE_REJECT_MO_HM_SWITCH_OFF SINGLE_REJECT_MO_HM_SWITCH_OFF SINGLE_REJECT_MW_SWITCH_TIME_ 0x0120XXXX0066XXXX SINGLE_REJECT_HW_SWITCH_TIME_ 0x0120XXXX0100XXXX CLAMP_BELT_MOTOR_BASE Free, not used 0x0120XXXX0200XXXX MAIN_MOTOR_BASE SINGLE_REJECT_MO_HM_SWITCH_OFF SINGLE_REJECT_HW_SWITCH_TIME_ 0x0120XXXX0200XXXX CLAMP_BELT_MOTOR_STATE Clamp_Belt_motor (M3) state received while running 0x0120XXXX0200XXXX MAIN_MOTOR_SPEED_SLOW_STATE main motor (M1) state at speed slow check 0x0120XXXX0200XXXX MAIN_MOTOR_SPEED_SLOW_TO_SLOW_ TRAILED 0x0120XXXX0204XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_MOTOR_SPEED_SLOW_TO_SLOW 0x0120XXXX0204XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_REJECT_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_REJECT_MOTOR_SPEED_SLOW_TO_FAST SINGLE_REJECT_MW_SWITCH_OFF SINGLE_REJECT_MW_ | 0x0120XXXX <b>0062</b> XXXX | SINGLE_REJECT_MAGNET_NOT_ON      |   |
| time out of range  0x0120XXXX0065XXXX SINGLE_REJECT_NO_HM_SWITCH_OFF by hardware  0x0120XXXX0100XXXX ERR 0x0120XXXX0100XXXX CLAMP_BELT_MOTOR_BASE free, not used 0x0120XXXX010XXXX CLAMP_BELT_MOTOR_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SLOW 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SAND 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SAND 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SAND 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SAND 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SAND 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_JITTER 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_JITTER 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_STATE 0x0120XXXX020XXXX MAIN_MOTOR_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_SPEED_MOTO_MOTO_MOTO_MOTO_MOTO_MOTO_MOTO_MOT  | 0x0120XXXX <b>0063</b> XXXX |                                  |   |
| Ox0120XXXX0066XXXX SINGLE_REJECT_HW_SWITCH_TIME_ single reject magnet (MA2) switched off by hardware but not in time limit ox0120XXXX0100XXXX CLAMP_BELT_MOTOR_BASE free, not used can be supported by the control ox support ox0120XXXX0200XXXX MAIN_MOTOR_SASE free, not used can be supported by the control ox0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_STATE main motor (M1) state at speed slow check main motor (M1) speed up at slow speed failed main motor (M1) speed check speed slow to slow support from the control ox0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SLOW main motor (M1) speed check speed slow to slow support failed from the control ox0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SLOW main motor (M1) speed check speed slow to slow support failed from the control ox0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST main motor (M1) speed check speed slow to fast support failed from the control ox0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_JITTER main motor (M1) speed check speed slow to slow speed failed support failed f | 0x0120XXXX <b>0064</b> XXXX |                                  | time out of range                           |
| OX0120XXXXX0100XXXX  | 0x0120XXXX <b>0065</b> XXXX | SINGLE_REJECT_NO_HW_SWITCH_OFF   |   |
| Ox0120XXXX0200XXXX  CLAMP_BELT_MOTOR_STATE  running  free, not used  0x0120XXXX0200XXXX  MAIN_MOTOR_BASE  free, not used  0x0120XXXX0202XXXX  MAIN_MOTOR_SPEED_SLOW_STATE  main motor (M1) state at speed slow check  0x0120XXXX0203XXXX  MAIN_MOTOR_SPEED_SLOW_TO_SLOW  failed  0x0120XXXX0204XXXX  MAIN_MOTOR_SPEED_SLOW_TO_FAST  failed  0x0120XXXX0204XXXX  MAIN_MOTOR_SPEED_SLOW_TO_FAST  fast  0x0120XXXX0205XXXX  MAIN_MOTOR_SPEED_SLOW_JITTER  jitter  0x0120XXXX0206XXXX  MAIN_MOTOR_SPEED_SLOWDOWN_ SLOW_FAILED  0x0120XXXX0208XXXX  MAIN_MOTOR_SPEED_MEDIUM_STATE  main motor (M1) speed check speed slow to fast  failed  0x0120XXXX0208XXXX  MAIN_MOTOR_SPEED_MEDIUM_STATE  main motor (M1) speed slow down at slow speed failed  0x0120XXXX0208XXXX  MAIN_MOTOR_SPEED_MEDIUM_TO_ FAILED  0x0120XXXX0209XXXX  MAIN_MOTOR_SPEED_MEDIUM_TO_ SLOW  MAIN_MOTOR_SPEED_MEDIUM_JITTER  inain motor (M1) speed check speed medium to fast speed failed  0x0120XXXX0210XXXX  MAIN_MOTOR_SPEED_MEDIUM_TO_ MAIN_MOTOR_SPEED_MEDIUM_TO_ SLOW  MAIN_MOTOR_SPEED_MEDIUM_TO_ MAIN_MOTOR_SPEED_MEDIUM_TO_ MAIN_MOTOR_SPEED_MEDIUM_TO_ SLOW  MAIN_MOTOR_SPEED_MEDIUM_JITTER  inain motor (M1) speed check speed medium  speed failed  0x0120XXXX0212XXXX  MAIN_MOTOR_SPEED_FAST_STATE  main motor (M1) speed slow down at medium  speed failed  0x0120XXXX0215XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  fast  fast  0x0120XXXX0216XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  fast  main motor (M1) speed check speed fast to fast  fast  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  fast  main motor (M1) speed check speed fast to fast  fast  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  fast  main motor (M1) speed check speed fast to fast  fast  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  main motor (M1) speed check speed fast to fast  fast  main motor (M1) | 0x0120XXXX <b>0066</b> XXXX |                                  |   |
| Ox0120XXXX020XXXX MAIN_MOTOR_BASE free, not used  0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_STATE main motor (M1) state at speed slow check  0x0120XXXX020XXXX MAIN_MOTOR_SPEED_SLOW_TO_SLOW failed 0x0120XXXX0203XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST failed 0x0120XXXX0204XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST failed 0x0120XXXX0205XXXX MAIN_MOTOR_SPEED_SLOW_JITTER flated 0x0120XXXX0206XXXX MAIN_MOTOR_SPEED_SLOW_DITTER flated 0x0120XXXX0206XXXX MAIN_MOTOR_SPEED_SLOWDOWN_ speed failed 0x0120XXXX0206XXXX MAIN_MOTOR_SPEED_MEDIUM_STATE main motor (M1) speed slow down at slow speed failed 0x0120XXXX0208XXXX MAIN_MOTOR_SPEED_MEDIUM_STATE main motor (M1) speed up at medium speed failed 0x0120XXXX0209XXXX MAIN_MOTOR_SPEED_MEDIUM_TO_ slow failed 0x0120XXXX0210XXXX MAIN_MOTOR_SPEED_MEDIUM_TO_ slow failed 0x0120XXXX0210XXXX MAIN_MOTOR_SPEED_MEDIUM_TO_ fast 0x0120XXXX0210XXXX MAIN_MOTOR_SPEED_MEDIUM_UTTER fister 0x0120XXXX0211XXXX MAIN_MOTOR_SPEED_MEDIUM_JITTER fast 0x0120XXXX0211XXXX MAIN_MOTOR_SPEED_MEDIUM_JITTER fast 0x0120XXXX0211XXXX MAIN_MOTOR_SPEED_FAST_STATE main motor (M1) speed check speed medium to speed failed 0x0120XXXX0213XXXX MAIN_MOTOR_SPEED_FAST_STATE main motor (M1) speed slow down at medium speed failed 0x0120XXXX0215XXXX MAIN_MOTOR_SPEED_FAST_STATE main motor (M1) speed check speed fast to slow speed failed 0x0120XXXX0215XXXX MAIN_MOTOR_SPEED_FAST_TO_SLOW main motor (M1) speed check speed fast to fast 0x0120XXXX0216XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast 0x0120XXXX0216XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast 0x0120XXXX0216XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast main motor (M1) speed check speed fast to fast 0x0120XXXX0218XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast main motor (M1) speed check speed fast to fast 0x0120XXXX0218XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast main motor (M1) speed check speed fast to fast 0x0120XXXX0218XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast main motor (M1) speed check speed fast to fast 0x0120XXXX0218XXXX MAIN_MOTOR_SPEED_FAST_JITTER fast main motor (M1) speed check speed fast to fast 0x0120XXXX0218XXXX MA | 0x0120XXXX <b>0100</b> XXXX | CLAMP_BELT_MOTOR_BASE            | free, not used                              |
| 0x0120XXXX0201XXXX   | 0x0120XXXX <b>0101</b> XXXX | CLAMP_BELT_MOTOR_STATE           | <u> </u>                                    |
| 0x0120XXXX0202XXXX   | 0x0120XXXX <b>0200</b> XXXX | MAIN_MOTOR_BASE                  | free, not used                              |
| SANDED   FAILED   Failed   Salow   S   | 0x0120XXXX <b>0201</b> XXXX | MAIN_MOTOR_SPEED_SLOW_STATE      | main motor (M1) state at speed slow check   |
| 0x0120XXXX0204XXXX MAIN_MOTOR_SPEED_SLOW_TO_FAST fast fast main motor (M1) speed check speed slow to fast speed failed speed fast check speed slow to fast main motor (M1) speed check speed slow to fast speed failed speed fast check speed slow jitter main motor (M1) speed check speed slow jitter speed failed speed failed speed failed speed failed speed failed speed failed speed fast check speed medium check fast speed failed speed check speed medium check speed slow failed speed failed speed check speed medium speed failed speed check speed medium to slow slow slow slow slow slow slow slo   | 0x0120XXXX <b>0202</b> XXXX |                                  |   |
| 0x0120XXXX0205XXXX MAIN_MOTOR_SPEED_SLOW_JITTER jitter main motor (M1) speed check speed slow speed failed main motor (M1) speed check speed medium to slow slow main motor (M1) speed check speed medium to slow slow and motor (M2) speed check speed medium to slow speed failed main motor (M3) speed check speed medium to slow slow and motor (M3) speed check speed medium to slow slow main motor (M1) speed check speed medium to slow slow and motor (M3) speed check speed medium to slow main motor (M3) speed check speed medium to slow main motor (M3) speed check speed medium to slow main motor (M3) speed check speed medium to slow main motor (M3) speed check speed medium to fast motor main motor (M3) speed check speed medium to fast motor main motor (M3) speed check speed medium to fast motor main motor (M3) speed check speed medium to fast main motor (M3) speed slow down at medium speed failed main motor (M3) speed slow down at medium speed failed main motor (M3) speed slow down at medium speed failed main motor (M3) speed slow down at medium speed failed main motor (M3) speed slow down at medium speed failed main motor (M3) speed slow down at medium speed failed main motor (M3) speed check speed fast check main motor (M3) speed check speed fast to slow main motor (M3) speed check speed fast to failed main motor (M3) speed check speed fast to failed main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast speed failed main motor (M3) speed check speed fast to fast main motor (M3) speed check speed fast to fast main moto | 0x0120XXXX <b>0203</b> XXXX | MAIN_MOTOR_SPEED_SLOW_TO_SLOW    | I = = = = = = = = = = = = = = = = = = =     |
| 0x0120xxxx0206xxxx   | 0x0120XXXX <b>0204</b> XXXX | MAIN_MOTOR_SPEED_SLOW_TO_FAST    | fast  |
| SLOW_FAILED  \$\text{SLOW_FAILED} \text{Speed failed} \text{SLOW_FAILED} \text{Speed medium check} \text{MAIN_MOTOR_SPEED_MEDIUM_STATE} \text{main motor (M1) state at speed medium check} \text{MAIN_MOTOR_SPEED_UP_MEDIUM_failed} \text{main motor (M1) speed up at medium speed failed} \text{MAIN_MOTOR_SPEED_MEDIUM_TO_slow} \text{Main motor (M1) speed check speed medium to slow} \text{MAIN_MOTOR_SPEED_MEDIUM_TO_fast} \text{main motor (M1) speed check speed medium to slow} \text{MAIN_MOTOR_SPEED_MEDIUM_TO_fast} \text{main motor (M1) speed check speed medium to fast} \text{MAIN_MOTOR_SPEED_MEDIUM_JITTER} \text{Jitter} \text{main motor (M1) speed check speed medium jitter} \text{MAIN_MOTOR_SPEED_SLOWDOWN_medium_failed} \text{main motor (M1) speed slow down at medium speed failed} \text{MAIN_MOTOR_SPEED_FAST_STATE} \text{main motor (M1) speed up at fast speed fast check} \text{MAIN_MOTOR_SPEED_FAST_TO_SLOW} \text{MAIN_MOTOR_SPEED_FAST_TO_SLOW} \text{main motor (M1) speed up at fast speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_TO_FAST_failed} \text{main motor (M1) speed check speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_TO_FAST_failed} \text{main motor (M1) speed check speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed check speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed check speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed check speed fast to slow} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed check speed fast to speed failed} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed slow down at fast speed failed} \text{MAIN_MOTOR_SPEED_FAST_JITTER} \text{main motor (M1) speed slow down at fast speed failed} MAIN_MOTOR_SPEED_SLOWDOWN_main motor (M1) clock missing at timer input i      | 0x0120XXXX <b>0205</b> XXXX | MAIN_MOTOR_SPEED_SLOW_JITTER     | jitter                                      |
| 0x0120XXXX0208XXXXMAIN_MOTOR_SPEED_UP_MEDIUM_<br>FAILEDmain motor (M1) speed up at medium speed<br>failed0x0120XXXX0209XXXXMAIN_MOTOR_SPEED_MEDIUM_TO_<br>SLOWmain motor (M1) speed check speed medium to<br>  | 0x0120XXXX <b>0206</b> XXXX |                                  |   |
| 0x0120XXXX0208XXXXFAILEDfailed0x0120XXXXX0209XXXXMAIN_MOTOR_SPEED_MEDIUM_TO_ SLOWmain motor (M1) speed check speed medium to slow0x0120XXXX0210XXXXMAIN_MOTOR_SPEED_MEDIUM_TO_ FASTmain motor (M1) speed check speed medium to fast0x0120XXXX0211XXXXMAIN_MOTOR_SPEED_MEDIUM_JITTER jittermain motor (M1) speed check speed medium to fast0x0120XXXX0212XXXXMAIN_MOTOR_SPEED_SLOWDOWN_ MEDIUM_FAILEDmain motor (M1) speed slow down at medium speed failed0x0120XXXX0213XXXXMAIN_MOTOR_SPEED_FAST_STATEmain motor (M1) state at speed fast check0x0120XXXXX0214XXXXMAIN_MOTOR_SPEED_UP_FAST_ failedfailed0x0120XXXXX0215XXXXMAIN_MOTOR_SPEED_FAST_TO_SLOW slowmain motor (M1) speed check speed fast to slow0x0120XXXXX0216XXXXMAIN_MOTOR_SPEED_FAST_TO_FAST fastmain motor (M1) speed check speed fast to fast0x0120XXXXX0217XXXXMAIN_MOTOR_SPEED_FAST_JITTER jittermain motor (M1) speed check speed fast speed fast0x0120XXXXX0218XXXXMAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILEDmain motor (M1) speed slow down at fast speed failed0x0120XXXXX0219XXXXMAIN_MOTOR_TIMER_NO_CLOCKmain motor (M1) clock missing at timer input0x0120XXXX0220XXXXMAIN_MOTOR_TIMER_NOT_ timer semaphore not available for main motor (M1) clock measurement   | 0x0120XXXX <b>0207</b> XXXX | MAIN_MOTOR_SPEED_MEDIUM_STATE    | main motor (M1) state at speed medium check |
| SLOW  0x0120XXXX0210XXXX  0x0120XXXX0211XXXX  MAIN_MOTOR_SPEED_MEDIUM_JITTER fast  0x0120XXXX0211XXXX  MAIN_MOTOR_SPEED_MEDIUM_JITTER  0x0120XXXX0212XXXX  MAIN_MOTOR_SPEED_SLOWDOWN_ MEDIUM_FAILED  0x0120XXXX0213XXXX  MAIN_MOTOR_SPEED_FAST_STATE  main motor (M1) speed slow down at medium speed failed  0x0120XXXX0214XXXX  MAIN_MOTOR_SPEED_FAST_STATE  main motor (M1) speed up at fast speed failed  0x0120XXXX0215XXXX  MAIN_MOTOR_SPEED_FAST_TO_SLOW  0x0120XXXX0215XXXX  MAIN_MOTOR_SPEED_FAST_TO_SLOW  0x0120XXXX0216XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST fast  0x0120XXXX0217XXXX  MAIN_MOTOR_SPEED_FAST_JITTER  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_FAST_JITTER  0x0120XXXX0219XXXX  MAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILED  0x0120XXXX0219XXXX  MAIN_MOTOR_TIMER_NO_CLOCK  MAIN_MOTOR_TIMER_NO_CLOCK  1 timer semaphore not available for main motor (M1) clock measurement  | 0x0120XXXX <b>0208</b> XXXX |                                  | , ,   |
| 0x0120xxxx0211xxxx   | 0x0120XXXX <b>0209</b> XXXX | SLOW                             | slow  |
| 0x0120XXXX0211XXXXMAIN_MOTOR_SPEED_MEDIUM_JITTERjitter0x0120XXXX0212XXXXMAIN_MOTOR_SPEED_SLOWDOWN_<br>MEDIUM_FAILEDmain motor (M1) speed slow down at medium<br>speed failed0x0120XXXX0213XXXXMAIN_MOTOR_SPEED_FAST_STATEmain motor (M1) state at speed fast check0x0120XXXX0214XXXXMAIN_MOTOR_SPEED_UP_FAST_<br>FAILEDmain motor (M1) speed up at fast speed<br>failed0x0120XXXX0215XXXXMAIN_MOTOR_SPEED_FAST_TO_SLOW<br>slowmain motor (M1) speed check speed fast to<br>fast0x0120XXXX0216XXXXMAIN_MOTOR_SPEED_FAST_TO_FASTmain motor (M1) speed check speed fast to<br>fast0x0120XXXX0217XXXXMAIN_MOTOR_SPEED_FAST_JITTERmain motor (M1) speed check speed fast<br>jitter0x0120XXXX0218XXXXMAIN_MOTOR_SPEED_SLOWDOWN_<br>FAST_FAILEDmain motor (M1) speed slow down at fast<br>speed failed0x0120XXXX0219XXXXMAIN_MOTOR_TIMER_NO_CLOCKmain motor (M1) clock missing at timer<br>input0x0120XXXX0220XXXXMAIN_MOTOR_TIMER_NOT_<br>AVAILABLEtimer semaphore not available for main<br>motor (M1) clock measurement  | 0x0120XXXX <b>0210</b> XXXX |                                  | fast  |
| 0x0120XXXX0212XXXXMEDIUM_FAILEDspeed failed0x0120XXXX0213XXXXMAIN_MOTOR_SPEED_FAST_STATEmain motor (M1) state at speed fast check0x0120XXXX0214XXXXMAIN_MOTOR_SPEED_UP_FAST_ failedmain motor (M1) speed up at fast speed failed0x0120XXXX0215XXXXMAIN_MOTOR_SPEED_FAST_TO_SLOW slowmain motor (M1) speed check speed fast to slow0x0120XXXX0216XXXXMAIN_MOTOR_SPEED_FAST_TO_FAST fastmain motor (M1) speed check speed fast to fast0x0120XXXX0217XXXXMAIN_MOTOR_SPEED_FAST_JITTER jittermain motor (M1) speed check speed fast jitter0x0120XXXX0218XXXXMAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILEDmain motor (M1) speed slow down at fast speed failed0x0120XXXX0219XXXXMAIN_MOTOR_TIMER_NO_CLOCKmain motor (M1) clock missing at timer input0x0120XXXX0220XXXXMAIN_MOTOR_TIMER_NOT_ AVAILABLEtimer semaphore not available for main motor (M1) clock measurement  | 0x0120XXXX <b>0211</b> XXXX |                                  | jitter                                      |
| 0x0120XXXX0214XXXXMAIN_MOTOR_SPEED_UP_FAST_<br>FAILEDmain motor (M1) speed up at fast speed<br>failed0x0120XXXX0215XXXXMAIN_MOTOR_SPEED_FAST_TO_SLOW<br>Slowmain motor (M1) speed check speed fast to<br>slow0x0120XXXX0216XXXXMAIN_MOTOR_SPEED_FAST_TO_FAST<br>fastmain motor (M1) speed check speed fast to<br>fast0x0120XXXX0217XXXXMAIN_MOTOR_SPEED_FAST_JITTER<br>Jittermain motor (M1) speed check speed fast<br>jitter0x0120XXXX0218XXXXMAIN_MOTOR_SPEED_SLOWDOWN_<br>FAST_FAILEDmain motor (M1) speed slow down at fast<br>speed failed0x0120XXXX0219XXXXMAIN_MOTOR_TIMER_NO_CLOCKmain motor (M1) clock missing at timer<br>input0x0120XXXX0220XXXXMAIN_MOTOR_TIMER_NOT_<br>AVAILABLEtimer semaphore not available for main<br>motor (M1) clock measurement  | 0x0120XXXX <b>0212</b> XXXX |                                  |   |
| 0x0120XXXX0214XXXXFAILEDfailed0x0120XXXX0215XXXXMAIN_MOTOR_SPEED_FAST_TO_SLOWmain motor (M1) speed check speed fast to slow0x0120XXXX0216XXXXMAIN_MOTOR_SPEED_FAST_TO_FASTmain motor (M1) speed check speed fast to fast0x0120XXXX0217XXXXMAIN_MOTOR_SPEED_FAST_JITTER jittermain motor (M1) speed check speed fast jitter0x0120XXXX0218XXXXMAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILEDmain motor (M1) speed slow down at fast speed failed0x0120XXXX0219XXXXMAIN_MOTOR_TIMER_NO_CLOCKmain motor (M1) clock missing at timer input0x0120XXXX0220XXXXMAIN_MOTOR_TIMER_NOT_ AVAILABLEtimer semaphore not available for main motor (M1) clock measurement  | 0x0120XXXX <b>0213</b> XXXX | MAIN_MOTOR_SPEED_FAST_STATE      | main motor (M1) state at speed fast check   |
| 0x0120XXXX0216XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  0x0120XXXX0216XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST  0x0120XXXX0217XXXX  MAIN_MOTOR_SPEED_FAST_JITTER  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILED  0x0120XXXX0219XXXX  MAIN_MOTOR_TIMER_NO_CLOCK  0x0120XXXX0219XXXX  MAIN_MOTOR_TIMER_NOTOR_TIME | 0x0120XXXX <b>0214</b> XXXX |                                  |   |
| 0x0120XXXX0216XXXX  MAIN_MOTOR_SPEED_FAST_TO_FAST fast  0x0120XXXX0217XXXX  MAIN_MOTOR_SPEED_FAST_JITTER  0x0120XXXX0218XXXX  MAIN_MOTOR_SPEED_SLOWDOWN_ FAST_FAILED  main motor (M1) speed slow down at fast speed failed  main motor (M1) clock missing at timer input  0x0120XXXX0219XXXX  MAIN_MOTOR_TIMER_NOT_ AVAILABLE  motor (M1) clock measurement  | 0x0120XXXX <b>0215</b> XXXX | MAIN_MOTOR_SPEED_FAST_TO_SLOW    | slow  |
| 0x0120XXXX0217XXXX MAIN_MOTOR_SPEED_FAST_SITTER jitter  0x0120XXXX0218XXXX MAIN_MOTOR_SPEED_SLOWDOWN_ main motor (M1) speed slow down at fast speed failed  0x0120XXXX0219XXXX MAIN_MOTOR_TIMER_NO_CLOCK main motor (M1) clock missing at timer input  0x0120XXXX0220XXXX MAIN_MOTOR_TIMER_NOT_ available for main motor (M1) clock measurement  | 0x0120XXXX <b>0216</b> XXXX | MAIN_MOTOR_SPEED_FAST_TO_FAST    | fast  |
| 0x0120xxxx0218xxxx       FAST_FAILED       speed failed         0x0120xxxx0219xxxx       MAIN_MOTOR_TIMER_NO_CLOCK       main motor (M1) clock missing at timer input         0x0120xxxx0220xxxx       MAIN_MOTOR_TIMER_NOT_ AVAILABLE       timer semaphore not available for main motor (M1) clock measurement   | 0x0120XXXX <b>0217</b> XXXX |                                  | jitter                                      |
| 0x0120XXXX0219XXXX MAIN_MOTOR_TIMER_NO_CLOCK input  0x0120XXXX0220XXXX MAIN_MOTOR_TIMER_NOT_ timer semaphore not available for main motor (M1) clock measurement   | 0x0120XXXX <b>0218</b> XXXX |                                  | speed failed                                |
| 0X0120XXXX0220XXXX AVAILABLE motor (M1) clock measurement  | 0x0120XXXX <b>0219</b> XXXX |                                  | input                                       |
| 0x0120XXXX <b>0300</b> XXXX STACKER_WHEEL_BASE free, not used  | 0x0120XXXX <b>0220</b> XXXX |                                  | 1   |
|  | 0x0120XXXX <b>0300</b> XXXX | STACKER_WHEEL_BASE               | free, not used                              |

| DX0120XXXX0301XXXX STACKER, MHEEL_COMMAND_INIT_ PARLIED  DX0120XXXX0302XXXX STACKER, MHEEL_COMMAND_INIT_ DX0120XXXX0303XXXX STACKER, MHEEL_STATE  DX0120XXXX0304XXXX STACKER, MHEEL_LITTG GL2 NO. DX0120XXXX0304XXXX STACKER, MHEEL_LITTG GL2 NO. DX0120XXXX0304XXXX DX0120XXXX0306XXXX DX0120XXXX0306XXXX DX0120XXXX0306XXXX DX0120XXXX0306XXXX STACKER, MHEEL_STATE  DX0120XXXX0306XXXX STACKER, MHEEL_LITTG GL2 NO. DX0120XXXX0306XXXX STACKER, MHEEL_STATE  DX0120XXXX0406XXXX STACKER, MHEEL_STATE  DX0120XXXX0606XXXX STACKER, MHEEL_STATE   |                             | +                                     |   |
|---|-----------------------------|---------------------------------------|---|
| SAULZOXXXXX0303XXXX STACKER_WHEEL_STATE  \$tackerwheel command step failed  \$x0120XXXX0303XXXX \$TACKER_WHEEL_STATE  \$tackerwheel (SM9) init without sensor  \$x0120XXXX0306XXXX \$TACKER_WHEEL_INIT_GL2_NO  \$x0120XXXX0306XXXX \$TACKER_WHEEL_INIT_OVERDRIVES_ \$x02120XXXX0306XXXX \$x0306XXXX \$x0300XXXX \$x0306XXXX \$x0300XXXX \$x03 | 0x0120XXXX <b>0301</b> XXXX | STACKER_WHEEL_COMMAND_HOLD_<br>FAILED | stackerwheel command hold failed          |
| SOLIZOXXXX0303XXXX STACKER_WHEEL_STATE  \$tackerwheel state received  \$tackerwheel (SM9) init without sensor  \$tackerwheel (SM9) init overdrives sensor  \$tackerwheel (SM9  | 0x0120XXXX <b>0302</b> XXXX |                                       | stackerwheel command init failed          |
| STACKER_NHEEL_INIT_GL2_NO   Stackerwheel (SM9) init without sensor  | 0x0120XXXX <b>0303</b> XXXX |                                       | stackerwheel command step failed          |
| Ox0120XXXX0305XXXX   DARK_LIGHT_CHANGE   GL2   dark/light_change   GL2   dark/light_change   GL2   G  | 0x0120XXXX <b>0304</b> XXXX | STACKER_WHEEL_STATE                   | stackerwheel state received               |
| SADIZOXXXXX0300XXXX   STACKER_WHEEL_STEP_GLZ_NO_DARK_LIGHT_CHANGE   STACKER_WHEEL_STEP_GLZ_NO_DARK_LIGHT_CHANGE   (GL2) dark/light change   | 0x0120XXXX <b>0305</b> XXXX |                                       | , , ,                                     |
| DARK_LIGHT_CHANGE   (GL2) dark/light change   | 0x0120XXXX <b>0306</b> XXXX |                                       |   |
| 0x0120XXXX0309XXXX STACKER_WHEEL_STEP_TIME_FAILED Stackerwheel (SM9) step time out of range 0x0120XXXX0400XXXXX CIRCLE_FORK_BASE free, not used 0x0120XXXX0401XXXX CIRCLE_FORK_GL8_ERROR GL8 not LIGHT after circle fork init 0x0120XXXX0401XXXX CIRCLE_FORK_GL8_ERROR GL9 not LIGHT after circle fork init 0x0120XXXX0404XXXX CIRCLE_FORK_GL9_ERROR GL9 not LIGHT after circle fork init 0x0120XXXX0404XXXX CIRCLE_FORK_GL9_ERROR GL9 not LIGHT after circle fork init 0x0120XXXX0405XXXX CIRCLE_FORK_GL9_ERROR GL9 not LIGHT after circle fork init 0x0120XXXX0405XXXX CIRCLE_FORK_CLAMP_OPEN_FAILED circlefork error 0x0120XXXXX0405XXXX CIRCLE_FORK_GL9_ERROR circlefork error 0x0120XXXXX0405XXXX CIRCLE_FORK_CLAMP_GPEN_FAILED circlefork error 0x0120XXXXX0405XXXX CIRCLE_FORK_CLAMP_GPEN_FAILED circlefork error 0x0120XXXXX0409XXXX CIRCLE_FORK_GLT_FAILED circlefork error 0x0120XXXXX0409XXXX CIRCLE_FORK_OUT_SAFE_FAILED circlefork error 0x0120XXXXX0410XXXX CIRCLE_FORK_DEAD_END_FAILED circlefork error 0x0120XXXXX0410XXXX CIRCLE_FORK_DEAD_END_FAILED circlefork error 0x0120XXXXX0411XXXX CIRCLE_FORK_DEAD_END_FAILED circlefork error 0x0120XXXXX0411XXXX CIRCLE_FORK_CLAMP_CLOSED_ circlefork error 0x0120XXXXX0412XXXX SHUTTER_BASE free, not used 0x0120XXXXX0501XXXX SHUTTER_DEAD_FAILED shutter (SM7/M7) not installed or type unknown 0x0120XXXXX0501XXXX SHUTTER_CLOSE_FAILED shutter (SM7/M7) open failed 0x0120XXXXX0504XXXX SHUTTER_CLOSE_FAILED shutter (SM7/M7) open failed 0x0120XXXXX0504XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed 0x0120XXXXX0504XXXX SINGLE_REJECT_BOX_BASE free, not used 0x0120XXXXX0504XXXX SHUTTER_OFEN_FAILED shutter (SM7/M7) open failed 0x0120XXXX0504XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) ont installed 0x0120XXXX0604XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (S  | 0x0120XXXX <b>0307</b> XXXX |                                       |   |
| 0x0120XXXX0400XXXX  | 0x0120XXXX <b>0308</b> XXXX |                                       |   |
| 0x0120XXXXV0401XXXX         CIRCLE_FORK_INIT_FAILED         circle fork init failed           0x0120XXXXV0402XXXX         CIRCLE_FORK_GL8_ERROR         GL8 not LIGHT after circle fork init           0x0120XXXXV0403XXXX         CIRCLE_FORK_GL9_ERROR         GL9 not LIGHT after circle fork init           0x0120XXXXV0404XXXX         CIRCLE_FORK_CLAMP_OPEN_FAILED         circle fork position not reached           0x0120XXXXV0405XXXX         CIRCLE_FORK_REJECT_FAILED         circlefork error           0x0120XXXXV0406XXXX         CIRCLE_FORK_CATCH_FAILED         circlefork error           0x0120XXXXV0408XXXX         CIRCLE_FORK_OUT_SAFE_FAILED         circlefork error           0x0120XXXXV0409XXXX         CIRCLE_FORK_IN_SAFE_FRONT_FAILED         circlefork error           0x0120XXXXV0410XXXX         CIRCLE_FORK_DEAD_END_FAILED         circlefork error           0x0120XXXXX0411XXXX         CIRCLE_FORK_CLAMP_CLOSED_FAILED         circlefork error           0x0120XXXXX0412XXXX         SHUTTER_BASE         free, not used           0x0120XXXXX0500XXXX         SHUTTER_BASE         free, not used           0x0120XXXXX0501XXXX         SHUTTER_CLOSE_FAILED         shutter (SM7/M7) one failed           0x0120XXXXX0503XXXX         SHUTTER_OFFER_FAILED         shutter (SM7/M7) open failed           0x0120XXXXX05004XXXX         SHUTTER_OFFER_FAILED         shutter (SM7/M7) offer failed   | 0x0120XXXX <b>0309</b> XXXX | STACKER_WHEEL_STEP_TIME_FAILED        | stackerwheel (SM9) step time out of range |
| 0x0120XXXX0402XXXX         CIRCLE_FORK_GL8_ERROR         GL8 not LIGHT after circle fork init           0x0120XXXX0403XXXX         CIRCLE_FORK_GL9_ERROR         GL9 not LIGHT after circle fork init           0x0120XXXX0404XXXX         CIRCLE_FORK_CLAMP_OPEN_FAILED         circle fork position not reached           0x0120XXXXX0405XXXX         CIRCLE_FORK_REJECT_FAILED         circlefork error           0x0120XXXX0406XXXX         CIRCLE_FORK_IN_SAFE_REAR_ PAILED         circlefork error           0x0120XXXXX0407XXXX         CIRCLE_FORK_CATCH_FAILED         circlefork error           0x0120XXXXX0409XXXX         CIRCLE_FORK_OUT_SAFE_FAILED         circlefork error           0x0120XXXXX0409XXXX         CIRCLE_FORK_OUT_SAFE_FAILED         circlefork error           0x0120XXXXX0410XXXX         CIRCLE_FORK_DEAD_END_FAILED         circlefork error           0x0120XXXXX0411XXXX         CIRCLE_FORK_CLAMP_CLOSED_ FAILED         circlefork error           0x0120XXXXX0412XXXX         CIRCLE_FORK_MECHANIK_TEST_ FAILED         circlefork error           0x0120XXXXX0500XXXX         SHUTTER_NOT_INSTALLED         shutter (SM7/M7) not installed or type unknown           0x0120XXXXX0501XXXX         SHUTTER_CLOSE_FAILED         shutter (SM7/M7) open failed           0x0120XXXXX0503XXXX         SHUTTER_OPEN_FAILED         shutter (SM7/M7) open failed           0x0120XXXX0504XXXX         SHUTTER_OPE  | 0x0120XXXX <b>0400</b> XXXX | CIRCLE_FORK_BASE                      | free, not used                            |
| Ox0120XXXX0403XXXX  | 0x0120XXXX <b>0401</b> XXXX | CIRCLE_FORK_INIT_FAILED               | circle fork init failed                   |
| 0x0120XXXX0404XXXX         CIRCLE_FORK_CLAMP_OPEN_FAILED         circle fork position not reached           0x0120XXXXX0405XXXX         CIRCLE_FORK_REJECT_FAILED         circlefork error           0x0120XXXX0406XXXX         FAILED         circlefork error           0x0120XXXX0407XXXX         CIRCLE_FORK_CATCH_FAILED         circlefork error           0x0120XXXX0409XXXX         CIRCLE_FORK_OUT_SAFE_FAILED         circlefork error           0x0120XXXX0410XXXX         CIRCLE_FORK_IN_SAFE_FRONT_FAILED         circlefork error           0x0120XXXX0410XXXX         CIRCLE_FORK_CLAMP_CLOSED_FAILED         circlefork error           0x0120XXXX0411XXXX         FAILED         circlefork error           0x0120XXXX0412XXXX         FAILED         circlefork error           0x0120XXXX0500XXXX         SHUTTER_BASE         free, not used           0x0120XXXX0501XXXX         SHUTTER_NOT_INSTALLED         shutter (SM7/M7) not installed or type unknown           0x0120XXXX0503XXXX         SHUTTER_OPEN_FAILED         shutter (SM7/M7) close failed           0x0120XXXX0503XXXX         SHUTTER_OFFER_FAILED         shutter (SM7/M7) open failed           0x0120XXXX0600XXXX         SINGLE_REJECT_BOX_BASE         free, not used           0x0120XXXXX0601XXXX         SINGLE_REJECT_BOX_NOT_STATE         single reject box (SM1) not installed           0x0120XXXX0603XXXX <td>0x0120XXXX<b>0402</b>XXXX</td> <td>CIRCLE_FORK_GL8_ERROR</td> <td>GL8 not LIGHT after circle fork init</td>  | 0x0120XXXX <b>0402</b> XXXX | CIRCLE_FORK_GL8_ERROR                 | GL8 not LIGHT after circle fork init      |
| 0x0120XXXX0405XXXX       CIRCLE_FORK_REJECT_FAILED       circlefork error         0x0120XXXX0406XXXX       CIRCLE_FORK_IN_SAFE_REAR_ FAILED       circlefork error         0x0120XXXX0407XXXX       CIRCLE_FORK_OUT_SAFE_FAILED       circlefork error         0x0120XXXX0409XXXX       CIRCLE_FORK_IN_SAFE_FRONT_ FAILED       circlefork error         0x0120XXXX0410XXXX       CIRCLE_FORK_CLAMP_CLOSED_ CIRCLEFORK error         0x0120XXXX0411XXXX       CIRCLE_FORK_MECHANIK_TEST_ FAILED       circlefork error         0x0120XXXXX0412XXXX       PAILED       circlefork error         0x0120XXXXX0500XXXX       SHUTTER_BASE       free, not used         0x0120XXXXX0500XXXX       SHUTTER_NOT_INSTALLED       shutter (SM7/M7) not installed or type unknown         0x0120XXXXX0503XXXX       SHUTTER_CLOSE_FAILED       shutter (SM7/M7) close failed         0x0120XXXXX0503XXXX       SHUTTER_OPEN_FAILED       shutter (SM7/M7) open failed         0x0120XXXXX0504XXXX       SHUTTER_OFFER_FAILED       shutter (SM7/M7) offer failed         0x0120XXXXX0600XXXX       SINGLE_REJECT_BOX_BASE       free, not used         0x0120XXXXX0601XXXX       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) not installed         0x0120XXXXX0603XXXX       SINGLE_REJECT_BOX_TIMEOUT       single reject box (SM1) init timeout         0x0120XXXX0604XXXX       SINGLE_REJECT_BOX_STATE<   | 0x0120XXXX <b>0403</b> XXXX | CIRCLE_FORK_GL9_ERROR                 | GL9 not LIGHT after circle fork init      |
| 0x0120XXXX0406XXXX         CIRCLE_FORK_IN_SAFE_REAR_FAILED         circlefork error           0x0120XXXX0407XXXX         CIRCLE_FORK_CATCH_FAILED         circlefork error           0x0120XXXX0408XXXX         CIRCLE_FORK_OUT_SAFE_FAILED         circlefork error           0x0120XXXX0409XXXX         CIRCLE_FORK_IN_SAFE_FRONT_FAILED         circlefork error           0x0120XXXX0410XXXX         CIRCLE_FORK_CLAMP_CLOSED_FAILED         circlefork error           0x0120XXXX0411XXXX         CIRCLE_FORK_MECHANIK_TEST_FAILED         circlefork error           0x0120XXXX0412XXXX         CIRCLE_FORK_MECHANIK_TEST_FAILED         circlefork error           0x0120XXXXX0500XXXX         SHUTTER_BASE         free, not used           0x0120XXXXX0501XXXX         SHUTTER_NOT_INSTALLED         shutter (SM7/M7) not installed or type unknown           0x0120XXXXX0503XXXX         SHUTTER_CLOSE_FAILED         shutter (SM7/M7) close failed           0x0120XXXXX0503XXXX         SHUTTER_OPEN_FAILED         shutter (SM7/M7) open failed           0x0120XXXXX0600XXXX         SHUTTER_OFFER_FAILED         shutter (SM7/M7) offer failed           0x0120XXXXX0601XXXX         SINGLE_REJECT_BOX_BASE         free, not used           0x0120XXXXX0601XXXX         SINGLE_REJECT_BOX_MONEY         single reject box (SM1) not installed           0x0120XXXXX0603XXXX         SINGLE_REJECT_BOX_TIMEOUT         single  | 0x0120XXXX <b>0404</b> XXXX | CIRCLE_FORK_CLAMP_OPEN_FAILED         | circle fork position not reached          |
| 0x0120XXXX0407XXXX CIRCLE_FORK_CATCH_FAILED circlefork error 0x0120XXXX0408XXXX CIRCLE_FORK_OUT_SAFE_FAILED circlefork error 0x0120XXXX0409XXXX CIRCLE_FORK_IN_SAFE_FAILED circlefork error 0x0120XXXX0410XXXX CIRCLE_FORK_DEAD_END_FAILED circlefork error 0x0120XXXX0411XXXX CIRCLE_FORK_DEAD_END_FAILED circlefork error 0x0120XXXX0411XXXX CIRCLE_FORK_MECHANIK_TEST_ circlefork error 0x0120XXXX0412XXXX SHUTTER_BASE free, not used 0x0120XXXX0500XXXX SHUTTER_NOT_INSTALLED shutter (SM7/M7) not installed or type unknown 0x0120XXXX0501XXXX SHUTTER_CLOSE_FAILED shutter (SM7/M7) open failed 0x0120XXXX0503XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed 0x0120XXXX0504XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) offer failed 0x0120XXXX0600XXXX SINGLE_REJECT_BOX_BASE free, not used 0x0120XXXX0600XXXX SINGLE_REJECT_BOX_NOT_ INSTALLED single reject box (SM1) not installed 0x0120XXXX0603XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) init timeout 0x0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) state received 0x0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) init failed   | 0x0120XXXX <b>0405</b> XXXX | CIRCLE_FORK_REJECT_FAILED             | circlefork error                          |
| 0x0120XXXX0408XXXX       CIRCLE_FORK_OUT_SAFE_FAILED       circlefork error         0x0120XXXX0409XXXX       CIRCLE_FORK_IN_SAFE_FRONT_       circlefork error         0x0120XXXX0410XXXX       CIRCLE_FORK_DEAD_END_FAILED       circlefork error         0x0120XXXX0411XXXX       CIRCLE_FORK_CLAMP_CLOSED_<br>FAILED       circlefork error         0x0120XXXX0412XXXX       CIRCLE_FORK_MECHANIK_TEST_<br>FAILED       circlefork error         0x0120XXXX0500XXXX       SHUTTER_BASE       free, not used         0x0120XXXX0501XXXX       SHUTTER_NOT_INSTALLED       shutter (SM7/M7) not installed or type unknown         0x0120XXXX0502XXXX       SHUTTER_CLOSE_FAILED       shutter (SM7/M7) open failed         0x0120XXXX0503XXXX       SHUTTER_OPEN_FAILED       shutter (SM7/M7) open failed         0x0120XXXX0504XXXX       SHUTTER_OFFER_FAILED       shutter (SM7/M7) offer failed         0x0120XXXXX0600XXXX       SINGLE_REJECT_BOX_BASE       free, not used         0x0120XXXXX0601XXXX       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) not installed         0x0120XXXXX0602XXXX       SINGLE_REJECT_BOX_TIMEOUT       single reject box (SM1) init timeout         0x0120XXXXX0604XXXX       SINGLE_REJECT_BOX_STATE       single reject box (SM1) init failed  | 0x0120XXXX <b>0406</b> XXXX |                                       | circlefork error                          |
| 0x0120XXXX0409XXXX       CIRCLE_FORK_IN_SAFE_FRONT_ FAILED       circlefork error         0x0120XXXX0410XXXX       CIRCLE_FORK_DEAD_END_FAILED       circlefork error         0x0120XXXX0411XXXX       CIRCLE_FORK_CLAMP_CLOSED_ FAILED       circlefork error         0x0120XXXX0412XXXX       CIRCLE_FORK_MECHANIK_TEST_ FAILED       circlefork error         0x0120XXXX0500XXXX       SHUTTER_BASE       free, not used         0x0120XXXX0501XXXX       SHUTTER_NOT_INSTALLED       shutter (SM7/M7) not installed or type unknown         0x0120XXXX0502XXXX       SHUTTER_CLOSE_FAILED       shutter (SM7/M7) close failed         0x0120XXXX0503XXXX       SHUTTER_OPEN_FAILED       shutter (SM7/M7) open failed         0x0120XXXX0504XXXX       SHUTTER_OFFER_FAILED       shutter (SM7/M7) offer failed         0x0120XXXXX0600XXXX       SINGLE_REJECT_BOX_BASE       free, not used         0x0120XXXXX0601XXXX       SINGLE_REJECT_BOX_NOT_ INSTALLED       single reject box (SM1) not installed         0x0120XXXXX0602XXXX       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) contains money         0x0120XXXXX0603XXXX       SINGLE_REJECT_BOX_TIMEOUT       single reject box (SM1) init timeout         0x0120XXXXX0605XXXX       SINGLE_REJECT_BOX_INIT_FAILED       single reject box (SM1) init failed  | 0x0120XXXX <b>0407</b> XXXX | CIRCLE_FORK_CATCH_FAILED              | circlefork error                          |
| OX0120XXXX0410XXXX  CIRCLE_FORK_DEAD_END_FAILED  CIRCLE_FORK_CLAMP_CLOSED_ CIRCLE_FORK_MECHANIK_TEST_  CX0120XXXX0412XXXX  CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLE_FORK_MECHANIK_TEST_ CIRCLEFORK_MECHANIK_TEST_ CIRCLEFORK_CLAMIC_CIRCLEFORM_MECHANIK_TEST_ CIRCLEFORM CIRCLEFOR  | 0x0120XXXX <b>0408</b> XXXX | CIRCLE_FORK_OUT_SAFE_FAILED           | circlefork error                          |
| 0x0120XXXX0411XXXX       CIRCLE_FORK_CLAMP_CLOSED_FAILED       circlefork error         0x0120XXXX0412XXXX       CIRCLE_FORK_MECHANIK_TEST_FAILED       circlefork error         0x0120XXXX0500XXXX       SHUTTER_BASE       free, not used         0x0120XXXX0501XXXX       SHUTTER_NOT_INSTALLED       shutter (SM7/M7) not installed or type unknown         0x0120XXXX0502XXXX       SHUTTER_CLOSE_FAILED       shutter (SM7/M7) close failed         0x0120XXXX0503XXXX       SHUTTER_OPEN_FAILED       shutter (SM7/M7) open failed         0x0120XXXX0504XXXX       SHUTTER_OFFER_FAILED       shutter (SM7/M7) offer failed         0x0120XXXX0600XXXX       SINGLE_REJECT_BOX_BASE       free, not used         0x0120XXXXX0601XXXX       SINGLE_REJECT_BOX_NOT_INSTALLED       single reject box (SM1) not installed         0x0120XXXXX0602XXXX       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) contains money         0x0120XXXXX0603XXXX       SINGLE_REJECT_BOX_STATE       single reject box (SM1) state received         0x0120XXXXX0605XXXX       SINGLE_REJECT_BOX_INIT_FAILED       single reject box (SM1) init failed  | 0x0120XXXX <b>0409</b> XXXX |                                       | circlefork error                          |
| OX0120XXXX0412XXXX  CIRCLE_FORK_MECHANIK_TEST_ circlefork error  OX0120XXXX0500XXXX  SHUTTER_BASE free, not used  OX0120XXXX0501XXXX  SHUTTER_NOT_INSTALLED shutter (SM7/M7) not installed or type unknown  OX0120XXXX0502XXXX  SHUTTER_CLOSE_FAILED shutter (SM7/M7) olose failed  OX0120XXXX0503XXXX  SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed  OX0120XXXX0504XXXX  SHUTTER_OPEN_FAILED shutter (SM7/M7) offer failed  OX0120XXXX0600XXXX  SINGLE_REJECT_BOX_BASE free, not used  OX0120XXXX0601XXXX  SINGLE_REJECT_BOX_NOT_ single reject box (SM1) not installed  OX0120XXXX0602XXXX  SINGLE_REJECT_BOX_MONEY single reject box (SM1) contains money  OX0120XXXX0603XXXX  SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout  OX0120XXXX0604XXXX  SINGLE_REJECT_BOX_STATE single reject box (SM1) state received  OX0120XXXX0605XXXX  SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed   | 0x0120XXXX <b>0410</b> XXXX | CIRCLE_FORK_DEAD_END_FAILED           | circlefork error                          |
| OX0120XXXX0500XXXX SHUTTER_BASE free, not used  Ox0120XXXX0501XXXX SHUTTER_NOT_INSTALLED shutter (SM7/M7) not installed or type unknown  Ox0120XXXX0502XXXX SHUTTER_CLOSE_FAILED shutter (SM7/M7) close failed  Ox0120XXXX0503XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed  Ox0120XXXX0504XXXX SHUTTER_OFFER_FAILED shutter (SM7/M7) offer failed  Ox0120XXXX0600XXXX SINGLE_REJECT_BOX_BASE free, not used  Ox0120XXXX0601XXXX SINGLE_REJECT_BOX_NOT_ installed  Ox0120XXXX0601XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) not installed  Ox0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout  Ox0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) init failed  | 0x0120XXXX <b>0411</b> XXXX |                                       | circlefork error                          |
| 0x0120XXXX0501XXXX SHUTTER_NOT_INSTALLED shutter (SM7/M7) not installed or type unknown  0x0120XXXX0502XXXX SHUTTER_CLOSE_FAILED shutter (SM7/M7) close failed  0x0120XXXX0503XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed  0x0120XXXX0504XXXX SHUTTER_OFFER_FAILED shutter (SM7/M7) offer failed  0x0120XXXX0600XXXX SINGLE_REJECT_BOX_BASE free, not used  0x0120XXXX0601XXXX SINGLE_REJECT_BOX_NOT_ installed  0x0120XXXX0602XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) not installed  0x0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout  0x0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) state received  0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed   | 0x0120XXXX <b>0412</b> XXXX |                                       | circlefork error                          |
| 0X0120XXXX0501XXXXSHUTTER_NOT_INSTALLEDunknown0x0120XXXX0502XXXXSHUTTER_CLOSE_FAILEDshutter (SM7/M7) close failed0x0120XXXX0503XXXXSHUTTER_OPEN_FAILEDshutter (SM7/M7) open failed0x0120XXXX0504XXXXSHUTTER_OFFER_FAILEDshutter (SM7/M7) offer failed0x0120XXXX0600XXXXSINGLE_REJECT_BOX_BASEfree, not used0x0120XXXX0601XXXXSINGLE_REJECT_BOX_NOT_<br>INSTALLEDsingle reject box (SM1) not installed0x0120XXXX0602XXXXSINGLE_REJECT_BOX_MONEYsingle reject box (SM1) contains money0x0120XXXX0603XXXXSINGLE_REJECT_BOX_TIMEOUTsingle reject box (SM1) init timeout0x0120XXXX0604XXXXSINGLE_REJECT_BOX_STATEsingle reject box (SM1) state received0x0120XXXX0605XXXXSINGLE_REJECT_BOX_INIT_FAILEDsingle reject box (SM1) init failed  | 0x0120XXXX <b>0500</b> XXXX | SHUTTER_BASE                          | free, not used                            |
| 0x0120XXXX0503XXXX SHUTTER_OPEN_FAILED shutter (SM7/M7) open failed 0x0120XXXX0504XXXX SHUTTER_OFFER_FAILED shutter (SM7/M7) offer failed 0x0120XXXX0600XXXX SINGLE_REJECT_BOX_BASE free, not used 0x0120XXXX0601XXXX SINGLE_REJECT_BOX_NOT_ INSTALLED single reject box (SM1) not installed 0x0120XXXX0602XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) contains money 0x0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout 0x0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) state received 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed   | 0x0120XXXX <b>0501</b> XXXX | SHUTTER_NOT_INSTALLED                 |   |
| 0x0120XXXX0504XXXX SHUTTER_OFFER_FAILED shutter (SM7/M7) offer failed 0x0120XXXX0600XXXX SINGLE_REJECT_BOX_BASE free, not used  0x0120XXXX0601XXXX SINGLE_REJECT_BOX_NOT_ installed 0x0120XXXX0602XXXX SINGLE_REJECT_BOX_MONEY single reject box (SM1) not installed 0x0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout 0x0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) state received 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed   | 0x0120XXXX <b>0502</b> XXXX | SHUTTER_CLOSE_FAILED                  | shutter (SM7/M7) close failed             |
| 0x0120XXXX0600XXXX       SINGLE_REJECT_BOX_BASE       free, not used         0x0120XXXX0601XXXX       SINGLE_REJECT_BOX_NOT_<br>INSTALLED       single reject box (SM1) not installed         0x0120XXXX0602XXXX       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) contains money         0x0120XXXX0603XXXX       SINGLE_REJECT_BOX_TIMEOUT       single reject box (SM1) init timeout         0x0120XXXX0604XXXX       SINGLE_REJECT_BOX_STATE       single reject box (SM1) state received         0x0120XXXX0605XXXX       SINGLE_REJECT_BOX_INIT_FAILED       single reject box (SM1) init failed  | 0x0120XXXX <b>0503</b> XXXX | SHUTTER_OPEN_FAILED                   | shutter (SM7/M7) open failed              |
| 0x0120XXXX0601XXXX  | 0x0120XXXX <b>0504</b> XXXX | SHUTTER_OFFER_FAILED                  | shutter (SM7/M7) offer failed             |
| 0x0120xxxx0601xxxx       INSTALLED       single reject box (SM1) not installed         0x0120xxxx0602xxxx       SINGLE_REJECT_BOX_MONEY       single reject box (SM1) contains money         0x0120xxxx0603xxxx       SINGLE_REJECT_BOX_TIMEOUT       single reject box (SM1) init timeout         0x0120xxxx0604xxxx       SINGLE_REJECT_BOX_STATE       single reject box (SM1) state received         0x0120xxxx0605xxxx       SINGLE_REJECT_BOX_INIT_FAILED       single reject box (SM1) init failed   | 0x0120XXXX <b>0600</b> XXXX | SINGLE_REJECT_BOX_BASE                | free, not used                            |
| 0x0120XXXX0603XXXX SINGLE_REJECT_BOX_TIMEOUT single reject box (SM1) init timeout 0x0120XXXX0604XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) state received 0x0120XXXX0605XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed  | 0x0120XXXX <b>0601</b> XXXX |                                       | single reject box (SM1) not installed     |
| 0x0120XXXX <b>0604</b> XXXX SINGLE_REJECT_BOX_STATE single reject box (SM1) state received 0x0120XXXX <b>0605</b> XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed  | 0x0120XXXX <b>0602</b> XXXX | SINGLE_REJECT_BOX_MONEY               | single reject box (SM1) contains money    |
| 0x0120XXXX <b>0605</b> XXXX SINGLE_REJECT_BOX_INIT_FAILED single reject box (SM1) init failed   | 0x0120XXXX <b>0603</b> XXXX | SINGLE_REJECT_BOX_TIMEOUT             | single reject box (SM1) init timeout      |
|   | 0x0120XXXX <b>0604</b> XXXX | SINGLE_REJECT_BOX_STATE               | single reject box (SM1) state received    |
| 0x0120XXXX <b>0606</b> XXXX SINGLE_REJECT_BOX_STANDART_ single reject box (SM1) standard position   | 0x0120XXXX <b>0605</b> XXXX | SINGLE_REJECT_BOX_INIT_FAILED         | single reject box (SM1) init failed       |
|   | 0x0120XXXX <b>0606</b> XXXX | SINGLE_REJECT_BOX_STANDART_           | single reject box (SM1) standard position |

|                             | FAILED   | error   |
|-----------------------------|--|---|
| 0x0120XXXX <b>0607</b> XXXX | SINGLE_REJECT_BOX_RESERVE_<br>FAILED           | single reject box (SM1) reserve position error        |
| 0x0120XXXX <b>0608</b> XXXX | SINGLE_REJECT_BOX_EMPTY_FAILED                 | single reject box (SM1) empty position error          |
| 0x0120XXXX <b>0700</b> XXXX | OUTPUT_TRANSPORT_BASE                          | free, not used  |
| 0x0120XXXX <b>0701</b> XXXX | NO_OUTPUT_TRANSPORT_INSTALLED                  | no output transport installed (RD 0x86 sensor 3)      |
| 0x0120XXXX <b>0702</b> XXXX | OUTPUT_TRANSPORT_WAGEN_1_ SWITCH_OPEN          | for out safe transport, switch Wagen_1 must be closed |
| 0x0120XXXX <b>0703</b> XXXX | OUTPUT_TRANSPORT_HALL_SENSOR_<br>ERROR         | more then on hall sensor (HL14) is active             |
| 0x0120XXXX <b>0704</b> XXXX | OUTPUT_TRANSPORT_CLAMP_NOT_<br>EMPTY_LS18      | clamp not empty in position stacker                   |
| 0x0120XXXX <b>0705</b> XXXX | OUTPUT_TRANSPORT_CLAMP_NOT_<br>EMPTY_LS27_LS28 | clamp not empty in position shutter                   |
| 0x0120XXXX <b>0706</b> XXXX | OUTPUT_TRANSPORT_INIT_FAILED                   | output transport init failed                          |
| 0x0120XXXX <b>0707</b> XXXX | OUTPUT_TRANSPORT_CLAMP_OPEN_<br>FAILED         | output transport clamp open failed                    |
| 0x0120XXXX <b>0708</b> XXXX | OUTPUT_TRANSPORT_CLAMP_CLOSE_<br>FAILED        | output transport clamp close failed                   |
| 0x0120XXXX <b>0709</b> XXXX | OUTPUT_TRANSPORT_DRIVE_TO_<br>STACKER_FAILED   | output transport drive to stacker failed              |
| 0x0120XXXX <b>0710</b> XXXX | OUTPUT_TRANSPORT_DRIVE_TO_<br>SHUTTER_FAILED   | output transport drive to shutter failed              |
| 0x0120XXXX <b>0711</b> XXXX | OUTPUT_TRANSPORT_DRIVE_TO_<br>REJECT_FAILED    | output transport drive to reject failed               |

| Code                        | Class                 |  |
|-----------------------------|-----------------------|--|
| 0x <b>012A</b> XXXXXXXXXXXX | CONTROL_GEAR          |  |
| Code                        | Component             |  |
| 0x012A <b>18A0</b> XXXXXXXX | CONTROL_GEAR          |  |
| Code                        | ERROR                 | Meaning  |
| 0x012AXXXX <b>0001</b> XXXX | INITIALIZATION_FAILED | serious errors occurred during the initialization, position not reached (photo-sensors or motor defect or not connected or hw damaged) |
| 0x012AXXXX <b>0002</b> XXXX | SELF_TEST_FAILED      | serious errors occurred during the initialization, position not reached (photo-sensors or motor defect or not connected or hw damaged) |
| 0x012AXXXX <b>0004</b> XXXX | POSITION_NOT_REACHED  | device jammed during movement to target, value holds target position   |
| 0x012AXXXX <b>0006</b> XXXX | POSITION_NOT_LEFT     | device jammed = did not leave position, value holds source position  |
| 0x012AXXXX <b>000A</b> XXXX | MOTOR_FAILURE         | motor did not start  |
| 0x012AXXXX <b>000C</b> XXXX | MOVE_TOO_SLOW         | device too slow in self test   |

| Code                        | Class                     |                          |
|-----------------------------|---------------------------|--------------------------|
| 0x <b>0130</b> XXXXXXXXXXXX | DES                       |                          |
| Code                        | Component                 |                          |
| 0x0130 <b>0070</b> XXXXXXXX | DES                       |                          |
| Code                        | ERROR                     | Meaning                  |
| 0x0130XXXX <b>0010</b> XXXX | NO_ODD_TRANSPORT_KEY      | transport key is not odd |
| 0x0130XXXX <b>0020</b> XXXX | LOAD_TRANSPORT_KEY_FAILED | loading failed           |
| 0x0130XXXX <b>0030</b> XXXX | NO_ODD_LINE_KEY           | line key is not odd      |
| 0x0130XXXX <b>0040</b> XXXX | LOAD_LINE_KEY_FAILED      | loding failed            |

| Code                        | Class                |
|-----------------------------|----------------------|
| 0x <b>0140</b> XXXXXXXXXXXX | DIGITAL_PHOTO_SENSOR |

| Code                        | Class                               |  |
|-----------------------------|-------------------------------------|--|
| 0x <b>0150</b> XXXXXXXXXXXX | DISPENSER                           |  |
| Code                        | Component                           |  |
| 0x0150 <b>1990</b> XXXXXXXX | DISPENSER                           |  |
| Code                        | ERROR                               | Meaning  |
| 0x0150XXXX <b>0011</b> XXXX | CHECK_TRANSPORT_ERROR               | the transport check failed, value is 0   |
| 0x0150XXXX <b>0020</b> XXXX | DISPENSE_FAILED                     | the dispense command failed, value is 0  |
| 0x0150XXXX <b>0030</b> XXXX | REFERENCE_FAILED                    | the reference command failed, value is 0   |
| 0x0150XXXX <b>0040</b> XXXX | CASH_OUT_NOT_AVAILABLE              | cash out is not available, value is 0  |
| 0x0150XXXX <b>0050</b> XXXX | SAFETY_SWITCH_OPENED                | the safety switch is open, value is 0  |
| 0x0150XXXX <b>0051</b> XXXX | DEVICE_IS_LOCKED                    | the device is locked (retract & quit), value is 0  |
| 0x0150XXXX <b>0060</b> XXXX | PRESSURE_NOT_OK                     | the pressure in a cassette could not be updated, value holds the cassette number   |
| 0x0150XXXX <b>0064</b> XXXX | RETRACT_NOTES_TO_STACKER_<br>FAILED | in case of a retract or bundle-reject from shutter the notes could not be retracted from the offer or shutter position into the stacker position |
| 0x0150XXXX <b>0065</b> XXXX | RETRACT_AND_QUIT_NOTES_FAILED       | in case of a retract & quit from shutter<br>the notes could not be retracted from the<br>offer or shutter position into the stacker<br>position  |
| 0x0150XXXX <b>0080</b> XXXX | RETRACT_FAILED                      | the retract failed, the notes could be transported to the retract tray, but could not be deposited in it   |
| 0x0150XXXX <b>0090</b> XXXX | REJECT_FAILED                       | the reject failed, the notes could be transported to the retract tray, but could not be deposited in it  |
| 0x0150XXXX <b>00A0</b> XXXX | DRIVE_TO_BOX_FAILED                 | the clamp could not be driven from the stacker to the box  |
| 0x0150XXXX <b>00A8</b> XXXX | DRIVE_TO_STACKER_FAILED             | the clamp could not be driven to the   |

|                             |                                     | stacker   |
|-----------------------------|-------------------------------------|---|
| 0x0150XXXX <b>00B0</b> XXXX | CLAMP_OPEN_FAILED                   | the clamp could not be opened                                     |
| 0x0150XXXX <b>00C0</b> XXXX | CLEAR_AFTER_NOTE_REMOVAL_<br>FAILED | missing exception text  |
| 0x0150XXXX <b>00D0</b> XXXX | CLOSE_OFFER_FAILED                  | not used  |
| 0x0150XXXX <b>00F0</b> XXXX | SHUTTER_NOT_EMPTY                   | not used  |
| 0x0150XXXX <b>0100</b> XXXX | CLAMP_IN_SHUTTER_EMPTY              | after the transport to the shutter, the clamp is unexpected empty |
| 0x0150XXXX <b>0110</b> XXXX | STACKER_NOT_EMPTY                   | unexpected notes in shutter after reject/retract                  |
| 0x0150XXXX <b>0120</b> XXXX | DRIVE_TO_SHUTTER_FAILED             | moving money to shutter failed                                    |
| 0x0150XXXX <b>0130</b> XXXX | SHUTTER_MANIPULATION_DETECTED       | missing exception text  |

| Code                        | Class                    |   |
|-----------------------------|--------------------------|---|
| 0x <b>0160</b> XXXXXXXXXXXX | DISPENSE_TRANSPORT       |   |
| Code                        | Component                |   |
| 0x0160 <b>1980</b> XXXXXXXX | DISPENSE_TRANSPORT       |   |
| Code                        | ERROR                    | Meaning   |
| 0x0160XXXX <b>0020</b> XXXX | SCAN_TIMEOUT             | time for dispense reached, value holds current cassette number                          |
| 0x0160XXXX <b>0022</b> XXXX | SCAN_TIMEOUT_ADDITIONAL  | timeout for additional dispense reached, value holds current cassette number            |
| 0x0160XXXX <b>0024</b> XXXX | REFERENCE_TIMEOUT        | timeout for reference reached, value is 0   |
| 0x0160XXXX <b>0026</b> XXXX | CHECK_TIMEOUT            | timeout for check transport reached, value is 0 or cassette number                      |
| 0x0160XXXX <b>0040</b> XXXX | DISPENSE_FAILED          | dispense interrupted because an external event, value holds the current cassette number |
| 0x0160XXXX <b>0042</b> XXXX | DISPENSE_ERROR           | dispense failed because an error appears, value holds the current cassette number       |
| 0x0160XXXX <b>0044</b> XXXX | EMPTY_CASSETTE_DISPENSE  | dispense failed because cassette went empty.  |
| 0x0160XXXX <b>0046</b> XXXX | EMPTY_CASSETTE_REFERENCE | reference failed because cassette went empty  |
| 0x0160XXXX <b>0050</b> XXXX | REFERENCE_FAILED         | reference failed, value holds the cassette number                                       |
| 0x0160XXXX <b>0052</b> XXXX | REFERENCE_ERROR          | reference interrupted because an error appears, value holds the cassette number         |
| 0x0160XXXX <b>0060</b> XXXX | CHECK_ERROR              | check transport failed in case of a motor error, value is 0                             |
| 0x0160XXXX <b>0070</b> XXXX | INVALID_CASSETTE_CODE    | undefined cassette code detected, value holds undefined cassette code                   |
| 0x0150XXXX <b>0080</b> XXXX | CASSETTE_EXCHANGE_ERROR  | main motor error during cassette exchanged, value is 0                                  |
| 0x0150XXXX <b>0090</b> XXXX | MAIN_MOTOR_ERROR         | main motor error during dispense, value holds last hardware state of the mainMotor      |
| 0x0150XXXX <b>00A0</b> XXXX | MAIN_MOTOR_STOPPED       | main motor stopped during dispense problems   |
| 0x0150XXXX <b>00B0</b> XXXX | TRANSPORT_LOCK           | transport lock during dispense, value holds current cassette number                     |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0170</b> XXXXXXXXXXXX | DMA188    |
| Code                        | Component |
| 0x0170 <b>0F00</b> XXXXXXXX | DMA0      |
| 0x0170 <b>0F10</b> XXXXXXXX | DMA1      |

| Code                        | Class                       |                                     |
|-----------------------------|-----------------------------|-------------------------------------|
| 0x <b>0180</b> XXXXXXXXXXX  | DOUBLE_DETECTION_CONTROLLER |                                     |
| Code                        | Component                   |                                     |
| 0x0180 <b>1310</b> XXXXXXXX | DDU_CONTROLLER              |                                     |
| Code                        | ERROR                       | Meaning                             |
| 0x0180XXXX <b>0010</b> XXXX | WRITE_ERROR                 | write error detected                |
| 0x0180XXXX <b>0020</b> XXXX | READ_ERROR                  | read error detected                 |
| 0x0180XXXX <b>0030</b> XXXX | NO_ACK_HIGH_LOW             | controller did not response in time |
| 0x0180XXXX <b>0040</b> XXXX | NO_ACK_LOW_FOR_MEASURING    | controller not ready for measuring  |
| 0x0180XXXX <b>0050</b> XXXX | NO_ACK_HIGH_FOR_MEASURING   | controller did not finish measuring |

| Code                        | Class                   |  |
|-----------------------------|-------------------------|--|
| 0x <b>0190</b> XXXXXXXXXXXX | DOUBLE_DETECTION_UNIT   |  |
| Code                        | Component               |  |
| 0x0190 <b>1940</b> XXXXXXXX | DOUBLE_DETECTION_UNIT   |  |
| Code                        | ERROR                   | Meaning  |
| 0x0190XXXX <b>0010</b> XXXX | GET_DATA_ERROR          | error when receiving data from controller                  |
| 0x0190XXXX <b>0020</b> XXXX | INIT_FAILED             | current regulation failed                                  |
| 0x0190XXXX <b>0030</b> XXXX | START_NOTE_UNKOWN       | note not referenced yet                                    |
| 0x0190XXXX <b>0032</b> XXXX | START_FAILED            | start not possible   |
| 0x0190XXXX <b>0040</b> XXXX | HIGH_CURRENT_DIFFERENCE | current difference between left and right channel too high |

| Code                        | Class      |
|-----------------------------|------------|
| 0x <b>01A0</b> XXXXXXXXXXXX | DRIVER_USB |
| Code                        | Component  |
| 0x01A0 <b>0200</b> XXXXXXXX | DRIVER_USB |

| Code                        | Class        |
|-----------------------------|--------------|
| 0x <b>01B0</b> XXXXXXXXXXXX | DRIVER_RS232 |
| Code                        | Component    |
| 0x01B0 <b>0230</b> XXXXXXXX | PC_RS232     |
| 0x01B0 <b>0240</b> XXXXXXXX | MUX_RS232    |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>01B2</b> XXXXXXXXXXXX | USBN9603  |
| Code                        | Component |
| 0x01B2 <b>0160</b> XXXXXXXX | USB_N9603 |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>01C0</b> XXXXXXXXXXXX | TL16C552  |
| Code                        | Component |
| 0x01C0 <b>0130</b> XXXXXXXX | UART1     |
| 0x01C0 <b>0140</b> XXXXXXXX | UART2     |
| 0x01C0 <b>0150</b> XXXXXXXX | TL16552_P |

| Code                        | Class  |
|-----------------------------|--------|
| 0x <b>01D0</b> XXXXXXXXXXXX | EEPROM |

| Code                         | Class         |
|------------------------------|---------------|
| 0x <b>01E0</b> XXXXXXXXXXXXX | ERROR_HANDLER |
|                              |               |
| Code                         | Component     |

| Code                        | Class              |   |
|-----------------------------|--------------------|---|
| 0x <b>01F0</b> XXXXXXXXXXXX | FORK               |   |
| Code                        | Component          |   |
| 0x01F0 <b>0B30</b> XXXXXXXX | SINGLE_REJECT_FORK |   |
| Code                        | ERROR              | Meaning   |
| 0x01F0XXXX <b>0010</b> XXXX | ON_FAILED          | switching on failed, value is 0                       |
| 0x01F0XXXX <b>0011</b> XXXX | ON_TOO_SLOW        | switching on was too slow, value is switch time in ms |

| 0x01F0XXXX <b>0020</b> XXXX | OFF_FAILED   | switching off failed, value is 0   |
|-----------------------------|--------------|--|
| 0x01F0XXXX <b>0021</b> XXXX | OFF_TOO_SLOW | switching off was too slow, value is switch time in ms                   |
| 0x01F0XXXX <b>0022</b> XXXX | BLOCKED      | fork is in wrong position (checked in scanning)                          |
| 0x01F0XXXX <b>0030</b> XXXX | NOT_ON       | the state of a fork is off, without it has been switched off, value is 0 |
| 0x01F0XXXX <b>0040</b> XXXX | NOT_OFF      | the state of a fork is on, without it has been switched on, value is 0   |
| 0x01F0XXXX <b>0050</b> XXXX | ON_NOT_FREE  | fork could not switched on, because fork is not free, value is 0         |
| 0x01F0XXXX <b>0060</b> XXXX | OFF_NOT_FREE | fork could not switched off, because fork is not free, value is 0        |

| Code                        | Class                |
|-----------------------------|----------------------|
| 0x <b>0200</b> XXXXXXXXXXXX | HALL_SENSOR          |
| Code                        | Component            |
| 0x0200 <b>1200</b> XXXXXXXX | HALL_SENSOR_STACKER  |
| 0x0200 <b>1210</b> XXXXXXXX | HALL_SENSOR_SACKHOLE |
| 0x0200 <b>1220</b> XXXXXXXX | HALL_SENSOR_DEAD_END |
| 0x0200 <b>1230</b> XXXXXXXX | HALL_SENSOR_SHUTTER  |

| Code                        | Class           |
|-----------------------------|-----------------|
| 0x <b>0208</b> XXXXXXXXXXXX | HT1381          |
| Code                        | Component       |
| 0x0208 <b>0100</b> XXXXXXXX | REAL_TIME_CLOCK |

| Code                        | Class           |                                      |
|-----------------------------|-----------------|--------------------------------------|
| 0x <b>0208</b> XXXXXXXXXXXX | HT1381          |                                      |
| Code                        | Component       |                                      |
| 0x0208 <b>0100</b> XXXXXXXX | REAL_TIME_CLOCK |                                      |
| Code                        | ERROR           | Meaning                              |
| 0x0208XXXX <b>0010</b> XXXX | CLOCK_NOT_SET   | the clock is not set yet, value is 0 |

| Code                        | Class                |
|-----------------------------|----------------------|
| 0x <b>0210</b> XXXXXXXXXXXX | INTERRUPT_HANDLER    |
| Code                        | Component            |
| 0x0210 <b>0020</b> XXXXXXXX | INTERRUPT_CONTROLLER |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0220</b> XXXXXXXXXXXX | IO_TABLE  |
| Code                        | Component |
| 0x0220 <b>0060</b> XXXXXXXX | IO_TABLE  |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0228</b> XXXXXXXXXXXX | LED       |
| Code                        | Component |
| 0x0228 <b>16F0</b> XXXXXXXX | LED_RIGHT |
| 0x0228 <b>16F2</b> XXXXXXXX | LED_LEFT  |

| Code                        | Class                 |  |
|-----------------------------|-----------------------|--|
| 0x <b>022A</b> XXXXXXXXXXXX | LIFTING_COMB          |  |
| Code                        | Component             |  |
| 0x022A <b>18B0</b> XXXXXXXX | LIFTING_COMB          |  |
| Code                        | ERROR                 | Meaning  |
| 0x022AXXXX <b>0001</b> XXXX | INITIALIZATION_FAILED | serious errors occurred during the initialization, position not reached (photo-sensors or motor defect or not connected or hw damaged) |
| 0x022AXXXX <b>0002</b> XXXX | SELF_TEST_FAILED      | serious errors occurred during the initialization, position not reached (photo-sensors or motor defect or not connected or hw damaged) |
| 0x022AXXXX <b>0004</b> XXXX | POSITION_NOT_REACHED  | device jammed during movement to target, sensor-cabling defect or not plugged, value holds target position                             |
| 0x022AXXXX <b>0006</b> XXXX | POSITION_NOT_LEFT     | device jammed, sensor-cabling defect or not<br>plugged = device did not leave current<br>position, value holds source position         |
| 0x022AXXXX <b>000A</b> XXXX | MOTOR_FAILURE         | motor did not start, check motor, cabling and if power is available (24V)  |
| 0x022AXXXX <b>0010</b> XXXX | MOVE_TOO_SLOW         | a warning, if the time for a movement between the two positions is too low. Maybe the device is soiled                                 |

| Code                        | Class                 |
|-----------------------------|-----------------------|
| 0x <b>0230</b> XXXXXXXXXXXX | PHOTO_SENSOR          |
| Code                        | Component             |
| 0x0230 <b>0400</b> XXXXXXXX | SENSOR_STACKER_WHEEL  |
| 0x0230 <b>0410</b> XXXXXXXX | SENSOR_RETRACT_REJECT |

| 0x0230 <b>0420</b> XXXXXXXX | SENSOR_CATCH_LEFT             |
|-----------------------------|-------------------------------|
| 0x0230 <b>0430</b> XXXXXXXX | SENSOR_END_LEFT               |
| 0x0230 <b>0440</b> XXXXXXXX | SENSOR_CATCH_RIGHT            |
| 0x0230 <b>0450</b> XXXXXXXX | SENSOR_END_RIGHT              |
| 0x0230 <b>0460</b> XXXXXXXX | SENSOR_SHUTTER_OPEN_LOCKED    |
| 0x0230 <b>0470</b> XXXXXXXX | SENSOR_SHUTTER_CLOSED         |
| 0x0230 <b>0480</b> XXXXXXXX | SENSOR_MAGNET_TO_STACKER      |
| 0x0230 <b>0490</b> XXXXXXXX | SENSOR_MAGNET_TO_REJECT       |
| 0x0230 <b>04A0</b> XXXXXXXX | SENSOR_SINGLE_REJECT_TRAY_    |
|                             | POSITION                      |
| 0x0230 <b>0510</b> XXXXXXXX | SENSOR_LIFTING_COMB_COLLECT   |
| 0x0230 <b>0520</b> XXXXXXXX | SENSOR_LIFTING_COMB_TRANPORT  |
| 0x0230 <b>0530</b> XXXXXXXX | SENSOR_CONTROL_GEAR_DISPENSE_ |
|                             | TRANSPORT                     |
| 0x0230 <b>0540</b> XXXXXXXX | SENSOR_CONTROL_GEAR_OUTPUT_   |
|                             | TRANSPORT                     |
| 0x0230 <b>0710</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_1       |
| 0x0230 <b>0720</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_2       |
| 0x0230 <b>0730</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_3       |
| 0x0230 <b>0740</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_4       |
| 0x0230 <b>0750</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_5       |
| 0x0230 <b>0760</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_6       |
| 0x0230 <b>0770</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_7       |
| 0x0230 <b>0780</b> XXXXXXXX | SENSOR_EMPTY_CASSETTE_8       |
| 0x0230 <b>0805</b> XXXXXXXX | SENSOR_TRANSPORT_2            |
| 0x0230 <b>0825</b> XXXXXXXX | SENSOR_TRANSPORT_22           |
| 0x0230 <b>0830</b> XXXXXXXX | SENSOR_TRANSPORT_26           |
| 0x0230 <b>0835</b> XXXXXXXX | SENSOR_TRANSPORT_27           |
| 0x0230 <b>0840</b> XXXXXXXX | SENSOR_TRANSPORT_28           |
| 0x0230 <b>0845</b> XXXXXXXX | SENSOR_TRANSPORT_33           |
| 0x0230 <b>0850</b> XXXXXXXX | SENSOR_TRANSPORT_35           |
|                             |                               |

| Code                        | Class                |   |
|-----------------------------|----------------------|---|
| 0x <b>0240</b> XXXXXXXXXXXX | MAGNET_WITH_SENSOR   |   |
| Code                        | Component            |   |
| 0x0240 <b>0910</b> XXXXXXXX | MAGNET_SINGLE_REJECT |   |
| 0x0240 <b>0B20</b> XXXXXXXX | MAGNET_RR_BOX        |   |
| Code                        | ERROR                | Meaning   |
| 0x0240XXXX <b>0010</b> XXXX | TEST_FAILED          | the test of the magnet failed, value holds the state of the magnet. |

| Code                        | Class                    |
|-----------------------------|--------------------------|
| 0x <b>0250</b> XXXXXXXXXXXX | MAGNET                   |
| Code                        | Component                |
| 0x0250 <b>0900</b> XXXXXXXX | MAGNET_FOR_SINGLE_REJECT |
| 0x0250 <b>0920</b> XXXXXXXX | MAGNET_REJECT_RETRACT    |
| 0x0250 <b>0A10</b> XXXXXXXX | MAGNET_CASSETTE_1        |
| 0x0250 <b>0A20</b> XXXXXXXX | MAGNET_CASSETTE_2        |
| 0x0250 <b>0A30</b> XXXXXXXX | MAGNET_CASSETTE_3        |
| 0x0250 <b>0A40</b> XXXXXXXX | MAGNET_CASSETTE_4        |
| 0x0250 <b>0A50</b> XXXXXXXX | MAGNET_CASSETTE_5        |
| 0x0250 <b>0A60</b> XXXXXXXX | MAGNET_CASSETTE_6        |
| 0x0250 <b>0A70</b> XXXXXXXX | MAGNET_CASSETTE_7        |
| 0x0250 <b>0A80</b> XXXXXXXX | MAGNET_CASSETTE_8        |
| 0x0250 <b>0A90</b> XXXXXXXX | ALL_CASSETTE_MAGNETS     |

| Code                        | Class         |   |
|-----------------------------|---------------|---|
| 0x <b>0260</b> XXXXXXXXXXXX | MAIN_MOTOR    |   |
| Code                        | Component     |   |
| 0x0260 <b>1810</b> XXXXXXXX | MAIN_MOTOR    |   |
| Code                        | ERROR         | Meaning   |
| 0x0260XXXX <b>0010</b> XXXX | START_TIMEOUT | timeout during motor startup  |
| 0x0260XXXX <b>0015</b> XXXX | START_ERROR   | start failed, value holds response from controller @see MotorController::Response |
| 0x0260XXXX <b>0020</b> XXXX | STOP_TIMEOUT  | timeout during motor slowdown   |
| 0x0260XXXX <b>0025</b> XXXX | STOP_ERROR    | stop failed, value holds response from controller @see MotorController::Response  |
| 0x0260XXXX <b>0030</b> XXXX | OFF_TIMEOUT   | timeout during motor off  |
| 0x0260XXXX <b>0050</b> XXXX | HW_FAILURE    | main motor error occur  |

| Code                        | Class                 |
|-----------------------------|-----------------------|
| 0x <b>0270</b> XXXXXXXXXXXX | MOTOR_CONTROLLER      |
| Code                        | Component             |
| 0x0270 <b>1820</b> XXXXXXXX | CLAMP_DRIVE_MOTOR     |
| 0x0270 <b>1830</b> XXXXXXXX | CLAMP_BELT_MOTOR      |
| 0x0270 <b>1840</b> XXXXXXXX | SHUTTER_DC_MOTOR      |
| 0x0270 <b>1850</b> XXXXXXXX | SHUTTER_STEPPER_MOTOR |
| 0x0270 <b>1860</b> XXXXXXXX | SINGLE_REJECT_MOTOR   |
| 0x0270 <b>18A2</b> XXXXXXXX | CONTROL_GEAR_MOTOR    |

| Code                        | ERROR  | Meaning                                       |
|-----------------------------|--|---|
| 0x0270XXXX <b>0010</b> XXXX | MOTOR_CONTROLLER_START_NO_OK                 | error during motor start                      |
| 0x0270XXXX <b>0020</b> XXXX | MOTOR_CONTROLLER_START_STATE_<br>NO_OK       | motor state does not allow to start the motor |
| 0x0270XXXX <b>0030</b> XXXX | MOTOR_CONTROLLER_START_SERIAL_<br>ERROR      | serial error during motor start               |
| 0x0270XXXX <b>0040</b> XXXX | MOTOR_CONTROLLER_STOP_NO_OK                  | error during motor stop                       |
| 0x0270XXXX <b>0050</b> XXXX | MOTOR_CONTROLLER_STOP_SERIAL_<br>ERROR       | serial error during motor stop                |
| 0x0270XXXX <b>0060</b> XXXX | MOTOR_CONTROLLER_START_<br>LOGICAL_ERROR     | logical error during motor start              |
| 0x0270XXXX <b>0070</b> XXXX | MOTOR_CONTROLLER_SLOWDOWN_NO_<br>OK          | error during motor slowdown                   |
| 0x0270XXXX <b>0080</b> XXXX | MOTOR_CONTROLLER_SLOWDOWN_<br>SERIAL_ERROR   | serial error during motor slowdown            |
| 0x0270XXXX <b>0090</b> XXXX | MOTOR_CONTROLLER_OFF_NO_OK                   | error during motor off                        |
| 0x0270XXXX <b>0100</b> XXXX | MOTOR_CONTROLLER_OFF_SERIAL_<br>ERROR        | serial error during motor off                 |
| 0x0270XXXX <b>0110</b> XXXX | MOTOR_CONTROLLER_GETHWSTATE_<br>SERIAL_ERROR | serial error during getting hardware state    |
| 0x0270XXXX <b>0120</b> XXXX | MOTOR_CONTROLLER_SENDBYTE_<br>SERIAL_ERROR   | serial error during sending a byte            |

| Code                        | Class            |  |
|-----------------------------|------------------|--|
| 0x <b>0278</b> XXXXXXXXXXXX | NMC9346          |  |
| Code                        | Component        |  |
| 0x0278 <b>0E90</b> XXXXXXXX | COLLECTOR_EEPROM |  |
| Code                        | ERROR            | Meaning  |
| 0x0278XXXX <b>0010</b> XXXX | WRITE_ERROR      | write to eeprom failed, value is 0, eeprom could be defect, not connected  |
| 0x0278XXXX <b>0020</b> XXXX | READ_ERROR       | read from eeprom failed, value is 0, eeprom could be defect, not connected |

| Code                        | Class        |  |
|-----------------------------|--------------|--|
| 0x <b>0279</b> XXXXXXXXXXXX | NMC93468     |  |
| Code                        | Component    |  |
| 0x0279 <b>0D30</b> XXXXXXXX | NMC_EEPROM_1 |  |
| 0x0279 <b>0D40</b> XXXXXXXX | NMC_EEPROM_2 |  |
| 0x0279 <b>0D50</b> XXXXXXXX | NMC_EEPROM_3 |  |
| 0x0279 <b>0D60</b> XXXXXXXX | NMC_EEPROM_4 |  |
| 0x0279 <b>0D70</b> XXXXXXXX | NMC_EEPROM_5 |  |
| 0x0279 <b>0D80</b> XXXXXXXX | NMC_EEPROM_6 |  |
| 0x0279 <b>0D90</b> XXXXXXXX | NMC_EEPROM_7 |  |
| 0x0279 <b>0DA0</b> XXXXXXXX | NMC_EEPROM_8 |  |
| Code                        | ERROR        | Meaning  |
| 0x0279XXXX <b>0010</b> XXXX | WRITE_ERROR  | write to eeprom failed, value is 0, eeprom could be defect, not connected  |
| 0x0279XXXX <b>0020</b> XXXX | READ_ERROR   | read from eeprom failed, value is 0, eeprom could be defect, not connected |

| Code                        | Class |
|-----------------------------|-------|
| 0x <b>0280</b> XXXXXXXXXXXX | NOTE  |

| Code                        | Class                      |  |
|-----------------------------|----------------------------|--|
| 0x <b>0290</b> XXXXXXXXXXXX | OUTPUT_TRANSPORT_CMD_V4    |  |
| Code                        | Component                  |  |
| 0x0290 <b>1970</b> XXXXXXXX | OUTPUT_TRANSPORT           |  |
| Code                        | ERROR                      | Meaning  |
| 0x0290XXXX <b>0010</b> XXXX | INIT_FROM_UNDEFINED_FAILED | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0020</b> XXXX | INIT_CLAMP_ERR1            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0030</b> XXXX | INIT_CLAMP_ERR2            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0040</b> XXXX | INIT_CLAMP_ERR3            | search for the lost clamp failed, value is $\ensuremath{\mathtt{0}}$ |
| 0x0290XXXX <b>0050</b> XXXX | INIT_CLAMP_ERR4            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0060</b> XXXX | INIT_CLAMP_ERR5            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0070</b> XXXX | INIT_CLAMP_ERR6            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0080</b> XXXX | INIT_CLAMP_ERR7            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>0090</b> XXXX | INIT_CLAMP_ERR8            | search for the lost clamp failed, value is $\boldsymbol{0}$          |
| 0x0290XXXX <b>00A0</b> XXXX | INIT_CLAMP_ERR9            | search for the lost clamp failed, value is $\boldsymbol{0}$          |

|                             |   | •   |
|-----------------------------|---|---|
| 0x0290XXXX <b>00B0</b> XXXX | INIT_CIRCLE_FORK_ERR1                     | circlefork initialization or movement with a lost clamp failed  |
| 0x0290XXXX <b>00C0</b> XXXX | INIT_CIRCLE_FORK_ERR2                     | circlefork initialization or movement with a lost clamp failed  |
| 0x0290XXXX <b>00D0</b> XXXX | INIT_CIRCLE_FORK_ERR3                     | circlefork initialization or movement with a lost clamp failed  |
| 0x0290XXXX <b>00F0</b> XXXX | LEAVE_REJECT_POSITION_MOVE_<br>ERR1       | circlefork could not move correctly when leaving the reject-position  |
| 0x0290XXXX <b>0100</b> XXXX | LEAVE_REJECT_POSITION_MOVE_<br>ERR2       | circlefork could not move correctly when leaving the reject-position  |
| 0x0290XXXX <b>0110</b> XXXX | LEAVE_REJECT_POSITION_MOVE_<br>ERR3       | circlefork could not move correctly when leaving the reject-position  |
| 0x0290XXXX <b>0120</b> XXXX | LEAVE_REJECT_POSITION_INIT_ERR            | circlefork could not initialize when leaving the reject-position  |
| 0x0290XXXX <b>0130</b> XXXX | MOVE_TO_REJECT_POSITION_INIT_<br>ERR1     | circlefork could not initialize when driving into reject-position   |
| 0x0290XXXX <b>0135</b> XXXX | MOVE_TO_REJECT_POSITION_INIT_<br>ERR2     | clamp cannot leave sackhole-position  |
| 0x0290XXXX <b>0140</b> XXXX | MOVE_TO_REJECT_POSITION_INIT_<br>ERR3     | circlefork could not initialize when driving into reject-position   |
| 0x0290XXXX <b>0150</b> XXXX | DRIVE_CLAMP_TO_SENSOR_RECOVER_<br>ERR     | driving to sensor failed, clamp is lost between sensors, retry also failed  |
| 0x0290XXXX <b>0160</b> XXXX | HANDLE_CLAMP_BETWEEN_SENSORS_<br>INIT_ERR | when driving to sensor, a circlefork error occurred and the circlefork init failed                                  |
| 0x0290XXXX <b>0170</b> XXXX | DRIVE_TO_PROBLEM                          | driving to sensor failed, a retry is initiated, value is target position (@see ClampTarget)                         |
| 0x0290XXXX <b>0175</b> XXXX | DRIVE_TO_ERROR                            | all retries failed when driving to a sensor, value is target position (@see ClampTarget)                            |
| 0x0290XXXX <b>0178</b> XXXX | DRIVE_TO_EXCEPTION                        | an exception  |
| 0x0290XXXX <b>0180</b> XXXX | OPEN_ERROR                                | circlefork could not reach the open position when opening the clamp, value is 0                                     |
| 0x0290XXXX <b>0190</b> XXXX | NOT_IN_STACKER                            | after opening the clamp, the hall-sensor<br>for the stacker-position does not report<br>stacker position            |
| 0x0290XXXX <b>01A0</b> XXXX | CLOSE_ERROR                               | after closing the clamp, the hall-sensor<br>for the stacker-position does not report<br>stacker position            |
| 0x0290XXXX <b>01B0</b> XXXX | CLOSE_MOVE_ERROR                          | circlefork movement for closing the clamp failed  |
| 0x0290XXXX <b>01C0</b> XXXX | TRANSPORT_EJECT_DARK_JAM                  | both photosensors in shutter remain dark<br>for more than 2s when driving money out of<br>clamp (eject) = JAM !     |
| 0x0290XXXX <b>01D0</b> XXXX | TRANSPORT_OFFER_DARK_JAM                  | rear photosensor in shutter remains dark for more than 2s when offering money = JAM !                               |
| 0x0290XXXX <b>01E0</b> XXXX | TRANSPORT_RETRACT_LIGHT_JAM               | rear photosensor in shutter did not become dark within 300ms when retracting the offered money = JAM !              |
| 0x0290XXXX <b>01F0</b> XXXX | RECOVER_ERROR                             | when trying to drive clamp back to start position (in retry), the circlefork initialization failed                  |
| 0x0290XXXX <b>0200</b> XXXX | CLAMP_NOT_FOUND                           | in start-up, when driving from reject-<br>position into sack-hole, the clamp does not<br>appear at sack-hole sensor |
| 0x0290XXXX <b>0210</b> XXXX | CIRCLE_FORK_INIT_ERR                      | in start-up, when driving from reject-  |
|                             |   |   |

|                             |                       | position into sack-hole, the circlefork initialization failed                                   |
|-----------------------------|-----------------------|---|
| 0x0290XXXX <b>0220</b> XXXX | TYPE_UNKOWN           | the detected type (via cable-coding) is unknown   |
| 0x0290XXXX <b>0230</b> XXXX | TRANSPORT_FAILED      | belt-movement error, motor or photo-sensor error  |
| 0x0290XXXX <b>0240</b> XXXX | PHOTO_SENSOR_ERROR1   | photo-sensors could not be switched on or off (internal FW-error), value is 0                   |
| 0x0290XXXX <b>0250</b> XXXX | PHOTO_SENSOR_ERROR2   | photo-sensors could not be switched on or off (internal FW-error), value is 0                   |
| 0x0290XXXX <b>0260</b> XXXX | TRANSPORT_NOT_IN_SAFE | system is out of the safe, safety switch is open  |
| 0x0290XXXX <b>0270</b> XXXX | CLAMP_OPEN_ERROR      | clamp cannot unlock, recovery error   |
| 0x0290XXXX <b>0280</b> XXXX | CLAMP_CLOSE_ERROR     | clamp cannot close, recovery error  |
| 0x0290XXXX <b>0290</b> XXXX | CLAMP_TO_HL3_ERROR    | cannot move clamp to HL3, recovery error  |
| 0x0290XXXX <b>02A0</b> XXXX | CLAMP_TO_HL1_ERROR    | cannot move clamp to HL1, recovery error  |
| 0x0290XXXX <b>02B0</b> XXXX | CLAMP_TO_HL3_WARNING  | driving to sensor HL3 failed, a retry is initiated, value is target position (@see ClampTarget) |
| 0x0290XXXX <b>02C0</b> XXXX | CLAMP_TO_HL1_WARNING  | driving to sensor HL1 failed, a retry is initiated, value is target position (@see ClampTarget) |

| Code                        | Class                   |   |
|-----------------------------|-------------------------|---|
| 0x <b>0291</b> XXXXXXXXXXXX | OUTPUT_TRANSPORT_HDM    |   |
| Code                        | Component               |   |
| 0x0291 <b>1970</b> XXXXXXXX | OUTPUT_TRANSPORT        |   |
| Code                        | ERROR                   | Meaning   |
| 0x0291XXXX <b>0010</b> XXXX | INIT_FAILED             | the initialization failed, subcomponents like the lifting-comb, the bundle-reject-fork or the control-gear may have caused the error                |
| 0x0291XXXX <b>0020</b> XXXX | DRIVE_TO_STACKER_FAILED | driving the note bundle into the stacker position failed, bundle-reject-fork, control-gear, lifting-comb or photo sensors may have caused the error |
| 0x0291XXXX <b>0030</b> XXXX | DRIVE_TO_SHUTTER_FAILED | driving the note bundle into the shutter position failed, bundle-reject-fork, control-gear, lifting-comb or photo sensors may have caused the error |
| 0x0291XXXX <b>0040</b> XXXX | DRIVE_TO_REJECT_FAILED  | driving the note bundle into the reject position failed, bundle-reject-fork, control-gear, lifting-comb or photo sensors may have caused the error  |
| 0x0291XXXX <b>0041</b> XXXX | OFFERING_FAILED         | driving the note bundle into the offer position failed, main motor, photo sensors or stucked notes may have caused the error                        |
| 0x0291XXXX <b>0042</b> XXXX | EJECTING_FAILED         | ejecting the note bundle failed main motor, photo sensors or stucked notes may have caused the error  |
| 0x0291XXXX <b>0043</b> XXXX | REJECTING_FAILED        | rejecting offered notes failed, photo<br>sensors or stucked notes may have caused   |

|                             |   | the error   |
|-----------------------------|---|---|
| 0x0291XXXX <b>0050</b> XXXX | PHOTO_SENSORS_FAILED                      | Photo sensor task failed, no photo sensor access/release (hardware broken?)         |
| 0x0291XXXX <b>0060</b> XXXX | MAIN_MOTOR_FAILED                         | Main motor could not be started, hardware broken?                                   |
| 0x0291XXXX <b>0070</b> XXXX | NOTES_JAM                                 | Unexpected note at photo sensor   |
| 0x0291XXXX <b>0080</b> XXXX | LIGHT_JAM                                 | Sensor light timeout, note has not reached the desired sensor in time               |
| 0x0291XXXX <b>0090</b> XXXX | DARK_JAM                                  | Sensor dark timeout, note has not left the desired sensor in time                   |
| 0x0291XXXX <b>00A0</b> XXXX | OFFER_NOTES_FAILED                        | offering the notes failed, shutter could not open or note bundle stuck in transport |
| 0x0291XXXX <b>00B0</b> XXXX | EJECT_NOTES_FAILED                        | ejecting the notes failed, shutter could not open or note bundle stuck in transport |
| 0x0291XXXX <b>00C0</b> XXXX | CLOSE_OFFER_FAILED                        | an error occurred while trying to backtrack the note bundle or closing the shutter  |
| 0x0291XXXX <b>00D0</b> XXXX | TRANSPORT_OFFER_LIGHT_JAM                 | bundle could not be moved to the shutter, bundle is stuck in the transport          |
| 0x0291XXXX <b>00E0</b> XXXX | TRANSPORT_EJECT_DARK_JAM                  | bundle could not be ejected, bundle covers the shutter sensor too long              |
| 0x0291XXXX <b>00F0</b> XXXX | TRANSPORT_REJECT_DARK_JAM                 | bundle could not be rejected, bundle covers the shutter sensor too long             |
| 0x0291XXXX <b>0100</b> XXXX | TRANSPORT_FAILED                          | motor or photo sensors failed while transporting the bundle                         |
| 0x0291XXXX <b>0110</b> XXXX | CONTROL_GEAR_INIT_ERROR                   | control gear init error   |
| 0x0291XXXX <b>0120</b> XXXX | CONTROL_GEAR_OUTPUT_POS_<br>NOT_REACHED   | control-gear cannot reach output-position   |
| 0x0291XXXX <b>0130</b> XXXX | CONTROL_GEAR_DISPENSE_POS_<br>NOT_REACHED | control-gear cannot reach dispense-position   |

| Code                        | Class                                   |   |
|-----------------------------|---|---|
| 0x <b>02A0</b> XXXXXXXXXXXX | PRESSURE_REGULATOR                      |   |
| Code                        | Component                               |   |
| 0x02A0 <b>1510</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_1           |   |
| 0x02A0 <b>1520</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_2           |   |
| 0x02A0 <b>1530</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_3           |   |
| 0x02A0 <b>1540</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_4           |   |
| 0x02A0 <b>1550</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_5           |   |
| 0x02A0 <b>1560</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_6           |   |
| 0x02A0 <b>1570</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_7           |   |
| 0x02A0 <b>1580</b> XXXXXXXX | PRESSURE_REGULATOR_CASSETTE_8           |   |
| Code                        | ERROR                                   | Meaning   |
| 0x02A0XXXX <b>0010</b> XXXX | AD_CONVERTER_LOCKED_IN_<br>UPDATE       | ad-converter was locked during updating, so<br>the method returns the last status value,<br>value holds the user who locks the<br>converter |
| 0x02A0XXXX <b>0011</b> XXXX | AD_CONVERTER_LOCKED_IN_GET_PRE<br>SSURE | ad-converter was locked during getting pressure, so the method returns 0 as pressure value, value holds the user who                        |

|                             |                                  | locks the converter   |
|-----------------------------|----------------------------------|---|
| 0x02A0XXXX <b>0012</b> XXXX | SELFTEST_ERROR                   | self test error   |
| 0x02A0XXXX <b>0020</b> XXXX | SELECTED_RESOURCE_LOCKED         | <pre>photosensortask was locked during getting pressure, so the method returns 0 as pressure value, value holds getHandle()</pre> |
| 0x02A0XXXX <b>0030</b> XXXX | INVALID_STATE                    | state-machine of update() used with invalid status, value holds the invalid status  |
| 0x02A0XXXX <b>0040</b> XXXX | FIND_CURRENT_FAILED              | initializing of the pressure by current incrementing failed, value holds pressure value   |
| 0x02A0XXXX <b>0041</b> XXXX | INIT_WITHOUT_CASSETTE_<br>FAILED | initializing of cmos data failed, value holds pressure value  |
| 0x02A0XXXX <b>0042</b> XXXX | INIT_WITH_CASSETTE_FAILED        | initializing of cmos data with inserted cassette failed, value holds pressure value   |
| 0x02A0XXXX <b>0050</b> XXXX | PRESSURE_REGULATION_FAILED       | pressure regulation failed, value is 0  |
| 0x02A0XXXX <b>0070</b> XXXX | MAX_PRESSURE_TOO_LOW             | the maximum pressure reaches not the old<br>work-pressure, value holds the highest<br>pressure value, which was found             |
| 0x02A0XXXX <b>0080</b> XXXX | PRESSURE_NOT_FOUND               | the necessary pressure could not be reached, value holds the target pressure  |

| Code                        | Class         |
|-----------------------------|---------------|
| 0x <b>02B0</b> XXXXXXXXXXXX | PROTOCOL_BYTE |

| Code                        | Class                          |
|-----------------------------|--------------------------------|
| 0x <b>02B8</b> XXXXXXXXXXXX | PROTOCOL_NCR_IBM / PROTOCOL_HW |
| Code                        | Component                      |
| 0x0220 <b>0290</b> XXXXXXXX | PROTOCOL_NCR_IBM               |

| Code                        | Class            |
|-----------------------------|------------------|
| 0x02C0XXXXXXXXXXXXX         | PROTOCOL_CONSOLE |
| Code                        | Component        |
| 0x02C0 <b>0280</b> XXXXXXXX | PROTOCOL_WIN32   |

| Code                        | Class             |
|-----------------------------|-------------------|
| 0x <b>02D0</b> XXXXXXXXXXXX | PROTOCOL_ISO      |
| Code                        | Component         |
| 0x02D0 <b>0250</b> XXXXXXXX | PROTOCOL_ISO_PC   |
| 0x02D0 <b>0260</b> XXXXXXXX | PROTOCOL_ISO_SCOP |

| Code                        | Class           |                                      |
|-----------------------------|-----------------|--------------------------------------|
| 0x <b>02E0</b> XXXXXXXXXXXX | REAL_TIME_CLOCK |                                      |
| Code                        | Component       |                                      |
| 0x02E0 <b>0100</b> XXXXXXXX | REAL_TIME_CLOCK |                                      |
| Code                        | ERROR           | Meaning                              |
| 0x02E0XXXX <b>0010</b> XXXX | CLOCK_NOT_SET   | the clock is not set yet, value is 0 |

| Code                        | Class              |  |
|-----------------------------|--------------------|--|
| 0x <b>02F0</b> XXXXXXXXXXXX | REJECT_RETRACT_BOX |  |
| Code                        | Component          |  |
| 0x02F0 <b>1620</b> XXXXXXXX | REJECT_RETRACT_BOX |  |
| Code                        | ERROR              | Meaning  |
| 0x02F0XXXX <b>0010</b> XXXX | SWITCH_TRAY_FAILED | switch between reject/retract tray via magnet failed, the desired direction is stored in value @see Tray Either the magnet or the photo-sensor is defective or the mechanic is not working properly (e.g. blocked) |
| 0x02F0XXXX <b>0020</b> XXXX | SELFTEST_ERROR     | Selftest of the reject-/retract-tray failed  |

| Code                         | Class      |
|------------------------------|------------|
| 0x <b>02F5</b> XXXXXXXXXXXXX | REJECT_BOX |
| Code                         | Component  |
| 0x02F5 <b>1625</b> XXXXXXXX  | REJECT_BOX |

| Code                         | Class  |
|------------------------------|--------|
| 0x <b>02F8</b> XXXXXXXXXXXXX | ROLLER |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0300</b> XXXXXXXXXXXX | RTOS      |
| Code                        | Component |
| 0x0300 <b>0040</b> XXXXXXXX | RTOS      |

| Code                        | Class             |
|-----------------------------|-------------------|
| 0x <b>0310</b> XXXXXXXXXXXX | SCAN_PHOTO_SENSOR |

| Code                        | Component                  |  |
|-----------------------------|----------------------------|--|
| 0x0310 <b>0610</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_1 |  |
| 0x0310 <b>0620</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_2 |  |
| 0x0310 <b>0630</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_3 |  |
| 0x0310 <b>0640</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_4 |  |
| 0x0310 <b>0650</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_5 |  |
| 0x0310 <b>0660</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_6 |  |
| 0x0310 <b>0670</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_7 |  |
| 0x0310 <b>0680</b> XXXXXXXX | SENSOR_DISPENSE_CASSETTE_8 |  |
| 0x0310 <b>0800</b> XXXXXXXX | SENSOR_TRANSPORT_1         |  |
| 0x0310 <b>0810</b> XXXXXXXX | SENSOR_TRANSPORT_18        |  |
| 0x0310 <b>0815</b> XXXXXXXX | SENSOR_TRANSPORT_19        |  |
| 0x0310 <b>0820</b> XXXXXXXX | SENSOR_TRANSPORT_21        |  |
| 0x0310 <b>0835</b> XXXXXXXX | SENSOR_TRANSPORT_27        |  |
| 0x0310 <b>1940</b> XXXXXXXX | DOUBLE_DETECTION_UNIT      |  |
| Code                        | ERROR                      | Meaning  |
| 0x0310XXXX <b>0010</b> XXXX | LIGHT_JAM                  | a note did not reach the sensor in a given time, value holds   |
| 0x0310XXXX <b>0020</b> XXXX | DARK_JAM                   | a note did not leave the sensor in a given time, value holds the current motor-clock or timestamp          |
| 0x0310XXXX <b>0030</b> XXXX | UNEXPECTED_NOTE            | an unexpected note was seen at the sensor, value holds the current motor-clock or timestamp                |
| 0x0310XXXX <b>0040</b> XXXX | NOTE_EARLY                 | a note did reach the sensor too early, value holds the expected note arrival in motor-clocks or timestamps |
| 0x0310XXXX <b>0050</b> XXXX | NOTE_LATE                  | a note did reach the sensor too late, value holds the expected note arrival in motor-clocks or timestamps  |
| 0x0310XXXX <b>0100</b> XXXX | NULL_POINTER               | the current note-pointer is 0 (internal firmware-error), value is 0  |
| 0x0310XXXX <b>010</b> 1XXXX | NEW_FAILED                 | no more memory for a new note (internal firmware-error), value is 0  |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0320</b> XXXXXXXXXXXX | SCOP      |
|                             |           |
| Code                        | Component |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>0330</b> XXXXXXXXXXXX | Shutter   |
| Code                        | Component |
| 0x0330 <b>1910</b> XXXXXXXX | Shutter   |

| Code                        | ERROR                              | Meaning   |
|-----------------------------|------------------------------------|---|
| 0x0330XXXX <b>0010</b> XXXX | TEST_ERROR                         | the shutter test failed, value holds the shutter position   |
| 0x0330XXXX <b>0020</b> XXXX | SELFTEST_ERROR                     | the shutter self test failed  |
| 0x0330XXXX <b>0030</b> XXXX | OPEN_ERROR                         | the opening of the shutter failed, value holds the shutter position   |
| 0x0330XXXX <b>0040</b> XXXX | CLOSE_ERROR                        | the closing of the shutter failed, value holds the shutter position   |
| 0x0330XXXX <b>0050</b> XXXX | OFFER_ERROR                        | the offering of the money failed, value holds the shutter position  |
| 0x0330XXXX <b>0060</b> XXXX | TIMEOUT_WHILE_TESTING              | timeout during testing the shutter, value holds shutter position  |
| 0x0330XXXX <b>0070</b> XXXX | NOT_INSTALLED_OR_UNKOWN            | type detect error, the shutter is not installed or unknown, value is 0  |
| 0x0330XXXX <b>0080</b> XXXX | TIMEOUT_WHILE_LEAVING_<br>POSITION | the shutter left a position and found the target position not in time. value holds the position of the shutter  |
| 0x0330XXXX <b>0081</b> XXXX | CLOSE_BLOCKED                      | just a warning that the shutter was blocked during closing, if shutter is always blocked after the retries, it comes to an CLOSE_ERROR. Value holds number of retries |

| Code                        | Class                              |   |
|-----------------------------|------------------------------------|---|
| 0x <b>0331</b> XXXXXXXXXXXX | CMD_V4_IN_SAFE_SHUTTER             |   |
| Code                        | Component                          |   |
| 0x0331 <b>1910</b> XXXXXXXX | Shutter                            |   |
| Code                        | ERROR                              | Meaning   |
| 0x0331XXXX <b>0010</b> XXXX | TEST_ERROR                         | the shutter test failed, value holds the shutter position   |
| 0x0331XXXX <b>0011</b> XXXX | SELFTEST_ERROR                     | the shutter self test failed  |
| 0x0331XXXX <b>0020</b> XXXX | OPEN_ERROR                         | the opening of the shutter failed, value holds the shutter position   |
| 0x0331XXXX <b>0030</b> XXXX | CLOSE_ERROR                        | the closing of the shutter failed, value holds the shutter position   |
| 0x0331XXXX <b>0040</b> XXXX | OFFER_ERROR                        | the offering of the money failed, value holds the shutter position  |
| 0x0331XXXX <b>0050</b> XXXX | TIMEOUT_WHILE_TESTING              | timeout during testing the shutter, value holds shutter position  |
| 0x0331XXXX <b>0060</b> XXXX | NOT_INSTALLED_OR_UNKOWN            | type detect error, the shutter is not installed or unknown, value is 0  |
| 0x0331XXXX <b>0070</b> XXXX | TIMEOUT_WHILE_LEAVING_<br>POSITION | the shutter left a position and found the target position not in time. value holds the position of the shutter  |
| 0x0331XXXX <b>0080</b> XXXX | CLOSE_BLOCKED                      | just a warning that the shutter was blocked during closing, if shutter is always blocked after the retries, it comes to an CLOSE_ERROR. Value holds number of retries |
| 0x0331XXXX <b>0081</b> XXXX | OPEN_BLOCKED                       | just a warning that the shutter was blocked during opening, if shutter is always blocked after the retries, it comes to an OPEN_ERROR. Value holds number of retries  |
| 0x0331XXXX <b>0082</b> XXXX | POSITION_ERROR                     | unknown shutter position, possible broken sensors   |

| Code                        | Class                              |   |
|-----------------------------|------------------------------------|---|
| 0x <b>0332</b> XXXXXXXXXXXX | CMD_V4_OUT_SAFE_SHUTTER            |   |
| Code                        | Component                          |   |
| 0x0332 <b>1910</b> XXXXXXXX | Shutter                            |   |
| Code                        | ERROR                              | Meaning   |
| 0x0332XXXX <b>0010</b> XXXX | TEST_ERROR                         | the shutter test failed, value holds the shutter position   |
| 0x0332XXXX <b>0011</b> XXXX | SELFTEST_ERROR                     | the shutter self test failed  |
| 0x0332XXXX <b>0020</b> XXXX | OPEN_ERROR                         | the opening of the shutter failed, value holds the shutter position   |
| 0x0332XXXX <b>0030</b> XXXX | CLOSE_ERROR                        | the closing of the shutter failed, value holds the shutter position   |
| 0x0332XXXX <b>0040</b> XXXX | OFFER_ERROR                        | the offering of the money failed, value holds the shutter position  |
| 0x0332XXXX <b>0050</b> XXXX | TIMEOUT_WHILE_TESTING              | timeout during testing the shutter, value holds shutter position  |
| 0x0332XXXX <b>0060</b> XXXX | NOT_INSTALLED_OR_UNKOWN            | type detect error, the shutter is not installed or unknown, value is 0  |
| 0x0332XXXX <b>0070</b> XXXX | TIMEOUT_WHILE_LEAVING_<br>POSITION | the shutter left a position and found the target position not in time. value holds the position of the shutter  |
| 0x0332XXXX <b>0080</b> XXXX | CLOSE_BLOCKED                      | just a warning that the shutter was blocked during closing, if shutter is always blocked after the retries, it comes to an CLOSE_ERROR. Value holds number of retries |
| 0x0332XXXX <b>0081</b> XXXX | OPEN_BLOCKED                       | just a warning that the shutter was blocked during opening, if shutter is always blocked after the retries, it comes to an OPEN_ERROR. Value holds number of retries  |
| 0x0332XXXX <b>0082</b> XXXX | POSITION_ERROR                     | unknown shutter position, possible broken sensors   |

| Code                         | Class                 |   |
|------------------------------|-----------------------|---|
| 0x <b>0333</b> XXXXXXXXXXXXX | HDM_SHUTTER           |   |
| Code                         | Component             |   |
| 0x0333 <b>1910</b> XXXXXXXX  | Shutter               |   |
| Code                         | ERROR                 | Meaning   |
| 0x0333XXXX <b>0010</b> XXXX  | TEST_ERROR            | the shutter test failed, value holds the shutter position           |
| 0x0333XXXX <b>0011</b> XXXX  | SELFTEST_ERROR        | the shutter self test failed  |
| 0x0333XXXX <b>0020</b> XXXX  | OPEN_ERROR            | the opening of the shutter failed, value holds the shutter position |
| 0x0333XXXX <b>0030</b> XXXX  | CLOSE_ERROR           | the closing of the shutter failed, value holds the shutter position |
| 0x0333XXXX <b>0040</b> XXXX  | OFFER_ERROR           | the offering of the money failed, value holds the shutter position  |
| 0x0333XXXX <b>0050</b> XXXX  | TIMEOUT_WHILE_TESTING | timeout during testing the shutter, value holds shutter position    |

| 0x0333XXXX <b>0060</b> XXXX | NOT_INSTALLED_OR_UNKOWN            | type detect error, the shutter is not installed or unknown, value is 0  |
|-----------------------------|------------------------------------|---|
| 0x0333XXXX <b>0070</b> XXXX | TIMEOUT_WHILE_LEAVING_<br>POSITION | the shutter left a position and found the target position not in time. value holds the position of the shutter  |
| 0x0333XXXX <b>0080</b> XXXX | CLOSE_BLOCKED                      | just a warning that the shutter was blocked during closing, if shutter is always blocked after the retries, it comes to an CLOSE_ERROR. Value holds number of retries |
| 0x0333XXXX <b>0081</b> XXXX | OPEN_BLOCKED                       | just a warning that the shutter was blocked during opening, if shutter is always blocked after the retries, it comes to an OPEN_ERROR. Value holds number of retries  |
| 0x0333XXXX <b>0082</b> XXXX | POSITION_ERROR                     | unknown shutter position, possible broken sensors   |

| Code<br>0x <b>0334</b> XXXXXXXXXXXXX | Class SHUTTER PROTECT PC8xxx |   |
|--------------------------------------|------------------------------|---|
| Code 0x033419A0XXXXXXXX              | Component SHUTTER_PROTECT    |   |
| Code                                 | ERROR                        | Meaning   |
| 0x0334XXXX <b>0010</b> XXXX          | PROTECT_COM_ERROR            | the communication to the shutter protect failed (communication defect or not connected)         |
| 0x0334XXXX <b>0015</b> XXXX          | PROTECT_INIT_FAILD           | the shutter protect initialization failed (shutter protect hw not initialization or hw damaged) |
| 0x0334XXXX <b>0020</b> XXXX          | PROTECT_MEASUREMEND_WRONG    | shutter protect measurement wrong   |
| 0x0334XXXX <b>0025</b> XXXX          | PROTECT_MANIPULATION         | shutter protect detected manipulation   |
| 0x0334XXXX <b>0030</b> XXXX          | PROTECT_WRONG                | the shutter protect detect front building   |

| Code                         | Class                     |   |
|------------------------------|---------------------------|---|
| 0x <b>0335</b> XXXXXXXXXXXXX | SHUTTER_PROTECT_IR_LS     |   |
| Code                         | Component                 |   |
| 0x0335 <b>19A0</b> XXXXXXXX  | SHUTTER_PROTECT           |   |
| Code                         | ERROR                     | Meaning   |
| 0x0335XXXX <b>0010</b> XXXX  | PROTECT_COM_ERROR         | the communication to the shutter protect failed (communication defect or not connected)         |
| 0x0335XXXX <b>0015</b> XXXX  | PROTECT_INIT_FAILD        | the shutter protect initialization failed (shutter protect hw not initialization or hw damaged) |
| 0x0335XXXX <b>0020</b> XXXX  | PROTECT_MEASUREMEND_WRONG | shutter protect measurement wrong   |
| 0x0335XXXX <b>0025</b> XXXX  | PROTECT_MANIPULATION      | shutter protect detected manipulation   |
| 0x0335XXXX <b>0030</b> XXXX  | PROTECT_WRONG             | the shutter protect detect front building   |

| Code                        | Class              |   |
|-----------------------------|--------------------|---|
| 0x <b>0340</b> XXXXXXXXXXXX | SINGLE_REJECT_TRAY |   |
| Code                        | Component          |   |
| 0x0340 <b>1900</b> XXXXXXXX | SINGLE_REJECT_TRAY |   |
| Code                        | ERROR              | Meaning   |
| 0x0340XXXX <b>0010</b> XXXX | INIT_FAILED        | the init of the single reject tray failed, value is 0 |
| 0x0340XXXX <b>0020</b> XXXX | IS_EMPTY_ERROR     | isEmpty() throws exception, value is 0                |
| 0x0340XXXX <b>0030</b> XXXX | POSITION_ERROR     | unknown target position                               |

| Code                        | Class                          |                                       |
|-----------------------------|--------------------------------|---------------------------------------|
| 0x <b>0350</b> XXXXXXXXXXXX | SINGLE_REJECT_MOTOR            |                                       |
| Code                        | Component                      |                                       |
| 0x0350 <b>1860</b> XXXXXXXX | SINGLE_REJECT_TRAY             |                                       |
| Code                        | ERROR                          | Meaning                               |
| 0x0350XXXX <b>0010</b> XXXX | INIT_FAILED                    | initial sequence failed               |
| 0x0350XXXX <b>0020</b> XXXX | DRIVE_TO_STANDARD_TRAY_FAILED  | driving to standard tray failed       |
| 0x0350XXXX <b>0030</b> XXXX | DRIVE_TO_RESERVE_TRAY_FAILED   | driving to reserve tray failed        |
| 0x0350XXXX <b>0040</b> XXXX | DRIVE_TO_EMPTY_POSITION_FAILED | driving to empty position failed      |
| 0x0350XXXX <b>0050</b> XXXX | WAIT_FOR_COMPLETION_FAILED     | timeout during waiting for completion |

| Code                        | Class            |                                  |
|-----------------------------|------------------|----------------------------------|
| 0x <b>0360</b> XXXXXXXXXXXX | STACKER_WHEEL    |                                  |
| Code                        | Component        |                                  |
| 0x0360 <b>1880</b> XXXXXXXX | STACKER_WHEEL    |                                  |
| Code                        | ERROR            | Meaning                          |
| 0x0360XXXX <b>0010</b> XXXX | STEP_TIMEOUT     | timeout during set execution     |
| 0x0360XXXX <b>0020</b> XXXX | STEP_MOTOR_ERROR | motor error while driving a step |
| 0x0360XXXX <b>0030</b> XXXX | SCAN_STEP_FAILED | scan step execution failed       |
| 0x0360XXXX <b>0040</b> XXXX | INIT_FAILED      | initial sequence failed          |
| 0x0360XXXX <b>0050</b> XXXX | NULL_POINTER     | null pointer exception           |

| Code                        | Class         |
|-----------------------------|---------------|
| 0x <b>0370</b> XXXXXXXXXXXX | STATE_MACHINE |
| Code                        | Component     |
| 0x0370 <b>4020</b> XXXXXXXX | STATE_MACHINE |

| Code                        | ERROR                      | Meaning                     |
|-----------------------------|----------------------------|-----------------------------|
| 0x0370XXXX <b>0010</b> XXXX | STACKER_NOT_FREE           | unexpected notes in stacker |
| 0x0370XXXX <b>0020</b> XXXX | CLAMP_IS_EMPTY             | general error               |
| 0x0370XXXX <b>0022</b> XXXX | CLAMP_NOT_EMPTY            | general error               |
| 0x0370XXXX <b>0030</b> XXXX | SHUTTER_NOT_EMPTY          | general error               |
| 0x0370XXXX <b>0040</b> XXXX | SHUTTER_CLOSED             | general error               |
| 0x0370XXXX <b>0042</b> XXXX | SHUTTER_NOT_OPEN           | general error               |
| 0x0370XXXX <b>0044</b> XXXX | SHUTTER_NOT_CLOSED         | general error               |
| 0x0370XXXX <b>0050</b> XXXX | CLAMP_OPEN_FAILED          | general error               |
| 0x0370XXXX <b>0060</b> XXXX | PRESENT_FAILED             | general error               |
| 0x0370XXXX <b>0070</b> XXXX | REJECT_RETRACT_FAILED      | general error               |
| 0x0370XXXX <b>0072</b> XXXX | REJECT_FAILED              | general error               |
| 0x0370XXXX <b>0074</b> XXXX | RETRACT_FAILED             | general error               |
| 0x0370XXXX <b>0080</b> XXXX | CLEAR_SINGLE_REJECT_FAILED | general error               |
| 0x0370XXXX <b>0090</b> XXXX | DEVICE_LOCK_ERROR          | general error               |
| 0x0370XXXX <b>0100</b> XXXX | DRIVE_TO_SHUTTER_FAILED    | general error               |
| 0x0370XXXX <b>0102</b> XXXX | DRIVE_TO_STACKER_FAILED    | general error               |
| 0x0370XXXX <b>0104</b> XXXX | DRIVE_TO_REJECT_FAILED     | general error               |
| 0x0370XXXX <b>0200</b> XXXX | TEST_DISPENSE_FAILED       | general error               |

| Code                        | Class                        |  |
|-----------------------------|------------------------------|--|
| 0x <b>0372</b> XXXXXXXXXXXX | CLEARING_MACHINE             |  |
| Code                        | Component                    |  |
| 0x0372 <b>2002</b> XXXXXXXX | CLEARING_MACHINE             |  |
| Code                        | ERROR                        | Meaning                                      |
| 0x0372XXXX <b>0010</b> XXXX | START_CLEARING_FAILED        | due to open security switch                  |
| 0x0372XXXX <b>0015</b> XXXX | POWER_NOT_ENABLED            | power is not enabled                         |
| 0x0372XXXX <b>0020</b> XXXX | CLEAR_INTO_BOX_ERROR         | context: see previous errors for true reason |
| 0x0372XXXX <b>0030</b> XXXX | CLEAR_OUTPUT_TRANSPORT_ERROR | context: see previous errors for true reason |
| 0x0372XXXX <b>0040</b> XXXX | DEVICE_LOCKED                | please reset device lock                     |
| 0x0372XXXX <b>0050</b> XXXX | CLEAR_SINGLE_REJECT_ERROR    | context: see previous errors for true reason |
| 0x0372XXXX <b>0060</b> XXXX | CHECK_TRANSPORT_ERROR        | context: see previous errors for true reason |
| 0x0372XXXX <b>0070</b> XXXX | REJECT_FAILED                | context: see previous errors for true reason |
| 0x0372XXXX <b>0080</b> XXXX | RETRACT_FAILED               | context: see previous errors for true reason |
| 0x0372XXXX <b>0090</b> XXXX | DRIVE_TO_REJECT_FAILED       | context: see previous errors for true reason |

| 0x0372XXXX <b>00A0</b> XXXX | CLAMP_OPEN_FAILED       | <pre>clamp could not open (stepper, photo-sensor or clamp defect)</pre> |
|-----------------------------|-------------------------|---|
| 0x0372XXXX <b>00B0</b> XXXX | DRIVE_TO_STACKER_FAILED | context: see previous errors for true reason                            |
| 0x0372XXXX <b>00C0</b> XXXX | DISPENSER_INIT_FAILED   | hardware failure in dispenser   |

| Code                        | Class                       |  |
|-----------------------------|-----------------------------|--|
| 0x <b>0374</b> XXXXXXXXXXXX | STANDARD_MACHINE            |  |
| Code                        | Component                   |  |
| 0x0374 <b>2001</b> XXXXXXXX | STANDARD_MACHINE            |  |
| Code                        | ERROR                       | Meaning  |
| 0x0374XXXX <b>0001</b> XXXX | INVALID_COMMAND             | command not allowed in this state                |
| 0x0374XXXX <b>0010</b> XXXX | DISPENSE_FAILED             | context: see previous errors for true reason     |
| 0x0374XXXX <b>0011</b> XXXX | SINGLE_REJECT_FORK_BLOCKED  | single reject fork is blocked in reject position |
| 0x0374XXXX <b>0020</b> XXXX | OPEN_SHUTTER_FAILED         | shutter error                                    |
| 0x0374XXXX <b>0022</b> XXXX | CLOSE_SHUTTER_FAILED        | shutter error                                    |
| 0x0374XXXX <b>0024</b> XXXX | TEST_SHUTTER_FAILED         | shutter error                                    |
| 0x0374XXXX <b>0030</b> XXXX | CLAMP_IN_SHUTTER_EMPTY      | no notes in clamp                                |
| 0x0374XXXX <b>0040</b> XXXX | STACKER_NOT_EMPTY           | unexpected notes in stacker                      |
| 0x0374XXXX <b>0050</b> XXXX | DRIVE_TO_SHUTTER_FAILED     | context: see previous errors for true reason     |
| 0x0374XXXX <b>0052</b> XXXX | DRIVE_TO_STACKER_FAILED     | context: see previous errors for true reason     |
| 0x0374XXXX <b>0054</b> XXXX | DRIVE_TO_REJECT_FAILED      | context: see previous errors for true reason     |
| 0x0374XXXX <b>0060</b> XXXX | PRESENT_FAILED              | context: see previous errors for true reason     |
| 0x0374XXXX <b>0061</b> XXXX | PRESENT_FROM_STACKER_FAILED | context: see previous errors for true reason     |
| 0x0374XXXX <b>0062</b> XXXX | EJECT_FAILED                | context: see previous errors for true reason     |
| 0x0374XXXX <b>0070</b> XXXX | CLOSE_OFFER_FAILED          | context: see previous errors for true reason     |
| 0x0374XXXX <b>0080</b> XXXX | CLAMP_OPEN_FAILED           | context: see previous errors for true reason     |
| 0x0374XXXX <b>0090</b> XXXX | CLAMP_NOT_EMPTY             | clamp should be empty                            |
| 0x0374XXXX <b>00A0</b> XXXX | SHUTTER_NOT_EMPTY           | shutter should be empty                          |
| 0x0374XXXX <b>00B0</b> XXXX | RETRACT_FAILED              | context: see previous errors for true reason     |
| 0x0374XXXX <b>00C0</b> XXXX | REJECT_FAILED               | context: see previous errors for true reason     |

| Code                        | Class         |
|-----------------------------|---------------|
| 0x <b>0376</b> XXXXXXXXXXXX | ERROR_MACHINE |

| Code                        | ERROR        | Meaning      |
|-----------------------------|--------------|--------------|
| 0x0376XXXX <b>0010</b> XXXX | RESET_FAILED | reset failed |

| Code                        | Class                  |                                 |
|-----------------------------|------------------------|---------------------------------|
| 0x <b>0378</b> XXXXXXXXXXXX | CONTROL_MACHINE        |                                 |
| Code                        | Component              |                                 |
| 0x0378 <b>2000</b> XXXXXXXX | CONTROL_MACHINE        |                                 |
| Code                        | ERROR                  | Meaning                         |
| 0x0378XXXX <b>0010</b> XXXX | TOO_MANY_FAILED_RESETS | failed resets are limited to 10 |
| 0x0378XXXX <b>0020</b> XXXX | UNCAUGHT_EXCEPTION     | an unexpected exception occured |

Meaning

dma channel was locked

parameters (e.g. 0)

reasons can be: DMA0\_LOCKED, invalid

| Code                        | Class               |
|-----------------------------|---------------------|
| 0x <b>0380</b> XXXXXXXXXXX  | STATUS_CODE_DISPLAY |
| Code                        | Component           |
| 0x0380 <b>0D20</b> XXXXXXXX | STATUS_CODE         |

| Code                        | Class   |
|-----------------------------|---------|
| 0x <b>0390</b> XXXXXXXXXXXX | STEPPER |

| Code                        | Class              |
|-----------------------------|--------------------|
| 0x <b>0392</b> XXXXXXXXXXXX | TIMER_STEPPER      |
| Code                        | Component          |
| 0x0392 <b>1010</b> XXXXXXXX | STEPPER_CASSETTE_1 |
| 0x0392 <b>1020</b> XXXXXXXX | STEPPER_CASSETTE_2 |
| 0x0392 <b>1030</b> XXXXXXXX | STEPPER_CASSETTE_3 |
| 0x0392 <b>1040</b> XXXXXXXX | STEPPER_CASSETTE_4 |
| 0x0392 <b>1050</b> XXXXXXXX | STEPPER_CASSETTE_5 |
| 0x0392 <b>1060</b> XXXXXXXX | STEPPER_CASSETTE_6 |
| 0x0392 <b>1070</b> XXXXXXXX | STEPPER_CASSETTE_7 |
| 0x0392 <b>1080</b> XXXXXXXX | STEPPER_CASSETTE_8 |
| 0x0392 <b>1100</b> XXXXXXXX | STEPPER_23         |
| 0x0392 <b>18B2</b> XXXXXXXX | STEPPER_5          |
| 0x0392 <b>18C2</b> XXXXXXXX | STEPPER_6          |
| Code                        | ERROR              |
| 0x0392XXXX <b>0010</b> XXXX | DMA0_LOCKED        |

START\_FAILED

0x0392XXXX**0020**XXXX

| Code                        | Class                     |
|-----------------------------|---------------------------|
| 0x <b>03A0</b> XXXXXXXXXXXX | SWITCH                    |
| Code                        | Component                 |
| 0x03A0 <b>1600</b> XXXXXXXX | REJECT_RETRACT_BOX_SWITCH |
| 0x03A0 <b>1610</b> XXXXXXXX | IN_SAFE_SWITCH            |
| 0x03A0 <b>1630</b> XXXXXXXX | DOOR_SWITCH               |
| 0x03A0 <b>1640</b> XXXXXXXX | DOOR_ENABLE_SWITCH        |
| 0x03A0 <b>1650</b> XXXXXXXX | SAFETY_SWITCH             |
| 0x03A0 <b>1660</b> XXXXXXXX | SAFETY_SWITCH_FLAG        |
| 0x03A0 <b>1670</b> XXXXXXXX | JUMPER_DOOR               |
| 0x03A0 <b>1680</b> XXXXXXXX | JUMPER_SCOP               |
| 0x03A0 <b>1690</b> XXXXXXXX | JUMPER_CLEAR_CMOS         |
| 0x03A0 <b>1698</b> XXXXXXXX | JUMPER_NEN                |
| 0x03A0 <b>16A0</b> XXXXXXXX | JUMPER_A                  |
| 0x03A0 <b>16B0</b> XXXXXXXX | JUMPER_B                  |
| 0x03A0 <b>16C0</b> XXXXXXXX | JUMPER_C                  |
| 0x03A0 <b>16D0</b> XXXXXXXX | JUMPER_D                  |

| Code                        | Class             |         |
|-----------------------------|-------------------|---------|
| 0x <b>03B0</b> XXXXXXXXXXXX | SYSTEM            |         |
| Code                        | Component         |         |
| 0x03B0 <b>0010</b> XXXXXXXX | SYSTEM_V4         |         |
| Code                        | ERROR             | Meaning |
| 0x03B0XXXX <b>0020</b> XXXX | RESPONSE_NOT_SEND | not use |

| Code                        | Class |
|-----------------------------|-------|
| 0x <b>03C0</b> XXXXXXXXXXXX | TASK  |

| Code                        | Class                 |                        |
|-----------------------------|-----------------------|------------------------|
| 0x <b>03C2</b> XXXXXXXXXXXX | HARDWARE_TASK         |                        |
| Code                        | Component             |                        |
| 0x03C2 <b>3030</b> XXXXXXXX | HARDWARE_TASK         |                        |
| Code                        | ERROR                 | Meaning                |
| 0x03C2XXXX <b>0010</b> XXXX | MACHINE_STATE_INVALID | unknown state          |
| 0x03C2XXXX <b>0020</b> XXXX | DEVICE_STATE_INVALID  | unknown value          |
| 0x03C2XXXX <b>0030</b> XXXX | COMP_STATE_INVALID    | invalid cassette state |
| 0x03C2XXXX <b>0040</b> XXXX | Manipulation          | Manipulation           |

| 0x03C2XXXX <b>0100</b> XXXX | PHOTO_SENSOR_ERROR   | general error   |
|-----------------------------|----------------------|---|
| 0x03C2XXXX <b>0110</b> XXXX | NO_CASSETTES         | general error   |
| 0x03C2XXXX <b>0120</b> XXXX | NO_OUTPUT_TRANSPORT  | invalid code on output-transport connector (or not connected) |
| 0x03C2XXXX <b>0130</b> XXXX | HARDWARE_DEFECT      | hardware defect   |
| 0x03C2XXXX <b>0140</b> XXXX | ERROR_RR_MAGNET      | magnet MA6 ( reject/retract-tray ) blocked or damaged         |
| 0x03C2XXXX <b>0141</b> XXXX | PLD_VERSION_ERROR    | Invalid PLD Version   |
| 0x03C2XXXX <b>0150</b> XXXX | ERROR_SR_MAGNET      | magnet MA2 ( singlereject) blocked or damaged                 |
| 0x03C2XXXX <b>0200</b> XXXX | MAILBOX_CREATE_ERROR | general error   |
| 0x03C2XXXX <b>0210</b> XXXX | RESPONSE_NOT_SEND    | internal error  |
| 0x03C2XXXX <b>0300</b> XXXX | UNCAUGHT_EXCEPTION   | internal error  |

| Code                        | Class                     |                         |
|-----------------------------|---------------------------|-------------------------|
| 0x <b>03C4</b> XXXXXXXXXXXX | PHOTO_SENSOR_TASK         |                         |
| Code                        | Component                 |                         |
| 0x03C4 <b>3000</b> XXXXXXXX | PHOTO_SENSOR_TASK         |                         |
| Code                        | ERROR                     | Meaning                 |
| 0x03C4XXXX <b>0010</b> XXXX | START_SENSORS_NO_OK       | hw-failure              |
| 0x03C4XXXX <b>0020</b> XXXX | INIT_SENSORS_NO_OK        | init failed, hw-failure |
| 0x03C4XXXX <b>0030</b> XXXX | ON_NO_OK                  | internal error          |
| 0x03C4XXXX <b>0040</b> XXXX | ON_CASSNR_NO_OK           | internal error          |
| 0x03C4XXXX <b>0050</b> XXXX | RELEASE_NO_OK             | internal error          |
| 0x03C4XXXX <b>0060</b> XXXX | OFF_NO_OK                 | internal error          |
| 0x03C4XXXX <b>0070</b> XXXX | SUSPEND_NO_OK             | internal error          |
| 0x03C4XXXX <b>0080</b> XXXX | RESUME_NO_OK              | internal error          |
| 0x03C4XXXX <b>0090</b> XXXX | ADJUST_NO_OK              | internal error          |
| 0x03C4XXXX <b>0100</b> XXXX | ADAPT_NO_OK               | internal error          |
| 0x03C4XXXX <b>0110</b> XXXX | SEND_RECEIVE_STATE        | internal error          |
| 0x03C4XXXX <b>0120</b> XXXX | SEND_RECEIVE_SENDER_NO_OK | internal error          |
| 0x03C4XXXX <b>0130</b> XXXX | SEND_RECEIVE_NO_RESPONSE  | internal error          |
| 0x03C4XXXX <b>0140</b> XXXX | INTERNAL_ERROR            | internal error          |
| 0x03C4XXXX <b>0150</b> XXXX | COVERED_PHOTOSENSOR       | internal error          |
| 0x03C4XXXX <b>0160</b> XXXX | PHOTOSENSOR_HW_FAILED     | internal error          |

| Code                         | Class        |
|------------------------------|--------------|
| 0x <b>03C6</b> XXXXXXXXXXXXX | COMMAND_TASK |

| Code                        | Component    |
|-----------------------------|--------------|
| 0x03C6 <b>3020</b> XXXXXXXX | COMMAND_TASK |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x03C8XXXXXXXXXXXXX         | LINE_TASK |
| Code                        | Component |
| 0x03C8 <b>3010</b> XXXXXXXX | LINE_TASK |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>03CA</b> XXXXXXXXXXXX | SCAN_TASK |
| Code                        | Component |
| 0x03CA <b>3040</b> XXXXXXXX | SCAN_TASK |

| Code                         | Class                     |  |
|------------------------------|---------------------------|--|
| 0x <b>03CB</b> XXXXXXXXXXXXX | CONTROLLER_TASK           |  |
| Code                         | Component                 |  |
| 0x03CB <b>3050</b> XXXXXXXX  | CONTROLLER_TASK           |  |
| Code                         | ERROR                     | Meaning  |
| 0x03CBXXXX <b>0010</b> XXXX  | SEND_TO_DEVICE_ERROR      | sending the data to the remote device failed, the device is out of operation or the communication is damaged |
| 0x03CBXXXX <b>0020</b> XXXX  | RECEIVE_FROM_DEVICE_ERROR | receiving data from the remote device failed, the device is out of operation or the communication is damaged |

| Code                        | Class                                |                                       |
|-----------------------------|--------------------------------------|---------------------------------------|
| 0x <b>03CC</b> XXXXXXXXXXXX | SELF_TEST                            |                                       |
| Code                        | Component                            |                                       |
| 0x03CC <b>4040</b> XXXXXXXX | SELF_TEST                            |                                       |
| Code                        | ERROR                                | Meaning                               |
| 0x03CCXXXX <b>0001</b> XXXX | BOARD_TEST_FAILED                    | controller self test failed           |
| 0x03CCXXXX <b>0002</b> XXXX | RAM_TEST_FAILED                      | RAM self test failed                  |
| 0x03CCXXXX <b>0010</b> XXXX | BCD_TEST_FAILED                      | Bcd self test failed                  |
| 0x03CCXXXX <b>0020</b> XXXX | INTERRUPT_CONTROLLER_TEST_<br>FAILED | interrupt controller self test failed |
| 0x03CCXXXX <b>0030</b> XXXX | THREAD_TEST_FAILED                   | thread self test failed               |
| 0x03CCXXXX <b>0040</b> XXXX | SEMAPHORE_TEST_FAILED                | Semaphore self test failed            |

| Code                        | Class          |   |
|-----------------------------|----------------|---|
| 0x <b>03D0</b> XXXXXXXXXXXX | TIMER188       |   |
| Code                        | Component      |   |
| 0x03D0 <b>0110</b> XXXXXXXX | TIMERO         |   |
| 0x03D0 <b>0111</b> XXXXXXXX | TIMER1         |   |
| 0x03D0 <b>0112</b> XXXXXXXX | TIMER2         |   |
| Code                        | ERROR          | Meaning   |
| 0x03D0XXXX <b>0001</b> XXXX | TIMER_NOT_FREE | timer start failed, because already in use, value is mode (@see Mode) |

| Code                        | Class     |
|-----------------------------|-----------|
| 0x <b>03E0</b> XXXXXXXXXXXX | TRACE     |
|                             |           |
| Code                        | Component |

| Code                        | Class |
|-----------------------------|-------|
| 0x <b>03F0</b> XXXXXXXXXXXX | USB   |

| Code                        | Class                 |
|-----------------------------|-----------------------|
| 0x <b>0400</b> XXXXXXXXXXXX | SEVEN_SEGMENT_DISPLAY |
| Code                        | Component             |
| 0x0400 <b>0D00</b> XXXXXXXX | DISPLAY_LOW           |
| 0x0400 <b>0D10</b> XXXXXXXX | DISPLAY_HIGH          |

| Code                        | Class       |
|-----------------------------|-------------|
| 0x <b>0410</b> XXXXXXXXXXXX | LOGICAL_USB |
| Code                        | Component   |
| 0x0410 <b>0210</b> XXXXXXXX | PC_USB      |
| 0x0410 <b>0220</b> XXXXXXXX | DEBUG_USB   |

| Code                        | Class         |  |
|-----------------------------|---------------|--|
| 0x <b>0500</b> XXXXXXXXXXXX | POWER_MANAGER |  |
| Code                        | Component     |  |
| 0x0500 <b>0001</b> XXXXXXXX | POWER_MANAGER |  |
| Code                        | ERROR         | Meaning  |
| 0x0500XXXX <b>0010</b> XXXX | IO_LOG        | set if it is necessary, after critical errors, to log the io-flags |

## Appendix V: DQC - Error stack

### Before firmware release 16.20:

The error stack contains the device status, cassette status and photosensor values for each command that was acknowledged with status 'E' or 'D'. For reasons of storage space and performance, only the useful data is saved and transmitted; code words, separators and similar characters that do not contain any data are not.

The error stack holds maximum of 10 entries, with the oldest being overwritten as soon as it is full.

| char | year[2];    |
|------|-------------|
| char | dot;        |
| char | month[2];   |
| char | dot2;       |
| char | date[2];    |
| char | comma ;     |
| char | hour[2];    |
| char | doubleDot;  |
| char | minute[2];  |
| char | doubleDot2; |
| char | second[2];  |
| char | comma1;     |
| char | len[4];     |
| char | sSw[1];     |
| char | dLoc[1];    |
| char | cas[1];     |
| char | shErr[1];   |
| char | shut[1];    |
| char | mon[1];     |
| char | ter[1];     |
| char | ts[2] ;     |
| char | tf[1];      |
| char | sr[1];      |
| char | dis[1];     |
| char | cex[1];     |
| char | door[1];    |
| char | doS[1];     |
|      |             |

| char type[1];  |  |  |
|--|--|--|
| char nVm[1];   |  |  |
| char sedm[1];  |  |  |
| char ICmd[2];  |  |  |
| char ISta[1];  |  |  |
| char sCle[1];  |  |  |
| char sRes[1];  |  |  |
| char tst[1];   |  |  |
| char sCod[2];  |  |  |
| char or[1];  |  |  |
| char transport[1];   |  |  |
| char cOut[1];  |  |  |
| char error[16];  |  |  |
| char warning[16];  |  |  |
| char len[4];   |  |  |
| char rSta[1];  |  |  |
| char rAct[4];  |  |  |
| char rRet[2];  |  |  |
| struct Cassette  |  |  |
| { // the following structure is repeated 8 times (for all cassettes supported) |  |  |
| char sta[1];   |  |  |
| char num[7];   |  |  |
| char cur[3];   |  |  |
| char rel[4];   |  |  |
| char val[8];   |  |  |
| char len[3];   |  |  |
| char tol[2];   |  |  |
| char act[4];   |  |  |
| char ndv[4];   |  |  |
| char low[4];   |  |  |
| char ld[2];  |  |  |
| char rej[3];   |  |  |
| } cassettes[Dispenser ::MAX_CASSETTES] ;                                       |  |  |
| char photoSensorData[40]   |  |  |

### From firmware release 16.20 and higher:

The error stack contains the date, time, firmware ID, device status, and the first 10 error and warning codes (each 16 Byte) for each command answered with the acknowledgment status 'E' or 'D'. For reasons of storage space and performance, only the useful data is saved and transmitted; code words and most separators are not. The error stack holds maximum of 10 entries, with the oldest being overwritten as soon as it is full.

Since the error stack has been modified during firmware development, but older error entries should not be lost during a FW update, the size of a total error stack entry is maybe larger than the actual amount of reference data. This is recognized by the filler bytes (Hex 0x00) at the end of the data.

### Structure

| char | year[2]         |                                 |
|------|-----------------|---------------------------------|
| char | dot             |                                 |
| char | month[2]        |                                 |
| char | dot2            |                                 |
| char | day[2]          |                                 |
| char | comma           |                                 |
| char | hour[2]         |                                 |
| char | doubleDot       |                                 |
| char | minute[2]       |                                 |
| char | doubleDot       |                                 |
| char | second[2]       |                                 |
| char | comma           |                                 |
| char | Firmware ID[61] | (Booter and FW ID as under DIL) |
| char | comma           |                                 |
| char | len[4]          |                                 |
| char | sSw[1]          |                                 |
| char | dLoc[1]         |                                 |
| char | cas[1]          |                                 |
| char | shErr[1]        |                                 |
| char | shut[1]         |                                 |
| char | mon[1]          |                                 |
| char | ter[1]          |                                 |
| char | ts[2]           |                                 |
| char | tf[1]           |                                 |

| char |                |
|------|----------------|
| char | dis[1]         |
| char | cex[1]         |
| char | door[1]        |
| char | doS[1]         |
| char | type[1]        |
| char | nVm[1]         |
| char | sedm[1]        |
| char | ICmd[2]        |
| char | ISta[1]        |
| char | sCle[1]        |
| char | sRes[1]        |
| char | tst[1]         |
| char | sCod[2]        |
| char | or[1]          |
| char | transport[1]   |
| char | cOut[1]        |
| char | shutProtect[1] |
| char | comma          |
| char | error0[16]     |
| char | doubleDot      |
| :    | :              |
| char | error8[16]     |
| char | doubleDot      |
| char | error9[16]     |
| char | comma          |
| char | warning0[16]   |
| char | doubleDot      |
| :    | :              |
| char | warning8[16]   |
| char | doubleDot      |
| char | warning9[16]   |
|      |                |

## Appendix X: Status areas

All statuses are described via code words and value. Code words are 2-10 characters (bytes) long. The upper limit in AZM-NG was 8.

## D - Device status

| Code word | Entry | Meaning   |                    |  |
|-----------|-------|---|--------------------|--|
| LEN=      | dddd, | Total length (incl. length specification)   | (decimal in ASCII) |  |
| S_SW=     | a,    | Safety switch C = switched O = open   | (ASCII)            |  |
| DLOC=     | a,    | Device lock after note retract N = no Y = yes, set  | (ASCII)            |  |
| CAS=      | a,    | Cassettes can be processed N = no Y = yes   | (ASCII)            |  |
| SHERR=    | a,    | Error on shutter B = blocked or cash trapping detection error N = no error  | (ASCII)            |  |
| SHUT=     | a,    | Shutter status C = closed M = missing O = open U = undefined or cash trapping detection error                       | (ASCII)            |  |
| MON=      | a,    | Cash output status N = Cash not accessible to customer P = Cash accessible to customer R = Retract W = Cash removed | (ASCII)            |  |
| TER=      | a,    | Transport error J = JAM M = Manipulation at output sensor O = OK  | (ASCII)            |  |

| Code word | Entry | Meaning  |         |
|-----------|-------|--|---------|
| TS=       | aa,   | Transport status (byte legend for transports:  1. Byte is the start position and the 2nd byte the target position)  0 = No notes existing  1 = Cassette  2 = Stacker  3 = Reject  4 = Stop over (output direction)  5 = Output position  8 = Retract  9 = Undefined position | (ASCII) |
| TF=       | a,    | Transport – free (transport status of the last device command)  N = Cash paths were not free  Y = Free cash paths and shutter closed   | (ASCII) |
| SR=       | a,    | Status of single reject switch O = OK R = Defective (transport direction reject) S = Defective (transport direction collecting tray)   | (ASCII) |
| DIS=      | a,    | Device error during dispensing E = Too many bundle rejects J = Repeat of 'Additional dispense' not possible M = Too many notes with incorrect dimensions N = Note dispensing not possible O = OK S = To many multiple dispenses  | (ASCII) |
| CEX=      | a,    | Cassette inventory changed N = no Y = yes  | (ASCII) |
| DOOR=     | a,    | Door switch status C = closed M = missing O = open   | (ASCII) |
| DO_S=     | a,    | Observe door contact during encryption N = no Y = yes  | (ASCII) |

| Code word | Entry | Meaning  |                    |
|-----------|-------|--|--------------------|
| TYPE=     | a,    | Device type U = Undefined F = Frontload R = Rearload   | (ASCII)            |
| N_VM=     | a,    | Number of dispenser modules 1 - 6  | (decimal in ASCII) |
| SEDM=     | a,    | SW EDM I = IV request necessary L = Line code missing O = Encryption active T = Transport code missing   | (ASCII)            |
| LCMD=     | aa,   | Specification and additional specification of the last command   | (ASCII)            |
| LSTA=     | a,    | Status code of the last command  | (ASCII)            |
| SCLE=     | a,    | Clearing Status (after RESET / Power up)  0 = Transport paths were free  1 = No cash accessible to customer; Reject OK  2 = Cash was accessible to customer; Retract OK  3 = Cash was accessible to customer. Meanwhile they were removed.  4 = Cash was not accessible to customer. An error occurred during clearing. (See SRES)  5 = Cash was accessible to customer. An error occurred during clearing. (See SRES) | (ASCII)            |
| SRES=     | a,    | Status code after RESET / Clearing / Power up  | (ASCII)            |
| TST=      | a,    | Self-test was active N = no Y = yes  | (ASCII)            |
| SCOD=     | aa,   | Current status display   | (ASCII)            |
| OR=       | a,    | Operator Request N = no W = Warning Y = yes  | (ASCII)            |

| Code word         | Entry                     | Meaning  |                        |
|-------------------|---------------------------|--|------------------------|
| TRANSPORT =       | a,                        | Output transport configuration A = in safe front B = in safe rear C = out safe rear D = out safe front E = out safe rear, PC8xxx - system F = out safe front, PC8xxx - system G = in safe rear, PC8xxx - system H = not yet realized for the CMD family U = ProCash 5100 (VCMD) * = unknown coding   | (ASCII)                |
| C_OUT=            | a,                        | CashOut available C = Minimum configuration missing (RR box + cash-out cassette) J = JAM (note jam) L = device lock M = Main motor DCM1 defective P = Start-up phase S = Safety switch T = Clamp transport defective Y = CashOut possible  | (ASCII)                |
| SHUT_PROT<br>ECT= | a,                        | Cash trapping detection O = OK, no error K = Cash trapping device detected M = Cash trapping device manipulation (e.g. color spraying) D = Cash trapping detection defective (e.g. no communication, not initialized, faultily initialized, implausibly initialized) U = Cash trapping detection not present (see shutter plug for coding) | (ASCII)                |
| ERROR=            | dddddd<br>dddddd<br>dddd, | Error number (digit $1 - 4 = $ class, $5 - 8 = $ object, $9 - 12 = $ error code, $13 - 16 = $ error value)   | (hexadecimal in ASCII) |
| WARNING=          | dddddd<br>dddddd<br>,     | Warning number (cf. interpretation of ERROR above)   | (hexadecimal in ASCII) |
|                   | ,                         | End character after last parameter   | (ASCII)                |

The contents of the two cells are only changed by commands that initiate device operations. (Reset, dispense transaction, ...)

### **Definitions**

**LEN** Contains the total length of the status range (incl. length specification).

**S\_SW** Status of the safety switch (is ascertained again for every device command with a specification A, B, C and G).

C = Closed; device in operating position

O = Open; device not in operating position

DLOC Device lock. Is set after DCQ (cash retained but not stored). Device lock enabled as soon as the clamp has reached the stacking position after retract (output position for the operator). If the clamp is not in the stacking position during a reset/clearing with a set device lock, it is moved to this position and opened. Any available cash can then be removed. A retract in the RR-box is not carried out

N = Lock not set

Y = Lock set, Reset per DFR command (RESET lock flag).

**CAS** General status of the cassettes

N = Cassettes cannot be processed

Y = Cassettes can be processed

At least 2 ready cassettes are needed to operate the CMD-V4: the RR-box as well as the cash-out cassette. Operability is not given if this minimum requirement is not fulfilled. The flag is set accordingly.

SHERR Shutter error

B = Blocked or cash trapping detection error

N = No error

This cell indicates whether or not a shutter error has occurred. If an error has occurred, the <SHUT> status can be evaluated. A cash trapping detection error is additionally registered in this cell and the status can be evaluated in <SHUT\_PROTECT>.

SHUT Shutter status

C = Closed and locked

M = MissingO = Open

U = Undefined or cash trapping detection error

The current status after the last transport command as well as after RESET / Clearing is managed here. The cell is additionally set following a cash trapping detection error.

MON Status of note output

N = No cash accessible to customer

P = Cash accessible to customer

R = Retract

W = Cash has been removed

The status switches to 'N' at the beginning of a dispensing. Switch to 'P' when the shutter is opened, i.e. it is no longer closed and locked. The flag is updated accordingly after note output, retract or RESET / CLEARING. A change to 'R' is made if the cash is no longer accessible to the customer, i.e. if the shutter is closed and the output sensor is free.

### TER Transport error

J = Banknote jam

M = Manipulation

O = OK; no error

The flag is set to 'J' (jam) if the CMD-V4 detects a note jam or if the stacking compartment is blocked. This is used together with the following flag 'TS' to determine where the cash is currently situated. Status 'M' indicates an output sensor that was probably covered by a manipulation.

### **TS** Transport status

This flag is divided into two parts. The CMD-V4 manages the flag in case of transports, dispensings, and clearing runs as follows:

Prior to the transport, the start position is stated in the 1st byte and in the 2nd byte the target position. If there is a note jam during transport **<TER>=J**, evaluation of the two bytes of the transport status helps identifying the area where the jam has occurred.

### Possible positions:

0 = No notes available 1 = Cassette

2 = Stacker 3 = Reject compartment 4 = Stop over (output) 5 = Removal position 8 = Retract compartment 9 = Undefined position

Appendix F (page Fehler! Textmarke nicht definiert.Fehler! Textmarke nicht definiert.) indicates the possible transport positions.

### **TF** Transport free

This is the status value for the cash paths after the last dispensing, reference value, reset flag, RESET or clearing command, or after power-on.

N = Cash paths were not free

Y = Cash paths were free and shutter closed

## SR Status of single reject deflector

O = OK

R = efect (Transportrichtung Reject)

S = Faulty (collecting tray transport direction)

This flag is set if the reject switch is faulty. Handling of the error in the CMD-V4 depends on the switch position:

Transport direction: collecting tray

This case concerns a status.

The CMD-V4 can continue to operate with limited capacity.

As soon as a single reject becomes necessary, the notes dispensed up to that point are lost. A note bundle reject then takes place.

Transport direction: Reject

In this case, further dispensing is impossible. The device can no longer be operated.

All notes dispensed so far are stored in the reject escrow (including counter increment). Troubleshooting must be completed with RESET. The flag is reset (**<SR>=O**) when this is done successfully.

### **DIS** Device error during dispensing

E = Too many bundle rejects

J = Repeat of an 'Additional dispense' not possible. During the process:

- A note jam was eliminated with a test note.
- Single reject could not be performed (single reject deflector missing or direction facing stacker).

M = Too many wrong-sized notes

N = Note cannot be dispensed

O = No error

S = Too many double dispenses

The CMD-V4 sets this flag to 'O' before the 1st note is being dispensed.

The event that has caused the device error is registered if necessary.

### **CEX** Cassettes available changed

N = no

Y = yes

The flag is set by the CMD-V4 if it detects that the number of cassettes available has changed.

This is reset by means of a command sent by the HOST.

### **DOOR** Door sensor status

C = Closed

M = Missing

O = Open

The status of the door sensor is newly determined with each command to the CMD-V4.

CMD-V4 itself considers the flag when handling encryption commands, provided **<DO\_S> = Y** has been configured.

### **DO S** CMD-V4 behavior at the start/end of encryption

N = Do not consider door sensor

Y = Consider door sensor

The flag is read out and updated from the hardware settings during system startup and during RESET.

## **TYPE** Device type

The current device version is mapped to a defined ID:

R = Rearload

F = Frontload

U = undefined

## **N\_VM** Number of separator modules 1 - 6 (contains the configuration presetting)

### **SEDM** Status of software EDM

I = Initial value must be requested

L = Line key LK missing

O = Encryption active

T = Transport key TK missing

If the line is not encrypted, the status is 'T / L / I'.

## **LCMD** Specification + additional specification of the last command

### **LSTA** Status code of the last command

The contents of the two cells are only changed by commands that initiate device operations. (Reset, dispense transaction, ...)

## SCLE Clearing status after RESET / Clearing / POWER UP

- 0 = Transport paths were free
- 1 = No cash accessible to customer; Reject successful.
- 2 = Cash was accessible to customer; retract was successful.
- 3 = Cash was accessible to customer; it has been withdrawn in the meantime.
- 4 = Cash was not accessible to customer; an error occurred during clearing (s. SRES).
- 5 = Cash was accessible to customer; an error occurred during clearing (s. SRES).

# SRES Status code after RESET / Clearing / POWER UP see Appendix A (page 88)

SRES and SCLE belong together. What was done is specified in SCLE; the result is documented in SRES.

**TST** Self-test was active, Reset necessary.

N = noY = yes

## **SCOD** Operator status display

When the safe is closed, the operator can be provided with this information, e.g. on the operator panel. For contents and meaning see **Appendix B** (page **Fehler! Textmarke nicht definiert.)**.

### **OR** Operator request

N = no

W = Warning (dirty photosensors)

Y = A status has occurred that requires operator intervention. Further information can be found in the individual status areas.

Error causes with no explicit code word in the device status e.g. photosensors, faulty motors, are identified on the operator status display. See **Appendix B** (page **Fehler! Textmarke nicht definiert.Fehler! Textmarke nicht definiert.**).

### TRANSPORT Output transport variant

A = in safe front

B = in Safe rear (also known to many as outdoor rearload)

- C = out Safe rear (also known to many as indoor rearload)
- D = out safe front (also known to many people as 'indoor frontload')
- E = out safe rear (für PC8xxx systems)
- F = out safe front (for PC8xxx systems)
- G = in safe rear (for PC8xxx systems)
- H = (VCMD with horizontal output) does not yet exist
- U = ProCash 5100 (VCMD)
- \* = unknown coding

The flag is recognized by the connector coding and updated at system startup and RESET.

### C OUT CashOut available

This cell allows global checking to determine whether the CashOut functionality is available or not.

- C = Minimum configuration not available (RR box + cash-out cassette)
- J = JAM (note iam)
- L = Device lock
- M = Main motor DCM1 faulty
- P = CMD-V4 booting
- S = Safety switch
- T = Clamp transport defective
- Y = CashOut possible
- The status can only be changed if:
  - CashOut was previously possible.
  - The last of several reasons documented is no longer relevant.

# SHUT\_P Cash trapping detection available ROTECT

- O = OK, no error
- K = Cash trapping device detected
- M = Cash trapping device manipulation (e.g. color spraying)
- D = Cash trapping detection defective (e.g. no communication, not initialized, faultily initialized, implausibly initialized)
- U = Cash trapping detection not present (see shutter plug for coding)

For reset of the K, M status after error recovery or removal of the cash trapping device see section "Reset of a cash trapping detection error" (page 10).

### **ERROR** Error number

The four-digit error number details the cause of the current error. For the cause and remedial measures: see **Appendix G – Error Number Table** (page 111)

### WARNING Warning number

The four-digit warning number details the cause of the current erroneous function. For the cause and remedial measures: see **Appendix G – Error Number Table** (page 111)

## C - Cassette status

| Code word | Entry         | Meaning  |                    |
|-----------|---------------|--|--------------------|
| LEN=      | dddd,         | Total length (incl. length specification)  | (decimal in ASCII) |
| RSTA=     | a,            | Status of RR box M = Cassette missing or inserted incorrectly N = Cassette newly added R = Cassette ready  | (ASCII)            |
| RACT=     | dddd,         | Number of notes rejected   | (decimal in ASCII) |
| RRET=     | dd,           | Number of retracts   | (decimal in ASCII) |
|           |               |  |                    |
| nSTA=     | a,            | Status of cash-out cassette n (n = 1 - 6)  D = Cassette EEPRPOM read error  E = Cassette physically empty  M = Cassette missing or not correctly inserted  N = Cassette reinserted  P = Parameter not known in measurement station  R = Cassette ready  V = Document ready for being pulled off (printing cass.) | (ASCII)            |
| NNUM=     | dddddd<br>d,  | Cassette ID  | (decimal in ASCII) |
| nCUR=     | aaa,          | Currency code  | (ASCII)            |
| nREL=     | dddd,         | Release date (YYMM)  | (decimal in ASCII) |
| nVAL=     | dddddd<br>dd, | Value of note  | (decimal in ASCII) |

| Code word | Entry | Meaning   |                    |
|-----------|-------|---|--------------------|
| nLEN=     | ddd,  | Width of note   | (decimal in ASCII) |
| nTOL=     | dd,   | Cut tolerance of note   | (decimal in ASCII) |
| nACT=     | dddd, | Current number of notes   | (decimal in ASCII) |
| nNDV=     | dddd, | Number of notes in the device   | (decimal in ASCII) |
| nLOW=     | dddd, | Specification of minimum quantity                                     | (decimal in ASCII) |
| nL_D=     | dd,   | Last dispense: no. of notes   | (decimal in ASCII) |
| nREJ=     | ddd,  | Last dispense: number of rejected notes                               | (decimal in ASCII) |
| SRACT=    | dd    | current number of notes being parked in the single reject compartment |                    |
|           | ;     | End character after last parameter                                    | (ASCII)            |

Data from the dispenser modules is acknowledged (n = 1 to  $n = \langle N_V M_z \rangle$ ).

Dispenses are not hindered with a logically empty cash-out cassette or a full RR box.

The operator must ensure that the CMD-V4 has the correct data before customer mode is activated!.

### **Definitions**

i

The highlighted status of a cell or completely highlighted status words are only returned if standard mode is activated!

**LEN** Contains the total length of the status range (incl. length specification).

RSTA Status of RR box

M = Cassette missing or incorrectly inserted

N = Cassette re-inserted

R = Cassette ready

The cell is updated by the CMD-V4 during RESET / Clearing and dispensing.

### **RACT** REJECT counter

The number of singled out notes in the device is documented in **RACT**. The number usually corresponds to the total of all nREJ values that were determined during dispensing commands. Differences to the sum of nREJ values can arise due to trial dispensing processes or test notes.

Notes which were identified by the measurement station as being double or too long increment the counter by one. Undefined banknotes (banknotes released without banknote dispensing) are not counted. Notes which are still in the transport path following a jam are counted. The counter is defined via a SW call and remains unchanged, both during a power failure and when the cassettes are changed.

#### RRET Retract counter

The number of cash storage procedures is documented in **RRET**. The value is increased before the beginning of a retract. This counter is reset with the 'Clear retract counter' command (DFT).

One range exists per cash-out cassette (n = 1 - 6):

nSTA Cassette status

D = Read error cassette EEPROM

E = Cassette is physically empty

M = Cassette missing or incorrectly inserted

N = Cassette re-inserted

P = Parameters unknown in measurement station

R = Cassette ready

V = printing cassette, document available (printing cassette only)

The cell is updated cyclically by the CMD-V4. Dispensing commands only include cash-out cassettes with the status:

- 'R' Cassette is ready
- 'V' Document ready for dispensing from printing cassette.

Status **D** can only be quit by removing the cassette.

**nNUM** Cassette ID; it can be set for specific customers using the software.

The 7-digit cassette ID is read from a non-volatile memory in the dispenser cassette and stored when the system is started or when 'RESET' takes place. When the cassettes are delivered, the default setting for the cassette ID is the serial number of the cassette.

The **printing cassette** does not have a non-volatile memory. The cassette ID is therefore initialized with the default value (standard: ----), when the command 'Confirm HW configuration' is processed.

nCUR Currency codenREL Release datenVAL Value of note

These 3 parameters define the note exactly: They are read from a non-volatile memory in the dispenser cassette and stored when the system is started or when RESET takes place. This parameters can be updated via software.

**nCUR** is the 3-digit currency characteristic to ISO 4217 (codes for representation of currencies and funds).

Coding "★★★" indicates a cassette that has not yet been initialized or a defective cassette position.

**nREL** contains an additional 4-digit ID (YYMM of the output). This allows the CMD-V4 to process notes with the same nominal value but different note properties.

**nVAL** determines the value of the note.

**nLEN** Width of note in transport direction

### **nTOL** Cut tolerance in transport direction

Both values are 0 if the Note parameter I command was used and no reference value has yet been determined.

### **nACT** Current number of notes

### **nNDV** Number of notes in the device

The two counters provide information about the position of the notes. They are defined via a SW call and remain unchanged, both during a power failure and when the cassettes are changed.

**nACT** is decremented with every note that is dispensed.

**nNDV** is updated when a note is output. After the shutter has been moved from its 'SHUT' position,

the counter is incremented: <nNDV> - <nL\_D> for n = 1 - 6

### **nLOW** Minimum quantity specification

A minimum quantity can be defined for each cassette per software (default = 0, no monitoring).

Cassettes with mechanical filling level detector have priority over the software setting.

The position of the dispensed notes and the filling level status of each cassette are transferred in the acknowledgment of the dispensing commands.

L = Reached / fallen below minimum quantity

O = OK; minimum quantity not yet reached

E = Cassette physically empty, if < nSTA > = E

### **nL\_D** Number of notes (2-digit)

**nREJ** Number of rejected notes (3-digit)

### **SRACT** Single reject compartment counter

The number of the singled out notes in **SRACT** presently parked in the single reject compartment is documented. Notes that should not be paid out are transported to the single reject compartment. Notes which were identified by the measurement station as being double or too long increment the counter by one.

The compartment is emptied after note output, note bundle reject, retract, clearing, or power OFF/ON and the counter reset.

## F - Features

The highlighted features cannot be configured via the SW!

| Code word      |                | Meaning  |         |
|----------------|----------------|--|---------|
| BARC=          | <b>y</b><br>a, | Special cassette commands<br>available<br>N = no<br>Y = yes  | (ASCII) |
| C_TYPE=        | aa,            | Cassette type One entry exists for each dispensing module (number as in <n_vm>)  ★ = Cassette type not yet initialized D = Printing cassette L = Mechanical fill level sensor active M = Mechanical fill level sensor S = Standard cassette</n_vm> | (ASCII) |
| PRINT=         | a,             | Printing cassette extension is part of the firmware  N = no Y = yes  | (ASCII) |
| DO_BAD=        | a,             | Double dispense evaluation configurable N = no Y = yes   | (ASCII) |
| ERRS=          | a,             | 'ERROR info' command is part of<br>the firmware<br>N = no<br>Y = yes   | (ASCII) |
| SINGLE_REJECT= | a,             | Availability of single reject (installed and functioning)  N = no Y = yes  | (ASCII) |
| RTC=           | a,             | Real-time clock available N = no Y = yes   | (ASCII) |

| Code word                | Entr         | r Meaning  |                    |  |  |
|--------------------------|--------------|--|--------------------|--|--|
|                          | у            |  |                    |  |  |
| SCOP=                    | a,           | SCOP is part of the firmware and available N = no Y = yes  | (ASCII)            |  |  |
| BAUD=                    | ddd/<br>ddd, | possible baud rates (V.24 line)<br>192/560 = 19200/56000 baud  | (decimal in ASCII) |  |  |
| BAUD_CHANGE=             | a,           | V.24 line parameters configurable N = no A = automatic baud rate switch                                  | (ASCII)            |  |  |
| BUILD=                   | aa,          | Internal version number  | (ASCII)            |  |  |
| MAX_NOTES=               | dd,          | Maximum number of notes per bundle 60 for CMD_V4   | (decimal in ASCII) |  |  |
| FAMILY=                  | a,           | C = CMD-V4 family  | (ASCII)            |  |  |
| CONFIG_RETRACT_<br>COUNT | a,           | Counting of retracts configurable  N = no  Y = yes   |                    |  |  |
| CONFIG_BUTTON_3          | a,           | Trial dispensing process via button function 3 can be disabled via configuration  N = no Y = yes         |                    |  |  |
| CHECK_SHUTTER_<br>ATTACK | a,           | Shutter monitoring after DCW with automatic clamp retraction configurable  N = No Y = Yes                |                    |  |  |
| DES_OPT=                 | а,           | Special encryption procedures available N = no, only DES procedure Y = yes, further procedures available | (ASCII)            |  |  |

| Code word             | Entr | Meaning   |         |
|-----------------------|------|---|---------|
|                       | У    |   |         |
| ACCESS_CODE=          | a,   | Activation procedure is part of the firmware and commands activated N = not supported; standard in the CMD_V4   | (ASCII) |
|                       |      | I = Activation procedure available. Only limited command utilization possible, all other commands are rejected showing context error. The limited commands are: *IL, DAblank, DAB, DEx, DHx, DSC, and DSD. (with PC8xxx – transports) |         |
|                       |      | Y = Activation procedure available,<br>all commands can be used (with<br>PC8xxx – transports)   |         |
| SHUT_PROTECT_O<br>PT= | a,   | Cash trapping detection is part of the firmware   |         |
|                       |      | N = is not supported  |         |
|                       |      | Y = yes, is supported   |         |
|                       | ,    | End character after last parameter  | (ASCII) |

For a cassette with mechanical filling level detector, the correct filling level (cassette type) is not displayed until the banknote pressure has built up. For example, when inserting cassettes, the indicator M or L under C\_TYPE is only reliable when the cassette status of the respective cassette changes from M (Missing) to N (New).

# **K – Firmware configuration**

| Code word                           | Entr<br>y | Meaning   |         |
|-------------------------------------|-----------|---|---------|
| SDO_BAD=                            | a,        | Dual dispense evaluation N = Do not reject 2 GOOD notes Y = Always reject dual dispenses  | (ASCII) |
| MAX_NOTES=                          | dd,       | Maximum possible amount of notes per transaction (20 - 60)  | (ASCII) |
| COUNT_MULTIPLE_<br>NOTES=           | a,        | Y= Count all notes that can<br>be identified double and<br>threefold (this is not 100 %<br>of all dual and triple<br>combinations!) shall be<br>counted double and<br>threefold (in nACT and<br>RACT)<br>N = Only count valid dual<br>dispenses as double | (ASCII) |
| RESTRICT_CASSETTE_NO<br>TIFICATION= | a,        | N = Logging on cassettes<br>(DFN,DFO,DFA,DFB) also<br>permitted if TF=N<br>Y = as before  | (ASCII) |
| LOW_IDLE_PRESSURE=                  | а,        | Y = In idle position, move<br>the pressure carriage back<br>slightly (for polymer notes)<br>N = previous behavior   | (ASCII) |
| JAM_LOCK_ENABLED=                   | a,        | Reset suppression after banknote jam  N = Resets are always permitted.  Y = no reset on detected note jam. A reset is only carried out after button function 1 or the safety switch has been actuated.  |         |

| Code word                  | Entr | Meaning   |         |
|----------------------------|------|---|---------|
| Sout Word                  | у    | Meaning   |         |
| RETRACT_COUNT_IN_BOX =     | a,   | Y = A retract is counted in RRET if the notes are stored in the retract box/tray.  N = A retract is counted in RRET if the shutter is closed after retracting the notes from the offer cash position.                 |         |
| BUTTON_3_TESTDISPENSE =    | a,   | Y = Button function 3 results<br>in a trial dispensing process<br>with subsequent rest.<br>N = Button function 3 only<br>carries out a reset, analog to<br>button function 1.   |         |
| CHECK_FOR_SHUTTER _ATTACK= | a,   | Y = The shutter is monitored after successful DCW; automatic retract of the clamp as soon as the shutter has left the 'Shut' status. See also Appendix Y: Detection of a shutter manipulation after DCW N = as before |         |
| DES_OPTION =               | d,   | Encryption procedure Switching-over only possible with the encryption disabled. 0 = DES-encryption, standard 1 = 3DES encryption  | (ASCII) |
| DES_CLEAR_BUTTON_6=        | a,   | N = Encryption cannot be disabled, standard Y = Encryption can be disabled at open door switch and depressed pushbutton 6.  | (ASCII) |

| Entr | Meaning  |  |  |
|------|--|--|--|
| d,   | Change position when offering the bundle after the DCO command.  0 = Bundle is transported out farthermost, standard:  7 = Bundle is transported out the shortest possible fashion | (ASCII)  |  |
| d,   | Shutter position when offering the bundle.  0 = Standard  1 = Shutter is placed onto the bundle the least : 9 = Shutter is placed onto   | (ASCII)  |  |
| а,   | Position of the shutter plate<br>at shutter OPEN<br>N = standard<br>Y = Shutter plate is opened<br>some mm less wide   | (ASCII)  |  |
| a,   | Cash trapping detection N = switched off Y = switched on, standard   | (ASCII)  |  |
| d,   | Distance of alarm threshold to shutter plate 0 = Standard 1 = least distance : 9 = widest distance   | (ASCII)  |  |
|      | d, d, a,   | d, Change position when offering the bundle after the DCO command.  0 = Bundle is transported out farthermost, standard:  7 = Bundle is transported out the shortest possible fashion  d, Shutter position when offering the bundle.  0 = Standard  1 = Shutter is placed onto the bundle the least:  9 = Shutter is placed onto the bundle the strongest  a, Position of the shutter plate at shutter OPEN  N = standard  Y = Shutter plate is opened some mm less wide  a, Cash trapping detection  N = switched off  Y = switched on, standard  d, Distance of alarm threshold to shutter plate  0 = Standard  1 = least distance  :  9 = widest distance |  |

#### **Definitions**

#### SHUT\_PROTECT\_ OPT

Cash trapping detection

Existence of a trapping device detection is not checked under

this configuration.

N = trapping device detection is disabled

Y = trapping device detection is enabled, standard

For a reset of the error see section "Reset of a cash trapping detection error" (page 10).

# **NGE**

**SHUT\_ALARM\_RA** Distance of alarm threshold to shutter plate

0 = Standard (for outdoor shutter approx. 50 mm, for indoor shutter approx. 35 mm distance) (see shutter plug for coding)

1 = alarm threshold approx. 25 mm distance

9 = alarm threshold approx. 70 mm distance

## **Configuration after CMOS initialization**

### **Device status**

| N_VM=n, | Number of dispenser modules                         |
|---------|---|
|         | n = Number of types detected from <c_type></c_type> |

### **Features**

| C_TYPE=★★, | Cassette type of cassettes, per recognized dispenser unit |
|------------|---|
|            | ★ = cassette type not yet initialized                     |
|            | D = printing cassette                                     |

## **FW** configuration

| SDO_BAD=N                        | Double dispense evaluation of the measurement station:                        |
|----------------------------------|---|
| MAX_NOTES=60                     | '2 GOOD' notes are not disqualified.  Maximum number of notes per transaction |
| COUNT_MULTIPLE_NOTES=N           | Compatible behavior   |
| RESTRICT_CASSETTE_NOTIFICATION=Y | Compatible behavior   |
| LOW_IDLE_PRESSURE=N              | Compatible behavior   |
| JAM_LOCK_ENABLED=N               | Compatible behavior   |
| RETRACT_COUNT_IN_BOX=N           | Compatible behavior   |
| BUTTON_3_TESTDISPENSE=Y          | Compatible behavior   |
| CHECK_FOR_SHUTTER_ATTACK=N       | Compatible behavior   |
| DES_OPTION=N                     | Compatible behavior   |
| DES_CLEAR_BUTTTON_6=N            | Compatible behavior   |
| OFFER_CASH_POS=0                 | Compatible behavior   |
| OFFER_SHUTTER_POS=0              | Compatible behavior   |
| OPEN_SHUTTER_REDUCE=0            | Compatible behavior   |
| SHUT_PROTECT_OPT=Y               | Cash trapping detection enabled   |
| SHUT_ALARM_RANGE=0               | Distance of alarm threshold to shutter plate                                  |

## **Appendix Y: Special features**

## Different behavior of the clamp for DCE and DCP

There is a distinctive difference in the process control for the commands DCE (output cash) and DCP (cash presentation). With the command DCP the clamp is moved back slightly before the shutter opens. The clamp retracts to its final position after the shutter has opened to then present the notes. With the command DCE, the clamp remains in the end position while the shutter is being opened and subsequently outputs the notes.

## DCW and the locking handle

The CMD-V4 has a locking switch (SW 3) that is positioned above the reject/retract cassette. This switch indicates if the separator has not been correctly inserted into the safe -> status display "09". This is necessary because the clamp's transport route must be correctly placed on devices with their cash output outside of the safe. Otherwise, transport of the clamp from the stacker to the shutter can cause jams. For this reason, the device type and the status of the locking handle are checked with

For this reason, the device type and the status of the locking handle are checked with command DCW (transport target = Stop Over). If it is a device with cash output outside the safe and if the separator has been inserted incorrectly, the command DCW is acknowledged with "D" – Out of service.

## **Detecting shutter manipulation after DCW**

If the firmware property CHECK\_SHUTTER\_ATTACK = Y has been set, it will be possible to enable an additional security feature via configuration.

The shutter status is monitored by the firmware after a successful DCW command (banknote transport to parking position). If the shutter's position sensors should detect another position than "closed", then:

- 1. the clamp is moved from the shutter position to the stacker position so as to prevent any unauthorized access to notes
- 2. The following device statuses are set until the next reset (DA):
  - SHUT = U (regardless of whether or not the shutter closes again)
  - -TER = M
  - TS = 42
  - -SCOD = 29
- 3. The following device statuses remain unchanged:
  - TF = N
  - -MON = N
- 4. Following commands are still permitted at this status:
  - DAblank (reset)
  - DEx (status commands)
  - DHx (key handling)
  - Dlx (software supply except DIC)
  - DQx (error statistics, realtime clock, EEPROM)
  - DYx (test commands)

The device can only be brought back to a ready state following a successful reset (DAblank).

| Notes |  |  |
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