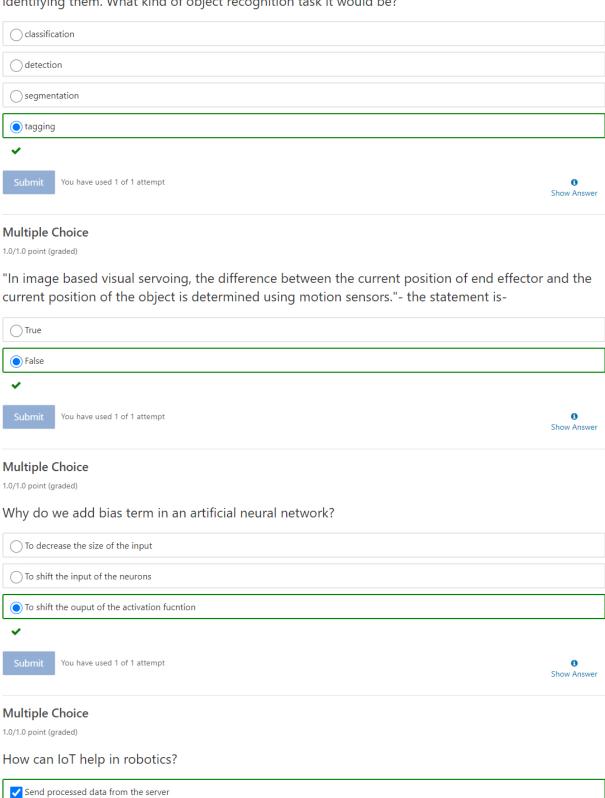


	ĸΑ	

Multiple Choice

1.0/1.0 point (graded)

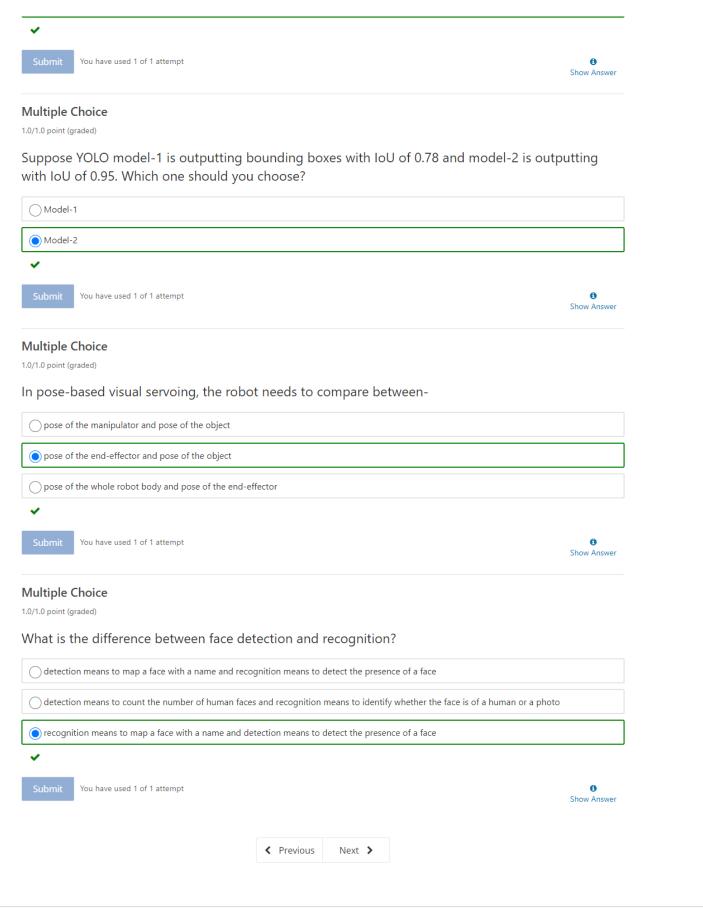
Suppose you are building an obstacle avoiding robot which can drive avoiding different objects after identifying them. What kind of object recognition task it would be?



✓ Remotely commanding the robots

✓ Help in creating netowork of robots

Help in powering the robot wirelessly



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