Mahta Akhyani

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RESEARCH INTERESTS

Human Robot Interaction, Social Cognitive Robots, Biomechanics, Assistive Technology, Bio-inspired Robots

PUBLICATIONS

Mahta Akhyani, Hadi Moradi, "Modular Customizable ROS-Based Framework for Rapid Development of Social

Robots" Github - arXiv [PDF]

In Prepration

Submitted

Pegah Soleiman, Mahta Akhyani, Alireza Kargar, Hadi Moradi, "Empathy toward Robotic Social Environment vs. Human Social Environment, Comparison between people with Autism Spectrum Disorder and typically developing ones"

Internships

Summer 2024

Research Assistant, GIST (Gwangju Institute of Science and Technology), South Korea

- Researching trust in Human-Robot Interaction (HRI)
- Developing and implementing Trust-POMDP algorithm for human-exoskeleton interactions

EDUCATION

2018 - 2023

Bachelor of Science: Chemical Engineering

University of Tehran - Iran

GPA: 15.63/20 (16/20 in the last 2 years)

Subdiscipline: Biotechnology

B.Sc. thesis (Full Marked): Design of mobile robot with SLAM capabilities for pipe inspection in chemical and

petroleum industries Media - arXiv [PDF]

SKILLS

Proficient:

Python - ROS - Gazebo - Javascript - HTML/CSS - Robotics platforms (e.g. Raspberry Pi, Arduino, Jetson Nano) -Version control (Git) - 3D modeling (Solidworks)

Experienced:

Django REST framework - Ubuntu - Machine Learning and AI (TensorFlow, Pandas, NumPy, MatPlotLib)

Intermediate:

C++, C, AVR, Computer vision and AI (OpenCV, MediaPipe, Praat)

RESEARCH EXPERIENCE

08/2022 - 10/2023 Terahertz Photoelectronics Lab

Department of Computer and Electrical Engineering, University of Tehran

Supervisor: Prof. Mohammad Neshat

Project Title: Electrically Conductive Mixed Matrix Membrane-Based 3-Layered Geometrically Matching Head Phantom More info

• Synthesized and characterized polymers including PANI, PDMS, starch, RTV-2, graphene and carbon black for a multilayer head phantom through CPC and MMM fabrication

04/2022 - 07/2022 **B.Sc. Thesis Project** Media - arXiv [PDF]

Design of mobile robot with SLAM capabilities for pipe inspection in chemical and petroleum industries

- Development of a sensor fusion pipeline integrating Kinect camera and IMU data to improve odometry estimates
- Simulated and built a mobile robot platform and testing the ROS/Gmapping SLAM approach on it in a maze

06/2021 - 07/2024 Advanced Robotics and Intelligent Systems Lab

Department of Computer and Electrical Engineering, University of Tehran

Supervisor: Prof. Hadi Moradi

Project Title: Understanding Empathy Towards Social Robots and Its Implications for Individuals with Autism

- Investigated empathy in human-robot and robot-robot interactions using EEG, comparing responses of individuals with autism and neurotypical participants
- Examined joint attention responses in autism for both robotic and human social interactions

Project Title: Modular Customizable ROS-Based Framework for Rapid Development of Social Robots

- Developed reusable robot skill modules (face analysis, speech processing, dialogue agents, actuator control)
- Engineered a distributed data processing pipeline optimized for multiple sensors

Project Title: Designing Affective Expressions for Social Robots to Interact with Children with Autism Media

- Utilized video/photo editing to design facial expressions for the robot
- · Synthesizing empathetic speech by a random forest model learned using extracted audio MFCC features with Praat

03/2019 - 02/2020 **Pharmacology Lab**

Department of Chemical Engineering, University of Tehran

Supervisor: Prof. Reza Zarghami

Project Title: Chem-E-Car Competition (Designed and constructed a car powered by synthezised chemical energy

source and brake system)

TEACHING EXPERIENCE

Spring 2022 **Teaching Assistant**

Advanced Robotics (Graduate)

Department of computer and electrical engineering, University of Tehran

Lecturer: Prof. Hadi Moradi

Provided hands-on tutoring to students on ROS-based localization techniques for Anki Vector robot

Winter 2021 **Teaching Assistant**

Learning Python with Computer Vision approach

RoboTech Academy

• Developed assignments and quizes, and provided tutoring support to reinforce learning concepts

Summer 2019 **Self-Directed Volunteer Teacher**

Teaching Python fundamentals during summer to 12 students

JOB EXPERIENCE

04/2020 - 02/2021 Co-founder and Leader of Fanjoo

Online platform for peer knowledge exchange and optional income

Addressed gap between education and workforce needs by empowering users to gain in-demand technical skills outside traditional academia. More info - GitHub

Skills achieved:

• Effective Collaboration • Self Disciplinary

• Project Management

• Team Leadership

10/2019 - 01/2020 Django Backend Developer

UTech Academy - Tehran, Iran

• Independent back-end Django REST developer GitHub

CERTIFICATIONS AND EXTRA COURSES

April 2022 TOEFL Test

• Overall Score: 97/120 (r27,125,s22,w23)

Spring 2021 **Fundamentals of Mechatronics (Graduate-level)**

Department of electrical and computer engineering, University of Tehran, Iran

• Project Grade: **120 out of 80** (Extra Credit) • Overall Grade: 19.5 out of 20

Winter 2020 **Deep Learning and Computer Vision**

RoboTech Academy

Summer 2019 **Back-End Developing with Django**

> UTech Academy • Grade: 100/100

Summer 2018 **Programming with Python**

Tehran Institute of Technology

• Grade: 95/100

HONOURS AND AWARDS

University Entrance Exam top 0.7% Summer 2018

Ranked top 0.7% in among 144000 participants in **IUEE** for B.Sc.

Spring 2017 Best Provincial Project, 18th Khwarizmi Scientific Competition Youth Awards (KYA), Tehran

Project Title: "Designing Different Types of Electrical Compass".

REFERENCES

Professor Prof. Hadi Moradi moradih@ut.ac.ir Assistant Professor Prof. Mohammad Neshat mneshat@ut.ac.ir Lecturer Prof. Kambiz Shoarinejad <u>kambiz 1@ucla.edu</u>