Deadline: 12.05.2014, 12 noon

Results via e-mail to: jens.kersten@uni-weimar.de

## **Exercise 2**

- Gradient of Gaussian filtering (GoG)
- Förstner interest point operator

You are free to use the provided image (ampelmaennchen.png) or own photos. Please compute **grayscale image** as first step, if there are more than one channels.

## A) Gradient of Gaussian filtering (GoG)

a. Compute two GoG-filter masks for GoG-filtering in x- and y-direction (see slides of lectures and assignment session). Example: for  $\sigma = 0.5$  the masks are:

$$G_{x} = \begin{bmatrix} 0.0000 & 0.0001 & 0.0000 & -0.0001 & -0.0000 \\ 0.0002 & 0.0466 & 0.0000 & -0.0466 & -0.0002 \\ 0.0017 & 0.3446 & 0.0000 & -0.3446 & -0.0017 \\ 0.0002 & 0.0466 & 0.0000 & -0.0466 & -0.0002 \\ 0.0000 & 0.0001 & 0.0000 & -0.0001 & -0.0000 \end{bmatrix}, G_{y} = G_{x}^{T}$$

- b. Apply the two filters on the input image to derive a filtered image in x- and y-direction ( $I_x$  and  $I_y$ ) using *self-written* code. Ignore the edges of the image (no padding needed).
- c. Compute the gradient magnitude image G (just a by-product and not used in further steps)

$$G = \sqrt{(I_x)^2 + (I_y)^2}$$

using the filter outputs  $I_x$  and  $I_y$ . Plot and export the resulting image.

## B) Förstner operator:

- a. Compute the autocorrelation Matrix M for each pixel using a moving window of 5x5 pixels (ignore the edges of the image).
- b. Instead of storing the matrix M for each pixel, compute the cornerness w and roundness q for each pixel from that matrix. The results are two matrices W and Q. Make a plot of these two images.
- c. Derive a mask of potential interest points by simultaneously applying the thresholds  $t_w=1.0$  and  $t_q=0.5$  on W and Q, respectively. The result is a mask  $M_C$  with pixel values = 1, if  $w>t_w$  and  $q>t_q$ , and 0 otherwise.
- d. Multiply W or Q with the interest point mask  $\bar{Q} = Q \cdot M_C$  and use the function "houghpeaks" to derive pixel coordinates of the interest points from  $\bar{Q}$ .
- e. Plot an overlay of the initial input image and the detected points.