

# Set Theory

15 October 2017 23:47

- $\omega \in A$   
w belongs to A
- Subset :  $A \subseteq B$ 
  - all elements of A are contained in set B

Empty set:  $\emptyset = \{ \}$

Universal set:  $\Omega$   
all elements

**Cardinality** - number of elements in a set  
Singleton - cardinality 1

**De Morgan's laws**

**Disjoint**: no shared elements

break the bar  
change the operator

**Partition**: collection of disjoint sets form  $\Omega$

- $\overline{A \cup B} = \bar{A} \cap \bar{B}$
- $\overline{A \cap B} = \bar{A} \cup \bar{B}$

## Distributive Law

- $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$
- $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$

Union:  $A \cup B$   
all elements that belong to at least one of the sets

Intersection:  $A \cap B$   
all elements that belong to all of the sets

Complement: not A  
 $\bar{A}$  = all elements in  $\Omega$  not in A

Difference:  $A/B$   
elements in A that are also not in B  
 $A/B = A \cap \bar{B}$

# Sample Spaces and Events

28 October 2017 18:07

$S$  - universal set

Event - subset of  $S$

- null event - empty set
- **elementary** event - singleton

# Probability Axioms

28 October 2017 18:07

For any two events E and F

set function P:

takes a set as argument

returns value

- $\max(P(E), P(F)) \leq P(E \cup F) \leq P(E) + P(F)$
- $P(E) + P(F) - 1 \leq P(E \cap F) \leq \min(P(E), P(F))$

for set function to be a probability,

for any event  $E \subseteq S$ :

- $0 \leq P(E) \leq 1$
- $P(S) = 1$
- if  $E \cap F = \emptyset$  (disjoint / mutually exclusive) then
  - $P(E \cup F) = P(E) + P(F)$

- Otherwise, if not disjoint:

- $P(E \cup F) = P(E) + P(F) - P(E \cap F)$

- addition rule - takes away overlap

# Conditional Probability

28 October 2017 18:08

## **P(A/B)**

probability A occurs given that B has occurred

- $P(A|B) = \frac{P(A \cap B)}{P(B)}$

- gives intersection as a % of area of B

- $P(\bar{A}|B) = 1 - P(A|B)$

## Multiplication Law:

- $P(A \cap B) = P(B|A)P(A) = P(A|B)P(B)$

## Independence:

- $P(A|B) = P(A)P(B)$

# Probability Tables

28 October 2017 18:08

Separate rows or columns are **disjoint**

obtain **conditional probability** from rows or columns as well

# Total Probability

28 October 2017 18:08

Form an unconditional probability from conditional ones

$A_i$ ,  $i=0\dots j$ , form a partition of  $S$ , then,

- $$P(B) = \sum_{i=1}^k P(B|A_i) P(A_i)$$

# Bayes Theorem

28 October 2017 18:08

## Switching conditional probabilities:

- $P(A_k|B) = \frac{P(B|A_k)P(A_k)}{P(B)}$

- probability that  $A_k$  occurred if B occurred

Can represent  $P(B)$  as a total probability

- $P(A_k|B) = \frac{P(B|A_k)P(A_k)}{P(B|A_1)P(A_1) + \dots + P(B|A_k)P(A_k)}$

# Discrete Random Variables

28 October 2017 17:16

Maps a Sample space S, into R - a set of real numbers

## Theoretical Mean - Expected Value:

- $E(X) = \sum_x x f_X(x) = \sum_x x P(X = x)$
- population mean,  $\mu = E(X)$
- Properties:
  - $E(aX + b) = aE(X) + b$
  - $E(X + Y) = E(X) + E(Y)$

Probability Mass Function - returns probability of  $P(X=x)$  - noted by  $f_X(x)$

**CMF** -  $F_X(x)$  Cumulative version of PMF, used for  $P(X < x_k)$

PMF can vary by another variable - noted by  $f_X(x; \theta)$

## Theoretical Variance:

- $Var[X] = E[(X - \mu)^2] = E(X^2) - E(X)^2 \geq 0$
- population variance,  $\sigma^2$
- Properties:
  - $Var(aX + b) = a^2 Var(X)$
  - $Var(X \pm Y) = Var(X) + Var(Y)$ 
    - for uncorrelated X,Y



# Uniform Distribution

29 October 2017 13:20

- PMF:  $f_X(x) = \frac{1}{k}$  , for  $x = 1, 2, \dots, k$
- CDF:  $F_X(x) = \frac{x}{k}$
- $E(X) = \frac{k+1}{2}$ 
  - more generally,  $E(X) = \frac{a+b}{2}$  for  $x: a \dots b$
- $Var[X] = \frac{k^2 - 1}{12}$

# Binomial Distribution

29 October 2017 13:54

## Requires:

- two **mutually exclusive** outcomes
- **n identical, independent** trials
- **constant probability** of success,  $p$

$$\underline{X \sim \text{Bin}(n, p)}$$

- random variable  $X$  is binomially distributed
- **n** number of trials
- **p** probability of success

$$\bullet f_X(x; p, n) = \binom{n}{x} p^x (1 - p)^{n-x}$$

$$\bullet E(X) = np$$

$$\bullet \text{Var}[X] = np(1 - p)$$

# Geometric Distribution

29 October 2017 14:16

REVISE A LEVEL GEO SERIES PROPERTIES

'how many trials before the first success'

$$\underline{X \sim \text{Geo}(p)}$$

X - counts number of trials until first success

p - probability of a success

$$\bullet f_X(x; p) = (1 - p)^{x-1} p, \quad \text{for } x = 1, 2, \dots$$

$$\bullet E(X) = \frac{1}{p}$$

$$\bullet \text{Var}[X] = \frac{1 - p}{p^2}$$

# Poisson Distribution

29 October 2017 14:26

## Requirements

- independent events in time and space

$$\underline{X \sim \text{Poisson}(\lambda)}$$

- $\lambda > 0$
- $f_X(x; \lambda) = \frac{e^{-\lambda} \lambda^x}{x!}$  ,  $for\ x = 0, 1, 2, \dots$
- $E(X) = Var(X) = \lambda$

# Continuous Random Variables

29 October 2017 16:29

Probability Density Function - - noted by  $f_X(x)$

- must be **non-negative**
- total **area under graph = 1**

**CDF** -  $F_X(x)$  Cumulative version of PDF, used for  $P(X < x_k)$

$$F_X(x_0) = P(X \leq x_0) = \int_{-\infty}^{x_0} f_X(x) dx$$

- $F_X(-\infty) = 0$
- $F_X(\infty) = 1$

$$PDF = \frac{d}{dx} CDF \rightarrow f_X(x) = \frac{dF_X(x)}{dx}$$

PDF can vary by another variable - noted by  $f_X(x; \theta)$

Theoretical Mean - Expected Value:

$$\bullet E(g(X)) = \int_{-\infty}^{\infty} g(x) * f_X(x) ds$$

- Properties:
  - $E(aX + b) = aE(X) + b$

Theoretical Variance:

$$\bullet Var[X] = E[(X - \mu)^2] = E(X^2) - E(X)^2 \geq 0$$

- Properties:
  - $Var(aX + b) = a^2 Var(X)$

# Continuous Uniform Distribution

05 November 2017

19:38

$$\underline{X \sim Unif(a, b)}$$

$$f_X(x) = \begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$

$$E(X) = \frac{b+a}{2}$$

$$Var(X) = \frac{(b-a)^2}{12}$$

$$F_X(u) = \begin{cases} 0 & u < a \\ \frac{u-a}{b-a} & a \leq u \leq b \\ 1 & u > b \end{cases}$$

# Exponential Distribution

05 November 2017

19:46

$$\underline{X \sim \text{expo}(\lambda)}$$

$$E(X) = \frac{1}{\lambda}$$

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x} & x > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Var}(X) = \frac{1}{\lambda^2}$$

$$F_X(u; \lambda) = \begin{cases} 0 & u \leq 0 \\ 1 - e^{-\lambda u} & u > 0 \end{cases}$$

## Memoryless Property:

$$P(T > b + a \mid T > a) = P(T > b)$$

- **doesn't matter** that a has occurred

## \* Change of Variable

05 November 2017 20:12

$$f_Y(y) = f_X(x) \left| \frac{dx}{dy} \right|$$



# Normal Distribution

05 November 2017

20:12

$$X \sim N(\mu, \sigma^2)$$

$$X = \sigma Z + \mu$$

$$E(X) = \mu$$

$$\text{Var}(X) = \sigma^2$$

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$Z \sim N(0,1)$$

$$\mu = 0$$

$$\sigma^2 = 1$$

$$\phi(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}}$$

$$\Phi(z) = \int_{-\infty}^z \phi(u) du$$

Sampled - Var - Var / n^2

## \* Chebyshev's Inequality

14 January 2018 22:20

$X$  is a random variable with

$$\mu = E(X)$$

$$\sigma^2 = Var(X)$$

then, for all  $a > 0$

$$P(|X - \mu| \geq a) \leq \frac{\sigma^2}{a^2}$$

## \* Time-to-failure

28 October 2017 18:06

Weibull

Prob of component failure =  $\Theta$

> prob component doesn't fail =  $1 - \Theta$

Prob system **with n** components **functions**

In Series: = *product of each working*

In parallel: =  $1 - \text{product of each failing}$

$$F_T(t; \lambda, \beta) = \begin{cases} 1 - e^{-(\lambda t)^\beta} & t > 0 \\ 0 & \text{otherwise} \end{cases}$$

failure time distribution  $F_T(t)$

failure time density  $f_T(t)$

Mean time to failure

$$\text{MTTF} = \int_0^\infty R_T(t) dt$$

reliability time distribution  $R_T(t) = 1 - F_T(t)$

$$\text{hazard rate} = \frac{f_T(t)}{R_T(t)}$$

cumulative hazard function  $H$  *integral hazard rate*

# Marginals

28 October 2017 18:06

independent if:

- joint PMF/PDF = product of **marginal** PMFs/PDFs

## \* Conditional

19 May 2018 00:44

### Conditional

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)}$$

### Variance

$$\text{Var}[X|Y=y] = \begin{cases} \sum_i [x_i - E[X|Y=y]]^2 P(X=x_i|Y=y), & \text{disc} \\ \int_{-\infty}^{+\infty} [x - E[X|Y=y]]^2 f_{X|Y}(x|y) dx, & \text{cont.} \end{cases}$$

For random variables  $X$  and  $Y$ ,

$$\text{Var}(X) = E[\text{Var}[X|Y]] + \text{Var}[E[X|Y]]$$

### Expectation

#### GET MARGINAL FIRST

$$= \int_{-\infty}^{\infty} x f_X(x) dx$$

Screen clipping taken: 25/05/2018 01:31

### Conditional Expectation

$$g(y) = E[X|Y=y] = \begin{cases} \sum_i x_i P(X=x_i|Y=y), & \text{discrete,} \\ \int_{-\infty}^{+\infty} x f_{X|Y}(x|y) dx, & \text{continuous.} \end{cases}$$

Note that  $E(X)$  is a number while  $E[X|Y]$  is a random variable!

## \* Covariance

19 May 2018 01:03

$\text{Cov}(X, Y)$

$> 0$  - large X with large Y

$< 0$  - large X with small Y

if independent  $\rightarrow \text{cov}() = 0$

but  $\text{cov} = 0 \nrightarrow$  independence

# Correlation

19 May 2018 01:50

$$\rho = \text{Corr}(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}} = \frac{\text{Cov}(X, Y)}{\sigma_x \sigma_y}$$

**FROM -1 to +1**

# Joint Normal

19 May 2018 08:35



## \* Moments

19 May 2018 09:42

$$m_r = E[X^r]$$

### MGF

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The MGF of a random variable  $X$  is defined as

$$m_X(t) = E(e^{tX}) = \begin{cases} \sum_x e^{tx} f_X(x) & X \text{ discrete} \\ \int_{-\infty}^{\infty} e^{tx} f_X(x) dx & X \text{ continuous} \end{cases}$$

### Two independent RVs

$$\begin{aligned} m_{X+Y}(t) &= E(e^{t(X+Y)}) = E(e^{tX} e^{tY}) \\ &= E(e^{tX}) E(e^{tY}) = m_X(t) m_Y(t). \end{aligned}$$

### Power Series

$$\begin{aligned} m_X(t) &= E(e^{tX}) = E\left(\sum_{r=0}^{\infty} \frac{(tX)^r}{r!}\right) = \sum_{r=0}^{\infty} \frac{E(X^r)}{r!} t^r \\ &= 1 + \frac{E(X)}{1!} t + \frac{E(X^2)}{2!} t^2 + \frac{E(X^3)}{3!} t^3 + \dots \\ &= 1 + \frac{m_1}{1!} t + \frac{m_2}{2!} t^2 + \frac{m_3}{3!} t^3 + \dots \end{aligned}$$

### Differentiate

evaluate the derivatives of  $m_X(t)$  at  $t = 0$ . First, notice that

$$\begin{aligned} \frac{d}{dt} m_X(t) &= m_1 + m_2 t + \frac{m_3}{2} t^2 + \dots \\ \frac{d^2}{dt^2} m_X(t) &= m_2 + m_3 t + \frac{m_4}{2} t^2 + \dots \\ &\vdots \end{aligned}$$

evaluate the derivatives of  $m_X(t)$  at  $t = 0$ . First, notice that

$$\begin{aligned}\frac{d}{dt}m_X(t) &= m_1 + m_2t + \frac{m_3}{2}t^2 + \dots \\ \frac{d^2}{dt^2}m_X(t) &= m_2 + m_3t + \frac{m_4}{2}t^2 + \dots \\ &\vdots \\ \frac{d^r}{dt^r}m_X(t) &= m_r + m_{r+1}t + \frac{m_{r+2}}{2}t^2 + \dots\end{aligned}$$

## \* Two independent RV

19 May 2018 10:21

**Summary:** For two independent random variables  $X$  and  $Y$ ,

$$f_{X,Y}(x,y) = f_X(x)f_Y(y)$$

$$E(XY) = E(X)E(Y)$$

$$\text{Cov}(X,Y) = 0$$

$$\rho = 0$$

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y)$$

$$\text{Var}(X - Y) = \text{Var}(X) + \text{Var}(Y)$$

$$m_{X+Y}(t) = m_X(t)m_Y(t)$$

$$E[X|Y] = E(X)$$

## \* Change of Variables

19 May 2018 10:26

$$Z = g(X, Y)$$

THEN

PDF of Z

$$f_Z(z) = \int_{x=-\infty}^{+\infty} f_{XY}(x, y(z, x)) dx$$

IF XY Independent

$$f_Z(z) = \int_{y=-\infty}^{+\infty} f_X(z - y) f_Y(y) dy$$

CONVOLUTION

$$U = R(X, Y) \quad V = S(X, Y)$$

THEN

if  $X = L(U, V), Y = T(U, V)$

Jacobian

$$J = \begin{bmatrix} \frac{\partial X}{\partial U} & \frac{\partial X}{\partial V} \\ \frac{\partial Y}{\partial U} & \frac{\partial Y}{\partial V} \end{bmatrix} = \begin{bmatrix} \frac{\partial L}{\partial U} & \frac{\partial L}{\partial V} \\ \frac{\partial T}{\partial U} & \frac{\partial T}{\partial V} \end{bmatrix}$$

$$f_{UV}(u, v) = |\det(J)| f_{XY}(x, y)$$

# Rayleigh Distribution

19 May 2018 11:52

Assume  $X$  and  $Y$  independent and both distributed  $\sim N(0, \sigma^2)$ , such that

$$f_{X,Y}(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{(x^2+y^2)}{2\sigma^2}}.$$

We are interested in  $U = \sqrt{X^2 + Y^2}$ .

Let us add the RV  $V = \tan^{-1} \left( \frac{Y}{X} \right)$  such that

$$X = U \cos V, \quad Y = U \sin V$$

If  $X$  and  $Y$  are zero mean independent Normal random variables with common variance, then  $\sqrt{X^2 + Y^2}$  has a Rayleigh distribution and  $\tan^{-1} \left( \frac{Y}{X} \right)$  has a uniform distribution. Moreover these two derived RVs are independent.

Alternatively, for  $X$  and  $Y$  zero mean independent Normal random variables,  $X + jY$  represents a complex Normal RV. It follows that the magnitude and phase of a complex Normal RV are independent with Rayleigh and uniform distributions respectively.

## Properties

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- ▶ RVs  $X_1, \dots, X_n$  are independent
- ▶ RVs have the same expectation:  $E(X_i) = \mu, \forall i$
- ▶ RVs have the same variance:  $\text{Var}(X_i) = \sigma^2, \forall i$

Results focus on

$$S_n = X_1 + \dots + X_n, \quad E S_n = n\mu, \quad \text{Var } S_n = n\sigma^2$$
$$\bar{X}_n = \frac{X_1 + \dots + X_n}{n}, \quad E \bar{X}_n = \mu, \quad \text{Var } \bar{X}_n = \frac{\sigma^2}{n}$$

# Weak Law

28 October 2017 18:07

$$U_n \xrightarrow{p} \theta.$$

$$\forall \epsilon > 0 \quad \lim_{n \rightarrow \infty} P(|U_n - \theta| > \epsilon) = 0$$

## Weak Law of Large Numbers

$$\forall \epsilon > 0 \quad \lim_{n \rightarrow \infty} P(|\bar{X}_n - \mu| > \epsilon) = 0$$

$$\forall \epsilon > 0 \quad \lim_{n \rightarrow \infty} P(|\bar{X}_n - \mu| \leq \epsilon) = 1.$$

**RVs independent and identically distributed**

$$X_1 + X_2 + \dots + X_n \rightarrow N(n\mu, n\sigma^2) .$$



Statistic is any quantity calculated from sample data

Statistic is a random variable - has a sampling distribution

$$E[\bar{X}] = \mu$$

IF  $n > 30$   
and samples are iid.

$$Var[\bar{X}] = \frac{\sigma^2}{n}$$

$$\bar{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

$$s = \frac{\sigma}{\sqrt{n}}$$

Recall the formula for the sample variance:

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2.$$

# Point Estimation

19 May 2018 13:20

estimate value of unknown parameters ( $\theta$ ) in with sample data

$$f(x|\theta)$$

- roman symbols - sample
- Greek symbols - population parameters

Point Estimator - best guess at unknown population parameter

# Estimator Properties

19 May 2018 13:20

Aim for:

- **unbiasedness**
- **minimum variance**

in the sampling distribution

## Bias:

for an unbiased point estimator  $\hat{\theta}$

$$E[\hat{\theta}] = \theta$$

show that it equals, if know it's unbiased

$\hat{\theta} - \theta$  gives the bias of the estimator

Can assess bias without knowing  $\theta$  if we are confident of the parent distribution

e.g. sample mean is ALWAYS unbiased

AIM for MVU Estimator

but sometimes a little bias can give much smaller variance

So, choose **estimator with smallest Mean Squared Error - MSE**

$$MSE_{\theta}(\hat{\theta}) = E[(\hat{\theta} - \theta)^2] = Var(\theta) + \{Bias_{\theta}(\theta)\}^2$$

$$\hat{\theta} = \omega^n \sum_{i=1}^n X_i$$

$$E(\hat{\theta}) = \omega^n \sum_{i=1}^n E(X_i)$$

$$Var(\hat{\theta}) = \omega^{n+1} \sum_{i=1}^n Var(X_i)$$

## Generating Estimators:

- Method of Moments
- Least Squares
- Maximum likelihood

# Method of Moments

19 May 2018 13:20

## EQUATING SAMPLE MEAN TO POPULATION MEAN

$k$ th moment of  $X$  is  $m_k = E(X^k)$

### Kth Sample Moment

$$\frac{1}{n} \sum_{i=1}^n X_i^k, \quad \text{for } k = 1, 2, \dots$$

$\hat{\theta}$  = *corresponding sample moment*

# Maximum Likelihood Estimation

19 May 2018 13:20

Likelihood function , sample size n

$$L(\theta) = \prod_{i=1}^n f(x_i|\theta)$$

once simplified, take log

$$\ell(\theta) = \log L(\theta)$$

Take **first derivative and equate to 0**

- get Maximum Likelihood Estimator
- (used to get ML estimates)

Take second derivative

- confirm it is a maximum (<0)