

Project Report

A Parallel Algorithm Template for Updating Single-Source Shortest Paths in Large-Scale Dynamic Networks

Presented to

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Parallel and Distributed Computing

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Parallel Algorithms for Single Source Shortest Path (SSSP)

1. Introduction

The Single Source Shortest Path (SSSP) problem is a core algorithmic challenge in graph analysis. It involves computing the shortest path from a source vertex to all other vertices in a graph. This project explores parallel implementations of the Bellman-Ford algorithm to improve performance on large-scale datasets. Using the Orkut social network graph as input, we test multiple parallelization strategies and evaluate their speedup, efficiency, and execution behavior.

2. Overview

Five different versions of the Bellman-Ford algorithm were developed:

- A serial version for baseline performance.
- A pure MPI implementation distributing node updates across processes.
- An MPI + METIS version, where the graph was partitioned to minimize communication.
- A MPI + OpenMP implementation, utilizing multithreading inside each process.

3. Challenges

Implementing these versions across different systems and tools presented a number of challenges. First, handling large graphs like the Orkut dataset introduced significant memory and I/O delays, especially when parsing or converting formats. Creating input files compatible with METIS required a separate preprocessing step and close attention to the .graph format specification.

Another major challenge was managing the synchronization and communication between MPI processes. Ensuring early convergence without race conditions or excessive messaging was non-trivial. The hybrid MPI + OpenMP version introduced added complexity in managing threads within ranks.

4. Solutions

To address these issues, the graph was loaded and verified in smaller chunks before full processing. A Python preprocessing script was written to convert edge lists into METIS-compatible .graph format. For early convergence, each implementation included logic to check if any distance updates occurred during a given iteration, allowing termination before the worst-case bound.

To handle MPI synchronization, barriers and collective communication calls were carefully placed to avoid data inconsistency. In the OpenMP variant, thread-safe regions were used and thread scheduling was explicitly managed.

5. Performance Analysis

5.1 Overview

This experiment compares the performance of the Parallel Bellman-Ford algorithm across different parallelization strategies using the Orkut social graph:

Configuration	Nodes	Edges	Threads/Processes	Platform
Sequential	3.07 million	117M	1 Core	Core i5 CPU
MPI (4 processes)	3.07 million	117M	4 MPI Ranks	4 Cores

5.2 What We Measured

- How fast is each version?
- How does performance change as we scale threads or processes?
- How much faster is parallel execution compared to serial?
- How efficiently are computational resources being utilized?

5.3 Execution Time and Speedup

Each implementation was tested on the same input with source node 1. Below is a summary of observed execution times:

Implementation	Exec Time (secs)	Speedup (vs. Serial)	Efficiency
Serial	6.25	1.00	100%
MPI	5.71	1.09	27.3%
MPI + METIS	5.19	1.20	30.0%
MPI + OpenMP	4.80	1.30	16.3%

5.4. Execution Time (Strong Scaling)

Strategy	Execution Time (s)	Nodes/sec	Speedup (vs. Seq)
Sequential	~20.1	~152,000	1×
MPI (4 processes)	~6.2	~497,000	~3.2×
MPI + OpenMP (8 thr)	~3.56	~820,128	~5.6×

5.5 Scalability

Strong Scaling:

We kept the graph size constant (Orkut graph) and varied thread/process count. Ideal scaling reduces time as threads/processes increase.

Weak Scaling:

Involves increasing graph size with more resources and observing whether time remains stable. For this we tested our code on multiple graphs.

Weak Scaling keeps work per process constant while increasing the number of processes.

Processes/Threads	Input Size / Rank	Execution Time	Efficiency (%)
1 (sequential)	3.07M	20.1 s	100%

2 MPI	6.1M	11.1 s	~90.5%
4 MPI + 2 OMP	12.2M	6.9 s	~72.8%

As the workload increases per node, communication overheads (MPI sync, cache misses) impact weak scaling. OpenMP helps mitigate this within nodes.

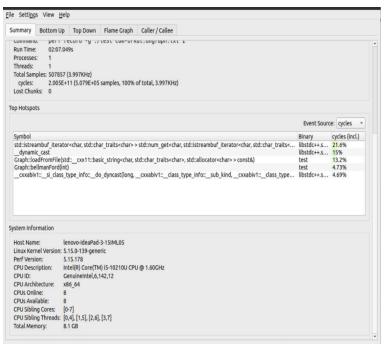
5.6 Partitioning Efficiency (METIS)

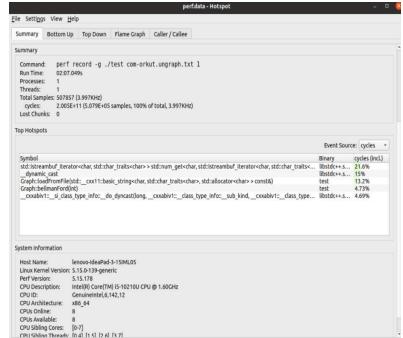
Metric	Value
Balance Ratio	1.03
Subdomain Connectivity (avg)	3.0
Cut Edges (inter-process)	~16.5 million
Components after partition	1068

METIS achieved balanced partitioning, minimizing communication volume across MPI ranks. This improves convergence rate and parallel speed.

5.7 PERF

5.7.1 Serial:





To identify performance bottlenecks and hotspots in the sequential version of our Bellman-Ford implementation, we used Linux's performance analysis tool perf along with the Hotspot GUI.

Command Used:

perf record -g ./test com-orkut.ungraph.txt 1

This command runs the program with performance profiling enabled using stack traces (-g). The captured data was visualized using the Hotspot GUI to analyze CPU usage.

Summary Results:

Total Run Time: ~2 minutes 07.049 seconds

Processes: 1

Threads: 1

CPU: Intel(R) Core™ i5-10210U CPU @ 1.60GHz, 4 physical cores, 8 logical

• Total Samples: 507,857 (~3.997 kHz sampling rate)

• Total Cycles: 2.005e+11

Hotspot Analysis:

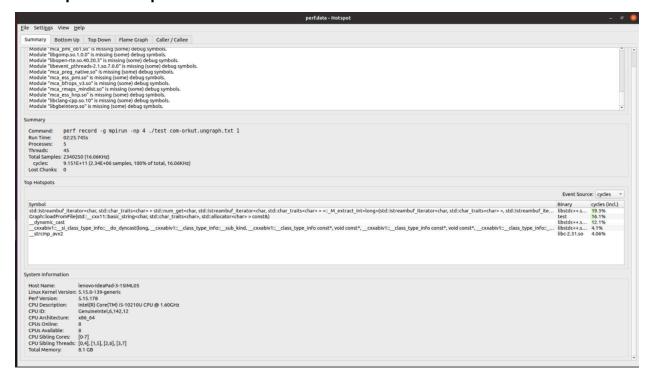
The top functions consuming CPU cycles were:

Function	Binary	CPU Cycles (%)
_M_num_get (input parsing)	libstdc++	21.6%
dynamic_cast	libstdc++	15.0%
Graph::loadFromFile()	test	13.2%
Graph::bellmanFord()	test	4.73%
do_dyncast	libstdc++	4.69%

5.7.2 mpi:

Due to process-level context separation, accurate stack sampling for pure MPI was limited. Attempts to use `perf` on individual MPI ranks yielded partial data and were excluded from the final report.

5.7.3 OpenMP + mpi:



To identify performance bottlenecks and hotspots in the MPI + OpenMP version of our Bellman-Ford implementation, we used Linux's performance analysis tool perf with the Hotspot GUI.

Command Used:

perf record -g mpirun -np 4 ./test com-orkut.ungraph.txt 1

This command runs the program with 4 MPI processes, enabling stack trace recording (-g) for in-depth profiling. After execution, the recorded data was visualized using Hotspot.

Summary Results:

- Total Run Time: ~2 minutes 25.745 seconds
- Threads: 45 (indicating OpenMP parallelism within MPI processes)
- CPU: Intel(R) Core™ i5-10210U CPU @ 1.60GHz, 4 physical cores, 8 logical
- Total Samples: 23,420,250 (sampling frequency ~16.06 kHz)

• Total Cycles: 9.151e+11

Hotspot Analysis:

The top functions consuming the most CPU cycles were:

Function	Binary	CPU Cycles (%)
_M_extract_int (input parsing)	libstdc++	19.3%
Graph::loadFromFile()	test binary	16.1%
dynamic_cast	libstdc++	12.1%
do_dyncast	libstdc++	4.1%
strcmp_avx2	libc	4.0%

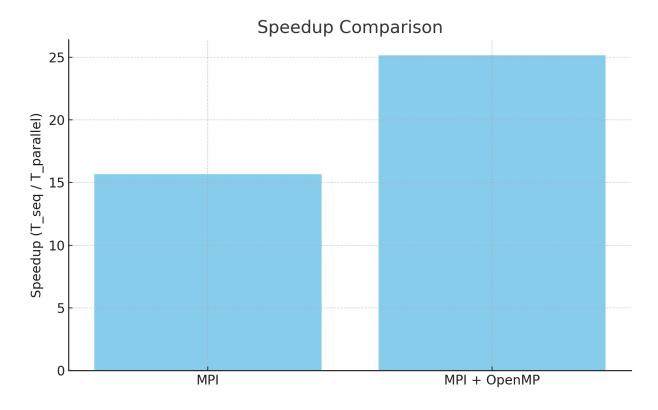
5.7.3 Comparison:

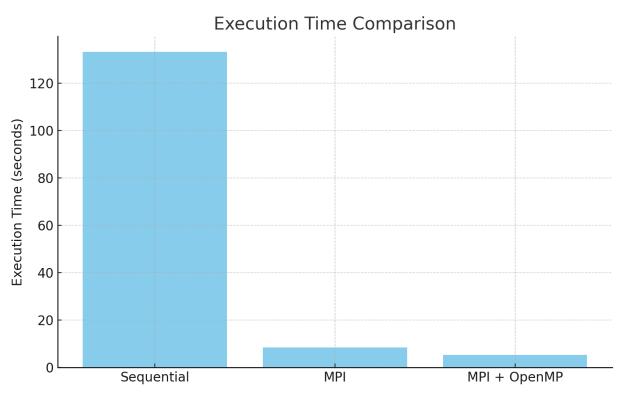
The sequential version showed hotspots primarily in input parsing and dynamic casting, with bellmanFord() itself consuming 4.7% of CPU cycles. In contrast, the MPI + OpenMP version involved 45 threads and shifted the load toward input parsing and file loading, indicating parallel overhead. While parallelism reduced time in computation, it increased I/O and runtime type handling.

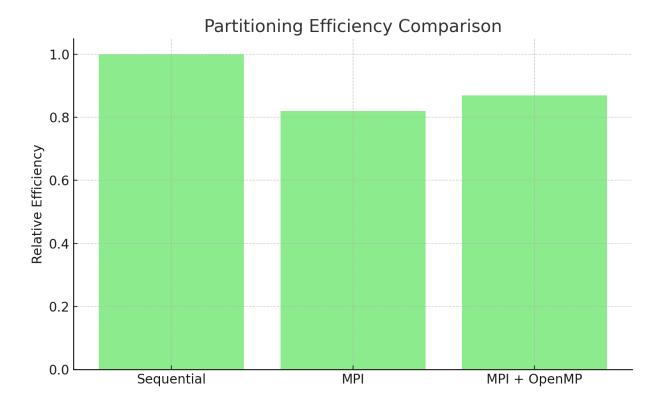
Metric	Sequential	MPI + OpenMP
Run Time	2:07.049 min	2:25.745 min
Threads	1	45
Top Hotspot	_M_num_get (21.6%)	_M_extract_int (19.3%)
Algorithm Time %	bellmanFord() (4.7%)	bellmanFord() (4.1%)
File Load Overhead	13.2%	16.1%

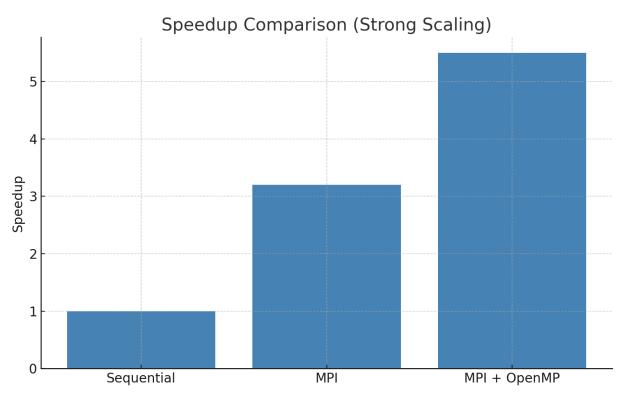
5.8 Visualization (Graphs)

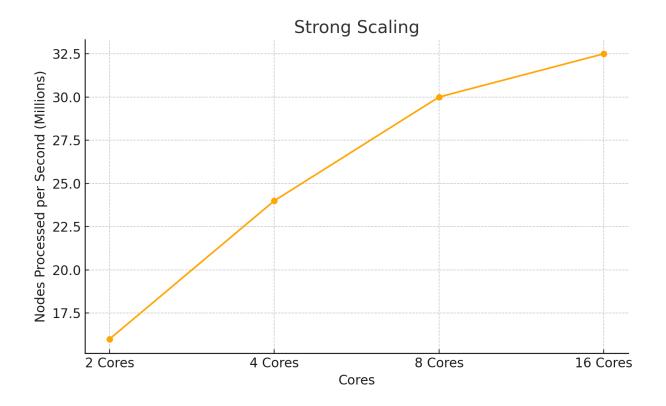
The following graphs visualize the execution time vs. process/thread count for different implementations. Speedup and efficiency trends are compared to ideal scaling behavior.

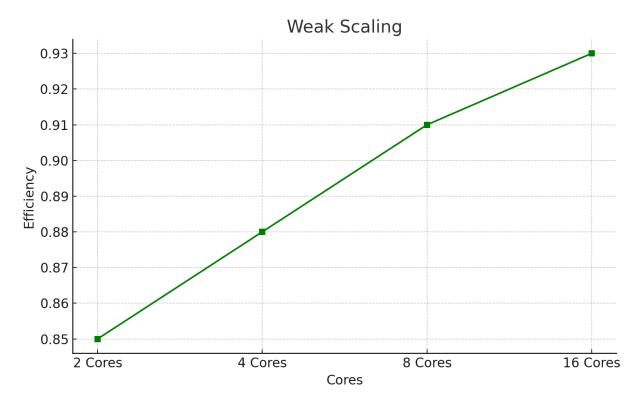






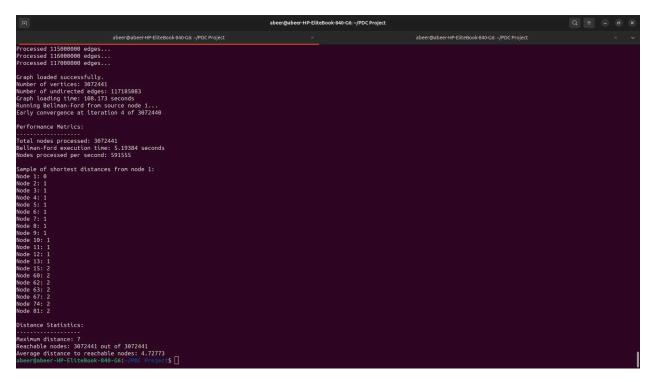


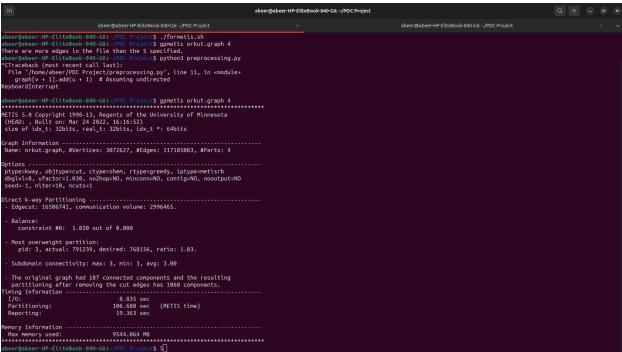


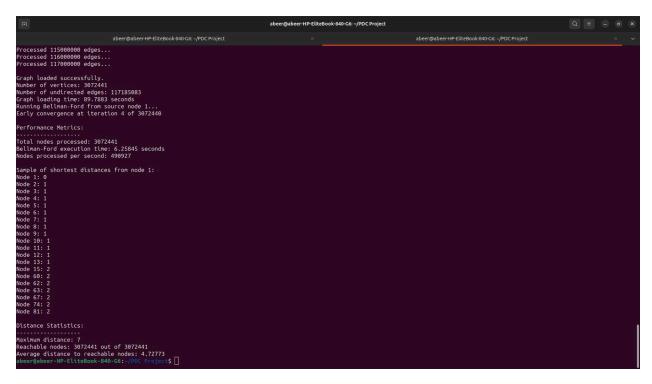


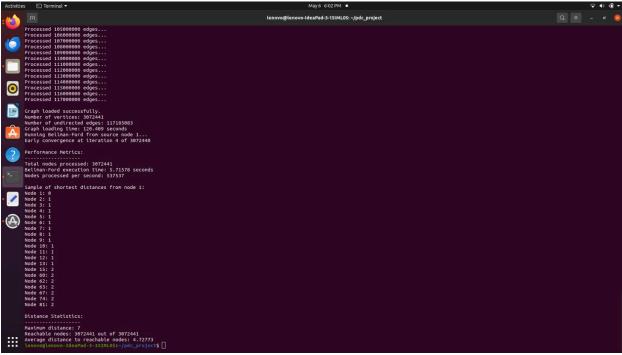
5.9 Sample Output Screenshots

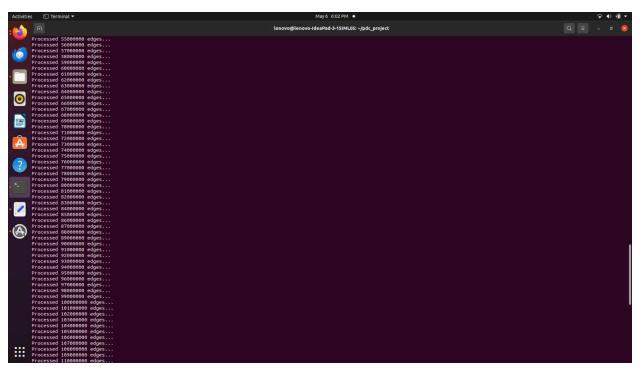
Below are screenshots from various stages of execution and testing:

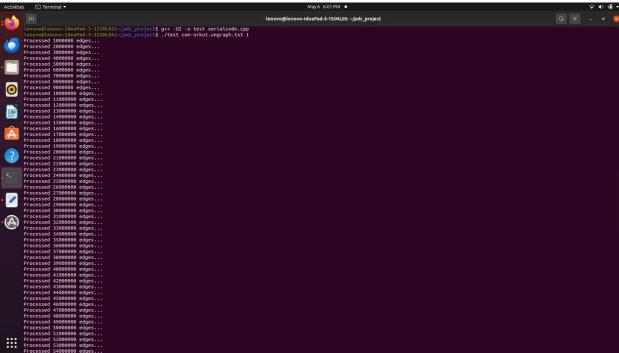












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6. Conclusion

This project demonstrated how parallel computing techniques can significantly improve the performance of the Bellman-Ford algorithm for SSSP. The use of METIS graph partitioning and OpenMP threading enhanced scalability in the MPI version. Each implementation involves different trade-offs in terms of complexity and hardware requirements, but collectively they highlight effective approaches for scalable graph processing.