

ECE 6360 Parallel and Heterogeneous Computing

Raytracing – Parallel Path Tracing

Rubric

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CMake repository compiles (gcc/g++)	_____ / required
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report on parallel speedup	_____ / 25

Helpful Pseudocode

- Feel free to ask about any of these algorithms in the General chat on Teams

Path Tracing (general approach)

```
while ( rendering ) {  
  for each pixel:  
    r = GenerateRay(...)  
    path_color = [0, 0, 0]  
    path_scattering = [1, 1, 1]  
    for each bounce:  
      t, entity = CalculateClosestHit(r, ...)  
      r = entity->Scatter(...)  
      path_color += entity->emission * path_scattering  
      path_scattering *= entity->scattering;  
}
```

Scattering

```
Scatter(...) function:  
  p = r(p)  
  n = normal()  
  new_ray = SampleHemisphere(n, ...)  
  cos( $\theta$ ) = dot(new_ray, n)  
  return emission, scattering * cos( $\theta$ )
```

Sample Hemispheres

You'll have to write a function that randomly samples a hemisphere. As input, you'll need the surface normal \mathbf{n} and the solid angle α that you want to sample (for a hemisphere $\alpha = \pi$). You will also need two random numbers $x_0, x_1 \in [0, 1)$.

You can uniformly sample the surface of a unit sphere using Archimedes' principle (see lecture). First, use the random numbers to calculate a sample on a unit cylinder in cylindrical coordinates (θ, z) :

$$z = x_0(1 - \cos \alpha) + \cos \alpha \quad \theta = x_1 2\pi$$

Then project these spherical coordinates onto a unit sphere in spherical coordinates (θ, ϕ) – since you already have θ you can calculate $\phi = \cos^{-1} z$. Converting these spherical coordinates into Cartesian coordinates gives you a vector that is within the solid angle α of the z-axis:

$$\mathbf{v}' = \begin{bmatrix} \cos \theta \sin \phi \\ \sin \theta \sin \phi \\ \cos \phi \end{bmatrix}$$

This vector \mathbf{v} provides a new random ray orientation that lies within the specified solid angle ($\alpha = \pi$ for a hemisphere) of the z-axis. Now you can align the z-axis with the surface normal by calculating a rotation matrix \mathbf{R} to transform \mathbf{v}' .

Calculate the axis and rotation angle β needed to rotate the z-axis to align with \mathbf{n} . This can be done using the cross product:

$$\mathbf{a} = \mathbf{n} \times \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

where the rotation axis is $\mathbf{s} = \frac{\mathbf{a}}{\|\mathbf{a}\|}$ and $\cos \beta = \mathbf{s} \cdot \mathbf{n}$.

$$\mathbf{R} = \begin{bmatrix} s_x^2(1 - \cos \beta) + \cos \beta & s_x s_y(1 - \cos \beta) - s_z \sin \beta & s_x s_z(1 - \cos \beta) + s_y \sin \beta \\ s_x s_y(1 - \cos \beta) + s_z \sin \beta & s_y^2(1 - \cos \beta) + \cos \beta & s_y s_z(1 - \cos \beta) - s_x \sin \beta \\ s_x s_z(1 - \cos \beta) - s_y \sin \beta & s_y s_z(1 - \cos \beta) + s_x \sin \beta & s_z^2(1 - \cos \beta) + \cos \beta \end{bmatrix}$$

The final sample direction for your new ray is:

$$\mathbf{v} = \mathbf{R} \mathbf{v}'$$